利用MegEngine的分布式通信算子实现复杂的并行训练

MEGVII 旷视

旷视研究院基础模型组研究员 周亦庄

2021年03月25日





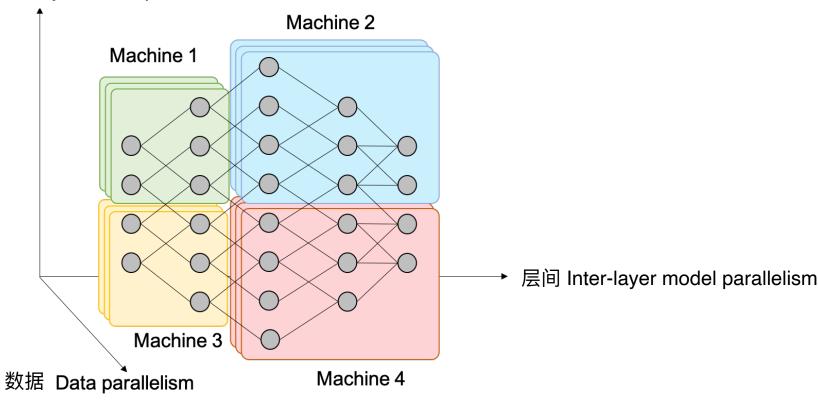
Code Available:

https://github.com/zhouyizhuang-megvii/MegEngineParallelTutorial

引言:深度学习中的并行



层内 Intra-layer model parallelism





- 0. MegEngine的通信算子
- 1. 简单参数并行
- 2. 层内模型并行(Intra-layer Model Parallelism)
 - 2.1. 全连接(Fully Connected)模型并行
 - 2.2. 组卷积(Group Convolution)模型并行
- 3. 层间模型并行(Inter-layer Model Parallelism)
 - 3.1. 简单模型并行
 - 3.2. 流水线并行(Pipeline Parallelism)
 - 3.2.1. 流水线推理
 - 3.2.2. 手动checkpoint与GPipe

0. MegEngine的通信算子



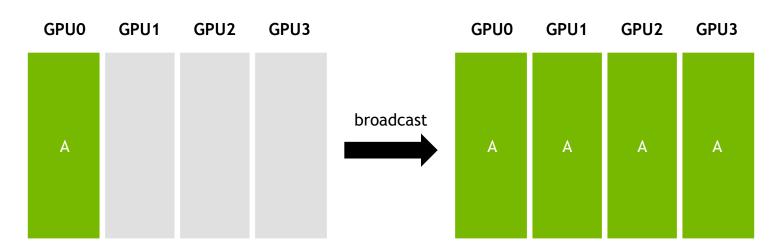
F.distributed	算子	对应的微分算子	行为	常用用途
	broadcast	reduce_sum	同步	数据并行
Collective communication	reduce_sum	broadcast	求和	
集合通信 (一对多)	scatter	gather	拆分	
	gather	scatter	集中	
	all_reduce_sum	all_reduce_sum	同步求和	数据并行
Collective Communication	all_gather	reduce_scatter_sum	同步集中	层内模型并行
集合通信(多对多)	reduce_scatter_sum	all_gather	求和后拆分	层内模型并行
	all_to_all	all_to_all	转置	层内模型并行
Point-to-point Communication	remote_send	remote_recv	发送	层间模型并行
点对点通信	remote_recv	remote_send	接收	层间模型并行

