

MATH1061/1002 Cheatsheet (Linear Algebra)

Semester 1, 2024

Abyan Majid

 [Source](#)

1	Complex numbers	2	2.4	Vector space	4
1.1	Imaginary unit	2	2.5	Unit vector	5
1.2	Cartesian, standard polar, exponential polar forms	2	2.6	Linear combination	5
1.3	Complex conjugate	2	2.7	Parallel vectors	5
1.4	Modulus of a complex number	2	2.8	Standard basis vectors	5
1.5	Principal argument	2	2.9	Dot product	5
1.6	Arithmetic in cartesian form	3	2.10	Theorems for dot products	5
1.7	Arithmetic in polar forms	3	2.11	Angle between vectors using dot product .	6
1.8	Equality of complex numbers	3	2.12	Orthogonal vectors	6
1.9	Roots of complex numbers	3	2.13	Projections	6
1.10	Complex exponential function	3	2.14	Cross products	6
2	Vectors	4	2.15	Properties for cross products	6
2.1	Vector algebra	4	2.16	Area inscribed by vectors in \mathbb{R}^3	7
2.2	Magnitude of a vector	4	2.17	Angle between vectors using cross product	7
2.3	Useful theorems for vector algebra	4	2.18	Forms of lines in \mathbb{R}^2	7
			2.19	Skewness of lines	7
			2.20	Forms of planes in \mathbb{R}^3	8

1 Complex numbers

1.1 Imaginary unit

Imaginary unit
$i = \sqrt{-1}$

1.2 Cartesian, standard polar, exponential polar forms

Name	Form
Cartesian	$z = a + bi$
Standard Polar	$r(\cos \theta + i \sin \theta)$
Exponential Polar	$re^{i\theta}$

1.3 Complex conjugate

Complex conjugate
Complex conjugate of $z = a + bi$ is $\bar{z} = a - bi$

Complex conjugate properties	
Property	Definition
Conjugate of a Sum	$\overline{z + w} = \bar{z} + \bar{w}$
Conjugate of a Product	$\overline{zw} = \bar{z} \times \bar{w}$
Conjugate of a Power	$\overline{z^n} = (\bar{z})^n$

1.4 Modulus of a complex number

Modulus
The modulus of a complex number $z = a + bi$ is $ z = \sqrt{a^2 + b^2} = \sqrt{z\bar{z}}$

1.5 Principal argument

Principal argument
The principal argument of $z \in \mathbb{C}$, denoted $\text{Arg } z$, satisfies $-\pi < \text{Arg } z \leq \pi$ So, to get principal argument, add or subtract multiples of 2π to/from θ .

Modulus properties	
Property	Definition
Multiplicative Property of Moduli	$ zw = z w $
Division Property of Moduli	$ \frac{z}{w} = \frac{ z }{ w }$
Triangle Inequality	$ z + w \leq z + w $
Reverse Triangle Inequality	$ z - w \geq z - w $

1.6 Arithmetic in cartesian form

Operation	let $z = a + bi$ and $w = c + di$
Addition	$z + w = (a + c) + (b + d)i$
Subtraction	$z - w = (a - c) + (b - d)i$
Multiplication	$z \times w = (a + bi)(c + di)$ $z \times w = ac + adi + bci + bdi^2$ $z \times w = (ac - bd) + (ad + bc)i$
Division	$z \div w = \frac{z}{w} \times \frac{\overline{w}}{\overline{w}}$ $z \div w = \frac{a + bi}{c + di} \times \frac{c - di}{c - di}$

1.7 Arithmetic in polar forms

let $z = re^{i\theta}$ and $w = se^{i\phi}$		
Operation	Exponential polar	Standard polar
Multiplication	$zw = rse^{i(\theta+\phi)}$	$zw = rs(\cos(\theta + \phi) + i \sin(\theta + \phi))$
Division	$\frac{z}{w} = \left(\frac{r}{s}\right)e^{i(\theta-\phi)}$	$\frac{z}{w} = \frac{r}{s}(\cos(\theta - \phi) + i \sin(\theta - \phi))$
Power	$z^n = r^n e^{in\theta}$ where $n \in \mathbb{Z}$	$z^n = r^n(\cos(n\theta) + i \sin(n\theta))$

1.8 Equality of complex numbers

Equality in Cartesian form
$(a + bi) = (c + di)$ if and only if $a = c$, $b = d$

Equality in polar forms
$re^{i\theta} = se^{i\phi}$ if and only if $r = s$ and $\theta = \phi + 2k\pi$ for $k \in \mathbb{Z}$

1.9 Roots of complex numbers

When asked to find the roots of $z^n = \alpha$
$z = r^{\frac{1}{n}} e^{i(\frac{\theta+2k\pi}{n})}$ satisfy $z^n = \alpha$ for each $k = 0, 1, 2, \dots, n - 1$.

