



## Extensions to IES, Mappings and Use Cases

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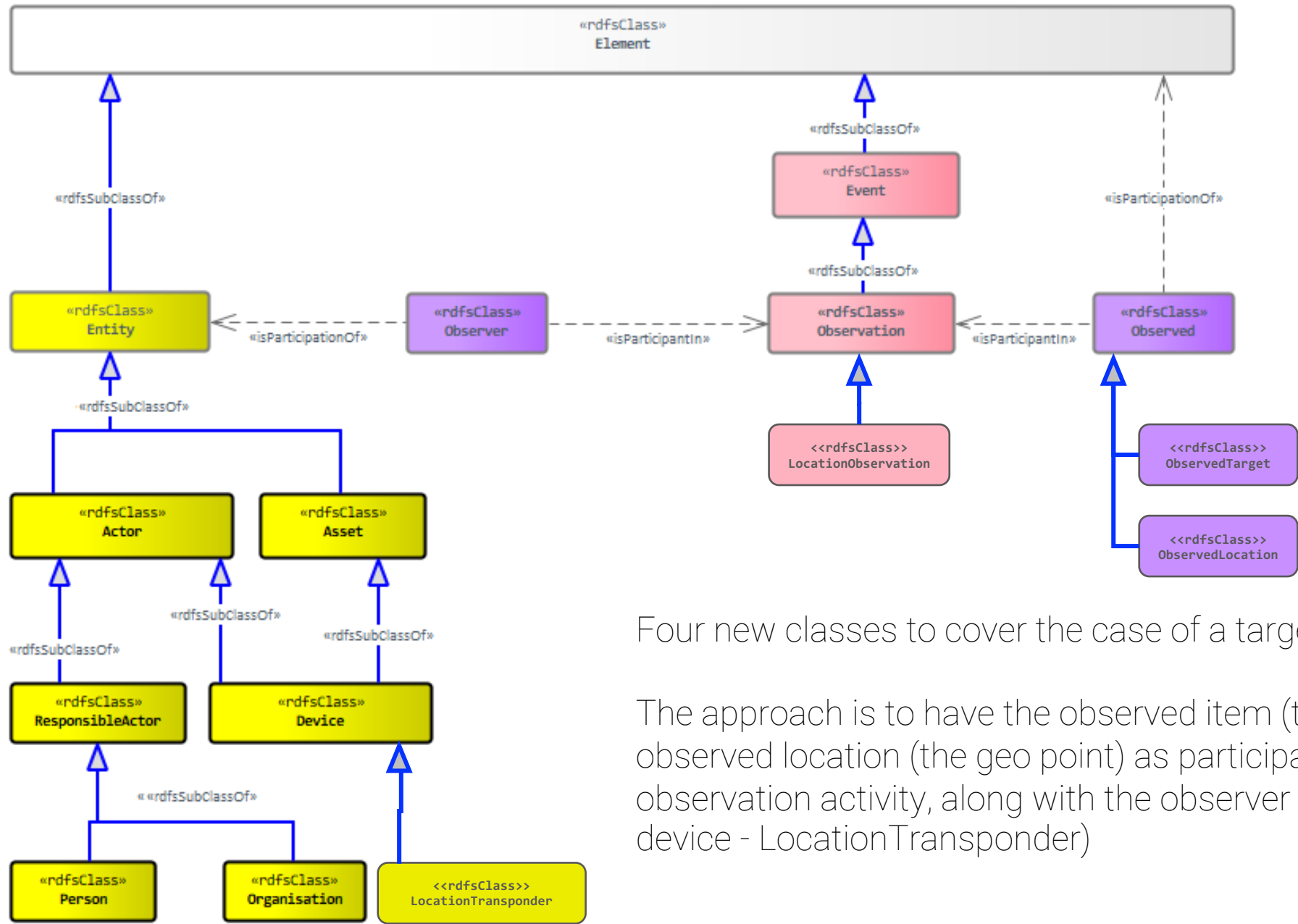
## Stage 1 – Track Data

We have built a simple track provider that accumulates AIS data until it hits a user-defined threshold of data points per vessel then it pushes out an IES message containing the track information for that vessel onto the Kafka log. Users can set the throughput rate and track size as environment variables that are provided to the container (Docker).

Data is in n-triples format, zipped before being put onto Kafka. At the request of Canada, heading, course and vessel / activity type data has not been mapped (they plan to calculate it).

The slides that follow show the necessary additions to IES that were needed (LocationObservation and LocationTransponder)

# Extensions to IES for Tracks



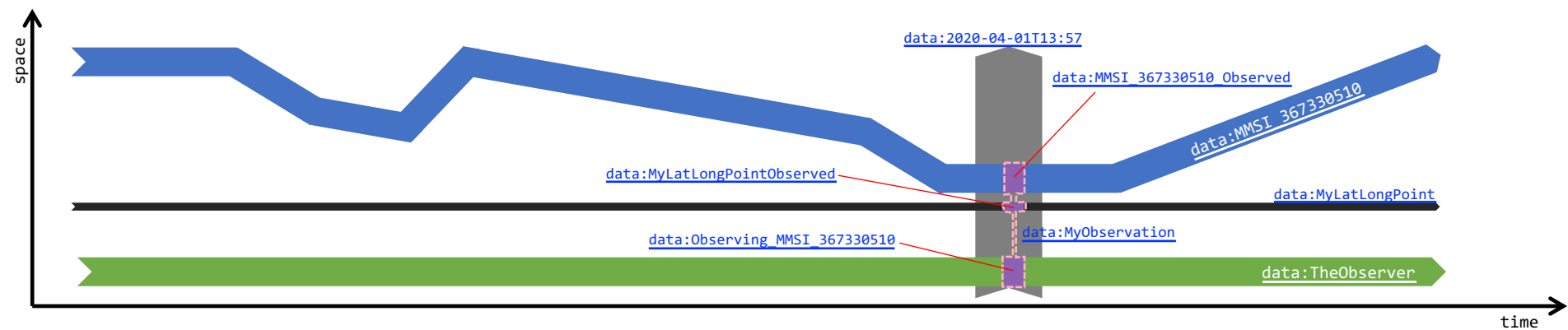
Four new classes to cover the case of a target's location.

The approach is to have the observed item (the vessel) and the observed location (the geo point) as participants in the observation activity, along with the observer (the AIS receiver, a device - LocationTransponder)

