

# Why Adversarial Interaction Creates Non-Homogeneous Patterns: A Pseudo-Reaction Diffusion Model for Turing Instability

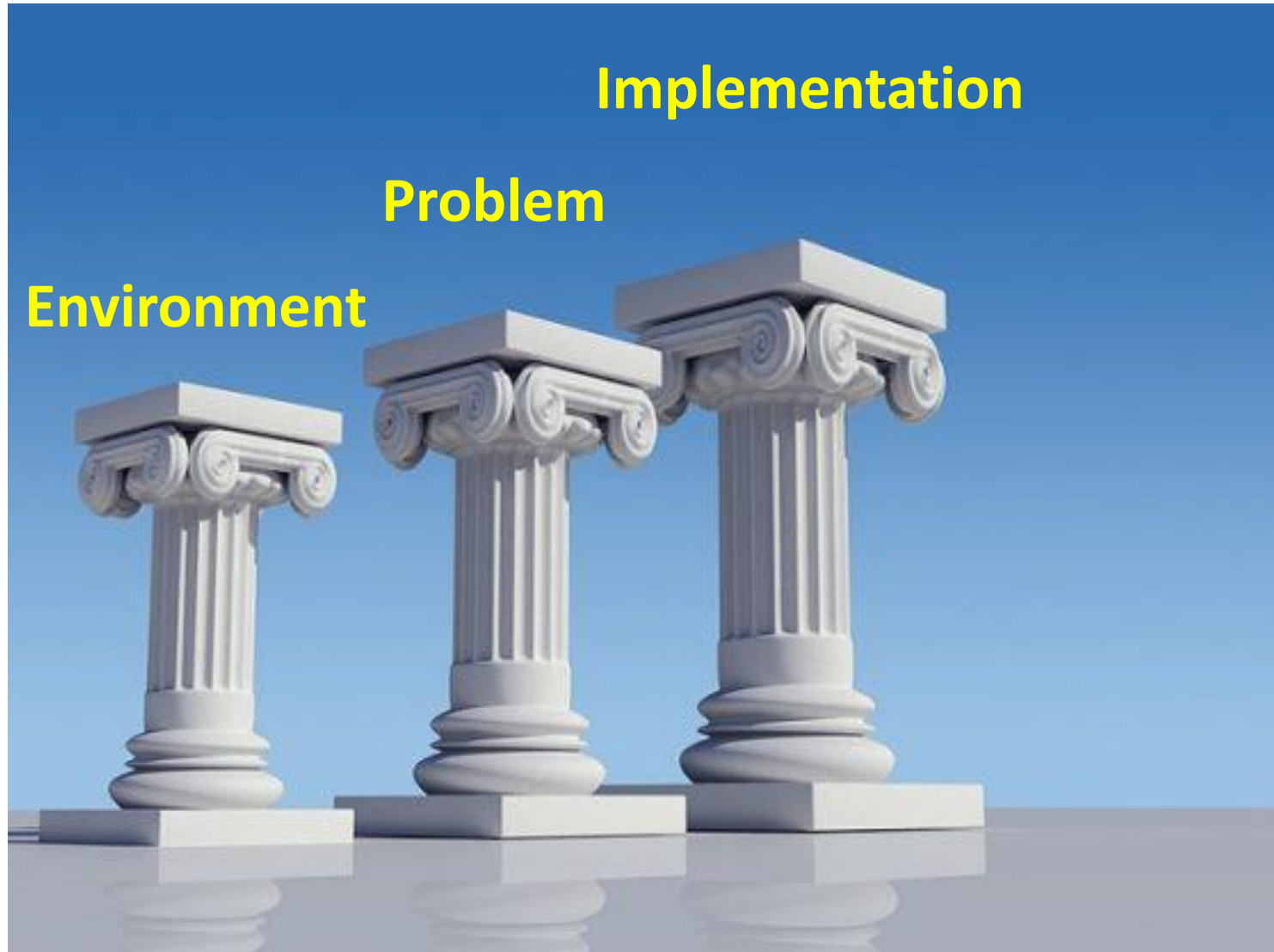
**Litu Rout**

Association for the Advancement of Artificial Intelligence (AAAI-21)

# Why Adversarial Interaction Creates Non-Homogeneous Patterns: A Pseudo-Reaction Diffusion Model for Turing Instability

- Adversarial Interaction
  - Generative Adversarial Networks (GANs)
  - Application of conditional GANs
- Non-Homogeneous Patterns
  - Homogeneous patterns
  - Supervised learning
- Reaction-Diffusion
  - Turing's RD model (1952)
  - Gray-Scott RD model (1984)
- Turing Instability
  - Reaction dynamics
  - Diffusion dynamics

# Three Pillars of Deep Learning



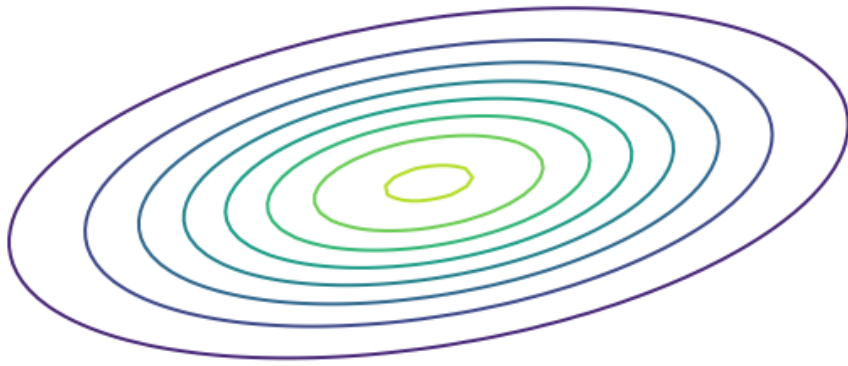
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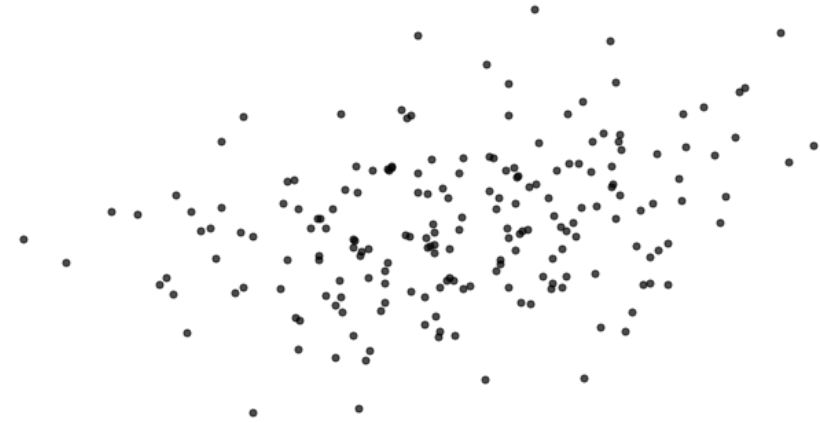
# Outline

- Maximum Likelihood Estimation
- Reverse KL Divergence
- Introduction to GANs
- GANs in Remote Sensing

# Generative Modeling: Density Estimation

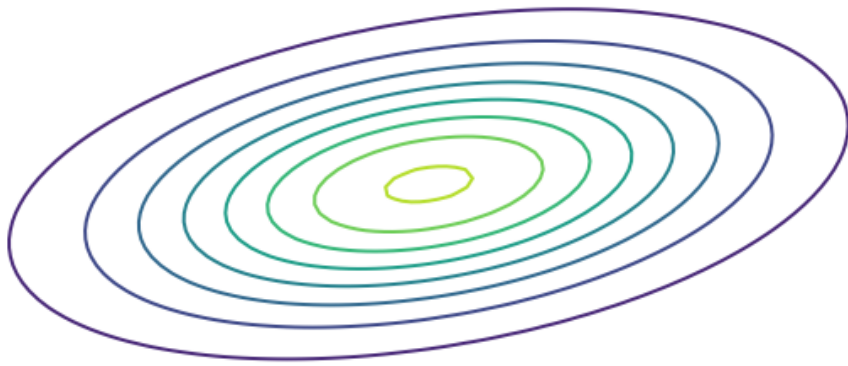


(a)

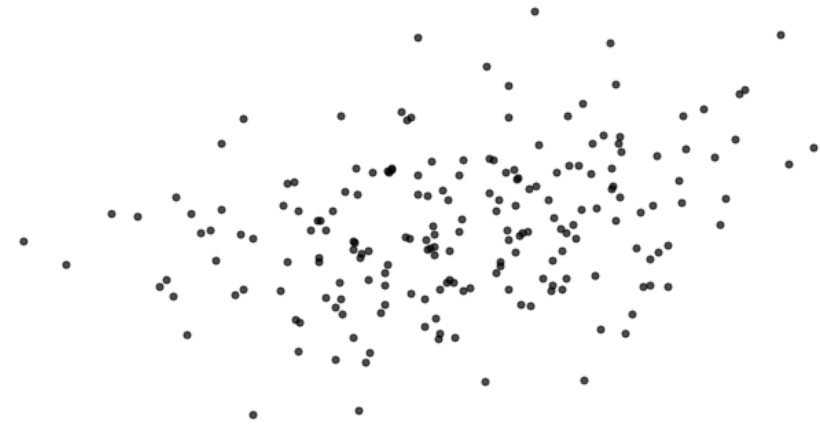


(b)

# Generative Modeling: Density Estimation



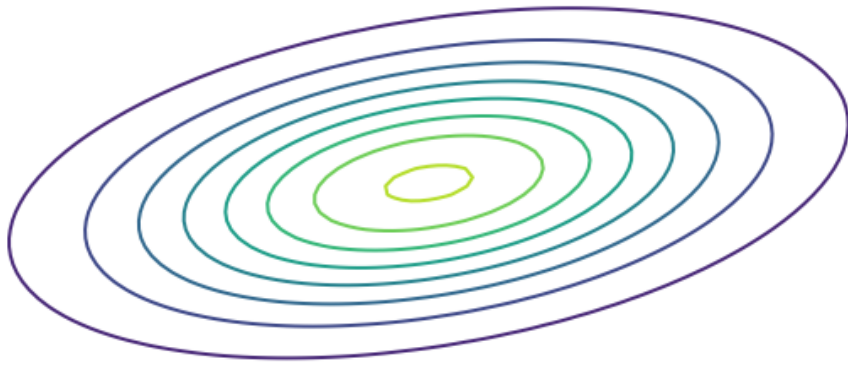
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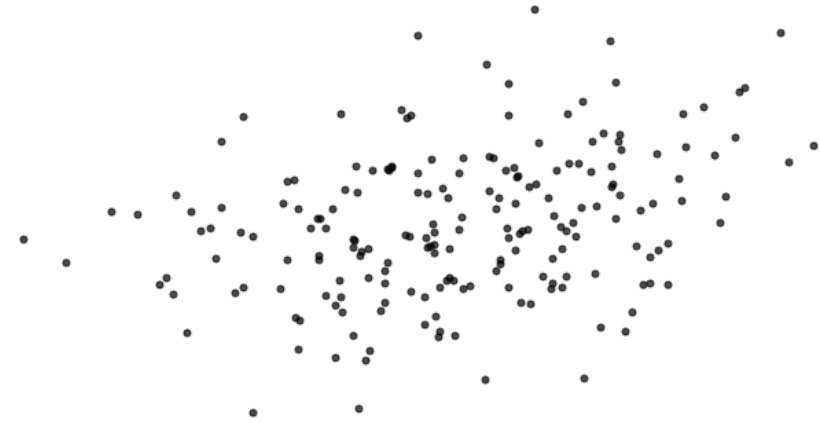
(b)

$$\begin{aligned}\theta^* &= \arg \min_{\theta} \text{KL}(p(x) || q_{\theta}(x)) \\ &= \arg \min_{\theta} \mathbb{E}_{x \sim p} [\log p(x) - \log q_{\theta}(x)] \\ &= \arg \min_{\theta} \mathbb{E}_{x \sim p} [\log p(x)] - \mathbb{E}_{x \sim p} [\log q_{\theta}(x)]\end{aligned}$$

# Generative Modeling: Density Estimation



(a)

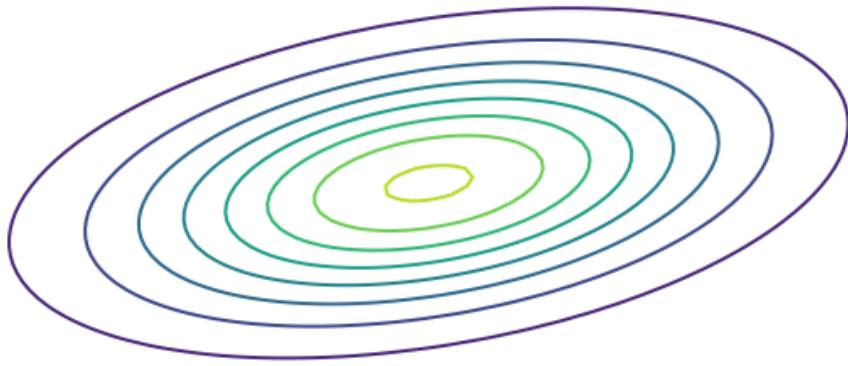


(b)

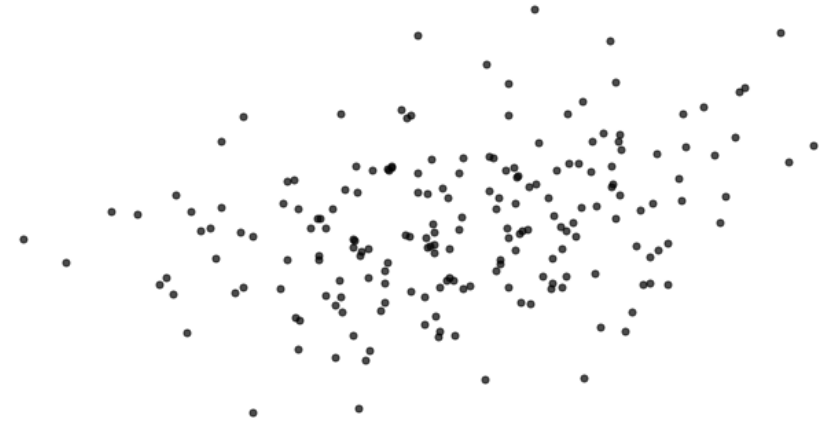
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# Generative Modeling: Density Estimation



(a)

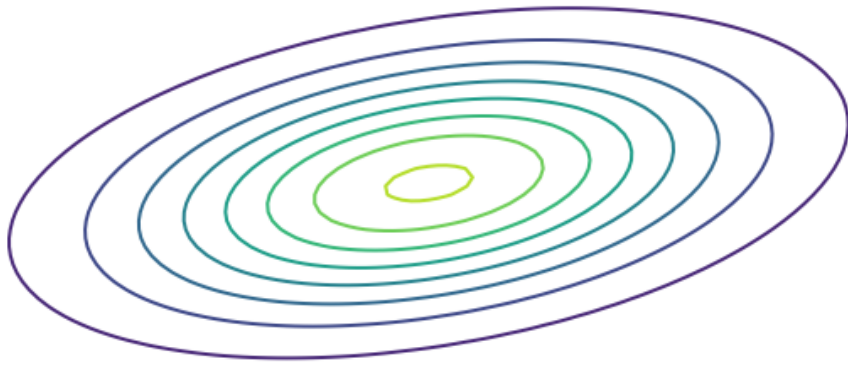


(b)

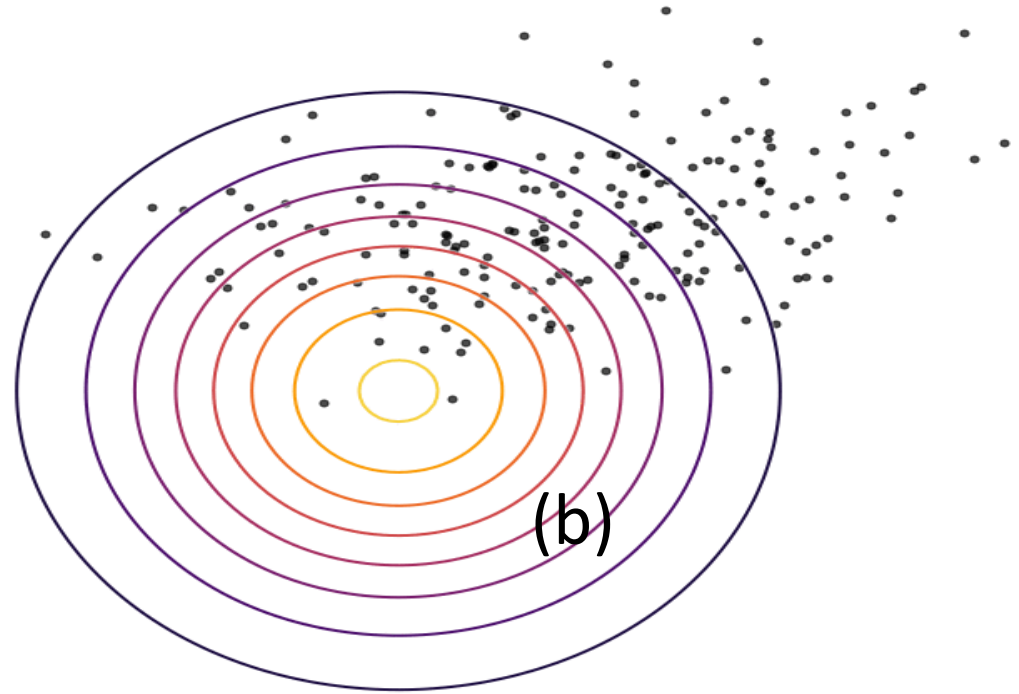
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$$\theta(t+1) = \theta(t) + \eta \frac{\partial L(\theta)}{\partial \theta(t)}$$

# Generative Modeling: Density Estimation

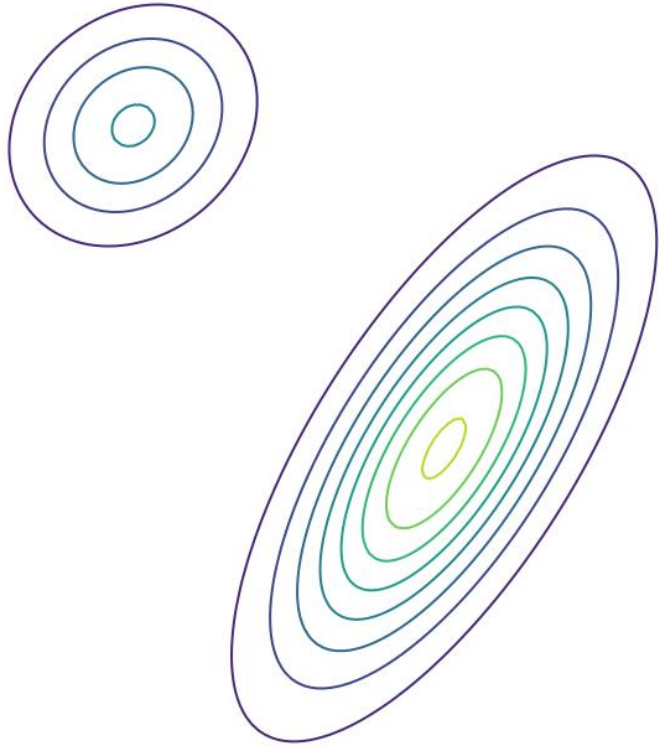


(a)

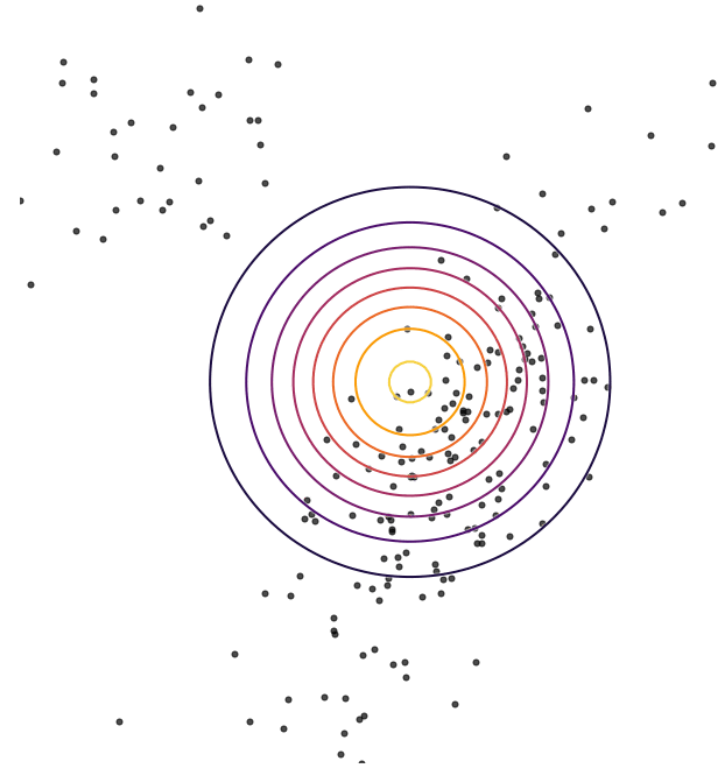


(b)

# Generative Modeling: Density Estimation

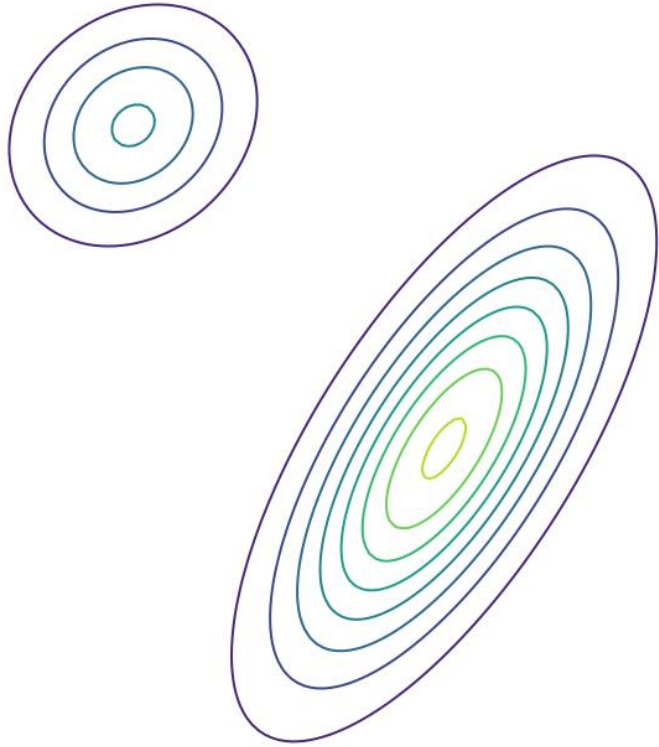


(a)



