

1 Negative Niche Construction Favors the
2 Evolution of Cooperation

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11 Abstract

12 By benefitting others at a cost to themselves, cooperators face an ever present
13 threat from defectors—individuals that avail themselves of the cooperative ben-
14 efit without contributing. A longstanding challenge to evolutionary biology is
15 to understand the mechanisms that support the many instances of coopera-
16 tion that nevertheless exist. Hammarlund et al. recently demonstrated that
17 cooperation can persist by hitchhiking along with beneficial non-social adapta-
18 tions. Importantly, cooperators play an active role in this process. In spatially-
19 structured environments, clustered cooperator populations reach greater densi-
20 ties, which creates more mutational opportunities to gain beneficial non-social
21 adaptations. Cooperation rises in abundance by association with these adap-
22 tations. However, once adaptive opportunities have been exhausted, the ride
23 abruptly ends as cooperators are displaced by adapted defectors. Using an
24 agent-based model, we demonstrate that the selective feedback that is created
25 as populations construct their local niches can maintain cooperation indefi-
26 nitely. This cooperator success depends specifically on negative niche con-
27 struction, which acts as a perpetual source of adaptive opportunities. As
28 populations adapt, they alter their environment in ways that reveal additional
29 opportunities for adaptation. Despite being independent of niche construction
30 in our model, cooperation feeds this cycle. By reaching larger densities, popu-
31 lations of cooperators are better able to adapt to changes in their constructed
32 niche and successfully respond to the constant threat posed by defectors. We
33 relate these findings to previous studies from the niche construction literature

³⁴ and discuss how this model could be extended to provide a greater under-
³⁵ standing of how cooperation evolves in the complex environments in which it
³⁶ is found.

37 Introduction

38 Cooperative behaviors are common across all branches of the tree of life. In-
39 sects divide labor within their colonies, plants and soil bacteria exchange es-
40 sential nutrients, birds care for others' young, and the trillions of cells in the
41 human body coordinate to provide vital functions. Each instance of cooper-
42 ation presents an evolutionary challenge: How can individuals that sacrifice
43 their own well-being to help others avoid subversion by those that do not? Over
44 time, we would expect these *defectors* to rise in abundance at the expense of
45 others, eventually driving cooperators—and perhaps the entire population—to
46 extinction (note that some refer to these costly social behaviors as “altruism”
47 (Kerr *et al.*, 2004; West *et al.*, 2007c)).

48 Several factors can prevent this *tragedy of the commons* (Hamilton, 1964;
49 Nowak, 2006; West *et al.*, 2007b). One such factor involves non-random so-
50 cial interaction, in which cooperators benefit more from the cooperative act
51 than defectors. This can occur when cooperators are clustered together in
52 spatially-structured populations (Fletcher and Doebeli, 2009; Nadell *et al.*,
53 2010; Kuzdzal-Fick *et al.*, 2011) or when cooperators use communication
54 (Brown and Johnstone, 2001; Darch *et al.*, 2012) or other cues (Sinervo *et*
55 *al.*, 2006; Gardner and West, 2010; Veelders *et al.*, 2010) to cooperate condi-
56 tionally with kin. Cooperation can also be bolstered by pleiotropic connections
57 to personal benefits (Foster *et al.*, 2004; Dandekar *et al.*, 2012) or through as-
58 sociation with alleles encoding self-benefitting traits (Asfahl *et al.*, 2015). In
59 the latter case, the associated alleles may provide private benefits that are

entirely independent from the public benefits of cooperation. In asexual populations of cooperators and defectors, this sets the stage for an “adaptive race” in which both types vie for the first highly beneficial adaptation (Waite and Shou, 2012; Morgan *et al.*, 2012). The tragedy of the commons can be deferred if a cooperator, by chance, wins the adaptive race.

Hammarlund *et al.* (2015) recently showed that in spatially-structured populations, the “Hankshaw effect” can give cooperators a substantial leg up on defectors in an adaptive race. Inspired by a fictional character in Tom Robbins’ *Even Cowgirls Get the Blues*, the Hankshaw effect describes how costly traits can be maintained by actively creating opportunities to hitchhike along with highly beneficial traits. Sissy Hankshaw was born with extremely oversized thumbs. Although her thumbs were an impairment to everyday activities, they made her a prolific hitchhiker. Similarly, cooperation is costly, but it increases local population density. As a result, cooperators are more likely to acquire beneficial mutations. By hitchhiking along with these adaptations, cooperation can rise in abundance. Nevertheless, this advantage is fleeting. As soon as the opportunities for adaptation are exhausted, cooperators are once again at a selective disadvantage against adapted defectors that arise via mutation. However, cooperation can be maintained when frequent environmental changes produce a steady stream of new adaptive opportunities (Hammarlund *et al.*, 2015). Although organisms typically find themselves in dynamic environments, the frequency and regularity of these changes might not ensure long-term cooperator survival.

