



102S PRO SN:0520102P10265 (Calibrated on 19/03/2023)

รายงานผลการวัดสอบทางเรขาคณิตสำหรับระบบกล้องเฉียง  
ที่ติดตั้งบนยูเอวี

Geometric Camera Calibration Report for UAV-Equipped  
Small-Format Oblique Camera System



PCV & LS Lab

Department of Survey Engineer,  
Faculty of Engineering,  
Chulalongkorn University

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จัดทำโดย

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ภาควิชาวิศวกรรมสำรวจ

คณะวิศวกรรมศาสตร์ จุฬาลงกรณ์มหาวิทยาลัย

## กิตติกรรมประกาศ

คณะวิจัยขอขอบคุณ บริษัท ไทยสกายวิชั่น จำกัด ซึ่งเป็นผู้สนับสนุนและอนุเคราะห์ข้อมูลภาพถ่ายทางอากาศและข้อมูลสัญญาณจีเอนเอสเอสมาใช้ในการประมวลผลข้อมูลและวิเคราะห์หาค่าพารามิเตอร์และแบบจำลองทางคณิตศาสตร์ของระบบกล้องเดียว

งานวิจัยครั้งนี้สำเร็จลงด้วยดี ข้อมูลที่ได้จะถูกนำไปประมวลผล วิจัย พัฒนาองค์ความรู้ด้านการทำแผนที่และแบบจำลองสามมิติทั้งจากระบบถ่ายภาพกล้องเดียวสำหรับสถาบันการศึกษาและบริษัทที่ปรึกษาการทำแผนที่จากภาพถ่ายทางอากาศต่อไป

คณะวิจัย

Pending and not



## Geometric Calibration of the Small-Format Oblique Camera System

### Photogrammetric Block Information

Photogrammetrist	1. Phisan Santitamnont (Dr.-Ing)
UAV Camera Operator	2. Thirawat Bannakulpiphat (M.Eng.)
	3. Team Thai Sky Vision (TSV)
Flight Date and Time	19/03/2023 (After 12.00 PM.)
Report Date / Release	10/04/2023
Test Field	Geodetic GNSS and UAV Testing Field, Chulalongkorn University
Location	Saraburi, Thailand (Latitude: 14°.5236N, Longitude: 101°.0235E)
Aircraft	DJI MATRICE 300
Camera	SHARE 102S PRO
Block Name	Full block CU-SBR
Number of Photo	4,135 (827 photo per camera)
Nadir Photo Overlap (%)	80%
Nadir Photo Side-lap (%)	80%
Number of Rig Station	827
Number of Flight-Strip	16
Number of GCP/CP	Total 40
Photogrammetric Processing Software	Pix4D Mapper version 4.7.5

### Camera Specification

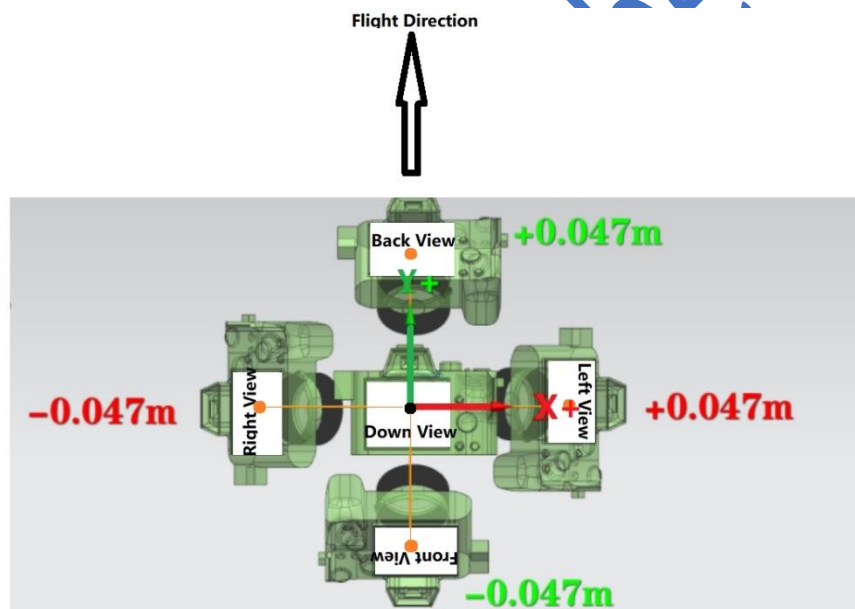
Parameter	Description
CMOS Size	23.5 × 15.6 mm (APS-C)
Pixel	24.3 MP (Total ≥ 120 MP)
Resolution (Single CCD)	6000 × 4000
Pixel Size	3.9 μm
Exposure Interval	≥ 0.8 s
Focal Length (Nadir/Oblique)	25 mm/ 35 mm
Weight	650 g
Data Storage	1280 GB
Size	140*140*80 mm



