An Introduction to Parallel Programming with the Message Passing Interface

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Boost.MPI library co-authored with Matthias Troyer





Parallel Programming

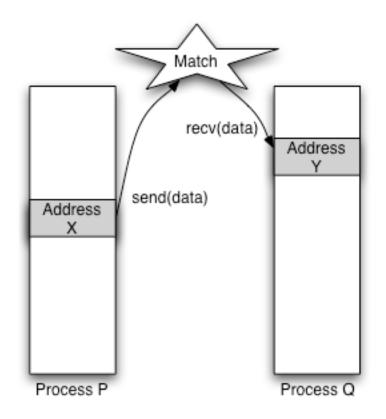
- Many parallel architectures
 - Shared memory/distributed memory/NUMA
 - SMP, multi-core, massively threaded
 - Desktops, clusters, supercomputer
- Many paradigms for parallel programming
 - Task-parallel
 - Data-parallel
 - Message passing





Communicating: Cooperative Operations

- Message-passing is an approach that makes the exchange of data cooperative
- Data must both be explicitly sent and received
- Any change in the receiver's memory is made with the receiver's participation







Message Passing Interface

- MPI is a standard interface for writing programs using message passing
 - Library interface: C, C++, Fortran, *Boost C*++
 - Tools for executing MPI programs
- MPI is widely implemented:
 - Commercial: Sun, Microsoft, Cray, IBM, etc.
 - Open-source: Open MPI, MPICH, etc.
- Focus on high-performance computing





MPI is not Sockets

- Similarities to sockets:
 - Distributed-memory with message passing
 - Widely supported, architecture-independent
- Major differences:
 - Single messages vs. data streams
 - Collective communication
 - SPMD-focused
 - Performance-minded (to a fault)





Boost.MPI vs. Standard C MPI

- C MPI is very low-level
 - void pointers, explicit datatypes, PODs only
- Boost.MPI is a Boostified MPI
 - Clean, generic C++ interfaces
 - Complete support for user-defined data types
 - Plays well with the Standard Library and Boost
 - Interoperates with C MPI





When To Use MPI?

- You need a portable parallel program:
 - Data size exceeds what one system can store
 - Data processing requirements exceed what one system can handle
- You are writing a parallel library
- You care about performance





Tutorial Outline

- MPI programs and communicators
 - Writing an MPI program
 - Launching an MPI program
- Collective communication I
- Point-to-point communication
- Transmitting your own data types
- Communicators and groups
- Collective communication II





Single Program, Multiple Data

- MPI programs are typically SPMD
 - Single MPI executable
 - Spawn that executable multiple times
 - All processes communicate via MPI

```
#include <boost/mpi.hpp>
#include <iostream>
namespace mpi = boost::mpi;
int main(int argc, char* argv[]) {
    mpi::environment env(argc, argv);
    mpi::intracommunicator world;
    std::cout < "I am process " < world.rank()
    < " of " << world.size() << " running on "
    < mpi::environment::processor_name() << "\n";
    return 0;
}</pre>
```





Hello, World!

```
#include <boost/mpi.hpp>
#include <iostream>
namespace mpi = boost::mpi;

int main(int argc, char* argv[]) {
   mpi::environment env(argc, argv);
   mpi::intracommunicator world;
   std::cout << "I am process " << world.rank()
        << " of " << world.size() << " running on "
        << mpi::environment::processor_name() << "\n";
   return 0;
}</pre>
```





Initializing the MPI environment

- □ Class boost::mpi::environment
 - Only one per program, allocated on the stack
 - Constructor initializes MPI communication
 - Destructor finalizes MPI

```
mpi::environment env(argc, argv);
```





MPI Communicators

- Communicators provide MPI's interprocess communication capabilities.
- world communicator connects all MPI processes.

```
mpi::intracommunicator world;
```

- Simple communicator queries:
 - size(): how many MPI processes?
 - rank(): which process number am !?





