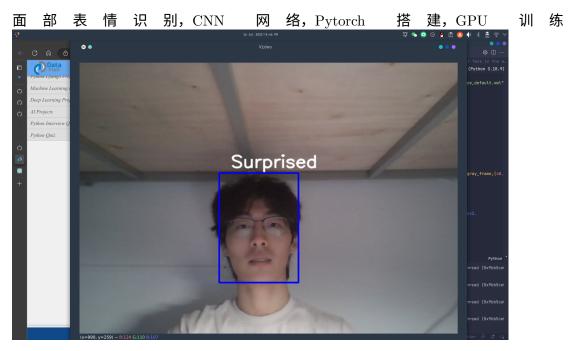
2_emojify 吴清柳

July 31, 2023

1 Facial Emotion Recognition using CNN



```
import cv2

from keras.models import Sequential
from keras.layers import Dense, Dropout, Flatten
from keras.layers import Conv2D
from keras.optimizers import Adam
from keras.layers import MaxPooling2D
from keras.preprocessing.image import ImageDataGenerator
```

2023-07-17 09:49:02.159971: I tensorflow/core/platform/cpu_feature_guard.cc:193] This TensorFlow binary is optimized with oneAPI Deep Neural Network Library (oneDNN) to use the following CPU instructions in performance-critical operations: SSE4.1 SSE4.2 AVX AVX2 FMA To enable them in other operations, rebuild TensorFlow with the appropriate compiler flags.

```
[3]: train_dir = "../dataset/train"
     val_dir = "../dataset/test"
     train_datagen = ImageDataGenerator(rescale=1.0 / 255)
     val_datagen = ImageDataGenerator(rescale=1.0 / 255)
     train_generator = train_datagen.flow_from_directory(
         train_dir,
         target_size=(48, 48),
         batch size=64,
         color_mode="grayscale",
         class_mode="categorical",
     validation_generator = val_datagen.flow_from_directory(
         val_dir,
         target_size=(48, 48),
         batch_size=64,
         color_mode="grayscale",
         class_mode='categorical'
     )
```

Found 28709 images belonging to 7 classes. Found 7178 images belonging to 7 classes.

```
[4]: # Build the CNN model
     # Layers in Sequential are stacked on top of each other
     emotion_model = Sequential()
     # 2D Conv layer with 32 filters of size 3x3. Input shape is (48,48,1), for
     # grayscale images of size 48x48.
     emotion_model.add(
         Conv2D(32, kernel_size=(3, 3), activation="relu", input_shape=(48, 48, 1))
     )
     emotion_model.add(Conv2D(64, kernel_size=(3, 3), activation="relu"))
     emotion_model.add(MaxPooling2D(pool_size=(2, 2)))
     emotion_model.add(Dropout(0.25))
     emotion_model.add(Conv2D(128, kernel_size=(3, 3), activation="relu"))
     emotion_model.add(MaxPooling2D(pool_size=(2, 2)))
     emotion_model.add(Conv2D(128, kernel_size=(3, 3), activation="relu"))
     emotion_model.add(MaxPooling2D(pool_size=(2, 2)))
     emotion_model.add(Dropout(0.25))
     emotion_model.add(Flatten())
     emotion_model.add(Dense(1024, activation="relu"))
     emotion_model.add(Dropout(0.25))
     emotion_model.add(Dense(7, activation="softmax"))
```