## Quality Report

### 1. Camera position from manufacturer note

Camera	X (mm)	Y (mm)	Z (mm)	Camera
102S PRO	???.??	???.??	???.??	Ortho view
	???.??	???.??	???.??	Left view
	???.??	???.??	???.??	Right view
	???.??	???.??	???.??	Forward view
	???.??	???.??	???.??	Backward view





### 2. Initial and adjusted rig relative parameters

\*หมายเหตุ: พารามิเตอร์ที่ใช้ยังไม่ใช่ค่าที่สอดคล้องกับลักษณะทางกายภาพความเป็นจริงของระบบกล้อง หากได้ค่าที่สอดคล้องจะทำการวัดสอบพารามิเตอร์ใหม่

#### ? Camera Rig «SHARE\_OBQ\_RIG» Relatives. Images: 4135

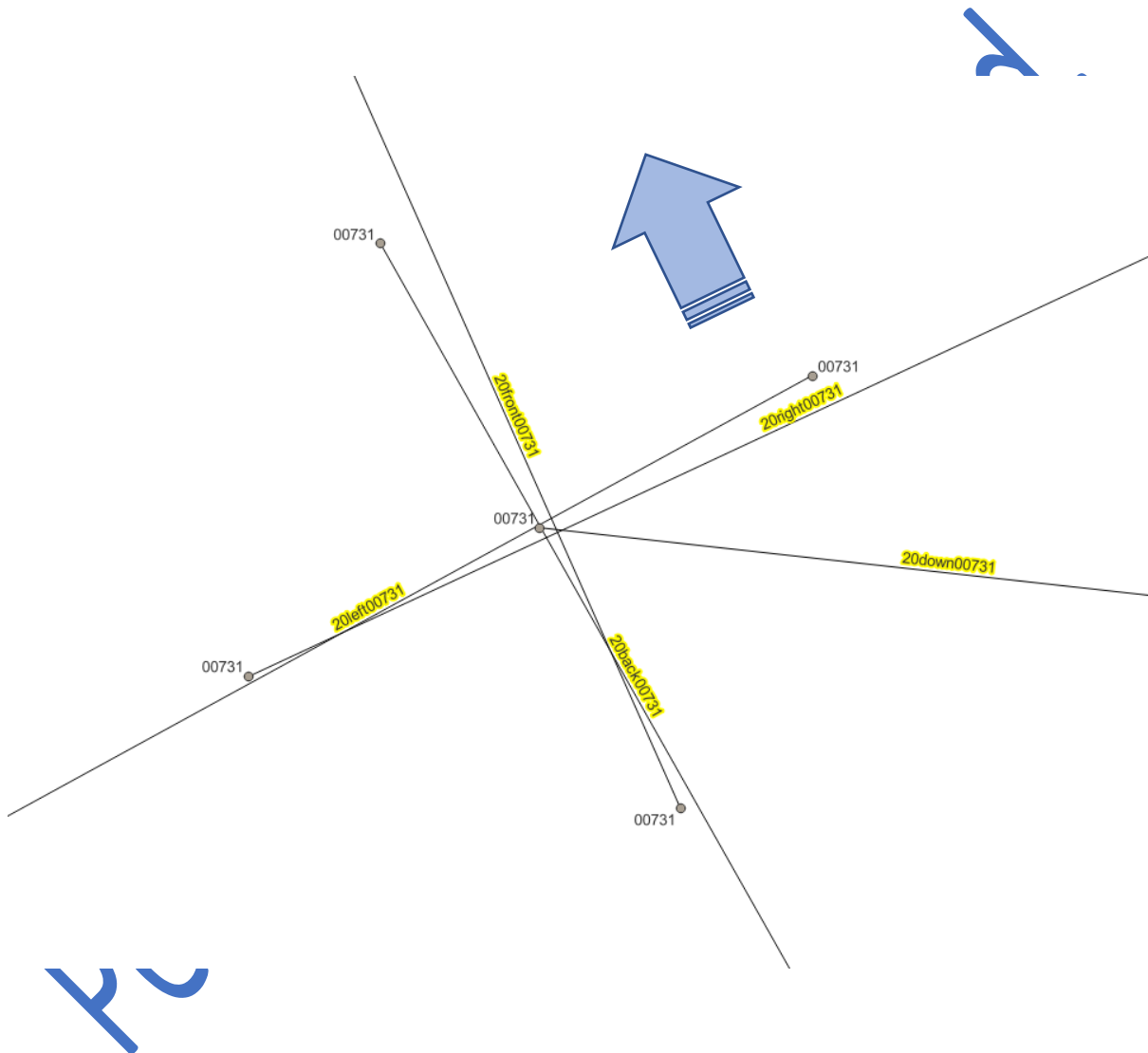
	Transl X [m]	Transl Y [m]	Transl Z [m]	Rot X [degree]	Rot Y [degree]	Rot Z [degree]
SHARE102SPRO265DOWN_25.2_6000x4000 (RGB)	Reference Camera					
SHARE102SPRO265BACK_35.2_6000x4000 (RGB)						
Initial Values	0.000	-0.047	-0.025	-45.000	0.000	0.000
Optimized values	0.000	-0.047	-0.025	-44.623	-0.791	-0.140
Uncertainties (sigma)				0.016	0.002	0.017
SHARE102SPRO265FRONT_35.3_6000x4000 (RGB)						
Initial Values	0.000	0.047	-0.025	45.000	0.000	-180.000
Optimized values	0.000	0.047	-0.025	45.456	0.211	179.954
Uncertainties (sigma)				0.012	0.015	0.002
SHARE102SPRO265LEFT_35.4_6000x4000 (RGB)						
Initial Values	0.047	0.000	-0.025	0.000	-45.000	90.000
Optimized values	0.047	0.000	-0.025	0.984	-45.332	90.944
Uncertainties (sigma)				0.008	0.005	0.013
SHARE102SPRO265RIGHT_35.4_6000x4000 (RGB)						
Initial Values	-0.047	0.000	-0.025	0.000	45.000	-90.000
Optimized values	-0.047	0.000	-0.025	-1.583	45.010	-88.886
Uncertainties (sigma)				0.002	0.003	0.003