1.10 Complex exponential function

Complex exponential function
<p>For $z = a + bi$, we define $e^z = e^a e^{bi}$, which means</p> $e^z = e^a(\cos b + i \sin b)$ <p>from which we know $e^z = e^a$ and $\arg(e^z) = b$.</p>

2 Vectors

2.1 Vector algebra

Let $\mathbf{u} = [u_1, \dots, u_n], \mathbf{v} = [v_1, \dots, v_n] \in \mathbb{R}^n, c \in \mathbb{R}$			
Operation	What to do	Operation	What to do
Addition	$\mathbf{u} + \mathbf{v} = \begin{bmatrix} u_1 + v_1 \\ \vdots \\ u_n + v_n \end{bmatrix}$	Scalar multiplication	$c\mathbf{u} = \begin{bmatrix} cu_1 \\ \vdots \\ cu_n \end{bmatrix}$
Subtraction	$\mathbf{u} - \mathbf{v} = \begin{bmatrix} u_1 - v_1 \\ \vdots \\ u_n - v_n \end{bmatrix}$	Negation	$-\mathbf{u} = \begin{bmatrix} -u_1 \\ \vdots \\ -u_n \end{bmatrix}$

2.2 Magnitude of a vector

Magnitude of a vector
The magnitude (length) of a vector \mathbf{u} is given by $\ \mathbf{u}\ = \sqrt{u_1^2 + u_2^2 + \dots + u_n^2}$ <p>Also note that $\ c\mathbf{u}\ = c \ \mathbf{u}\$</p>

2.3 Useful theorems for vector algebra

Let $\mathbf{u} = [u_1, \dots, u_n], \mathbf{v} = [v_1, \dots, v_n] \in \mathbb{R}^n, c, d \in \mathbb{R}$ and \mathbf{o} be the zero vector	
No	Theorem
1	$\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$
2	$(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$
3	$\mathbf{u} + \mathbf{o} = \mathbf{u}$
4	$\mathbf{u} + (-\mathbf{u}) = \mathbf{o}$
5	$c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$
6	$\mathbf{u}(c + d) = c\mathbf{u} + d\mathbf{u}$
7	$c(d\mathbf{u}) = (cd)\mathbf{u}$
8	$1\mathbf{u} = \mathbf{u}$

2.4 Vector space

Vector Space
<p>A <i>vector space</i> is a set V equipped with:</p> <ul style="list-style-type: none"> • Addition: For any $\mathbf{u}, \mathbf{v} \in V$, there exists $\mathbf{u} + \mathbf{v} \in V$. • Scalar multiplication: For any $\mathbf{u} \in V$ and any scalar $c \in \mathbb{R}$, there exists $c\mathbf{u} \in V$. <p>These operations must satisfy properties (1)-(8) defined in Section 2.3.</p> <p>Examples: \mathbb{R}^n and \mathbb{C} are both examples of vector spaces.</p>

2.5 Unit vector

Unit vector
A "unit vector" is a vector of length 1. If $\mathbf{u} \in \mathbb{R}^n$, $\ \mathbf{u}\ \neq 0$ then $\frac{1}{\ \mathbf{u}\ }\mathbf{u}$ is a unit vector.

2.6 Linear combination

Linear combination
A "linear combination" of $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k \in \mathbb{R}^n$ is a vector of the form $C_1\mathbf{v}_1 + C_2\mathbf{v}_2 + \dots + C_k\mathbf{v}_k$.
Example: $[2, 2]$ is a linear combination of $[-1, 2], [0, 6]$ because $[2, 2] = (-2)[-1, 2] + (1)[0, 6]$

2.7 Parallel vectors

Parallel vectors
Vectors \mathbf{u} and \mathbf{v} are parallel if $\mathbf{u} = c\mathbf{v}$ or $\mathbf{v} = c\mathbf{u}$ for $c \in \mathbb{R}$.

