

# Explicit, Dynamic Memory Management with Temporal and Spatial Guarantees

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Universität Salzburg



Artist Summer School 2009  
Tsinghua University, Beijing, China

# Memory Management

- Allocation:
  - ▶ `malloc`

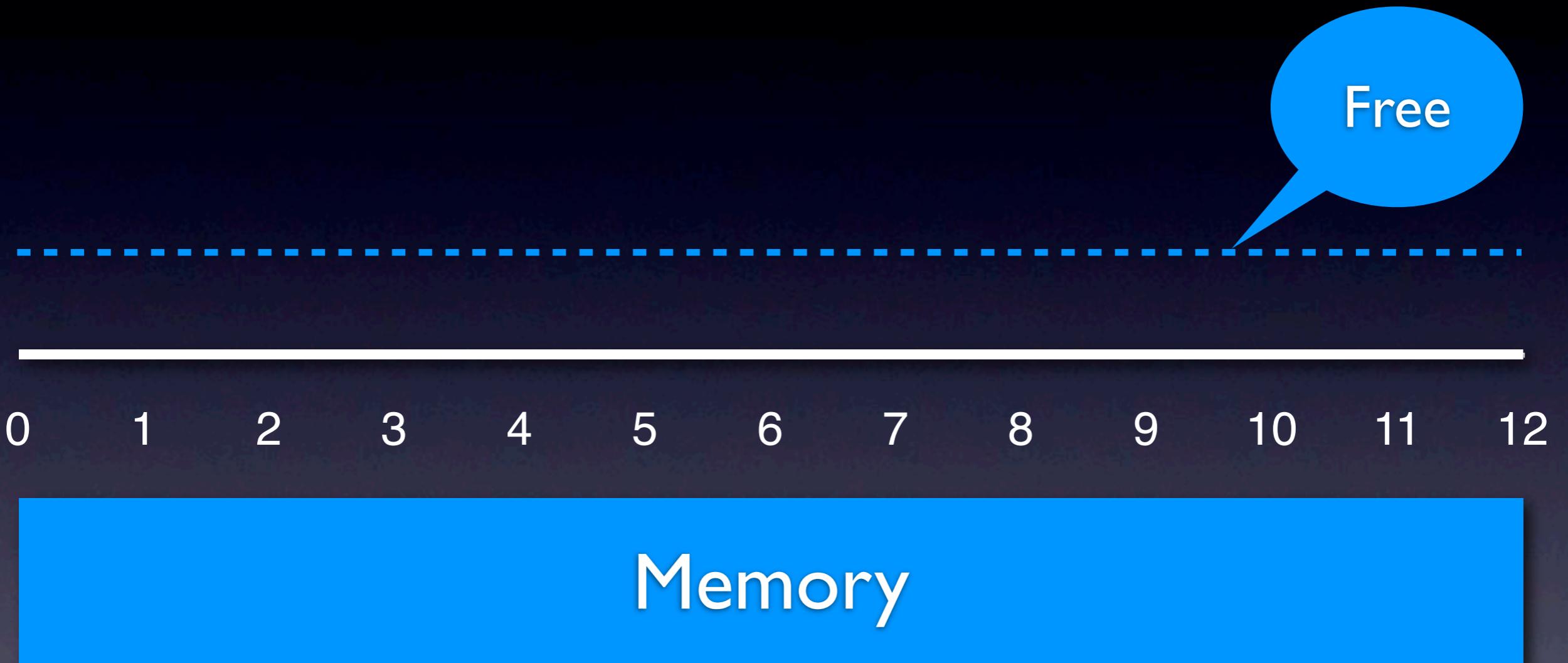
# Memory Management

- Allocation:
  - ▶ `malloc`
- Deallocation:
  - ▶ `free`

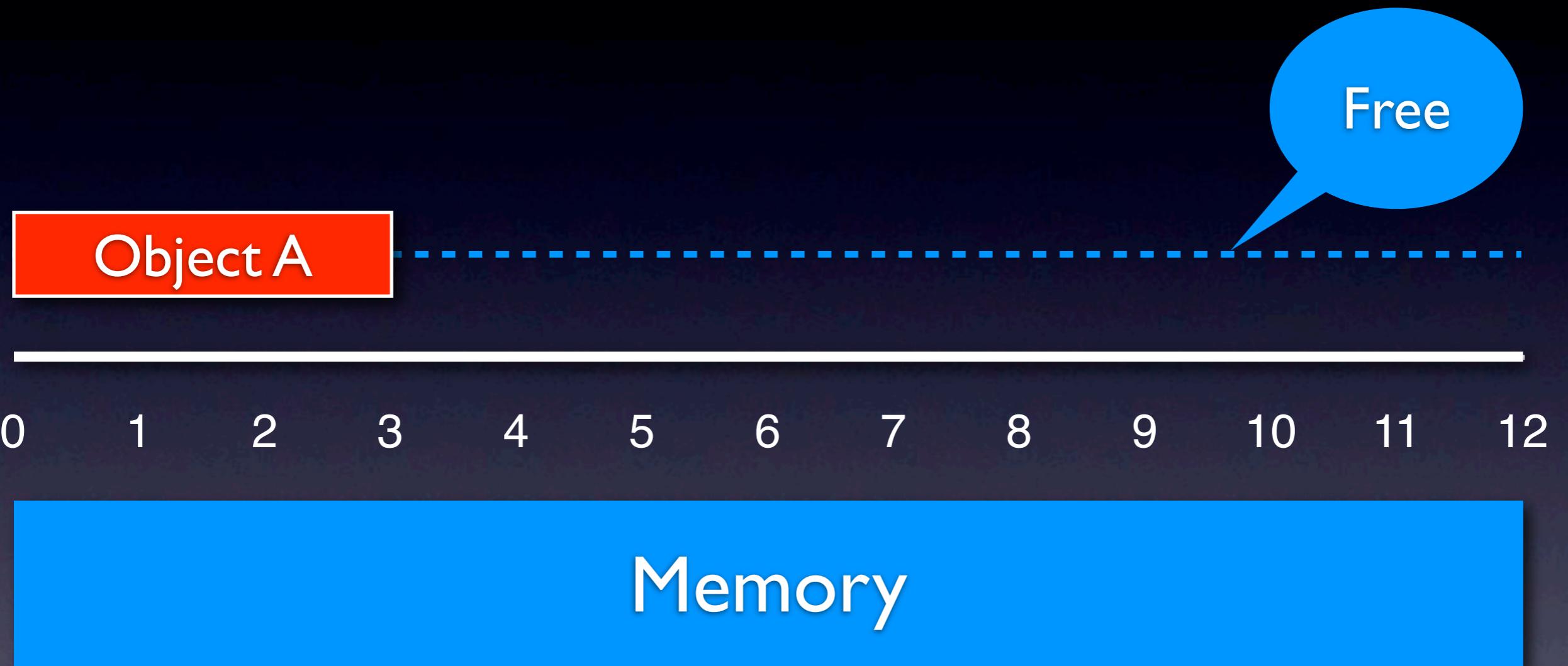
# Memory Management

- Allocation:
  - ▶ `malloc`
- Deallocation:
  - ▶ `free`
- Access:
  - ▶ `read` and `write`

