



# Part I

Presentation by: Quincy Jacobs

# The Tools

Getting all the tools necessary to get started with WebGL is surprisingly easy.

1. Check your browser's compatibility: [webglreport.com](http://webglreport.com)
2. Open your favorite text editor or IDE for JavaScript.

Now you're good to go.

# The HTML

```
<!doctype html>
<html lang="en">
  <head>
    <meta charset="utf-8">
    <title>WebGL Example 1</title>
  </head>

  <body>
    <canvas id="glcanvas" width="640" height="480"></canvas>
  </body>

  <script src="index.js"></script>
</html>
```

Our actual WebGL code goes into index.js

# The CSS

# The First Step

Drawing a black background using WebGL

```
main();

function main(){
    const canvas = document.querySelector('#glcanvas');
    const gl = canvas.getContext('webgl2');

    // make sure we have a gl context
    if (!gl) {
        alert('Unable to initialize WebGL. Your browser or machine may not support it.');
        return;
    }

    // set clear color to black, fully opaque
    gl.clearColor(0.0, 0.0, 0.0, 1.0);

    // clear the color buffer with specified clear color
    gl.clear(gl.COLOR_BUFFER_BIT);
}
```

# The First Step

You can download/clone the code from my Github:

<https://github.com/QuincyJacobs/WebGLTutorial>

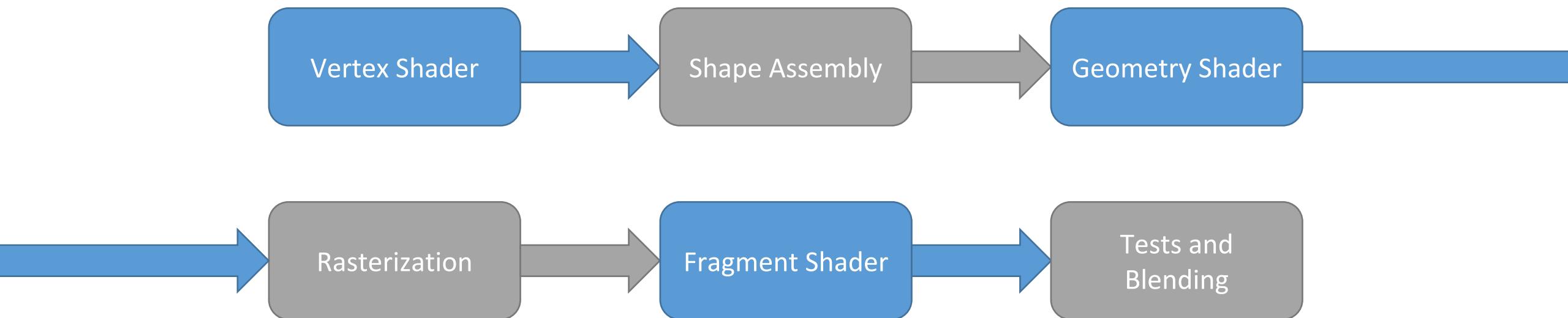
# Graphics pipeline



= Adjustable steps (Shaders)



= Automatic steps



# Steps for drawing a triangle

We will need all of the following WebGL objects to draw a triangle:

1. Vertex array buffer
2. Element array buffer
3. Vertex shader
4. Fragment shader
5. Shader program

# Steps for drawing a triangle

These necessary elements are created and used in the following steps:

1. ArrayBuffer Objects
1. Shaders and Shader Program
1. Linking Buffers and Shaders
1. Drawing

# Step 1: Array Buffer Objects

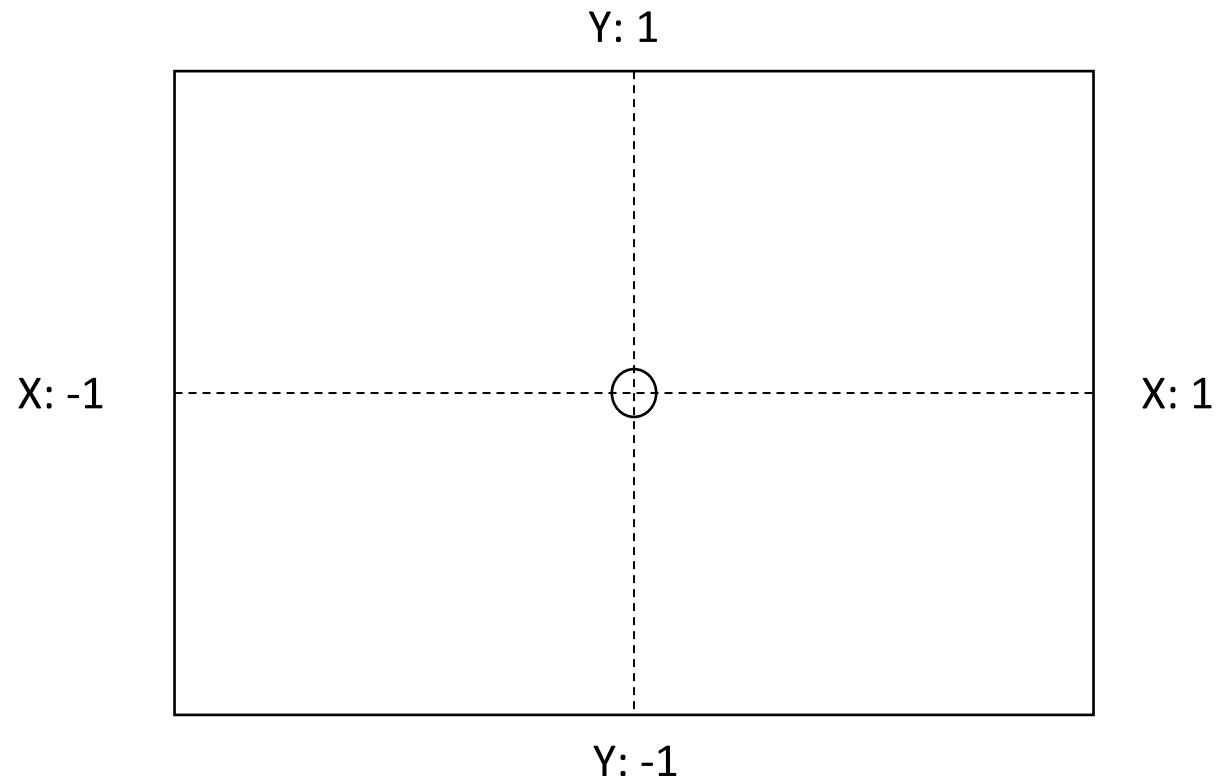
# Array Buffer Objects

A Vertex Buffer contains information about each vertice, which shaders will use for calculations and translations.

Our vertex buffer will only contain 3d positions for each vertex:

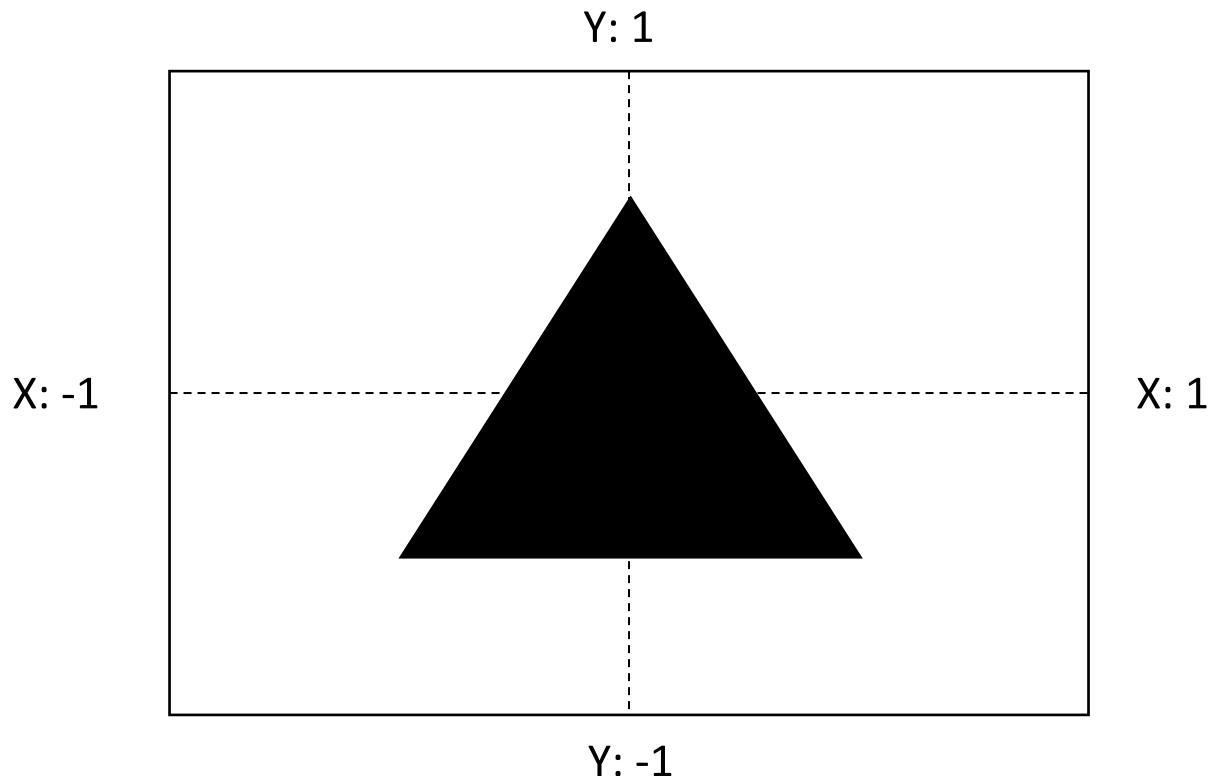
# Array Buffer Objects

How does WebGL interpret the view?



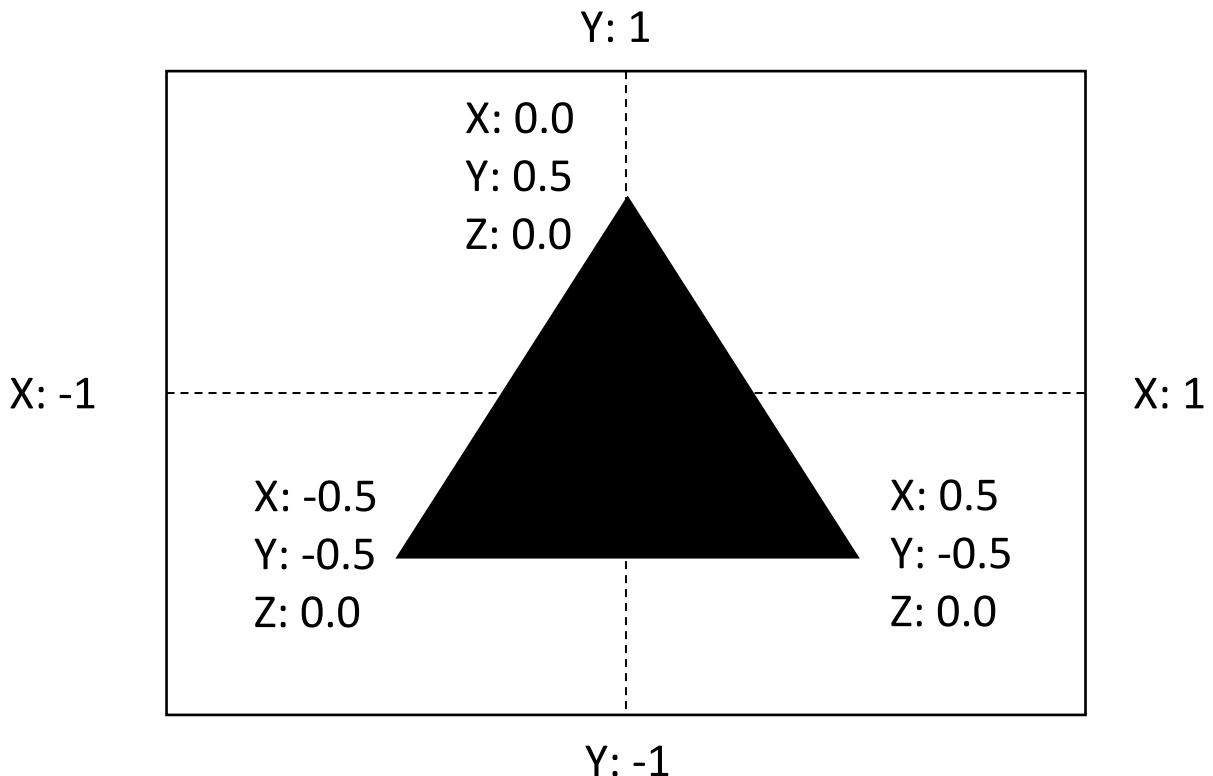
# Array Buffer Objects

What will our triangle look like?



# Array Buffer Objects

What data do we need?



# Array Buffer Objects

The result:

```
var positions = [-0.5, -0.5, 0.0, 0.5, -0.5, 0.0, 0.0, 0.5, 0.0];
```

Let's format this mess...

# Array Buffer Objects

The result:

```
var positions = [
    // x      y      z
    -0.5, -0.5,  0.0,   // lower left corner
    0.5,  -0.5,  0.0,   // lower right corner
    0.0,  0.5,  0.0    // upper corner
];
```

Better!

# Array Buffer Objects

Now let's prepare our buffer so WebGL can eventually send it to the shaders.

