

1 Negative Niche Construction Favors the
2 Evolution of Cooperation

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Abstract

By benefitting others at a cost to themselves, cooperators face an ever present threat from defectors—individuals that avail themselves of the cooperative benefit without contributing. A longstanding challenge to evolutionary biology is to understand the mechanisms that support the many instances of cooperation that nevertheless exist. Hammarlund et al. recently demonstrated that, in spatially-structured environments, clustered cooperator populations reach greater densities, which creates more mutational opportunities to gain beneficial non-social adaptations. Cooperation rises in abundance through hitchhiking with these mutations. However, once adaptive opportunities have been exhausted, the ride abruptly ends as cooperators are displaced by adapted defectors. Using an agent-based model, we demonstrate that the selective feedback that is created as populations construct their local niches can maintain cooperation at high proportions, and even allow cooperator invasion in some cases. This cooperator success depends specifically on negative niche construction, which acts as a perpetual source of adaptive opportunities. As populations adapt, they alter their environment in ways that reveal additional opportunities for adaptation. Despite being independent of niche construction in our model, cooperation feeds this cycle. By reaching larger densities, populations of cooperators are better able to adapt to changes in their constructed niche and successfully respond to the constant threat posed by defectors. We relate these findings to previous studies from the niche construction literature and discuss how this model could be extended to provide a greater under-

³⁴ standing of how cooperation evolves in the complex environments in which it
³⁵ is found.

36 Introduction

37 Cooperative behaviors are common across all branches of the tree of life. In-
38 sects divide labor within their colonies, plants and soil bacteria exchange es-
39 sential nutrients, birds care for others' young, and the trillions of cells in the
40 human body coordinate to provide vital functions. Each instance of cooper-
41 ation presents an evolutionary challenge: How can individuals that sacrifice
42 their own well-being to help others avoid subversion by those that do not? Over
43 time, we would expect these *defectors* to rise in abundance at the expense of
44 others, eventually driving cooperators—and perhaps the entire population—to
45 extinction.

46 Several factors can prevent this *tragedy of the commons* (Hamilton, 1964;
47 Nowak, 2006; West *et al.*, 2007b). One such factor involves non-random so-
48 cial interaction, in which cooperators benefit more from the cooperative act
49 than defectors. This can occur when cooperators are clustered together in
50 spatially-structured populations (Fletcher and Doebeli, 2009; Nadell *et al.*,
51 2010; Kuzdzal-Fick *et al.*, 2011), or when cooperators use communication
52 (Brown and Johnstone, 2001; Darch *et al.*, 2012) or other cues (Sinervo *et*
53 *al.*, 2006; Gardner and West, 2010; Veelders *et al.*, 2010) to cooperate condi-
54 tionally with kin. Cooperation can also be bolstered by pleiotropic connections
55 to personal benefits (Foster *et al.*, 2004; Dandekar *et al.*, 2012) or through as-
56 sociation with alleles encoding self-benefitting traits (Asfahl *et al.*, 2015). In
57 the latter case, the associated alleles may provide private benefits that are
58 entirely independent from the public benefits of cooperation. In asexual popu-

lations of cooperators and defectors, this sets the stage for an “adaptive race” in which both types vie for the first highly beneficial adaptation (Waite and Shou, 2012; Morgan *et al.*, 2012). The tragedy of the commons can be deferred if a cooperator, by chance, wins the adaptive race.

Hammarlund *et al.* (2015) recently showed that in spatially-structured populations, the “Hankshaw effect” can give cooperators a substantial leg up on defectors in an adaptive race. Inspired by a fictional character in Tom Robbins’ *Even Cowgirls Get the Blues*, the Hankshaw effect describes how a trait can proliferate by actively creating opportunities to hitchhike along with other highly beneficial traits. In Robbins’ novel, Sissy Hankshaw was born with extremely oversized thumbs. Although her thumbs were an impairment to everyday activities, they made her a prolific hitchhiker. Similarly, cooperative behaviors can enjoy increased opportunities to hitchhike, despite their cost, by increasing their local population density. This makes cooperators more likely to acquire beneficial mutations. By hitchhiking along with these adaptations, cooperation can rise in abundance. Nevertheless, this advantage is fleeting. As soon as the opportunities for adaptation are exhausted, cooperators are once again at a selective disadvantage against adapted defectors that arise via mutation. However, cooperators can maintain their advantage when frequent environmental changes produce a steady stream of new adaptive opportunities (Hammarlund *et al.*, 2015). Although organisms typically find themselves in dynamic environments, the frequency and regularity of these changes might not ensure long-term cooperator survival.

Importantly, organisms do more than passively experience changing environ-

83 ments. Through their activities, their interactions with others, and even their
 84 deaths, organisms continually modify their environment. This *niche construc-*
 85 *tion* process can produce evolutionary feedback loops in which environmental
 86 modification alters selection, which, in turn, alters the distribution of types and
 87 their corresponding influence on the environment (Odling-Smee *et al.*, 2003).
 88 The nature of this feedback can have dramatic evolutionary consequences. One
 89 critical distinction is whether the constructing type is favored in the environ-
 90 ment that it constructs. Under *positive niche construction*, selection favors
 91 the constructor, and evolution stagnates as this type fixes. Whereas under
 92 *negative niche construction*, selection favors a type other than the constructor,
 93 which creates an opportunity for novel adaptation. If the adapted type arises
 94 and also engages in negative niche construction, cycles of construction and
 95 adaptation can ensue, such that populations find themselves endlessly chasing
 96 beneficial mutations as their adaptive landscape continually shifts.

97 Here, we show that the selective feedbacks that result from niche construction
 98 can enable the evolution of cooperation. Further, we find that it is specifically
 99 negative niche construction that is responsible for this result due to the endless
 100 opportunities for adaptation that it produces. Under certain circumstances,
 101 we demonstrate that niche construction can even allow cooperators to invade
 102 established defector populations. These results suggest that by playing an
 103 active role in their own evolution, cooperators can ensure their own survival.

Methods

Building upon Hammarlund *et al.* (2015), we describe an individual-based model in which cooperators and defectors evolve and compete in a population of subpopulations (i.e., a metapopulation). Through mutation, individuals gain adaptations to their environment, which increase reproductive fitness and allow those lineages to rise in abundance. These lineages then spread throughout the population by migration to neighboring subpopulations.

