Embedded Software Engineering

3 Unit Course, Winter 2010 CS Department, Univ. of Salzburg

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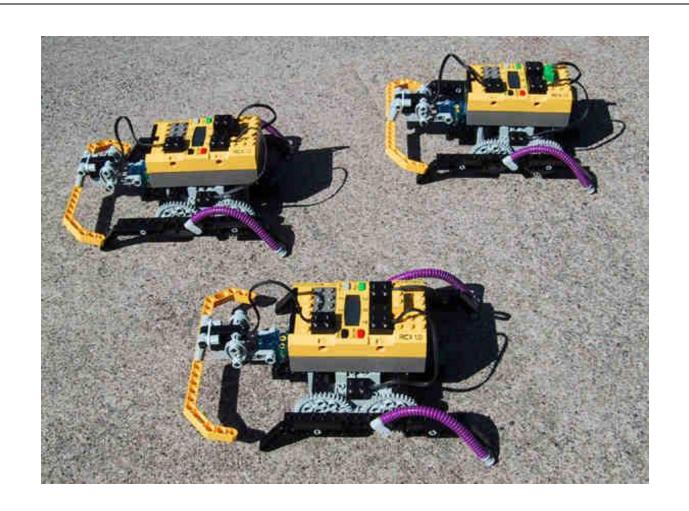
It's significant



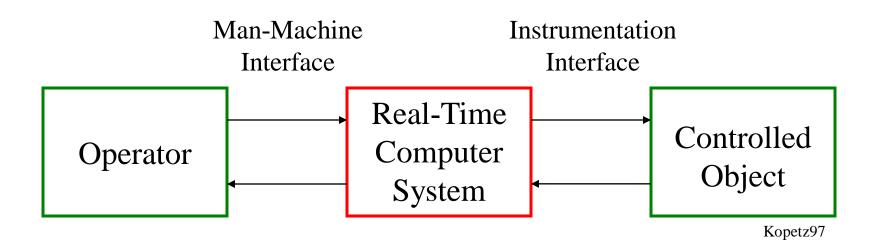
It's risky



It's fun



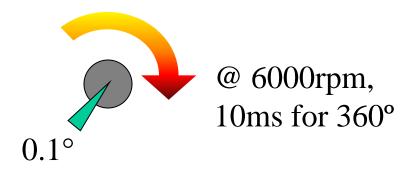
Problem



Methodologies for the implementation of embedded real-time applications

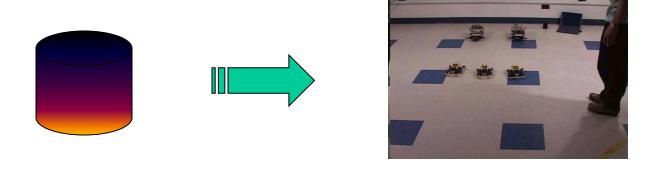
- Methodology: tool-supported, abstract, compositional
- Implementation: compositional, scalable, dependable

Engine Controller



- Temporal accuracy of 3µsec
- Up to 100 concurrent software tasks
- Hard real-time: no missed deadlines

Video Streaming



- 25 frames/sec
- Dynamic resource allocation
- Soft real-time: degraded QoS

Real-Time Systems

Characteristics	Hard	Soft
Response time	Hard-required	Soft-desired
Peak-load performance	Predictable	Degraded
Control of pace	Environment	Computer
Redundancy	Active	Checkpoint
Error detection	Autonomous	User assisted

