

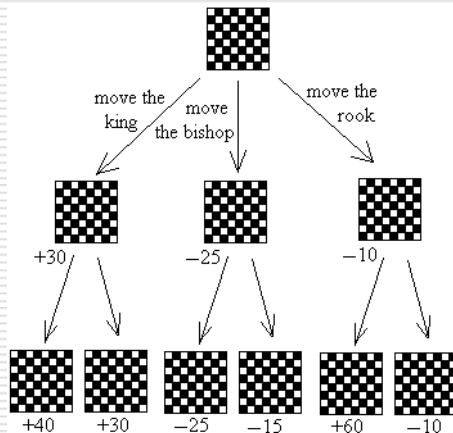
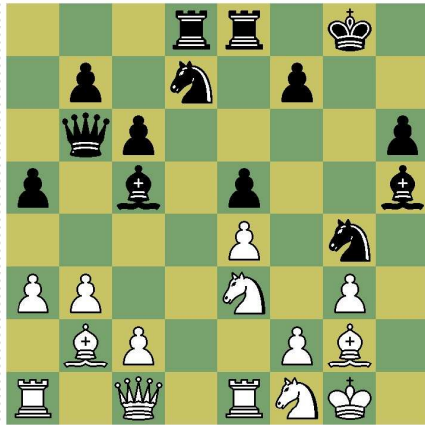
ORTS: A Case Study of Multi-Tasking in Soar

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Soar Workshop 2006

Outline

1. Motivation for studying Real Time Strategy games
2. ORTS and AIIDE competition
3. SORTS Design
4. Multi-tasking in SORTS
5. Progress & Conclusions

Traditional Games in AI



- ❑ Discrete time/actions
- ❑ Perfect information
 - ↪ Enumerable states
- ❑ Low perceptual/motor load
- ❑ Examples:
 - Chess
 - Towers of Hanoi
 - Water Jug

Real-Time Strategy Games



- ☐ Played in real time
- ☐ Maintain an economy
- ☐ Develop production capabilities via cities/bases
- ☐ Defend against enemy attacks
- ☐ Launch attacks against enemies
- ☐ Examples:
 - Starcraft
 - Command & Conquer

Real-Time Strategy Games



- ❑ Continuous time/space/actions
- ❑ Imperfect information
 - ↪ State space not practically enumerable
- ❑ High perceptual/motor load

Challenges

	Which game stresses this more?	What's better at this (presently)?
Look-ahead	Chess	Computer
Opponent modeling	Chess	Human
State abstraction	RTS	Human
Spatial/Temporal reasoning	RTS	Human
Manage perceptual overloading	RTS	Human
Multi-faceted gameplay	RTS	Computer
Divided Attention	RTS	Computer

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Open Real Time Strategy



- ☐ Open source RTS implementation
- ☐ Designed specifically for AI research
- ☐ Completely customizable via scripts
- ☐ C++ API
 - receive information about state of the world from server
 - Send commands to server
- ☐ Under active development at University of Alberta

AI Competition at AIIDE 06



- ☐ Game 1 – Resource gathering
- ☐ Game 2 – Offense and Defense
- ☐ Game 3 – Full RTS game

