

# Day 4: Probabilistic ML

and considerations for physical data

Vanessa Boehm, March 10 2022  
LSSTC-DSFP Session 14

# Deep Neural Models

## Deep Classification Networks



class 2

class 4

Learn a *classification* task  
generally supervised and non-probabilistic\*

# Deep Neural Models

## Deep Classification Networks

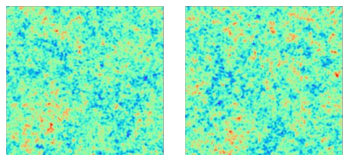


class 2

class 4

Learn a *classification* task  
generally supervised and non-probabilistic\*

## Deep Regression Networks



$S_8=0.55$

$S_8=0.78$

Learn a *regression* task  
generally supervised and non-probabilistic\*

# Deep Neural Models

## Deep Classification Networks

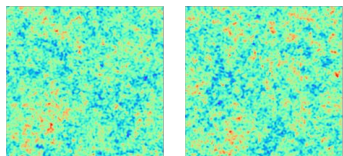


class 2

class 4

Learn a *classification* task  
generally supervised and non-probabilistic\*

## Deep Regression Networks



$S_8=0.55$

$S_8=0.78$

Learn a *regression* task  
generally supervised and non-probabilistic\*

## Deep Generative Networks



$\log p = -254$

$\log p = -332$

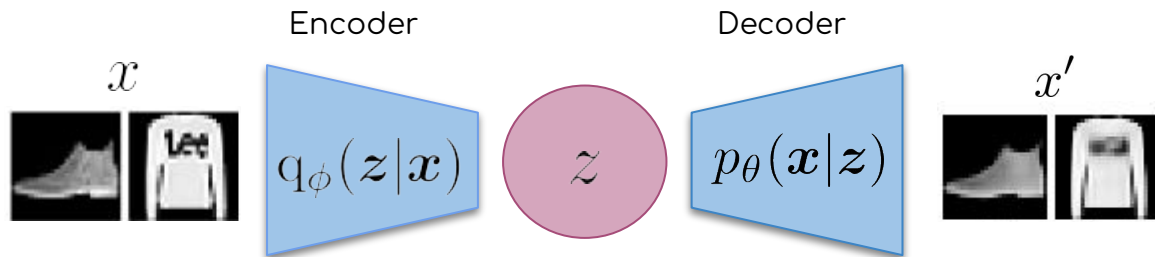
data generation



*Density estimation and data generation*  
generally unsupervised and fully probabilistic

# Example: Variational Autoencoder

Kingma & Welling 2013, Rezende 2014 + countless variants



density estimation :

$$\ln p_\theta(\mathbf{x}) = \ln \int d\mathbf{z} p(\mathbf{z}) p(\mathbf{x}|\mathbf{z})$$

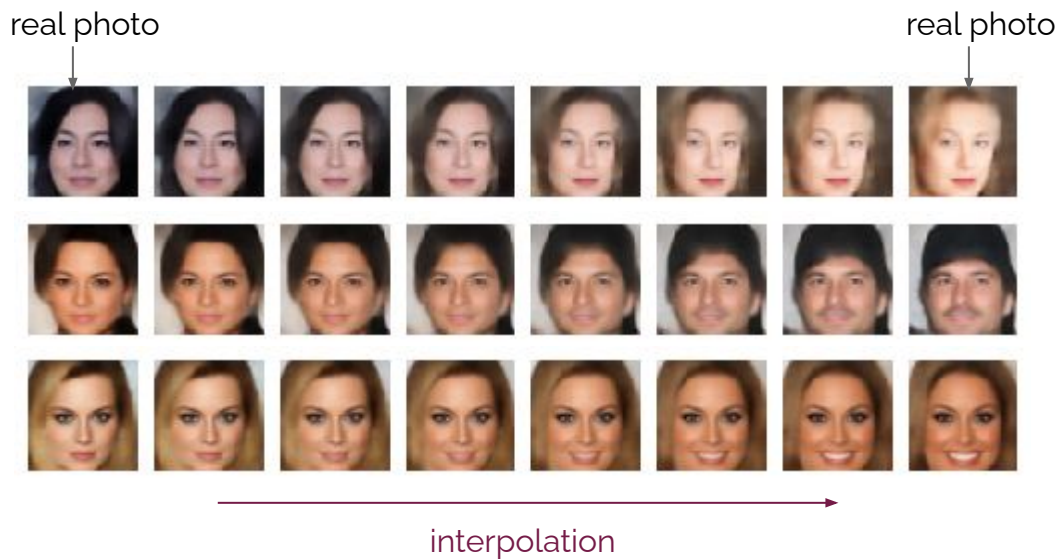
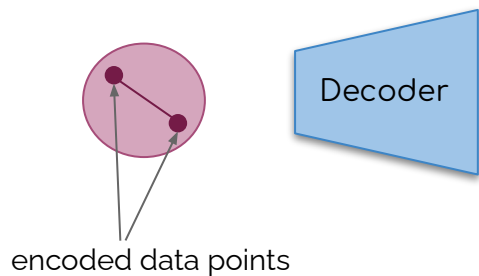
$$\geq \underbrace{\mathbb{E}_{q_\phi(z|x)} [\ln p_\theta(\mathbf{x}|z)]}_{\text{reconstruction error}} - \underbrace{D_{\text{KL}} [q_\phi(z|x) || p(z)]}_{\text{regularization}}$$

