Multi Comm Terminal

Hobbyist Terminal Program to communicate with Embedded systems

By Michael Roop

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Introduction

This program will allow users to communicate with embedded devices such as Arduinos, Raspberry Pie, and others using different communication mediums.

Supported Mediums

- Bluetooth Classic:
 - o Connects to a device which implements a Bluetooth serial access point.
 - o Tested against an Arduino Uno with an ITEA Bluetooth shield with an HC-05 module.
 - o An Arduino code sample is provided
- BLE (Bluetooth Low Power):
 - Connects to a device which implements BLE Characteristics for inputs and outputs.
 - o Tested against an Arduino WIFI Rev2. With forked ArduinoBLE branch
 - https://github.com/unknownconstant/ArduinoBLE
 - An Arduino code sample is provided.
- WIFI:
 - o Connects to a device which implements a WIFI Access Point.
 - o The access point shows up as an SSID like any router.
 - The device also must provide a socket address and port.
 - Tested against an Arduino WIFI Rev2.
 - An Arduino code sample is provided.
- USB:
 - o Connection via hard wired USB port
 - o Tested against an Arduino Uno
 - An Arduino code sample is provided
- Ethernet
 - Connection via hard wired Ethernet cable
 - o Tested against a Sunfounder Ethernet shield on an Arduino Uno

Data Storage

Data storage root depends on if running as a Windows Application or a Win App Desktop Application (From the App Store). Currently I am only releasing via the Windows App store so it should not be a problem

- Windows Desktop Application: C:\Users\UserName\AppData\Local\MultiCommSerialTerminal
- Win App:
 C:\Users\Michael\UserName\Local\Packages\LlongGUIDSstring\LocalCache\Local\MultiCommSerialTerminal

An example of the long GUID string would be: 1c29e46d-d1d0-4f21-acbf-d63f3611c3a2_k00brw8eakxmj

Data is stored in various directories under that root. The only time you might ever want to access it directly is to view the debug logs to report errors

All contents are in plain text in JSON format. Except for the credentials files which are encrypted. Do NOT change the file names as you will lose access to the data.

An interesting side note is that if the Windows Desktop directory tree is already created, the Win App will store the data in those directories instead of the normal Win App directory. Also, the data will not be removed if the App is deleted. I have noticed some bizarre side effects with this so if you ever get a desktop version you would do well to delete the App first and vice versa, making sure to delete the desktop storage tree

These are the current sub directories

- Documents: Has a copy of the User Manual. You can access it through the App
- Logs: Up to 10 log files that contain data from running the App
- Scripts: Command sets
- SerialConfigurations: The serial configuration for USB connections
- Settings: Current App Settings
- WifiCredentials: WIFI connection credentials and parameters

Lists of Commands

The user can create, store, and retrieve lists of ASCII based messages. The messages can be sent to the embedded device once connection is established. The embedded device can interpret those character strings as a command to launch certain actions. This allows the user to control the device remotely. For more information see the Intro to embedded messaging in the appendix

Serial Configurations

On first connection to a USB device on COM port n, with a USB vendor id of n and a USB product Id of n, a dialog comes with the configuration of the device as read from the device. The user can modify those and save the results in the serial configurations directory

Terminators

The user can create, store, and retrieve end of message terminator sequences. The terminator(s) will be automatically added to the end of the outgoing message. The terminators are non-printable characters which tell the embedded device that the full message has been received. The device must also add those terminators to the end of any response or other synchronous messages from the device.

WIFI Credentials

On first connection, the WIFI password, as well as the host name (or IP address) and service port are entered and saved if the connection is successful. There is functionality to go back and edit or delete those stored credentials. They are encrypted

Languages

The App currently supports 17 languages in most areas of the UI:

- Arabic
- Bengali (India)
- Chinese (Simplified)
- Czech
- English
- French
- German
- Hindi
- Italian
- Japanese
- Korean
- Portuguese
- Russian
- Spanish
- Turkish
- Ukrainian
- Vietnamese

I followed a simple approach of single word descriptions for headers and buttons. I used the Microsoft Technical Language Portal to get the translation. See: https://www.microsoft.com/en-us/language/Search?&searchTerm=Automatic&langID=303&Source=true&productid=0. This allows for a high precision in rendering of the languages.

Settings

The file contains, among other things, currently selected preferences so that the App starts with the same selections as last time. Currently those preferences are Language, Terminators, Command list. More could be added over time

User Interface

Buttons





Buttons have both an icon and text. So, if you inadvertently switch to a language you do not understand you can still navigate back to change it.

Wordless Buttons

These are small and used throughout. The usage should be self-evident



Add: Add a new Item



Edit: Edit and existing item



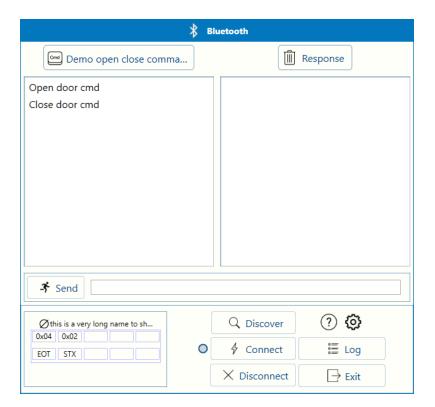
Delete: Remove an item

Run Window

This is a common page format to run commands through different communication mediums. You will get this by clicking on the Menu for Bluetooth, WIFI, USB, and Ethernet. BLE has its own page format. Not all the controls are enabled on every page.

You can have one window of each communication medium open at the same time. The exception is Bluetooth and BLE. Since they both use the same radio, only one of the two can be open. If you try to open the second Bluetooth type, the first opened type will close.

I am considering allowing multiple USB, Ethernet pages open at the same time if there is a demand for such



Elements



Demo open close comma...

Open door cmd Close door cmd





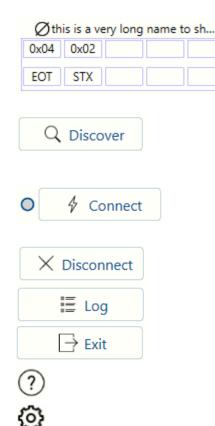
Title. Before any device selection the name of the medium is posted. After you do a discovery and select a device, its name will be posted here next to the medium type icon.

The currently selected Command list. The name of the list is displayed. If the name is too long, it will be cut short with ellipses. If you tap on this it will bring up a selection dialog where you can change the list

Commands from the selected commands list. When you tap one, its command is posted in the Send box

This will send the command in the Send box to the device if you have established a connection. You can also free edit the contents of the Send box and send that text

Tapping on this will clear all the responses from the response list below



The shows the currently selected Terminators set. Tapping on this will bring up a select dialog to change the set

Launches a discovery of the available connections. The method of discovery varies per medium.

Establish a connection for the selected device. If you have not previously selected a device, you will be presented with a select dialog. The light to the left turns green on successful connection

Break any current connection

Opens a pane at the bottom to show scrolling debug information

Close the page

Provides information on selected device. If none is selected, you will get the select dialog first.

Settings. Varies per connection medium

Main Window



Elements:

'Hamburger' icon on title bar. Click on it to open drop down menu where you can set language, etc.

