# CHISELVERIFY: A VERIFICATION LIBRARY FOR CHISEL

<u>Andrew Dobis</u>\*, Tjark Petersen\*, Hans Jakob Damsgaard\*, Kasper Hesse\*, Enrico Tolotto\*, Simon Thye Andersen\*, Richard Lin† & Martin Schoeberl\*.

\*Technical University of Denmark (DTU) Department of Applied Mathematics & Computer Science †University of California Berkeley Department of Electrical Engineering & Computer Sciences





#### OUTLINE

➤ <u>Background:</u> Verification & Chisel.

➤ <u>Current solutions</u>: Current ways to verify chisel designs.

➤ <u>Motivation</u>: Need for Verification tools for Chisel.

➤ Our solution: bringing verification to Chisel directly in Scala.

➤ <u>Evaluation</u>: Comparing verification with ChiselVerify to verification with UVM.

## BACKGROUND

#### **BACKGROUND: VERIFICATION**

- Verification of digital systems:
  - ➤ Testing a design before it has been taped out.
  - ➤ Verification tools allow to verify that the tests we are writing "test the right things".

- ➤ Universal Verification Methodology (UVM):
  - ➤ Testing methodology implemented in SystemVerilog, a popular solution for verification.
  - ➤ Allows for the writing of standardised test-benches, which can be reused on multiple designs.

#### **BACKGROUND: VERIFICATION TOOLS**

#### ➤ Functional Coverage:

- Qualitative and fine-grained coverage metric.
- ➤ Gives progress on "which features have been tested?".

#### Constrained Random Verification (CRV):

- ➤ Enables the creation of random variables which generate values that satisfy a set of constraints.
- ➤ Allows for the generation of constantly valid inputs, making a small test case capable of covering many of the component's functionalities.

#### BACKGROUND: CHISEL

#### ➤ Chisel:

- ➤ Hardware Construction Language embedded in Scala.
- ➤ Allows for the use of **Object-Oriented** and **Functional** programming constructs in the scope of hardware description.
- ➤ Compiles through an intermediate representation called **FIRRTL** before generating output **Verilog**.
- ➤ Can be either **synthesised** or **simulated** using:
  - ➤ Output **Verilog** (e.g. with **verilator**)
  - ➤ Intermediate **FIRRTL** with **Treadle** (a custom simulator and testing engine).

## CURRENT SOLUTIONS

#### OVERVIEW OF THE CURRENT SOLUTIONS

#### ➤ For Chisel:

- ➤ ChiselTest: "traditional" test-benches with peek-poke-expect interfaces and forking, lacks verification features.
- ➤ **ScalaTest**: Software testing framework, not ideal for hardware, doesn't simulate the hardware, only checks the Chisel code itself.

#### ➤ For Verilog:

- ➤ **SystemVerilog**: Extension of Verilog that enables object oriented programming and verification features inside of the test-benches.
- ➤ UVM: Verification Methodology, enables a standardised testing method that can be reused for many different DUTs.

#### **CURRENT SOLUTIONS: WHAT'S MISSING?**

- Other types of solutions:
  - ➤ <u>RFuzz:</u> Fuzzer for RTL circuits. Only allows fuzzing, no verification tools.
  - ➤ <u>Chisel Formal:</u> Formal Verification in Chisel, static verification, doesn't solve the same problems.
- ➤ What's missing in these solutions:
  - ➤ **ChiselTest**: For test-benches, not really verification.
  - > ScalaTest: Not made for Hardware.
  - SystemVerilog & UVM:
    - ➤ Too verbose, requires ~800 LOC for a test-bench.
    - ➤ Requires multiple languages to test a Chisel design.

# MOTIVATION

#### MOTIVATION: CURRENT LACK OF VERIFICATION TOOLS

➤ So far Chisel doesn't have any "native" tools that allow the easy use of verification functionalities.

➤ Current solutions all require external tools to function.

➤ We need tools which are built **for** Chisel.

➤ We also want tools which are **efficient** to use and **easy to learn**, not the case of current popular solution like SystemVerilog with UVM.