reconstruction error

regularization

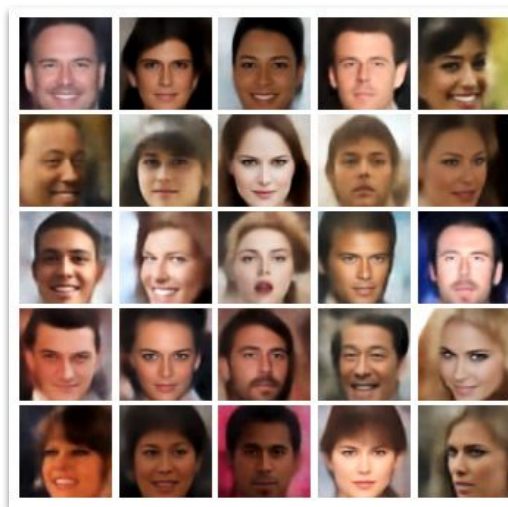
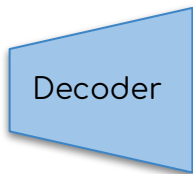
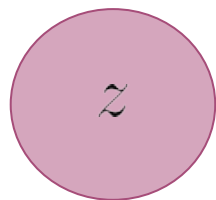
Gaussian prior

# Applications of VAEs: Data Interpolation



# Applications of VAEs: Data Generation

- Sample from Gaussian prior and decode



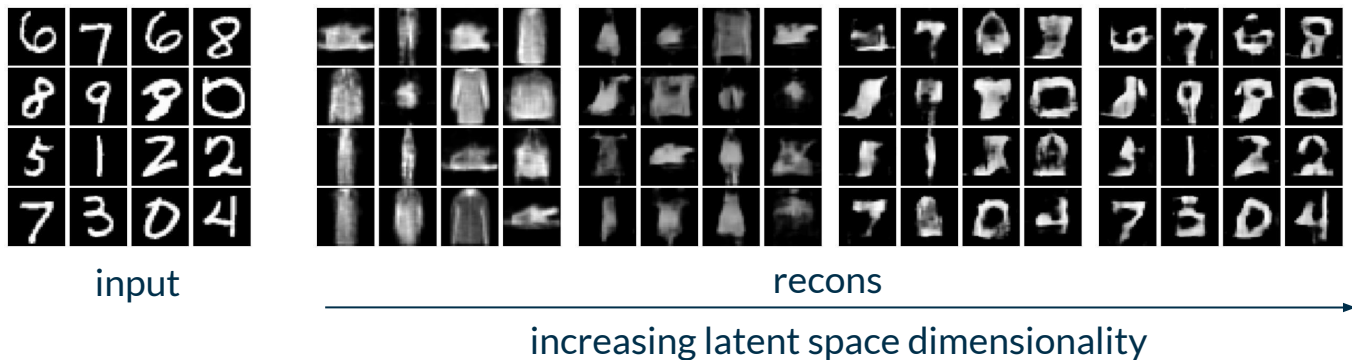
# Applications of VAEs: Anomaly detection

- **Option 1:** Use reconstruction error as anomaly metric
  - Problem high dimensional latent spaces and powerful decoders can result in small reconstruction errors even for anomalous data points