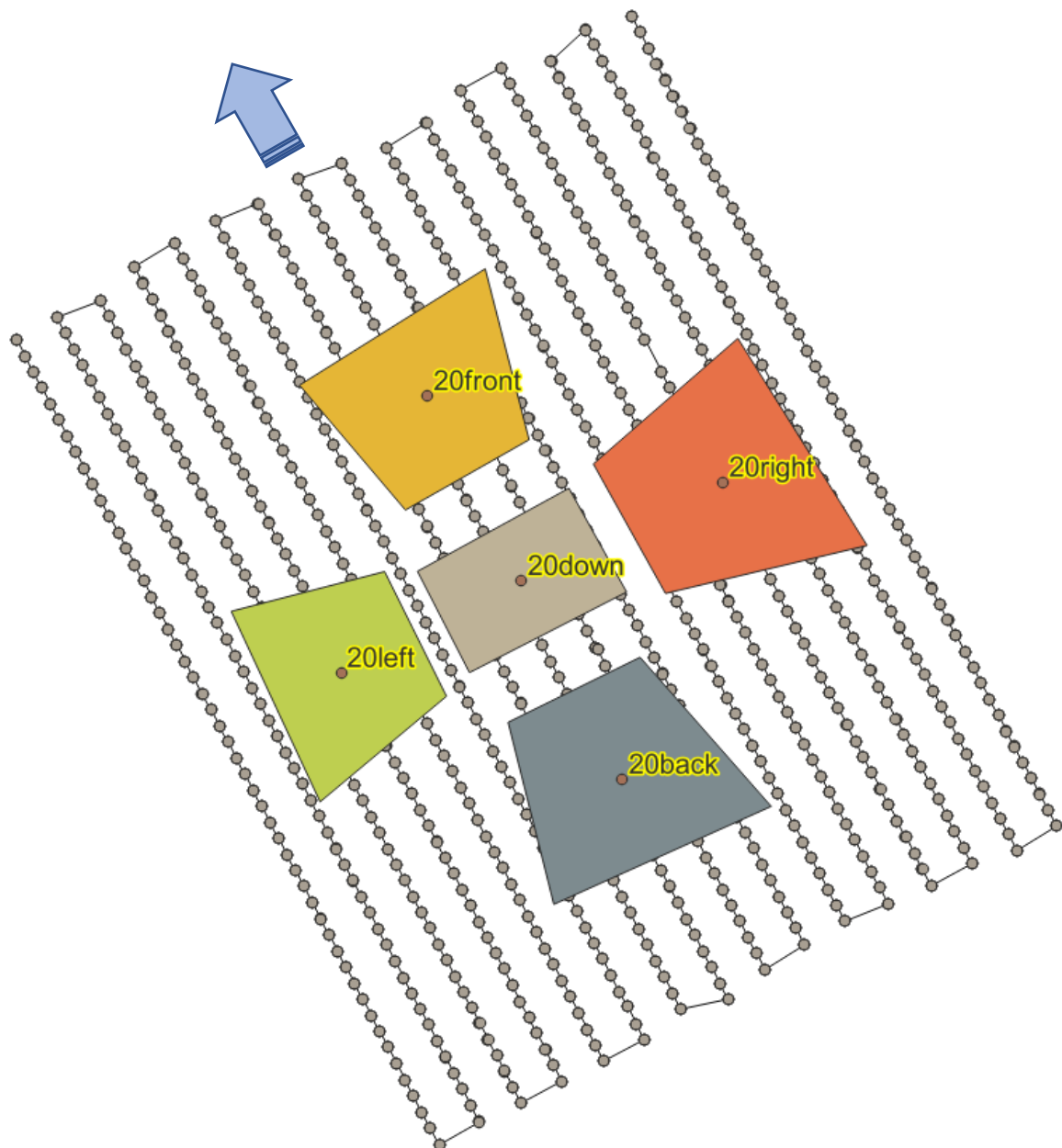


## Geometric Calibration of the Small-Format Oblique Camera System

Evaluation result passed: (ตรวจสอบอีกครั้งหลังจากแทนค่าพารามิเตอร์ได้ถูกต้อง)

Uncertainty	Tx, Ty, Tz (mm)	Rot X (degrees)	Rot Y (degrees)	Rot Z (degrees)
Criterion	Constraint	0.015	0.015	0.015
Passed	?	?	?	?





PER





## Geometric Calibration of the Small-Format Oblique Camera System

### 3. Internal Camera Parameter

**SHARE102SPRO265DOWN\_25.2\_6000x4000 (RGB). Sensor Dimensions: 22.604 [mm] x 15.069 [mm]**

EXIF ID: SHARE102SPRO265DOWN\_25.2\_6000x4000

	Focal Length	Principal Point x	Principal Point y	R1	R2	R3	T1	T2
Initial Values	6685.710 [pixel] 25.187 [mm]	3002.620 [pixel] 11.312 [mm]	2028.210 [pixel] 7.641 [mm]	-0.053	0.137	-0.047	0.000	0.000