Building an MPI Program

```
#include <boost/mpi.hpp>
#include <iostream>
namespace mpi = boost::mpi;
int main(int argc, char* argv[]) {
 mpi::environment env(argc, argv);
 mpi::intracommunicator world;
 std::cout << "I am process " << world.rank()</pre>
   << " of " << world.size() << " running on "
   << mpi::environment::processor name() << "\n";
 return 0;
□ Compile with mpic++:
mpic++ -I$BOOST ROOT hello.cpp -lboost mpi-mt 1 35
```





Executing an MPI Program

mpiexec launches MPI jobs

```
mpiexec -np 8 ./hello
```

Output:

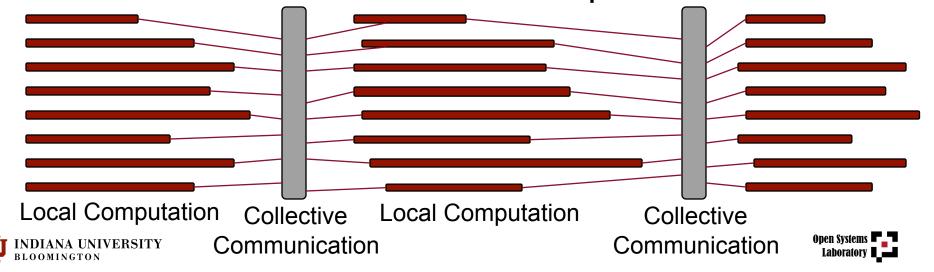
```
I am process 2 of 8 running on odin017.cs.indiana.edu
I am process 0 of 8 running on odin015.cs.indiana.edu
I am process 1 of 8 running on odin016.cs.indiana.edu
I am process 3 of 8 running on odin018.cs.indiana.edu
I am process 4 of 8 running on odin019.cs.indiana.edu
I am process 7 of 8 running on odin022.cs.indiana.edu
I am process 5 of 8 running on odin020.cs.indiana.edu
I am process 6 of 8 running on odin021.cs.indiana.edu
```





Collective Communication

- Collective communication involves all MPI processes
 - Processes each supply some data
 - Processes coordinate to compute the result
 - Results are sent back to the processes



Collectives I - Barrier

- Collective communication involves all processes in a communicator.
- barrier() waits for all processes to reach that barrier before exiting

```
// Everyone works on step #1
world.barrier();
// Everyone works on step #2
world.barrier();
// Everyone works on step #3
```





Collectives I – Broadcast

- Broadcast values from one process to every process.
 - The root provides the value
 - Every process receives the value





Broadcast Example

A simple command interpreter run in parallel:

```
while (true) {
   string command;
   if (world.rank() == 0)
      command = ReadUserInput();
   broadcast(world, command, 0);
   if (command == "quit")
      break;
   ExecuteCommand(command);
}
```





Collectives I – Gather

- Gathers data from all of the processes into a vector at a specified "root".
 - Everyone must provide the same communicator, root, and their own value
 - Only the root needs an output vector





Gather Example

Let's print all of the processor names in sorted order:





Gather Results

Output:

```
odin015.cs.indiana.edu odin016.cs.indiana.edu odin017.cs.indiana.edu odin018.cs.indiana.edu odin019.cs.indiana.edu odin020.cs.indiana.edu odin021.cs.indiana.edu odin021.cs.indiana.edu odin022.cs.indiana.edu
```





Collectives I – Scatter

Scatters values from the root to every process (the reverse of gather)





Scatter Example

Master process distributes tasks to each of the processes:

```
class Task { ... };

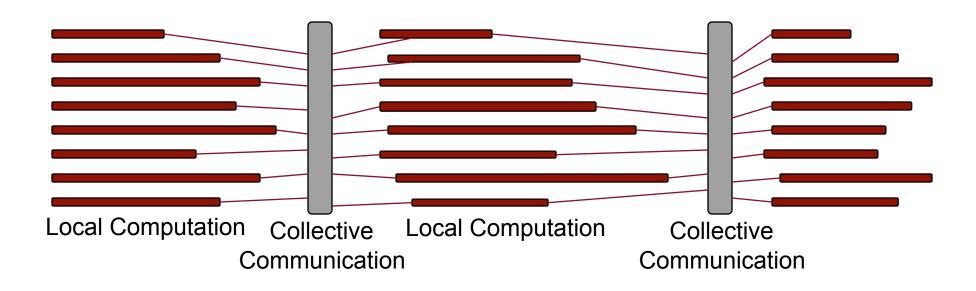
std::vector<Task> tasks;

if (world.rank() == 0)
    GenerateTasks(tasks); //tasks.size() == world.size()
Task myTask;
scatter(world,tasks, myTask, 0);
myTask.Execute();
```





Process Skew



Uneven computation time leads to wasted cycles, poor scalability.





