

Overengineering max(a, b)

Mixed Comparison Functions, Common References, and Rust's Lifetime Annotations

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think-cell

- The world's leading business presentation software
- Founded in 2002, now with 1,000,000+ users at 25,000+ companies
- Seamlessly integrated into PowerPoint, streamlining every aspect of presentation creation
- Reverse-engineer Microsoft's code, develop unique layout algorithm
- Member of the Standard C++ Foundation

And we do everything in C++!



What this talk is about

■ We are going to implement max(a, b).



What this talk is about

- We are going to implement max(a, b).
- We are embarking on a journey of accidental and essential complexity.



What this talk is about

- We are going to implement max(a, b).
- We are embarking on a journey of accidental and essential complexity.
- We are going to look at the worst feature C++ has ever added.



Definition

The maximum function max(a, b) returns the greater of the two arguments.



How hard can it be?



```
int max(int a, int b)
{
    if (a < b)
        return b;
    else
        return a;
}</pre>
```

```
int max(int a, int b)
{
    return a < b ? b : a;
}</pre>
```



```
[[nodiscard]] constexpr int max(int a, int b) noexcept
{
   return a < b ? b : a;
}</pre>
```





```
template <typename T>
const T& max(const T& a, const T& b)
{
   return a < b ? b : a;
}</pre>
```



```
template <typename T>
const T& max(const T& a, const T& b)
{
   return a < b ? b : a;
}</pre>
```

Are we done?



What are the type requirements?



Type requirements

Syntactic requirements

T must provide an operator< that returns something contextually convertible to bool.



Type requirements

Syntactic requirements

T must provide an operator< that returns something contextually convertible to bool.

Semantic requirements

The operator< must implement a strict total order.



Definition

A strict total order of a set S is a binary relation < $\subseteq S \times S$ that has three properties:



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Irreflexivity: $a \not< a$ for all $a \in S$.



Definition

A strict total order of a set S is a binary relation $\subseteq S \times S$ that has three properties:

- Irreflexivity: $a \not< a$ for all $a \in S$.
- **2** Transitivity: If a < b and b < c, then a < c for all $a, b, c \in S$.



Definition

A strict total order of a set S is a binary relation $\subseteq S \times S$ that has three properties:

- Irreflexivity: $a \not< a$ for all $a \in S$.
- **Transitivity**: If a < b and b < c, then a < c for all $a, b, c \in S$.
- **3** Trichotomy: For all $a, b \in S$, exactly one of a < b, a = b, or b < a holds.



```
template <typename T>
    // Requires: T has an operator< that implements a strict total order.
const T& max(const T& a, const T& b)
{
    return a < b ? b : a;
}</pre>
```



```
template <typename T>
    // Requires: T has an operator< that implements a strict total order.
const T& max(const T& a, const T& b)
{
    return a < b ? b : a;
}</pre>
```

Are we done?



```
struct person {
    int id;
    std::string name;
};
struct person_by_name {
    person& p;
    friend auto operator<=>(person_by_name lhs, person_by_name rhs) {
        return lhs.p.name <=> rhs..p.name;
};
auto result = max(person_by_name{p1}, person_by_name{p2});
```



```
auto p1 = person{1, "Jonathan"};
auto p2 = person{2, "Jonathan"};
auto result = max(person_by_name{&p1}, person_by_name{&p2});
```



```
auto p1 = person{1, "Jonathan"};
auto p2 = person{2, "Jonathan"};
auto result = max(person_by_name{&p1}, person_by_name{&p2});
```

This violates trichotomy.



Definition

A strict weak order of a set S is a binary relation < \subseteq $S \times S$ that has four properties:



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Definition

A strict weak order of a set S is a binary relation $\subseteq S \times S$ that has four properties:

- **1** Irreflexivity: $a \not< a$ for all $a \in S$.
- **2** Transitivity: If a < b and b < c, then a < c for all $a, b, c \in S$.



Definition

A strict weak order of a set S is a binary relation < \subseteq $S \times S$ that has four properties:

- Irreflexivity: $a \not< a$ for all $a \in S$.
- **2** Transitivity: If a < b and b < c, then a < c for all $a, b, c \in S$.
- **3** Asymmetry: If a < b, then $b \not< a$ for all $a, b \in S$



Definition

A strict weak order of a set S is a binary relation $\subseteq S \times S$ that has four properties:

- **1** Irreflexivity: $a \not< a$ for all $a \in S$.
- **2** Transitivity: If a < b and b < c, then a < c for all $a, b, c \in S$.
- **3** Asymmetry: If a < b, then $b \not < a$ for all $a, b \in S$
- **Transitivity of incomparability**: Define $a \sim b$ if neither a < b nor b < a. If $a \sim b$ and $b \sim c$, then $a \sim c$ for all $a, b, c \in S$.



Definition

A strict weak order of a set S is a binary relation $\subseteq S \times S$ that has four properties:

- Irreflexivity: $a \not< a$ for all $a \in S$.
- **2** Transitivity: If a < b and b < c, then a < c for all $a, b, c \in S$.
- **3** Asymmetry: If a < b, then $b \not < a$ for all $a, b \in S$
- **Transitivity of incomparability**: Define $a \sim b$ if neither a < b nor b < a. If $a \sim b$ and $b \sim c$, then $a \sim c$ for all $a, b, c \in S$.

