

# Introduction to

# Algorithm Design and Analysis

[13] Undirected Graph

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# In the last class ...

- **Directed Acyclic Graph**
  - Topological order
  - Critical path analysis
- **Strongly Connected Component (SCC)**
  - Strong connected component and condensation
  - Finding SCC based on DFS

# DFS on Undirected Graph

- **Undirected Graph**

- Symmetric Digraph
- Undirected Graph DFS Skeleton

- **Biconnected Components**

- Articulation Points
- Bridge

- **Other undirected graph problems**

- Orientation of an undirected graph
- Simplified Minimum Spanning Tree

# What is Different for “Undirected”

- Characteristics of undirected graph traversal
  - One edge may be traversed for **two times** in opposite directions.
- For an undirected graph, DFS provides an orientation for each of its edges
  - Oriented in the direction in which they are first encountered.

# Edges in DFS

- **Cross edge**

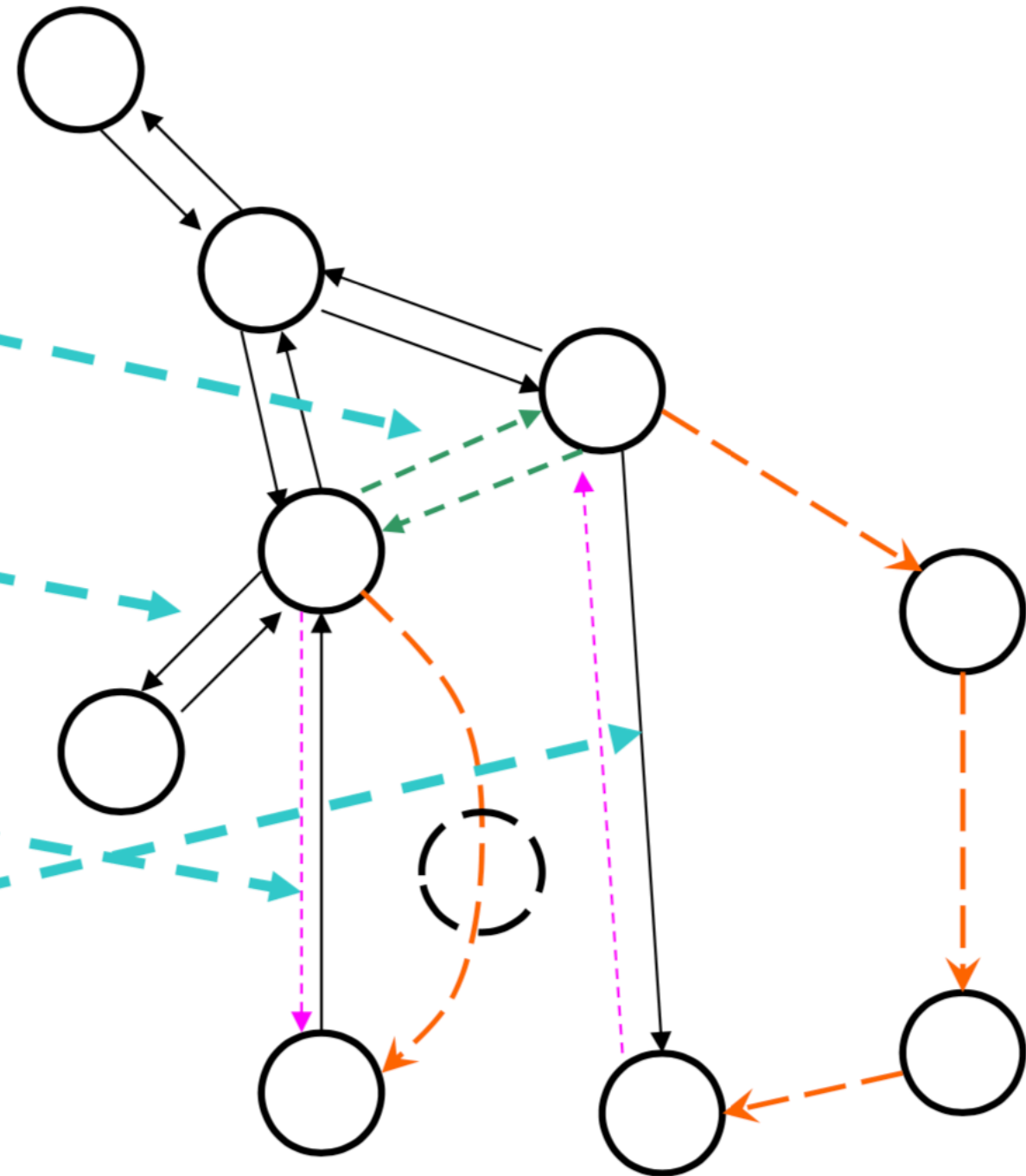
- Not existing

- **Back edge**

- Back to the direct parent:  
**second encounter**
- Otherwise: **first encounter**

- **Forward edge**

- Always **second encounter, and first time as back edge**



# Modifications to the DFS Skeleton

- All the **second encounter** are **bypassed**.
- So, the **only substantial modification** is for the possible back edges leading to an ancestor, but not direct parent.
- We need know the **parent**, that is, the direct ancestor, for the vertex to be processed.

# DFS Skeleton for Undirected Graph

- `void dfsSweep(intList[] adjVertices, int n, ...)`
- `int ans;`
- `<Allocate color array and initialize to white>`
- `for each vertex v of G, in some order`
- `if(color[v]==white)`
- `Int vAns=dfs(adjVertices, color, v, -1,...);`
- `<Process vAns>`
- `//continue loop`
- `return ans;`

# DFS Skeleton for Undirected Graph

- `int dfs(intList[] adjVertices, int[] color, int v, int p,...)`
- `int w; intList remAdj; int ans; color[v]=gray;`
- `<Preorder processing of vertex v>`
- `remAdj=adjVertices[v];`
- `while(remAdj != nil)`
- `w=first(remAdj);`
- `if(color[w]==white)`
- `<Exploratory processing for tree edge vw>`
- `dfs(adjVertices, color, w, v, ...);`
- `<Backtrack processing for tree edge vw, using wAns>`
- `else if(color[w]==gray && w!=p)`
- `<Checking for nontree edge vw>`
- `remAdj=rest(remAdj);`
- `<Postorder processing of vertex v, including final computation of ans>`
- `color[v]=black;`
- `return ans;`