Author: Michael Roop Link to my LinkedIn profile

Icons: ICONS8 Link to the Icons 8 which provided the icons

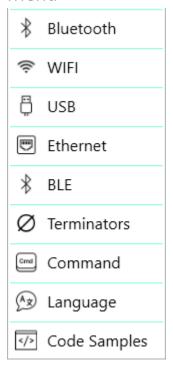
Build: 2020.12.17.06 Build number for reporting errors

<u>User Manual</u> Link to this user manual in PDF format

Support Link to an email address for support

Exit the App

Menu



Select the run page for various communication mediums general settings. We will start with the general settings

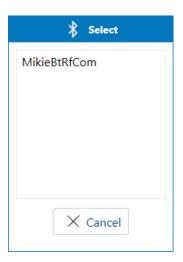
Bluetooth Run Page

Click on the menu item

∦ Bluetooth

It will bring up the run page. General functionality of the run page is explained above.

Clicking on the Discover button (or info Icon if nothing yet selected) will bring up the Select dialog for paired Bluetooth Classic devices



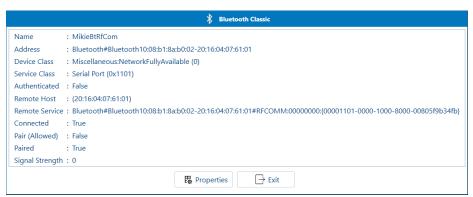
Clicking on a selection will close the dialog and set it as your selected device. You will notice that the device name is now listed on the title bar of the Run page



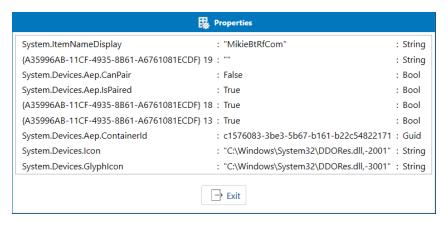
Info

Click on the info icon





Click on exit to close, or the Properties button to show properties



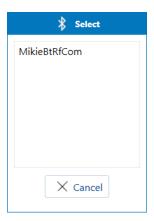
Settings

Click on the Settings icon





If you click on the *Pair* button you will get a list of non-paired devices. Clicking on the *Unpair* button will bring up a list of paired devices.



Clicking on a selection will bring up a decision dialog to determine whether to continue the operation. Note that the selection dialog for unpaired devices takes some time to load as it scans for any available device



The title shows you if you are going to pair or unpair a device. The name of the device is posted next, the *Continue* message. Clicking on Yes will complete the operation.

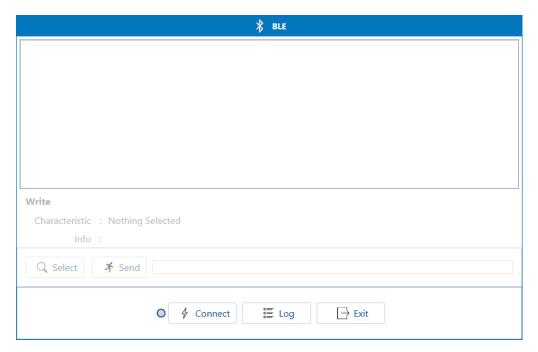
When pairing you enter your PIN



BLE Run Page (Bluetooth Low Energy)

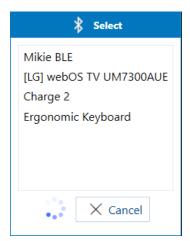
Select BLE from the menu



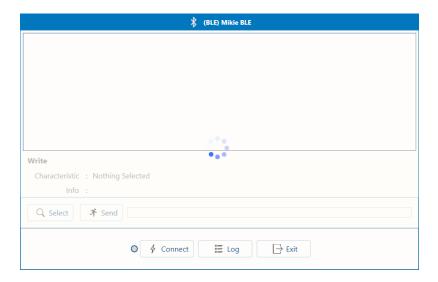


This page format differs from the other device pages. You can read and write values to and from a BLE device. See the appendix for a BLE Arduino sample

Click on Connect o bring up the selection dialog.



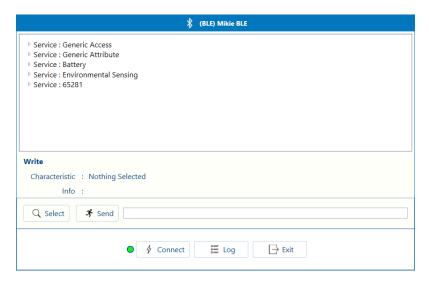
The busy spinner shows on the left of the Cancel button. It will disappear when the scan is completed. Or you can select any device showing on the list at any time to stop the scan and go back to the view page.



The spinner will show on the view page while the connection is completed, and all the services are loaded.

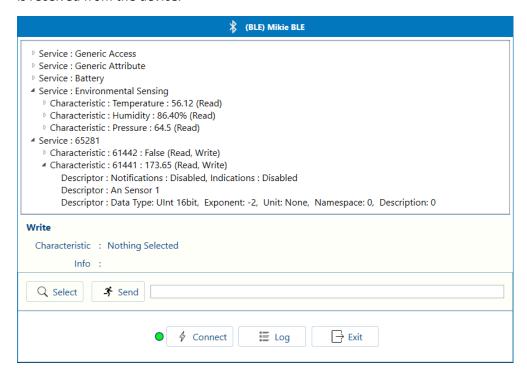
It is possible to get an error when loading the services and their characteristics. Trying again will often work.



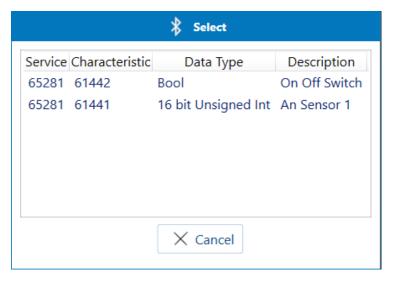


On successful completion you will get a tree of Services -> Characteristics -> Descriptors. You can drill down to look at the contents

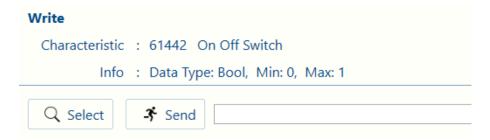
The App will subscribe to all Characteristics that allow Notifications. The display will show the data as it is received from the device.



If you have Write enabled characteristics on the device, the Write section will be enabled. Click on the *Select* button to see a list a Write enabled characteristics.

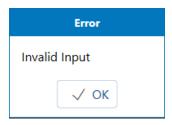


Select the characteristic that you want to send data to. The dialog will close, and the information will be transferred to the BLE window.



In this example a Bool data type was selected. The characteristic name, description, data type, allowable value range are displayed. Enter text in the send box and click send

If you attempt to send a value out of range, you will get an error



If the value is valid you will not be prompted

Special Note

You will need a forked version of the ArduinoBLE library if you want it to work with Windows or Android. See link in sample

WIFI Run Page

Click on WIFI on the menu

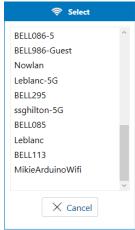


WIFI

It will bring up the run page. General functionality of the run page is explained above.