### OUR SOLUTION: CHISELVERIFY

#### CHISELVERIFY: OVERVIEW

- ➤ Hardware Verification library for Chisel, inspired by UVM.
- ➤ Powered entirely by Scala and ChiselTest.

- ➤ ChiselVerify brings the following to the Chisel ecosystem:
  - Functional Coverage
  - ➤ Constrained Random Verification
  - ➤ Bus Functional Models
  - ➤ Timed Assertions

### CHISELVERIFY: FUNCTIONAL COVERAGE

#### FUNCTIONAL COVERAGE: WHAT IS IT?

#### **Verification Plan**

Representation of the DUT's expected features.

#### CoverGroup

Set of DUT ports that will be sampled together, represents a "feature".

#### **CoverPoint**

Set of values that a port is expected to have to verify a feature, represents a feature of single port.

#### **Bins**

Definition of a set of values that a port should reach during testing, done in two ways:

Range: first to last (both included)

Conditional:
Arbitrary
(portValues) =>
Boolean function

#### **Cross**

Defines a relation between two bins in a CoverPoint, i.e. how many value pairs, within the defined cross set, have these two points reached during testing.

#### Example:

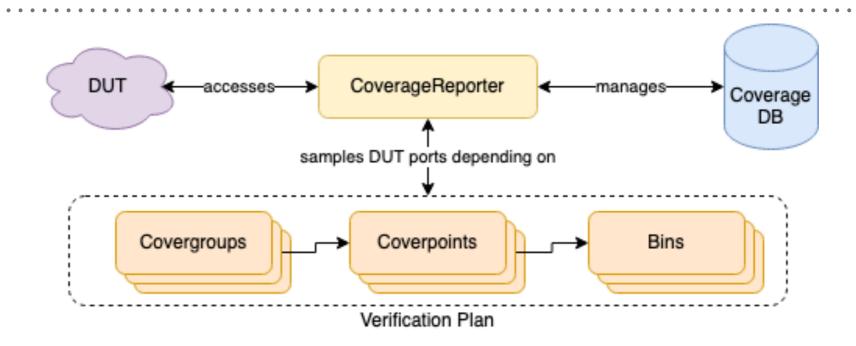
Cross(A, B, 1 to 1, 1 to 1) => Have ports A and B reached the value 1 at the same time?

#### **Timed**

Same idea as the cross bin, but with an added time constraint, i.e. have the two points hit a cross set within a given number of cycles from each other?

There are 3 ways to define a time constraint: Always, Eventually and Never

#### FUNCTIONAL COVERAGE: HOW DID WE DO IT?



- ➤ CoverageDB: DataBase that maintains the values gathered for all of the bins across multiple tests in a test suite.
- ➤ Coverage Reporter: Handles the registration of CoverPoints and Bins to the DB, samples the bin values and creates the coverage report.
  - ➤ This is used to create the verification plan.

#### FUNCTIONAL COVERAGE: API

#### Two main constructs:

➤ <u>Cover</u>: Represents a feature of the DUT. Can be represented by both a single and multiple DUT ports. Its behavior is defined by the **bins** it contains.

```
case class cover(pointName: String, ports: Data*)

def apply(b: Bin*)

def apply(delay: DelayType)(b: Bin*)
```

➤ <u>Bins</u>: Definition of a part of a feature. Defined using value ranges or condition, and can contain timing information.

```
def bin(name: String, range: Option[Range] = None, condition: Option[Seq[BigInt] => Boolean] = None, expectedHits: BigInt = 0)
```

#### FUNCTIONAL COVERAGE: USING IT

➤ Create the coverage reporter and verification plan.

```
val cr = new CoverageReporter(dut)
cr.register(
    cover("accu", dut.io.outA)( //CoverPoint 1
        bin("lo10", 0 until 10), bin("First100", 0 until 100)),
    cover("test", dut.io.outB)( //CoverPoint 2
        bin("testLo10", 0 until 10)),
    //Declare cross points
    cover("accuAndTest", dut.io.outA, dut.io.outB)(
        cross("both1", Seq(1 to 1, 1 to 1)))
)
```

