

# Markov Chains

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This article constitutes my notes for the ‘Markov Chains’ course, held in Michaelmas 2021 at Cambridge. These notes are *not a transcription of the lectures*, and differ significantly in quite a few areas. Still, all lectured material should be covered.

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### 1 Introduction

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## §1 Introduction

For this whole course,  $I$  will be a finite or countable set. All of our random variables will also be defined on the same probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .

### Definition 1.1 (Markov Chain)

A **stochastic process**  $(X_n)_{n \geq 0}$  is called a **Markov chain** if for all  $n \geq 0$  and all  $x_0, \dots, x_{n+1} \in I$ , we have<sup>a</sup>

$$\mathbb{P}(X_{n+1} = x_{n+1} \mid X_n = x_n, \dots, X_0 = x_0) = \mathbb{P}(X_{n+1} = x_{n+1} \mid X_n = x_n).$$

<sup>a</sup>We assume here that we are not conditioning on a zero probability event.

**Remark.** This definition gives a *discrete time* Markov chain. It is possible to define a continuous time Markov chain, but we won’t worry about that for now.

If  $\mathbb{P}(X_{n+1} = y \mid X_n = x)$  for all  $x, y \in I$  is independent of  $n$ , then  $X$  is called **time-homogeneous**. Otherwise, it is **time-inhomogeneous**. In this course, we will only study time-homogeneous Markov chains.

We will write  $P(x, y) = \mathbb{P}(X_1 = y \mid X_0 = x)$ , where  $x, y \in I$ . We call  $P$  a **stochastic matrix**, because

$$\sum_{y \in I} P(x, y) = 1,$$

that is, the sum of each row is 1.

**Remark.** The index set does not have to be  $\mathbb{N}$ , it could be say  $\{0, 1, \dots, N\}$  for  $N \in \mathbb{N}$ .

So to characterize a Markov chain, we need this matrix  $P$ , giving the probability of passing from a state  $x$  to a state  $y$ . We call this matrix the **transition matrix** of  $X$ .

**Definition 1.2 (Markov)**

We say that  $X$  is **Markov**( $\lambda, P$ ) if  $X_0$  has distribution  $\lambda$  and  $P$  is the transition matrix. That is,

- (i)  $\mathbb{P}(X_0 = x_0) = \lambda_{x_0}, x_0 \in I,$
- (ii)  $\mathbb{P}(X_{n+1} = x_{n+1} \mid X_n = x_n, \dots, X_0 = x_0) = P(x_n, x_{n+1}) = P_{x_n x_{n+1}}.$

We usually represent a Markov chain by its diagram corresponding to the allowed transitions.

**Example 1.3 (Diagram of a Markov Chain)**

Let  $\alpha, \beta \in (0, 1)$ . We consider the matrix

$$P = \begin{pmatrix} \alpha & 1 - \alpha \\ 1 - \beta & \beta \end{pmatrix}.$$

This is a transition matrix on two states which we can call 1 and 2. Here  $\alpha$  is the probability of staying at 1, and  $1 - \alpha$  is the probability of moving from state 2 when at state 1.

A diagram of this is given below. This is a directed graph with the relevant probabilities labelling each edge.

**Example 1.4**

Suppose that we have the transition matrix

$$P = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ 1 & 0 & 0 \end{pmatrix}.$$

This is a transition matrix on three states and corresponds with the diagram

**Theorem 1.5**

The process  $X$  is **Markov**( $\lambda, P$ ) if and only if for all  $n \geq 0$  and all  $x_0, \dots, x_n \in I$  we have

$$\mathbb{P}(X_0 = x_0, \dots, X_n = x_n) = \lambda_{x_0} P(x_0, x_1) \cdots P(x_{n-1}, x_n).$$

*Proof.* First suppose that  $X$  is **Markov**( $\lambda, P$ ). Then

$$\begin{aligned} \mathbb{P}(X_n = x_n, \dots, X_0 = x_0) &= \mathbb{P}(X_n = x_n \mid X_{n-1} = x_{n-1}, \dots, X_0 = x_0) \\ &\quad \cdot \mathbb{P}(X_{n-1} = x_{n-1}, \dots, X_0 = x_0) \\ &= P(x_{n-1}, x_n) \cdot \mathbb{P}(X_{n-1} = x_{n-1}, \dots, X_0 = x_0) \\ &= P(x_0, x_1) \cdots P(x_{n-1}, x_n) \mathbb{P}(X_0 = x_0) \\ &= \lambda_{x_0} P(x_0, x_1) \cdots P(x_{n-1}, x_n), \end{aligned}$$

as required.

Now suppose that the property holds. Then  $n = 0$  gives  $\mathbb{P}(X_0 = x_0) = \lambda_{x_0}$ , so our base case holds. Then

$$\begin{aligned}\mathbb{P}(X_n = x_n \mid X_{n-1} = x_{n-1}, \dots, X_0 = x_0) &= \frac{\lambda_{x_0} P(x_0, x_1) \cdots P(x_{n-1}, x_n)}{\lambda_{x_0} P(x_0, x_1) \cdots P(x_{n-2}, x_{n-1})} \\ &= P(x_{n-1}, x_n)\end{aligned}$$

□

Now we are going to define some useful notation.

### Definition 1.6 ( $\delta_i$ -mass)

For  $i \in I$ , the  $\delta_i$ -mass of  $i$  is defined as  $\delta_{ij} = \mathbb{1}(i = j)$ .

Recall the notion of independence for random variables. Let  $X_1, \dots, X_n$  be discrete random variables. They are *independent* if for all  $x_1, \dots, x_n \in I$ , we have

$$\mathbb{P}(X_1 = x_1, \dots, X_n = x_n) = \prod_{i=1}^n \mathbb{P}(X_i = x_i).$$

We have a similar notion for sequences of random variables. We say a sequence  $(X_n)_{n \geq 0}$  is *independent* if for all  $i_1 < i_2 < \dots < i_k$  and all  $x_1, \dots, x_k$ ,

$$\mathbb{P}(X_{i_1} = x_1, \dots, X_{i_k} = x_k) = \prod_{j=1}^k \mathbb{P}(X_{i_j} = x_j).$$

If  $X = (X_n)_{n \geq 0}$  and  $Y = (Y_n)_{n \geq 0}$  are two sequences of random variables, they are independent if for all  $k, m$  and  $i_1 < \dots < i_k, j_1 < \dots < j_m$  we have

$$\begin{aligned}\mathbb{P}(X_{i_1} = x_1, \dots, X_{i_k} = x_k, Y_{j_1} = y_1, \dots, Y_{j_m} = y_m) \\ = \mathbb{P}(X_{i_1} = x_1, \dots, X_{i_k} = x_k) \cdot \mathbb{P}(Y_{j_1} = y_1, \dots, Y_{j_m} = y_m)\end{aligned}$$

### Theorem 1.7 (Simple Markov Property)

Suppose that  $X$  is Markov( $\lambda, P$ ). Fix  $m \in \mathbb{N}$  and  $i \in I$ . Conditional on  $X_m = i$ , the process  $(X_{m+n})_{n \geq 0}$  is Markov( $\delta_i, P$ ) and it is independent of  $X_0, \dots, X_m$ .

*Proof.* We need to show that

$$\mathbb{P}(X_m = x_0, \dots, X_{m+n} = x_n \mid X_m = i) = \delta_{ix_0} P(x_0, x_1) \cdots P(x_{n-1}, x_n).$$

(To be completed next lecture)

□

**Remark.** Informally, this theorem says ‘past and future are independent given the present’.