Clicking on the Discover button (or info Icon if nothing yet selected) will bring up the Select dialog for WIFI devices. This can take some time as it is scanning all the available WIFI connections.





Selecting a connection will close the dialog and set the selection on the run page.



Info

Click on the info icon





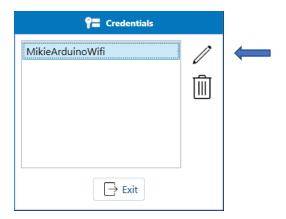
Settings

Click on the Settings icon

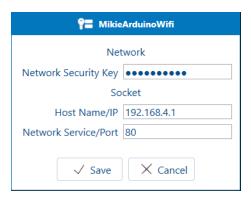




The Credentials dialog provides a way to edit or delete credentials and connection parameters for a previous WIFI connection. You can only add to the credentials list when you attempt a new connection. To edit or delete a credential highlight one of them



Click on the *Edit* icon to open the editor. The list has the SSID of the WIFI



The security key is the password for the WIFI access point (like a router). The Host name/IP or those that you have exposed on your embedded device. See the Arduino WIFI code sample in the appendix.

Click on Save to store your changes, or cancel to discard

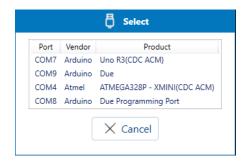
USB Run Page

Click on the USB menu item



It will bring up the run page. General functionality of the run page is explained above.

Clicking on the Discover button (or info Icon if nothing yet selected) will bring up the Select dialog for USB devices.



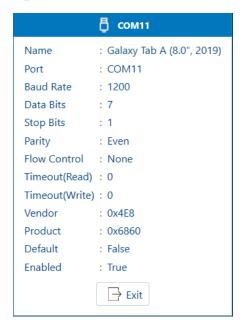
Selecting a device will set it as the device to connect to. Its name will be posted on the title bar. NOTE: There is a bug at the OS level which sometimes gives the incorrect name for the device.



Info

Click on the info icon

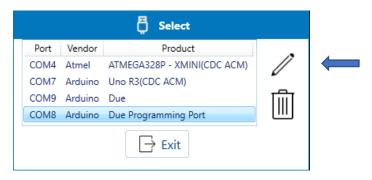




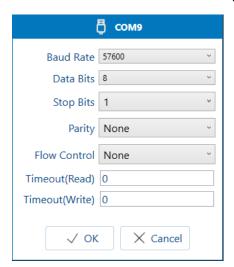
Settings

Click on the Settings icon





This is a list of the current devices. Highlight one and click on the edit icon.



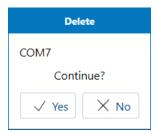
The configuration which comes up is either in the stored list of configurations or the default that the device presents.

This will have the configuration information based on what was harvested from the serial connection and any changes you made on first connection. Since there is no feedback if you have wrong settings, you may need to come back here to correct them. You must enter the settings that the embedded device is expecting. Look at the Arduino code sample for serial.

Change the settings and click OK to save. This is what will be used to connect. Note: The lookup is based on COM port and name, so if a different device of same name is connected to the same COM port you will have to change the settings to match those of the embedded device.

This will have the configuration information based on what was harvested from the serial connection and any changes you made on first connection. Since there is no feedback if you have wrong settings, you may need to come back here to correct them. You must enter the settings that the embedded device is expecting. Look at the Arduino code sample for serial.

If you click on the delete button you are presented with a confirmation dialog.



Click on Yes to delete it, No to exit without changes.

Of special note:

The Timeout values (milliseconds) should be set low so that the read and write will not stall before sending up accumulated bytes up the stack

Unless an error dialog comes up you should be ready to send and receive messages. You will not have to enter this information again

Note: The serial port does not return an error if your settings are not what is expected at the embedded device. In that case you will have to return to the Menu->USB Settings->Edit to change them.

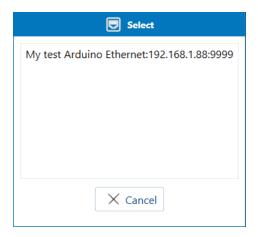
Ethernet Run Page (TBD)

Click on the menu item



It will bring up the run page. General functionality of the run page is explained above.

Clicking on the Discover button (or info Icon if nothing yet selected) will bring up the Select dialog for Ethernet connections. If there are none, you will be able to create a new one on first connection to a network. Ethernet does not provide the possibility of scanning for connections so you will need to know the IP address and port of your embedded device.



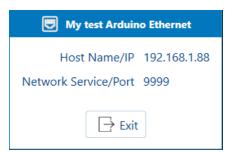
Selecting it will set the title bar to the connection



Info

Click on the info icon



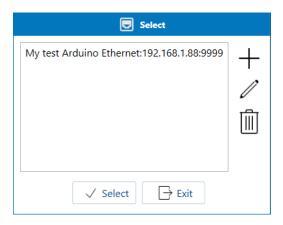


This will give you some basic information on the selected connection

Settings

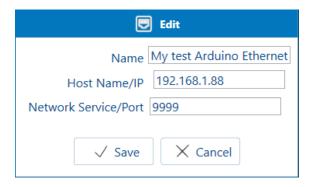
Click on the Settings icon





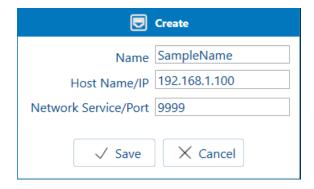
You can edit or delete any stored connection settings.

Click on the Edit icon to bring up the edit dialog



Modify entries and click on Save to store

Click on the Add icon to create a new Ethernet connection



Enter the information and click on Save to store the information

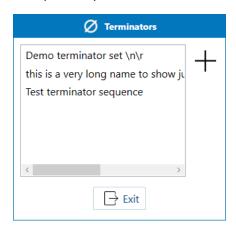
Terminators

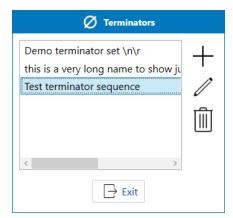
Ø Terminators

Clicking on this brings up a dialog box with currently stored terminator sequence.

- A terminator sequence contains one or more nonprintable characters that are added to the end of the outgoing message.
- The embedded device must be expecting that sequence to determine when an incoming message is complete.
- The embedded device must also all those terminators to its outgoing messages since the App is expecting those to determine when the incoming message is complete

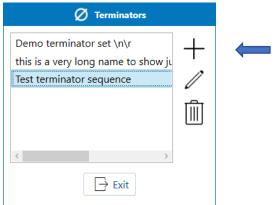
On Open, only the Add button is visible.



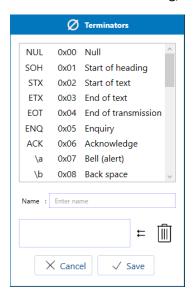


When you select a terminator set, the edit and delete button will appear.

Adding a terminator sequence set



In the Terminator set dialog, click on the Add button and a Dialog appears to create a new set



Enter the name identify the set in the future. Click on any terminator in the list and it will be added to the sequence. You must do these in the sequence that is expected on the embedded device.