# Applications of VAEs: Anomaly detection

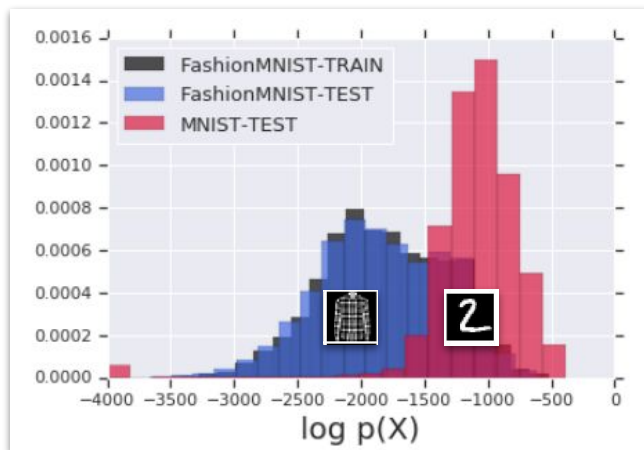
- **Option 1:** Use reconstruction error as anomaly metric
  - Problem high dimensional latent spaces and powerful decoders can result in small reconstruction errors even for anomalous data points



# Applications of VAEs: Anomaly detection

## Option 2: Use $p(x)$ estimate (ELBO for VAE) as anomaly metric

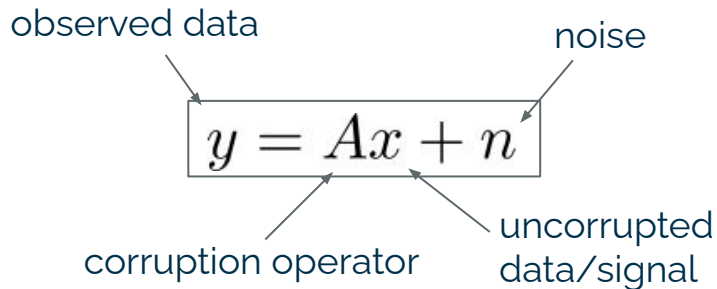
- Problem: Tends to fail for various reasons, sometimes *catastrophically* (Choi et al 2018, Nalisnick et al 2019a, Hendrycks et al 2019)



# Applications of VAEs: Reconstruction of Corrupted Data



# Applications of VAEs: Reconstruction of Corrupted Data



$$p(x|y) = p(y|x)p(x)$$

high dimensional posterior

unknown prior/  
data distr.

The equation  $p(x|y) = p(y|x)p(x)$  is shown. An arrow points from  $p(x|y)$  to the text "high dimensional posterior". Another arrow points from  $p(x)$  to the text "unknown prior/  
data distr."

# Reconstruction of Corrupted Data

1. Train a **Variational Autoencoder** on uncorrupted data
2. Replace  $\mathbf{x}$  by it's generative process  $\mathbf{g}(\mathbf{z})$
3. The new, exact prior distribution is Gaussian

observed data

noise

$$y = A(g_{\theta}(z)) + n'$$

corruption operator

generative model

The diagram shows the equation  $y = A(g_{\theta}(z)) + n'$  enclosed in a box. Four arrows point to different parts of the equation: 'observed data' points to  $y$ , 'noise' points to  $n'$ , 'corruption operator' points to  $A$ , and 'generative model' points to  $g_{\theta}$ .

low dimensional posterior

known prior

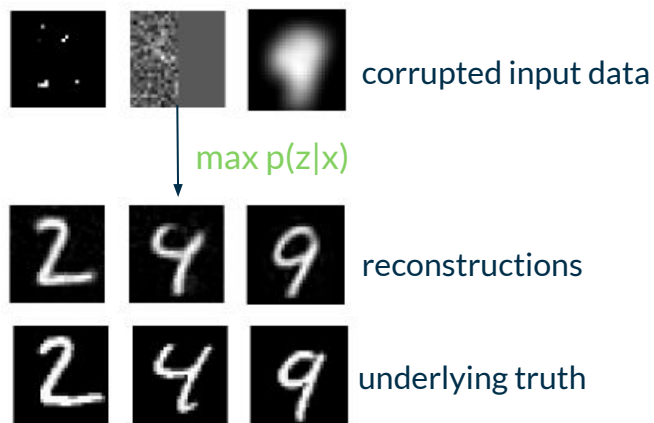
$$p(z|y) = p(y|z)p(z)$$

The diagram shows the equation  $p(z|y) = p(y|z)p(z)$  enclosed in a box. Two arrows point to different parts of the equation: 'low dimensional posterior' points to  $p(z|y)$  and 'known prior' points to  $p(z)$ .

