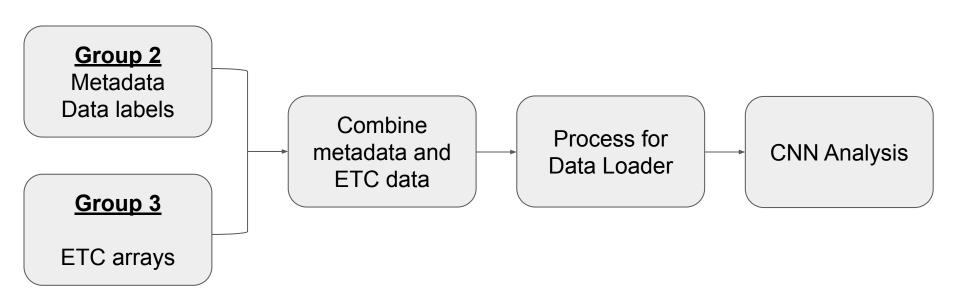
# Group 4 - Deep Learning

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## Workflow



#### DataLoader

```
array([[[0, 0, 0, ..., 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
        [0, 3, 5, \ldots, 1, 1, 1]],
       [[0, 0, 1, \ldots, 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
        [0, 0, 0, ..., 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
        [0, 1, 3, \ldots, 1, 1, 1]],
       [[0, 0, 0, ..., 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
        [0, 0, 0, ..., 1, 1, 1],
        [0, 0, 0, ..., 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1]],
       [[0, 0, 0, ..., 3, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
        [0, 0, 0, \ldots, 1, 1, 1],
         [0, 0, 0, \ldots, 1, 1, 1]]
```

#### **Group 2**

Metadata Data labels

#### **Group 3**

ETC arrays

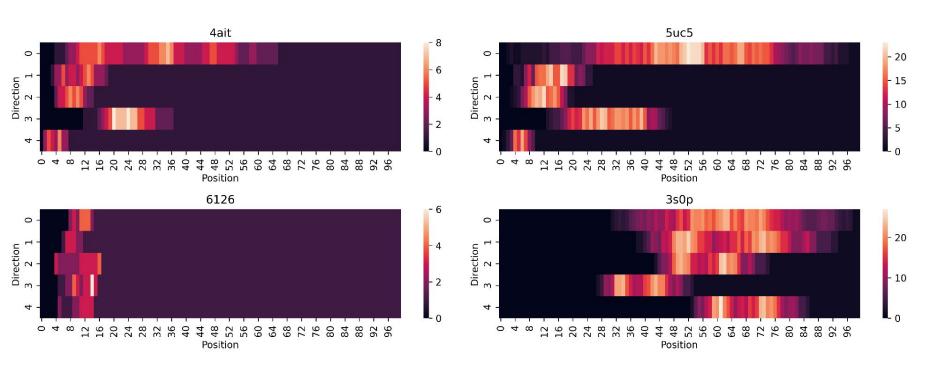
#### **Combine Data**

Iterate through files
Combine labels and ETC arrays

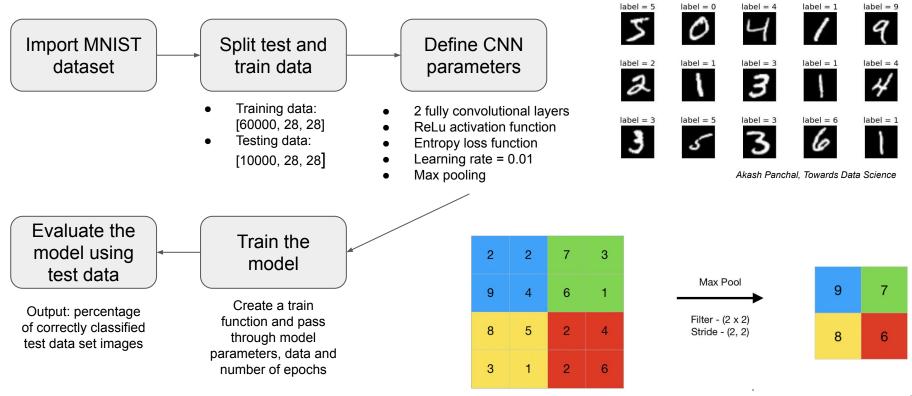
#### **Process for DataLoader**

Reshape ETC arrays
 Convert arrays to Tensors
 Load Tensors into TensorDatasets
 Load Dataset into DataLoader

