

# Introduction to

# Algorithm Design and Analysis

[14] Minimum Spanning Tree

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# In the last class...

- **Undirected and Symmetric Digraph**

- DFS skeleton

- **Biconnected Components**

- Articulation point
- Bridge

- **Other undirected graph problems**

- Orientation for undirected graphs
- MST based on graph traversal

# Greedy Strategy

- Optimization Problem
- Greedy Strategy
- MST Problem
  - Prim's Algorithm
  - Kruskal's Algorithm
- Single-Source Shortest Path Problem
  - Dijkstra's Algorithm

# Greedy Strategy for Optimization Problems

- **Coin change Problem**

- [candidates] A finite set of coins, of 1, 5, 10 and 25 units, with enough number for each value
- [constraints] Pay an exact amount by a selected set of coins
- [optimization] a smallest possible number of coins in the selected set

- **Solution by greedy strategy**

- For each selection, choose the highest-valued coin as possible

# Greedy Fails Sometimes

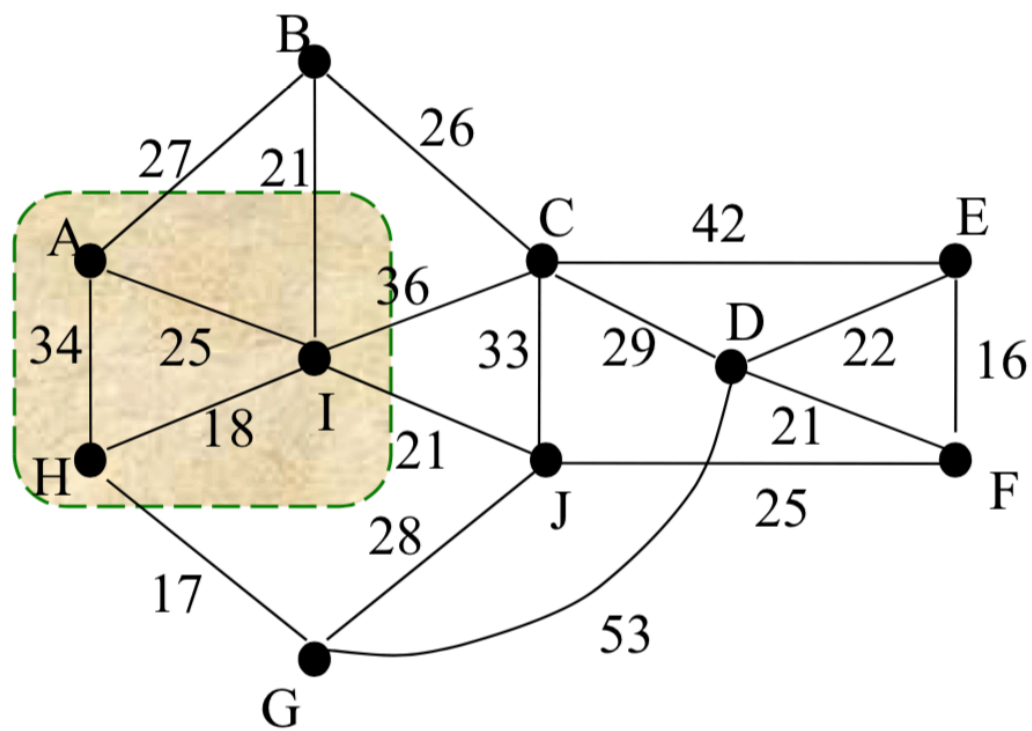
- We have to pay 15 in total
- If the available types of coins are  $\{1, 5, 12\}$ 
  - The greedy choice is  $\{12, 1, 1, 1\}$
  - But the smallest set of coins is  $\{5, 5, 5\}$
- If the available types of coins are  $\{1, 5, 10, 25\}$ 
  - The greedy choice is always correct

# Greedy Strategy

- Expanding the partial solution **step by step**
- In each step, a selection is made from a set of candidates. The choice made **must** be:
  - [Feasible] it has to satisfy the problem's constraints
  - [Locally optimal] it has to be the best local choice among all feasible choices on the step
  - [Irrevocable] the choice cannot be revoked in subsequent steps

```
set greedy(set candidate)
  set S=∅;
  while not solution(S) and candidate≠∅
    select locally optimizing x from candidate;
    candidate=candidate-{x};
    if feasible(x) then S=S∪{x};
  if solution(S) then return S
  else return ("no solution")
```

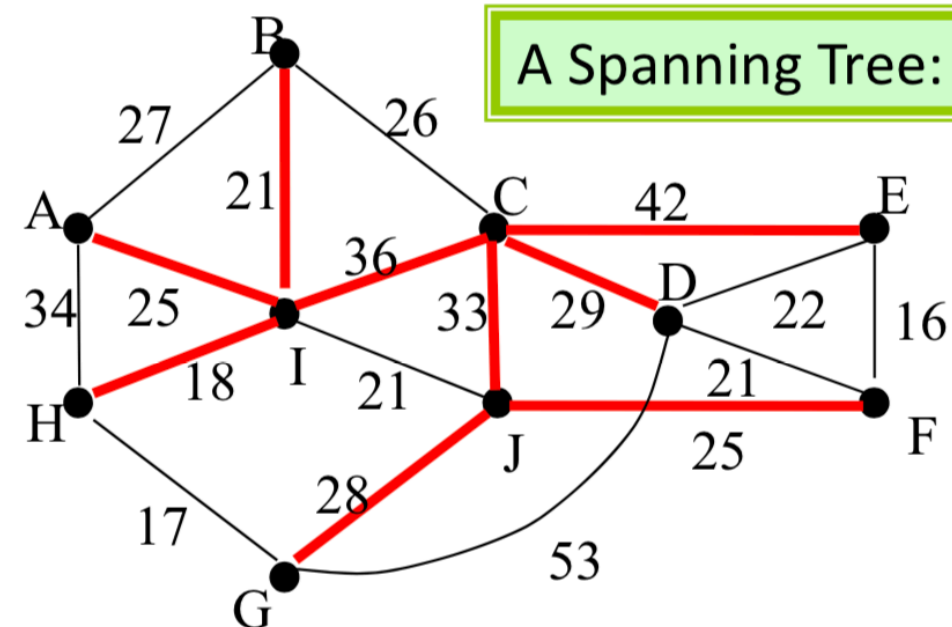
# Weighted Graph and MST



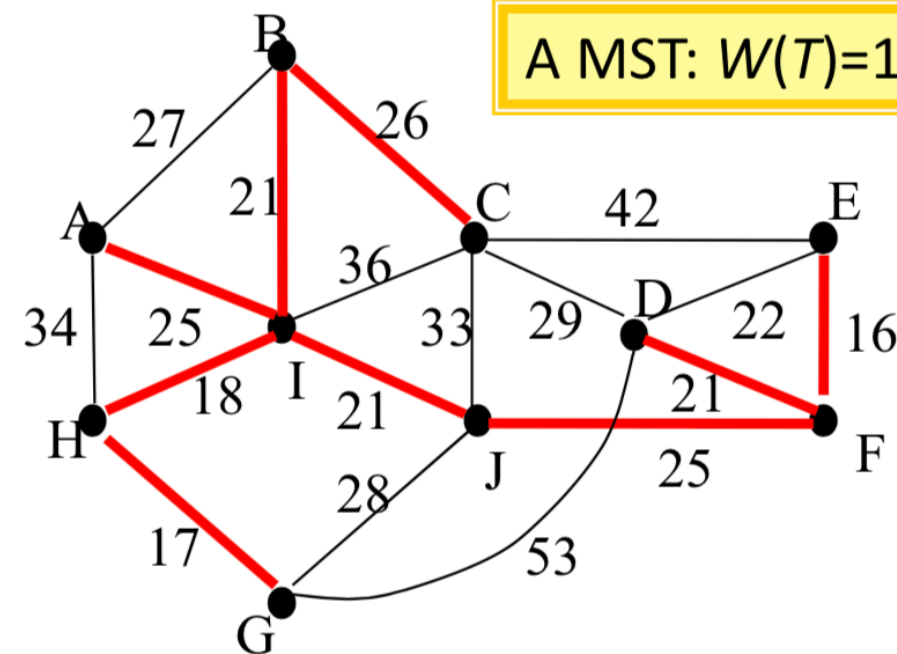
A weighted graph

The nearest neighbor of vertex **I** is **H**

The nearest neighbor of shaded subset of vertex is **G**



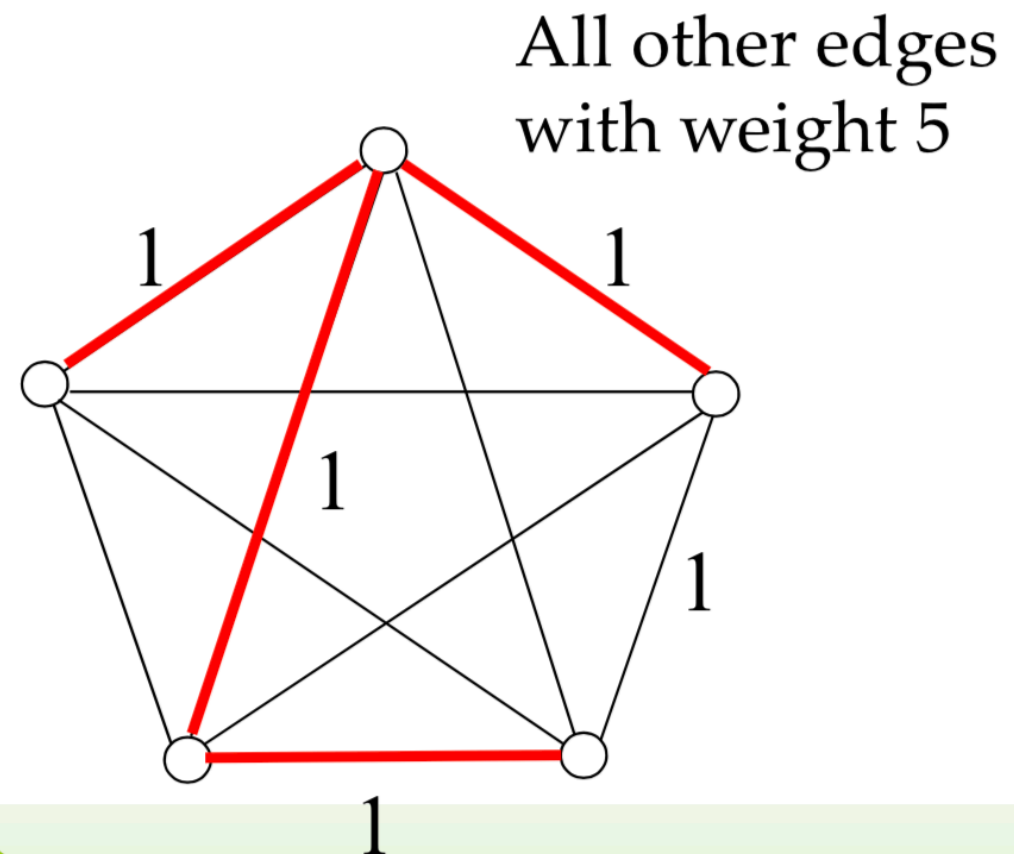
A Spanning Tree:  $W(T)=257$



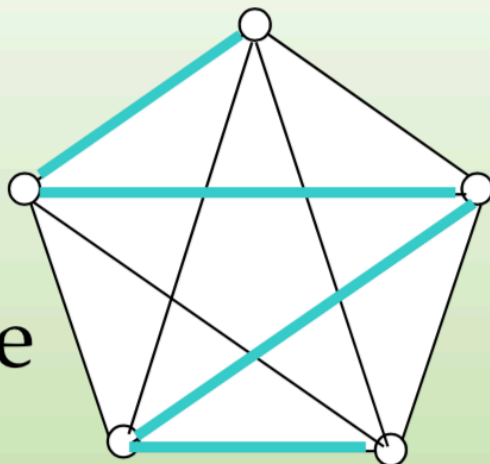
A MST:  $W(T)=190$

# Graph Traversal and MST

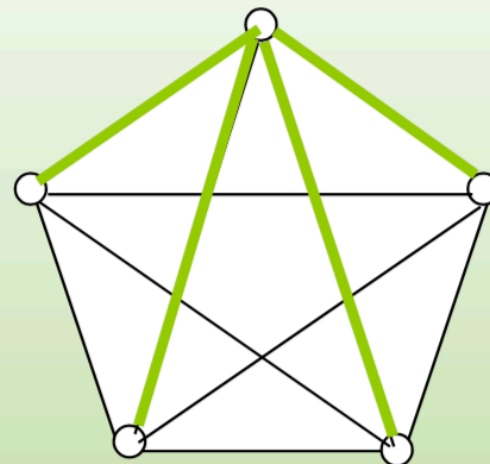
There are cases that graph traversal tree **cannot** be minimum spanning tree, with the vertices explored in any order.



DFS tree



BFS tree



in any ordering of vertex



# Greedy Algorithms for MST

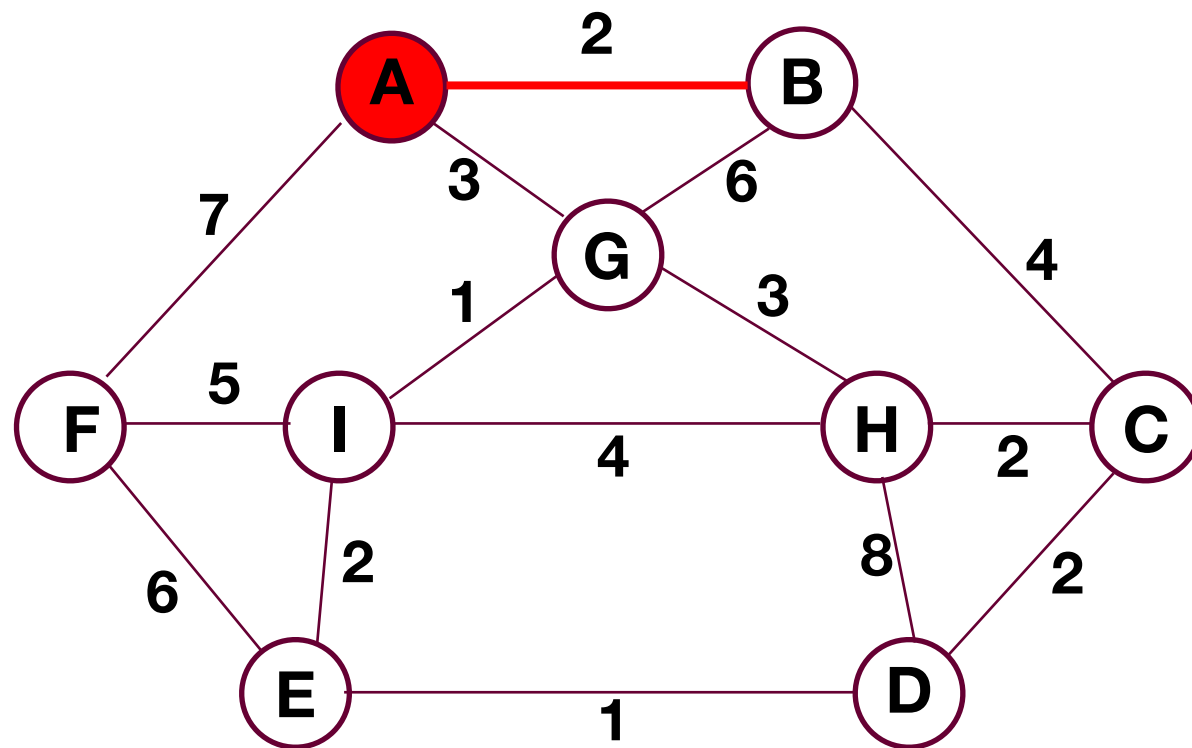
- Prim's algorithm:

- Difficult selecting: “best local optimization means **no cycle and small weight under limitation**”
- Easy checking: doing nothing

- Kruskal's algorithm:

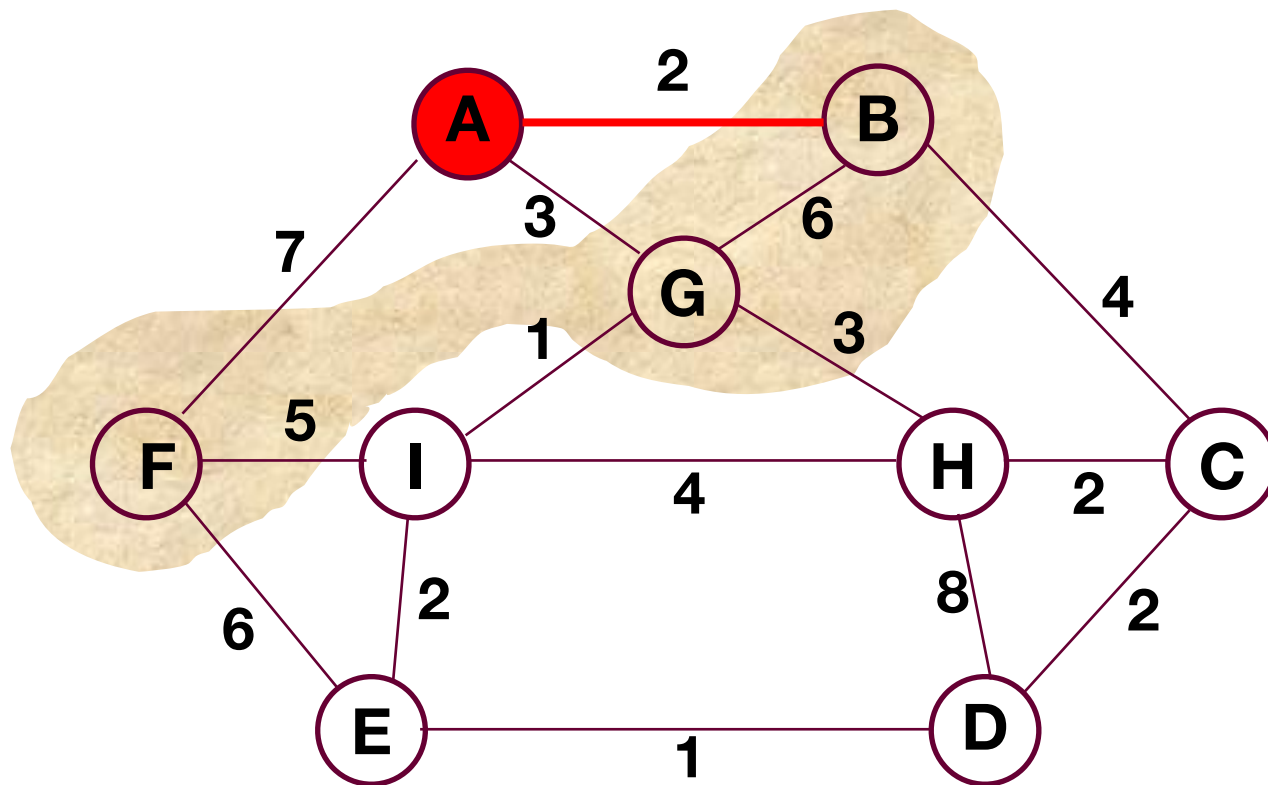
- Easy selecting: smallest in primitive meaning
- Difficult checking: **no cycle**

# Prim's Algorithm



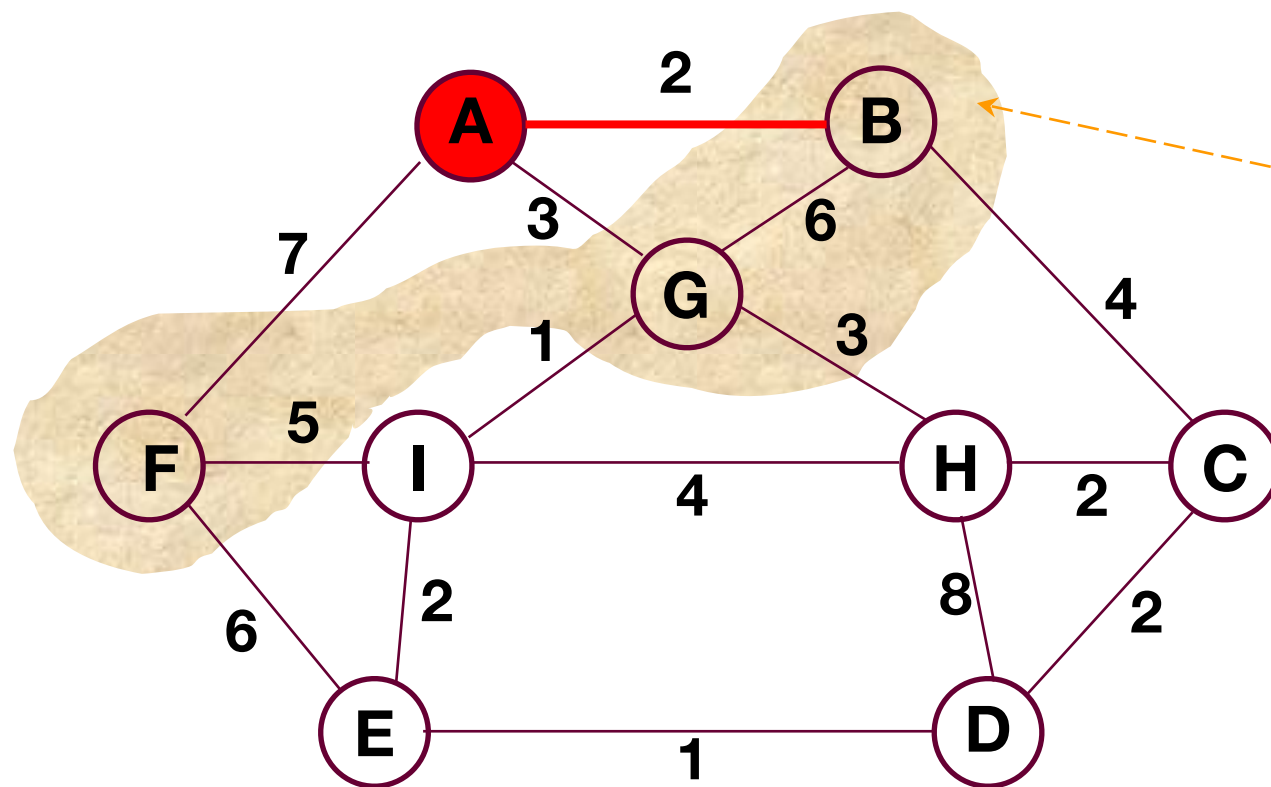
edges included in the MST

# Prim's Algorithm



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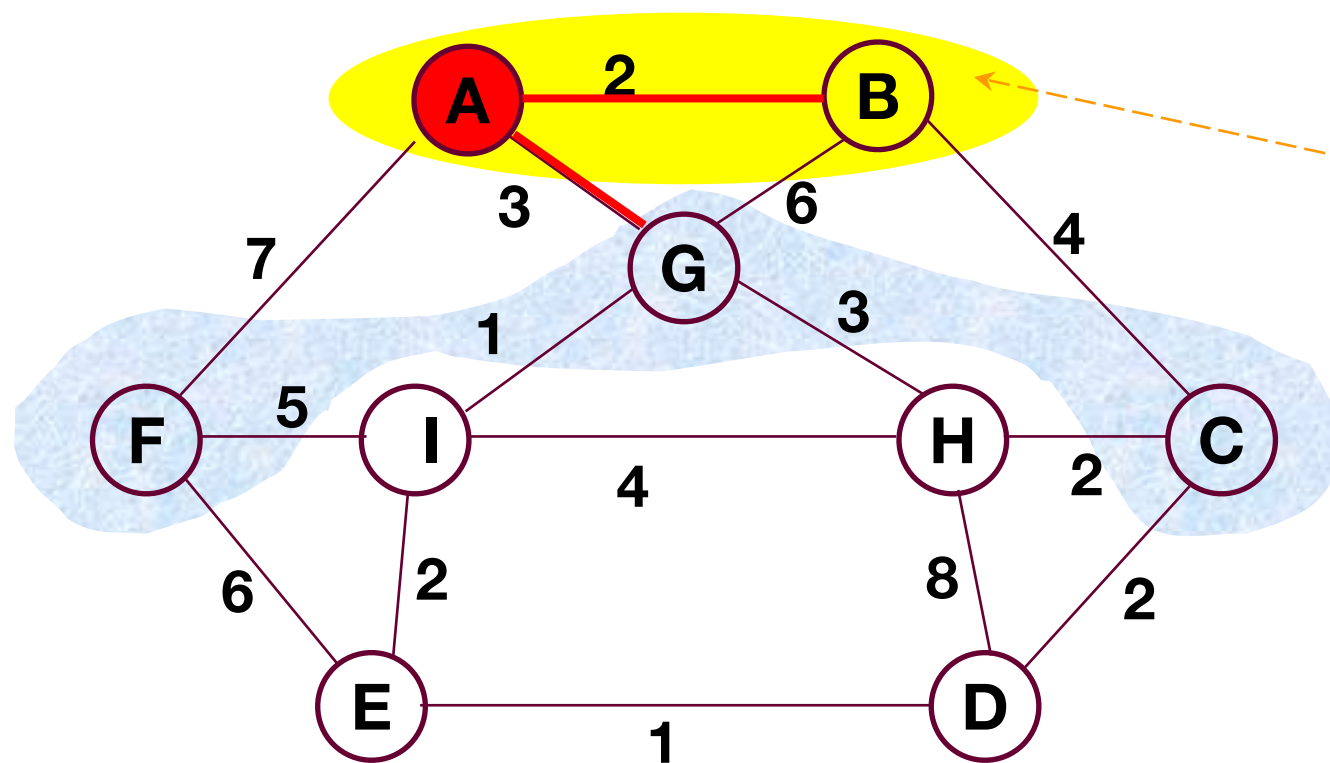
# Prim's Algorithm



Greedy strategy:  
For each set of fringe vertex,  
select the edge with the  
minimal weight, that is, local  
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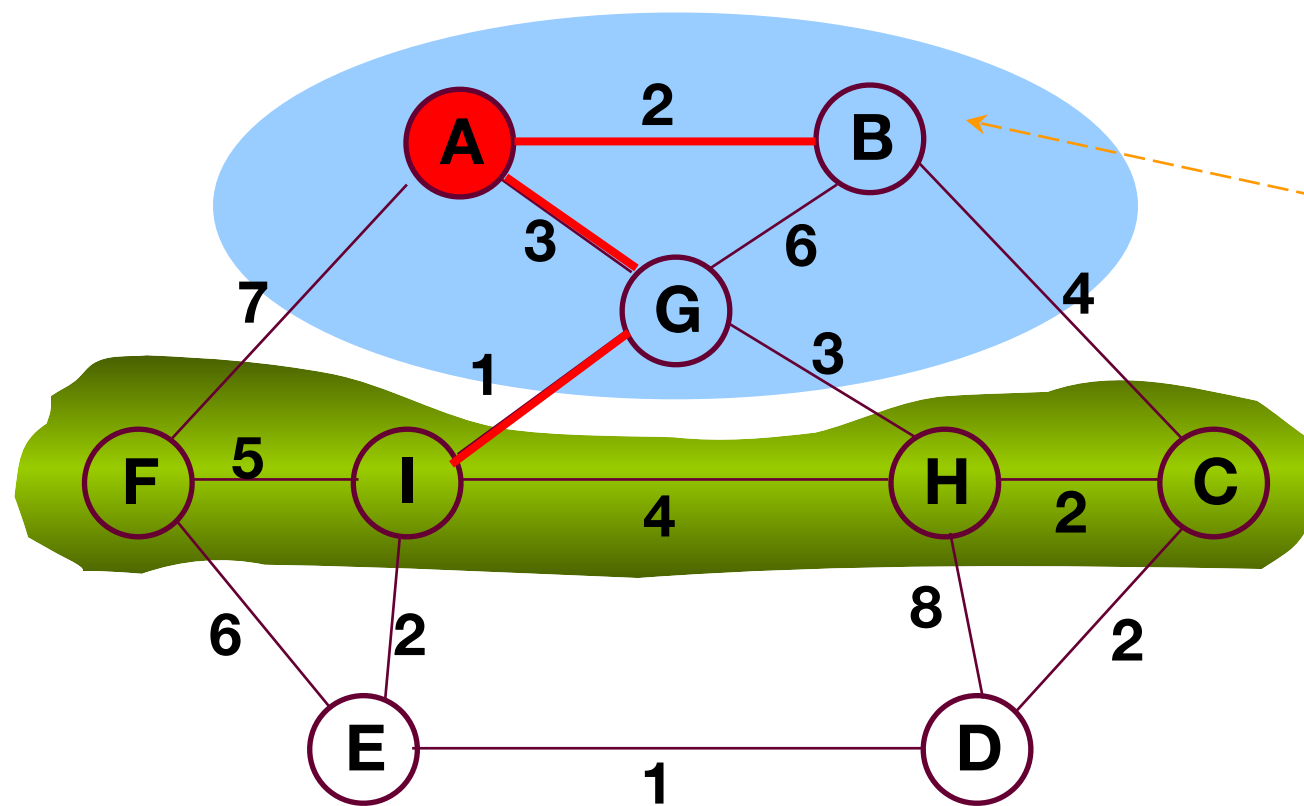