The result after you have clicked on form feed, then line feed.

Click on the delete icon to remove the last one in the sequence.

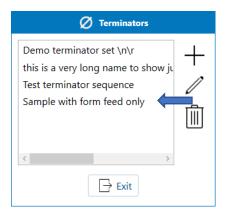


The result after clicking on the delete icon once

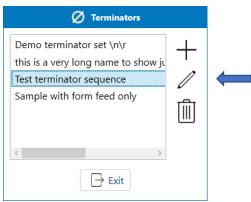
Make sure you enter a name then click on Save

Name : Sample with form feed only \f

Your new terminator set is now stored



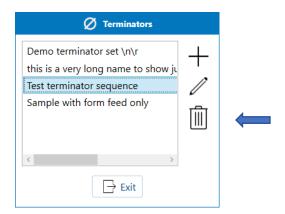
Edit Terminator set



Select the set to edit and click on the Edit icon. Same process for adding a new one

Deleting a Terminator set

At the Terminator set list dialog, select a set, and click on the *Delete* icon



You will be given the choice to delete or cancel

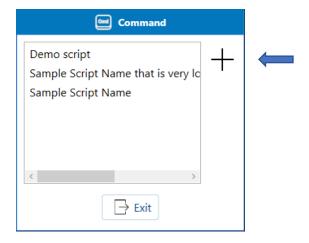


Commands



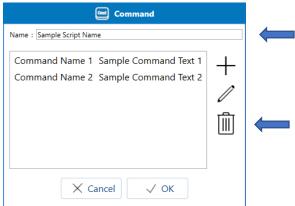
Click on the command menu item

The Commands list displays a set of existing command sets that are stored.

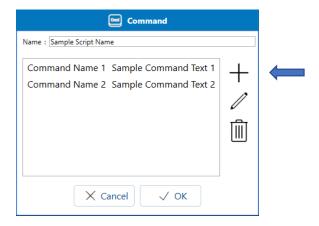


To add a new Command set, click on the Add button or select an existing to bring up more options.

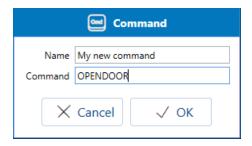
Adding a command list



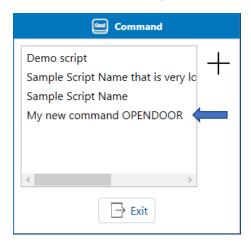
Edit the name. Edit the commands or select them and click on the Delete icon.



Click on the Add icon to create a new command



Enter the name that will be displayed for this command. It will show up on the list. The Command text (message) is what is sent to the embedded device. It must be exactly what the device is expecting. Terminators are added apart from this text. Select *Ok* to add the command



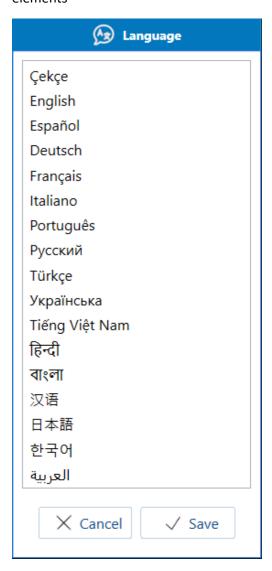
The new command is added to the command set

To delete a command, highlight it and click on the Delete icon

Language



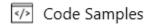
Clicking on this will bring up the Language selector. Currently there are 17 languages supported for UI elements



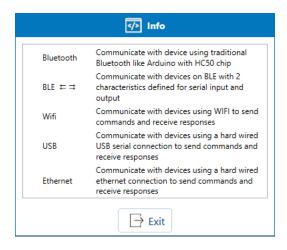
Highlight the requested language and you will see the language change on all open windows. Click Save to save that language as the current. It will be saved as your preference for future sessions. Click on Cancel to revert to previous language

Code Samples

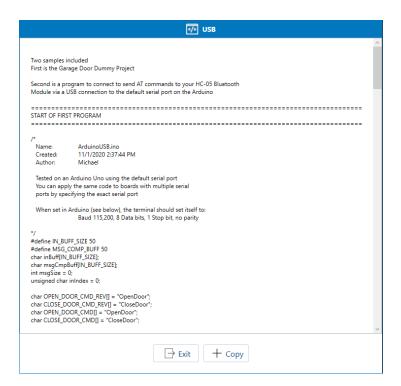
Select the menu item



The code sample list will pop up



Select any of the samples in the list to open the code sample



Scroll to view the code. Click on the copy button to copy the contents to the clipboard

Appendix

Introduction to Embedded Messaging

Your embedded device such as Arduinos may run code that can run without any outside input. However in some cases you may want to send commands remotely to, say, turn on an IO that trips a solenoid that starts to open a garage door.

On simple systems, messages are sent as a string made up of ASCII printable characters (0x41 to 0x7E). That would include punctuations and upper and lower characters. Non printable characters are reserved to specify message termination indicators (terminators)

In this application I have a list from 0x00 (NULL) to 0x1F (unit separator (down arrow)) that you can select as your terminators

So, a command sent to the embedded device to open the garage door might look like this:

OpenDoor\n\r.

The "OpenDoor" is the message, the " $\n\$ " is the terminator sequence. The $\n\$ (0x0A) is a new line character and the $\n\$ (0xoD) is a carriage return. The backslash is how those are typically inserted in C or C# string.

The App allows you to create a terminator sequence which it automatically adds to the message. You select that sequence based on how you programmed your device. On the flip side, the App expects that same terminator sequence on all message sent back to it.

The messages and terminator sequences you create are stored separately so you can mix and match at run time.

