

## References

Bradford, Russell J., and James H. Davenport. "Effective tests for cyclotomic polynomials." In International Symposium on Symbolic and Algebraic Computation, pp. 244-251. Springer, Berlin, Heidelberg, 1988.

`sympy.polys.factortools.dup_zz_cyclotomic_poly(n, K)`

Efficiently generate  $n$ -th cyclotomic polynomial.

`sympy.polys.factortools.dup_zz_cyclotomic_factor(f, K)`

Efficiently factor polynomials  $x^{*n} - 1$  and  $x^{*n} + 1$  in  $Z[x]$ .

Given a univariate polynomial  $f$  in  $Z[x]$  returns a list of factors of  $f$ , provided that  $f$  is in the form  $x^{*n} - 1$  or  $x^{*n} + 1$  for  $n \geq 1$ . Otherwise returns None.

Factorization is performed using cyclotomic decomposition of  $f$ , which makes this method much faster than any other direct factorization approach (e.g. Zassenhaus's).

## References

[R707]

`sympy.polys.factortools.dup_zz_factor_sqf(f, K)`

Factor square-free (non-primitive) polynomials in  $Z[x]$ .

`sympy.polys.factortools.dup_zz_factor(f, K)`

Factor (non square-free) polynomials in  $Z[x]$ .

Given a univariate polynomial  $f$  in  $Z[x]$  computes its complete factorization  $f_1, \dots, f_n$  into irreducibles over integers:

```
f = content(f) f_1**k_1 ... f_n**k_n
```

The factorization is computed by reducing the input polynomial into a primitive square-free polynomial and factoring it using Zassenhaus algorithm. Trial division is used to recover the multiplicities of factors.

The result is returned as a tuple consisting of:

```
(content(f), [(f_1, k_1), ..., (f_n, k_n)])
```

## Examples

Consider the polynomial  $f = 2 * x^{*4} - 2$ :

```
>>> from sympy.polys import ring, ZZ
>>> R, x = ring("x", ZZ)

>>> R.dup_zz_factor(2*x**4 - 2)
(2, [(x - 1, 1), (x + 1, 1), (x**2 + 1, 1)])
```

In result we got the following factorization:

```
f = 2 (x - 1) (x + 1) (x**2 + 1)
```

Note that this is a complete factorization over integers, however over Gaussian integers we can factor the last term.

By default, polynomials  $x^{**n}-1$  and  $x^{**n}+1$  are factored using cyclotomic decomposition to speedup computations. To disable this behaviour set `cyclotomic=False`.

## References

[R708]

`sympy.polys.factortools.dmp_zz_wang_non_divisors(E, cs, ct, K)`

Wang/EEZ: Compute a set of valid divisors.

`sympy.polys.factortools.dmp_zz_wang_test_points(f, T, ct, A, u, K)`

Wang/EEZ: Test evaluation points for suitability.

`sympy.polys.factortools.dmp_zz_wang_lead_coeffs(f, T, cs, E, H, A, u, K)`

Wang/EEZ: Compute correct leading coefficients.

`sympy.polys.factortools.dmp_zz_diophantine(F, c, A, d, p, u, K)`

Wang/EEZ: Solve multivariate Diophantine equations.

`sympy.polys.factortools.dmp_zz_wang_hensel_lifting(f, H, LC, A, p, u, K)`

Wang/EEZ: Parallel Hensel lifting algorithm.

`sympy.polys.factortools.dmp_zz_wang(f, u, K, mod=None, seed=None)`

Factor primitive square-free polynomials in  $\mathbb{Z}[X]$ .

Given a multivariate polynomial  $f$  in  $\mathbb{Z}[x_1, \dots, x_n]$ , which is primitive and square-free in  $x_1$ , computes factorization of  $f$  into irreducibles over integers.

The procedure is based on Wang's Enhanced Extended Zassenhaus algorithm. The algorithm works by viewing  $f$  as a univariate polynomial in  $\mathbb{Z}[x_2, \dots, x_n][x_1]$ , for which an evaluation mapping is computed:

$x_2 \rightarrow a_2, \dots, x_n \rightarrow a_n$

where  $a_i$ , for  $i = 2, \dots, n$ , are carefully chosen integers. The mapping is used to transform  $f$  into a univariate polynomial in  $\mathbb{Z}[x_1]$ , which can be factored efficiently using Zassenhaus algorithm. The last step is to lift univariate factors to obtain true multivariate factors. For this purpose a parallel Hensel lifting procedure is used.

The parameter `seed` is passed to `_randint` and can be used to seed `randint` (when an integer) or (for testing purposes) can be a sequence of numbers.

## References

[R709], [R710]

`sympy.polys.factortools.dmp_zz_factor(f, u, K)`

Factor (non square-free) polynomials in  $\mathbb{Z}[X]$ .

Given a multivariate polynomial  $f$  in  $\mathbb{Z}[x]$  computes its complete factorization  $f_1, \dots, f_n$  into irreducibles over integers:

```
f = content(f) f_1**k_1 ... f_n**k_n
```

The factorization is computed by reducing the input polynomial into a primitive square-free polynomial and factoring it using Enhanced Extended Zassenhaus (EEZ) algorithm. Trial division is used to recover the multiplicities of factors.

The result is returned as a tuple consisting of:

```
(content(f), [(f_1, k_1), ..., (f_n, k_n)])
```

Consider polynomial  $f = 2 * (x ** 2 - y ** 2)$ :

```
>>> from sympy.polys import ring, ZZ
>>> R, x,y = ring("x,y", ZZ)

>>> R.dmp_zz_factor(2*x**2 - 2*y**2)
(2, [(x - y, 1), (x + y, 1)])
```

In result we got the following factorization:

```
f = 2 (x - y) (x + y)
```

## References

[R711]

`sympy.polys.factortools.dmp_ext_factor(f, u, K)`

Factor multivariate polynomials over algebraic number fields.

`sympy.polys.factortools.dup_gf_factor(f, K)`

Factor univariate polynomials over finite fields.

`sympy.polys.factortools.dmp_factor_list(f, u, K0)`

Factor multivariate polynomials into irreducibles in  $K[X]$ .

`sympy.polys.factortools.dmp_factor_list_include(f, u, K)`

Factor multivariate polynomials into irreducibles in  $K[X]$ .

`sympy.polys.factortools.dmp_irreducible_p(f, u, K)`

Returns True if a multivariate polynomial  $f$  has no factors over its domain.

## Groebner basis algorithms

Groebner bases can be used to answer many problems in computational commutative algebra. Their computation is rather complicated, and very performance-sensitive. We present here various low-level implementations of Groebner basis computation algorithms; please see the previous section of the manual for usage.

`sympy.polys.groebnertools.groebner(seq, ring, method=None)`

Computes Groebner basis for a set of polynomials in  $K[X]$ .

Wrapper around the (default) improved Buchberger and the other algorithms for computing Groebner bases. The choice of algorithm can be changed via method argument or `sympy.polys.polyconfig.setup()` (page 2643), where method can be either buchberger or f5b.

`sympy.polys.groebnertools.spoly(p1, p2, ring)`

Compute  $\text{LCM}(\text{LM}(p1), \text{LM}(p2))/\text{LM}(p1)*p1 - \text{LCM}(\text{LM}(p1), \text{LM}(p2))/\text{LM}(p2)*p2$  This is the S-poly provided p1 and p2 are monic

`sympy.polys.groebnertools.red_groebner(G, ring)`

Compute reduced Groebner basis, from BeckerWeispfenning93, p. 216

Selects a subset of generators, that already generate the ideal and computes a reduced Groebner basis for them.

`sympy.polys.groebnertools.is_groebner(G, ring)`

Check if G is a Groebner basis.

`sympy.polys.groebnertools.is_minimal(G, ring)`

Checks if G is a minimal Groebner basis.

`sympy.polys.groebnertools.is_reduced(G, ring)`

Checks if G is a reduced Groebner basis.

`sympy.polys.fglmtools.matrix_fgfm(F, ring, O_to)`

Converts the reduced Groebner basis F of a zero-dimensional ideal w.r.t.  $O_{\text{from}}$  to a reduced Groebner basis w.r.t.  $O_{\text{to}}$ .

## References

[R712]

Groebner basis algorithms for modules are also provided:

`sympy.polys.distributedmodules.sdm_spoly(f, g, O, K, phantom=None)`

Compute the generalized s-polynomial of f and g.

The ground field is assumed to be K, and monomials ordered according to O.

This is invalid if either of f or g is zero.

If the leading terms of f and g involve different basis elements of F, their s-poly is defined to be zero. Otherwise it is a certain linear combination of f and g in which the leading terms cancel. See [SCA, defn 2.3.6] for details.

If phantom is not None, it should be a pair of module elements on which to perform the same operation(s) as on f and g. The in this case both results are returned.