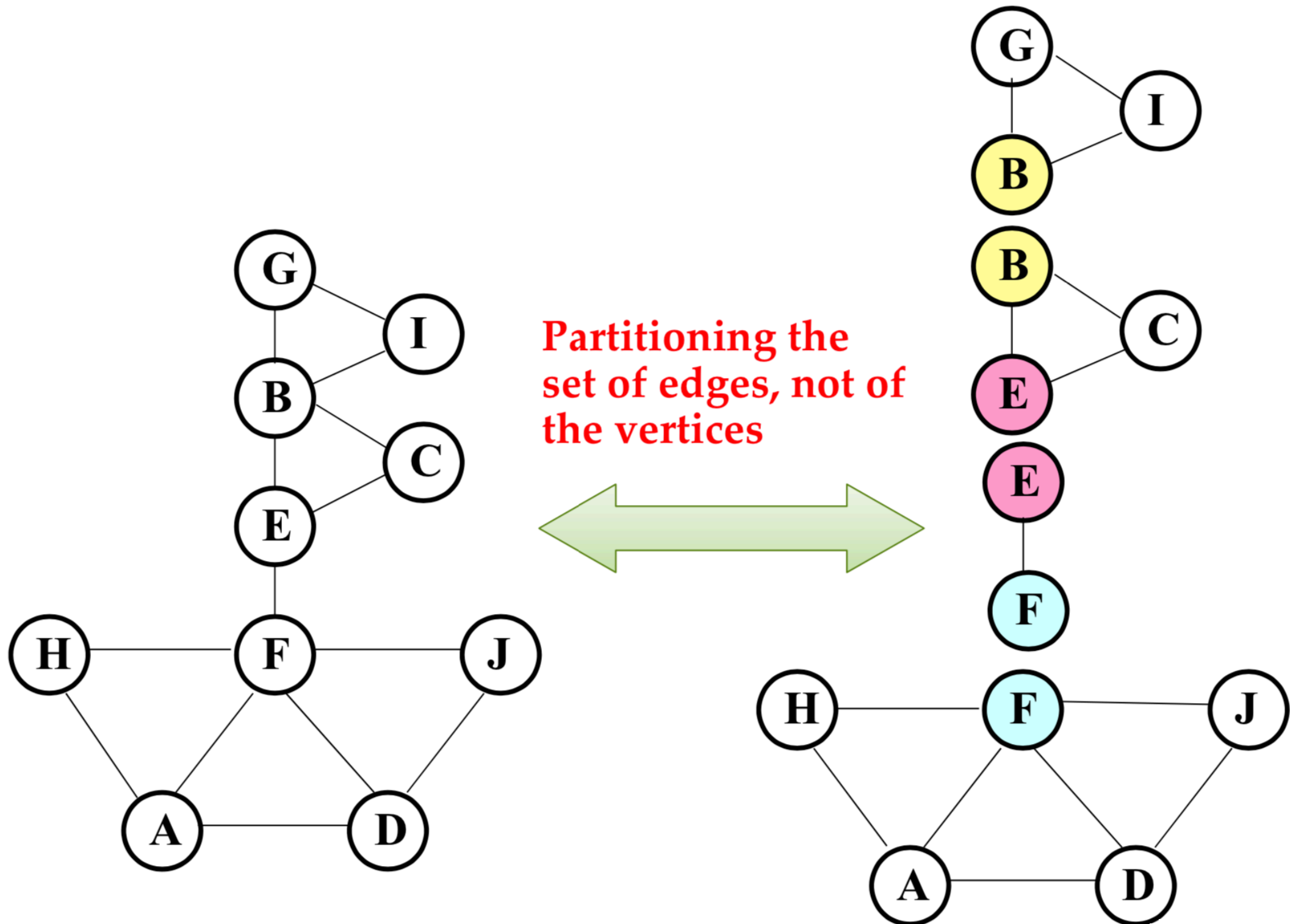
# Complexity of Undirected DFS

- $\Theta(m+n)$ 
  - If each inserted statement for specialized application runs in constant time
  - The same with directed graph DFS
- Extra space  $\Theta(n)$ 
  - For array color, or activation frames of recursion

# Biconnected Graph

- Being connected
  - Tree: acyclic, least (cost) connected
  - Node/edge connected: fault-tolerant connection
- Articulation point (2-node connected)
  - $v$  is an articulation point if deleting  $v$  leads to disconnection
- Bridge (2-edge connected)
  - $uv$  is a bridge if deleting  $uv$  leads to disconnection