Importantly, organisms do more than passively experience changing environ-

84 ments. Through their activities, their interactions with others, and even their
 85 deaths, organisms continually modify their environment. This *niche construc-*
 86 *tion* process can produce evolutionary feedback loops in which environmental
 87 modification alters selection, which, in turn, alters the distribution of types and
 88 their corresponding influence on the environment (Odling-Smee *et al.*, 2003).
 89 The nature of this feedback can have dramatic evolutionary consequences. One
 90 critical distinction is whether the constructing type is favored in the environ-
 91 ment that it constructs. Under *positive niche construction*, selection favors
 92 the constructor, and evolution stagnates as this type fixes. Whereas under
 93 *negative niche construction*, selection favors a type other than the construc-
 94 tor, which creates an opportunity for novel adaptation. If the adapted type
 95 arises and also engages in negative niche construction, cycles of construction
 96 and adaptation can ensue, such that populations find themselves continually
 97 chasing beneficial mutations as their adaptive landscape perpetually shifts.
 98 Here, we show that the selective feedbacks that result from niche construction
 99 can maintain cooperation indefinitely. Further, we find that it is specifically
 100 negative niche construction that is responsible for this result due to the endless
 101 opportunities for adaptation that it produces. These results suggest that by
 102 playing an active role in their own evolution, cooperators can ensure their
 103 survival.

Methods

Building upon Hammarlund *et al.* (2015), we describe an individual-based model in which cooperators and defectors evolve and compete in a population of subpopulations (i.e., a metapopulation). Through mutation, individuals gain adaptations to their environment, which increase reproductive fitness and allow those lineages to rise in abundance. These lineages then spread throughout the population by migration to neighboring subpopulations.

In the expanded model described here, subpopulations additionally modify their local environment. As this process occurs, environmental changes feed back to affect selection. We use this model to explore how niche construction affects the evolution of cooperation; specifically, how cooperative behavior can hitchhike along with adaptations to modified environments.

Model Description

Individual Genotypes and Adaptation

Each individual has a haploid genome with $L + 1$ loci, where integers represent different alleles at each locus (Table 1 lists all model parameters and their values). An allele at the *cooperation locus* (locus zero) determines whether that individual is a cooperator (allele 1), which carries fitness cost c , or a defector (allele 0). The remaining L loci are *adaptive loci*, and are each occupied by a value from the set $\{0, 1, 2, \dots, A\}$.

Allele 0 represents a lack of adaptation, while non-zero alleles signify two

types of adaptations, both of which increase fitness. First, adaptations to the *external environment* confer a fitness benefit δ . This selective value is the same regardless of which non-zero allele is present. We assume $\delta > c$, which allows a minimally adapted cooperator to recoup the cost of cooperation and gain a fitness advantage.

Niche Construction and Selective Feedbacks

Individual fitness is also affected by aspects of the local environment that are modified by organisms. This constructed “niche” depends on the specific allelic states present in the subpopulation. As allelic states change, the subpopulation alters its environment, creating a unique niche. As described below, the specific alleles at each locus become important.

In our model, the feedback that results from niche construction takes the form of density dependent selection, and individuals evolve to better match their constructed niche. We do not represent this niche explicitly, but rather allow the allelic composition of the subpopulation to feed back to affect selection. Specifically, the selective value of non-zero allele a at adaptive locus l —and consequently the fitness of an individual carrying that allele—increases with the number of individuals in the subpopulation that have allele $a - 1$ at locus $l - 1$. For example, if $L = 5$, $A = 6$, and allele 4 has fixed at locus 2, then selection favors a genotype with allele 5 at locus 3. And as allele 5 fixes at locus 3, the niche that this population constructs will favor allele 6 at locus 4 (see [Box 1](#)). As a consequence, genotypes with sequentially increasing allelic

147 states will tend to evolve.

148 We treat both adaptive loci and their non-zero allelic states as “circular”: the
 149 selective value of an allele at locus 1 is affected by the allelic composition of
 150 the subpopulation at locus L . Similarly, the selective value of allele 1 at any
 151 locus increases with the number of individuals carrying allele A at the previous
 152 locus. This circularity is represented by the function $\beta(x, X)$, which gives the
 153 integer that is below an arbitrary value x in the set $\{1, 2, \dots, X\}$:

$$\beta(x, X) = \text{mod}_X(x - 2 + X) + 1 \quad (1)$$

154 Here, $\text{mod}_X(x)$ is the integer remainder when dividing x by X . For example,
 155 $\beta(3, 5)$ returns 2, while $\beta(1, 5)$ returns 5. Using this function, the selective
 156 value of allele a at adaptive locus l increases by ϵ for each individual in the
 157 subpopulation that has allele $\beta(a, A)$ at locus $\beta(l, L)$. Thus, ϵ specifies the
 158 intensity of selection due to niche construction.

159 Individual Fitness

160 For an individual with allelic state a_l at locus l , fitness is defined as:

$$W = z - \underbrace{ca_0}_{\text{cost of cooperation}} + \underbrace{\delta \sum_{l=1}^L I(a_l)}_{\text{adaptation to external environment}} + \underbrace{\epsilon \sum_{l=1}^L n(\beta(a_l, A), \beta(l, L))}_{\text{adaptation to constructed environment}} \quad (2)$$

161 where z is a baseline fitness, $n(a, l)$ is the number of individuals in the sub-
 162 population with allele a at locus l , and $I(a)$ indicates whether a given allele is

163 non-zero:

$$I(a) = \begin{cases} 1 & \text{if } a \in \{1, 2, \dots, A\} \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

164 Thus, an individual's fitness is determined both by adaptations to the external
165 environment and by adaptations to its constructed environment. **Box 1** illus-
166 trates the process of adaptation to the constructed environment. While the
167 separation between exogenous and endogenous environmental change may not
168 always be as clearly differentiated in natural systems, it allows us to directly
169 explore the effects of niche construction.