# Visualization of Reshaped ETC Arrays



#### Convolutional Neural Network (CNN) examples



## 1. Setup and loading data

```
▼ 1.1 Install dependencies and setup

                                                                         小业岛目
  [5] pip install tensorflow tensorflow-qpu opency-python matplotlib
       import tensorflow as tf
       import os
       import cv2
       import imphdr
       from matplotlib import pyplot as plt
       import numpy as np
       # Deep Learning Model
       from tensorflow.keras.models import Sequential
       from tensorflow.keras.layers import Conv2D, MaxPooling2D, Dense, Flatten, Dropout
       # Model Evaluation
       from tensorflow.keras.metrics import Precision, Recall, BinaryAccuracy
       # Saving the model
       from tensorflow.keras.models import load model
```

```
▼ 1.2 Load Data

       #Known data directory, this directory has to have all data sorted. Class 1
       # images on a directory, class 2 images in another directory and so on.
       data dir = 'path to data directory'
  [ ] # Code line to know which classes 'data dir' has inside
       os.listdir(data dir)
  [ ] # Code line to automatically indicate the code the data directory and how big
       # the batches of images will be
       # tf.keras.utils.image dataset from directory?? can help to check other dataset
       # parameters
       data = tf.keras.utils.image_dataset_from_directory('path_to_data_directory',
                                                          batch size = 15)
  [ ] # Visual representation of the data set
       data iterator = data.as numpy iterator()
       batch = data iterator.next()
  [ ] # Visual representation of the data set
       fig, ax = plt.subplots(ncols=8, figsize = (20,20))
       for idx, img in enumerate(batch[0][:8]):
         ax[idx].imshow(img.astype(int))
         ax[idx].title.set_text(batch[1][idx])
```

## 2. Image Preprocessing

```
▼ 2.1 Scale Images
  [ ] # Scaling the image means that the pixels that had a numerical value between
       # 0 and 255, now will have a value between 0 and 1 in order to facilitate the
       # calculus.
       data = data.map(lambda x,y: (x/255, y))
  1 # Proof that he max value is 1
       batch[0].max()
  1 # Proof that he min value is 0
       batch[0].min()
  [ ] # Visual representation of the scaled data
       scaled iterator = data.as numpy iterator()
       batch = scaled iterator.next()
  fig, ax = plt.subplots(ncols=8, figsize = (20,20))
       for idx, img in enumerate(batch[0][:8]):
         ax[idx].imshow(img)
         ax[idx].title.set text(batch[1][idx])
```

```
▼ 2.2 Split Data
  [ ] # This will let us know how many batches we have
       # A batch can be seen as an array that contains info of given quantity of images
       # (this quantity was given in the 3rd code line of '1.2 Load Data')
       len(data)
  [ ] # Define the # of batches that will be used for training (~70% of data)
       train size = int(len(data)*.7)
       train size
  [ ] # Define the # of batches that will be used for validation (~20% of data)
       val size = int(len(data)*.2)+1
       val size
  [ ] # Define the # of batches that will be used for testing (~10% of data)
       test_size = int(len(data)*.1)+1
       test size
  [ ] # Sorting data
       train = data.take(train size)
       val = data.skip(train size).take(val size)
       test = data.skip(train size + val size).take(test size)
```

## 3.1 Deep learning model (architecture design)

[ ] # Define the type of model # Sequential means that there is just one kind of input and only one output model = Sequential() [ ] # tf.keras.layers?? Manual to the different kind of layer [ ] # Architecture design model.add(Conv2D(16, (3,3), 1, activation='relu', input shape = (256,256,3))) model.add(MaxPooling2D()) # 16 is the number of filters # (3,3) size of the filter # 1 means that the convolution will go trhoug every single part of the image model.add(Conv2D(32, (3,3), 1, activation = 'relu')) model.add(MaxPooling2D()) model.add(Conv2D(16, (3,3), 1, activation = 'relu')) model.add(MaxPooling2D()) model.add(Flatten()) model.add(Dense(256, activation = 'relu')) model.add(Dense(1, activation = 'sigmoid')) # I used sigmoid because it is a binomial CNN so the sigmoid activation function # works well for binary classification because it just has two outputs, 0 or 1 # This code line allows to compile the CNN but it is intended to work for binary # classification model.compile('adam', loss = tf.losses.BinaryCrossentropy(), metrics = ['accuracy'])