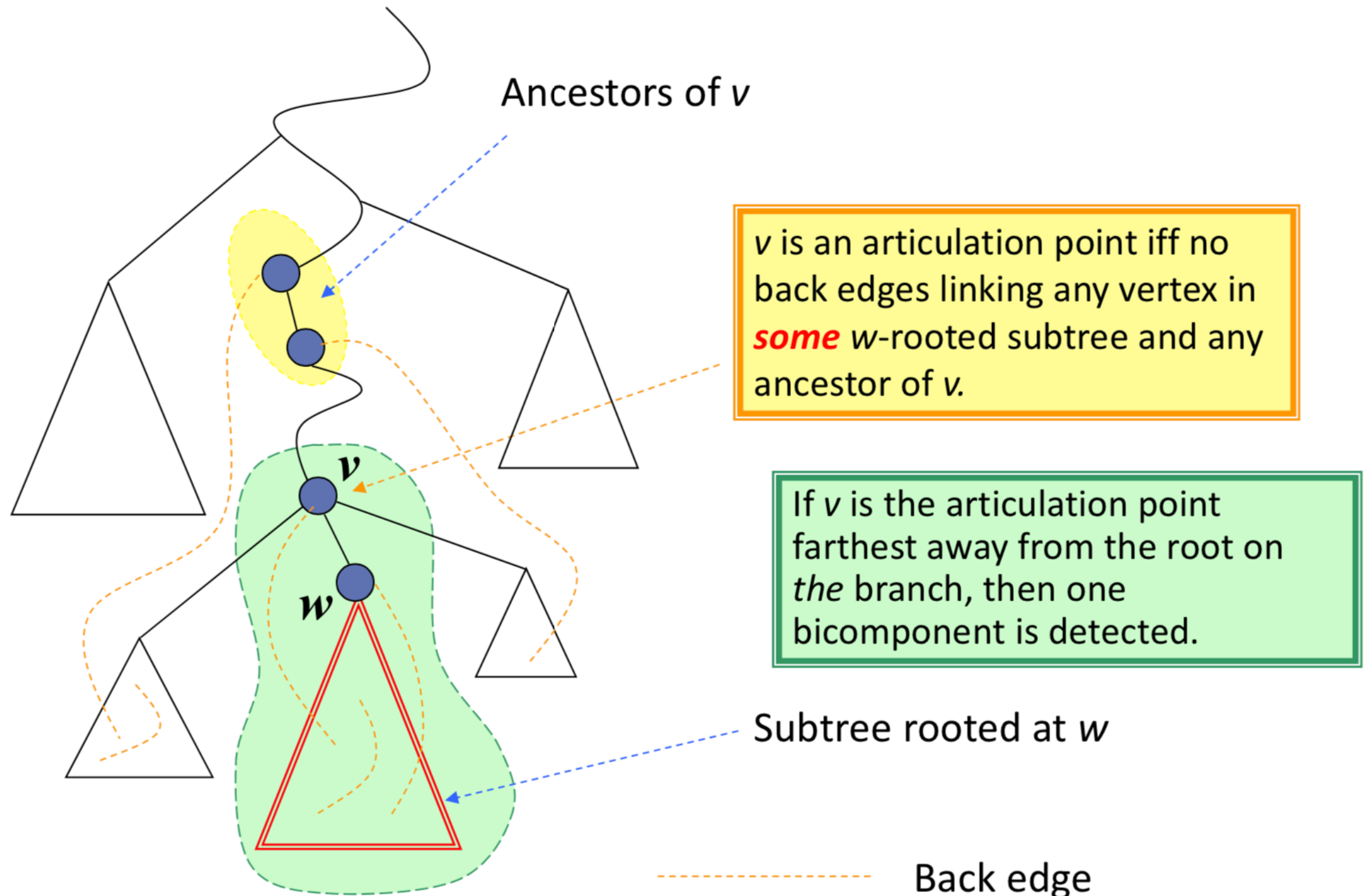
# Articulation Points



# Definition Transformation

- “Short definition”
  - Deleting  $v$  leads to disconnection
- “Long definition”
  - If there **exist** nodes  $w$  and  $x$ , such that  $v$  is in **every** path from  $w$  to  $x$  ( $w$  and  $x$  are vertices different from  $v$ )
- “Long definition” or “DFS definition”
  - **No** back edges linking **any** vertex in **some**  $w$ -rooted subtree and any ancestor of  $v$