保密信息



BROADCAST

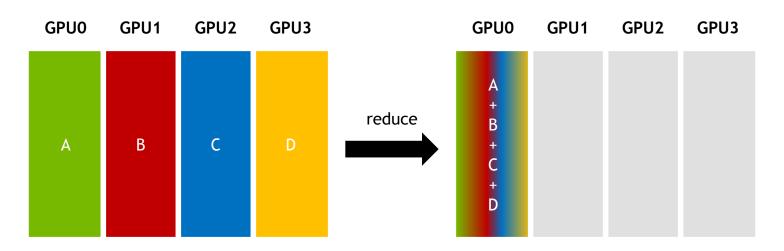
One sender, multiple receivers





REDUCE

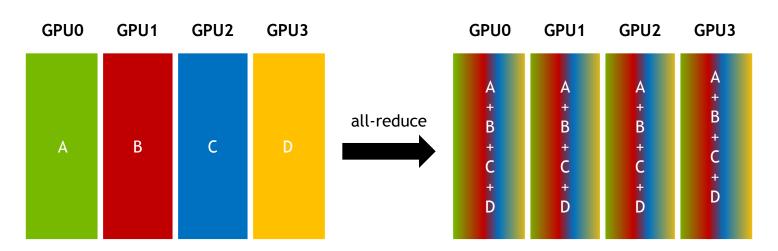
Combine data from all senders; deliver the result to one receiver





ALL-REDUCE

Combine data from all senders; deliver the result to all participants



0. MegEngine的通信算子



GATHER

Multiple senders, one receiver

GPU0	GPU1	GPU2	GPU3		GPU0	GPU1	GPU2	GPU3
А	В	С	D		А			
				gather	В			
					С			
					D			



ALL-GATHER

Gather messages from all; deliver gathered data to all participants

GPU0	GPU1	GPU2	GPU3		GPU0	GPU1	GPU2	GPU3
А	В	С	D		A	А	А	А
				all-gather	В	В	В	В
					С	С	С	С
					D	D	D	D

0. MegEngine的通信算子



ALL-TO-ALL

Scatter/Gather distinct messages from each participant to every other

GPU0	GPU1	GPU2	GPU3		GPU0	GPU1	GPU2	GPU3
A0	В0	C 0	D0		A0	A1	A2	A3
A1	B1	C 1	D1	all-to-all	В0	B1	В2	В3
A2	B2	C2	D2		C 0	C1	C2	C 3
A3	В3	C 3	D3		D0	D1	D2	D3

0. MegEngine的通信算子



SCATTER

One sender; data is distributed among multiple receivers

GPU0	GPU1	GPU2	GPU3		GPU0	GPU1	GPU2	GPU3
А					A	В	С	D
В				scatter				
С								
D								

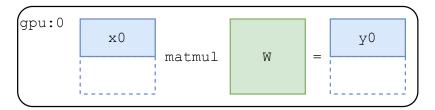


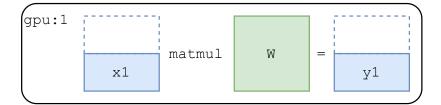
REDUCE-SCATTER

Combine data from all senders; distribute result across participants

GPU0	GPU1	GPU2	GPU3		GPU0	GPU1	GPU2	GPU3
A0	В0	C 0	D0		A0+B0+ C0+D0	A1+B1+ C1+D1	A2+B2+ C2+D2	A3+B3+ C3+D3
A1	B1	C 1	D1	reduce- scatter				
A2	B2	C2	D2					
A3	В3	C 3	D3					

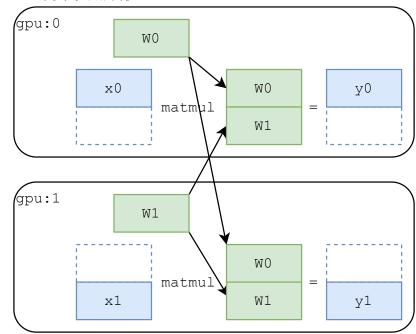
1. 数据并行





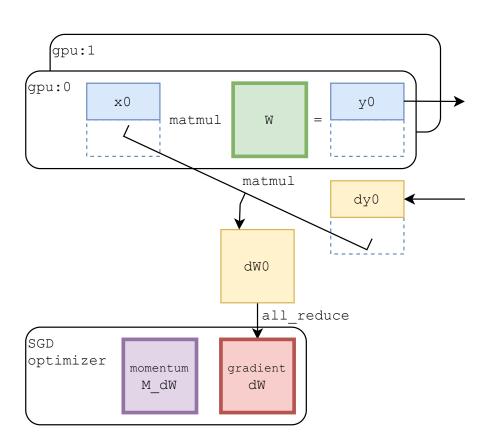
def forward(self, x):
 return F.nn.linear(x, self.weight)

