

# PVS Formalization of Model Checking Intermediate Language

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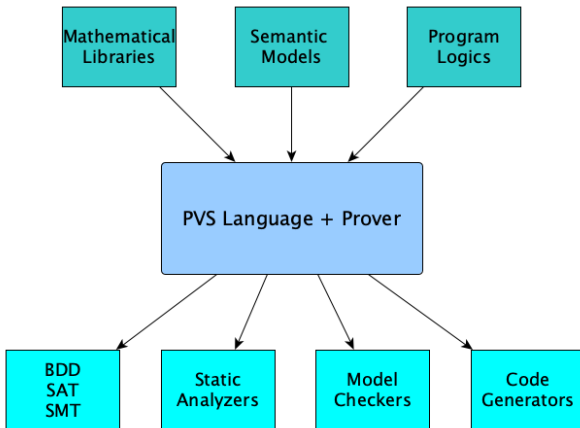
# Brief Introduction to PVS

- PVS is an interactive proof assistant based on higher-order logic developed at SRI over the last three decades.
- PVS is also a *research prototype* for exploring ideas in formalization, automation, interaction, proof maintenance, and library construction.
- The interactive theorem prover combines automation (using SMT and other decision procedures) with interaction using powerful and robust proof commands that can be combined within proof strategies.
- *Almost all of the specification language is safely executable as a functional language, with code generators for Common Lisp, Clean, C, and Rust (with an ML generator in progress).*
- PVS is a *single language and proof platform* spanning formalization from mathematical modeling to practical system development.



# PVS as an Interface Logic

- PVS blends an expressive specification language with an productive proof automation.
- It was essentially created as a semantic bridge between automated reasoning applications and automated tools.



# The PVS Language in Brief

- A PVS specification is a collection of libraries.
  - Each library is a collection of files.
  - Each file is a sequence of theories.
  - Each theory is a sequence of declarations/definitions of types, constants, and formulas (Boolean expressions).
- Types include
  - 1 Booleans, number types
  - 2 Predicate subtypes:  $\{x : T \mid p(x)\}$  for type  $T$  and predicate  $p$ .
  - 3 Dependent function  $[x : D \rightarrow R(x)]$ , tuple  $[x : T_1, T_2(x)]$ , and record  $[\#a : T_1, b : T_2(x)\#]$  types.
  - 4 (Dependent) algebraic/coalgebraic datatypes: lists, ordinals.
- Expressions in PVS are
  - 1 Booleans, numbers
  - 2 Application :  $f(a_1, \dots, a_n)$
  - 3 Abstraction :  $\lambda(x_1 : T_1, \dots, x_n : T_n) : a$
  - 4 Tuples:  $(a_1, \dots, a_n)$ ,  $a'3$
  - 5 Records:  $(\#l_1 := a_1, \dots, l_n := a_n\#)$ ,  $a'l_i$
  - 6 Conditionals: IF  $a_1$  THEN  $a_2$  ELSE  $a_3$  ENDIF
  - 7 Updates:  $a$  WITH  $[(3)'1'age := 37]$ .

# PVS Example: Summation

```
hsummation: THEORY
BEGIN
  i, m, n: VAR nat
  f: VAR [nat -> nat]

  hsum(f)(n): RECURSIVE nat =
    (IF n = 0 THEN 0 ELSE f(n - 1) + hsum(f)(n - 1) ENDIF)
    MEASURE n

  id(n): nat = n
  hsum_id: LEMMA hsum(id)(n + 1) = (n * (n + 1)) / 2

  square(n): nat = n * n
  sum_of_squares: LEMMA 6 * hsum(square)(n + 1) = n * (n + 1) * (2 * n + 1)

  cube(n): nat = n * n * n
  sum_of_cubes: LEMMA 4 * hsum(cube)(n + 1) = n * n * (n + 1) * (n + 1)

  quart(n): nat = square(square(n))
  sum_of_quarts: LEMMA
    hsum(quart)(n + 1) =
      ((6 * (n ^ 5)) + (15 * (n ^ 4)) + (10 * (n ^ 3)) - n) / 30
END hsummation
```

- A transition system is a triple  $\langle state, init, trans \rangle$  consisting of
  - A *state* type
  - An initialization predicate *init* on *state*
  - A transition relation *trans* on *state*
- This should be easily representable in PVS, so what's the problem?
- Transition systems/model checking was already integrated into PVS by 1994, with predicate abstraction added in 1997.
- However, writing transition systems directly in a specification logic can be painful.
- It is better to use the logic for semantic (deep or shallow) embedding of a transition system language.