# Articulation Point Algorithm

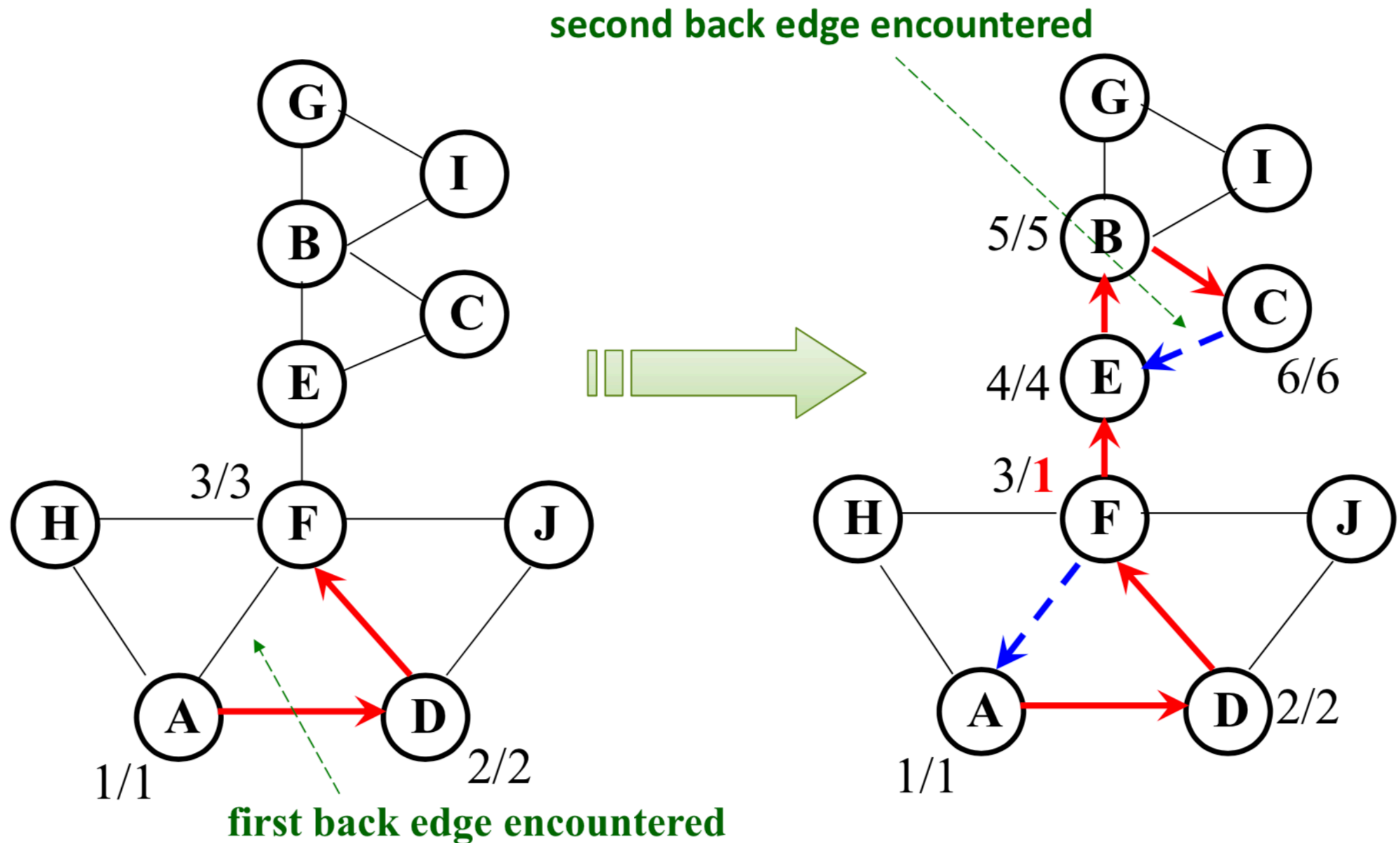


# Updating the value of **back**

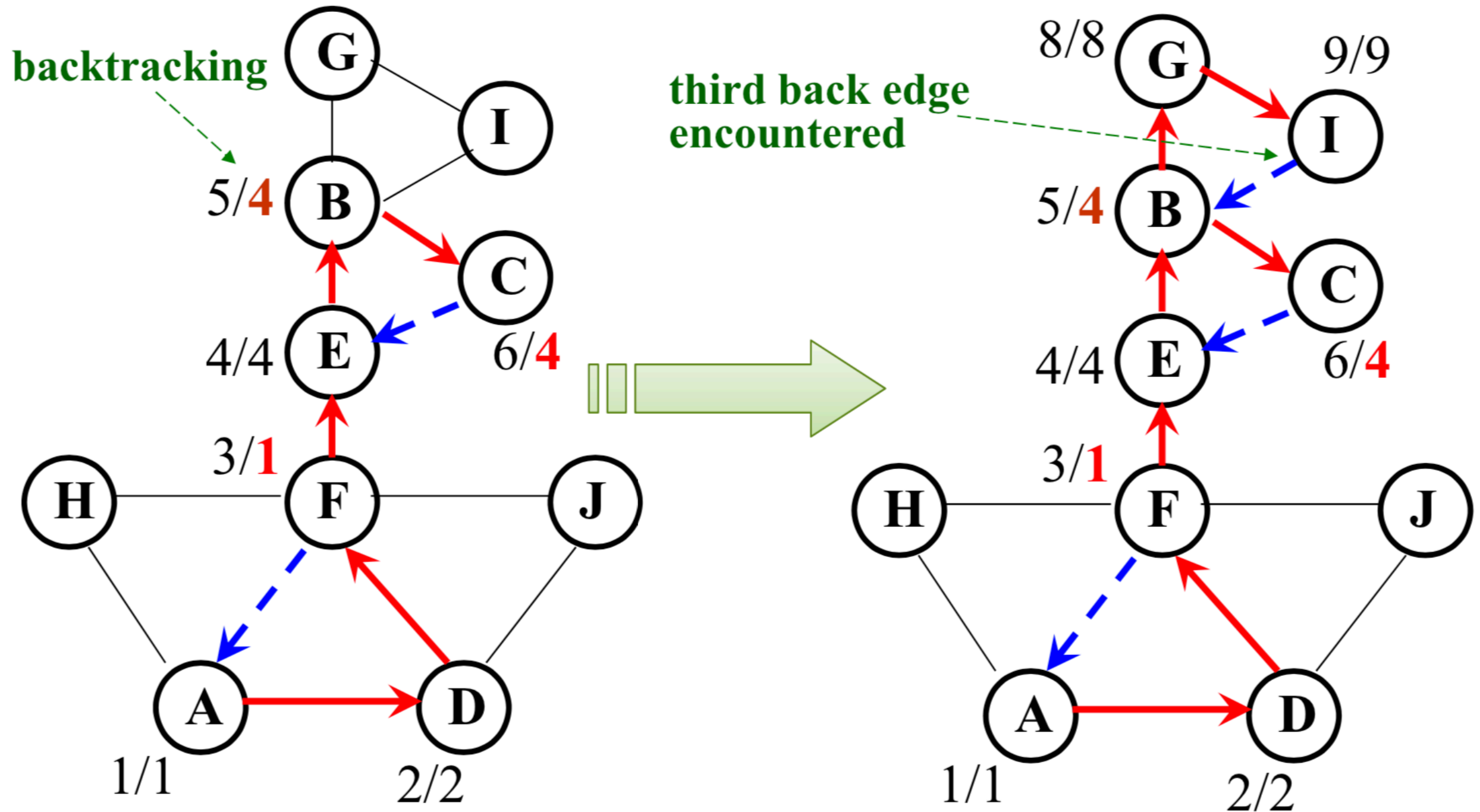
- **v first discovered**
  - $\text{back} = \text{discoverTime}(v)$
- **Trying to explore, but a back edge  $vw$  from  $v$  encountered**
  - $\text{back} = \min(\text{back}, \text{discoverTime}(w))$
- **Backtracking from  $w$  to  $v$** 
  - $\text{back} = \min(\text{back}, \text{wback})$

The back value of  $v$  is the smallest discover time a back edge “sees” from **any** subtree of  $v$ .

