A Graphical Memory Architecture

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Memory Architecture

- Nature of memories used w/in decision cycle
- Short-term/working and long-term memories
 - Soar 1-8: working memory + production memory
 - ACT-R: buffers + production memory, semantic memory
 - Soar 9: working memory, ST visual imagery + production memory, semantic memory, episodic memory, LT visual memory
- Focus here is on representation and access
 - Haven't yet got to learning





Goals

- Broadly functional memory architecture
 - Both procedural and declarative knowledge
 - Hybrid: Continuous/signal + discrete/symbolic
 - Mixed: Probabilistic/uncertain + discrete/symbolic
- Uniform implementation
- Provide core for development of full hybrid mixed architecture
 - Melding scope with simplicity and elegance





Approach

Base roughly on Soar 9 and ACT-R

- Working memory
- Procedural LT Memory
 - Productions
- Declarative LT Memory
 - Semantic: Predict unspecified attributes of objects based on specified ones (cues)
 - Episodic: Retrieve best episode based on recency and match to cues
- Eventually imagery as well, but not yet

Implement via graphical models

Layered approach: graph and memory layers





Graph Layer: Factor Graphs w/ Summary Product

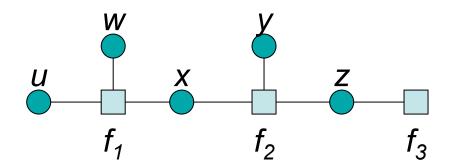
Factor graphs are undirected bipartite graphs

- Decompose functions: e.g., $f(u, w, x, y, z) = f_1(u, w, x) f_2(x, y, z) f_3(z)$
- Map to variable & factor nodes (with functions in factor nodes)

Summary product algorithm does message passing

- Compute values of variables (marginals) by sum-product
- Compute best overall (max. a posteriori) by max-product

Complete reimplementation from last year with improved functionality, generality, efficiency







Generalized Function/Message Representation

N dimensional continuous functions

Approximated as piecewise linear functions over rectilinear regions

Span (continuous) signals, (continuous and discrete) probability distributions, symbols

- Discretize domain for discrete distributions & symbolic
 - **•** [0,1>, [1,2>, [2,3>, ...
- Booleanize range (and add symbol table) for symbolic
 - E.g., [0,1>=1 → RED true; [1,2>=0 → GREEN false

y∖x	[0,10>	[10,25>	[25,50>
[0,5>	0	.2 <i>y</i>	0
[5,15>	.5 <i>x</i>	1	.1+.2 <i>x</i> +.4 <i>y</i>



Memory Layer: Distinguish WM and LTM

Representation is predicate based

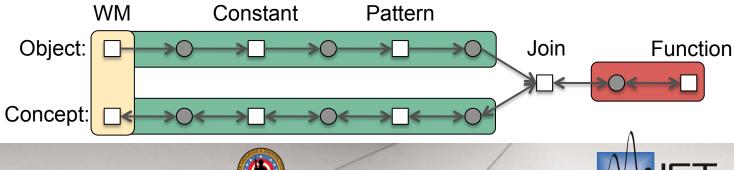
- E.g., Object(s, O1), Concept(O1, c)
- Arguments may be constants, or variables (in LTM)

Long-term memories compile into graphs

- LTM is composed of conditionals (generalized rules)
- Each conditional is a set of predicate patterns and a function

WM compiles into functions in peripheral factor nodes

 It is just an N dimensional continuous function where normal symbolic wmes correspond to unit regions with Boolean values



CONDITIONAL ConceptPrior

Condition: Object(s,01)
Condact: Concept(01,c)

