view_frames Result Recorded at time: 1500.605 Broadcaster: /amcl Average rate: 40.296 Hz Most recent transform: 1500.664 (-0.059 sec old) Buffer length: 3.375 sec odom Broadcaster: /gazebo Average rate: 10.303 Hz Most recent transform: 1500.576 (0.029 sec old) Buffer length: 3.300 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1500.605 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.306 Hz Average rate: 10.306 Hz Most recent transform: 0.000 (1500.605 sec old) Most recent transform: 0.000 (1500.605 sec old) Most recent transform: 0.000 (1500.605 sec old) Most recent transform: 1500.577 (0.028 sec old) Most recent transform: 1500.577 (0.028 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.299 sec Buffer length: 3.299 sec upper_chassis left_wheel hokuyo right_wheel camera