# Example

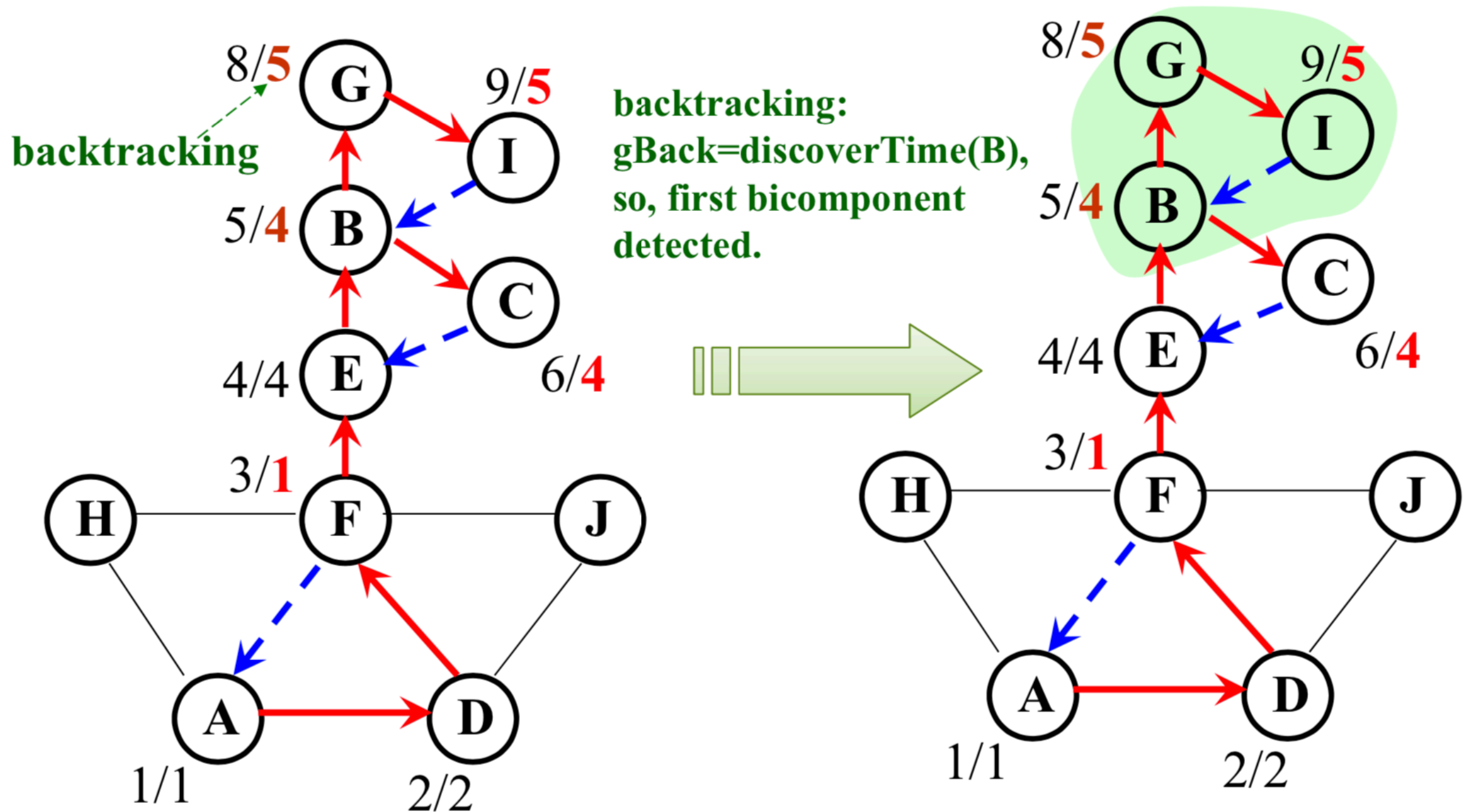


# Example





# Example



# Keeping the Track of Backing

- Tracking data

- For each vertex  $v$ , a local variable  $back$  is used to store the required information, as the value of **discoverTime** of some vertex.

- Testing for bicomponent

- At backtracking from  $w$  to  $v$ , the condition implying a bicomponent is:

- $wBack \geq discoverTime(v)$

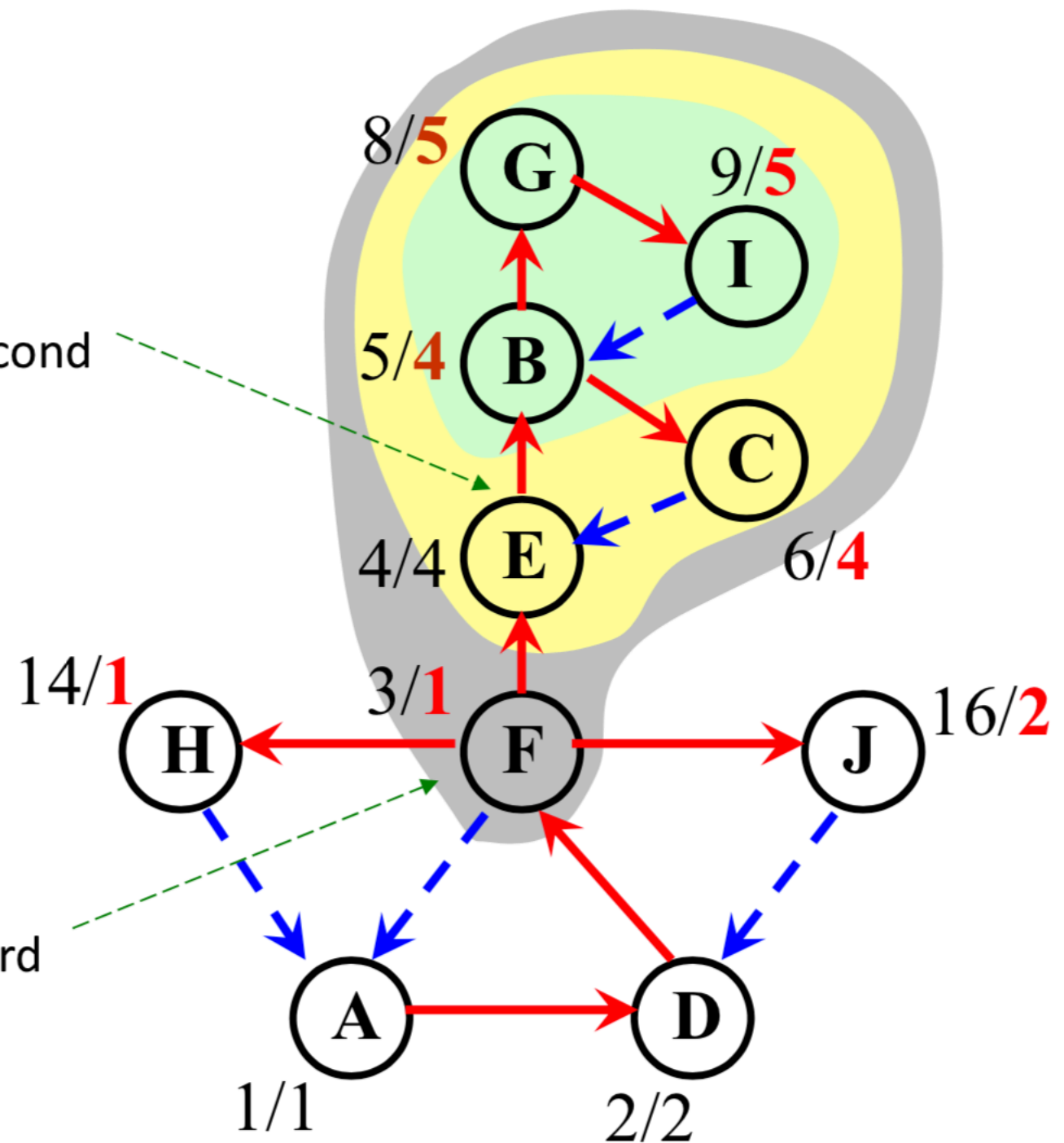
(where **wback** is the returned back value for  $w$ )

When  $back$  is no less than the discover time of  $v$ , there is at least one subtree of  $v$  connected to other part of the graph only by  $v$ .