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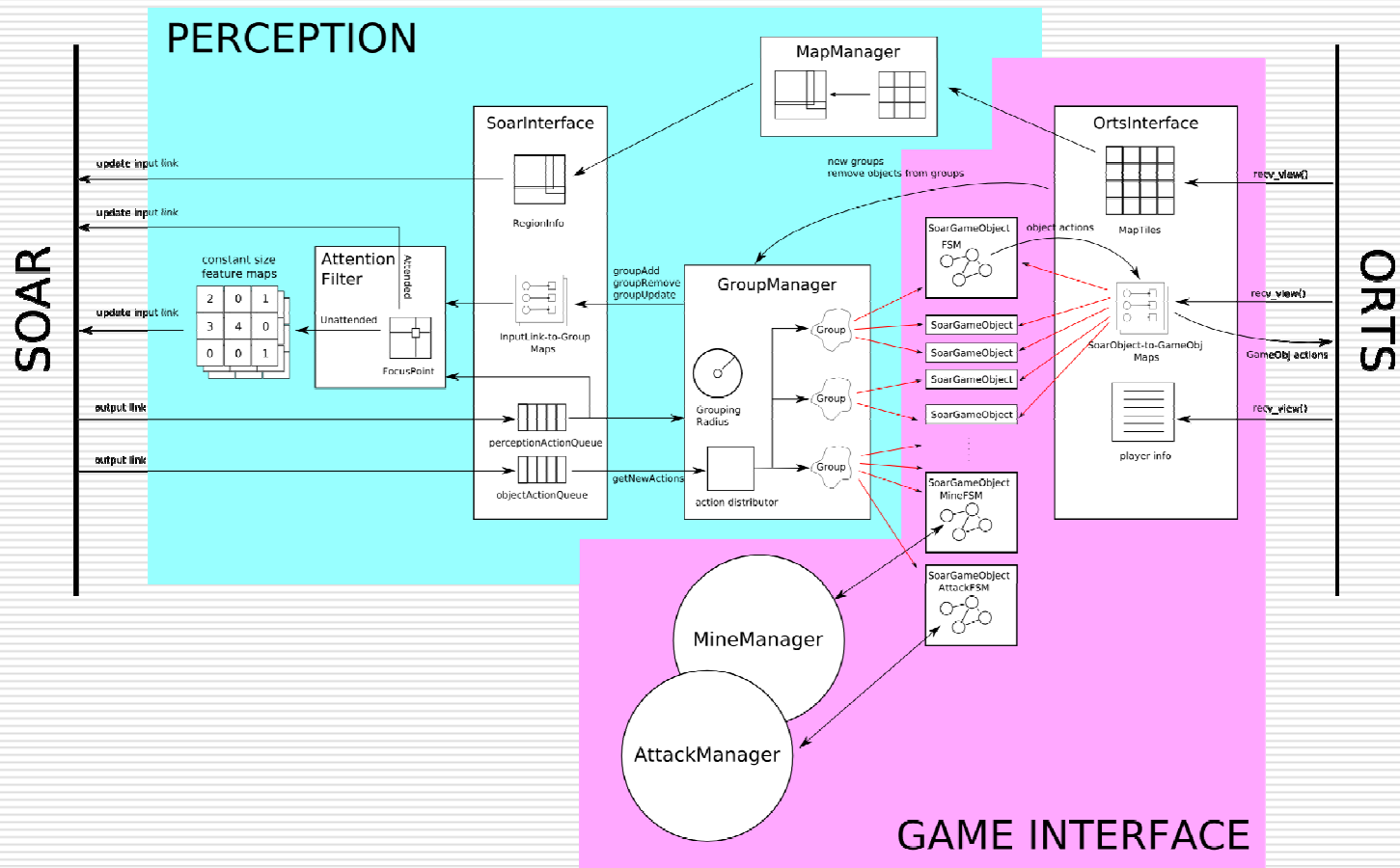
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Our Approach: SORTS

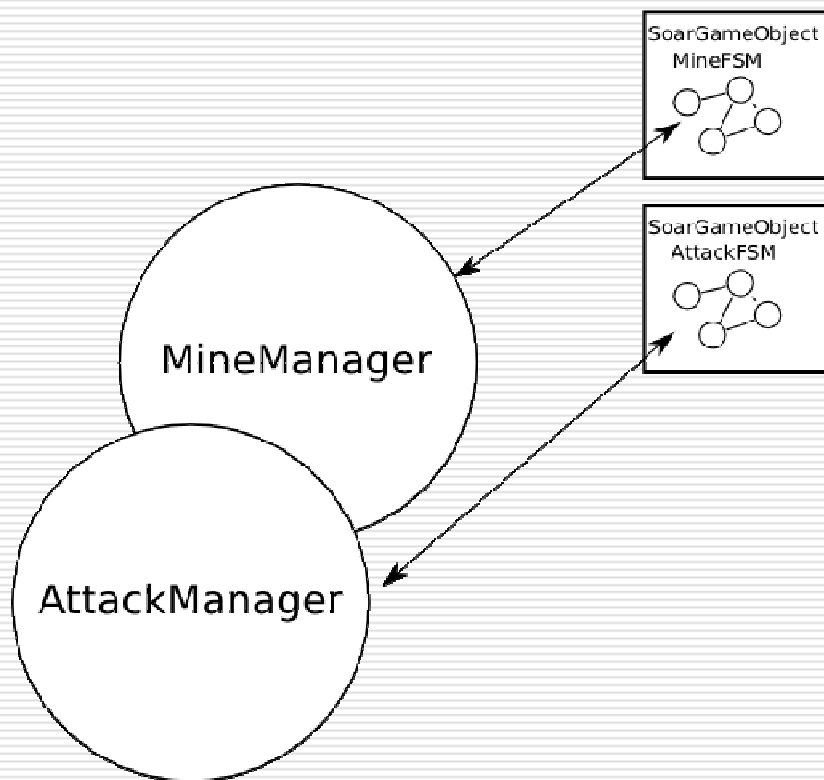


- ❑ Create a Soar agent to play ORTS
- ❑ Middleware serves as both Soar's perceptual system as well as a gaming interface
 - Like a real game interface, the middleware handles micromanagement such as pathfinding and default unit behaviors

