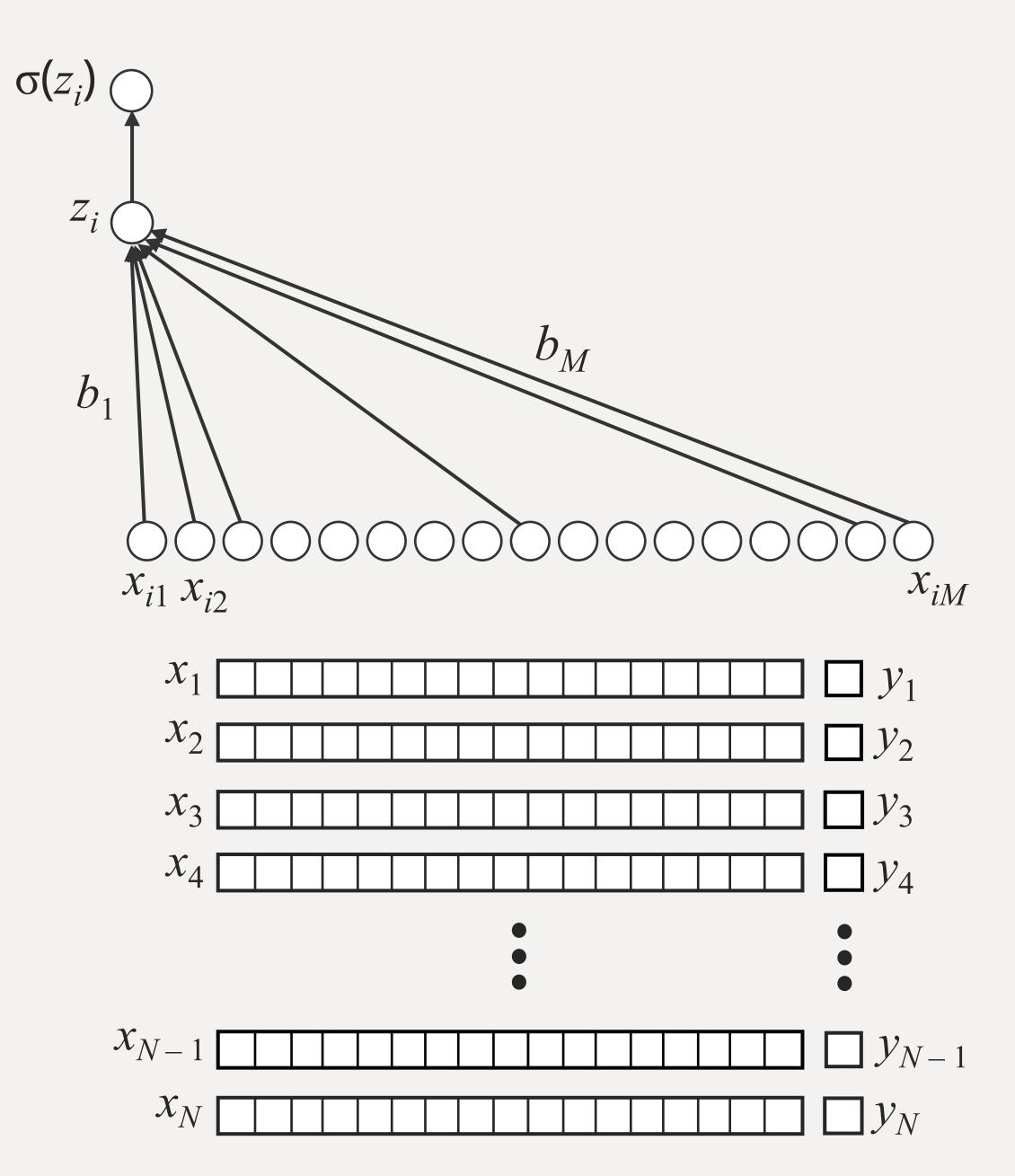
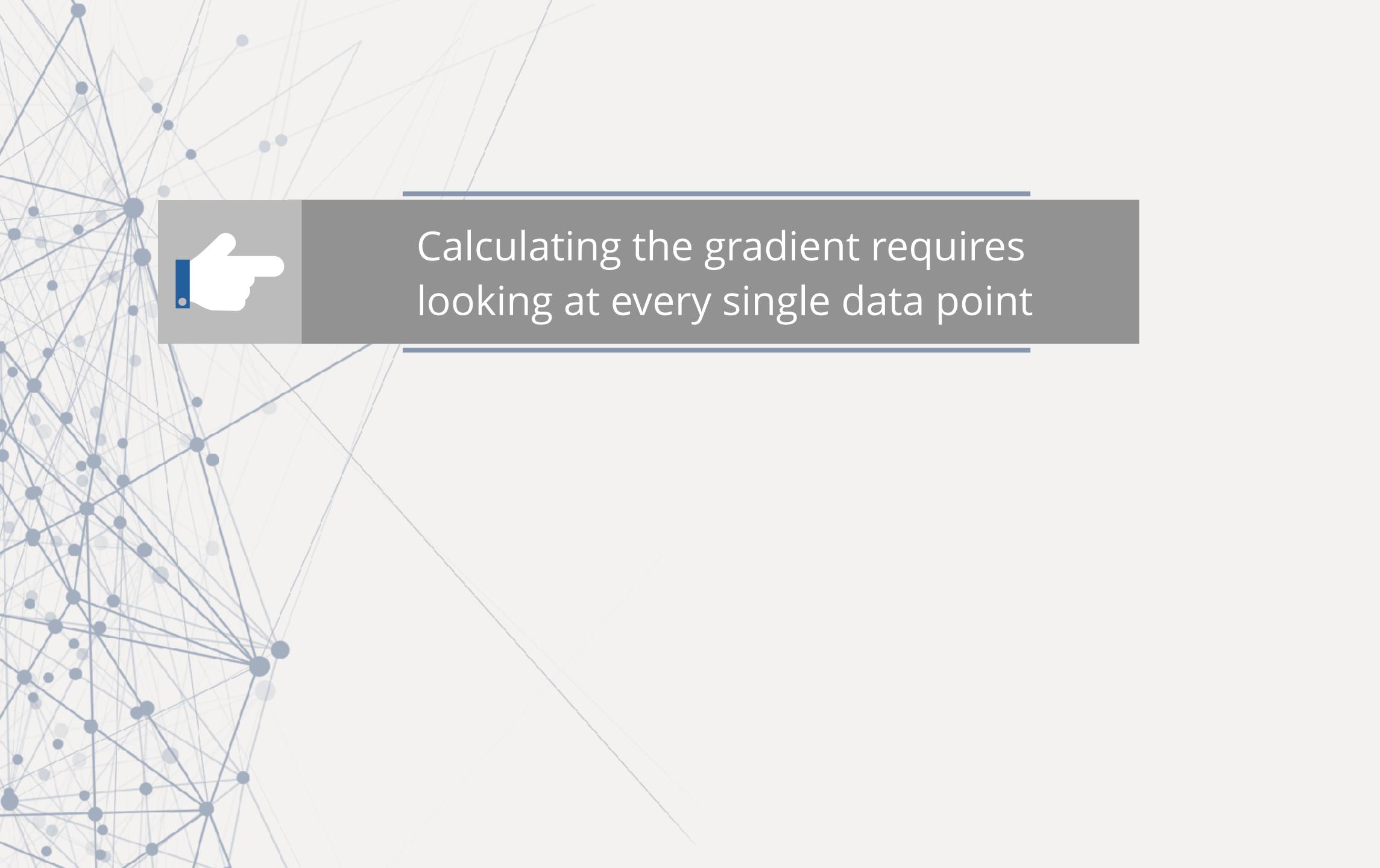