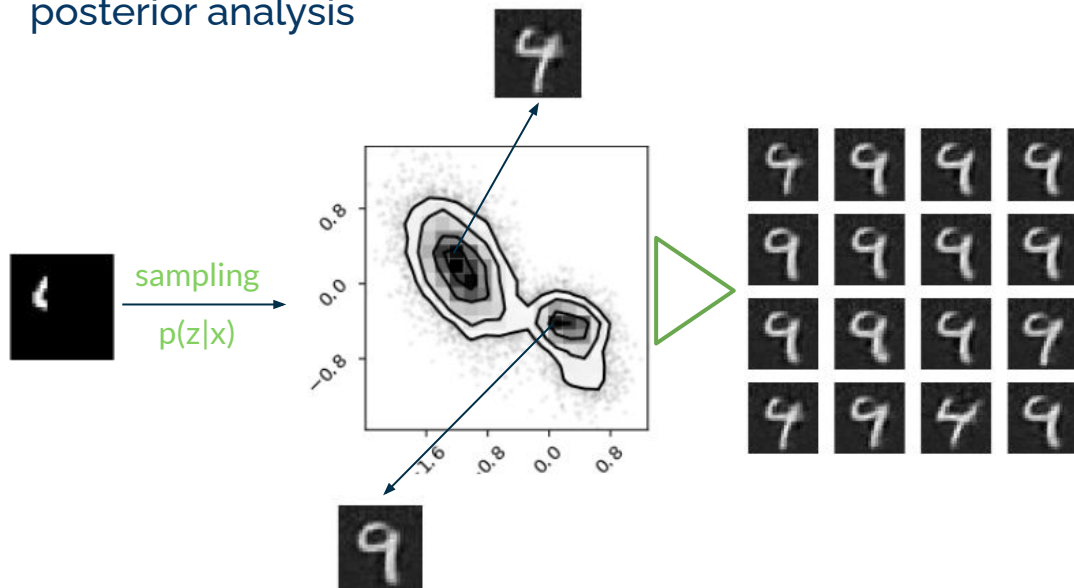
# Reconstruction of Corrupted Data

e.g. Boehm et al. 2019

## reconstruction



## posterior analysis



# Problems with VAEs

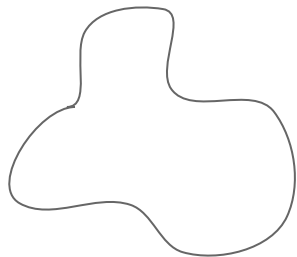
- VAEs often struggle to maximize both terms in the ELBO at the same time
  - The encoded distribution is often not perfectly Gaussian
  - The approximate posterior distribution is often a bad approximation to the true one. Don't use it! (exercise)
  - Lots of hyperparameters need to be optimized to obtain the desired results (e.g. sample size in the training, form of likelihood etc)
  - Vast literature on how to improve VAEs... E.g. beta-VAE, where a scalar parameter  $\beta$  is used to up- or downweight the KL-term.

# Another density estimator: Normalizing Flows

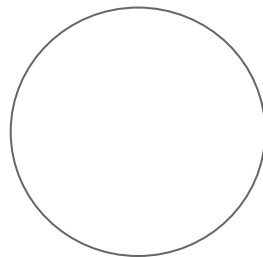
NFs are bijective models. No data compression only transformation!

e.g. RealNVP (Dinh et al. 2019), Glow (Kingma et al 2018), MAF (Papamakarios 2017), NSF (Durcan 2019), SINF (Dai et al 2021)

data space distribution



latent space distribution



encoder

$$z = \mathbf{b}_\theta(x)$$

$$x = \mathbf{b}_\theta^{-1}(z)$$

decoder

density estimation :

$$\ln p_\theta(x) = \ln q(z) + \ln |\nabla_x \mathbf{b}_\theta(x)|$$

Jacobian of  
transformation

Gaussian distribution



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Jacobian of  
transformation

Gaussian distribution

# Today's exercise

- Use a normalizing flow to improve the VAE training. If we use an NF as prior it helps the VAE achieve a Gaussian prior distribution!
- Find out how well  $q(z|x)$  matches  $p(z|x)$
- Reconstruct corrupted data by maximizing the posterior  $p(z|x)$