2023-07-17 09:49:07.924673: I

```
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.949355: I
tensorflow/compiler/xla/stream executor/cuda/cuda gpu executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.949664: I
tensorflow/compiler/xla/stream executor/cuda/cuda gpu executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.950856: I tensorflow/core/platform/cpu_feature_guard.cc:193]
This TensorFlow binary is optimized with oneAPI Deep Neural Network Library
(oneDNN) to use the following CPU instructions in performance-critical
operations: SSE4.1 SSE4.2 AVX AVX2 FMA
To enable them in other operations, rebuild TensorFlow with the appropriate
compiler flags.
2023-07-17 09:49:07.951713: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.951954: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.952102: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.997469: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.997661: I
tensorflow/compiler/xla/stream executor/cuda/cuda gpu executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.997796: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:981]
successful NUMA node read from SysFS had negative value (-1), but there must be
at least one NUMA node, so returning NUMA node zero
2023-07-17 09:49:07.997888: I
tensorflow/core/common_runtime/gpu/gpu_device.cc:1613] Created device
/job:localhost/replica:0/task:0/device:GPU:0 with 4279 MB memory: -> device: 0,
name: NVIDIA GeForce RTX 3060 Laptop GPU, pci bus id: 0000:01:00.0, compute
capability: 8.6
```

```
[5]: # Train the model
    emotion_model.compile(
       loss="categorical_crossentropy",
       optimizer=Adam(learning_rate=0.0001, decay=1e-6),
       metrics=["accuracy"],
    emotion_model_info = emotion_model.fit_generator(
       train_generator,
       steps_per_epoch=28709 // 64,
       epochs=50,
       validation data=validation generator,
       validation_steps=7178 // 64,
   Epoch 1/50
   /tmp/ipykernel_3283901/729160076.py:7: UserWarning: `Model.fit_generator` is
   deprecated and will be removed in a future version. Please use `Model.fit`,
   which supports generators.
     emotion_model_info = emotion_model.fit_generator(
   2023-07-17 09:49:11.474218: E
   tensorflow/core/grappler/optimizers/meta_optimizer.cc:954] layout failed:
   INVALID_ARGUMENT: Size of values 0 does not match size of permutation 4 @ fanin
   shape insequential/dropout/dropout/SelectV2-2-TransposeNHWCToNCHW-
   LayoutOptimizer
   2023-07-17 09:49:11.595667: I
   tensorflow/compiler/xla/stream_executor/cuda/cuda_dnn.cc:428] Loaded cuDNN
   version 8800
   2023-07-17 09:49:12.058971: I
   tensorflow/compiler/xla/stream executor/cuda/cuda blas.cc:630] TensorFloat-32
   will be used for the matrix multiplication. This will only be logged once.
   accuracy: 0.2728 - val_loss: 1.6283 - val_accuracy: 0.3758
   Epoch 2/50
   448/448 [============= ] - 6s 14ms/step - loss: 1.5656 -
   accuracy: 0.3932 - val_loss: 1.5067 - val_accuracy: 0.4210
   Epoch 3/50
   accuracy: 0.4454 - val_loss: 1.4125 - val_accuracy: 0.4636
   accuracy: 0.4788 - val_loss: 1.3264 - val_accuracy: 0.5008
   accuracy: 0.5021 - val_loss: 1.2807 - val_accuracy: 0.5138
   Epoch 6/50
   accuracy: 0.5229 - val_loss: 1.2504 - val_accuracy: 0.5229
```

```
Epoch 7/50
accuracy: 0.5398 - val_loss: 1.2287 - val_accuracy: 0.5306
accuracy: 0.5546 - val_loss: 1.1861 - val_accuracy: 0.5467
accuracy: 0.5652 - val_loss: 1.1785 - val_accuracy: 0.5587
Epoch 10/50
accuracy: 0.5763 - val_loss: 1.1546 - val_accuracy: 0.5621
Epoch 11/50