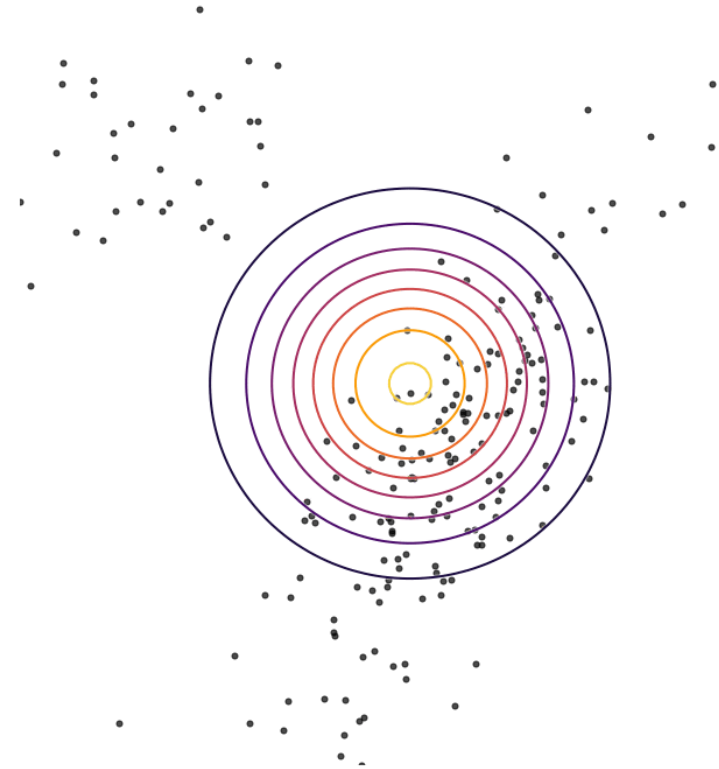
(b)

# Generative Modeling: Density Estimation



(a)

$$\theta^* = \arg \max_{\theta} \mathbb{E}_{x \sim p} [\log q_{\theta}(x)]$$

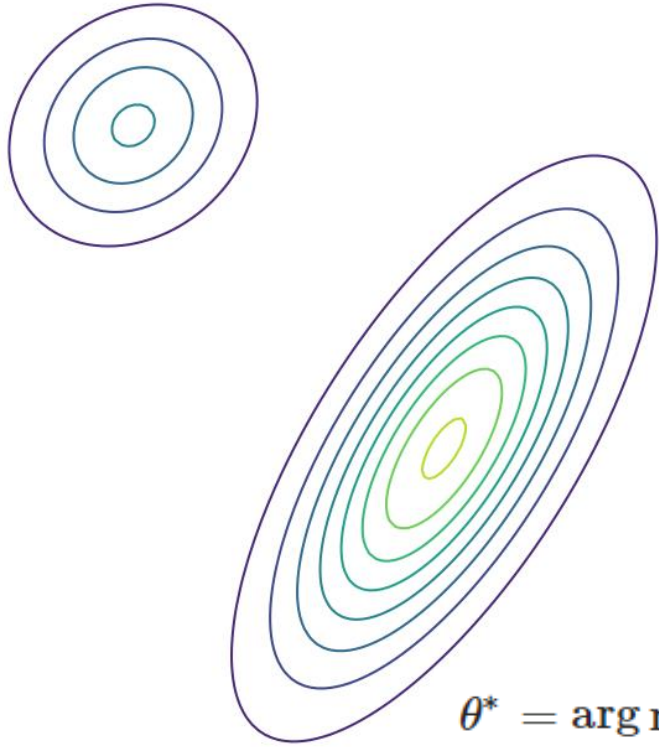


(b)

# Outline

- Maximum Likelihood Estimation
- Reverse KL Divergence
- Introduction to GANs
- GANs in Remote Sensing

# Generative Modeling: Density Estimation



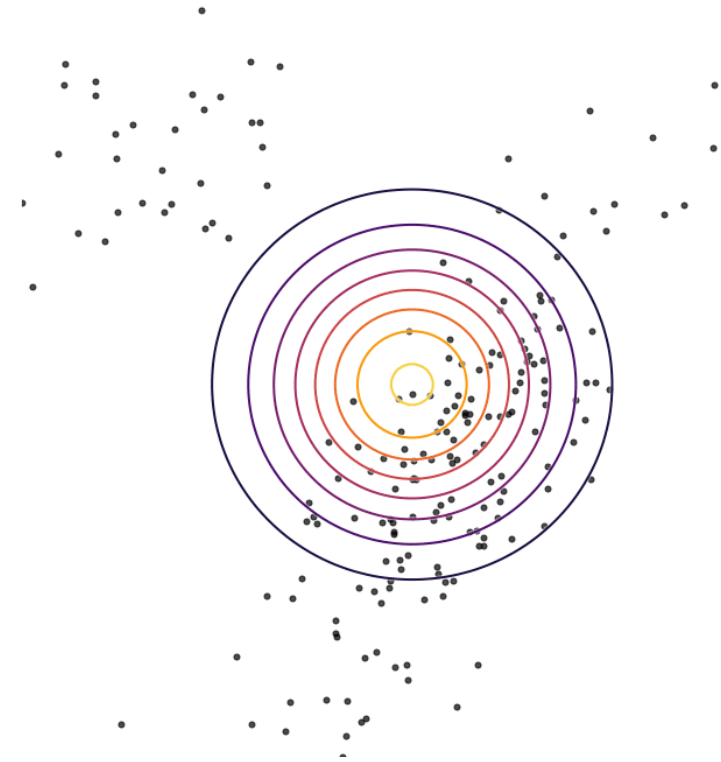
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$$\theta^* = \arg \min_{\theta} \text{KL}(q_{\theta} || p)$$

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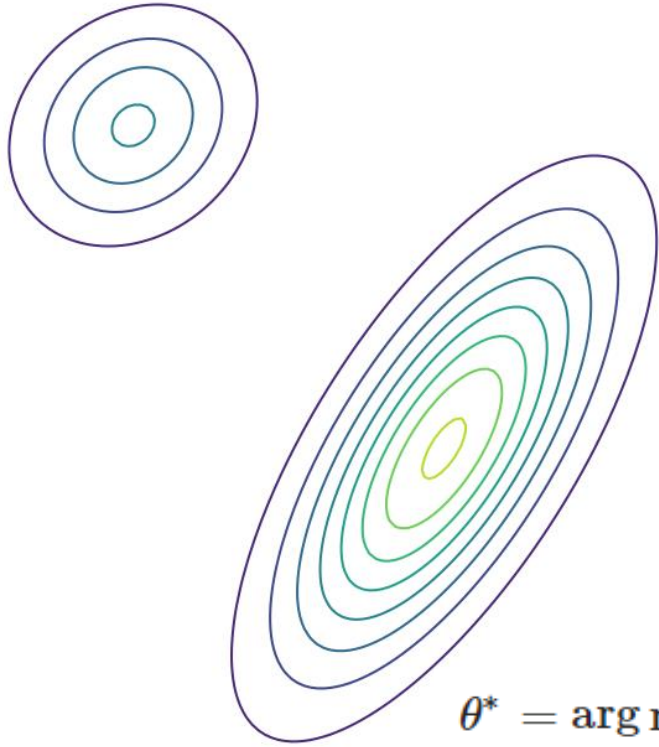
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$$= \arg \max_{\theta} -\mathbb{E}_{x \sim q_{\theta}} [\log q_{\theta}(x)] + \mathbb{E}_{x \sim q_{\theta}} [\log p(x)]$$



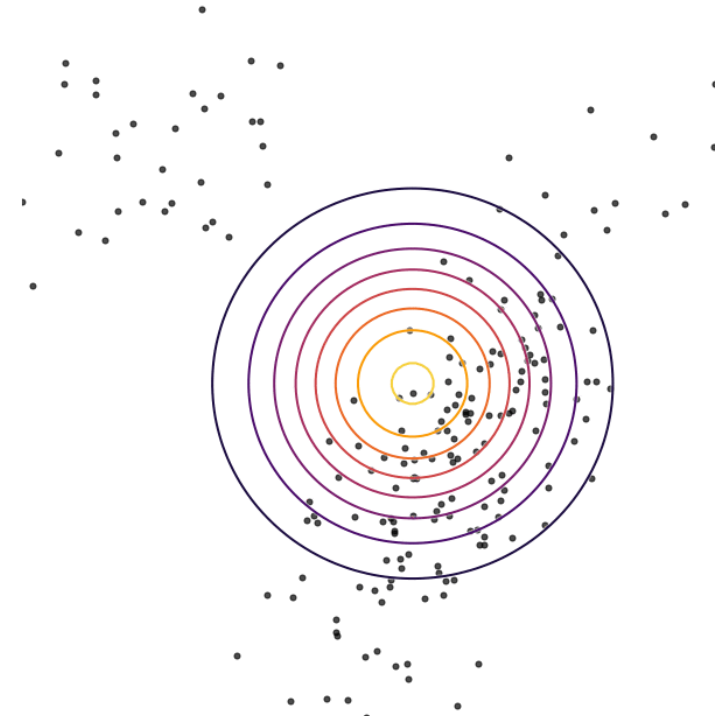
(b)

# Generative Modeling: Density Estimation



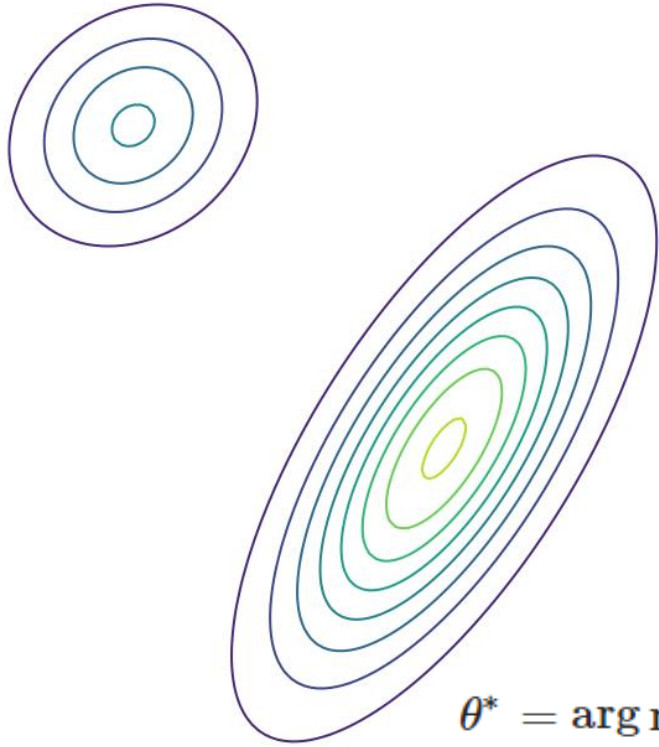
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(b)

# Generative Modeling: Density Estimation



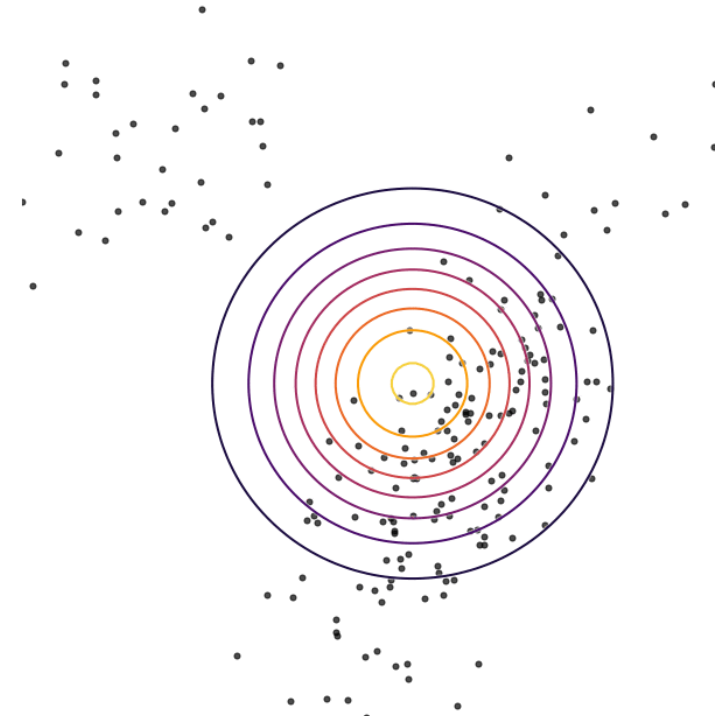
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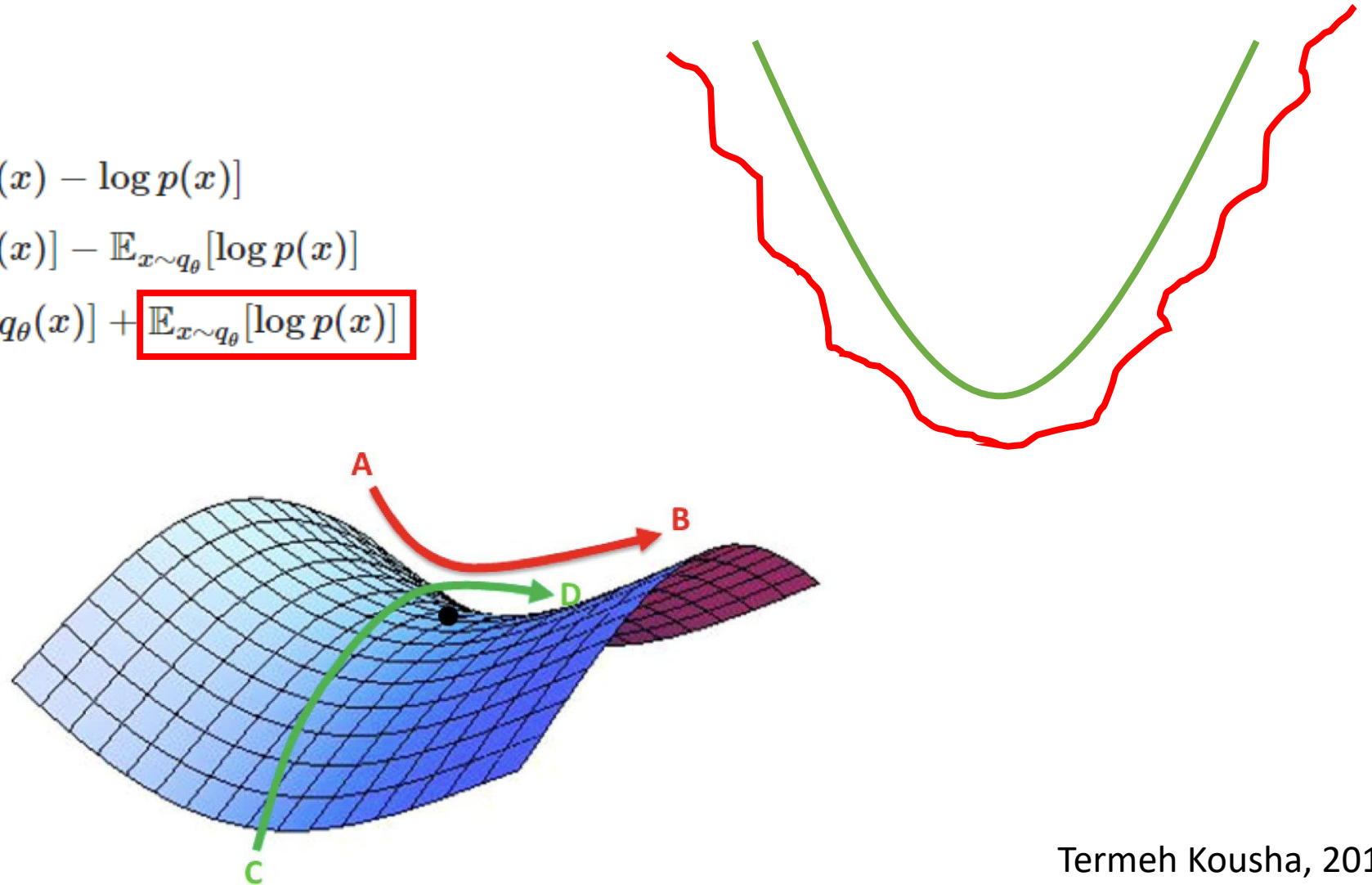


(b)



# Generative Modeling: Density Estimation

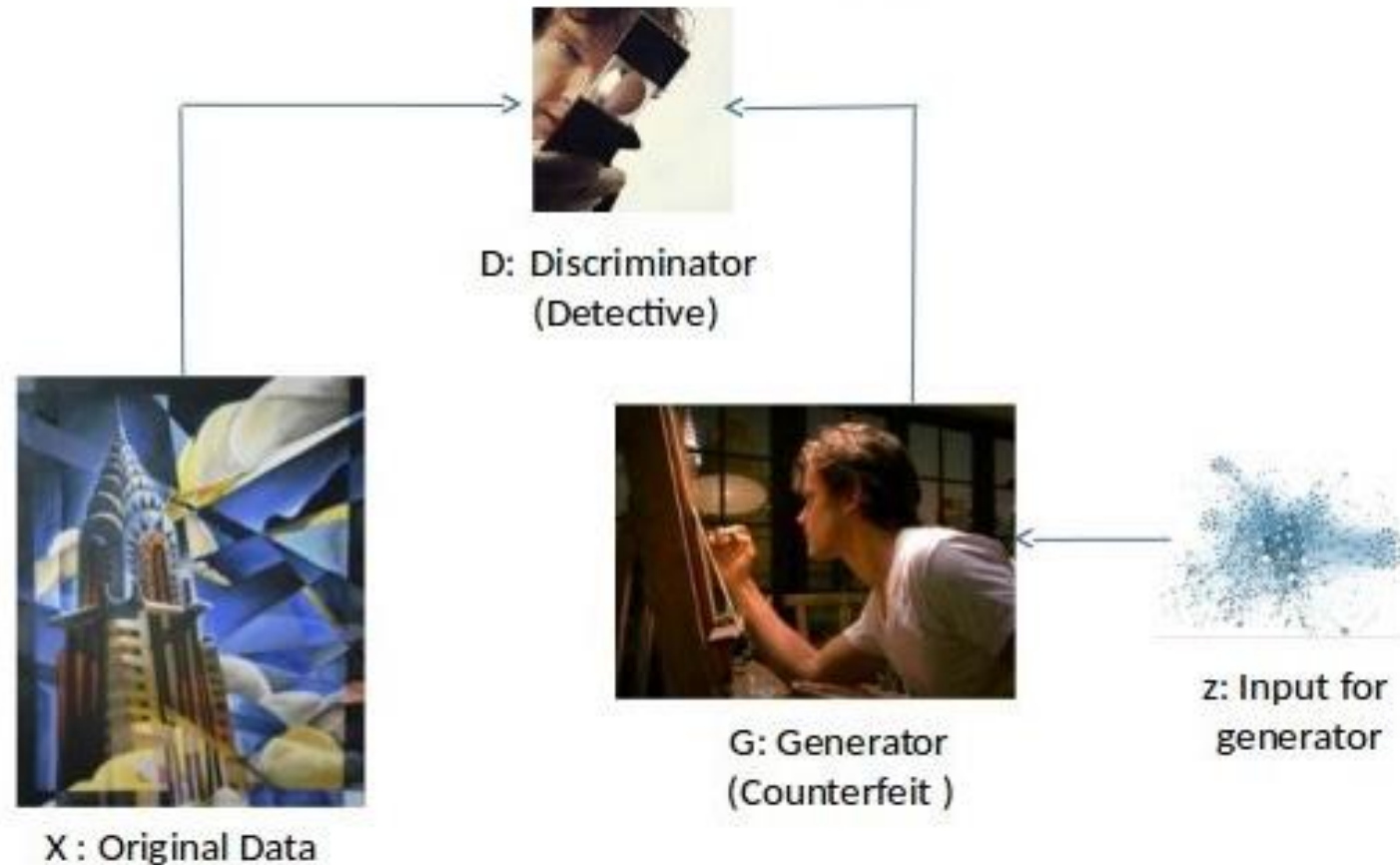
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# Outline

- Maximum Likelihood Estimation
- Reverse KL Divergence
- Introduction to GANs
- GANs in Remote Sensing

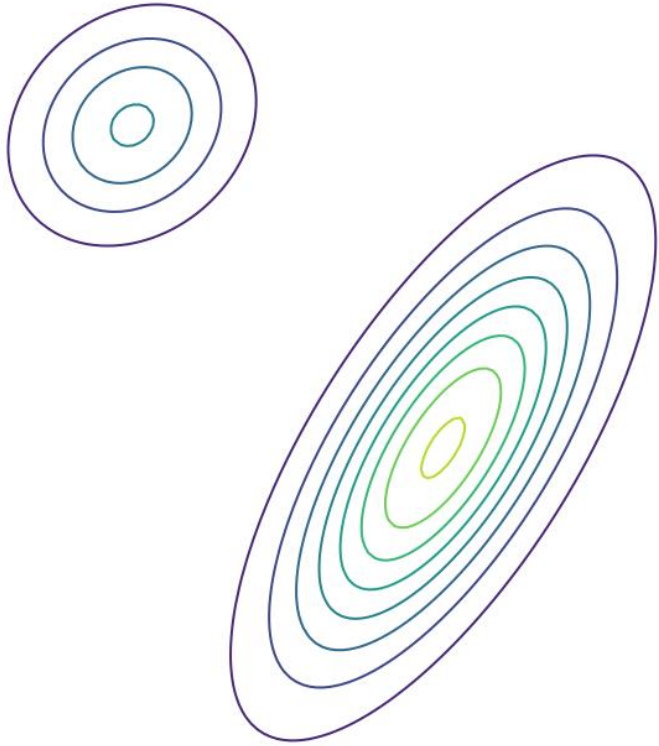
# Generative Modeling: Density Estimation



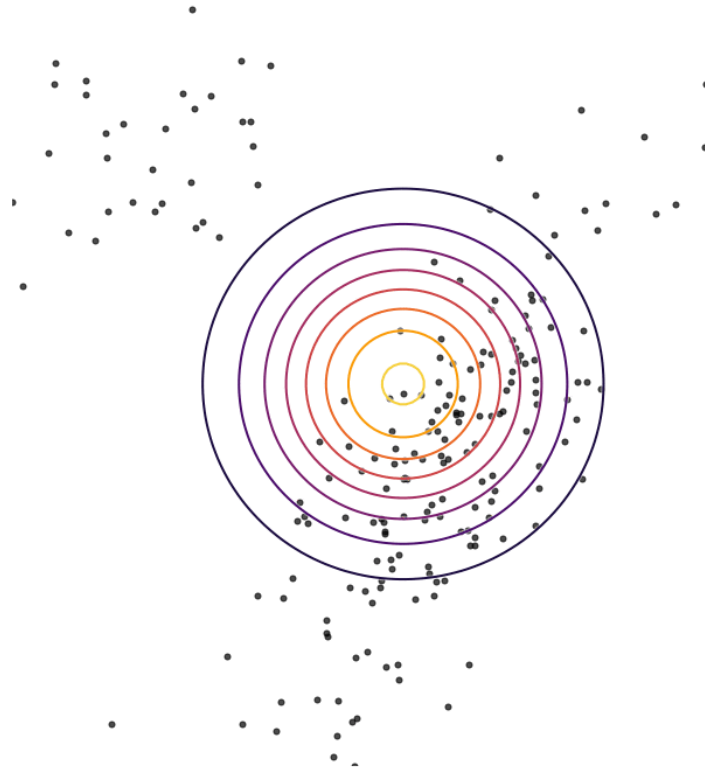
$$\theta^* = \arg \min_{\theta} \max_{\phi} \mathbb{E}_{x \sim p, \hat{x} \sim q_{\theta}} V(f_{\phi}(x), f_{\phi}(\hat{x}))$$

$$V(f_{\phi}(x), f_{\phi}(\hat{x})) = \log f_{\phi}(x) + \log[1 - f_{\phi}(\hat{x})]$$

