Chapter 2 - OpenROAD workflow

Course authors (Git file)



- History of OpenROAD
- OpenROAD Flow Scripts
- Fill insertion
- Resources



Section 1

History of OpenROAD



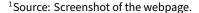
Foundations and Realization of Open, Accessible Design (OpenROAD)

At the top of the documentation:

https://openroad-flow-scripts.readthedocs.io



Figure 1: Darpa IDEA 1





Darpa IDEA

https://www.darpa.mil/research/programs/intelligent-design-of-electronic-assets



Program Summary

Next-generation intelligent systems supporting Department of Defense (DoD) applications like artificial intelligence, autonomous vehicles, shared spectrum communication, electronic warfare, and radar require processing efficiency that is orders of magnitude beyond what is available through current commercial electronics. Reaching the performance levels required by these DoD

Figure 2: Darpa IDEA ²





Darpa ERI

2018/2019 Darpa ERI, cadence and the people

https://community.cadence.com/tags/openroad

Start reading from the bottom!

ERI: OpenROAD



If I had to summarize DARPA's Electronic Resurgence Initiative in one phrase, it would be "getting the cost of design down," As I've said several times this week, the US Department of Defense (DoD) does not have high volumes and so the cost of a part...

> over 6 years ago Cadence Blogs Breakfast Bytes

The DARPA Electronic Resurgence Initiative (ERI)



Paul McLellan

Many weeks ago DARPA organized a summit at the Palace of Fine Arts in San Francisco. The first day consisted of a workshop and some other presentations including one by Cadence's Tom Beckley, Since Tom's presentation was very similar to what he presented...

> over 6 years ago Cadence Blogs





OpenROAD V1.0

Document with OpenROAD V1.0 Expectations:

https://vlsicad.ucsd.edu/NEWS19/OpenROAD%20RTL-to-GDS%20v1.0%20Expectations.pdf

OpenROAD v1.0 Expectations

Andrew B. Kahng and Tom Spyrou The OpenROAD Project

November 22, 2019

Web: https://theopenroadproject.org/ GitHub: https://github.com/The-OpenROAD-Project

The OpenROAD v1.0 tool, to be released in July 2020, will be capable of push-button, DRC-clean RTL-to-GDS layout generation in a commercial FinFET process node. The tool is currently visible here. In its v1.0 form, it will be integrated on an incremental substrate provided by the OpenBB database and the OpenBB database and the OpenBB database and the OpenSTA static timing engine. It will also offer users and



Figure 4: OpenROAD v1.0 4

V1.0 Roadmap

How to deal with these expectations:

https://eri-summit.darpa.mil/docs/ERIsummit2019/posh/08IDEA%20UCSD%20Website.pdf

Looking Forward (Year 2 = Phase 1B)

- V1.0 July 2020 must advance 20 years on EDA industry learning curve within next 2-3 quarters
 - 1980's file-based integration July 2019
 - 2000's tight integration on shared incremental substrate July 2020
- Next: architecture, database, build/CI/devops, CAE/PE,
 - + teaching EDA SW to the OpenROAD/FOSS community
- Professionals on the team: mandatory
 - Industry veterans who have "done this before"

Figure 5: Looking forward ⁵



⁵Source: Screenshot of the webpage.

Courses for OpenROAD

A single excellent project (some of us might know):

https://theopenroadproject.org/Courses/



Figure 6: Courses ⁶



⁶Source: Screenshot of the webpage.

Help is on the way

Kudos to this course:

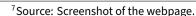
https://theopenroadproject.org/news/6455/



Kudos to Christian Wittke (IHP) and Thorsten Knoll (HSRM) on their development of a Digital EDA Course using IHP-SG13G2 and OpenROAD!

See the video of Christian's ORConf 2024 talk at https://www.youtube.com/watch?v=Ozd_yXoExLo!