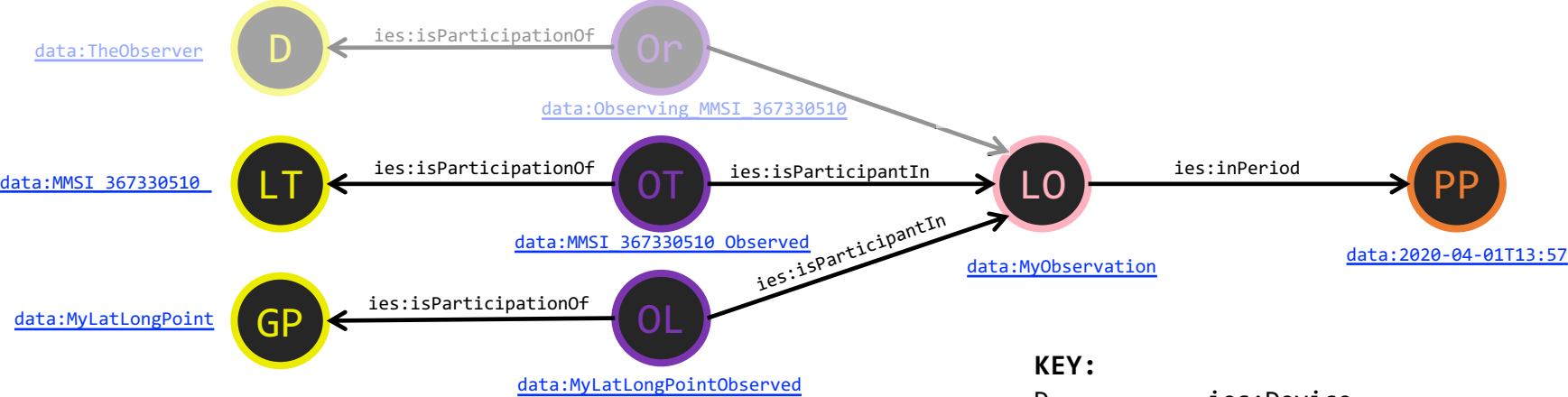
# RDF Schema for Track Extensions

@prefix	ies:	<http://ies.data.gov.uk/ontology/ies4#> .
@prefix	rdf:	<http://www.w3.org/1999/02/22-rdf-syntax-ns#> .
@prefix	rdfs:	<http://www.w3.org/2000/01/rdf-schema#> .
ies:LocationTransponder	rdf:type	rdfs:Class .
ies:LocationTransponder	rdfs:subClassOf	ies:CommunicationsDevice .
ies:LocationObservation	rdf:type	rdfs:Class .
ies:LocationObservation	rdfs:subClassOf	ies:Observation .
ies:ObservedLocation	rdf:type	rdfs:Class .
ies:ObservedLocation	rdfs:subClassOf	ies:Observed .
ies:ObservedTarget	rdf:type	rdfs:Class .
ies:ObservedTarget	rdfs:subClassOf	ies:Observed .

Example: Ship observed at location on 1<sup>st</sup> April at 1:57pm



Observer not known in the case of openly available AIS source data



**Namespaces:**

@prefix rdf: <http://www.w3.org/1999/02/22-rdf-syntax-ns#> .  
@prefix rdfs: <http://www.w3.org/2000/01/rdf-schema#> .  
@prefix ies: <http://ies.data.gov.uk/ies4#> .  
@prefix data: <http://data.gov.uk/testdata#> .

KEY:	
D	ies:Device
GP	ies:GeoPoint
LO	ies:LocationObservation
OL	ies:ObservedLocation
OT	ies:ObservedTarget
Or	ies:Observer
PP	ies:ParticularPeriod
LT	ies:LocationTransponder (new addition to model)