Kopetz97

Mechatronics

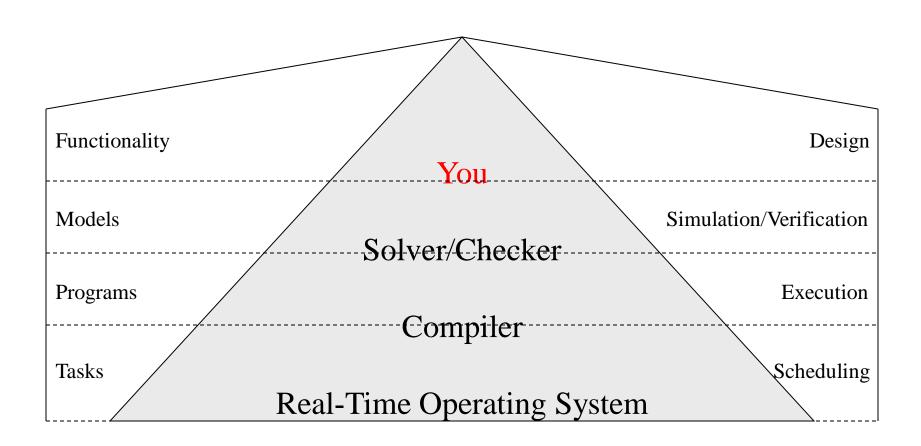


Fly-by-wire

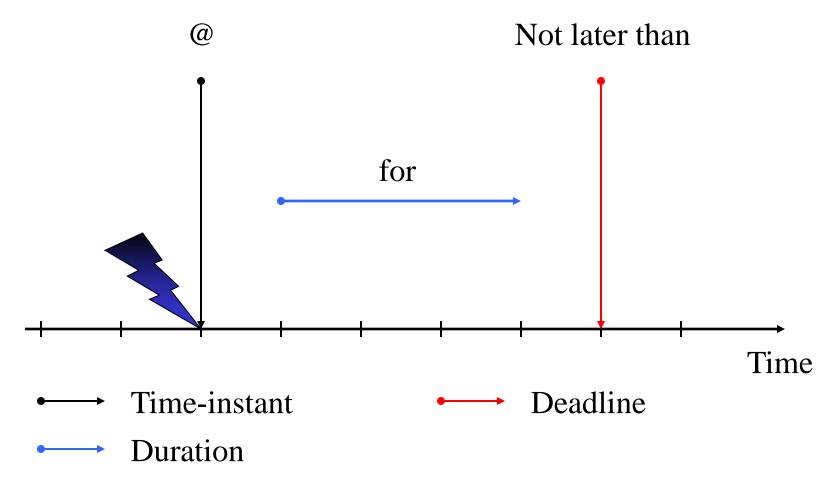


Drive-by-wire

Embedded Software Engineering



Real Time



Concurrency

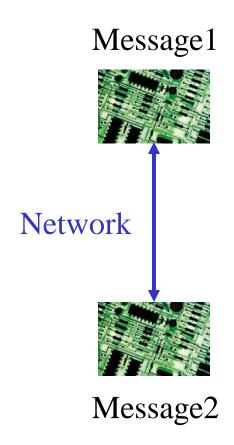
Task1 Task2



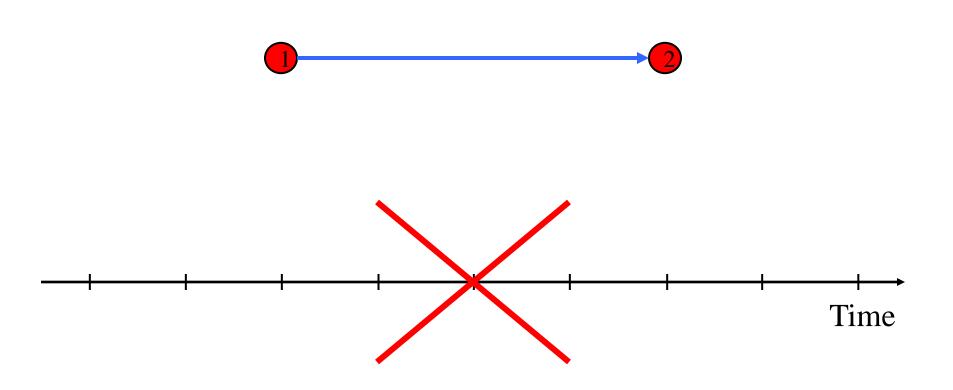
Host

In addition:

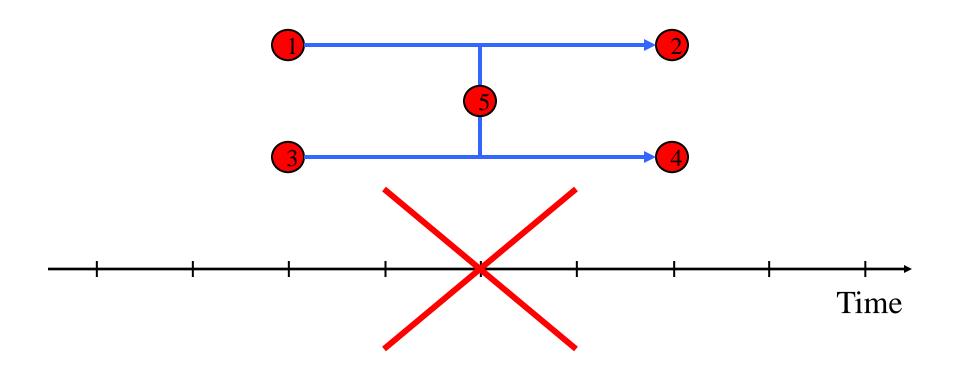
- Other resource constraints
- Time constraints