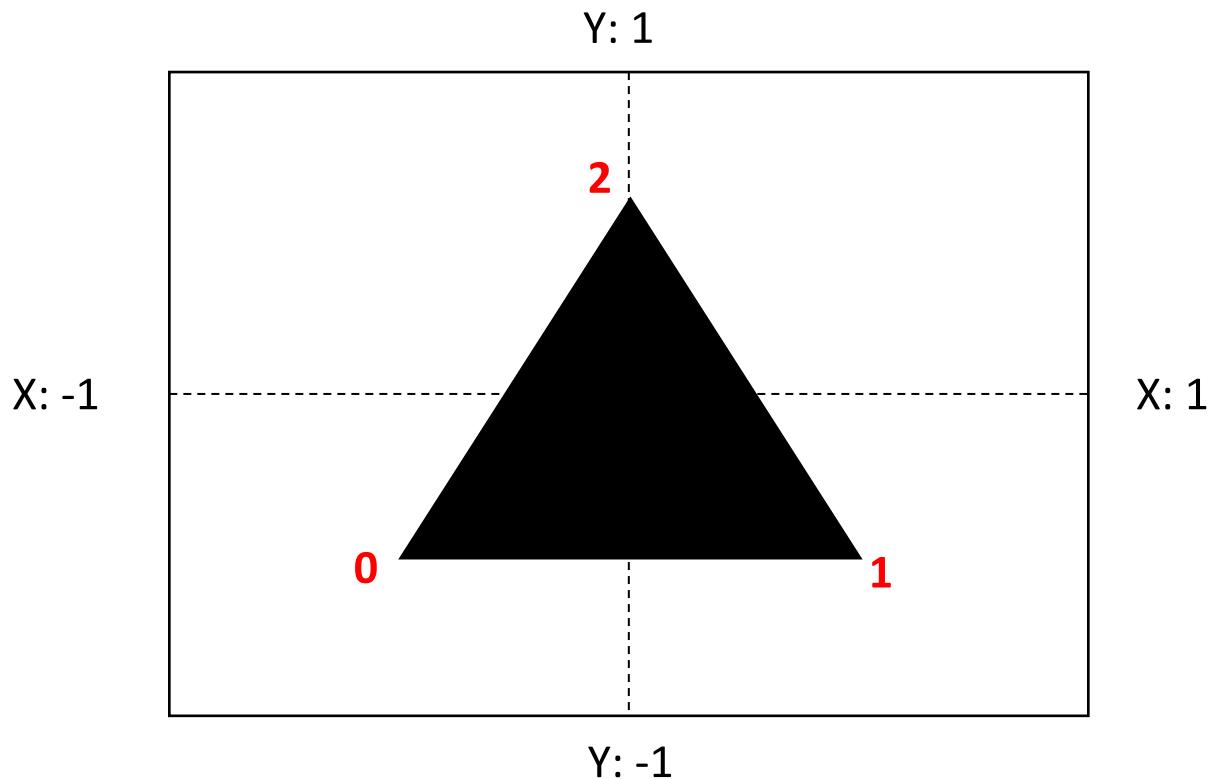
```
// create a buffer, bind it to webgl as our active buffer and put our vertices in the buffer
var vertex_buffer = gl.createBuffer();
gl.bindBuffer(gl.ARRAY_BUFFER, vertex_buffer);
gl.bufferData(gl.ARRAY_BUFFER, new Float32Array(positions), gl.STATIC_DRAW);

// unbind the buffer to prevent unwanted changes later
gl.bindBuffer(gl.ARRAY_BUFFER, null);
```

# Array Buffer Objects

Next we will need a buffer that holds the indices that form a triangle.

```
var positions = [  
    // x      y      z  
0 ->  -0.5, -0.5,  0.0,   // lower left corner  
1 ->  0.5, -0.5,  0.0,   // lower right corner  
2 ->  0.0,  0.5,  0.0   // upper corner  
];
```



# Array Buffer Objects

The Indices will be saved as an Element Array Buffer. The way to do this is similar to the (Vertex) Array Buffer

```
var indices = [0, 1, 2];

// now we will do the same for the indices
var index_buffer = gl.createBuffer();
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, index_buffer);
gl.bufferData(gl.ELEMENT_ARRAY_BUFFER, new Uint16Array(indices), gl.STATIC_DRAW);
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, null);
```

# Array Buffer Objects Results

```
// create an array holding all our vertex positions.      Note: This will become a triangle
var positions = [
    // x      y      z
    -0.5, -0.5,  0.0,   // lower left corner
    0.5, -0.5,  0.0,   // lower right corner
    0.0,  0.5,  0.0   // upper corner
];

// indices show the 3 points that create a triangle. This will not be of much help with just
// 1 triangle, but once we start drawing more it will start making more sense.
var indices = [0, 1, 2];

// create a buffer object, bind it to webgl as our active buffer and put our vertices in the buffer
var vertex_buffer = gl.createBuffer();
gl.bindBuffer(gl.ARRAY_BUFFER, vertex_buffer);
gl.bufferData(gl.ARRAY_BUFFER, new Float32Array(positions), gl.STATIC_DRAW);

// unbind the buffer to prevent unwanted changes later
gl.bindBuffer(gl.ARRAY_BUFFER, null);

// now we will do the same for the indices
var index_buffer = gl.createBuffer();
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, index_buffer);
gl.bufferData(gl.ELEMENT_ARRAY_BUFFER, new Uint16Array(indices), gl.STATIC_DRAW);
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, null);
```

## Step 2: Shaders and Shader Program

# Shaders and Shader Program

As we recall from the graphics pipeline slide, we can supply code for 3 Shaders:

Vertex Shader

Geometry Shader

Fragment Shader

We will only create a Vertex Shader and a Fragment Shader. The Geometry Shader is not necessary.

# Shaders and Shader Program

Shaders are written in their own language called GLSL (OpenGL Shader Language)

Our Shader code will be defined as a constant string.

Vertex Shader

```
// the vertex shader source code
const vertexShaderSource = `#version 300 es

    in vec3 coordinates;

    void main() {
        gl_Position = vec4(coordinates, 1.0);
    }
`;
```

Fragment Shader

```
// the fragment shader source code
const fragmentShaderSource = `#version 300 es

    precision mediump float;

    out vec4 fragmentColor;

    void main() {
        fragmentColor = vec4(0.0, 0.0, 0.0, 1.0);
    }
`;
```

# Shaders and Shader Program

In the next step we create Shader Objects, attach the source code, and compile the source code.

Vertex Shader

```
var vertexShader = gl.createShader(gl.VERTEX_SHADER);  
gl.shaderSource(vertexShader, vertexShaderSource);  
gl.compileShader(vertexShader);
```

Fragment Shader

```
var fragmentShader = gl.createShader(gl.FRAGMENT_SHADER);  
gl.shaderSource(fragmentShader, fragmentShaderSource);  
gl.compileShader(fragmentShader);
```

# Shaders and Shader Program

These lines will check if the shader compiled and give an error if it was not compiled.

```
// debugging the shader
if (!gl.getShaderParameter(fragmentShader, gl.COMPILE_STATUS)) {
    alert('An error occurred compiling the shaders: ' + gl.getShaderInfoLog(fragmentShader));
    gl.deleteShader(fragmentShader);
    return null;
}
```

# Shaders and Shader Program

Now we connect the shaders in a program and tell WebGL to use the program.

```
// finally create a shader program that links our shaders to each other.  
var shaderProgram = gl.createProgram();  
  
// attach our shaders to the program  
gl.attachShader(shaderProgram, vertexShader);  
gl.attachShader(shaderProgram, fragmentShader);  
  
// link the shader programs to each other  
gl.linkProgram(shaderProgram);  
  
// tell WebGL to use our shader program  
gl.useProgram(shaderProgram);
```

## Step 3: Linking Buffers and Shaders

# Linking Buffers and Shaders

This is all the code necessary to link the buffers and shaders.

```
// bind our buffer objects to WebGL
gl.bindBuffer(gl.ARRAY_BUFFER, vertex_buffer);
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, index_buffer);

// get the point in our vertex shader where we can insert our positions
var coordinatePosition = gl.getAttribLocation(shaderProgram, "coordinates");

// tell the vertex shader how to interpret the vertex data.
gl.vertexAttribPointer(coordinatePosition, 3, gl.FLOAT, false, 0, 0);

// tell WebGL to enable the vertex attribute we just specified.
gl.enableVertexAttribArray(coordinatePosition);
```

# Linking Buffers and Shaders

These 2 lines tell WebGL where to insert our Buffers into the shaders and how to interpret the Buffers.

```
// get the point in our vertex shader where we can insert our positions  
var coordinatePosition = gl.getAttribLocation(shaderProgram, "coordinates");  
  
// tell the vertex shader how to interpret the vertex data.  
gl.vertexAttribPointer(coordinatePosition, 3, gl.FLOAT, false, 0, 0);
```

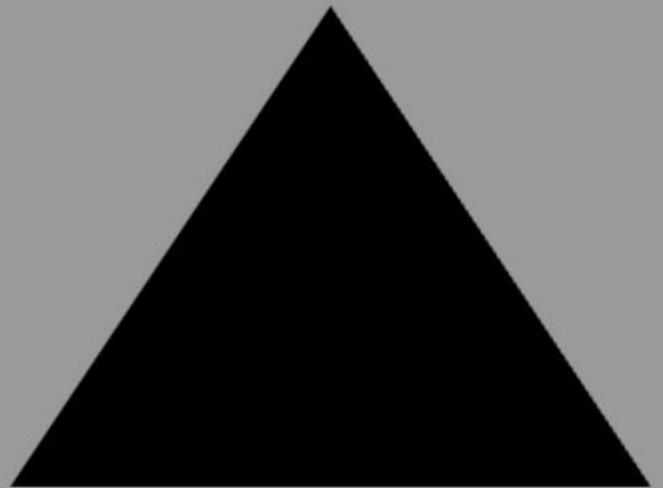
## Step 4: Drawing

# Drawing

This line tells WebGL to start drawing triangles.

```
// draw the triangle  
gl.drawElements(gl.TRIANGLES, indices.length, gl.UNSIGNED_SHORT, 0);
```

# The result



# Afsluiting

Thanks for  
listening.





## Part II

Presentation by: Quincy Jacobs

# Session preview

This session will focus on these points:

1. Colors array and (color) Vertex Buffer Object
1. Combining the Color and Position Vertex Buffers
1. Transformations and the math behind them  
Part 1: 2D vectors

Step 1: Colors array and  
(color) Vertex Buffer Object

# Colors array and (color) Vertex Buffer Object

Similar to the position vertex array the color vertex array will have 3 elements: r, g, b.



How does WebGL interpret color data?

# Colors array and (color) Vertex Buffer Object

WebGL takes in positive floats as RGBA color values between 0 and 1

R	0.0 ... 1.0
G	0.0 ... 1.0
B	0.0 ... 1.0

What will the raw data look like in code?

# Colors array and (color) Vertex Buffer Object

The array closely resembles the position array, and even the creation of the object is the same.

```
var colors = [
    //   r     g     b
    [1.0, 0.0, 0.0,   // lower left corner
     0.0, 1.0, 0.0,   // lower right corner
     0.0, 0.0, 0.0,   // upper left corner
     0.0, 0.0, 1.0],  // upper right corner
];

var color_buffer = gl.createBuffer();
gl.bindBuffer(gl.ARRAY_BUFFER, color_buffer);
gl.bufferData(gl.ARRAY_BUFFER, new Float32Array(colors), gl.STATIC_DRAW);
```

Where do we insert our colors in the shader?

# Colors array and (color) Vertex Buffer Object

We have to specify a new input variable in the Vertex Shader, and give it to the Fragment Shader

```
// the vertex shader source code
const vertexShaderSource = `#version 300 es

    in vec3 v_position;
    in vec3 v_color;

    out lowp vec3 f_color;

    void main() {
        f_color = v_color;
        gl_Position = vec4(v_position, 1.0);
    }
`;
```

```
// the fragment shader source code
const fragmentShaderSource = `#version 300 es

precision mediump float;

in lowp vec3 f_color;

out vec4 fragmentColor;

void main() {
    fragmentColor = vec4(f_color, 1.0);
}
`;
```

Next we will tie everything together in the code

# Colors array and (color) Vertex Buffer Object

```
var colors = [
    // r   g   b
    1.0, 0.0, 0.0, // lower left corner
    0.0, 1.0, 0.0, // lower right corner
    0.0, 0.0, 0.0, // upper left corner
    0.0, 0.0, 1.0  // upper right corner
];

var color_buffer = gl.createBuffer();
gl.bindBuffer(gl.ARRAY_BUFFER, color_buffer);
gl.bufferData(gl.ARRAY_BUFFER, new Float32Array(colors), gl.STATIC_DRAW);

var color_location = gl.getAttribLocation(shaderProgram, "v_color");
gl.vertexAttribPointer(color_location, 3, gl.FLOAT, false, 0, 0);
gl.bindBuffer(gl.ARRAY_BUFFER, null);

// bind our buffer objects to WebGL
gl.bindBuffer(gl.ARRAY_BUFFER, vertex_buffer);
gl.bindBuffer(gl.ARRAY_BUFFER, color_buffer);
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, index_buffer);

// tell WebGL to enable the vertex attribute we just specified.
gl.enableVertexAttribArray(position_location);
gl.enableVertexAttribArray(color_location);
```

## Step 2: Combining the Color and Position Vertex Buffers

# Combining the Color and Position Vertex Buffers

POSITION BUFFER	Vertice 1			Vertice 2			Vertice 3			...
	Position x	Position y	Position z	Position x	Position y	Position z	Position x	Position y	Position z	
COLOR BUFFER	Vertice 1			Vertice 2			Vertice 3			...
	R	G	B	R	G	B	R	G	B	

How should we combine these 2 arrays?

# Combining the Color and Position Vertex Buffers

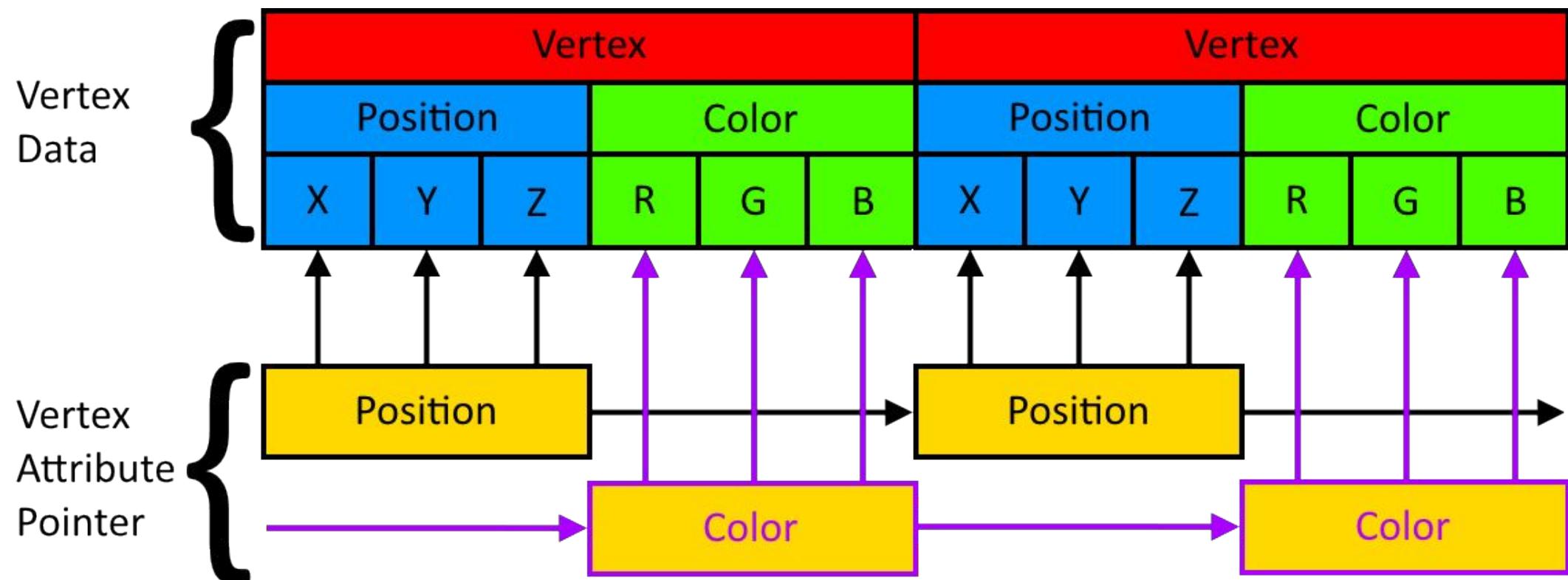
We simply place the position and color of each vertex right behind each other



How would WebGL filter these out and give them to the right in variable in the vertex shader?

