```
#include "datatypes.h"
 #include <p18f442.h>
 // Taktfrequenz
 #define F TAKT
                                              40000000
 // Gewünschte Pulsfrequenzen
                                                                 Die vier Frequenzen in
Hz. Von 10 KHz bis 250 KHz
 #define FREQUENCY1
                                              33000
 #define FREQUENCY2
                                              36000
 #define FREQUENCY3
                                              38000
 #define FREQUENCY4
                                              40000
                                                                                    tB=tp, die Konstan-
te gibt an, wieviele
Impulse in tB sind.
 // Gewünschte Burstdauer in Impulsen
 #define PULSESPERBURST
                                             30
UINT32 ui32CurrentPulseFrequency=0;
UINT32 ui32NewPulseFrequency=0;
void InterruptHandlerHigh (void);
 #pragma code InterruptVectorHigh = 0x08
void InterruptVectorHigh (void)
     goto InterruptHandlerHigh //jump to interrupt routine
  _endasm
#pragma code
#pragma interrupt InterruptHandlerHigh
void InterruptHandlerHigh ()
  if (PIR1bits.CCP1IF)
         PIR1bits.CCP1IF=0;
         TMR1H=0;
         TMR1L=0;
    }
}
UINT8 ui8LeseJumperEin(void)
    UINT8 ui8ReturnValue;
     ui8ReturnValue = PORTD & Ob11000000;
     ui8ReturnValue >>= 6;
    return _ui8ReturnValue;
void InitBursts(UINT32 _ui32PulseFrequency, UINT8 _ui8PulsesPerBurst, UINT32 _ui32TaktFrequenz)
    UINT16 _ui16CCPR1Value;
UINT8 _ui8PR2Value;
UINT32 ui32Temp;
    TRISC
                      = 0b11111001;
                                                 // CCP1-Pin und CCP2-Pin als Ausgänge
    CCP1CON
                      = 0b00000010;
                                                 // CCP1 im Compare-Modus, Pin-Toggle
    T1CON
                      = 0b00000001;
                                                 // 8-bit-Zugriff, 1:1 Prescaler, Osc Shut-Off, Int.
Clock, Timer on
    T3CON=0;
    PIE1bits.CCP1IE = 1;
    IPR1bits.CCP1IP = 1;
    ui32Temp
                     = _ui32TaktFrequenz*_ui8PulsesPerBurst;
     ui32Temp
                      /= (4* ui32PulseFrequency);
    _ui32Temp
                      -= 1:
    _ui16CCPR1Value = (UINT16) _ui32Temp;

CCPR1H = (UINT8) ( ui16CCPR1Value >> 8);

CCPR1L = (UINT8) ( _ui16CCPR1Value & 0b0000000011111111);
    CCPR1H
    CCPR1L
    CCP2CON
                     = 0b001111111;
                                                 // CCP2 im PWM-Modus
    T2CON
                     = 0b00000101;
                                                 // 1:4 Prescaler, 1:1 Postscaler, Timer on
                     = _ui32TaktFrequenz;
/= (16* ui32PulseFrequency);
    _ui32Temp
    ui32Temp
    _ui32Temp
                     -= 1;
                     = (UINT8) _ui32Temp;
= (UINT8) _ui32Temp;
    ui8PR2Value
    PR2
     ui8PR2Value
                     >>=1;
    CCPR2L =_ui8PR2Value;
```