## Examples

```
>>> from sympy.polys.distributedmodules import sdm_spoly
>>> from sympy.polys import QQ, lex
>>> f = [((2, 1, 1), QQ(1)), ((1, 0, 1), QQ(1))]
>>> g = [((2, 3, 0), QQ(1))]
>>> h = [((1, 2, 3), QQ(1))]
>>> sdm_spoly(f, h, lex, QQ)
[]
>>> sdm_spoly(f, g, lex, QQ)
[((1, 2, 1), 1)]
```

`sympy.polys.distributedmodules.sdm_ecart(f)`

Compute the ecart of  $f$ .

This is defined to be the difference of the total degree of  $f$  and the total degree of the leading monomial of  $f$  [SCA, defn 2.3.7].

Invalid if  $f$  is zero.

## Examples

```
>>> from sympy.polys.distributedmodules import sdm_ecart
>>> sdm_ecart([((1, 2, 3), 1), ((1, 0, 1), 1)])
0
>>> sdm_ecart([((2, 2, 1), 1), ((1, 5, 1), 1)])
3
```

`sympy.polys.distributedmodules.sdm_nf_mora(f, G, O, K, phantom=None)`

Compute a weak normal form of  $f$  with respect to  $G$  and order  $O$ .

The ground field is assumed to be  $K$ , and monomials ordered according to  $O$ .

Weak normal forms are defined in [SCA, defn 2.3.3]. They are not unique. This function deterministically computes a weak normal form, depending on the order of  $G$ .

The most important property of a weak normal form is the following: if  $R$  is the ring associated with the monomial ordering (if the ordering is global, we just have  $R = K[x_1, \dots, x_n]$ , otherwise it is a certain localization thereof),  $I$  any ideal of  $R$  and  $G$  a standard basis for  $I$ , then for any  $f \in R$ , we have  $f \in I$  if and only if  $NF(f|G) = 0$ .

This is the generalized Mora algorithm for computing weak normal forms with respect to arbitrary monomial orders [SCA, algorithm 2.3.9].

If `phantom` is not `None`, it should be a pair of “phantom” arguments on which to perform the same computations as on  $f$ ,  $G$ , both results are then returned.

`sympy.polys.distributedmodules.sdm_groebner(G, NF, O, K, extended=False)`

Compute a minimal standard basis of  $G$  with respect to order  $O$ .

The algorithm uses a normal form  $NF$ , for example `sdm_nf_mora`. The ground field is assumed to be  $K$ , and monomials ordered according to  $O$ .

Let  $N$  denote the submodule generated by elements of  $G$ . A standard basis for  $N$  is a subset  $S$  of  $N$ , such that  $\text{in}(S) = \text{in}(N)$ , where for any subset  $X$  of  $F$ ,  $\text{in}(X)$  denotes the submodule generated by the initial forms of elements of  $X$ . [SCA, defn 2.3.2]

A standard basis is called minimal if no subset of it is a standard basis.

One may show that standard bases are always generating sets.

Minimal standard bases are not unique. This algorithm computes a deterministic result, depending on the particular order of  $G$ .

If `extended=True`, also compute the transition matrix from the initial generators to the groebner basis. That is, return a list of coefficient vectors, expressing the elements of the groebner basis in terms of the elements of  $G$ .

This functions implements the “sugar” strategy, see

Giovini et al: “One sugar cube, please” OR Selection strategies in Buchberger algorithm.

## Options

Options manager for *Poly* (page 2378) and public API functions.

**class** `sympy.polys.polyoptions.Options`(*gens*, *args*, *flags=None*, *strict=False*)

Options manager for polynomial manipulation module.

## Examples

```
>>> from sympy.polys.polyoptions import Options
>>> from sympy.polys.polyoptions import build_options
```

```
>>> from sympy.abc import x, y, z
```

```
>>> Options((x, y, z), {'domain': 'ZZ'})
{'auto': False, 'domain': ZZ, 'gens': (x, y, z)}
```

```
>>> build_options((x, y, z), {'domain': 'ZZ'})
{'auto': False, 'domain': ZZ, 'gens': (x, y, z)}
```

## Options

- Expand — boolean option
- Gens — option
- Wrt — option
- Sort — option
- Order — option
- Field — boolean option
- Greedy — boolean option
- Domain — option
- Split — boolean option
- Gaussian — boolean option
- Extension — option

- Modulus — option
- Symmetric — boolean option
- Strict — boolean option

### Flags

- Auto — boolean flag
- Frac — boolean flag
- Formal — boolean flag
- Polys — boolean flag
- Include — boolean flag
- All — boolean flag
- Gen — flag
- Series — boolean flag

**clone**(*updates*={})

Clone self and update specified options.

`sympy.polys.polyoptions.build_options(gens, args=None)`

Construct options from keyword arguments or ... options.

### Configuration

Configuration utilities for polynomial manipulation algorithms.

`sympy.polys.polyconfig.setup(key, value=None)`

Assign a value to (or reset) a configuration item.

### Exceptions

These are exceptions defined by the polynomials module.

TODO sort and explain

**class** `sympy.polys.polyerrors.BasePolynomialError`

Base class for polynomial related exceptions.

**class** `sympy.polys.polyerrors.ExactQuotientFailed(f, g, dom=None)`

**class** `sympy.polys.polyerrors.OperationNotSupported(poly, func)`

**class** `sympy.polys.polyerrors.HeuristicGCDFailed`

**class** `sympy.polys.polyerrors.HomomorphismFailed`

**class** `sympy.polys.polyerrors.IsomorphismFailed`

**class** `sympy.polys.polyerrors.ExtraneousFactors`

**class** `sympy.polys.polyerrors.EvaluationFailed`

```

class sympy.polys.polyerrors.RefinementFailed
class sympy.polys.polyerrors.CoercionFailed
class sympy.polys.polyerrors.NotInvertible
class sympy.polys.polyerrors.NotReversible
class sympy.polys.polyerrors.NotAlgebraic
class sympy.polys.polyerrors.DomainError
class sympy.polys.polyerrors.PolynomialError
class sympy.polys.polyerrors.UnificationFailed
class sympy.polys.polyerrors.GeneratorsNeeded
class sympy.polys.polyerrors.ComputationFailed(func, nargs, exc)
class sympy.polys.polyerrors.GeneratorsError
class sympy.polys.polyerrors.UnivariatePolynomialError
class sympy.polys.polyerrors.MultivariatePolynomialError
class sympy.polys.polyerrors.PolificationFailed(opt, origs, exprs, seq=False)
class sympy.polys.polyerrors.OptionError
class sympy.polys.polyerrors.FlagError

```

## Reference

### Modular GCD

`sympy.polys.modulargcd.modgcd_univariate(f, g)`

Computes the GCD of two polynomials in  $\mathbb{Z}[x]$  using a modular algorithm.

The algorithm computes the GCD of two univariate integer polynomials  $f$  and  $g$  by computing the GCD in  $\mathbb{Z}_p[x]$  for suitable primes  $p$  and then reconstructing the coefficients with the Chinese Remainder Theorem. Trial division is only made for candidates which are very likely the desired GCD.

#### Parameters

**f** : PolyElement  
univariate integer polynomial  
**g** : PolyElement  
univariate integer polynomial

#### Returns

**h** : PolyElement  
GCD of the polynomials  $f$  and  $g$   
**cff** : PolyElement



cofactor of  $f$ , i.e.  $\frac{f}{h}$   
**cfg** : PolyElement  
 cofactor of  $g$ , i.e.  $\frac{g}{h}$

## Examples

```
>>> from sympy.polys.modulargcd import modgcd_univariate
>>> from sympy.polys import ring, ZZ
```

```
>>> R, x = ring("x", ZZ)
```

```
>>> f = x**5 - 1
>>> g = x - 1
```

```
>>> h, cff, cfg = modgcd_univariate(f, g)
>>> h, cff, cfg
(x - 1, x**4 + x**3 + x**2 + x + 1, 1)
```

```
>>> cff * h == f
True
>>> cfg * h == g
True
```

```
>>> f = 6*x**2 - 6
>>> g = 2*x**2 + 4*x + 2
```

```
>>> h, cff, cfg = modgcd_univariate(f, g)
>>> h, cff, cfg
(2*x + 2, 3*x - 3, x + 1)
```

```
>>> cff * h == f
True
>>> cfg * h == g
True
```

## References

1. [Monagan00]

[Monagan00]

`sympy.polys.modulargcd.modgcd_bivariate(f, g)`

Computes the GCD of two polynomials in  $\mathbb{Z}[x, y]$  using a modular algorithm.

The algorithm computes the GCD of two bivariate integer polynomials  $f$  and  $g$  by calculating the GCD in  $\mathbb{Z}_p[x, y]$  for suitable primes  $p$  and then reconstructing the coefficients with the Chinese Remainder Theorem. To compute the bivariate GCD over  $\mathbb{Z}_p$ , the polynomials  $f \bmod p$  and  $g \bmod p$  are evaluated at  $y = a$  for certain  $a \in \mathbb{Z}_p$  and then their univariate GCD in  $\mathbb{Z}_p[x]$  is computed. Interpolating those yields the bivariate GCD in

$\mathbb{Z}_p[x, y]$ . To verify the result in  $\mathbb{Z}[x, y]$ , trial division is done, but only for candidates which are very likely the desired GCD.