Arduino Bluetooth Sample

```
// Name: ArduinoBluetoothDataTests.ino
// Created: 12/12/2019 3:14:05 PM
// Author: Michael
//
// Sample to send and receive date to and from Arduino Bluetooth shield
//
// Written and tested in Visual Studio using Visual Micro
// Tested against Arduino Uno and itea Bluetooth shield with HC-05 module
// MUST HAVE BOARD TOGGLED TO DATA
// MUST HAVE BOARD JUMPERS SET FOLLOWING for IO4 TX and IO5 RX
// 00 | 000
// 000000
// MUST HAVE DEBUG SERIAL SET TO 9600 Baud
// MUST HAVE BT SERIAL SET TO 38400 Baud
// Must pair with Bluetooth first. The Multi Comm Terminal provides that
// functionality
```

```
#include <SoftwareSerial.h>
#ifndef SECTION DATA
int i = 0;
// The jumpers on BT board are set to 4TX and 5RX.
// They are reversed on serial since RX from BT gets TX to serial
SoftwareSerial btSerial(5, 4); //RX,TX
bool hasInput = false;
#define IN BUFF SIZE 100
char buff[IN BUFF SIZE];
unsigned char inIndex = 0;
#endif // !SECTION DATA
// the setup function runs once when you press reset or power the board
void setup() {
       // There is some strange behaviour when using different baud rates
      SetupCommunications (9600, 38400);
}
// the loop function runs over and over again until power down or reset
void loop() {
      ListenToBTData();
// Private helpers
void SetupCommunications(long dbgBaud, long btBaud) {
      btSerial.begin(btBaud);
      Serial.begin(dbgBaud);
      while (!Serial) {
             ; // wait for serial port to connect. Needed for Native USB only
      Serial.println("Debug serial active");
      // example had pin 9 set low, then high but does not seem necessary
}
void ListenToBTData() {
      if (btSerial.available() > 0) {
             if (inIndex >= IN BUFF SIZE) {
                    inIndex = \overline{0};
                    Serial.println("Corrupt BT input. Purge buffer");
             buff[inIndex] = (char)btSerial.read();
             if (buff[inIndex] == '\r') {
                    Serial.write("CR");
             }
             else if (buff[inIndex] == '\n') {
                    Serial.write("LN");
             else {
                    Serial.write(buff[inIndex]);
             }
             // Doing \n\r
             if (buff[inIndex] == '\r') {
                    Serial.println("Printing msg in buffer");
                    hasInput = true;
                    Serial.write(buff, inIndex + 1);
                    btSerial.write(buff, inIndex + 1);
```

```
memset(buff, 0, IN_BUFF_SIZE);
                     inIndex = 0;
              else {
                     inIndex++;
                     // Wipe out buffer if too long
                     if (inIndex >= IN_BUFF_SIZE) {
    inIndex = 0;
                            Serial.println("Corrupt BT input. Purge buffer");
                     else {
              }
       else {
              if (hasInput) {
                     hasInput = false;
              if (i % 50 == 0) {
                     Serial.print("No BT msg # ");
                     Serial.print((i / 10));
                     Serial.println("");
              i++;
              delay(100);
       }
}
```

Arduino BLE Sample

Arduino code partialy based on:

```
Name:
           DemoArduinoBLE.ino
 Created: Jan 15, 2021
  Sets up the BLE to have characteristics that change value in real time.
       Battery Level // 0x180F Defined in BLE Spec
                           // 0x2A6E
      Temperature
      Humidity
                           // 0x2A6F
                           // 0x2A6D
      Pressure
      Custom
                       // My Uuid 0xF001 - has format descriptor for parsing - supports
Write
       Bool on/Off switch // My Uuid 0xF002 - has format descriptor for parsing -
supports Write
      Here is a partial list of BLE Format data types for the Format Descriptor. Some
are
       not yet supported. Those will be displayed as a series of bytes
       Boolean = 1
       UInt_2bit = 2
        UInt 4bit = 3
        UInt 8bit = 4
        UInt_12bit = 5
        UInt_16bit = 6
        UInt_24bit = 7
        UInt_32bit = 8
        UInt_48bit = 9
        UInt_64bit = 10
        UInt_128bit = 11 ** Not supported **
        Int 8bit = 12
        Int_12bit = 13
        Int_16bit = 14
        Int_24bit = 15
        Int_32bit = 16
        Int 48bit = 17
        Int 64bit = 18
        Int_128bit = 19 ** Not supported **
        IEEE_754_32bit_floating_point = 20
        IEEE_754_64bit_floating_point = 21
        IEEE_11073_16bit_SFLOAT = 22 ** Not supported **
        IEEE_11073_32bit_FLOAT = 23 ** Not supported **
        IEEE_20601_format = 24 ** Not supported **
        UTF8_String = 25
        UTF16_String = 26
             OpaqueStructure = 27 ** Not supported **
  For this to work you need the forked version of ArduinoBLE
  which supports connection to Windows and Android
  https://github.com/unknownconstant/ArduinoBLE
  Tested on Arduino Uno WIFI Rev 2
```

```
https://programmaticponderings.com/2020/08/04/getting-started-with-bluetooth-low-
energy-ble-and-generic-attribute-profile-gatt-specification-for-iot/
  With some modifications.
 Values are generated internally for demo instead or reading I/O
#include <ArduinoBLE.h>
#include <string.h>
// Variables
const int GENERIC ACCESS APPEARANCE ID = 1792; // BLE Spec 0x1792
// Create battery service
BLEService batteryService("180F");
BLETypedCharacteristic<uint8 t> batteryLevelCharacteristic("2A19", BLERead | BLENotify);
// Environment sensing service
BLEService environmentService("181A");
BLETypedCharacteristic<uint32 t> pressureCharacteristic("2A6D", BLERead | BLENotify);
BLETypedCharacteristic<int16_t> tempCharacteristic("2A6E", BLERead | BLENotify);
BLETypedCharacteristic<uint16_t> humidCharacteristic("2A6F", BLERead | BLENotify);
// Custom 2 byte sensor service
BLEService ioService("FF01");
BLETypedCharacteristic<uint16 t> analogSensorCharacteristic("F001", BLERead | BLENotify |
BLEWrite);
BLEDescriptor sensorDescriptorUserDescription("2901", "An Sensor 1"); // Defined in Spec
uint8 t format[7] = {
                    // Data type. BLE spec 6 = uint16 t. Defines size of data in
      0x6,
characteristic read
                    // Exponent -2 sbyte. stored as byte. parsed out as sbyte to
       (byte)-2,
maintain sign
                    // Measurement uint16_t. 0 is unit-less. Adds abbreviation on
      0x0, 0x0 ,
display string
                    // Namespace byte. 0 is undefined, 1 is BLE Sig (only one defined in
      0x0,
spec)
                    // Description uint
      0x0, 0x0
// BLE spec 0x2904 is the Format Descriptor
BLEDescriptor sensorDescriptorFormat("2904", format, sizeof(format));
// Custom bool onOff sensor
BLEDescriptor onOffDescriptorUserDescription("2901", "On Off Switch"); // Defined in Spec
BLEBooleanCharacteristic onOffCharacteristic("F002", BLERead | BLENotify | BLEWrite);
uint8 t onOffData[]{ 0x01,0x0, 0x0,0x0, 0x0,0x0, 0x0 };
BLEDescriptor onOffDataDesc("2904", onOffData, sizeof(onOffData));
// Track dummy values
uint8 t batteryLevel = 93;
int16 t tempLevel = 3392;
uint16 t humidityLevl = 4400;
uint32 t pressureLevel = 28500;
uint16 t analogLevel = 16025;
byte isOn = 1; // On by default
```

```
unsigned long lasMsTimeUpdate = 0;
bool upIncrement = true;
// Main Arduino functions
// the setup function runs once when you press reset or power the board
void setup() {
      Serial.begin(9600);
      while (!Serial) {}
      Serial.println("started...");
      SetupBLE();
}
// the loop function runs over and over again forever
void loop() {
      BLEDevice central = BLE.central();
      if (central) {
             while (central.connected()) {
                    WriteBatteryLevelOnMsInterval(2000);
                    delayMicroseconds(10);
             }
      }
}
//-----
// Other functions
void SetupBLE() {
      if (!BLE.begin()) {
             Serial.println("FAIL");
             while (1);
      }
      // Device
      BLE.setLocalName("Mikie BLE"); // visible in search
      BLE.setDeviceName("MR BLE Device");
      BLE.setAppearance(GENERIC ACCESS APPEARANCE ID);
      BLE.setEventHandler(BLEConnected, bleOnConnectHandler);
      BLE.setEventHandler(BLEDisconnected, bleOnDisconnectHandler);
      // Battery service
      batteryService.addCharacteristic(batteryLevelCharacteristic);
      BLE.addService(batteryService);
      BLE.setAdvertisedService(batteryService);
      // Environment sensing service with 3 characteristics
      environmentService.addCharacteristic(tempCharacteristic);
      environmentService.addCharacteristic(humidCharacteristic);
      environmentService.addCharacteristic(pressureCharacteristic);
      BLE.addService(environmentService);
      BLE.setAdvertisedService(environmentService);
      // My custom sensor service
      onOffCharacteristic.addDescriptor(onOffDataDesc);
      onOffCharacteristic.addDescriptor(onOffDescriptorUserDescription);
      onOffCharacteristic.setEventHandler(BLEWritten, onOffHandler);
      ioService.addCharacteristic(onOffCharacteristic);
      analogSensorCharacteristic.addDescriptor(sensorDescriptorUserDescription);
```

```
analogSensorCharacteristic.addDescriptor(sensorDescriptorFormat);
       analogSensorCharacteristic.setEventHandler(BLEWritten, uint16CustomWriteHandler);
       ioService.addCharacteristic(analogSensorCharacteristic);
       BLE.addService(ioService);
       BLE.setAdvertisedService(ioService);
       BLE.advertise();
      WriteValues();
       Serial.println("BLE started");
}
void WriteBatteryLevelOnMsInterval(unsigned long msInterval) {
       // Simulate reading of actual hardware sensors for demo
       unsigned long currentMs = millis();
       if ((currentMs - lasMsTimeUpdate) > msInterval) {
              lasMsTimeUpdate = currentMs;
              if (isOn) {
                     if (upIncrement) {
                            tempLevel += 111;
                            humidityLevl += 212;
                            pressureLevel += 18;
                            analogLevel += 67;
                            batteryLevel++;
                            if (batteryLevel > 99) {
                                   batteryLevel = 99;
                                   upIncrement = false;
                                   batteryLevel--;
                            }
                     else {
                            tempLevel -= 111;
                            humidityLevl -= 212;
                            pressureLevel -= 18;
                            analogLevel -= 67;
                            batteryLevel--;
                            if (batteryLevel < 85) {</pre>
                                   upIncrement = true;
                                   batteryLevel = 60;
                            }
                     WriteValues();
              }
       }
}
void ResetValues() {
       batteryLevel = 93;
       tempLevel = 3392;
       humidityLevl = 4400;
       pressureLevel = 285;
       analogLevel = 16025;
}
void WriteValues() {
```

```
batteryLevelCharacteristic.writeValue(batteryLevel);
      tempCharacteristic.writeValue(tempLevel);
      humidCharacteristic.writeValue(humidityLevl);
      pressureCharacteristic.writeValue(pressureLevel);
      analogSensorCharacteristic.writeValue(analogLevel);
      Serial.print("
                       Battery:"); Serial.println(batteryLevel);
      Serial.print("Temperature:"); Serial.println(tempLevel);
      Serial.print("
                      Pressure:"); Serial.println(pressureLevel);
      Serial.print(" Humidity:"); Serial.println(humidityLevl);
      Serial.print(" An sensor:"); Serial.println(analogLevel);
}
//-----
// Event handlers
void bleOnConnectHandler(BLEDevice central) {
      Serial.println("CONNECTED");
}
void bleOnDisconnectHandler(BLEDevice central) {
      Serial.println("DISCONNECTED");
      ResetValues();
}
void onOffHandler(BLEDevice central, BLECharacteristic characteristic) {
      isOn = characteristic.value()[0];
      Serial.print("OnOff:"); Serial.println(isOn);
}
void uint16CustomWriteHandler(BLEDevice central, BLECharacteristic characteristic) {
      memcpy(&analogLevel, characteristic.value(), sizeof(analogLevel));
      Serial.print("analogLevel:"); Serial.println(analogLevel);
}
```