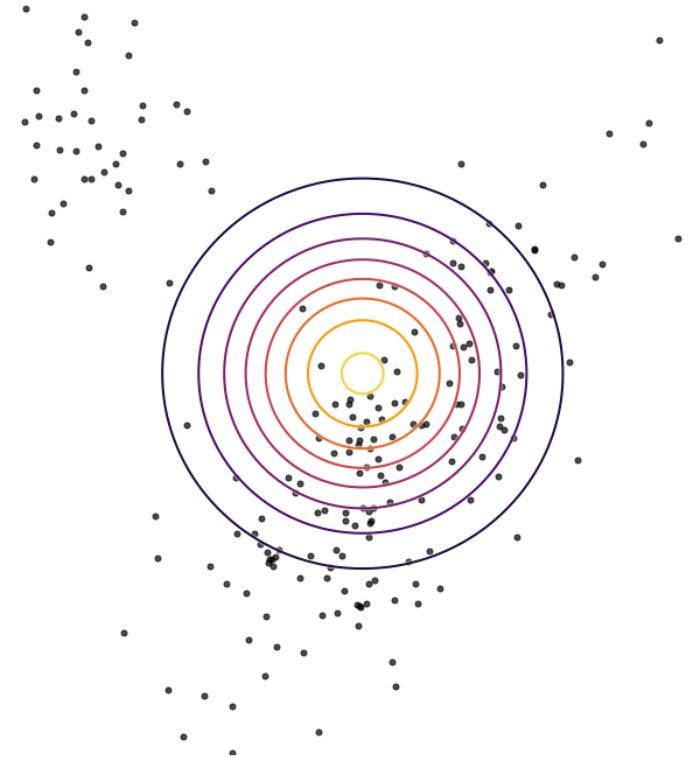
# Generative Modeling: Density Estimation



(a)



(b)

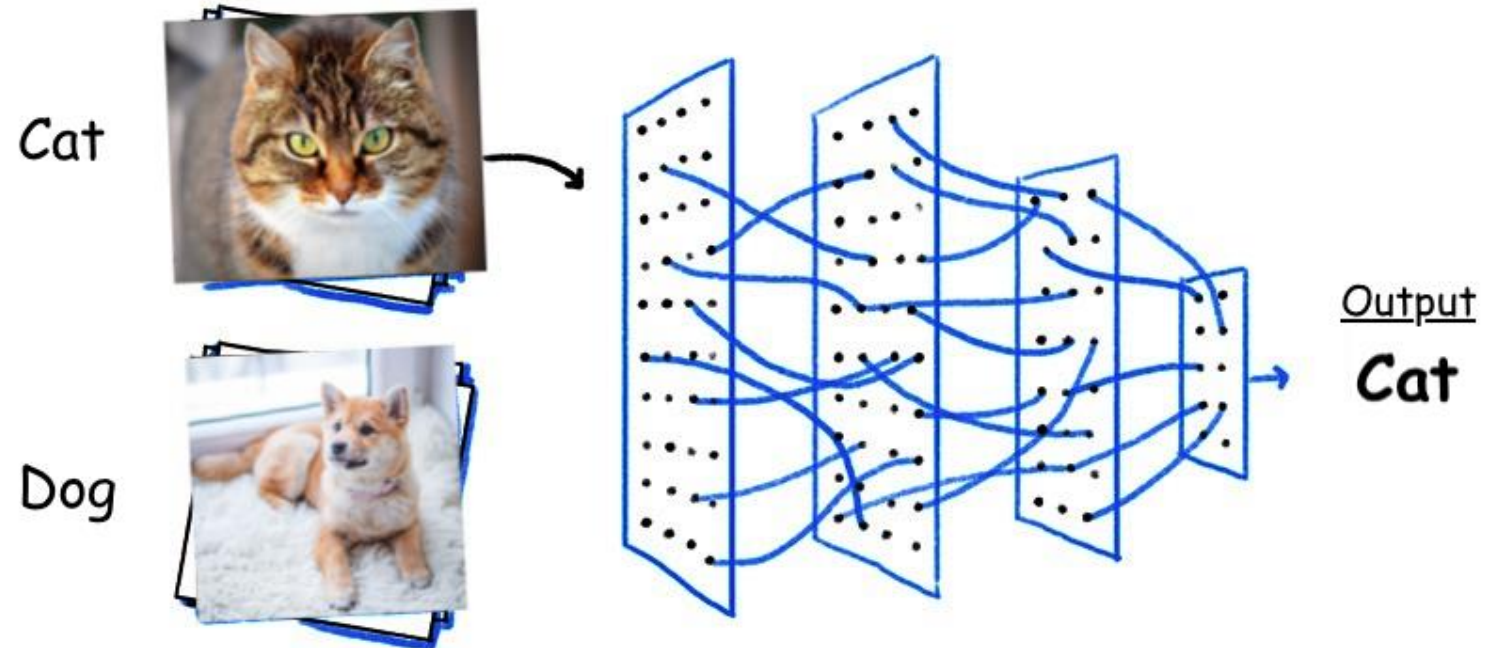


(c)

# Why Generative Adversarial Networks?

- Image Classification as Discriminator

- Given input  $X$ , predict label  $Y$
- Estimate  $P(Y|X)$



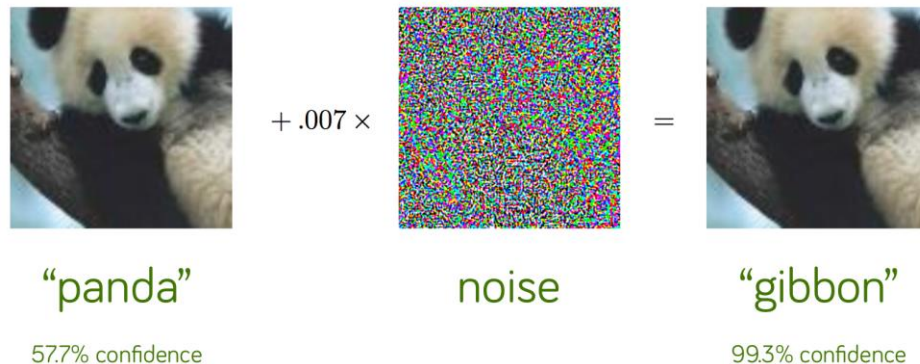
# Why Generative Adversarial Networks?

- Image Classification as Discriminator

- Given input  $X$ , predict label  $Y$
- Estimate  $P(Y|X)$

- Challenges in Discriminative Models

- Unknown  $P(X)$
- Can't sample from  $P(X)$



What I cannot create, I do not understand.

— Richard P. Feynman —





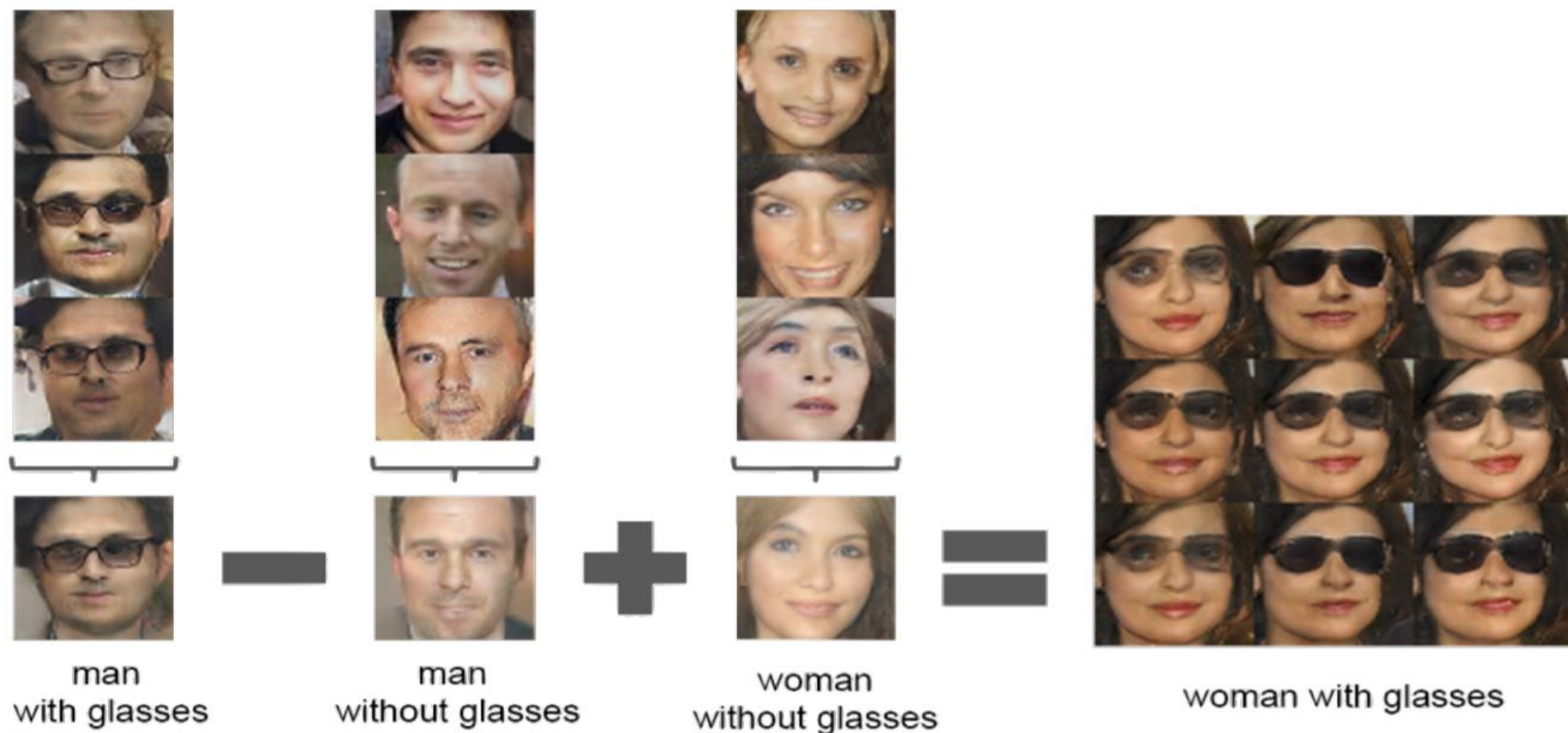
# Why Generative Adversarial Networks?

- Image Classification as Discriminator
  - Given input  $X$ , predict label  $Y$
  - Estimate  $P(Y|X)$
- Challenges in Discriminative Models
  - Unknown  $P(X)$
  - Can't sample from  $P(X)$
- Motivation for GANs
  - Model  $P(X)$
  - Generate new samples

Faces Dataset



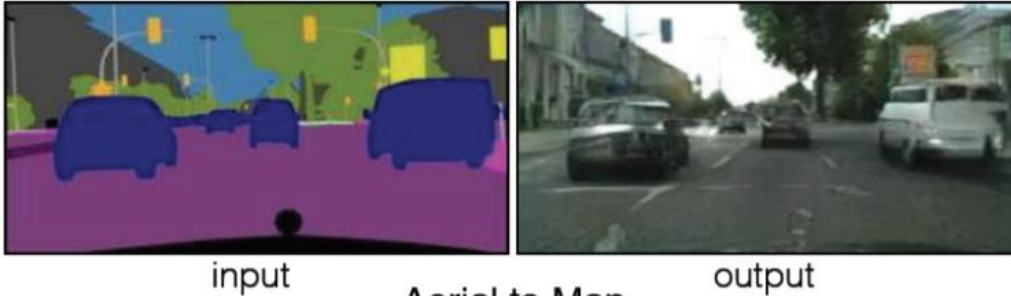
# Generative Modeling: Latent Space Interpolation



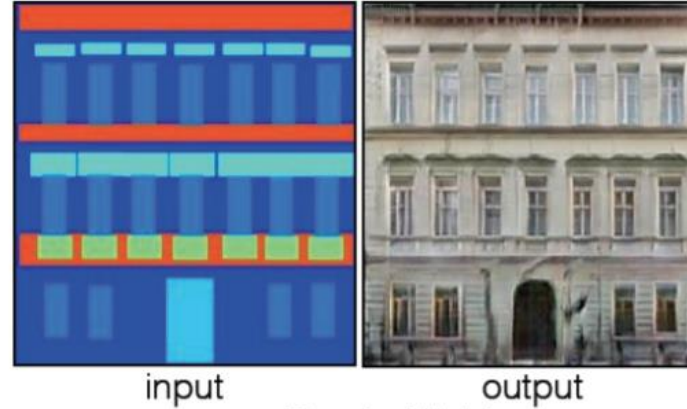


# Generative Modeling: Image-to-Image Translation

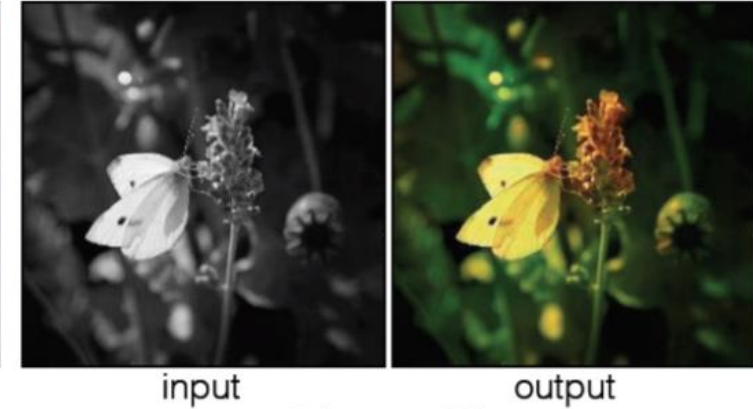
Labels to Street Scene



Labels to Facade



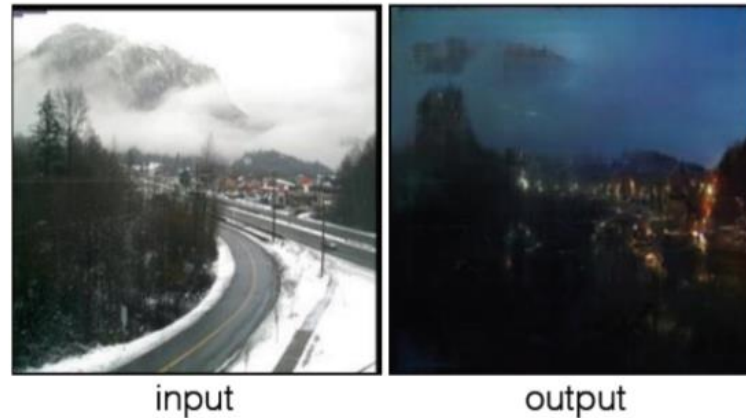
BW to Color



Aerial to Map



Day to Night

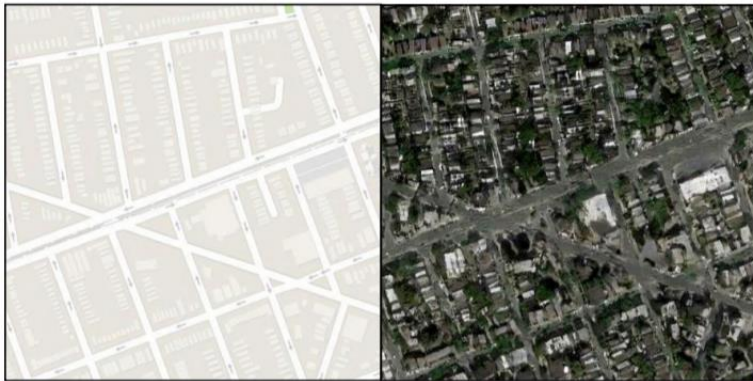
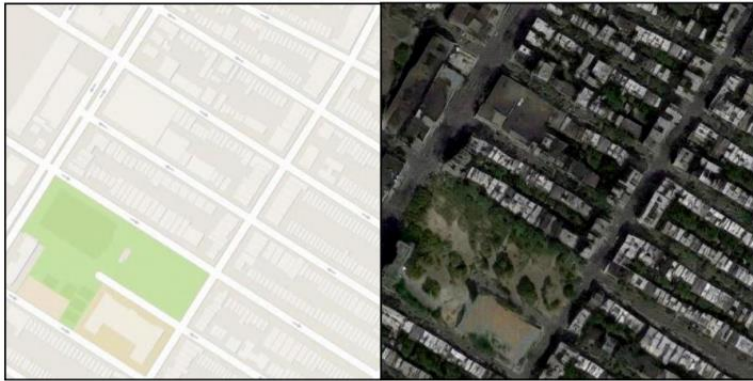


Edges to Photo



# Generative Modeling: Image-to-Image Translation

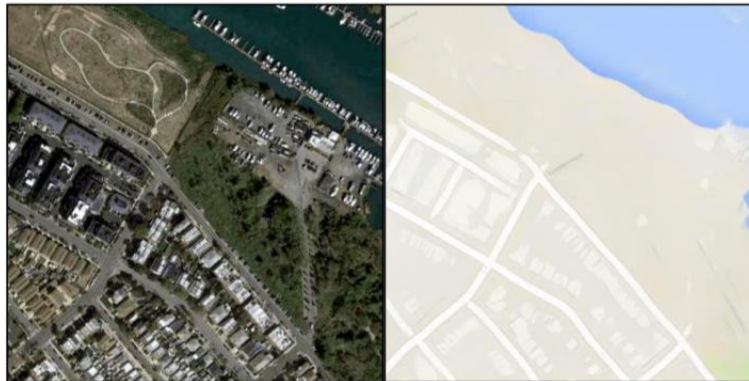
Map to aerial photo



input

output

Aerial photo to map

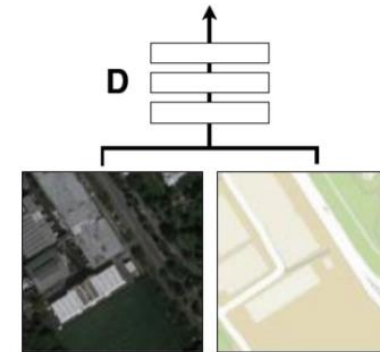


input

output

Positive examples

Real or fake pair?

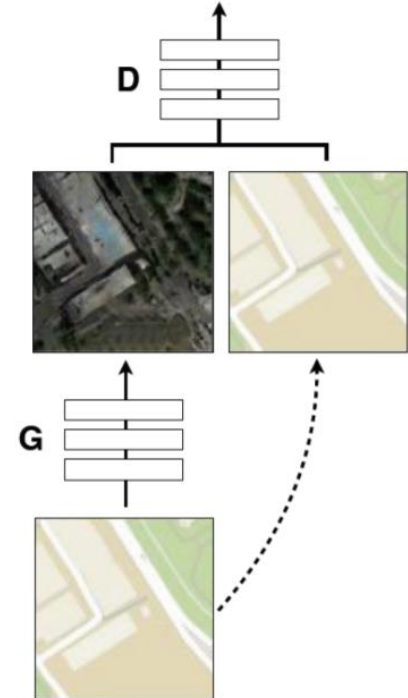


**G** tries to synthesize fake images that fool **D**

**D** tries to identify the fakes

Negative examples

Real or fake pair?





# Generative Modeling: Sample Generation

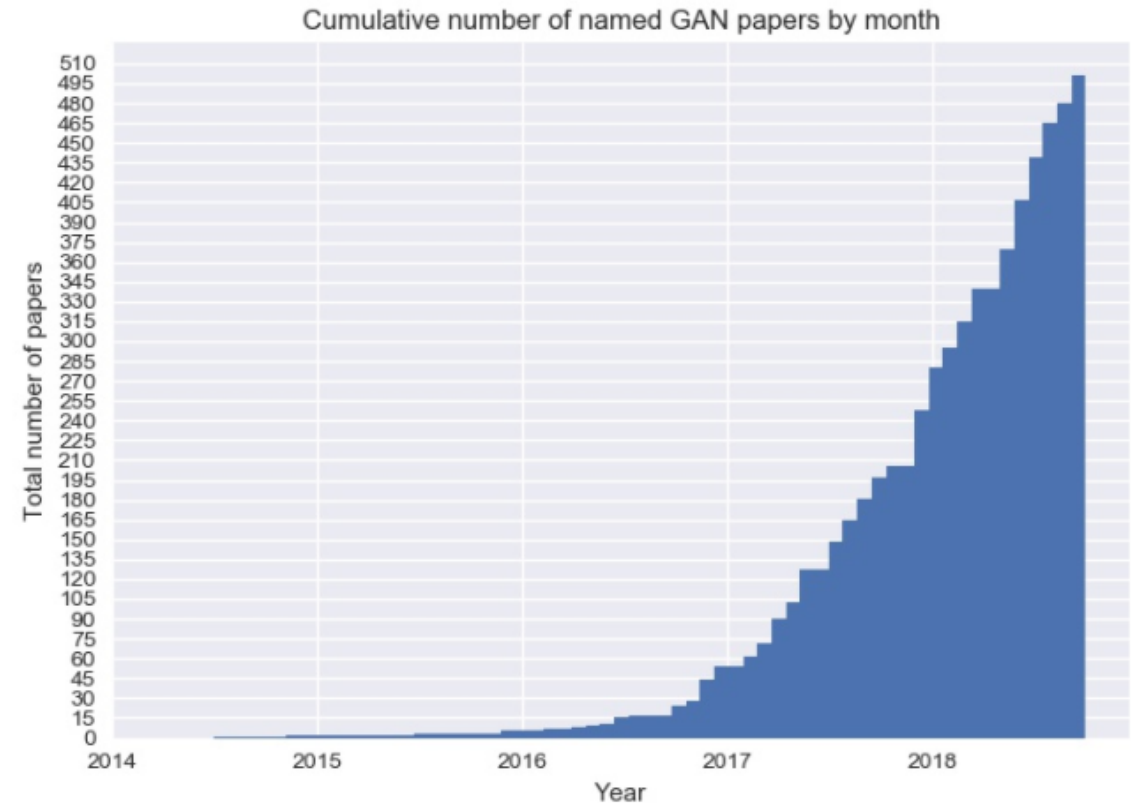


Training Data  
(CelebA)



Sample Generator  
(Karras et al, 2017)