# Combining the Color and Position Vertex Buffers

We use 2 vertex attribute pointers, one for positions and one for colors. Now let's see the code.



# Combining the Color and Position Vertex Buffers

The code simply pastes the rgb values after the xyz values.

```
// create an array holding all our vertex data.  
var vertices = [  
    //---positions---\    /---colors---\  
    // x      y      z      r      g      b  
    -0.5,  -0.5,  0.0,  1.0,  0.0,  0.0,  // lower left corner  
    0.5,   -0.5,  0.0,  0.0,  1.0,  0.0,  // lower right corner  
    -0.5,   0.5,  0.0,  0.0,  0.0,  0.0,  // upper left corner  
    0.5,   0.5,  0.0,  0.0,  0.0,  1.0,  // upper right corner  
];
```

How will we feed the Vertex fragment with this data?

# Combining the Color and Position Vertex Buffers

We use 2 pointers as specified in the image before.

```
// create a buffer, bind it to webgl as our active buffer and put our vertices in the buffer
var vertex_buffer = gl.createBuffer();
gl.bindBuffer(gl.ARRAY_BUFFER, vertex_buffer);
gl.bufferData(gl.ARRAY_BUFFER, new Float32Array(vertices), gl.STATIC_DRAW);

// position attribute pointer
var position_location = gl.getAttribLocation(shaderProgram, "v_position");
gl.vertexAttribPointer(position_location, 3, gl.FLOAT, false, 6*4, 0);

// color attribute pointer
var color_location = gl.getAttribLocation(shaderProgram, "v_color");
gl.vertexAttribPointer(color_location, 3, gl.FLOAT, false, 6*4, 3*4);
```

There is just one more loose end left.

# Combining the Color and Position Vertex Buffers

We remove our color buffer and don't bind it anymore.

```
// bind our buffer objects to WebGL
gl.bindBuffer(gl.ARRAY_BUFFER, vertex_buffer);
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, index_buffer);

// tell WebGL to enable the vertex attribute we just specified.
gl.enableVertexAttribArray(position_location);
gl.enableVertexAttribArray(color_location);
```

The location is still necessary as that is the point in the shader we will feed data to.

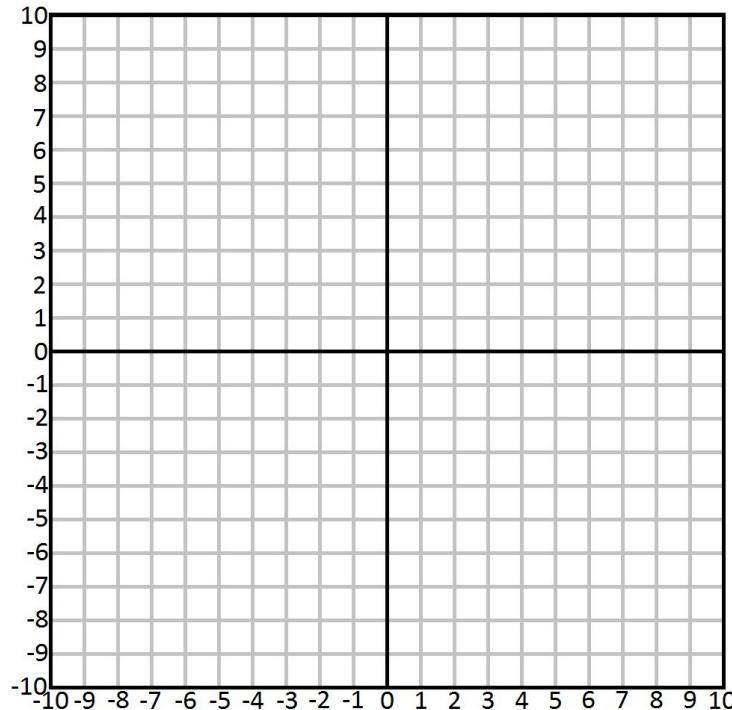
# Step 3: Transformations and the math behind them

## Part 1: 2D vectors

Disclaimer: I am not a mathematician

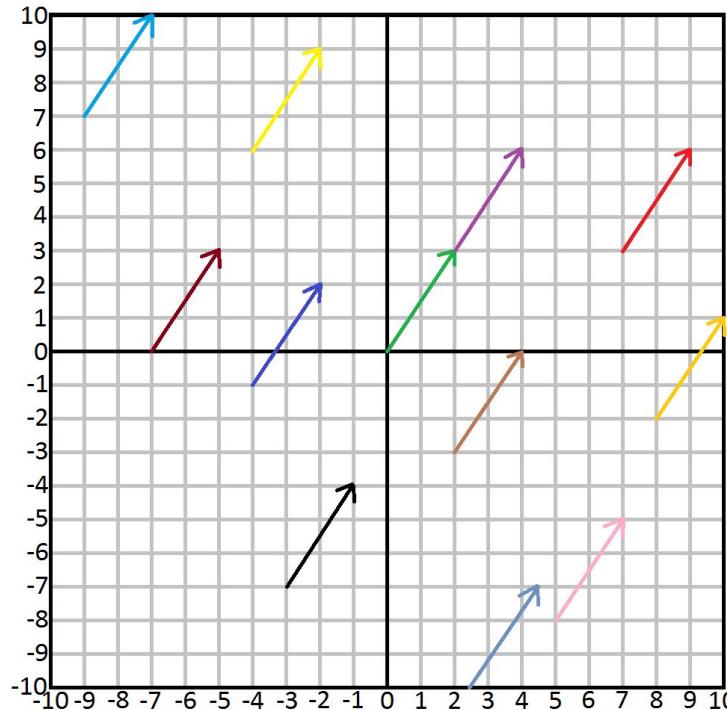
# Math part 1: 2D vectors

Let's start off with 2D examples and slowly work into 3D and transformations.  
This is a 2D Cartesian system.



# Math part 1: 2D vectors

This is a 2D Cartesian system with vectors.



Which arrow indicates vector  $(2, 3)$ ?

# Math part 1: 2D vectors

All of them are the same vector.

A vector in mathematics indicates only 2 things:

1. Direction
2. Magnitude

A vector is usually notated with a bold symbol or a symbol with an arrow on top.

$$\mathbf{v} = \vec{v} = \begin{pmatrix} x \\ y \end{pmatrix}$$

The 2 numbers in a vector are usually displayed on top of each other for convenience

# Math part 1: 2D vectors

Vectors can also be manipulated in many different ways.

Let's start with scalar operations:

$$\text{Vector: } \mathbf{v} = \vec{v} = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

$$\text{Scalar: } s = 5$$

$$\text{Multiplication: } \vec{v} * s = \begin{pmatrix} 2 * 5 \\ 5 * 5 \end{pmatrix} = \begin{pmatrix} 10 \\ 25 \end{pmatrix}$$

$$\text{Division: } \vec{v} / s = \begin{pmatrix} 2 / 5 \\ 5 / 5 \end{pmatrix} = \begin{pmatrix} 0.4 \\ 1 \end{pmatrix}$$

The scalar will simply be applied to every member of the vector, even with 3D vectors.

Addition and Subtraction with just a scalar are weird:

# Math part 1: 2D vectors

Vectors can also be manipulated in many different ways.

Let's start with scalar operations:

$$\text{Vector: } \mathbf{v} = \vec{\mathbf{v}} = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

$$\text{Scalar: } s = 5$$

$$\text{Addition: } \vec{\mathbf{v}} + s = \begin{pmatrix} 2 + 5 \\ 5 + 5 \end{pmatrix} = \begin{pmatrix} 7 \\ 10 \end{pmatrix}$$

$$\text{Subtraction: } \vec{\mathbf{v}} - s = \begin{pmatrix} 2 - 5 \\ 5 - 5 \end{pmatrix} = \begin{pmatrix} -3 \\ 0 \end{pmatrix}$$

$$\text{Multiplication: } \vec{\mathbf{v}} * s = \begin{pmatrix} 2 * 5 \\ 5 * 5 \end{pmatrix} = \begin{pmatrix} 10 \\ 25 \end{pmatrix}$$

$$\text{Division: } \vec{\mathbf{v}} / s = \begin{pmatrix} 2 / 5 \\ 5 / 5 \end{pmatrix} = \begin{pmatrix} 0.4 \\ 1 \end{pmatrix}$$

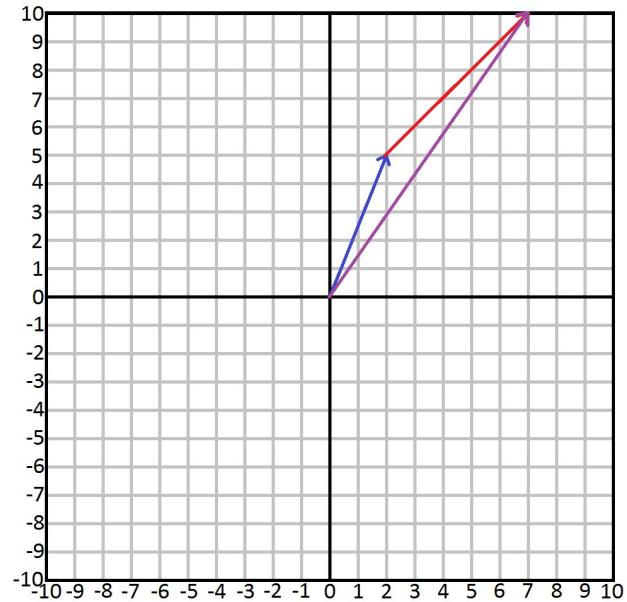
The scalar will simply be applied to every member of the vector, even with 3D vectors.

Why are adding and subtracting scalars a weird thing to do to vectors?

# Math part 1: 2D vectors

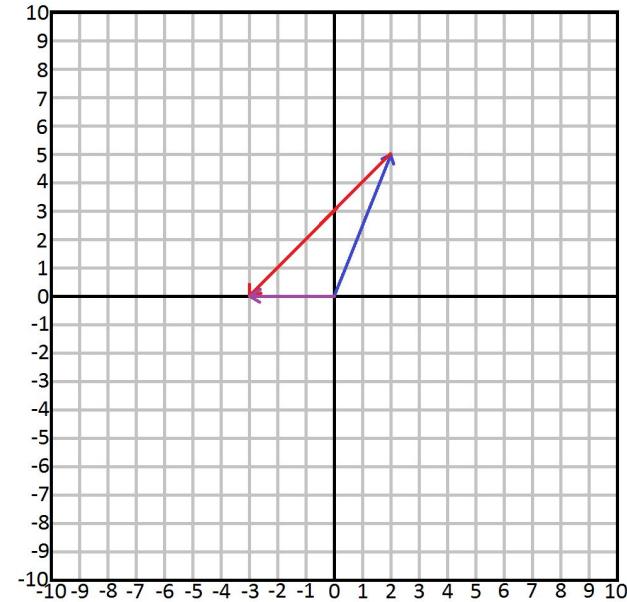
Addition and subtraction can only move a vector like a bishop in chess.

There is no correlation because both direction and magnitude change in weird ways.



$$\text{Vector: } \mathbf{v} = \vec{v} = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

$$\text{Scalar: } s = 5$$



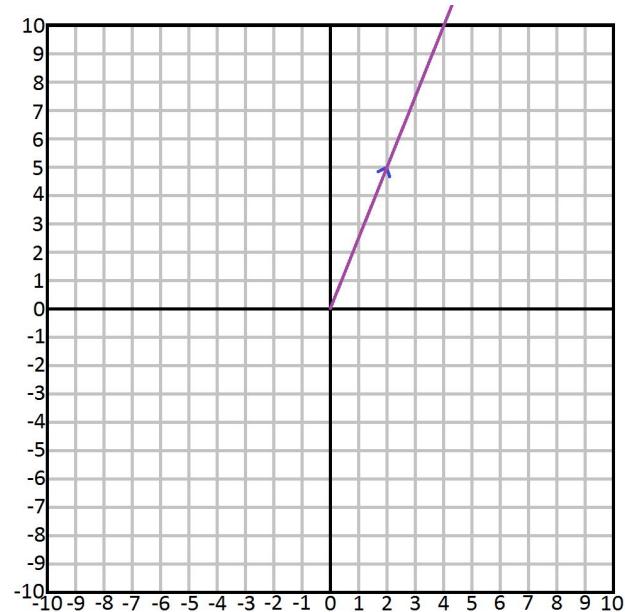
$$\text{Addition: } \vec{v} + s = \begin{pmatrix} 2 + 5 \\ 5 + 5 \end{pmatrix} = \begin{pmatrix} 7 \\ 10 \end{pmatrix}$$

$$\text{Subtraction: } \vec{v} - s = \begin{pmatrix} 2 - 5 \\ 5 - 5 \end{pmatrix} = \begin{pmatrix} -3 \\ 0 \end{pmatrix}$$

Multiplying and Dividing by a scalar is much more useful.

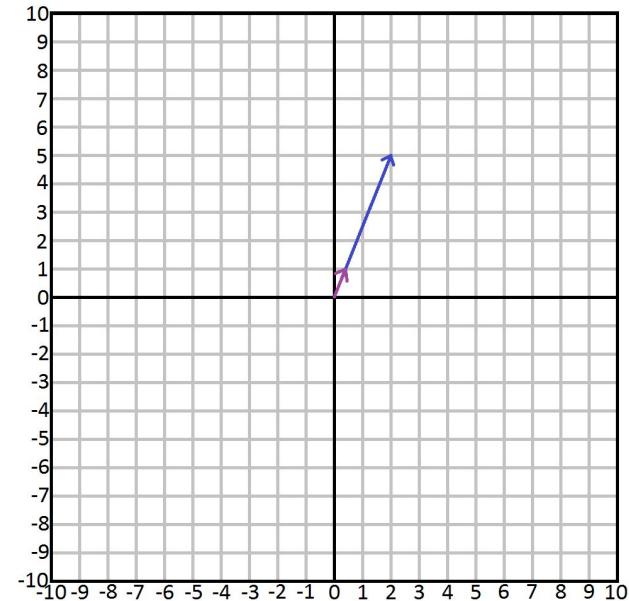
# Math part 1: 2D vectors

Multiplication and Division lengthen or shorten the distance of the vector.  
The direction will remain, making them very useful.



Vector:  $\mathbf{v} = \vec{v} = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$

Scalar:  $s = 5$



**Multiplication:**  $\vec{v} * s = \begin{pmatrix} 2 * 5 \\ 5 * 5 \end{pmatrix} = \begin{pmatrix} 10 \\ 25 \end{pmatrix}$

**Division:**  $\vec{v} / s = \begin{pmatrix} 2 / 5 \\ 5 / 5 \end{pmatrix} = \begin{pmatrix} 0.4 \\ 1 \end{pmatrix}$

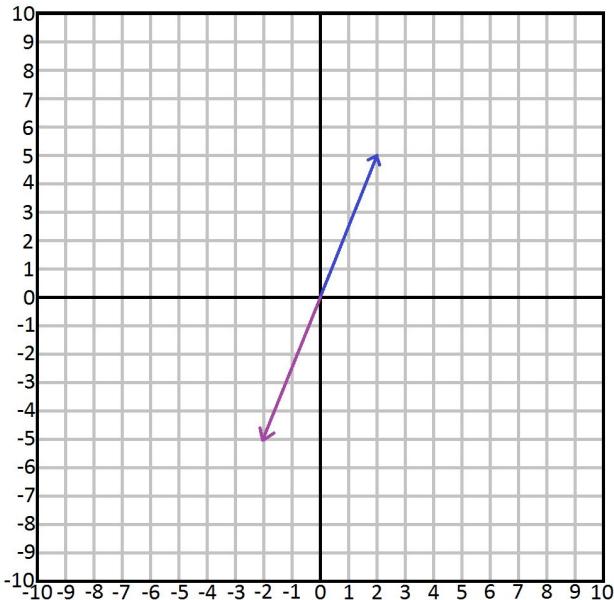
Another useful operation is flipping the vector. Any idea how you can do this?