In the expanded model described here, subpopulations also continually modify their local environment. These environmental changes feed back to affect selection. We use this model to explore how niche construction affects the evolution of cooperation; specifically, how cooperative behavior can hitchhike along with adaptations to modified environments.

Model Description

Individual Genotypes and Adaptation

Each individual has a haploid genome with $L + 1$ loci, where integers represent different alleles at each locus (Table 1 lists all model parameters and their values). An allele at the *cooperation locus* (locus zero) determines whether that individual is a cooperator (allele 1), which carries fitness cost c , or a defector (allele 0). The remaining L loci are *adaptive loci*, and are each occupied by a value from the set $\{0, 1, 2, \dots, A\}$, where A is the number of different adaptive alleles possible at each locus.

Allele 0 represents a lack of adaptation, while non-zero alleles signify two types of adaptations, both of which increase fitness. First, adaptations to the *external environment* confer a fitness benefit δ . This selective value is the same regardless of which non-zero allele is present. We assume $\delta > c$, which allows a minimally adapted cooperator to recoup the cost of cooperation and gain a fitness advantage.

Niche Construction and Selective Feedbacks

Individual fitness is also affected by aspects of the local environment that are modified by organisms. This constructed “niche” depends on the specific allelic states present in the subpopulation. As allelic states change, the subpopulation alters its environment in new ways, creating a unique niche. As described below, the specific alleles at each locus become important.

In our model, the feedback that results from niche construction takes the form of density dependent selection, and individuals evolve to better match their constructed niche. We do not represent this niche explicitly, but rather allow the allelic composition of the subpopulation to feed back to affect selection. Specifically, the selective value of non-zero allele a at adaptive locus l —and consequently the fitness of an individual carrying that allele—increases with the number of individuals in the subpopulation that have allele $a - 1$ at locus $l - 1$. For example, if $L = 5$, $A = 6$, and allele 4 has fixed at locus 2, then selection favors genotypes with allele 5 at locus 3. And as allele 5 becomes more abundant at locus 3, the niche that this population constructs will in-

creasingly favor allele 6 at locus 4 (see [Box 1](#)). As a consequence, genotypes with sequentially increasing allelic states will tend to evolve.

We treat both adaptive loci and their non-zero allelic states as “circular”: the selective value of an allele at locus 1 is affected by the allelic composition of the subpopulation at locus L . Similarly, the selective value of allele 1 at any locus increases with the number of individuals carrying allele A at the previous locus. This circularity is represented by the function $\beta(x, X)$, which gives the integer that is below an arbitrary value x in the set $\{1, 2, \dots, X\}$:

$$\beta(x, X) = \text{mod}_X(x - 2 + X) + 1 \quad (1)$$

Here, $\text{mod}_X(x)$ is the integer remainder when dividing x by X . For example, $\beta(3, 5)$ is 2, while $\beta(1, 5)$ is 5. Using this function, the selective value of allele a at adaptive locus l increases by ϵ for each individual in the subpopulation that has allele $\beta(a, A)$ at locus $\beta(l, L)$. Thus, ϵ specifies the intensity of selection due to niche construction.

Individual Fitness

For an individual with allelic state a_l at locus l , fitness is defined as:

$$W = z - \underbrace{ca_0}_{\text{cost of cooperation}} + \underbrace{\delta \sum_{l=1}^L I(a_l)}_{\text{adaptation to external environment}} + \underbrace{\epsilon \sum_{l=1}^L n(\beta(a_l, A), \beta(l, L))}_{\text{adaptation to constructed environment}} \quad (2)$$

where z is a baseline fitness, $n(a, l)$ is the number of individuals in the sub-

163 population with allele a at locus l , and $I(a)$ indicates whether a given allele is
 164 non-zero:

$$I(a) = \begin{cases} 1 & \text{if } a \in \{1, 2, \dots, A\} \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

165 Thus, an individual's fitness is determined both by adaptations to the external
 166 environment and by adaptations to its constructed environment. **Box 1** illus-
 167 trates the process of adaptation to the constructed environment. While the
 168 separation between exogenous and endogenous environmental change may not
 169 always be as clearly differentiated in natural systems, it allows us to directly
 170 explore the effects of niche construction.

171 **Subpopulation Growth and the Benefit of Cooperation**

172 The effects of cooperation are independent of the external and constructed com-
 173 ponents of the environment and do not provide direct fitness benefits (Equation
 174 **2**). Instead, cooperation enables a subpopulation to reach a greater density. If
 175 p is the proportion of cooperators present at the beginning of a growth cycle,
 176 then that subpopulation reaches size $S(p)$, where:

$$S(p) = S_{min} + p(S_{max} - S_{min}) \quad (4)$$

177 S_{min} and S_{max} define the sizes reached by all-defector and all-cooperator sub-
 178 populations, respectively. This benefit affects all individuals equally and accu-

179 mulates linearly with the proportion of cooperators in the subpopulation. We
180 also explore non-linear benefit accumulation in the Supplementary Material.
181 Because cooperators improve group productivity (Equation 4) but decrease in
182 proportion within mixed groups (Equation 2), this form of cooperation would
183 also qualify as “multi-level altruism” (see Supplementary Material and Kerr
184 *et al.* (2004)).

185 Individuals compete as subpopulations grow. Each individual’s probability of
186 reproductive success is proportional to its fitness. The composition of a sub-
187 population with size P and cooperator proportion p after growth is multinomial
188 with parameters $S(p)$ and $\{\pi_1, \pi_2, \dots, \pi_P\}$, where π_i represents the reproduc-
189 tive fitness of individual i relative to others in its subpopulation (Equation
190 2).

191 Mutation

192 For simplicity, we apply mutations to new offspring after subpopulation growth.
193 Mutations occur independently at each locus and cause an allelic state change.
194 At the binary cooperation locus, mutations occur at rate μ_c . These mutations
195 flip the allelic state, causing cooperators to become defectors and vice versa.
196 Mutations occur at rate μ_a at each adaptive locus. These mutations replace
197 the existing allele with a value randomly sampled from the set $\{0, 1, \dots, A\}$.

