

TODO title

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Abstract

Through their interactions, their activities, and even their mere presence, organisms change the environment for themselves and others. This “niche construction” process becomes particularly interesting when it creates evolutionary feedback, whereby selective pressures are altered in response to environmental change. Here we consider how niche construction influences the evolution of cooperation, which has been a long-standing challenge to evolutionary theory. We simulate populations of individuals that cooperatively produce a public good that permits increased growth in a stressful environment and investigate how local- and global-scale niche construction affects the ability of these populations to resist invasion by non-producing cheats. We find that niche construction profoundly impacts the evolution of cooperation by creating new opportunities for adaptation. Cooperators are able to escape subversion by cheats as long as niche construction clears these paths of adaptation. This work provides a crucial step towards understanding how evolution occurs in complex environments like those found in nature.

20 Introduction

21 Cooperative behaviors are common across all branches of the tree of life. In-
22 sects divide labor within their colonies, plants and soil bacteria exchange es-
23 sential nutrients, birds care for others' young, and the trillions of cells in the
24 human body restrain their growth and coordinate to provide vital functions.
25 Each instance of cooperation presents an evolutionary challenge: How can in-
26 dividuals that sacrifice their own well-being to help others avoid subversion by
27 those that do not? Over time, we would expect these *defectors* to rise in abun-
28 dance at the expense of others, eventually driving cooperators—and perhaps
29 the entire population—to extinction.

30 Several factors can defer this potential *tragedy of the commons* (Hamilton,
31 1964; Hardin, 1968; Nowak, 2006; West *et al.*, 2007b). For example, coopera-
32 tors must benefit more from the cooperative act than others. This can occur
33 when cooperators are clustered together in spatially-structured populations
34 (Fletcher and Doebeli, 2009; Nadell *et al.*, 2010; Kuzdzal-Fick *et al.*, 2011) or
35 when cooperators use communication (Brown and Johnstone, 2001; Darch *et*
36 *al.*, 2012) or other cues (Sinervo *et al.*, 2006; Gardner and West, 2010; Veelders
37 *et al.*, 2010) to cooperate conditionally with kin. Interestingly, cooperation can
38 also be bolstered by genetic linkage with self-benefitting traits (Foster *et al.*,
39 2004; Dandekar *et al.*, 2012; Asfahl *et al.*, 2015), setting the stage for an “adap-
40 tive race” in which cooperators and defectors vie for the first highly-beneficial
41 non-social adaptation (Waite and Shou, 2012; Morgan *et al.*, 2012).

42 Hankshaw and Kerr (2015) recently showed that in spatially-structured pop-

43 ulations, cooperators gain a substantial leg up on defectors in an adaptive
44 race when the cooperative behavior increases local population density, thus
45 increasing the likelihood of acquiring beneficial non-social mutations. Never-
46 theless, this advantage is fleeting. As soon as the opportunities for adaptation
47 are exhausted, cooperators are once again at a disadvantage against defectors.
48 However, cooperation can be maintained indefinitely when frequent environ-
49 mental changes produce a stream of non-social adaptive opportunities (**If this**
50 **isn't included in Hankshaw paper, remove this sentence and re-write**
51 **next**). Although natural organisms typically find themselves in changing en-
52 vironments, cooperators may not be able to rely on the the environment to
53 provide sufficient adaptive opportunities for their long-term survival.

54 Here, we extend the model presented in Hankshaw and Kerr (2015) to address
55 whether the selective feedbacks generated by niche construction can act as a
56 source of adaptive opportunities that enables cooperators to persist. In the
57 model, cooperators produce a public good that increases the local carrying
58 capacity for their population. As in Hankshaw and Kerr (2015), populations
59 can also acquire non-social adaptations, which present an opportunity for co-
60 operation to hitchhike along. In our extended model, populations alter their
61 local environments based on the presence of these different non-social adap-
62 tations. As a result, selection for non-social alleles is altered, creating an
63 eco-evolutionary feedback. This has several potential benefits for cooperators.
64 First, because populations of cooperators are larger, they are more likely to
65 gain mutations that are beneficial in the changing environment. Similarly,
66 this difference in size means that larger cooperator populations “export” their

67 niche at a higher rate than defectors. Finally, because each population con-
68 structs a unique niche, the threat of immigrant defectors may be diminished
69 by maladaptation to a cooperator population’s niche.