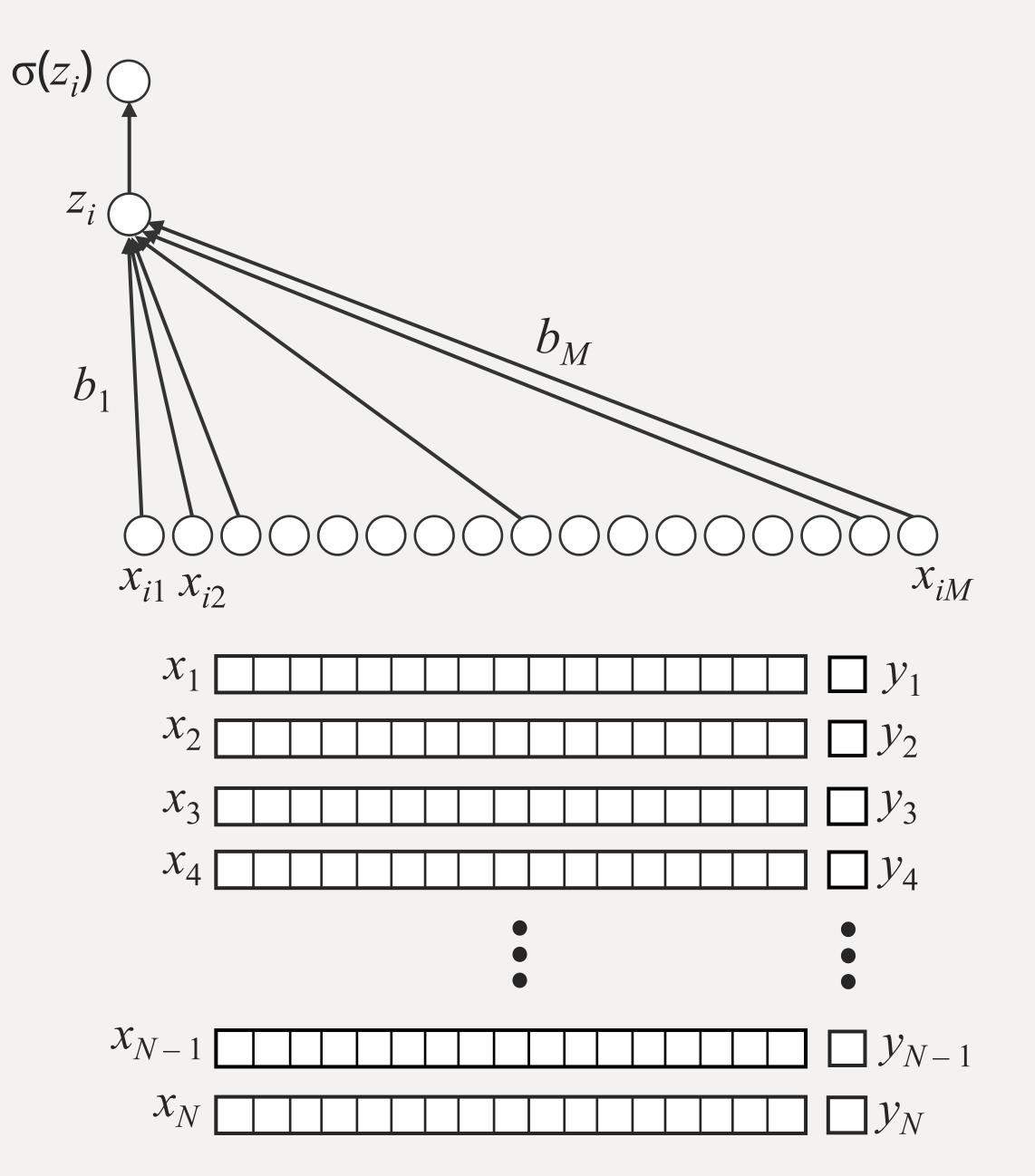
How can we handle big data from an optimization perspective?

$$b^* = \arg\min_{b} \frac{1}{N} \sum_{i}^{N} \ell(y_i, \sigma(z_i))$$





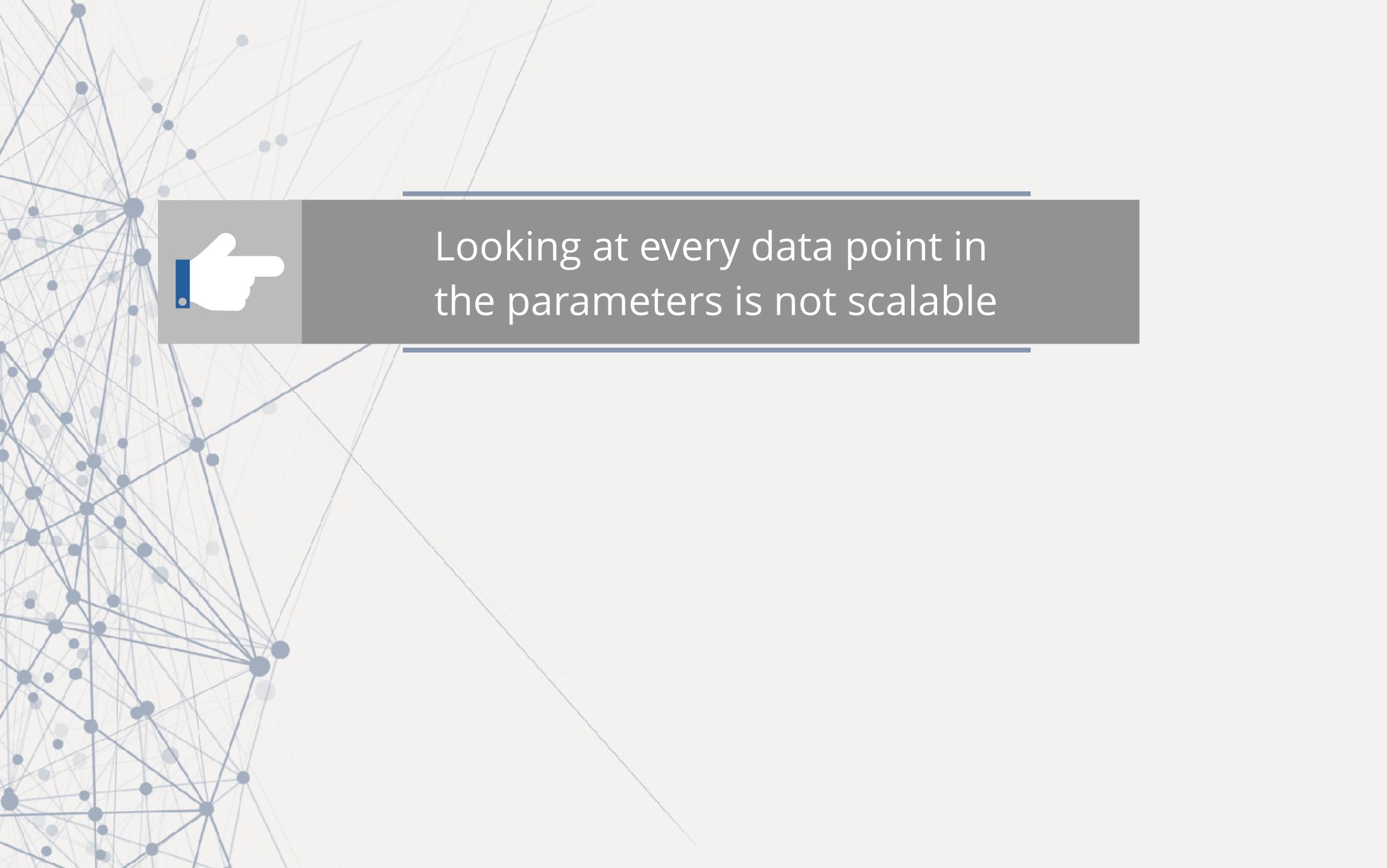
$$\nabla \frac{1}{N} \sum_{i}^{N} \ell(y_i, \sigma(z_i)) = \frac{1}{N} \sum_{i}^{N} \nabla \ell(y_i, \sigma(z_i))$$