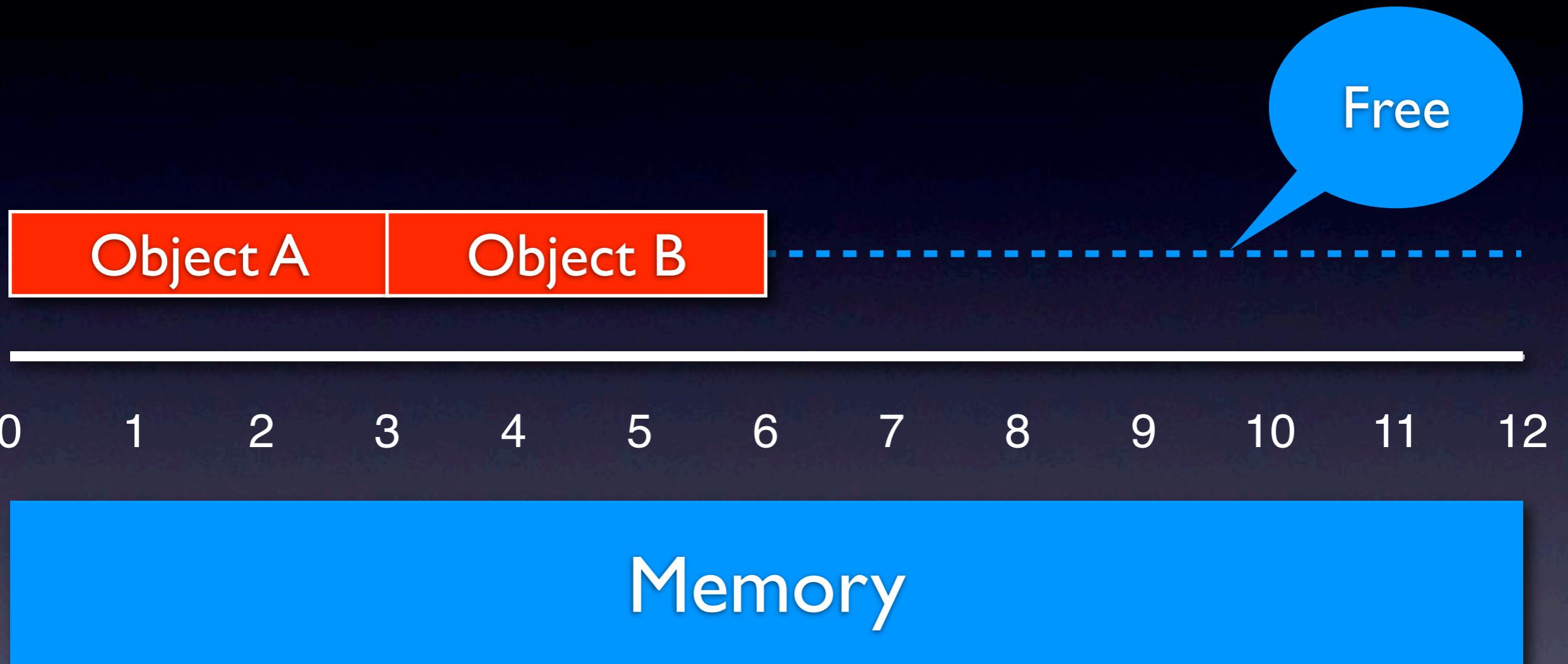
# Allocation



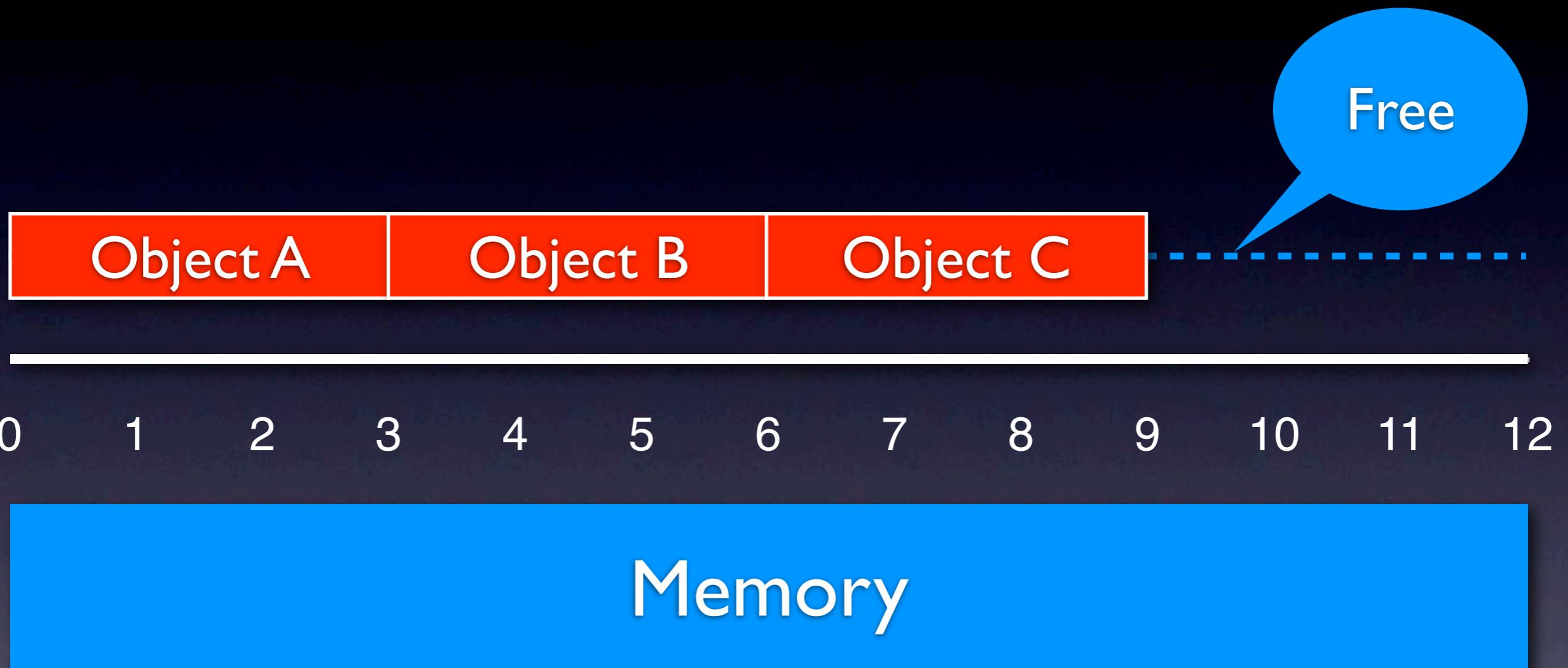