448/448 [============ ] - 6s 14ms/step - loss: 1.0971 -
accuracy: 0.5899 - val_loss: 1.1342 - val_accuracy: 0.5692
Epoch 12/50
accuracy: 0.6007 - val_loss: 1.1243 - val_accuracy: 0.5752
Epoch 13/50
accuracy: 0.6093 - val_loss: 1.1206 - val_accuracy: 0.5752
Epoch 14/50
accuracy: 0.6238 - val_loss: 1.1092 - val_accuracy: 0.5845
Epoch 15/50
accuracy: 0.6344 - val_loss: 1.1015 - val_accuracy: 0.5830
Epoch 16/50
448/448 [============ ] - 7s 14ms/step - loss: 0.9583 -
accuracy: 0.6470 - val_loss: 1.0874 - val_accuracy: 0.5932
Epoch 17/50
accuracy: 0.6563 - val_loss: 1.0878 - val_accuracy: 0.5961
Epoch 18/50
accuracy: 0.6670 - val_loss: 1.0768 - val_accuracy: 0.6014
Epoch 19/50
accuracy: 0.6793 - val_loss: 1.0733 - val_accuracy: 0.6060
Epoch 20/50
accuracy: 0.6919 - val_loss: 1.0764 - val_accuracy: 0.6063
448/448 [============ ] - 7s 15ms/step - loss: 0.8162 -
accuracy: 0.6991 - val_loss: 1.0786 - val_accuracy: 0.6098
Epoch 22/50
accuracy: 0.7159 - val_loss: 1.0843 - val_accuracy: 0.6060
```

```
Epoch 23/50
accuracy: 0.7267 - val_loss: 1.0808 - val_accuracy: 0.6087
Epoch 24/50
accuracy: 0.7398 - val_loss: 1.0977 - val_accuracy: 0.6105
accuracy: 0.7495 - val_loss: 1.0835 - val_accuracy: 0.6140
Epoch 26/50
accuracy: 0.7638 - val_loss: 1.0951 - val_accuracy: 0.6151
Epoch 27/50
accuracy: 0.7723 - val_loss: 1.1041 - val_accuracy: 0.6129
Epoch 28/50
accuracy: 0.7843 - val_loss: 1.1255 - val_accuracy: 0.6187
Epoch 29/50
448/448 [============== ] - 6s 14ms/step - loss: 0.5709 -
accuracy: 0.7946 - val_loss: 1.1197 - val_accuracy: 0.6225
Epoch 30/50
accuracy: 0.8023 - val_loss: 1.1368 - val_accuracy: 0.6205
Epoch 31/50
accuracy: 0.8163 - val_loss: 1.1554 - val_accuracy: 0.6200
Epoch 32/50
448/448 [============ ] - 6s 14ms/step - loss: 0.4888 -
accuracy: 0.8250 - val_loss: 1.1744 - val_accuracy: 0.6164
Epoch 33/50
accuracy: 0.8356 - val_loss: 1.1698 - val_accuracy: 0.6190
Epoch 34/50
accuracy: 0.8418 - val_loss: 1.1938 - val_accuracy: 0.6207
Epoch 35/50
accuracy: 0.8520 - val_loss: 1.2137 - val_accuracy: 0.6210
Epoch 36/50
accuracy: 0.8569 - val_loss: 1.2180 - val_accuracy: 0.6214
Epoch 37/50
448/448 [============ ] - 6s 14ms/step - loss: 0.3731 -
accuracy: 0.8687 - val_loss: 1.2565 - val_accuracy: 0.6198
Epoch 38/50
accuracy: 0.8725 - val_loss: 1.2841 - val_accuracy: 0.6250
```

```
accuracy: 0.8800 - val_loss: 1.2896 - val_accuracy: 0.6208
   Epoch 40/50
   accuracy: 0.8863 - val_loss: 1.3039 - val_accuracy: 0.6223
   Epoch 41/50
   accuracy: 0.8896 - val_loss: 1.3082 - val_accuracy: 0.6164
   Epoch 42/50
   accuracy: 0.8970 - val_loss: 1.3191 - val_accuracy: 0.6256
   Epoch 43/50
   accuracy: 0.9020 - val_loss: 1.3495 - val_accuracy: 0.6219
   Epoch 44/50
   accuracy: 0.9067 - val_loss: 1.3711 - val_accuracy: 0.6239
   Epoch 45/50
   accuracy: 0.9096 - val_loss: 1.4030 - val_accuracy: 0.6184
   Epoch 46/50
   accuracy: 0.9166 - val_loss: 1.3908 - val_accuracy: 0.6204
   Epoch 47/50
   accuracy: 0.9193 - val_loss: 1.4336 - val_accuracy: 0.6210
   Epoch 48/50
   448/448 [============ ] - 7s 16ms/step - loss: 0.2309 -
   accuracy: 0.9182 - val_loss: 1.4185 - val_accuracy: 0.6189
   Epoch 49/50
   accuracy: 0.9279 - val_loss: 1.4498 - val_accuracy: 0.6165
   Epoch 50/50
   accuracy: 0.9273 - val_loss: 1.4822 - val_accuracy: 0.6180
[6]: # save the model weigh
   import datetime
   emotion_model.save_weights(f'model-{datetime.date.today()}.h5')
[22]: # using OpenCV haarcascade xml detect the bounding boxes of face in the webcamu
    ⇔and predict the emotions
   cv2.ocl.setUseOpenCL(False)
   emotion_dict = {
     0: "Angry",
```

