Long-Term Learning in Soar



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Long-Term Learning Fundamental Questions

Will learning go on forever?

 How much of learned knowledge is ever used?

 Can we use understanding of chunk use to improve performance?

Experiments with "simple-learner" alone

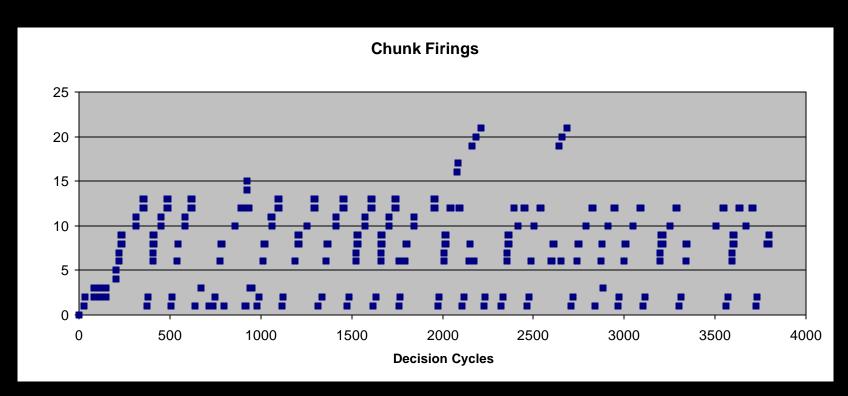




- At least 7 occasions for chunking
- More depending on starting position
- Initial circuit is 140 dc
- After chunking, 132 dc
- Chunking ends & all chunks on circuit are used each cycle

Experiments with "simple-learner" with "simple" tank



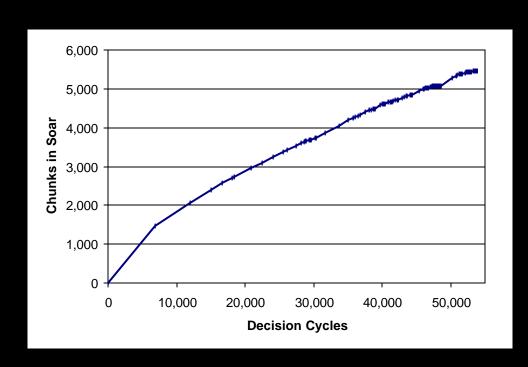


Experimenting with John Laird's Planning Bot

Experimental design:

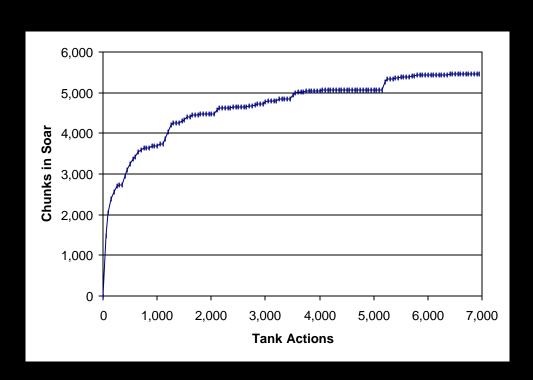
- John's Bot alone, run for twice the default period
- Excise chunks based on the gap between use
- Monitor performance . . .





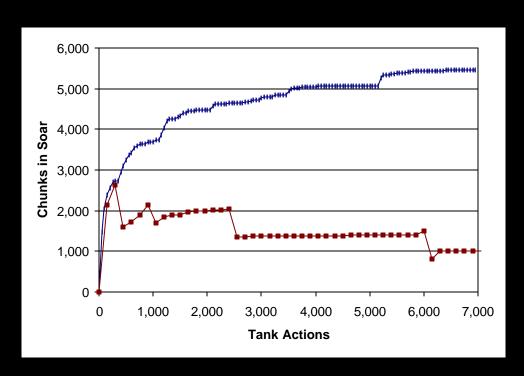
Learning continues, but it's slowing. . .



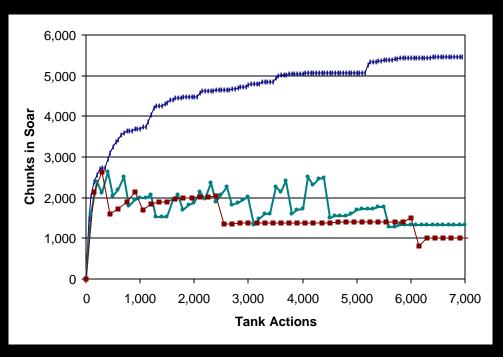


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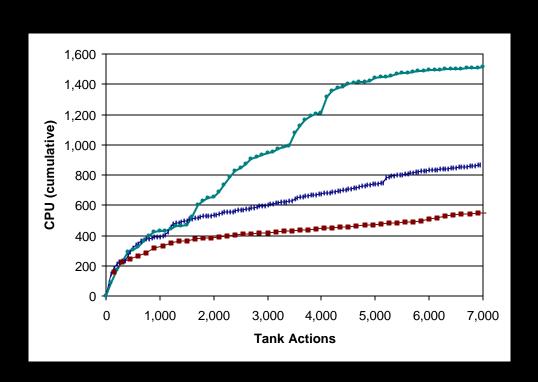


Chunks excised based on a 5,000DC gap between uses

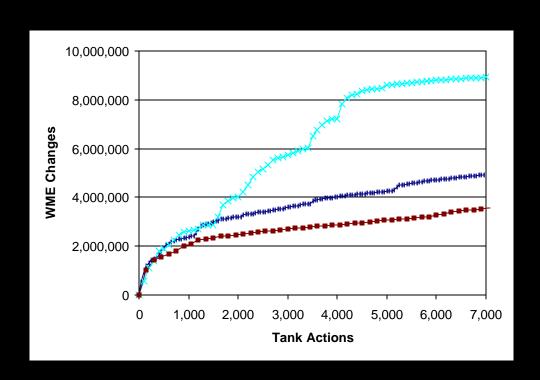


← Learning without excising

- ← Excising with 500DC gap
- ← Excising with 5,000DC gap



- ← Excising with 500DC gap
- Learning without excising
- ← Excising with 5,000DC gap



- ← Excising with 500DC gap
- Learning without excising
- ← Excising with 5,000DC gap

Implications for Soar and Soar as a "Computational Theory of Cognition"

- Consider allowing access to Soar's internal performance to support excising...
- Modify Allen Newell's definition of intelligence to include performance considerations with longterm memory . . .
- Implications for Cognitive Science . . .
- Comments? WKennedy@gmu.edu