Graph Theory

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This set of notes is a work-in-progress account of the course 'Graph Theory', originally lectured by Dr Julian Sahasrabudhe in Lent 2020 at Cambridge. These notes are not a transcription of the lectures, but they do roughly follow what was lectured (in content and in structure).

These notes are my own view of what was taught, and should be somewhat of a superset of what was actually taught. I frequently provide different explanations, proofs, examples, and so on in areas where I feel they are helpful. Because of this, this work is likely to contain errors, which you may assume are my own. If you spot any or have any other feedback, I can be contacted at ak2316@cam.ac.uk.

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1 Introduction

For many people, 'Graph Theory' is a first course in combinatorics. It's an area with a big focus on problem solving, and it can give a perspective on many other areas of mathematics.

§1.1 Definitions

We will begin our course in graph theory naturally by defining what a graph is.

Definition 1.1.1 (Graph)

A **graph** is an ordered pair G = (V, E) where V is the set of **vertices**, and $E \subseteq \{\{x,y\} \mid x,y \in V, x \neq y\}$ is a set of unordered pairs of vertices called **edges**.

We have a natural way of drawing a graph. For each vertex we have a point in the plane, and for each edge we draw a line between the corresponding pair of vertices.

Example 1.1.2 (Example of a Graph)

The ordered pair (V, E) where $V = \{1, 2, ..., 6\}$ and $E = \{\{1, 2\}, \{2, 3\}, ..., \{5, 6\}\}$ is a graph.



This graph is known as P_6 , a path on 6 vertices.

§1.1.1 Common Graphs

There are some graphs that will appear repeatedly throughout the course, and we will define them now.

Definition 1.1.3 (Path)

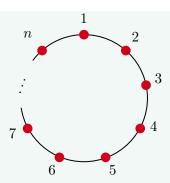
We define P_n to be the graph $V = \{1, ..., n\}$, $E = \{\{1, 2\}, \{2, 3\}, ..., \{n - 1, n\}\}$ as shown.

$$1$$
 2 3 $n-1$ n

We call this a **path** on n vertices, and say it has **length** n-1.

Definition 1.1.4 (Cycle)

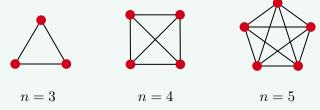
We define C_n (for $n \geq 3$) to be the graph $V = \{1, ..., n\}$, $E = \{\{1, 2\}, ..., \{n-1, n\}, \{n, 1\}\}$ as shown.



We call this the **cycle** on n vertices.

Definition 1.1.5 (Complete Graph)

The **complete graph** on n vertices K_n is the graph $\{1, \ldots, n\}$ and $E = \{\{i, j\} \mid i \neq j \in V\}$.

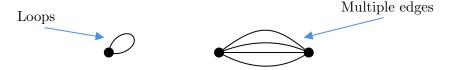


Note that there is an edge between every pair of vertices.

Definition 1.1.6 (Empty Graph)

We define the **empty graph** on n vertices $\overline{K_n}$ to have $V = \{1, \ldots, n\}$ but $E = \emptyset$.

Remark. In our definition of a graph, we *don't allow* loops, and there *cannot* be multiple edges between the same set of vertices.



These limitations are inherent in our definition, where we use sets rather than multisets. You can define graphs where such things are allowed, but for now we will outlaw them. We also note that edges are *unordered pairs*, so for now edges have no direction.

To be slightly more succinct, we will use some shorthand notation.

Notation. If G = (V, E) is a graph, and we have some edge $\{x, y\} \in E$, we will denote it by xy. We will also define |G| = |V|, and e(G) = |E|.

Example 1.1.7 (Vertices and Edges of K_n)

Consider the graph K_n . We have $|K_n| = n$, and $e(K_n) = {k \choose 2}$, as there is an edge between any pair of vertices.

§1.1.2 Subgraphs

Now we will define the notion of a *subgraph*, in the natural way.

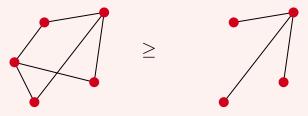
Definition 1.1.8 (Subgraph)

We say that H = (V', E') is a **subgraph** of G = (V, E) if $V' \subseteq V$ and $E' \subseteq E$.

Informally, H is a subgraph of G if we can remove vertices and edges from G to get H. Let's look at some examples.

Example 1.1.9 (Example of a Subgraph)

The graph on the right is a subgraph of the graph on the left.



We are also going to use some notation for removing an edge or a vertex from a graph. Of course, when removing a vertex you also have to remove the edges connecting to it.

