

# The Dataflow Library and the Arts

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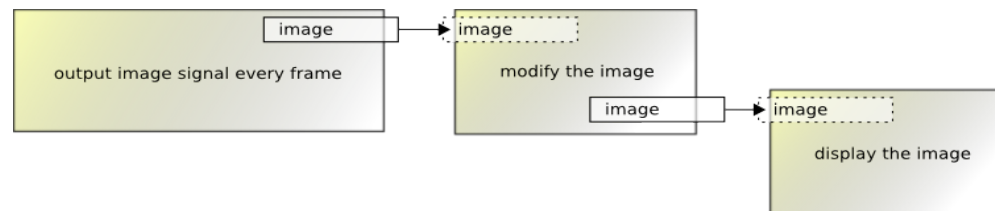
M.F.A. student, Dance

# Presentation Outline

- The Dataflow library
  - Motivation
  - Overview
  - Future Directions
- The Arts
  - Art based interactive installations
  - AMELiA and a pattern recognition library developed with the interactive installations
  - Rehearsal Assistant – a media tool for performing arts

# Dataflow

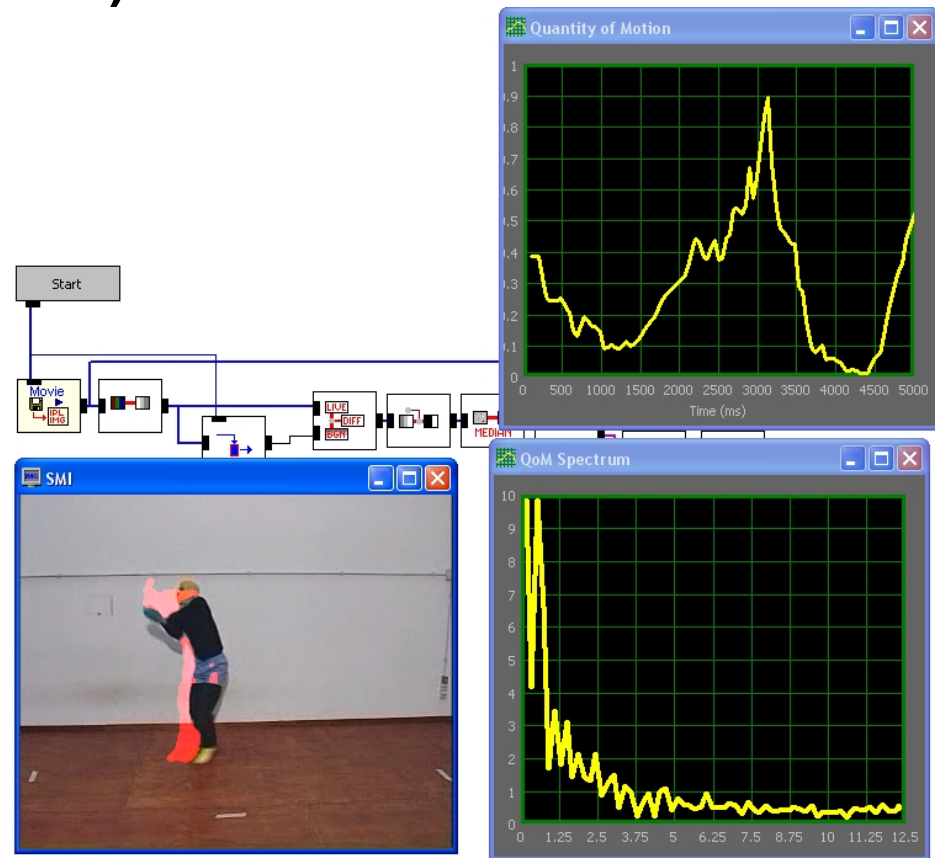
- models a program as a directed graph of the data flowing between operations (wikipedia)
- Example:



- My interest comes from experience with various visual programming environments

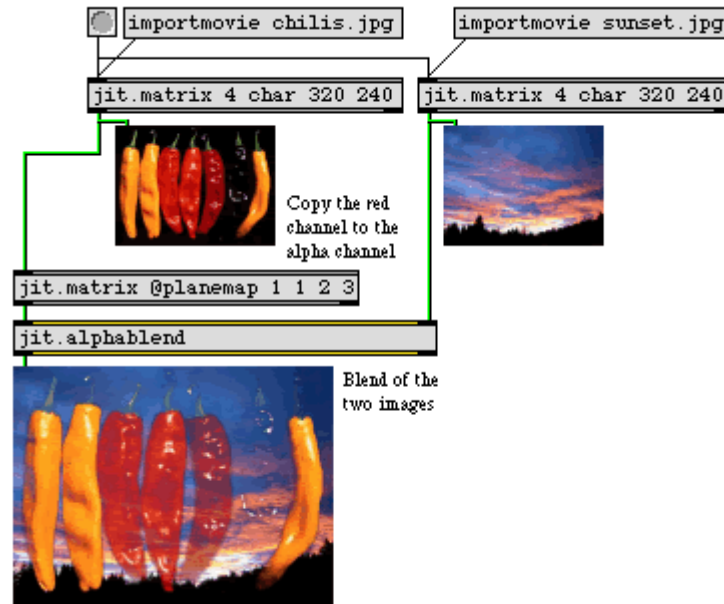
# Visual Dataflow Environments

- EyesWeb (real-time multimodal distributed interactive applications)



# Visual Dataflow Environments

- Max / MSP (interactive graphical programming environment for music, audio, and media)