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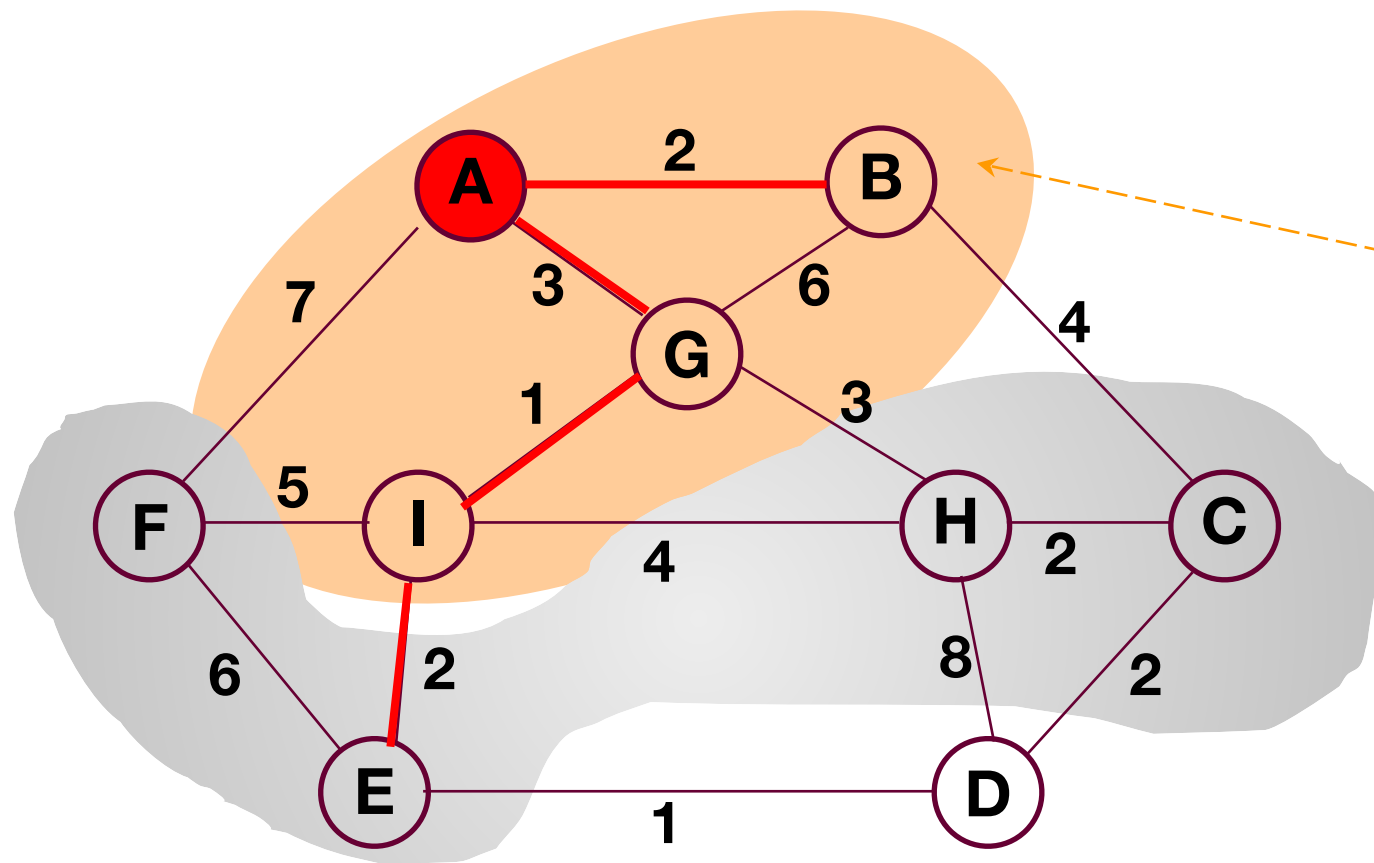


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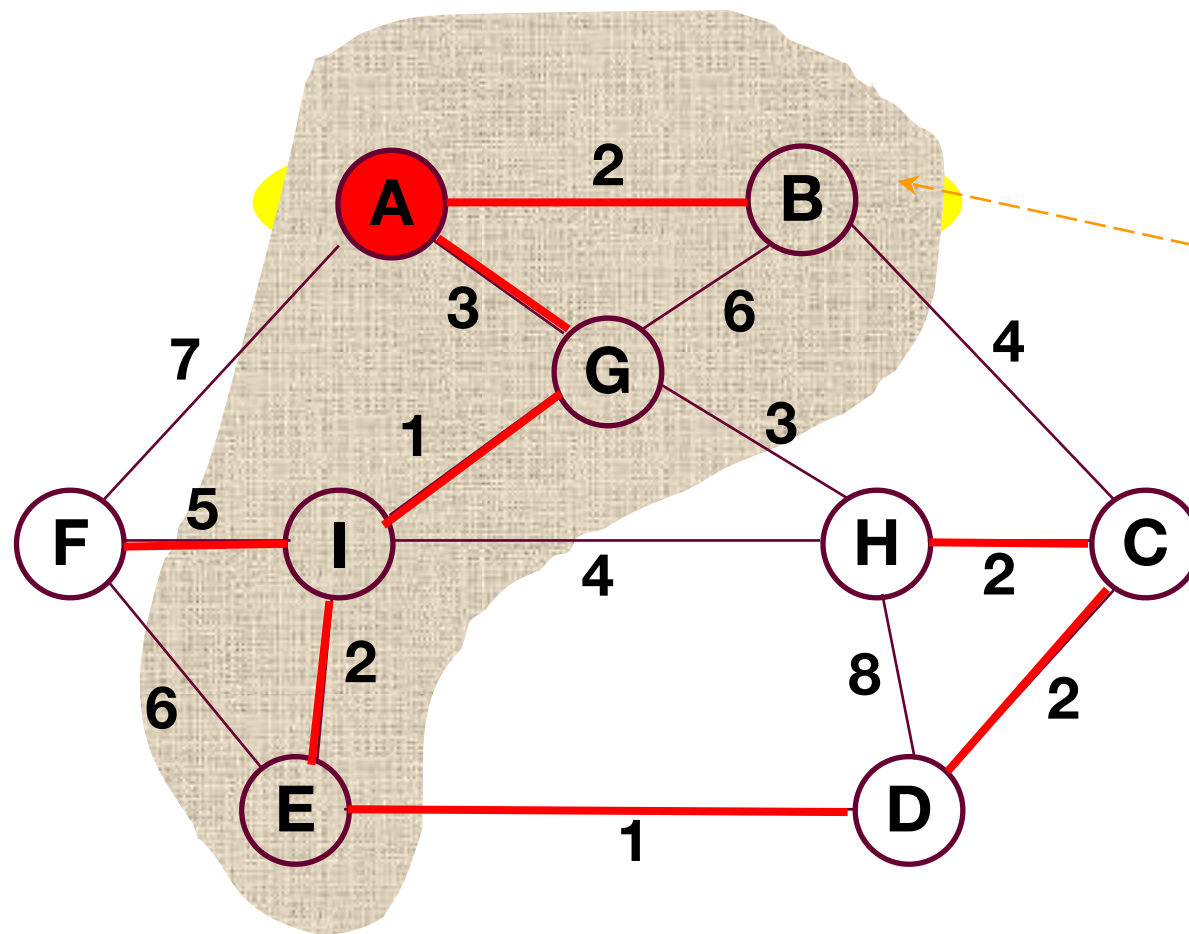
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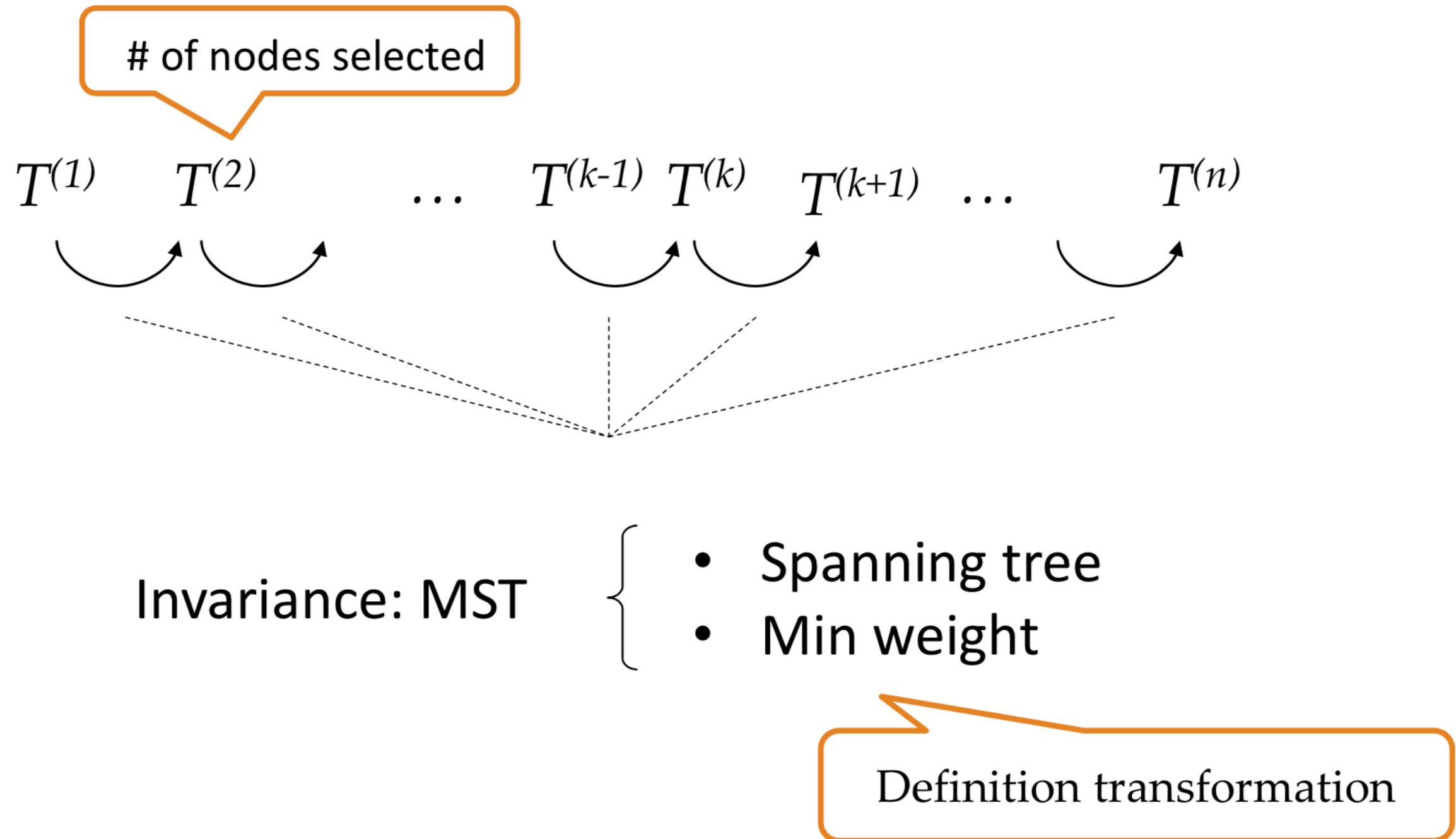


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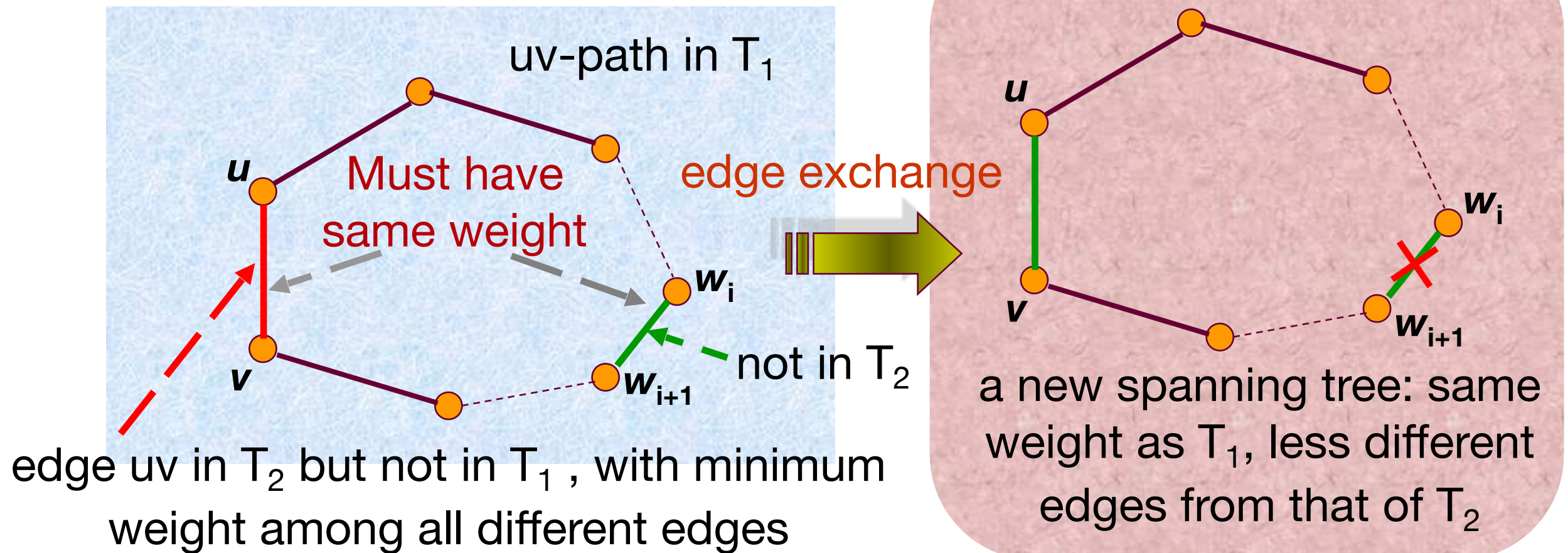


# Correctness: How to Prove



# Minimum Spanning Tree Property

- A spanning tree  $T$  of a connected, weighted graph has MST property if and only if for any non-tree edge  $uv$ ,  $T \cup \{uv\}$  contain a cycle in which  $uv$  is **one of** the maximum-weight edge.
- All the spanning trees having MST property have the same weight.

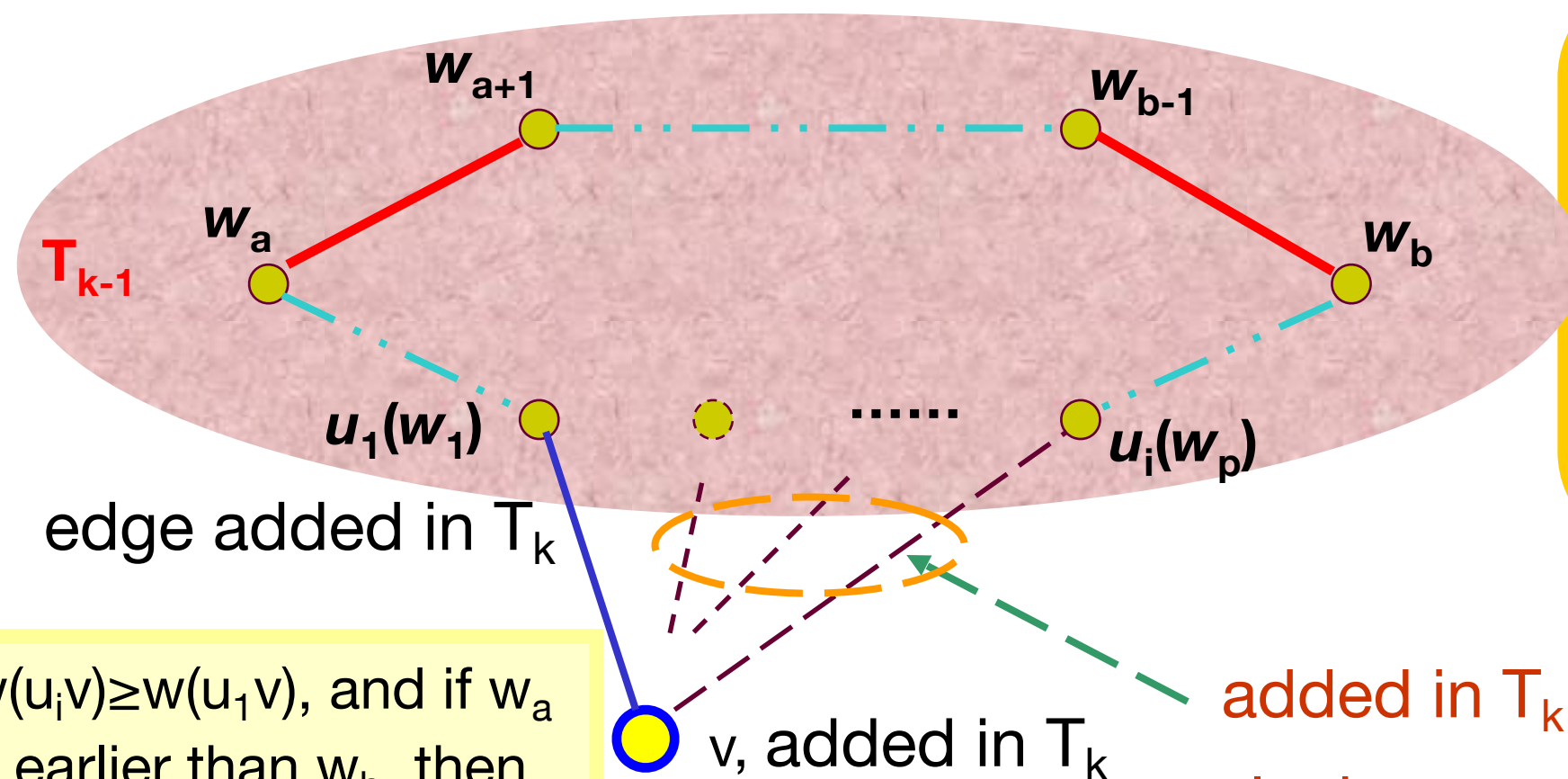


# MST Property and Minimum Spanning Tree

- In a connected, weighted graph  $G=\{V,E,W\}$ , a tree  $T$  is a minimum spanning tree if and only if  $T$  has the MST property.
- Proof
  - $\Rightarrow$  For a minimum spanning tree  $T$ , if it doesn't have the MST property. So, there is a non-tree edge  $uv$ , and  $T \cup \{uv\}$  contains an edge  $xy$  with weight larger than that of  $uv$ . Substituting  $uv$  for  $xy$  results in a spanning tree with less weight than  $T$ . Contradiction.
  - $\Leftarrow$  As claimed above, any minimum spanning tree has the MST property. Since  $T$  has the MST property, it has the same weight as any minimum spanning tree, i.e.  $T$  is a minimum spanning tree as well.

# Correctness of Prim's Algorithm

- Let  $T_k$  be the tree constructed after the  $k^{\text{th}}$  step of Prim's algorithm is executed. Then  $T_k$  has the MST property in  $G_k$ , the subgraph of  $G$  induced by vertices of  $T_k$ .



assumed first and last edges with larger weight than  $w(u_i v)$ , resulting contradictions.

Note:  $w(u_i v) \geq w(u_1 v)$ , and if  $w_a$  added earlier than  $w_b$ , then  $w_a w_{a+1}$  and  $w_{b-1} w_b$  added later than any edges in  $u_1 w_a$ -path, and  $v$  as well

added in  $T_k$  to form a cycle, only these need be considered

# Key Issue in Implementation

- Maintaining the set of fringe vertices
  - Create the set and update it after each vertex is “selected” (**deleting** the vertex having been selected and **inserting** new fringe vertices)
  - Easy to decide the vertex with “highest priority”
  - Changing the priority of the vertices (**decreasing key**)
- The choice: priority queue

# Implementing Prim's Algorithm

## Main Procedure

```
primMST(G,n)
Initialize the priority queue pq as empty;
Select vertex s to start the tree;
Set its candidate edge to (-1,s,0);
insert(pq,s,0);
while (pq is not empty)
    v=getMin(pq); deleteMin(pq);
    add the candidate edge of v to the tree;
    updateFringe(pq,G,v);
return
```

getMin(pq) always be  
the vertex with the  
smallest key in the  
fringe set.

ADT operation executions:

insert, getMin, deleteMin:  $n$  times

decreaseKey:  $m$  times

## Updating the Queue

updateFringe(pq,G,v)

For all vertices  $w$  adjacent to  $v$  //  $2m$  loops

newWgt=w(v,w);

if  $w$ .status is unseen then

Set its candidate edge to (v,w,newWgt);

insert(pq,w,newWgt)

else

if newWgt<getPriority(pq,w)

Revise its candidate edge to (v,w,newWgt);

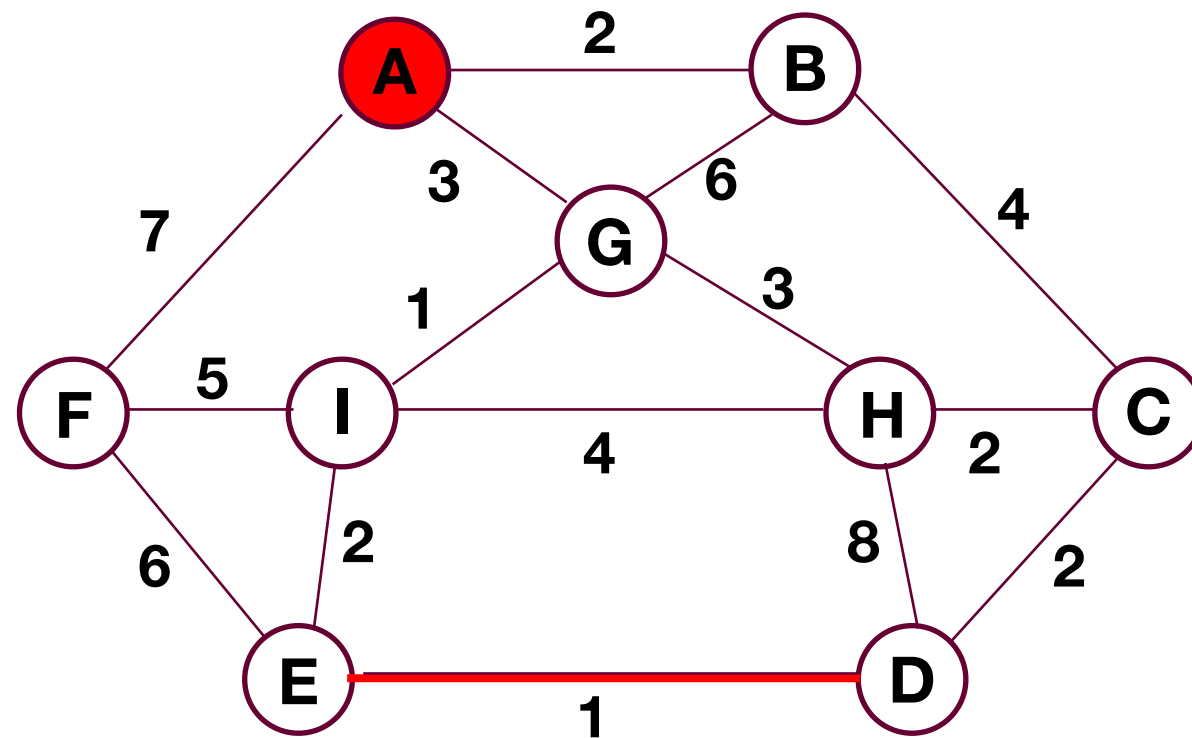
decreaseKey(pq,w,newWgt)

return

# Complexity

- Operations on ADT priority queue: (for a graph with vertices and  $m$  edges)
  - insert:  $n$ ;    getMin:  $n$ ;    deleteMin:  $n$ ;
  - decreaseKey:  $m$  (appears in  $2m$  loops, but execute at most  $m$ )
- So,
  - $T(n,m)=O(nT(\text{getMin})+nT(\text{deleteMin}+\text{insert})+mT(\text{decreaseKey}))$
- Implementing priority queue using array, we can get  $\Theta(n^2+m)$

# Kruskal's Algorithm



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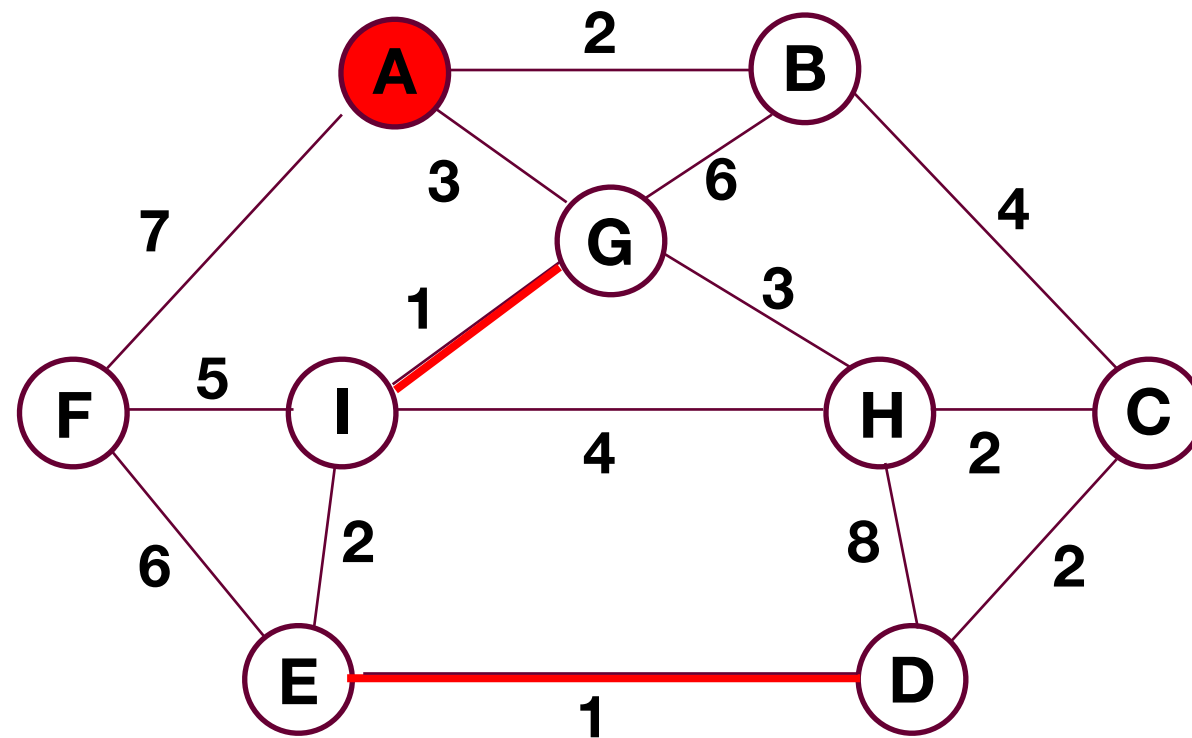
edges included in the MST

Also Greedy strategy:

From the set of edges not yet included in the partially built MST, select the edge with the minimal weight, that is, local optimal, in another sense.