MNIST Data Set

~60,000 images

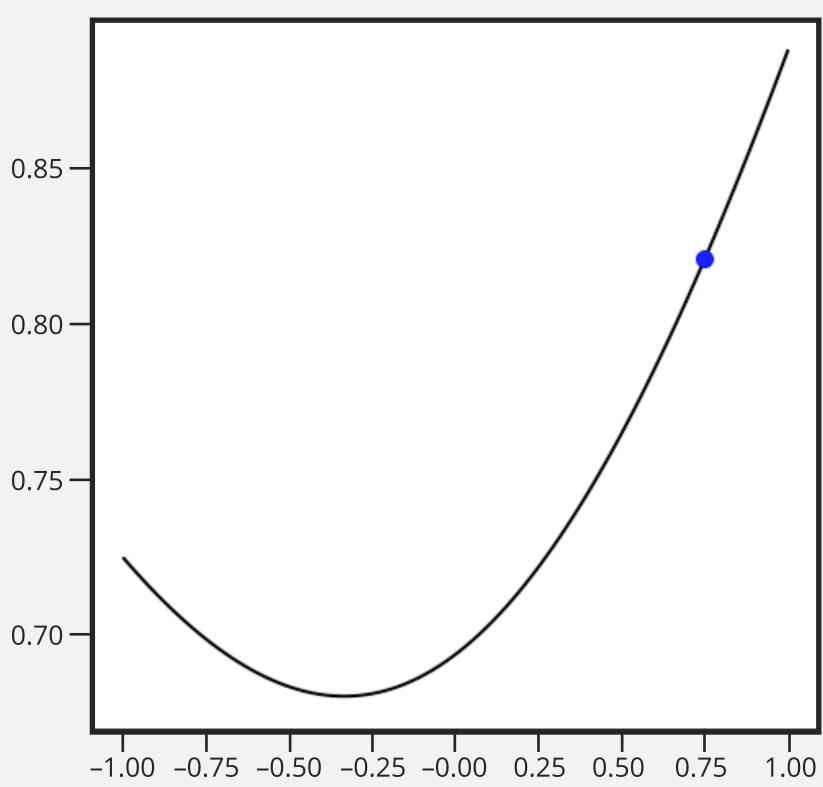


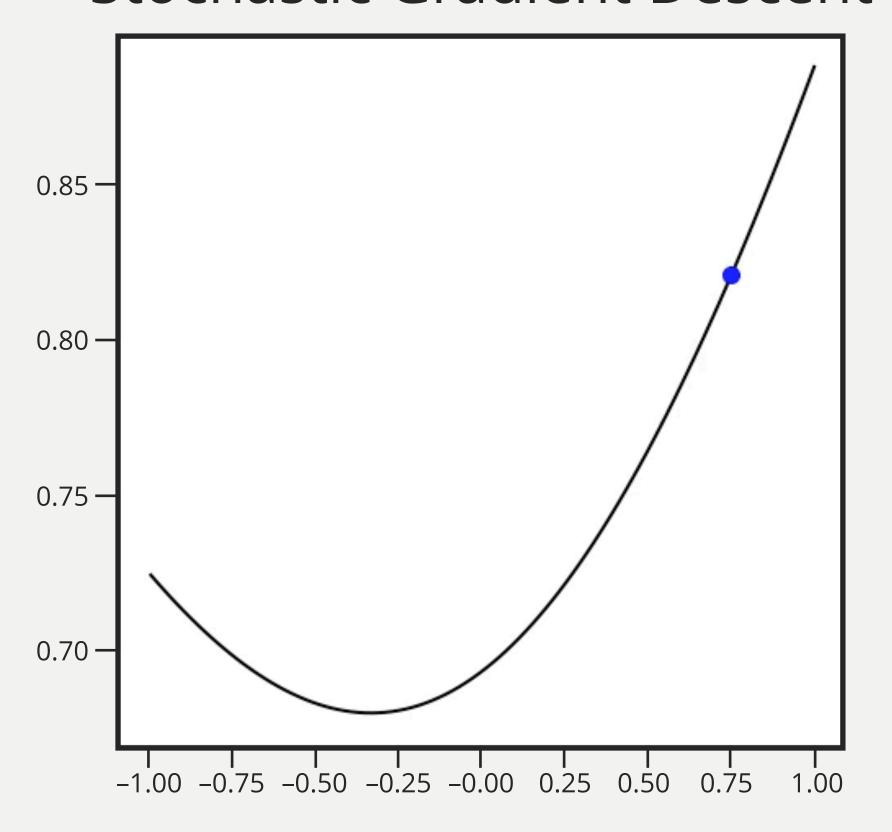
j

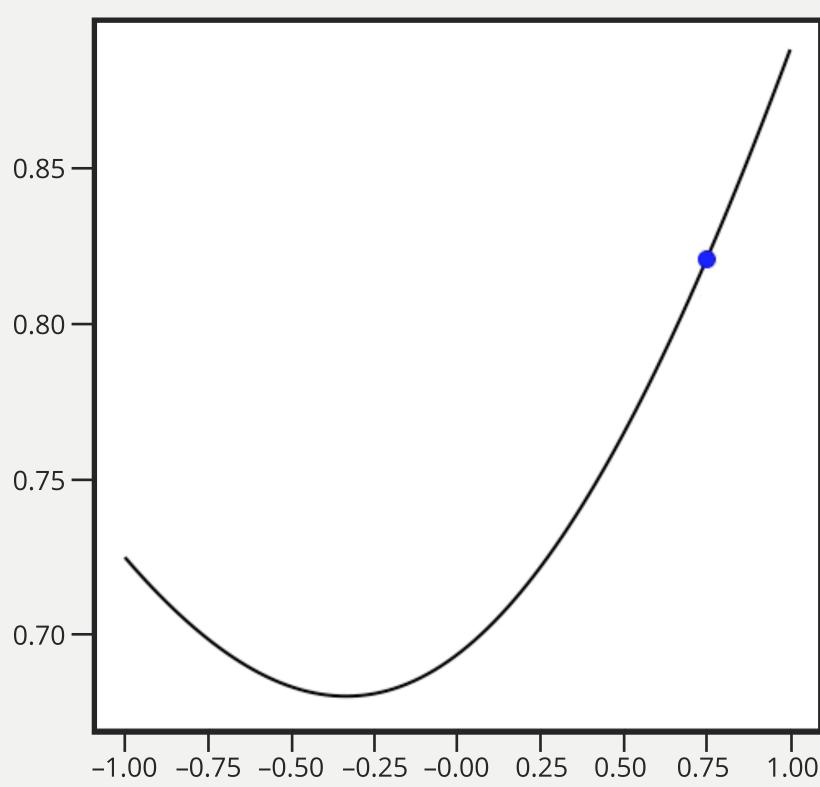
$$\nabla \ell(y_j, \sigma(z_j)) \approx \frac{1}{N} \sum_{i=1}^{N} \nabla \ell(y_i, \sigma(z_i))$$

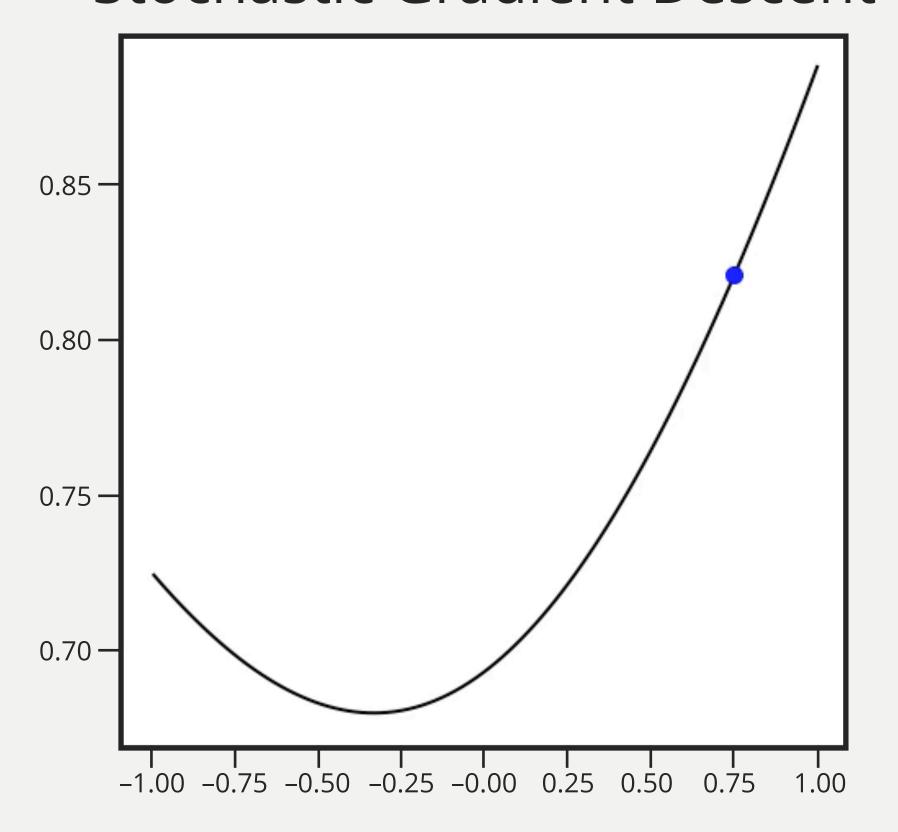
Does this work?

What would this look like?