Why Use Collective Comm?

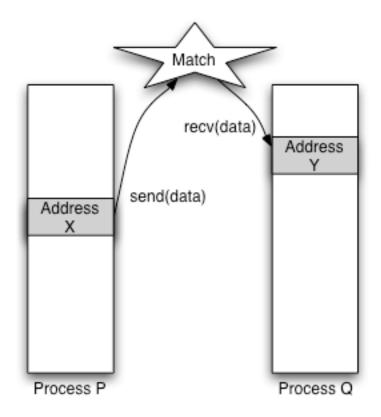
- □ For correctness:
 - Easy to globally exchange data correctly.
- For performance:
 - The right collective is often better implemented than the equivalent point-topoint operation.
 - Beware process skew!





Point-to-Point Communication

- Each process can send a single message to another process
- Message contains:
 - A communicator
 - A destination
 - A tag that identifies the message
 - Data (of any type)

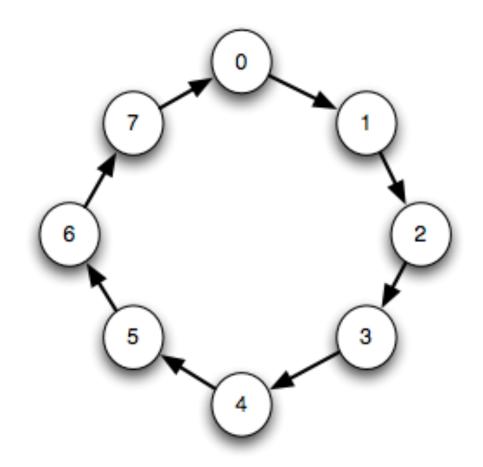






Example: Ring Communication

- Process 0 initiates a message
- Process 1 receives that message, forwards to process 2.
- Continue propagation until the message reaches 0.



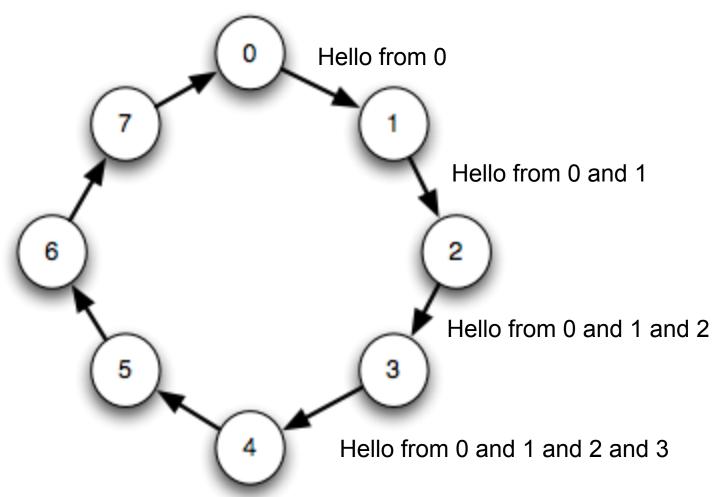




Example: Ring Communication

```
std::string msg;
if (world.rank() == 0) {
 msg = "Hello from 0";
 world.send(1, 0, msg);
 world.recv(world.size()-1, 0, msg);
  std::cout << msg << '\n';
} else {
 world.recv(world.rank()-1, 0, msg);
  std::cout << msg << '\n';
 msq += "and"
      + lexical cast<std::string>(world.rank());
 world.send((world.rank()+1) % world.size(), 0, msg);
                                                      Open Systems
INDIANA UNIVERSITY
```

Ring Communication Output







Wildcard Receives

- Receive operation matches a message based on source process and tag
- Wildcards match messages from any source process (mpi::any_source) with any tag (mpi::any tag).
- Example:

```
std::string msg;
world.recv(boost::mpi::any source, 0, msg);
```