# Kruskal's Algorithm



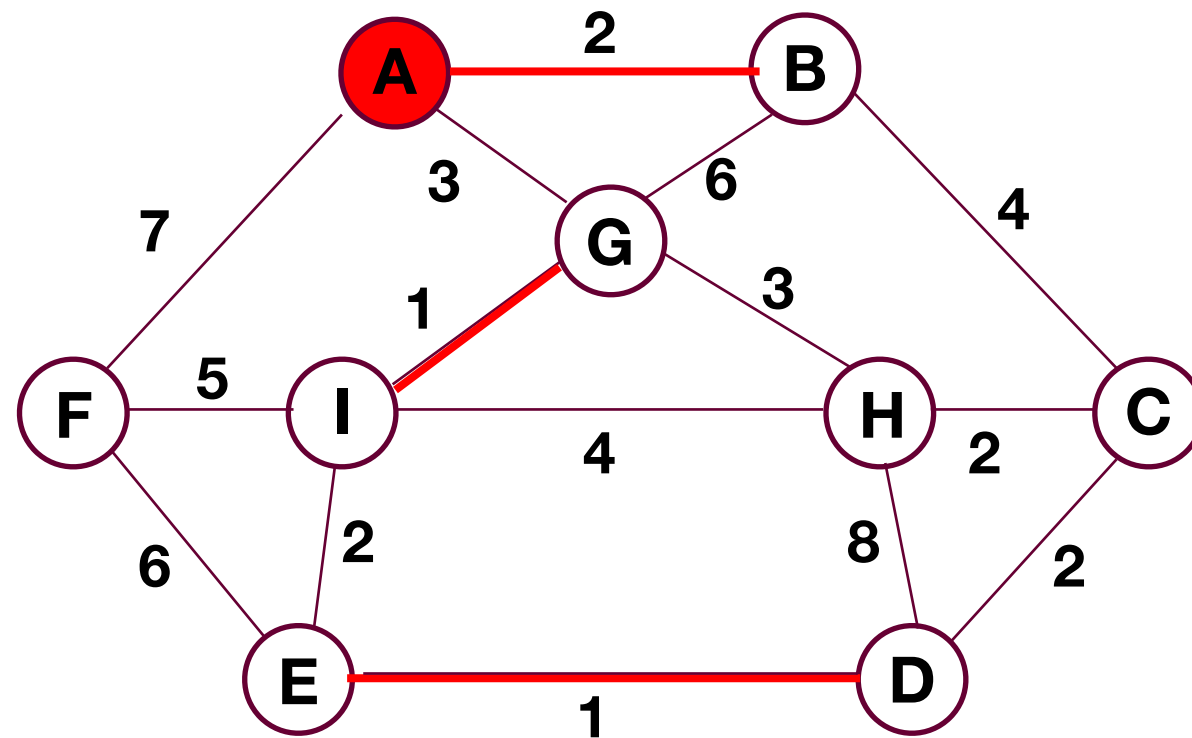
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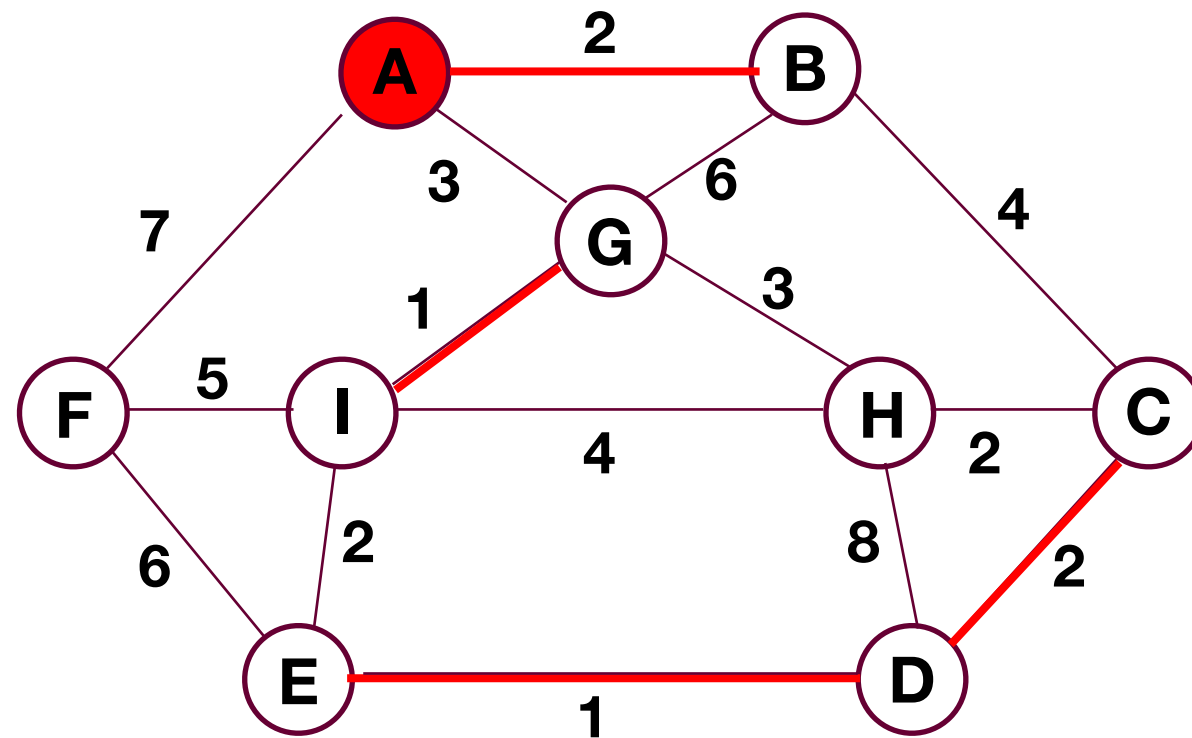


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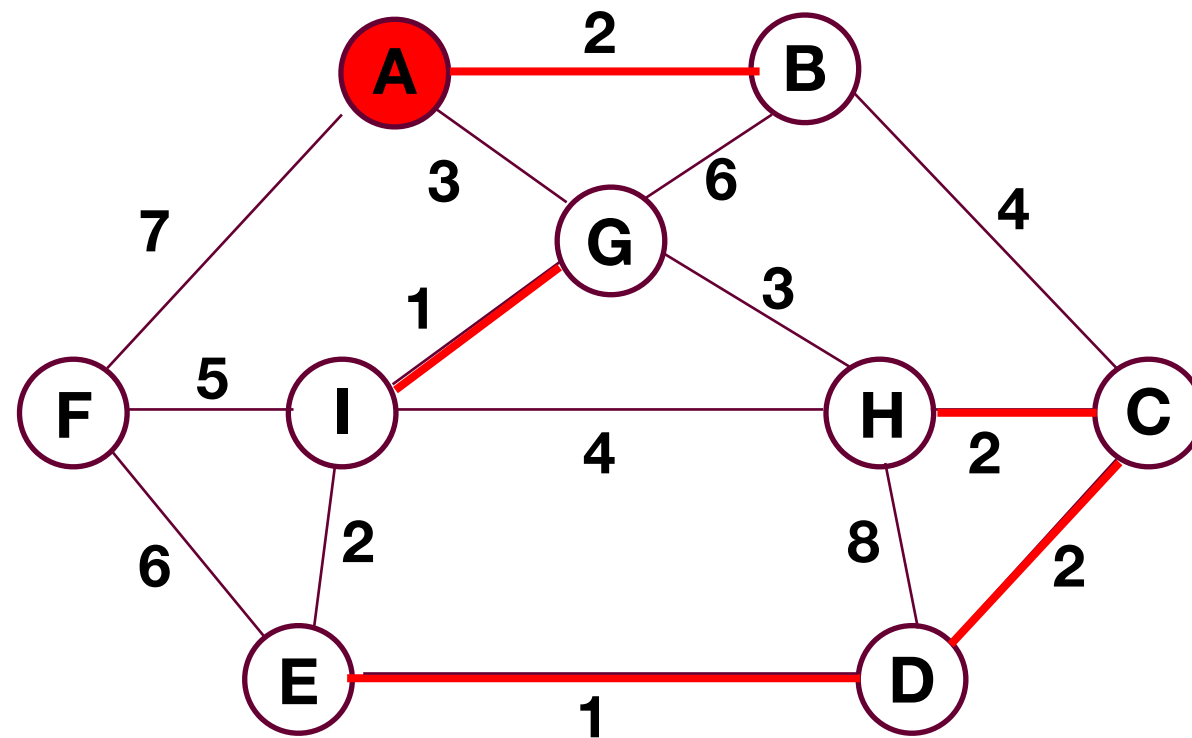


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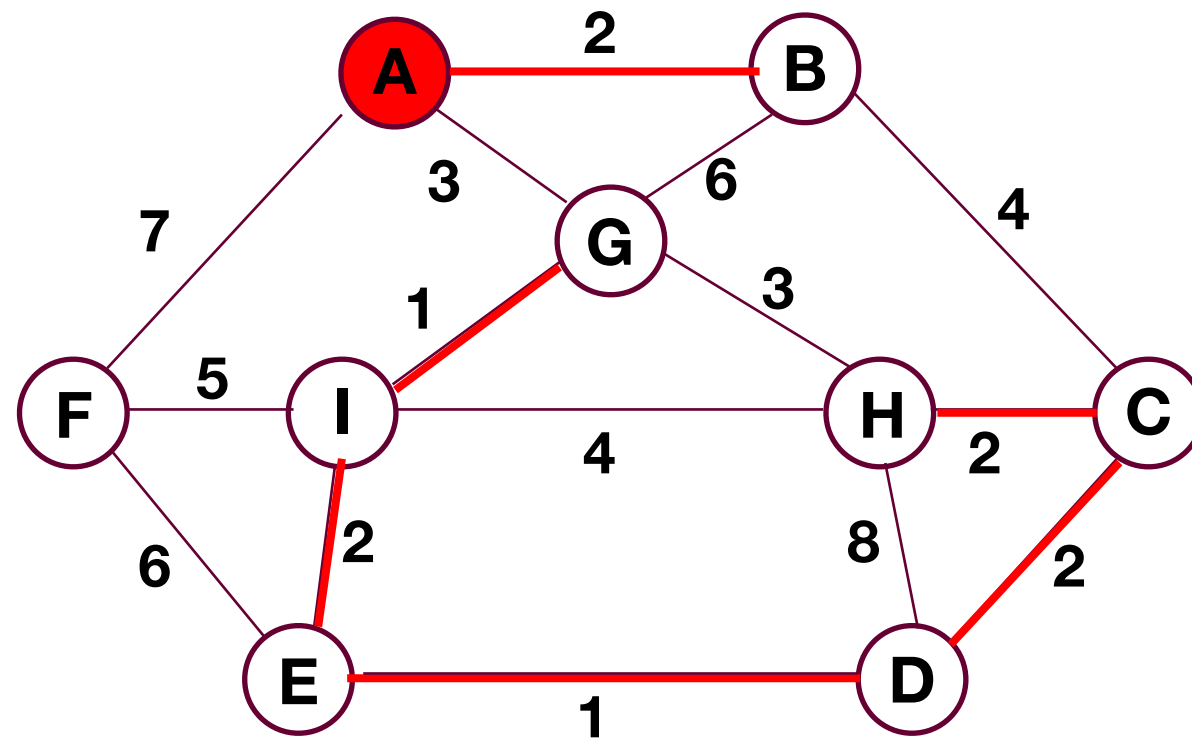


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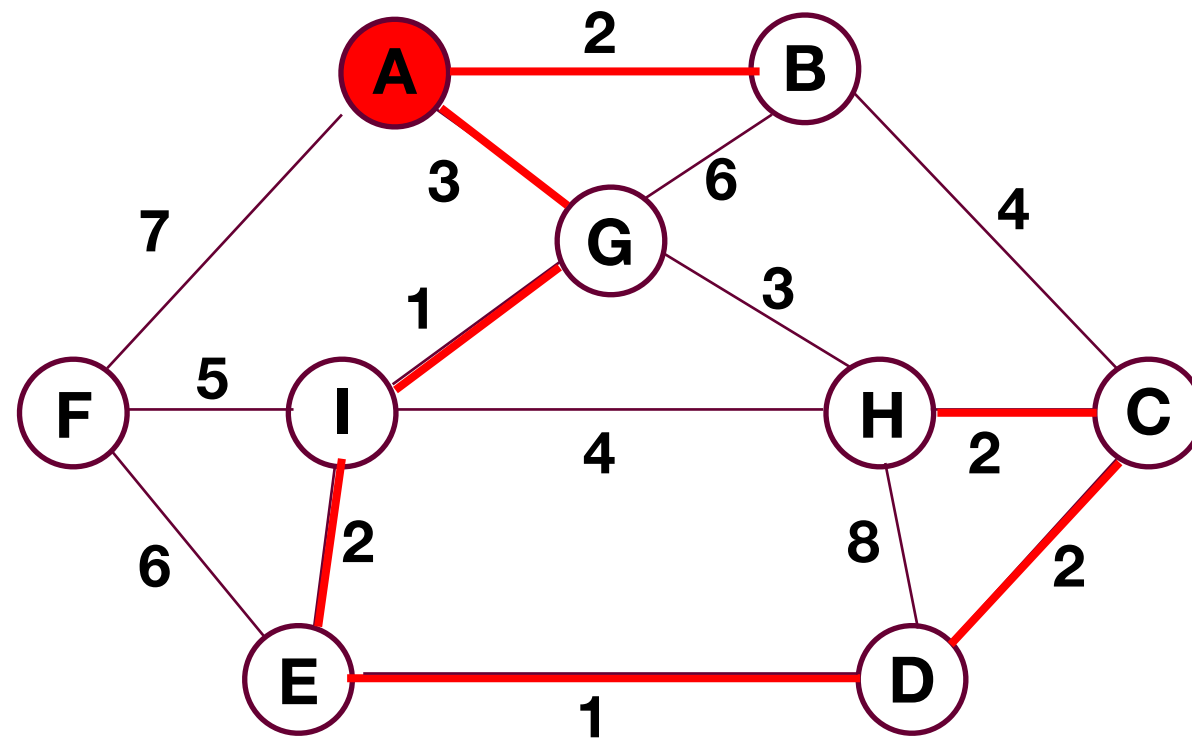
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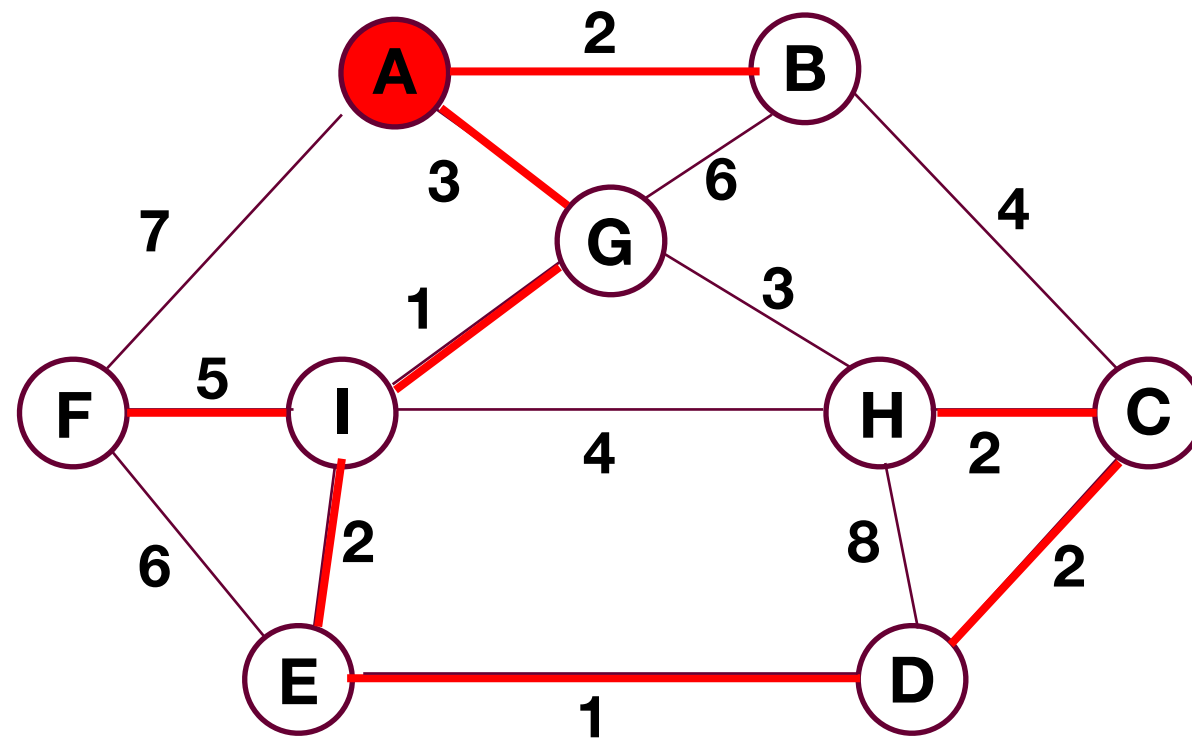
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# Key Issue in Implementation

- How to know an insertion of edge will result in a cycle **efficiently**?
- For correctness: the two endpoints of the selected edge **cannot** be in the same connected components.
- For the efficiency: connected components are implemented as dynamic equivalence classes using union-find.



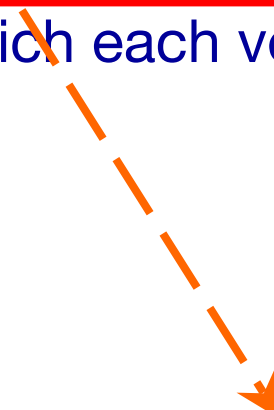
# Kruskal's Algorithm: the Procedure

- `kruskalMST(G,n,F) //outline`
- **int** count;
- Build a minimizing priority queue, pq, of edges of G, prioritized by weight.
- Initialize a Union-Find structure, sets, in which each vertex of G is in its own set.
- 
- $F = \phi$ ;
- **while** (`isEmpty(pq) == false`)
- `vwEdge = getMin(pq);`
- `deleteMin(pq);`
- **int** vSet = `find(sets, vwEdge.from);`
- **int** wSet = `find(sets, vwEdge.to);`
- **if** (`vSet  $\neq$  wSet`)
- Add vwEdge to F;
- `union(sets, vSet, wSet)`
- **return**

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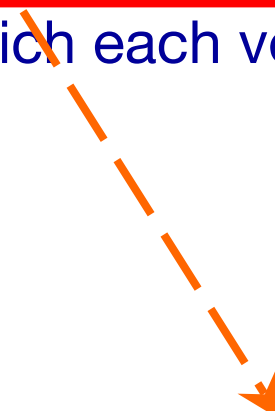
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Simply sorting, the cost will  
be  $\Theta(m \log m)$

# Prim vs. Kruskal

- Lower bound for MST
  - For a correct MST, each edge in the graph should be examined at least once.
  - So, the lower bound is  $\Omega(m)$ .
- $\Theta(n^2+m)$  and  $\Theta(m \log m)$ , which is better?
  - Generally speaking, depends on the density of edge of the graph.

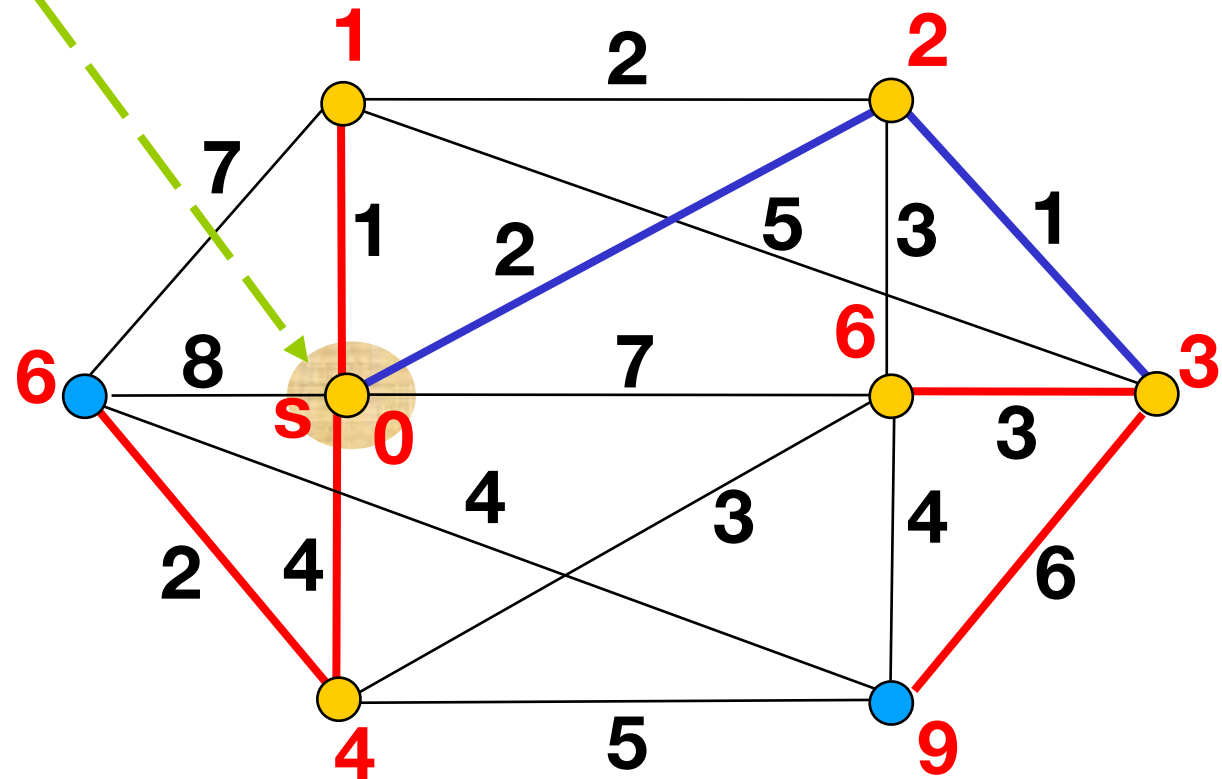
# Single Source Shortest Paths

The single source

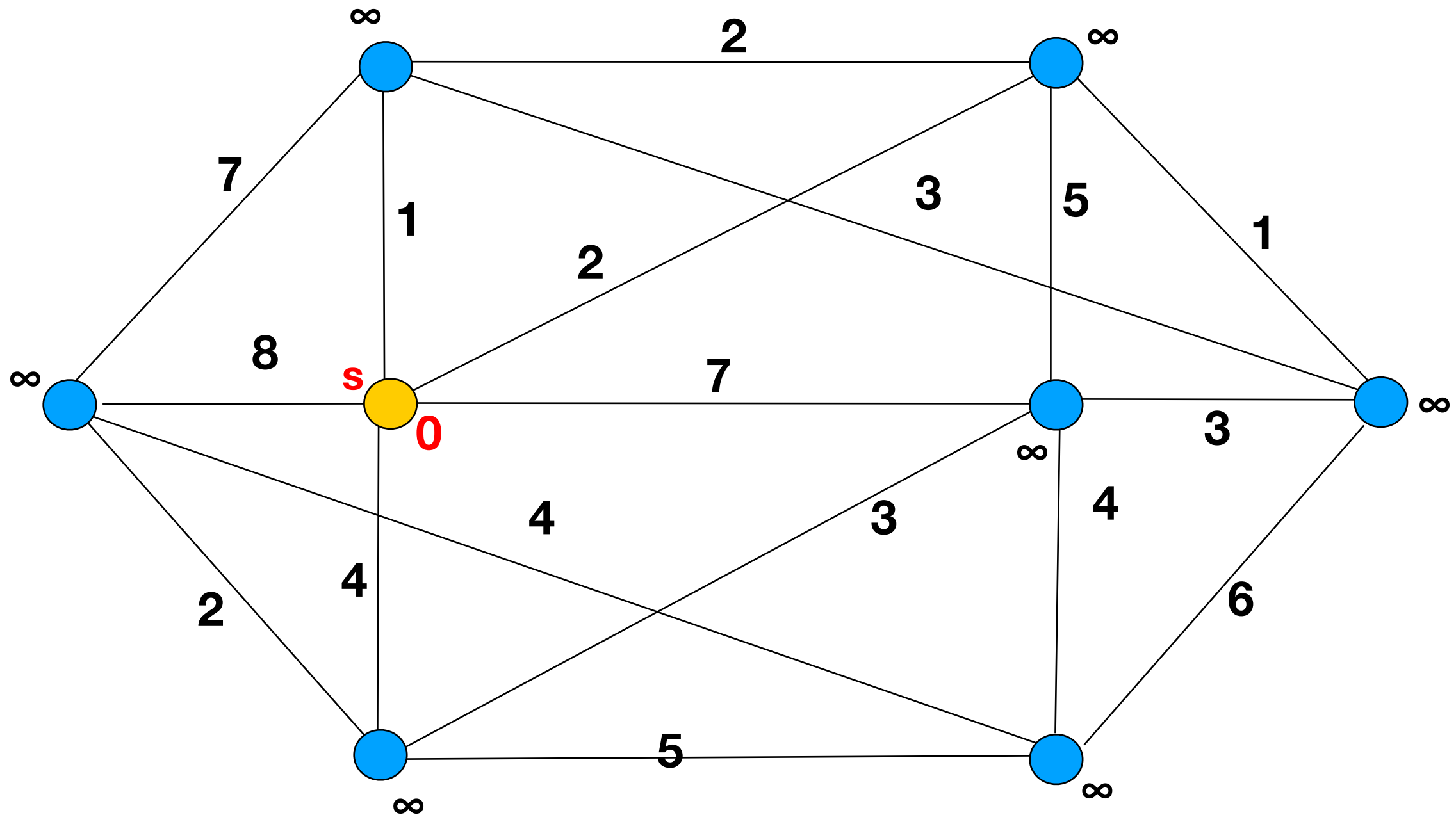
Red labels on each vertex is the length of the shortest path from  $s$  to the vertex.

Note:

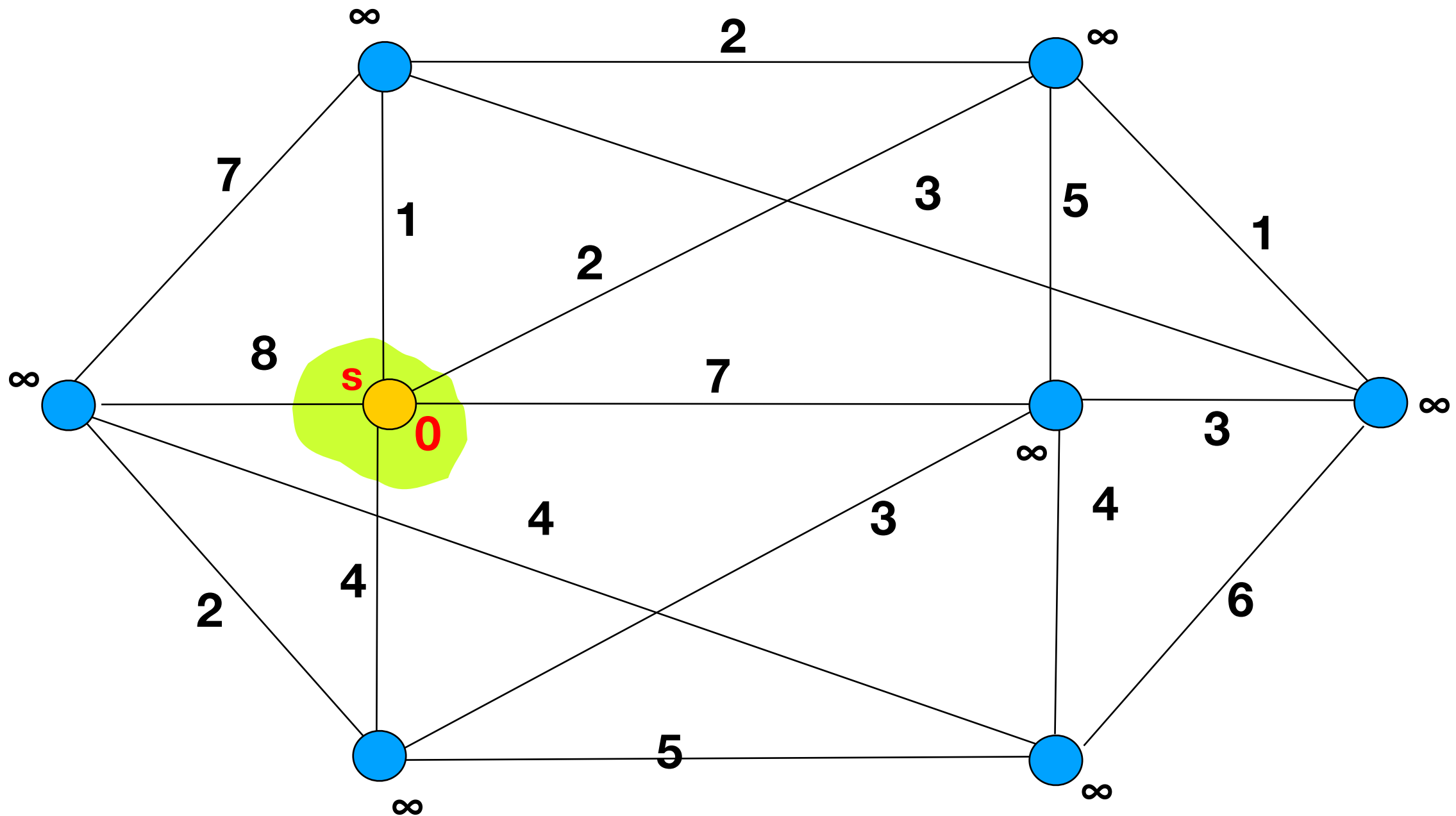
The shortest  $[0, 3]$ -path doesn't contain the shortest edge leaving  $s$ , the edge  $[0, 1]$