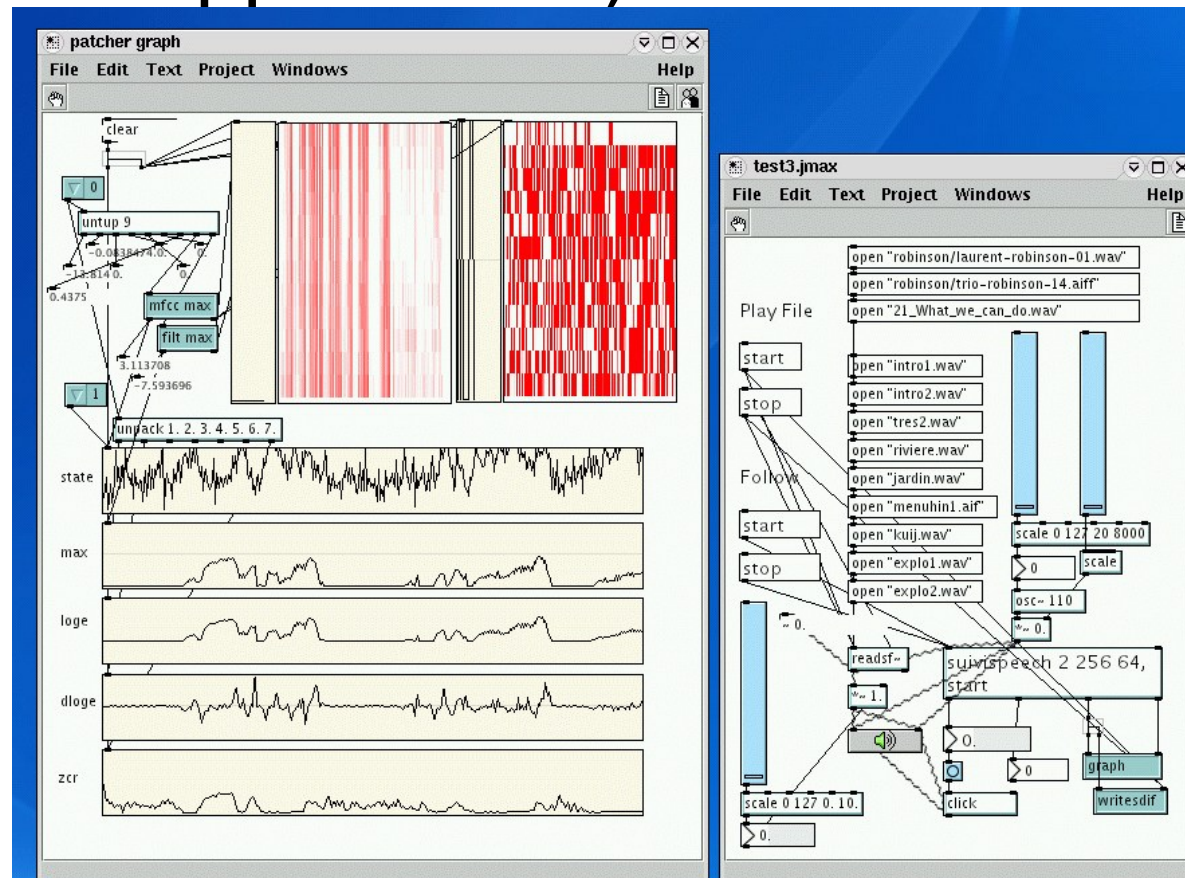
# Visual Dataflow Environments

- Pure Data (creation of interactive computer music and multimedia works)