# Example Track Data (in RDF Turtle)

```
@prefix data: <http://ais.data.gov.uk/ais-ies-test#> .
@prefix ies: <http://ies.data.gov.uk/ontology/ies4#> .

#Boilerplate stuff - setting the naming schemes used in the data, and the owners of those schemes. This could be put in a separate RDF file and
referenced if need be
<http://imo.org> a ies:Organisation ;
ies:hasName data:96fbe176-74a3-4dd8-ac76-ade4c3d3d1 .
data:96fbe176-74a3-4dd8-ac76-ade4c3d3d1 a ies:OrganisationName ;
ies:representationValue "International Maritime Organisation" .
<http://imo.org#imo-NamingScheme> a ies:NamingScheme ;
ies:schemeOwner <http://imo.org> .
<http://itu.int> a ies:Organisation ;
ies:hasName data:23a814e7-4859-48d9-a91d-14218198bb70 .
data:23a814e7-4859-48d9-a91d-14218198bb70 a ies:OrganisationName ;
ies:representationValue "International Telecommunications Union" .
<http://itu.int#msi-NamingScheme> a ies:NamingScheme ;
ies:schemeOwner <http://itu.int> .

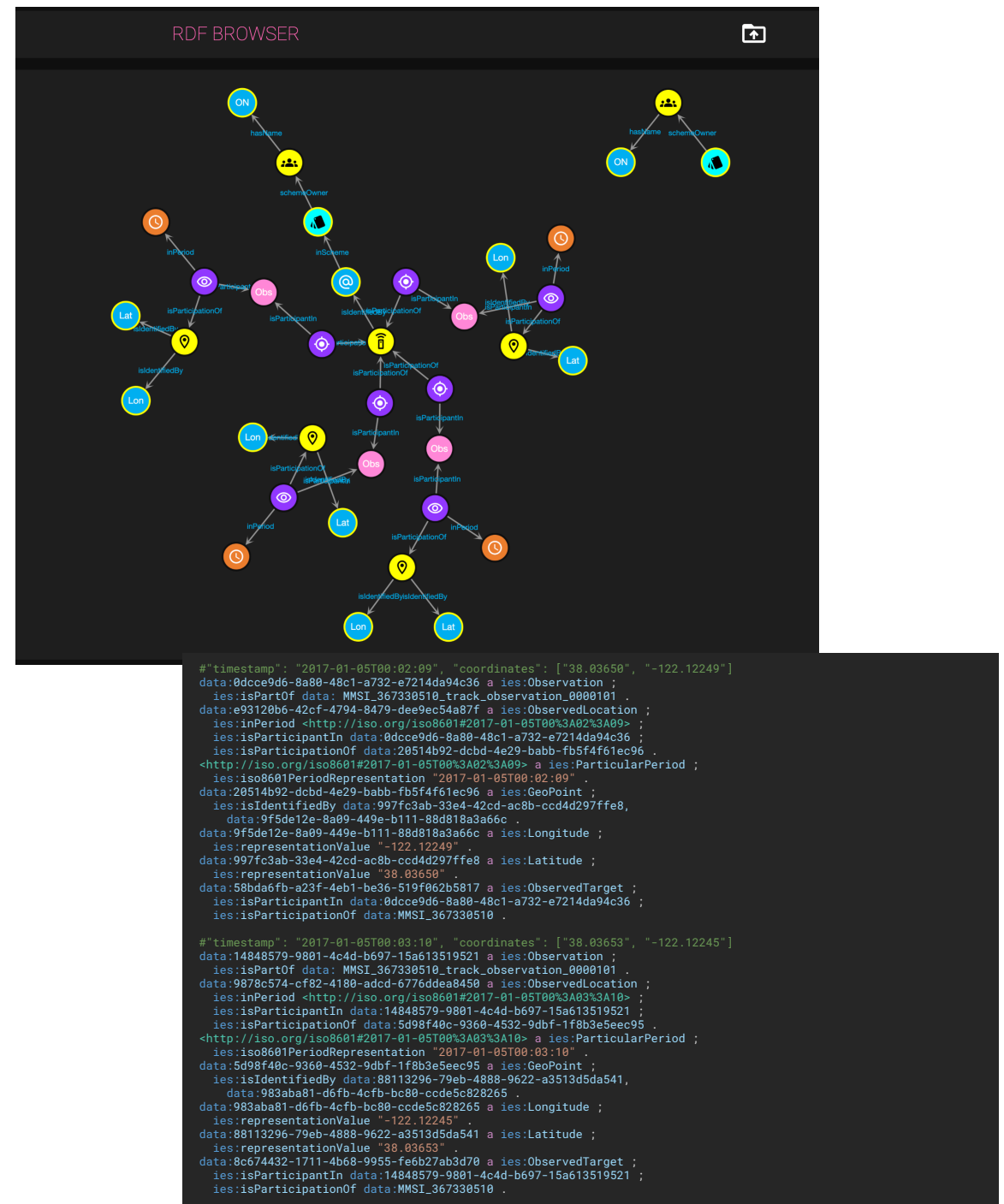
#The transponder - note, LocationTransponder was added as a new class to the IES ontology for the purposes of MIKES
data:MMSI_367330510 a ies:LocationTransponder ;
ies:isIdentifiedBy data:7f79de9e-1307-4a8a-969a-ff683864868a .
data:7f79de9e-1307-4a8a-969a-ff683864868a a ies:CommunicationsIdentifier ;
ies:inScheme <http://itu.int#msi-NamingScheme> ;
ies:representationValue "367330510" .

#The overarching track observation (each individual LocationObservation is part of this)
data: MMSI_367330510_track_observation_0000101 a ies:Observation .

#Now the observations - note this is just using simple lat and long points from IES. We have not tried to use the EPSG stuff yet as lat and
long are already covered in the model.

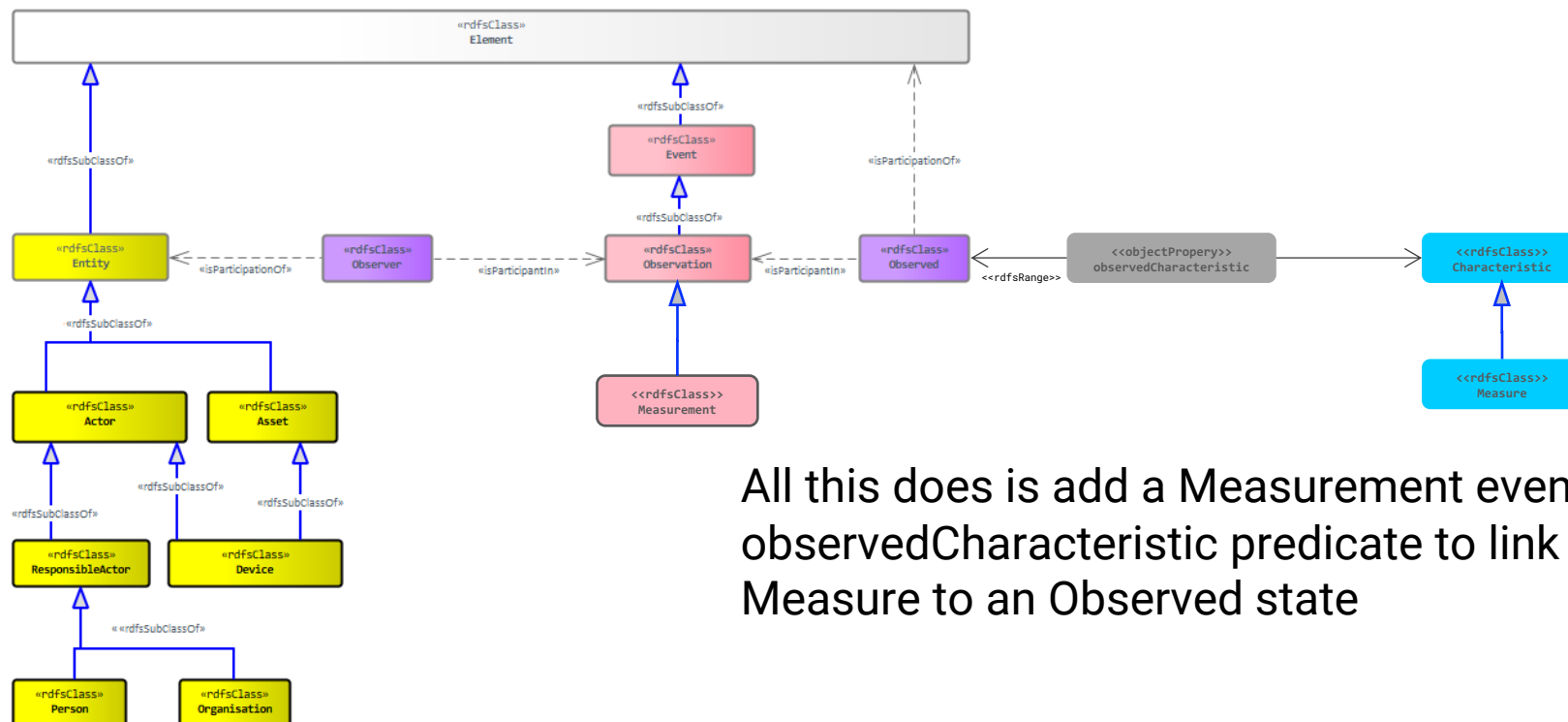
#"timestamp": "2017-01-05T00:00:00", "coordinates": ["38.03654", "-122.12249"]
data:1d867d78-b763-495e-81d3-18ca7ff23d62 a ies:LocationObservation ;
ies:isPartOf data: MMSI_367330510_track_observation_0000101 .
data:cbf8c7bf-ee6f-4089-af6d-d4b7f5043f7a a ies:ObservedLocation ;
ies:inPeriod <http://iso.org/iso8601#2017-01-05T00%3A00%3A00> ;
ies:isParticipantIn data:1d867d78-b763-495e-81d3-18ca7ff23d62 ;
ies:isParticipationOf data:2953e2a9-5197-4508-87ad-7e96901a9dc3 .
<http://iso.org/iso8601#2017-01-05T00%3A00%3A00> a ies:ParticularPeriod ;
ies:iso8601PeriodRepresentation "2017-01-05T00:00:00" .
data:2953e2a9-5197-4508-87ad-7e96901a9dc3 a ies:GeoPoint ;
ies:isIdentifiedBy data:170a29fb-ba21-4d8a-9dbe-5ece6ee8b741,
data:5f48dd15-c79e-4bd6-8857-4e5d38fa9a34 .
data:5f48dd15-c79e-4bd6-8857-4e5d38fa9a34 a ies:Longitude ;
ies:representationValue "-122.12249" .
data:170a29fb-ba21-4d8a-9dbe-5ece6ee8b741 a ies:Latitude ;
ies:representationValue "38.03654" .
data:131f4043-067b-47ad-9ef6-7983dc0689de a ies:ObservedTarget ;
ies:isParticipantIn data:1d867d78-b763-495e-81d3-18ca7ff23d62 ;
ies:isParticipationOf data:MMSI_367330510 .

#"timestamp": "2017-01-05T00:01:08", "coordinates": ["38.03654", "-122.12250"]
data:cdbb5fa7-1d38-4722-a10c-05635d31ab23 a ies:Observation ;
ies:isPartOf data: MMSI_367330510_track_observation_0000101 .
data:6ea333b2-0818-45fc-934d-58767cbc5e2e a ies:ObservedLocation ;
ies:inPeriod <http://iso.org/iso8601#2017-01-05T00%3A01%3A08> ;
ies:isParticipantIn data:cdbb5fa7-1d38-4722-a10c-05635d31ab23 ;
ies:isParticipationOf data:dab518fd-46b0-4064-8039-c407637b6b0d .
<http://iso.org/iso8601#2017-01-05T00%3A01%3A08> a ies:ParticularPeriod ;
ies:iso8601PeriodRepresentation "2017-01-05T00:01:08" .
data:dab518fd-46b0-4064-8039-c407637b6b0d a ies:GeoPoint ;
ies:isIdentifiedBy data:53a426bb-04da-421b-8934-3b562dec25a7,
data:f32165d4-e134-402c-8646-4f684dbf70b8 .
data:53a426bb-04da-421b-8934-3b562dec25a7 a ies:Longitude ;
ies:representationValue "-122.12250" .
data:f32165d4-e134-402c-8646-4f684dbf70b8 a ies:Latitude ;
ies:representationValue "38.03654" .
data:5d6457cb-df4d-4def-a3f2-9529efe0e982 a ies:ObservedTarget ;
ies:isParticipantIn data:cdbb5fa7-1d38-4722-a10c-05635d31ab23 ;
ies:isParticipationOf data:MMSI_367330510 .
```



## Observation of measures / characteristics

DRAFT – Not Approved by Dstl Yet



All this does is add a Measurement event class and an observedCharacteristic predicate to link a characteristic or Measure to an Observed state

# Course over Ground, Speed over Ground

DRAFT – Not Approved by Dstl Yet

Addition of ClassOfMeasure powertype allows for new measures to be added without having to use subtype in your data. In the case of course and speed, there is no need to add them to the model (unless someone decides they need to be standard measures). Example would be:

<degreesNorth>  
<course>

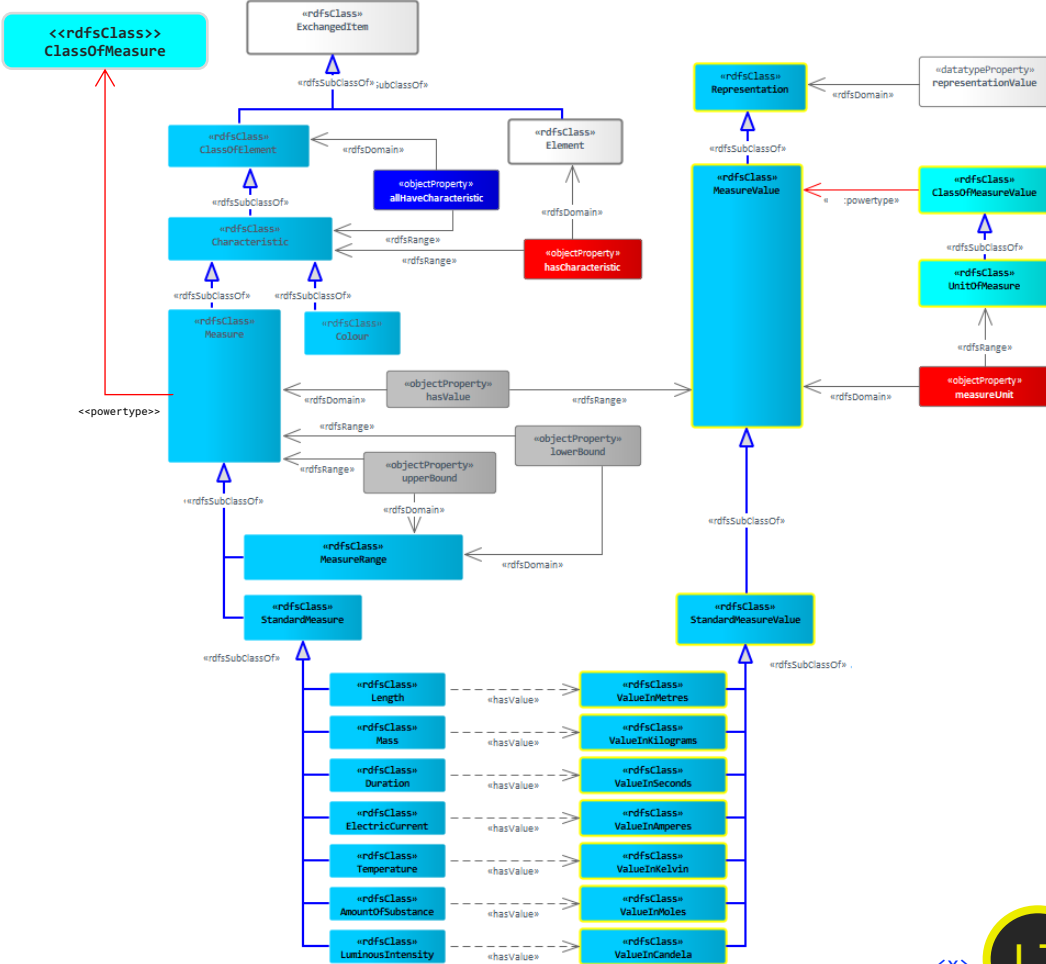
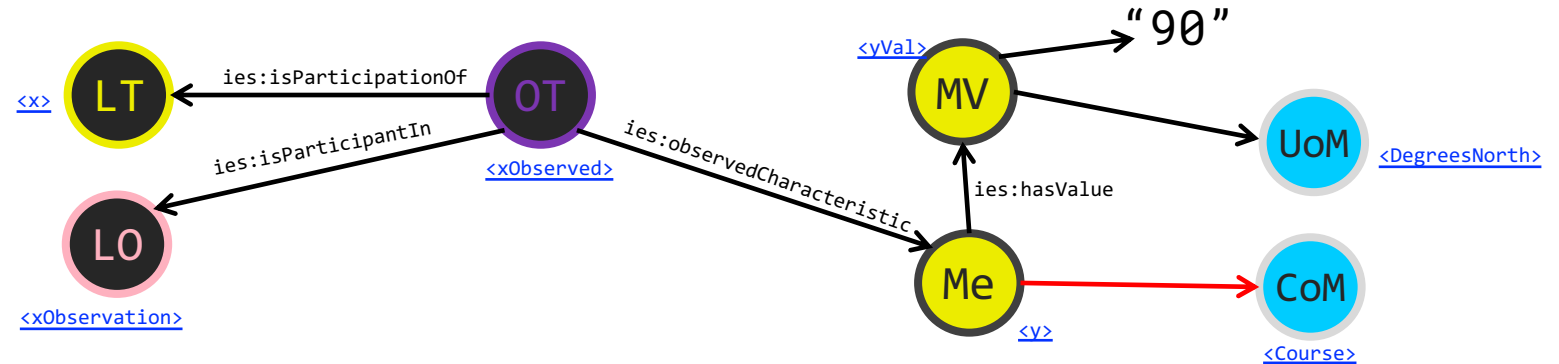
rdf:type  
rdf:type

ies:UnitOfMeasure .  
ies:ClassOfMeasure .

<x>  
<x0bserved>  
<x0bserved>  
<x0bserved>  
<x0bserved>  
<y>  
<y>  
<yVal>  
<yVal>  
<yVal>

rdf:type  
rdf:type  
ies:isParticipationOf  
ies:isParticipationIn  
ies:observedCharacteristic  
rdf:type  
ies:hasValue  
rdf:type  
ies:representationValue  
ies:measureUnit

ies:LocationTransponder .  
ies:ObservedTarget .  
<x> .  
<x0bservation>  
<y> .  
<course> .  
<yVal> .  
ies:MeasureValue .  
"90" .  
<degNorth> .





## Alternate Coordinate Systems – using EPSG codes

DRAFT – Not Approved by Dstl Yet

Some of the track analytics apps use varying coordinate systems. EPSG has categorised a huge number of these coordinate systems and mapped them onto between 2 and 4 parameters, so we are proposing to capture this in IES.

```
@prefix      ies:
@prefix      rdf:
@prefix      rdfs:
```