Arduino WIFI Sample

```
// -----
// Name: TestArduinoWifi.ino
// Created: 10/16/2020 1:22:40 PM
// Author: Michael
11
// Tested on the Arduino UNO WIFI Rev2
//
// Sets up the board as a WIFI access point with a socket
// Initial example code found in:
// https://www.arduino.cc/en/Reference/WiFiNINABeginAP
// -----
#include <SPI.h>
#include <WiFiNINA.h>
#include "wifi_defines.h"
// -----
// The wifi_defines.h has the strings for the SSID and password
\ensuremath{//} Here are the contents
//
       #pragma once
//
//
      Must be 8 or more characters
//
      #define MY SSID "MikieArduinoWifi"
//
//
      Must be 8 or more characters
//
       #define MY PASS "1234567890"
//
char ssid[] = MY SSID;
char pwd[] = MY PASS;
int keyIndex = 0;
int status = WL IDLE STATUS;
int led = LED \overline{BUILTIN};
// Port 80 of socket usually used for HTTP - just using it as a entry
// The Multi Comm Terminal must enter whatever port number is set in
// the Arduino
WiFiServer server (80);
void setup() {
      // Serial is just to push data for debugging the Arduino code. Can be removed
      Serial.begin(57600);
      while(!Serial){}
      Serial.println("Serial started");
     pinMode(led, OUTPUT);
      // Check for the WiFi module:
      if (WiFi.status() == WL_NO_MODULE) {
            Serial.println("Communication with WiFi module failed!");
           // don't continue
           while (true);
      }
      String fv = WiFi.firmwareVersion();
      Serial.print("WIFI firmware version ");
      Serial.println(fv);
```

```
if (fv < WIFI FIRMWARE LATEST VERSION) {
             Serial.print("Version below ");
             Serial.println(WIFI FIRMWARE LATEST VERSION);
             Serial.println("Please upgrade the firmware");
      }
      // by default the local IP address of will be 192.168.4.1
      // you can override it with the following:
      // Whatever you choose will be the IP that you enter in
      // the Multi Comm Connection parameters
      // WiFi.config(IPAddress(10, 0, 0, 1));
       // Print the network name (SSID);
      Serial.print("Creating access point named: ");
      Serial.println(ssid);
      // Create access point
      status = WiFi.beginAP(ssid, pwd);
      if (status != WL AP LISTENING) {
             Serial.print("Status "); Serial.println(status);
             Serial.println("Access point creation failed");
             while (true) { }
      }
      delay(10000);
      server.begin();
      // you're connected now, so print out the status to the serial debug:
      printWifiStatus();
}
// the loop function runs over and over again until power down or reset
void loop() {
      // Print a message to debug if a device has connected or disconnected
      if (status != WiFi.status()) {
             status = WiFi.status();
             if (status == WL AP CONNECTED) {
                    Serial.println("Device connected to AP");
             else {
                    // Device has disconnected from AP. Back in listening mode
                    Serial.println("Device disconnected from AP");
             }
      ListenForClient();
}
// Determines if a client has connected a socket and sent a message
void ListenForClient() {
       //https://www.arduino.cc/en/Reference/WiFiNINABeginAP
      WiFiClient client = server.available();
      if (client) {
             Serial.println("Got a client connected new client");
             String currentLine = "";
             // Loop while the client's connected
             while (client.connected()) {
                    if (client.available()) {
                           // Read a byte
                           char c = client.read();
                           // Print character serial for debug
```

```
Serial.write(c);
                           // This will bounce each character through the socket
                          // The MultiCommMonitor will pick up the terminators and
                          // Display it as a return message
                          // In the real world, you would accumulate the bytes until
                          // the expected termintor sequence is detected.
                          // You would then
                          // - Look at the message
                          // - Determine operation requested
                          // - Do the operation
                          // - Optionaly, send back a response with expected
terminators
                           // See samples for BT Classic and BLE
                          client.print(c);
             // close the connection:
             client.stop();
             // Send a debug message
             Serial.println("client disconnected");
      }
void printWifiStatus() {
      // print the SSID of the network you're attached to:
      Serial.print("SSID: ");
      Serial.println(WiFi.SSID());
      // print your board's socket IP address:
      IPAddress ip = WiFi.localIP();
      Serial.print("IP Address: ");
      Serial.println(ip);
      // print the received signal strength:
      long rssi = WiFi.RSSI();
      Serial.print("signal strength (RSSI):");
      Serial.print(rssi);
      Serial.println(" dBm");
}
```