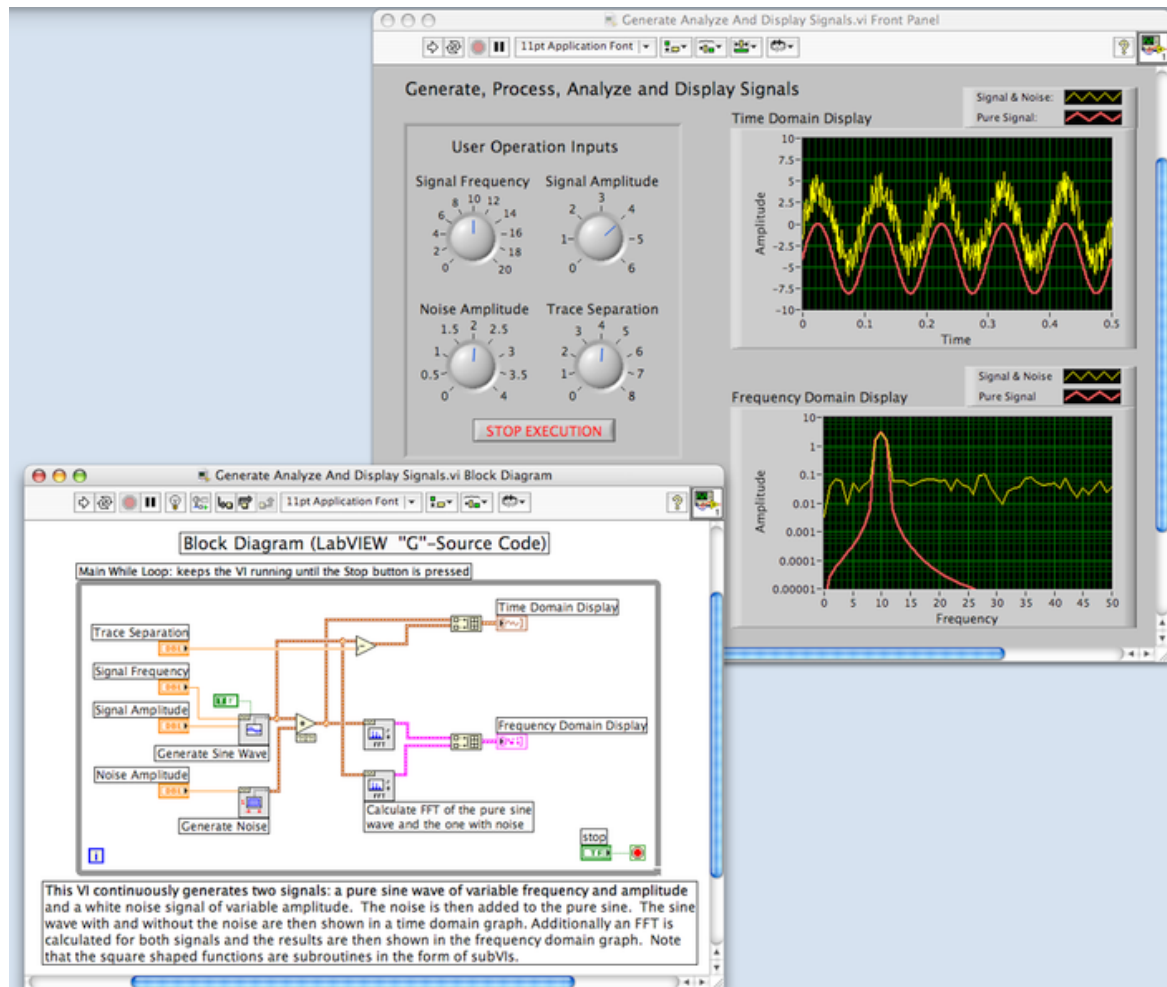
# Visual Dataflow Environments

- jMax (building interactive real-time music and multimedia applications)



# Visual Dataflow Environments

- LabVIEW (commonly used for data acquisition, instrument control, and industrial automation)





# Advantages of dataflow programming

- not exclusive of other paradigms
- promotes some good programming practices
- makes development and maintenance very intuitive
- can be divided between threads, processors, or computers more easily
- lends itself well to visual programming environments

# The Dataflow library

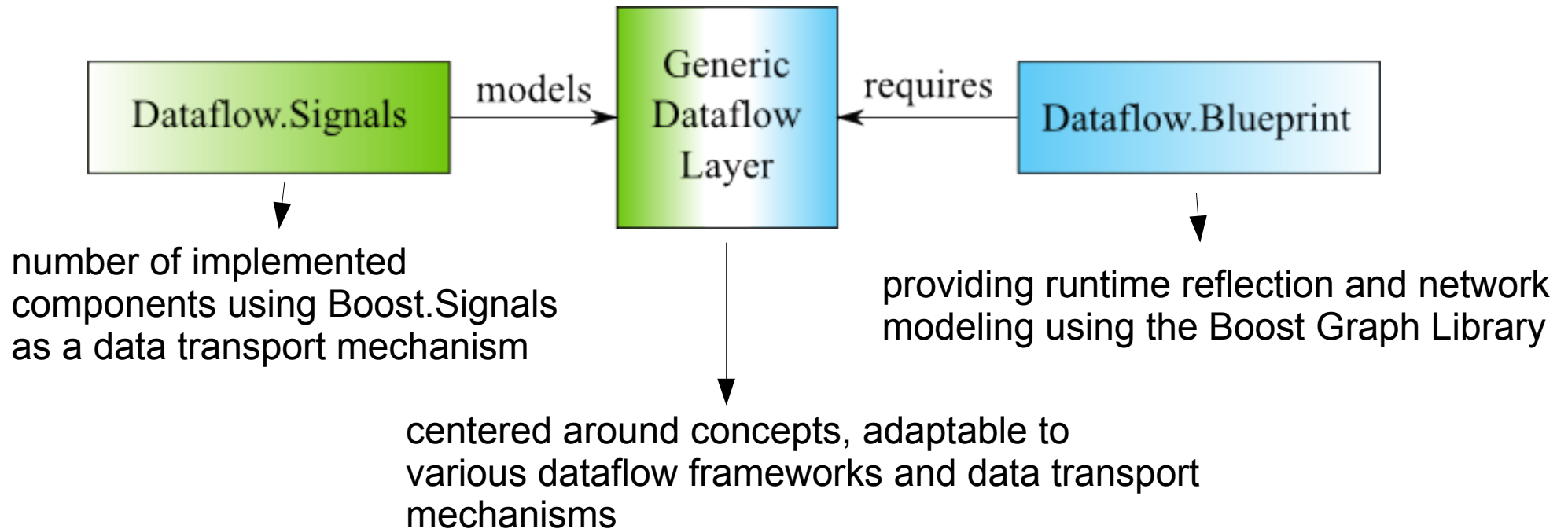
Original intention: let's make another dataflow framework using Boost.Signals

Google Summer of Code (thanks Google, thanks Boost!)



Let's make a generic dataflow library

# Dataflow library overview



- Fundamental concepts:
  - Port
  - Component

# Dataflow.Signals

- Uses function calls to transport data with connections stored using Boost.Signals
- Offers
  - A number of useful general-purpose components, and building blocks for implementing new components.
  - Various free functions and operators for connecting and using components.

# Dataflow.Signals example 1

```
#include <boost/dataflow/signals/support.hpp>
#include <iostream>
#include <string>

void consumer_function(const std::string &data)
{
    std::cout << data << std::endl;
}

void signal_function_example()
{
    boost::signal<void(const std::string &)> producer;
    boost::function<void(const std::string &)> consumer(consumer_function);

    connect(producer, consumer); // make a connection between the two.
    producer("Hello World"); // signal goes to the function.
}
```

# Dataflow.Signals example 2

```
#include <boost/dataflow/utility/bind_mem_fn.hpp>

class consumer_class
{
public:
    void consumer_mem_fn(const std::string &data)
    {
        std::cout << data << std::endl;
    }
};

void signal_mem_fn_example()
{
    using boost::dataflow::utility::bind_mem_fn;

    boost::signal<void(const std::string &)> producer;
    consumer_class consumer;

    // make a connection between the producer and consumer.
    connect(producer, bind_mem_fn(&consumer_class::consumer_mem_fn, consumer));
    producer("Hello World"); // signal goes to the member function.
}
```