# Allocation



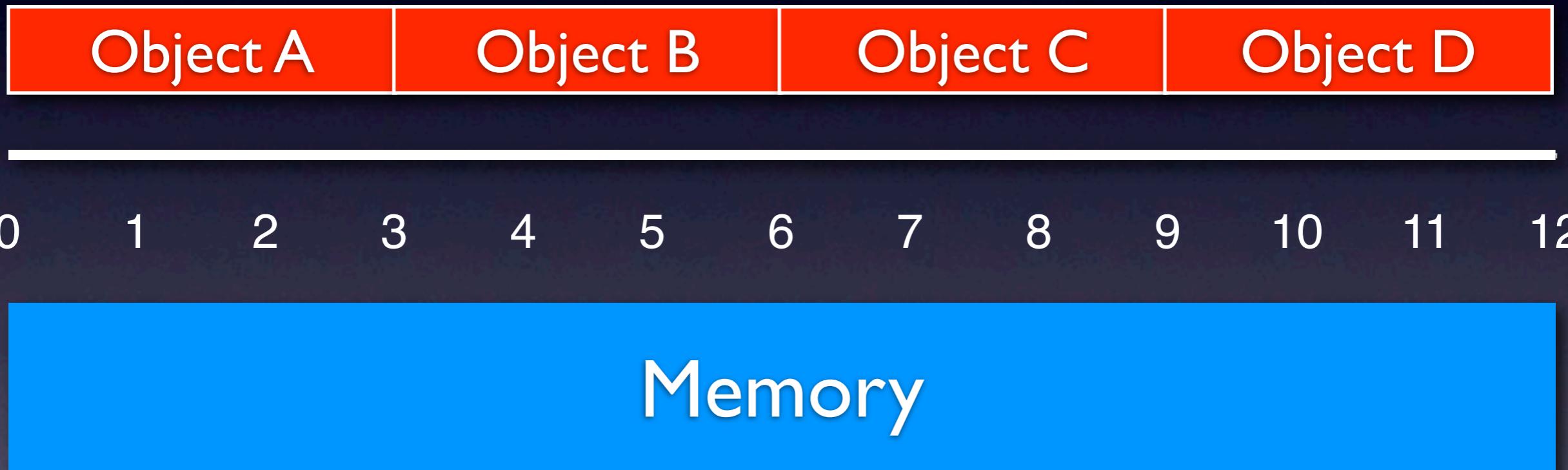
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