### Parameters

**f** : PolyElement  
bivariate integer polynomial

**g** : PolyElement  
bivariate integer polynomial

### Returns

**h** : PolyElement  
GCD of the polynomials  $f$  and  $g$

**cff** : PolyElement  
cofactor of  $f$ , i.e.  $\frac{f}{h}$

**cfg** : PolyElement  
cofactor of  $g$ , i.e.  $\frac{g}{h}$

### Examples

```
>>> from sympy.polys.modulargcd import modgcd_bivariate
>>> from sympy.polys import ring, ZZ
```

```
>>> R, x, y = ring("x, y", ZZ)
```

```
>>> f = x**2 - y**2
>>> g = x**2 + 2*x*y + y**2
```

```
>>> h, cff, cfg = modgcd_bivariate(f, g)
>>> h, cff, cfg
(x + y, x - y, x + y)
```

```
>>> cff * h == f
True
>>> cfg * h == g
True
```

```
>>> f = x**2*y - x**2 - 4*y + 4
>>> g = x + 2
```

```
>>> h, cff, cfg = modgcd_bivariate(f, g)
>>> h, cff, cfg
(x + 2, x*y - x - 2*y + 2, 1)
```

```
>>> cff * h == f
True
>>> cfg * h == g
True
```

## References

1. [Monagan00]

[Monagan00]

`sympy.polys.modulargcd.modgcd_multivariate(f, g)`

Compute the GCD of two polynomials in  $\mathbb{Z}[x_0, \dots, x_{k-1}]$  using a modular algorithm.

The algorithm computes the GCD of two multivariate integer polynomials  $f$  and  $g$  by calculating the GCD in  $\mathbb{Z}_p[x_0, \dots, x_{k-1}]$  for suitable primes  $p$  and then reconstructing the coefficients with the Chinese Remainder Theorem. To compute the multivariate GCD over  $\mathbb{Z}_p$  the recursive subroutine `_modgcd_multivariate_p()` (page 2648) is used. To verify the result in  $\mathbb{Z}[x_0, \dots, x_{k-1}]$ , trial division is done, but only for candidates which are very likely the desired GCD.

### Parameters

**f** : PolyElement  
multivariate integer polynomial

**g** : PolyElement  
multivariate integer polynomial

### Returns

**h** : PolyElement  
GCD of the polynomials  $f$  and  $g$

**cff** : PolyElement  
cofactor of  $f$ , i.e.  $\frac{f}{h}$

**cfg** : PolyElement  
cofactor of  $g$ , i.e.  $\frac{g}{h}$

## Examples

```
>>> from sympy.polys.modulargcd import modgcd_multivariate
>>> from sympy.polys import ring, ZZ
```

```
>>> R, x, y = ring("x, y", ZZ)
```

```
>>> f = x**2 - y**2
>>> g = x**2 + 2*x*y + y**2
```

```
>>> h, cff, cfg = modgcd_multivariate(f, g)
>>> h, cff, cfg
(x + y, x - y, x + y)
```

```
>>> cff * h == f
True
>>> cfg * h == g
True
```

```
>>> R, x, y, z = ring("x, y, z", ZZ)
```

```
>>> f = x*z**2 - y*z**2
>>> g = x**2*z + z
```

```
>>> h, cff, cfg = modgcd_multivariate(f, g)
>>> h, cff, cfg
(z, x*z - y*z, x**2 + 1)
```

```
>>> cff * h == f
True
>>> cfg * h == g
True
```

**See also:**

[`\_modgcd\_multivariate\_p`](#) (page 2648)

## References

1. [Monagan00]
2. [Brown71]

[Monagan00], [Brown71]

`sympy.polys.modulargcd._modgcd_multivariate_p(f, g, p, degbound, contbound)`

Compute the GCD of two polynomials in  $\mathbb{Z}_p[x_0, \dots, x_{k-1}]$ .

The algorithm reduces the problem step by step by evaluating the polynomials  $f$  and  $g$  at  $x_{k-1} = a$  for suitable  $a \in \mathbb{Z}_p$  and then calls itself recursively to compute the GCD in  $\mathbb{Z}_p[x_0, \dots, x_{k-2}]$ . If these recursive calls are successful for enough evaluation points, the GCD in  $k$  variables is interpolated, otherwise the algorithm returns `None`. Every time a GCD or a content is computed, their degrees are compared with the bounds. If a degree greater than the bound is encountered, then the current call returns `None` and a new evaluation point has to be chosen. If at some point the degree is smaller, the correspondent bound is updated and the algorithm fails.

### Parameters

**f** : PolyElement

multivariate integer polynomial with coefficients in  $\mathbb{Z}_p$

**g** : PolyElement

multivariate integer polynomial with coefficients in  $\mathbb{Z}_p$

**p** : Integer

prime number, modulus of  $f$  and  $g$

**degbound** : list of Integer objects

`degbound[i]` is an upper bound for the degree of the GCD of  $f$  and  $g$  in the variable  $x_i$

**contbound** : list of Integer objects

`contbound[i]` is an upper bound for the degree of the content of the GCD in  $\mathbb{Z}_p[x_i][x_0, \dots, x_{i-1}]$ , `contbound[0]` is not used can therefore be chosen arbitrarily.

### Returns

**h** : PolyElement

GCD of the polynomials  $f$  and  $g$  or None

### References

1. [Monagan00]
2. [Brown71]

[Monagan00], [Brown71]

`sympy.polys.modulargcd.func_field_modgcd(f, g)`

Compute the GCD of two polynomials  $f$  and  $g$  in  $\mathbb{Q}(\alpha)[x_0, \dots, x_{n-1}]$  using a modular algorithm.

The algorithm first computes the primitive associate  $\tilde{m}_\alpha(z)$  of the minimal polynomial  $m_\alpha$  in  $\mathbb{Z}[z]$  and the primitive associates of  $f$  and  $g$  in  $\mathbb{Z}[x_1, \dots, x_{n-1}][z]/(\tilde{m}_\alpha)[x_0]$ . Then it computes the GCD in  $\mathbb{Q}(x_1, \dots, x_{n-1})[z]/(m_\alpha(z))[x_0]$ . This is done by calculating the GCD in  $\mathbb{Z}_p(x_1, \dots, x_{n-1})[z]/(\tilde{m}_\alpha(z))[x_0]$  for suitable primes  $p$  and then reconstructing the coefficients with the Chinese Remainder Theorem and Rational Reconstruction. The GCD over  $\mathbb{Z}_p(x_1, \dots, x_{n-1})[z]/(\tilde{m}_\alpha(z))[x_0]$  is computed with a recursive subroutine, which evaluates the polynomials at  $x_{n-1} = a$  for suitable evaluation points  $a \in \mathbb{Z}_p$  and then calls itself recursively until the ground domain does no longer contain any parameters. For  $\mathbb{Z}_p[z]/(\tilde{m}_\alpha(z))[x_0]$  the Euclidean Algorithm is used. The results of those recursive calls are then interpolated and Rational Function Reconstruction is used to obtain the correct coefficients. The results, both in  $\mathbb{Q}(x_1, \dots, x_{n-1})[z]/(m_\alpha(z))[x_0]$  and  $\mathbb{Z}_p(x_1, \dots, x_{n-1})[z]/(\tilde{m}_\alpha(z))[x_0]$ , are verified by a fraction free trial division.

Apart from the above GCD computation some GCDs in  $\mathbb{Q}(\alpha)[x_1, \dots, x_{n-1}]$  have to be calculated, because treating the polynomials as univariate ones can result in a spurious content of the GCD. For this `func_field_modgcd` is called recursively.

### Parameters

**f, g** : PolyElement

polynomials in  $\mathbb{Q}(\alpha)[x_0, \dots, x_{n-1}]$

### Returns

**h** : PolyElement

monic GCD of the polynomials  $f$  and  $g$

**cff** : PolyElement

cofactor of  $f$ , i.e.  $\frac{f}{h}$

**cfg** : PolyElement

cofactor of  $g$ , i.e.  $\frac{g}{h}$

## Examples

```
>>> from sympy.polys.modulargcd import func_field_modgcd
>>> from sympy.polys import AlgebraicField, QQ, ring
>>> from sympy import sqrt
```

```
>>> A = AlgebraicField(QQ, sqrt(2))
>>> R, x = ring('x', A)
```

```
>>> f = x**2 - 2
>>> g = x + sqrt(2)
```

```
>>> h, cff, cfg = func_field_modgcd(f, g)
```

```
>>> h == x + sqrt(2)
True
>>> cff * h == f
True
>>> cfg * h == g
True
```

```
>>> R, x, y = ring('x, y', A)
```

```
>>> f = x**2 + 2*sqrt(2)*x*y + 2*y**2
>>> g = x + sqrt(2)*y
```

```
>>> h, cff, cfg = func_field_modgcd(f, g)
```

```
>>> h == x + sqrt(2)*y
True
>>> cff * h == f
True
>>> cfg * h == g
True
```

```
>>> f = x + sqrt(2)*y
>>> g = x + y
```

```
>>> h, cff, cfg = func_field_modgcd(f, g)
```

```
>>> h == R.one
True
>>> cff * h == f
True
>>> cfg * h == g
True
```

## References

1. [Hoeij04]

[Hoeij04]

## Undocumented

Many parts of the polys module are still undocumented, and even where there is documentation it is scarce. Please contribute!