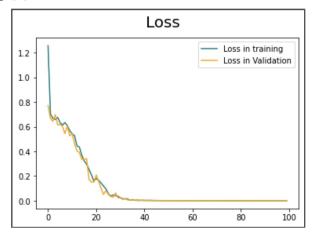
# Training and validation

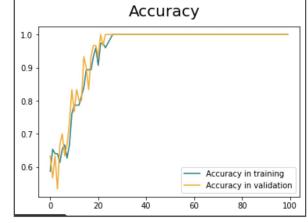
```
▼ 3.2 Training the CNN

  [ ] # Establish directory for callbacks
      logdir = 'path to logs directory'
       tensorboard callback = tf.keras.callbacks.TensorBoard(log dir=logdir)
  [ ] # Fit the model
      # Set # of epochs
       hist = model.fit(train, epochs = 100, validation data = val,
                        callbacks = [tensorboard callback])

▼ 3.3 Training and validation Performance

  [ ] #Visual representation of the training and validation loss performance
       fig = plt.figure()
       plt.plot(hist.history['loss'], color = 'teal', label = 'loss in training')
       plt.plot(hist.history['val_loss'], color = 'orange', label = 'loss in validation')
       fig.suptitle('loss', fontsize = 20)
       plt.legend(loc = "upper left")
       plt.show()
  [ ] #Visual representation of the training and validation accuracy performance
       fig = plt.figure()
       plt.plot(hist.history['accuracy'], color = 'teal', label = 'Accuracy in training')
       plt.plot(hist.history['val accuracy'], color = 'orange', label = 'Accuracy in validation')
       fig.suptitle('Accuracy', fontsize = 20)
       plt.legend(loc = "lower right")
       plt.show()
```

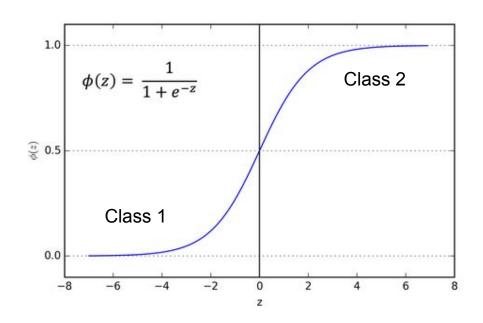




## 4. Making predictions

```
▼ 4 Making predictions

  [ ] # I suggest that for this part, we can use images that haven't been part of any
       # of the datasets (training, validation and test) they could be new images.
       # Load the new image and visualize it
       img = cv2.imread('path to image which is going to be predicted')
       plt.imshow(img)
       plt.show()
  [ ] # Resize the new image
       resize = tf.image.resize(img, (256,256))
       plt.imshow(resize.numpy().astype(int))
       plt.show()
  [ ] # Scale and pass the image trhoug the CNN
       yhat = model.predict(np.expand dims(resize/255, 0))
  [ ] # print the final value (this value is the one requiered for the classification)
      yhat
  [ ] # I used a sigmoidal function so all the values below 0.5 will become 0 (class 1)
       # and all the values higher than 0.5 will become 1 (class 2)
      if yhat > 0.5:
         print(f'It is predicted to be class 2')
       else:
         print(f'It is predicted to be class 1')
```



## Next Steps for the CNN

- Build a CNN that can handle 3D data (hyper-cylinder or hyper-sphere)
- Decide how many convolutional and pooling layers to use
  - Also consider: activation functions, kernel size, stride
- Test model with a sample of random proteins
- Train and optimize the CNN
- May need to tweak ECT data depending on model accuracy and compute time

# Reflections on the Project

- Would combine groups 3 and 4 because deep learning requires data from group 3 before CNNs can be constructed.
- Learned general process of CNN-no time to optimize one.
- Practiced working on collaborative programming (w/ GitHub).