A strict weak order of a set S defines a strict total order of the equivalence classes of \sim .



```
template <typename T>
    // Requires: T has an operator< that implements a strict weak order.
const T& max(const T& a, const T& b)
{
    return a < b ? b : a;
}</pre>
```

```
template <typename T>
    // Requires: T has an operator< that implements a strict weak order.
const T& max(const T& a, const T& b)
    return a < b ? b : a;
auto p1 = person{1, "Jonathan"};
auto p2 = person{2, "Jonathan"};
auto result = max(person_bv_name{p1}, person_bv_name{p2});
```

Should this be p1 or p2?



```
template <typename T>
    // Requires: T has an operator< that implements a strict weak order.
const T& max(const T& a, const T& b)
{
    return a < b ? b : a;
}</pre>
```

```
template <typename T>
    // Requires: T has an operator< that implements a strict weak order.
const T& max(const T& a, const T& b)
    return a < b ? b : a;
template <typename T>
    // Requires: T has an operator< that implements a strict weak order.
const T& max(const T& a, const T& b)
    return b < a ? a : b;
```



```
template <typename T>
    // Requires: T has an operator< that implements a strict weak order.
const T& max(const T& a, const T& b)
    return a < b ? b : a;
template <typename T>
    // Requires: T has an operator< that implements a strict weak order.
const T& max(const T& a, const T& b)
    return b < a ? a : b;
```

Let's stick with the first option.





```
std::string a = "hello";
std::string_view b = "world";
std::print("{}\n", max(a, b)); // error
```



```
std::string a = "hello";
std::string_view b = "world";
std::print("{}\n", max(a, b)); // error

template <typename T>
const T& max(const T& a, const T& b) { ... }
```

```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(const T& a, const U& b)
{
    return a < b ? b : a;
}</pre>
```



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(const T& a, const U& b) -> std::common_type_t<T, U>
{
    return a < b ? b : a;
}</pre>
```



Aside: std::common_type is weird



Aside: std::common_type is weird

Plus some weird exception.



Aside: std::common_type is user-customizable

You can specialize std::common_type for your own types!



Aside: std::common_type is user-customizable

You can specialize std::common_type for your own types!

This does not affect ?:.



```
template <typename ... T>
using std::common_type_t = ...;
```



```
template <typename ... T>
using std::common_type_t = ...;
std::common_type_t<A, B, C> != std::common_type_t<B, C, A>.
```



```
template <typename ... T>
using std::common_type_t = ...;

std::common_type_t<A, B, C> != std::common_type_t<B, C, A>.

struct A {};
struct B : A {};
struct C : A {};
```



```
template <typename ... T>
using std::common_type_t = ...;
std::common_type_t<A, B, C> != std::common_type_t<B, C, A>.
struct A {}:
struct B : A {}:
struct C : A {}:
std::common_type_t<std::common_type_t<A, B>, C> is A.
std::common_type_t<std::common_type_t<B, C>, A> does not exist.
```



```
std::string a = "hello";
std::string_view b = "world";
std::print("{}\n", max(a, b));
```

world



```
int    a = -1;
unsigned b = +1;
std::print("{}\n", max(a, b));
```



```
int    a = -1;
unsigned b = +1;
std::print("{}\n", max(a, b));
4294967295
```



int() < unsigned() can be implemented in three ways:</pre>



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1 Compare the mathematical value they represent (correct).



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- 1 Compare the mathematical value they represent (correct).
- Convert both to int, then compare two ints.



int() < unsigned() can be implemented in three ways:</pre>

- 1 Compare the mathematical value they represent (correct).
- Convert both to int, then compare two ints.
- 3 Convert both to unsigned, then compare two unsigneds (C++).



int() < unsigned() can be implemented in three ways:</pre>

- Compare the mathematical value they represent (correct).
- 2 Convert both to int, then compare two ints.

std::cmp_less does the correct thing.



std::common_type_t<int, unsigned> can be one of:



std::common_type_t<int, unsigned> can be one of:

The next larger signed integer type that can fit both types (correct).



std::common_type_t<int, unsigned> can be one of:

1 The next larger signed integer type that can fit both types (correct).

2 int.



std::common_type_t<int, unsigned> can be one of:

- 1 The next larger signed integer type that can fit both types (correct).
- 2 int.
- 3 unsigned (C++).



std::common_type_t<int, unsigned> can be one of:

- 1 The next larger signed integer type that can fit both types (correct).
- 2 int.
- unsigned (C++).
- invalid (think-cell).



think-cell: Safe conversions

```
template <typename Source, typename Target>
concept tc::safely_convertible_to = ...;
```

- std::convertible_to<Source, Target>, and
- that conversion is "safe"



think-cell: Safe conversions

```
template <typename Source, typename Target>
concept tc::safely_convertible_to = ...;
```

- std::convertible_to<Source, Target>, and
- that conversion is "safe"

Conversions which are not "safe":

- Derived to Base (slicing)
- int to unsigned



think-cell: Safe common type

```
template <typename ... Ts>
using tc::common_type_t = ...;

std::common_type_t<Ts...> provided tc::safely_convertible_to<Ts,
std::common_type_t<Ts...> && ....
```



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(const T& a, const U& b) -> tc::common_type_t<T, U>
{
    return a < b ? b : a;
}</pre>
```



```
template <typename T, typename U>
   // Requires: T and U have a common operator< that
   // implements a strict weak order.
auto max(const T& a, const U& b) -> tc::common_type_t<T, U>
    return a < b ? b : a;
int a = -1:
unsigned b = 1:
std::print("{}\n", max(a, b)); // error
```





```
template <typename T, typename U>

// Requires: T and U have a common operator< that

// implements a strict weak order.

auto max(const T& a, const U& b) -> tc::common_type_t<T, U> { ... }
```

```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(const T& a, const U& b) -> tc::common_type_t<T, U> { ... }

std::string a = "hello";
std::string b = "world";
std::print("{}\n", max(a, b));
```



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(const T& a, const U& b) -> tc::common_type_t<T, U> { ... }

std::string a = "hello";
std::string b = "world";
std::print("{}\n", max(a, b));
```

Unnecessary copy of the result.



```
std::string a = "hello";
std::string b = "world";
std::print("{}\n", max(a, b));
```



```
std::string a = "hello";
std::string b = "world";
std::print("{}\n", max(a, b));
```

No copy of the result.