## Series Manipulation using Polynomials

Any finite Taylor series, for all practical purposes is, in fact a polynomial. This module makes use of the efficient representation and operations of sparse polynomials for very fast multi-variate series manipulations. Typical speedups compared to SymPy's `series` method are in the range 20-100, with the gap widening as the series being handled gets larger.

All the functions expand any given series on some ring specified by the user. Thus, the coefficients of the calculated series depend on the ring being used. For example:

```
>>> from sympy.polys import ring, QQ, RR
>>> from sympy.polys.ring_series import rs_sin
>>> R, x, y = ring('x, y', QQ)
>>> rs_sin(x*y, x, 5)
-1/6*x**3*y**3 + x*y
```

QQ stands for the Rational domain. Here all coefficients are rationals. It is recommended to use QQ with ring series as it automatically chooses the fastest Rational type.

Similarly, if a Real domain is used:

```
>>> R, x, y = ring('x, y', RR)
>>> rs_sin(x*y, x, 5)
-0.166666666666667*x**3*y**3 + x*y
```

Though the definition of a polynomial limits the use of Polynomial module to Taylor series, we extend it to allow Laurent and even Puiseux series (with fractional exponents):

```
>>> from sympy.polys.ring_series import rs_cos, rs_tan
>>> R, x, y = ring('x, y', QQ)

>>> rs_cos(x + x*y, x, 3)/x**3
-1/2*x**(-1)*y**2 - x**(-1)*y - 1/2*x**(-1) + x**(-3)

>>> rs_tan(x**QQ(2, 5)*y**QQ(1, 2), x, 2)
1/3*x**(6/5)*y**(3/2) + x**(2/5)*y**(1/2)
```

By default, PolyElement did not allow non-natural numbers as exponents. It converted a fraction to an integer and raised an error on getting negative exponents. The goal of the ring series module is fast series expansion, and not to use the polys module. The reason we use it as our backend is simply because it implements a sparse representation and most of the

basic functions that we need. However, this default behaviour of polys was limiting for ring series.

Note that there is no such constraint (in having rational exponents) in the data-structure used by polys- dict. Sparse polynomials (PolyElement) use the Python dict to store a polynomial term by term, where a tuple of exponents is the key and the coefficient of that term is the value. There is no reason why we can't have rational values in the dict so as to support rational exponents.

So the approach we took was to modify sparse polys to allow non-natural exponents. And it turned out to be quite simple. We only had to delete the conversion to int of exponents in the `__pow__` method of PolyElement. So:

```
>>> x**QQ(3, 4)
x**(3/4)
```

and not 1 as was the case earlier.

Though this change violates the definition of a polynomial, it doesn't break anything yet. Ideally, we shouldn't modify polys in any way. But to have all the series capabilities we want, no other simple way was found. If need be, we can separate the modified part of polys from core polys. It would be great if any other elegant solution is found.

All series returned by the functions of this module are instances of the PolyElement class. To use them with other SymPy types, convert them to Expr:

```
>>> from sympy.polys.ring_series import rs_exp
>>> from sympy.abc import a, b, c
>>> series = rs_exp(x, x, 5)
>>> a + series.as_expr()
a + x**4/24 + x**3/6 + x**2/2 + x + 1
```

## rs\_series

Direct use of elementary ring series functions does give more control, but is limiting at the same time. Creating an appropriate ring for the desired series expansion and knowing which ring series function to call, are things not everyone might be familiar with.

*rs\_series* is a function that takes an arbitrary Expr and returns its expansion by calling the appropriate ring series functions. The returned series is a polynomial over the simplest (almost) possible ring that does the job. It recursively builds the ring as it parses the given expression, adding generators to the ring when it needs them. Some examples:

```
>>> from sympy.polys.ring_series import rs_series
>>> from sympy.functions.elementary.trigonometric import sin
>>> rs_series(sin(a + b), a, 5)
1/24*sin(b)*a**4 - 1/2*sin(b)*a**2 + sin(b) - 1/6*cos(b)*a**3 + cos(b)*a

>>> rs_series(sin(exp(a*b) + cos(a + c)), a, 2)
-sin(c)*cos(cos(c) + 1)*a + cos(cos(c) + 1)*a*b + sin(cos(c) + 1)

>>> rs_series(sin(a + b)*cos(a + c)*tan(a**2 + b), a, 2)
cos(b)*cos(c)*tan(b)*a - sin(b)*sin(c)*tan(b)*a + sin(b)*cos(c)*tan(b)
```

It can expand complicated multivariate expressions involving multiple functions and most importantly, it does so blazingly fast:



```
>>> %timeit ((sin(a) + cos(a))**10).series(a, 0, 5)
1 loops, best of 3: 1.33 s per loop

>>> %timeit rs_series((sin(a) + cos(a))**10, a, 5)
100 loops, best of 3: 4.13 ms per loop
```

*rs\_series* is over 300 times faster. Given an expression to expand, there is some fixed overhead to parse it. Thus, for larger orders, the speed improvement becomes more prominent:

```
>>> %timeit rs_series((sin(a) + cos(a))**10, a, 100)
10 loops, best of 3: 32.8 ms per loop
```

To figure out the right ring for a given expression, *rs\_series* uses the *sring* function, which in turn uses other functions of *polys*. As explained above, non-natural exponents are not allowed. But the restriction is on exponents and not generators. So, *polys* allows all sorts of symbolic terms as generators to make sure that the exponent is a natural number:

```
>>> from sympy.polys.rings import sring
>>> R, expr = sring(1/a**3 + a**QQ(3, 7)); R
Polynomial ring in 1/a, a**(1/7) over ZZ with lex order
```

In the above example,  $1/a$  and  $a^{1/7}$  will be treated as completely different atoms. For all practical purposes, we could let  $b = 1/a$  and  $c = a^{1/7}$  and do the manipulations. Effectively, expressions involving  $1/a$  and  $a^{1/7}$  (and their powers) will never simplify:

```
>>> expr*R(1/a)
(1/a)**4 + (1/a)*(a**(1/7))**3
```

This leads to similar issues with manipulating Laurent and Puiseux series as faced earlier. Fortunately, this time we have an elegant solution and are able to isolate the *series* and *polys* behaviour from one another. We introduce a boolean flag *series* in the list of allowed Options for polynomials (see [sympy.polys.polyoptions.Options](#) (page 2642)). Thus, when we want *sring* to allow rational exponents we supply a *series=True* flag to *sring*:

```
>>> rs_series(sin(a**QQ(1, 3)), a, 3)
-1/5040*a**(7/3) + 1/120*a**(5/3) - 1/6*a + a**(1/3)
```

## Contribute

*rs\_series* is not fully implemented yet. As of now, it supports only multivariate Taylor expansions of expressions involving *sin*, *cos*, *exp* and *tan*. Adding the remaining functions is not at all difficult and they will be gradually added. If you are interested in helping, read the comments in *ring\_series.py*. Currently, it does not support Puiseux series (though the elementary functions do). This is expected to be fixed soon.

You can also add more functions to *ring\_series.py*. Only elementary functions are supported currently. The long term goal is to replace SymPy's current *series* method with *rs\_series*.

## Manipulation of power series

Functions in this module carry the prefix `rs_`, standing for “ring series”. They manipulate finite power series in the sparse representation provided by `polys.ring.ring`.

### Elementary functions

`sympy.polys.ring_series.rs_log(p, x, prec)`

The Logarithm of  $p$  modulo  $O(x^{prec})$ .

### Notes

Truncation of integral  $\int x^{p-1} \frac{dp}{dx}$  is used.

### Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_log
>>> R, x = ring('x', QQ)
>>> rs_log(1 + x, x, 8)
1/7*x**7 - 1/6*x**6 + 1/5*x**5 - 1/4*x**4 + 1/3*x**3 - 1/2*x**2 + x
>>> rs_log(x**QQ(3, 2) + 1, x, 5)
1/3*x**(9/2) - 1/2*x**3 + x**(3/2)
```

`sympy.polys.ring_series.rs_LambertW(p, x, prec)`

Calculate the series expansion of the principal branch of the Lambert W function.

### Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_LambertW
>>> R, x, y = ring('x, y', QQ)
>>> rs_LambertW(x + x*y, x, 3)
-x**2*y**2 - 2*x**2*y - x**2 + x*y + x
```

### See also:

[LambertW](#) (page 412)

`sympy.polys.ring_series.rs_exp(p, x, prec)`

Exponentiation of a series modulo  $O(x^{prec})$

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_exp
>>> R, x = ring('x', QQ)
>>> rs_exp(x**2, x, 7)
1/6*x**6 + 1/2*x**4 + x**2 + 1
```

`sympy.polys.ring_series.rs_atan(p, x, prec)`

The arctangent of a series

Return the series expansion of the atan of p, about 0.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_atan
>>> R, x, y = ring('x, y', QQ)
>>> rs_atan(x + x*y, x, 4)
-1/3*x**3*y**3 - x**3*y**2 - x**3*y - 1/3*x**3 + x*y + x
```

**See also:**

[atan](#) (page 397)

`sympy.polys.ring_series.rs_asin(p, x, prec)`

Arcsine of a series

Return the series expansion of the asin of p, about 0.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_asin
>>> R, x, y = ring('x, y', QQ)
>>> rs_asin(x, x, 8)
5/112*x**7 + 3/40*x**5 + 1/6*x**3 + x
```

**See also:**

[asin](#) (page 395)

`sympy.polys.ring_series.rs_tan(p, x, prec)`

Tangent of a series.

Return the series expansion of the tan of p, about 0.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_tan
>>> R, x, y = ring('x, y', QQ)
>>> rs_tan(x + x*y, x, 4)
1/3*x**3*y**3 + x**3*y**2 + x**3*y + 1/3*x**3 + x*y + x
```

### See also:

[\\_tan1](#) (page 2656), [tan](#) (page 391)

`sympy.polys.ring_series._tan1(p, x, prec)`

Helper function of `rs_tan()` (page 2655).

Return the series expansion of tan of a univariate series using Newton's method. It takes advantage of the fact that series expansion of atan is easier than that of tan.

Consider  $f(x) = y - \arctan(x)$  Let  $r$  be a root of  $f(x)$  found using Newton's method. Then  $f(r) = 0$  Or  $y = \arctan(x)$  where  $x = \tan(y)$  as required.

`sympy.polys.ring_series.rs_cot(p, x, prec)`

Cotangent of a series

Return the series expansion of the cot of p, about 0.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_cot
>>> R, x, y = ring('x, y', QQ)
>>> rs_cot(x, x, 6)
-2/945*x**5 - 1/45*x**3 - 1/3*x + x**(-1)
```

### See also:

[cot](#) (page 392)

`sympy.polys.ring_series.rs_sin(p, x, prec)`

Sine of a series

Return the series expansion of the sin of p, about 0.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_sin
>>> R, x, y = ring('x, y', QQ)
>>> rs_sin(x + x*y, x, 4)
-1/6*x**3*y**3 - 1/2*x**3*y**2 - 1/2*x**3*y - 1/6*x**3 + x*y + x
```

(continues on next page)

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```
>>> rs_sin(x**QQ(3, 2) + x*y**QQ(7, 5), x, 4)
-1/2*x**(7/2)*y**(14/5) - 1/6*x**3*y**(21/5) + x**(3/2) + x*y**(7/5)
```

#### See also:

[sin](#) (page 389)

`sympy.polys.ring_series.rs_cos(p, x, prec)`

Cosine of a series

Return the series expansion of the cos of p, about 0.

#### Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_cos
>>> R, x, y = ring('x, y', QQ)
>>> rs_cos(x + x*y, x, 4)
-1/2*x**2*y**2 - x**2*y - 1/2*x**2 + 1
>>> rs_cos(x + x*y, x, 4)/x**QQ(7, 5)
-1/2*x**(3/5)*y**2 - x**(3/5)*y - 1/2*x**(3/5) + x**(-7/5)
```

#### See also:

[cos](#) (page 390)

`sympy.polys.ring_series.rs_cos_sin(p, x, prec)`

Return the tuple (`rs_cos(p, x, prec)`, `rs_sin(p, x, prec)`).

Is faster than calling `rs_cos` and `rs_sin` separately

`sympy.polys.ring_series.rs_atanh(p, x, prec)`

Hyperbolic arctangent of a series

Return the series expansion of the atanh of p, about 0.

#### Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_atanh
>>> R, x, y = ring('x, y', QQ)
>>> rs_atanh(x + x*y, x, 4)
1/3*x**3*y**3 + x**3*y**2 + x**3*y + 1/3*x**3 + x*y + x
```

#### See also:

[atanh](#) (page 406)

`sympy.polys.ring_series.rs_sinh(p, x, prec)`

Hyperbolic sine of a series

Return the series expansion of the sinh of p, about 0.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_sinh
>>> R, x, y = ring('x, y', QQ)
>>> rs_sinh(x + x*y, x, 4)
1/6*x**3*y**3 + 1/2*x**3*y**2 + 1/2*x**3*y + 1/6*x**3 + x*y + x
```

### See also:

[sinh](#) (page 402)

`sympy.polys.ring_series.rs_cosh(p, x, prec)`

Hyperbolic cosine of a series

Return the series expansion of the cosh of p, about 0.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_cosh
>>> R, x, y = ring('x, y', QQ)
>>> rs_cosh(x + x*y, x, 4)
1/2*x**2*y**2 + x**2*y + 1/2*x**2 + 1
```

### See also:

[cosh](#) (page 403)

`sympy.polys.ring_series.rs_tanh(p, x, prec)`

Hyperbolic tangent of a series

Return the series expansion of the tanh of p, about 0.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_tanh
>>> R, x, y = ring('x, y', QQ)
>>> rs_tanh(x + x*y, x, 4)
-1/3*x**3*y**3 - x**3*y**2 - x**3*y - 1/3*x**3 + x*y + x
```

### See also:

[tanh](#) (page 403)

`sympy.polys.ring_series.rs_hadamard_exp(p1, inverse=False)`

Return sum  $f_i/i! * x^{**i}$  from sum  $f_i * x^{**i}$ , where x is the first variable.

If `invers=True` return sum  $f_i * i! * x^{**i}$

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_hadamard_exp
>>> R, x = ring('x', QQ)
>>> p = 1 + x + x**2 + x**3
>>> rs_hadamard_exp(p)
1/6*x**3 + 1/2*x**2 + x + 1
```

## Operations

`sympy.polys.ring_series.rs_mul(p1, p2, x, prec)`

Return the product of the given two series, modulo  $O(x^{**prec})$ .

`x` is the series variable or its position in the generators.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_mul
>>> R, x = ring('x', QQ)
>>> p1 = x**2 + 2*x + 1
>>> p2 = x + 1
>>> rs_mul(p1, p2, x, 3)
3*x**2 + 3*x + 1
```

`sympy.polys.ring_series.rs_square(p1, x, prec)`

Square the series modulo  $O(x^{**prec})$

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_square
>>> R, x = ring('x', QQ)
>>> p = x**2 + 2*x + 1
>>> rs_square(p, x, 3)
6*x**2 + 4*x + 1
```

`sympy.polys.ring_series.rs_pow(p1, n, x, prec)`

Return  $p1^{**n}$  modulo  $O(x^{**prec})$

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_pow
>>> R, x = ring('x', QQ)
>>> p = x + 1
>>> rs_pow(p, 4, x, 3)
6*x**2 + 4*x + 1
```

`sympy.polys.ring_series.rs_series_inversion(p, x, prec)`  
Multivariate series inversion  $1/p$  modulo  $O(x^{**prec})$ .

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_series_inversion
>>> R, x, y = ring('x, y', QQ)
>>> rs_series_inversion(1 + x*y**2, x, 4)
-x**3*y**6 + x**2*y**4 - x*y**2 + 1
>>> rs_series_inversion(1 + x*y**2, y, 4)
-x*y**2 + 1
>>> rs_series_inversion(x + x**2, x, 4)
x**3 - x**2 + x - 1 + x**(-1)
```

`sympy.polys.ring_series.rs_series_reversion(p, x, n, y)`  
Reversion of a series.

$p$  is a series with  $O(x^{**n})$  of the form  $p = ax + f(x)$  where  $a$  is a number different from 0.

$$f(x) = \sum_{k=2}^{n-1} a_k x_k$$

### Parameters

**a\_k** : Can depend polynomially on other variables, not indicated.

**x** : Variable with name x. **y** : Variable with name y.

### Returns

Solve  $p = y$ , that is, given  $ax + f(x) - y = 0$ ,

find the solution  $x = r(y)$  up to  $O(y^n)$ .

## Algorithm

If  $r_i$  is the solution at order  $i$ , then:  $ar_i + f(r_i) - y = O(y^{i+1})$

and if  $r_{i+1}$  is the solution at order  $i + 1$ , then:  $ar_{i+1} + f(r_{i+1}) - y = O(y^{i+2})$

We have,  $r_{i+1} = r_i + e$ , such that,  $ae + f(r_i) = O(y^{i+2})$  or  $e = -f(r_i)/a$

So we use the recursion relation:  $r_{i+1} = r_i - f(r_i)/a$  with the boundary condition:  $r_1 = y$



## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_series_reversion, rs_trunc
>>> R, x, y, a, b = ring('x, y, a, b', QQ)
>>> p = x - x**2 - 2*b*x**2 + 2*a*b*x**2
>>> p1 = rs_series_reversion(p, x, 3, y); p1
-2*y**2*a*b + 2*y**2*b + y**2 + y
>>> rs_trunc(p.compose(x, p1), y, 3)
y
```

`sympy.polys.ring_series.rs_nth_root(p, n, x, prec)`

Multivariate series expansion of the  $n$ th root of  $p$ .