SORTS Architecture



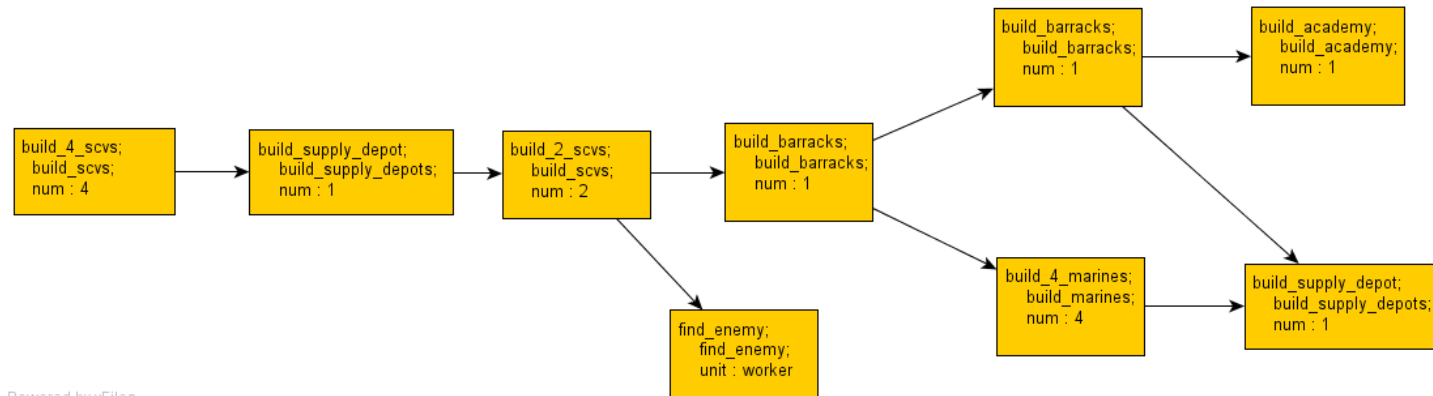
Low Level Control



- ❑ Each unit controlled by finite state machines
- ❑ Soar agent doesn't have to micromanage
- ❑ MineManager and AttackManager necessary for finer control in competition

Soar Agent Preliminary Design

- ❑ Three ways of acting
 - Static plans
 - ❑ Defined ahead of time, like the opening book in chess
 - ❑ Partial Order Plans



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Soar Agent Preliminary Design

- Three ways of acting
 - Opportunistic plans
 - Plans that the agent comes up with while playing the game
 - Backward chaining
 - Example: I need to build anti-air defenses to counter enemy fighters, but to do that I need to build a factory first

Soar Agent Preliminary Design

- Three ways of acting
 - Reactions
 - Reactions to the current state that can occur at any time
 - Example: I can't win this battle, retreat with remaining forces

Soar Agent Preliminary Design

□ Situation Awareness

- Soar agent can only “see” a limited area of game field at any time
- Agent must make decisions that account for unseen parts of the game field too
- Must maintain situation awareness by memorizing important things going on at different parts of the map



Division of Responsibilities

☐ Soar handles

- State abstraction
- Planning
- High level commands
- Multi-tasking

☐ MW handles

- Visual abstraction
- Command implementation
- Default unit behaviors
- “Uninteresting” strategies
 - ☐ Mining
 - ☐ Micromanage attacks