# Example

Backtracking from B to E:  
bBack=discoverTime(E), so, the second  
bicomponent is detect

Backtracking from E to F:  
eBack>discoverTime(F), so, the third  
bicomponent is detect



# Articulation Point Algorithm

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**Algorithm 12:** ARTICULATION-POINT-DFS( $v$ )

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```
1  $v.color := \text{GRAY}$  ;
2  $time := time + 1$  ;
3  $v.discoverTime := time$  ;
4  $v.back := v.discoverTime$  ;
5 foreach neighbor  $w$  of  $v$  do
6     if  $w.color = \text{WHITE}$  then
7          $w.back := \text{ARTICULATION-POINT-DFS}(w)$  ;
8         if  $w.back \geq v.discoverTime$  then
9             Output  $v$  as an articulation point ;
10         $v.back := \min\{v.back, w.back\}$  ;
11    else
12        if  $vw$  is  $BE$  then                                     /*  $w$  是  $v$  非父节点的祖先节点 */
13             $v.back := \min\{v.back, w.discoverTime\}$  ;
14 return  $back$  ;
```

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# Correctness

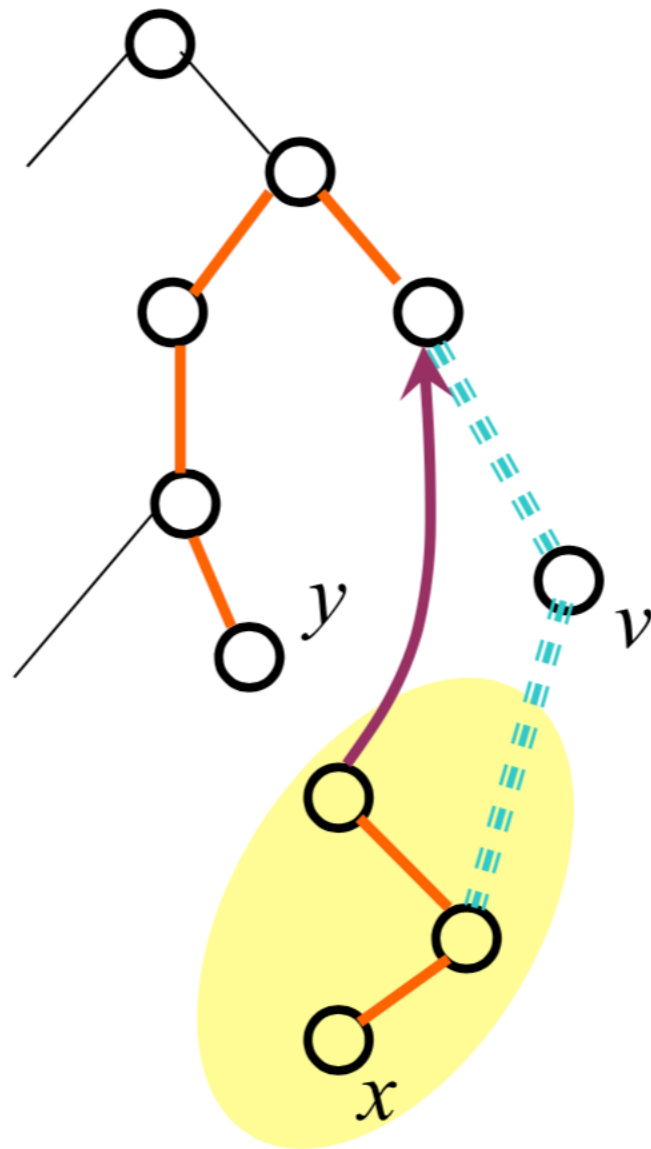
- We have seen that:
  - If  $v$  is the articulation point farthest away from the root on the branch, then one bicomponent is detected.
- So, we need only prove that:
  - In a DFS tree, a vertex (not root)  $v$  is an articulation point **if and only if** (1)  $v$  is not a leaf; (2) **some** subtree of  $v$  has **no back edge** incident with a proper ancestor of  $v$ .