170 Subpopulation Growth and the Benefit of Cooperation

171 While cooperation is costly, its effects are independent of the external and
172 constructed components of the environment. Cooperation enables a subpopu-
173 lation to reach a greater density. If p is the proportion of cooperators present at
174 the beginning of a growth cycle, then that subpopulation reaches the following
175 size:

$$S(p) = S_{min} + p(S_{max} - S_{min}) \quad (4)$$

176 where S_{min} and S_{max} define the sizes reached by all-defector and all-cooperator
177 subpopulations, respectively. This benefit affects all individuals equally and
178 accumulates linearly with the proportion of cooperators in the subpopulation.

179 We further explore how the rate at which cooperators increase population
180 density in the Supporting Information.

181 During growth, individuals compete through differential reproduction. Each
182 individual's probability of success is proportional to its fitness. The composi-
183 tion of a subpopulation with size P and cooperator proportion p after growth
184 is multinomial with parameters $S(p)$ and $\{\pi_1, \pi_2, \dots, \pi_P\}$, where π_i represents
185 the reproductive fitness of individual i relative to others in its subpopulation
186 (Equation 2).

187 **Mutation**

188 For simplicity, we apply mutations to new offspring after subpopulation growth.
189 Mutations occur independently at each locus and cause an allelic state change.
190 At the binary cooperation locus, mutations occur at rate μ_c . These mutations
191 flip the allelic state, causing cooperators to become defectors and vice versa.
192 Mutations occur at rate μ_a at each adaptive locus. These mutations replace
193 the existing allele with a value randomly sampled from the set $\{0, 1, \dots, A\}$.

194 **Migration**

195 Populations consist of N^2 patches arranged as an $N \times N$ lattice, where each
196 patch can support a subpopulation. After mutation, individuals emigrate to
197 an adjacent patch. For each source subpopulation, a single destination patch is
198 randomly chosen from the source patch's Moore neighborhood, which is com-
199 posed of the nearest 8 patches on the lattice. Because the population lattice

200 has boundaries, patches located on the periphery have smaller neighborhoods.
201 Individuals emigrate with probability m , which means larger subpopulations
202 produce more emigrants. Through immigration, subpopulations can exceed
203 S_{max} individuals. As described below, however, this increase in population
204 size is temporary.

205 **Population Initialization and Simulation**

206 Following Hammarlund *et al.* (2015), we begin simulations with sparse pop-
207 ulations. Subpopulations are first seeded at all patches with cooperator pro-
208 portion p_0 and size $S(p_0)$. The population is then thinned. Each individual
209 survives this bottleneck with probability σ . Starting from this initial state,
210 simulations then proceed for T cycles, where each discrete cycle consists of
211 subpopulation growth, mutation, migration, and dilution. Dilution reduces
212 each subpopulation to support growth in the next cycle. Each individual re-
213 mains with probability d , regardless of its genotype. Dilution remained the
214 same for each of the simulations described, however we further explore its
215 effects in the Supporting Information.

216 **Simulation Source Code and Software Dependencies**

217 The simulation software and configurations for the experiments reported are
218 available online (Connelly *et al.*, 2015). Simulations used Python 3.4, NumPy
219 1.9.1, Pandas 0.15.2 (McKinney, 2010), and NetworkX 1.9.1 (Hagberg *et al.*,
220 2008). Data analyses were performed with R 3.2.2 (R Core Team, 2015).

221 Reported 95% confidence intervals were estimated by bootstrapping with 1000
222 resamples.

223 Results

224 Using the model described in the previous section, we perform simulations
225 that follow the evolution of cooperation in a population of subpopulations
226 that are connected by spatially-limited migration. Individuals increase their
227 competitiveness by gaining adaptations. While cooperation does not directly
228 affect the fitness benefits that these adaptations confer, it does have indirect
229 effects on the adaptive process. Specifically, cooperation increases subpopula-
230 tion density. As a result, larger subpopulations of cooperators experience more
231 mutational opportunities. Cooperation can rise in abundance by hitchhiking
232 along with beneficial mutations, which compensate for the cost of cooperation.
233 Importantly, subpopulations alter their local environments, which feeds back
234 to influence selection. Here, we explore how such niche construction affects
235 the evolution of cooperation.

236 Cooperation Persists with Niche Construction

237 Without any opportunity for adaptation ($L = 0$), cooperators are swiftly elim-
238 inated (Figure 1A). Despite an initial lift in cooperator abundance due to
239 increased productivity, the cost of cooperation becomes disadvantageous as
240 migration mixes the initially isolated subpopulations. When populations can

241 adapt to the external environment ($L > 0$ and $\delta > 0$), but niche construction
 242 is absent ($\epsilon = 0$), cooperators are maintained only transiently (Figure 1B).
 243 Here, larger cooperator subpopulations adapt more quickly to their external
 244 environment. As previously described by Hammarlund *et al.* (2015), coopera-
 245 tion is subsequently lost once populations become fully adapted. This occurs
 246 when isogenic defectors (i.e., defectors with identical adaptive loci) arise via
 247 mutation and displace cooperators due to their selective advantage. However,
 248 when niche construction feeds back to influence selection ($\epsilon > 0$), cooperation
 249 persists in the majority of replicate populations (Figure 1C). We see in Figure
 250 2A that despite some oscillations, cooperation is maintained at high levels in
 251 the majority of these populations.