Epoch 39/50

```
1: "Disgusted",
    2: "Fearful",
    3: "Happy",
    4: "Neutral",
    5: "Sad",
    6: "Surprised",
}
cap = cv2.VideoCapture(0)
# load the cascade classifier before loop
haarcascade_path = cv2.data.haarcascades + "haarcascade_frontalface_default.xml"
bounding_box = cv2.CascadeClassifier(haarcascade_path)
while True:
    ret, frame = cap.read()
    if not ret:
        break
    gray_frame = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
    num_faces = bounding_box.detectMultiScale(
        gray_frame, scaleFactor=1.3, minNeighbors=5
    )
    for x, y, w, h in num_faces:
        cv2.rectangle(frame, (x, y - 50), (x + w, y + h + 10), (255, 0, 0), 2)
        roi_gray_frame = gray_frame[y : y + h, x : x + w]
        cropped_img = np.expand_dims(
            np.expand_dims(cv2.resize(roi_gray_frame, (48, 48)), -1), 0
        )
        emotion_prediction = emotion_model.predict(cropped_img)
        maxindex = int(np.argmax(emotion_prediction))
        cv2.putText(
            frame,
            emotion_dict[maxindex],
            (x + 20, y - 60),
            cv2.FONT_HERSHEY_SIMPLEX,
            (255, 255, 255),
            cv2.LINE_AA,
        )
    cv2.imshow(
        "Video", cv2.resize(frame, (1200, 860), interpolation=cv2.INTER CUBIC)
    if cv2.waitKey(1) & OxFF == ord("q"):
```

```
break
cap.release()
cv2.destroyAllWindows()
```