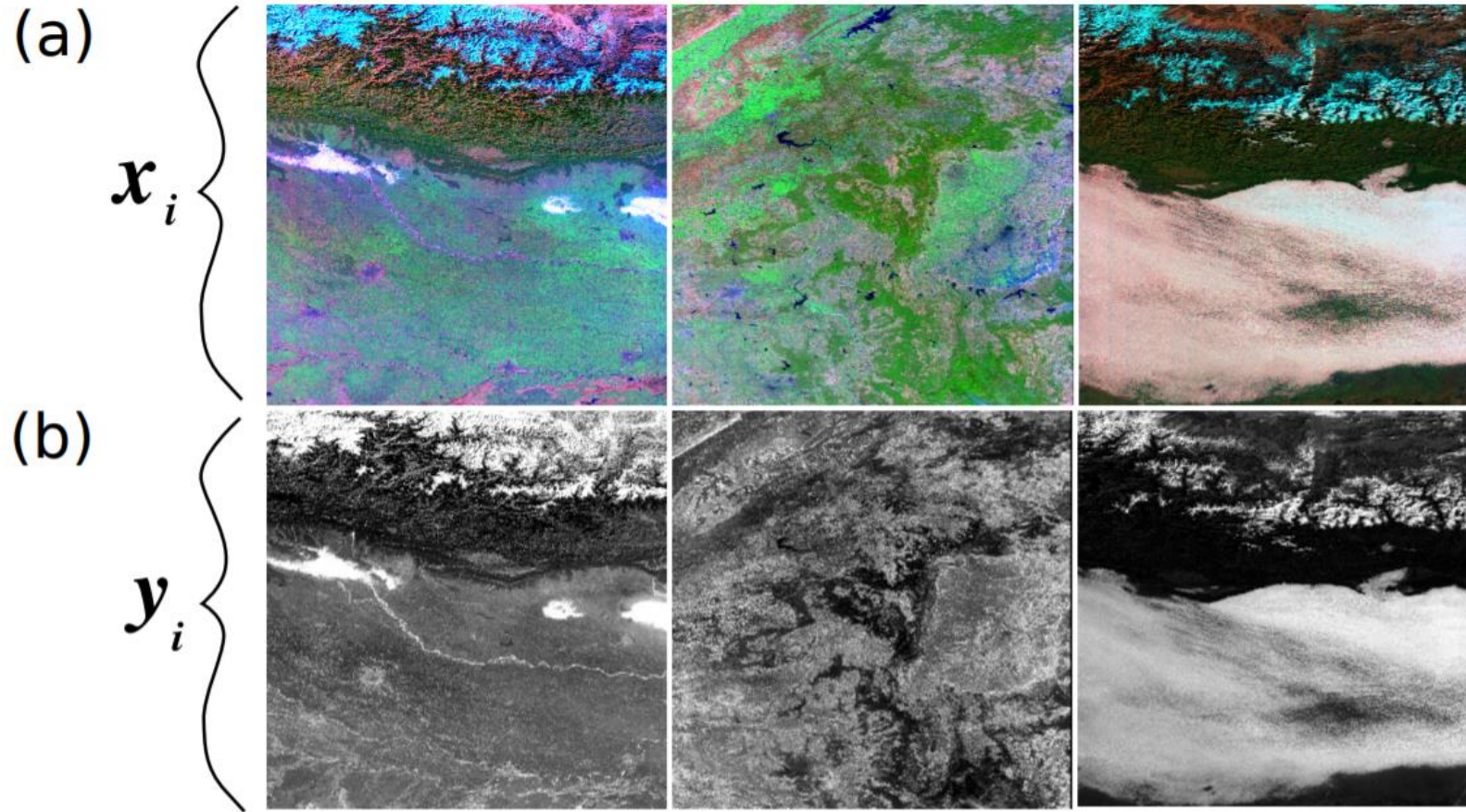
# Generative Modeling: Sample Generation



# Outline

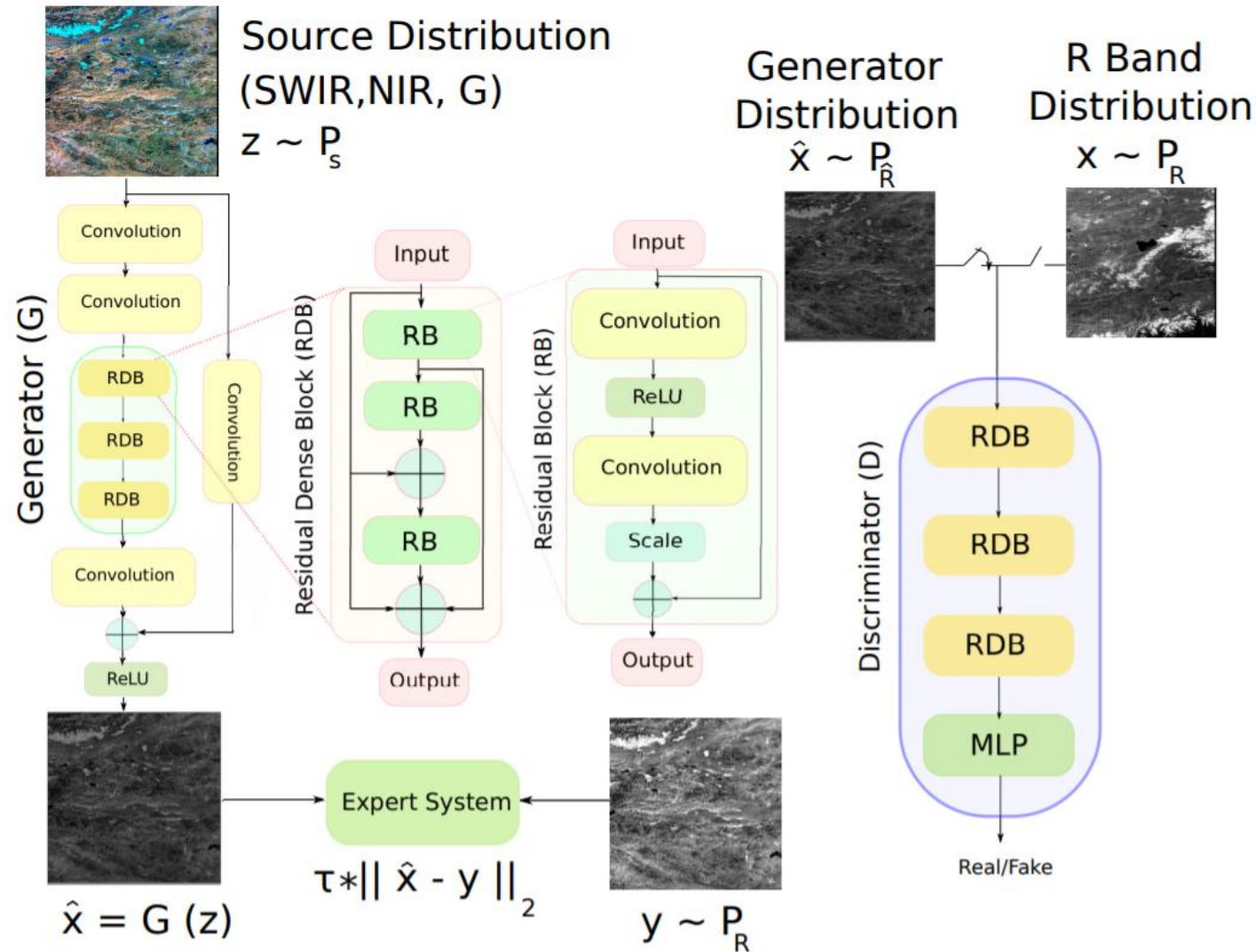
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- Reverse KL Divergence
- Introduction to GANs
- GANs in Remote Sensing

# Generative Modeling: Missing Data Reconstruction





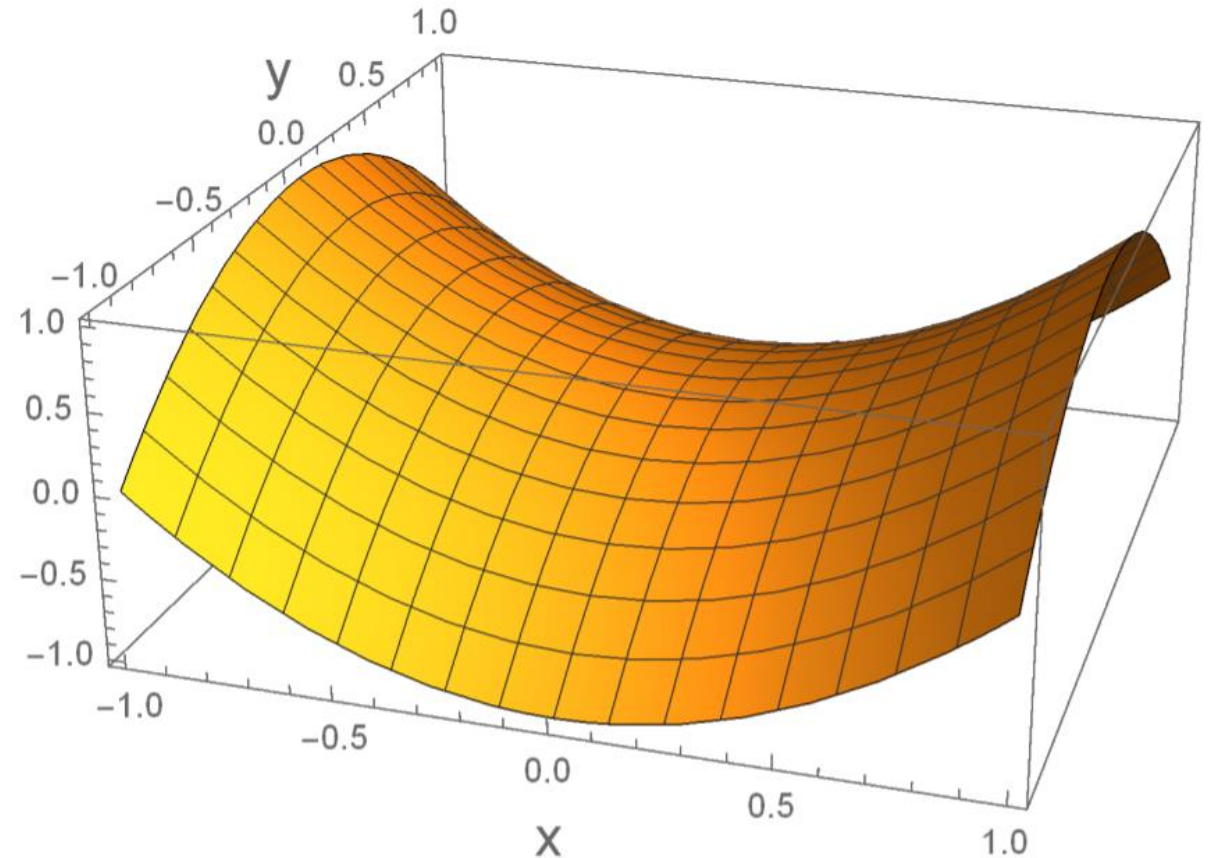
# Generative Modeling: Missing Data Reconstruction



# Generative Modeling: Missing Data Reconstruction

$$\min_G \mathbb{E}_{x \sim \mathbb{P}_R} [D(x)] - \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{R}}} [D(\hat{x})] \\ + \mathbb{E}_{y \sim \mathbb{P}_R} [\|\tau(\hat{x} - y)\|_2],$$

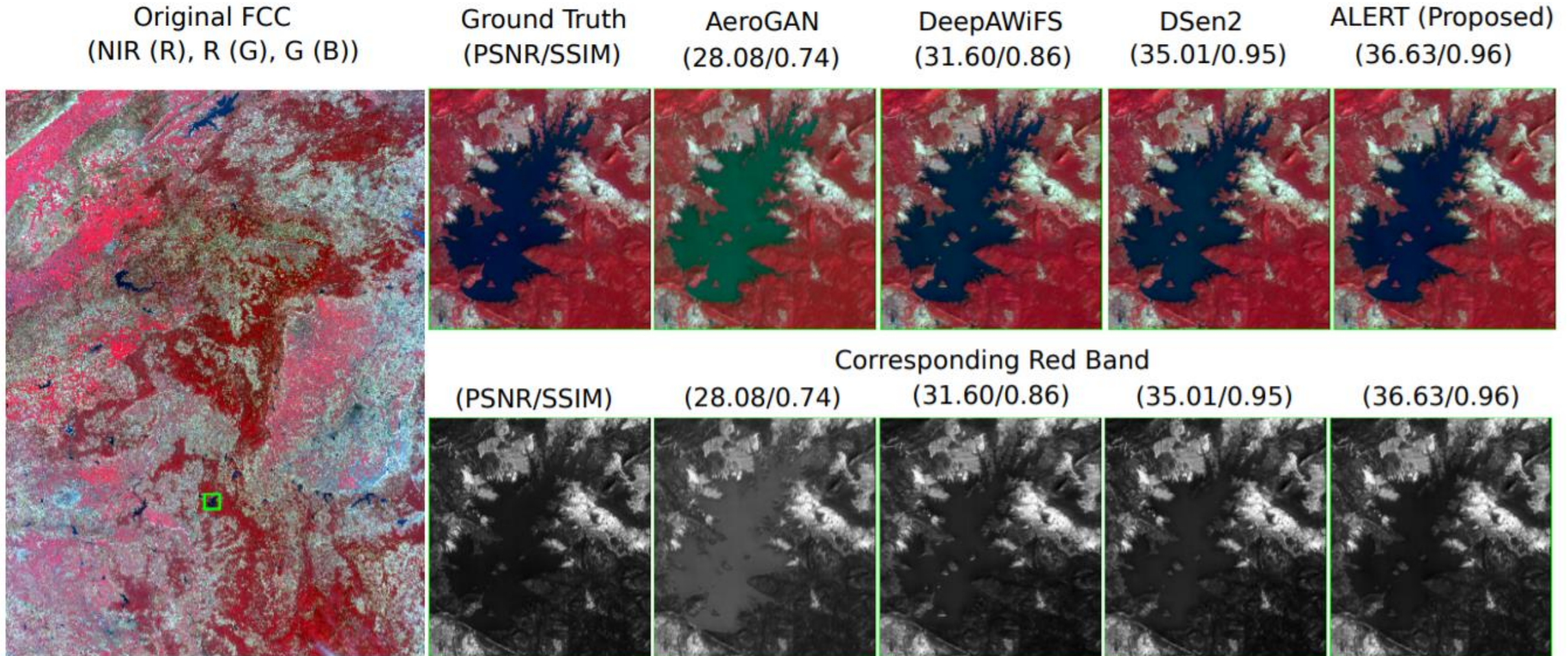
$$\min_D \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{R}}} [D(\hat{x})] - \mathbb{E}_{x \sim \mathbb{P}_R} [D(x)] \\ + \lambda \mathbb{E}_{\tilde{x} \sim \mathbb{P}_{\tilde{R}}} [(\|\nabla_{\tilde{x}} D(\tilde{x})\|_2 - 1)^2]$$



Jin et al. 2020, ICML

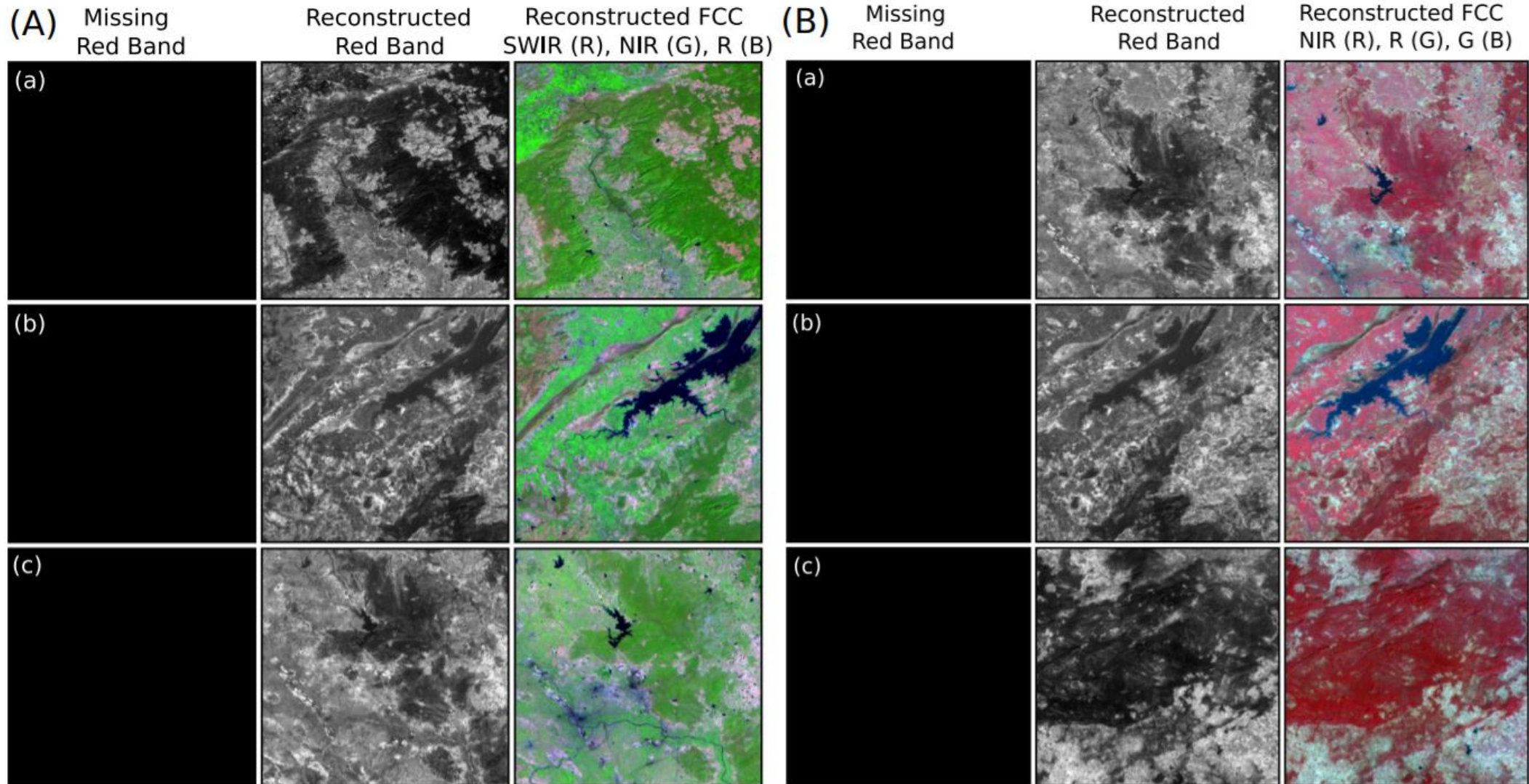


# Generative Modeling: Missing Data Reconstruction





# Generative Modeling: Missing Data Reconstruction



# Generative Modeling: Missing Data Reconstruction





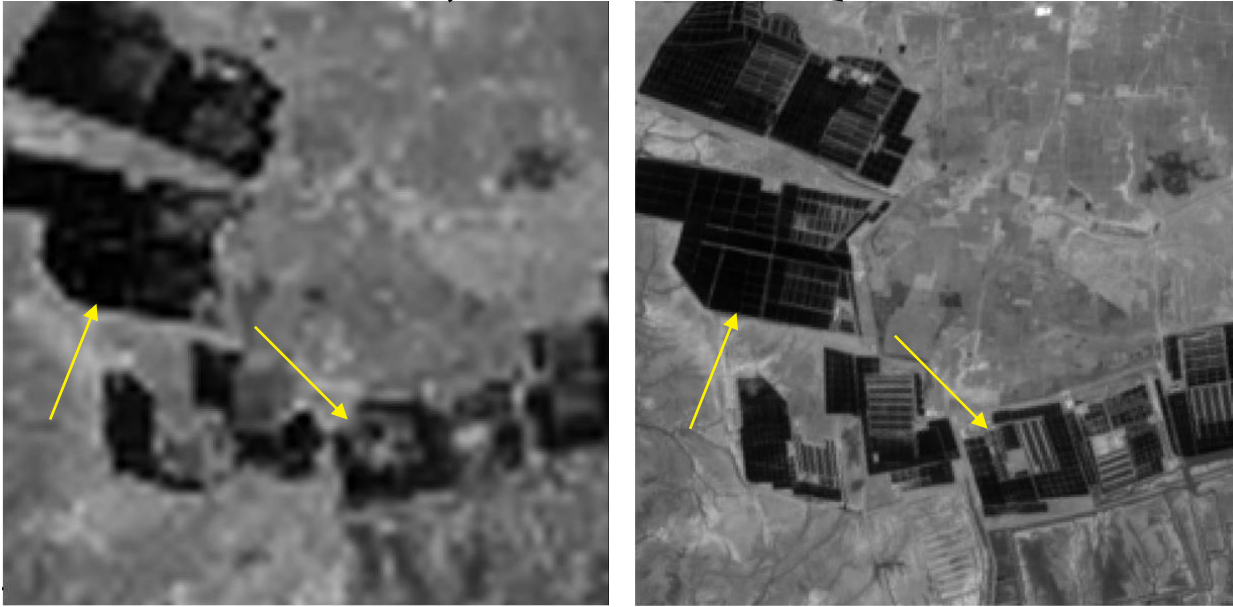
# Outline

- Maximum Likelihood Estimation
- Reverse KL Divergence
- Introduction to GANs
- GANs in Remote Sensing
  - Problem Formulation

# Super-resolution as conditional band synthesis

LR-SWIR

HR-SWIR



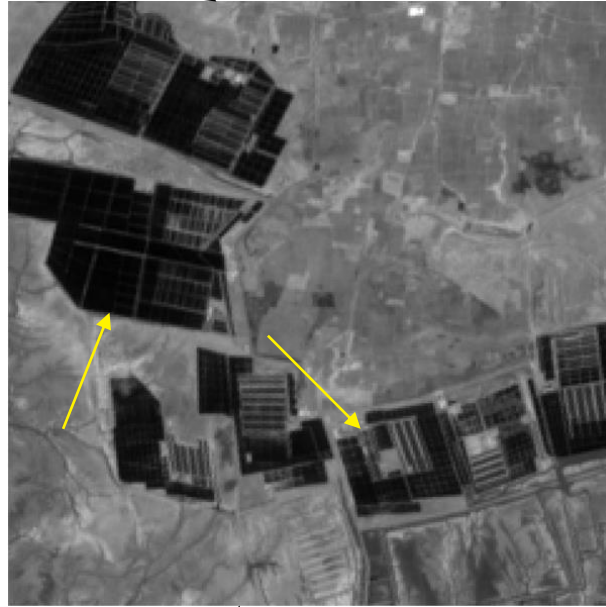
- Direct super-resolution is intractable.
- Lack necessary geometric attributes.

# Super-resolution as conditional band synthesis

LR-SWIR

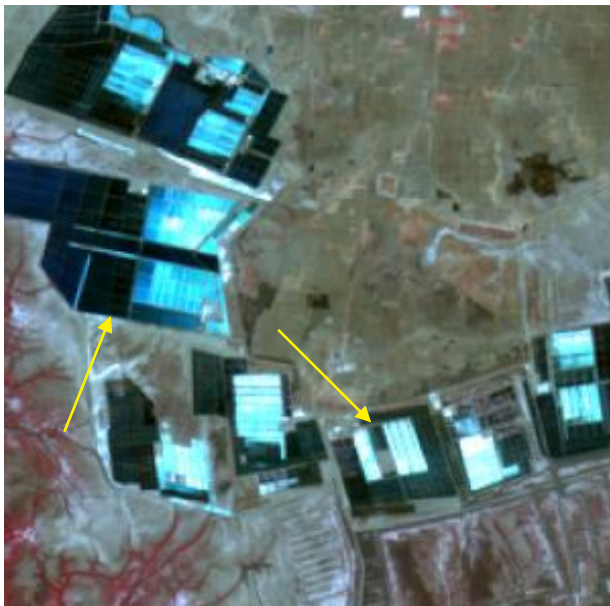


HR-SWIR



- Direct super-resolution is intractable.
- Lack necessary geometric attributes.

- Reformulate as conditional band synthesis.
- Geometry from existing high resolution bands: HR-NIR, R, G.
- Radiometry from corresponding low resolution band: LR-SWIR.