Notation (Adding/Removing Vertices & Edges). For an edge xy or a vertex x, we define G - xy to be the graph G with the edge xy removed, and G - x to be G with vertex x removed, along with all edges incident to x. We will also define G + xy to be G with the edge xy, and G + x to be G with the vertex x.

§1.1.3 Graph Isomorphism

Now that we have defined graphs, it's natural to define some notion of isomorphism.

Definition 1.1.10 (Graph Isomorphism)

Let G = (V, E) and H = (V', E') be graphs. We say that $f : V \to V'$ is a **graph** isomorphism if $f(u)f(v) \in E' \iff uv \in E$.

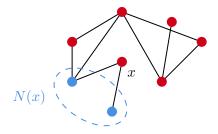
If there is a graph isomorphism between G and H then we say they are **isomorphic**.

Now for the following discussion, fix some graph G = (V, E), and let $x \in V$.

Definition 1.1.11 (Neighbourhood)

We define the **neighborhood** of x to be the set $N(x) = \{y \in V \mid xy \in E\}$.

Note that as in the diagram below, x is not in its own neighborhood.



Definition 1.1.12 (Degree)

We define the **degree** of a vertex x to be d(x) = |N(x)|. This is equal to the number of edges that are incident to x.

Definition 1.1.13 (Regularity)

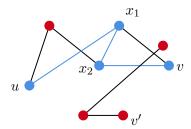
A graph G is said to be **regular** if all of the degrees are the same. We say G is k-regular if d(x) = k for all $x \in V$.

Example 1.1.14 (Regular and Non-Regular Graphs)

The graphs K_n is n-1 regular, and C_n is 2-regular. The graph P_n is not regular.

§1.1.4 Connectivity

We now want to define some notion of *connectivity*, where a vertex u is connected to vertex v if you can follow some path in the graph to get from u to v.



For example, in the graph above we want to say somehow that u and v are connected, but u and v' are not. To do this, we will introduce some more definitions.

Definition 1.1.15 (uv Path)

A *uv* path is a sequence x_1, x_2, \ldots, x_l where x_1, \ldots, x_l are distinct, $x_1 = u$, $x_l = v$ and $x_i x_{i+1} \in E$.

In the example above, ux_1x_2v is a uv path.

The slight subtlety in this condition is the *distinctness* condition. For example, if $x_1 ldots x_l$ is a uv path and $y_1 ldots y_{l'}$ is a vw path, then $x_1 ldots x_l y_1 ldots y_{l'}$ may not be a uw path since we may have reused an edge. Of course, we can just not reuse edges by avoiding cycles.

Proposition 1.1.16 (Joining Paths)

If $x_1
dots x_l$ is a uv path and $y_1
dots y_{l'}$ is a vw path, then $x_1
dots x_l
dots y_{l'}$ contains a uw path.

Proof. Choose a minimal subsequence $w_1 \dots w_r$ of $x_1 \dots x_l y_1 \dots y_{l'}$ such that

- 1. $w_i w_{i+1} \in E$.
- 2. $w_1 = u, w_r = w$.

We now claim that $w_1 ldots w_r$ is a uw path. If this was not the case, then it must fail on distinctness, so there would exist some z such that the sequence is

$$w_1 \dots w_a z w_{a+2} \dots w_b z w_{b+2} w_r$$

but now note that

$$w_1 \dots w_a z w_{b+2} \dots w_r$$

also satisfies the conditions for the subsequence, but is strictly shorter length. This contradicts the minimality condition. \Box

Now given G = (V, E), let's define an equivalence relation \sim on V, where

 $x \sim y \iff$ there exists an xy path in G.

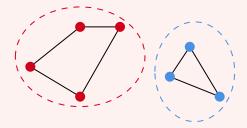
Proposition 1.1.17

 \sim is an equivalence relation.

Proof. Note that \sim is reflexive and symmetric, and we get transitivity from our previous proposition.

Example 1.1.18

In the graph below, the vertices that are the same colour are in the same equivalence class under \sim .



Definition 1.1.19 (Connected Graph)

If there is a path between any two vertices in G then we say that G is **connected**.

Definition 1.1.20 (Connected Components)

We call the equivalence classes of \sim on G the **components** or **connected components** of G.

§1.2 Trees

We will now discuss a special class of graph called *trees*. This class is quite restrictive (yet is quite useful), and they have some nice properties.

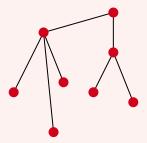
To define what a tree is, we first need a notion of when a graph is acyclic.

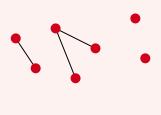
Definition 1.2.1 (Acyclic)

A graph G is said to be **acyclic** if it does not contain any subgraph isomorphic to a cycle, C_n .