2. 简单参数并行

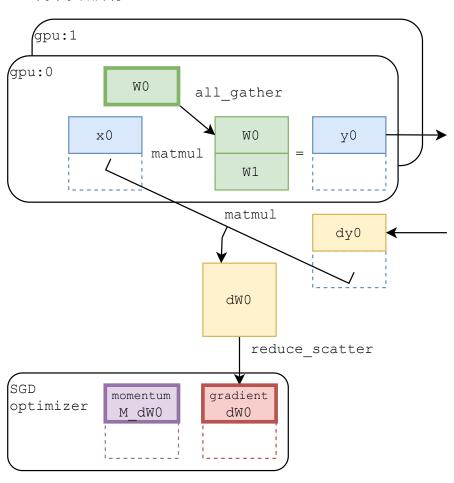


def forward(self, x):
 weight = F.distributed.all_gather(self.weight)
 return F.nn.linear(x, weight)

1. 数据并行



2. 简单参数并行



1. 简单参数并行



1. 数据并行

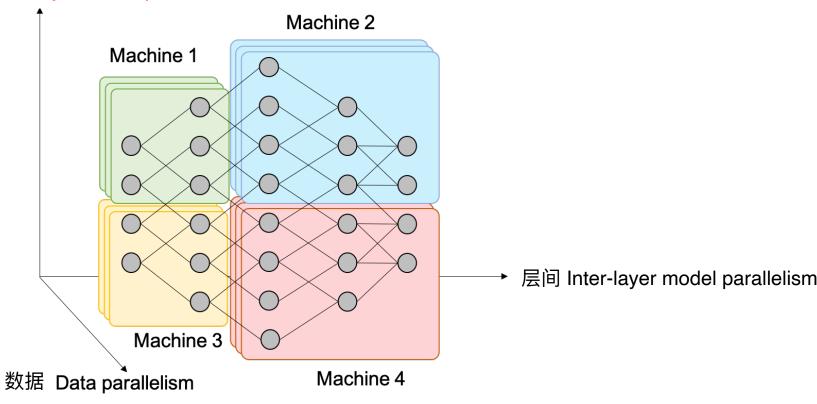
```
model = M.Linear(inp, oup, bias=False)
def forward(self, x):
    return F.nn.linear(x, self.weight)
model.forward = forward
# equal to `dist.bcast_list_(model.parameters())`
for p in model.parameters():
    p._reset(F.distributed.broadcast(p))
gm = ad.GradManager().attach(
        model.parameters(),
        callbacks=dist.make_allreduce_cb("SUM")
```

2. 简单参数并行

2. 层内模型并行(Intra-layer Model Parallelism)

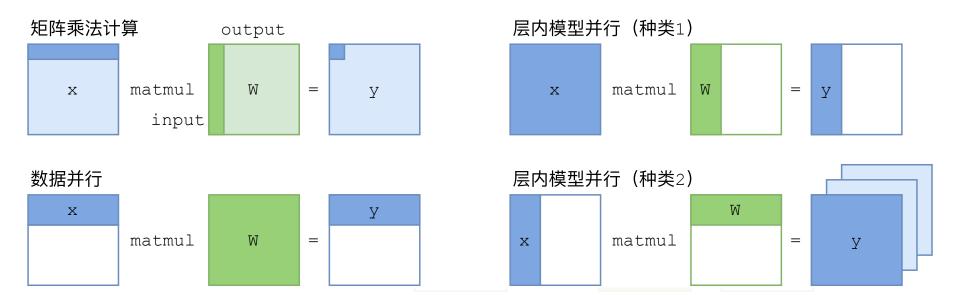


层内 Intra-layer model parallelism



2. 层内模型并行(Intra-layer Model Parallelism)