The complications in describing transition systems arise from

- Frame conditions
- Open versus Closed Systems
- Modules, module reuse, and module (multi-)composition
- Deadlock: Does every (reachable) state have a successor?
- Input Enabledness: Can any input be accepted in any state?
- Fairness: Which infinite behaviors are acceptable?
- Nondeterminism: Modelling needs nondeterminism, but implementations are deterministic (modulo inputs)
- Bounded vs. unbounded state
- Synchronous Interaction: Moore vs. Mealy machines.
- Refinement: When are the behaviors of one model subsumed by those of another?

While these can all be elegantly captured in a logic, the design choices are best captured in a bespoke language.

- UNITY
- TLA
- I/O Automata
- Reactive Modules
- SAL
- SMV, NuXmv
- MCMT, used by SALLY and Cubicle.
- Synchronous languages like Lustre, Signal, and Esterel.



# Model Checking in PVS

CTL model checking was added to PVS in 1994/95.

```
ctlops[state : TYPE]: THEORY
BEGIN
  u,v,w: VAR state
  f,g,Q,P,p1,p2: VAR pred[state]
  Z: VAR pred[[state, state]]
  N: VAR [state, state -> bool]
  CONVERSION+ K_conversion

  EX(N,f)(u):bool = (EXISTS v: (f(v) AND N(u, v)))
  EG(N,f):pred[state] = nu(LAMBDA Q: (f AND EX(N,Q)))
  EU(N,f,g):pred[state] = mu(LAMBDA Q: (g OR (f AND EX(N,Q))))

  EF(N,f):pred[state] = EU(N, TRUE, f)
  AX(N,f):pred[state] = NOT EX(N, NOT f)
  AF(N,f):pred[state] = NOT EG(N, NOT f)
  AG(N,f):pred[state] = NOT EF(N, NOT f)
  AU(N,f,g):pred[state]
    = NOT EU(N, NOT g, (NOT f AND NOT g)) AND AF(N, g)

  CONVERSION- K_conversion
END ctlops
```

```
ltl [state: TYPE+] : THEORY

BEGIN

  ltlexpr: DATATYPE
  BEGIN
    atom(pred: [state -> bool]): atom?
    X(xarg: ltlexpr): X?
    LOR(orarg1, orarg2: ltlexpr): LOR?
    LNOT(notarg: ltlexpr): LNOT?
    G(garg: ltlexpr): G?
    U(uarg1, uarg2: ltlexpr): U?
  END ltlexpr

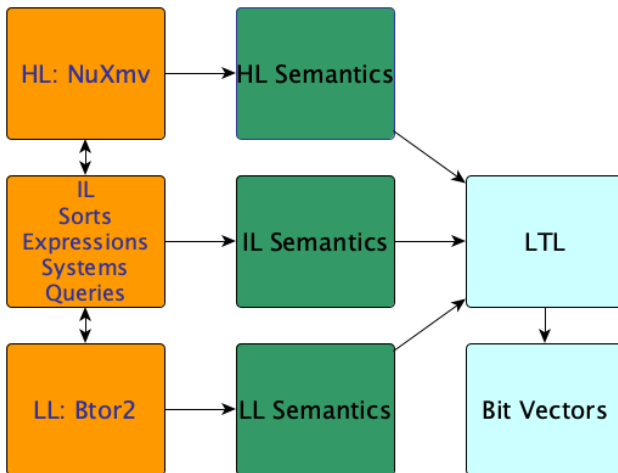
  ...
END ltl
```

```
s, s1, s2: VAR sequence[state]
A, B, C: VAR ltlexpr
p, q, r: VAR [state -> bool]
i, j, k: VAR nat

models(s, A): RECURSIVE bool =
  (CASES A OF
    atom(p): p(s(0)),
    X(B): models(suffix(s, 1), B),
    LOR(B, C): models(s, B) OR models(s, C),
    LNOT(B): NOT models(s, B),
    G(B): FORALL i: models(suffix(s, i), B),
    U(B, C): EXISTS i: models(suffix(s, i), C) AND
              FORALL (j: below(i)): models(suffix(s, j), B)
  ENDCASES)
MEASURE A BY <<
```

# Roadmap

The goal with IL is to create a syntactic/semantic bridge between high-level and low-level languages mapping problems and witnesses.