# Dijkstra's Algorithm: an Example

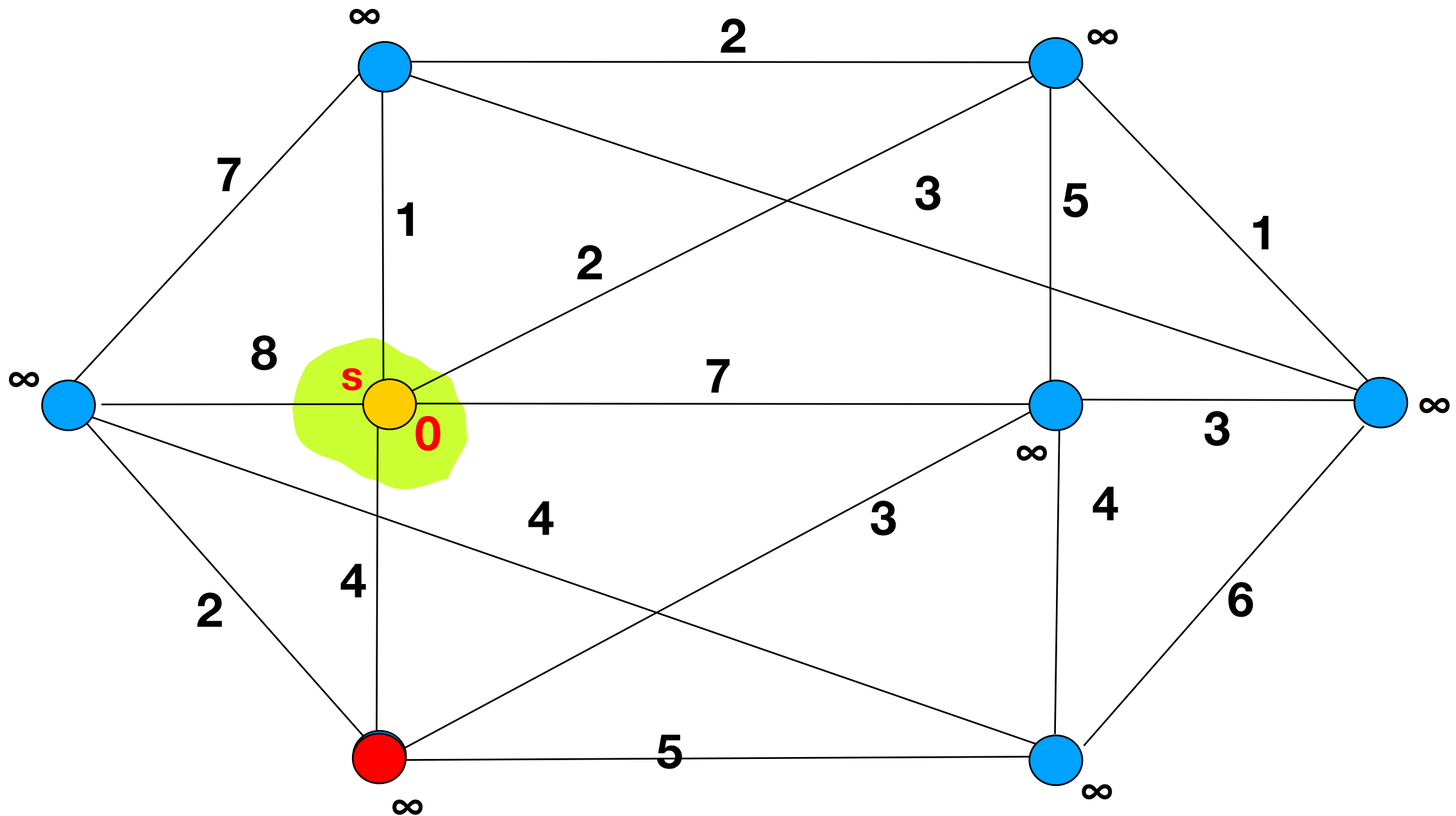


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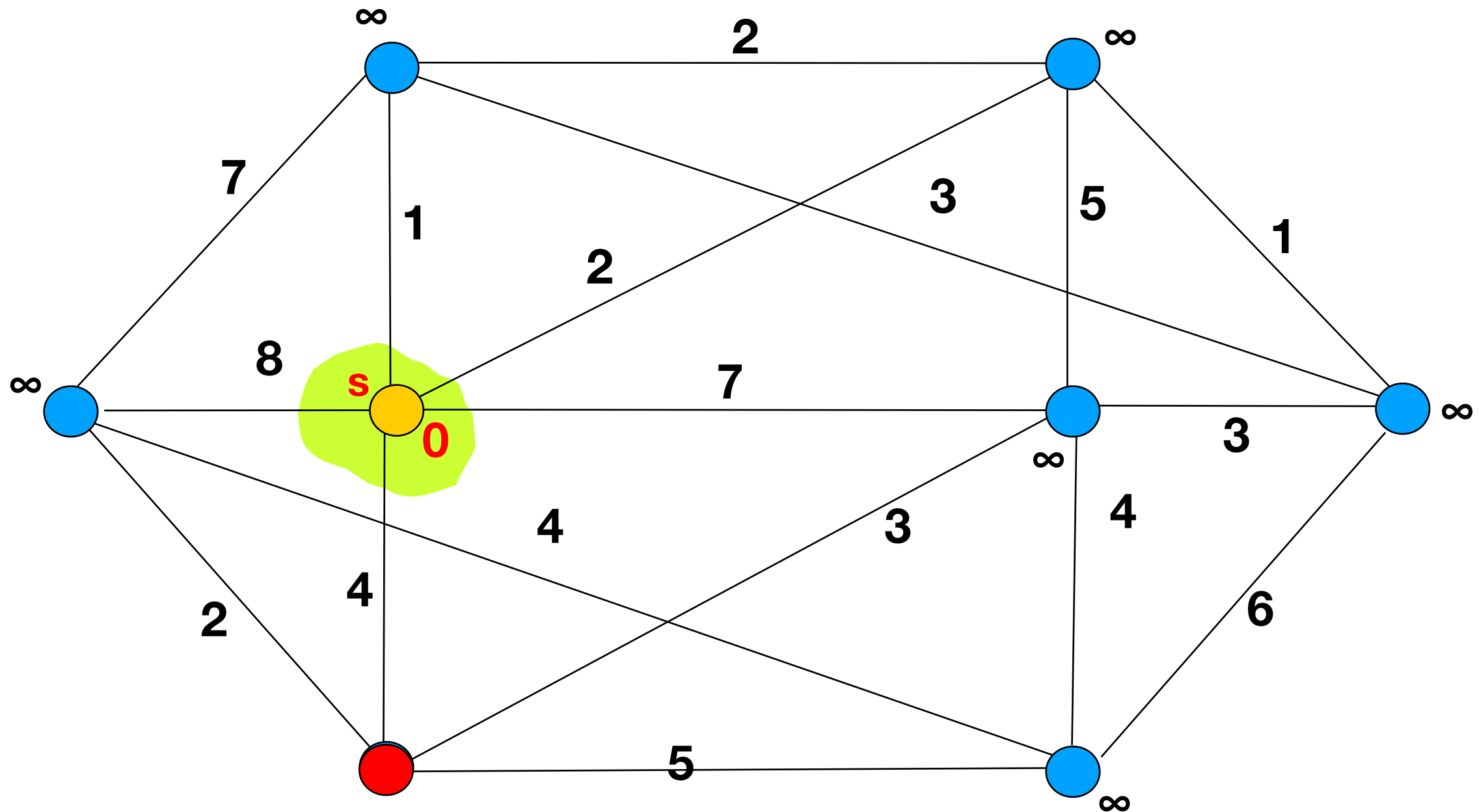




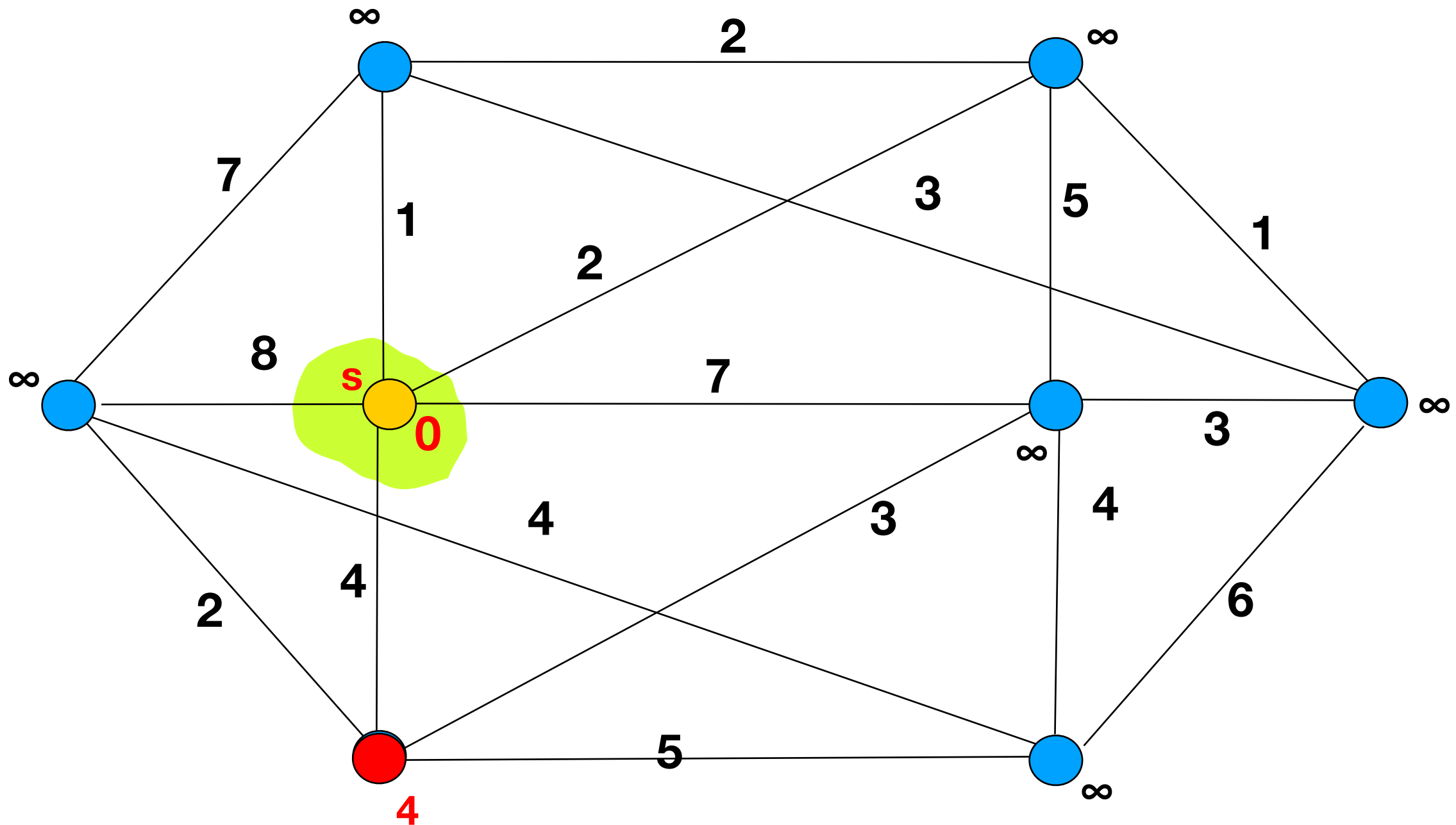
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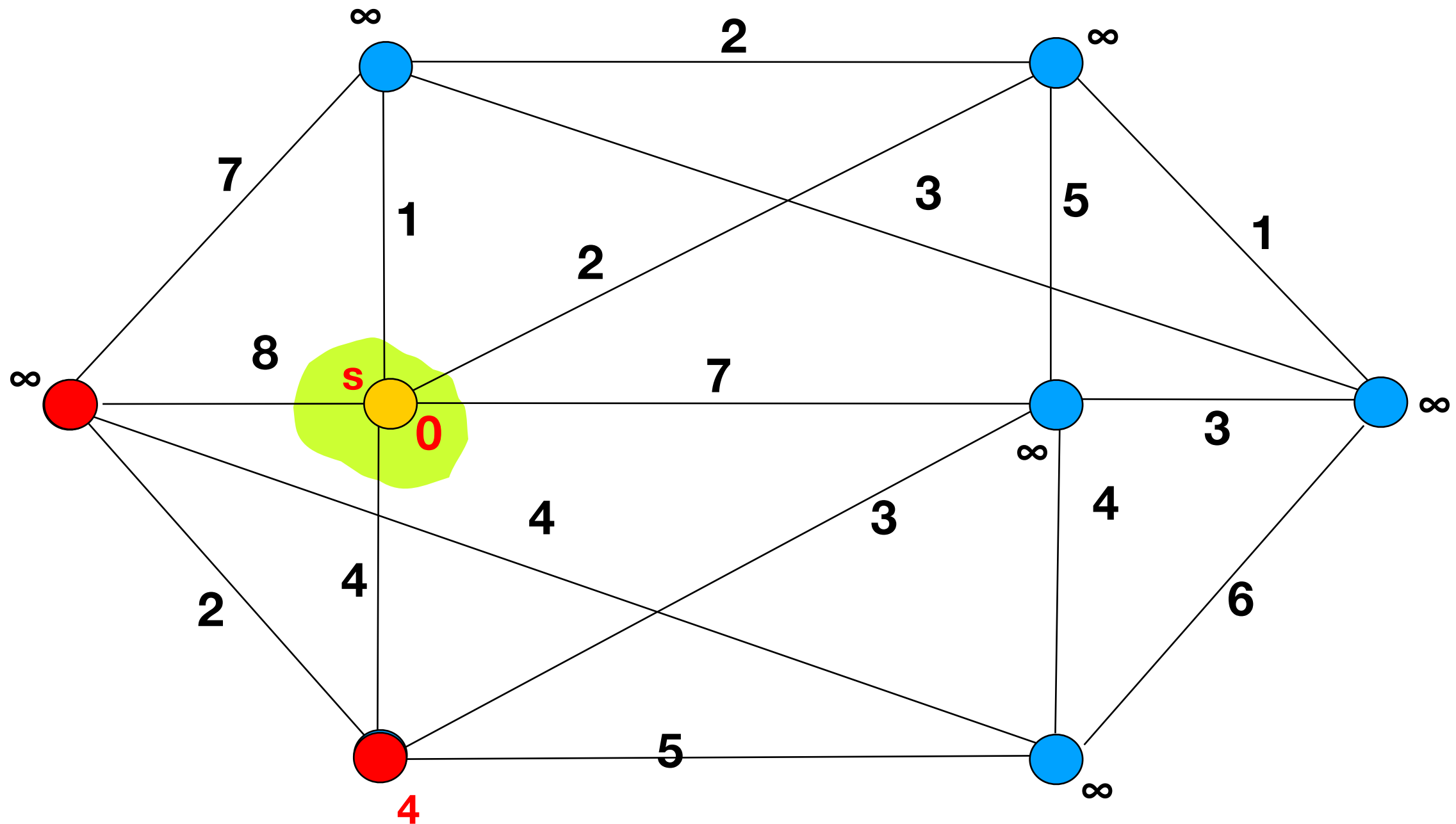
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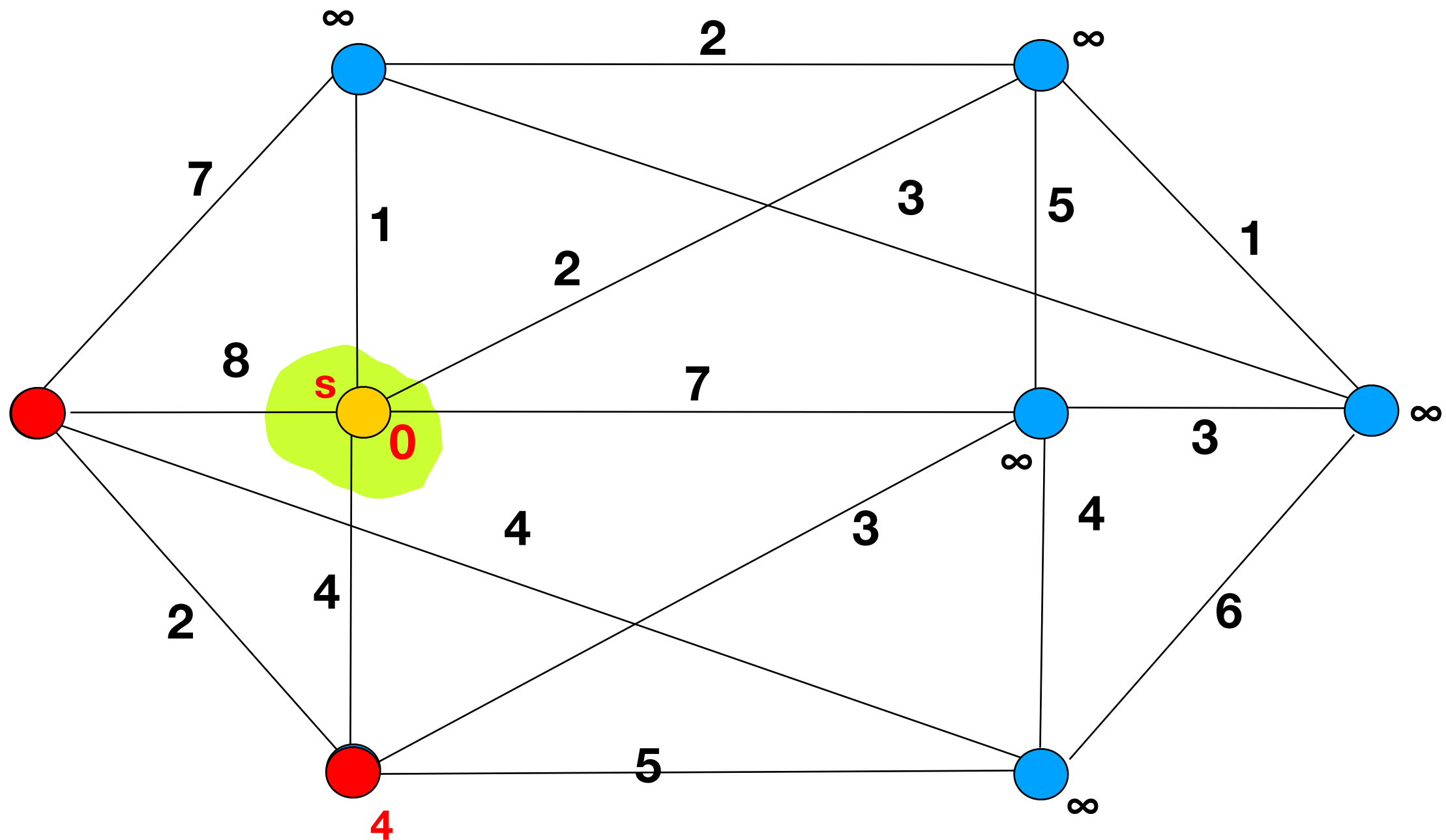
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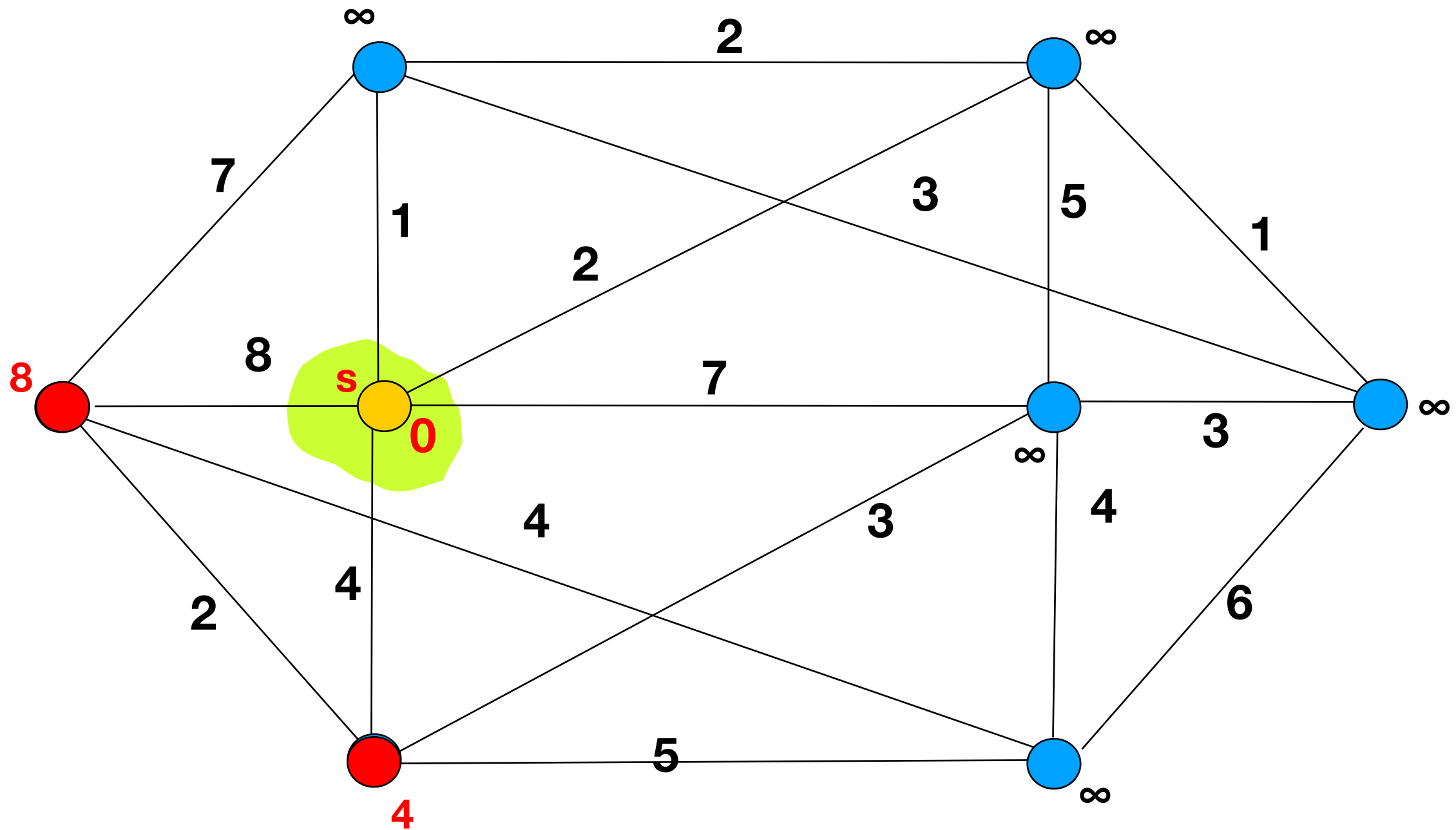
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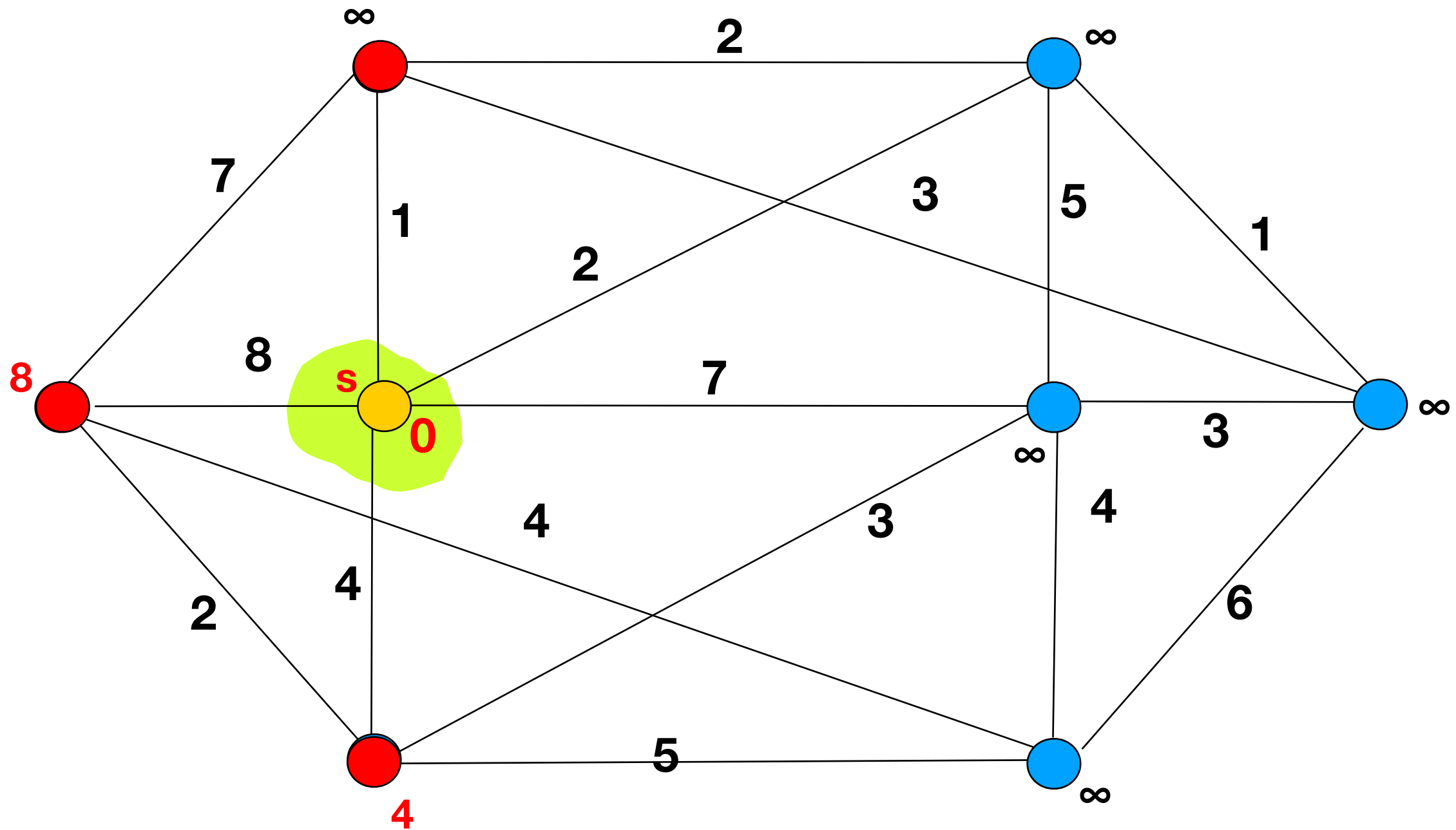
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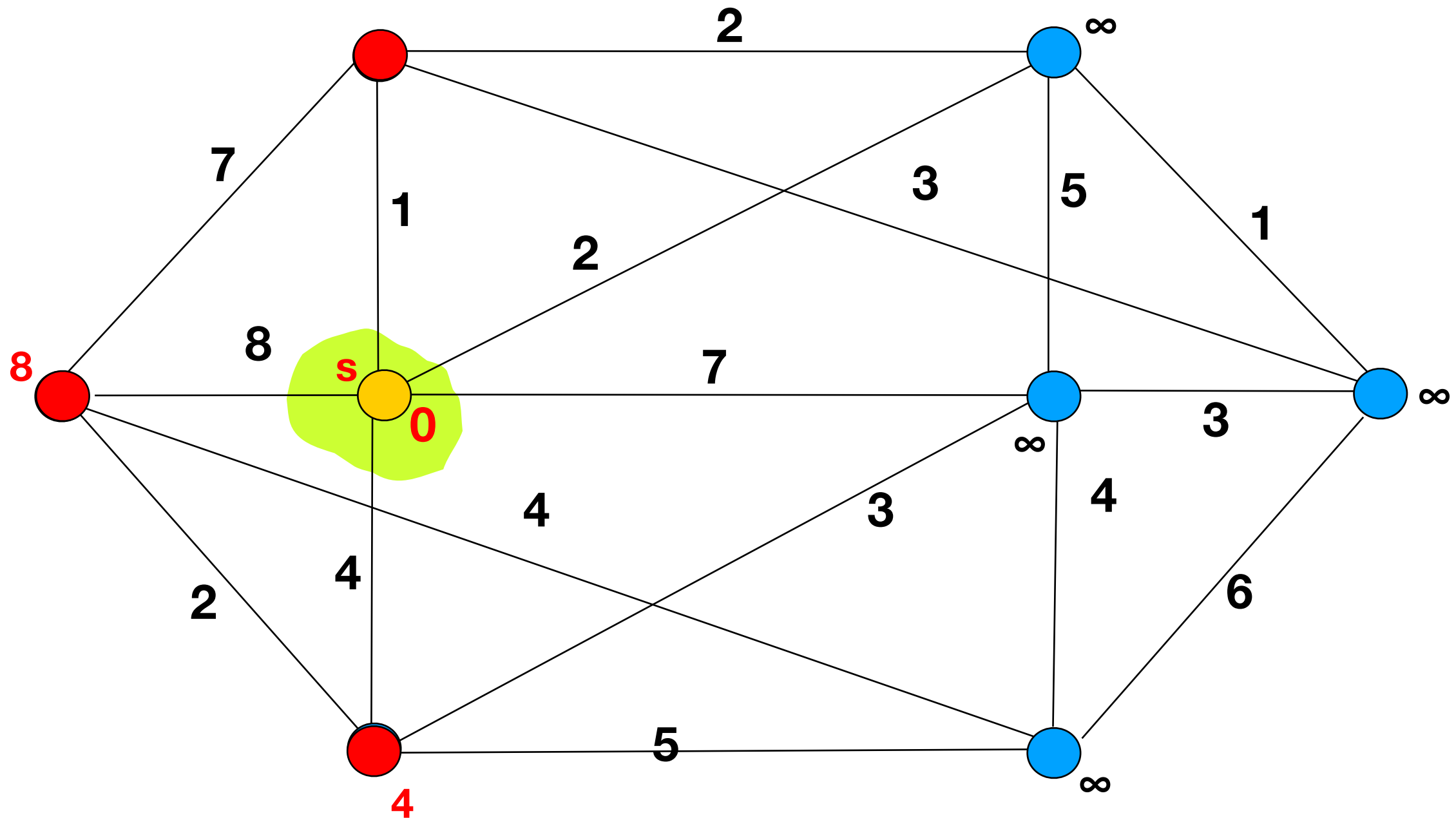
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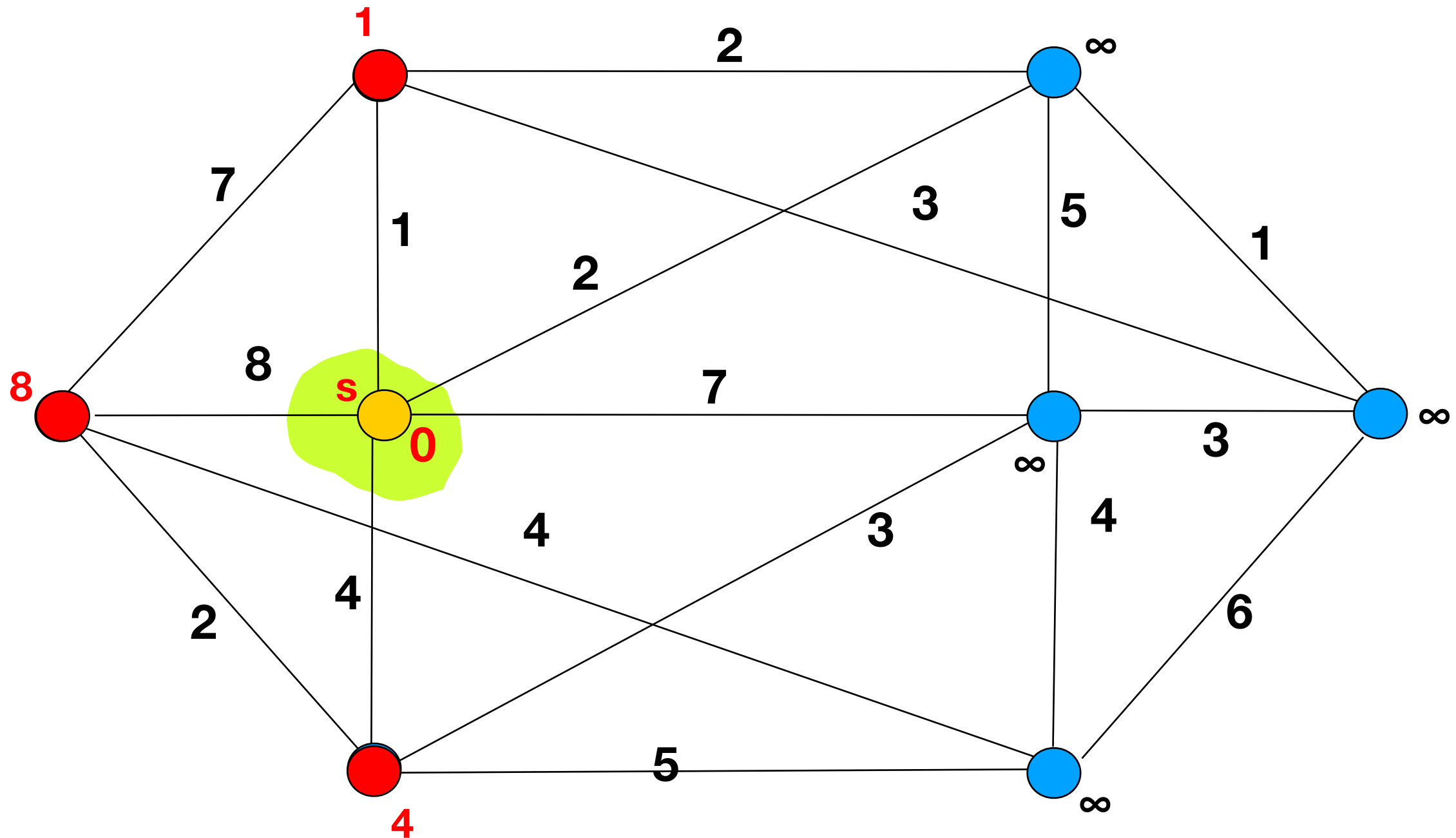