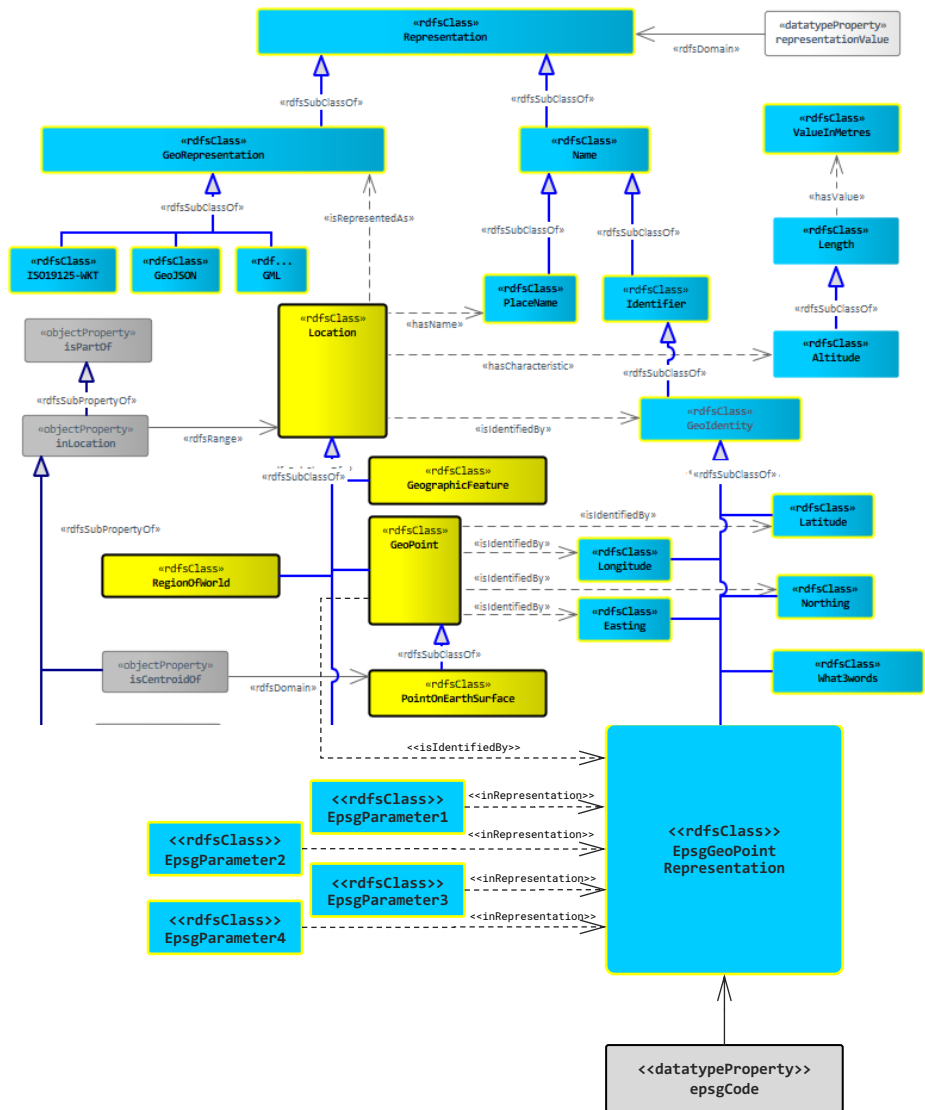
```
<http://ies.data.gov.uk/ontology/ies4#> .
<http://www.w3.org/1999/02/22-rdf-syntax-ns#> .
<http://www.w3.org/2000/01/rdf-schema#> .
```

```
ies:EpsgGeoPointRepresentation
ies:LocationTransponder
ies:epsgCode
ies:epsgCode
ies:epsgCode
ies:EpsgParameter1
ies:EpsgParameter1
ies:EpsgParameter2
ies:EpsgParameter2
ies:EpsgParameter3
ies:EpsgParameter3
ies:EpsgParameter4
ies:EpsgParameter4
```

```

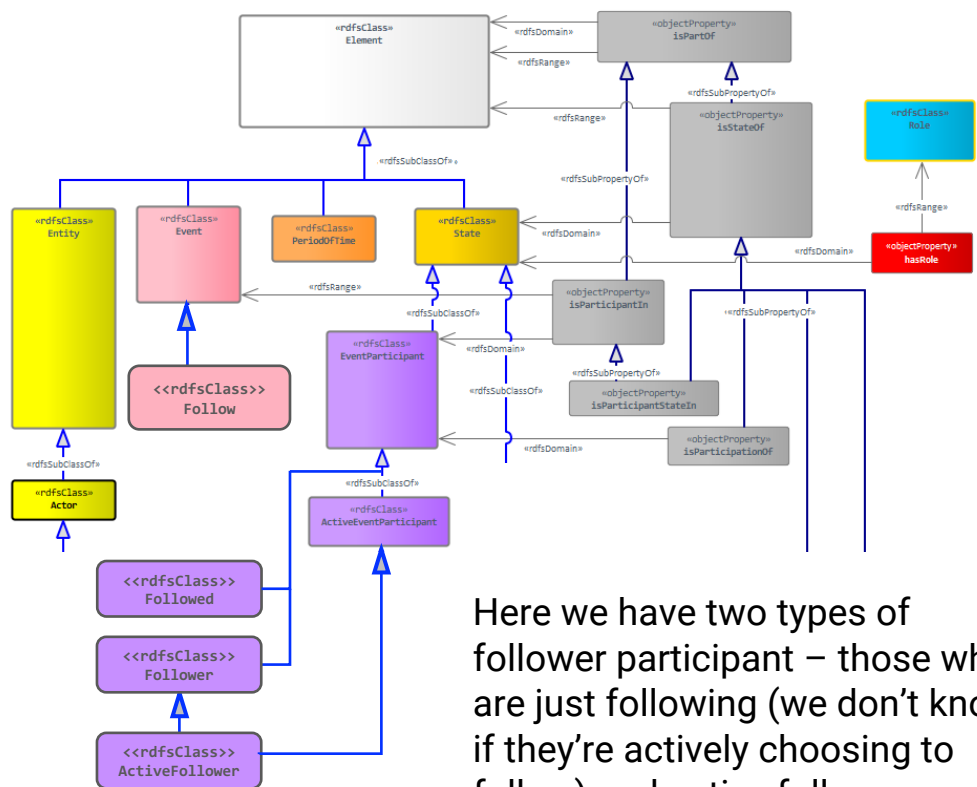
rdf:type                rdfs:Class .
rdfs:subClassOf         ies:GeoIdentity .
rdf:type                owl:datatypeProperty .
rdfs:subPropertyOf     ies:attribute .
rdfs:domain            ies:EpsgGeoPointRepresentation .
rdf:type                rdfs:Class .
rdfs:subClassOf         ies:Representation .
rdf:type                rdfs:Class .
rdfs:subClassOf         ies:Representation .
rdf:type                rdfs:Class .
rdfs:subClassOf         ies:Representation .
rdf:type                rdfs:Class .
rdfs:subClassOf         ies:Representation .

```

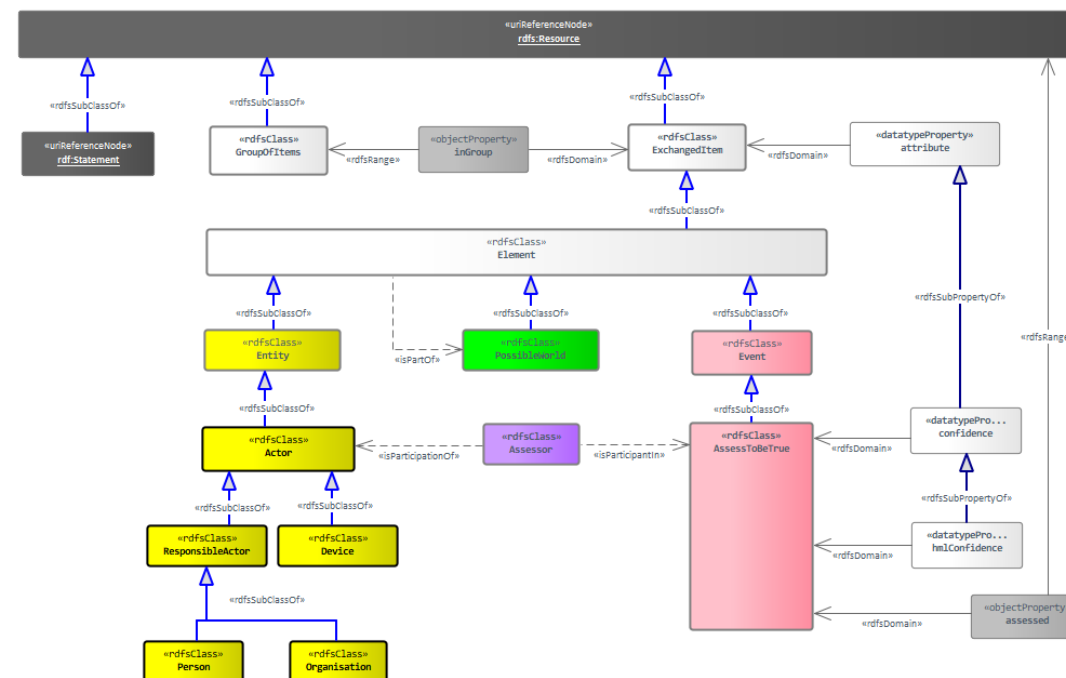


## Extensions to IES for “following”

In this approach, we simply use what's already in IES, with the only required extensions are to create a Following event, and the necessary EventParticipant roles for the follower and the followed.



Here we have two types of follower participant – those who are just following (we don't know if they're actively choosing to follow) and active follower.