# Model Checking Intermediate Language

- The state of a system consists of its *input*  $\bar{i}$ , *local/state*  $\bar{s}$ , and *output* variables  $\bar{o}$  (with SMT-LIB sorts).
- Additional constraints can be imposed by invariants  $P(i, o, s)$  that must hold of every reachable state.
- A system is specified by an initialization predicate  $I(i, o, s)$  and a transition relation  $T(i, o, s, i', o', s')$ .

```
(define-system S
  :input ((i1 isort1) ... (im isortm))
  :output ((o1 osort1) ... (on osortn))
  :local ((s1 ssort1) ... (sp ssortp))
  :init (I1 ... Ih)
  :trans (T1 ... Tt)
  :inv (P1 ... Pr)
)
```

- Other commands can be used to declare/define new sorts and functions, and pose queries.

# Deep Embedding: The Sort Language

We define a *deep embedding* of the sort, expression, and system *syntax* and *semantics* in PVS.

```
ID: TYPE = nat

% An IL sort is a name, a Boolean, bit vector of length len,
% or an array from index to range.
ILSort: DATATYPE
BEGIN
  ILName(id: ID): ILName?
  ILBool: ILBool?
  ILBitVec(len: posnat): ILBitVec?
  ILArray(index: ILSort, range: ILSort): ILArray?
END ILSort
```

Examples: ILBool, ILName(3), ILBitVec(8),  
ILArray(ILBitvec(8), ILBool).

# Good Sort?

```
max_sort_id, m1, m2: VAR ID

% A good IL sort is one whose ids are all below the max sort id.
goodILSort?(max_sort_id)(S: ILSort): RECURSIVE bool =
  CASES S OF
    ILName(id): id < max_sort_id,
    ILArray(index, range): goodILSort?(max_sort_id)(index)
                          AND goodILSort?(max_sort_id)(range)
  ELSE TRUE
ENDCASES
MEASURE S BY <<
```

If `max_sort_id` is 8, then `ILName(8)` is not a good sort.

A sort context is finite, array-representable sequence of ILSorts.

```
ILSortCtx: TYPE = aseq[ILSort]

goodILSortCtx?(sort_ctx: ILSortCtx): bool =
  (FORALL (i: below(sort_ctx'length)):
    goodILSort?(i)(sort_ctx'seq(i)))

GoodILSortCtx: TYPE = (goodILSortCtx?)
```

A well-formed sort context is a finite sequence of sorts where each  $i$ 'th sort is well-formed relative to  $i$ .



# Syntax for a Bit-Vector Domain

The Bit-Vector domain admits types that are bit-vectors or spaces of maps between two types.

```
BitVecSyntax : THEORY

  BEGIN

    BitVecType: DATATYPE
    BEGIN
      BitVec(len: nat): BitVec?
      BVArray(dom, rng: BitVecType): BVArray?
    END BitVecType
  END BitVecSyntax
```

We need a domain in which to interpret ILSort.

```
BitVecSemantics : THEORY
BEGIN

  IMPORTING BitVecSyntax

  X, Y, Z: VAR BitVecType

  BitVecSem: DATATYPE
  BEGIN
    bv(len: nat, vector: bvec[len]): bv?
    barray(sequence: finseq[BitVecSem]): barray?
  END BitVecSem

  A, B, C: VAR BitVecSem
```

# Sort Semantics

Easy to map each ILSort to its BitVecType, except for ILName(id) (mapped by sort\_map) and ILBool (one-bit bit-vector).

```
ILSortSemMap(max_sort_id): TYPE = [below(max_sort_id)-> BitVecType]

ILSort2Sem(sort_ctx: GoodILSortCtx,
           max_sort_id : upto(sort_ctx'length),
           sort_map : ILSortSemMap(max_sort_id))
  (sort: GoodILSort(max_sort_id)): RECURSIVE BitVecType =
CASES sort OF
  ILName(id): sort_map(id),
  ILBool: BitVec(1),
  ILBitVec(len): BitVec(len),
  ILArray(index, range):
    BVArray(ILSort2Sem(sort_ctx, max_sort_id, sort_map)(index),
            ILSort2Sem(sort_ctx, max_sort_id, sort_map)(range))
ENDCASES
MEASURE sort BY <<
```