➤ Sample the CoverPoints inside of the test.

```
cr.sample()
```

#### RESULT: FUNCTIONAL COVERAGE REPORT

Create and print the coverage report

```
//Generate report
val report = cr.report
print(report.serialize)
```

➤ Example result:

```
======== COVERAGE REPORT =========
========= GROUP ID: 1 ==========
COVER_POINT PORT NAME: accu
BIN lo10 COVERING Range 0 until 10 HAS 10 HIT(S) = 100,00%
BIN First100 COVERING Range 0 until 100 HAS 50 HIT(S) = 50,00%
COVER_POINT PORT NAME: test
BIN testLo10 COVERING Range 0 until 10 HAS 4 HIT(S) = 40,00%
CROSS_POINT accuAndTest FOR POINTS accu AND test
BIN both1 COVERING Range 1 to 1 CROSS Range 1 to 1 HAS 1 HIT(S) = 100,00%
```

# CHISELVERIFY: CONSTRAINED RANDOM VERIFICATION

#### CONSTRAINED RANDOM VERIFICATION: WHAT IS IT?

- ➤ Model tests using randomness:
  - ➤ Give random inputs to the DUT and expect values using a golden model.
- ➤ Guide the randomness using constraints:
  - ➤ We don't want the randomness to be uniformly distributed => use constraints to describe the random distribution.
- ➤ Idea: Add a Constraint Programming Language to Scala/Chisel
  - ➤ Create Random Objects, then define Random Variables and Constraints in it.
  - ➤ Random Objects define a **Constraint Satisfaction Problem (CSP)**. This problem is solved using a CSP Solver.
  - ➤ We use **JaCoP** as a CSP Solver.

#### CONSTRAINED RANDOM VERIFICATION: HOW DID WE DO IT?

- ➤ Random objects created by extending the **RandObj** trait using a given **Model** with a seed.
- ➤ Random fields are added as **Rand/Randc** values inside the class.
- ➤ Constraints are defined using either:
  - Single constraints: using "#" (e.g. val lenConstraint = len > 2)
  - ➤ ConstraintGroups which are equivalent to SV

```
Example:
class Frame extends RandObj(new Model) {
  val pkType: RandVar = rand(0, 3)
  val len: RandVar = rand(0, 10)
  val noRepeat: RandVar = rand(0, 1, Cyclic)

val legal: ConstraintGroup = new ConstraintGroup {
  len >= 2
  len <= 5
  }
}</pre>
```

#### CONSTRAINED RANDOM VERIFICATION: WHAT DO WE ADD?

- ➤ The list of operator used to construct constraint is the following: <, <=, >, >=, ==, div, \*, mod, +, -, \=, ^, in, inside.
- ➤ We also added conditional constraints using:
  - ➤ **IfCon**: If a condition is met, then use the constraint
  - **ElseC**: If a condition is met, then use the constraint, else use an other.

#### Example:

```
val constraint1: crv.Constraint = IfCon(len == 1) {
        payload.size == 3
   } ElseC {
        payload.size == 10
```

#### CONSTRAINED RANDOM VERIFICATION: USING IT

dist can also be used to define custom distributions on a random variable by associating ranges to weights using the := operator.

➤ The randomize() method returns true only if the CSP Solver found a set of values that satisfy the current constraints.

#### Example:

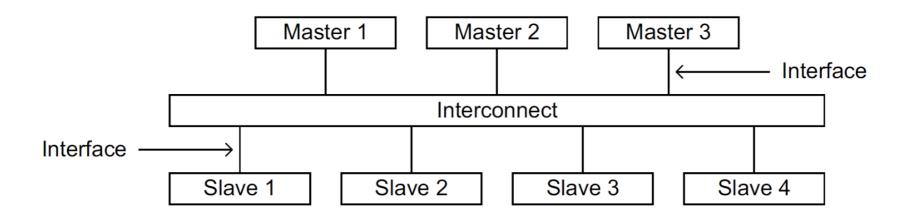
```
val myPacket = new Frame(new Model)
assert(myPacket.randomize)
```

# CHISELVERIFY: BUS FUNCTIONAL MODELS

#### **BUS FUNCTIONAL MODEL: WHAT IS IT?**

- ➤ Abstraction of the inner workings of a standardised interface.
- ➤ Allows for the use of data transfer via **Transactions**, rather than having to deal with the inner wiring manually.
- ➤ Software abstraction, is useful for faster verification.