198 Migration

199 Populations consist of N^2 patches arranged as an $N \times N$ lattice, where each
200 patch can support a subpopulation. After mutation, individuals emigrate to
201 an adjacent patch. This process is unaffected by fitness. For each source
202 subpopulation, a single destination patch is randomly chosen from the source
203 patch's Moore neighborhood, which encompasses the nearest 8 patches on the
204 lattice. Because the population lattice has boundaries, patches located on the
205 periphery have smaller neighborhoods. Individuals emigrate with probability
206 m , which means larger subpopulations produce more emigrants. Through
207 immigration, subpopulations can exceed S_{max} individuals. As described below,
208 however, this increase in population size is temporary.

209 Population Initialization and Simulation

210 Following Hammarlund *et al.* (2015), we begin simulations with sparse pop-
211 ulations. Subpopulations are first seeded at all patches with cooperator pro-
212 portion p_0 and size $S(p_0)$. The population is then thinned. Each individual
213 survives this bottleneck with probability σ_i . Starting from this initial state,
214 simulations then proceed for T cycles, where each discrete cycle consists of
215 subpopulation growth, mutation, migration, and dilution. Dilution reduces
216 each subpopulation to support growth in the next cycle. Each individual sur-
217vives dilution with probability σ_d , regardless of its genotype. Dilution remains
218 the same for each of the simulations described, however we further explore its
219 effects in the Supplementary Material.

220 **Simulation Source Code and Software Dependencies**

221 The simulation software and configurations for the experiments reported are
222 available online (Connelly *et al.*, 2015). Simulations used Python 3.4, NumPy
223 1.9.1, Pandas 0.15.2 (McKinney, 2010), and NetworkX 1.9.1 (Hagberg *et al.*,
224 2008). Data analyses were performed with R 3.2.2 (R Core Team, 2015).
225 Reported 95% confidence intervals were estimated by bootstrapping with 1000
226 resamples.

227 **Results**

228 Using the model described in the previous section, we perform simulations
229 that follow the evolution of cooperation in a population of subpopulations
230 that are connected by spatially-limited migration. Individuals increase their
231 competitiveness by gaining adaptations. While cooperation does not directly
232 affect the fitness benefits that these adaptations confer, it does have indirect
233 effects on the adaptive process. Specifically, cooperation increases subpopula-
234 tion density. As a result, larger subpopulations of cooperators experience more
235 mutational opportunities. Cooperation can rise in abundance by hitchhiking
236 along with beneficial mutations, which compensate for the cost of cooperation.
237 Importantly, subpopulations alter their local environments, which feeds back
238 to influence selection. Here, we explore how such niche construction affects
239 the evolution of cooperation.

Cooperation Persists with Niche Construction

Without any opportunity for adaptation ($L = 0$), cooperators are swiftly eliminated (Figure 1A). Despite an initial lift in cooperator abundance due to increased productivity, the cost of cooperation becomes disadvantageous as migration mixes the initially isolated subpopulations. When populations can adapt to the external environment ($L > 0$ and $\delta > 0$), but niche construction is absent ($\epsilon = 0$), cooperators are maintained only transiently (Figure 1B). Here, larger cooperator subpopulations adapt more quickly to their external environment, which allows them to rise in abundance. As previously described by Hammarlund *et al.* (2015), cooperation is swiftly lost once populations become fully adapted. This occurs when isogenic defectors (i.e., defectors with identical adaptive loci) arise via mutation and displace cooperators due to their selective advantage. However, when niche construction feeds back to influence selection ($\epsilon > 0$), cooperation persists in the majority of replicate populations (Figure 1C). We see in Figure 2A that despite some oscillations, cooperation is maintained at high levels in the majority of these populations.

Fitness Increases Alone do not Support Persisting Cooperation

An individual's fitness is affected in this model by adaptations to both the external environment and to the constructed environment. Here, we determine whether cooperation is maintained as we see in Figure 2A solely due to the larger selective values that result from the contributions of niche con-

struction. We performed simulations in which these selective contributions were transferred to supplement the benefits conferred by adaptation to the external, non-constructed environment (i.e., replacing $\epsilon = 0.3$, $\delta = 0.3$ with $\epsilon = 0$, $\delta = 0.6$). In doing so, we conservatively estimate the selective effects of niche construction. Nevertheless, we find that simply increasing selective values extends the maintenance of cooperation, but does not enable cooperators to persist (Figure 2B). Niche construction, therefore, plays a decisive role here.

Negative Niche Construction is Critical to Cooperator Persistence

In our model, an adaptation to the constructed environment initiates a new instance of niche construction, leading to sequentially increasing allelic states across the adaptive loci. Under certain conditions, this construction always makes the constructor sub-optimal for the niche it creates. This form of negative niche construction occurs when the number of adaptive alleles (A) does not divide evenly into the number of adaptive loci (L). In such a case, any sequence of integers on the circular genome will always contain a break in the sequence; that is, one locus will perpetually have an allele that is not one less than the allele at the next locus (see Box 1, Part D). Given this unavoidable mismatch, types will always construct a niche in which selection for a different type is enhanced. When negative niche construction is removed (by setting $L = 5$, $A = 5$; see Box 1, Part C), cooperators are again driven to extinc-

tion after an initial lift in abundance (Figure 2C). Here, a fully-adapted type constructs a niche that favors itself. When this occurs, a fully-adapted cooperator is at a selective disadvantage against a fully-adapted defector, which does not incur the cost of cooperation. These results indicate that the type of niche construction matters. Specifically, negative niche construction is key for maintaining cooperation by the Hawkshaw effect. Here, cooperators prevent defector invasion by hitchhiking along with adaptations to the constructed environment.

Selective Feedbacks Limit Defector Invasion

The process of adaptation to the constructed niche can limit invasion by defectors, which arise either through migration from neighboring patches or through mutation at the cooperation locus. This latter challenge is particularly threatening, as these isogenic defectors are equally adapted, yet do not incur the cost of cooperation. As demonstrated in Figure 3A, when adaptation to the environment cannot occur, isogenic defectors rapidly invade when introduced as a single subpopulation in the center of a population of otherwise all-cooperator subpopulations. However, cooperators resist defector invasion in over half of the replicate populations when adaptations can arise through mutation (Figure 3B). Figure 4 depicts one such instance. In that population, isogenic defectors are seeded at a single patch in an otherwise all-cooperator population. These defectors quickly begin to spread. However, a neighboring cooperator population gains an adaptation, which increases its fitness above that of the defector.

