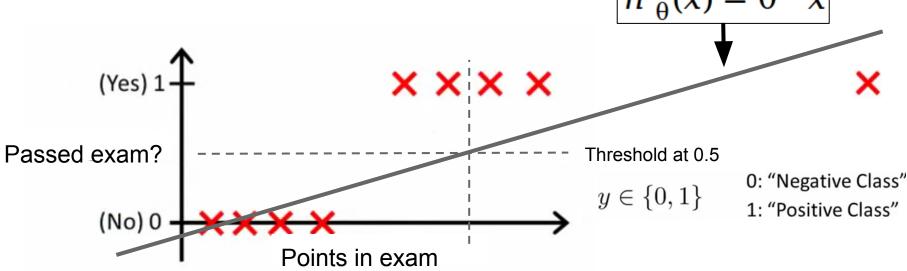
IMPRO3

Logistic Regression 30.04.2014

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Motivation

- Logistic Regression is for **Classification**
- Typically binary classification
 - Is this mail spam?
 - Did he/she pass the exam? $h_{\Theta}(x) =$

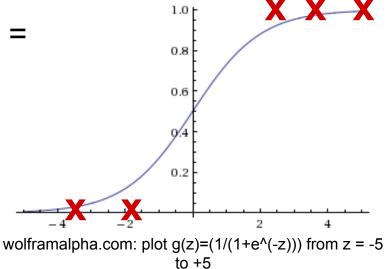


- $h_{\theta}(x) < 0$ and $h_{\theta}(x) > 1$ are possible In example:
- $0 \le h_{\theta}(x) \le 1$ With Logistic Regression:

Hypothesis and Cost Representation

$$g(z) = \frac{1}{1+e^{-z}} \quad \text{with } h_{\theta}(x) = g(\theta^T x)$$

$$\Rightarrow h_{\theta}(x) = \frac{1}{1+e^{-\theta^T x}}$$



$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} Cost(h_{\theta}(x^{(i)}), y^{(i)}) \quad Cost(h_{\theta}(x), y) = \begin{cases} -log(h_{\theta}(x)) & \text{if } y = 1 \\ -log(1 - h_{\theta}(x)) & \text{if } y = 0 \end{cases}$$

- => We want to minimize cost J
- => Gradient Descent, repeat:

$$\theta_j = \theta_j - \alpha \frac{\Delta J(\theta)}{\Delta \theta_j} with \ \frac{\Delta J(\theta)}{\Delta \theta_j} = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

Pseudocode

```
X = [m, n] // training set of features
y = [m] // vector of classification
alpha = 1 // learning rate
theta = [n] -> all 0
Gradient descent:
for 1:number_iterations
  for i = 1:n
    grad(i) = 0; derivative of cost function
    for j = 1:m
                                                                    Very naive way,
      grad(i) += (sigmoid(X(j,:)*theta)-y(j))*X(j,i));
                                                                    can be vectorized
    end
                            h(x)
    grad(i) = grad(i)/m;
  end
  theta = theta - alpha * grad;
end
```

Stochastic Gradient Descent (for large training sets)

```
X = [m, n] // training set of features
y = [m] // vector of classification
alpha = 1 // learning rate
theta = [n] -> all 0
```

Stochastic Gradient Descent:

```
Randomly_Shuffle_Training_Set(X,y) repeat until theta converges
```

```
for j = 1:m

for i = 1:n

grad(i) = (sigmoid(X(j,:)*theta)-y(j))*X(j,i));

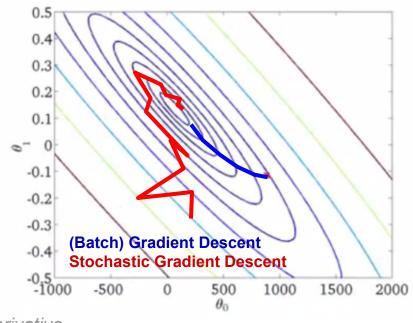
end

theta = theta - alpha * grad;

end

h(x)

set a lit
```



=> make progress in each iteration (modify the parameters to fit the training set a little bit better)

=> generally, move the parameters in the direction of the global minimum

end