[WARN:002201.998] global cap_v41.cpp:982 open VIDEOIO(V4L2:/dev/video0): can't open camera by index

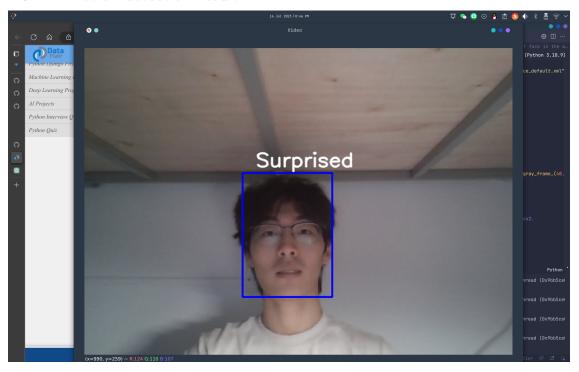
[ERROR:002201.998] global obsensor_uvc_stream_channel.cpp:156

getStreamChannelGroup Camera index out of range

[ERROR:0@2201.998] global persistence.cpp:512 open Can't open file:

 $\verb|'haarcascade_frontalface_default.xml| a read mode \\$

1.0.1 Emotion detection result



1.1 Code for GUI and mapping with emojis

save the emojis corresponding to each of the seven enotions in the dataset.

```
[23]: import tkinter as tk
  from tkinter import *
  import cv2
  from PIL import Image, ImageTk
  import os
  import numpy as np
  import cv2
  from keras.models import Sequential
  from keras.layers import Dense, Dropout, Flatten
```

```
from keras.layers import Conv2D
from keras.optimizers import Adam
from keras.layers import MaxPool2D
from keras.preprocessing.image import ImageDataGenerator
emotion_model = Sequential()
emotion_model.add(
   Conv2D(32, kernel_size=(3, 3), activation="relu", input_shape=(48, 48, 1))
)
emotion_model.add(Conv2D(64, kernel_size=(3, 3), activation="relu"))
emotion_model.add(MaxPooling2D(pool_size=(2, 2)))
emotion model.add(Dropout(0.25))
emotion_model.add(Conv2D(128, kernel_size=(3, 3), activation="relu"))
emotion_model.add(MaxPooling2D(pool_size=(2, 2)))
emotion_model.add(Conv2D(128, kernel_size=(3, 3), activation="relu"))
emotion_model.add(MaxPooling2D(pool_size=(2, 2)))
emotion_model.add(Dropout(0.25))
emotion_model.add(Flatten())
emotion_model.add(Dense(1024, activation="relu"))
emotion_model.add(Dropout(0.5))
emotion model.add(Dense(7, activation="softmax"))
emotion_model.load_weights("./model-2023-07-17.h5")
cv2.ocl.setUseOpenCL(False)
emotion dict = {
   0: " Angry
   1: "Disgusted",
   2: " Fearful ",
   3: " Happy
   4: " Neutral ".
   5: " Sad
   6: "Surprised",
}
emoji_dist = {
   0: "./emojis/angry.png",
   2: "./emojis/disgusted.png",
   2: "./emojis/fearful.png",
   3: "./emojis/happy.png",
   4: "./emojis/neutral.png",
   5: "./emojis/sad.png",
   6: "./emojis/surpriced.png",
global last_frame1
last_frame1 = np.zeros((480, 640, 3), dtype=np.uint8)
global cap1
show_text = [0]
```

```
def show_vid():
    cap1 = cv2.VideoCapture(0)
    if not cap1.isOpened():
        print("Cannot open the camera(0)")
    flag1, frame1 = cap1.read()
    frame1 = cv2.resize(frame1, (600, 500))
    haarcascade_path = (
        cv2.data.haarcascades + "haarcascade_frontalface_default.xml"
    bounding_box = cv2.CascadeClassifier(haarcascade_path)
    gray_frame = cv2.cvtColor(frame1, cv2.COLOR_BGR2GRAY)
    num_faces = bounding_box.detectMultiScale(
        gray_frame, scaleFactor=1.3, minNeighbors=5
    )
    for x, y, w, h in num_faces:
        cv2.rectangle(frame1, (x, y - 50), (x + w, y + h + 10), (255, 0, 0), 2)
        roi_gray_frame = gray_frame[y : y + h, x : x + w]
        cropped_img = np.expand_dims(
            np.expand_dims(cv2.resize(roi_gray_frame, (48, 48)), -1), 0
        prediction = emotion_model.predict(cropped_img)
        maxindex = int(np.argmax(prediction))
        cv2.putText(
            frame1,
            emotion_dict[maxindex],
            (x + 20, y - 60),
            cv2.FONT_HERSHEY_SIMPLEX,
            1,
            (255, 255, 255),
            cv2.LINE_AA,
        show_text[0] = maxindex
    if flag1 is None:
        print("Major error!")
    elif flag1:
        global last_frame1
        last_frame1 = frame1.copy()
        pic = cv2.cvtColor(last_frame1, cv2.COLOR_BGR2RGB)
        img = Image.fromarray(pic)
        imgtk = ImageTk.PhotoImage(image=img)
        lmain.imgtk = imgtk
        lmain.configure(image=imgtk)
```

```
lmain.after(10, show_vid)
    if cv2.waitKey(1) & OxFF == ord("q"):
        exit()
def show_vid2():
    frame2 = cv2.imread(emoji_dist[show_text[0]])
    pic2 = cv2.cvtColor(frame2, cv2.COLOR_BGR2RGB)
    img2 = Image.fromarray(frame2)
    imgtk2 = ImageTk.PhotoImage(image=img2)
    lmain2.imgtk2 = imgtk2
    lmain3.configure(
       text=emotion_dict[show_text[0]], font=("arial", 45, "bold")
    )
    lmain2.configure(image=imgtk2)
    lmain2.after(10, show_vid2)
if __name__ == "__main__":
   root = tk.Tk()
    # img = ImageTk.PhotoImage(Image.open("../dataset/test/happy/
 → PrivateTest_10077120.jpg"))
    # heading = Label(root, image=img, bg="black")
    # heading = Label(root, image=img, bg="black")
    # heading.pack()
    heading2 = Label(
        root,
        text="Photo to Emoji",
       pady=20,
        font=("arial", 45, "bold"),
       bg="black",
       fg="#CDCDCD",
    )
    heading2.pack()
    lmain = tk.Label(master=root, padx=50, bd=10)
    lmain2 = tk.Label(master=root, bd=10)
    lmain3 = tk.Label(master=root, bd=10, fg="#CDCDCD", bg="black")
    lmain.pack(side=LEFT)
    lmain.place(x=50, y=250)
    lmain3.pack()
    lmain3.place(x=960, y=250)
    lmain2.pack(side=RIGHT)
    lmain2.place(x=900, y=350)
```

```
root.title("Photo To Emoji")
root.geometry("1400x900+100+10")
root["bg"] = "black"
exitbutton = Button(
    root,
    text="Quit",
    fg="red",
    command=root.destroy,
    font=("arial", 25, "bold"),
).pack(side=BOTTOM)
show_vid()
show_vid2()
root.mainloop()
```

```
Cannot open the camera(0)
```

```
[ WARN:0043796.046] global cap_v4l.cpp:982 open VIDEOIO(V4L2:/dev/video0): can't open camera by index [ERROR:0043796.047] global obsensor_uvc_stream_channel.cpp:156 getStreamChannelGroup Camera index out of range
```

```
Traceback (most recent call last)
Cell In[23], line 160
    152 root["bg"] = "black"
    153 exitbutton = Button(
   154 root.
   155
          text="Quit",
   (...)
           font=("arial", 25, "bold"),
   158
    159 ).pack(side=BOTTOM)
--> 160 show_vid()
    161 show_vid2()
    162 root.mainloop()
Cell In[23], line 64, in show_vid()
           print("Cannot open the camera(0)")
     63 flag1, frame1 = cap1.read()
---> 64 frame1 = cv2.resize(frame1, (600, 500))
     66 haarcascade_path = (
     67
            cv2.data.haarcascades + "haarcascade_frontalface_default.xml"
     69 bounding_box = cv2.CascadeClassifier(haarcascade_path)
error: OpenCV(4.8.0) /io/opencv/modules/imgproc/src/resize.cpp:4062: error:
 ⇔(-215:Assertion failed) !ssize.empty() in function 'resize'
```