```
std::print("{}\n", max("hello", std::string("world")));
```



```
std::print("{}\n", max("hello", std::string("world")));
```

Unnecessary copy of the result, should be a move.



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
    requires requires { typename tc::common_type_t<T, U>; }
decltype(auto) max(T&& a, U&& b)
{
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
}
```



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
    requires requires { typename tc::common_type_t<T, U>; }
decltype(auto) max(T&& a, U&& b)
{
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
}
```

What if std::remove_cvref_t<T> and std::remove_cvref_t<U> are the same type?



What does the ternary operator do?

?:	T&	const T&	T&&	const T&&
T&	T&	const T&	T	Т
const T&	const T&	const T&	Т	T
T&&	T	T	T&&	const T&&
const T&&	T	T	const T&&	const T&&



What does the ternary operator do?

?:	T&	const T&	T&&	const T&&
T&	T&	const T&	T	Т
const T&	const T&	const T&	Т	T
T&&	T	T	T&&	const T&&
const T&&	T	T	const T&&	const T&&

?: is a prvalue when mixing an Ivalue and an rvalue reference.



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
    requires requires { typename tc::common_type_t<T, U>; }
decltype(auto) max(T&& a, U&& b)
{
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
}
```



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
    requires requires { typename tc::common_type_t<T, U>; }
decltype(auto) max(T&& a, U&& b)
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
std::print("{}\n", max("hello", std::string("world")));
```

Result will be moved.



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
    requires requires { typename tc::common_type_t<T, U>; }
decltype(auto) max(T&& a, U&& b)
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
std::print("{}\n", max("hello", std::string("world")));
```

Result will be moved.

```
auto a = std::string("world");
std::print("{}\n", max(std::string("hello"), a));
```



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
    requires requires { typename tc::common_type_t<T, U>; }
decltype(auto) max(T&& a, U&& b)
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
std::print("{}\n", max("hello", std::string("world")));
```

Result will be moved.

```
auto a = std::string("world");
std::print("{}\n", max(std::string("hello"), a));
```

Unnecessary copy of a.



```
template <typename ... Ts>
using std::common_reference_t = ...;
```

- If std::remove_cvref_t<T> and std::remove_cvref_t<U> are the same type, figure out the correct cv-ref qualification.
- Otherwise, use std::common_type_t<T, U>.



```
template <typename ... Ts>
using std::common_reference_t = ...;
```

- If std::remove_cvref_t<T> and std::remove_cvref_t<U> are the same type, figure out the correct cv-ref qualification.
- Otherwise, use std::common_type_t<T, U>.

```
Crucially: not decltype( false ? ... : ... ).
```



What does std::common_reference do?

std::common_reference	T&	const T&	T&&	const T&&
T&	T&	const T&	const T&	const T&
const T&	const T&	const T&	const T&	const T&
T&&	const T&	const T&	T&&	const T&&
const T&&	const T&	const T&	const T&&	const T&&

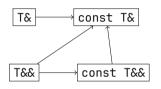


What does std::common_reference do?

std::common_reference	T&	const T&	T&&	const T&&
T&	T&	const T&	const T&	const T&
const T&	const T&	const T&	const T&	const T&
T&&	const T&	const T&	T&&	const T&&
const T&&	const T&	const T&	const T&&	const T&&

std::common_reference is a const Ivalue reference when mixing an Ivalue and an rvalue reference.





Binds to:		Temporary	const	
T&		no	no	
const	T&	yes	yes	
3&T		yes	no	
const	3&T	yes	yes	

Thus:

- The common reference is const T& as that is the universal receiver.
- Functions that don't care about lifetime or mutation, use const T&.



Is that ideal?



Is that ideal?

Binds to	Temporary	const	
T&	no	no	
const T&	yes	yes	
T&&	yes	no	
const T&&	yes	yes	



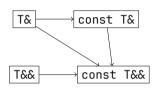
Is that ideal?

Binds to	Temporary	const	
T&	no	no	
const T&	yes	yes	
T&&	yes	no	
const T&&	yes	yes	

We are missing "no" + "yes"!



C++Better



Binds to:	Temporary	const	
T&	no	no	
const T&	no	yes	
A&T	yes	no	
const T&&	yes	yes	

Then:

- The common reference is const T&& as that is the universal receiver.
- Functions that don't care about lifetime or mutation, use const T&&.



think-cell: Better common reference

```
template <typename ... Ts>
using tc::common_reference_t = ...;
```

- tc::common_reference_t<int&, int&&> is const int&&, not const int&.
- Uses tc::common_type_t not std::common_type_t.



think-cell: Better common reference

tc::common_reference	T&	const T&	T&&	const T&&
T&	T&	const T&	const T&&	const T&&
const T&	const T&	const T&	const T&&	const T&&
T&&	const T&&	const T&&	T&&	const T&&
const T&&	const T&&	const T&&	const T&&	const T&&



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(T&& a, U&& b)
    -> tc::common_reference_t<T, U>
{
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
}
```



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(T&& a, U&& b)
    -> tc::common_reference_t<T, U>
{
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
}
```

?: is a prvalue when mixing lvalues and rvalues!



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(T&& a, U&& b)
    -> tc::common_reference_t<T, U>
    if (a < b)
        return std::forward<U>(b):
    else
        return std::forward<T>(a);
```



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(T&& a, U&& b)
    -> tc::common reference t<T, U>
    if (a < b)
        return static_cast<tc::common_reference_t<T, U>>(
            std::forward<U>(b)
        );
    else
        return static_cast<tc::common_reference_t<T, U>>(
            std::forward<T>(a)
        );
```

```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(T&& a, U&& b)
    -> tc::common reference t<T, U>
    return tc_conditional_rvalue_as_ref(
        a < b.
        std::forward<U>(b),
        std::forward<T>(a)
```



tc_conditional_rvalue_as_ref

```
#define tc_conditional_rvalue_as_ref(cond, lhs, rhs) \
    ((cond) \
    ? (tc::common_reference_t<decltype((lhs)), decltype((rhs))>)(lhs) \
    : (tc::common_reference_t<decltype((lhs)), decltype((rhs))>)(rhs))
```



Aside: Better base class conversion

```
struct A {};

struct B : A { using base = A; }

struct C : A { using base = A; }

struct D : C { using base = C; }

B b;
D d;
A& ref = tc_conditional_rvalue_as_ref(cond, b, d);
```



Aside: Better base class conversion

```
struct A {};

struct B : A { using base = A; }

struct C : A { using base = A; }

struct D : C { using base = C; }

B b;
D d;
A& ref = tc_conditional_rvalue_as_ref(cond, b, d);
```

Fun TMP challenge: Given T and U find the most-derived common base class by walking ::base.