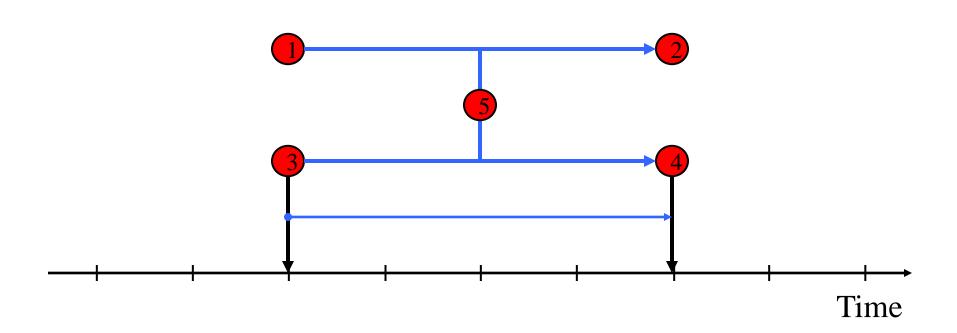
Sequential Programming



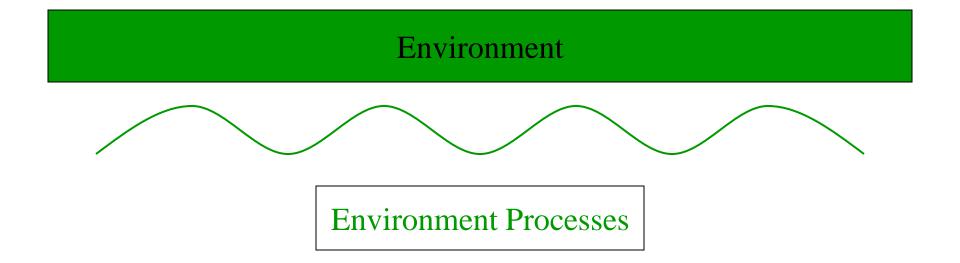
Multiprogramming

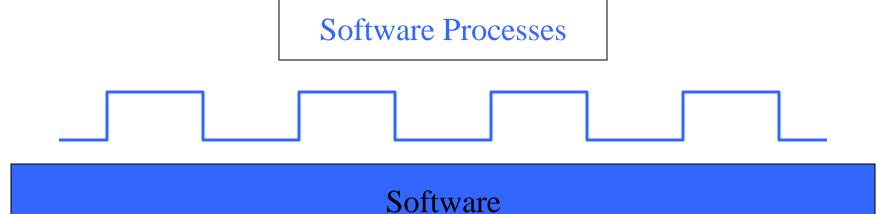


Real-Time Programming

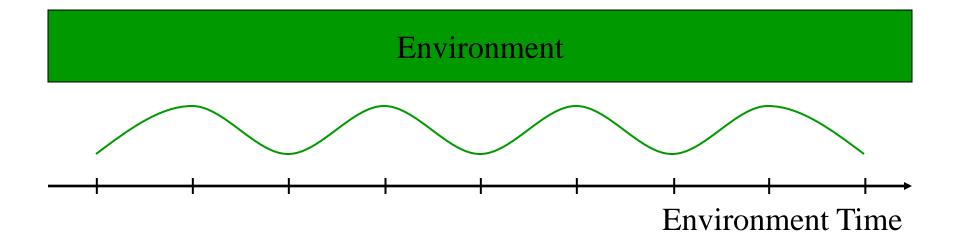


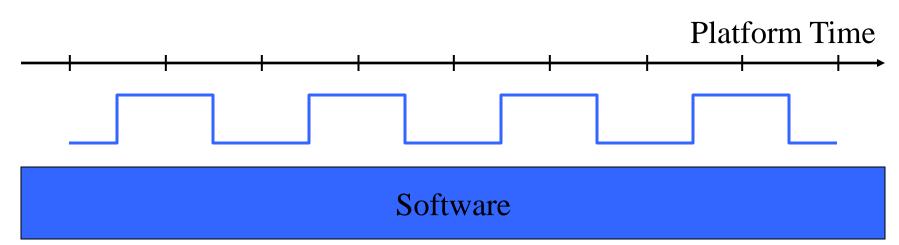
Embedded Software





Environment vs. Platform Time





The Art of Embedded Programming