Optimized Values	6423.603 [pixel] 24.200 [mm]	3000.463 [pixel] 11.304 [mm]	2024.668 [pixel] 7.628 [mm]	-0.050	0.120	-0.023	0.000	-0.000
Uncertainties (Sigma)	0.279 [pixel] 0.001 [mm]	0.256 [pixel] 0.001 [mm]	0.193 [pixel] 0.001 [mm]	0.000	0.002	0.005	0.000	0.000

**SHARE102SPRO265BACK\_35.2\_6000x4000 (RGB). Sensor Dimensions: 22.839 [mm] x 15.226 [mm]**

EXIF ID: SHARE102SPRO265BACK\_35.2\_6000x4000

	Focal Length	Principal Point x	Principal Point y	R1	R2	R3	T1	T2
Initial Values	9257.140 [pixel] 35.237 [mm]	3040.020 [pixel] 11.572 [mm]	2014.680 [pixel] 7.669 [mm]	-0.012	0.040	-0.334	-0.000	-0.001
Optimized Values	9015.691 [pixel] 34.318 [mm]	2999.100 [pixel] 11.416 [mm]	1952.867 [pixel] 7.434 [mm]	-0.053	0.265	-1.014	-0.001	0.003
Uncertainties (Sigma)	0.745 [pixel] 0.003 [mm]	2.710 [pixel] 0.010 [mm]	2.493 [pixel] 0.009 [mm]	0.003	0.044	0.178	0.000	0.000