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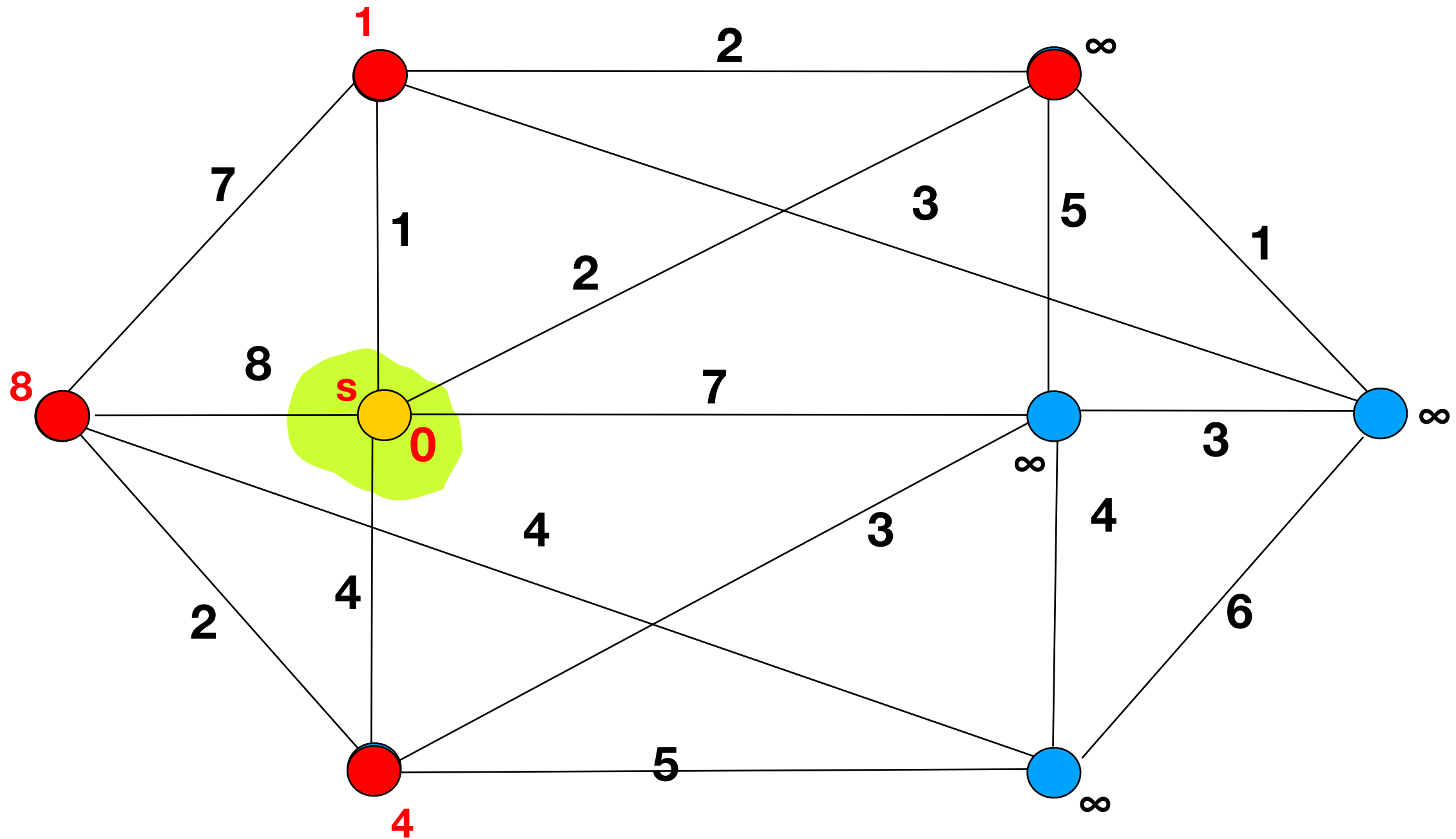




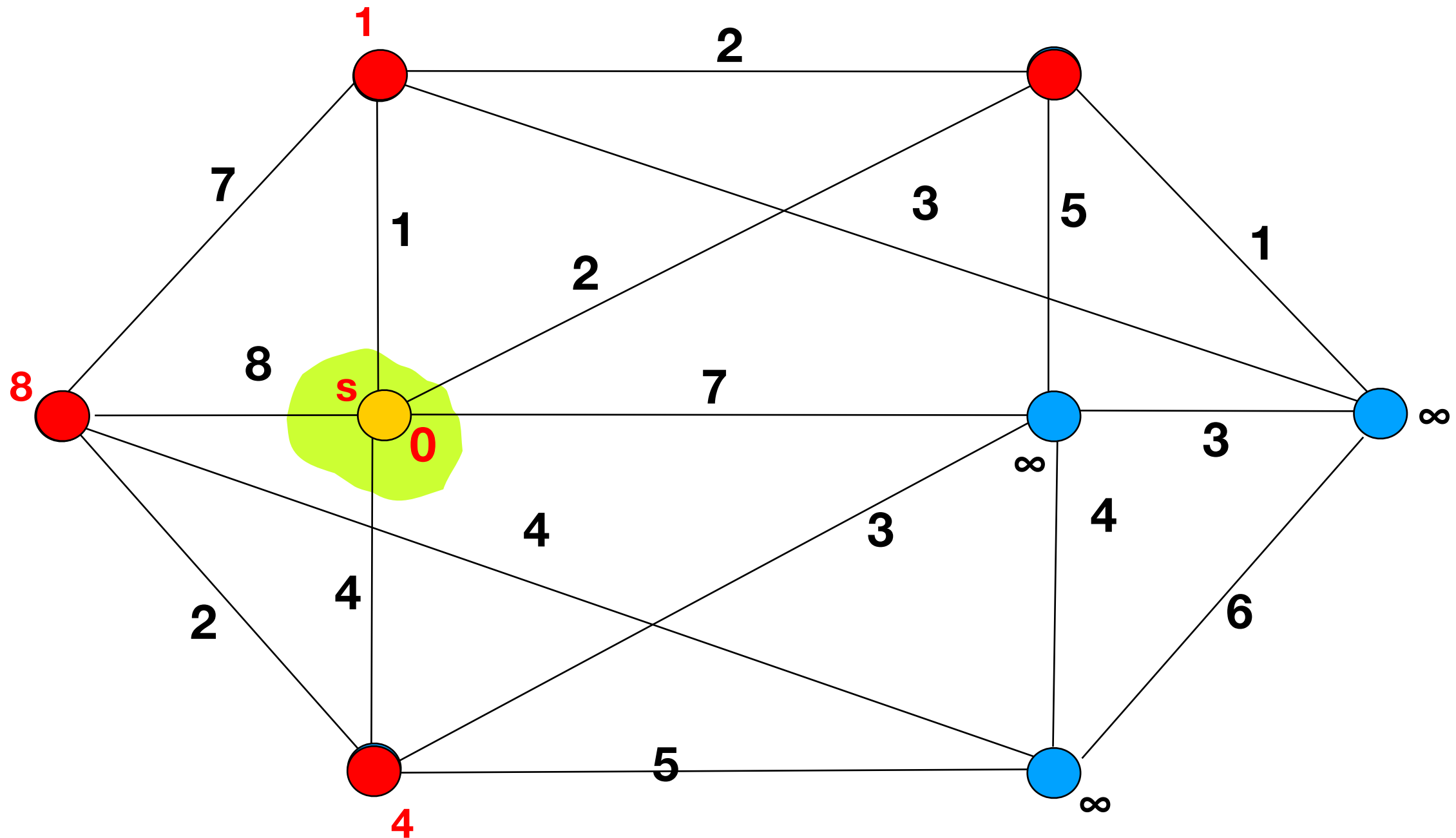
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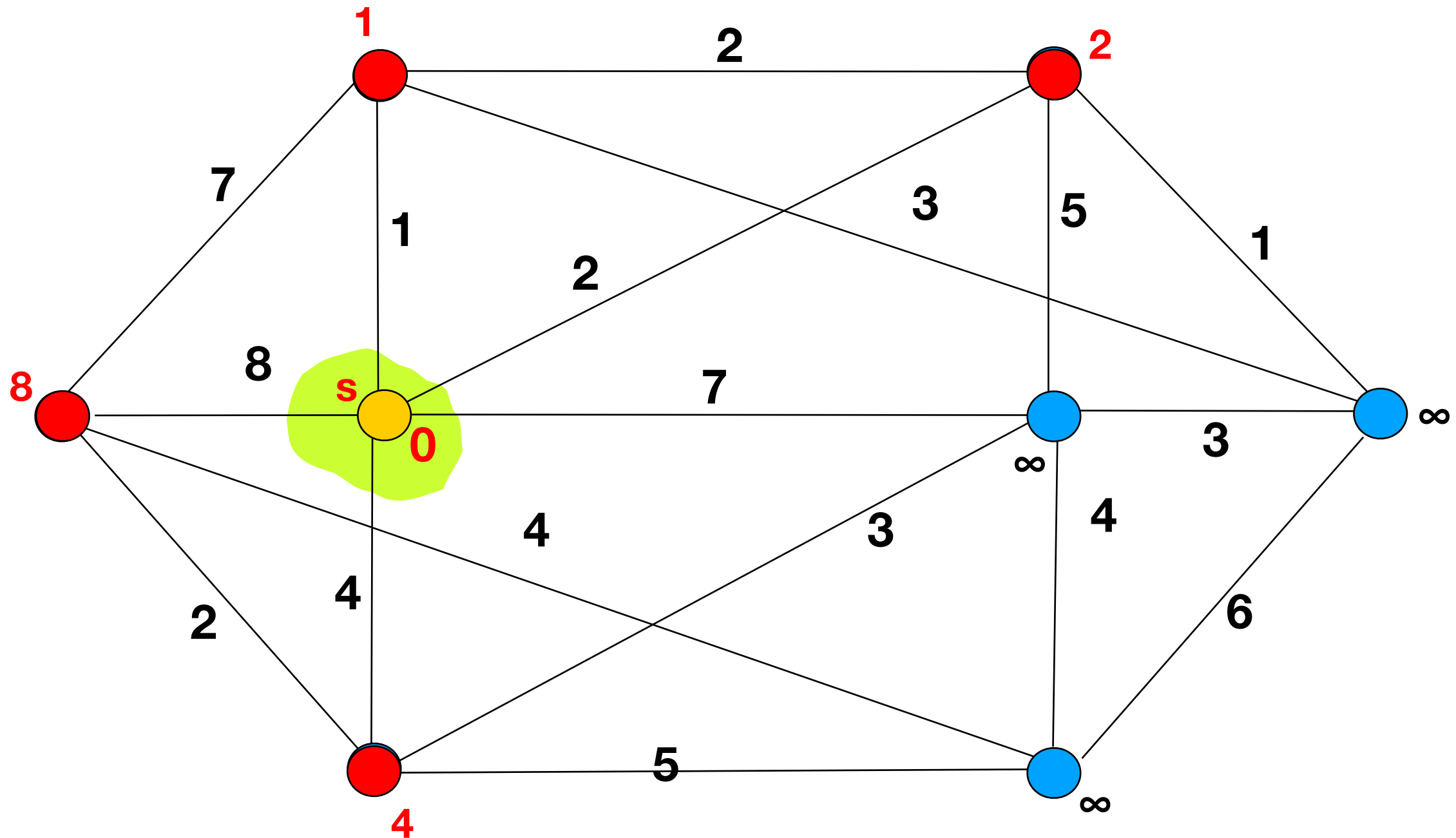
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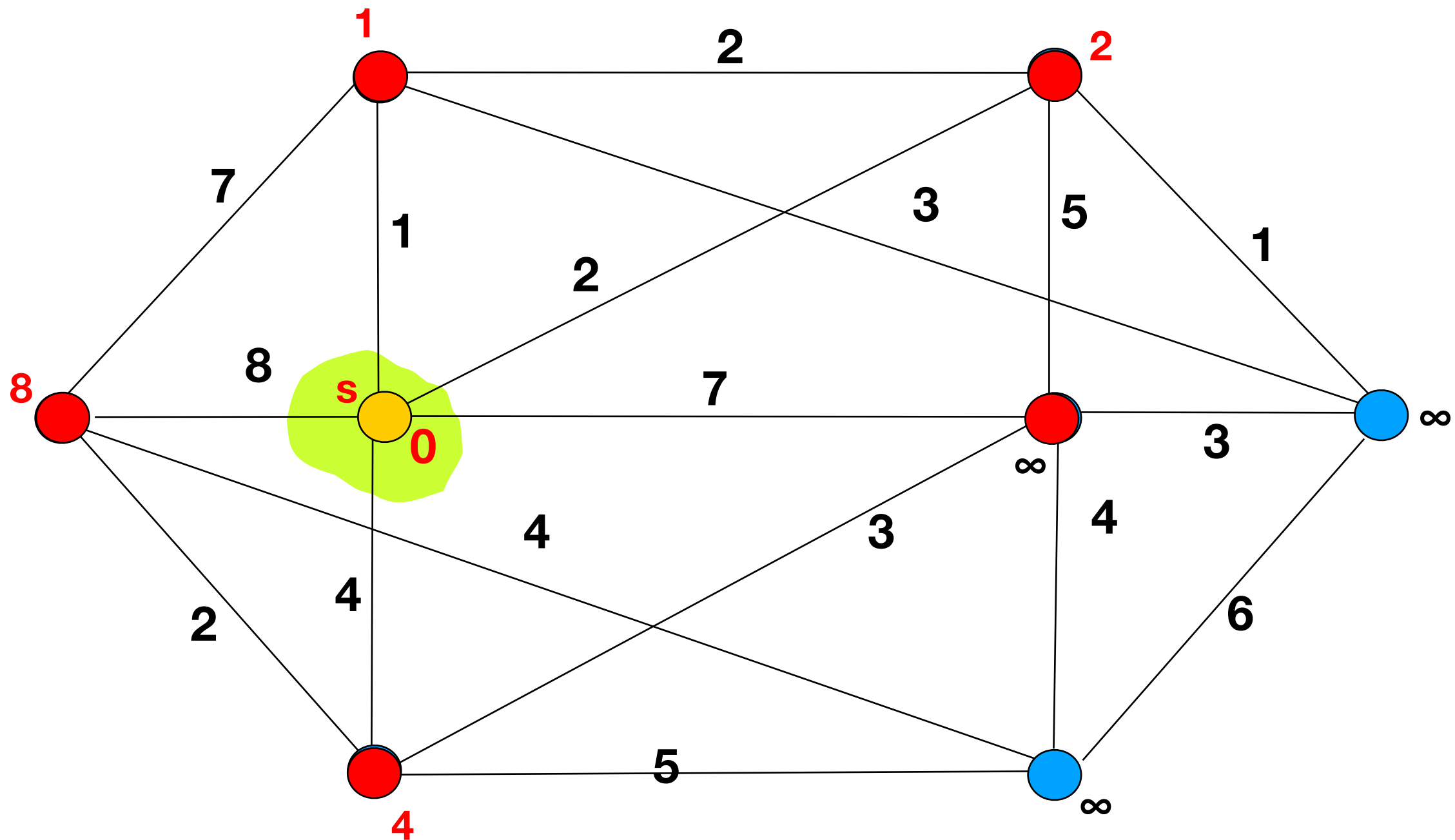
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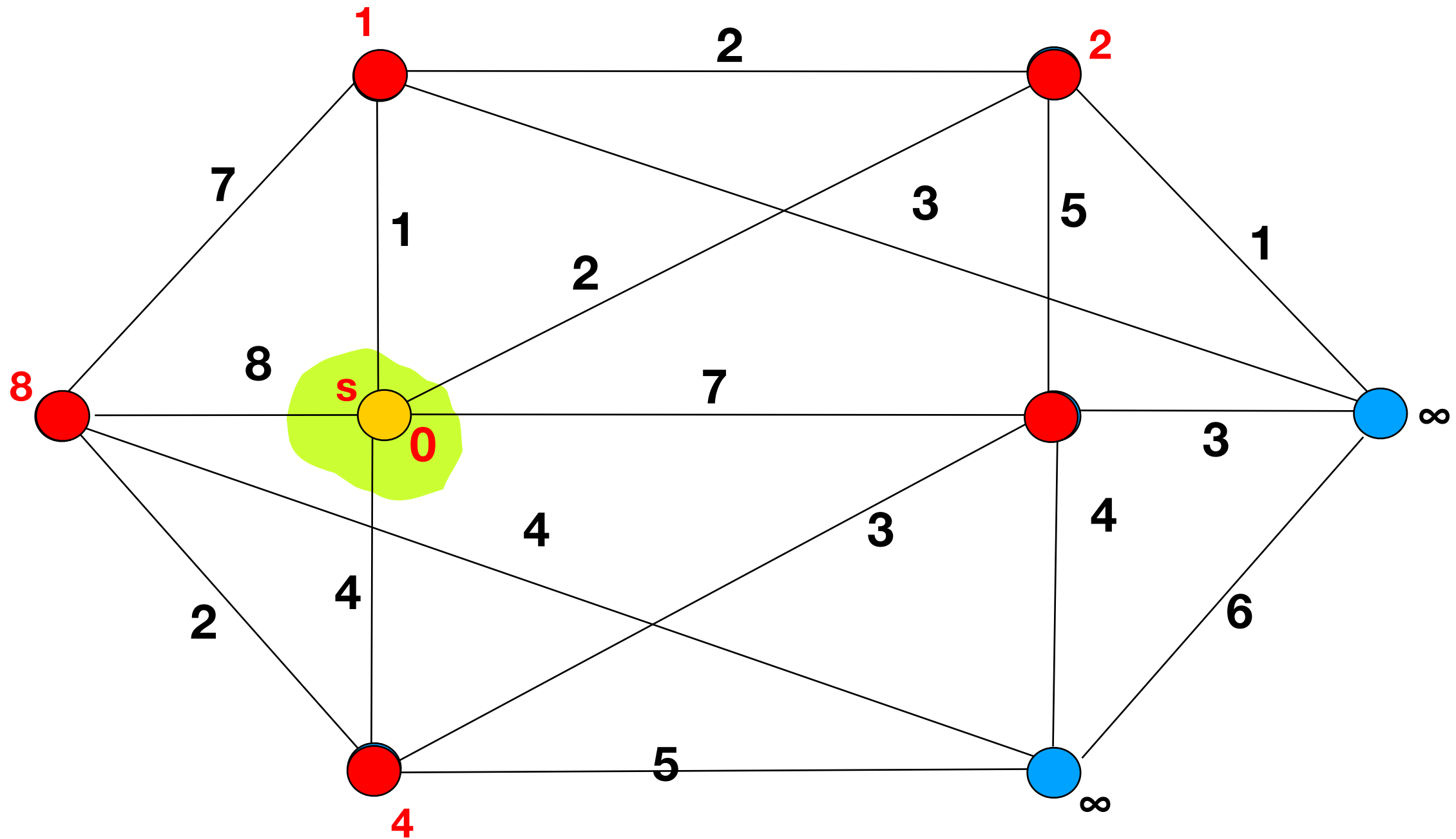
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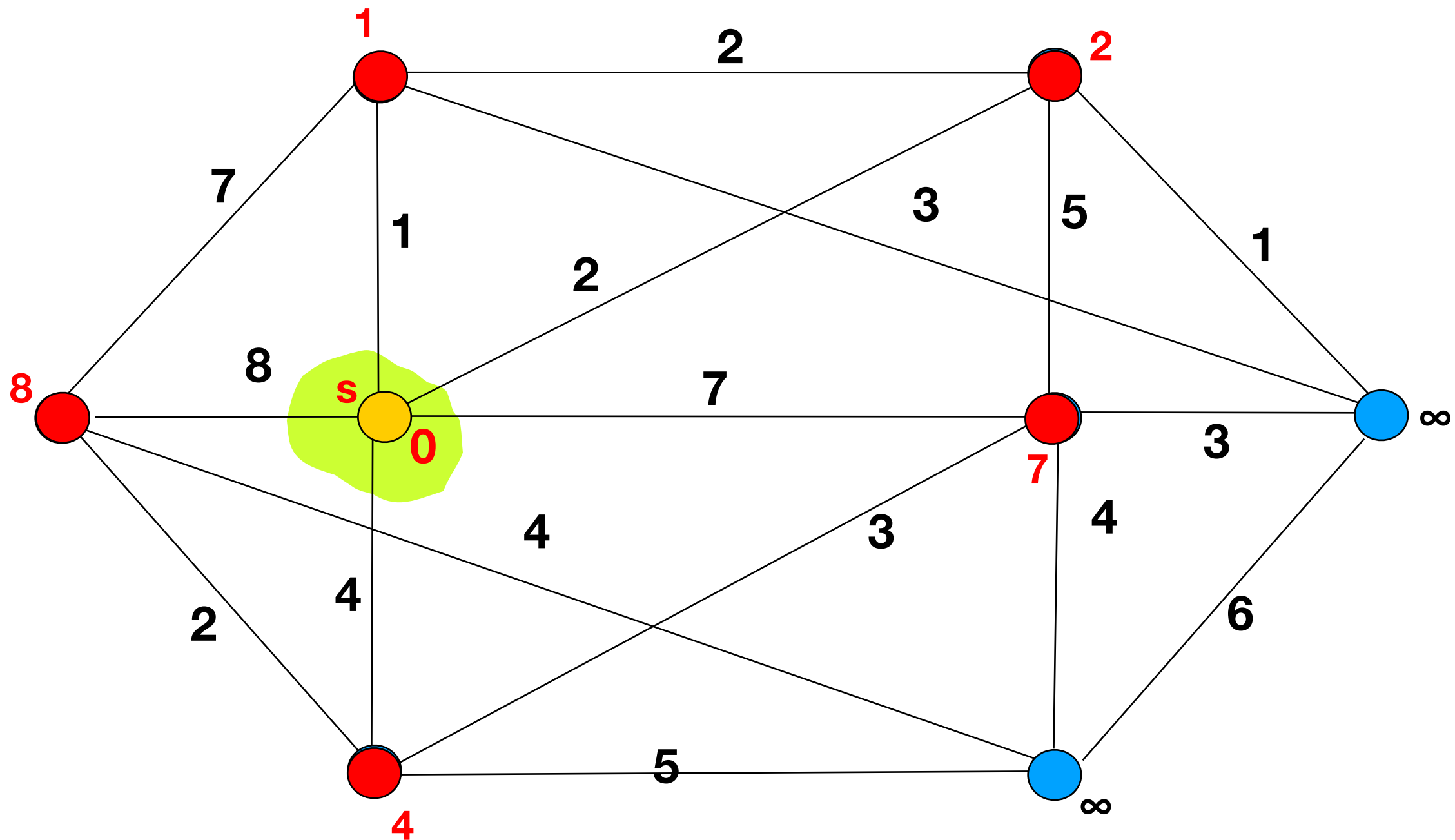
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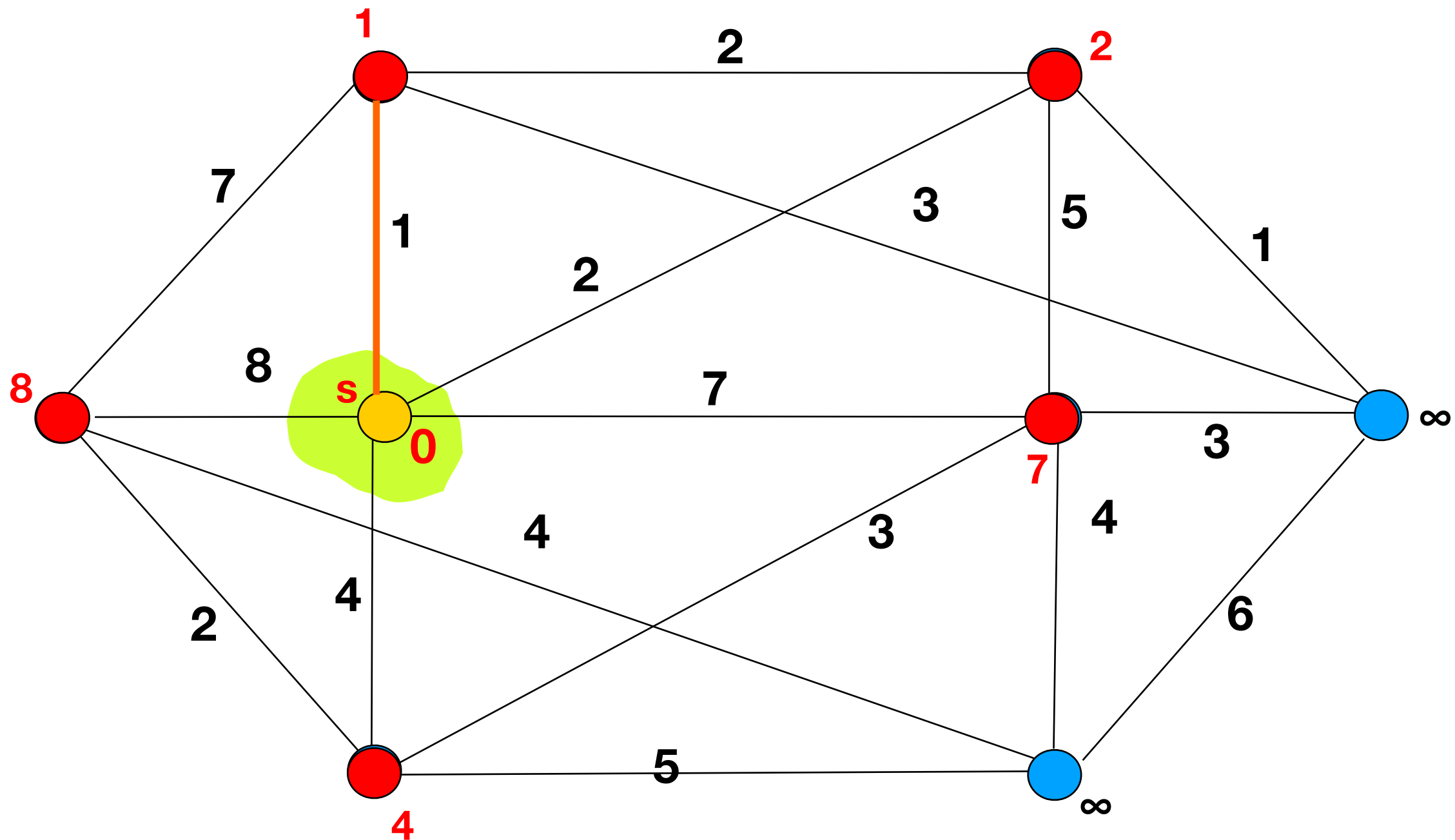
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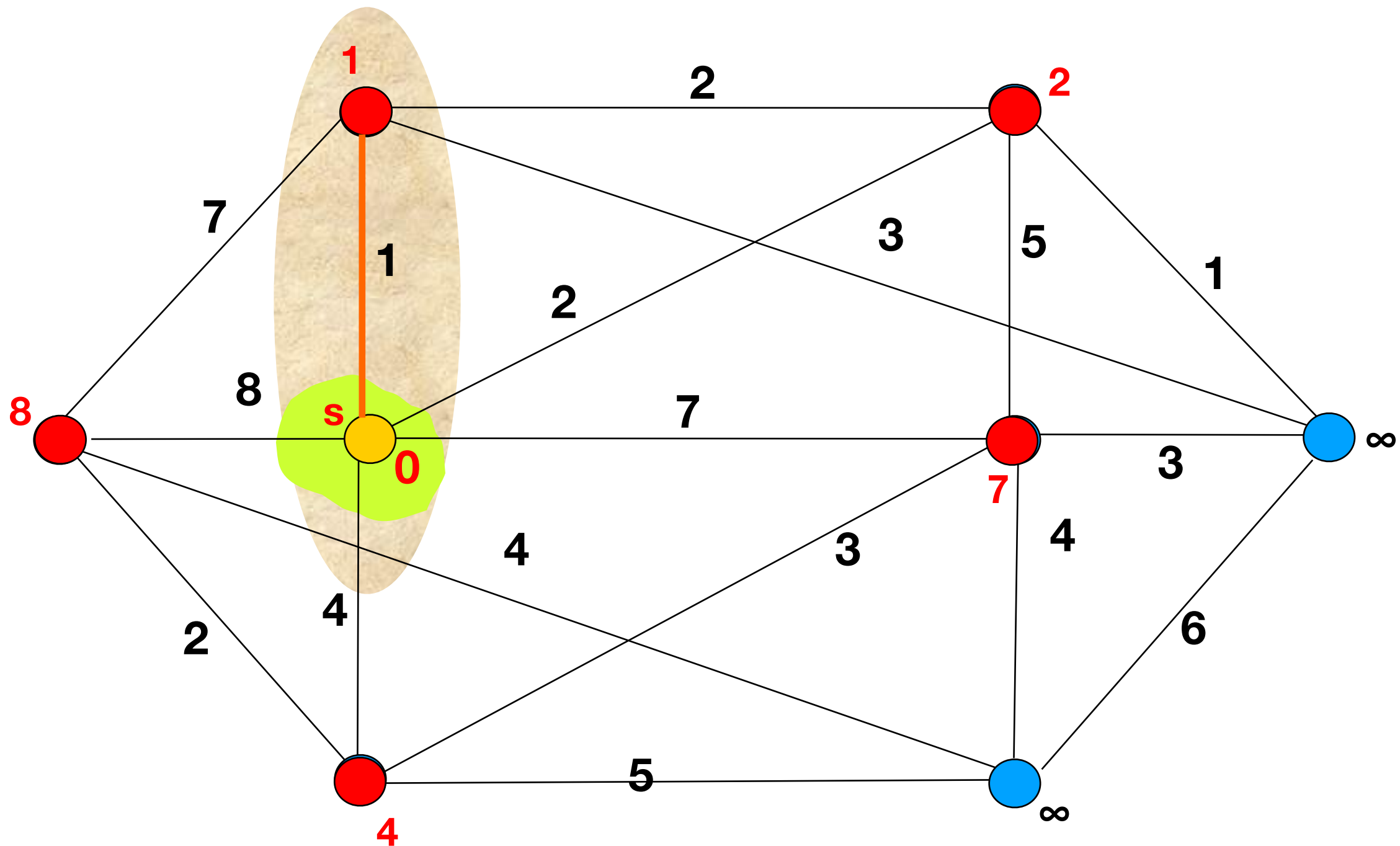