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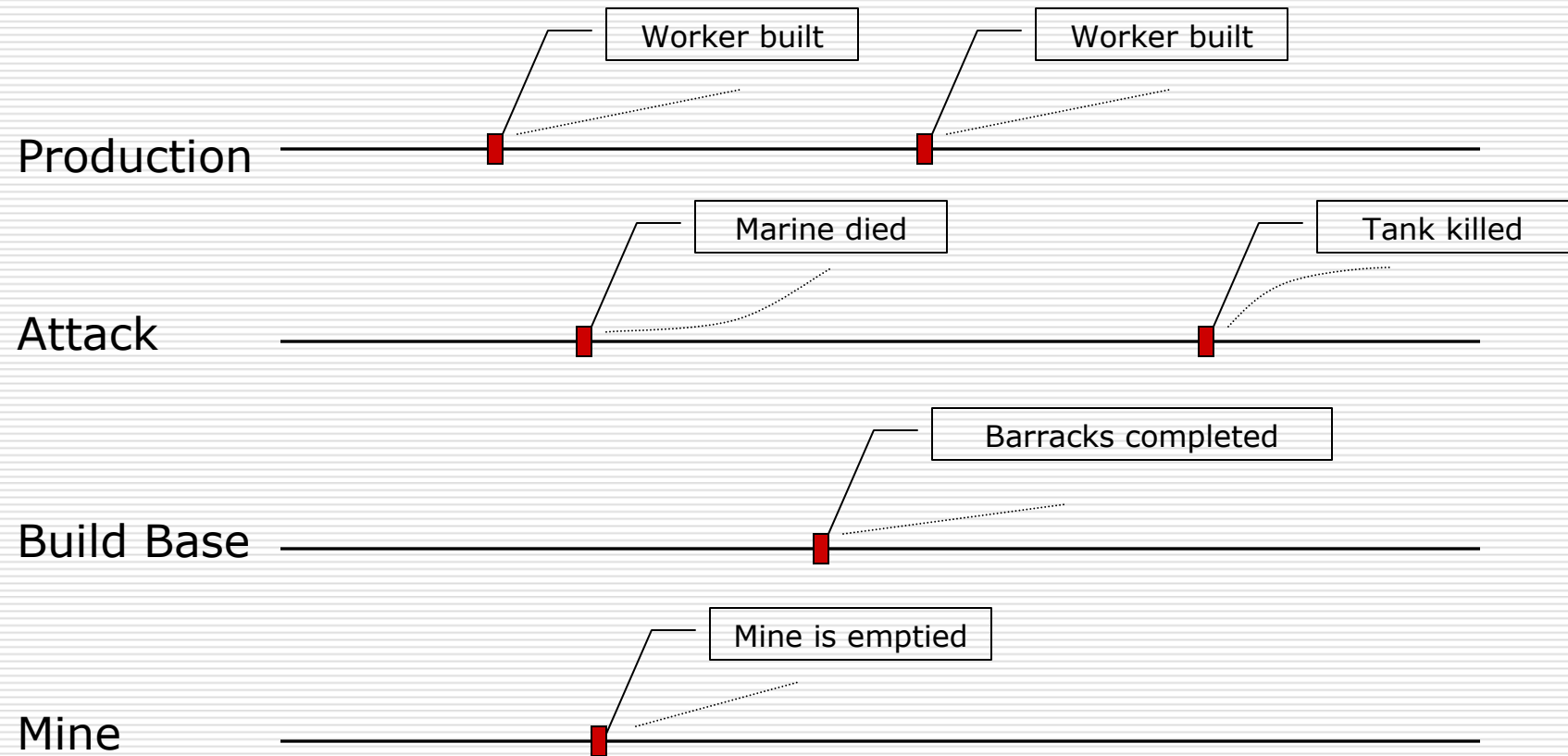
Multi-tasking

- RTS games typically require player to manage many simultaneous tasks
 - Tasks are attentionally and cognitively far apart
 - Hence there is a cost in switching between tasks
 - Attention tunneling is usually detrimental

Channel Model Approach

- Group actions taken over the entire game into tasks
 - How to group is not yet finalized
 - Follow human tendency
- Each task is a *channel*
 - The agent performs some action on the channel then waits for feedback in the form of *Events*
 - Arrival times of events are not known
 - There is a cost incurred that is a function of the amount of time an event remains on a channel unprocessed

Channel Model



Task Switching

- ❑ The agent builds an internal model of expected event arrival times on each channel
- ❑ Accuracy of the model distinguishes novice and expert players
- ❑ Environmental cues help to determine when to switch
- ❑ Top-down and bottom-up control

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Progress

☐ What is implemented

- Perceptual system
- Command system (Game Interface)
- Low level FSMs
- Planning

☐ What has to be implemented

- Real Soar agents
- Situation awareness

Progress

☐ Competition

- Game 1 – 80%
- Game 2 – 30%
- Game 3 – 30%

Conclusions

- ❑ RTS games present a set of challenges to AI research that chess does not
- ❑ We are building SORTS to try to meet some of these challenges
- ❑ SORTS will make a good platform on which to test the new Soar architecture

Conclusions

☐ Nuggets

- Provides a rich environment to test many of Soar's new capabilities
- Forced us to confront issues that would not have come up in other environments / architectures

☐ Coals

- Still in pre-alpha stage
- Some decisions were made in the interest of competition performance rather than psychological plausibility
- Abuses working memory