Probing Unreceived Messages

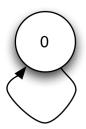
- Look for a message that can be received.
 - Match message on source/tag
 - status structure has:
 - source() and tag() of message
 - count<T>() with the number of T's in the message

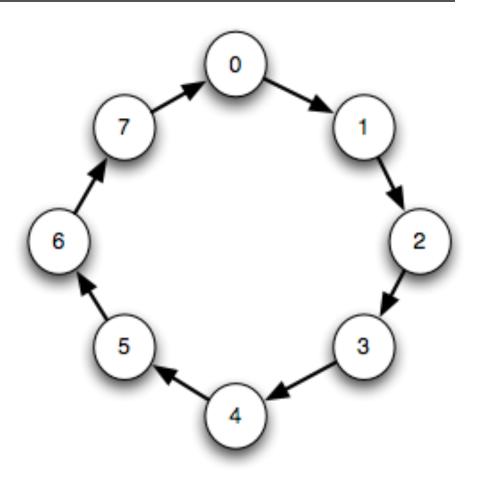




Revisiting the Ring

- Our ring program works with > 1 processes.
- What happens with just one process?



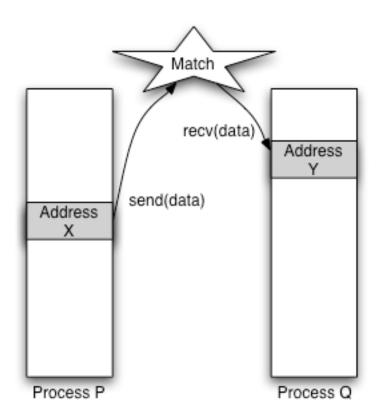






Deadlock!

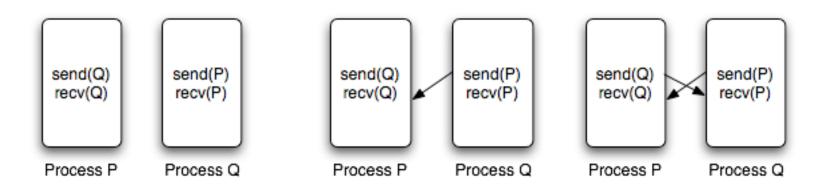
```
std::string msg;
if (world.rank() == 0) {
  msg = "Hello from 0";
  world.send(0, 0, msg);
  world.recv(0, 0, msg);
}
```







Deadlock Situations



- Sends can block until matching receive is found:
 - Buffering in MPI might hide these problems.
 - Many MPI implementations detect them.





Non-Blocking Communication

- Separates the initiation of a communication operation from its completion
 - "i" prefix indicates a non-blocking operation
 - Non-blocking operations return a request object
 - request object used to complete the communication





Safe Send-to-Self Operation

```
std::string msg;
if (world.rank() == 0) {
   std::string out_msg = "Hello from 0";
   std::vector<mpi::request> requests;
   requests.push_back(world.isend(0, 0, out_msg));
   requests.push_back(world.irecv(0, 0, msg));
   mpi::wait_all(requests.begin(), requests.end());
}
```





Non-Blocking Requests

One request per communication:

```
class request {
public:
    status wait();
    optional<status> test();
    void cancel();
};
```





Completing Multiple Requests

Wait until all requests have completed, output status objects.





Completing Multiple Requests

Wait until any request has completed, and return it.





Testing Multiple Requests

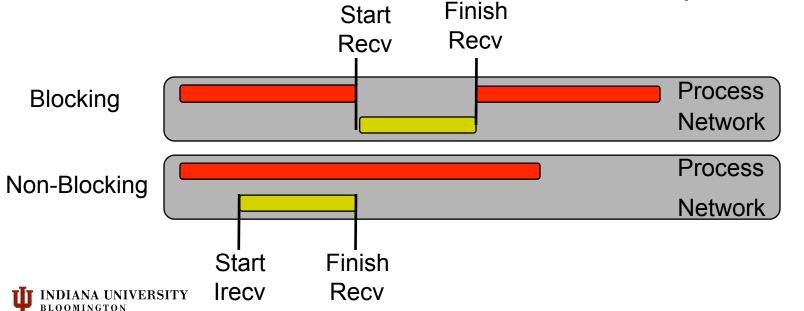
Determine whether any request has completd; if so, return it.