### Parameters

**p** : Expr

The polynomial to computer the root of.

**n** : integer

The order of the root to be computed.

**x** : *PolyElement* (page 2554)

**prec** : integer

Order of the expanded series.

## Notes

The result of this function is dependent on the ring over which the polynomial has been defined. If the answer involves a root of a constant, make sure that the polynomial is over a real field. It cannot yet handle roots of symbols.

## Examples

```
>>> from sympy.polys.domains import QQ, RR
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_nth_root
>>> R, x, y = ring('x, y', QQ)
>>> rs_nth_root(1 + x + x*y, -3, x, 3)
2/9*x**2*y**2 + 4/9*x**2*y + 2/9*x**2 - 1/3*x*y - 1/3*x + 1
>>> R, x, y = ring('x, y', RR)
>>> rs_nth_root(3 + x + x*y, 3, x, 2)
0.160249952256379*x*y + 0.160249952256379*x + 1.44224957030741
```

`sympy.polys.ring_series.rs_trunc(p1, x, prec)`

Truncate the series in the  $x$  variable with precision  $prec$ , that is, modulo  $O(x^{**prec})$

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_trunc
>>> R, x = ring('x', QQ)
>>> p = x**10 + x**5 + x + 1
>>> rs_trunc(p, x, 12)
x**10 + x**5 + x + 1
>>> rs_trunc(p, x, 10)
x**5 + x + 1
```

`sympy.polys.ring_series.rs_subs(p, rules, x, prec)`

Substitution with truncation according to the mapping in rules.

Return a series with precision `prec` in the generator `x`

Note that substitutions are not done one after the other

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_subs
>>> R, x, y = ring('x, y', QQ)
>>> p = x**2 + y**2
>>> rs_subs(p, {x: x+ y, y: x+ 2*y}, x, 3)
2*x**2 + 6*x*y + 5*y**2
>>> (x + y)**2 + (x + 2*y)**2
2*x**2 + 6*x*y + 5*y**2
```

which differs from

```
>>> rs_subs(rs_subs(p, {x: x+ y}, x, 3), {y: x+ 2*y}, x, 3)
5*x**2 + 12*x*y + 8*y**2
```

## Parameters

**p** : *PolyElement* (page 2554) Input series.

**rules** : dict with substitution mappings.

**x** : *PolyElement* (page 2554) in which the series truncation is to be done.

**prec** : *Integer* (page 987) order of the series after truncation.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_subs
>>> R, x, y = ring('x, y', QQ)
>>> rs_subs(x**2+y**2, {y: (x+y)**2}, x, 3)
6*x**2*y**2 + x**2 + 4*x*y**3 + y**4
```

`sympy.polys.ring_series.rs_diff(p, x)`

Return partial derivative of `p` with respect to `x`.

### Parameters

**x** : *PolyElement* (page 2554) with respect to which p is differentiated.

### Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_diff
>>> R, x, y = ring('x, y', QQ)
>>> p = x + x**2*y**3
>>> rs_diff(p, x)
2*x*y**3 + 1
```

`sympy.polys.ring_series.rs_integrate(p, x)`

Integrate p with respect to x.

### Parameters

**x** : *PolyElement* (page 2554) with respect to which p is integrated.

### Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_integrate
>>> R, x, y = ring('x, y', QQ)
>>> p = x + x**2*y**3
>>> rs_integrate(p, x)
1/3*x**3*y**3 + 1/2*x**2
```

`sympy.polys.ring_series.rs_newton(p, x, prec)`

Compute the truncated Newton sum of the polynomial p

### Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_newton
>>> R, x = ring('x', QQ)
>>> p = x**2 - 2
>>> rs_newton(p, x, 5)
8*x**4 + 4*x**2 + 2
```

`sympy.polys.ring_series.rs_compose_add(p1, p2)`

compute the composed sum  $\text{prod}(p2(x - \text{beta}))$  for beta root of p1)

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_compose_add
>>> R, x = ring('x', QQ)
>>> f = x**2 - 2
>>> g = x**2 - 3
>>> rs_compose_add(f, g)
x**4 - 10*x**2 + 1
```

## References

[R730]

## Utility functions

`sympy.polys.ring_series.rs_is_puiseux(p, x)`

Test if  $p$  is Puiseux series in  $x$ .

Raise an exception if it has a negative power in  $x$ .

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_is_puiseux
>>> R, x = ring('x', QQ)
>>> p = x**QQ(2,5) + x**QQ(2,3) + x
>>> rs_is_puiseux(p, x)
True
```

`sympy.polys.ring_series.rs_puiseux(f, p, x, prec)`

Return the puiseux series for  $f(p, x, prec)$ .

To be used when function  $f$  is implemented only for regular series.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_puiseux, rs_exp
>>> R, x = ring('x', QQ)
>>> p = x**QQ(2,5) + x**QQ(2,3) + x
>>> rs_puiseux(rs_exp, p, x, 1)
1/2*x**(4/5) + x**(2/3) + x**(2/5) + 1
```

`sympy.polys.ring_series.rs_puiseux2(f, p, q, x, prec)`

Return the puiseux series for  $f(p, q, x, prec)$ .

To be used when function  $f$  is implemented only for regular series.

`sympy.polys.ring_series.rs_series_from_list(p, c, x, prec, concur=1)`

Return a series  $\sum c[n] * p^{**n}$  modulo  $O(x^{**prec})$ .

It reduces the number of multiplications by summing concurrently.

$ax = [1, p, p^{**2}, \dots, p^{*(J-1)}]$   $s = \sum(c[i] * ax[i] \text{ for } i \text{ in } \text{range}(r, (r+1) * J)) * p^{*((K-1) * J)}$   
with  $K \geq (n+1)/J$

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_series_from_list, rs_trunc
>>> R, x = ring('x', QQ)
>>> p = x**2 + x + 1
>>> c = [1, 2, 3]
>>> rs_series_from_list(p, c, x, 4)
6*x**3 + 11*x**2 + 8*x + 6
>>> rs_trunc(1 + 2*p + 3*p**2, x, 4)
6*x**3 + 11*x**2 + 8*x + 6
>>> pc = R.from_list(list(reversed(c)))
>>> rs_trunc(pc.compose(x, p), x, 4)
6*x**3 + 11*x**2 + 8*x + 6
```

`sympy.polys.ring_series.rs_fun(p, f, *args)`

Function of a multivariate series computed by substitution.

The case with `f` method name is used to compute `rs_tan` and `rs_nth_root` of a multivariate series:

`rs_fun(p, tan, iv, prec)`

`tan` series is first computed for a dummy variable `_x`, i.e., `rs_tan(_x, iv, prec)`. Then we substitute `_x` with `p` to get the desired series

## Parameters

**p** : *PolyElement* (page 2554) The multivariate series to be expanded.

**f** : *ring\_series* function to be applied on `p`.

**args[-2]** : *PolyElement* (page 2554) with respect to which, the series is to be expanded.

**args[-1]** : Required order of the expanded series.

## Examples

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import rs_fun, _tan1
>>> R, x, y = ring('x, y', QQ)
>>> p = x + x*y + x**2*y + x**3*y**2
>>> rs_fun(p, _tan1, x, 4)
1/3*x**3*y**3 + 2*x**3*y**2 + x**3*y + 1/3*x**3 + x**2*y + x*y + x
```

`sympy.polys.ring_series.mul_xin(p, i, n)`

Return  $p * x_i * n$ .

$x_i$  is the  $i$ th variable in  $p$ .

`sympy.polys.ring_series.pow_xin(p, i, n)`