252 **Fitness Increases Alone do not Support Persisting Coop-** 253 **eration**

254 An individual's fitness is affected in this model by adaptations to both the ex-
 255 ternal environment and to the constructed environment. Here, we determine
 256 whether cooperation is maintained as we see in Figure 2A solely due to the
 257 larger selective values that result from the contributions of niche construction.
 258 We performed simulations in which these contributions were transferred to sup-
 259 plement the benefits conferred by adaptation to the external, non-constructed
 260 environment (i.e., replacing $\epsilon = 0.3$, $\delta = 0.3$ with $\epsilon = 0$, $\delta = 0.6$). In doing so,
 261 we conservatively estimate the selective effects of niche construction. Neverthe-
 262 less, we find that simply increasing selective values does not enable cooperators

263 to persist (Figure 2B). Niche construction, therefore, plays a decisive role here.

264 Negative Niche Construction is Critical to Cooperator 265 Persistence

266 In our model, an adaptation to the constructed environment initiates a new
267 instance of niche construction, leading to sequentially increasing allelic states
268 across the adaptive loci. Under certain conditions, this construction always
269 makes the constructor sub-optimal for the niche it creates. This negative niche
270 construction occurs when the number of adaptive alleles (A) does not divide
271 evenly into the number of adaptive loci (L). In such a case, any sequence of
272 integers on the circular genome will always contain a break in the sequence;
273 that is, one locus will have an allele that is not one less than the allele at the
274 next locus (see Box 1). Given this unavoidable mismatch, types will always
275 construct a niche in which selection for a different type is increased. When
276 negative niche construction is removed (by setting $L = 5$, $A = 5$, Box 1, Part
277 C), cooperators are again driven to extinction after an initial lift in abundance
278 (Figure 2C). Here, a fully-adapted type constructs a niche that favors itself.
279 When this occurs, a fully-adapted cooperator is at a selective disadvantage
280 against fully-adapted defectors, which do not incur the cost of cooperation.
281 These results indicate that the type of niche construction matters. Specif-
282 ically, negative niche construction is crucial for maintaining cooperation by
283 the Hankshaw effect. Here, cooperators escape invasion by hitchhiking along
284 with adaptations to the constructed environment.

Selective Feedbacks Limit Defector Invasion

The adaptation resulting from selective feedbacks can limit invasion by defectors, which arise either through migration from neighboring patches or through mutation at the cooperation locus. This latter challenge is particularly threatening, as these isogenic defectors are equally adapted, yet do not incur the cost of cooperation. As demonstrated in [Figure 3A](#), isogenic defectors rapidly spread when introduced as a single subpopulation in the center of a population of otherwise all-cooperator subpopulations. However, cooperators resist defector invasion in over half of the replicate populations when adaptations can arise via mutation ([Figure 3B](#)). [Figure 4](#) depicts one such instance. In that population, isogenic defectors are seeded at a single patch in an otherwise all-cooperator population. These defectors quickly begin to spread. However, a neighboring cooperator population gains an adaptation, which increases its fitness above that of the defector. This type spreads more quickly, stopping the spread of defectors and eventually driving them to extinction. Because this adaptation occurs in a cooperator population, cooperation is able to hitchhike to safety. Importantly, this new cooperator type is favored because of the niche that its ancestral type—and therefore also the defector—constructed. Here, cooperators can find safety in numbers—because their larger subpopulations have more mutational opportunities, they are more likely to gain adaptations that rescue them from invasion. Further, these larger cooperator subpopulations exert greater influence on their niches, which increases selection for an adapted type. This allows that type to appear and to spread more quickly in the population. [Figure 3C](#) shows how quickly an adapted cooperator type can

309 invade a population of defectors.

310 Discussion

311 Despite their negative effects, deleterious traits can rise in abundance through
312 genetic linkage with other traits that are strongly favored by selection (May-
313 nard Smith and Haigh, 1974). In a process termed the “Hankshaw effect”,
314 Hammarlund *et al.* (2015) recently demonstrated that traits such as coopera-
315 tion and spite can actively prolong their existence by increasing their likelihood
316 of hitchhiking with a beneficial trait. In that work and here, subpopulations
317 of cooperators grow to a higher density than those of defectors. These larger
318 cooperator subpopulations therefore experience more mutations and are conse-
319 quently more likely to gain adaptations. Although this process favors coopera-
320 tion in the short term, it eventually reaches a dead end: When the opportu-
321 nities for adaptation are exhausted, and cooperators can no longer hitchhike,
322 they face extinction. Here, we have investigated whether niche construction
323 might serve to perpetually generate new adaptive opportunities and thus favor
324 cooperation indefinitely.

325 When niche construction occurs, cooperation can indeed persist (Figures 1C
326 and 2A). In our model, niche construction introduces additional selective ef-
327 fects that influence the evolutionary process, leading to a more pronounced
328 Hankshaw effect. However, these fitness benefits alone do not maintain co-
329 operation (Figure 2B). Niche construction and the selective feedbacks that it
330 produces play a crucial role.

