

GPIO VVC – Quick Reference

gpio_set (VVCT, vvc_instance_idx, data, msg)

Example: gpio_set(GPIO_VVCT, 1, C_BAUDRATE_9600, "Set baudrate to 9600");

gpio_get (VVCT, vvc_instance_idx, msg)

Example: gpio_get(GPIO_VVCT, 1, "Read baudrate");

gpio_check (VVCT, vvc_instance_idx, data_exp, msg, [alert_level])

Example: gpio_check(GPIO_VVCT, 1, x"3B", "Check data from UART RX", ERROR);

gpi_expect (VVCT, vvc_instance_idx, data_exp, timeout, msg, [alert_level])

Example: gpi_expect(GPIO_VVCT, 1, x"0D", 2 ms, "Read UART RX until CR is found or timeout", ERROR);

VVC



gpio_vvc.vhd

Common VVC procedures applicable for this VVC

- See UVVM Methods QuickRef for details.

Name

await_completion()
await_any_completion()
enable_log_msg()
disable_log_msg()
flush_command_queue()
terminate_current_command()
fetch_result()
insert_delay()
get_last_received_cmd_idx()
terminate_current_command()

GPIO VVC Configuration record 't_vvc_config'

- Accessible via `shared_gpio_vvc_config` – se section 2.

Record element

inter_bfm_delay
[cmd/result]_queue_count_max
[cmd/result]_queue_count_threshold
[cmd/result]_queue_count_threshold_severity
result_queue_count_max
result_queue_count_threshold_severity
result_queue_count_threshold
bfm_config
msg_id_panel

GPIO VVC Status record signal 't_vvc_status'

- Accessible via `shared_gpio_vvc_status` – se section 3.

Record element

current_cmd_idx
previous_cmd_idx
pending_cmd_idx



UVVM™

VVC target parameters

| Name | Type | Example(s) | Description |
|------------------|---------------------|------------|--|
| VVCT | t_vvc_target_record | GPIO_VVCT | VVC target type compiled into each VVC in order to differentiate between VVCs. |
| vvc_instance_idx | integer | 1 | Instance number of the VVC |

VVC functional parameters

| Name | Type | Example(s) | Description |
|-------------|------------------|---------------------|--|
| data | std_logic_vector | x"FF" | The data to be written (in gpio_set). |
| data_exp | std_logic_vector | x"FF" | The expected data to be read (in gpio_check or gpio_expect). |
| msg | string | "Set baudrate" | A custom message to be appended in the log/alert |
| alert_level | t_alert_level | ERROR or TB_WARNING | Set the severity for the alert that may be asserted by the method. |

VVC entity signals

| Name | Type | Direction | Description |
|-------------|-----------|-----------|----------------------------|
| gpio_vvc_if | t_gpio_if | Inout | See GPIO BFM documentation |

VVC entity generic constants

| Name | Type | Default | Description |
|--|-------------------|---------------------------|--|
| GC_DATA_WIDTH | natural | 32 | Bits in the GPIO data word |
| GC_INSTANCE_IDX | natural | 1 | Instance number to assign the VVC |
| GC_DEFAULT_LINE_VALUE | boolean | TRUE | Default value of input or output GPIO. |
| GC_GPIO_BFM_CONFIG | t_gpio_bfm_config | C_GPIO_BFM_CONFIG_DEFAULT | Configuration for the GPIO BFM, see GPIO BFM documentation. |
| GC_CMD_QUEUE_COUNT_MAX | natural | 1000 | Absolute maximum number of commands in the VVC command queue |
| GC_CMD_QUEUE_COUNT_THRESHOLD | natural | 950 | An alert will be generated when reaching this threshold to indicate that the command queue is almost full. The queue will still accept new commands until it reaches C_CMD_QUEUE_COUNT_MAX. |
| GC_CMD_QUEUE_COUNT_THRESHOLD_SEVERITY | t_alert_level | WARNING | Alert severity which will be used when command queue reaches GC_CMD_QUEUE_COUNT_THRESHOLD. |
| GC_RESULT_QUEUE_COUNT_MAX | natural | 1000 | Maximum number of unfetched results before result_queue is full. |
| GC_RESULT_QUEUE_COUNT_THRESHOLD | natural | 950 | An alert with severity 'result_queue_count_threshold_severity' will be issued if command queue exceeds this count. Used for early warning if result queue is almost full. Will be ignored if set to 0. |
| GC_RESULT_QUEUE_COUNT_THRESHOLD_SEVERITY | t_alert_level | WARNING | Severity of alert to be initiated if exceeding result_queue_count_threshold |

VVC details

All VVC procedures are defined in `vvc_methods_pkg` (dedicated this VVC), and `uvvm_vvc_framework.uvvm_methods_pkg` and `uvvm_vvc_framework.uvvm_support_pkg` (common VVC procedures). It is also possible to send a multicast to all instances of a VVC with `ALL_INSTANCES` as parameter for `vvc_instance_idx`.