2.8 Standard basis vectors

Standard basis vectors
$\mathbf{e}_1 = [1, 0, 0], \mathbf{e}_2 = [0, 1, 0], \mathbf{e}_3 = [0, 0, 1]$ are the standard basis vectors in \mathbb{R}^3 .
Similarly, $\mathbf{e}_1 = [1, 0, \dots, 0], \mathbf{e}_2 = [0, 1, 0, \dots, 0], \dots, \mathbf{e}_n = [0, 0, \dots, 0, 1] \in \mathbb{R}^n$ are the standard basis vectors in \mathbb{R}^n

2.9 Dot product

Dot product
For $\mathbf{u} = [u_1, \dots, u_n], \mathbf{v} = [v_1, \dots, v_n] \in \mathbb{R}^n$, we define the dot product $\mathbf{u} \cdot \mathbf{v} = u_1v_1 + u_2v_2 + \dots + u_nv_n \in \mathbb{R}$

2.10 Theorems for dot products

Let $\mathbf{u}, \mathbf{v}, \mathbf{w} \in \mathbb{R}^n, c \in \mathbb{R}$	
No	Theorem
1	$\mathbf{u} \cdot \mathbf{v}$
2	$\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w}$
3	$(c\mathbf{u}) \cdot \mathbf{v} = c(\mathbf{u} \cdot \mathbf{v})$
4	$\mathbf{u} \cdot \mathbf{u} \geq 0$
5	$\ \mathbf{u}\ = \sqrt{\mathbf{u} \cdot \mathbf{u}}$
6	$ \mathbf{u} \cdot \mathbf{v} \leq \ \mathbf{u}\ \ \mathbf{v}\ $ (Cauchy-Schwarz Inequality)
7	$\ \mathbf{u} + \mathbf{v}\ \leq \ \mathbf{u}\ + \ \mathbf{v}\ $ (Triangle Inequality)

2.11 Angle between vectors using dot product

Angle between vectors using dot product
<p>We define angle between vectors $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$ to be a unique value $\theta \in [0, \pi]$ such that:</p> $\cos \theta = \frac{\mathbf{u} \cdot \mathbf{v}}{\ \mathbf{u}\ \ \mathbf{v}\ }$ <p>which means we can also find $\mathbf{u} \cdot \mathbf{v}$ if we know the the magnitude of u and v, and the angle in between:</p> $\mathbf{u} \cdot \mathbf{v} = \ \mathbf{u}\ \ \mathbf{v}\ \cos \theta$

2.12 Orthogonal vectors

Orthogonal vectors
<p>Vectors $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$ are orthogonal iff $\mathbf{u} \cdot \mathbf{v} = 0$</p> <p>Note: Orthogonal vectors are perpendicular</p> $\mathbf{u} \cdot \mathbf{v} = 0 \implies \cos \theta = \frac{\mathbf{u} \cdot \mathbf{v}}{\ \mathbf{u}\ \ \mathbf{v}\ } = 0$ $\theta = \cos^{-1}(0) = \frac{\pi}{2}, \text{ i.e. perpendicular.}$

2.13 Projections

Projections
<p>The projection of \mathbf{u} onto \mathbf{v} is defined by</p> $\text{proj}_{\mathbf{v}}(\mathbf{u}) = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \right) \mathbf{v}$

2.14 Cross products

Cross products
<p>Cross product of $\mathbf{u} = [u_1, u_2, u_3], \mathbf{v} = [v_1, v_2, v_3] \in \mathbb{R}^3$ is the vector</p> $\mathbf{u} \times \mathbf{v} = \begin{bmatrix} u_2 v_3 - u_3 v_2 \\ u_3 v_1 - u_1 v_3 \\ u_1 v_2 - u_2 v_1 \end{bmatrix}$

2.15 Properties for cross products

Let $\mathbf{u}, \mathbf{v}, \mathbf{w} \in \mathbb{R}^3, c \in \mathbb{R}$	
No	Property
1	$\mathbf{u} \times \mathbf{v} \neq \mathbf{v} \times \mathbf{u}$ (not commutative)
2	$\mathbf{u} \times (\mathbf{v} \times \mathbf{w}) \neq (\mathbf{u} \times \mathbf{v}) \times \mathbf{w}$ (not associative)
3	$\mathbf{u} \times \mathbf{v} = -(\mathbf{v} \times \mathbf{u})$ (anti-commutative)
4	$\mathbf{u} \times \mathbf{u} = \mathbf{0}$
5	$\mathbf{u} \cdot (\mathbf{u} \times \mathbf{v}) = 0 = \mathbf{v} \cdot (\mathbf{u} \times \mathbf{v})$ i.e. given 2 vectors, their cross product is orthogonal to both vectors.
6	$\mathbf{u} \times (\mathbf{v} + \mathbf{w}) = (\mathbf{u} \times \mathbf{v}) + (\mathbf{u} \times \mathbf{w})$
7	$c(\mathbf{u} + \mathbf{v}) = (c\mathbf{u}) \times \mathbf{v} = \mathbf{u} \times (c\mathbf{v})$

2.16 Area inscribed by vectors in \mathbb{R}^3

Let $\mathbf{u}, \mathbf{v} \in \mathbb{R}^3$	
Shape	Area
Parallelogram	The area of the parallelogram inscribed by \mathbf{u}, \mathbf{v} is $\ \mathbf{u} \times \mathbf{v}\ $
Triangle	The area of the triangle inscribed by \mathbf{u}, \mathbf{v} is $\frac{1}{2}\ \mathbf{u} \times \mathbf{v}\ $