Arduino USB Sample

```
ArduinoUSB.ino
  Name:
  Created: 11/1/2020 2:37:44 PM
  Author: Michael
  Tested on an Arduino Uno using the default serial port
  You can apply the same code to boards with multiple serial
  ports by specifying the exact serial port
  When set in Arduino (see below), the terminal should set itself to:
             Baud 115,200, 8 Data bits, 1 Stop bit, no parity
*/
#define IN BUFF SIZE 50
#define MSG COMP BUFF 50
char inBuff[IN BUFF SIZE];
char msgCmpBuff[IN BUFF SIZE];
int msqSize = 0;
unsigned char inIndex = 0;
char OPEN DOOR CMD[] = "OpenDoor";
char CLOSE DOOR CMD[] = "CloseDoor";
int OPEN CMD LEN = 8;
int CLOSE_CMD_LEN = 9;
// the setup function runs once when you press reset or power the board
void setup() {
      // 115,200 Baud, 8 Data bits, no parity, 1 stop bit
      \ensuremath{//} The terminal should find those same parameters. If you do not set
      // it here, the values are not detected in the terminal
      Serial.begin(115200, SERIAL 8N1);
      while (!Serial) {
}
// the loop function runs over and over again until power down or reset
void loop() {
      ListenForData();
void ListenForData() {
      int available = Serial.available();
      if (available > 0) {
             msgSize = 0;
             // Error check to avoid overrun of buffer
             if ((inIndex + available) > IN BUFF SIZE) {
                    Serial.write("ERROR-PURGING INPUT\r\n");
                    inIndex = 0;
                    return;
             size t count = Serial.readBytes(&inBuff[inIndex], available);
             inIndex += count;
             for (int i = 0; i < inIndex; i++) {
```

```
// Make assumption that \n\ comming in so look for \ for end
                     if (i > 1) {
                           if (inBuff[i-1] == '\r' && inBuff[i] == '\n') {
                                  msqSize = i - 1;
                                  memset(msgCmpBuff, 0, MSG_COMP_BUFF);
memcpy(msgCmpBuff, inBuff, msgSize);
                                  memmove(inBuff , &inBuff[i + 1] , (inIndex + count) -
(msgSize + 2));
                                   inIndex -= msgSize + 2;
                                  memset(&inBuff[inIndex], 0, (IN BUFF SIZE -
inIndex));
                                  CompareForResponse(msgSize);
                            }
                     }
             }
       }
}
/// <summary>Compare the incoming message to carry out IO actions</summary>
/// <param name="msgSize">Size of the incoming message</param>
void CompareForResponse(int msgSize) {
       // Compare from start of buffer. Garbage at end of Command
       // and before terminator is ignored (OpenDoorlsdlfkdjdflj)
       if (strncmp(msgCmpBuff, OPEN DOOR CMD, OPEN CMD LEN) == 0) {
              Serial.write("OPENING\r\n");
             OpenGarageDoor();
       else if (strncmp(msgCmpBuff, CLOSE DOOR CMD, CLOSE CMD LEN) == 0) {
              Serial.write("CLOSING\r\n");
             CloseGarageDoor();
       else {
             Serial.write("NOT_HANDLED\r\n");
       }
}
void OpenGarageDoor() {
       // Do you IO stuff here to open the door
void CloseGarageDoor() {
       // Do you IO stuff here to close the door
```

```
Arduino USB Sample 2 for AT Commands
             ArduinoSerial BT AT Cmds.ino
Name:
             11/11/2020 1:08:41 PM
Created:
Author:
             Michael
To enable the Multi Comm Terminal to send AT commands to the
HC-05 module on an ITEA board
Module must be set to CMD via switch.
 If the module is software switched I will need to add
that in a command
Written and tested in Visual Studio using Visual Micro
Tested against Arduino Uno and ITEA Bluetooth shield with HC-05 module
MUST HAVE BOARD TOGGLED TO CMD
MUST HAVE BOARD JUMPERS SET FOLLOWING for IO4 TX and IO5 RX
 000 00
 00 | 000
 000000
MUST HAVE DEBUG SERIAL SET TO 9600 Baud
MUST HAVE BT SERIAL SET TO 38400 Baud
Command
                    Response
                                                Details
ΑT
                    +NAME:itead
AT+VERSION
                    +VERSION:hc01.comV2.1
AT+ADDR
                    +ADDR:2016:4:76101
AT+UART
                                                 Baud, data bits, stop bits
                    +UART:9600,0,0
AT+NAME=<param>
                                                Sets the module name
                    +NAME:<Param>
                                                Get the module name
AT+NAME?
AT+ORGL
                    OK
                                                Restore to defaults
AT+RESET
                    OK
                                                Reset
                                                (1=master, 0=client)
AT+ROLE
                    +ROLE:0
AT+PSWD
                    +PSWD:1234
                                                 (pairing PIN)
*/
#include <SoftwareSerial.h>
#define IN_BUFF_SIZE 100
char buff[IN_BUFF_SIZE];
// The jumpers on BT board are set to 4TX and 5RX.
// They are reversed on serial since RX from BT gets TX to serial
SoftwareSerial btSerial(5, 4); //RX,TX
// the setup function runs once when you press reset or power the board
void setup() {
    //Need 38400 for BT and 9600 for serial to send AT commands
    //strange because BT AT cmd shows BT baud is 9600.
   SetupCommunications(9600, 38400);
}
// the loop function runs over and over again until power down or reset
```

```
void loop() {
    int count = Serial.available();
    if (count > 0) {
        Serial.readBytes(buff, count);
        btSerial.write(buff, count);
    }
    count = btSerial.available();
    if (count > 0) {
        btSerial.readBytes(buff, count);
        Serial.write(buff, count);
    }
}
void SetupCommunications(long dbgBaud, long btBaud) {
    Serial.begin(dbgBaud);
    btSerial.begin(btBaud);
    while (!Serial) {
        ; // wait for default serial port to connect
    }
}
```