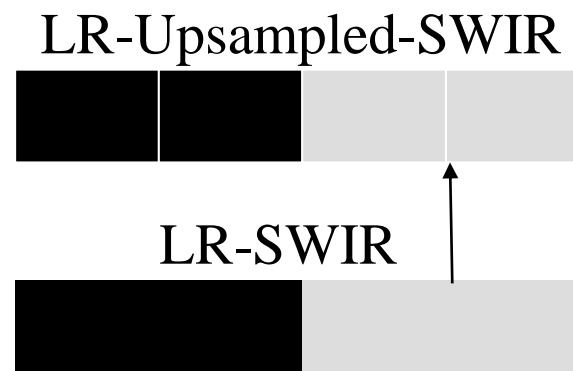
FCC: NIR (R), R (G), G(B)

# Traditional Approach

LR-SWIR

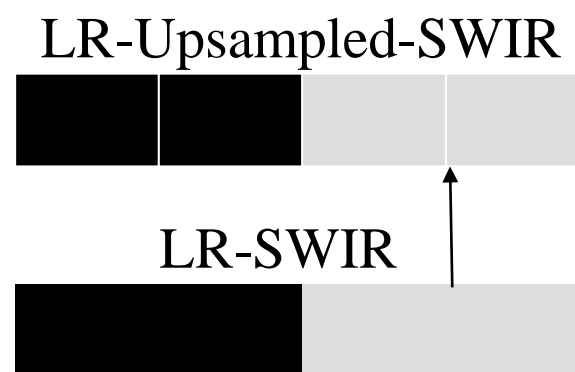


# Traditional Approach

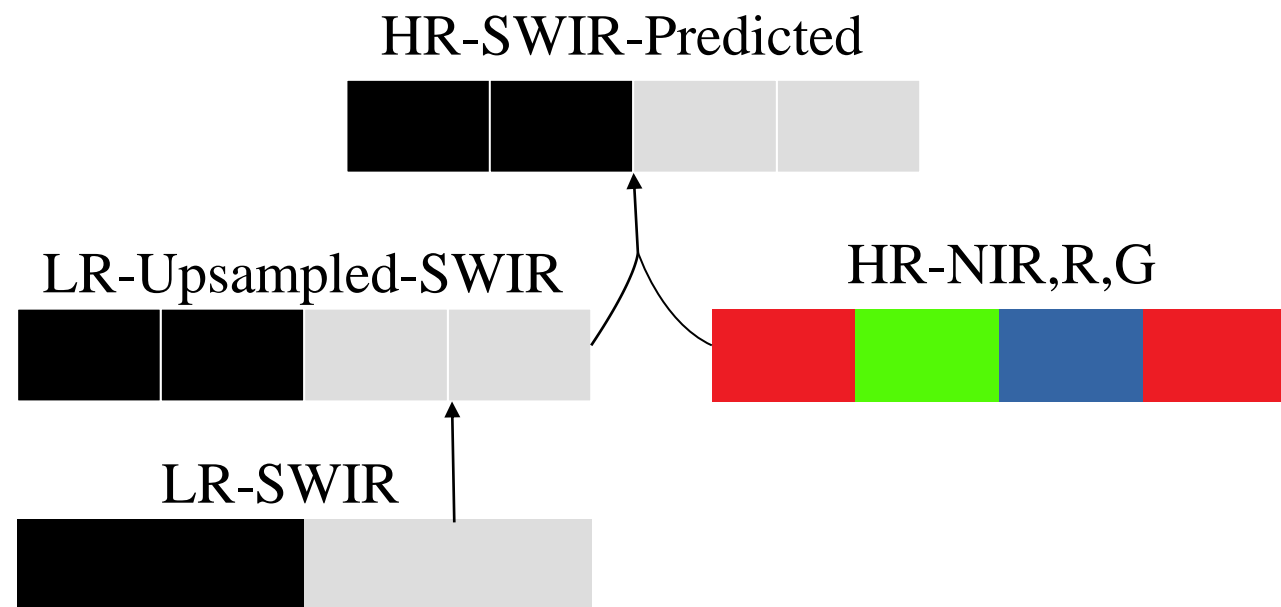




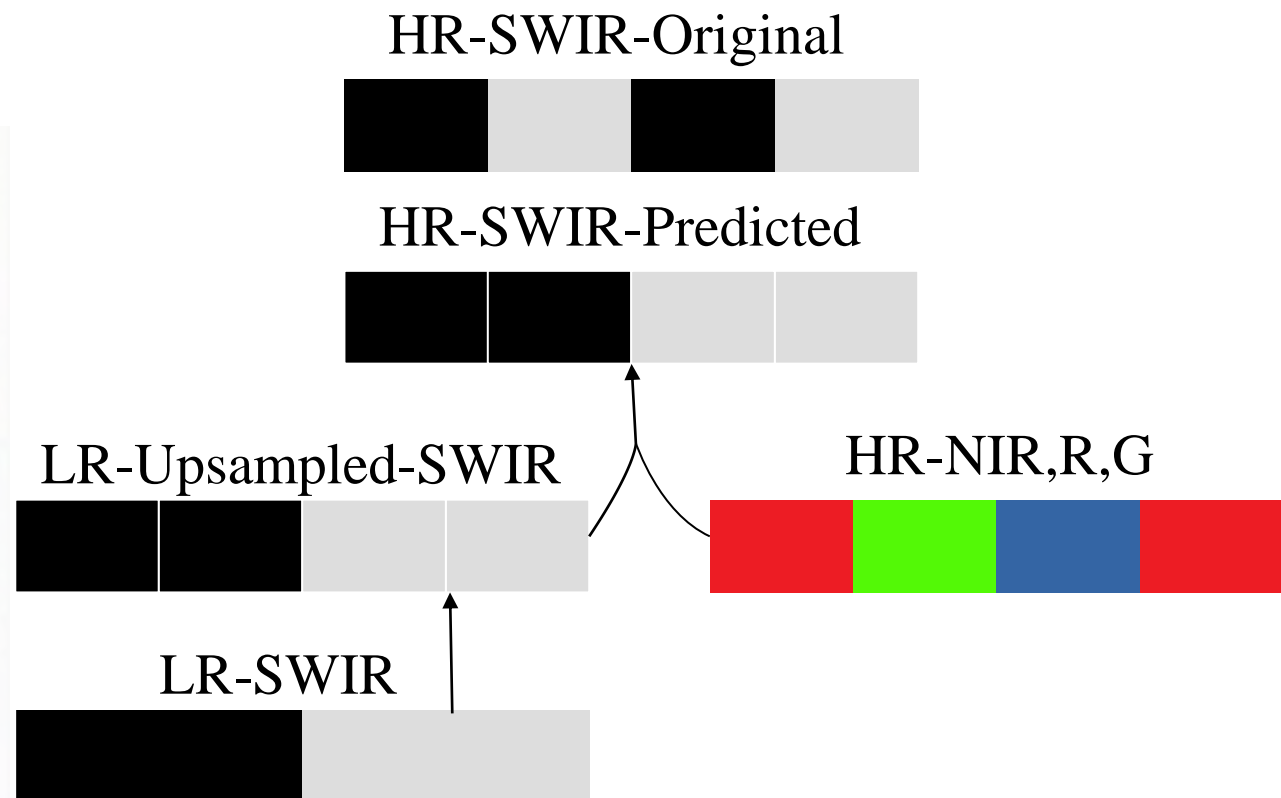
# Traditional Approach



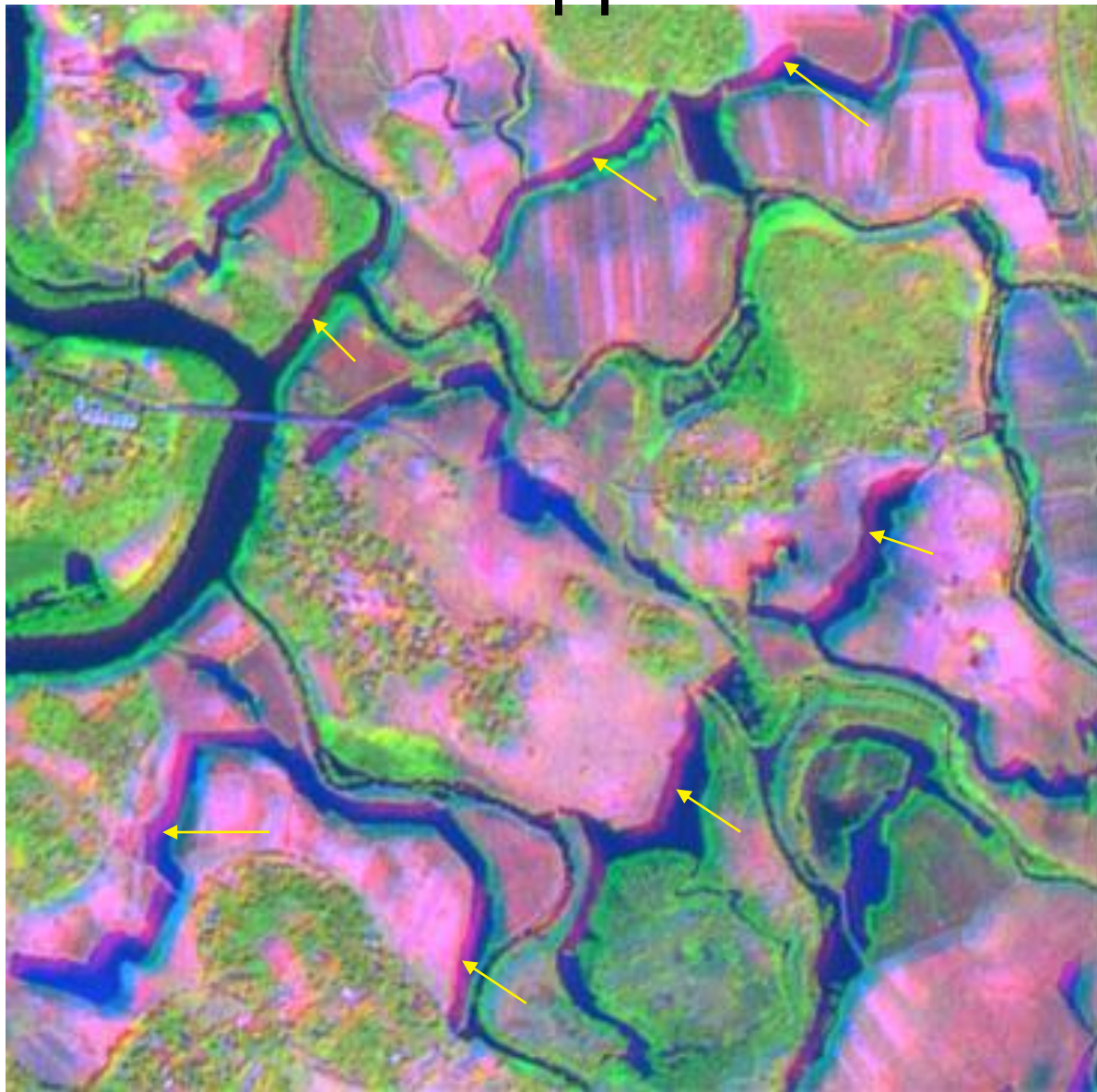
# Traditional Approach



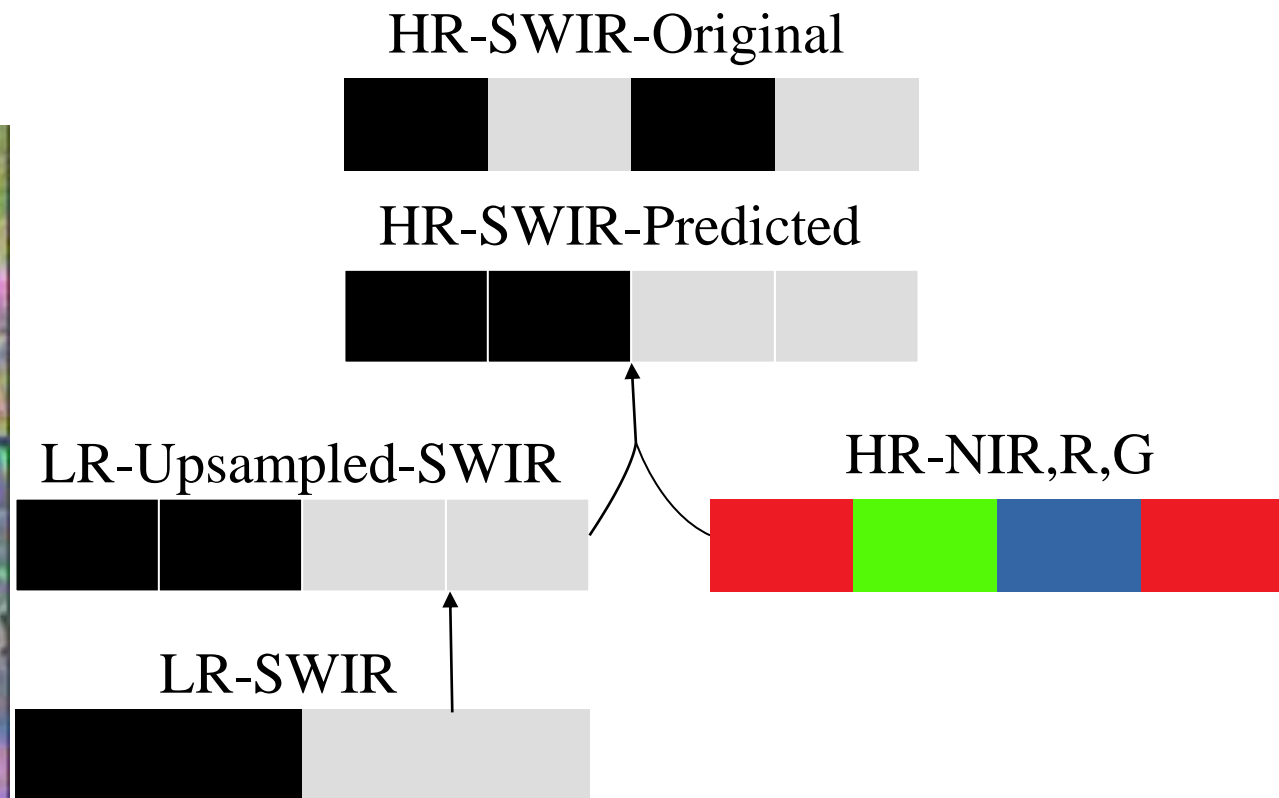
# Traditional Approach



# Traditional Approach



FCC: SWIR (R), NIR (G), Red (B)

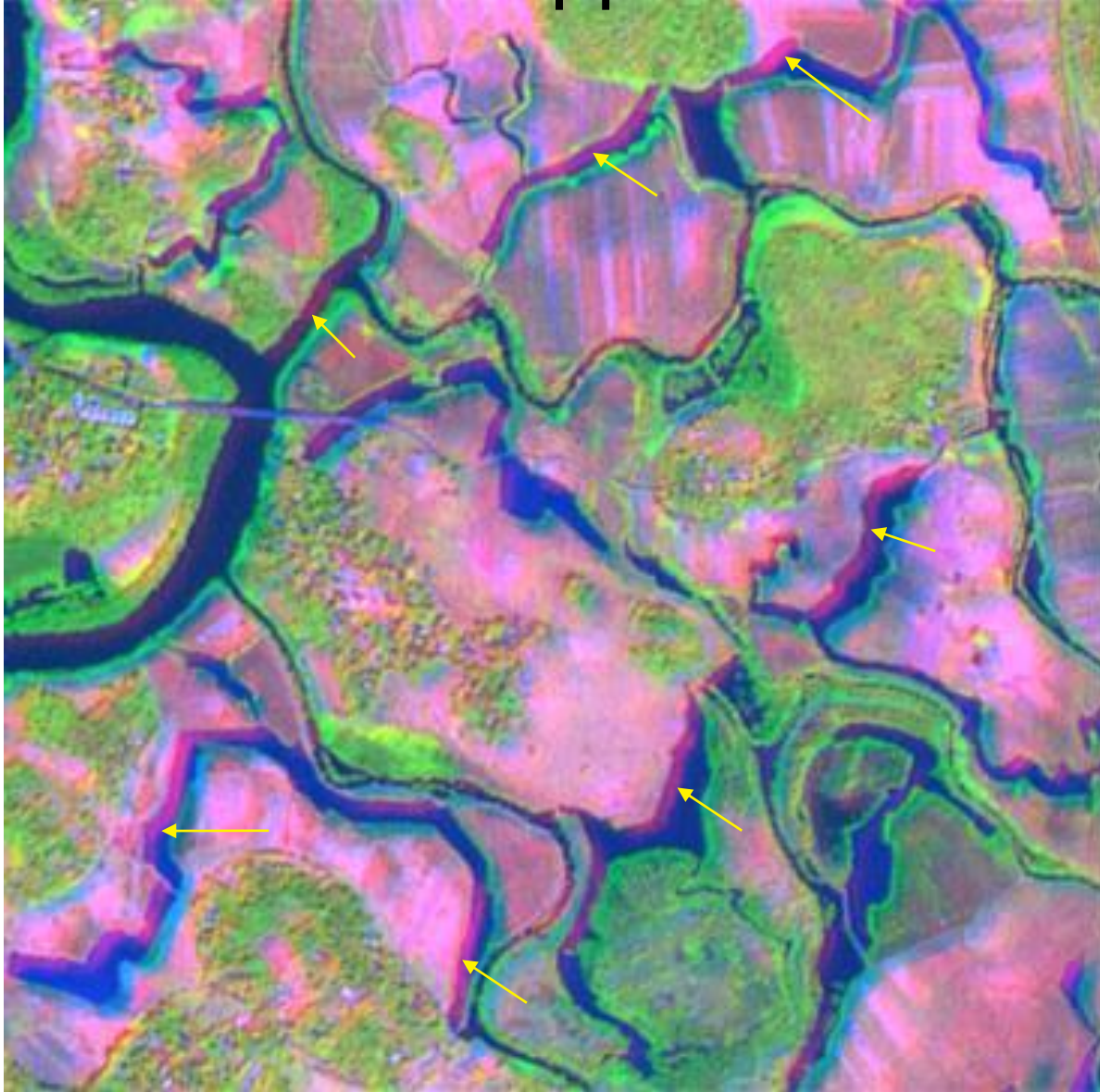


Over dependence on upsampled coarse resolution band results in unpleasant artifacts.

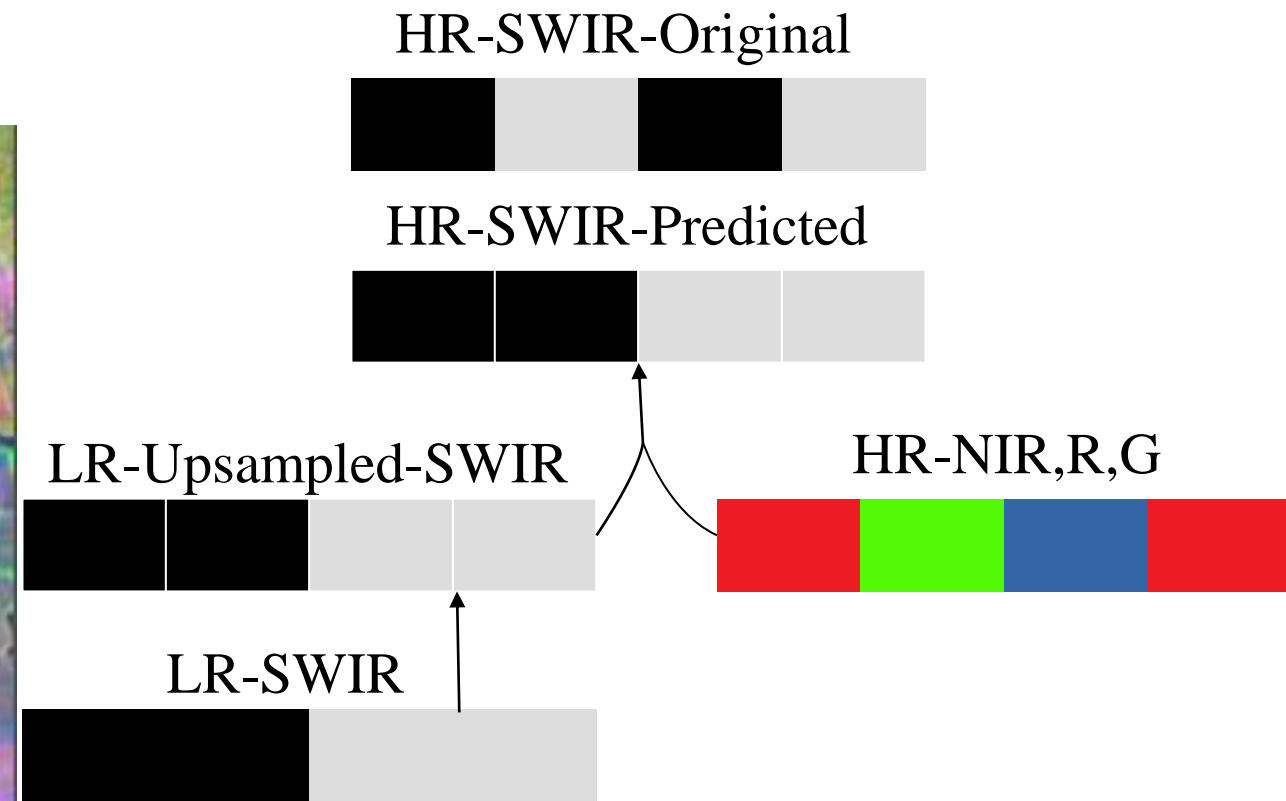
- Geometric distortion
- Radiometric imbalance



# Traditional Approach



FCC: SWIR (R), NIR (G), Red (B)