➤ We chose to create a first BFM for the AXI4 Bus:



#### **BUS FUNCTIONAL MODEL: HOW TO USE IT**

➤ Create a FunctionalMaster for your AXI interfaced DUT.

```
val manager = new FunctionalManager(dut)
```

- ➤ Create transactions:
  - ➤ Write:

```
// Create write transaction
manager.createWriteTrx(0, Seq(42), size = 2)

// Wait for the write to complete (spin on response)
var resp = manager.checkResponse()
while (resp == None) {
    resp = manager.checkResponse()
    dut.clock.step()
}

// Create read transaction
manager.createReadTrx(0, size = 2)

// Wait for read to complete (spin on read data)
var data = manager.checkReadData()
while (data == None) {
    data = manager.checkReadData()
    dut.clock.step()
}
```

➤ Read:

### CHISELVERIFY: TIMED ASSERTIONS

#### TIMED ASSERTIONS: QUICK OVERVIEW

- ➤ Allows to create predicated assertions that take into account certain timing delays.
- > Types of delays: Given a delay of x cycles:
  - **Exactly**: Assertion is true exactly in x cycles.
  - **Eventually**: Assertion is true at least once in the next x cycles.
  - ➤ **Always:** Assertion is true every cycle for the next x cycles.
  - ➤ **Never:** Assertion isn't true at any cycle for the next x cycles.
- ➤ Two types of Timed Assertions:
  - ➤ ExpectTimed: Uses *ChiselTest*'s expect for the assertion.
  - ➤ **AssertTimed:** Uses a software assert() for the assertion.

#### TIMED ASSERTIONS: USING IT

#### Example:

```
eventually(2, "aEqb expected timing is wrong") { dut.io.a.peek() === dut.io.b.peek() }
exact(2, "aEqb expected timing is wrong") { dut.io.a.peek() === dut.io.b.peek() }
always(2, "aEqb expected timing is wrong") { dut.io.a.peek() === dut.io.b.peek() }
never(2, "aEqb expected timing is wrong") { dut.io.a.peek() === dut.io.b.peek() }
```

# CONCLUSION

#### CONCLUSION

➤ ChiselVerify brings verification to the Chisel ecosystem.

➤ High-Level Functional backend (i.e. Scala) allows for much more efficiency during verification process (in comparison to SystemVerilog with UVM).

➤ Can be used to verify non-Chisel designs as well thanks to Chisel Blackboxes.

#### REFERENCES

- ➤ IEEE Standard for SystemVerilog—Unified Hardware Design, Specification, and VerificationLanguage.IEEE Std 1800-2017 (Revision of IEEE Std 1800-2012), pages 1–1315, 2018.
- C. Spear; SystemVerilog for verification: a guide to learning the testbench language features; Springer Science & Business Media, 2008.
- ➤ K. Kuchcinski and R. Szymanek, "Jacop java constraint programming solver," 2013, cP Solvers: Modeling, Applications, Integration, and Standardization, co-located with the 19th International Conference on Principles and Practice of Constraint Programming; Conference date: 16-09-2013.
- ➤ Xillinx AXI reference guide: <a href="https://www.xilinx.com/support/documentation/">https://www.xilinx.com/support/documentation/</a> ip\_documentation/axi\_ref\_guide/latest/ug1037-vivado-axi-reference-guide.pdf

#### GETTING STARTED USING CHISELVERIFY

> Current Project repository:

https://github.com/chiselverify/chiselverify/

> Project Wiki (Good way to get started):

https://github.com/chiselverify/chiselverify/wiki/

➤ ChiselVerify is published on Maven. To use it, add following line to your build.sbt:

libraryDependencies += "io.github.chiselverify" % "chiselverify" % "0.1"

## QUESTIONS?