## Sistemas Distribuídos

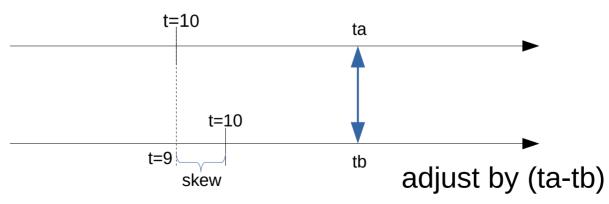
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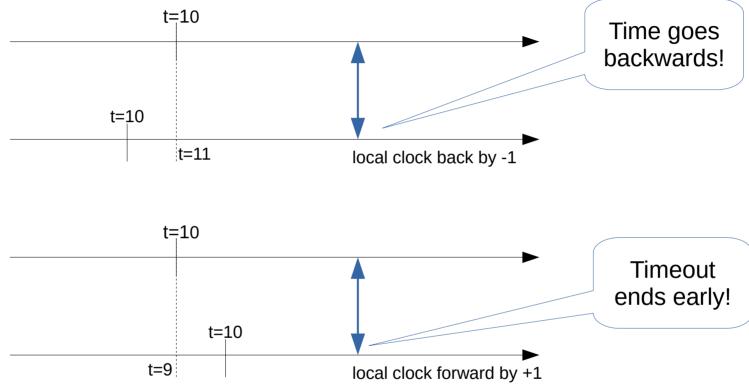
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- Hardware clocks are not perfect and drift over time
- Clock skew can be a problem with:
  - shared files
  - certain algorithms...

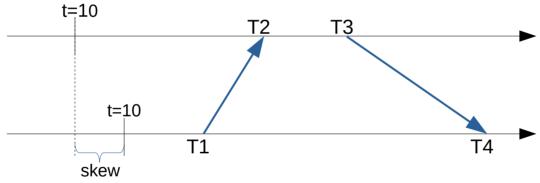
Ideally:





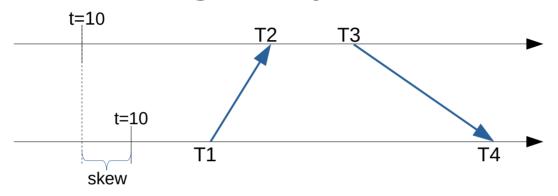
 The clock must be <u>adjusted in small increments</u>, over a longer period of time by making it faster or slower

- In practice, there are unpredictable
  - transmission delays
  - processing delays



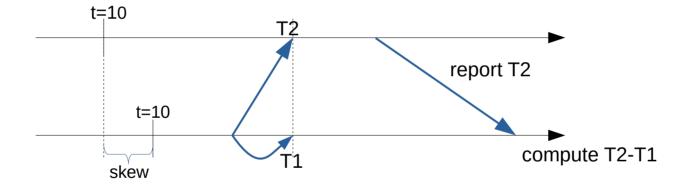
 The best we can do is adjust by (T2-T1) – (estimated message delay)

What is the message delay?



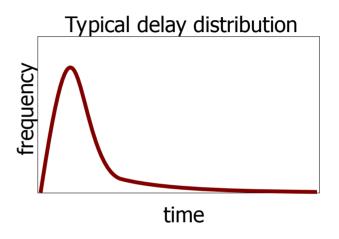
- Network Time Protocol (NTP):
  - assume delays are the same = ((T2-T1)+(T4-T3))/2
  - repeat several times and pick the smallest delay

- Reference Base Synchronization (RBS):
  - assume true broadcast medium (aprox. zero delay)



## **Timeouts**

- Used to assess status of remote processes
- Tight timeouts are dangerous:
  - E.g., proportional to mean delay
  - Means low coverage
- Large timeouts are not useful:
  - E.g., proportional to high percentile
  - Taking advantage of time causes a very large performance penalty



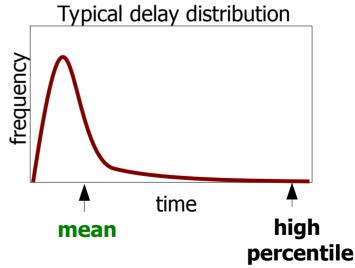
### **Timeouts**

- Solutions that do not use time are more robust:
  - In wide area networks
  - With performance perturbations
- Solutions that do not use time might have better

performance:

Run time proportional to mean delay

 Even if more message exchanges are necessary

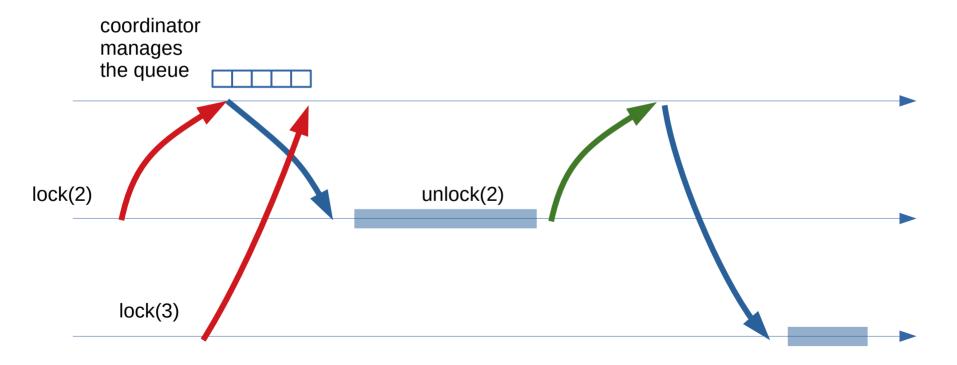


# Asynchronous system model

- Assume no global time reference
- Assume no bounds on:
  - clock drift
  - processing time
  - message passing time
- Can we still solve important problems?

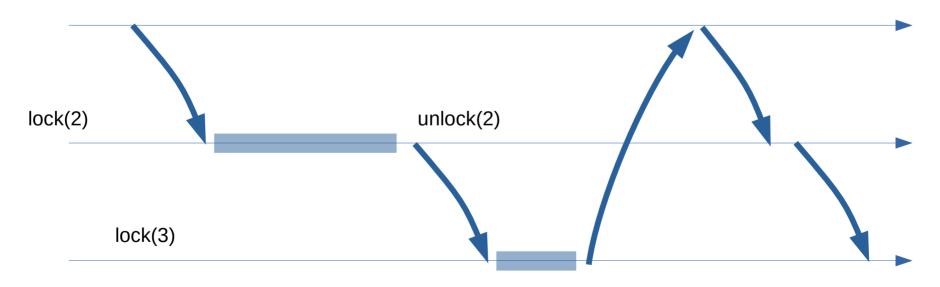
- Solution in a distributed system?
- Recall the definition of mutual exclusion:
  - No two threads in the critical section
  - No deadlock / no starvation
- We consider:
  - Number of message hops to entering critical section
  - Load balancing

- Centralized queue kept by a coordinator:
  - 1 round-trip to enter / asymmetric load

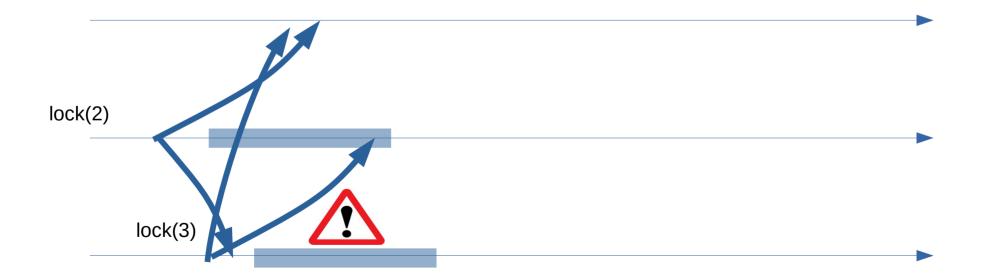


- Exchange a token in a ring:
  - n/2 hops to entering / symmetric load

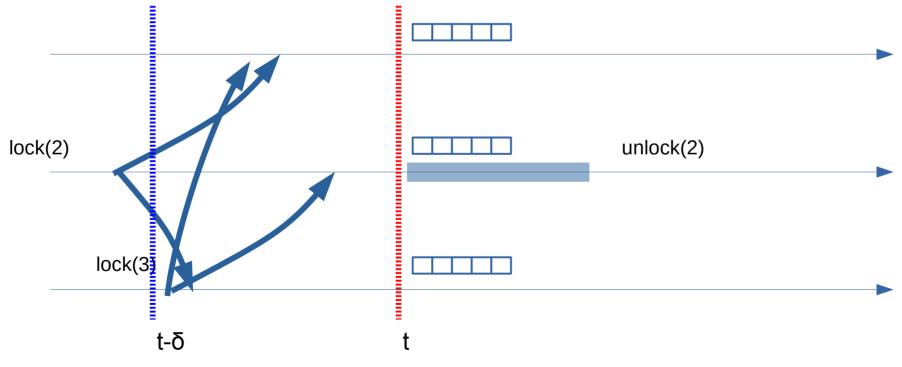
#### No explicit queue!