**SHARE102SPRO265FRONT\_35.3\_6000x4000 (RGB). Sensor Dimensions: 22.858 [mm] x 15.239 [mm]**

EXIF ID: SHARE102SPRO265FRONT\_35.3\_6000x4000

	Focal Length	Principal Point x	Principal Point y	R1	R2	R3	T1	T2
Initial Values	9257.140 [pixel] 35.266 [mm]	3042.170 [pixel] 11.590 [mm]	1997.070 [pixel] 7.608 [mm]	-0.015	0.135	-0.800	0.000	-0.000
Optimized Values	8999.712 [pixel] 34.286 [mm]	3111.765 [pixel] 11.855 [mm]	1979.437 [pixel] 7.541 [mm]	0.062	-0.975	3.652	0.003	0.002
Uncertainties (Sigma)	0.541 [pixel] 0.002 [mm]	2.302 [pixel] 0.009 [mm]	1.830 [pixel] 0.007 [mm]	0.002	0.032	0.130	0.000	0.000

**SHARE102SPRO265LEFT\_35.4\_6000x4000 (RGB). Sensor Dimensions: 22.968 [mm] x 15.312 [mm]**

EXIF ID: SHARE102SPRO265LEFT\_35.4\_6000x4000

	Focal Length	Principal Point x	Principal Point y	R1	R2	R3	T1	T2
Initial Values	9257.140 [pixel] 35.436 [mm]	3054.980 [pixel] 11.694 [mm]	2016.620 [pixel] 7.720 [mm]	-0.006	-0.005	-0.190	0.000	0.001
Optimized Values	9041.725 [pixel] 34.611 [mm]	3045.577 [pixel] 11.658 [mm]	2054.176 [pixel] 7.863 [mm]	0.003	-0.059	-0.199	0.000	-0.001
Uncertainties (Sigma)	0.430 [pixel] 0.002 [mm]	1.781 [pixel] 0.007 [mm]	0.648 [pixel] 0.002 [mm]	0.002	0.027	0.117	0.000	0.000

**SHARE102SPRO265RIGHT\_35.4\_6000x4000 (RGB). Sensor Dimensions: 22.924 [mm] x 15.283 [mm]**

EXIF ID: SHARE102SPRO265RIGHT\_35.4\_6000x4000

	Focal Length	Principal Point x	Principal Point y	R1	R2	R3	T1	T2
Initial Values	9257.140 [pixel] 35.368 [mm]	3008.110 [pixel] 11.493 [mm]	2019.280 [pixel] 7.715 [mm]	-0.009	0.009	-0.245	0.000	0.001
Optimized Values	9023.686 [pixel] 34.476 [mm]	2955.669 [pixel] 11.293 [mm]	2008.004 [pixel] 7.672 [mm]	0.000	-0.123	0.289	-0.000	-0.002
Uncertainties (Sigma)	0.389 [pixel] 0.001 [mm]	0.088 [pixel] 0.000 [mm]	0.114 [pixel] 0.000 [mm]	0.002	0.023	0.103	0.000	0.000