The possible worlds model does not need to change, and we can use it in the usual IES fashion with AssessToBeTrue. The Assessor could then be a System (e.g. Odysseus, Wisdom)

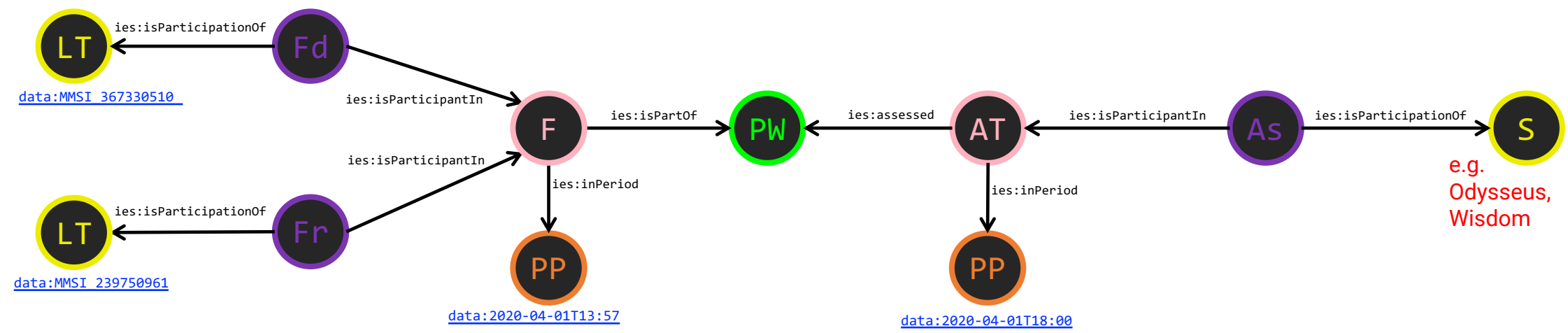
The confidence could be expressed using the UK Govt PHIA Probability Yardstick -  
<https://www.app.college.police.uk/app-content/intelligence-management/analysis/delivering-effective-analysis/>

Probably also need to add AssessToBeFalse (again with the same confidence criteria).

# RDF Schema for “Following” Use-Case Extensions

@prefix	ies:	<http://ies.data.gov.uk/ontology/ies4#> .
@prefix	rdf:	<http://www.w3.org/1999/02/22-rdf-syntax-ns#> .
@prefix	rdfs:	<http://www.w3.org/2000/01/rdf-schema#> .
ies:Follow	rdf:type	rdfs:Class .
ies:Follow	rdfs:subClassOf	ies:Event .
ies:Followed	rdf:type	rdfs:Class .
ies:Followed	rdfs:subClassOf	ies:EventParticipant .
ies:Follower	rdf:type	rdfs:Class .
ies:Follower	rdfs:subClassOf	ies:EventParticipant .
ies:ActiveFollower	rdf:type	rdfs:Class .
ies:ActiveFollower	rdfs:subClassOf	ies:Follower .
ies:ActiveFollower	rdfs:subClassOf	ies:ActiveEventParticipant .

# Option One Example – A following B



Note time of following event and time of assessment may be different

```
Namespaces:
@prefix rdf: <http://www.w3.org/1999/02/22-rdf-syntax-ns#> .
@prefix rdfs: <http://www.w3.org/2000/01/rdf-schema#> .
@prefix ies: <http://ies.data.gov.uk/ies4#> .
@prefix data: <http://data.gov.uk/testdata#> .
```

KEY:	
As	ies:Assessor
AT	ies:AssessToBeTrue
F	ies:Follow
Fd	ies:Followed
Fr	ies:Follower
LT	ies:LocationTransponder
PP	ies:ParticularPeriod
PW	ies:PossibleWorld
S	ies:System