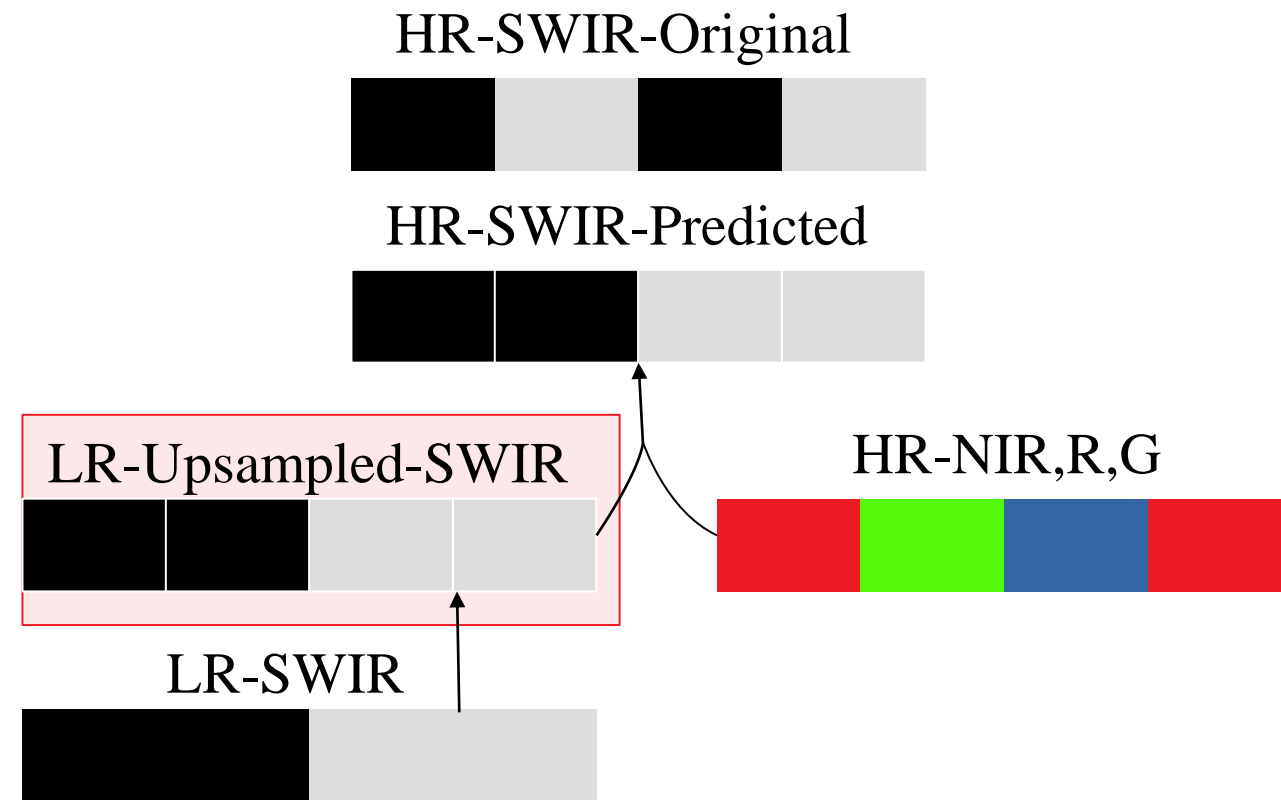


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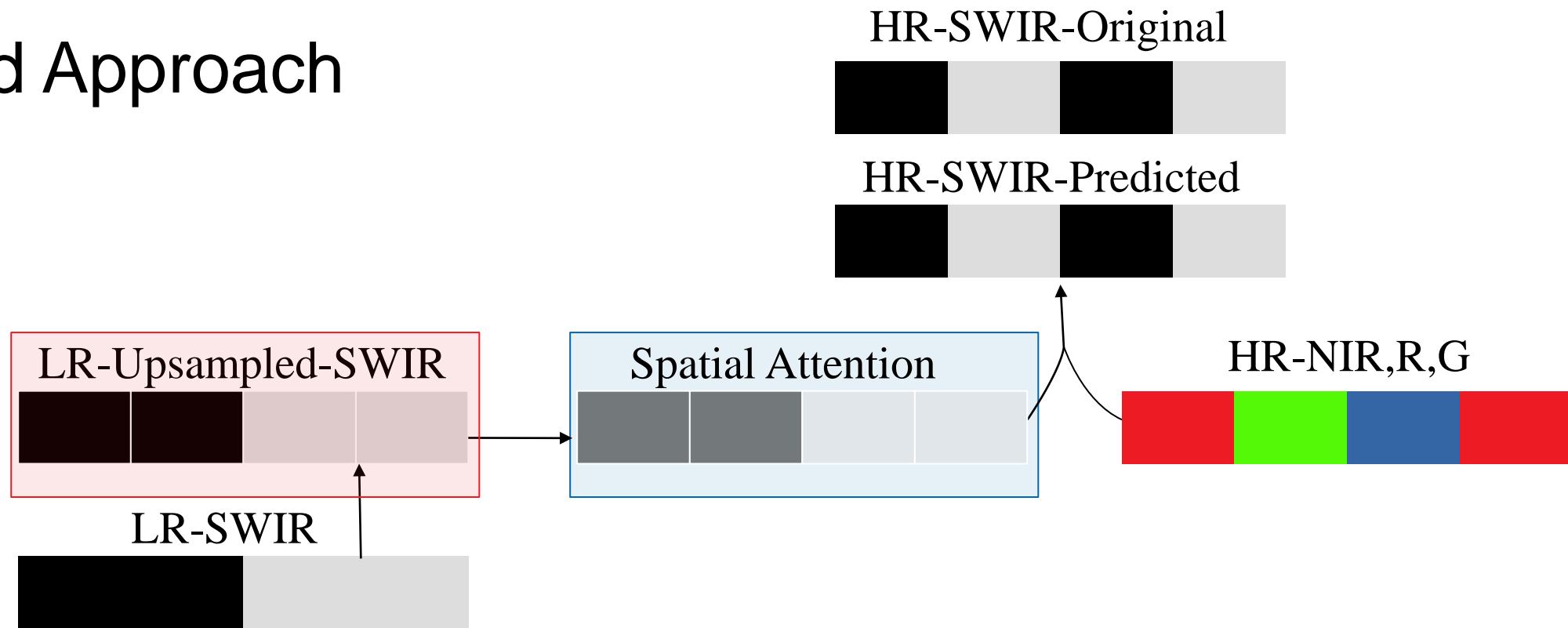
# Traditional Approach



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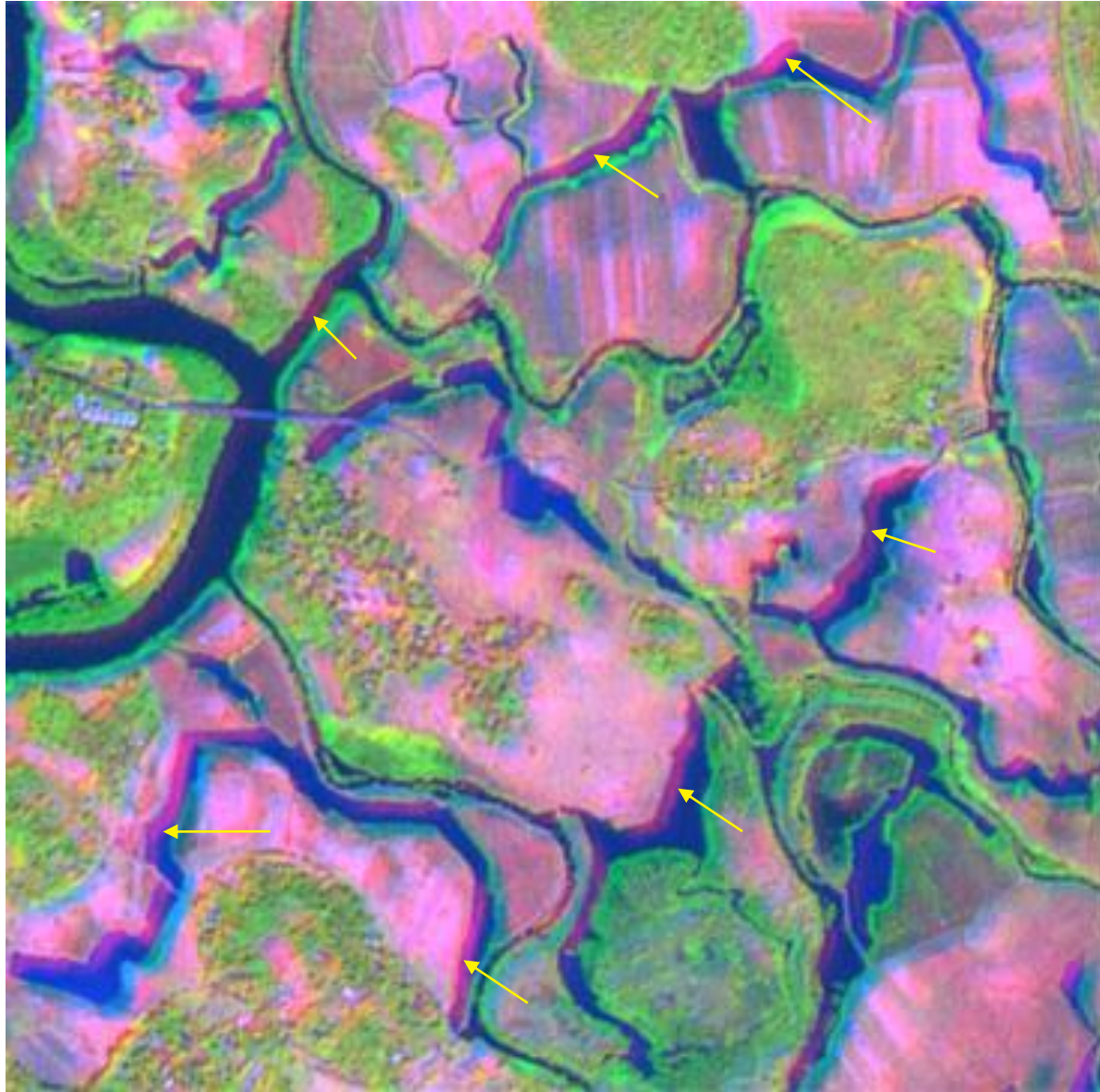
- Geometric distortion
- Radiometric imbalance

# Proposed Approach

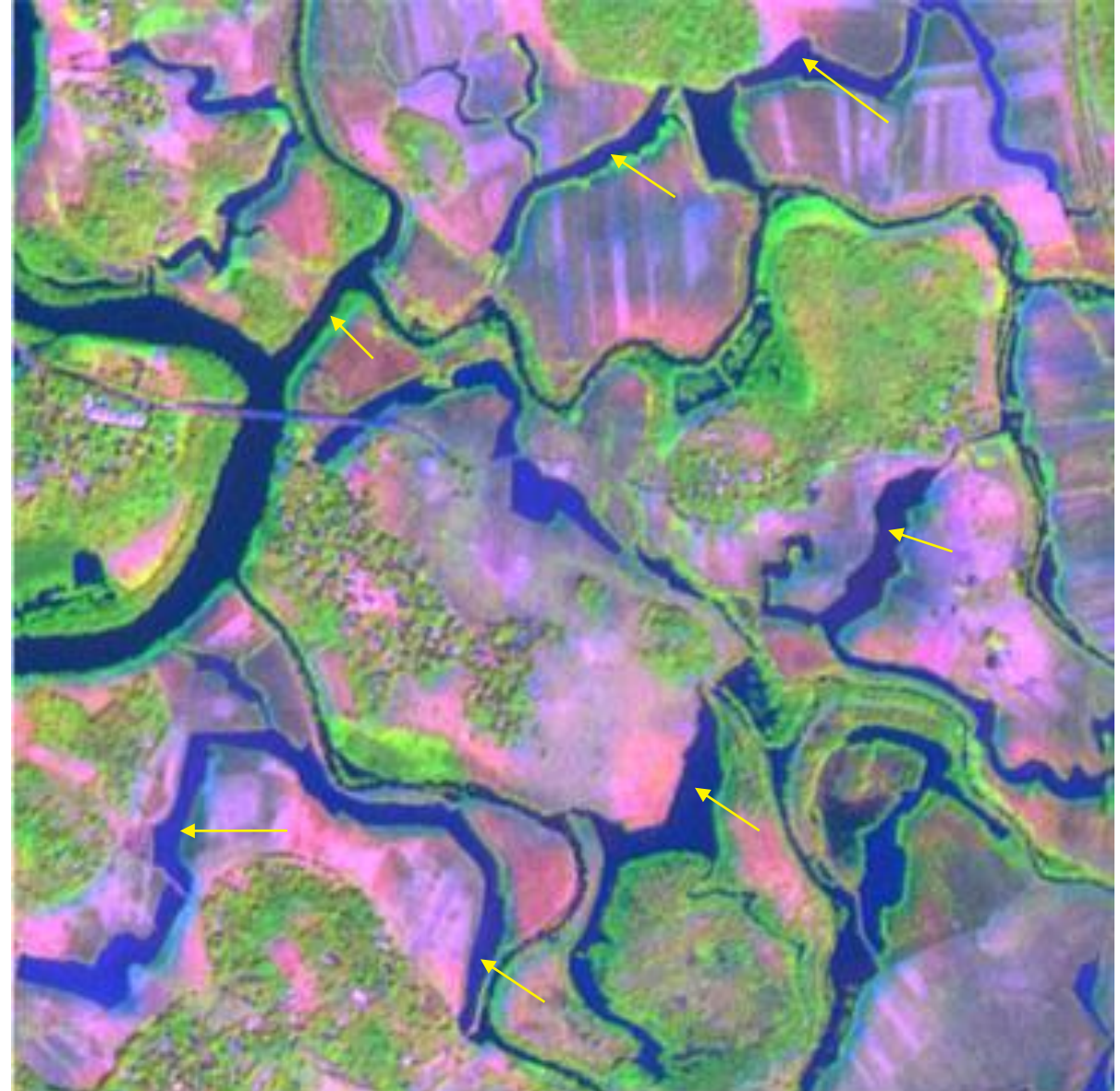


Over dependency on upsampled coarse resolution band can be suppressed by replacing it with spatial attention map.

Traditional Approach



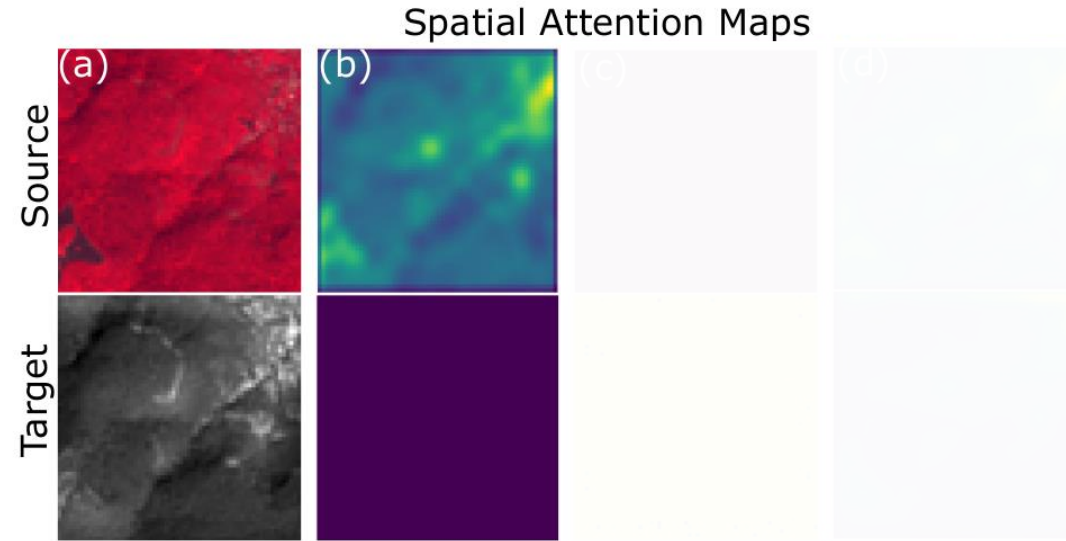
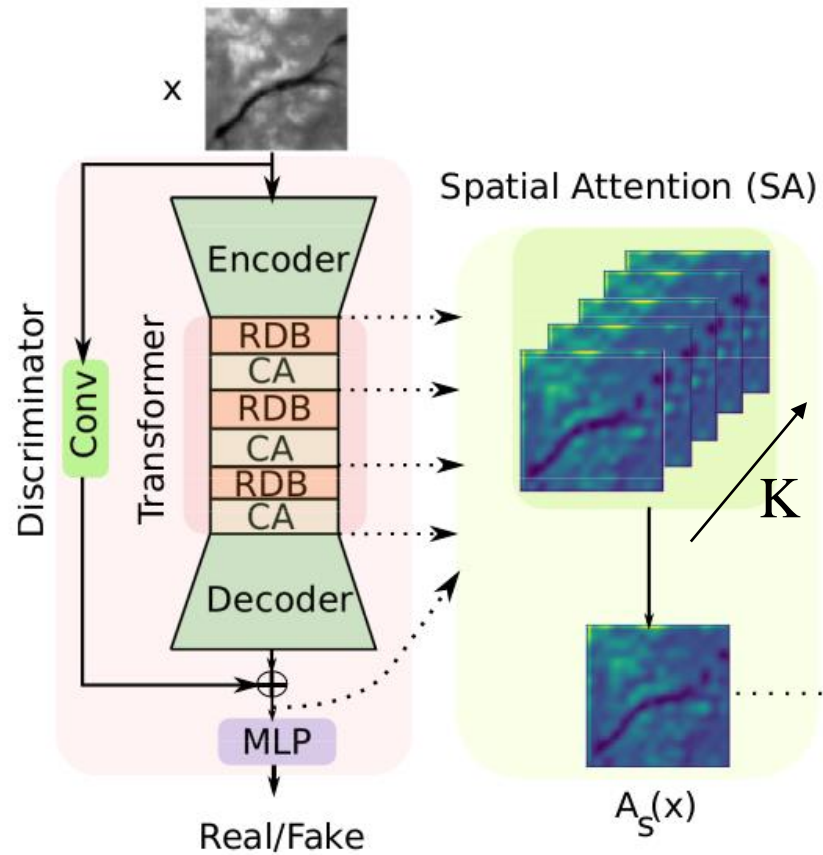
Proposed Approach



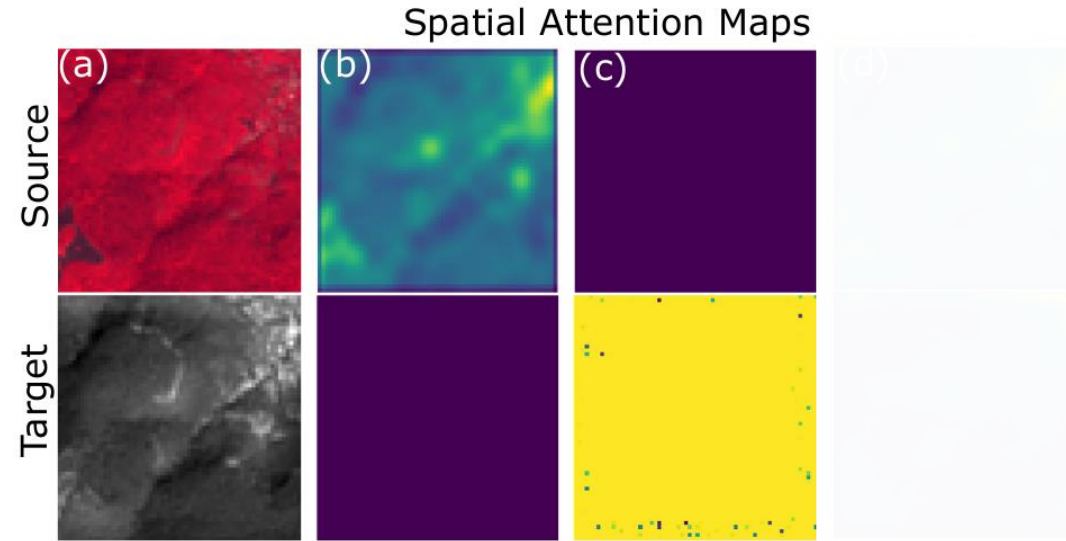
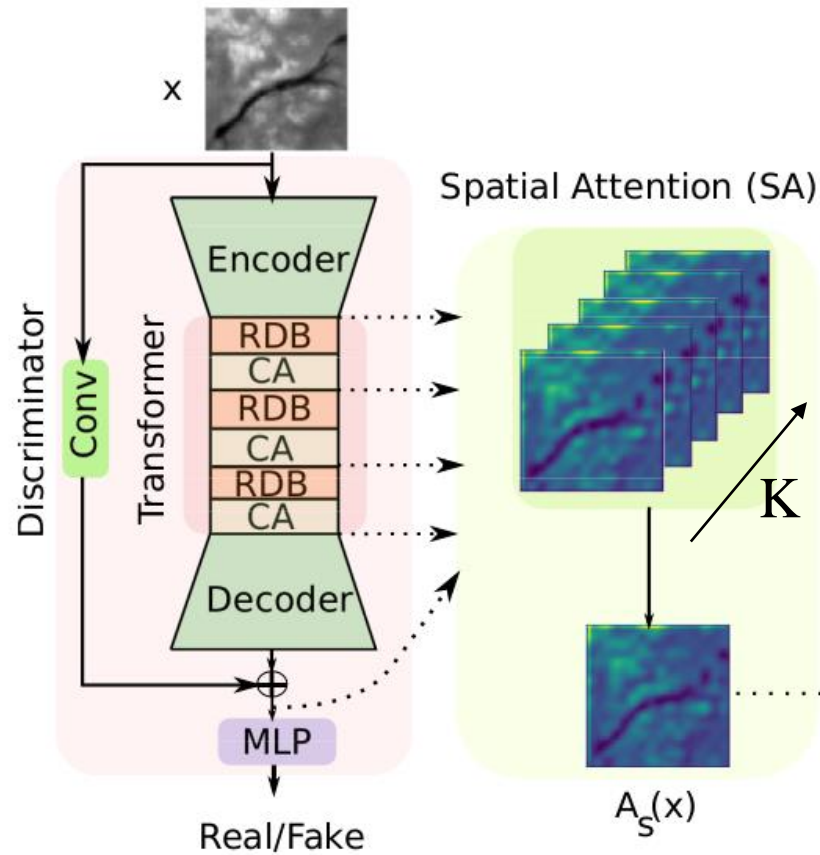
FCC: SWIR (R), NIR (G), Red (B)



# Spatial Attention from Discriminator

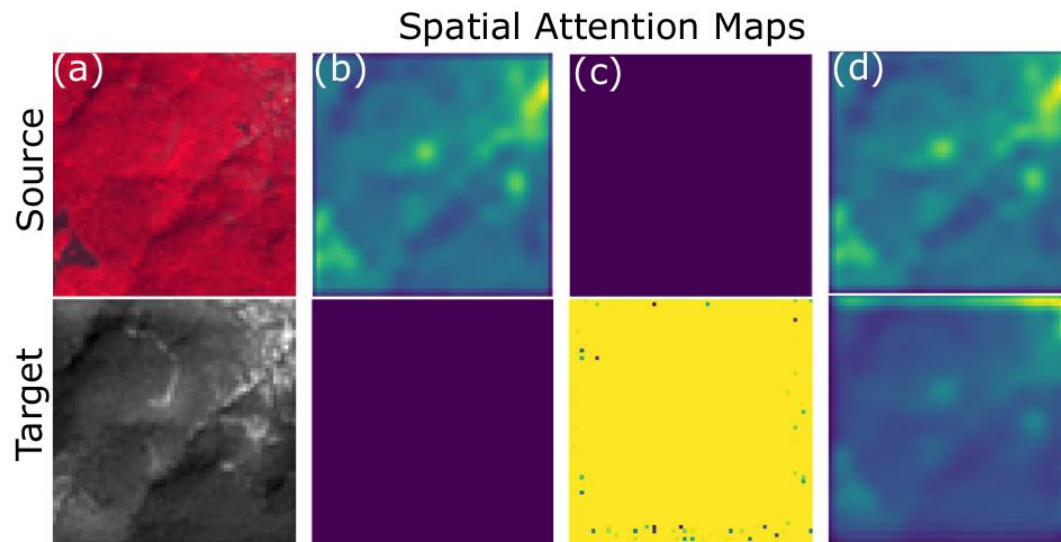
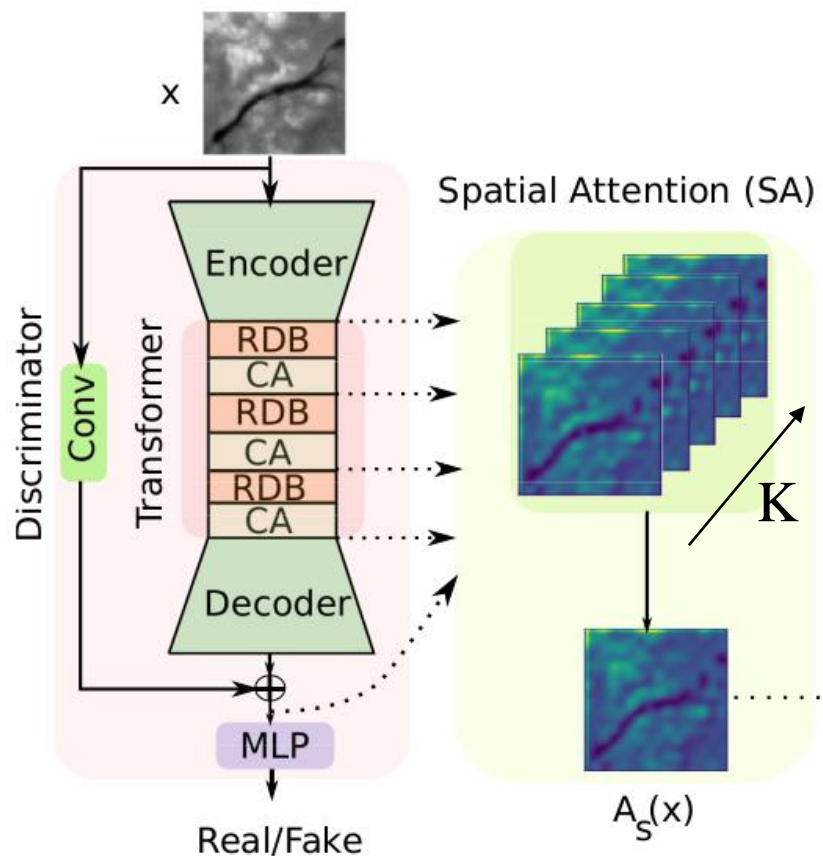