# Characteristics of Articulation Point

- In a DFS tree, a vertex (not root)  $v$  is an articulation point **if and only if** (1)  $v$  is not a leaf; (2) **some** subtree of  $v$  has **no back edge** incident with a proper ancestor of  $v$ .
- $\Leftarrow$  Trivial
- $\Rightarrow$ 
  - By definition,  $v$  is on every path between some  $x, y$  (different from  $v$ ).
  - At least one of  $x, y$  is a proper descendent of  $v$  (otherwise,  $x \leftrightarrow \text{root} \leftrightarrow y$  not containing  $v$ ).
  - By **contradiction**, suppose that every subtree of  $v$  has a back edge to a proper ancestor of  $v$ , we can find a  $xy$ -path not containing  $v$  for all possible cases (only 2 cases)



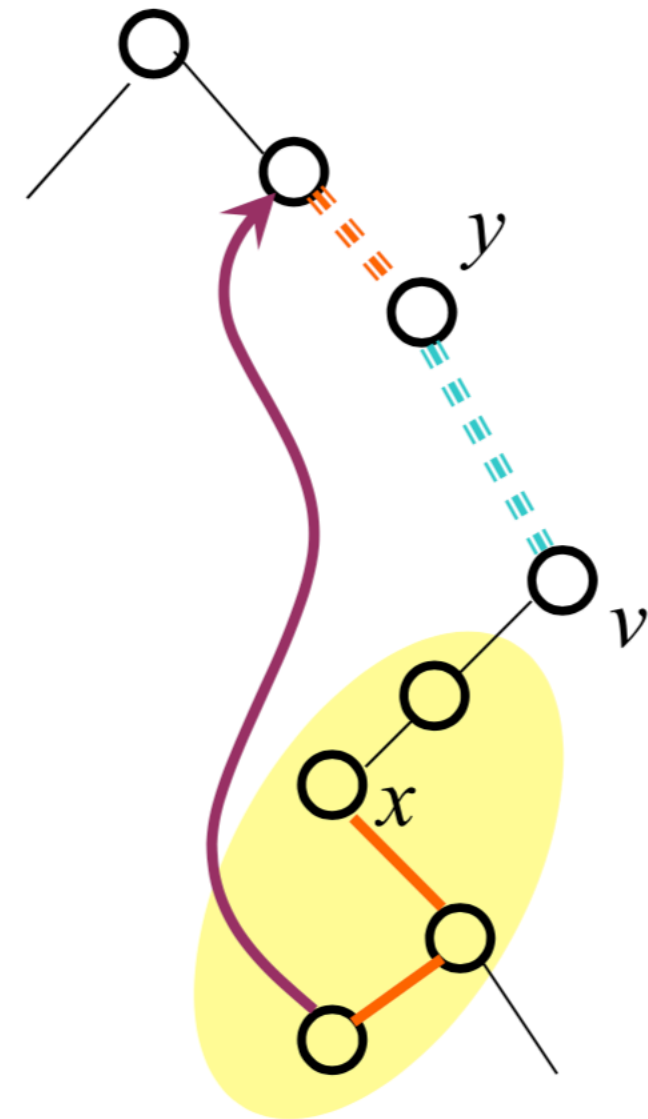
# Case 1



Case 1.1: another is not an ancestor of  $v$

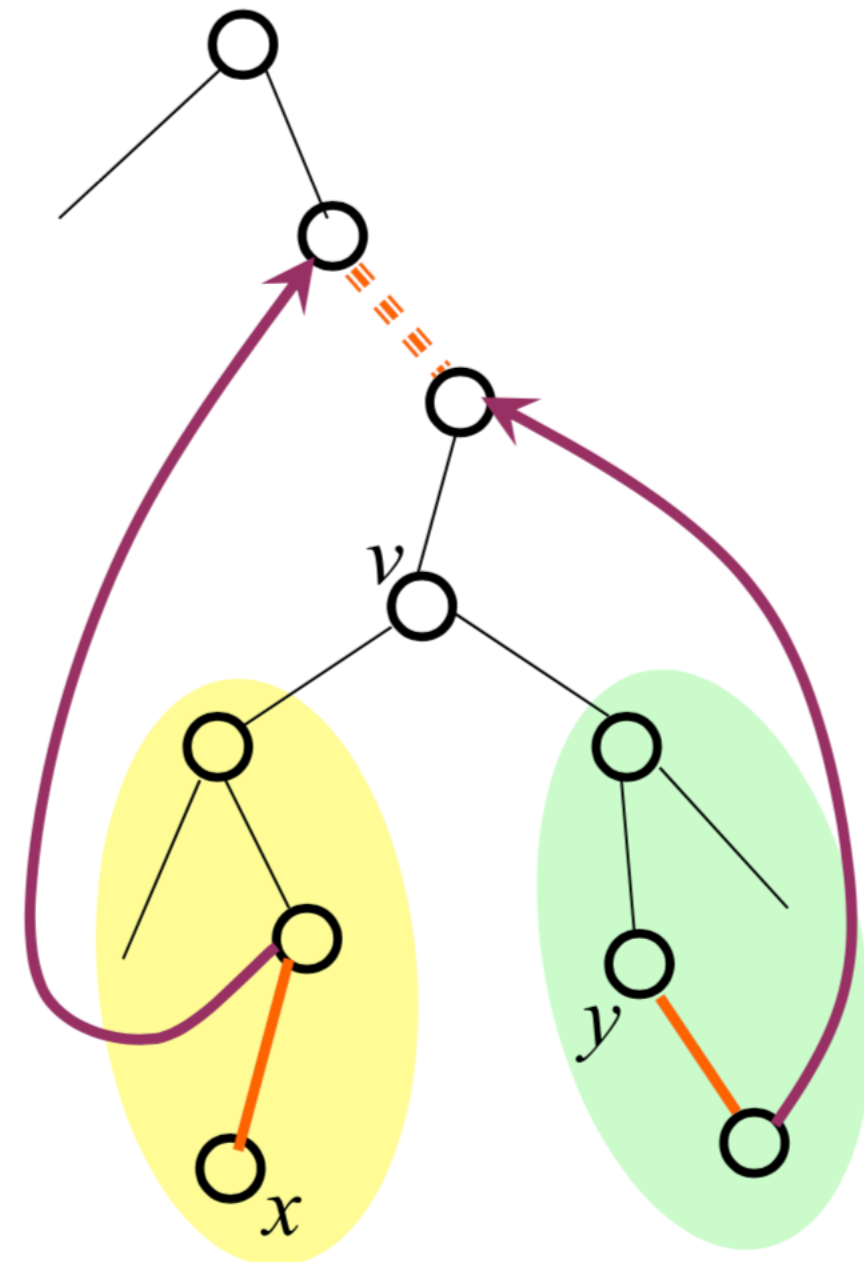
suppose that **every** subtree of  $v$  has a back edge to a proper ancestor of  $v$ , and, exactly one of  $x, y$  is a descendant of  $v$ .

Case 1.2: another is an ancestor of  $v$



# Case 2

suppose that **every** subtree of  $v$  has a back edge to a proper ancestor of  $v$ , and, both  $x, y$  are descendants of  $v$ .

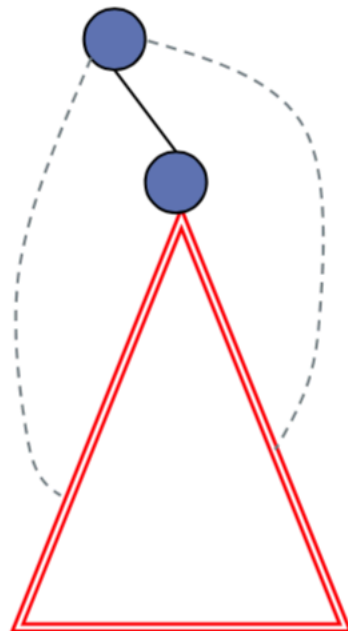




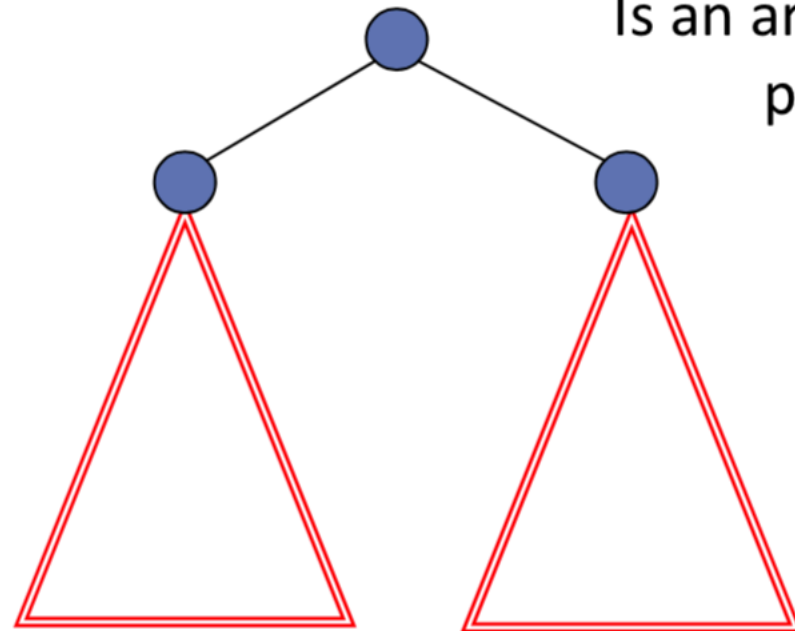
# What about the root?

- One single DFS tree
  - We only consider each connected component
- Root AP  $\equiv$  Two or more sub-trees
  - The root is an articulation point

Not an  
articulation point

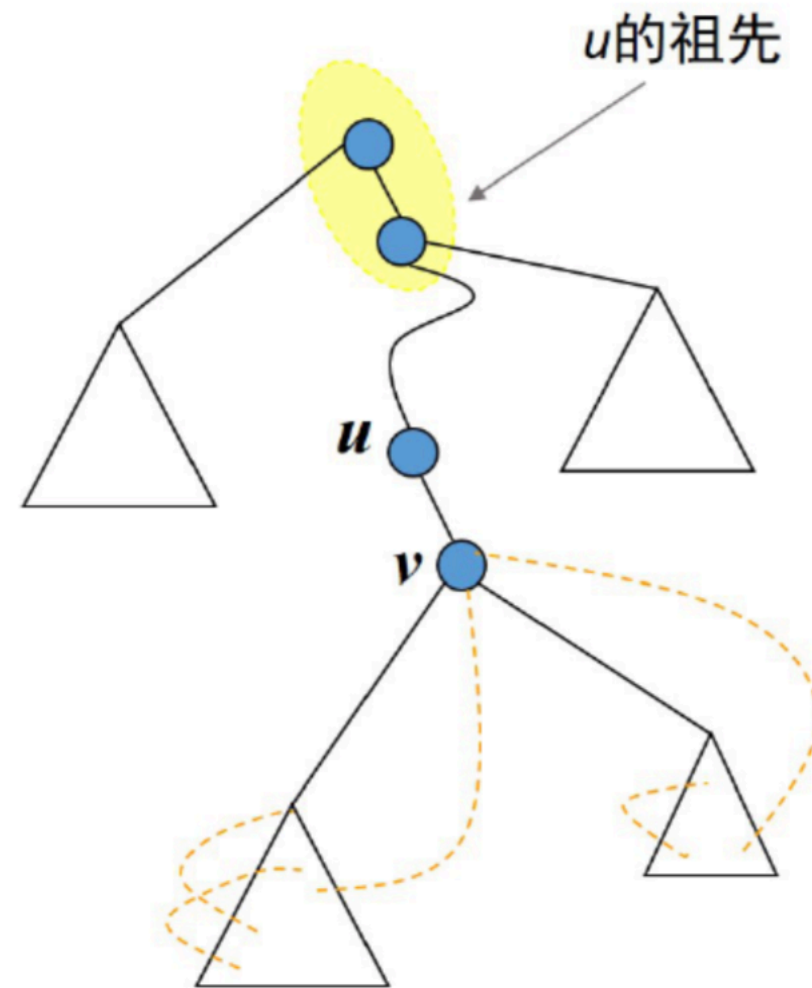


Is an articulation  
point



# Defining the Bridge

- Short definition
  - Removing  $uv$  leading to disconnection
- Long definition
  - Edge  $uv$  is a bridge iff node  $u$  and  $v$  are connected only by  $uv$