# Math part 1: 2D vectors

Flipping a vector is done by simple multiplying the vector with the scalar -1.

Vector:  $\mathbf{v} = \vec{v} = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$

Scalar:  $s = -1$



Multiplication:  $\vec{V} * S = \begin{pmatrix} 2 * -1 \\ 5 * -1 \end{pmatrix} = \begin{pmatrix} -2 \\ -5 \end{pmatrix}$

Let's continue to vector on vector operations.

# Math part 1: 2D vectors

Take these 2 vectors:

$$\mathbf{v} = \vec{v} = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

$$\mathbf{w} = \vec{w} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

**Addition:**  $\vec{v} + \vec{w} = \begin{pmatrix} 2 + 3 \\ 5 + 1 \end{pmatrix} = \begin{pmatrix} 5 \\ 6 \end{pmatrix}$

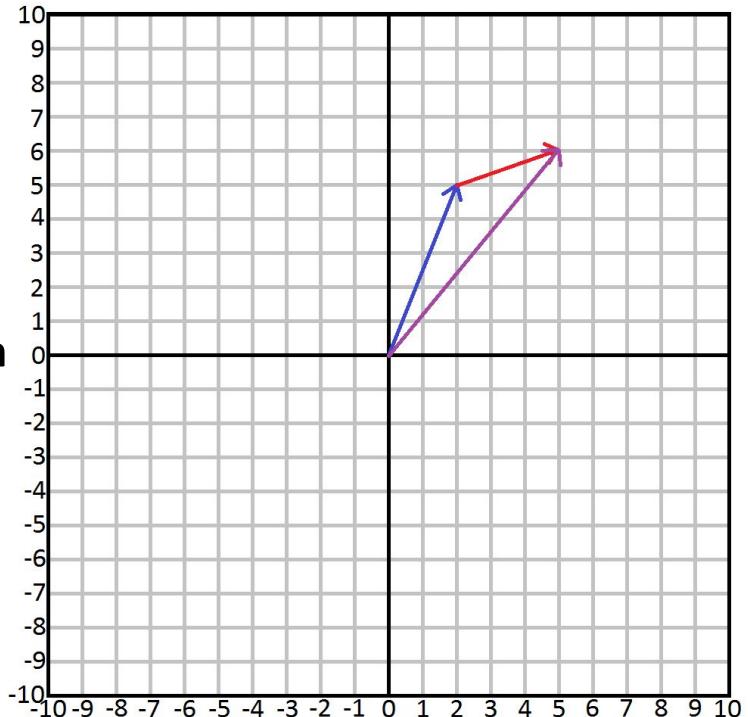
**Subtraction:**  $\vec{v} - \vec{w} = \begin{pmatrix} 2 - 3 \\ 5 - 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 4 \end{pmatrix}$

Seeing this visually will make it much clearer.

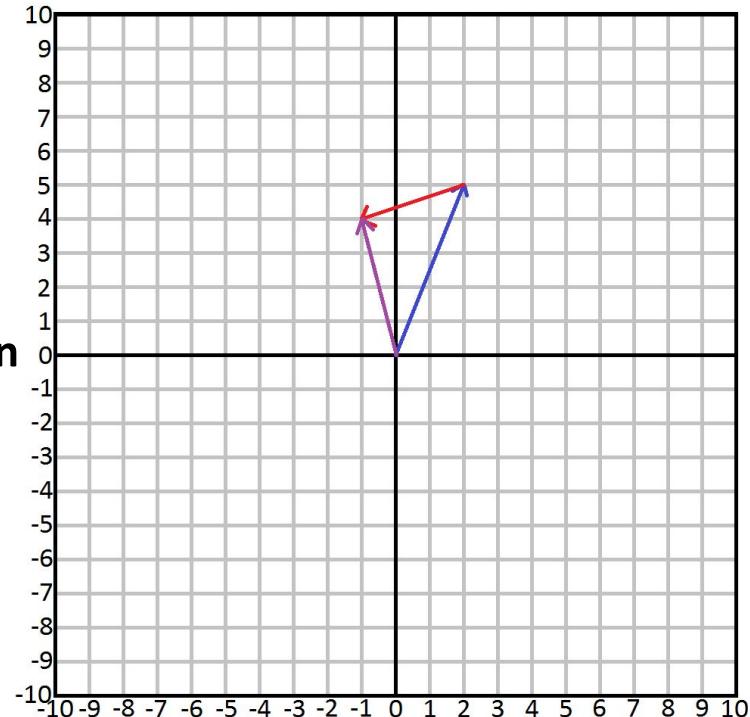
# Math part 1: 2D vectors

This is the visual representation of the Addition and Subtraction of our **v** and **w** vectors

Addition



Subtraction

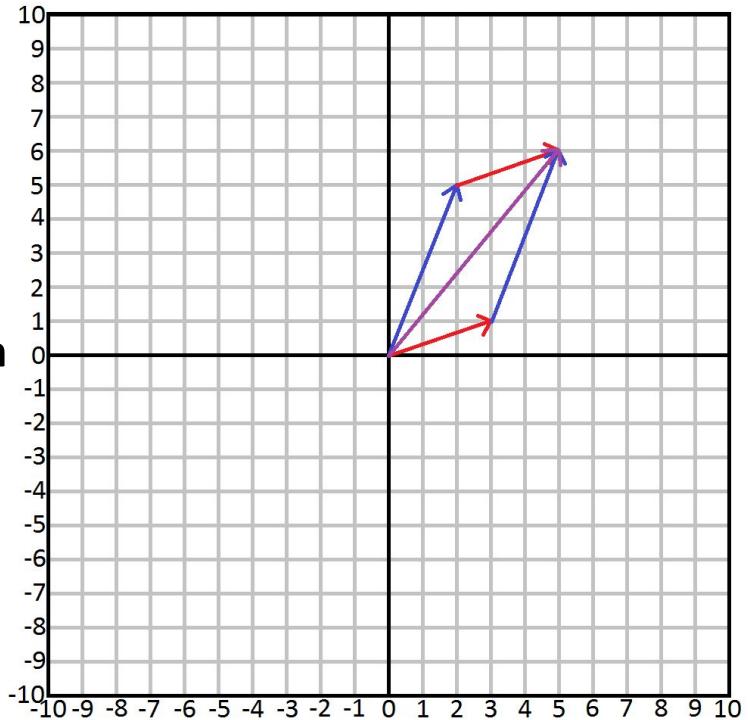


Will these vectors have the same outcome regardless of order?

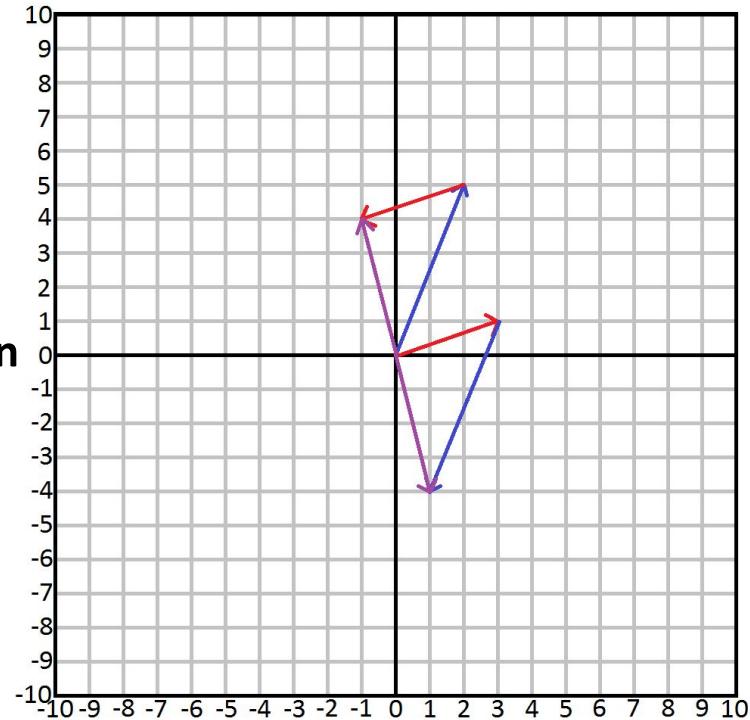
# Math part 1: 2D vectors

Addition does, subtraction does not.

**Addition**



**Subtraction**



The math will continue at the end of part III



To be continued next time...



Thanks for  
listening.





## Part III

Textures, Vectors, and 4 matrices to move your triangles.

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# Session preview

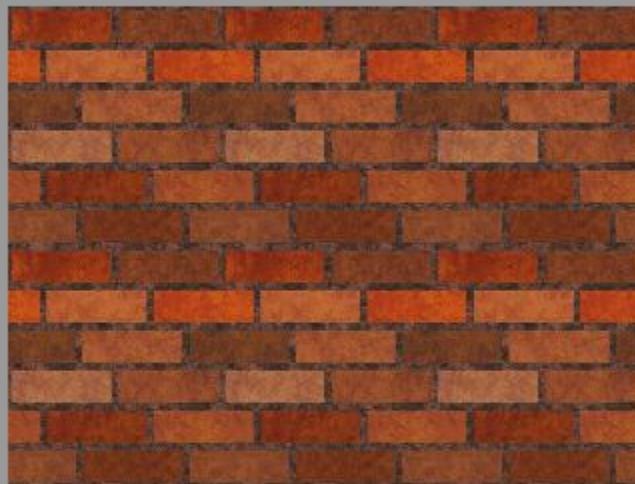
This session will focus on these points:

- 1. Adding a texture**
- 2. Math**
  - 2D/3D vectors
  - Matrices
- 3. Applying math in WebGL**

- 
- Step 1: Adding a texture
  - Step 2: Math
  - Step 3: Applying math in WebGL

# Adding a texture

What we have



# Adding a texture

## To-do list

- Texture object
- Loading image
- Texture parameters
- Texture in shader
- Texture “vertices”
- Texture attribute pointer

# Adding a texture

## Creating a texture object.

1. Let WebGL create the object
2. Bind the object to WebGL
3. Create a placeholder image

```
// create a texture and bind it to the gl context
var texture = gl.createTexture();
gl.bindTexture(gl.TEXTURE_2D, texture);

// image placeholder until it has been loaded from a file
gl.texImage2D(gl.TEXTURE_2D, 0, gl.RGBA, 1, 1, 0, gl.RGBA, gl.UNSIGNED_BYTE,
              new Uint8Array([127, 127, 127, 255]));
```

# Adding a texture

## To-do list

- Texture object
- Loading image
- Texture parameters
- Texture in shader
- Texture “vertices”
- Texture attribute pointer

# Adding a texture

## Loading an image.

```
var image = new Image();
path = 'https://image.source/image';
requestCORSIfNotSameOrigin(image, path);
image.src = path;
```

## Cross-Origin Resource Sharing (CORS)

```
// function to request CORS for Cross-Origin Images
function requestCORSIfNotSameOrigin(img, url)
{
    if ((new URL(url)).origin !== window.location.origin)
    {
        img.crossOrigin = "";
    }
}
```

# Adding a texture

## To-do list

- Texture object
- Loading image
- Texture parameters
- Texture in shader
- Texture “vertices”
- Texture attribute pointer

# Adding a texture

Set texture parameters after image load

```
// when the image is loaded, set the texture properties
image.addEventListener('load', function()
{
    // set 4 different texture settings (https://developer.mozilla.org/en-US/docs/Web/API/WebGLRenderingContext/texParameter)
    gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_S, gl.REPEAT);
    gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_T, gl.REPEAT);
    gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_MIN_FILTER, gl.NEAREST);
    gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_MAG_FILTER, gl.NEAREST);

    // instead of setting texParameteri 4 times we can use the line below,
    // but we will also lose the ability to alter texture behavior.
    //gl.generateMipmap(gl.TEXTURE_2D);
    gl.texImage2D(gl.TEXTURE_2D, 0, gl.RGBA, gl.RGBA, gl.UNSIGNED_BYTE, image);

});
```

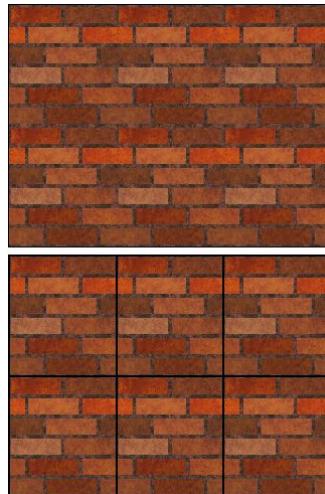
# Adding a texture

TEXTURE\_WRAP\_S

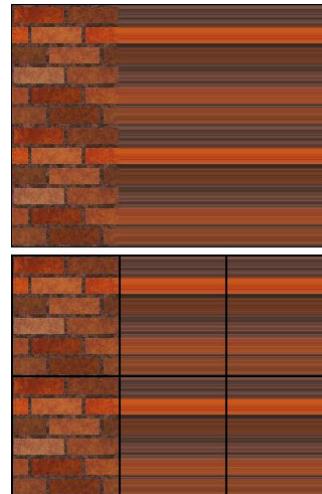
```
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_S, gl.REPEAT);
```

3 options for TEXTURE\_WRAP\_S:

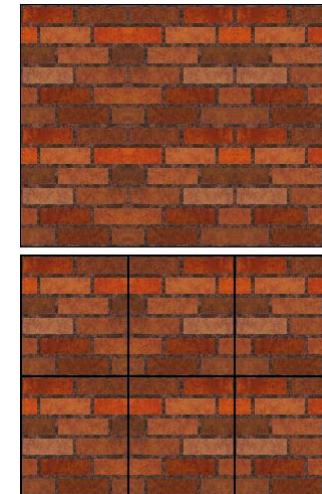
gl.REPEAT



gl.CLAMP\_TO\_EDGE



gl.MIRRORED\_REPEAT



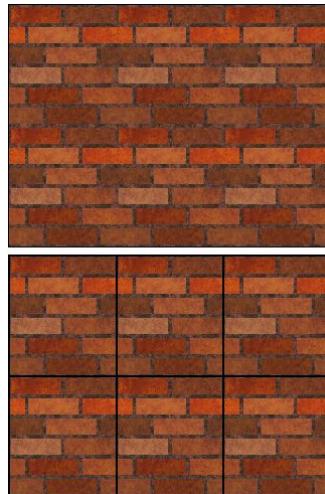
# Adding a texture

TEXTURE\_WRAP\_T

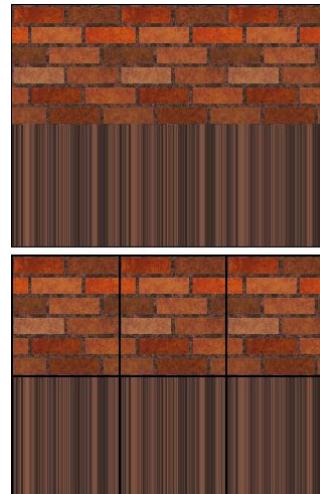
```
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_T, gl.REPEAT);
```

