

## 787. Cheapest Flights Within K Stops

Medium    5350    246    Add to List    Share

There are  $n$  cities connected by some number of flights. You are given an array `flights` where `flights[i] = [fromi, toi, pricei]` indicates that there is a flight from city `fromi` to city `toi` with cost `pricei`.

You are also given three integers `src`, `dst`, and `k`, return **the cheapest price** from `src` to `dst` with at most `k` stops. If there is no such route, return `-1`.

```
class Solution {
public:
    int findCheapestPrice(int n, vector<vector<int>>& flights, int src, int dst, int k)
    {
        // build the graph as adjacent list format
        typedef pair<int, int> PII;
        vector<vector<PII>> graph(n, vector<PII>());
        for (auto flight: flights)
        {
            int f = flight[0], t = flight[1], w = flight[2];
            graph[f].push_back({t, w});
        }

        // shortest path to all vertices from src
        int dist[n];

        // initilize to infinity
        memset(dist, INTMAX, sizeof dist);
        dist[src] = 0;

        // early termination flag
        bool any_updated = false;
        bool vertices_updated[n];
        memset(vertices_updated, false, sizeof vertices_updated);

        // src is updated as base case
        vertices_updated[src] = true;

        // tmp holders;
        int tmp_dist[n];
        bool tmp_vertices_updated[n];
```

```

for (int i = 0; i < k + 1; i++)
{
    // initialize all vertices as not updated for i stops
    memset(tmp_vertices_updated, false, sizeof tmp_vertices_updated);
    // store i - 1 stops dist to a tmp holder
    memcpy(tmp_dist, dist, sizeof tmp_dist);
    // enumerate all vertices, as from
    for (int f = 0; f < n; f++)
    {
        // jump over vertices not updated at i - 1 stops iteration
        if (!vertices_updated[f]) continue;
        // for every adjacent nodes, as to
        for (auto [t, w] : graph[f]) {
            // update dist[t], we need to use tmp_dist, because for
            // we need to make sure dist[f] is from i - 1 stops
            // and dist[f] might be updated at i stops
            dist[t] = min(dist[t], tmp_dist[f] + w);
            if (dist[t] == tmp_dist[f] + w)
            {
                // update early termination flags
                any_updated = true;
                tmp_vertices_updated[t] = true;
            }
        }
    }
    // if no updates, early termination
    if (!any_updated) break;
    any_updated = false;
    // replace vertices_updated with tmp holders data
    memcpy(vertices_updated, tmp_vertices_updated, sizeof
vertices_updated);
}
// if dst cannot reached return -1, otherwise return dist[dst]
if (dist[dst] < INTMAX) return dist[dst];
return -1;
}
};

```

## Algorithm:

### Sub Problem

We could raise our main problem: calculate `dist[v]` (`k stops`) shortest path from src to every vertices `v` with at most `k` stops. Once the main problem is solved we could just return `dist[dst]` as it is the shortest path from src to dst within `k` stops.

Then we could reduce the main problem to our sub problem: calculate `dist[v] (i stops)` shortest path from `src` to every vertices with at most `i` stops ( $i < k$ )

## Recurrence Equation

We need to get the recurrence equation between sub problems `dist[v] (i stops)` and `dist[v] (i - 1) stops`

For shortest path from `src` to `v` with at most `i` stops , they can be divided to two cases:

Case1: the path has at most `i - 1` stops. Which is the definition of `dist[v] (i - 1 stops)`

Case2: the path has `k` stops. Which means every edges point to `v` could be the last edge in the path, therefore `dist[v] (i stops) = min{ dist[w] (i - 1 stops) + weight(w -> v) for every adjacent w }`

The minimum value among these two cases should be the shortest path from `src` to `v` with at most `i` stops. Therefore it can be written as :

```
dist[v] (i stops) = min{
    dist[v] (i - 1) stops,
    min {
        dist[w] (i - 1 stops) + weight(w -> v) for every adjacent w
    }
}
```

## Base case

If we do not take any flight, we could only reach `src`, and the price is 0. Other vertices should be initialize to infinity.

## Merge Sub Problems

We need to derive the results of sub problems from base case. So we start from 0-stops, to `k` stops. As the following pseudo code shows, the outer loop indicates current stops number. Then we enumerate all vertices, update the `dist` according to recurrence equation we represented above.

```
for i = 0 to k {
    foreach vertex f in all cities {
        if f is not updated at last iteration {
            continue
        }
    }
}
```

```

    }

    dist[v] = dist[v] (i - 1) stops

    for vertex t in all cities such that (f, t) in all flights {
        dist[v] (i stops) = min( dist[v] (i stops), dist[f] (i -
1 stops) + weight (f -> t)
    }
}
break if no dist[v] updated in current iteration
}

```

Note: if a node is not updated at  $i - 1$  stops, it could be passed at  $i$  stops. Because as our recurrence equation shows, for case 2: only path has  $i$  stops could possibly update  $\text{dist}[v] (i \text{ stops})$ , therefore if a node is not updated at  $i - 1$  stops, the path should always lower than or equal to  $i - 1$  stops. which could be covered by  $\text{dist}[v] (i - 1 \text{ stops})$ . Therefore, we could jump over any vertices does not get updated in previous iteration.

And if all vertices do not updated, which means case 2 will never happens, so we could just stop the algorithm, because  $\text{dist}[v] (k \text{ stops}) = \text{dist}[v] (k - 1) \text{ stops} = \dots = \text{dist}[v] (i \text{ stops})$

## Time Complexity

At worst case, we need to loop  $K$  times if there's no early termination, and in the inner loop, in worst case, we will enumerate all edges by one time.

The recurrence relation is  $T(K) = T(K - 1) + O(E) = O(KE)$

Therefore, the time complexity for is  $O(KE)$ , where  $K$  is the number of stops,  $E$  is the number of edges.