- A distributed algorithm is hard to achieve:
  - As concurrent lock requests are received by different destinations in different orders, safety is not ensured



- Taking advantage of synchronized clocks:
  - Assume  $\delta$  > (transmission delay + skew)
  - Consider only messages up to t- $\delta$ , order by timestamp



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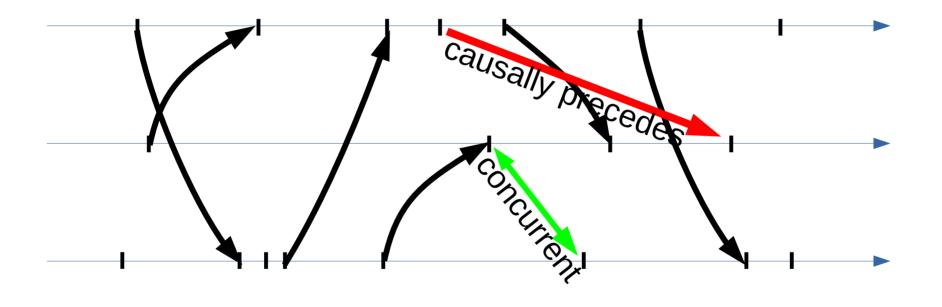
## Summary

- Mutual exclusion in a distributed system becomes easier as we don't have concurrency within each process
  - It will become harder again when we consider faults...
- Using clocks and time has a profound impact in the solution

## Time in distributed systems

 What is special about time that makes it useful for distributed algorithms?

# Causality

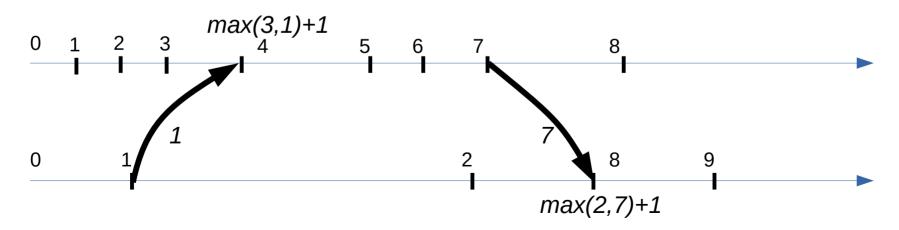


## Time and causality

- *Clock(i)* the time at which i happened
- If i precedes j then Clock(i)<Clock(j)</li>
- For some event j:
  - When we are sure that there is no unknown i such that Clock(i)<Clock(j)</li>
  - Then there is no i such that *i precedes j*
- Can we build a logical clock with the same property?

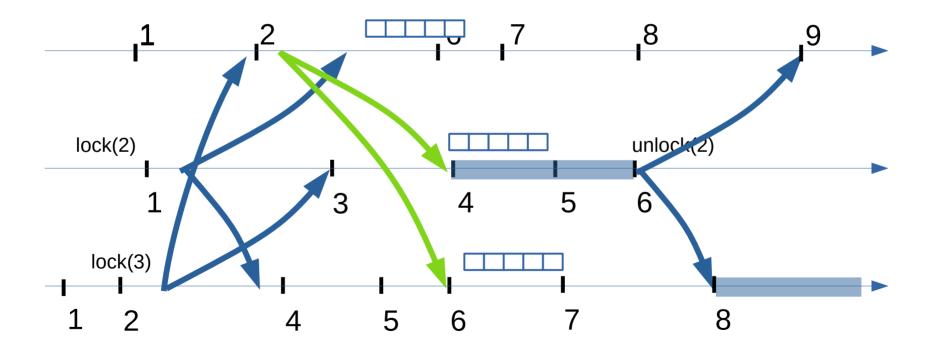
# Lamport's logical clocks

- Local events: increment counter
- Send events: increment and then tag with counter
- Receive events: update local counter to maximum and then increment



- Algorithm sketch:
  - Start by assuming that processes are continually exchanging messages...
  - ri[j] latest timestamp from j at i
  - Consider requests with t <= min(ri[j], for all j)</li>
    - (akin to t-δ!)
  - Order by timestamp, break ties by process id
- (The complete version is the Ricart-Agrawala distributed mutex algorithm)

• 1 hop to enter / symmetric load



# Logical time

- The same approach used for the waiting queue in the mutex can be used for other deterministic applications
  - Replicated State Machine (RSM)
- Logical time is widely applicable in distributed systems to solve many problems