Same as TEXTURE\_WRAP\_S, but on the y-axis:

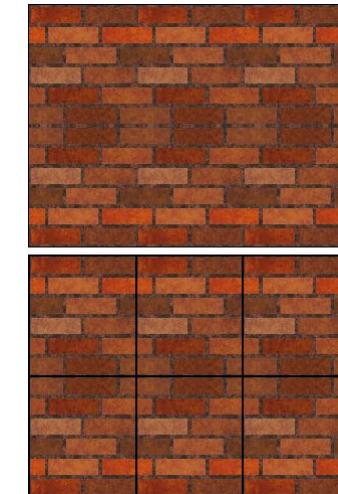
gl.REPEAT



gl.CLAMP\_TO\_EDGE



gl.MIRRORED\_REPEAT



# Adding a texture

## **TEXTURE\_MIN\_FILTER** and **TEXTURE\_MAG\_FILTER**

```
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_MIN_FILTER, gl.NEAREST);  
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_MAG_FILTER, gl.NEAREST);
```

Control the stretching of the image with 6 options:

GL\_NEAREST - (no filtering, no mipmaps)

GL\_LINEAR - (filtering, no mipmaps)

GL\_NEAREST\_MIPMAP\_NEAREST - (no filtering, sharp switching between mipmaps)

GL\_NEAREST\_MIPMAP\_LINEAR - (no filtering, smooth transition between mipmaps)

GL\_LINEAR\_MIPMAP\_NEAREST - (filtering, sharp switching between mipmaps)

GL\_LINEAR\_MIPMAP\_LINEAR - (filtering, smooth transition between mipmaps)

# Adding a texture

## To-do list

- Texture object
- Loading image
- Texture parameters
- Texture in shader
- Texture “vertices”
- Texture attribute pointer

# Adding a texture

## Vertex shader

Abuse the vertex shader as a conduit

```
// the vertex shader source code
const vertexShaderSource = `#version 300 es

    in vec3 v_position;
    in vec3 v_color;
    in vec2 v_texture;

    out lowp vec3 f_color;
    out lowp vec2 f_texture;

    void main() {
        f_color = v_color;
        f_texture = v_texture;
        gl_Position = vec4(v_position, 1.0);
    }
`;
```

# Adding a texture

## Fragment shader

```
// the fragment shader source code
const fragmentShaderSource = `#version 300 es

precision mediump float;

in lowp vec3 f_color;
in lowp vec2 f_texture;

out vec4 fragmentColor;

uniform sampler2D u_texture;

void main() {
    fragmentColor = texture(u_texture, f_texture);
    //fragmentColor = vec4(f_color, 1.0);
}
`;
```

# Adding a texture

## To-do list

- Texture object
- Loading image
- Texture parameters
- Texture in shader
- Texture “vertices”
- Texture attribute pointer

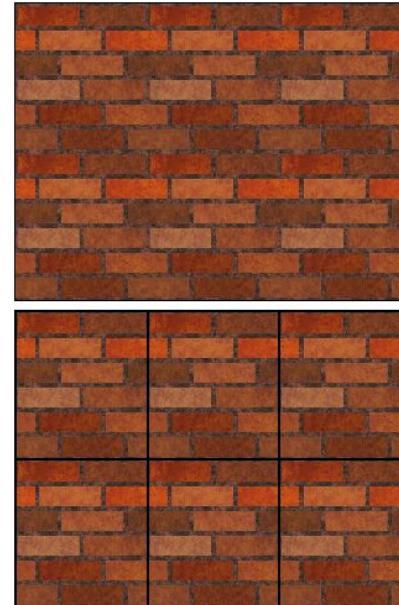
# Adding a texture

Inputting texture coordinates

The actual texture



Desired result



# Adding a texture

The coordinates for the image itself

0.0 : 0.0

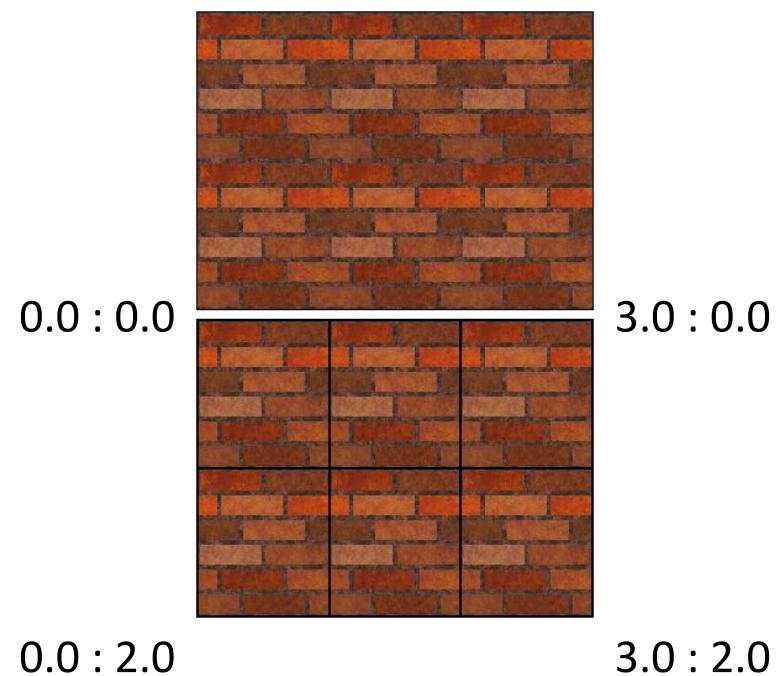


1.0 : 0.0

1.0 : 1.0

# Adding a texture

The coordinates for the desired result:



# Adding a texture

## Implementing the coordinates

```
// create an array holding all our vertex data.  
var vertices = [  
    //---positions---\  /---colors---\  /--texture--\  
    // x      y      z      r      g      b  
    -0.5, -0.5, 0.0, 1.0, 0.0, 0.0, 0.0, 2.0,    // lower left corner  
    0.5, -0.5, 0.0, 0.0, 1.0, 0.0, 3.0, 2.0,    // lower right corner  
    -0.5, 0.5, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,    // upper left corner  
    0.5, 0.5, 0.0, 0.0, 0.0, 1.0, 3.0, 0.0     // upper right corner  
];
```

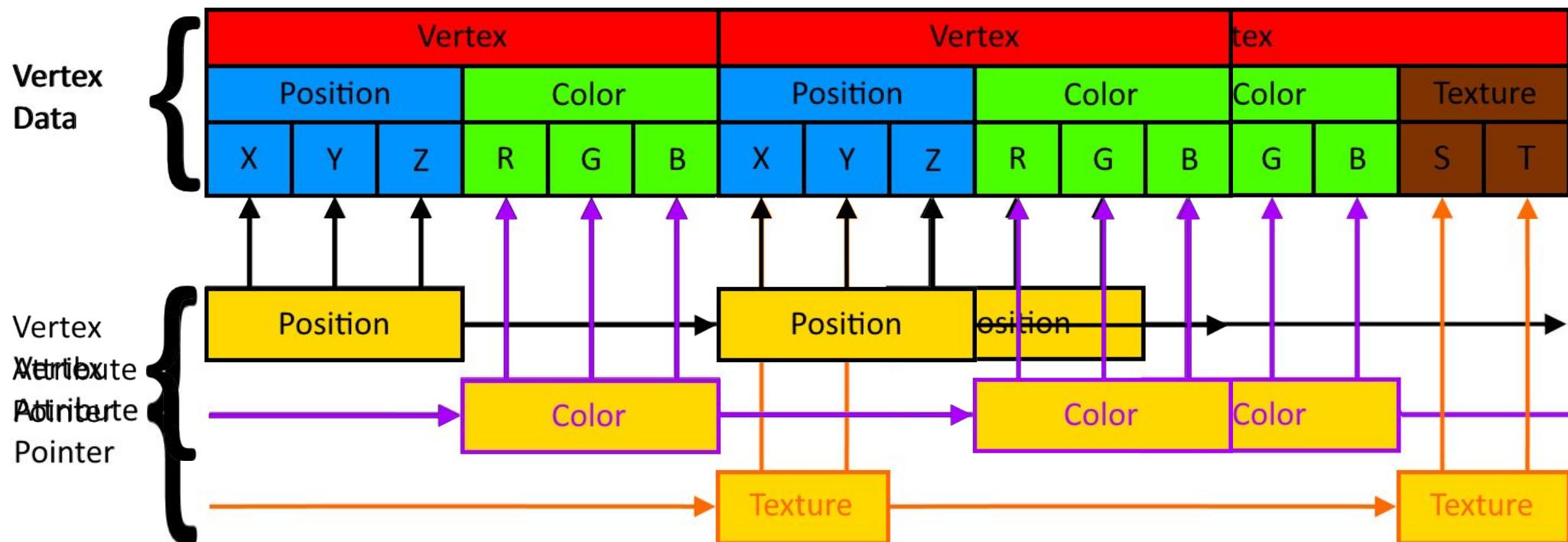
# Adding a texture

## To-do list

- Texture object
- Loading image
- Texture parameters
- Texture in shader
- Texture “vertices”
- Texture attribute pointer

# Adding a texture

The **texture attribute pointer** adds in just like the **color attribute pointer**.



# Adding a texture

Add the texture **vertex attribute pointer**

```
// create a buffer, bind it to webgl as our active buffer and put our vertices in the buffer
var vertex_buffer = gl.createBuffer();
gl.bindBuffer(gl.ARRAY_BUFFER, vertex_buffer);
gl.bufferData(gl.ARRAY_BUFFER, new Float32Array(vertices), gl.STATIC_DRAW);

// position attribute pointer
var position_location = gl.getAttribLocation(shaderProgram, "v_position");
gl.vertexAttribPointer(position_location, 3, gl.FLOAT, false, 6*4, 0);

// color attribute pointer
var color_location = gl.getAttribLocation(shaderProgram, "v_color");
gl.vertexAttribPointer(color_location, 3, gl.FLOAT, false, 6*4, 3*4);

// texture attribute pointer
var texture_location = gl.getAttribLocation(shaderProgram, "v_texture");
gl.vertexAttribPointer(texture_location, 2, gl.FLOAT, false, 8*4, 6*4);
```

# Adding a texture

Enable the **vertex attribute arrays**

```
// tell WebGL to enable the vertex attribute we just specified.  
gl.enableVertexAttribArray(position_location);  
gl.enableVertexAttribArray(color_location);  
gl.enableVertexAttribArray(texture_location);
```

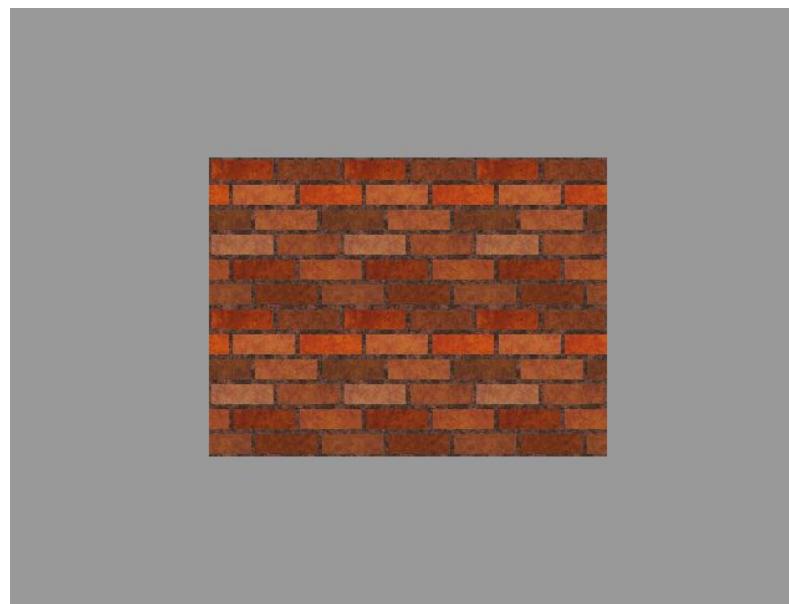
# Adding a texture

## To-do list

- ☒ Texture object
- ☒ Loading image
- ☒ Texture parameters
- ☒ Texture in shader
- ☒ Texture “vertices”
- ☒ Texture attribute pointer

# Adding a texture

The final result:





Step 1: Adding a texture

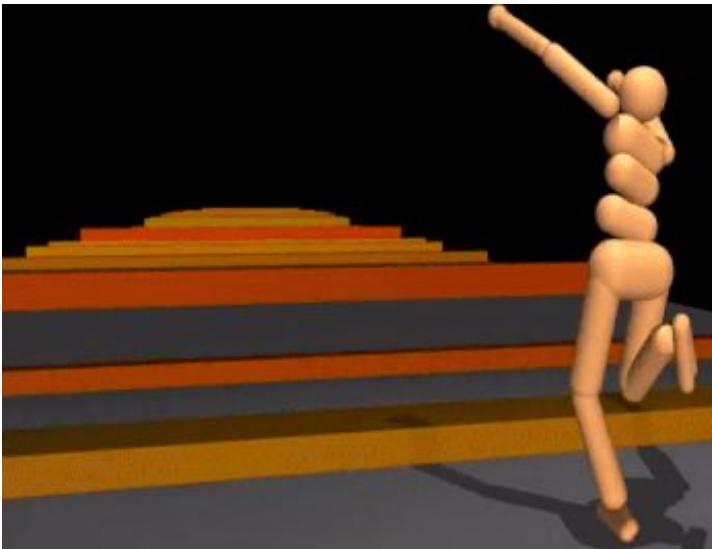
**Step 2: Math**

Step 3: Applying math in WebGL

Disclaimer: I am not a mathematician

# Math

What you discussed last term.