# Spatial Attention from Discriminator





# Spatial Attention from Discriminator



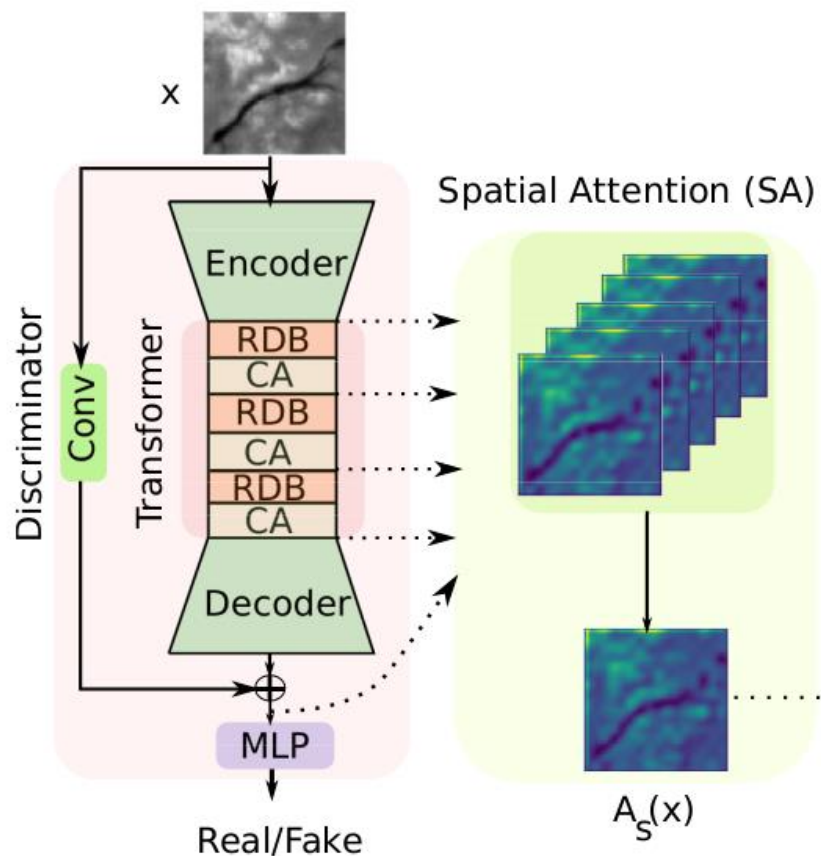
$$A_S(x) = \mathcal{N}(D_S(x)),$$

$$D_S(x) = \sum_{i=1}^K \mathcal{N} \left( \sum_{j=1}^C |A_{ij}(x)| \right)$$

# Spatial Attention from Discriminator

Spatial Attention Loss

$$\mathcal{L}_{sa} = \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{x}}, y \sim \mathbb{P}_y} \left[ \|A_s(\hat{x}) - A_s(y)\|_2^2 \right]$$



Domain Adaptation Loss

$$\mathcal{L}_{da} = \mathbb{E}_{\tilde{y} \sim \mathbb{P}_{\tilde{y}}, y \sim \mathbb{P}_y} \left[ \|A_s(\tilde{y}) - A_s(y)\|_2^2 \right]$$

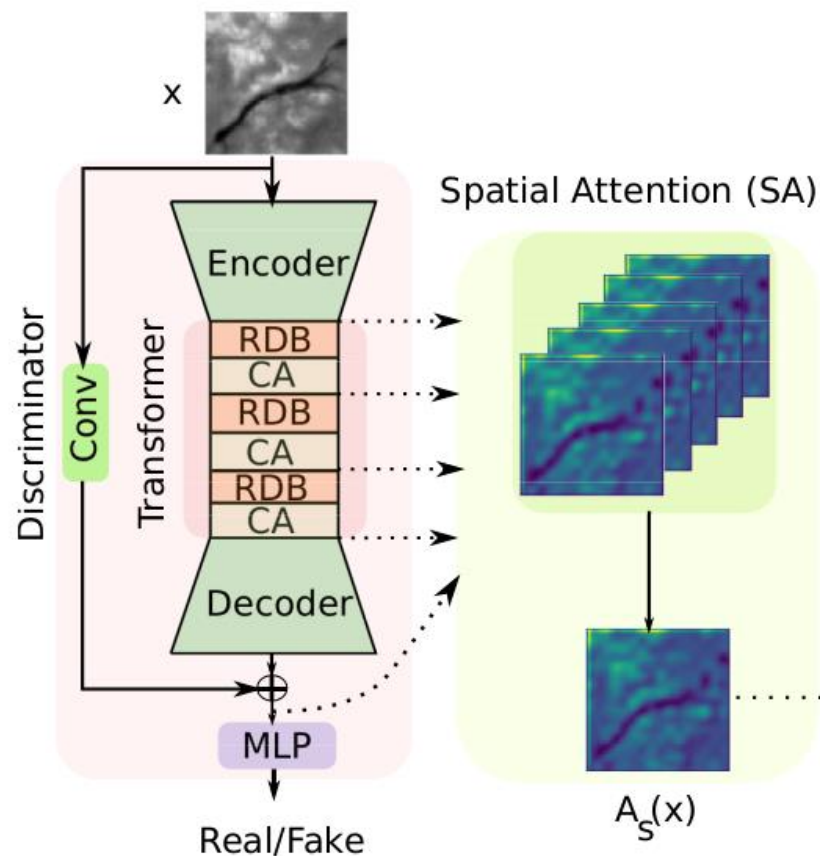
# Spatial Attention from Discriminator

Spatial Attention Loss

$$\mathcal{L}_{sa} = \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{x}}, y \sim \mathbb{P}_y} \left[ \|A_s(\hat{x}) - A_s(y)\|_2^2 \right]$$

Domain Adaptation Loss

$$\mathcal{L}_{da} = \mathbb{E}_{\tilde{y} \sim \mathbb{P}_{\tilde{y}}, y \sim \mathbb{P}_y} \left[ \|A_s(\tilde{y}) - A_s(y)\|_2^2 \right]$$



Discriminator Objective

$$\begin{aligned} \min_D \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{x}}} [D(\hat{x})] - \mathbb{E}_{x \sim \mathbb{P}_x} [D(x)] \\ + \lambda_{gp} \mathbb{E}_{\tilde{x} \sim \mathbb{P}_{\tilde{x}}} \left[ (\|\nabla_{\tilde{x}} D(\tilde{x})\|_2 - 1)^2 \right] \\ + \lambda_{sa} \mathcal{L}_{sa} + \lambda_{da} \mathcal{L}_{da}, \end{aligned}$$

# Spatial Attention from Discriminator

Spatial Attention Loss

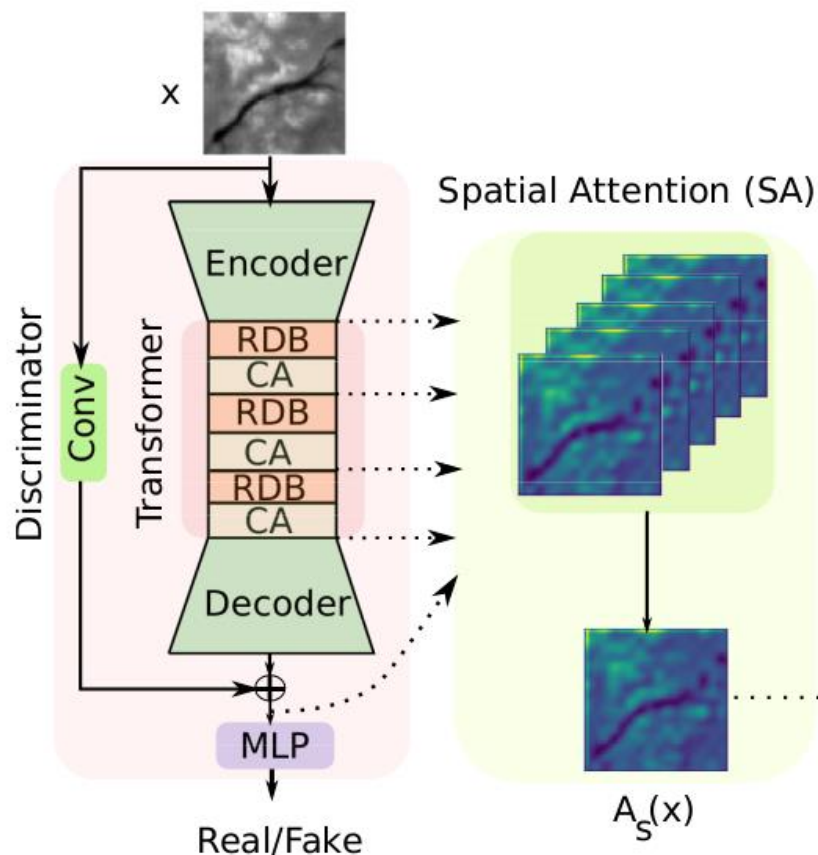
$$\mathcal{L}_{sa} = \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{x}}, y \sim \mathbb{P}_y} \left[ \|A_s(\hat{x}) - A_s(y)\|_2^2 \right]$$

Domain Adaptation Loss

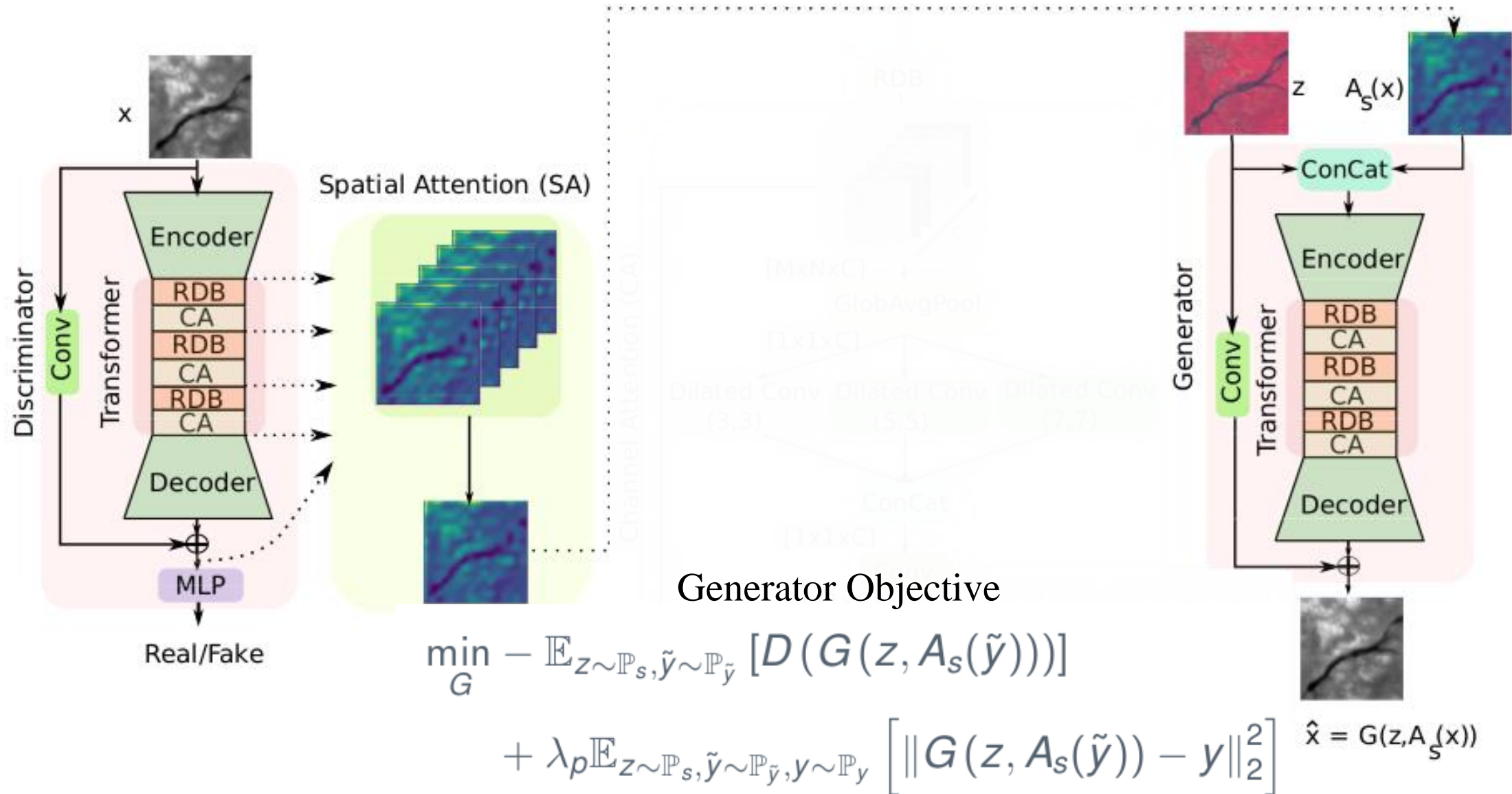
$$\mathcal{L}_{da} = \mathbb{E}_{\tilde{y} \sim \mathbb{P}_{\tilde{y}}, y \sim \mathbb{P}_y} \left[ \|A_s(\tilde{y}) - A_s(y)\|_2^2 \right]$$

Discriminator Objective

$$\begin{aligned} \min_D \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{x}}} [D(\hat{x})] - \mathbb{E}_{x \sim \mathbb{P}_x} [D(x)] \\ + \lambda_{gp} \mathbb{E}_{\tilde{x} \sim \mathbb{P}_{\tilde{x}}} \left[ (\|\nabla_{\tilde{x}} D(\tilde{x})\|_2 - 1)^2 \right] \\ + \lambda_{sa} \mathcal{L}_{sa} + \lambda_{da} \mathcal{L}_{da}, \end{aligned}$$