306 This type spreads more quickly, stopping the spread of defectors and eventu-
307 ally driving them to extinction. Because this adaption arises in a cooperator
308 population, cooperation is able to hitchhike to safety. Importantly, this new
309 cooperator type is favored because of the niche that its ancestral type—and
310 therefore also the defector—constructed. Here, cooperators can find safety in
311 numbers: because their larger subpopulations have more mutational opportu-
312 nities, they are more likely to gain adaptations that rescue them from invasion.
313 Further, these larger cooperator subpopulations exert greater influence on their
314 niches, which increases selection for an adapted type. This allows that type to
315 appear and to spread more quickly in the population. **Figure 3C** shows how
316 quickly an adapted cooperator type can invade a population of defectors.

317 **Negative Niche Construction can Promote Cooperator** 318 **Invasion**

319 The majority of the results shown above have focused on the maintenance
320 of cooperation. Specifically, cooperators have started at—and maintained—
321 reasonably high proportions in their populations. In the previous section, we
322 considered cooperator invasion; however, cooperators began in their own single
323 subpopulation without defectors. It remains to be seen whether cooperators
324 can invade from extreme rarity. In a population in which cooperators are ini-
325 tially absent, can cooperators that arise by mutation increase in frequency?
326 With baseline parameters (**Table 1**), cooperators tend not to invade over 3000
327 cycles when the initial cooperator proportion is low (see Supplemental Materi-

als). However, when the benefits of cooperation are increased ($S_{max} = 8000$), cooperators can readily invade and reach high proportions (Figure 5A). Despite this large benefit, cooperator success still depends on the presence of niche construction. Without the selective effects that negative niche construction continually exerts, cooperators cannot invade (Figure 5B).

Discussion

Despite their negative effects, deleterious traits can rise in abundance through genetic linkage with other traits that are strongly favored by selection (Hartfield and Otto, 2011). The role of hitchhiking in the evolution cooperation has been explored experimentally and theoretically (Schwilk and Kerr, 2002; Santos and Szathmary, 2008; Morgan *et al.*, 2012; Waite and Shou, 2012; Asfahl *et al.*, 2015; Wilder and Stanley, 2015). In a process termed the “Hankshaw effect”, Hammarlund *et al.* (2015) recently demonstrated that traits such as cooperation and spite can actively prolong their existence by increasing their likelihood of hitchhiking with a beneficial trait. In that work and here, subpopulations of cooperators grow to a higher density than those of defectors. These larger subpopulations are more likely to gain adaptations as a result of this increase in growth and the corresponding mutational opportunities. Although this process favors cooperation in the short term, it eventually reaches a dead end: When the opportunities for adaptation are exhausted, and cooperators can no longer hitchhike, they face extinction. Here, we have investigated whether niche construction might serve to perpetually generate new adaptive

350 opportunities and thus favor cooperation.

351 When niche construction occurs, cooperation can indeed persist (Figures 1C
352 and 2A). In our model, niche construction introduces additional selective ef-
353 fects that influence the evolutionary process, leading to a more pronounced
354 Hankshaw effect. However, these fitness benefits alone do not maintain co-
355 operation (Figure 2B). Niche construction and the selective feedbacks that it
356 produces play a crucial role.

357 We find that it is specifically *negative* niche construction that maintains coop-
358 eration (Figure 2C) and even can support invasion by cooperators (Figure 5A).
359 As cooperator and defector types gain adaptations, they alter their environ-
360 ment in ways that favor other types. Thus, negative niche construction serves
361 as a perpetual source of adaptation. Here we observe another facet of the
362 Hankshaw effect: Because subpopulations of cooperators are larger, they are
363 better able to respond to the adaptive opportunities that they create through
364 negative niche construction. By gaining adaptations more quickly, cooperators
365 resist invasion by defectors (Figure 3B). Even in the presence of an isogenic de-
366 fector type, cooperator subpopulations are more likely to produce the mutant
367 most adapted to the current constructed niche, which can then displace the
368 slower-adapting defectors. These recurring cycles of defector invasion and co-
369 operator adaptation underlie the oscillations in cooperator proportion seen in
370 Figure 2A. Mutation is still a stochastic process, cooperators lose the adaptive
371 race and are driven to extinction when defectors gain these adaptations first.
372 We see this occur occasionally in Figures 2A and 3B. However, under other
373 parameter settings within our model, it is possible for cooperaors at extremely

low abundances to later re-emerge and invade (Figure 5A). In these instances, negative niche construction provides continual opportunities for cooperators to dominate.

Cooperation as Niche Construction

In our model, niche construction and adaptation are independent of cooperation, which allows us to focus on hitchhiking. However, individuals often cooperate in ways that alter the environment. These cooperative behaviors, therefore, can themselves be seen as niche construction. For example, bacteria produce a multitude of extracellular products that scavenge soluble iron (Griffin *et al.*, 2004), digest large proteins (Diggle *et al.*, 2007; Darch *et al.*, 2012), and reduce the risk of predation (Cosson *et al.*, 2002), among many others (West *et al.*, 2007a). As in our model, these forms of cooperation are likely to increase local subpopulation density. While many studies have focused on how the environment affects the evolution of these cooperative traits, relatively few have addressed how the environmental changes created by these products feed back to influence evolution.

Perhaps most similar to this study, Van Dyken and Wade (2012) demonstrated that when two negative niche constructing, cooperative behaviors co-evolve, selection can increasingly favor these traits, which are otherwise disfavored when alone. In that model, “reciprocal niche construction” occurred when the negative feedback resulting from one strategy positively influenced selection for the other, creating a perpetually oscillating cycle that maintained both

396 forms of cooperation. Arguably, this can be seen as an instance of hitchhiking:
397 The currently-maladaptive form of cooperation is maintained by association
398 with the adaptive form.