A dense collection of mathematical equations and diagrams covering various fields of science and engineering, including:

- Electric Circuits:  $R = R_1 + R_2$ ,  $\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2}$ ,  $E_1 = 10 \text{ ohm} (m_1 - m_2) = \frac{(r_1)^2}{(r_2)^2}$ ,  $D = \frac{1}{\pi r^2}$ ,  $E = \frac{m \omega^2}{2}$ .
- Hydraulics:  $P_1 = P_2$ ,  $h_1 p_1 = h_2 p_2$ ,  $\sum M = 0$ ,  $\vec{M} = \vec{F} \cdot L$ .
- Optics:  $S = \frac{U}{R}$ ,  $I = \frac{U}{S}$ ,  $F = \frac{q}{S}$ ,  $A = Q$ ,  $J = \lim_{\Delta t \rightarrow 0} \frac{\Delta S}{\Delta t}$ ,  $h = \frac{J^2 - I^2}{2g}$ ,  $Q = UIt$ ,  $\phi = BS \cos \alpha$ ,  $x = x_0 + \sqrt{t}$ ,  $V = \frac{4}{3} \pi R^3$ .
- Mechanics:  $F = m \ddot{x}$ ,  $A = mgh$ ,  $L = 2\pi R$ ,  $T = \frac{2\pi}{\omega}$ ,  $C_2 = HD$ ,  $U_I = \sqrt{\frac{GM}{R}}$ ,  $y = \sin x$ ,  $y = e^x$ ,  $U_Q = U_C \sqrt{\frac{1-e}{1+e}}$ ,  $S = \pi R^2$ ,  $E = mc^2$ ,  $\phi = \frac{1}{4\pi} \int \frac{Q}{r^2} dV$ ,  $\vec{B} = \mu_0 I \vec{S}$ ,  $\oint \vec{B} d\vec{l} = \mu_0 I S$ ,  $\omega = \frac{\omega}{R}$ ,  $P = \frac{U^2}{R}$ ,  $L = 4\pi R^2 G T^4$ .
- Thermodynamics:  $PV = \frac{P_0 V_0}{T_0}$ ,  $P_1 + P_2 = P$ ,  $F \cdot S$ ,  $\lim_{x \rightarrow 0} \frac{\sin x}{x}$ .

# Math

What you will actually learn.



# Step 2: Math

2D/3D vectors  
Matrices

Disclaimer: I am still not a mathematician

# Math: 2D/3D vectors

## To-do list

- 3D vector
- Vector length
- Unit vector
- Dot product
- Cross product

# Math: 2D/3D vectors

Last time: addition and subtraction with 2D vectors.

$$\mathbf{v} = \vec{v} = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

$$\mathbf{w} = \vec{w} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

**Addition:**

$$\vec{v} + \vec{w} = \begin{pmatrix} 2 + 3 \\ 5 + 1 \end{pmatrix} = \begin{pmatrix} 5 \\ 6 \end{pmatrix}$$

**Subtraction:**

$$\vec{v} - \vec{w} = \begin{pmatrix} 2 - 3 \\ 5 - 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 4 \end{pmatrix}$$

# Math: 2D/3D vectors

Addition and subtraction with 3D vectors.

$$\mathbf{v} = \vec{v} = \begin{pmatrix} 2 \\ 5 \\ 4 \end{pmatrix}$$

$$\mathbf{w} = \vec{w} = \begin{pmatrix} 3 \\ 1 \\ 2 \end{pmatrix}$$

**Addition:**

$$\vec{v} + \vec{w} = \begin{pmatrix} 2 + 3 \\ 5 + 1 \\ 4 + 2 \end{pmatrix} = \begin{pmatrix} 5 \\ 6 \\ 6 \end{pmatrix}$$

**Subtraction:**

$$\vec{v} - \vec{w} = \begin{pmatrix} 2 - 3 \\ 5 - 1 \\ 4 - 2 \end{pmatrix} = \begin{pmatrix} -1 \\ 4 \\ 2 \end{pmatrix}$$

# Math: 2D/3D vectors

## To-do list

- 3D vector
- Vector length
- Unit vector
- Dot product
- Cross product

# Math: 2D/3D vectors

Length (or magnitude) of a vector:

- indicates how far a vector travels
- independent of direction
- always positive
- usually written as  $|v|$

# Math: 2D/3D vectors

The length (or magnitude) of a 2D vector:

- formula:

$$|v| = \sqrt{(v_x)^2 + (v_y)^2}$$

- rearrangement of:

$$c^2 = a^2 + b^2$$

- proof:

$$|v| = \sqrt{(3)^2 + (4)^2} = 5$$

$$\mathbf{v} = \vec{v} = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

# Math: 2D/3D vectors

The length (or magnitude) of a 3D vector:

- formula:

$$|v| = \sqrt{(v_x)^2 + (v_y)^2 + (v_z)^2}$$

- rearrangement of:

$$d^2 = a^2 + b^2 + c^2$$

- proof:

$$|v| = \sqrt{(3)^2 + (4)^2 + (5)^2} \approx 7.07$$

$$\mathbf{v} = \vec{v} = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix}$$

# Math: 2D/3D vectors

## To-do list

- 3D vector
- Vector length
- Unit vector
- Dot product
- Cross product

# Math: 2D/3D vectors

## The unit vector:

- length of 1
- useful in calculations
- normalizing
- usually written as  $\hat{V}$

# Math: 2D/3D vectors

Vector

$$\mathbf{v} = \vec{\mathbf{v}} = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

Length

$$|\mathbf{v}| = \sqrt{(3)^2 + (4)^2} = 5$$

The (2D) unit vector:

- formula:

$$\hat{\mathbf{v}} = \vec{\mathbf{v}} / |\mathbf{v}|$$

- proof:

$$\hat{\mathbf{v}} = \begin{pmatrix} 3/5 \\ 4/5 \end{pmatrix} = \begin{pmatrix} 0.6 \\ 0.8 \end{pmatrix}$$

$$|\hat{\mathbf{v}}| = \sqrt{(0.6)^2 + (0.8)^2} = \sqrt{1} = 1$$

# Math: 2D/3D vectors

Vector

$$\mathbf{v} = \vec{\mathbf{v}} = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix}$$

Length

$$|\mathbf{v}| = \sqrt{(3)^2 + (4)^2 + (5)^2} \approx 7.07$$

The (3D) unit vector:

- formula:

$$\hat{\mathbf{v}} = \vec{\mathbf{v}} / |\mathbf{v}|$$

- proof:

$$\hat{\mathbf{v}} = \begin{pmatrix} 3 / 7.07 \\ 4 / 7.07 \\ 5 / 7.07 \end{pmatrix} \approx \begin{pmatrix} 0.424 \\ 0.566 \\ 0.707 \end{pmatrix}$$

$$|\mathbf{v}| = \sqrt{(0.424)^2 + (0.566)^2 + (0.707)^2} = \sqrt{1} = 1$$

# Math: 2D/3D vectors

## To-do list

- 3D vector
- Vector length
- Unit vector
- Dot product
- Cross product

# Math: 2D/3D vectors

## The dot product:

- “multiplying” vectors
- results in a scalar
- angle
- usually written as  $\mathbf{a} \cdot \mathbf{b}$

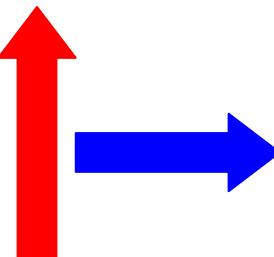
# Math: 2D/3D vectors

## The dot product:

- positive:



- 0:



- negative



# Math: 2D/3D vectors

The dot product:

- Formula 1:

$$\vec{a} \cdot \vec{b} = |a| \cdot |b| \cdot \cos\theta$$

- Formula 2:

$$\vec{a} \cdot \vec{b} = a_x \cdot b_x + a_y \cdot b_y (+ a_z \cdot b_z)$$

# Math: 2D/3D vectors

Vector

$$\mathbf{a} = \vec{a} = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} \quad \mathbf{b} = \vec{b} = \begin{pmatrix} 6 \\ 2 \\ 1 \end{pmatrix}$$

Length

$$|\mathbf{a}| = \sqrt{(3)^2 + (4)^2 + (5)^2} \approx 7.07$$

$$|\mathbf{b}| = \sqrt{(6)^2 + (2)^2 + (1)^2} \approx 6.4$$

Unit vector

$$\hat{\mathbf{a}} = \vec{a} / |\mathbf{a}| = \begin{pmatrix} 3 / 7.07 \\ 4 / 7.07 \\ 5 / 7.07 \end{pmatrix} \approx \begin{pmatrix} 0.424 \\ 0.566 \\ 0.707 \end{pmatrix}$$

$$\hat{\mathbf{b}} = \vec{b} / |\mathbf{b}| = \begin{pmatrix} 6 / 6.4 \\ 2 / 6.4 \\ 1 / 6.4 \end{pmatrix} \approx \begin{pmatrix} 0.938 \\ 0.313 \\ 0.156 \end{pmatrix}$$

# Math: 2D/3D vectors

Let's try to calculate the dot product.

Method 1

$$\vec{a} \cdot \vec{b} = a_x \cdot b_x + a_y \cdot b_y + a_z \cdot b_z$$

1.  $\vec{a} \cdot \vec{b} = 3 \cdot 6 + 4 \cdot 2 + 5 \cdot 1$

2.  $\vec{a} \cdot \vec{b} = 18 + 8 + 5$

3.  $\vec{a} \cdot \vec{b} = 31$

# Math: 2D/3D vectors

Let's try to calculate the dot product.

Method 2

$$\vec{a} \cdot \vec{b} = |a| \cdot |b| \cdot \cos\theta$$

1.  $31 = \sqrt{50} \cdot \sqrt{41} \cdot \cos\theta$
2.  $\cos\theta = 31 / (\sqrt{50} \cdot \sqrt{41})$
3.  $\cos\theta \approx 0.6847\dots$
4.  $\theta = \cos^{-1}(0.6847\dots) = 46.79$
5.  $\sqrt{50} \cdot \sqrt{41} \cdot \cos(46.79) = 31$

# Math: 2D/3D vectors

## To-do list

- 3D vector
- Vector length
- Unit vector
- Dot product
- Cross product

# Math: 2D/3D vectors

## The cross product:

- “multiplying” vectors
- results in a vector
- right angle
- usually written as  $\mathbf{a} \times \mathbf{b}$

# Math: 2D/3D vectors

The cross product:

- Formula 1:

$$\vec{a} \times \vec{b} = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \times \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = \left( \begin{array}{l} a_y \cdot b_z - a_z \cdot b_y \\ a_z \cdot b_x - a_x \cdot b_z \\ a_x \cdot b_y - a_y \cdot b_x \end{array} \right) = \begin{pmatrix} c_x \\ c_y \\ c_z \end{pmatrix}$$

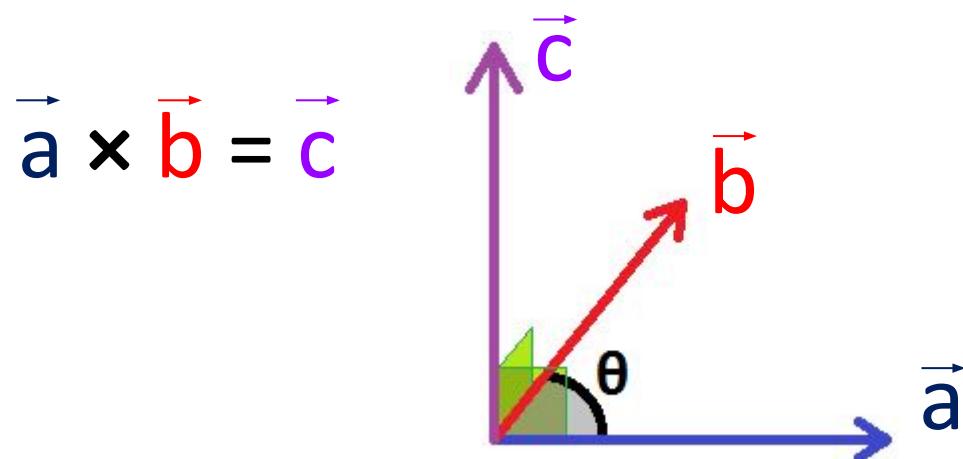
- Formula 2:

$$\vec{a} \times \vec{b} = |a| \cdot |b| \cdot \sin\theta \cdot \mathbf{n}$$

# Math: 2D/3D vectors

The cross product:

$$\vec{a} \times \vec{b} = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \times \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = \begin{pmatrix} a_y \cdot b_z - a_z \cdot b_y \\ a_z \cdot b_x - a_x \cdot b_z \\ a_x \cdot b_y - a_y \cdot b_x \end{pmatrix} = \begin{pmatrix} c_x \\ c_y \\ c_z \end{pmatrix}$$



# Math: 2D/3D vectors

The cross product:

$$\vec{a} \times \vec{b} = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \times \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = \begin{pmatrix} a_y \cdot b_z - a_z \cdot b_y \\ a_z \cdot b_x - a_x \cdot b_z \\ a_x \cdot b_y - a_y \cdot b_x \end{pmatrix} = \begin{pmatrix} c_x \\ c_y \\ c_z \end{pmatrix}$$

$$\vec{a} \times \vec{b} = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} \times \begin{pmatrix} 6 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \cdot 1 - 5 \cdot 2 \\ 5 \cdot 6 - 3 \cdot 1 \\ 3 \cdot 2 - 4 \cdot 6 \end{pmatrix} = \begin{pmatrix} -6 \\ 27 \\ -18 \end{pmatrix}$$

# Math: 2D/3D vectors

## To-do list

- ☒ 3D vector
- ☒ Vector length
- ☒ Unit vector
- ☒ Dot product
- ☒ Cross product

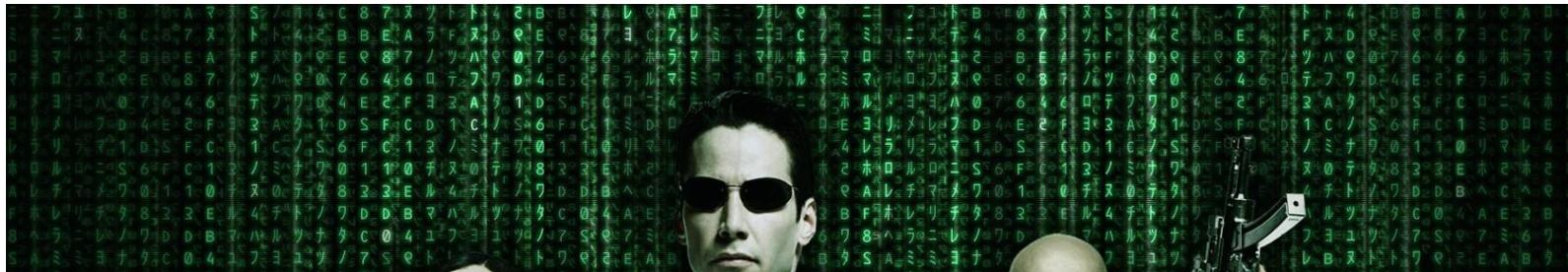
# Step 2: Math

2D/3D vectors  
Matrices

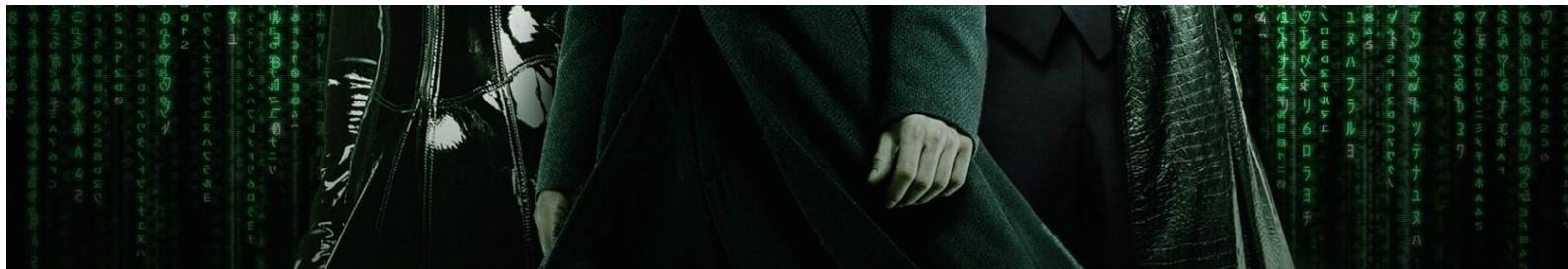
Disclaimer: I am still not a mathematician

# Math: Matrices

What is a matrix? What can you learn?