Arduino BLE Sample

```
Name:
          DemoArduinoBLE.ino
  Created: Jan 15, 2021
  Sets up the BLE to have characteristics that change value in real time.
       Battery Level // 0x180F Defined in BLE Spec
       Temperature
                          // 0x2A6E
      Humidity
                           // 0x2A6F
      Pressure
                           // 0x2A6D
                   // My Uuid 0xF001 - has format descriptor for parsing
   Custom
       a list of Format data types are found in user manual
  For this to work you need the forked version of ArduinoBLE
  which supports connection to Windows and Android
  https://github.com/unknownconstant/ArduinoBLE/tree/pairing
  Tested on Arduino Uno WIFI Rev 2
  Arduino code partialy based on:
  https://programmaticponderings.com/2020/08/04/getting-started-with-bluetooth-low-
energy-ble-and-generic-attribute-profile-gatt-specification-for-iot/
  With some modifications.
  Values are generated internally for demo instead or reading I/O
 */
#include <ArduinoBLE.h>
// Variables
const int GENERIC_ACCESS_APPEARANCE_ID = 1792; // BLE Spec 0x1792
// Create battery service
BLEService batteryService("180F");
BLETypedCharacteristic<uint8_t> batteryLevelCharacteristic("2A19", BLERead | BLENotify);
// Environment sensing service
BLEService environmentService("181A");
BLETypedCharacteristic<uint32_t> pressureCharacteristic("2A6D", BLERead | BLENotify);
BLETypedCharacteristic<int16_t> tempCharacteristic("2A6E", BLERead | BLENotify);
BLETypedCharacteristic<uint16_t> humidCharacteristic("2A6F", BLERead | BLENotify);
// Custom 2 byte sensor service
BLEService ioService("FF01");
BLETypedCharacteristic<uint16 t> analogSensorCharacteristic("F001", BLERead | BLENotify);
BLEDescriptor sensorDescriptorUserDescription("2901", "aSensor1"); // Defined in Spec
uint8_t format[7] = {
                    // Data type. BLE spec 6 = uint16 t. Defines size of data in
      0x6,
characteristic read
                   // Exponent -2 sbyte. stored as byte. parsed out as sbyte to
       (byte)-2,
maintain sign
      0x0, 0x0 ,
                    // Measurement uint16 t. 0 is unit-less. Adds abbreviation on
display string
```

```
0x0,
                 // Namespace byte. 0 is undefined, 1 is BLE Sig (only one defined in
spec)
                 // Description uint
     0x0, 0x0
};
// BLE spec 0x2904 is the Format Descriptor
BLEDescriptor senforDescriptorFormat("2904", format, sizeof(format));
// Track dummy values
uint8 t batteryLevel = 93;
int16_t tempLevel = 3392;
uint16_t humidityLev1 = 4400;
uint32 t pressureLevel = 28500;
uint16 t analogLevel = 16025;
unsigned long lasMsTimeUpdate = 0;
bool upIncrement = true;
//-----
//-----
// Main Arduino functions
// Executed once on power on or reset
void setup() {
     Serial.begin(9600);
     while (!Serial) {}
     Serial.println("started...");
     SetupBLE();
}
// the loop function runs over and over again forever
void loop() {
     BLEDevice central = BLE.central();
     if (central) {
           while (central.connected()) {
                 WriteBatteryLevelOnMsInterval(5000);
                 delayMicroseconds(10);
           }
     }
       -----
//-----
// Helper functions
void SetupBLE() {
     if (!BLE.begin()) {
           Serial.println("FAIL");
           while (1);
     }
     // Device
     BLE.setLocalName("Mikie BLE"); // visible in search
     BLE.setDeviceName("MR BLE Device");
     BLE.setAppearance(GENERIC ACCESS APPEARANCE ID);
     BLE.setEventHandler(BLEConnected, bleOnConnectHandler);
     BLE.setEventHandler(BLEDisconnected, bleOnDisconnectHandler);
     // Battery service
```

```
batteryService.addCharacteristic(batteryLevelCharacteristic);
       BLE.addService(batteryService);
       BLE.setAdvertisedService(batteryService);
       // Environment sensing service with 3 characteristics
       environmentService.addCharacteristic(tempCharacteristic);
       environmentService.addCharacteristic(humidCharacteristic);
       environmentService.addCharacteristic(pressureCharacteristic);
       BLE.addService(environmentService);
       BLE.setAdvertisedService(environmentService);
       // My custom sensor service
       analogSensorCharacteristic.addDescriptor(sensorDescriptorUserDescription);
       analogSensorCharacteristic.addDescriptor(senforDescriptorFormat);
       ioService.addCharacteristic(analogSensorCharacteristic);
       BLE.addService(ioService);
       BLE.setAdvertisedService(ioService);
       BLE.advertise();
       WriteValues();
       Serial.println("BLE started");
}
void WriteBatteryLevelOnMsInterval(unsigned long msInterval) {
       // Simulate reading of actual hardware sensors for demo
       unsigned long currentMs = millis();
       if ((currentMs - lasMsTimeUpdate) > msInterval) {
              lasMsTimeUpdate = currentMs;
              if (upIncrement) {
                     tempLevel += 111;
                     humidityLevl += 212;
                     pressureLevel += 18;
                     analogLevel += 67;
                     batteryLevel++;
                     if (batteryLevel > 99) {
                            batteryLevel = 99;
                            upIncrement = false;
                            batteryLevel--;
                     }
              else {
                     tempLevel -= 111;
                     humidityLevl -= 212;
                     pressureLevel -= 18;
                     analogLevel -= 67;
                     batteryLevel--;
                     if (batteryLevel < 85) {</pre>
                            upIncrement = true;
                            batteryLevel = 60;
                     }
              WriteValues();
       }
}
```

```
void ResetValues() {
      batteryLevel = 93;
      tempLevel = 3392;
      humidityLevl = 4400;
      pressureLevel = 285;
      analogLevel = 16025;
}
void WriteValues() {
      batteryLevelCharacteristic.writeValue(batteryLevel);
      tempCharacteristic.writeValue(tempLevel);
      humidCharacteristic.writeValue(humidityLevl);
      pressureCharacteristic.writeValue(pressureLevel);
      analogSensorCharacteristic.writeValue(analogLevel);
      Serial.print("
                      Battery:"); Serial.println(batteryLevel);
      Serial.print("Temperature:"); Serial.println(tempLevel);
      Serial.print(" Pressure:"); Serial.println(pressureLevel);
      Serial.print("
      Serial.print(" Humidity:"); Serial.println(humidityLevl);
Serial.print(" An sensor:"); Serial.println(analogLevel);
}
//-----
//-----
// Event handlers
// When a connection is established to device
void bleOnConnectHandler(BLEDevice central) {
      Serial.println("CONNECTED");
}
// When a connection to device is broken
void bleOnDisconnectHandler(BLEDevice central) {
      Serial.println("DISCONNECTED");
      ResetValues();
}
//-----
```