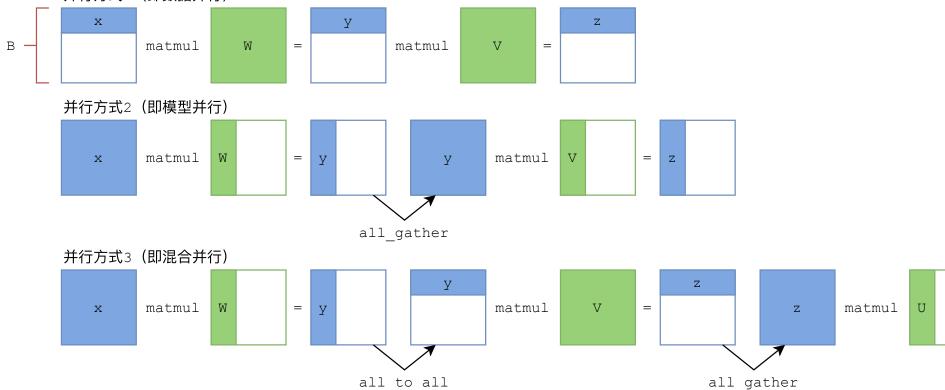
并行方式2(即模型并行)



2. 层内模型并行(Intra-layer Model Parallelism)



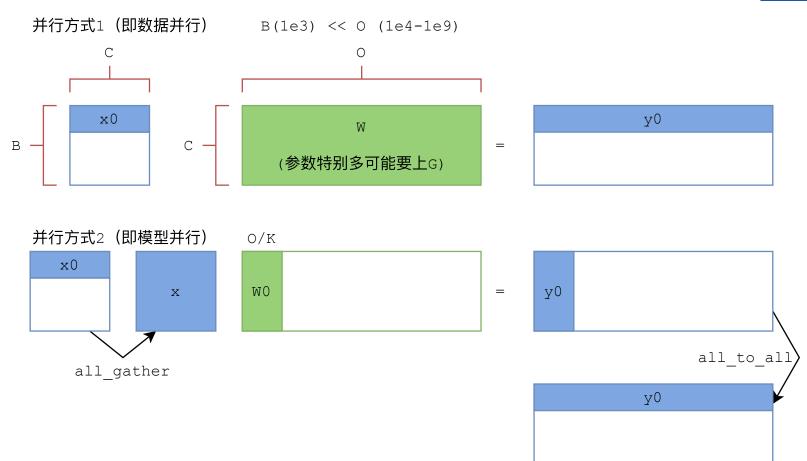
并行方式1(即数据并行)