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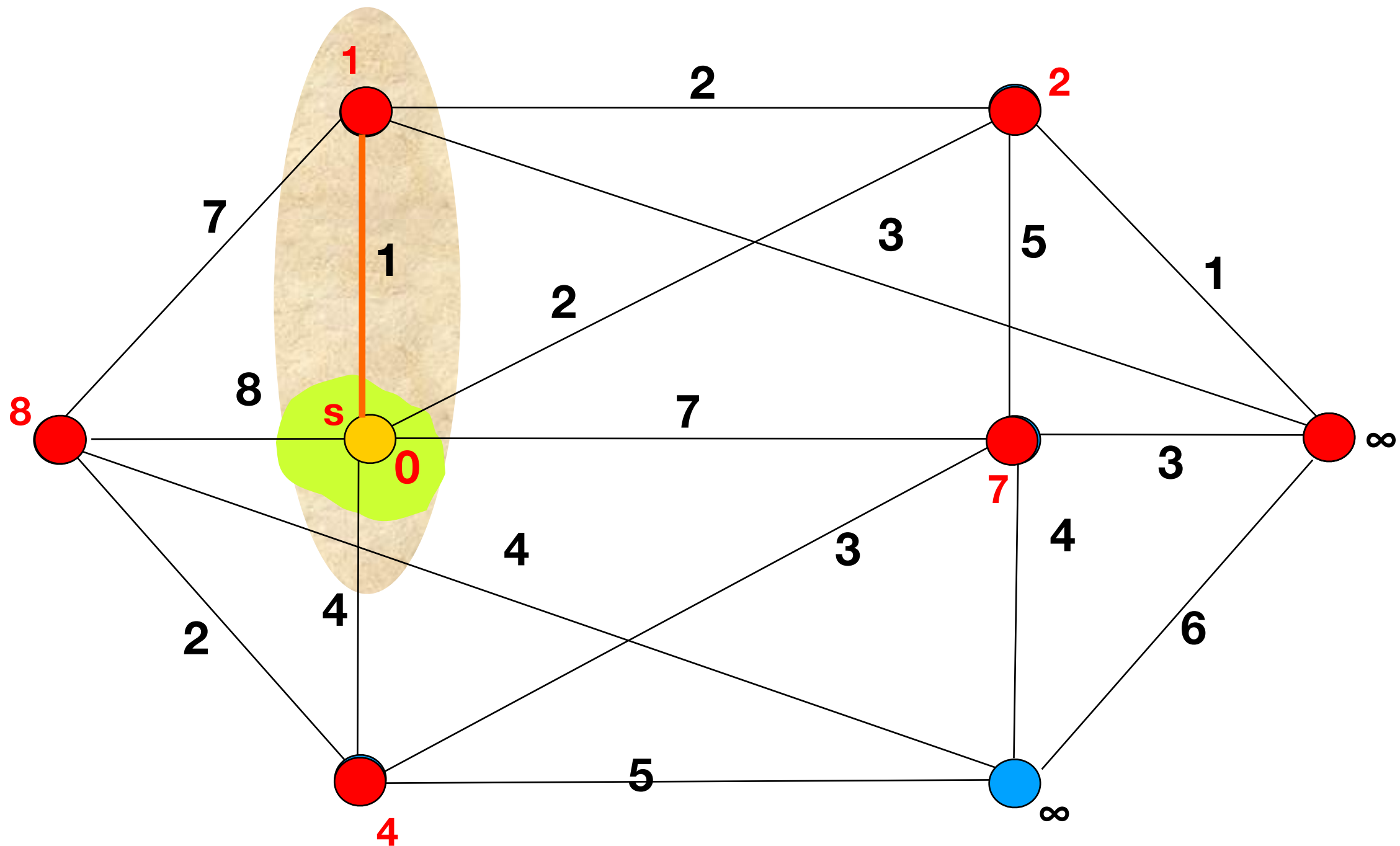




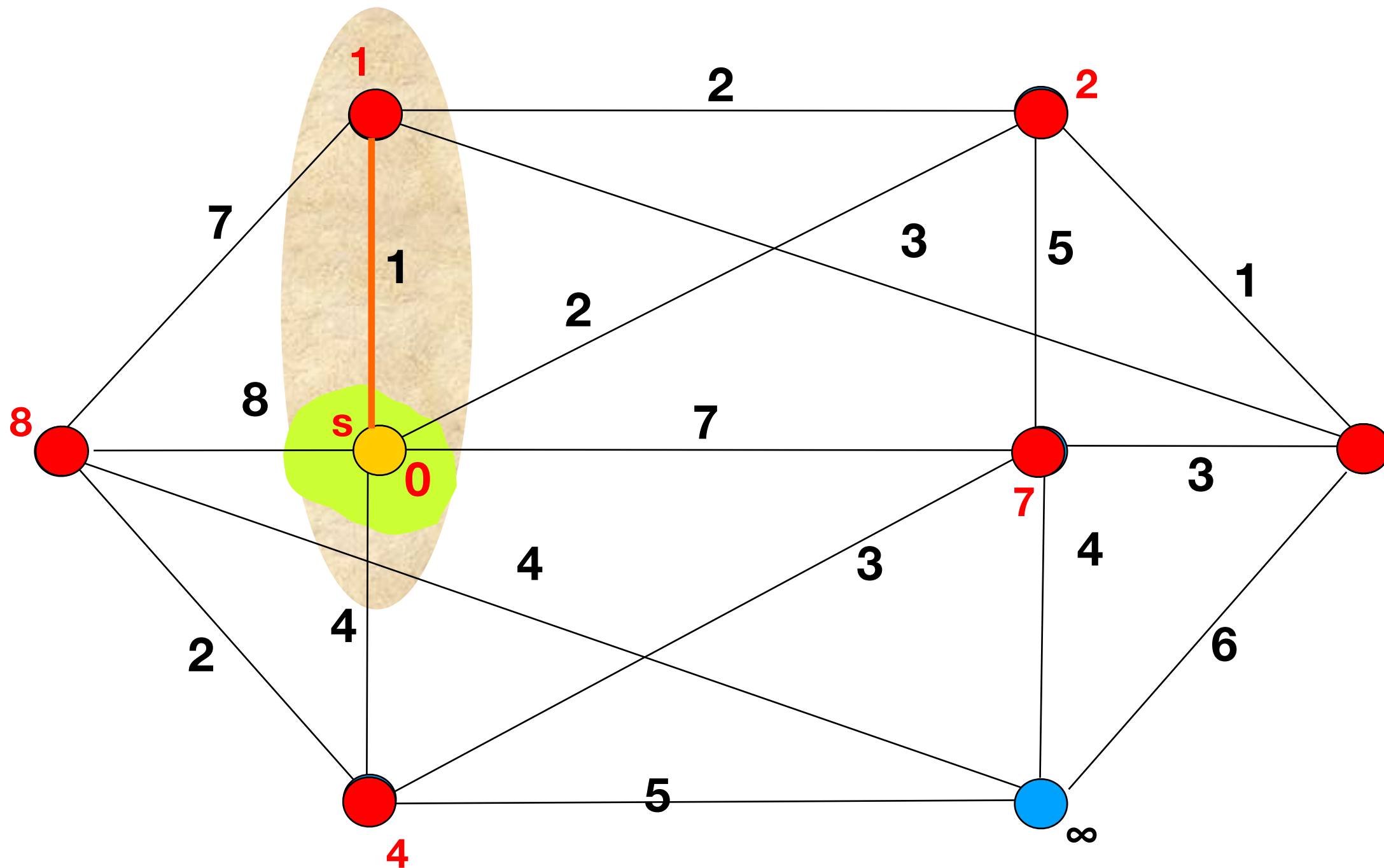
# Dijkstra's Algorithm: an Example



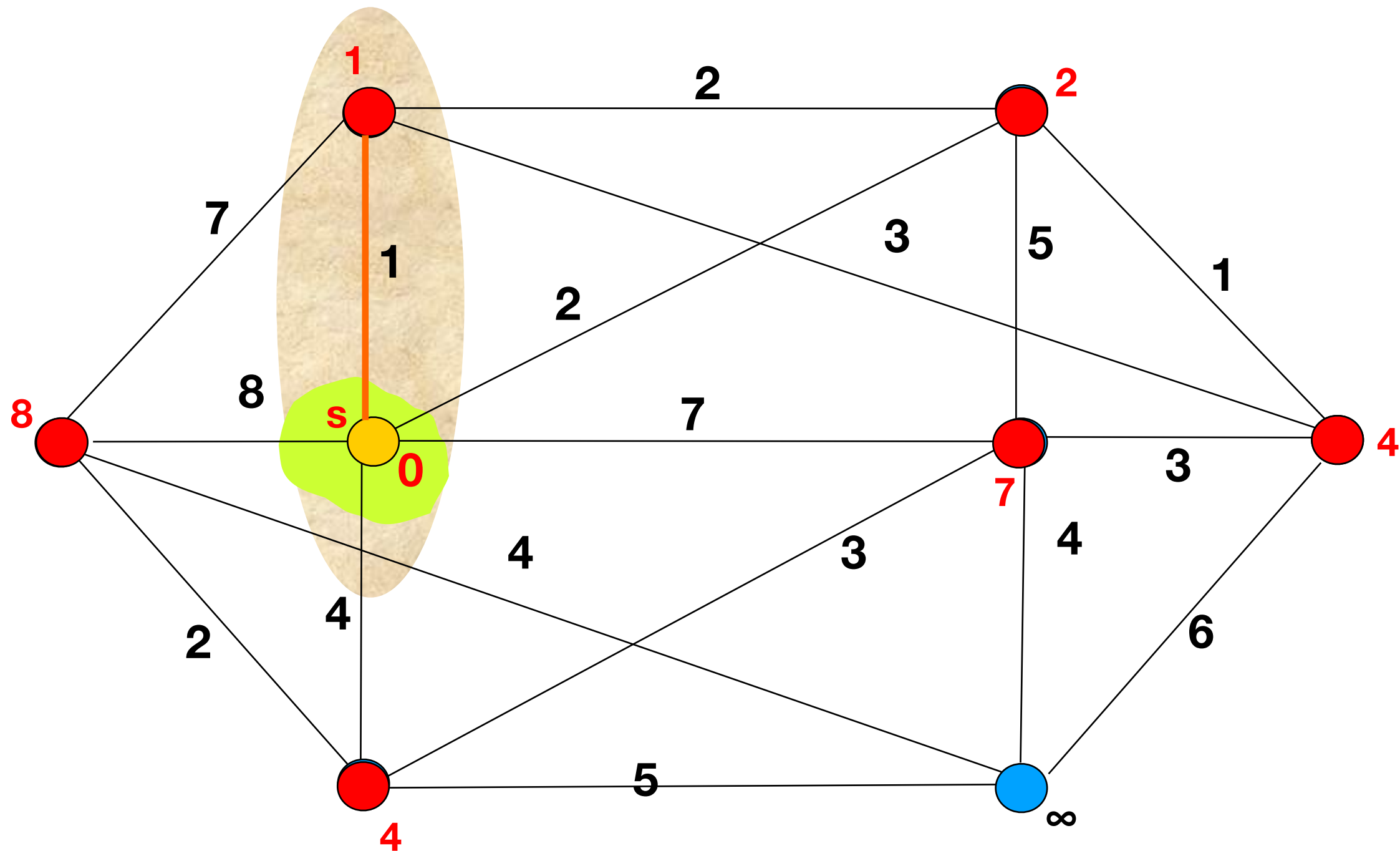
# Dijkstra's Algorithm: an Example



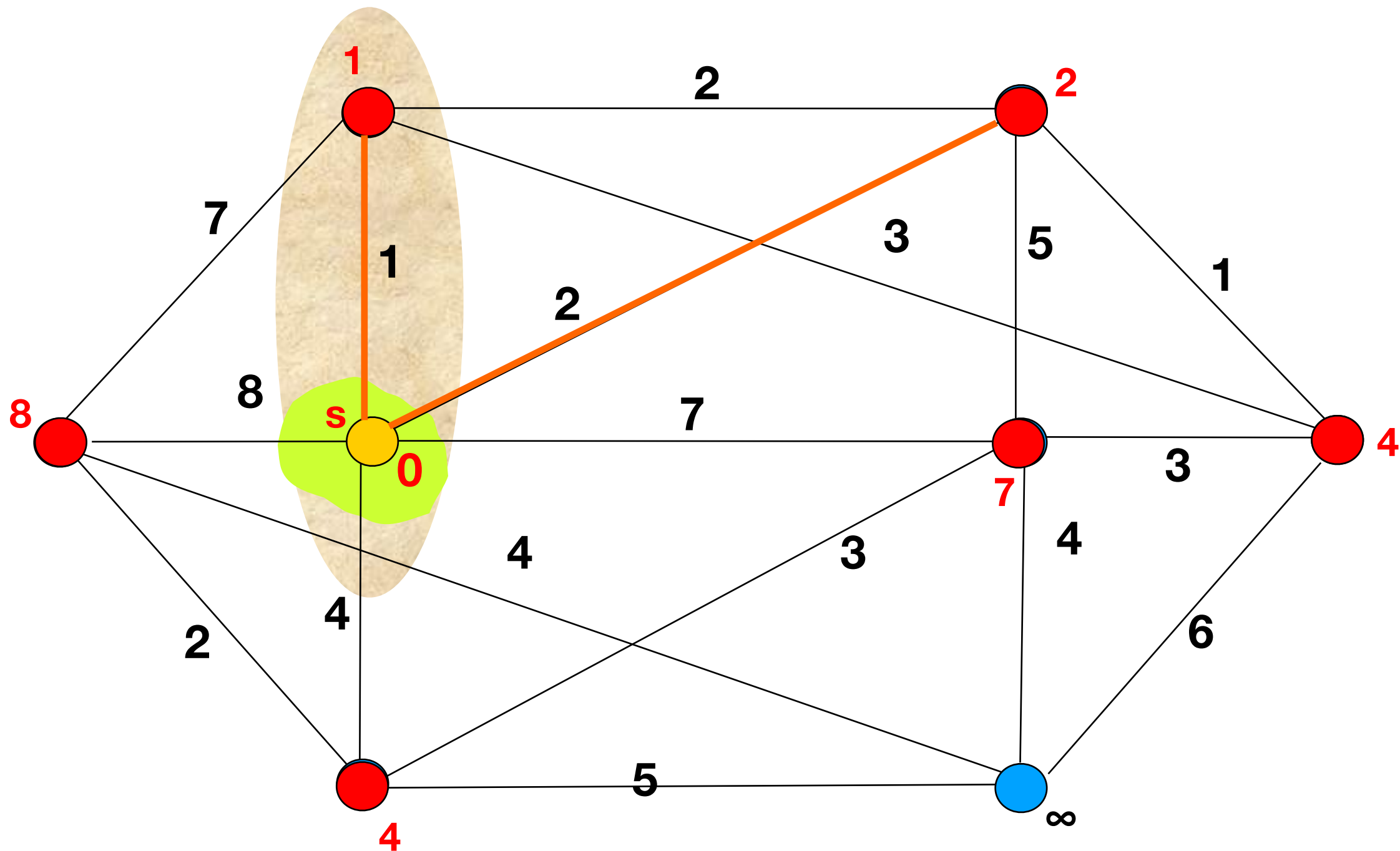
# Dijkstra's Algorithm: an Example



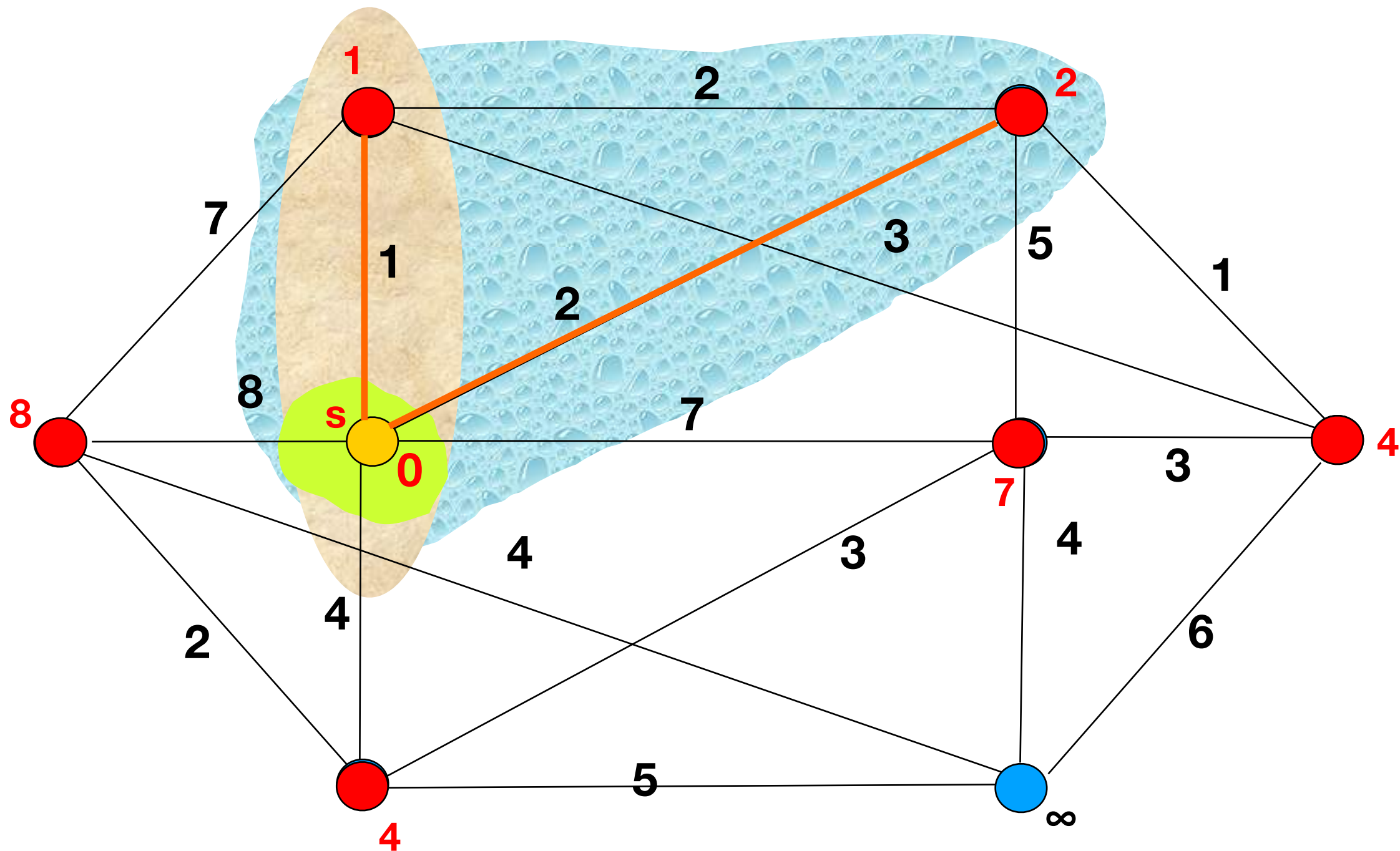
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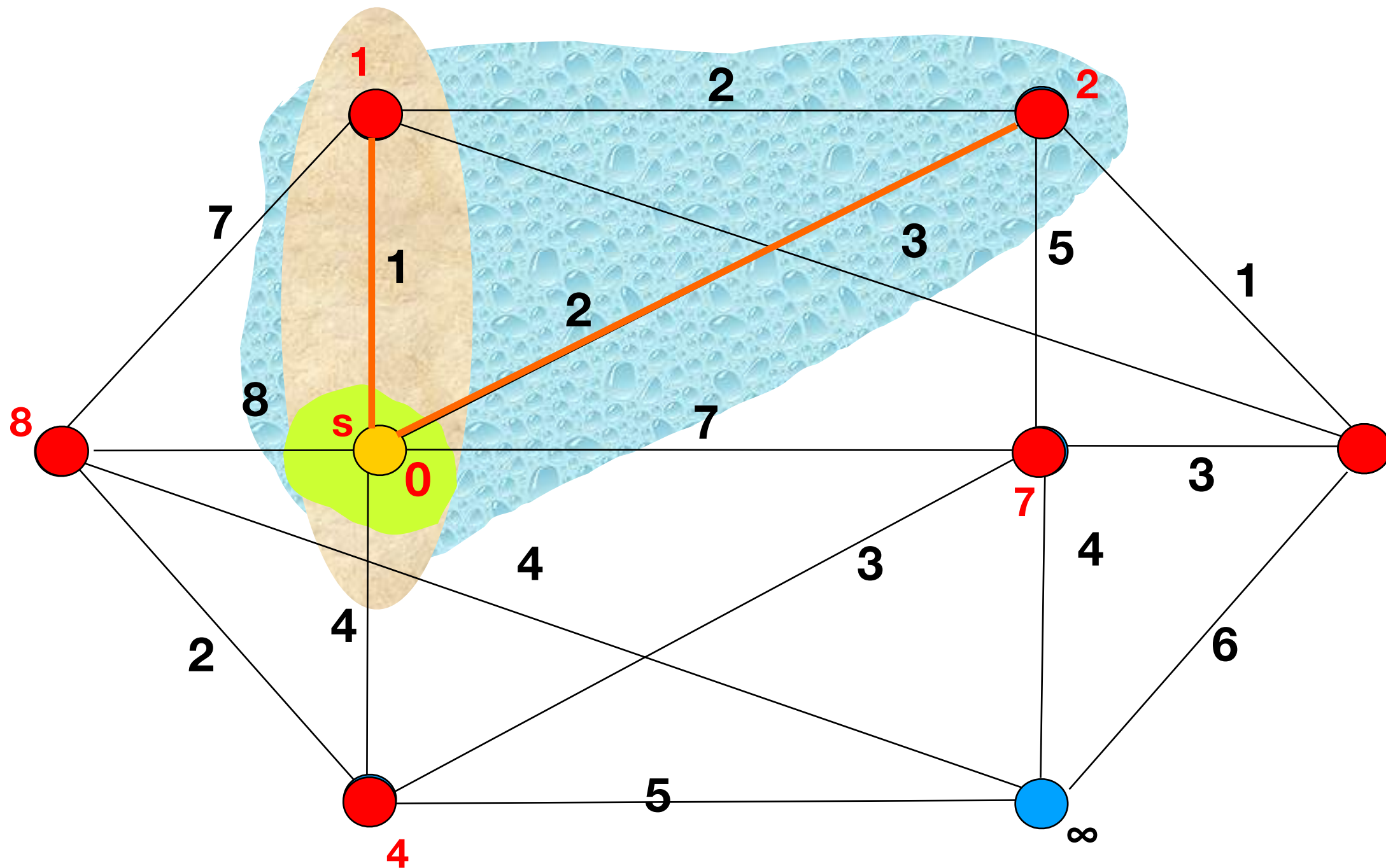
# Dijkstra's Algorithm: an Example



# Dijkstra's Algorithm: an Example

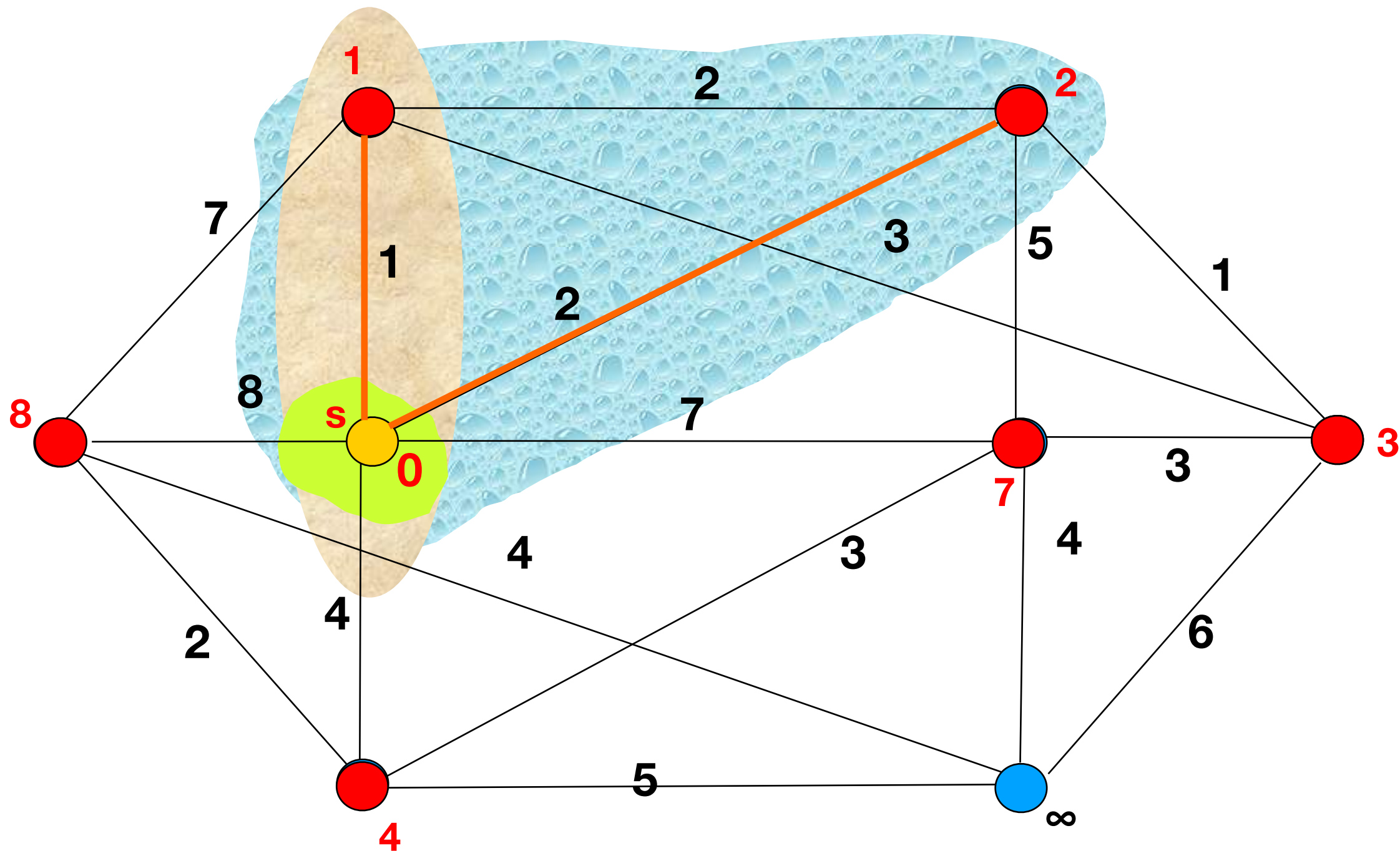


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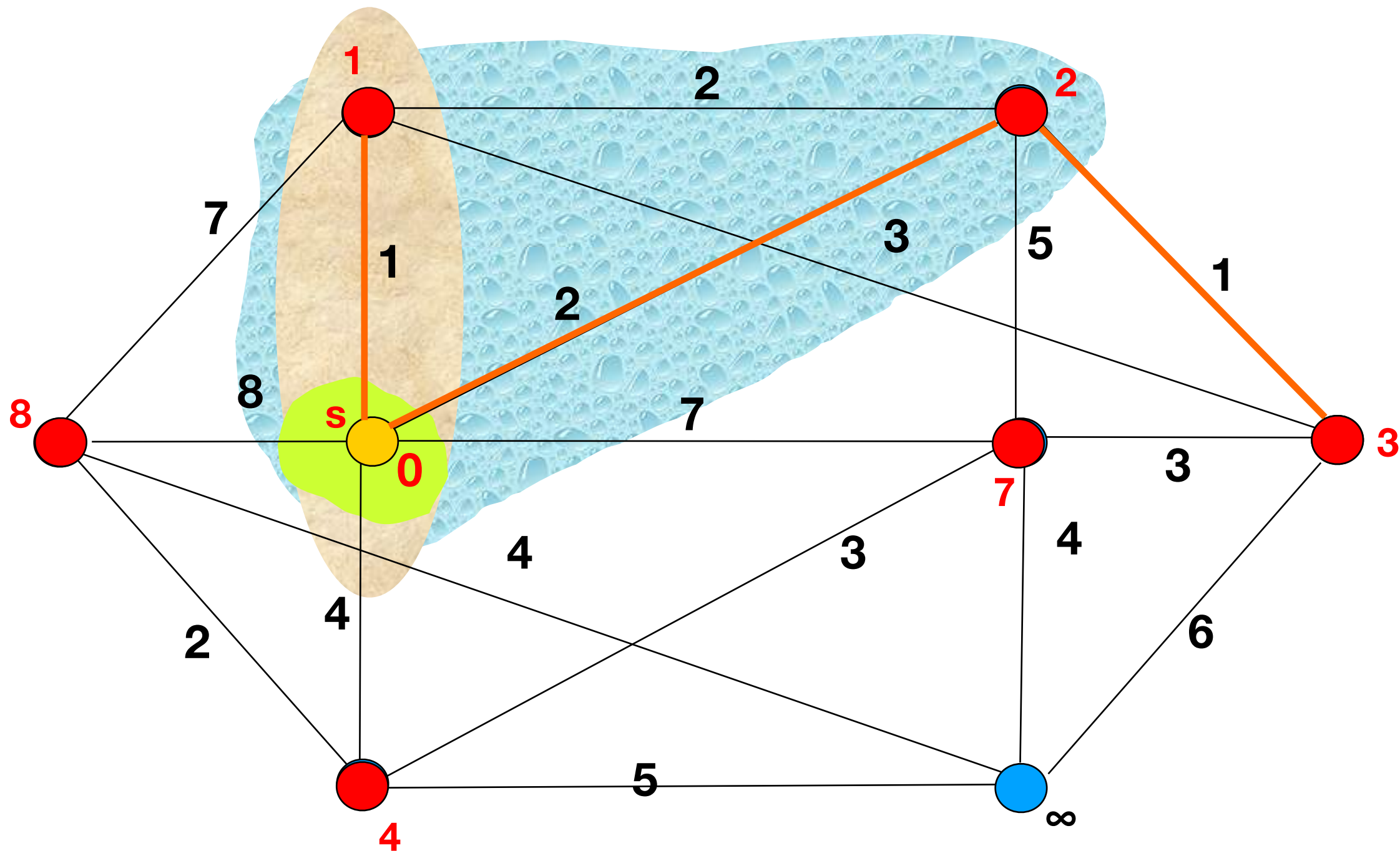