```
template <typename T, typename U>
    // Requires: T and U have a common operator< that
    // implements a strict weak order.
auto max(T&& a, U&& b)
    -> tc::common_reference_t<T, U>
    return tc_conditional_rvalue_as_ref(
        a < b.
        std::forward<U>(b),
        std::forward<T>(a)
    );
```

```
tnink-cell 💆
```

auto a = std::string("world");

std::print("{}\n", max(std::string("hello"), a));



```
template <typename T, typename U>
auto max(T&& a, U&& b) -> tc::common reference t<T, U> {
    return to conditional rvalue as ref(
        a < b.
        std::forward<U>(b), std::forward<T>(a)
    );
template <typename T, typename U>
auto min(T&& a, U&& b) -> tc::common_reference_t<T, U> {
    return tc_conditional_rvalue_as_ref(
       a > b.
        std::forward<U>(b), std::forward<T>(a)
    );
```

```
template <typename T, typename U, typename V>
decltype(auto) clamp(T&& v, U&& lo, V&& hi)
{
    return min(
        max(std::forward<T>(v), std::forward<U>(lo)),
        std::forward<V>(hi)
    );
}
```

```
template <typename T, typename U, typename V>
decltype(auto) clamp(T&& v, U&& lo, V&& hi)
    return min(
       max(std::forward<T>(v), std::forward<U>(lo)),
        std::forward<V>(hi)
   );
std::string lo = "a";
std::string hi = "z";
std::string v = "h";
auto clamped = clamp(v, lo, hi); // ok
```

```
template <typename T, typename U, typename V>
decltype(auto) clamp(T&& v, U&& lo, V&& hi)
    return min(
        max(std::forward<T>(v), std::forward<U>(lo)),
        std::forward<V>(hi)
   );
std::string_view lo = "a":
std::string_view hi = "z";
std::string v = "h";
auto clamped = clamp(v, lo, hi); // crαsh!
```

```
template <typename T, typename U, typename V>
decltype(auto) clamp(
      T&& v, // std::string&
      U&& lo, // std::string_view&
      V&& hi // std::string_view&
    return min(
        max(std::forward<T>(v), std::forward<U>(lo)),
        std::forward<V>(hi)
   );
```



```
template <typename T, typename U, typename V>
decltype(auto) clamp(
      T&& v, // std::string&
      U&& lo, // std::string_view&
      V&& hi // std::string_view&
    return min(
       max(std::forward<T>(v), std::forward<U>(lo)), // std::string_view
        std::forward<V>(hi)
   );
```



```
template <typename T, typename U, typename V>
decltype(auto) clamp(
      T&& v, // std::string&
      U&& lo, // std::string_view&
      V&& hi // std::string_view&
    return min(
        max(std::forward<T>(v), std::forward<U>(lo)), // std::string_view
        std::forward<V>(hi)
                                                      // std::string_view&
   );
```



```
template <typename T, typename U, typename V>
decltype(auto) clamp(
      T&& v, // std::string&
      U&& lo, // std::string_view&
      V&& hi // std::string_view&
    return min(
        max(std::forward<T>(v), std::forward<U>(lo)), // std::string_view
        std::forward<V>(hi)
                                                      // std::string view&
    ); // const std::string_view&&
```



Whose fault is it?



Whose fault is it?

Projection A function that returns a reference whose lifetime is tied to one of the arguments.

Composed Projection A projection built by composing multiple projections.



Whose fault is it?

Projection A function that returns a reference whose lifetime is tied to one of the arguments. Composed Projection A projection built by composing multiple projections.

Problem: If projections return rvalue references to prvalue arguments, composing them can lead to returning dangling references.



Solution 1: A projection never returns an rvalue reference.



Solution 1: A projection never returns an rvalue reference.

```
template <typename T>
using decay_rvalue_t = std::conditional_t<</pre>
    std::is_rvalue_reference_v<T>, std::decay_t<T>, T
>;
template <typename T, typename U>
auto max(T&& a, U&& b)
    -> decay rvalue t<tc::common reference t<T, U>>
    return tc_conditional_rvalue_as_ref(
        a < b, std::forward<U>(b), std::forward<T>(a)
    );
```

Solution 1: A projection never returns an rvalue reference.

```
template <typename T>
using decay_rvalue_t = std::conditional_t<</pre>
    std::is_rvalue_reference_v<T>, std::decay_t<T>, T
>;
template <typename T, typename U>
auto max(T&& a, U&& b)
    -> decay rvalue t<tc::common reference t<T, U>>
    return tc_conditional_rvalue_as_ref(
        a < b, std::forward<U>(b), std::forward<T>(a)
    );
```

think-cell 4

Solution 2: A projection never returns an rvalue reference to a prvalue argument.



Solution 2: A projection never returns an rvalue reference to a prvalue argument.

```
template <typename T, typename ... Args>
using decay if prvalue t = ???:
template <tvpename T, typename U>
auto max(T&& a, U&& b)
    -> decay_if_prvalue_t<tc::common_reference_t<T, U>, T, U>
    return to conditional rvalue as ref(
        a < b, std::forward<U>(b), std::forward<T>(a)
    );
```



Solution 2: A projection never returns an rvalue reference to a prvalue argument.

```
template <typename T, typename ... Args>
using decay if prvalue t = ???:
template <tvpename T, typename U>
auto max(T&& a, U&& b)
    -> decay_if_prvalue_t<tc::common_reference_t<T, U>, T, U>
    return to conditional rvalue as ref(
        a < b, std::forward<U>(b), std::forward<T>(a)
    );
```

Problem: Not actually implementable.