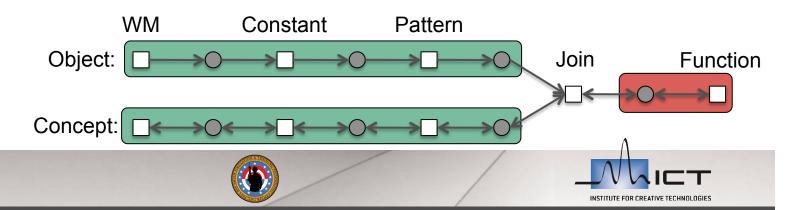
Walker	Table	Dog	g Human	
1	3	5	1	

Conditionals

USC

Patterns can be conditions, actions or condacts

- Conditions and actions embody normal rule semantics
 - Conditions: Messages flow from WM
 - Actions: Messages flow towards WM
- Condacts embody (bidirectional) constraint/probability semantics
 - Messages flow in both directions: local match + global influence
- Encoded as (generalized) linear alpha networks
- Pattern networks joined via bidirectional beta network
- Functions are defined over condact variables



Additional Details

- Link directionality is set independently for each link
 - Determines which messages are sent
- Whether to use sum or max is specified on an individual variable/node basis
 - Overall algorithm thus mixes sum-product and max-product
- Variables can be specified as unique or multiple
 - Unique variables sum to 1 and use sum for marginals: [.1 .5 .4]
 - Multiple variables can have any or all elements valued at 1 and use max for marginals: [1 1 0 0 1]
- Predicates can be declared as open world or closed world with respect to matching WM
- Pattern variables cause sharing of graph structure
 - May be within a single conditional or across multiple conditionals





Memories

Production Memory

- Just conditions and actions
 - Although may also have a function
- CWA and multiple variables

CONDITIONAL Transitive

Condition: Next(a,b)

Next(b,c)

Action: Next(a,c)

Semantic Memory

- Just condacts (in pure form)
- OWA and unique variables
- Naïve Bayes (prior on concept + conditionals on attributes)

CONDITIONAL ConceptWeight

Condact: Concept(01,c)[$\alpha 1$]

Weight(01, w)

CONDITIONAL ConceptPrior

Condition: Object(s,01)

Condact: Concept(01,c)[$\alpha 1$]

Walker	Table	Dog	Human
.1	.3	.5	.1

w\c	Walker	Table	
[1,10>	.01 <i>w</i>	.001 <i>w</i>	
[10,20>	.201 <i>w</i>	u	
[20,50>	0	.025 00025 <i>w</i>	
[50,100>	u	u	





Memories (cont.)

Episodic Memory

- Just condacts (in pure form)
- OWA and unique variables
- Exponential prior on time + conditionals on episode attributes

Conditional TimeConcept
Condact: Time(t)[$\alpha 3$]
Concept(01, c)

t \c	Walker	Table	Dog	Human
1	1	0	0	0
2	0	0	0	1
3	0	0	0	1
4	0	0	1	0

Constraint Memory

- Just condacts (in pure form)
- OWA and multiple variables

CONDITIONAL TwoColorConstraint12
Condact: Color(R1, c1)[α 7]
Color(R2, c2)[α 8]

c1\c2	Red	Blue
Red	0	1
Blue	1	0

CONDITIONAL TimePrior
Condact: Time(t)[$\alpha 3$]

0	1	2	3	4
0	.032	.087	.237	.644





Key Similarities and Differences

Similarities

- All based on WM and LTM
- All LTM based on conditionals
- All conditionals map to graph
- Processing by summary product

Is analogy vs. generalization driven by max vs. sum over instance-based memory?

Differences

- Procedural vs. declarative
 - Conditions/actions vs. condacts
 - Directionality of message flow
 - Closed vs. open world
 - Multiple vs. unique variables
- Semantic vs. episodic
 - Marginal/sum vs. MAP/max
 - Condition on concept vs. time
 - General probs. vs. instances

Constraints are actually hybrid: condacts, OWA, multiple Other variations and hybrids are also possible





Summary

Gold

- Uniform implementation of four distinct LTMs
- Reveals subtle underlying differences among the LTMs
- An important step towards a full hybrid mixed architecture
 - Working on decisions
 - Then subgoaling & learning
 - Proposal on imagery
 - Leverage continuous functions at core and known facility of graphical models for perception

Coal

- Subtle incompatibilities imply less uniformity in details
 - They have also proven quite difficult to resolve cleanly
- Progress can be slow & difficult
 - With occasional bursts of insight
- Not full memory implementations
 - And no learning
- Still far from full architecture
 - And from showing that there is a significant functional gain from this approach