$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix}$$



# Math: Matrices

## To-do list

- Matrix specifications
- Matrix addition
- Matrix multiplications
- Identity matrix
- Scale matrix
- Translation matrix
- Rotation matrix

# Math: Matrices

A matrix:

- is rectangular
- $n \times n$  dimensions
- represents a linear function

# Math: Matrices

A matrix:

- usually written as

$$(3 \times 3) \quad \begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix}$$

$$(2 \times 2) \quad \begin{bmatrix} a_{1,1} & a_{1,2} \\ a_{2,1} & a_{2,2} \end{bmatrix}$$

$$(3 \times 2) \quad \begin{bmatrix} a_{1,1} & a_{1,2} \\ a_{2,1} & a_{2,2} \\ a_{3,1} & a_{3,2} \end{bmatrix}$$

# Math: Matrices

## To-do list

- Matrix specifications
- Matrix addition
- Matrix multiplications
- Identity matrix
- Scale matrix
- Translation matrix
- Rotation matrix

# Math: Matrices

## Matrix + Scalar

$$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} + 5 = \begin{bmatrix} 1 + 5 & 4 + 5 & 7 + 5 \\ 2 + 5 & 5 + 5 & 8 + 5 \\ 3 + 5 & 6 + 5 & 9 + 5 \end{bmatrix} = \begin{bmatrix} 6 & 9 & 12 \\ 7 & 10 & 13 \\ 8 & 11 & 14 \end{bmatrix}$$

Scalars will be applied to every element in the matrix.

# Math: Matrices

Matrix + Matrix

$$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} + \begin{bmatrix} 8 & 5 & 2 \\ 7 & 4 & 1 \\ 6 & 3 & 0 \end{bmatrix} =$$

$$\begin{bmatrix} 1+8 & 4+5 & 7+2 \\ 2+7 & 5+4 & 8+1 \\ 3+6 & 6+3 & 9+0 \end{bmatrix} = \begin{bmatrix} 9 & 9 & 9 \\ 9 & 9 & 9 \\ 9 & 9 & 9 \end{bmatrix}$$

# Math: Matrices

## To-do list

- Matrix specifications
- Matrix addition
- Matrix multiplications
- Identity matrix
- Scale matrix
- Translation matrix
- Rotation matrix

# Math: Matrices

Matrix · Matrix

$$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} \cdot \begin{bmatrix} 8 & 5 & 2 \\ 7 & 4 & 1 \\ 6 & 3 & 0 \end{bmatrix}$$

You can **multiply** a matrix as long as the amount of columns on the left equal the amount of rows on the right.

# Math: Matrices

Matrix · Matrix

$$\begin{bmatrix} (1 \cdot 8 + 4 \cdot 7 + 7 \cdot 6) & (1 \cdot 5 + 4 \cdot 4 + 7 \cdot 3) & (1 \cdot 2 + 4 \cdot 1 + 7 \cdot 0) \\ (2 \cdot 8 + 5 \cdot 7 + 8 \cdot 6) & (2 \cdot 5 + 5 \cdot 4 + 8 \cdot 3) & (2 \cdot 2 + 5 \cdot 1 + 8 \cdot 0) \\ (3 \cdot 8 + 6 \cdot 7 + 9 \cdot 6) & (3 \cdot 5 + 6 \cdot 4 + 9 \cdot 3) & (3 \cdot 2 + 6 \cdot 1 + 9 \cdot 0) \end{bmatrix}$$

$$\begin{bmatrix} 78 & 42 & 6 \\ 99 & 54 & 9 \\ 120 & 66 & 12 \end{bmatrix}$$

# Math: Matrices

## Matrix · Matrix

$$\begin{bmatrix} (1 \cdot 2) + (4 \cdot 1) + (7 \cdot 0) \\ (2 \cdot 2) + (5 \cdot 1) + (8 \cdot 0) \\ (3 \cdot 2) + (6 \cdot 1) + (9 \cdot 0) \end{bmatrix} \cdot \begin{bmatrix} 8 & 5 & 2 \\ 7 & 4 & 1 \\ 6 & 3 & 0 \end{bmatrix} = \begin{bmatrix} 78 & 42 & 6 \\ 99 & 54 & 9 \\ 120 & 66 & 12 \end{bmatrix}$$

# Math: Matrices

## Matrix · Matrix

Can you multiply these matrices?

$$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} \cdot \begin{bmatrix} 8 & 5 \\ 7 & 4 \\ 6 & 3 \end{bmatrix}$$

# Math: Matrices

## Matrix · Matrix

Can you multiply these matrices?

$$\begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} \cdot \begin{bmatrix} 8 & 5 \\ 7 & 4 \\ 6 & 3 \end{bmatrix}$$

# Math: Matrices

## Matrix · Vector

Can you multiply this matrix by this vector?

$$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} \cdot \begin{bmatrix} 8 \\ 7 \\ 6 \end{bmatrix}$$

# Math: Matrices

## To-do list

- Matrix specifications
- Matrix addition
- Matrix multiplications
- Identity matrix
- Scale matrix
- Translation matrix
- Rotation matrix

# Math: Matrices

An identity matrix:

- consists of 0's
- with diagonal 1's
- starting point
- same result

# Math: Matrices

The identity matrix:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Math: Matrices

An identity matrix:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix}$$

# Math: Matrices

## To-do list

- Matrix specifications
- Matrix addition
- Matrix multiplications
- Identity matrix
- Scale matrix
- Translation matrix
- Rotation matrix

# Math: Matrices

## A scale matrix:

- diagonal scale factor
- multiplies members of vector
- modifies length
- does not modify direction

# Math: Matrices

A scale matrix:

$$\begin{bmatrix} S_1 & 0 & 0 & 0 \\ 0 & S_2 & 0 & 0 \\ 0 & 0 & S_3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Math: Matrices

A scale matrix:

$$\begin{bmatrix} S_1 & 0 & 0 & 0 \\ 0 & S_2 & 0 & 0 \\ 0 & 0 & S_3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} S_1 \cdot x \\ S_2 \cdot y \\ S_3 \cdot z \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

# Math: Matrices

A scale matrix:

Scaling each member by a factor 2.

$$\begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 4 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \cdot 3 \\ 2 \cdot 4 \\ 2 \cdot 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 8 \\ 10 \\ 1 \end{bmatrix}$$

# Math: Matrices

## To-do list

- Matrix specifications
- Matrix addition
- Matrix multiplications
- Identity matrix
- Scale matrix
- Translation matrix
- Rotation matrix

# Math: Matrices

A translation matrix:

- column addition factor
- adds to members of vector
- modifies length
- modifies direction

# Math: Matrices

A translation matrix:

$$\begin{bmatrix} 1 & 0 & 0 & T_1 \\ 0 & 1 & 0 & T_2 \\ 0 & 0 & 1 & T_3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Math: Matrices

A translation matrix:

$$\begin{bmatrix} 1 & 0 & 0 & T_1 \\ 0 & 1 & 0 & T_2 \\ 0 & 0 & 1 & T_3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x + T_1 \\ y + T_2 \\ z + T_3 \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

# Math: Matrices

A translation matrix:

Translating with the vector [1, 2, 3].

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 4 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 + 1 \\ 4 + 2 \\ 5 + 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \\ 8 \\ 1 \end{bmatrix}$$

# Math: Matrices

## To-do list

- Matrix specifications
- Matrix addition
- Matrix multiplications
- Identity matrix
- Scale matrix
- Translation matrix
- Rotation matrix

# Math: Matrices

A rotation matrix:

- rotates around an axis
- modifies other 2 axis
- does not modify length
- modifies direction

# Math: Matrices

## Rotation matrices:

x-axis

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(\theta) & \sin(\theta) & 0 \\ 0 & -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

y-axis

$$\begin{bmatrix} \cos(\theta) & 0 & -\sin(\theta) & 0 \\ 0 & 1 & 0 & 0 \\ \sin(\theta) & 0 & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

z-axis

$$\begin{bmatrix} \cos(\theta) & \sin(\theta) & 0 & 0 \\ -\sin(\theta) & \cos(\theta) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Math part 4: Matrix • Vector

**x-axis rotation matrix:**

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(\theta) & \sin(\theta) & 0 \\ 0 & -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \cdot \cos(\theta) + z \cdot \sin(\theta) \\ y \cdot -\sin(\theta) + z \cdot \cos(\theta) \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

( $\theta$  is the rotation)

# Math part 4: Matrix • Vector

## x-axis rotation matrix:

Rotating by 1 radian. (almost 57.3 degrees)

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(1) & \sin(1) & 0 \\ 0 & -\sin(1) & \cos(1) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 4 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \cdot 0.54 + 5 \cdot 0.84 \\ 4 \cdot -0.84 + 5 \cdot 0.54 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 6.37 \\ -0.66 \\ 1 \end{bmatrix}$$

(Rotation in radians)

# Math part 4: Matrix • Vector

**y-axis rotation matrix:**

$$\begin{bmatrix} \cos(\theta) & 0 & -\sin(\theta) & 0 \\ 0 & 1 & 0 & 0 \\ \sin(\theta) & 0 & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \cdot \cos(\theta) + z \cdot -\sin(\theta) \\ y \\ x \cdot \sin(\theta) + z \cdot \cos(\theta) \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

( $\theta$  is the rotation)

# Math part 4: Matrix • Vector

## y-axis rotation matrix:

Rotating by 1 radian. (almost 57.3 degrees)

$$\begin{bmatrix} \cos(1) & 0 & -\sin(1) & 0 \\ 0 & 1 & 0 & 0 \\ \sin(1) & 0 & \cos(1) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 4 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \cdot 0.54 + 5 \cdot -0.84 \\ 4 \\ 3 \cdot 0.84 + 5 \cdot 0.54 \\ 1 \end{bmatrix} = \begin{bmatrix} -2.59 \\ 4 \\ 5.23 \\ 1 \end{bmatrix}$$

(Rotation in radians)

# Math part 4: Matrix • Vector

**z-axis rotation matrix:**

$$\begin{bmatrix} \cos(\theta) & \sin(\theta) & 0 & 0 \\ -\sin(\theta) & \cos(\theta) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \cdot \cos(\theta) + y \cdot \sin(\theta) \\ x \cdot -\sin(\theta) + y \cdot \cos(\theta) \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

( $\theta$  is the rotation)

# Math part 4: Matrix • Vector

## z-axis rotation matrix:

Rotating by 1 radian. (almost 57.3 degrees)

$$\begin{bmatrix} \cos(1) & \sin(1) & 0 & 0 \\ -\sin(1) & \cos(1) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 4 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \cdot 0.54 + 4 \cdot 0.84 \\ 3 \cdot -0.84 + 4 \cdot 0.54 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 4.99 \\ -0.36 \\ 5 \\ 1 \end{bmatrix}$$

(Rotation in radians)

# Math: Matrices

## To-do list

- ☒ Matrix specifications
- ☒ Matrix addition
- ☒ Matrix multiplications
- ☒ Identity matrix
- ☒ Scale matrix
- ☒ Translation matrix
- ☒ Rotation matrix



Step 1: Adding a texture

Step 2: Math

**Step 3: Applying math in WebGL**

Disclaimer: I am not a mathematician

# Applying the math

How much we still have to learn.



# Applying the math

## To-do list

- Create math library
- Edit Vertex Shader
- Identity matrix code
- Matrix multiplications code
- Scale matrix in code
- Translation matrix in code
- Rotation matrices in code

# Applying the math

We'll build our own small math library.

```
// Object holding functions for 3d math
var math3d = new function()
{
}
```

# Applying the math

Converter for radians/degrees.

```
this.degreesToRadians = function(degrees)
{
    return (degrees * (Math.PI / 180.0));
}

this.radiansToDegrees = function(radians)
{
    return (radians * (180.0 / Math.PI));
}
```

# Applying the math

## To-do list

- Create math library
- Edit Vertex Shader
- Identity matrix code
- Matrix multiplications code
- Scale matrix in code
- Translation matrix in code
- Rotation matrices in code

# Applying the math

Change the Vertex Shader.

```
// the vertex shader source code
const vertexShaderSource = `#version 300 es

in vec3 v_position;
in vec3 v_color;
in vec2 v_texture;

out lowp vec3 f_color;
out lowp vec2 f_texture;

uniform mat4 transform;

void main() {
    f_color = v_color;
    f_texture = v_texture;
    gl_Position = vec4(v_position, 1.0) * transform;
}
`;
```

We only supply the transformation

# Applying the math

Get the transform uniform location in the vertex shader.

```
var transform_location = gl.getUniformLocation(shaderProgram, "transform");
```

Supply our transform matrix.

```
gl.uniformMatrix4fv(transform_location, false, matrix);
```

# Applying the math

## To-do list

- Create math library
- Edit Vertex Shader
- Identity matrix code
- Matrix multiplications code
- Scale matrix in code
- Translation matrix in code
- Rotation matrices in code

# Applying the math

The identity matrix:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Applying the math

## Identity matrix function:

```
// Object holding functions for 3d math
var math3d = new function()
{
    // Return the identity matrix (a matrix with diagonal 1's so each row and column will always have a 1 once)
    this.identityMatrix = function()
    {
        return new Float32Array(
            [1, 0, 0, 0,
             0, 1, 0, 0,
             0, 0, 1, 0,
             0, 0, 0, 1]);
    }
}
```

This calls returns an identity matrix:

```
var matrix = math3d.identityMatrix();
```

# Applying the math

## To-do list

- Create math library
- Edit Vertex Shader
- Identity matrix code
- Matrix multiplications code
- Scale matrix in code
- Translation matrix in code
- Rotation matrices in code