2.17 Angle between vectors using cross product

Angle between vectors using cross product
Let $\mathbf{u}, \mathbf{v} \in \mathbb{R}^3$ and θ the angle between them. Then, $\ \mathbf{u} \times \mathbf{v}\ = \ \mathbf{u}\ \ \mathbf{v}\ \sin \theta$ which means $\theta = \sin^{-1} \frac{\ \mathbf{u} \times \mathbf{v}\ }{\ \mathbf{u}\ \ \mathbf{v}\ }$

2.18 Forms of lines in \mathbb{R}^2

Let \mathbf{p} : position vector pointing to the line \mathbf{n} : normal vector (vector orthogonal to the line) \mathbf{d} : direction vector (vector parallel to the line)			
Name	Form	How to obtain	Survives \mathbb{R}^n
Normal form	$\mathbf{n} \cdot (\mathbf{x} - \mathbf{p}) = 0$	1) Find $\mathbf{p}, \mathbf{n} \in \mathbb{R}^2$ 2) Write $\mathbf{n} \cdot (\mathbf{x} - \mathbf{p}) = 0$	No
General form	$ax + by = c$	1) Find the normal form 2) Let $\mathbf{x} = [x, y]$, $\mathbf{n} = [a, b]$, and write $c = \mathbf{n} \cdot \mathbf{p}$ 3) Simplify as follows $\mathbf{n} \cdot (\mathbf{x} - \mathbf{p}) = 0$ $\implies [a, b] \cdot ([x, y] - \mathbf{p}) = 0$ $\implies [a, b] \cdot [x, y] - c = 0$ $\implies ax + by = c$	No
Vector form	$\mathbf{x} = \mathbf{p} + t\mathbf{d}, t \in \mathbb{R}$	1) Find $\mathbf{p}, \mathbf{d} \in \mathbb{R}^2$ 2) Write $\mathbf{x} = \mathbf{p} + t\mathbf{d}, t \in \mathbb{R}$	Yes
Parametric equations	$x = p_1 + td_1$ $y = p_2 + td_2$ for $t \in \mathbb{R}$	1) Find the vector form 2) Write equations using each corresponding components of \mathbf{x}, \mathbf{p} and \mathbf{d}	Yes

2.19 Skewness of lines

Skewness of lines
Two lines are "skew" if they are NOT parallel and do NOT intersect. (applicable only to \mathbb{R}^3 and above since all non-parallel lines in \mathbb{R}^2 has to intersect)

2.20 Forms of planes in \mathbb{R}^3

<p>Let</p> <p>\mathbf{p} : position vector pointing to the line</p> <p>\mathbf{n} : normal vector (vector orthogonal to the line)</p> <p>\mathbf{u}, \mathbf{v} : direction vector (vector parallel to the line)</p>			
Name	Form	How to obtain	Survives \mathbb{R}^n
Normal form	$\mathbf{n} \cdot (\mathbf{x} - \mathbf{p}) = 0$	1) Find $\mathbf{p}, \mathbf{n} \in \mathbb{R}^3$ 2) Write $\mathbf{n} \cdot (\mathbf{x} - \mathbf{p}) = 0$	No
General form	$ax + by + cz = d$	1) Find the normal form 2) Let $\mathbf{x} = [x, y, z]$, $\mathbf{n} = [a, b, c]$, and write $d = \mathbf{n} \cdot \mathbf{p}$ 3) Simplify as follows $\mathbf{n} \cdot (\mathbf{x} - \mathbf{p}) = 0$ $\implies [a, b, c] \cdot ([x, y, z] - \mathbf{p}) = 0$ $\implies ax + by + cz = d$	No
Vector form	$\mathbf{x} = \mathbf{p} + s\mathbf{u} + t\mathbf{v}$ for $s, t \in \mathbb{R}$	1) Find $\mathbf{p}, \mathbf{u}, \mathbf{v} \in \mathbb{R}^3$ 2) Write $\mathbf{x} = \mathbf{p} + s\mathbf{u} + t\mathbf{v}$, for $s, t \in \mathbb{R}$	Yes
Parametric equations	$x = p_1 + su_1 + tv_1$ $y = p_2 + su_2 + tv_2$ $z = p_3 + su_3 + tv_3$ for $s, t \in \mathbb{R}$	1) Find the vector form 2) Write equations using each corresponding components of $\mathbf{x}, \mathbf{p}, \mathbf{u}$ and \mathbf{v}	Yes