1 VVC procedure details and examples

| Procedure | Description |
|---------------------|---|
| gpio_set() | <p>gpio_set (VVCT, vvc_instance_idx, data, msg)</p> <p>The <code>gpio_set()</code> VVC procedure adds a SET command to the GPIO VVC executor queue, that will run as soon as all preceding commands have completed. When the SET command is scheduled to run, the executor calls the GPIO BFM <code>gpio_set()</code> procedure, described in the GPIO BFM QuickRef.</p> <p>Example:</p> <pre>gpio_set (GPIO_VVCT, 1, C_BAUDRATE_9600, "Set baudrate to 9600");</pre> |
| gpio_get() | <p>gpio_get (VVCT, vvc_instance_idx, msg)</p> <p>The <code>gpio_get()</code> VVC procedure adds a GET command to the GPIO VVC executor queue, that will run as soon as all preceding commands have completed. When the transmit command is scheduled to run, the executor calls the GPIO BFM <code>gpio_get()</code> procedure, described in the GPIO BFM QuickRef. The received data from DUT will not be returned in this procedure call since it is non-blocking for the sequencer/caller, but the received data will be stored in the VVC for a potential future fetch (see example with <code>fetch_result</code> below).</p> <p>Example:</p> <pre>gpio_get (GPIO_VVCT, 1, "Read baudrate");</pre> <p>Example with <code>fetch_result()</code> call: Result is placed in <code>v_data</code></p> <pre>variable v_cmd_idx : natural; -- Command index for the last read variable v_data : std_logic_vector(31 downto 0); -- Result from read (...) gpio_get(GPIO_VVCT, 1, "Read baudrate"); v_cmd_idx := get_last_received_cmd_idx(GPIO_VVCT, 1); await_completion(GPIO_VVCT, 1, v_cmd_idx, 1 us, "Wait for receive to finish"); fetch_result(GPIO_VVCT, 1, v_cmd_idx, v_data, "Fetching result from receive operation");</pre> |
| gpio_check() | <p>gpio_check (VVCT, vvc_instance_idx, data_exp, msg, alert_level)</p> <p>The <code>gpio_check()</code> VVC procedure adds a CHECK command to the GPIO VVC executor queue, that will run as soon as all preceding commands have completed. When the CHECK command is scheduled to run, the executor calls the GPIO BFM <code>gpio_check()</code> procedure, described in the GPIO BFM QuickRef.</p> <p>Example:</p> <pre>gpio_check (GPIO_VVCT, 1, x"F5", "Check data from UART RX");</pre> <p>The procedure can also be called with the optional parameters, e.g.:</p> <pre>gpio_check (GPIO_VVCT, 1, x"5F", "Check data from UART RX", ERROR);</pre> |

gpio_expect()

gpio_expect (VVCT, vvc_instance_idx, data_exp, timeout, msg, alert_level)

The gpio_expect() VVC procedure adds a EXPECT command to the GPIO VVC executor queue, that will run as soon as all preceding commands have completed. When the EXPECT command is scheduled to run, the executor calls the GPIO BFM gpio_expect() procedure, described in the GPIO BFM QuickRef.

Example:

```
gpio_expect(GPIO_VVCT, 1, x"0D", 2 ms, "Read UART RX until CR is found or timeout");
```

The procedure can also be called with the optional parameters, e.g.:

```
gpio_expect(GPIO_VVCT, 1, x"0D", 2 ms, "Read UART RX until CR is found or timeout", ERROR);
```