# Applying the math

Matrix · Matrix

$$\begin{bmatrix} (1 \cdot 8 + 4 \cdot 7 + 7 \cdot 6) & (1 \cdot 5 + 4 \cdot 4 + 7 \cdot 3) & (1 \cdot 2 + 4 \cdot 1 + 7 \cdot 0) \\ (2 \cdot 8 + 5 \cdot 7 + 8 \cdot 6) & (2 \cdot 5 + 5 \cdot 4 + 8 \cdot 3) & (2 \cdot 2 + 5 \cdot 1 + 8 \cdot 0) \\ (3 \cdot 8 + 6 \cdot 7 + 9 \cdot 6) & (3 \cdot 5 + 6 \cdot 4 + 9 \cdot 3) & (3 \cdot 2 + 6 \cdot 1 + 9 \cdot 0) \end{bmatrix}$$

$$\begin{bmatrix} 78 & 42 & 6 \\ 99 & 54 & 9 \\ 120 & 66 & 12 \end{bmatrix}$$

# Applying the math

The matrix multiplication function:

```
this.multiplyMatrix = function(m1, m2)
{
    return new Float32Array(
        [m1[0]*m2[0] + m1[1]*m2[4] + m1[2]*m2[8] + m1[3]*m2[12],
        m1[0]*m2[1] + m1[1]*m2[5] + m1[2]*m2[9] + m1[3]*m2[13],
        m1[0]*m2[2] + m1[1]*m2[6] + m1[2]*m2[10] + m1[3]*m2[14],
        m1[0]*m2[3] + m1[1]*m2[7] + m1[2]*m2[11] + m1[3]*m2[15],
        m1[4]*m2[0] + m1[5]*m2[4] + m1[6]*m2[8] + m1[7]*m2[12],
        m1[4]*m2[1] + m1[5]*m2[5] + m1[6]*m2[9] + m1[7]*m2[13],
        m1[4]*m2[2] + m1[5]*m2[6] + m1[6]*m2[10] + m1[7]*m2[14],
        m1[4]*m2[3] + m1[5]*m2[7] + m1[6]*m2[11] + m1[7]*m2[15],
        m1[8]*m2[0] + m1[9]*m2[4] + m1[10]*m2[8] + m1[11]*m2[12],
        m1[8]*m2[1] + m1[9]*m2[5] + m1[10]*m2[9] + m1[11]*m2[13],
        m1[8]*m2[2] + m1[9]*m2[6] + m1[10]*m2[10] + m1[11]*m2[14],
        m1[8]*m2[3] + m1[9]*m2[7] + m1[10]*m2[11] + m1[11]*m2[15],
        m1[12]*m2[0] + m1[13]*m2[4] + m1[14]*m2[8] + m1[15]*m2[12],
        m1[12]*m2[1] + m1[13]*m2[5] + m1[14]*m2[9] + m1[15]*m2[13],
        m1[12]*m2[2] + m1[13]*m2[6] + m1[14]*m2[10] + m1[15]*m2[14],
        m1[12]*m2[3] + m1[13]*m2[7] + m1[14]*m2[11] + m1[15]*m2[15]]));
}
```

(Calculates 1 array item per line, 16 in total)

# Applying the math

## To-do list

- Create math library
- Edit Vertex Shader
- Identity matrix code
- Matrix multiplications code
- Scale matrix in code
- Translation matrix in code
- Rotation matrices in code

# Applying the math

A scale matrix:

$$\begin{bmatrix} S_1 & 0 & 0 & 0 \\ 0 & S_2 & 0 & 0 \\ 0 & 0 & S_3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} S_1 \cdot x \\ S_2 \cdot y \\ S_3 \cdot z \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

# Applying the math

The code for the scale function.

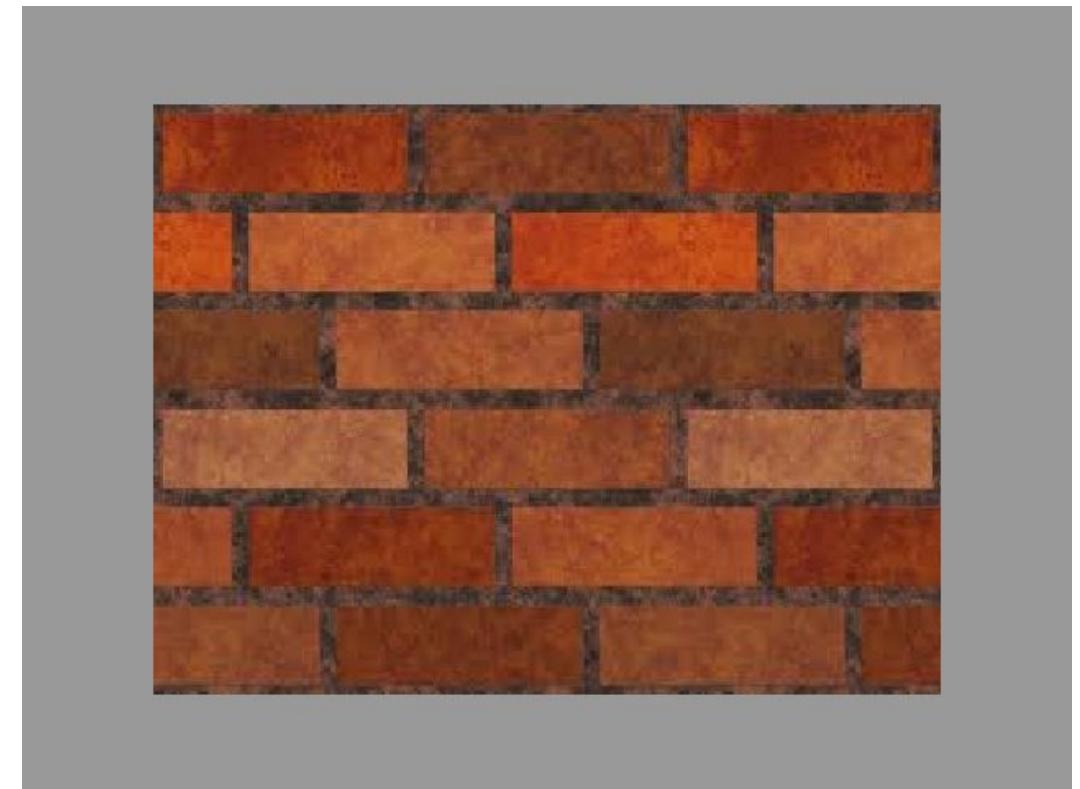
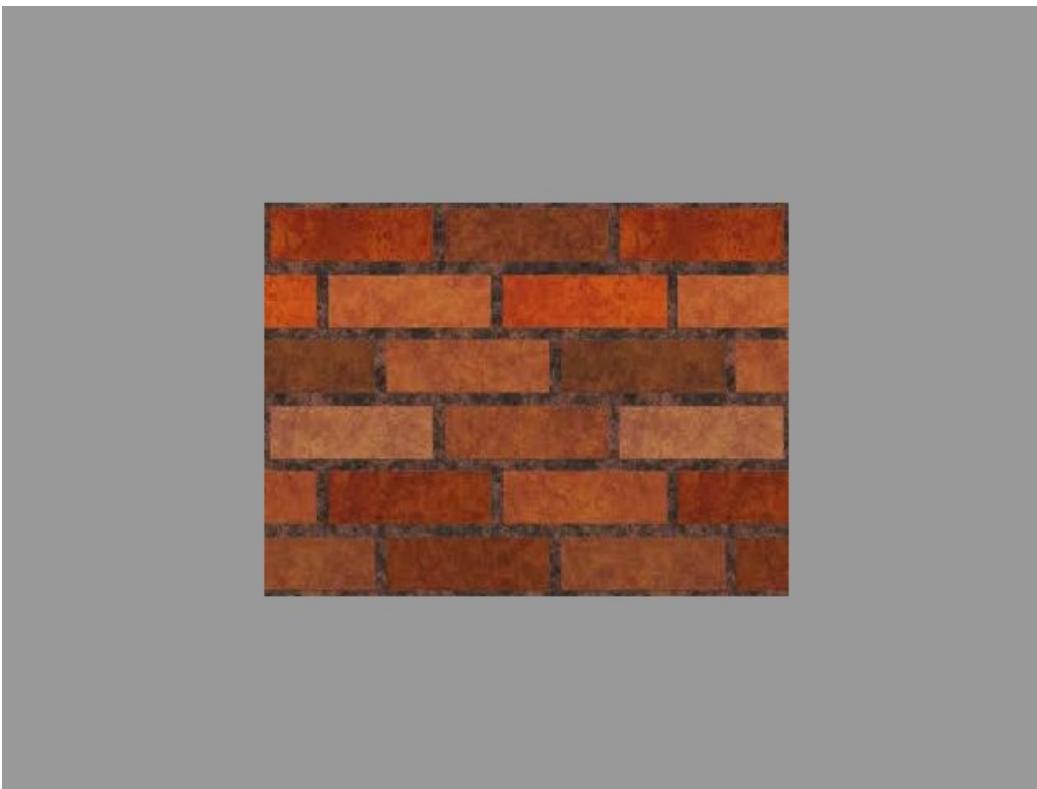
```
this.scaleMatrix = function(s1, s2, s3)
{
    return new Float32Array(
        [s1, 0, 0, 0,
         0, s2, 0, 0,
         0, 0, s3, 0,
         0, 0, 0, 1]);
}
```

Usage

```
var transform_location = gl.getUniformLocation(shaderProgram, "transform");
var matrix = math3d.identityMatrix();
matrix = math3d.multiplyMatrix(matrix, math3d.scaleMatrix(1.5, 1.5, 1.5));
gl.uniformMatrix4fv(transform_location, false, matrix);
```

# Applying the math

Scaling by 1.5:



# Applying the math

## To-do list

- Create math library
- Edit Vertex Shader
- Identity matrix code
- Matrix multiplications code
- Scale matrix in code
- Translation matrix in code
- Rotation matrices in code

# Applying the math

A translation matrix:

$$\begin{bmatrix} 1 & 0 & 0 & T_1 \\ 0 & 1 & 0 & T_2 \\ 0 & 0 & 1 & T_3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x + T_1 \\ y + T_2 \\ z + T_3 \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

# Applying the math

The code for the translate function.

```
this.translationMatrix = function(t1, t2, t3)
{
    return new Float32Array(
        [1, 0, 0, t1,
         0, 1, 0, t2,
         0, 0, 1, t3,
         0, 0, 0, 1]);
}
```

## Usage

```
var transform_location = gl.getUniformLocation(shaderProgram, "transform");
var matrix = math3d.identityMatrix();
matrix = math3d.multiplyMatrix(matrix, math3d.translationMatrix(0.2, 0.2, 0.2));
gl.uniformMatrix4fv(transform_location, false, matrix);
```

# Applying the math

Translating by [0.2, 0.2, 0.2]:



# Applying the math

## To-do list

- Create math library
- Edit Vertex Shader
- Identity matrix code
- Matrix multiplications code
- Scale matrix in code
- Translation matrix in code
- Rotation matrices in code

# Applying the math

An x-axis rotation matrix:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(\theta) & \sin(\theta) & 0 \\ 0 & -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \cdot \cos(\theta) + z \cdot \sin(\theta) \\ y \cdot -\sin(\theta) + z \cdot \cos(\theta) \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

# Applying the math

The code for the x rotation function.

```
// Clockwise rotation on the x axis
this.xRotationMatrix = function(rotationInDegrees)
{
    var rotationInRadians = this.degreesToRadians(rotationInDegrees);
    var c = Math.cos(rotationInRadians);
    var s = Math.sin(rotationInRadians);

    return new Float32Array(
        [1, 0, 0, 0,
         0, c, s, 0,
         0, -s, c, 0,
         0, 0, 0, 1]);
}
```

Usage

```
var transform_location = gl.getUniformLocation(shaderProgram, "transform");
var matrix = math3d.identityMatrix();
matrix = math3d.multiplyMatrix(matrix, math3d.xRotationMatrix(55));
gl.uniformMatrix4fv(transform_location, false, matrix);
```

# Applying the math

Rotating around the x axis by 75 degrees.



# Applying the math

A y-axis rotation matrix:

$$\begin{bmatrix} \cos(\theta) & 0 & -\sin(\theta) & 0 \\ 0 & 1 & 0 & 0 \\ \sin(\theta) & 0 & \cos(\theta) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \cdot \cos(\theta) + z \cdot -\sin(\theta) \\ y \\ x \cdot \sin(\theta) + z \cdot \cos(\theta) \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

# Applying the math

The code for the y rotation function.

```
// Clockwise rotation on the y axis
this.yRotationMatrix = function(rotationInDegrees)
{
    var rotationInRadians = this.degreesToRadians(rotationInDegrees);
    var c = Math.cos(rotationInRadians);
    var s = Math.sin(rotationInRadians);

    return new Float32Array(
        [c, 0, -s, 0,
         0, 1, 0, 0,
         s, 0, c, 0,
         0, 0, 0, 1]);
}
```

Usage

```
var transform_location = gl.getUniformLocation(shaderProgram, "transform");
var matrix = math3d.identityMatrix();
matrix = math3d.multiplyMatrix(matrix, math3d.yRotationMatrix(55));
gl.uniformMatrix4fv(transform_location, false, matrix);
```

# Math part 4: Matrix • Vector

Rotating around the y axis by 75 degrees.



# Applying the math

A z-axis rotation matrix:

$$\begin{bmatrix} \cos(\theta) & \sin(\theta) & 0 & 0 \\ -\sin(\theta) & \cos(\theta) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \cdot \cos(\theta) + y \cdot \sin(\theta) \\ x \cdot -\sin(\theta) + y \cdot \cos(\theta) \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ 1 \end{bmatrix}$$

# Applying the math

The code for the z rotation function.

```
// Clockwise rotation on the z axis
this.zRotationMatrix = function(rotationInDegrees)
{
    var rotationInRadians = this.degreesToRadians(rotationInDegrees);
    var c = Math.cos(rotationInRadians);
    var s = Math.sin(rotationInRadians);

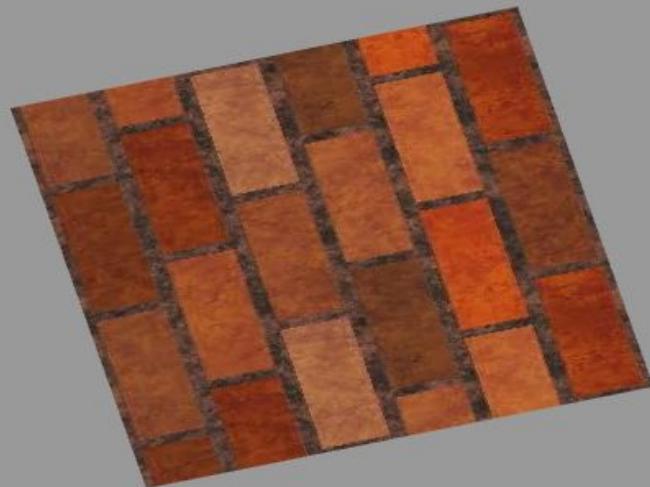
    return new Float32Array(
        [c, s, 0, 0,
         -s, c, 0, 0,
         0, 0, 1, 0,
         0, 0, 0, 1]);
}
```

Usage

```
var transform_location = gl.getUniformLocation(shaderProgram, "transform");
var matrix = math3d.identityMatrix();
matrix = math3d.multiplyMatrix(matrix, math3d.zRotationMatrix(55));
gl.uniformMatrix4fv(transform_location, false, matrix);
```

# Applying the math

Rotating around the z axis by 75 degrees.



# Applying the math

## To-do list

- ☒ Create math library
- ☒ Edit Vertex Shader
- ☒ Identity matrix code
- ☒ Matrix multiplications code
- ☒ Scale matrix in code
- ☒ Translation matrix in code
- ☒ Rotation matrices in code



To be continued next time...



Thanks for listening.





## Part IV

Presentation by: Quincy Jacobs