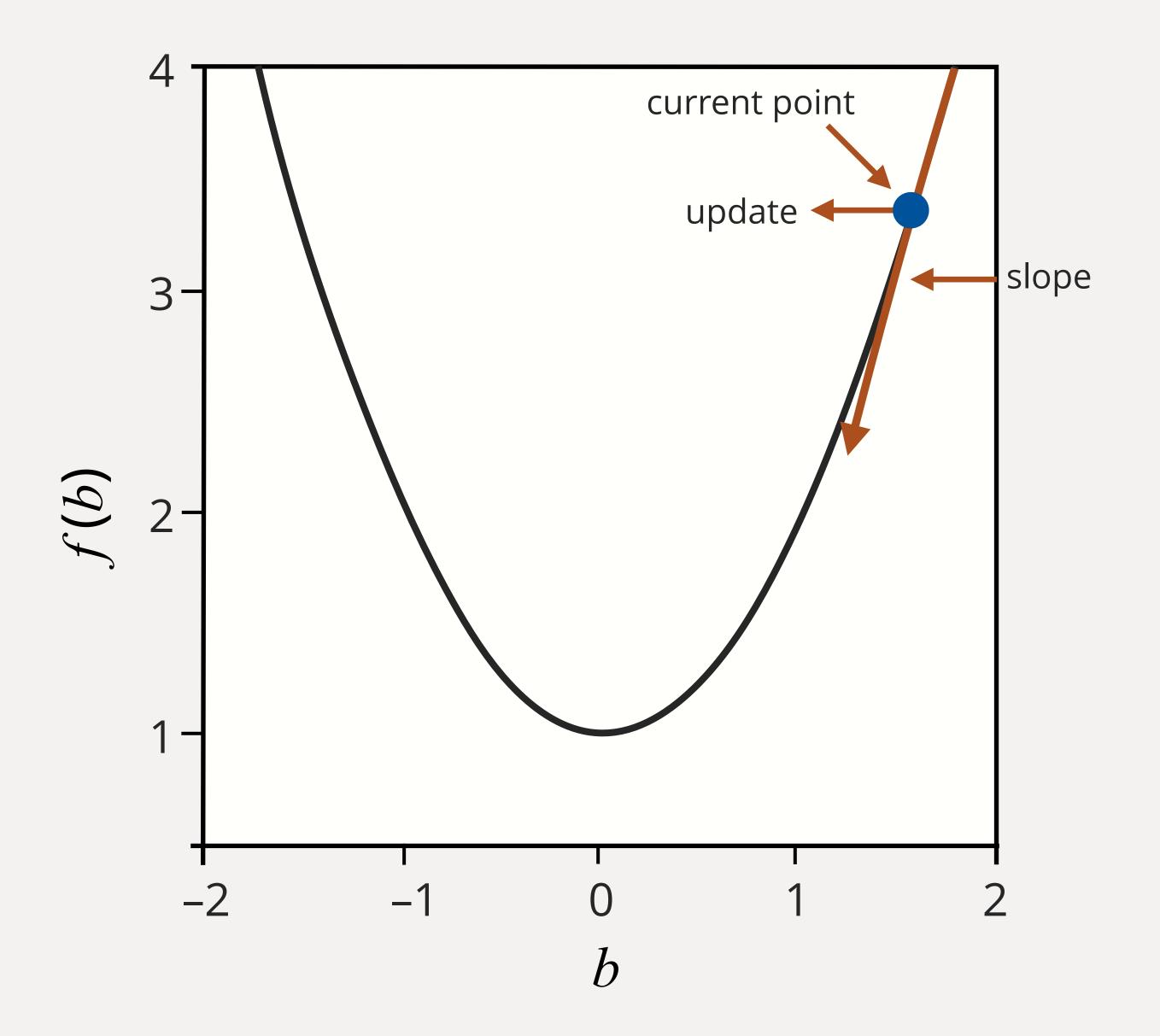
Why does this work?