331 We find that it is specifically *negative* niche construction that maintains coop-
 332 eration (Figure 2C). As cooperator and defector types gain adaptations, they
 333 alter their environment in ways that favor other types. Thus, negative niche
 334 construction serves as a perpetual source of adaptation. Here we observe an-
 335 other facet of the Hankshaw effect: Because subpopulations of cooperators are
 336 larger, they are better able to respond to the adaptive opportunities that are
 337 created by negative niche construction. By gaining adaptations more quickly,
 338 cooperators resist invasion by defectors (Figure 3B). Even in the presence of
 339 an isogenic defector type, cooperator subpopulations are more likely to pro-
 340 duce the mutant most adapted to the current constructed niche, which can
 341 then displace the slower-adapting defectors. These recurring cycles of defec-
 342 tor invasion and cooperator adaptation underlie the oscillations in cooperator
 343 proportion seen in Figure 2A. When mutations do not confer these adapta-
 344 tions, cooperators lose the adaptive race and are driven to extinction. This is
 345 something that we see occur stochastically in Figures 2A and 3B.

346 Cooperation as Niche Construction

347 In our model, niche construction and adaptation are independent of cooper-
 348 ation, which allows us to focus on hitchhiking. However, individuals often
 349 cooperate in ways that alter the environment. These cooperative behaviors,
 350 therefore, can themselves be seen as niche construction. For example, bacteria
 351 produce a host of extracellular products that scavenge soluble iron (Griffin *et*
 352 *al.*, 2004), digest large proteins (Diggle *et al.*, 2007; Darch *et al.*, 2012), and

353 reduce the risk of predation (Cosson *et al.*, 2002), among many others (West
354 *et al.*, 2007a). As in our model, these forms of cooperation are likely to in-
355 crease local subpopulation density. While many studies have focused on how
356 the environment affects the evolution of these cooperative traits, relatively few
357 have addressed how the environmental changes created by these products feed
358 back to influence evolution.

359 Perhaps most similar to this study, Van Dyken and Wade (2012) demonstrated
360 that when two negative niche constructing, cooperative behaviors co-evolve,
361 selection can increasingly favor these traits, which are otherwise disfavored
362 when alone. In that model, “reciprocal niche construction” occurred when the
363 negative feedback resulting from one strategy positively influenced selection
364 for the other, creating a perpetually oscillating cycle that maintained both
365 forms of cooperation. Arguably, this can be seen as an instance of hitchhiking:
366 the currently-maladaptive form of cooperation is maintained by association
367 with the adaptive form.

368 When dispersal is limited, competition among kin can undermine cooperation.
369 To separate kin competition from kin selection, Lehmann (2007) developed
370 a model in which a cooperative, niche-constructing behavior only benefitted
371 future generations. Kin competition was thereby reduced, and cooperation
372 instead benefitted descendants. This work highlights an important aspect of
373 niche construction: Often, the rate of selective feedback from niche construc-
374 tion is different from the rate at which populations grow.

375 Evolution at Multiple Timescales

376 In our work, the niche is modeled implicitly by the composition of the sub-
377 population. Any changes in the subpopulation, therefore, produce immediate
378 effects on the constructed environment and the resulting selective feedbacks.
379 However, timescales in our model could be de-coupled in two ways. First, co-
380 operators modify their niche by enabling their subpopulation to reach larger
381 density (Equation 4). These increased subpopulation sizes play a critical role
382 by effectively increasing the rate of evolution in these subpopulations. Because
383 of the importance of this process, it would be very informative to explore how
384 sensitive our results are to the rate at which cooperators increase subpopulation
385 sizes and the rate at which this benefit decays in the absence of cooperators.
386 Similarly, our results could be substantially affected by alterations in the rate
387 at which the constructed environment changes in response to changes in the
388 subpopulation.

389 Other studies, while not focused on cooperation, have similarly shown that the
390 timescales at which niche construction feedbacks occur can strongly influence
391 evolutionary outcomes (Laland *et al.*, 1996, 1999). This perspective may be
392 crucial for understanding the evolution of cooperative behaviors like the pro-
393 duction of public goods. In these instances, environmental changes are likely
394 to occur on different timescales than growth, which can have profound effects.
395 For example, a multitude of factors, including protein durability (Brown and
396 Taddei, 2007; Kümmerli and Brown, 2010), diffusion (Allison, 2005; Driscoll
397 and Pepper, 2010), and resource availability (Zhang and Rainey, 2013; Ghoul

398 *et al.*, 2014) influence both the rate and the degree to which public goods alter
 399 the environment. While Lehmann (2007) showed that cooperation was favored
 400 when selective feedbacks act over longer timescales, niche construction may in
 401 fact hinder cooperation when selection is more quickly altered. For example,
 402 when public goods accumulate in the environment, cooperators must decrease
 403 production to remain competitive (Kümmerli and Brown, 2010; Dumas and
 404 Kümmerli, 2012). This favors cooperation that occurs facultatively, perhaps
 405 by sensing the abiotic (Bernier *et al.*, 2011; Koestler and Waters, 2014) or bi-
 406 otic environment (Brown and Johnstone, 2001; Darch *et al.*, 2012). To study
 407 how regulatory traits such as these evolve, we could instead represent the niche
 408 explicitly, allowing it to have its own dynamics.

409 **Cooperation and Niche Construction in Host-Symbiont** 410 **Co-Evolution**

411 In many biological systems, the environments modified by organisms are them-
 412 selves other organisms. In these instances, the “niche” becomes a biological
 413 entity with its own evolutionary process. A logical extension to our model
 414 would be to treat the environment as an organism. Such a model could be
 415 used to explore the evolution of cooperation in host-symbiont systems, where
 416 cooperation among symbionts affects host fitness. As the host population
 417 changes, either in response to symbiont cooperation or other factors, so too
 418 does selection on their symbiont populations. In our model, each patch could
 419 become hosts with their own genotypes, and death and reproduction at the

420 host level could be defined in ways that are sensitive to both host and sym-
421 biont genotypes. Here, evolutionary outcomes depend greatly on the degree
422 of shared interest between the host and symbiont.