# Dijkstra's Algorithm: an Example

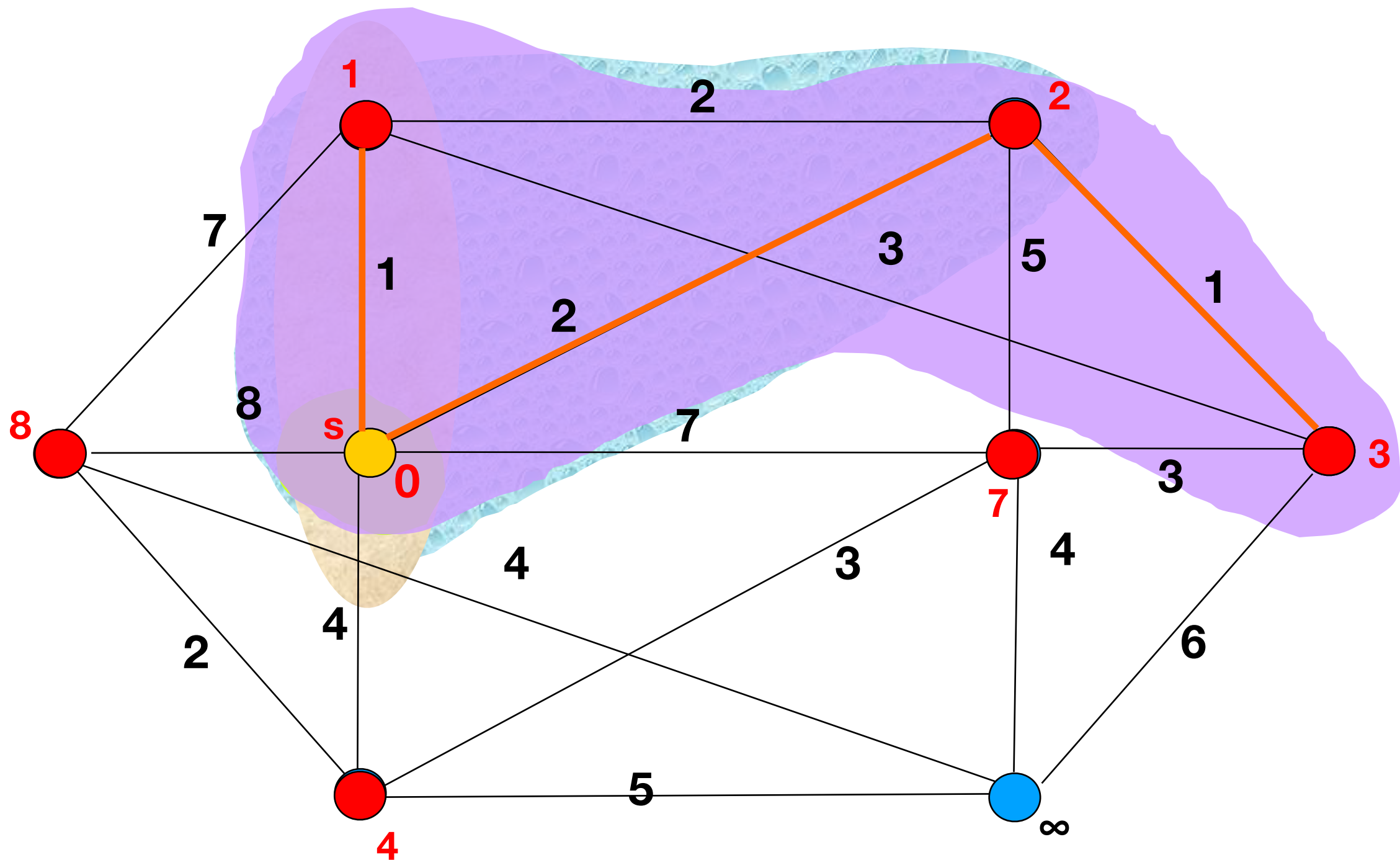




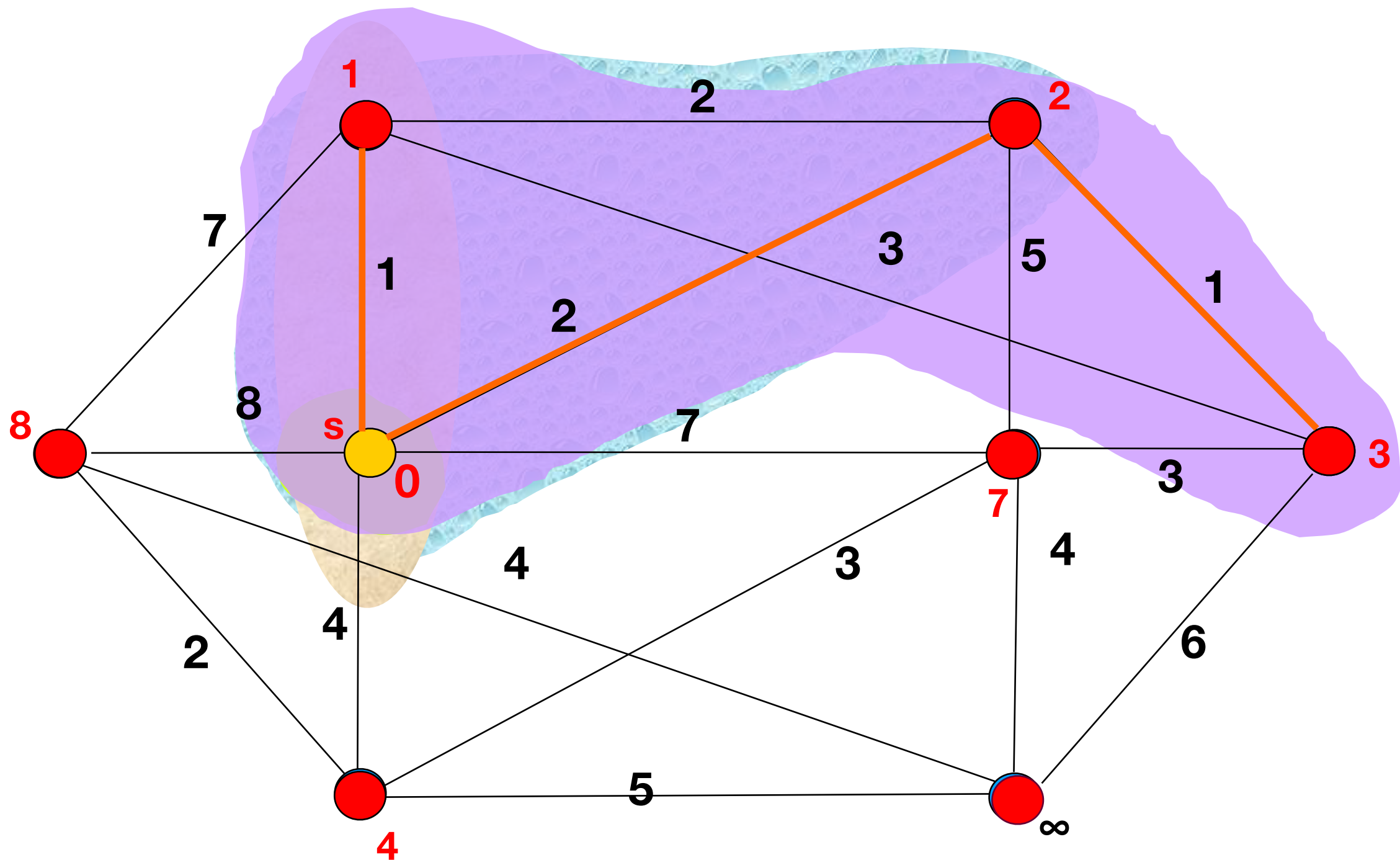
# Dijkstra's Algorithm: an Example



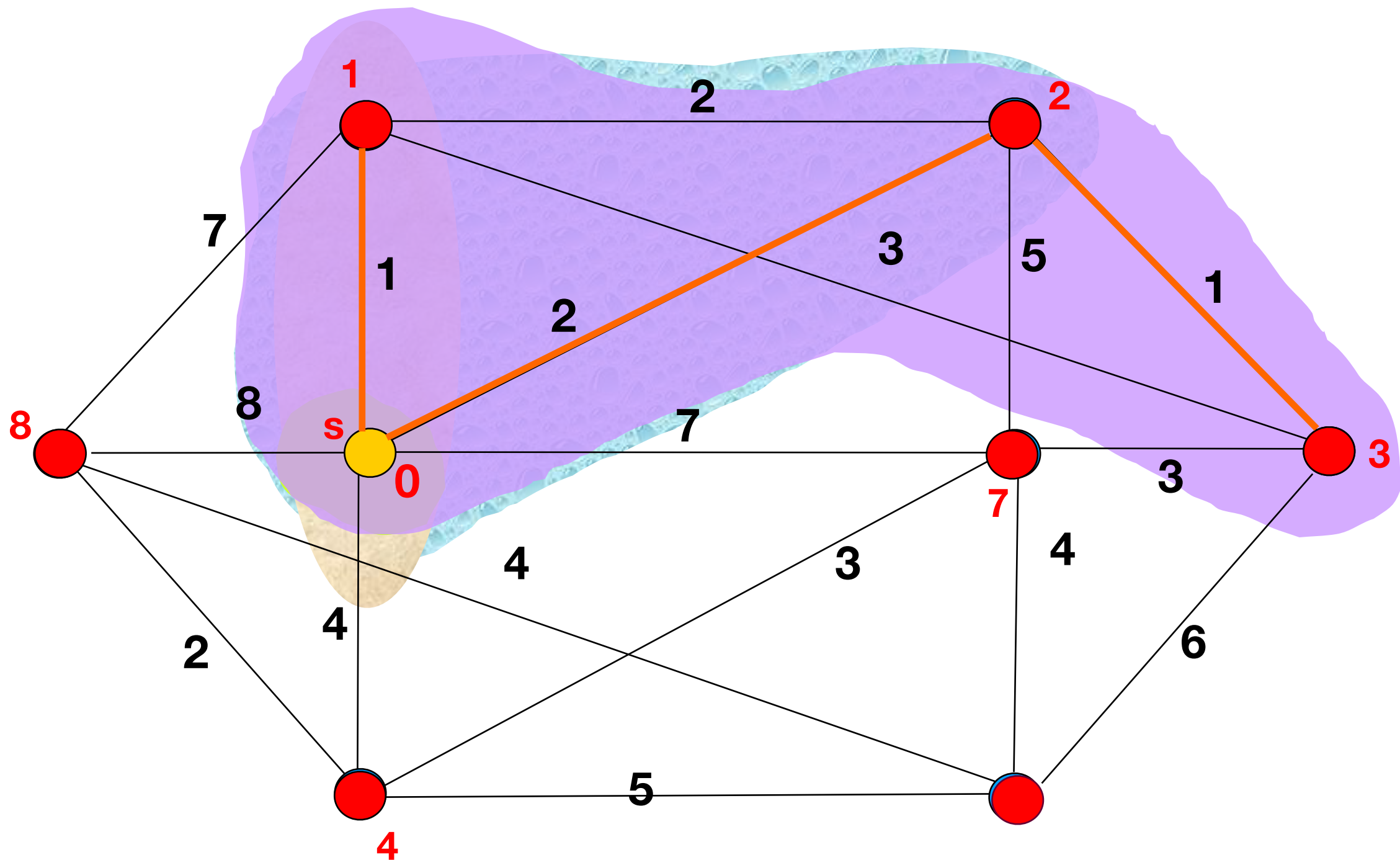
# Dijkstra's Algorithm: an Example



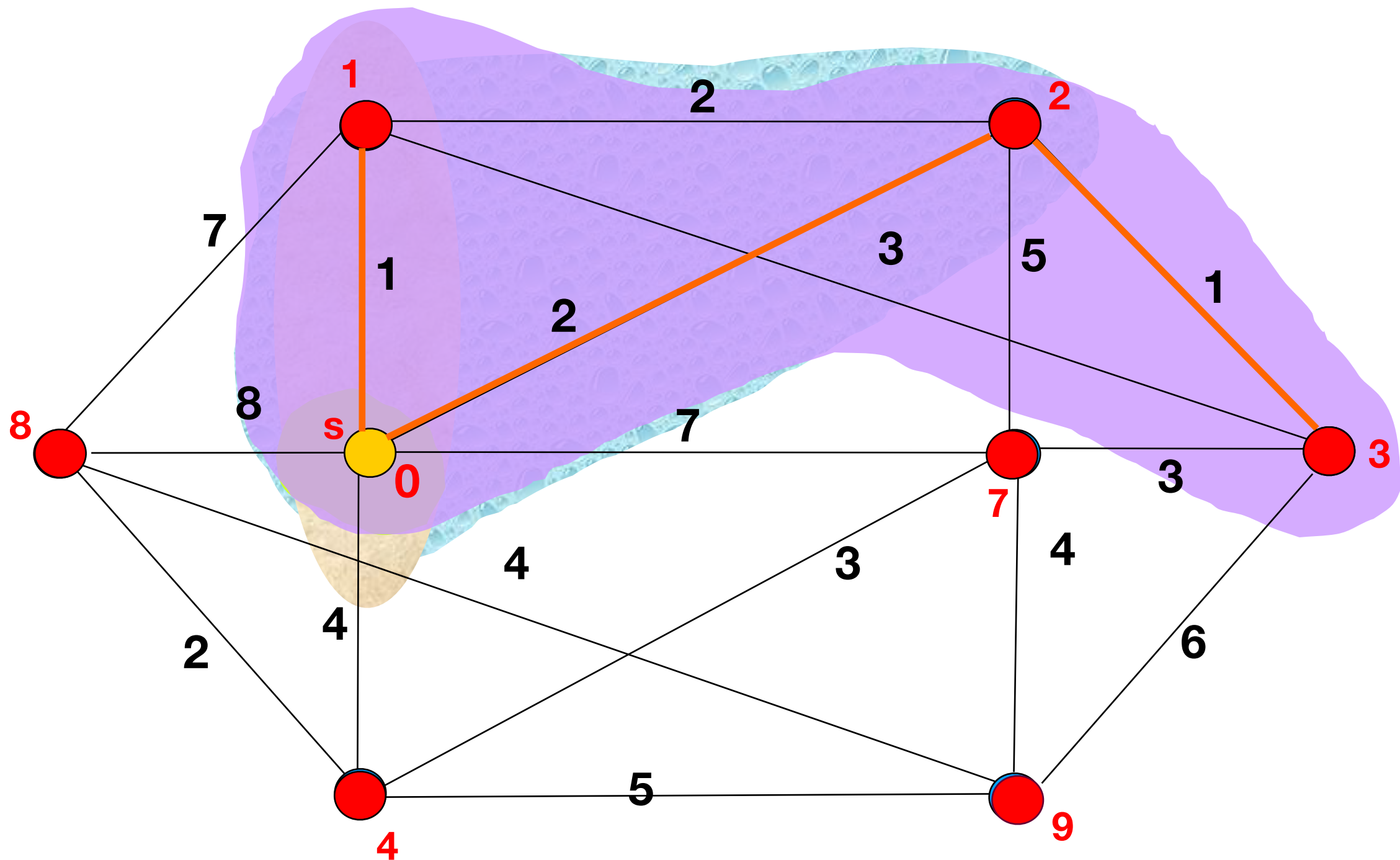
# Dijkstra's Algorithm: an Example



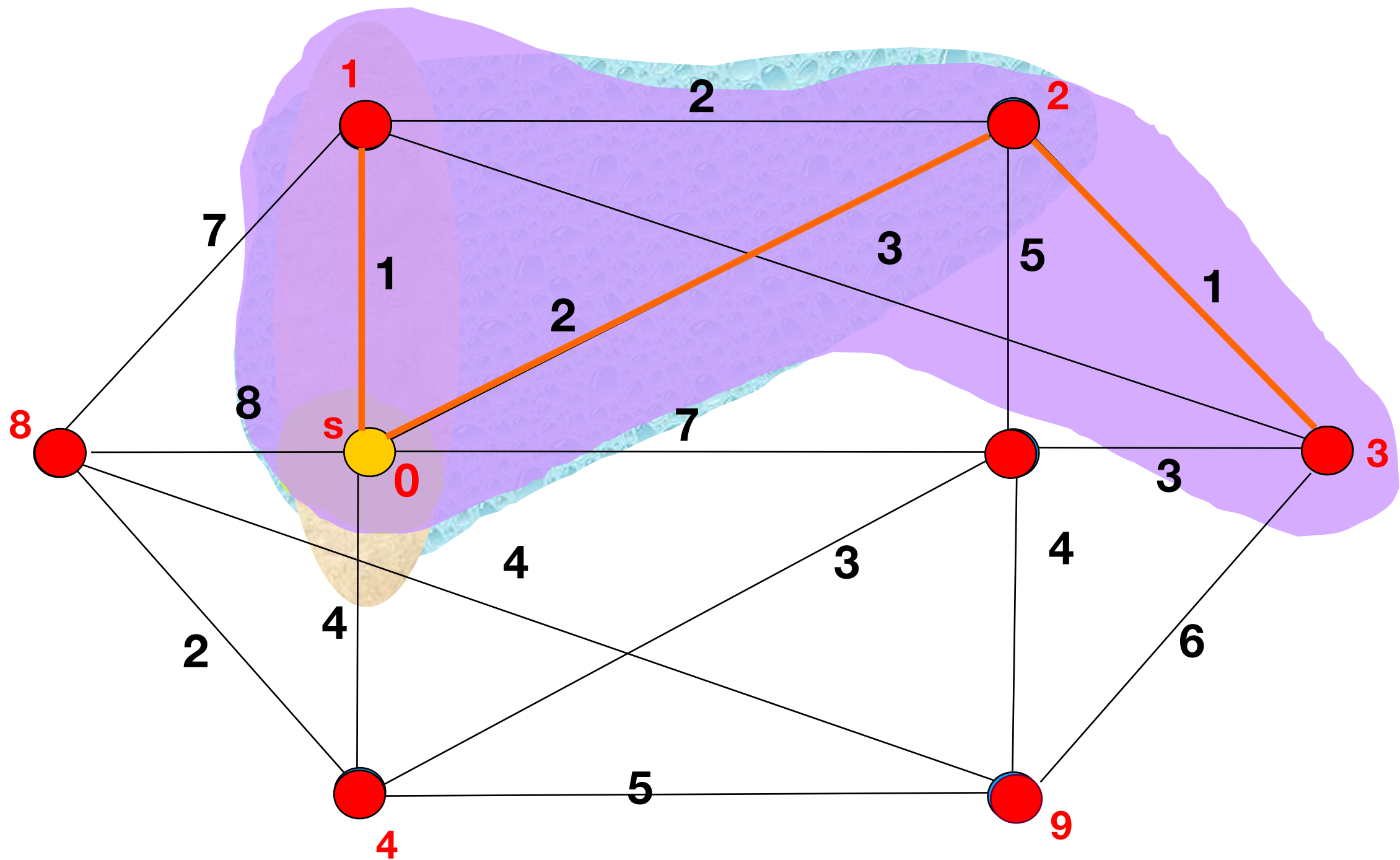
# Dijkstra's Algorithm: an Example



# Dijkstra's Algorithm: an Example

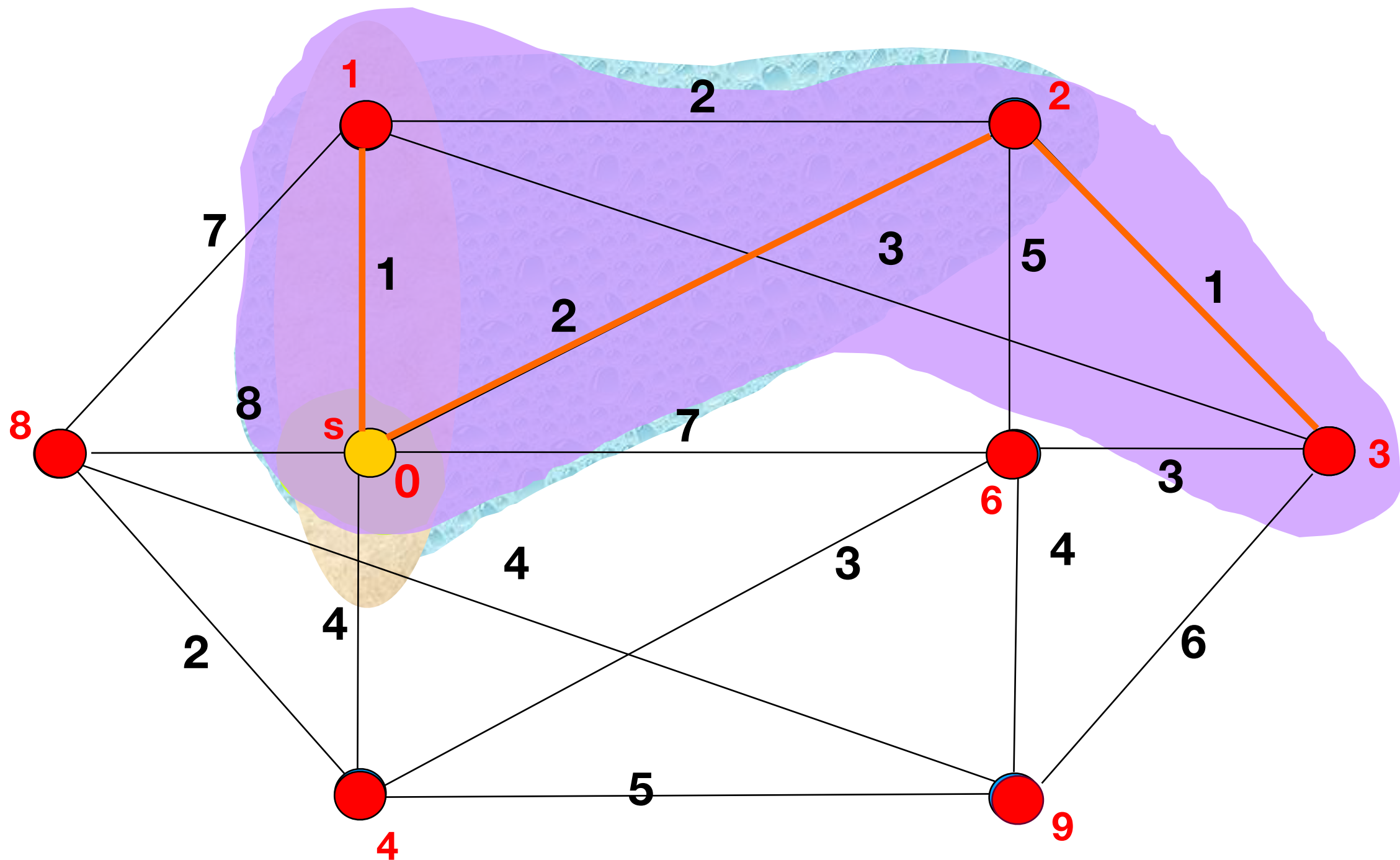


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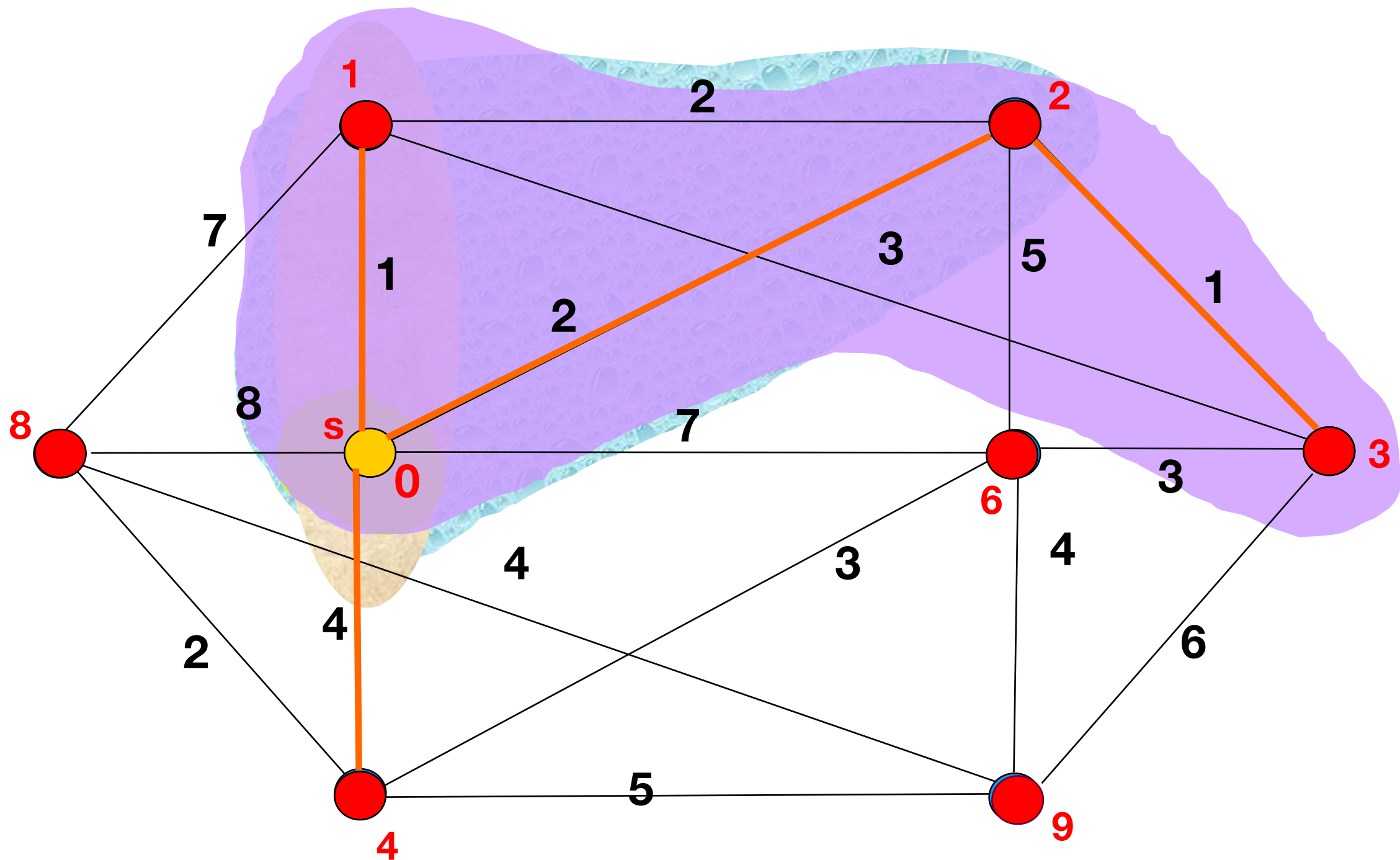




