Heat-Conduction Tests

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August 23, 2016

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Porous-flow heat conduction is governed by the equation

$$0 = \frac{\partial}{\partial t} \mathcal{E} + \nabla \cdot \mathbf{F}^{\mathrm{T}} , \qquad (1.1)$$

Here \mathcal{E} is the energy per unit volume in the rock-fluid system, and \mathbf{F}^T is the heat flux. In the porous-flow module

$$\mathcal{E} = (1 - \phi)\rho_R C_R T + \phi \sum_{\beta} S_{\beta} \rho_{\beta} \mathcal{E}_{\beta} , \qquad (1.2)$$

when there is no adsorbed species. Here T is the temperature, ϕ is the rock porosity, and S_{β} is the saturation of phase β . The remainder of the notation is described in the next paragraph. When studying problems involving heat conduction (with no fluid convection)

where λ is the tensorial thermal conductivity of the rock-fluid system.

The tests described in this section use the following simple forms for each term

- ρ_R , which is the rock-grain density (that is, the density of rock with zero porespace), measured in kg.m⁻³, is assumed constant in the current implementation of the PorousFlow module.
- C_R , which is the rock-grain specific heat capacity, measured in J.kg⁻¹.K⁻¹, is assumed constant in the current implementation of the PorousFlow module.
- ρ_{β} , which is the density of fluid phase β , is assumed in this chapter to be a function of the fluid pressure only (this is so Equation (1.1) may be easily solved more general forms are allowed in the PorousFlow module).
- \mathcal{E}_{β} , which is the specific internal energy of the fluid phase β , and is measured in J.kg⁻¹, is assumed in this chapter to be

$$\mathcal{E}_{\beta} = C_{\nu}^{\beta} T , \qquad (1.4)$$

where C_{ν}^{β} is the fluid's specific heat capacity at constant volume. This specific heat capacity is assumed constant (so that Equation (1.1) may be easily solved — more general forms are allowed in the PorousFlow module).

• λ is assumed to vary between λ^{dry} and λ^{wet} , depending on the aqueous saturation:

$$\lambda_{ij} = \lambda_{ij}^{\text{dry}} + S^n \left(\lambda_{ij}^{\text{wet}} - \lambda_{ij}^{\text{dry}} \right), \tag{1.5}$$

where S is the aqueous saturation, and n is a positive user-defined exponent. More general forms may be easily accommodated in the PorousFlow module, but to date none have been coded.

Under these conditions, Equation (1.1) becomes

$$\dot{T} = \nabla_i \alpha_{ij} \nabla_i T \ . \tag{1.6}$$

The tensor α is

$$\alpha_{ij} = \frac{\lambda_{ij}}{(1 - \phi)\rho_R C_R + \rho \sum_{\beta} S_{\beta} \rho_{\beta} C_{\nu}^{\beta}}.$$
 (1.7)

For constant saturation and porepressure, α_{ij} is also constant.

Consider the one-dimensional case where the spatial dimension is the semi-infinite line $x \ge 0$. Suppose that initially the temperature is constant, so that

$$T(x,t=0) = T_0 \text{ for } x \ge 0.$$
 (1.8)

Then apply a fixed-pressure Dirichlet boundary condition at x = 0 so that

$$T(x = 0, t > 0) = T_{\infty} \tag{1.9}$$

The solution of the above differential equation is well known to be

$$T(x,t) = T_{\infty} + (T_0 - T_{\infty}) \operatorname{Erf}\left(\frac{x}{\sqrt{4\alpha t}}\right) , \qquad (1.10)$$

where Erf is the error function.

This is verified by using the following tests on a line of 10 elements.

- 1. A transient analysis with no fluids. The parameters chosen are $\lambda_{ij} = \text{diag}(2.2)$, $\phi = 0.9$, $\rho_R = 0.5$ and $C_R = 2.2$ is chosen, so that $\alpha_{ij} = 1/(0.9 \times 0.5)$.
- 2. A transient analysis with 2 fluid phases. The parameters chosen are $\lambda^{\text{dry}} = 0.3$, $\lambda^{\text{wet}} = 1.7$ and S = 0.5, so that $\lambda_{ij} = \text{diag}(1)$. $\rho_{\text{gas}} = 0.4$, $\rho_{\text{water}} = 0.3$, $\rho_{R} = 0.25$, $C_{\nu}^{\text{gas}} = 1$, $C_{\nu}^{\text{water}} = 2$, $C_{R} = 1.0$, and $\phi = 0.8$. With these parameters, $\alpha_{ij} = 1/(0.9 \times 0.5)$.

An example verification is shown in Figure 1.1. These tests are part of the automatic test suite.

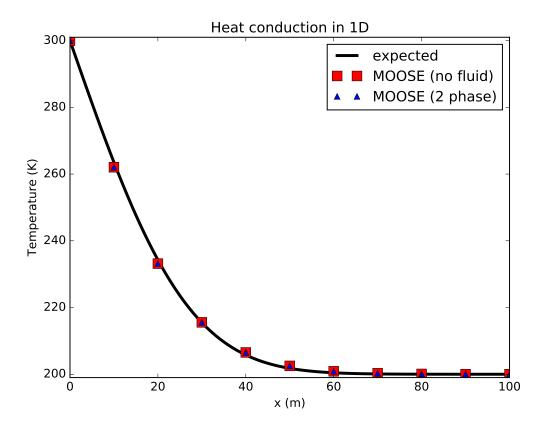


Figure 1.1: Comparison between the MOOSE result (in dots), and the exact analytic expression given by Eqn (1.10). This test had 10 elements in the x direction, with $0 \le x \le 100$ m, and ran for a total of 10^2 seconds with 10 timesteps.