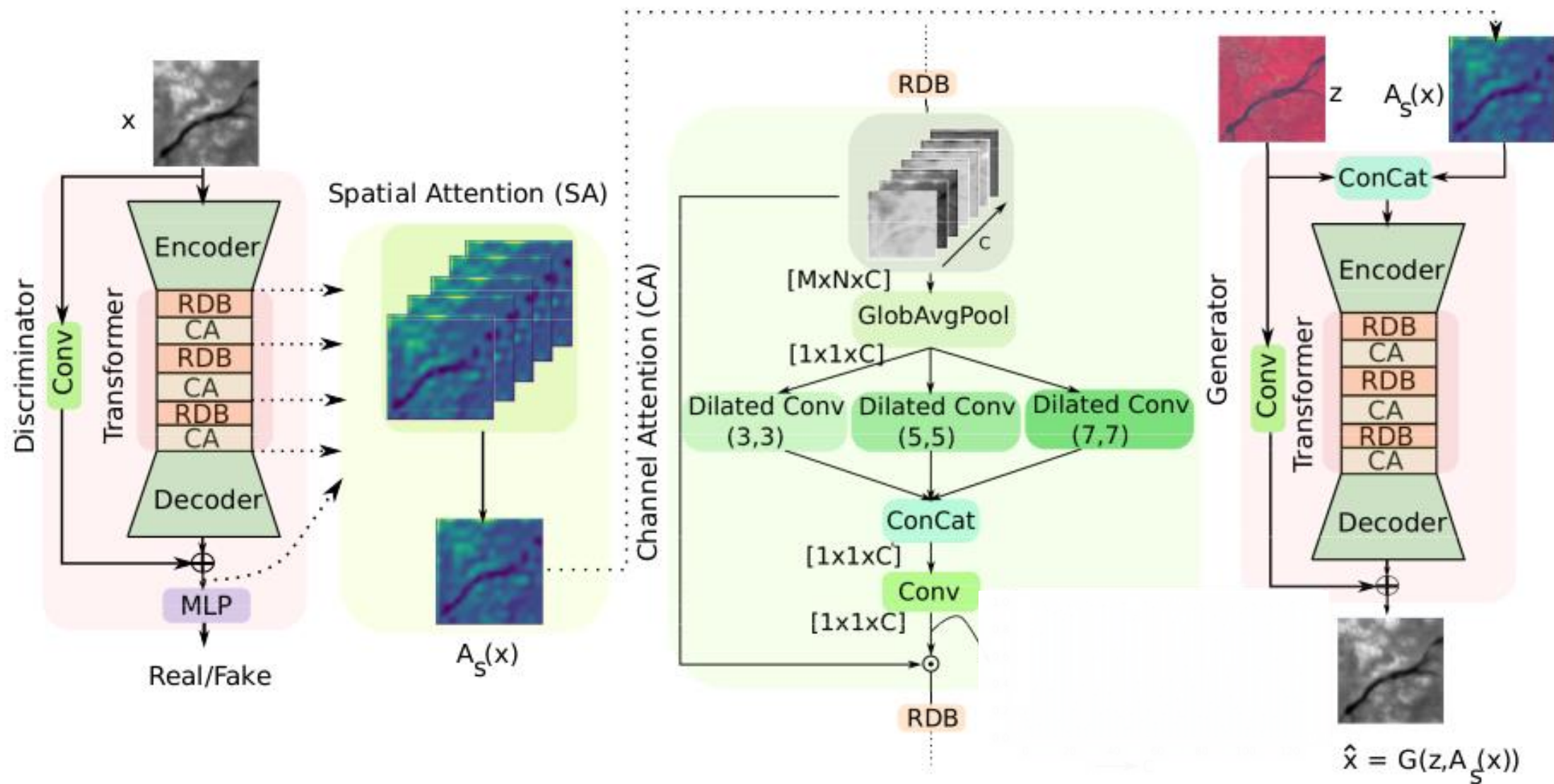


# Spatial Attention from Discriminator

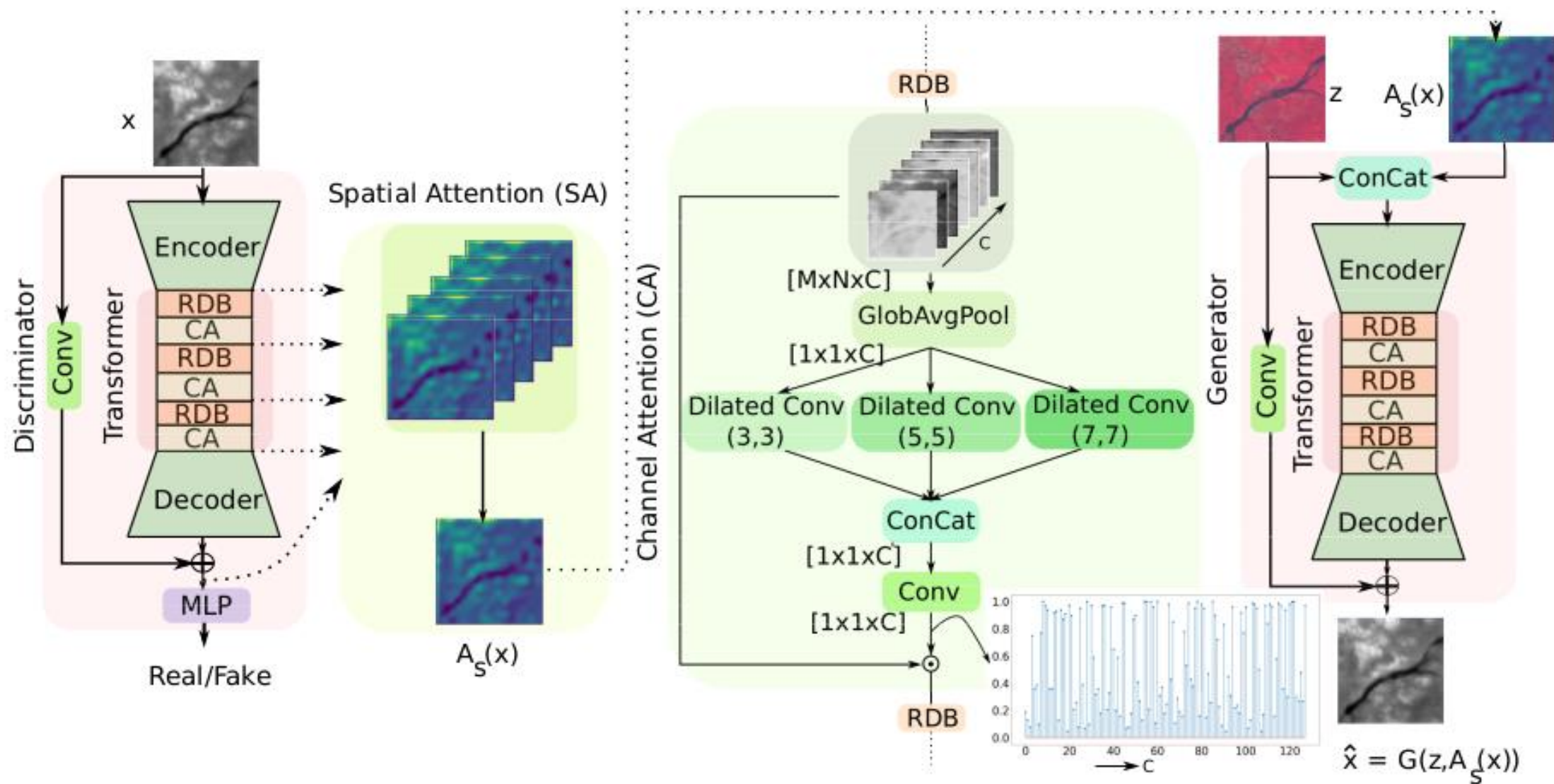




# Spatio-Spectral Laplacian Attention

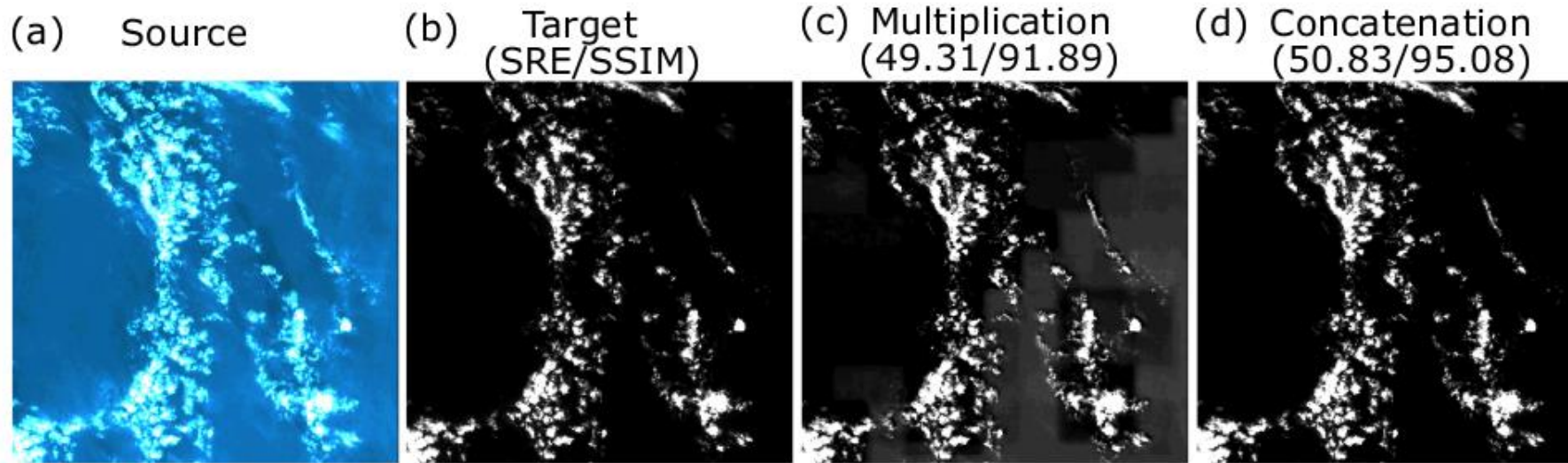


# Spatio-Spectral Laplacian Attention



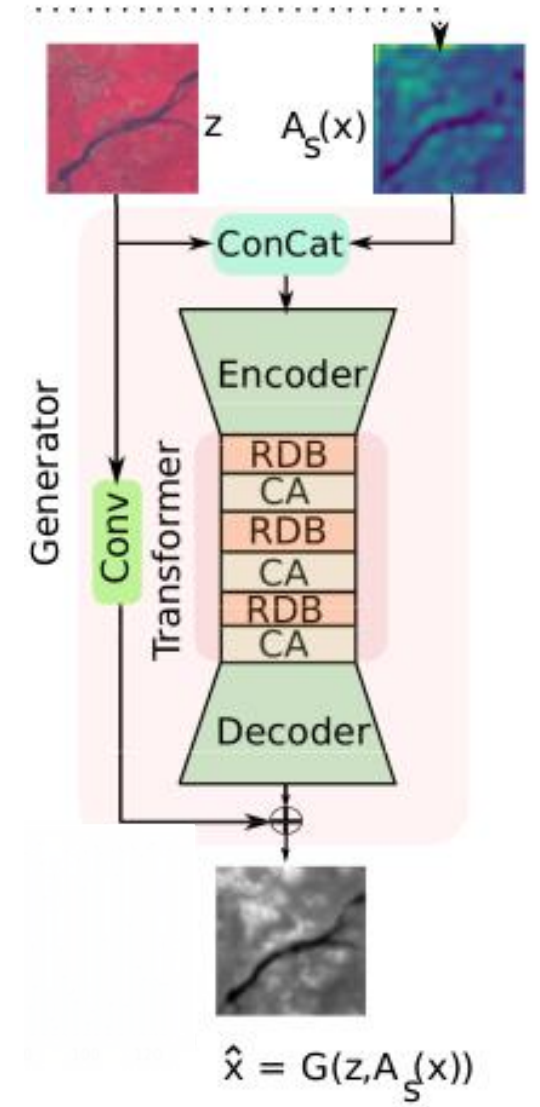
Spectral attention coefficients

# Combining Spatial Attention with Source Bands

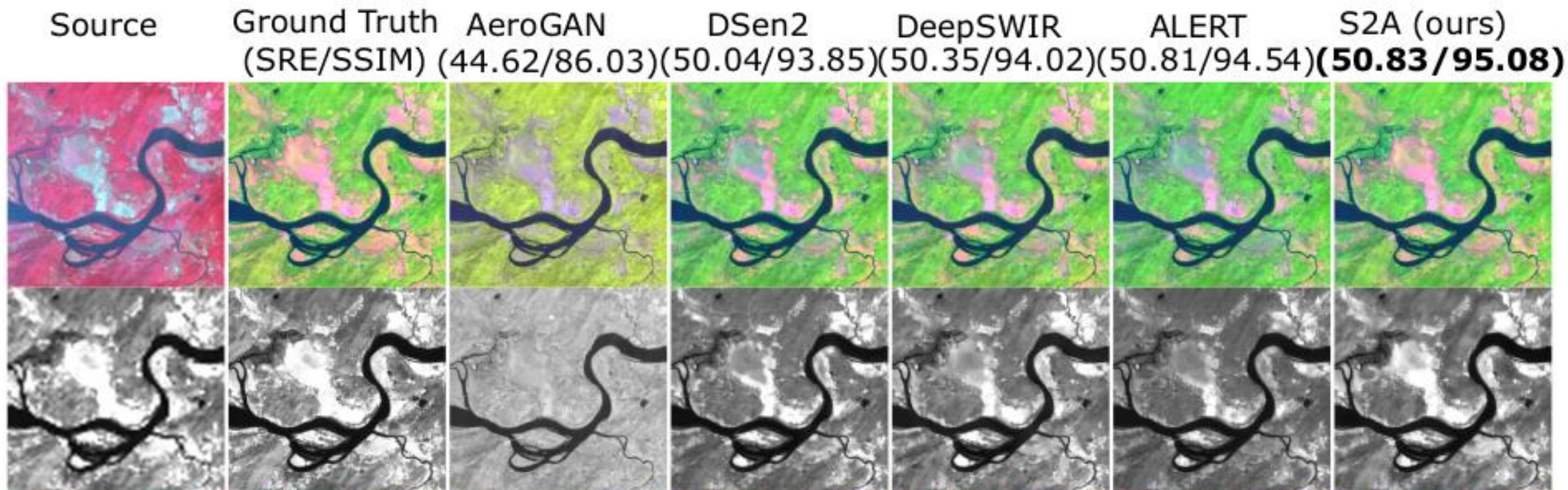


Multiplication:

- Attention module latches on to bright targets.
- Synthesized band contains blocky artifacts.

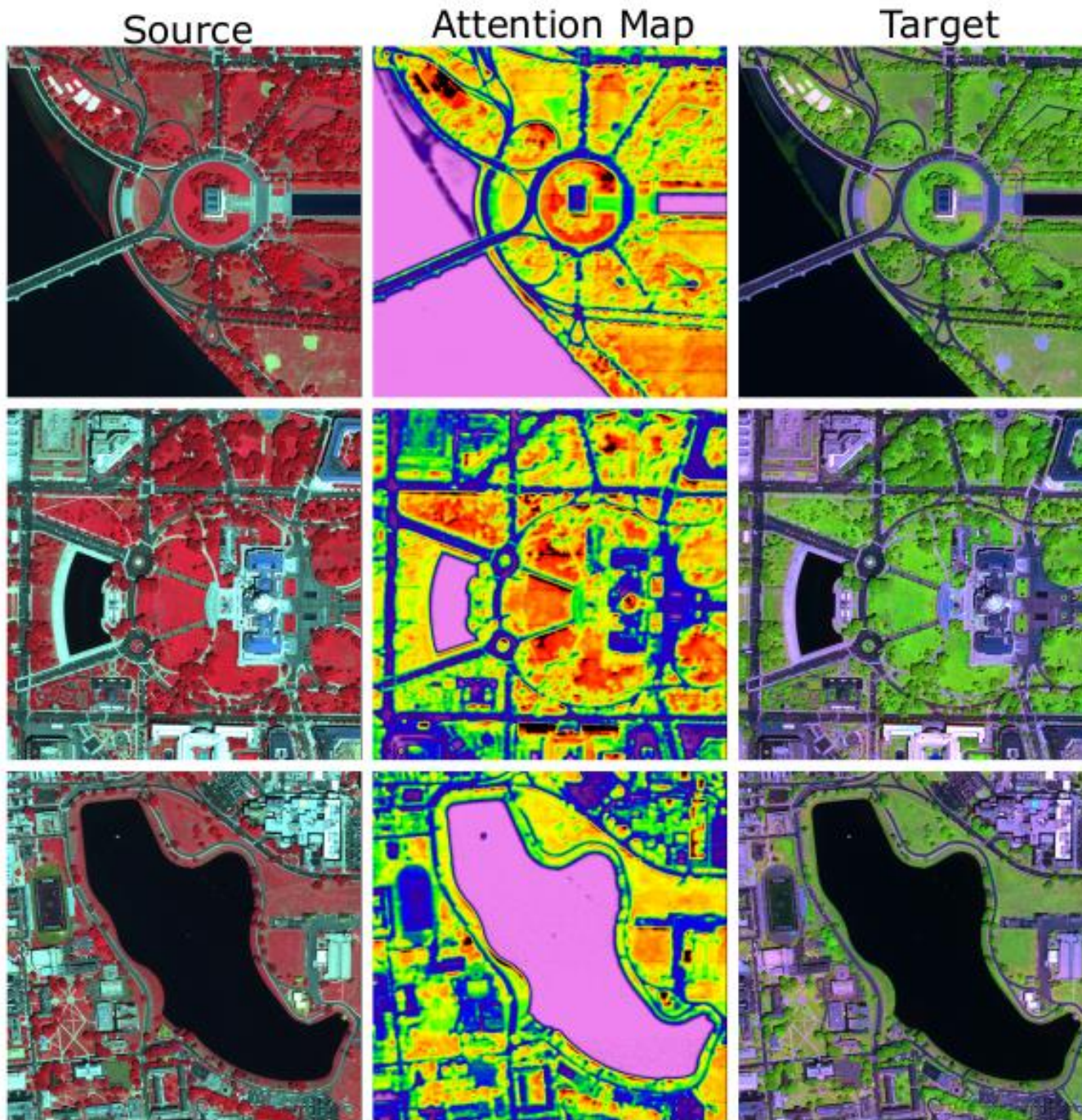






Method	RMSE	SSIM(%)	SRE(dB)	PSNR(dB)	SAM(deg)
AeroGAN [31]	21.62	86.03	44.62	36.50	12.15
DSen2 [21]	14.14	93.85	50.04	41.94	7.88
DeepSWIR [33]	13.75	94.02	50.35	42.27	7.66
ALERT [32]	12.97	94.54	50.81	42.80	7.48
S2A (ours)	11.74	95.08	50.83	42.76	6.87

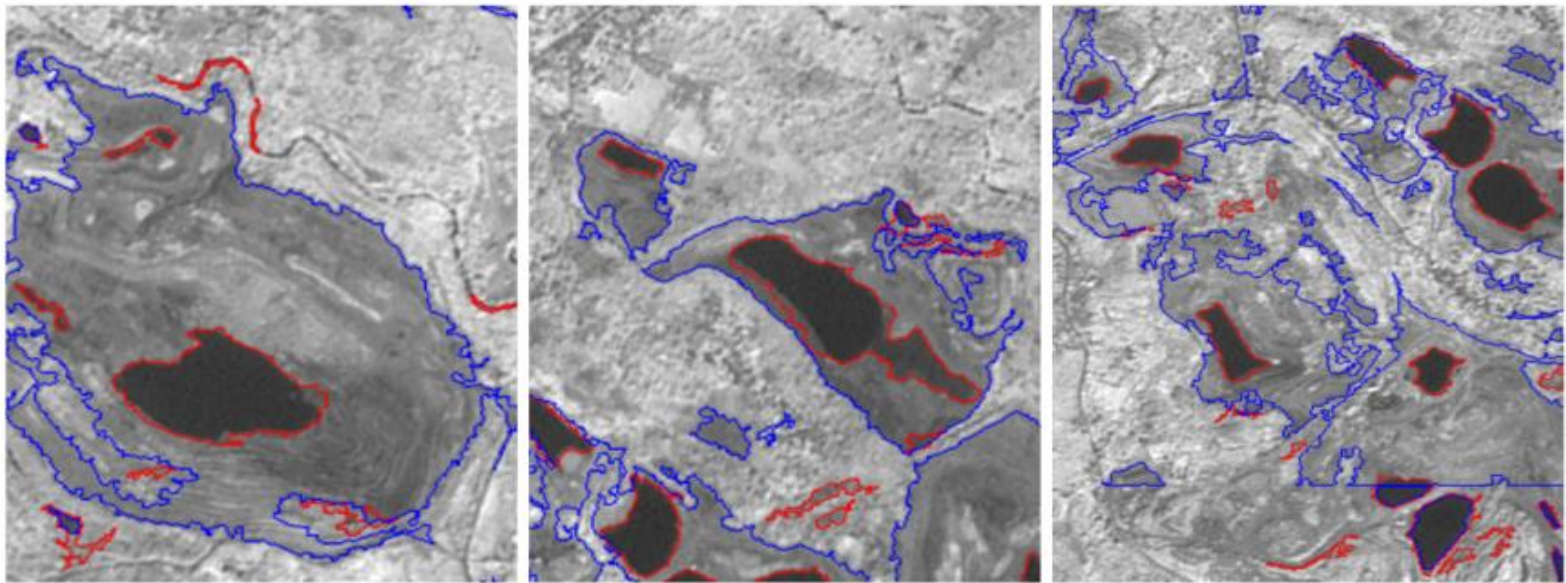




- Learns to attend to relevant parts of source imagery.
- Homogeneous and heterogeneous targets are discernible.
- Similar features have similar attention coefficients



# Wetland Delineation



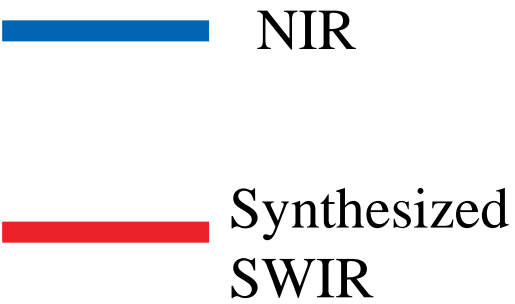
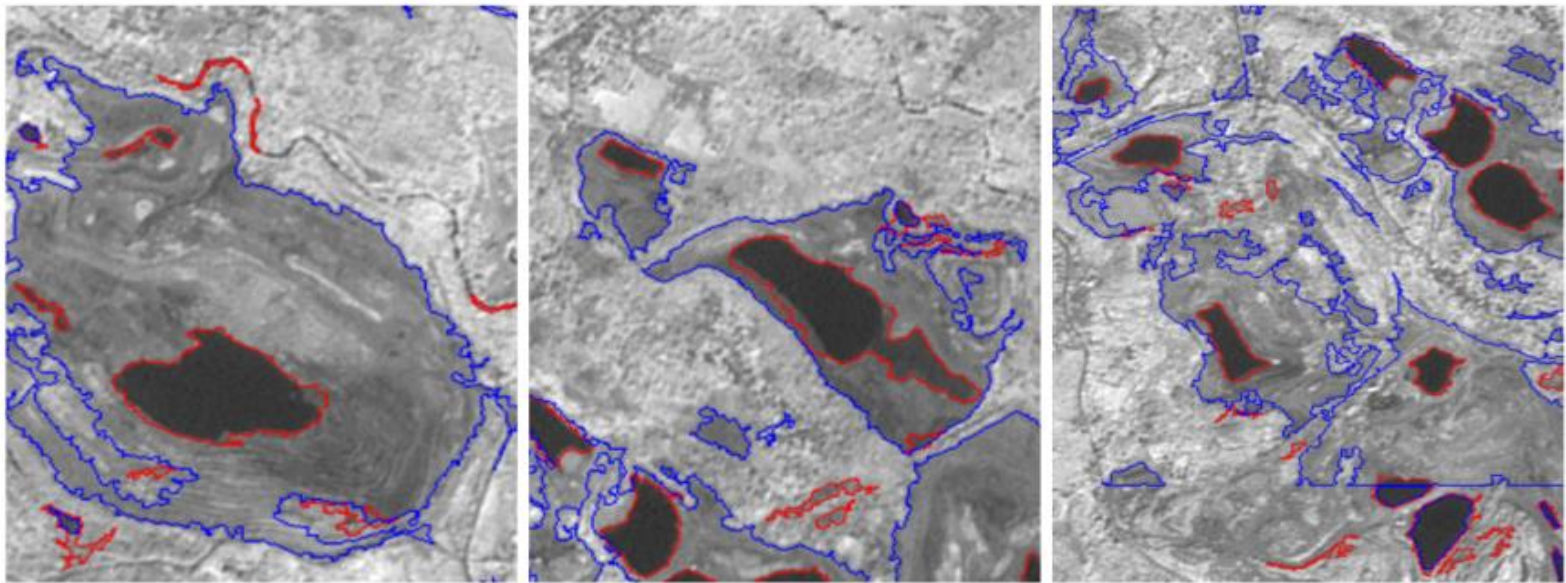
— NIR

— Synthesized SWIR

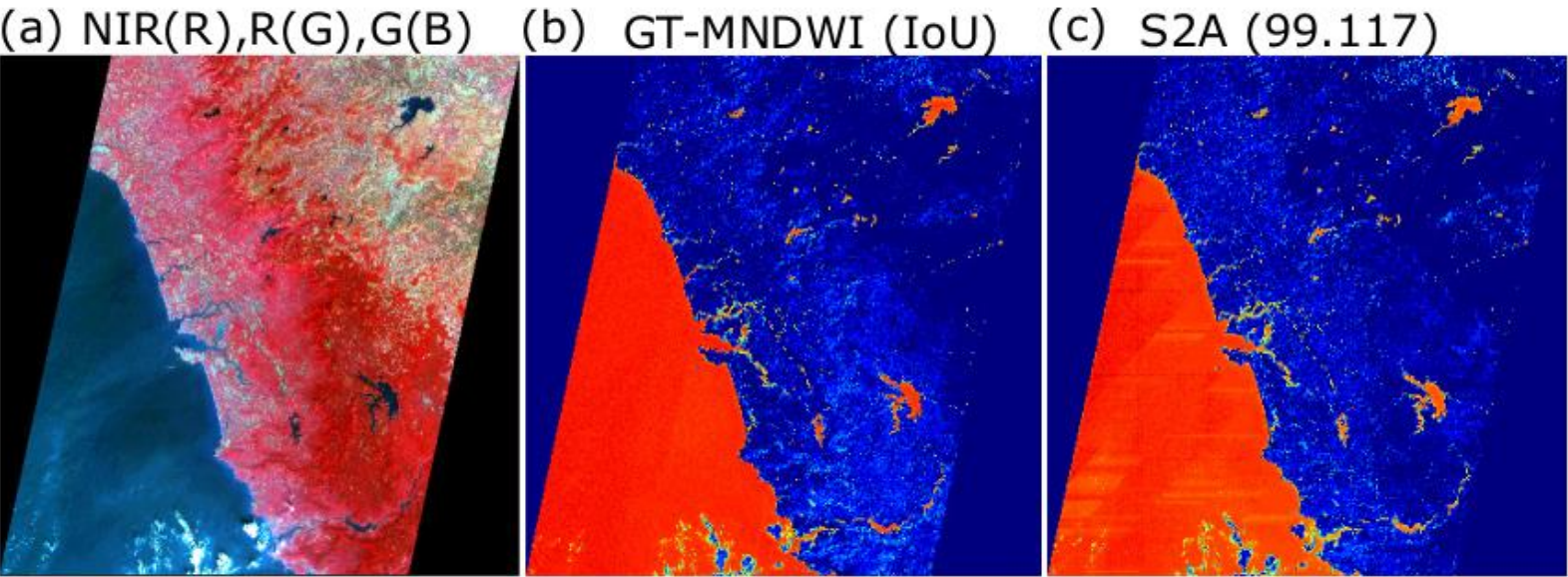
# Water Segmentation



# Wetland Delineation

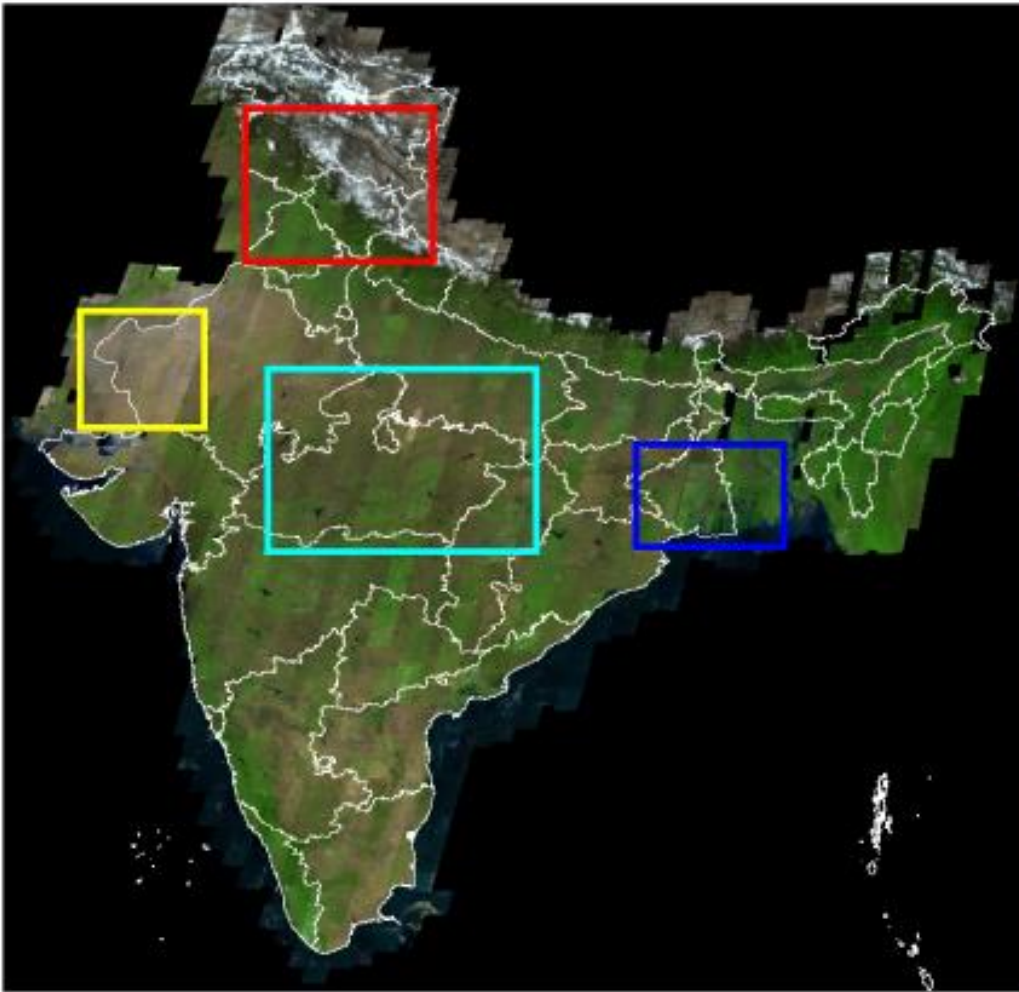


# Water Segmentation





# Additional Value Product Generation

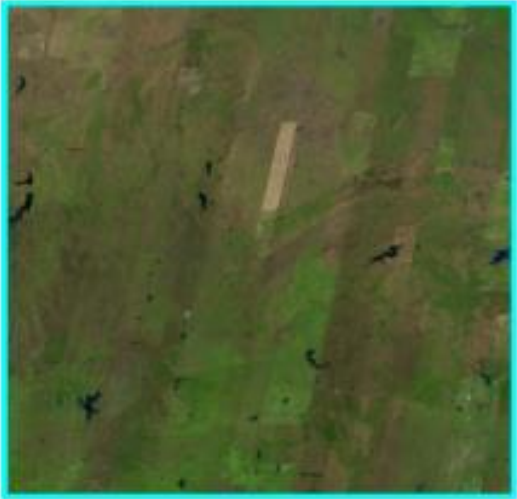


India

Hilly Terrain



Desert



Main land



Coastal

# Outline

- Maximum Likelihood Estimation
- Reverse KL Divergence
- Introduction to GANs
- GANs in Remote Sensing
  - Problem Formulation

# Why Adversarial Interaction Creates Non-Homogeneous Patterns: A Pseudo-Reaction Diffusion Model for Turing Instability

- Adversarial Interaction
  - Generative Adversarial Networks (GANs)
  - Application of conditional GANs
- Non-Homogeneous Patterns
  - Homogeneous patterns
  - Supervised learning
- Reaction-Diffusion
  - Turing's RD model (1952)
  - Gray-Scott RD model (1984)
- Turing Instability
  - Reaction dynamics
  - Diffusion dynamics