- DFS Definition
  - Edge  $uv$  is a tree edge in DFS
  - There is no subtree rooted at  $v$  to any proper ancestor of  $v$  (including  $u$ )



# Bridge Algorithm

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**Algorithm 11: BRIDGE-DFS( $u$ )**

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```
1  $u.color := \text{GRAY}$  ;
2  $time := time + 1$  ;
3  $u.discoverTime := time$  ;
4  $u.back := u.discoverTime$  ;
5 foreach neighbor  $v$  of  $u$  do
6   if  $v.color = \text{WHITE}$  then
7     BRIDGE-DFS( $v$ ) ;
8      $u.back := \min\{u.back, v.back\}$  ;
9     if  $v.back > u.discoverTime$  then
10      Output  $uv$  as a bridge ;
11   else
12     if  $uv$  is BE then                                     /*  $v$  是  $u$  非父节点的祖先节点 */
13       $u.back := \min\{u.back, v.discoverTime\}$  ;
```

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# Other Traversal Problems

- **Orientation of an undirected graph**
  - Give each edge a direction
  - Satisfying pre-specified constraints
    - E.g., the “in-degree of each vertex is at least 1”
- **Possible or not?**
  - If possible, how to?
- **As for “in-degree  $\geq 1$ ”**
  - Orientation possible iff. the graph has at least a circle
    - Find the end point of some back edge
    - A second DFS from this end point

# Other Traversal Problems

**MST: Minimum Spanning Tree**

- **Get MST in  $O(m+n)$  time**
  - Given that edges weights are only 1 and 2
- **Graph traversal is sufficient**
  - DFS over “weight 1 edges” only
  - DFS over “weight 2 edges” only

Thank you!

Q & A