# Dataflow.Signals example 3

```
class producer_component
    : public signals::filter<producer_component, void(const std::string &)>
{
public:
    void invoke()
    {
        // out is the default output signal.
        out("Hello World");
    }
};

class consumer_component
    : public signals::consumer<consumer_component>
{
public:
    // This is our signal consumer.
    void operator()(const std::string &data)
    {
        std::cout << data << std::endl;
    }
};

void component_component_example()
{
    producer_component producer;
    consumer_component consumer;

    // Because we inherited from filter/consumer, connecting is easy.
    connect(producer, consumer);
    producer.invoke(); // producer sends "Hello World" to consumer.
};
```

# Dataflow.Signals example 4

```
#include <boost/dataflow/signals/connection/operators.hpp>

class filter_component
    : public signals::filter<filter_component, void(const std::string &)>
{
public:
    // This is our signal consumer. It will also produce a signal when called.
    void operator()(const std::string &data)
    {
        out(data + "!");
    }
};

void component_component_component_example()
{
    producer_component producer;
    filter_component filter;
    consumer_component consumer;

    // The following is equivalent to:
    // connect(producer, filter);
    // connect(filter, consumer);
    producer >>= filter >>= consumer;
    // producer sends "Hello World" to filter, filter sends "Hello World!".
    producer.invoke();
}
```



# Dataflow.Signals example 5

```
// instantiate all of the components we need
signals::storage<void ()> banger;
signals::storage<void (float)> floater(2.5f);
signals::storage<void (float)> collector(0.0f);

// ---Connect the dataflow network -----
//
// ,----- . void()
// | banger | -----
// `-----' |
//             |
//             v
//             ,-(send_slot)-. void(float) ,-----
//             | floater | -----> | collector |
//             `-----' `-----'
//
// -----

banger >>= floater.send_slot();
floater >>= collector;

// signal from banger is will invoke floater.send(), which causes
// floater to output 2.5
banger();
BOOST_CHECK_EQUAL(floater.at<0>(), 2.5f);
BOOST_CHECK_EQUAL(collector.at<0>(), 2.5f);

floater.close();
floater(1.5f); // change the value in floater
invoke(floater); // we can also signal floater directly
BOOST_CHECK_EQUAL(collector.at<0>(), 1.5f);
```

# More examples with library

- Implementing distributed dataflow applications using Dataflow.Signals and Boost.Asio

```
// ---Connect the dataflow network on one computer-----  
//  
//  
//      '-----'.  
//      |  input  | --> |  sender  | --- -- - (socket)  
//      '-----'  
//  
// -----  
  
// ---Connect the dataflow network on other computer -----  
//  
//  
//      '-----'.  
// (socket) - -- --- | receiver | --> |  proc  | --> |  out  |  
//      '-----'  
//  
// -----
```

# More examples with library

- An image processing network using Dataflow.Signals and Boost.GIL

```
// ---Connect the dataflow network -----
//
//
//          ,-----,
//          | control | -----+
//          `-----'          |
//          |            |          |
//          v            v          |
//
// ,-----, ,-----, ,-----,
// | timer | --> | generator | --+-----> 0 | ,-----,
// `-----' `-----' |            | | mux | --> | display |
//                      |            | |      |
//                      +->| filter | --> 1 | `-----'
//                      `-----'
//
// -----
```

# More examples from the documentation

- Pull-based networks
- Disconnecting
- Multiple slots of different signatures
- Multiple inputs of the same signature
- Multiple outputs
- Implementing new components using filter and consumer classes

# Dataflow.Signals components

Component	Use
<a href="#"><u>consumer</u></a>	Base class for your own input-only components.
<a href="#"><u>filter</u></a>	Base class for your own input/output or output-only components.
<a href="#"><u>storage</u></a>	Stores signal arguments.
<a href="#"><u>counter</u></a>	Counts the number of signals passing through.
<a href="#"><u>junction</u></a>	Convenient when multiple producers need to be connected to the same set of consumers. Also has gate functionality.
<a href="#"><u>multiplexer</u></a>	Allows selection of which of the input ports is forwarded
<a href="#"><u>mutex</u></a>	Provides mutexing on incoming signals for multithreaded environments
<a href="#"><u>condition</u></a>	Signals a threading condition whenever a signal is received
<a href="#"><u>function</u></a>	Allows any Boost.Function object to be applied to a passing signal
<a href="#"><u>chain</u></a>	Chains a number of components together into a new component
<a href="#"><u>socket_sender</u></a> and <a href="#"><u>socket_receiver</u></a>	Allow a signal dataflow network to straddle a network socket

# Component Bases - instantiator

- Instantiator instantiates an object while a signal is passing
- Example – mutex instantiates a `scoped_lock` on a mutex:

```
template<typename Signature,  
        typename OutSignal=SIGNAL_NETWORK_DEFAULT_OUT,  
        typename SignalArgs=typename default_signal_args<Signature>::type  
>  
class mutex : public  
    instantiator<  
        mutex<Signature, OutSignal, SignalArgs>,  
        boost::mutex, boost::mutex::scoped_lock, Signature, OutSignal, SignalArgs>  
{  
};
```

# Component Bases - applicator

- Applicator applies a function object to a member whenever a signal passes
- Example – counter increments an int:

```
template<
    typename Signature,
    typename OutSignal=SIGNAL_NETWORK_DEFAULT_OUT,
    typename T=int,
    typename SignalArgs=typename default_signal_args<Signature>::type
>
class counter : public applicator<
    counter<Signature, OutSignal, T, SignalArgs>,
    T, detail::postincrement<T>, Signature, OutSignal, SignalArgs>
{
public:
    /** Initializes the internal counter to 0. */
    counter()
    {    reset(); }
    /** Sets the internal counter to 0.    */
    void reset()
    {    counter::member = 0; }
    /** \return The internal signal counter.    */
    T count() const
    {    return counter::member; }
};
```