399 When dispersal is limited, competition among kin can undermine cooperation.
400 To separate kin competition from kin selection, Lehmann (2007) developed
401 a model in which a cooperative, niche-constructing behavior only benefitted
402 future generations. Kin competition was thereby reduced, and cooperation
403 instead benefitted descendants. This work highlights an important aspect of
404 niche construction: Often, the rate of selective feedback from niche construc-
405 tion is different from the rate at which populations grow.

406 **Evolution at Multiple Timescales**

407 In our work, the niche is modeled implicitly by the composition of the sub-
408 population. Any changes in the subpopulation, therefore, produce immediate
409 effects on the constructed environment and the resulting selective feedbacks.
410 However, timescales in our model could be de-coupled in two ways. First, co-
411 operators modify their niche by enabling their subpopulation to reach larger
412 density (Equation 4). These increased subpopulation sizes play a critical role
413 by effectively increasing the rate of evolution in these subpopulations. Because
414 of the importance of this process, it would be very informative to explore how
415 sensitive our results are to the rate at which cooperators increase subpopulation
416 sizes and the rate at which this benefit decays in the absence of cooperators.
417 Similarly, our results could be substantially affected by alterations in the rate

418 at which the constructed environment changes in response to changes in the
419 subpopulation.

420 Other studies, while not focused on cooperation, have similarly shown that the
421 timescales at which niche construction feedbacks occur can strongly influence
422 evolutionary outcomes (Laland *et al.*, 1996, 1999). This perspective may be
423 crucial for understanding the evolution of cooperative behaviors like the pro-
424 duction of public goods. In these instances, environmental changes are likely
425 to occur on different timescales than growth, which can have profound effects.
426 For example, a multitude of factors, including protein durability (Brown and
427 Taddei, 2007; Kümmerli and Brown, 2010), diffusion (Allison, 2005; Driscoll
428 and Pepper, 2010), and resource availability (Zhang and Rainey, 2013; Ghoul
429 *et al.*, 2014) influence both the rate and the degree to which public goods
430 alter the environment. While Lehmann (2007) showed that cooperation was
431 favored when selective feedbacks act over longer timescales, niche construction
432 may in fact hinder cooperation when selection is more quickly altered. For ex-
433 ample, when public goods accumulate in the environment, cooperators must
434 decrease production to remain competitive (Kümmerli and Brown, 2010; Du-
435 mas and Kümmerli, 2012). This favors cooperation that occurs facultatively,
436 perhaps by sensing the abiotic (Bernier *et al.*, 2011; Koestler and Waters, 2014)
437 or biotic environment (Brown and Johnstone, 2001; Darch *et al.*, 2012). To
438 study how regulatory traits such as these evolve, we could instead represent
439 the niche explicitly, allowing it to have its own dynamics. A representation
440 in which the “niche” is simultaneously influenced by external forces and the
441 actions of organisms would more closely resemble many natural systems.

Cooperation and Niche Construction in Host-Symbiont Co-Evolution

In many biological systems, the environments modified by organisms are themselves other organisms. In these instances, the “niche” becomes a biological entity with its own evolutionary process. A logical extension to our model would be to treat the environment as an organism. Such a model could be used to explore the evolution of cooperation in host-symbiont systems, where cooperation among symbionts affects host fitness. As the host population changes, either in response to symbiont cooperation or other factors, so too does selection on their symbiont populations. In our model, each patch could become hosts with their own genotypes, and death and reproduction at the host level could be defined in ways that are sensitive to both host and symbiont genotypes. Here, evolutionary outcomes depend greatly on the degree of shared interest between the host and symbiont.

Of particular importance are cases where the interests of host and symbiont are in conflict. By selecting for new, more resistant host genotypes or by provoking a specific immune response, pathogens make their host environment less hospitable and can therefore be seen as potent negative niche constructors. The results that we have presented here suggest that such negative niche construction can perhaps favor cooperative behavior among these symbiont pathogens. This may be especially relevant when infection is mediated by cooperative behaviors. For example, the cooperative production of several public goods by the pathogenic bacterium *Pseudomonas aeruginosa* facilitate infection in hosts

465 with cystic fibrosis (Harrison, 2007). Models such as what we have described
466 may permit exploration into how cooperation and niche construction intersect
467 in these and other medically-relevant instances.

468 More generally, it was recently argued that incorporating the effects of niche
469 construction is critical for improving our understanding of viral evolution
470 (Hamblin *et al.*, 2014) and evolution in co-infecting parasites (Hafer and Milin-
471 ski, 2015). Incorporating host dynamics, transmission, co-evolution, and the
472 feedbacks that they produce is likely to be equally important for gaining
473 a greater understanding of how cooperative behaviors evolve in these host-
474 symbiont settings.

475 **Summary**

476 We have previously shown that a combination of non-social adaptation and
477 population structure can favor the evolution of cooperation (Hammarlund *et*
478 *al.* (2015)). However, this “Hankshaw effect” was transient; without con-
479 tinual opportunities for adaptation (e.g., a changing environment), defectors
480 eventually dominate. Here, we explore one source for such continual oppor-
481 tunities: negative niche construction. Specifically, the process of adaptation
482 creates opportunities for further adaptation through selective feedback. In our
483 model, the active role of the organism is paramount; not only does coopera-
484 tive behavior make hitchhiking more likely, given adaptive opportunities, but
485 these adaptive opportunities themselves are continually generated through the
486 effects organisms have on their environment.

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Box 1: Description of niche construction in our model

See [Figure B1](#)

(A) Individuals. The genome of each individual consists of a single *cooperation locus* and L *adaptive loci* (here, $L = 5$). At the cooperation locus (labeled 0), this individual has allele 1, making it a cooperator. The adaptive loci (labeled 1 - 5) are arranged as a circular chromosome, where each locus has an integer allele between 0 and A , inclusive. In the description that follows, we focus exclusively on these adaptive loci. Genotypes are given by their allelic states starting with locus 1 . For instance, the genotype shown here is $[2,0,5,2,1]$. Because of their circular structure, allele 2 at the first locus follows allele 1 at the fifth locus.