```
template <typename T>
void f(T&& t);
```

Category	Т	T&&
Ivalue	U&	U&
xvalue	U	&&U
prvalue	U	&&U



```
template <typename T>
void f(T&& t);
```

Category	Т	T&&
Ivalue	U&	J&
xvalue	U	&&U
prvalue	U	&&U

A function cannot distinguish between prvalues and xvalue arguments.



C++Better

```
template <typename T>
void f(T&& t);
```

Category	Т	3&T
Ivalue	J&	J&
xvalue	&&U	&&U
prvalue	U	&&U



C++Better

```
template <typename T>
void f(T&& t);
```

Category	Т	T&&
Ivalue	U&	U&
xvalue	3&U	&&U
prvalue	U	&&U

A function could actually distinguish between prvalues and xvalue arguments!



```
return min(
    max(std::forward<T>(v), std::forward<U>(lo)),
    std::forward<V>(hi)
); // dangling
```



```
return min(
    max(std::forward<T>(v), std::forward<U>(lo)),
    std::forward<V>(hi)
); // dangling

some_function(min(
    max(std::forward<T>(v), std::forward<U>(lo)),
    std::forward<V>(hi)
)); // fine
```



```
return min(
    max(std::forward<T>(v), std::forward<U>(lo)),
    std::forward<V>(hi)
); // dangling

some_function(min(
    max(std::forward<T>(v), std::forward<U>(lo)),
    std::forward<V>(hi)
)); // fine
```

The user of a composed projection should be responsible for preventing dangling references!



Solution 3: A composed projection never returns a reference to an intermediate prvalue.



Solution 3: A composed projection never returns a reference to an intermediate prvalue.

```
template <typename T>
auto decay_rvalue(T&& v) -> decay_rvalue_t<T&&> {
    return std::forward<T>(v);
template <typename T, typename U, typename V>
decltype(auto) clamp(T&& v, U&& lo, V&& hi) {
    return decay_rvalue(min(
        max(std::forward<T>(v), std::forward<U>(lo)),
        std::forward<V>(hi)
   )):
```

Solution 3: A composed projection never returns a reference to an intermediate prvalue.

```
template <bool Cond, typename T>
auto decay_if(T&& v)
    -> std::conditional_t<Cond, std::decay_t<T>, T&&> {
    return std::forward<T>(v);
template <typename T, typename U, typename V>
decltype(auto) clamp(T&& v, U&& lo, V&& hi) {
    using max_t = decltype(max(std::forward<T>(v), std::forward<U>(lo)));
    return decay_if<!std::is_reference_v<max_t>>(min(
        max(std::forward<T>(v), std::forward<U>(lo)),
        std::forward<V>(hi)
    )):
                                                                             ₫ اد
```



```
template <typename F, typename G, typename H>
struct dovekie
    F f:
   G g;
   H h;
    template <typename T, typename U>
    decltype(auto) operator()(T&& t, U&& u) const
    {
        return f(g(std::forward<T>(t)), h(std::forward<U>(u)));
};
```



```
template <typename F, typename G, typename H>
struct dovekie
    F f:
    G q;
    H h;
    template <typename T, typename U>
    decltype(auto) operator()(T&& t, U&& u) const
    {
        return decay_if<q_or_h_returns_prvalue>(
            f(g(std::forward<T>(t)), h(std::forward<U>(u)))
        );
```

```
template <typename F, typename G, typename H>
struct dovekie
    F f:
   G g;
    H h;
    template <typename T, typename U>
    decltype(auto) operator()(T&& t, U&& u) const
    {
        return decay_if<f_returns_an_rvalue_to_prvalue_of_q_or_h>(
            f(g(std::forward<T>(t)), h(std::forward<U>(u)))
        );
```

C++ isn't a particularly great language, but all problems in C++ can be fixed with more C++.



tc::temporary - A new reference type

Idea: Introduce a special "reference to temporary" type.



tc::temporary - A new reference type

```
template <typename T> requires std::is_object_v<T>
class temporary {
    T&& m_ref;
public:
    template <std::same as<T&> U>
    explicit temporary(U ref) noexcept : m_ref(ref) {}
    template <std::same_as<T&&> U>
    temporary(U ref) noexcept : m_ref(std::move(ref)) {}
    operator T&() const& noexcept {
      return m_ref;
    operator T&&() const&& noexcept {
      return std::move(m ref);
```

```
template <typename T>
using prvalue_as_temporary_t = std::conditional_t<</pre>
    std::is_reference<T>::value | tc::is_temporary<T>,
        Τ,
        tc::temporary<T>
>;
#define tc_prvalue_as_temporary(...) \
    static_cast<tc::prvalue_as_temporary_t<decltype((__VA_ARGS__))>> \
        ( VA ARGS )
```



```
int f();
int object = 0;

tc_prvalue_as_temporary(object) // int&
```



```
int f();
int object = 0;

tc_prvalue_as_temporary(object)  // int&

tc_prvalue_as_temporary(std::move(object))  // int&&
```





Creating a temporary



Creating a temporary

Is there overhead?



static_cast<decltype((expr))>(expr)

- If expr is an Ivalue or xvalue, casts it to an Ivalue or rvalue reference.
- If expr is a prvalue, copy-elision keeps it as a prvalue.



static_cast<decltype((expr))>(expr)

- If expr is an Ivalue or xvalue, casts it to an Ivalue or rvalue reference.
- If expr is a prvalue, copy-elision keeps it as a prvalue.

 \rightarrow no-op



static_cast<decltype((expr))>(expr)

- If expr is an Ivalue or xvalue, casts it to an Ivalue or rvalue reference.
- If expr is a prvalue, copy-elision keeps it as a prvalue.

```
\rightarrow no-op
```

static_cast<decltype(expr)>(expr)

- If expr is a non-identifier, as above.
- If expr is an identifier referring to an Ivalue reference or object, casts it to an Ivalue reference.
- If expr is an identifier referring to an rvalue reference, casts it to an rvalue reference.



static_cast<decltype((expr))>(expr)

- If expr is an Ivalue or xvalue, casts it to an Ivalue or rvalue reference.
- If expr is a prvalue, copy-elision keeps it as a prvalue.

 \rightarrow no-op

static_cast<decltype(expr)>(expr)

- If expr is a non-identifier, as above.
- If expr is an identifier referring to an Ivalue reference or object, casts it to an Ivalue reference.
- If expr is an identifier referring to an rvalue reference, casts it to an rvalue reference.
- \rightarrow std::forward



Rule: A tc::temporary must never be returned from a function.



Rule: A tc::temporary must never be returned from a function.