## Example “Following” Data:

```

@prefix data: <http://ais.data.gov.uk/ais-ies-test#> .
@prefix ies: <http://ies.data.gov.uk/ontology/ies4#> .
@prefix iso8601: <http://iso.org/iso8601#> .
@prefix xsd: <http://www.w3.org/2001/XMLSchema#> .

data:0edbd5f1-1c3b-4e59-b296-b4781313edff a ies:Assessor ;
ies:isParticipantIn data:528acb27-8877-4965-995d-ba6f72f3363a ;
ies:isParticipationOf data:a4da7459-b746-4a85-aedf-27fc21649013 .

data:196be3f6-8dd6-4d31-8807-9802714f94f3 a ies:BoundingState ;
ies:inPeriod iso8601:2007-01-01T00:00:09 ;
ies:isStartOf data:f89a179d-29e6-44aa-b3db-65921a98d30e .

data:d9e26359-258d-46d3-9383-4e3ae959160a a ies:Follower ;
ies:isParticipantIn data:f89a179d-29e6-44aa-b3db-65921a98d30e ;
ies:isParticipationOf data:MMSI_367000150 .

data:da95c036-d980-4b98-934f-16373d38eabe a ies:BoundingState ;
ies:inPeriod iso8601:2007-01-01T00:05:40 ;
ies:isEndOf data:f89a179d-29e6-44aa-b3db-65921a98d30e .

data:dac815eb-06a7-45c7-a208-e38fbfe3d5c7 a ies:Followed ;
ies:isParticipantIn data:f89a179d-29e6-44aa-b3db-65921a98d30e ;
ies:isParticipationOf data:MMSI_366952890 .

data:05560c92-c9fb-4c6d-a342-d8ff127f41ea a ies:Name ;
ies:representationValue "HAL"^^xsd:string .

data:528acb27-8877-4965-995d-ba6f72f3363a a ies:Assess ;
ies:assessed data:3c23fd87-227b-41bf-8211-e12bc8d4f492 .

data:7989b8b8-0847-4799-88fd-d5ba50b08cc6 a ies:Name ;
ies:representationValue "International Telecommunications Union"^^xsd:string .

data:MMSI_366952890 a ies:LocationTransponder ;
ies:isIdentifiedBy data:MMSI_366952890_idObj .

data:MMSI_366952890_idObj a ies:CommunicationsIdentifier ;
ies:inScheme <http://itu.int#mmsi-NamingScheme> ;
ies:representationValue "366952890"^^xsd:string .

data:MMSI_367000150 a ies:LocationTransponder ;
ies:isIdentifiedBy data:MMSI_367000150_idObj .

data:MMSI_367000150_idObj a ies:CommunicationsIdentifier ;
ies:inScheme <http://itu.int#mmsi-NamingScheme> ;
ies:representationValue "367000150"^^xsd:string .

data:a4da7459-b746-4a85-aedf-27fc21649013 a ies:System ;
ies:hasName data:05560c92-c9fb-4c6d-a342-d8ff127f41ea .

iso8601:2007-01-01T00:00:09 a ies:ParticularPeriod .

iso8601:2007-01-01T00:05:40 a ies:ParticularPeriod .

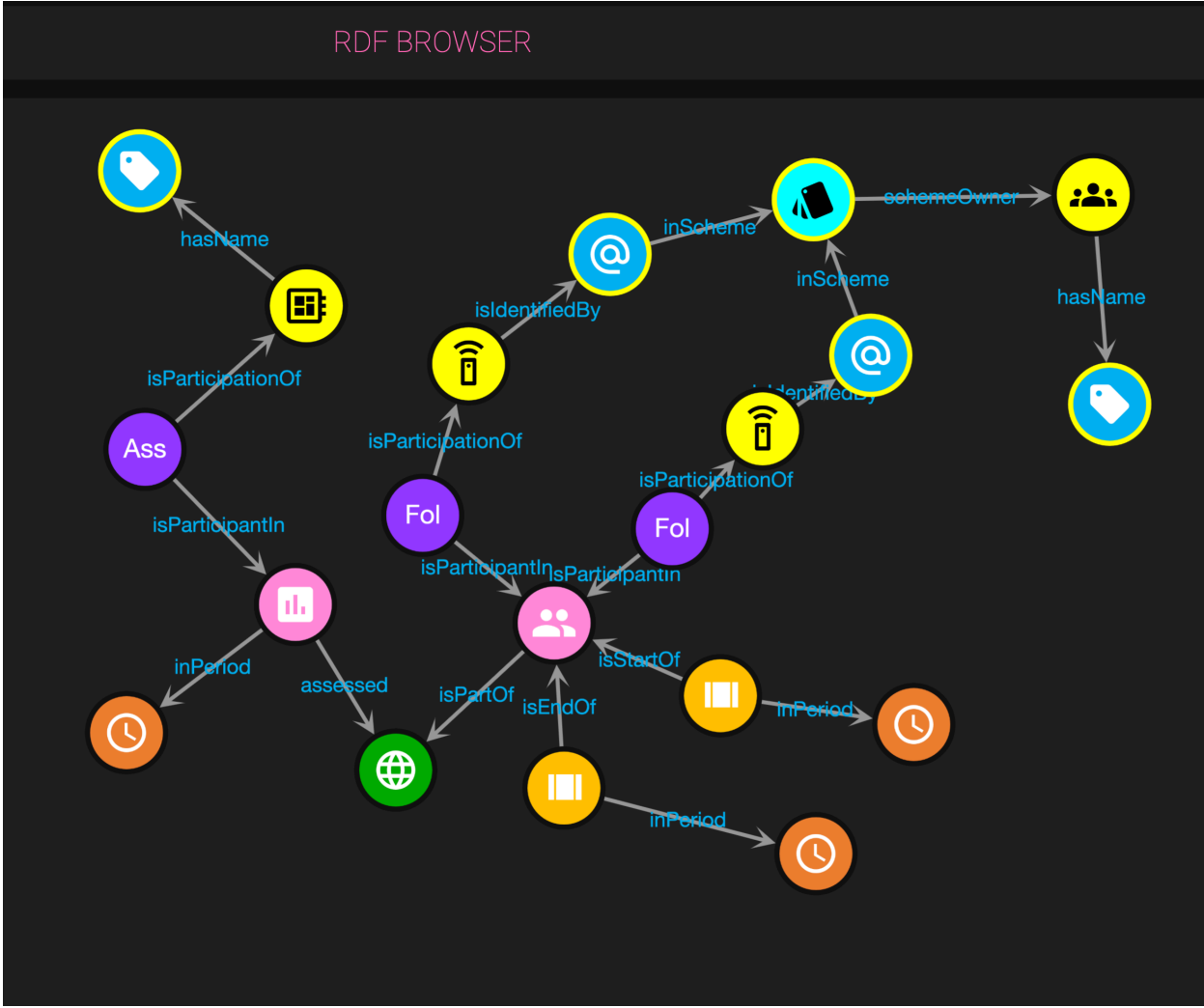
<http://itu.int> a ies:Organisation ;
ies:hasName data:7989b8b8-0847-4799-88fd-d5ba50b08cc6 .

data:3c23fd87-227b-41bf-8211-e12bc8d4f492 a ies:PossibleWorld .

<http://itu.int#mmsi-NamingScheme> a ies:NamingScheme ;
ies:schemeOwner <http://itu.int> .

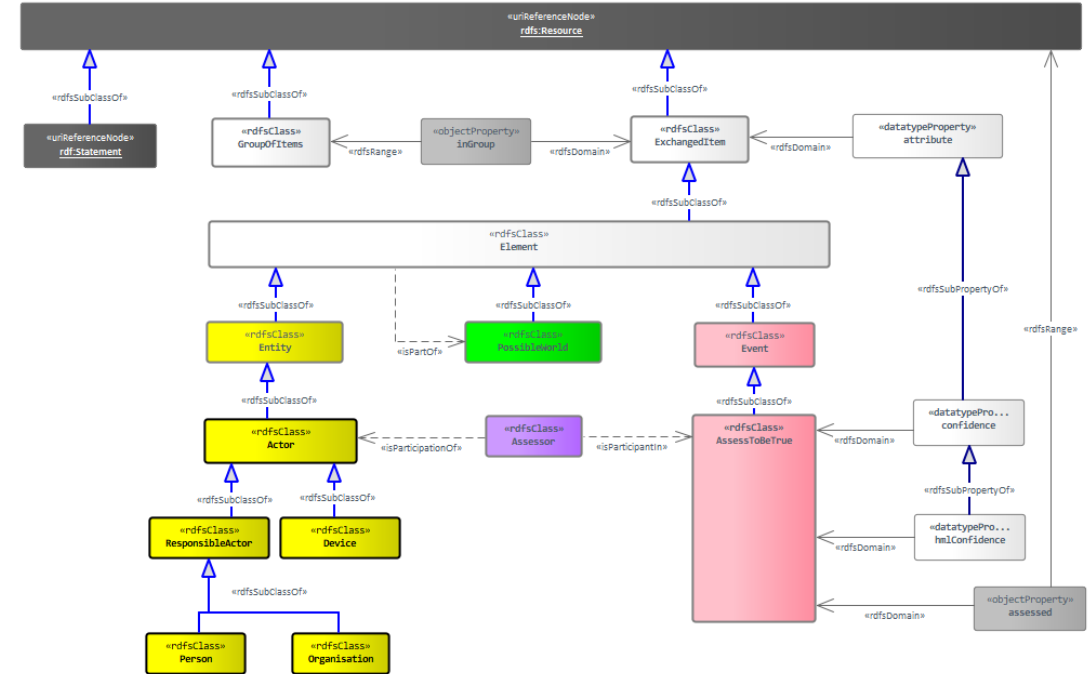
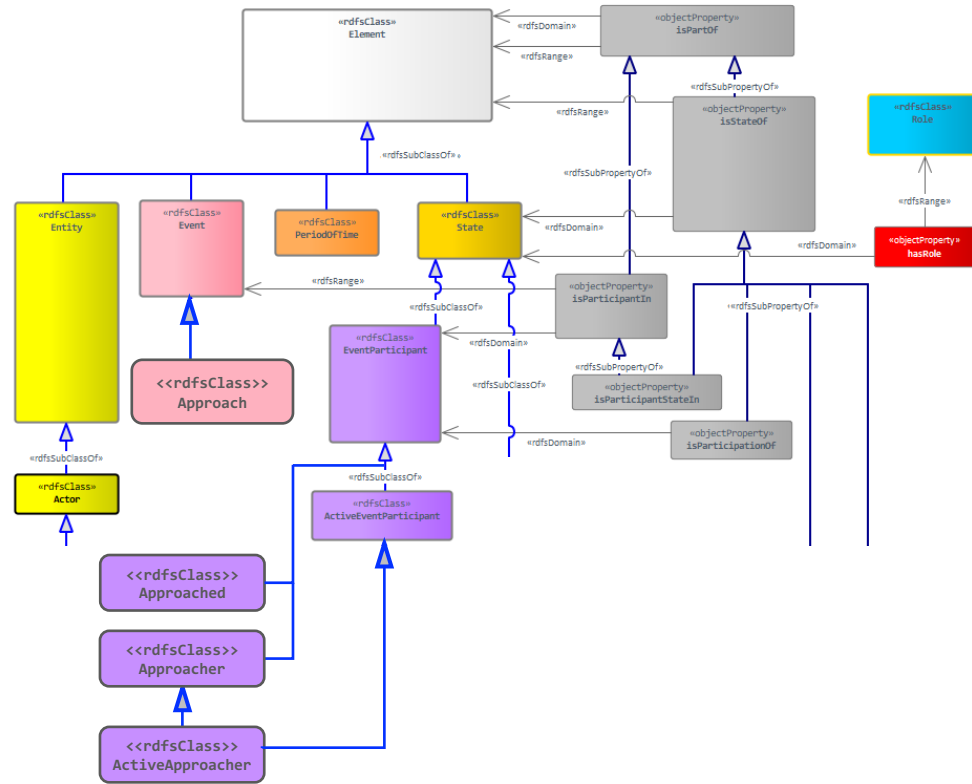
data:f89a179d-29e6-44aa-b3db-65921a98d30e a ies:Follow ;
ies:isPartOf data:3c23fd87-227b-41bf-8211-e12bc8d4f492 .