```
>>> from sympy.polys.domains import QQ
>>> from sympy.polys.rings import ring
>>> from sympy.polys.ring_series import pow_xin
>>> R, x, y = ring('x, y', QQ)
>>> p = x**QQ(2,5) + x + x**QQ(2,3)
>>> index = p.ring.gens.index(x)
>>> pow_xin(p, index, 15)
x**15 + x**10 + x**6
```

## Literature

The following is a non-comprehensive list of publications that were used as a theoretical foundation for implementing polynomials manipulation module.

## Poly solvers

This module provides functions for solving systems of linear equations that are used internally in sympy. Low-level linear systems solver.

### solve\_lin\_sys

`sympy.polys.solvers.solve_lin_sys(eqs, ring, _raw=True)`

Solve a system of linear equations from a PolynomialRing

#### Parameters

**eqs:** list[PolyElement]

The linear equations to be solved as elements of a PolynomialRing (assumed equal to zero).

**ring:** PolynomialRing

The polynomial ring from which eqs are drawn. The generators of this ring are the unknowns to be solved for and the domain of the ring is the domain of the coefficients of the system of equations.

**\_raw:** bool

If `_raw` is False, the keys and values in the returned dictionary will be of type Expr (and the unit of the field will be removed from the keys) otherwise the low-level polys types will be returned, e.g. PolyElement: PythonRational.

#### Returns

None if the system has no solution.

dict[Symbol, Expr] if `_raw=False`

dict[Symbol, DomainElement] if `_raw=True`.

## Explanation

Solves a system of linear equations given as PolyElement instances of a PolynomialRing. The basic arithmetic is carried out using instance of DomainElement which is more efficient than [Expr](#) (page 947) for the most common inputs.

While this is a public function it is intended primarily for internal use so its interface is not necessarily convenient. Users are suggested to use the [sympy.solvers.solve](#), [sympy.solvers.linsolve\(\)](#) (page 872) function (which uses this function internally) instead.

## Examples

```
>>> from sympy import symbols
>>> from sympy.polys.solvers import solve_lin_sys, sympy_eqs_to_ring
>>> x, y = symbols('x, y')
>>> eqs = [x - y, x + y - 2]
>>> eqs_ring, ring = sympy_eqs_to_ring(eqs, [x, y])
>>> solve_lin_sys(eqs_ring, ring)
{y: 1, x: 1}
```

Passing `_raw=False` returns the same result except that the keys are Expr rather than low-level poly types.

```
>>> solve_lin_sys(eqs_ring, ring, _raw=False)
{x: 1, y: 1}
```

See also:

[sympy\\_eqs\\_to\\_ring](#) (page 2668)

prepares the inputs to solve\_lin\_sys.

[linsolve](#) (page 872)

linsolve uses solve\_lin\_sys internally.

[sympy.solvers.solvers.solve](#) (page 836)

solve uses solve\_lin\_sys internally.

## eqs\_to\_matrix

`sympy.polys.solvers.eqs_to_matrix(eqs_coeffs, eqs_rhs, gens, domain)`

Get matrix from linear equations in dict format.

### Parameters

**eqs\_coeffs:** list[dict[Symbol, DomainElement]]

The left hand sides of the equations as dicts mapping from symbols to coefficients where the coefficients are instances of DomainElement.

**eqs\_rhs:** list[DomainElements]

The right hand sides of the equations as instances of DomainElement.

**gens:** list[Symbol]

The unknowns in the system of equations.

**domain:** Domain

The domain for coefficients of both lhs and rhs.

### Returns

The augmented matrix representation of the system as a DomainMatrix.

## Explanation

Get the matrix representation of a system of linear equations represented as dicts with low-level DomainElement coefficients. This is an *internal* function that is used by `solve_lin_sys`.

## Examples

```
>>> from sympy import symbols, ZZ
>>> from sympy.polys.solvers import eqs_to_matrix
>>> x, y = symbols('x, y')
>>> eqs_coeff = [{x:ZZ(1), y:ZZ(1)}, {x:ZZ(1), y:ZZ(-1)}]
>>> eqs_rhs = [ZZ(0), ZZ(-1)]
>>> eqs_to_matrix(eqs_coeff, eqs_rhs, [x, y], ZZ)
DomainMatrix([[1, 1, 0], [1, -1, 1]], (2, 3), ZZ)
```

**See also:**

[`solve\_lin\_sys`](#) (page 2666)

Uses `eqs_to_matrix()` (page 2667) internally

## `sympy_eqs_to_ring`

`sympy.polys.solvers.sympy_eqs_to_ring(eqs, symbols)`

Convert a system of equations from Expr to a PolyRing

### Parameters

**eqs:** List of Expr

A list of equations as Expr instances

**symbols:** List of Symbol

A list of the symbols that are the unknowns in the system of equations.

### Returns

Tuple[List[PolyElement], Ring]: The equations as PolyElement instances and the ring of polynomials within which each equation is represented.



## Explanation

High-level functions like `solve` expect `Expr` as inputs but can use `solve_lin_sys` internally. This function converts equations from `Expr` to the low-level poly types used by the `solve_lin_sys` function.

## Examples

```
>>> from sympy import symbols
>>> from sympy.polys.solvers import sympy_eqs_to_ring
>>> a, x, y = symbols('a, x, y')
>>> eqs = [x-y, x+a*y]
>>> eqs_ring, ring = sympy_eqs_to_ring(eqs, [x, y])
>>> eqs_ring
[x - y, x + a*y]
>>> type(eqs_ring[0])
<class 'sympy.polys.rings.PolyElement'>
>>> ring
ZZ(a)[x,y]
```

With the equations in this form they can be passed to `solve_lin_sys`:

```
>>> from sympy.polys.solvers import solve_lin_sys
>>> solve_lin_sys(eqs_ring, ring)
{y: 0, x: 0}
```

## `_solve_lin_sys`

`sympy.polys.solvers._solve_lin_sys(eqs_coeffs, eqs_rhs, ring)`

Solve a linear system from dict of PolynomialRing coefficients

## Explanation

This is an **internal** function used by `solve_lin_sys()` (page 2666) after the equations have been preprocessed. The role of this function is to split the system into connected components and pass those to `_solve_lin_sys_component()` (page 2670).

## Examples

Setup a system for  $x - y = 0$  and  $x + y = 2$  and solve:

```
>>> from sympy import symbols, sring
>>> from sympy.polys.solvers import _solve_lin_sys
>>> x, y = symbols('x, y')
>>> R, (xr, yr) = sring([x, y], [x, y])
>>> eqs = [{xr:R.one, yr:-R.one}, {xr:R.one, yr:R.one}]
>>> eqs_rhs = [R.zero, -2*R.one]
>>> _solve_lin_sys(eqs, eqs_rhs, R)
{y: 1, x: 1}
```

See also:

[solve\\_lin\\_sys](#) (page 2666)

This function is used internally by [solve\\_lin\\_sys\(\)](#) (page 2666).

## `_solve_lin_sys_component`

`sympy.polys.solvers._solve_lin_sys_component(eqs_coeffs, eqs_rhs, ring)`

Solve a linear system from dict of PolynomialRing coefficients

## Explanation

This is an **internal** function used by [solve\\_lin\\_sys\(\)](#) (page 2666) after the equations have been preprocessed. After [\\_solve\\_lin\\_sys\(\)](#) (page 2669) splits the system into connected components this function is called for each component. The system of equations is solved using Gauss-Jordan elimination with division followed by back-substitution.

## Examples

Setup a system for  $x - y = 0$  and  $x + y = 2$  and solve:

```
>>> from sympy import symbols, sring
>>> from sympy.polys.solvers import _solve_lin_sys_component
>>> x, y = symbols('x, y')
>>> R, (xr, yr) = sring([x, y], [x, y])
>>> eqs = [{xr:R.one, yr:-R.one}, {xr:R.one, yr:R.one}]
>>> eqs_rhs = [R.zero, -2*R.one]
>>> _solve_lin_sys_component(eqs, eqs_rhs, R)
{y: 1, x: 1}
```

See also:

[solve\\_lin\\_sys](#) (page 2666)

This function is used internally by [solve\\_lin\\_sys\(\)](#) (page 2666).

## Introducing the domainmatrix of the poly module

This page introduces the idea behind domainmatrix which is used in SymPy's [sympy.polys](#) (page 2360) module. This is a relatively advanced topic so for a better understanding it is recommended to read about [Domain](#) (page 2504) and [DDM](#) (page 2690) along with [sympy.matrices](#) (page 1217) module.

## What is domainmatrix?

It is way of associating Matrix with *Domain* (page 2504).

A domainmatrix represents a matrix with elements that are in a particular Domain. Each domainmatrix internally wraps a DDM which is used for the lower-level operations. The idea is that the domainmatrix class provides the convenience routines for converting between Expr and the poly domains as well as unifying matrices with different domains.

**In general, we represent a matrix without concerning about the *Domain* (page 2504) as:**

```
>>> from sympy import Matrix
>>> from sympy.polys.matrices import DomainMatrix
>>> A = Matrix([
... [1, 2],
... [3, 4]])
>>> A
Matrix([
[1, 2],
[3, 4]])
```

## DomainMatrix Class Reference

**class** sympy.polys.matrices.domainmatrix.**DomainMatrix**(rows, shape, domain, \*,  
fmt=None)

Associate Matrix with *Domain* (page 2504)

### Explanation

DomainMatrix uses *Domain* (page 2504) for its internal representation which makes it more faster for many common operations than current SymPy Matrix class, but this advantage makes it not entirely compatible with Matrix. DomainMatrix could be found analogous to numpy arrays with “dtype”. In the DomainMatrix, each matrix has a domain such as *ZZ* (page 2525) or *QQ<a>* (page 2539).

### Examples

Creating a DomainMatrix from the existing Matrix class:

```
>>> from sympy import Matrix
>>> from sympy.polys.matrices import DomainMatrix
>>> Matrix1 = Matrix([
... [1, 2],
... [3, 4]])
>>> A = DomainMatrix.from_Matrix(Matrix1)
>>> A
DomainMatrix({0: {0: 1, 1: 2}, 1: {0: 3, 1: 4}}, (2, 2), ZZ)
```

Directly forming a DomainMatrix:

```
>>> from sympy import ZZ
>>> from sympy.polys.matrices import DomainMatrix
>>> A = DomainMatrix([
...     [ZZ(1), ZZ(2)],
...     [ZZ(3), ZZ(4)]], (2, 2), ZZ)
>>> A
DomainMatrix([[1, 2], [3, 4]], (2, 2), ZZ)
```

**See also:**

[DDM](#) (page 2690), [SDM](#) (page 2692), [Domain](#) (page 2504), [Poly](#) (page 2378)

**add(B)**

Adds two DomainMatrix matrices of the same Domain

**Parameters**

**A, B: DomainMatrix**

matrices to add

**Returns**

DomainMatrix

DomainMatrix after Addition

**Raises**

**DMShapeError**

If the dimensions of the two DomainMatrix are not equal

**ValueError**

If the domain of the two DomainMatrix are not same

**Examples**

```
>>> from sympy import ZZ
>>> from sympy.polys.matrices import DomainMatrix
>>> A = DomainMatrix([
...     [ZZ(1), ZZ(2)],
...     [ZZ(3), ZZ(4)]], (2, 2), ZZ)
>>> B = DomainMatrix([
...     [ZZ(4), ZZ(3)],
...     [ZZ(2), ZZ(1)]], (2, 2), ZZ)
```

```
>>> A.add(B)
DomainMatrix([[5, 5], [5, 5]], (2, 2), ZZ)
```

**See also:**

[sub](#) (page 2686), [matmul](#) (page 2680)

**charpoly()**

Returns the coefficients of the characteristic polynomial of the DomainMatrix. These elements will be domain elements. The domain of the elements will be same as domain of the DomainMatrix.

### Returns

list

coefficients of the characteristic polynomial

### Raises

#### DMNonSquareMatrixError

If the DomainMatrix is not a not Square DomainMatrix

### Examples

```
>>> from sympy import ZZ
>>> from sympy.polys.matrices import DomainMatrix
>>> A = DomainMatrix([
...     [ZZ(1), ZZ(2)],
...     [ZZ(3), ZZ(4)]], (2, 2), ZZ)
```

```
>>> A.charpoly()
[1, -5, -2]
```

### columnspace()

Returns the columnspace for the DomainMatrix

### Returns

DomainMatrix

The columns of this matrix form a basis for the columnspace.

### Examples

```
>>> from sympy import QQ
>>> from sympy.polys.matrices import DomainMatrix
>>> A = DomainMatrix([
...     [QQ(1), QQ(-1)],
...     [QQ(2), QQ(-2)]], (2, 2), QQ)
>>> A.columnspace()
DomainMatrix([[1], [2]], (2, 1), QQ)
```

### convert\_to(K)

Change the domain of DomainMatrix to desired domain or field

### Parameters

**K** : Represents the desired domain or field.

Alternatively, None may be passed, in which case this method just returns a copy of this DomainMatrix.

### Returns

DomainMatrix

DomainMatrix with the desired domain or field

## Examples

```
>>> from sympy import ZZ, ZZ_I
>>> from sympy.polys.matrices import DomainMatrix
>>> A = DomainMatrix([
...     [ZZ(1), ZZ(2)],
...     [ZZ(3), ZZ(4)]], (2, 2), ZZ)
```

```
>>> A.convert_to(ZZ_I)
DomainMatrix([[1, 2], [3, 4]], (2, 2), ZZ_I)
```

### **det()**

Returns the determinant of a Square DomainMatrix

#### **Returns**

S.Complexes

determinant of Square DomainMatrix

#### **Raises**

##### **ValueError**

If the domain of DomainMatrix not a Field

## Examples

```
>>> from sympy import ZZ
>>> from sympy.polys.matrices import DomainMatrix
>>> A = DomainMatrix([
...     [ZZ(1), ZZ(2)],
...     [ZZ(3), ZZ(4)]], (2, 2), ZZ)
```

```
>>> A.det()
-2
```

### **classmethod diag(*diagonal*, *domain*, *shape=None*)**

Return diagonal matrix with entries from *diagonal*.

## Examples

```
>>> from sympy.polys.matrices import DomainMatrix
>>> from sympy import ZZ
>>> DomainMatrix.diag([ZZ(5), ZZ(6)], ZZ)
DomainMatrix({0: {0: 5}, 1: {1: 6}}, (2, 2), ZZ)
```

### **classmethod eye(*shape*, *domain*)**

Return identity matrix of size *n*

## Examples

```
>>> from sympy.polys.matrices import DomainMatrix
>>> from sympy import QQ
>>> DomainMatrix.eye(3, QQ)
DomainMatrix({0: {0: 1}, 1: {1: 1}, 2: {2: 1}}, (3, 3), QQ)
```

**classmethod** `from_Matrix(M, fmt='sparse', **kwargs)`

Convert Matrix to DomainMatrix

### Parameters

**M:** Matrix

### Returns

Returns DomainMatrix with identical elements as M

## Examples

```
>>> from sympy import Matrix
>>> from sympy.polys.matrices import DomainMatrix
>>> M = Matrix([
...     [1.0, 3.4],
...     [2.4, 1]])
>>> A = DomainMatrix.from_Matrix(M)
>>> A
DomainMatrix({0: {0: 1.0, 1: 3.4}, 1: {0: 2.4, 1: 1.0}}, (2, 2), RR)
```

We can keep internal representation as ddm using `fmt='dense'`

```
>>> from sympy import Matrix, QQ
>>> from sympy.polys.matrices import DomainMatrix
>>> A = DomainMatrix.from_Matrix(Matrix([[QQ(1, 2), QQ(3, 4)], [QQ(0, 1), QQ(0, 1)]]),
fmt='dense')
>>> A.rep
[[1/2, 3/4], [0, 0]]
```

### See also:

[Matrix](#) (page 1361)

**classmethod** `from_dict_sympy(nrows, ncols, elemsdict, **kwargs)`

### Parameters

**nrows:** number of rows

**ncols:** number of cols

**elemsdict:** dict of dicts containing non-zero elements of the DomainMatrix

### Returns

DomainMatrix containing elements of elemsdict

## Examples

```
>>> from sympy.polys.matrices import DomainMatrix
>>> from sympy.abc import x,y,z
>>> elemsdict = {0: {0:x}, 1:{1: y}, 2: {2: z}}
>>> A = DomainMatrix.from_dict_sympy(3, 3, elemsdict)
>>> A
DomainMatrix({0: {0: x}, 1: {1: y}, 2: {2: z}}, (3, 3), ZZ[x,y,z])
```

### See also:

[from\\_list\\_sympy](#) (page 2676)

**classmethod** `from_list(rows, domain)`

Convert a list of lists into a DomainMatrix

#### Parameters

**rows:** list of lists

Each element of the inner lists should be either the single arg, or tuple of args, that would be passed to the domain constructor in order to form an element of the domain. See examples.

#### Returns

DomainMatrix containing elements defined in rows

## Examples

```
>>> from sympy.polys.matrices import DomainMatrix
>>> from sympy import FF, QQ, ZZ
>>> A = DomainMatrix.from_list([[1, 0, 1], [0, 0, 1]], ZZ)
>>> A
DomainMatrix([[1, 0, 1], [0, 0, 1]], (2, 3), ZZ)
>>> B = DomainMatrix.from_list([[1, 0, 1], [0, 0, 1]], FF(7))
>>> B
DomainMatrix([[1 mod 7, 0 mod 7, 1 mod 7], [0 mod 7, 0 mod 7, 1 mod 7]], (2, 3), GF(7))
>>> C = DomainMatrix.from_list([(1, 2), (3, 1)], [(1, 4), (5, 1)]), QQ
>>> C
DomainMatrix([[1/2, 3], [1/4, 5]], (2, 2), QQ)
```

### See also:

[from\\_list\\_sympy](#) (page 2676)

**classmethod** `from_list_sympy(nrows, ncols, rows, **kwargs)`

Convert a list of lists of Expr into a DomainMatrix using `construct_domain`

#### Parameters

**nrows:** number of rows

**ncols:** number of columns

**rows:** list of lists