(B) Niche Construction. Consider a subpopulation fixed for genotype $[1,2,0,0,0]$. This subpopulation constructs environment $E_{[1,2,0,0,0]}$. Every non-zero allele influences selection at the next locus, favoring sequential allelic states. In this constructed environment, allele 3 at locus 3 would be favored. If genotype $[1,2,3,0,0]$ arises via mutation, it is expected to fix. However, genotype $[1,2,3,0,0]$ affects the environment differently. As $[1,2,3,0,0]$ rises in abundance, the constructed environment changes to $E_{[1,2,3,0,0]}$, which favors $[1,2,3,4,0]$.

(C) Niche Construction and Adaptation. The evolutionary transition shown in Part B is indicated in the dashed box. Here, we depict entire sub-

520 populations fixed for a genotype using a single instance of that genotype. Simi-
 521 larly, an arrow represents niche construction and adaptation to the constructed
 522 environment. We start with a case in which there are five alleles ($A = 5$). Sub-
 523 populations begin with the non-adapted genotype $[0,0,0,0,0]$, shown on the far
 524 left. A non-zero allele is introduced via mutation, which represents an adapta-
 525 tion to external aspects of the environment. Here, allele 1 arises and fixes at
 526 locus 1. The remainder of this figure focuses on adaptation to the constructed
 527 aspects of the environment. This genotype has a mismatch (shown by the red
 528 sector), because $E_{[1,0,0,0,0]}$ favors $[1,2,0,0,0]$. Assuming allele 2 arises at the
 529 second locus, it will be selected, creating a match at the first and second loci
 530 (green sector). Now there is a mismatch between the second and third loci
 531 in the resulting environment, which a new round of mutation and selection
 532 corrects, and so on. The green sector grows as the red sector shifts clockwise.
 533 When the population reaches $[1,2,3,4,5]$, it constructs $E_{[1,2,3,4,5]}$. Here, since
 534 allele 1 follows allele 5, there is no longer a mismatch, so no further adaptation
 535 occurs.

536 **(D) Negative Niche Construction.** A different case emerges when the num-
 537 ber of alleles does not evenly divide into the number of loci. Here, we change
 538 the number of alleles to six ($A = 6$). As shown on the far left, we begin with
 539 a subpopulation fixed for genotype $[1,2,3,4,5]$. This genotype has a mismatch,
 540 because the niche constructed by allele 5 favors allele 6 (not 1) at the next
 541 locus (locus 1). A mutant with genotype $[6,2,3,4,5]$ has a fitness advantage
 542 and can fix in $E_{[1,2,3,4,5]}$. However, as this type constructs $E_{[6,2,3,4,5]}$, a new
 543 mismatch appears. In this instance of negative niche construction, adapting

544 to correct one mismatch generates a new mismatch. This system can never
545 escape its mismatches—the red sector just shifts clockwise around the genome
546 perpetually. We call this negative niche construction, as the actions of con-
547 structors increase the fitness of a different genotype and thereby lower their
548 own relative fitness.

549 Figures

550 **Figure 1**

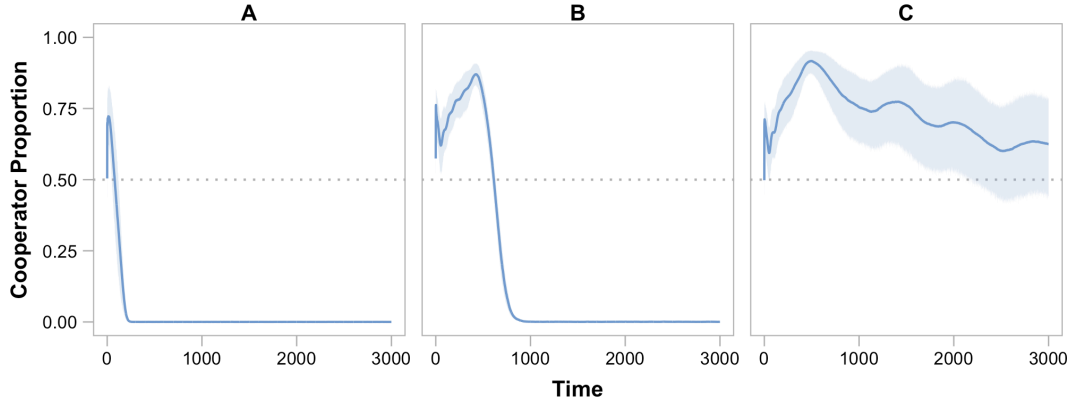


Figure 1: **Adaptation and the Evolution of Cooperation.** The average cooperator proportion among replicate populations for the duration of simulations are shown as curves, and shaded areas indicate 95% confidence intervals. (A) Without any opportunity to adapt ($L = 0$), cooperation is quickly lost. (B) When adaptation can occur ($L = 5$, $\delta = 0.3$), but niche construction does not affect selection ($\epsilon = 0$), cooperators rise in abundance by hitchhiking along with adaptations to the external environment. Nevertheless, this effect is transient, and defectors eventually dominate. (C) Niche construction ($\epsilon = 0.00015$) enables cooperation to be maintained in the majority of populations. Figure 2A shows the individual trajectories of these populations.

Figure 2

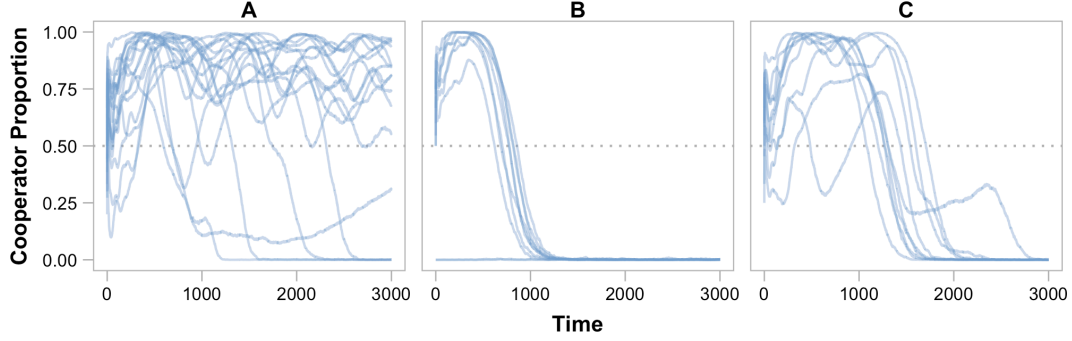


Figure 2: **Niche Construction and the Evolution of Cooperation.** The proportion of cooperators present in each replicate population is shown for the duration of simulations. **(A)** Despite some oscillation, cooperators dominate in 13 of 18 populations when niche construction affects selection. **(B)** When the selective effects of niche construction are transferred to supplement the benefits conferred by adaptation to the external, non-constructed environment, cooperators are driven to extinction by defectors (replacing $\epsilon = 0.3$, $\delta = 0.3$ with $\epsilon = 0$, $\delta = 0.6$). Note that cooperation was not present after initialization in one replicate population. **(C)** Cooperators are also driven to extinction without negative niche construction ($A = 5$).

