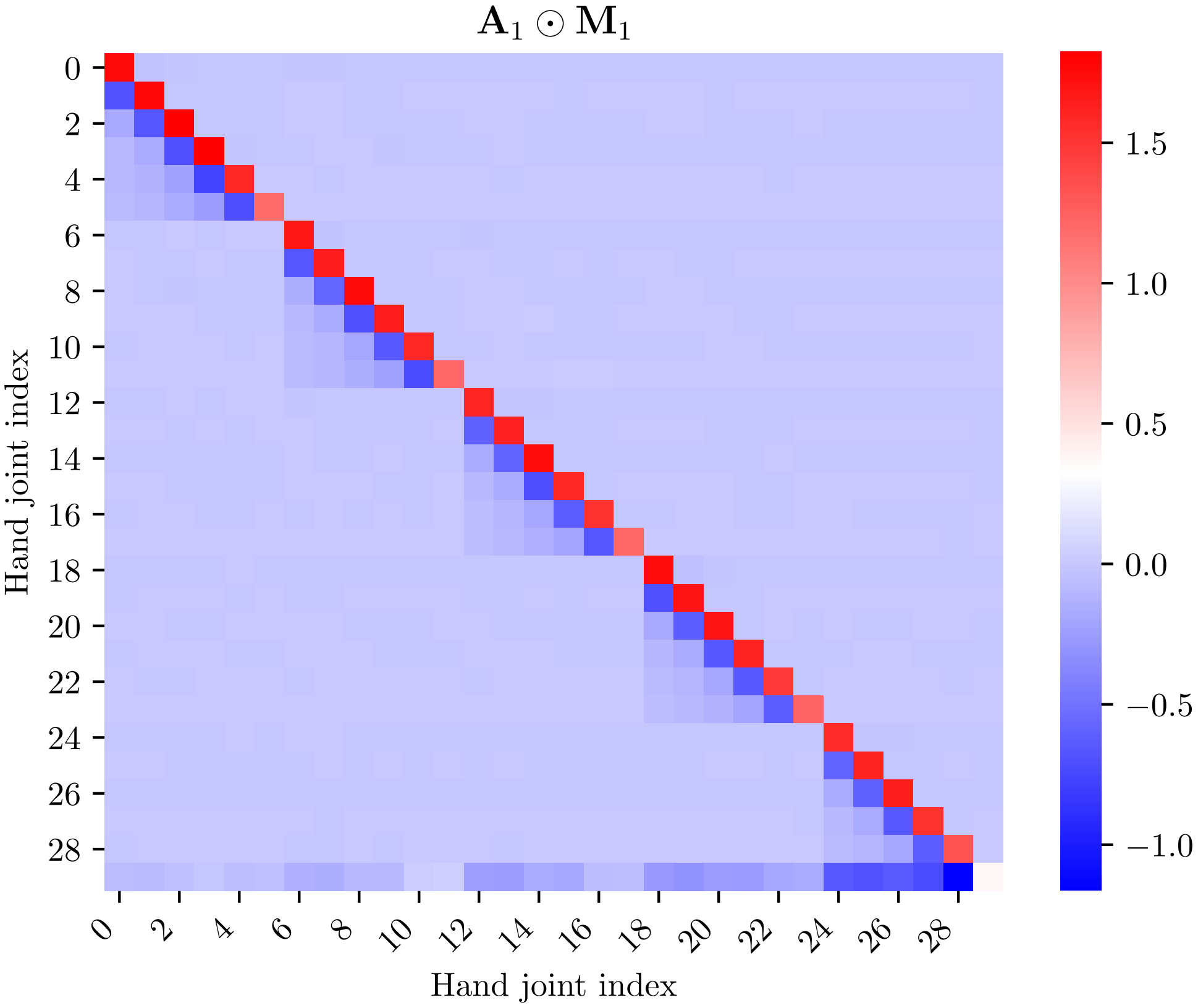
$\mathbf{A}_1 \odot \mathbf{M}_1$
Hand joint index
Hand joint index
0
2
4
6
8
10
12
14
16
18
20
22
24
26
28
1.5
1.0
0.5
0.0
−0.5
−1.0