# Component Bases - conditional

- Conditional only forwards a signal when a condition evaluates to true
- Example – junction forwards signal when open:

```
template<
    typename Signature,
    typename OutSignal=SIGNAL_NETWORK_DEFAULT_OUT,
    typename SignalArgs=typename default_signal_args<Signature>::type
>
class junction
    : public conditional<
        junction<Signature, OutSignal, SignalArgs>,
        volatile bool, detail::identity<bool>, Signature, OutSignal, SignalArgs>
    {
public:

    /** Initializes the junction to be enabled.      */
    junction(bool opened=true)
    {
        junction::member=opened;
    }

    /** Enables the junction (signals will be forwarded).      */
    void open() {junction::member = true;}
    /** Disables the junction (signals will not be forwarded).      */
    void close() {junction::member = false;}
};
```



# Generic Component Bases

- `modifier`
  - Can modify a passing signal (e.g., `signals::function`)
- `conditional_modifier`
  - Can modify a passing signal, it is passed on optionally (e.g., `signals::storage`)

# The Dataflow library

Generic Dataflow Layer

# Generic Dataflow Layer concepts

- Port
  - ComplementedPort
  - VectorPort
  - KeyedPort
- Component
- Operations
  - BinaryOperable (Connectable, Extractable...)
  - UnaryOperable (AllDisconnectable)
  - ComponentOperable (Invocable)

# Dataflow.Signals as an example

- Ports
  - `boost::signal` (call producer)
  - `boost::function` (call consumer)
  - Connectable if of the same signature
- Components
  - `signals::consumer` (base class)
  - `signals::filter` (base class)
  - ...

# How boost::signal becomes a ComplementedPort

- We declare a PortTraits type –  
boost::dataflow::signals::producer

```
template<typename T>
struct producer
    : public complemented_port_traits<ports::producer, boost::function<T>, tag>
{
    typedef T signature_type;
};
```

- We then register boost::signal with the PortTraits

```
template<typename Signature, typename Combiner, typename Group, typename GroupCompare>
struct register_traits<boost::signal<Signature, Combiner, Group, GroupCompare>, signals::tag >
{
    typedef signals::producer<Signature> type;
};
```

# How boost::function becomes a Port

- We declare a PortTraits type –  
boost::dataflow::signals::consumer

```
template<typename T>
struct consumer
    : public port_traits<ports::consumer, tag>
{
    typedef T signature_type;
};
```

- We then register boost::signal with the PortTraits

```
template<typename Signature>
struct register_traits<boost::function<Signature>, signals::tag >
{
    typedef signals::consumer<Signature> type;
};
```

# How they become Connectable

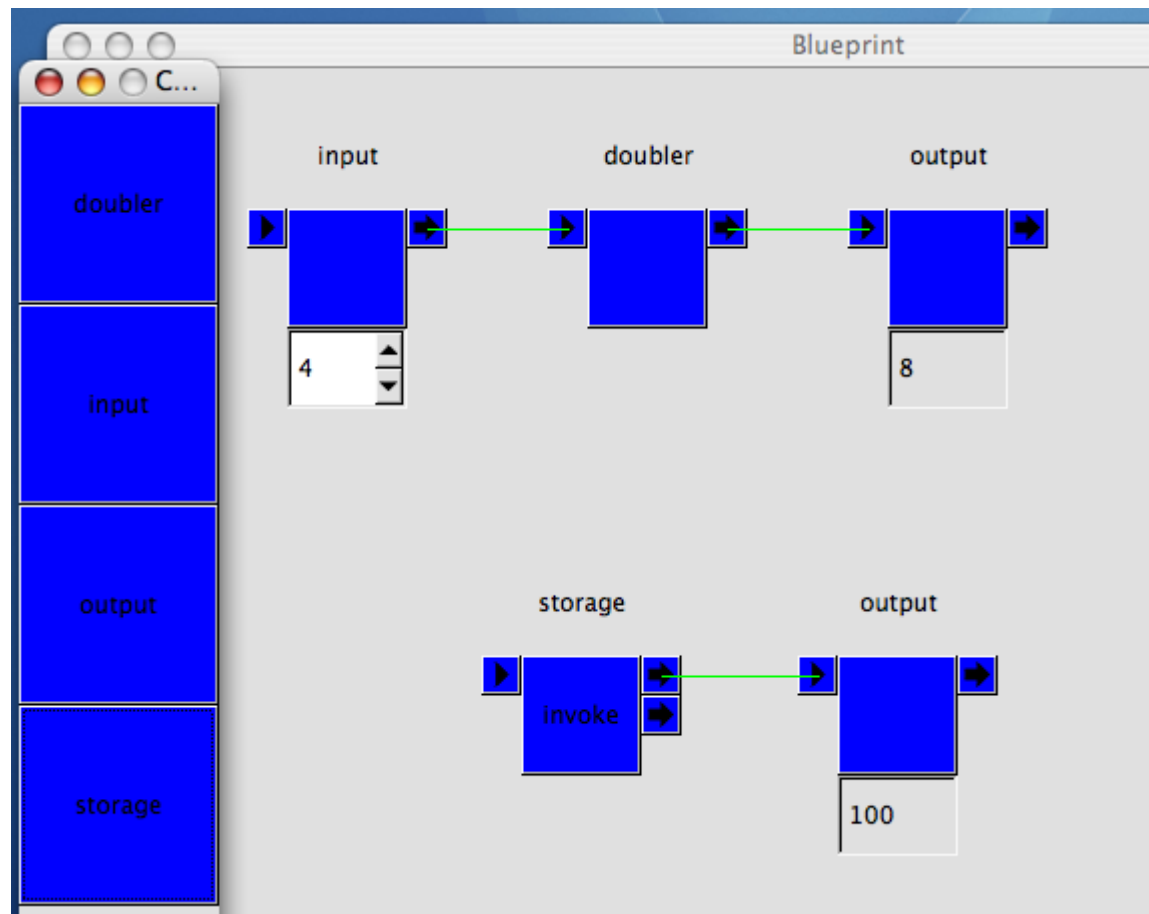
```
template<typename T>
struct binary_operation_impl<signals::producer<T>, signals::consumer<T>, operations::connect>
{
    typedef boost::signals::connection result_type;

    template<typename Producer, typename Consumer>
    result_type operator()(Producer &producer, Consumer &consumer)
    {
        return producer.connect(consumer);
    }
};
```