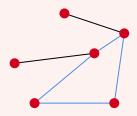
Example 1.2.2 (Example of Acyclic/Non-Acyclic Graphs)

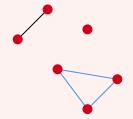
In the example below, the two graphs are both acyclic.





Two non-acyclic graphs are shown below. The subgraphs isomorphic to C_4 and C_3 are highlighted.





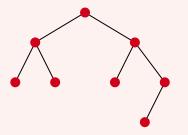
Definition 1.2.3 (Tree)

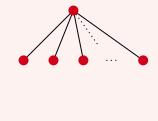
A **tree** is a connected, acyclic graph.

Example 1.2.4 (Examples of Trees)

The following three graphs are trees.







Proposition 1.2.5 (Characterising Trees)

The following are equivalent.

- (a) G is a tree.
- (b) G is a maximal acyclic graph (adding any edge creates a cycle).
- (c) G is a minimal connected graph (removing any edge disconnects the graph).

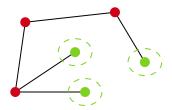
Proof. (a) \Longrightarrow (b). By definition G is acyclic. Let $x, y \in V$ such that $xy \notin E$. As G is connected, there is an xy path P. The that xPy then defines a cycle.

- $(b) \implies (a)$. By definition G is acyclic. So for a contradiction assume G is not connected and let x, y be vertices from different components. Now note G + xy is acyclic, but this contradicts the claim that G is maximally acyclic.
- $(a) \Longrightarrow (c)$. By definition G is connected. Suppose, for a contradiction, that there exists some vertices $x, y \in E$ with $x \neq y$ and G xy is connected. But then there is some xy path P that does not use the edge xy, so xPy is then a cycle, contradicting that G is acyclic.
- $(c) \implies (a)$. By definition G is connected. Again for a contradiction, assume that G contains a cycle C. Then let xy be an edge on C. We claim G xy is still connected. If $u, v \in V(G xy)$ then let P be a path in G from u to v. If xy does not appear as consecutive vertices on this path, then u is connected to v. Otherwise, we can consider a new path where we replace x, y with the other vertices in C xy in order. Thus u and v are still connected. This contradicts the minimal connectedness of G.

Definition 1.2.6 (Leaf)

Let G be a graph. A vertex $v \in V(G)$ is a **leaf** if d(v) = 1.

For example, the tree below has three leaves.



In general, trees has a leaf.

Proposition 1.2.7 (Trees Have Leaves)

Every tree T with $|T| \ge 2$ has a leaf.

Proof. Let T be a tree with $|T| \geq 2$, and let P be a path of maximum length in T, with $P = x_1 \dots x_k$. We claim that $d(x_k) = 1$. Observe that $\deg(x_k) \geq 1$, since $x_k x_{k-1} \in E$. If x_k is adjacent to another vertex $y \neq x_{k-1}$, then either $y \in A$

 $\{x_1, \ldots, x_{k-2}\}$, which would imply that T contains a cycle, or $y \notin \{x_1, \ldots, x_{k-2}\}$, then $x_1 \ldots x_k y$ is a path longer than P, which violates its maximality. \square

Remark. This proof gives us two leaves in T, which is the best we can hope for considering P_n is a tree with exactly two leaves.

Proposition 1.2.8 (Edges of a Tree)

Let T be a tree. Then e(T) = |T| - 1.

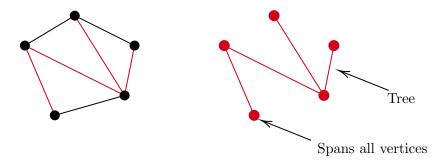
Proof. We will do induction on n = |T|. If n = 1, this is trivial as there is only one edge. Now given T with at least 2 vertices, let x be a leaf in T, and define T' = T - x.

T' must be acyclic, since we have only removed vertices. T' must also be connected since for all $u, v \in V(T')$ there exists a path from u to v in T that does not use x, so it is also a path from u to v in T'. Thus T' is a tree. Thus by induction, T' has n-2 edges, and e(T)=e(T')+1=|T|-1.

Now lets think about trees as subgraphs of other graphs.

Definition 1.2.9 (Spanning Tree)

Let G be a graph. We say T is a **spanning tree** of G if T is a tree on V(G) and is a subgraph of G.



Spanning trees are useful in a number of contexts, one of which is giving a sensible ordering to the vertices of a graph. They are particularly useful because of the following result.

Proposition 1.2.10 (Connected Graphs have Spanning Trees)

Every connected graph contains a spanning tree.

Proof. A tree is a minimal connected graph. So take the connected graph and remove edges until it becomes a minimal connected graph. Then this will be a subgraph of the original graph, and will thus be a spanning tree. \Box