423 Of particular importance are cases where the interests of host and symbiont
424 are in conflict. By selecting for new, more resistant host genotypes or by pro-
425 voking a specific immune response, pathogens make their host environment
426 less hospitable and can therefore be seen as potent negative niche construc-
427 tors. The results that we have presented here suggest that such negative niche
428 construction can favor cooperative behavior among these symbiont pathogens.
429 This may be especially relevant when infection is mediated by cooperative be-
430 haviors. For example, the cooperative production of several public goods by
431 *P. aeruginosa* facilitate infection in hosts with cystic fibrosis (Harrison, 2007).
432 Models such as what we have described may permit exploration into how coop-
433 eration and niche construction intersect here and in other medically-relevant
434 instances.

435 More generally, it was recently argued that incorporating the effects of niche
436 construction is critical for improving our understanding of viral evolution
437 (Hamblin *et al.*, 2014) and evolution in co-infecting parasites (Hafer and Milin-
438 ski, 2015). Incorporating host dynamics, transmission, co-evolution, and the
439 feedbacks that they produce is likely to be equally important for gaining
440 a greater understanding of how cooperative behaviors evolve in these host-
441 symbiont settings.

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Box 1: Description of niche construction in our model

See [Figure B1](#)

(A) Individuals. The genome of each individual consists of a single *coop-eration locus* and L *adaptive loci* (here, $L = 5$). At the cooperation locus (labeled 0), this individual has allele 1, making it a cooperator. The adaptive loci (labeled 1 - 5) are arranged as a circular chromosome, where each locus has an integer allele between 0 and A , inclusive. In the description that follows, we focus exclusively on these adaptive loci. Genotypes are given by their allelic states starting with locus 1 . For instance, the genotype shown here is $[2,0,5,2,1]$. Because of their circular structure, allele 2 at the first locus follows allele 1 at the fifth locus.

(B) Niche Construction. Consider a subpopulation fixed for genotype $[1,2,0,0,0]$. This subpopulation constructs environment $E_{[1,2,0,0,0]}$. Every non-zero allele influences selection at the next locus, favoring sequential allelic states. In this constructed environment, allele 3 at locus 3 would be favored. If genotype $[1,2,3,0,0]$ arises via mutation, it is expected to fix. However, genotype $[1,2,3,0,0]$ affects the environment differently. As $[1,2,3,0,0]$ rises in abundance, the constructed environment changes to $E_{[1,2,3,0,0]}$, which favors $[1,2,3,4,0]$.

(C) Niche Construction and Adaptation. The evolutionary transition shown in Part B is indicated in the dashed box. Here, we depict entire sub-

475 populations fixed for a genotype using a single instance of that genotype. Simi-
 476 larly, an arrow represents niche construction and adaptation to the constructed
 477 environment. We start with a case in which there are five alleles ($A = 5$). Sub-
 478 populations begin with the non-adapted genotype $[0,0,0,0,0]$, shown on the far
 479 left. A non-zero allele is introduced via mutation, which represents an adapta-
 480 tion to external aspects of the environment. Here, allele 1 arises and fixes at
 481 locus 1. The remainder of this figure focuses on adaptation to the constructed
 482 aspects of the environment. This genotype has a mismatch (shown by the red
 483 sector), because $E_{[1,0,0,0,0]}$ favors $[1,2,0,0,0]$. Assuming allele 2 arises at the
 484 second locus, it will be selected, creating a match at the first and second loci
 485 (green sector). Now there is a mismatch between the second and third loci
 486 in the resulting environment, which a new round of mutation and selection
 487 corrects, and so on. The green sector grows as the red sector shifts clockwise.
 488 When the population reaches $[1,2,3,4,5]$, it constructs $E_{[1,2,3,4,5]}$. Here, since
 489 allele 1 follows allele 5, there is no longer a mismatch, so no further adaptation
 490 occurs.

491 **(D) Negative Niche Construction.** A different case emerges when the
 492 number of alleles does not evenly divide into the number of loci. Here, we
 493 change the number of alleles to six ($A = 6$). As shown on the far left, we
 494 begin with a subpopulation fixed for genotype $[1,2,3,4,5]$. This genotype has a
 495 mismatch, because the niche constructed by allele 5 favors allele 6 (not 1) at the
 496 next locus (locus 1). A mutant with genotype $[6,2,3,4,5]$ has a fitness advantage
 497 and can fix in $E_{[1,2,3,4,5]}$. However, as this type constructs $E_{[6,2,3,4,5]}$, a new
 498 mismatch appears. In this instance of negative niche construction, adapting

499 to correct one mismatch generates a new mismatch. This system can never
500 escape its mismatches—the red sector just shifts clockwise around the genome
501 perpetually.