# Sort Context Semantics

A good sort context ensures that *each* sort is defined only in terms of *prior* sorts.

```
goodSortCtxSem?(sort_ctx: GoodILSortCtx)
    (sort_map : ILSortSemMap(sort_ctx'length))
  : bool =
  FORALL (i: below(sort_ctx'length)):
    ILSort2Sem(sort_ctx, i,
      restrict[below(sort_ctx'length), below(i), BitVecType]
        (sort_map))(sort_ctx'seq(i))
  = sort_map(i)

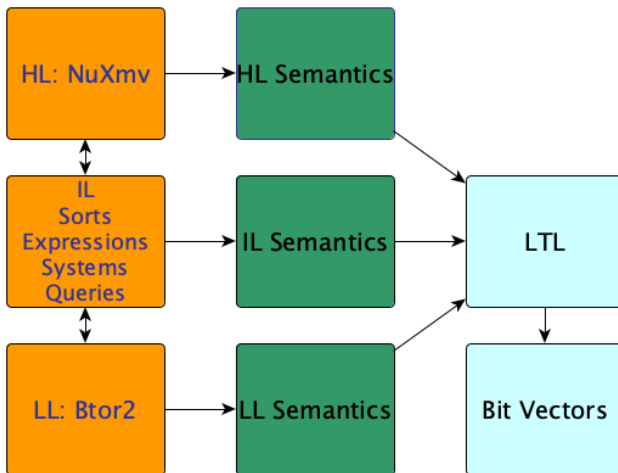
SortCtxSem(sort_ctx: GoodILSortCtx): TYPE
  = (goodSortCtxSem?(sort_ctx))
```

A few test cases:

```
test1_good_ILSort: bool =  
  goodILSort?(7)(ILName(8));  
test2_good_ILSort: bool =  
  goodILSort?(9)(ILArray(ILBitVec(8), ILName(8)));  
test3_good_ILSort: bool =  
  goodILSort?(0)(ILArray(ILBitVec(8), ILBitVec(8)))  
  
test1_goodILSortCtx: bool =  
  (LET ctx: ILSortCtx =  
    (# length := 3,  
     seq := [: ILArray(ILBitVec(8), ILBitVec(8)),  
              ILArray(ILBitVec(8), ILName(0)),  
              ILName(1) :] #)  
  IN goodILSortCtx?(ctx))
```

# Roadmap

The goal is to create a syntactic/semantic bridge between high-level and low-level languages mapping problems and witnesses.



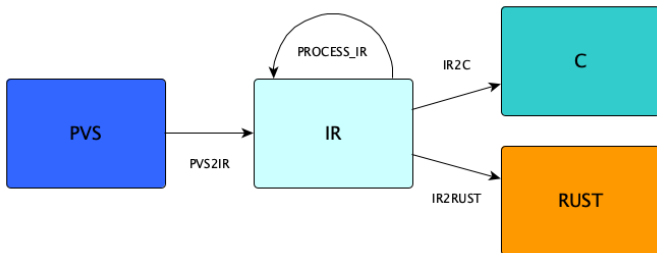
# PVS Formalization of Roadmap

- LTL2: Syntax/semantics of linear-time temporal logic with two-state predicates.
- ILExprSyntax: Defines IL expressions with an executable typechecker.
- ILExprSemantics: Defines BitVec semantics for IL expressions — need to prove type soundness.
- ILSystemSyntax: Processes IL commands (define/declare sorts, functions, systems) to build context, and IL queries.
- ILSystemSemantics (under development): LTL2 semantics for IL Systems.
- Btor2Syntax: Syntax of Btor2 nodes (sorts, expressions, systems, properties).
- Btor2Semantics: LTL2 semantics of Btor2
- IL2Btor2 (under development): Translation from IL to Btor2



# The PVS2C Code Generator

- PVS2C generates safe, efficient, standalone C code for a full functional fragment of PVS.
- Each PVS theory `foo.pvs` generates a `foo.h` and `foo.c`.<sup>1</sup>
- The translation is factored through an intermediate language that represents PVS expressions in A-normal form and performs a light static analysis to identify the *release points* for references.



<sup>1</sup>Férey, G., Sh., N.: Code Generation using a formal model of reference counting, NFM 2016. See also Wolfram Schulte, Deriving reference count garbage collectors, *6th International Symposium on Programming Language Implementation and Logic Programming*, 1994.