- They can now be treated in a generic fashion through the Dataflow library
- Other things offered at the generic level:
  - Disconnecting, Extracting, Invoking
  - Support for function objects as KeyedPorts

# What are the benefits of generic Dataflow?

- Generic algorithms / applications... like a visual programming environment!





# Dataflow.Blueprint

- Very much a work in progress
- Offers run-time reflection of components
- Offers run-time polymorphic classes with all Dataflow functionality (e.g., useful if components are loaded from a factory / bank / plugin)
- Stores the dataflow network blueprint in a BGL graph, which can then be analyzed
- ... see example in documentation

# Future Directions

- Expanding the blueprint layer
- Improving GUI based dataflow network construction
- Support for more layers
- Supporting a pin-based approach, as proposed by Tobias Schwinger

## No. 2: The Arts

# The Arts

- Art settings provide a lot of very interesting computational challenges
- Outline
  - Art based interactive installations
  - AMELiA – a pattern recognition library developed with the interactive installations
  - Rehearsal Assistant – a media tool for performing arts

# Art based interactive installations

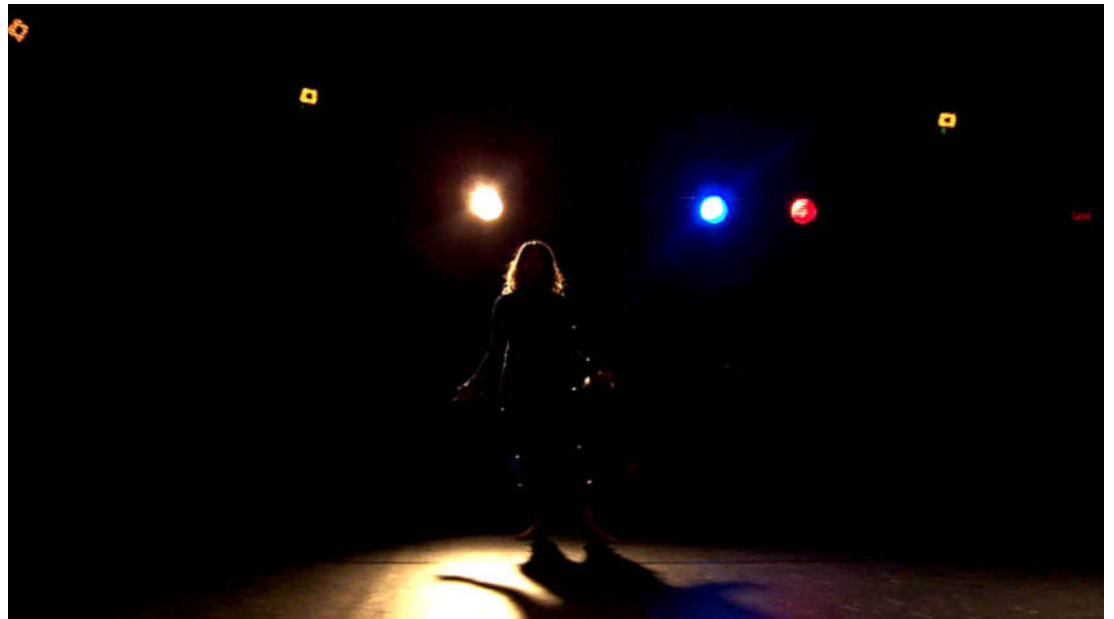
- Installation art uses sculptural materials and other media to modify the way a particular space is experienced (wikipedia)
- At Arts, Media and Engineering (AME), we construct environments that allow users to:
  - Explore their movement potential and creativity
  - Manipulate sound using movement
  - Learn concepts (physics, sustainability)
  - Communicate
  - Collaborate
- Art brings crucial knowledge to the construction

# Example 1: Handjabber

- Handjabber is an interactive audio installation that draws from understanding of how people use nonverbal language to communicate with each other.
- The installation takes advantage of motion capture technology and is meant for two people at a time.
- ... show video

# Example 2: The “Enactive” environment

- This environment analyzes certain spatial qualities of movement, and provides audio feedback reflecting the analysis
- The audio feedback can increase the user's awareness of their movement.
- ... show video



# Example 3: Biofeedback for stroke rehabilitation

- The environment provides a purposeful, engaging, visual and auditory scene in which patients can practice functional therapeutic reaching and grasping tasks, while receiving different types of simultaneous feedback indicating measures of both performance and results.
- ... show video





# Example 4: the SMALLab environment

- Interactivity using tangible objects
- Visual and audio feedback
- A modular design environment, many interactive scenarios
  - Mediated complexity / sustainability (experiential environments modeling complex problems)
  - Talking Circle (communication environment inspired by Native American traditions)
  - ...
- ... show video