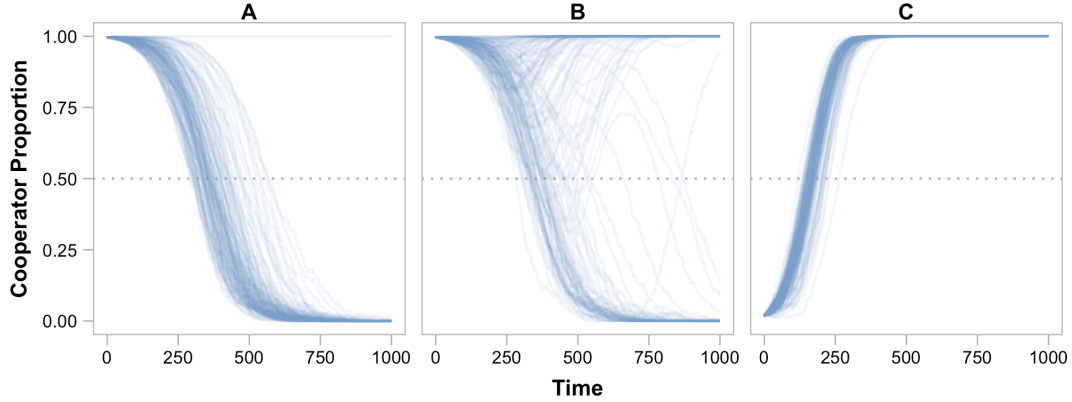
Figure 3

Figure 3: Niche Construction and Invasion. The proportion of cooperators present in each replicate population is shown for the duration of simulations ($T = 1000$). In each simulation, a rare type was initiated at a single patch in the center of the population lattice ($N^2 = 121$). Unless otherwise noted, mutations are disabled in these ecological simulations to highlight the dynamics of invasion ($\mu_a = 0, \mu_c = 0$). **(A)** When cooperators and defectors are isogenic (i.e., both types have stress alleles [1,2,3,4,5]), rare defectors quickly invade and drive cooperators to extinction due to the cost of cooperation. Note that defectors were stochastically eliminated in two replicate populations. **(B)** However, when populations can adapt, negative niche construction creates adaptive opportunities that enable cooperators to resist invasion by isogenic defectors. When adaptive mutations occur ($\mu_a = 0.00005$), cooperation remained dominant in 91 of 160 populations. Results from simulations where mutations also occurred at the cooperation locus are shown in Figure S8. **(C)** In fact, a cooperator (stress alleles [6,2,3,4,5], see Box 1) that is adapted to the niche constructed by the defectors can swiftly displace defectors.

553 **Figure 4**

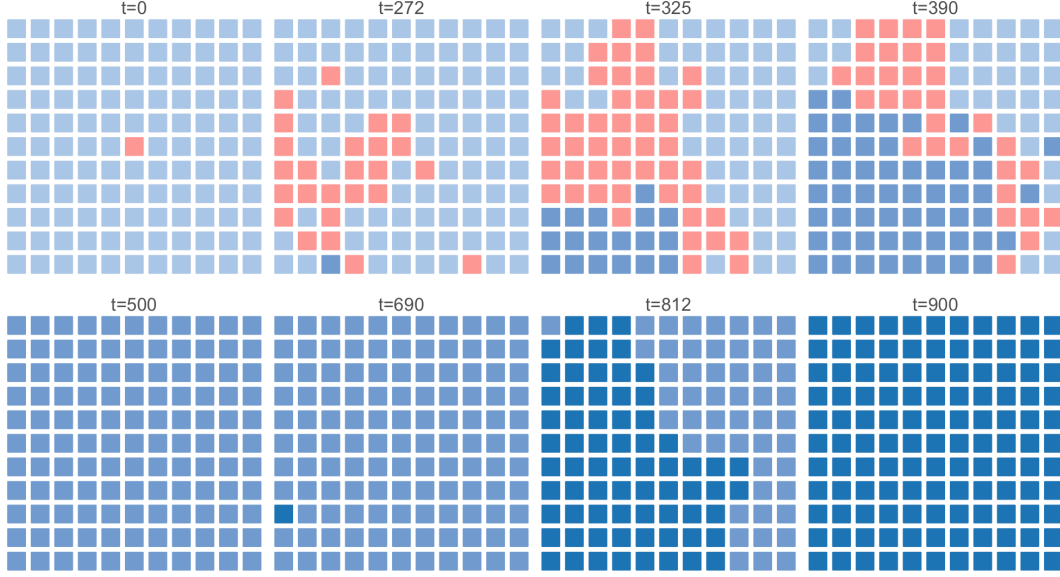


Figure 4: **Cooperator Adaptation Prevents Defector Invasion.** The spatial distribution of dominant types within each subpopulations is shown at different time points for one representative simulation in which isogenic defectors arise. To highlight the effects of adaptation, mutations did not occur at the cooperation locus ($\mu_c = 0$). At time $t = 0$ (upper left panel), a single isogenic defector subpopulation (red) is placed within an all-cooperator population (light blue). Because these defectors do not bear the cost of cooperation, they quickly spread ($t = 272$). However, cooperators in one subpopulation gain an adaptation that gives them a fitness advantage over defectors (second panel, medium blue, lower left). At $t = 325$, defectors continue to invade cooperator subpopulations. However, the adapted cooperator type spreads more quickly due to its fitness advantage, invading both defector and ancestral cooperator subpopulations ($t = 390$), until it eventually fixes in the population ($t = 500$). At $t = 690$, a new cooperator type emerges that is favored in the constructed niche (dark blue). This new type spreads rapidly ($t = 812$) until reaching fixation ($t = 900$). At this point, it becomes susceptible to invasion by the next “adapted” cooperator type, and the cycle continues.