```



# Extensions to IES for “approaching”

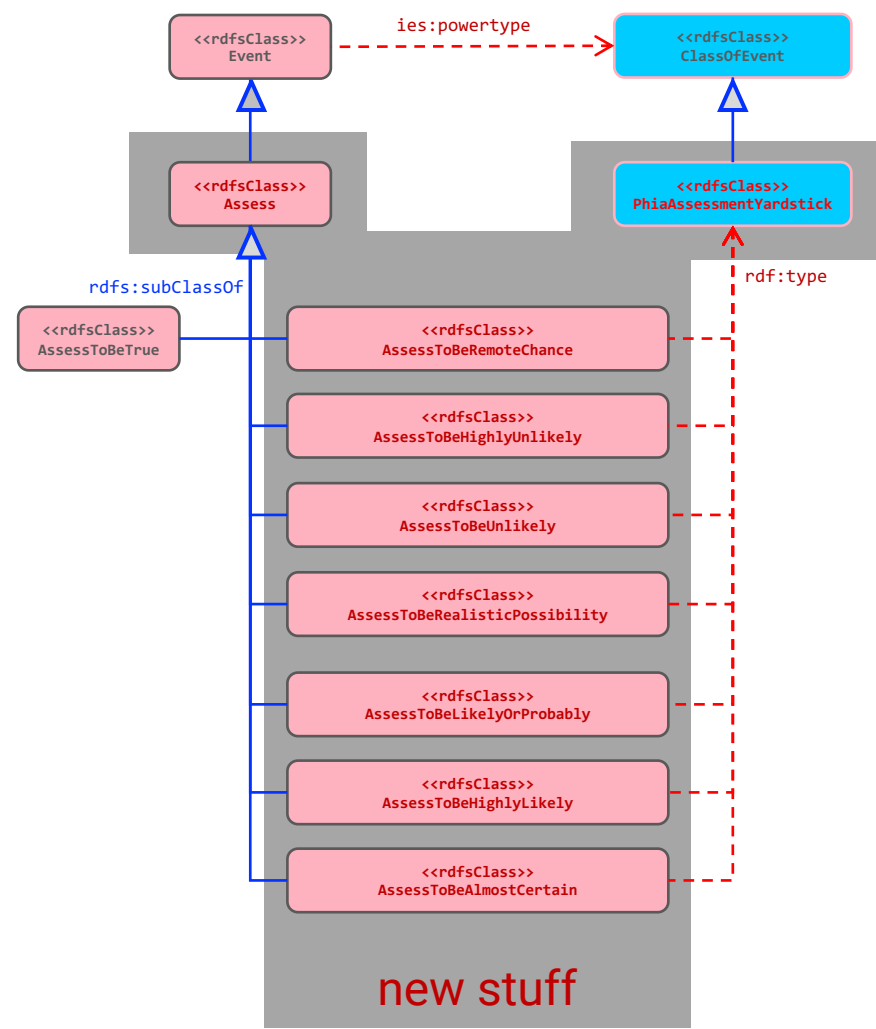
This extension follows exactly the same pattern as the “following” use-case. It even includes the idea of deliberate / active approaching



# RDF Schema for “Approaching” Use-Case Extensions

@prefix	ies:	<http://ies.data.gov.uk/ontology/ies4#> .
@prefix	rdf:	<http://www.w3.org/1999/02/22-rdf-syntax-ns#> .
@prefix	rdfs:	<http://www.w3.org/2000/01/rdf-schema#> .
ies:Approach	rdf:type	rdfs:Class .
ies:Approach	rdfs:subClassOf	ies:Event .
ies:Approached	rdf:type	rdfs:Class .
ies:Approached	rdfs:subClassOf	ies:EventParticipant .
ies:Approacher	rdf:type	rdfs:Class .
ies:Approacher	rdfs:subClassOf	ies:EventParticipant .
ies:ActiveApproacher	rdf:type	rdfs:Class .
ies:ActiveApproacher	rdfs:subClassOf	ies:Approacher .
ies:ActiveApproacher	rdfs:subClassOf	ies:ActiveEventParticipant .

# Proposed IES Modifications for Assessments



PHIA Probability Yardstick

Probability range	Judgement terms	Fraction range
≤ ≈5%	Remote chance	≤ ≈ 1/20
≈10% - ≈20%	Highly unlikely	≈1/10 - ≈1/5
≈25% - ≈35%	Unlikely	≈1/4 - ≈1/3
≈40% - <50%	Realistic possibility	≈4/10 - <1/2
≈55% - ≈75%	Likely or Probably	≈4/7 - ≈3/4
≈80% - ≈90%	Highly likely	≈4/5 - ≈9/10
≥ ≈95%	Almost certain	≥ ≈19/20
= approximately equal to	≥ is greater than or equal to	≤ is less than or

See: <https://www.app.college.police.uk/app-content/intelligence-management/analysis/delivering-effective-analysis/>



# RDF Schema for Assessment Extensions

@prefix	ies:	<http://ies.data.gov.uk/ontology/ies4#> .
@prefix	rdf:	<http://www.w3.org/1999/02/22-rdf-syntax-ns#> .
@prefix	rdfs:	<http://www.w3.org/2000/01/rdf-schema#> .
ies:Assess	rdf:type	rdfs:Class .
ies:Assess	rdfs:subClassOf	ies:Event .
ies:AssessToBeTrue	rdfs:subClassOf	ies:Assess .
ies:PhiaAssessmentYardstick	rdf:type	rdfs:Class .
ies:PhiaAssessmentYardstick	rdfs:subClassOf	ies:ClassOfEventEvent .
ies:AssessToBeRemoteChance	rdf:type	rdfs:Class .
ies:AssessToBeRemoteChance	rdf:type	ies:PhiaAssessmentYardstick .
ies:AssessToBeRemoteChance	rdfs:subClassOf	ies:Assess .
ies:AssessToBeHighlyUnlikely	rdf:type	rdfs:Class .
ies:AssessToBeHighlyUnlikely	rdf:type	ies:PhiaAssessmentYardstick .
ies:AssessToBeHighlyUnlikely	rdfs:subClassOf	ies:Assess .
ies:AssessToBeUnlikely	rdf:type	rdfs:Class .
ies:AssessToBeUnlikely	rdf:type	ies:PhiaAssessmentYardstick .
ies:AssessToBeUnlikely	rdfs:subClassOf	ies:Assess .
ies:AssessToBeRealisticPossibility	rdf:type	rdfs:Class .
ies:AssessToBeRealisticPossibility	rdf:type	ies:PhiaAssessmentYardstick .
ies:AssessToBeRealisticPossibility	rdfs:subClassOf	ies:Assess .
ies:AssessToBeLikelyOrProbably	rdf:type	rdfs:Class .
ies:AssessToBeLikelyOrProbably	rdf:type	ies:PhiaAssessmentYardstick .
ies:AssessToBeLikelyOrProbably	rdfs:subClassOf	ies:Assess .
ies:AssessToBeHighlyLikely	rdf:type	rdfs:Class .
ies:AssessToBeHighlyLikely	rdf:type	ies:PhiaAssessmentYardstick .
ies:AssessToBeHighlyLikely	rdfs:subClassOf	ies:Assess .
ies:AssessToBeAlmostCertain	rdf:type	rdfs:Class .
ies:AssessToBeAlmostCertain	rdf:type	ies:PhiaAssessmentYardstick .
ies:AssessToBeAlmostCertain	rdfs:subClassOf	ies:Assess .

This triple also needs to be removed from IES Schema:

**ies:AssessToBeTrue** **rdfs:subClassOf** **ies:Event** .

(Note: this is not a breaking change, as the class itself has not been removed)  
(Note: the **rdf:type rdfs:Class** triples aren't strictly needed given that **ies:ClassOfEvent** is a subclass of **rdfs:Class**, but not all ontology editors are smart enough to spot this.