all to all

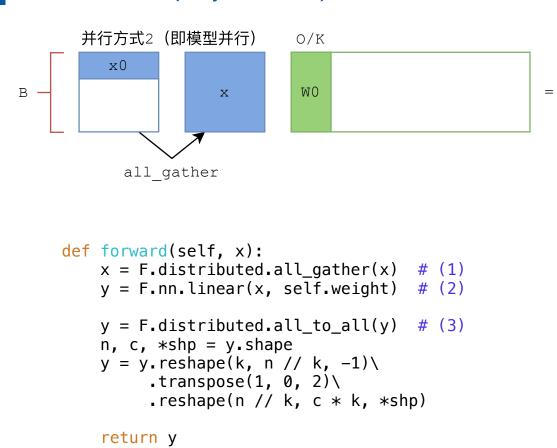
2.1. 场景一:全连接(Fully Connected)模型并行





■2.1. 场景一:全连接(Fully Connected)模型并行

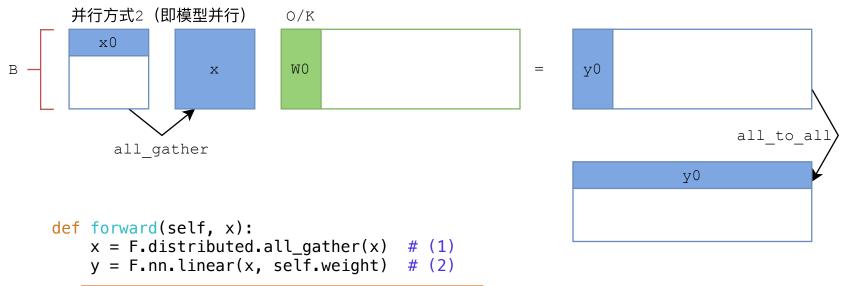




```
y0 all_to_all y0
```

■2.1. 场景一:全连接(Fully Connected)模型并行





```
y = F.distributed.all_to_all(y) # (3)
n, c, *shp = y.shape
y = y.reshape(k, n // k, -1)\
    .transpose(1, 0, 2)\
    .reshape(n // k, c * k, *shp)
```

reshape...transpose...

这些是什么??

数据重排布!

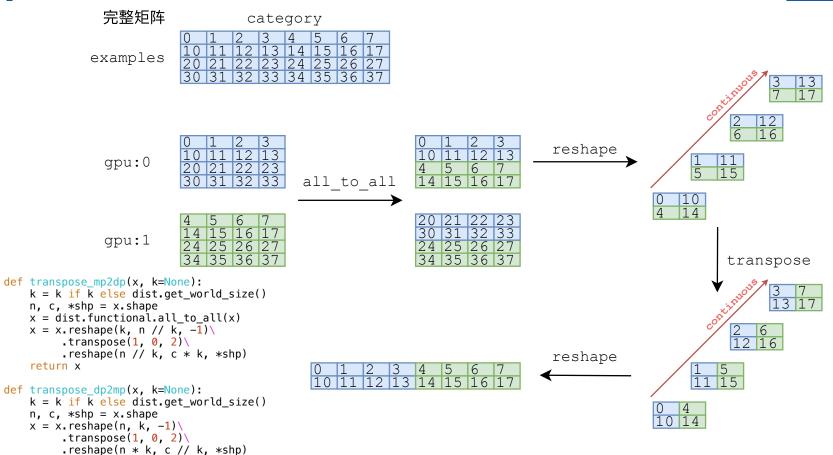
return y

2.1. 场景一:全连接(Fully Connected)模型并行

x = dist.functional.all to all(x)

return x



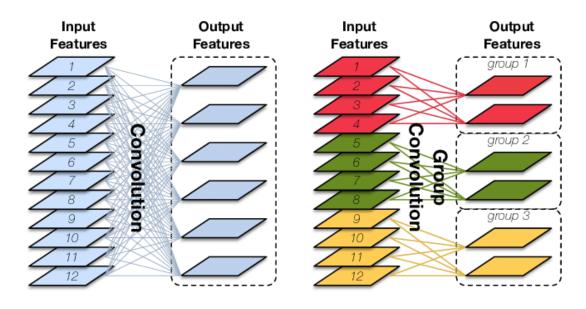


2.2. 场景二:组卷积(Group Convolution)模型并行



普通卷积

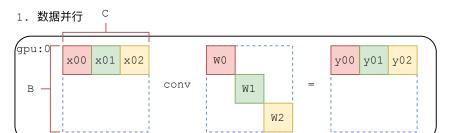
组卷积(等价于K个普通卷积)