# Dijkstra's Algorithm: an Example

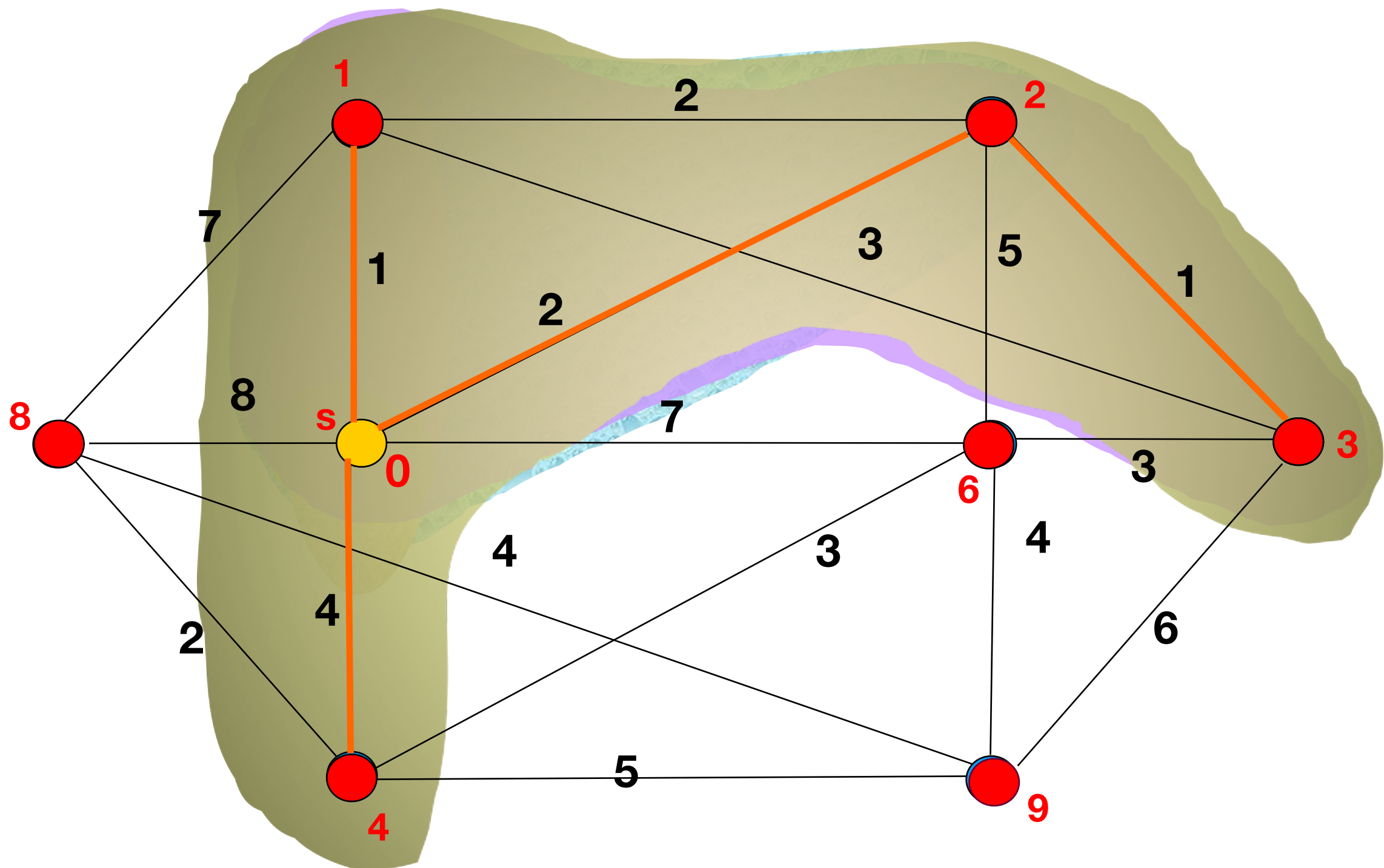


# Dijkstra's Algorithm: an Example

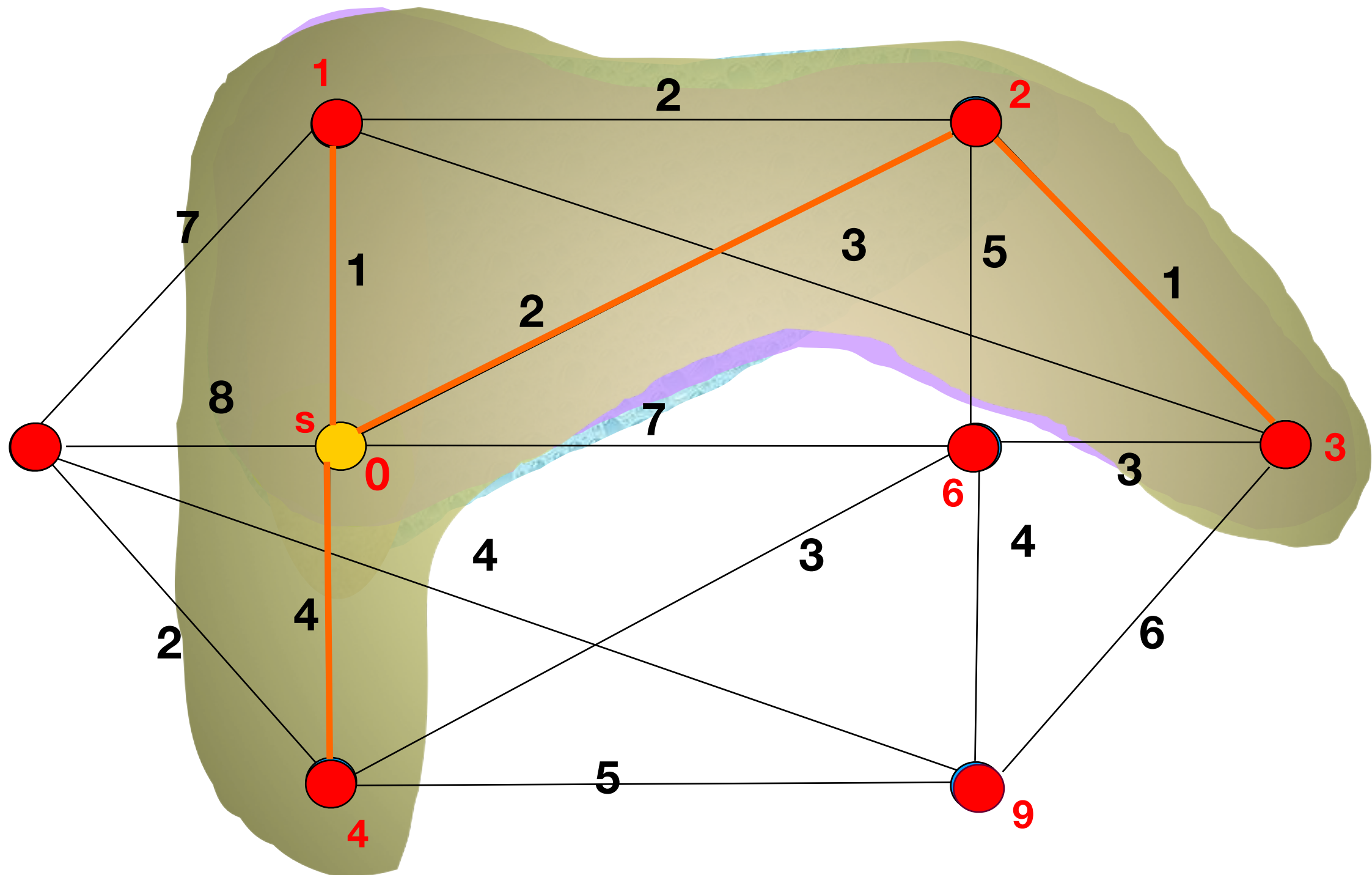




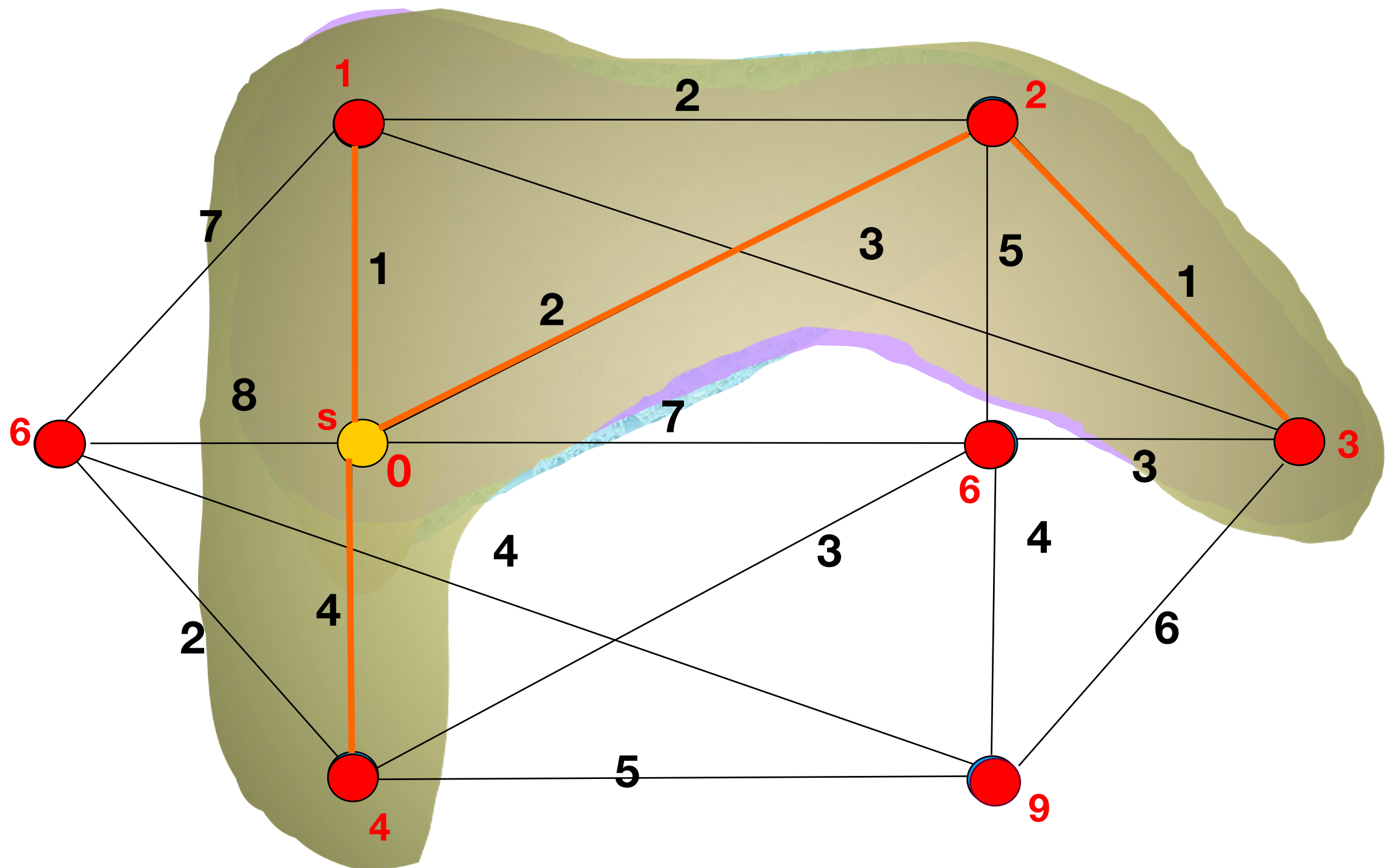
# Dijkstra's Algorithm: an Example



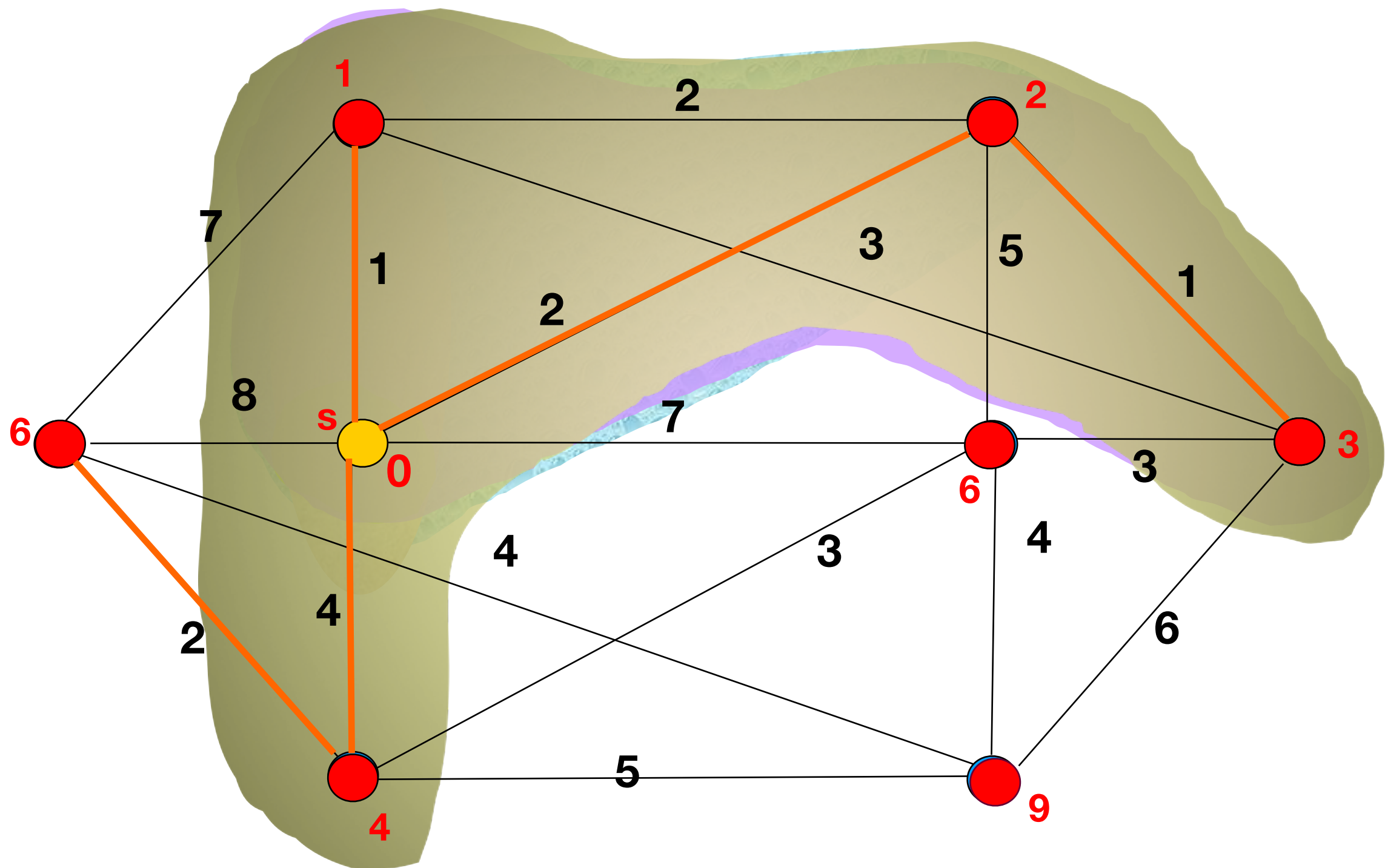
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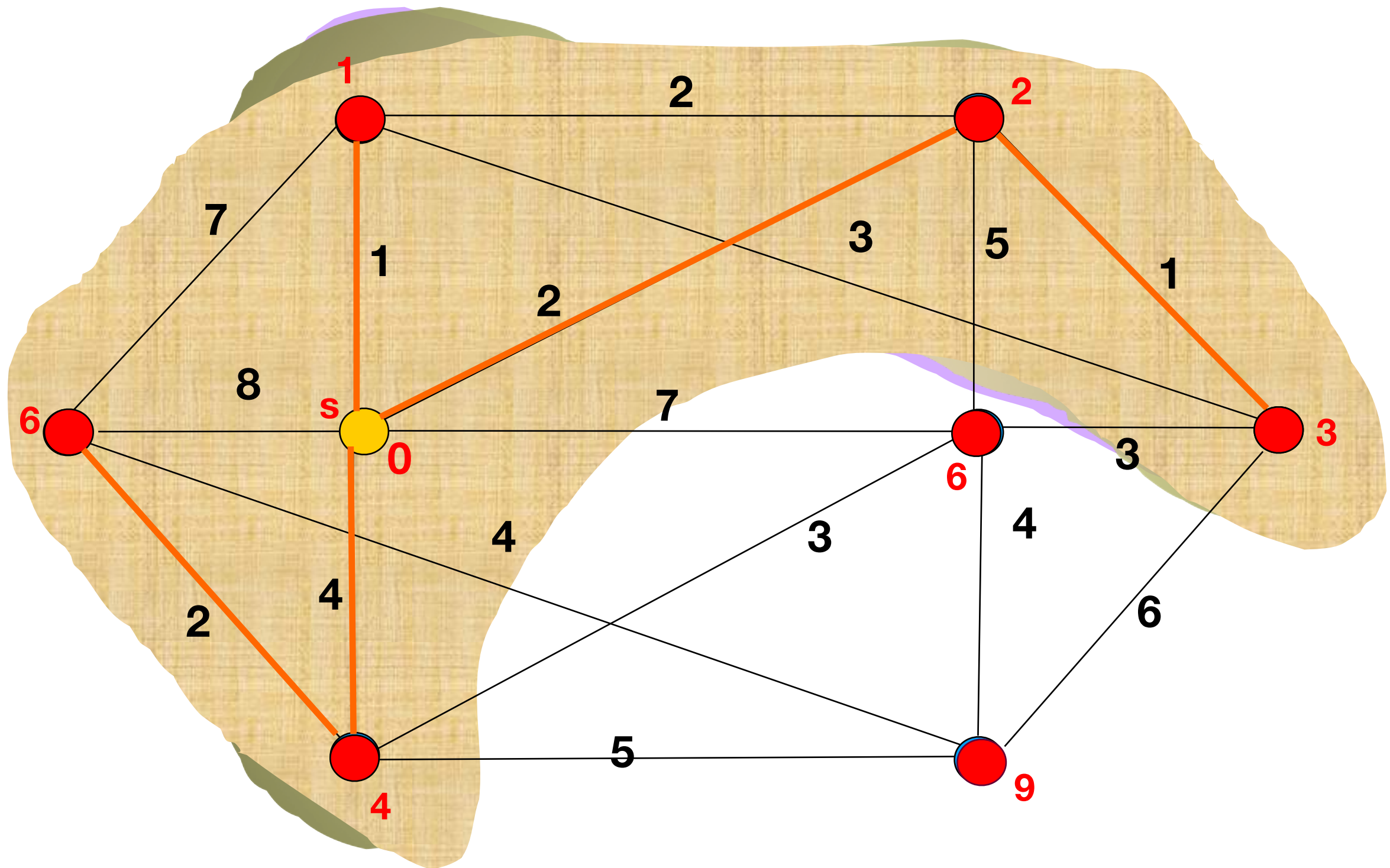
# Dijkstra's Algorithm: an Example



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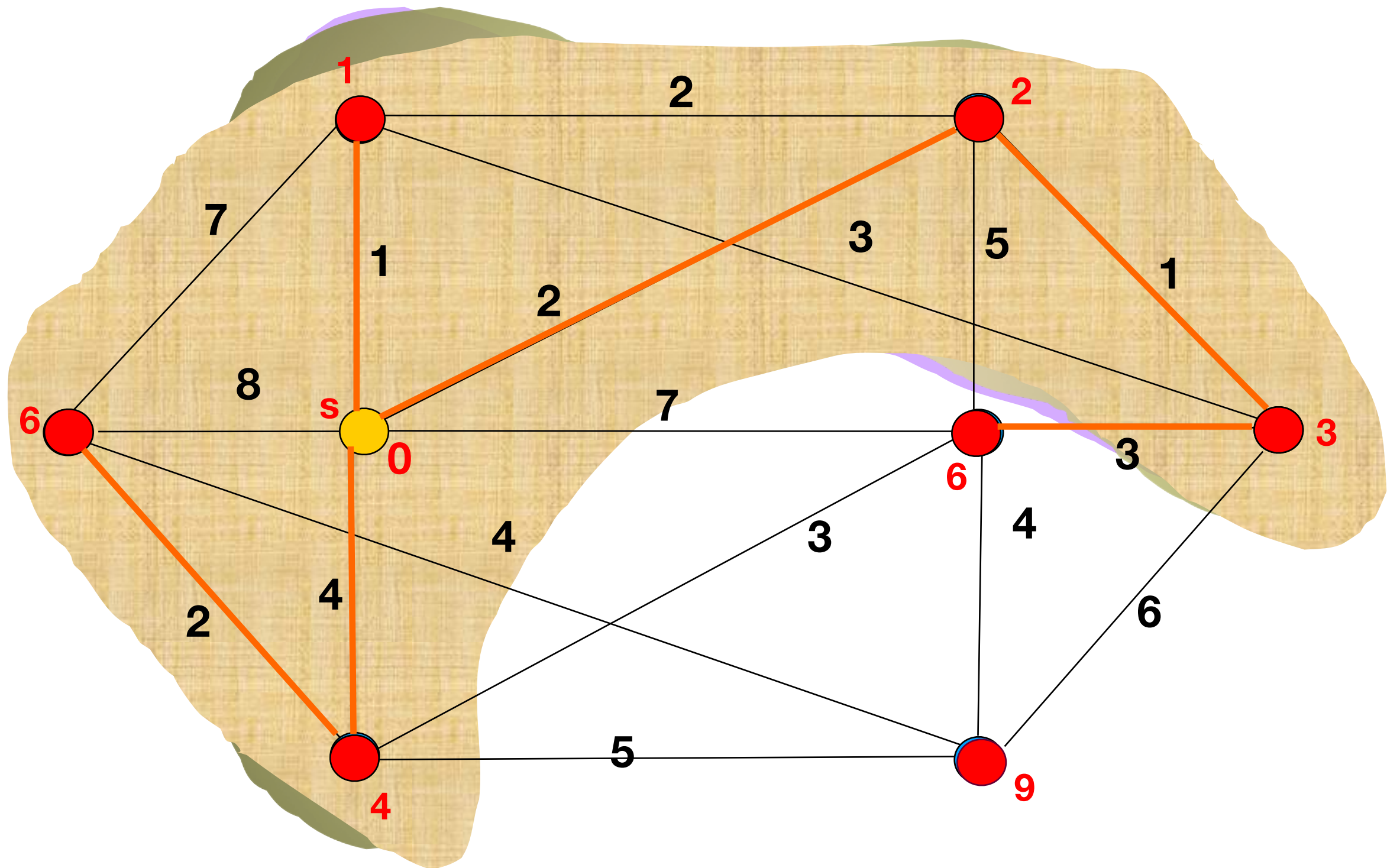


# Dijkstra's Algorithm: an Example

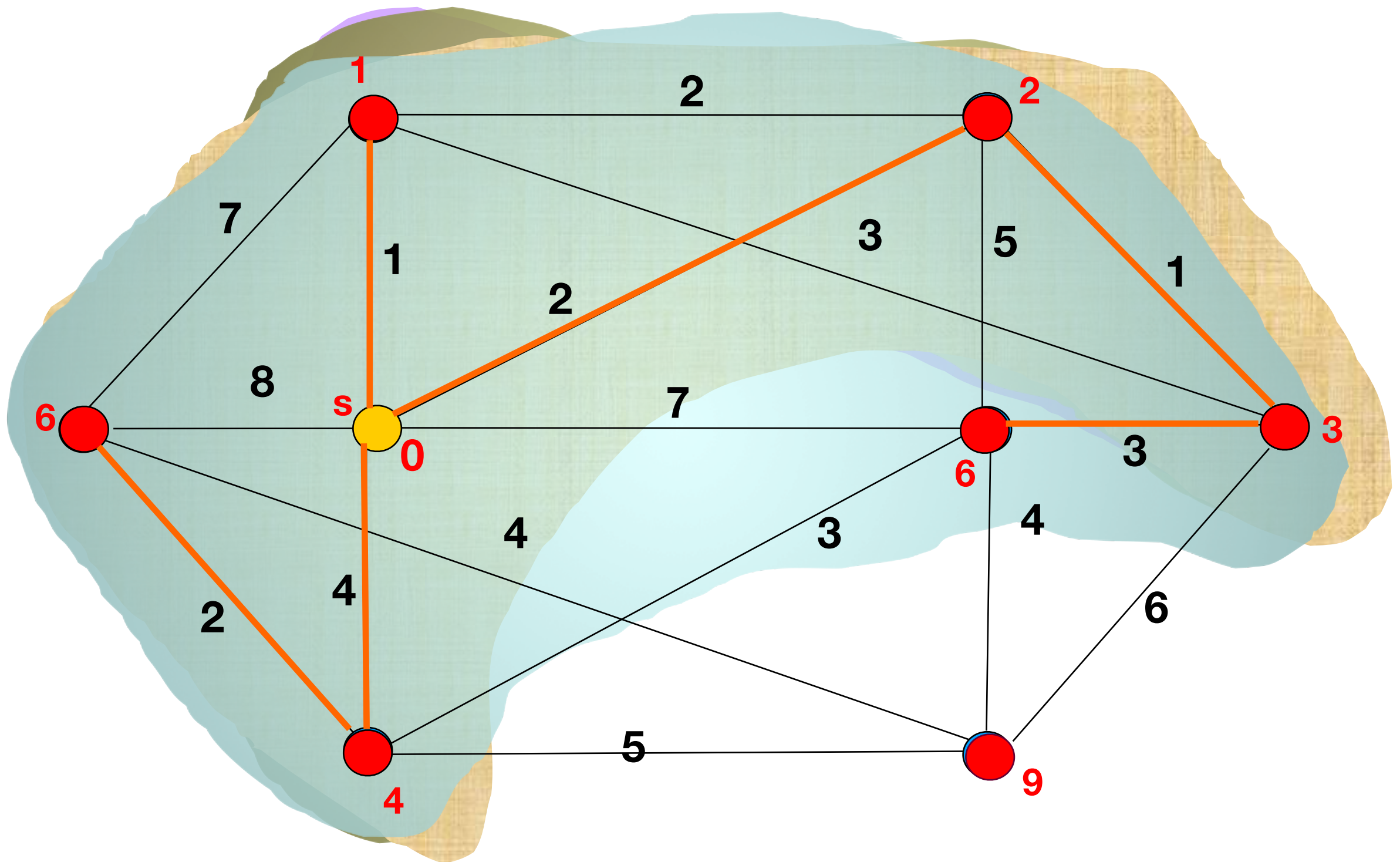




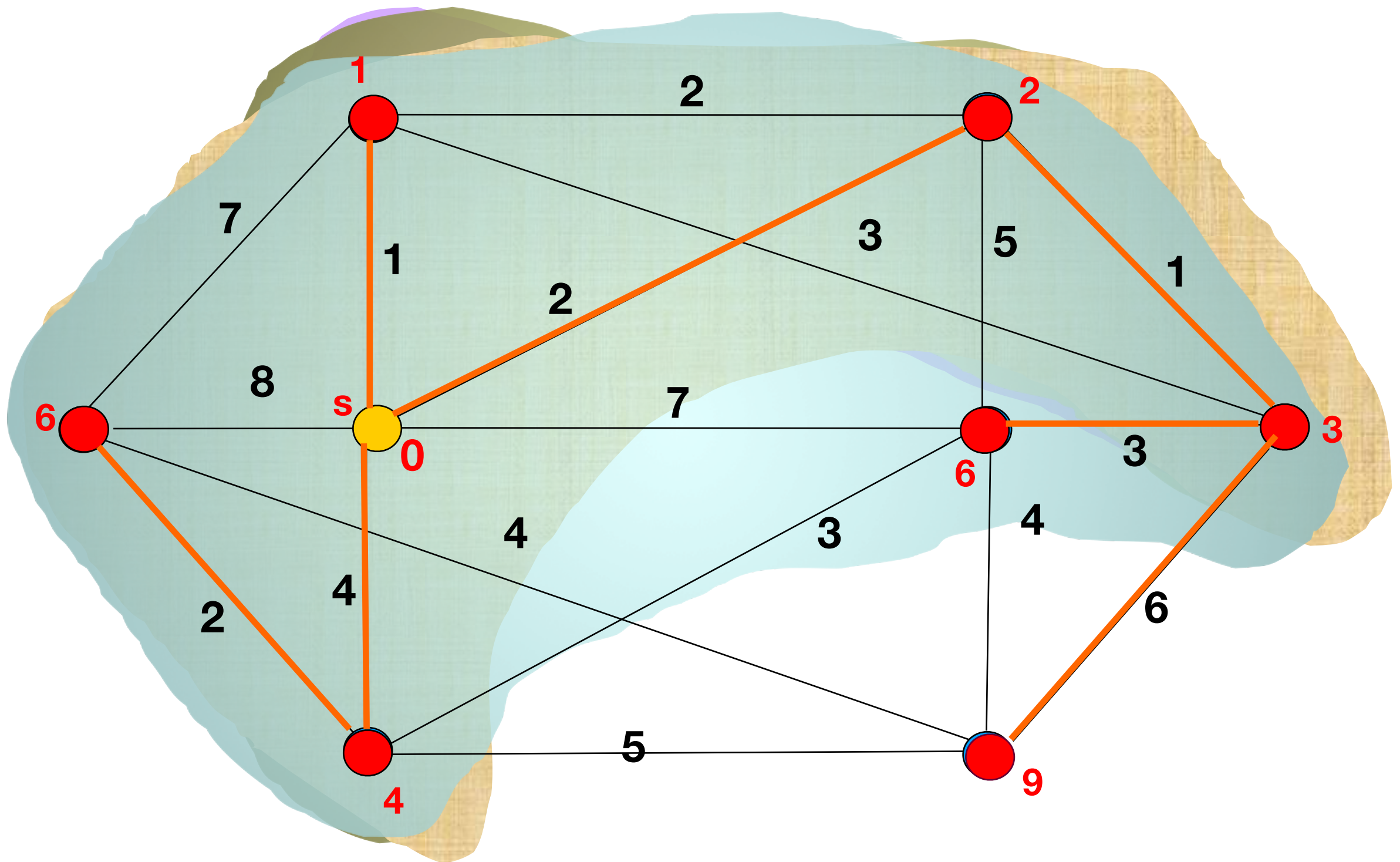
# Dijkstra's Algorithm: an Example



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# Dijkstra's Algorithm: an Example





Thank you!

Q & A