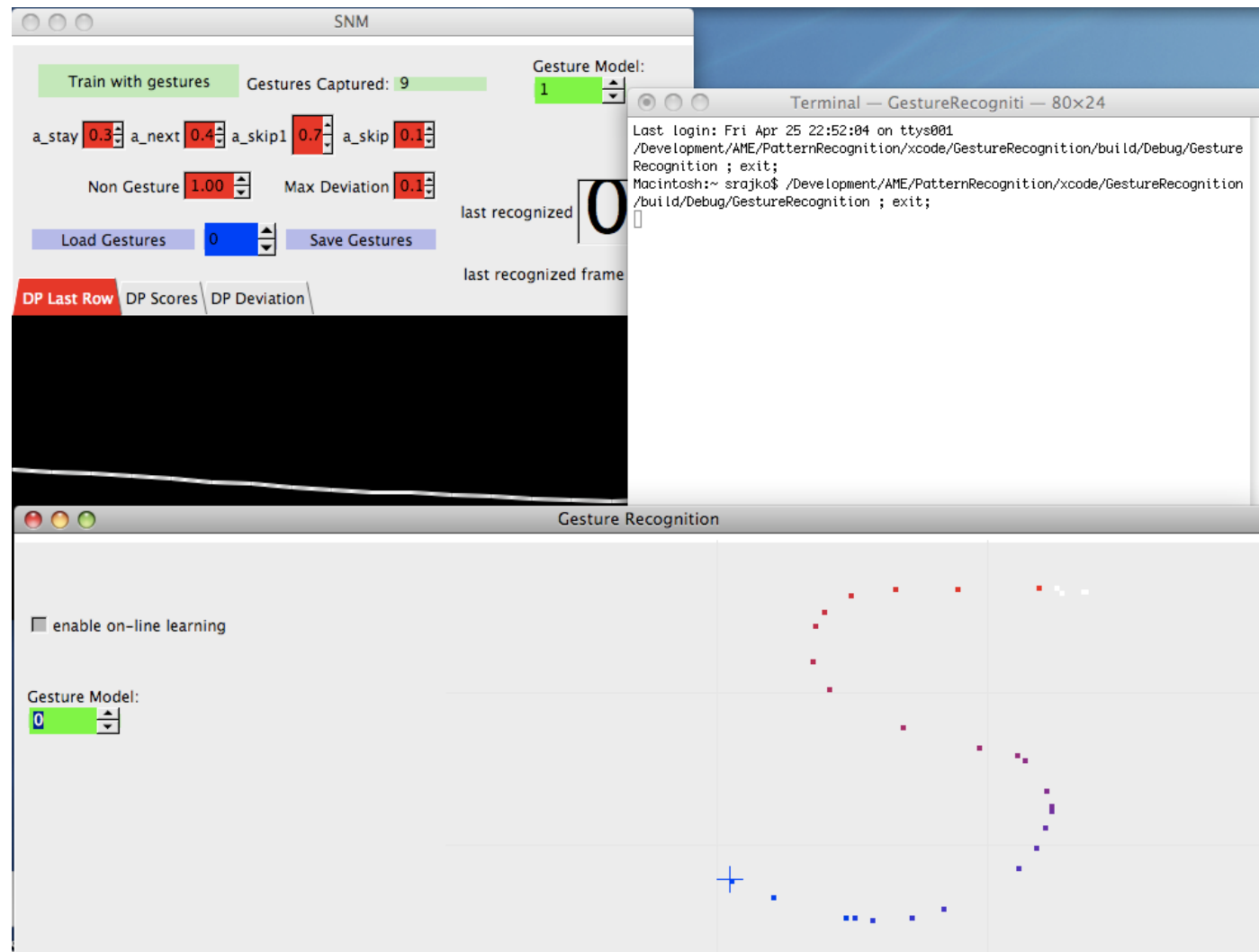
- AME recently allowed release of software under open source licenses
- Moving code from proprietary codebase to AMELiA (currently GPL-ed)
- First major library moved: A Patterns library
  - Hidden Markov model gesture recognition
  - Reduced parameter models for reduced training requirements / better run-time performance

# AME Patterns library

- a library for pattern analysis and recognition
- generic in the sense that it can be applied to patterns in different domains / modalities.
- to use the library in a particular domain, the library user simply needs to provide appropriate models of concepts used by the library.
- Currently focused on gesture recognition
  - Body gestures sensed using motion capture data
  - Gestures of tangible objects (e.g., ball) in space
  - Gestures of a mouse in a plane

# Mouse Gesture Recognition Example

- ... run example



# Using the Patterns library

- To recognize gestures, we need a ModelState:

```
class normal_model_state
{
public:
    typedef double observation_type;

    normal_model_state(double min_st_dev)
        : m_min_st_dev(min_st_dev)
    {}

    double operator()(double a)
    {
        return pdf(m_distribution, a);
    }

    template<typename Range>
    void train_with_examples(const Range &examples)
    {
        if (examples.size()==0)
            return;
        double mean=ame::range::mean(examples);
        double st_dev=ame::range::standard_deviation(examples, mean);

        m_distribution = boost::math::normal_distribution<>(mean, (std::max)(st_dev, m_min_st_dev));
    }
    const boost::math::normal_distribution<> distribution() const
    { return m_distribution; }

private:
    double m_min_st_dev;
    boost::math::normal_distribution<> m_distribution;
};
```

# We can now train gestures

- All it takes is one or more examples of each gesture

```
patterns::gesture_set_recognition<gesture_model_type> gsr(0.1, true);

using namespace boost::assign;

std::vector<std::vector<double> > training;

training.push_back(std::vector<double>());
training.back() += 1, 2, 3, 4, 5, 6;
gsr.add_gesture_with_examples(training, 0.2, 0.7, 0.1, 6, 10, 0, patterns::normal_model_state(1));

training.clear();
training.push_back(std::vector<double>());
training.back() += 6, 5, 4, 3, 2, 1;
gsr.add_gesture_with_examples(training, 0.2, 0.7, 0.1, 6, 10, 0, patterns::normal_model_state(1));
```