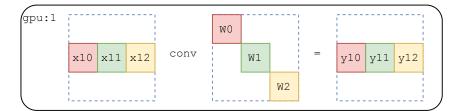


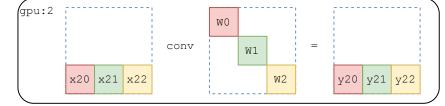
保密信息

2.2. 场景二:组卷积(Group Convolution)模型并行

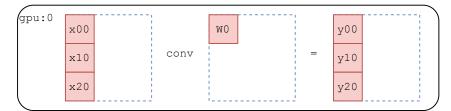








2. 模型并行

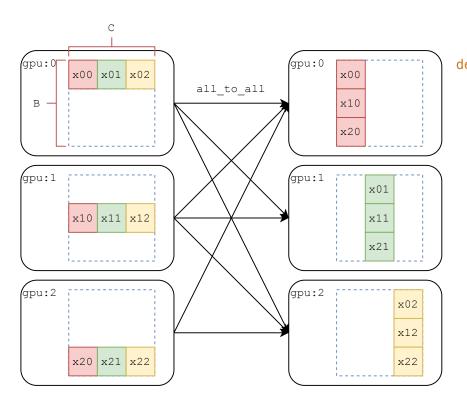






2.2. 场景二:组卷积(Group Convolution)模型并行





```
def forward(self, x, is_head=False, is_tail=False):
    k = dist.get_world_size()
    if is_head:
        x = transpose_dp2mp(x, k=k)

x = F.conv2d(x, self.weight, groups=1, **kwargs)

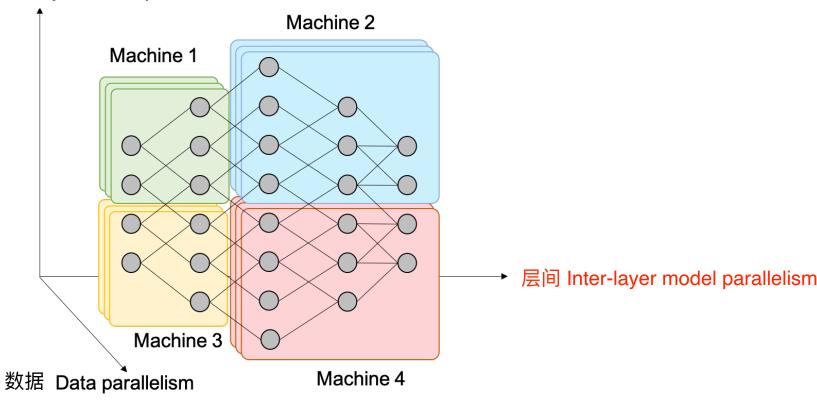
if is_tail:
    x = transpose_mp2dp(x, k=k)

return x
```

3. 层间模型并行(Inter-layer Model Parallelism)



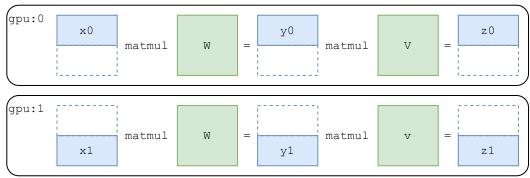
层内 Intra-layer model parallelism



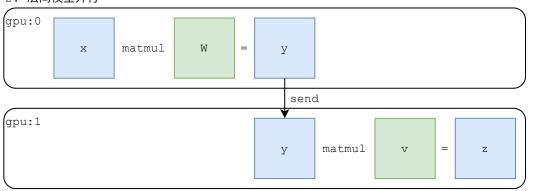
3. 层间模型并行(Inter-layer Model Parallelism)



1. 数据并行



2. 层间模型并行

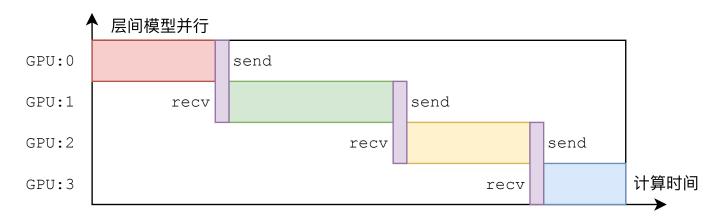


3. 层间模型并行(Inter-layer Model Parallelism)



```
def send_to_next_gpu(tensor):
    shape, dtype = tensor.shape, np.dtype(tensor.dtype).name
    dist.get_client().user_set(f"shape_of_src{dist.get_rank()}", shape)
    dist.get_client().user_set(f"dtype_of_src{dist.get_rank()}", dtype)
    return F.distributed.remote_send(tensor, dest_rank=dist.get_rank() + 1)

def recv_fr_prev_gpu():
    shape = dist.get_client().user_get(f"shape_of_src{dist.get_rank() - 1}")
    shape = dist.get_client().user_get(f"dtype_of_src{dist.get_rank() - 1}")
    return F.distributed.remote_recv(src_rank=dist.get_rank() - 1, shape=shape, dtype=dtype)
```