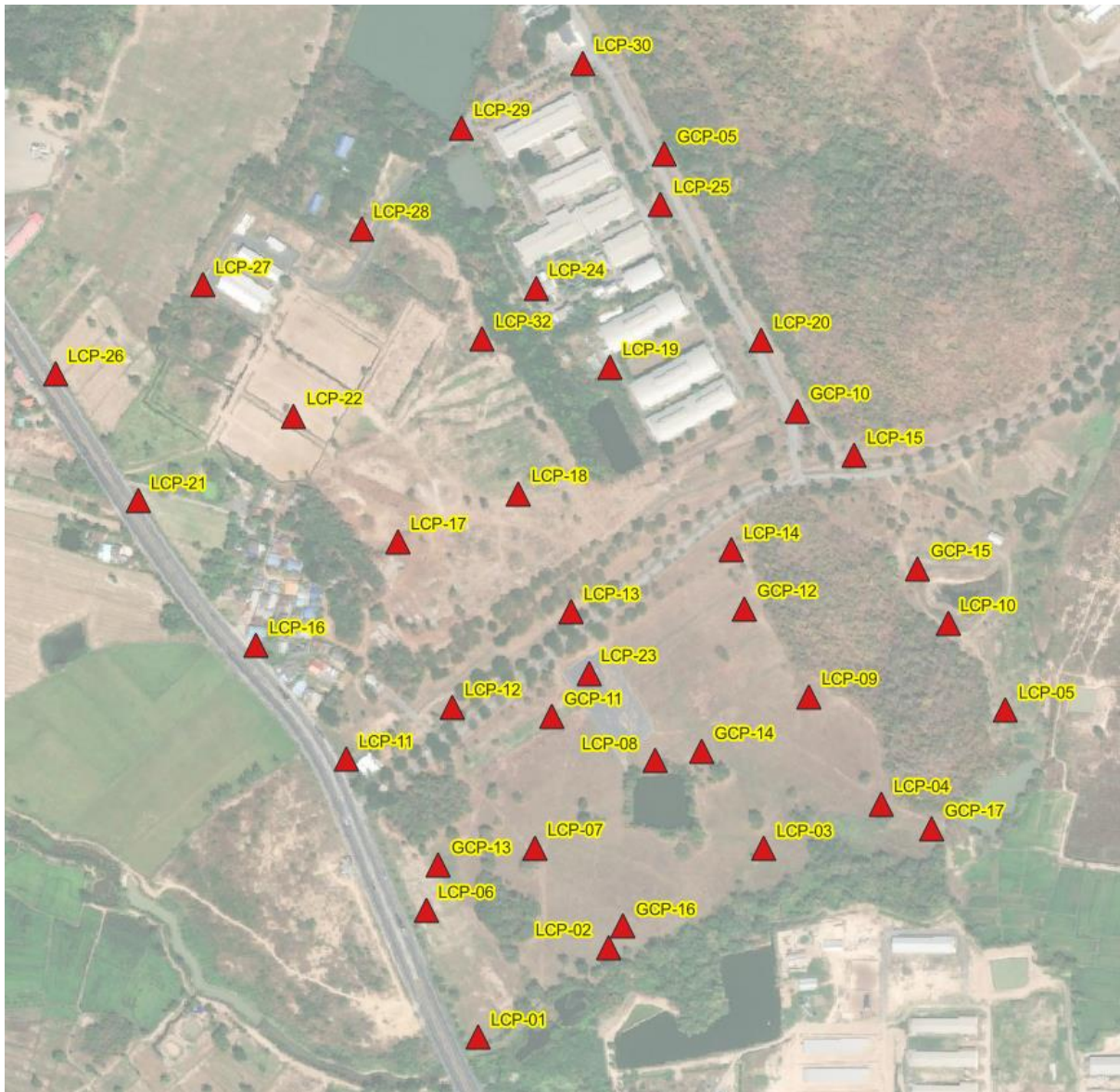


## Geometric Calibration of the Small-Format Oblique Camera System

Evaluation Results Passed: (ตรวจสอบอีกครั้งหลังจากแทนค่าพารามิเตอร์ได้ถูกต้อง)

	f	cx	cy	R1	R2	R3
Criterion	0.005 mm	0.015 mm	0.015 mm	0.005	0.060	0.400
DOWN	?	?	?	?	?	?
FRONT	?	?	?	?	?	?
REAR	?	?	?	?	?	?
LEFT	?	?	?	?	?	?
RIGHT	?	?	?	?	?	?

