view\_frames Result Recorded at time: 1613530776.288 base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 17.203 Hz Average rate: 26.397 Hz Most recent transform: 1613530776.287 (0.001 sec old) Most recent transform: 1613530776.187 (0.101 sec old) Buffer length: 4.825 sec Buffer length: 4.925 sec torso\_link\_b2 torso\_link\_b1 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 40.206 Hz Average rate: 31.677 Hz Most recent transform: 1613530776.287 ( 0.001 sec old) Most recent transform: 1613530776.287 ( 0.001 sec old) Buffer length: 4.925 sec Buffer length: 4.925 sec arm\_right\_link\_1\_s arm\_left\_link\_1\_s Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 40.206 Hz Average rate: 31.677 Hz Most recent transform: 1613530776.287 ( 0.001 sec old) Most recent transform: 1613530776.287 (0.001 sec old) Buffer length: 4.925 sec Buffer length: 4.925 sec arm\_right\_link\_2\_1 arm\_left\_link\_2\_1 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 40.206 Hz Average rate: 31.677 Hz Most recent transform: 1613530776.287 ( 0.001 sec old) Most recent transform: 1613530776.287 (0.001 sec old) Buffer length: 4.925 sec Buffer length: 4.925 sec arm\_right\_link\_3\_e arm\_left\_link\_3\_e Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 31.677 Hz Average rate: 40.206 Hz Most recent transform: 1613530776.287 (0.001 sec old) Most recent transform: 1613530776.287 (0.001 sec old) Buffer length: 4.925 sec Buffer length: 4.925 sec arm\_right\_link\_4\_u arm\_left\_link\_4\_u Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 40.206 Hz Average rate: 31.677 Hz Most recent transform: 1613530776.287 ( 0.001 sec old) Most recent transform: 1613530776.287 (0.001 sec old) Buffer length: 4.925 sec Buffer length: 4.925 sec arm\_left\_link\_5\_r arm\_right\_link\_5\_r Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 31.677 Hz Average rate: 40.206 Hz Most recent transform: 1613530776.287 (0.001 sec old) Most recent transform: 1613530776.287 (0.001 sec old) Buffer length: 4.925 sec Buffer length: 4.925 sec arm\_right\_link\_6\_b arm\_left\_link\_6\_b Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 31.677 Hz Average rate: 40.206 Hz Most recent transform: 1613530776.287 ( 0.001 sec old) Most recent transform: 1613530776.287 (0.001 sec old) Buffer length: 4.925 sec Buffer length: 4.925 sec arm\_right\_link\_7\_t arm\_left\_link\_7\_t Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1613530776.288 sec old) Most recent transform: 0.000 ( 1613530776.288 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec arm\_right\_link\_tool0 arm\_left\_link\_tool0 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1613530776.288 sec old) Most recent transform: 0.000 ( 1613530776.288 sec old) Most recent transform: 0.000 ( 1613530776.288 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec robotiq\_arg2f\_base\_link motoman\_right\_hand\_safety motoman\_left\_hand Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1613530776.288 sec old) Buffer length: 0.000 sec right\_outer\_knuckle right\_inner\_knuckle motoman\_right\_ee motoman\_left\_hand\_safety left\_outer\_knuckle left\_inner\_knuckle Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1613530776.288 sec old) Most recent transform: 0.000 ( 1613530776.288 sec old) Most recent transform: 0.000 ( 1613530776.288 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec left\_outer\_finger right\_outer\_finger motoman\_left\_ee Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1613530776.288 sec old) Most recent transform: 0.000 ( 1613530776.288 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left\_inner\_finger right\_inner\_finger Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1613530776.288 sec old) Most recent transform: 0.000 ( 1613530776.288 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left\_inner\_finger\_pad right\_inner\_finger\_pad