Data is often redundant

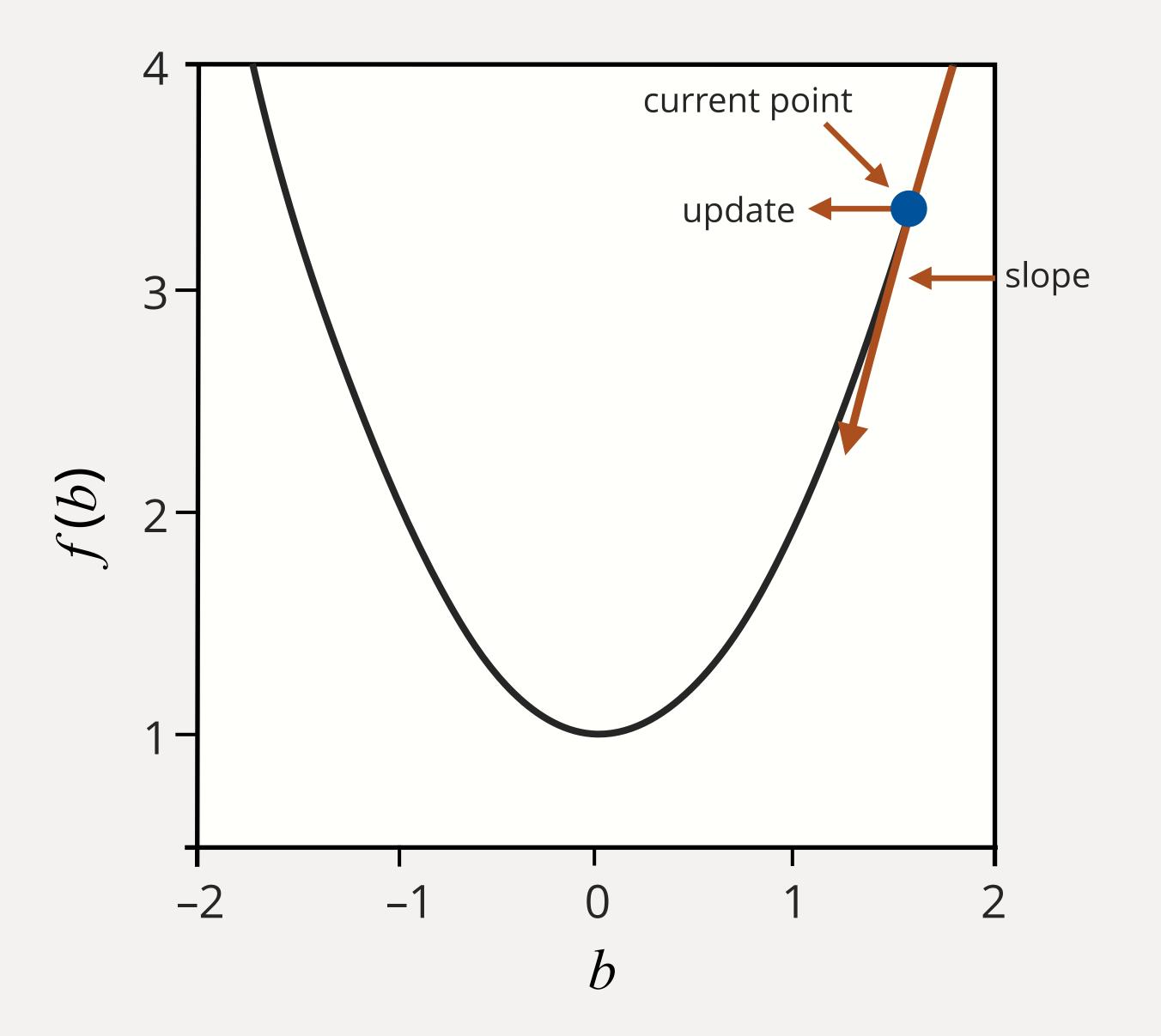


MNIST Data Set

- ~60,000 images
- Only have 10 **types** of images

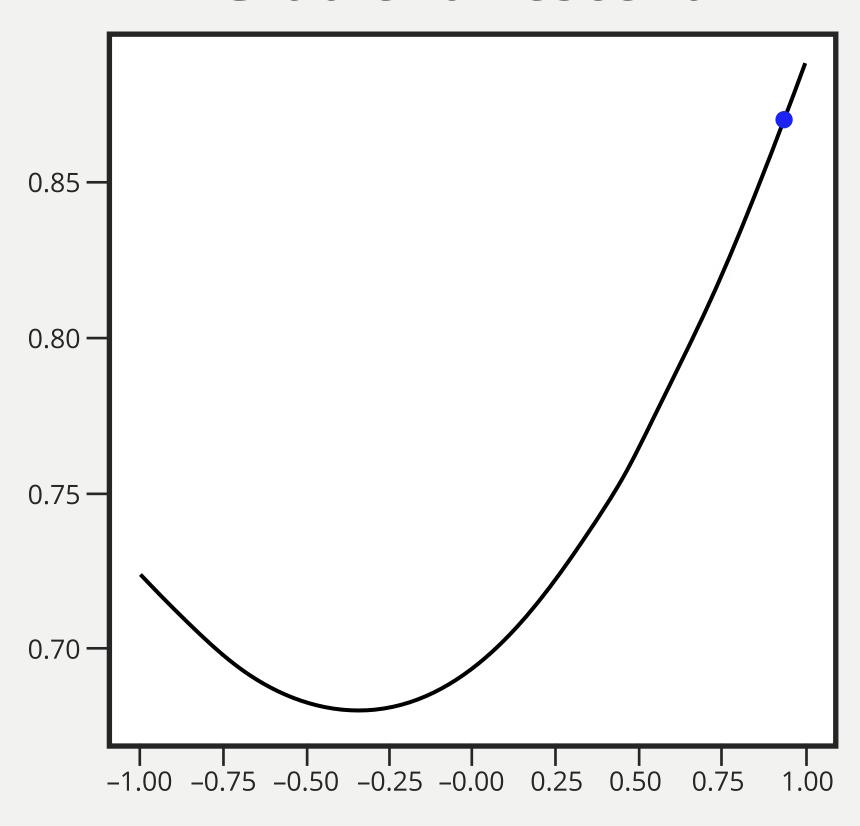


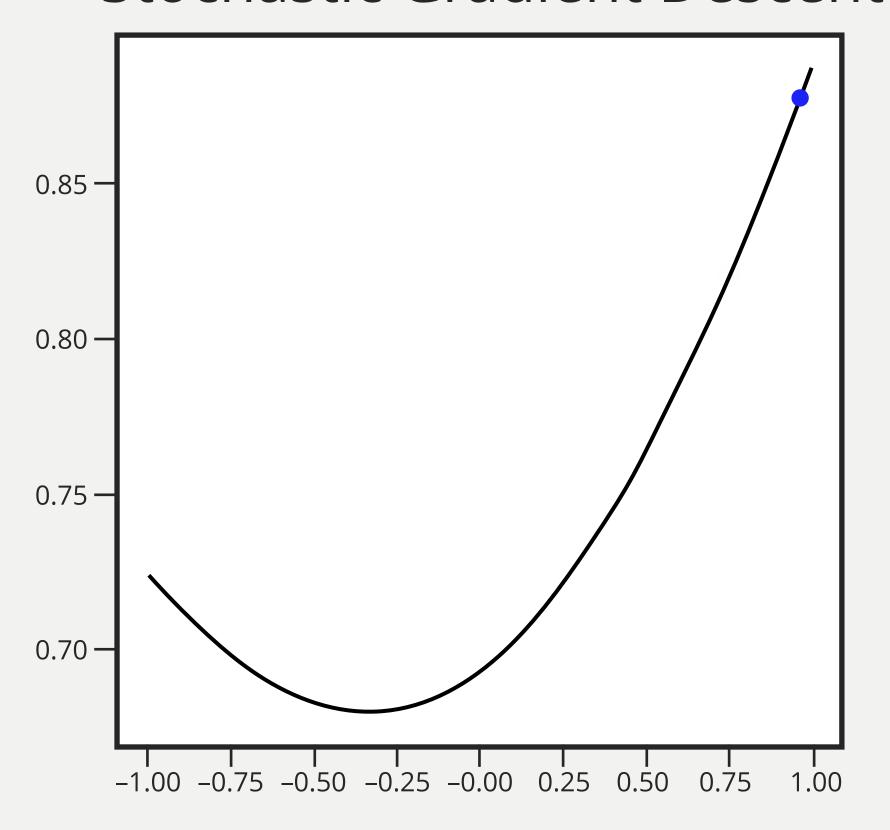
- 1 Start with initial value b^0
- Calculate gradient $\nabla f(b^k)$ over **all** data
- Iteratively update: $b^{k+1} \leftarrow b^k \alpha^k \nabla f(b^k)$
- Repeat 2-3 until solution is good enough

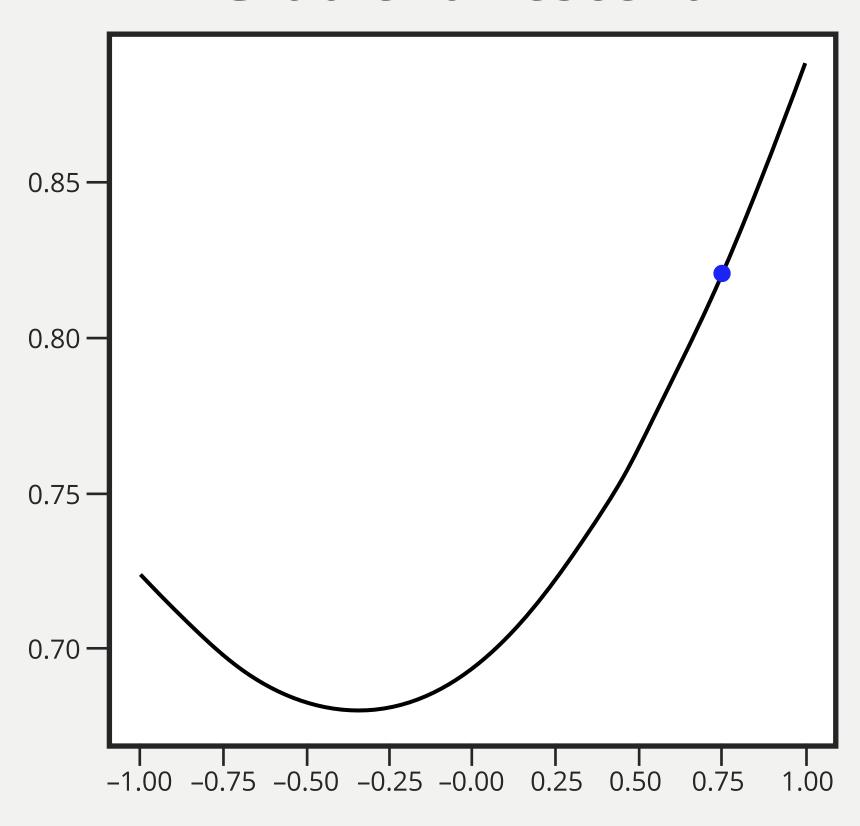


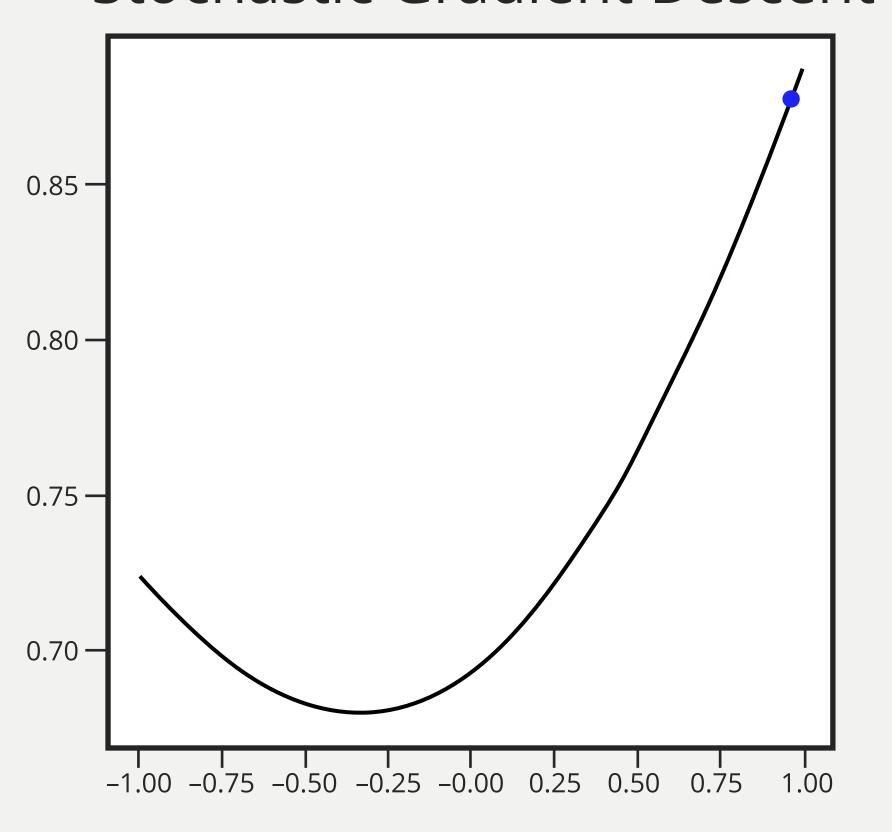
- 1 Start with initial value b^0
- 2 Choose a **random** data entry *j*
- Estimate gradient $\widehat{\nabla f}(b^k)$ by data point j
- Iteratively update: $b^{k+1} \leftarrow b^k \alpha^k \widehat{\nabla f}(b^k)$
- Repeat 2-4 until solution is good enough