#### 4. Distribution of Ground Control Points (GCPs) and Check Point (CPs)







## 5. Aerial Triangulation Result: partial GCP (20 points) vs partial Check Points (20 points)

### Ground Control Points

GCP Name	Accuracy XY/Z [m]	Error X [m]	Error Y [m]	Error Z [m]	Projection Error [pixel]	Verified/Marked
GCP-11 (3D)	0.020/0.050	0.008	-0.009	0.021	0.293	20 / 20
LCP-22 (3D)	0.020/0.050	-0.020	-0.030	-0.027	0.290	20 / 20
LCP-28 (3D)	0.020/0.050	-0.017	-0.014	-0.011	0.240	20 / 20
LCP-30 (3D)	0.020/0.050	-0.003	-0.004	-0.026	0.281	20 / 20
LCP-25 (3D)	0.020/0.050	-0.009	0.025	-0.023	0.280	20 / 20
LCP-19 (3D)	0.020/0.050	0.012	-0.017	-0.018	0.290	20 / 20
LCP-15 (3D)	0.020/0.050	0.002	-0.010	0.007	0.303	20 / 20
GCP-10 (3D)	0.020/0.050	0.022	0.014	-0.006	0.354	20 / 20
LCP-05 (3D)	0.020/0.050	-0.018	0.016	0.048	0.272	20 / 20
LCP-13 (3D)	0.020/0.050	0.019	-0.014	0.065	0.297	20 / 20
LCP-32 (3D)	0.020/0.050	0.023	-0.000	0.019	0.279	20 / 20
LCP-26 (3D)	0.020/0.050	-0.013	0.005	0.032	0.249	20 / 20
LCP-16 (3D)	0.020/0.050	-0.013	0.019	0.005	0.333	20 / 20
LCP-01 (3D)	0.020/0.050	-0.030	0.024	-0.035	0.282	20 / 20
LCP-06 (3D)	0.020/0.050	0.005	0.026	-0.022	0.422	20 / 20
GCP-13 (3D)	0.020/0.050	0.019	0.008	-0.007	0.345	20 / 20
LCP-02 (3D)	0.020/0.050	-0.005	-0.004	-0.046	0.274	20 / 20
LCP-03 (3D)	0.020/0.050	0.004	-0.009	-0.021	0.271	20 / 20
LCP-09 (3D)	0.020/0.050	0.007	-0.014	-0.040	0.284	20 / 20
GCP-16 (3D)	0.020/0.020	0.008	-0.012	0.016	0.187	20 / 20
Mean [m]		0.000029	-0.000116	-0.003352		
Sigma [m]		0.014953	0.015799	0.028861		
RMS Error [m]		0.014953	0.015799	0.029055		

Check Point Name	Accuracy XY/Z [m]	Error X [m]	Error Y [m]	Error Z [m]	Projection Error [pixel]	Verified/Marked
LCP-27		-0.0095	0.0090	-0.0315	0.3037	20 / 20
LCP-29		0.0044	-0.0266	-0.0535	0.1833	20 / 20
GCP-05		-0.0120	0.0763	-0.0011	0.3443	20 / 20
LCP-24		0.0209	0.0039	0.0630	0.2681	20 / 20
LCP-20		0.0217	0.0032	-0.0374	0.3046	20 / 20
GCP-15		0.0654	-0.0079	-0.0789	0.3161	20 / 20
LCP-10		0.0429	0.0312	-0.0479	0.2856	20 / 20
LCP-12		0.0069	-0.0028	0.0190	0.2781	20 / 20
LCP-18		0.0033	-0.0110	0.0167	0.3351	20 / 20
LCP-17		0.0038	-0.0271	-0.0417	0.2724	20 / 20
LCP-21		0.0317	-0.0083	0.0068	0.3001	20 / 20
LCP-11		0.0166	0.0298	0.0735	0.2051	20 / 20
LCP-08		0.0343	-0.0006	0.0196	0.3183	20 / 20
LCP-07		0.0016	-0.0076	-0.0259	0.2645	20 / 20
GCP-17		0.0380	0.0053	-0.0566	0.2828	20 / 20
LCP-04		0.0341	-0.0153	-0.0296	0.3090	20 / 20
GCP-12		0.0210	-0.0037	-0.0314	0.2080	20 / 20
LCP-14		0.0129	-0.0277	-0.0576	0.2756	20 / 20
GCP-14		0.0409	0.0011	-0.0281	0.2823	20 / 20
LCP-23		0.0169	-0.0147	-0.0060	0.2949	20 / 20
Mean [m]		0.019795	0.000326	-0.016427		
Sigma [m]		0.018906	0.023228	0.039003		
RMS Error [m]		0.027373	0.023230	0.042321		



## Geometric Calibration of the Small-Format Oblique Camera System

Evaluation Result: (ตรวจสอบอีกครั้งหลังจากแทนค่าพารามิเตอร์ได้ถูกต้อง)

	Error X	Error Y (m)	Error Z (m)	Projection Error
Criterion	0.035 m	0.035 m	0.065 m	0.5 pixel
Partial GCPs	?	?	?	?
Partial CPs	?	?	?	?

Pending and not be used.