# PVS2C: From Theory to Practice

The full PVS2C implementation covers

- ➊ Multi-precision rational numbers and integers, and floats
- ➋ Fixed-size arithmetic: uint8, uint16, uint32, uint64, int8, int16, int32, int64, with safe casting
- ➌ Dependent (dynamically sized) and infinite arrays
- ➍ Dependent records and tuples
- ➎ Higher-order functions and closures (with updates)
- ➏ Characters (ASCII and Unicode) and strings
- ➐ Algebraic datatypes
- ➑ Parametric theories with type parameters (unboxed polymorphism)
- ➒ Memory-mapped File I/O
- ➓ Semantic attachments
- ➔ JSON representation for data

PVS2C captures a functional subset of PVS that is usable as a safe programming language - a well-typed program cannot fail (modulo resource limitations).



# Experiments in Code Generation: HMAC from Wikipedia

```
function hmac is
  input:
    key:      Bytes    // Array of bytes
    message:  Bytes    // Array of bytes to be hashed
    hash:     Function // The hash function to use (e.g. SHA-1)
    blockSize: Integer // The block size of the hash function
                                //(e.g. 64 bytes for SHA-1)
    outputSize: Integer // The output size of the hash function
                                //(e.g. 20 bytes for SHA-1)

  // Keys longer than blockSize are shortened by hashing them
  if (length(key) > blockSize) then
    key <- hash(key) // key is outputSize bytes long

  // Keys shorter than blockSize are padded to blockSize by padding
  //with zeros on the right
  if (length(key) < blockSize) then
    key <- Pad(key, blockSize) // Pad key with zeros to make it
                                // blockSize bytes long
  o_key_pad <- key xor [0x5c * blockSize] // Outer padded key
  i_key_pad <- key xor [0x36 * blockSize] // Inner padded key
  return hash(o_key_pad || hash(i_key_pad || message))
```

```
hmac(blockSize: uint8,  
  key : bytestring,  
  (message : bytestring |  
    message'length + blockSize < bytestring_bound),  
  outputSize: upto(blockSize),  
  hash: [bytestring->lbytes(outputSize)]: lbytes(outputSize)  
= LET newkey = IF length(key) > blockSize THEN hash(key) ELSE key ENDIF,  
  newerkey: lbytes(blockSize)  
  = IF length(newkey) < blockSize  
    THEN padright(blockSize)(newkey)  
    ELSE newerkey  
  ENDIF,  
  oKeyPad = lbytesXOR(blockSize)(newerkey, nbytes(0x5c, blockSize)),  
  iKeyPad = lbytesXOR(blockSize)(newerkey, nbytes(0x36, blockSize))  
IN hash(oKeyPad ++ hash(iKeyPad ++ message))  
  
hmac256((blockSize: uint8 | 32 <= blockSize),  
  key : bytestring,  
  (message : bytestring |  
    message'length + blockSize < bytestring_bound))  
: lbytes(32)  
= hmac(blockSize, key, message, 32, sha256message)
```

```
bytestrings__bytestring_t
HMAC__hmac256(uint8_t ivar_2, bytestrings__bytestring_t ivar_3,
              bytestrings__bytestring_t ivar_4){
    bytestrings__bytestring_t result;
    uint8_t ivar_18;
    ivar_18 = (uint8_t)32;
    HMAC_funtype_0_t ivar_19;
    HMAC_closure_3_t cl1230;
    cl1230 = new_HMAC_closure_3();
    ivar_19 = (HMAC_funtype_0_t)cl1230;
    bytestrings__bytestring_t ivar_14;
    ivar_14 = (bytestrings__bytestring_t)
HMAC__hmac((uint8_t)ivar_2, (bytestrings__bytestring_t)ivar_3,
           (bytestrings__bytestring_t)ivar_4, (uint8_t)ivar_18,
           (HMAC_funtype_0_t)ivar_19);
    //copying to bytestrings__bytestring
    //from bytestrings__bytestring;
    result = (bytestrings__bytestring_t)ivar_14;
    if (result != NULL) result->count++;
    release_bytestrings__bytestring(ivar_14);
    return result;
}
```

# Conclusions

- An expressive specification language like PVS is convenient for representing/automating the syntax and semantics of other formalisms
- Many embeddings have been done in this manner: TLA, B Method, Duration Calculus, Ag, CTL, LTL, I/O Automata, Differential Dynamic Logic, ...
- This offers some advantages compared to working directly with the semantics.
- PVS's proof automation can be applied to the embedded language at both the object level and the meta-level.
- Conversely, automation for the embedded language can be integrated with PVS.
- With safe/efficient code generation in the form of PVS2C, software for the embedded language can be written in PVS itself and proved correct.