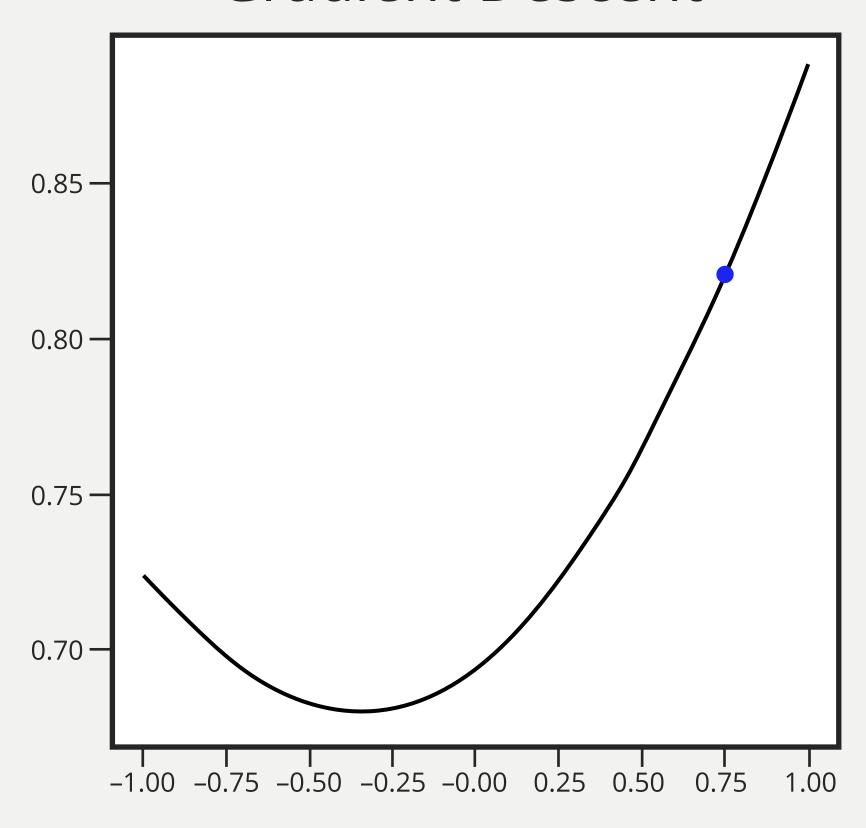
$$E_{j} \sim Unif(1,...,N) \left[\nabla f_{j}(b)\right] = \frac{1}{N} \sum_{i=1}^{N} \nabla f_{i}(b)$$