Figure 7: This course 7





Section 2

OpenROAD Flow Scripts



Flow steps





Figure 8: OpenROAD flow steps 8

Flow components

RTL-GDSII Using OpenROAD-flow-scripts

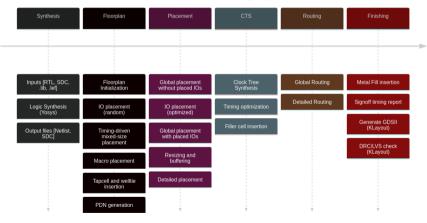




Figure 9: OpenROAD flow components 9

Section 3

Fill insertion



Fill insertion

There are two flow components that take care of filling area gaps in the design:

- Filler cell insertion
- Metal fill insertion

Both will be explained in the following section.



Filler cells: Reasons

Why filling the design area with more cells?

- After floorplaning and placement there will always be gaps between the standard cells
- These gaps must be filled to keep the continuity of
 - n-well and p-well spacing
 - railing
 - implants
- The filling with cells helps against the WPE (well proximity effect)



Filler cells: Properties

Filler cells

- have no logic function
- have no inputs and no outputs
- are not in the netlist of the design
- are available in different widths



Filler cells: GDS

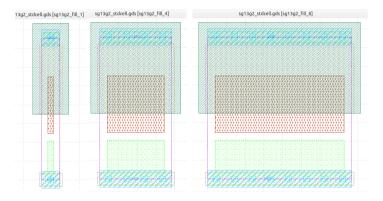


Figure 10: Filler cells in different widths (1, 4, 8)



Metal fill

What is metal filling?

- Metal filling adds polygons and shapes to the metal layer(s).
- These fillings have no logic functionality.
- The purpose is creating a more even or uniform distribution of the metal area.
- Physical reasons are planarity and reducing thinkness variations (CMP).
- Metal filling can affect timing and signal integrity.
- Metal filling is done algorithmical (mostly with scripts).

More to read:

https://semiengineering.com/knowledge_centers/materials/fill/



Section 4

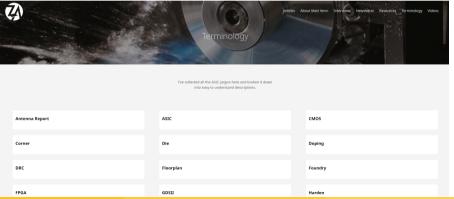
Resources



Help with the terminology

Searching the terms with a standard search engine might not bring usefull results every time. Matt Venn created a page for EDA terminology:

https://www.zerotoasiccourse.com/terminology/





The list of open-source tools

The list of flow steps and flow components in ORFS contains the information about the original open-source tools.

We will dive a little deeper into this list with the course training:

https://openroad-flow-scripts.readthedocs.io/en/latest/tutorials/FlowTutorial.html#running-the-automated-rtl-to-gds-flow



Additional links

Awesome open-source asic resources:

https://github.com/mattvenn/awesome-opensource-asic-resources

Zero-to-ASIC resources list:

https://www.zerotoasiccourse.com/resources/

AIC 2025 lectures by Carsten Wullf:

https://github.com/wulffern/aic2025

https://analogicus.com/aic2025/



Meet the developers

There is a slack community with most of the open-source silicon projects and people in it:

https://open-source-silicon.dev

This is the perfect place, if you

- search for people you heard of in open-source EDA.
- want to reach out to tool developers.
- have all sorts of questions in open-source EDA.
- look for a specific problem and want to see if others already are in a discussion about it.
- want to share your experience and help others.



Most of the tools in open-source EDA have their own channel in this slack. Just try search and add for the channel names.

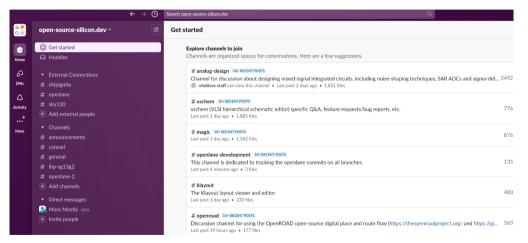


Figure 12: Channels in the open-source-silicon.dev slack