```
template <typename T>
using return_temporary_t = std::conditional_t<</pre>
    tc::is_temporary<T>,
        tc::decay_t<T>,
>;
#define tc_return_temporary(...) \
    return static cast<tc::return temporary t<decltype(( VA ARGS ))>>( \
        VA ARGS \
```



```
int object;
tc_return_temporary(object);

Equivalent to: return static_cast<int&>(object);
```

```
int object;
tc_return_temporary(object);

Equivalent to: return static_cast<int&>(object);
int object;
tc_return_temporary(std::move(object));

Equivalent to: return static_cast<int&>(std::move(object));
```

```
int object;
tc_return_temporary(object);
Equivalent to: return static_cast<int&>(object);
int object;
tc_return_temporary(std::move(object));
Equivalent to: return static_cast<int&&>(std::move(object));
tc_return_temporary(42);
Equivalent to: return static_cast<int>(42): (copy-elision!)
```



```
int object:
tc_return_temporary(object);
Equivalent to: return static cast<int&>(object):
int object;
tc return temporary(std::move(object));
Equivalent to: return static_cast<int&&>(std::move(object));
tc_return_temporary(42);
Equivalent to: return static_cast<int>(42): (copy-elision!)
tc_return_temporary(tc::temporary(42));
Equivalent to: return static_cast<int>(tc::temporary(42));
```

```
template <typename F, typename G, typename H>
struct dovekie
    F f:
   G g;
    H h;
    template <typename T, typename U>
    decltype(auto) operator()(T&& t, U&& u) const
    ₹
        tc_return_temporary(f(
            tc_prvalue_as_temporary(g(std::forward<T>(t))),
            tc_prvalue_as_temporary(h(std::forward<U>(u)))
        ));
```

Better invoke

Let's teach it to invoke:

```
#define tc_invoke(f, ...) \
    tc::invoke_impl(f, /* wrap arguments in tc_prvalue_as_temporary */)
```

Better invoke

Let's teach it to invoke:

```
#define tc_invoke(f, ...) \
    tc::invoke_impl(f, /* wrap arguments in tc_prvalue_as_temporary */)
template <typename T, typename U>
decltype(auto) operator()(T&& t, U&& u) const
    tc_return_temporary(
        tc_invoke(f,
            tc_invoke(q, std::forward<T>(t)),
            tc_invoke(h, std::forward<U>(u))
```

Consequence: Projections need to be aware of tc::temporary.



Consequence: Projections need to be aware of tc::temporary.

```
template <typename T, typename U>
tc::common_reference_t<T, U> f(T&& t, U&& u);
```

Must return a tc::temporary if at least one argument is a temporary.



Consequence: Projections need to be aware of tc::temporary.

```
template <typename T, typename U>
tc::common_reference_t<T, U> f(T&& t, U&& u);
```

Must return a tc::temporary if at least one argument is a temporary.

```
template <typename T, typename U>
T&& f(T&& t, U&& u);
```

Must return a tc::temporary if and only if the first argument is a temporary.



Consequence: Projections need to be aware of tc::temporary.

```
template <typename T, typename U>
tc::common_reference_t<T, U> f(T&& t, U&& u);
```

Must return a tc::temporary if at least one argument is a temporary.

```
template <typename T, typename U>
T&& f(T&& t, U&& u);
```

Must return a tc::temporary if and only if the first argument is a temporary.

```
template <typename T, typename U>
tc::common_type_t<T, U> f(T&& t, U&& u);
```

Must never return a tc::temporary.





```
template <typename T, typename U>
auto max(T&& a, U&& b)
    -> tc::common reference t<T, U>
    // Implicit conversion of tc::temporary -> T& if necessary.
    return tc_conditional_rvalue_as_ref(
        a < b, std::forward<U>(b), std::forward<T>(a)
    );
template <typename T>
decltype(auto) get_foo(T&& obj)
    return std::forward<T>(obj).foo; // no implicit conversion!
```

Unwrapping temporaries

```
template <typename T>
using unwrap_temporary_t = std::conditional_t<</pre>
    tc::is_temporary<T>,
        tc::decay_t<T>&&, T
>;
#define tc_unwrap_temporary(...) \
    static_cast<tc::unwrap_temporary_t<decltype((__VA_ARGS__))>>( \
        __VA_ARGS__ \
```



Unwrapping temporaries

```
template <typename T>
decltype(auto) get_foo(T&& obj)
{
    return tc_unwrap_temporary(std::forward<T>(obj)).foo;
}
```



Unwrapping temporaries

```
template <typename T>
decltype(auto) get_foo(T&& obj)
{
    return tc_unwrap_temporary(std::forward<T>(obj)).foo;
}
```

No tc::temporary annotation on the result.



Rewrapping temporaries

```
template <typename Result, typename ... Args>
using rewrap_temporary_t = std::conditional_t<</pre>
    std::is_rvalue_reference_v<Result> && (tc::is_temporary<Args> || ...),
        tc::temporary<std::remove_reference_t<Result>>,
        Result
>;
#define tc_rewrap_temporary(Args, ...) \
    static_cast<tc::rewrap_temporary_t<decltype((__VA_ARGS__)), Args>( \
        VA ARGS \
```

If the result is an rvalue reference and any of the arguments is a tc::temporary, wrap it in a tc::temporary.



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Rewrapping temporaries

```
template <typename Result, typename ... Args>
using rewrap_temporary_t = std::conditional_t<</pre>
    std::is_rvalue_reference_v<Result> && (tc::is_temporary<Args> || ...),
        tc::temporary<std::remove_reference_t<Result>>,
        Result
>;
#define tc_rewrap_temporary(Args, ...) \
    static_cast<tc::rewrap_temporary_t<decltype((__VA_ARGS__)), Args>( \
        VA ARGS \
```

If the result is an rvalue reference and any of the arguments is a tc::temporary, wrap it in a tc::temporary.

This is a heuristic.



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Unwrapping and rewrapping temporaries