Non-Blocking Performance

- Try to maximize communicationcomputation overlap:
 - Start communication as early as possible
 - Finish communication as late as possible





Why Use Non-Blocking Comm?

- □ For correctness:
 - Good for deadlock avoidance.
- For performance:
 - Communication-computation overlap.
 - Remove synchronization between processes.





Working with Types

Boost.MPI can transmit any serializable type

```
struct Point {
  float x, y, z;
  template<typename Archiver>
    void serialize(Archiver& ar, unsigned version) {
        ar & x & y & z;
    }
};
Point p = {3.14f, 2.71f, 0.0f};
comm.send(1, 0, p);
```





A Peek Under the Hood

- Boost.MPI uses Boost.Serialization with custom archivers
 - mpi::packed_oarchive serializes data in MPI's transmission format (MPI Pack)
 - mpi::packed_iarchive de-serializes
 data (MPI_Unpack)
- Allows interoperability with MPI programs written without Boost.MPI





Some Types Are More Equal Than Others

- Serialization is the lowest common denominator
 - Unnecessary serialization → poor performance
- Boost.MPI can bypass serialization for some types:
 - Primitive types will be transmitted fast
 - POD classes can bypass serialization





Transmitting Points, Fast

```
struct Point {
  float x, y, z;
  template<typename Archiver>
    void serialize(Archiver& ar, unsigned version) {
       ar & x & y & z;
    }
};
```

Enabling the optimization:

```
namespace boost { namespace mpi {
  template<>
    struct is_mpi_datatype<Point> : mpl::true_ { };
} }
```





Back Under the Hood

- MPI derived datatypes describe C structs for direct transmission
- Boost.MPI builds derived datatypes via Boost.Serialization
 - mpi_datatype_oarchive records offsets
 and types of struct members for MPI





Communicators and Groups

- Each communicator is a separate communication space
 - Distinct tags/messages from other communicators
 - Provides communication for an arbitrary subset of the MPI processes
 - Great for parallel libraries!





Cloning Communicators

Build a new communicator with the same processes as the old communicator:

```
communicator comm(world, comm.group());
```

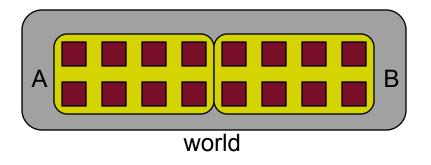
Typically used by libraries to separate their communication from users.





Splitting Into Subgroups

- Split the world into two subgroups, each with its own communicator:
 - Group A: First half of processes
 - Group B: Second half of processes









Rank Translation

- □ Each communicator C has ranks numbered 0..C.size()-1.
 - Due to subgroups, a process may have different ranks in different communicators
- Rank translation:

```
std::vector<int> subRanks, worldRanks;
for (int p = 0; p < subcomm.size(); ++p)
  subRanks.push_back(p);
subcomm.group().translate_ranks(subRanks.begin(),
  subRanks.end(), world.group(),
  std::back_inserter(worldRanks));</pre>
```





Advanced Group Manipulation

- communicator::group provides more
 advanced manipulation of groups
- Group operations:
 - operator&: intersection
 - operator|:union
 - operator-: difference
 - include/exclude specific ranks





When To Use (Sub)groups?

- In a library, clone the communicator to get your own communication space.
- If you are dividing your tasks into pieces that each cover several processes, use a communicator for each subgroup.





Collectives II – Reduce

- Reduce combines the values provided by each processor into a single value
 - out = op(in₀, op(in₁, op(in₂, ...)...)
 - op must be an associative binary operation





Reduction Example

Compute the global sum from local sums:

■ We could have written:

```
std::vector<int> sums;
gather(world, localSum, sums, 0);
if (world.rank() == 0) {
  globalSum = accumulate(sums.begin(), sums.end());
}
```





Collectives II – Allreduce

Allreduce is a reduce that broadcasts the result to all processes.