502 **Figures**

503 **Figure 1**

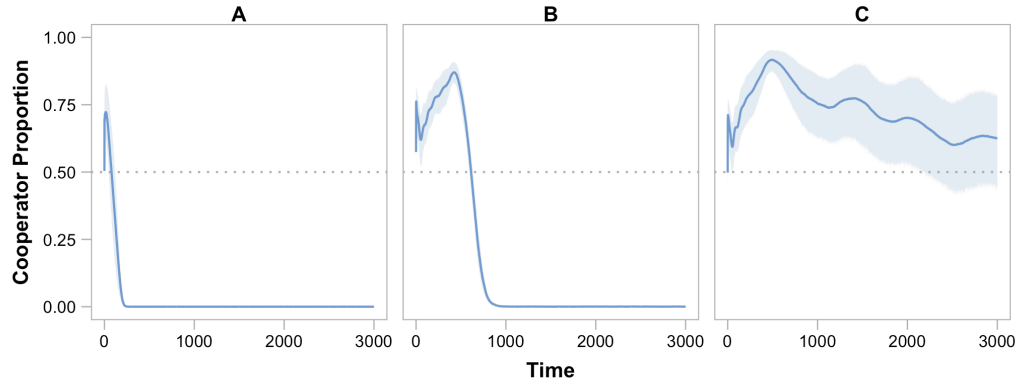


Figure 1: **Adaptation and the Evolution of Cooperation.** The average cooperator proportion among replicate populations for the duration of simulations are shown as curves, and shaded areas indicate 95% confidence intervals. **(A)** Without any opportunity to adapt ($L = 0$), cooperation is quickly lost. **(B)** When adaptation can occur ($L = 5$, $\delta = 0.3$), but niche construction does not affect selection ($\epsilon = 0$), cooperators rise in abundance by hitchhiking along with adaptations to the external environment. Nevertheless, this effect is transient, and cooperators eventually become extinct. **(C)** Niche construction ($\epsilon = 0.00015$) enables cooperation to be maintained indefinitely in the majority of populations. The trajectories of individual populations are shown in Figure 2A.

504 **Figure 2**

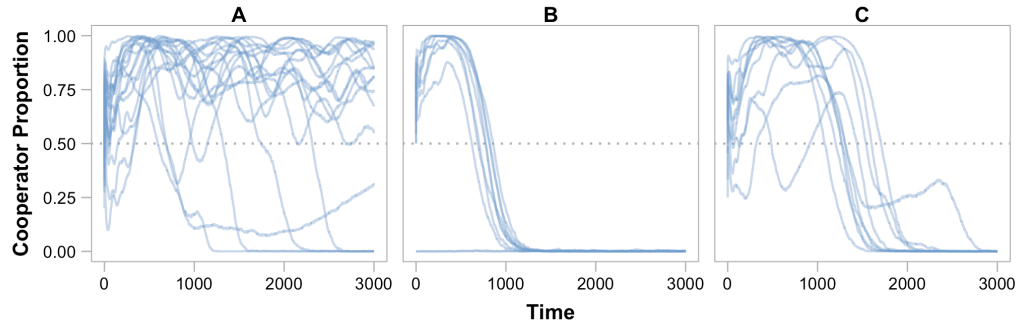


Figure 2: **Niche Construction and the Evolution of Cooperation.** The proportion of cooperators present in each replicate population is shown for the duration of simulations. **(A)** Despite some oscillation, cooperators dominate in 13 of 18 populations when niche construction affects selection. **(B)** When the selective effects of niche construction are transferred to supplement the benefits conferred by adaptation to the external, non-constructed environment, cooperators are driven to extinction by defectors (replacing $\epsilon = 0.3$, $\delta = 0.3$ with $\epsilon = 0$, $\delta = 0.6$). Note that cooperation was not present after initialization in one replicate population. **(C)** Cooperators are also driven to extinction without negative niche construction ($A = 5$).

505 **Figure 3**

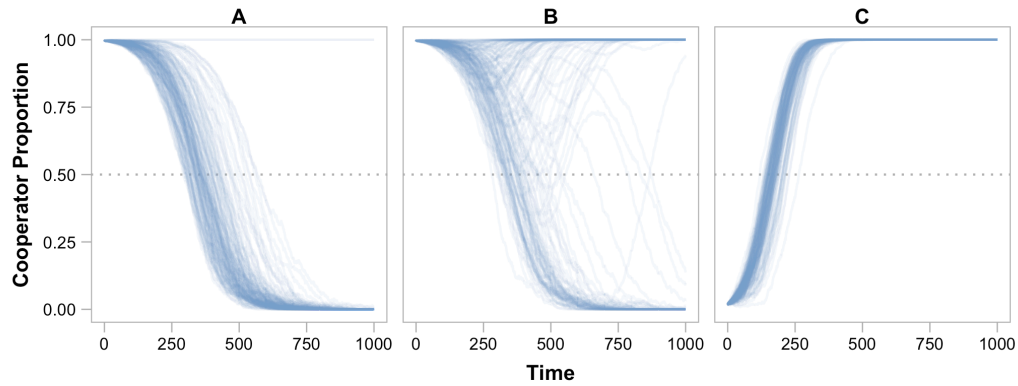


Figure 3: **Niche Construction and Invasion.** The proportion of cooperators present in each replicate population is shown for the duration of simulations ($T = 1000$). In each simulation, a rare type was initiated at a single patch in the center of the population lattice ($N^2 = 121$). Unless otherwise noted, mutations are disabled in these ecological simulations to highlight the dynamics of invasion ($\mu_a = 0, \mu_c = 0$). **(A)** When cooperators and defectors are isogenic (i.e., both types have stress alleles $[1,2,3,4,5]$), rare defectors quickly invade and drive cooperators to extinction due to the cost of cooperation. Defectors were stochastically eliminated in 2 replicate populations. **(B)** However, negative niche construction creates adaptive opportunities that enable cooperators to resist invasion by isogenic defectors. When adaptive mutations occur ($\mu_a = 0.00005$), cooperation remained dominant in 91 of 160 populations. Results from simulations where mutations also occurred at the cooperation locus are shown in Figure S2S1. **(C)** In fact, a cooperator (stress alleles $[6,2,3,4,5]$, see Box 1) that is adapted to the niche constructed by the defectors can swiftly displace defectors.