```
template <typename T, typename U>
decltype(auto) operator()(T&& t, U&& u) const
    tc_return_temporary(
       tc_invoke(f,
            tc_invoke(g, std::forward<T>(t)),
            tc_invoke(h, std::forward<U>(u))
```



```
template <typename T, typename U>
decltype(auto) operator()(T&& t, U&& u) const
   tc_return_temporary(
       tc_invoke(f,
            tc_invoke(q, std::forward<T>(t)),
            tc_invoke(h, std::forward<U>(u))
```

What if t or u is already a tc::temporary?



Temporary with lifetime

```
template <typename T, unsigned Lifetime>
class temporary { ... };
```

- Lifetime == 0: true temporary, need to decay in tc_return_temporary
- Lifetime > 0: only a temporary in some parent scope
- tc::common_reference_t, tc_rewrap_temporary: minimum lifetime of all temporaries



Temporary with lifetime

```
template <typename T, unsigned Lifetime>
class temporary { ... };
```

- Lifetime == 0: true temporary, need to decay in tc_return_temporary
- Lifetime > 0: only a temporary in some parent scope
- tc::common_reference_t, tc_rewrap_temporary: minimum lifetime of all temporaries

```
#define tc_increment_lifetime(...) ...
#define tc_decrement_lifetime(...) ...
```



Temporary with lifetime



This approach works.



This approach works.

- Composed projections use tc_invoke and tc_return_temporary → never returns a dangling reference.
- Tracking of tc::temporary is accurate → no unnecessary decay.



This approach works.

- Composed projections use tc_invoke and tc_return_temporary → never returns a dangling reference.
- Tracking of tc::temporary is accurate \rightarrow no unnecessary decay.

But: all templated projections need to be aware of tc::temporary.



Insight: tc::temporary is only relevant for projections that can return an rvalue reference.



Insight: tc::temporary is only relevant for projections that can return an rvalue reference.

```
template <typename F, typename ... Args>
decltype(auto) invoke_impl(F\&\& f, Args\&\&... args) {
    if constexpr (std::is_rvalue_reference_v<decltype(</pre>
        std::forward<F>(f)(
            tc_unwrap_temporary(std::forward<Args>(args))...
    )>)
        return tc_decrement_lifetime(std::forward<F>(f)(
            tc_increment_lifetime(std::forward<Args>(args))...
        )):
    else
        return std::forward<F>(f)(
            tc_unwrap_temporary(std::forward<Args>(args))...
        );
```

■ tc::temporary<const T, Lifetime>



- tc::temporary<const T, Lifetime>
- Reference collapsing rules:



- tc::temporary<const T, Lifetime>
- Reference collapsing rules:
 - tc::temporary<T, Lifetime>& → T&



- tc::temporary<const T, Lifetime>
- Reference collapsing rules:
 - tc::temporary<T, Lifetime>& \rightarrow T&
 - tc::temporary<T, Lifetime>&& → tc::temporary<T, Lifetime>



tc::temporary is being used in production:

■ It is only necessary for function objects in generic code.



tc::temporary is being used in production:

- It is only necessary for function objects in generic code.
- Composed projections handle temporaries appropriately.



tc::temporary is being used in production:

- It is only necessary for function objects in generic code.
- Composed projections handle temporaries appropriately.
- Generic library projections handle temporaries appropriately.



tc::temporary is being used in production:

- It is only necessary for function objects in generic code.
- Composed projections handle temporaries appropriately.
- Generic library projections handle temporaries appropriately.
- There isn't a single projection in user code that needs to handle temporary.



Most common projection:

Most common projection:

```
tc::transform(rng, tc_member(.foo));
```

Similar: tc_mem_fn(.size).





Requirements

Projections:

- No unnecessary copies.
- No unnecessary moves.

Composed Projections:

■ Don't return reference to intermediate temporary.



Requirements

Projections:

- No unnecessary copies.
- No unnecessary moves.

Composed Projections:

■ Don't return reference to intermediate temporary.

Problem: How to track whether a resulting reference is tied to an argument?



Rust approach: Built-in lifetime annotations

Mark the lifetime of the output reference (if it is one).

```
template <typename T, typename U>
auto max(T&&/l a, U&&/l b)
    -> tc::common_reference_t<T, U>/l
{
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
}
```



Rust approach: Built-in lifetime annotations

Mark the lifetime of the output reference (if it is one).

```
template <typename T, typename U>
auto max(T&&/l a, U&&/l b)
    -> tc::common_reference_t<T, U>/l
    return a < b ? std::forward<U>(b) : std::forward<T>(a);
```

Automatically decay references to dangling temporary in return.

```
template <typename T, typename U>
decltype(auto) operator()(T&&/l a, U&&/l b) const
    return f(g(std::forward<T>(t)), h(std::forward<U>(u)));
```

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This is still unnecessary complexity!



Why does Rust require lifetime annotations in the signature?



Why does Rust require lifetime annotations in the signature?

To ensure that you don't change the signature accidentally during internal refactorings.



Why does Rust require lifetime annotations in the signature?

To ensure that you don't change the signature accidentally during internal refactorings.

But: For a projection, the lifetime follows from the behavior!



Why do C++/Rust require explicit opt-in to call by reference?



Why do C++/Rust require explicit opt-in to call by reference?

Because it has consequences for lifetime tracking.



Why do C++/Rust require explicit opt-in to call by reference?

Because it has consequences for lifetime tracking.

But: For a projection, there is an obvious choice.



Better approach: Just write the projection

Specify that it is a projection, and the compiler does the right thing.

```
template <typename T, typename U>
projection auto max(T a, U b)
   -> tc::common_type_t<T, U>
{
   return a < b ? b : a;
}</pre>
```



Better approach: Just write the projection

Specify that it is a projection, and the compiler does the right thing.