Global Common Prefix

- Task: compute the longest prefix common to the strings stored in each process
- Example:
 - Process 0 has: "foot"
 - Process 1 has "foolish"
 - Process 2 has "foobar"
 - Result: "foo"





Example: Global Common Prefix

```
string
common prefix(const string& s1, const string& s2) {
  if (s1.size() <= s2.size())
    return string(sl.begin(),
                  mismatch(s1.begin(), s1.end(),
                           s2.begin()).first);
  else return common prefix(s2, s1);
string global common prefix
  = all reduce(comm, my_string, &common_prefix);
```





Collectives II - Scan

- Scan is a parallel prefix operation.
 - Process p receives the result of reducing values in₀..in_i
 - Typically used to compute partial sums (like the partial_sum algorithm)





Implementation of Collectives

- Boost.MPI re-implements all of the MPI collectives for serialized data types
- Pro: Provides greatly improved functionality over existing MPI collectives
- Con: MPI implementers have spent years optimizing their collectives.
 - We'll never be that fast.





Specialized Collectives

- 1. C MPI collective with predefined MPI Op
- C MPI collective with new MPI_Op, created implicitly with MPI_Op_create.
- 3. Boost.MPI implementation (commutative)
- 4. Boost.MPI implementation (associative only)

Predefined 1, 2 2 3, 4

Function Object Commutative 2 2 4





Point-to-Point vs. Collectives

- Use collectives when:
 - A collective matches the needs of your application
 - Your tasks are relatively well-balanced
- Use point-to-point messages when:
 - No collective matches your communication
 - Non-blocking communication can improve performance





Static Structure, Dynamic Data

- Many problems iteratively compute values on a static data structure
 - Example: Finite Element Analysis
- Characteristics:
 - Distributed data structure is static
 - Boundary values in the data structure exchanged in each iteration
- □ Values are non-contiguous, but serialization is too inefficient.



thermoanalytics.com





Separating the Meat from the Bones

- Boost.MPI provides abstractions for these problems:
 - skeleton: transmit "shape" of data once
 - content: transmit contents of data many times, efficiently



Gaspar Becerra, ca. 1520-1570 Royal Academy of Arts Collection





Skeleton/Content Example

Computation:

```
mesh2d<cell> m;
// load the mesh with data
comm.send(1,0,skeleton(m));
while(!done ) {
   // update local cells...
   // broadcast changes
   comm.send(1,1,
      get_content(m));
}
```

Rendering:

```
mesh2d<cell> m;
// receive the structure
// of the mesh
comm.recv(0,0,skeleton(m));
while (!done) {
  comm.recv(0,1,
    get_content(m));
  // display updated m
}
```





Summary & Recap

- MPI is designed for high-performance parallel applications
 - Desktop → Cluster → Supercomputer
- Major themes:
 - Communicators for cooperating among processes on the same task
 - Collectives to summarize/move data
 - Point-to-point for fine-grained communication





A Simple Task





Transmits Multiple Messages





Needs Explicit Serialization





Uses Unsafe Type Casts





Redundant Information





Point-to-Point in Boost.MPI

```
std::list<std::list<int> > ls;
comm.send(dest, tag, ls);
```

- □ Simple, obvious interface:
 - Treats user-defined, library-defined and built-in types uniformly
 - Eliminates need for redundancies and type casting
 - Retain same names, semantics as C MPI





MPI Features

- Point-to-point communication
 - Structured buffers and derived datatypes, heterogeneity
 - Modes: normal (blocking and non-blocking), synchronous, ready, buffered
- Collective
 - Both built-in and user-defined collective operations
 - Large number of data movement routines
 - Subgroups defined directly or by topology





MPI Features (cont'd)

- Dynamic process control
 - Allows creation and cooperative termination of processes after an MPI application has started.
 - Mechanism to establish communication between existing MPI applications.
- One-sided operations
 - Remote Memory Access (RMA) communication mechanisms
 - Communication: Put (remote write), Get (remote read) and Accumulate (remote update)
 - Support for both active and passive target synchronization.





MPI Features (cont'd)

- Parallel I/O
 - Portable interface for optimized parallel file access
 - Support for synchronous and asynchronous I/O
 - Allows for close coupling with parallel filesystems
 - Data partitioning expressed using derived datatypes.





MPI Features (cont'd)

- Application-oriented process topologies
 - Built-in support for grids and graphs (based on groups)
- Profiling
 - Hooks allow users to intercept MPI calls to install their own tools
- Environmental
 - Inquiry
 - Error control