# ... and recognize gestures

- ... run example

```
double input;
for(;;)
{
    std::cout << "enter next observation (enter a negative number to quit): " << std::endl;
    std::cin >> input;
    if (input<0)
        break;

    std::cout << "matches gesture: " << gsr.match(input) << std::endl;

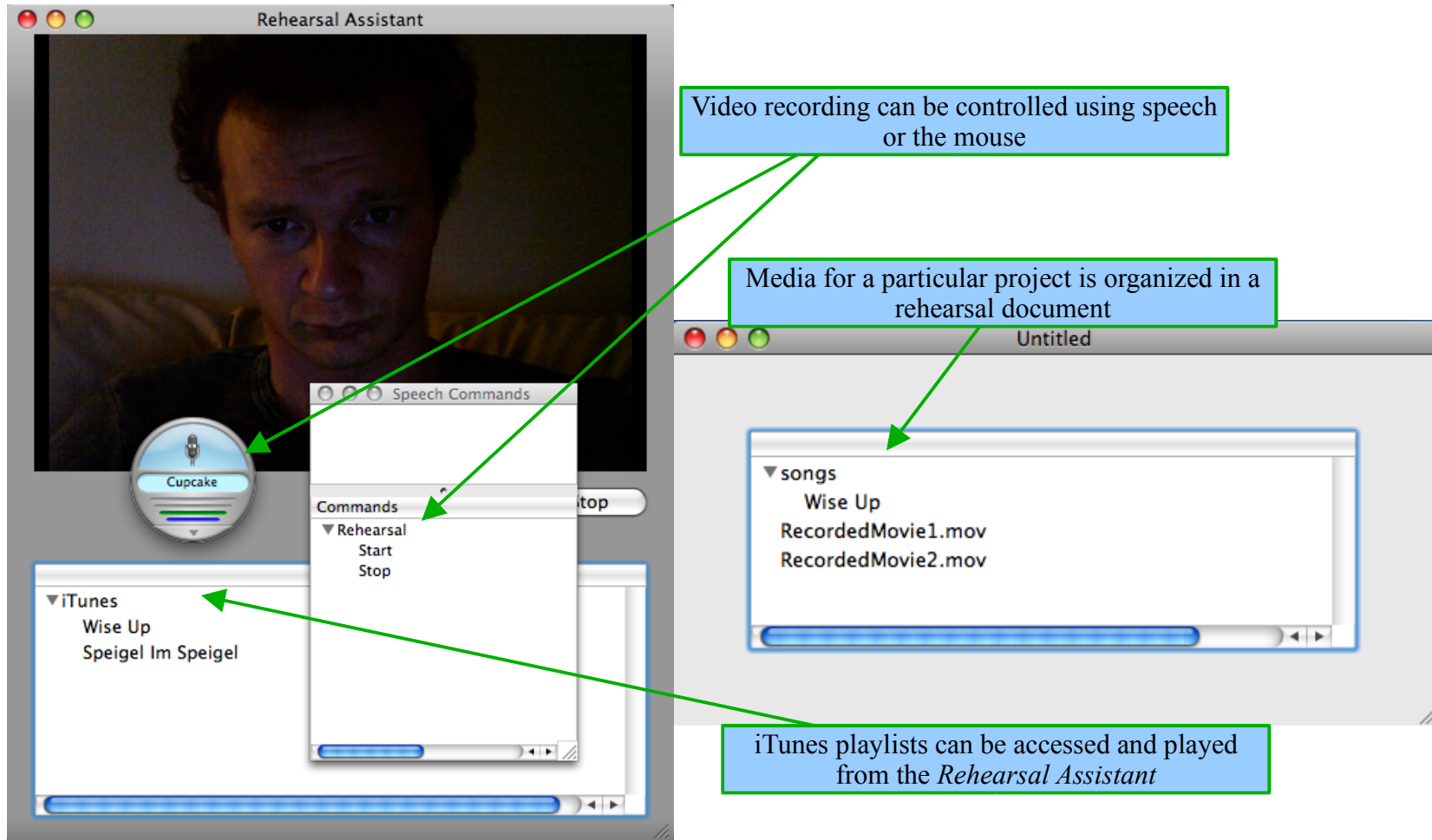
    gsr.get_match(match);
    std::cout << "match elements (observation, state): ";
    BOOST_FOREACH(gesture_model_type::match_element_type &element, match)
    {
        std::cout << "(" << element.first << ", " << element.second << ") ";
    }
    std::cout << std::endl;
}
```

# Rehearsal Assistant

- In very early prototype phase
- a software tool which helps performance artists conduct rehearsals by addressing media-related needs



# Prototype



# Audio Features

- preparation of audio/music tracks before rehearsal (track selection, cuing presets for relevant parts, tempo adjustment)
- playback during the rehearsal

# Video

- recording of rehearsals via a built-in or external camera
- playback of rehearsal videos
- streamlined sharing of videos through online repositories

# Annotation

- verbal annotations made by the rehearsal director can be recorded and synchronized with the corresponding sections of the rehearsal video recording
- annotations can be played back while replaying the video (additionally, a list of annotations is compiled and can be used to jump to specific parts of the recording)
- integration with MetaVidWiki for adding and viewing of text annotations through a web based interface, synchronized with the uploaded video recordings (work to ease the uploading of video to MetaVidWiki was accepted as a Google Summer of Code 2008 project)

# Thank You!!!

- Questions?