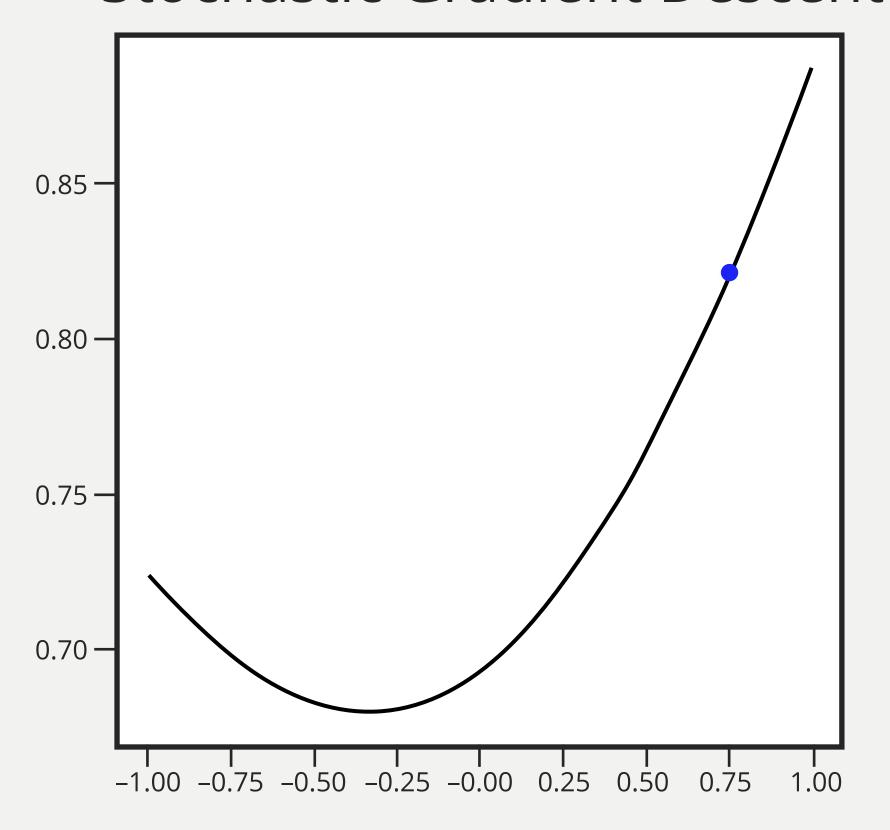




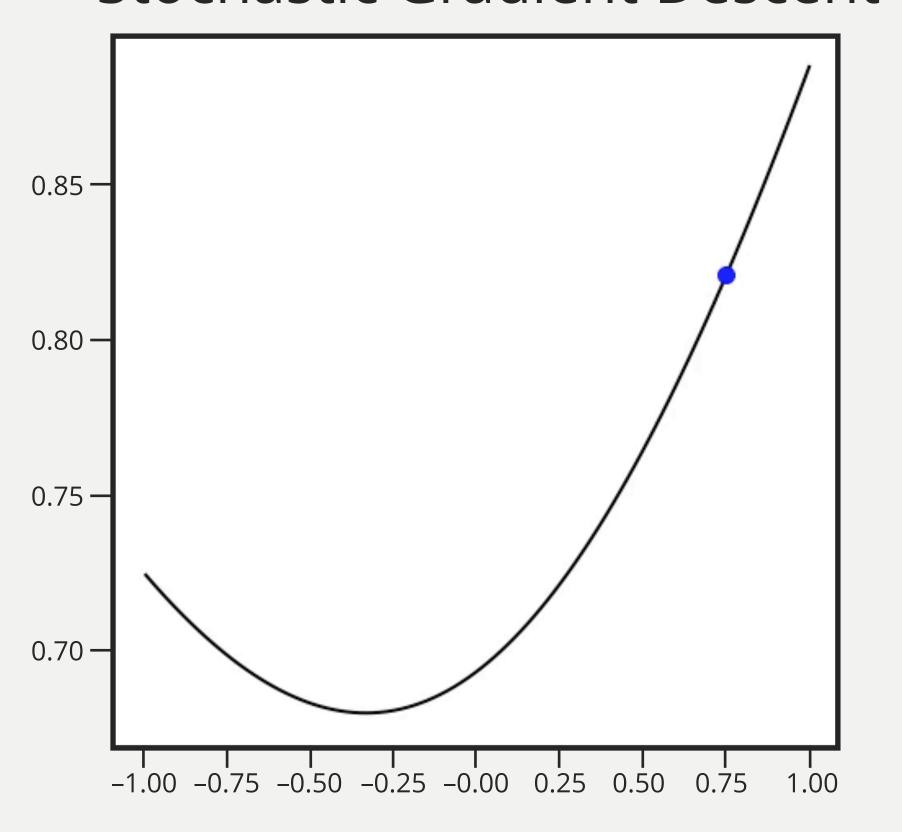




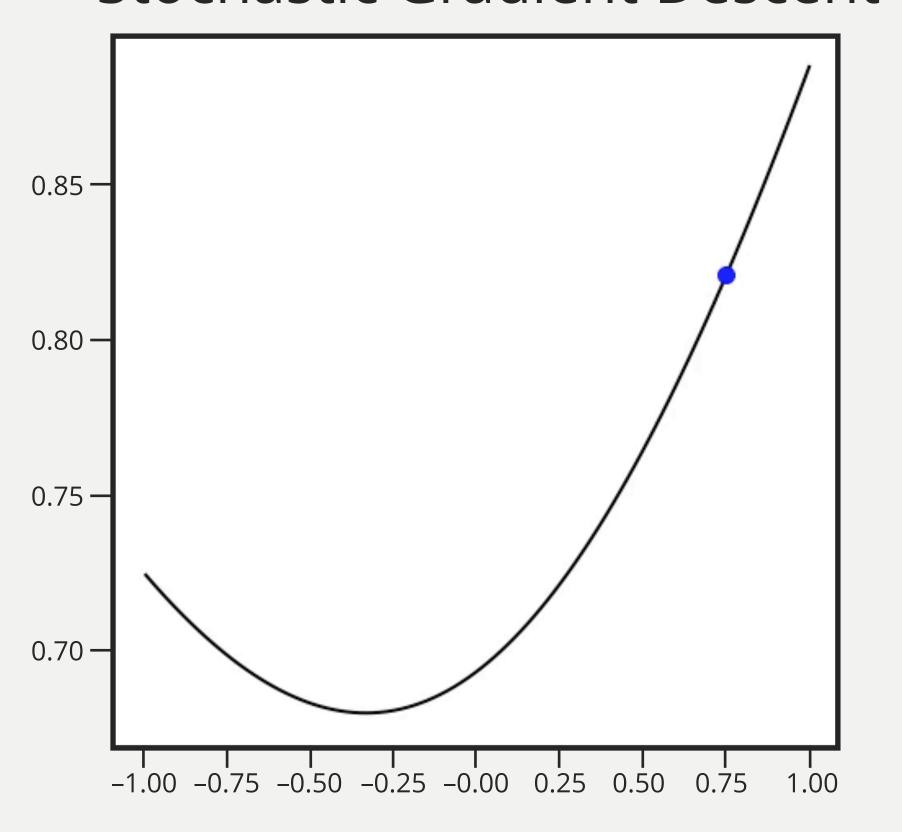




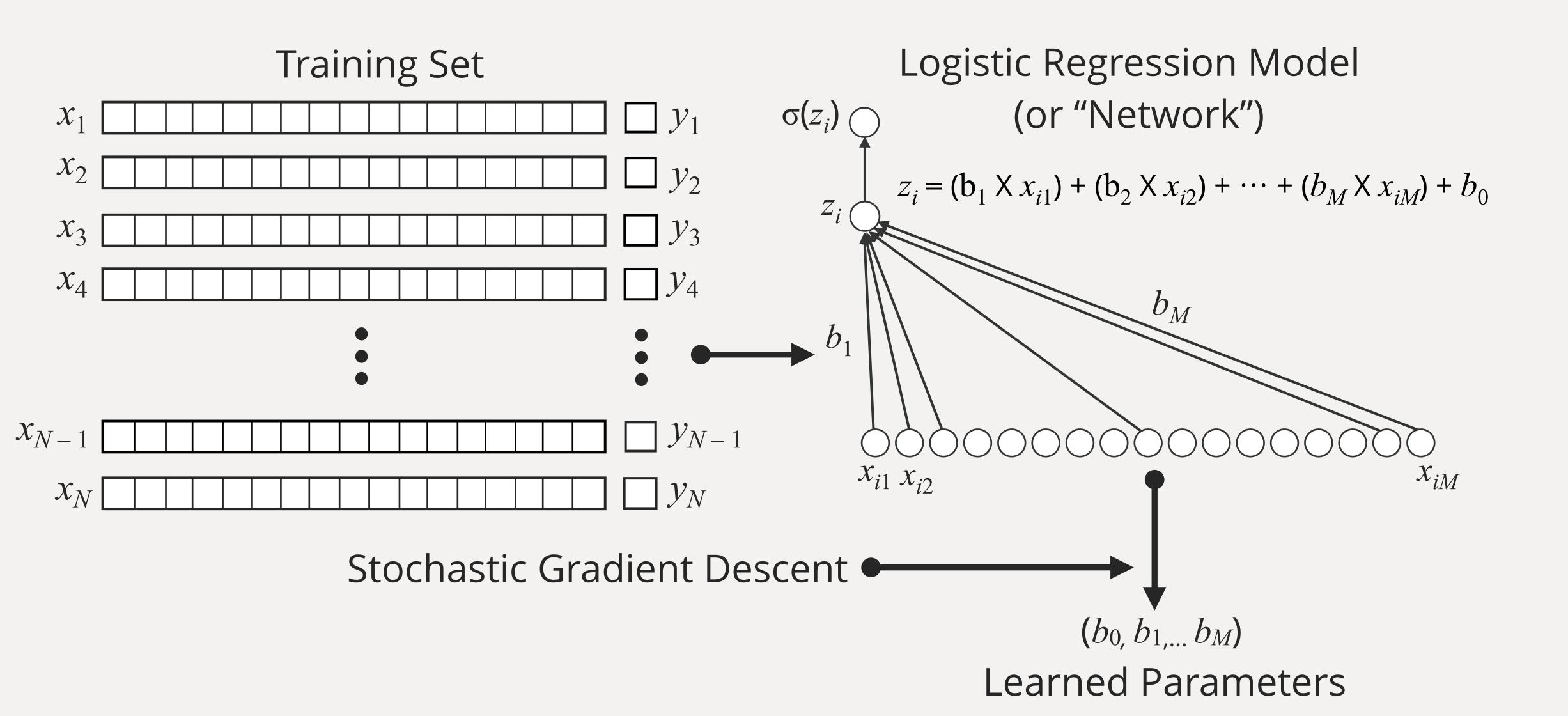
Gradient Descent 0.85 — 0.80 — 0.75 -0.70 -