3.1. 简单模型并行

普通数据并行

```
class ResNet18(M.Module):
   def init (self):
        super().__init__()
        self.stem = M.Sequential(
            M.ConvBn2d(3, 64, 7, stride=2, padding=3, bias=False),
           M.MaxPool2d(kernel size=3, stride=2, padding=1),
        self.features = M.Sequential(
            BasicBlock(64, 64, 1),
            BasicBlock(64, 64, 1),
            BasicBlock(64, 128, 2),
            BasicBlock(128, 128, 1),
            BasicBlock(128, 256, 2),
            BasicBlock(256, 256, 1),
            BasicBlock(256, 512, 2),
            BasicBlock(512, 512, 1),
        self.classifier = M.Linear(512, 1000)
   def forward(self, x):
       x = self.stem(x)
       x = self.features(x)
       x = F.avg_pool2d(x, 7)
       x = F.flatten(x, 1)
       x = self.classifier(x)
        return x
```

简单模型并行



```
def init (self):
    super(). init ()
    self.classifier = None
    if dist.get rank() == 0:
        self.features = M.Sequential(
           M.ConvBn2d(3, 64, 7, stride=2, padding=3, bias=False),
           M.MaxPool2d(kernel size=3, stride=2, padding=1),
           BasicBlock(64, 64, 1),
            BasicBlock(64, 64, 1),
   elif dist.get rank() == 1:
        self.features = M.Sequential(
            BasicBlock(64, 128, 2),
            BasicBlock(128, 128, 1),
   elif dist.get_rank() == 2:
        self.features = M.Sequential(
            BasicBlock(128, 256, 2),
            BasicBlock(256, 256, 1),
   elif dist.get rank() == 3:
        self.features = M.Sequential(
            BasicBlock(256, 512, 2),
            BasicBlock(512, 512, 1),
        self.classifier = M.Linear(512, 1000)
def forward(self, x):
    if dist.get rank() > 0:
        x = recv_fr_prev_gpu()
   x = self.features(x)
    if dist.get rank() != 3:
       _ = send_to_next_gpu(x)
    else:
        x = F.avg pool2d(x, 7)
        x = F.flatten(x, 1)
        x = self.classifier(x)
    return x
```

class ResNet18MP(M.Module):

3.1. 简单模型并行(推理&训练)

```
@dist.launcher(n_gpus=4)
def inference():
    m = ResNet18MP()
    x = F.ones([32, 3, 224, 224])
    y = m(x)
    print(y.shape)

# --- Get ---
# (32, 64, 56, 56)
# (32, 128, 28, 28)
# (32, 256, 14, 14)
# (32, 1000)
```

```
@dist.launcher(n gpus=4)
def train():
    m = ResNet18MP()
    x = F.ones([32, 3, 224, 224])
    label = F.zeros([32,], dtype="int32")
    gm = ad.GradManager().attach(m.parameters())
    opt = optim.SGD(m.parameters(), 1e-3, 0.9, 1e-4)
    for in range(2):
        with gm:
             y = m(x)
            if dist.get_rank() == 3:
                 loss = F.nn.cross_entropy(y, label)
             else:
                 loss = None
             gm.backward(loss)
        opt.step().clear_grad()
         print(loss)
# --- Get ---
# None
# None
# None
# Tensor(6.631501, device=qpu3:0)
# None
# None
# None
# Tensor(5.7957726, device=qpu3:0)
```

3.2. 流水线并行(Pipeline Parallelism)