## 6. Aerial Triangulation Result: full GCP (40 points)

### Ground Control Points

GCP Name	Accuracy XY/Z [m]	Error X [m]	Error Y [m]	Error Z [m]	Projection Error [pixel]	Verified/Marked
GCP-11 (3D)	0.020/0.050	-0.001	-0.007	0.021	0.297	20 / 20
LCP-27 (3D)	0.020/0.050	-0.009	0.008	-0.010	0.303	20 / 20
LCP-22 (3D)	0.020/0.050	-0.023	-0.026	-0.025	0.284	20 / 20
LCP-28 (3D)	0.020/0.050	-0.019	-0.013	-0.002	0.244	20 / 20
LCP-29 (3D)	0.020/0.050	0.006	-0.021	-0.032	0.180	20 / 20
LCP-30 (3D)	0.020/0.050	0.003	-0.008	-0.018	0.288	20 / 20
GCP-05 (3D)	0.020/0.050	-0.008	0.047	0.002	0.358	20 / 20
LCP-25 (3D)	0.020/0.050	-0.011	0.007	-0.016	0.287	20 / 20
LCP-24 (3D)	0.020/0.050	0.016	0.001	0.047	0.274	20 / 20
LCP-19 (3D)	0.020/0.050	0.003	-0.020	-0.023	0.301	20 / 20
LCP-15 (3D)	0.020/0.050	-0.014	-0.013	0.025	0.308	20 / 20
LCP-20 (3D)	0.020/0.050	0.008	0.000	-0.024	0.320	20 / 20
GCP-10 (3D)	0.020/0.050	0.009	0.012	0.004	0.357	20 / 20
GCP-15 (3D)	0.020/0.050	0.033	-0.013	-0.028	0.314	20 / 20
LCP-10 (3D)	0.020/0.050	0.009	0.025	-0.001	0.299	20 / 20
LCP-05 (3D)	0.020/0.050	-0.041	0.017	0.077	0.278	20 / 20
LCP-13 (3D)	0.020/0.050	0.008	-0.012	0.070	0.303	20 / 20
LCP-12 (3D)	0.020/0.050	0.001	-0.003	0.006	0.289	20 / 20
LCP-18 (3D)	0.020/0.050	-0.003	-0.006	0.016	0.339	20 / 20
LCP-17 (3D)	0.020/0.050	-0.003	-0.019	-0.035	0.276	20 / 20
LCP-32 (3D)	0.020/0.050	0.021	0.000	0.016	0.280	20 / 20
LCP-26 (3D)	0.020/0.050	-0.017	0.009	0.039	0.246	20 / 20
LCP-21 (3D)	0.020/0.050	0.017	-0.002	0.002	0.309	20 / 20
LCP-16 (3D)	0.020/0.050	-0.023	0.018	-0.006	0.345	20 / 20
LCP-11 (3D)	0.020/0.050	0.007	0.021	0.043	0.204	20 / 20
LCP-08 (3D)	0.020/0.050	0.017	0.003	0.025	0.317	20 / 20
LCP-01 (3D)	0.020/0.050	-0.028	0.026	-0.042	0.280	20 / 20
LCP-06 (3D)	0.020/0.050	0.003	0.024	-0.032	0.422	20 / 20
GCP-13 (3D)	0.020/0.050	0.016	0.006	-0.016	0.346	20 / 20
LCP-07 (3D)	0.020/0.050	-0.004	-0.005	-0.024	0.268	20 / 20
LCP-02 (3D)	0.020/0.050	-0.008	0.000	-0.043	0.274	20 / 20
LCP-03 (3D)	0.020/0.050	-0.010	-0.006	-0.006	0.271	20 / 20
GCP-17 (3D)	0.020/0.050	0.010	0.008	-0.020	0.288	20 / 20
LCP-04 (3D)	0.020/0.050	0.010	-0.012	-0.002	0.305	20 / 20
LCP-09 (3D)	0.020/0.050	-0.010	-0.012	-0.019	0.292	20 / 20
GCP-12 (3D)	0.020/0.050	0.004	-0.001	-0.009	0.204	20 / 20
LCP-14 (3D)	0.020/0.050	-0.001	-0.022	-0.033	0.272	20 / 20
GCP-14 (3D)	0.020/0.050	0.023	0.003	-0.015	0.286	20 / 20
LCP-23 (3D)	0.020/0.050	0.004	-0.011	-0.002	0.294	20 / 20
GCP-16 (3D)	0.020/0.020	0.003	-0.008	0.018	0.191	20 / 20
Mean [m]		0.000007	-0.000044	-0.001868		
Sigma [m]		0.014826	0.015214	0.028236		
RMS Error [m]		0.014826	0.015214	0.028298		



## Geometric Calibration of the Small-Format Oblique Camera System

Evaluation Result: (ตรวจสอบอีกครั้งหลังจากแทนค่าพารามิเตอร์ได้ถูกต้อง)

	Error X	Error Y (m)	Error Z (m)	Projection Error
Criterion	0.035 m	0.035 m	0.065 m	0.5 pixel
Full GCPs	?	?	?	?

Pending and not be used.