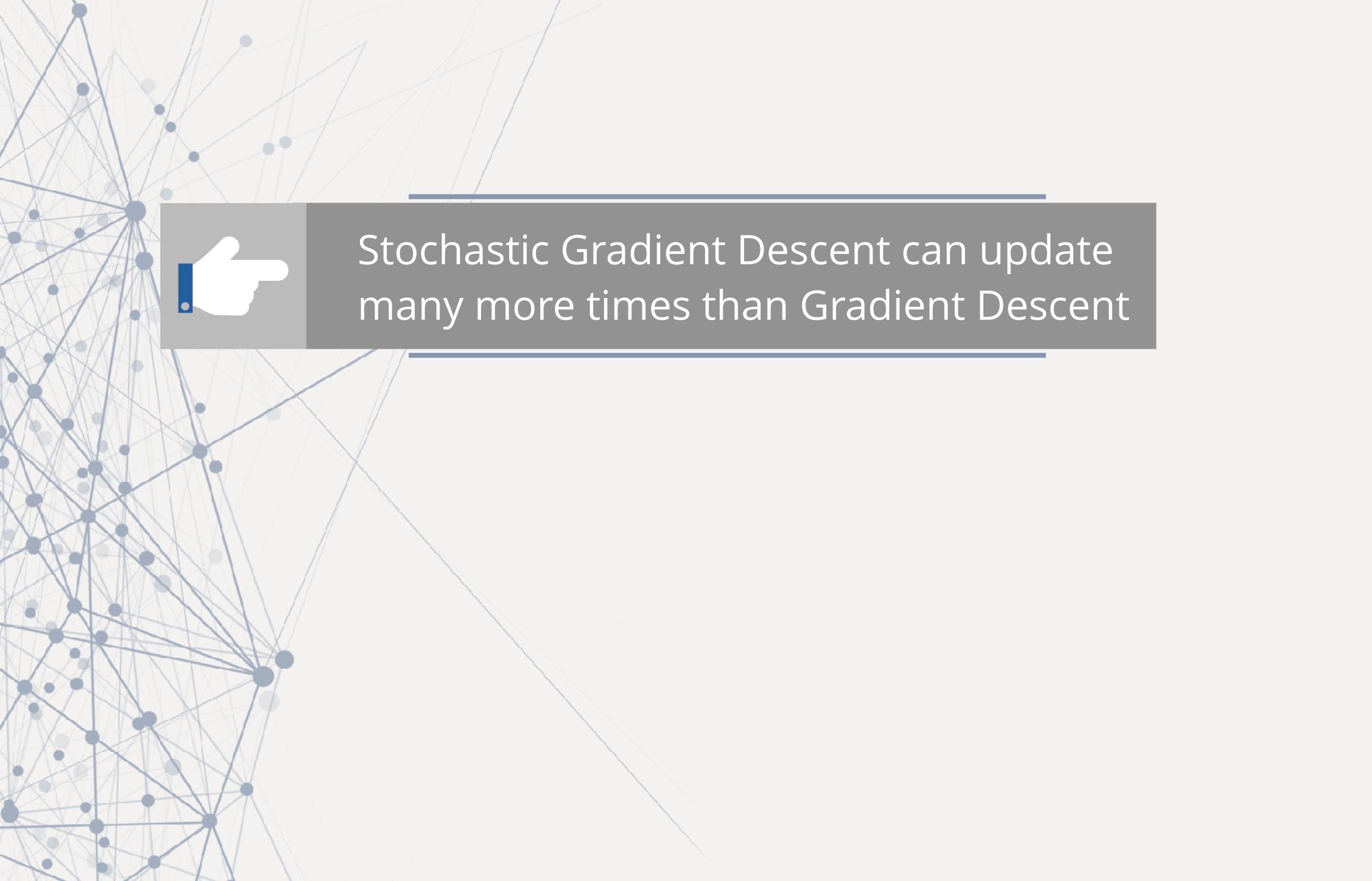


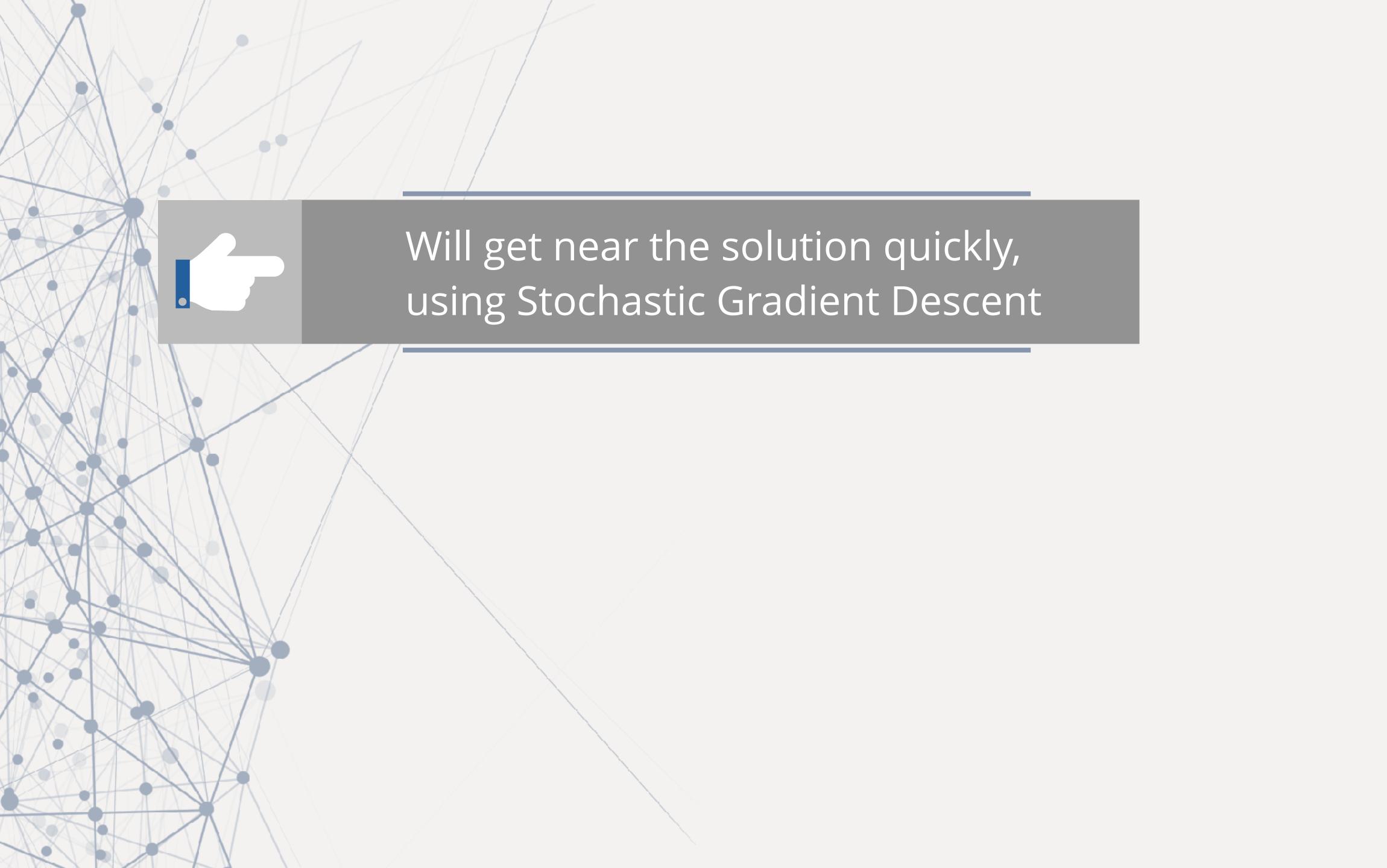
Gradient Descent 0.85 — 0.80 — 0.75 -0.70 -

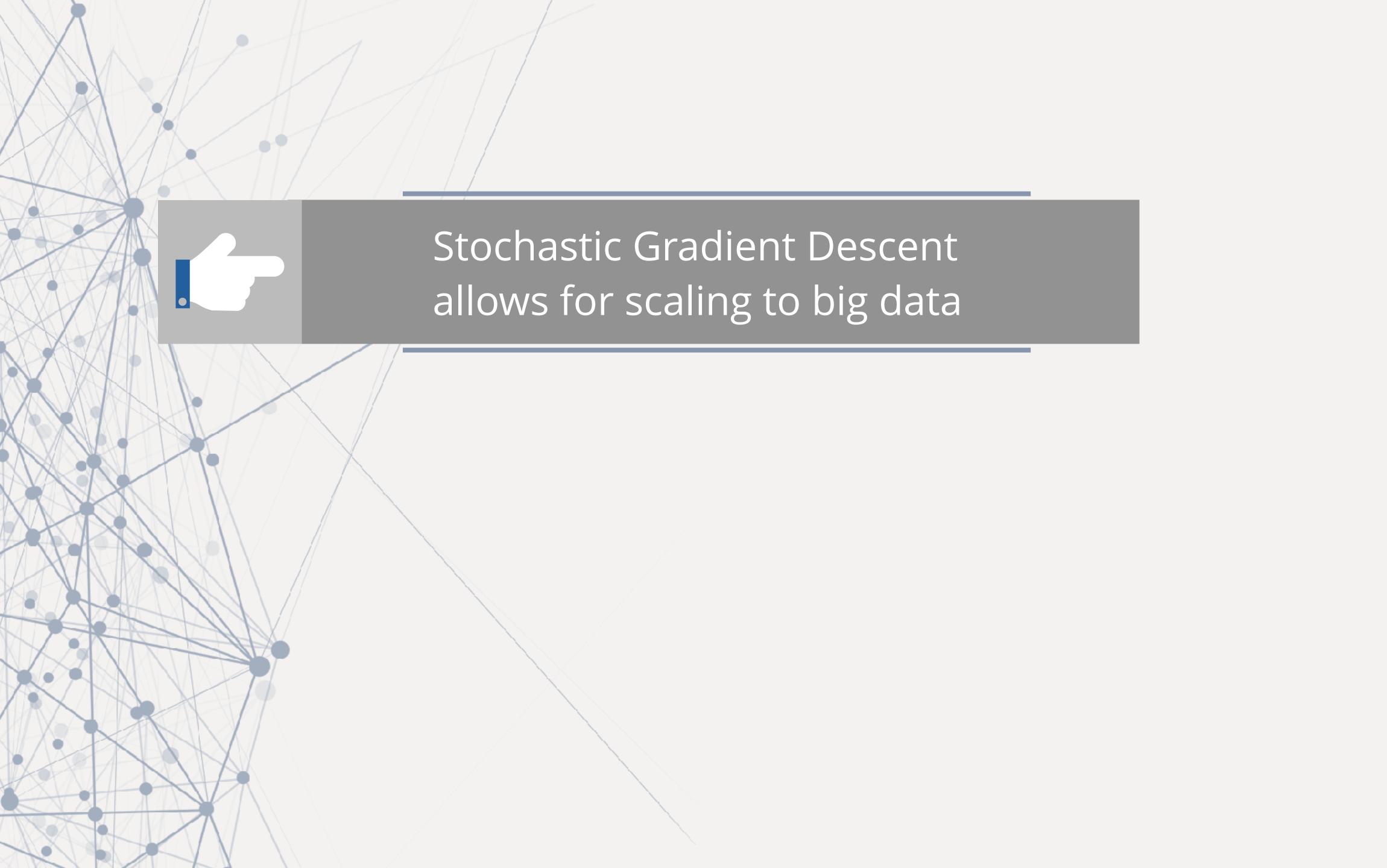


Learned Model Parameters









Credits

MNIST Dataset of Handwritten Digits (Images)

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