506 **Figure 4**

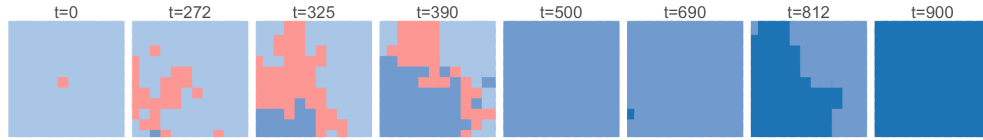


Figure 4: **Cooperator Adaptation Prevents Defector Invasion.** The spatial distribution of dominant types among subpopulations is shown at different time points for one representative simulation in which isogenic defectors arise. To highlight the effects of adaptation, mutations did not occur at the cooperation locus ($\mu_c = 0$). At time $t = 0$ (upper left panel), a single isogenic defector subpopulation (red) is placed within an all-cooperator population (light blue). Because these defectors do not bear the cost of cooperation, they quickly spread ($t = 272$). However, cooperators in one subpopulation gain an adaptation that gives them a fitness advantage over defectors (second panel, medium blue, lower left). At $t = 325$, defectors continue to invade cooperator subpopulations. However, the adapted cooperator type spreads more quickly due to its fitness advantage, invading both defector and ancestral cooperator subpopulations ($t = 390$), until it eventually fixes in the population ($t = 500$). At $t = 690$, a new cooperator type emerges that is favored due to negative niche construction (dark blue). This new type spreads rapidly ($t = 812$) until reaching fixation ($t = 900$). At this point, it becomes susceptible to invasion by the next “adapted” cooperator type, and the cycle continues.

507 **Box 1 Figures**

508 **Figure B1**

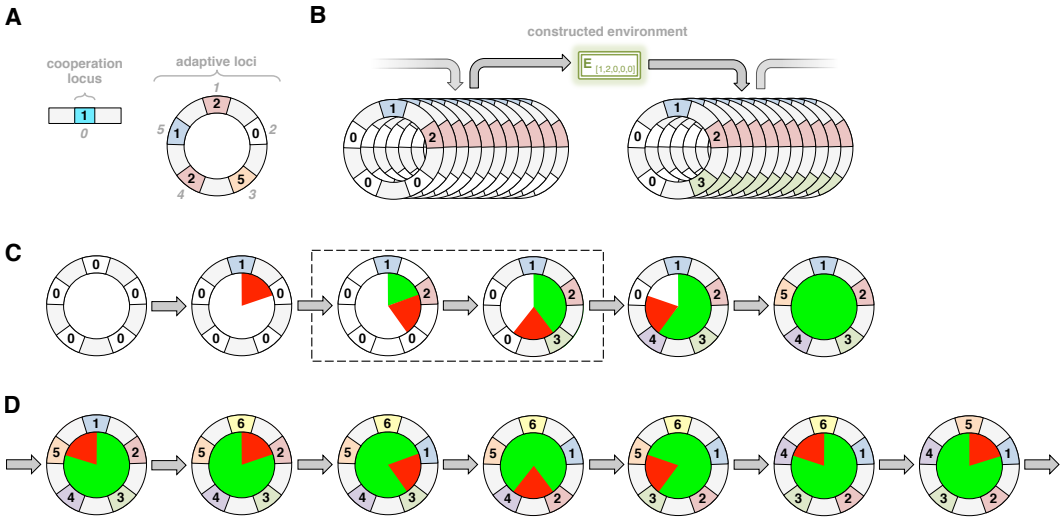


Figure B1: Figure for Box 1

Table 1: Model parameters and their values

Parameter	Description	Base Value	Alternate Values
L	Number of adaptive loci	5	0, 40
c	Cost of cooperation	0.1	0.1
A	Number of alleles	6	5, 6
δ	Benefit of adaptation to external environment	0.3	0, 0.6
ϵ	Benefit of adaptation to constructed environment	0.00015	0
z	Baseline fitness	1	
S_{min}	Minimum subpopulation size	800	80
S_{max}	Maximum subpopulation size	2000	200
μ_a	Mutation rate at adaptive loci	10^{-5}	0
μ_c	Mutation rate at cooperation locus	10^{-5}	0
N^2	Number of patches	625	625
m	Migration rate	0.05	
p_0	Initial cooperator proportion	0.5	0, 0.01, 0.1, 0.2, 0.3,
σ	Survival rate at population initialization	10^{-5}	
T	Number of simulation cycles	3000	1000
d	Subpopulation dilution factor	0.1	0.01, 0.3, 0.5, 0.7, 0.9
γ	Slope of cooperative benefit*	1.0	0.25, 0.5, 1.5, 2, 4

510 * See Supporting Information

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