```
template <typename T, typename U>
projection auto max(T a, U b)
    -> tc::common_type_t<T, U>
    return a < b ? b : a;
template <typename T, typename U>
projection auto operator()(T a, U b) const
    return f(q(a), h(b));
```



First-class references are the worst feature C++ has ever added.

Complexity in function arguments.



- Complexity in function arguments.
- T& vs. T&& vs. auto&&.



- Complexity in function arguments.
- T& vs. T&& vs. auto&&.
- Temporary lifetime extension.



- Complexity in function arguments.
- T& vs. T&& vs. auto&&.
- Temporary lifetime extension.
- Dangling references.



- Complexity in function arguments.
- T& vs. T&& vs. auto&&.
- Temporary lifetime extension.
- Dangling references.
- So much complexity for every language feature that interacts with them.



Parameter passing modes are much better.

- in vs. out vs. inout vs. regular parameters.
- Compiler figures out how to pass stuff.



Hylo: References aren't a thing.

- Value semantics only.
- Pass by reference as parameter passing optimization.
- Subscripts implement "projections".



Hylo: References aren't a thing.

- Value semantics only.
- Pass by reference as parameter passing optimization.
- Subscripts implement "projections".

This is a much cleaner design!



Conclusion



Is this really necessary?

If you want to avoid unnecessary moves yes, you need to::temporary like tracking If you are fine with unnecessary moves no, always decay rvalues



Is this really necessary?

If you want to avoid unnecessary moves yes, you need to::temporary like tracking If you are fine with unnecessary moves no, always decay rvalues

But really: We need different language design.



Bonus: Bells and whistles for max



Bonus: Bells and whistles for max

```
template <typename T, typename U>
auto max(T&& a, U&& b) -> tc::common_reference_t<T, U> {
    return tc_conditional_rvalue_as_ref(
        a < b,
        std::forward<U>(b), std::forward<T>(a)
    );
}
```



Custom predicate

```
template <typename Better, typename T, typename U>
auto best(Better&& better, T&& a, U&& b) -> tc::common_reference_t<T, U> {
    return tc_conditional_rvalue_as_ref(
        better(tc::as_const(b), tc::as_const(a)),
        std::forward<U>(b), std::forward<T>(a)
    );
}
```

Custom predicate

```
template <typename Better, typename T, typename U>
auto best(Better & better, T & a, U & b) -> tc::common_reference_t<T, U> {
    return tc_conditional_rvalue_as_ref(
        better(tc::as_const(b), tc::as_const(a)).
        std::forward<U>(b), std::forward<T>(a)
    );
template <typename T, typename U>
auto max(T&& a, U&& b) -> tc::common_reference_t<T, U> {
    return best(std::greater<>{}, std::forward<T>(a), std::forward<U>(b));
```

Custom predicate

```
template <typename Better, typename T, typename U>
auto best(Better & better, T & a, U & b) -> tc::common_reference_t<T, U> {
    return tc_conditional_rvalue_as_ref(
        better(tc::as_const(b), tc::as_const(a)),
        std::forward<U>(b), std::forward<T>(a)
    );
template <typename T, typename U>
auto max(T&& a, U&& b) -> tc::common_reference_t<T, U> {
    return best(std::greater<>{}, std::forward<T>(a), std::forward<U>(b));
template <typename T, typename U>
auto min(T&& a, U&& b) -> tc::common_reference_t<T, U> {
    return best(std::less<>{}, std::forward<T>(a), std::forward<U>(b));
                                                                            ⊈ ||د
```

```
template <typename Better, typename T, typename U>
    // Requires: Better implements a strict weak ordering.
decltype(auto) best(Better&& better, T&& a, U&& b) {
    auto result = better(tc::as_const(b), tc::as_const(a));
    if constexpr (std::same_as<decltype(result), std::true_type>) {
        return std::forward<U>(b);
    } else if constexpr (std::same_as<decltype(result), std::false_type>) {
        return std::forward<T>(a);
    } else {
        return tc_conditional_rvalue_as_ref(
            result, std::forward<U>(b), std::forward<T>(a)
        );
```

```
#define tc_conditional_rvalue_as_ref(b, lhs, rhs) \
    [&]() -> decltype(auto) { \
        if constexpr (std::same_as<decltype(b), std::true_type>) \
            return lhs; \
        else if constexpr (std::same_as<decltype(b), std::false_type>) \
            return rhs; \
        else \
            return ...; \
}()
```



```
#define tc_conditional_rvalue_as_ref(b, lhs, rhs) \
    [&]() -> decltype(auto) { \
        if constexpr (std::same_as<decltype(b), std::true_type>) \
            return lhs; \
        else if constexpr (std::same_as<decltype(b), std::false_type>) \
            return rhs; \
        else \
            return ...; \
}()
```

But: intermediate stack frame.



```
#define tc_conditional_rvalue_as_ref(b, lhs, rhs) \
    [&]() -> decltype(auto) { \
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            return rhs; \
        else \
            return ...; \
}()
```

But: intermediate stack frame.

Wish list: constexpr ?: or do expressions



```
auto biggest_size = best(
    [](const auto& lhs, const auto& rhs) {
        return std::bool_constant<sizeof(lhs) > sizeof(rhs)>{};
    },
    3.14, "hello world"
);
```



```
template <typename Better, typename T, typename U, typename ... Tail>
    // Requires: Better implements a strict weak ordering.
decltype(auto) best(Better&& better, T&& a, U&& b, Tail&&... tail) {
    auto result = better(tc::as_const(b), tc::as_const(a));
    if constexpr (std::same_as<decltype(result), std::true_type>) {
        return best(better, std::forward<U>(b), std::forward<Tail>(tail)...);
    } else if constexpr (std::same_as<decltype(result), std::false_type>) {
        return best(better, std::forward<T>(a), std::forward<Tail>(tail)...);
    } else {
        return tc_conditional_rvalue_as_ref(result,
            best(better, std::forward<U>(b), std::forward<Tail>(tail)...)
            best(better, std::forward<T>(a), std::forward<Tail>(tail)...)
        );
```

Conclusion

Every problem in C++ can be solved with more C++.

But maybe it shouldn't.

We're hiring: think-cell.com/career/dev

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