70 Many instances of cooperatively-produced public goods benefit populations
71 by making the environment more hospitable. For example, bacteria produce
72 a wide variety of exoproducts such as iron-scavenging siderophores (Griffin *et*
73 *al.*, 2004), proteases for protein digestion (Diggle *et al.*, 2007; Darch *et al.*,
74 2012), and many more (West *et al.*, 2007a). TODO little work has examined
75 feedback.

76 Niche construction and cooperation * (Van Dyken and Wade, 2012) *
77 (Lehmann, 2007) * (Platt and Bever, 2009) * (Schwilk and Kerr, 2002) *
78 What’s unique here—hitchhiking aspect

79 Niche construction and selective feedbacks

80 Niche construction and other social interactions

81 **Materials and Methods**

82 We develop a computational model to observe the evolution of public goods
83 cooperation in a spatially-structured metapopulation of populations. As de-
84 scribed below, populations grow to carrying capacity, mutate, and migrate
85 to neighboring patches. During this process, populations adapt to their lo-
86 cal environments. The environments are, in turn, modified by the presence
87 of these adapted individuals, allowing each population to construct a unique

niche along its evolutionary trajectory. Model parameters and their values are listed in Table 1.

Individuals and Fitness

Each individual has a genotype of length $L + 1$. A binary allele at the first locus determines whether or not the individual is a cooperator, which carries cost c . Note that we refer to all individuals with allelic state 0 at this locus as a “defector”, regardless of origin. The remaining L loci are *stress loci*, and are each occupied by a 0 or an integer from the set $A = \{1, \dots, a_{max}\}$, where a_{max} is the number of possible alleles. These alleles represent adaptations to the environment, and the number of loci determines the number of possible adaptations. All non-zero alleles carry fitness benefit δ . Organisms also influence their environment, which can feed back to influence selection. We model this as a form of frequency dependent selection. Specifically, the selective value of stress allele a at locus i increases with the proportion of the population that has allele $a - 1$ (modulo a_{max}) at locus $i - 1$. The slope of this increase is ϵ (which gauges the intensity of niche construction). As a consequence of this form of frequency dependence, genotypes with sequentially increasing allelic states will tend to evolve. Because mutations are random, as described below, each population will evolve sequences that start with different allelic states. These different sequences represent the unique niches constructed by populations. Under this model, the fitness of an individual with genotype g is:

$$W_g = z + a_{g,1}c + \delta \sum_{l=2}^{L+1} I_A(a_{g,l}) + \epsilon \sum_{h=1}^N I_{a_{h,1}}(a_{g,1}) + \epsilon \sum_{l=2}^L n(a_{g,l})$$

110 where $a_{g,l}$ represents the allelic state of genotype g at locus l , z is a baseline
 111 fitness, L is the number of stress loci, N is the population size at that patch,
 112 and c is the cost of the cooperative allele. $I_x(y)$ indicates whether the allelic
 113 state y matches allelic state x (1) or not (0). $n(a_{g,l})$ is the number of individuals
 114 in the population with allelic state at the previous locus equal to one less than
 115 that at the focal locus $a_{g,l}$, or:

$$n(a_{g,l}) = \sum_{h=1}^N I_{a_{g,l}}(1 + a_{h,l-1}(\text{mod } a_{max}))$$

116 Population Growth

117 If p is the proportion of cooperators in a population at the beginning of a
 118 growth cycle, then that population reaches the following size during the growth
 119 phase:

$$S(p) = S_{min} + p(S_{max} - S_{min})$$

120 Therefore, a population composed entirely of defectors reaches size S_{min} , while
 121 one composed entirely of cooperators reaches size S_{max} (with $S_{max} \geq S_{min}$).
 122 The function $S(p)$ gauges the benefit of public good production, as popula-
 123 tion size increases linearly with the proportion of cooperators. During growth,
 124 competition occurs. Consider an arbitrary genotype g . Let n_g be the num-

125 ber of individuals with genotype g , and let W_g be the fitness of genotype g
 126 (see equation [1]). The composition of genotypes after population growth is
 127 multinomial with parameters $S(p)$ and $\{\pi_1, \pi_2, \dots, \pi_{|G|}\}$, where:

$$\pi_g = \frac{n_g W_g}{\sum_{i=1}^G n_i W_i}$$

128 Thus, π_g is the probability that an individual in the population after growth
 129 has genotype g (such that $\sum \pi_g = 1$). G represents the set of all $(a_{max} + 1)^L$
 130 genotypes.