2 VVC Configuration

| Record element | Type | C_SPI_VVC_CONFIG_DEFAULT | Description |
|---------------------------------------|-------------------|---|---|
| inter_bfm_delay | t_inter_bfm_delay | C_GPIO_INTER_BFM_DELAY_DEFAULT | Delay between any requested BFM accesses towards the DUT. - TIME_START2START: Time from a BFM start to the next BFM start (A TB_WARNING will be issued if access takes longer than TIME_START2START). - TIME_FINISH2START: Time from a BFM end to the next BFM start. Any insert_delay() command will add to the above minimum delays, giving for instance the ability to skew the BFM starting time. |
| cmd_queue_count_max | natural | C_CMD_QUEUE_COUNT_MAX | Maximum pending number in command queue before queue is full. Adding additional commands will result in an ERROR. |
| cmd_queue_count_threshold | natural | C_CMD_QUEUE_COUNT_THRESHOLD | An alert with severity "cmd_queue_count_threshold_severity" will be issued if command queue exceeds this count. Used for early warning if command queue is almost full. Will be ignored if set to 0. |
| cmd_queue_count_threshold_severity | t_alert_level | C_CMD_QUEUE_COUNT_THRESHOLD_SEVERITY | Severity of alert to be triggered if command count exceeding cmd_queue_count_threshold |
| result_queue_count_max | natural | C_RESULT_QUEUE_COUNT_MAX | Maximum number of unfetched results before result_queue is full. |
| result_queue_count_threshold | natural | C_RESULT_QUEUE_COUNT_THRESHOLD | An alert with severity 'result_queue_count_threshold_severity' will be issued if command queue exceeds this count. Used for early warning if result queue is almost full. Will be ignored if set to 0. |
| result_queue_count_threshold_severity | t_alert_level | C_RESULT_QUEUE_COUNT_THRESHOLD_SEVERITY | Severity of alert to be initiated if exceeding result_queue_count_threshold |
| bfm_config | t_gpio_bfm_config | C_GPIO_BFM_CONFIG_DEFAULT | Configuration for GPIO BFM. See QuickRef for GPIO BFM |
| msg_id_panel | t_msg_id_panel | C_VVC_MSG_ID_PANEL_DEFAULT | VVC dedicated message ID panel |

The configuration record can be accessed from the Central Testbench Sequencer through the shared variable array, e.g.:

```
shared_gpio_vvc_config(C_VVC_IDX).inter_bfm_delay.delay_in_time := 10 ms;
```

3 VVC Status

The current status of the VVC can be retrieved during simulation. This is done by reading from the shared variable `shared_spi_vvc_status` record from the test sequencer. The record contains status for both channels, specified with the channel axis of the shared `spi_vvc_status` array. The record contents can be seen below:

| Record element | Type | Description |
|-------------------------------|---------|---|
| <code>current_cmd_idx</code> | natural | Command index currently running |
| <code>previous_cmd_idx</code> | natural | Previous command index to run |
| <code>pending_cmd_cnt</code> | natural | Pending number of commands in the command queue |

4 Additional Documentation

Additional documentation about UVVM and its features can be found under `"/uvvm_vvc_framework/doc/".`

5 Compilation

The GPIO VVC must be compiled with VHDL 2008.

It is dependent on the following libraries

- **UVVM Utility Library (UVVM-Util), version 2.2.0 and up**
- **UVVM VVC Framework, version 2.1.0 and up**
- **GPIO BFM**

Before compiling the GPIO VVC, make sure that `uvvm_vvc_framework` and `uvvm_util` have been compiled.

Compile order for the GPIO VVC:

| Compile to library | File | Comment |
|------------------------------|---|--|
| <code>bitvis_vip_gpio</code> | <code>gpio_bfm_pkg.vhd</code> | GPIO BFM |
| <code>bitvis_vip_gpio</code> | <code>vvc_cmd_pkg.vhd</code> | GPIO VVC command types and operations |
| <code>bitvis_vip_gpio</code> | <code>../uvvm_vvc_framework/src_target_dependent/td_target_support_pkg.vhd</code> | UVVM VVC target support package, compiled into the GPIO VVC library. |
| <code>bitvis_vip_gpio</code> | <code>../uvvm_vvc_framework/src_target_dependent/td_vvc_framework_common_methods_pkg.vhd</code> | UVVM framework common methods compiled into the GPIO VVC library |
| <code>bitvis_vip_gpio</code> | <code>vvc_methods_pkg.vhd</code> | GPIO VVC methods |
| <code>bitvis_vip_gpio</code> | <code>../uvvm_vvc_framework/src_target_dependent/td_queue_pkg.vhd</code> | UVVM queue package for the VVC |
| <code>bitvis_vip_gpio</code> | <code>../uvvm_vvc_framework/src_target_dependent/td_vvc_entity_support_pkg.vhd</code> | UVVM VVC entity methods compiled into the GPIO VVC library |
| <code>bitvis_vip_gpio</code> | <code>gpio_vvc.vhd</code> | GPIO VVC |

6 Simulator compatibility and setup

This VVC has been compiled and tested with Modelsim version 10.3d and Riviera-PRO version 2015.10.85.

For required simulator setup see **UVVM-Util** Quick reference.

INTELLECTUAL PROPERTY

Disclaimer: This IP and any part thereof are provided "as is", without warranty of any kind, express or implied, including but not limited to the warranties of merchantability, fitness for a particular purpose and noninfringement. In no event shall the authors or copyright holders be liable for any claim, damages or other liability, whether in an action of contract, tort or otherwise, arising from, out of or in connection with this IP.