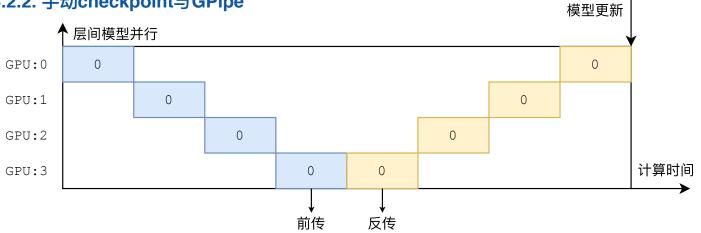


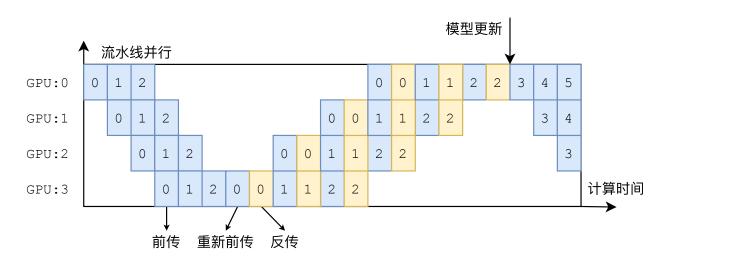
```
def forward(self, x):
    self.num chunks = 4
    self.inp chunks = []
                                                  层间模型并行
    self.oup_chunks = []
    if dist.get rank() == 0:
                                           GPU:0
        self.inp_chunks = F.split(x, 4)
                                           GPU:1
    for i in range(self.num chunks):
                                           GPU:2
        if dist.get rank() == 0:
            x = self.inp chunks[i]
                                                                                            计算时间
                                           GPU:3
        else:
            x = recv_fr_prev_gpu()
                                                  流水线并行
            self.inp chunks.append(x)
                                           GPU:0
        x = self_features(x)
                                           GPU:1
        if dist.get rank() != 3:
              = send to next gpu(x)
                                           GPU:2
        else:
                                                                                            计算时间
            x = F.avg pool2d(x, 7)
                                           GPU:3
            x = F.flatten(x, 1)
            x = self.classifier(x)
        self.oup chunks.append(x)
```

return F.concat(self.oup_chunks)

3.2.2. 手动checkpoint与GPipe







3.2.2. 手动checkpoint与GPipe

前传(不计算梯度)

```
def forward(self, x):
                                             def backward(self, label, gm):
                                                 label chunks = F.split(label, 4)
    self.num chunks = 4
    self.inp_chunks = []
                                                 losses = []
    self.oup_chunks = []
   if dist.get_rank() == 0:
                                                 for i, x in enumerate(self.inp chunks):
        self.inp_chunks = F.split(x, 4)
                                                     with qm:
                                                         gm.attach(x) # query gradient of the input
                                                         y = self.features(x)
    for i in range(self.num_chunks):
        if dist.get_rank() == 0:
           x = self.inp_chunks[i]
                                                         if dist.get_rank() == 3:
        else:
                                                             y = F.avg pool2d(y, 7)
                                                             y = F.flatten(y, 1)
            x = recv_fr_prev_gpu()
            self.inp_chunks.append(x)
                                                             y = self.classifier(y)
                                                             loss = F.nn.cross_entropy(y, label_chunks[i])
       x = self.features(x)
                                                             losses.append(loss)
        if dist.get_rank() != 3:
                                                             gm.backward(loss)
           _ = send_to_next_gpu(x)
                                                         else:
        else:
                                                             grad = grad_fr_next_gpu()
            x = F_avg_pool2d(x, 7)
                                                             gm.backward(y, dy=grad)
            x = F.flatten(x, 1)
            x = self.classifier(x)
                                                         if dist.get_rank() != 0:
        self.oup_chunks.append(x)
                                                             _ = grad_to_prev_gpu(x.grad)
    return F.concat(self.oup_chunks)
                                                 return sum(losses) / self.num_chunks if losses else None
```

反传(重新计算一遍前传)

Code Available: https://github.com/zhouyizhuang-megvii/MegEngineParallelTutorial