131 Mutation

132 For simplicity, we apply mutation after population growth. These mutations
 133 occur independently at each locus and result in an allelic state change. At the
 134 binary cooperation locus, mutations flip the allelic state at rate μ_c , causing
 135 cooperators to become defectors and vice versa. Mutations at a stress locus
 136 cause a new allelic state to be chosen at random from the set $\{0\} \cup A$. These
 137 mutation occur at each stress locus at rate μ_s . Therefore, the probability that
 138 genotype g mutates into genotype g' is given by:

$$\tau_{g \rightarrow g'} = \mu_s^{H_s(g, g')} (1 - \mu_s)^{\{L - H_s(g, g')\}} \mu_c^{H_p(g, g')} (1 - \mu_c)^{\{1 - H_p(g, g')\}}$$

139 where $H_s(g, g')$ and $H_p(g, g')$ are the Hamming distances between genotypes
 140 g and g' at the stress loci and cooperation locus, respectively. The Hamming
 141 distance is the number of loci at which allelic states differ. Because there is

no inherent relationship among alleles, each of the $a_{max} + 1$ alleles is equally likely to arise via mutation at a given locus.

Migration and Metapopulation Structure

The metapopulation consists of N^2 patches arranged in a $N \times N$ lattice. After mutation, individuals emigrate to an adjacent patch with probability m . This adjacent patch is randomly chosen with uniform probability from the source patch's Moore neighborhood, which is composed of the nearest 8 patches on the lattice. Because the metapopulation lattice has boundaries, patches located on an edge have smaller neighborhoods.

Initialization and Simulation

Metapopulations are initiated in a state that follows the onset of an environmental stress. First, populations are seeded at each patch with cooperator proportion p_0 and grown to density $S(p_0)$. Stress is then introduced by subjecting the population to a bottleneck. The number of survivors with each genotype g is sampled from a binomial distribution, where the number of trials is n_g . The probability of success is μ_t , which represents the likelihood that a mutation occurs that enables survival. Because individuals have not yet adapted to this new stress, the allelic state of each genotype is set to 0 at each stress locus ($\forall g \in G, l \in \{2, \dots, L + 1\} : a_{g,l} = 0$). Following initialization, simulations are run for T cycles, where each cycle consists of growth, mutation, and migration. After migration, populations are thinned to allow for growth in

163 the next cycle. The number of survivors for each genotype g is sampled from
164 a binomial distribution, where the number of trials is n_g and the probability
165 of success is d .

166 Source Code and Software Environment

167 The simulation software and configurations for the experiments reported are
168 available online (Us, 2015). Simulations used Python 3.4.0, NumPy 1.9.1,
169 Pandas 0.15.2 (McKinney, 2010), NetworkX 1.9.1 (Hagberg *et al.*, 2008). Data
170 analyses were performed with R 3.1.3 (R Core Team, 2015).

171 Results

172 results...

173 Discussion

- 174 • summary of results
- 175 • future primacy/recency
 - 176 – Laland et al. (1996)
 - 177 – Lehmann (2007)
- 178 • public goods as niche construction
- 179 • Host symbiont - many instances of cooperation occur among pathogens.

- 180 • future QS or other environmental sensing
- 181 • Facultative cooperation
- 182 – Rodrigues (2012)
- 183 – Dumas and Kümmerli (2010)
- 184 – Kümmerli and Brown (2010)
- 185 – Darch/Diggle
- 186 – QS?
- 187 – Environmental Sensing? # Acknowledgments
- 188 • PRFB
- 189 • BEACON
- 190 • Google
- 191 • Organizers?

¹⁹² **Figures**

Table 1: Model parameters and their value.

Parameter	Description	Base Value
L	Number of Stress Loci	3
a_{max}	Number of alleles	4
δ	Fitness benefit, nonzero alleles	0.5
ϵ	Fitness benefit, sequential alleles	TODO
c	Production Cost	0.1
z	Baseline fitness	1
S_{min}	Minimum Population Size	800
S_{max}	Maximum Population Size	2000
μ_s	Mutation Rate (Stress)	10^{-5}
μ_c	Mutation Rate (Cooperation)	10^{-5}
μ_t	Mutation Rate (Tolerance to New Stress)	10^{-5}
m	Migration Rate	0.05
d	Population Dilution Factor	0.1
N^2	Number of Metapopulation Sites	625
p_0	Initial Cooperator Proportion	0.5
T	Number of Simulation Cycles	TODO

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