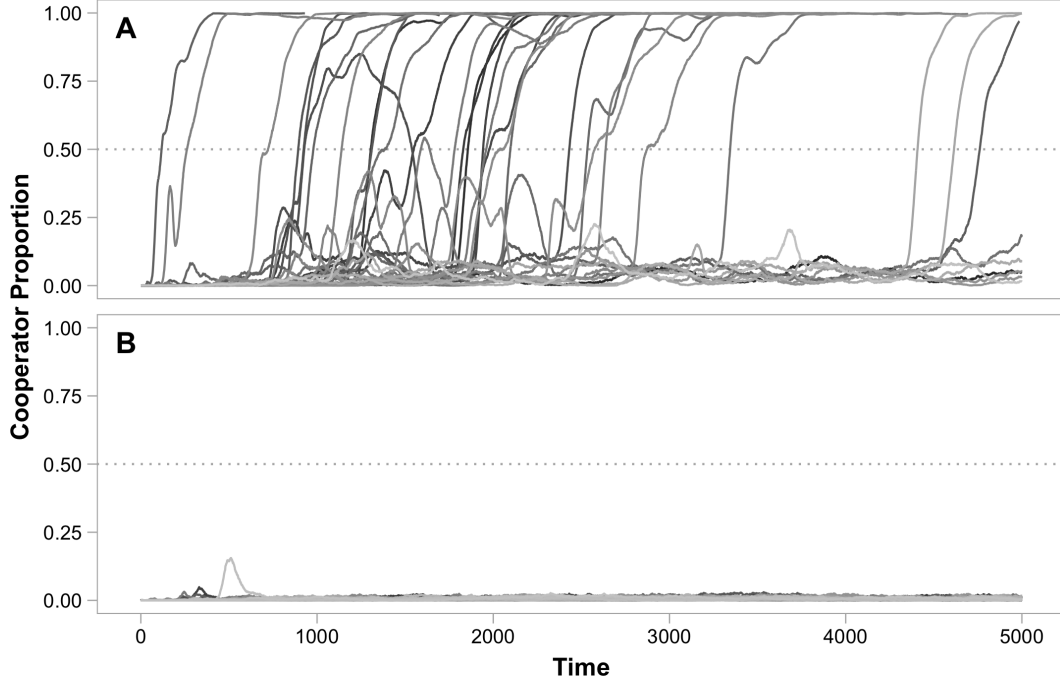
Figure 5

Figure 5: Niche Construction and the Invasion of Cooperation. The proportion of cooperators present in each of 50 replicate populations is shown for the duration of simulations ($T = 5000$). Baseline parameters are used, except for $S_{max} = 8000$, and the initial proportion of cooperators in each population is zero ($p_0 = 0$), which requires cooperators to arise via mutation. **(A)** Cooperators invade and reach very high proportions when niche construction affects selection (50 replicates shown). **(B)** Without niche construction ($\epsilon = 0$), cooperators do not invade (50 replicates shown).

555 **Box 1 Figures**

556 **Figure B1**

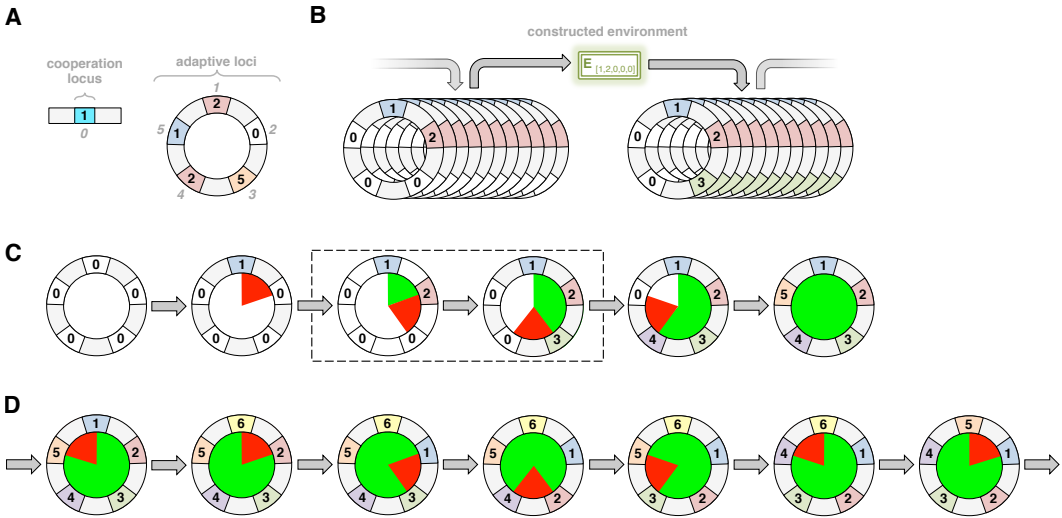


Figure B1: Figure for Box 1

Tables

Table 1: Model parameters and their values

Parameter	Description	Base Value	Alternate Values
L	Number of adaptive loci	5	0
c	Cost of cooperation	0.1	
A	Number of alleles	6	5, 6
δ	Benefit of adaptation to external environment	0.3	0, 0.6
ϵ	Benefit of adaptation to constructed environment	0.00015	0
z	Baseline fitness	1	
S_{min}	Minimum subpopulation size	800	
S_{max}	Maximum subpopulation size	2000	8000
μ_c	Mutation rate at cooperation locus	10^{-5}	0
μ_a	Mutation rate at adaptive loci	10^{-5}	0
N^2	Number of patches	625	625
m	Migration rate	0.05	
p_0	Initial cooperator proportion	0.5	0, 0.01, 0.1, 0.2, 0.3, 0.9, 0.99, 1*
σ_i	Survival rate at population initialization	10^{-5}	
T	Number of simulation cycles	3000	1000, 5000
σ_d	Survival after dilution	0.1	0.01, 0.3, 0.5, 0.7, 0.9*
γ	Slope of cooperative benefit*	1.0	0.25, 0.5, 1.5, 2, 4

* See Supplementary Material

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