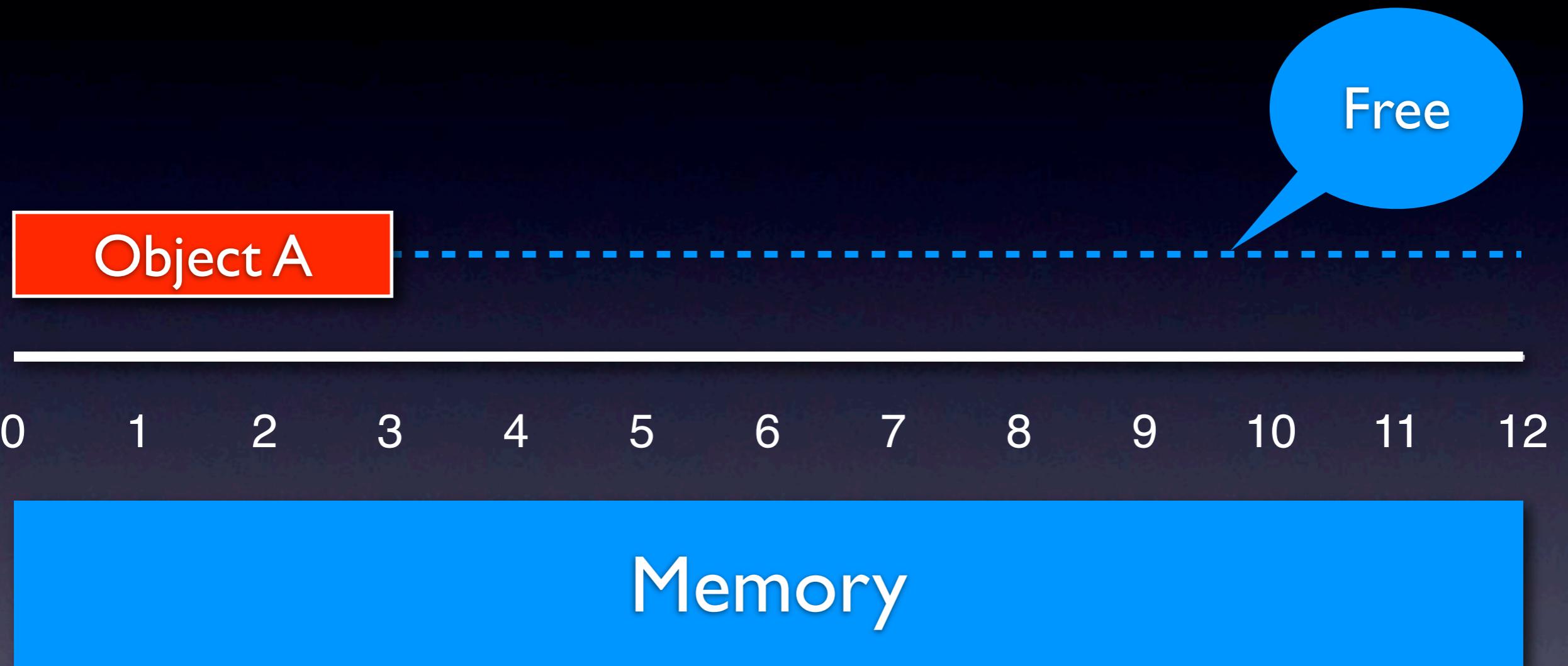
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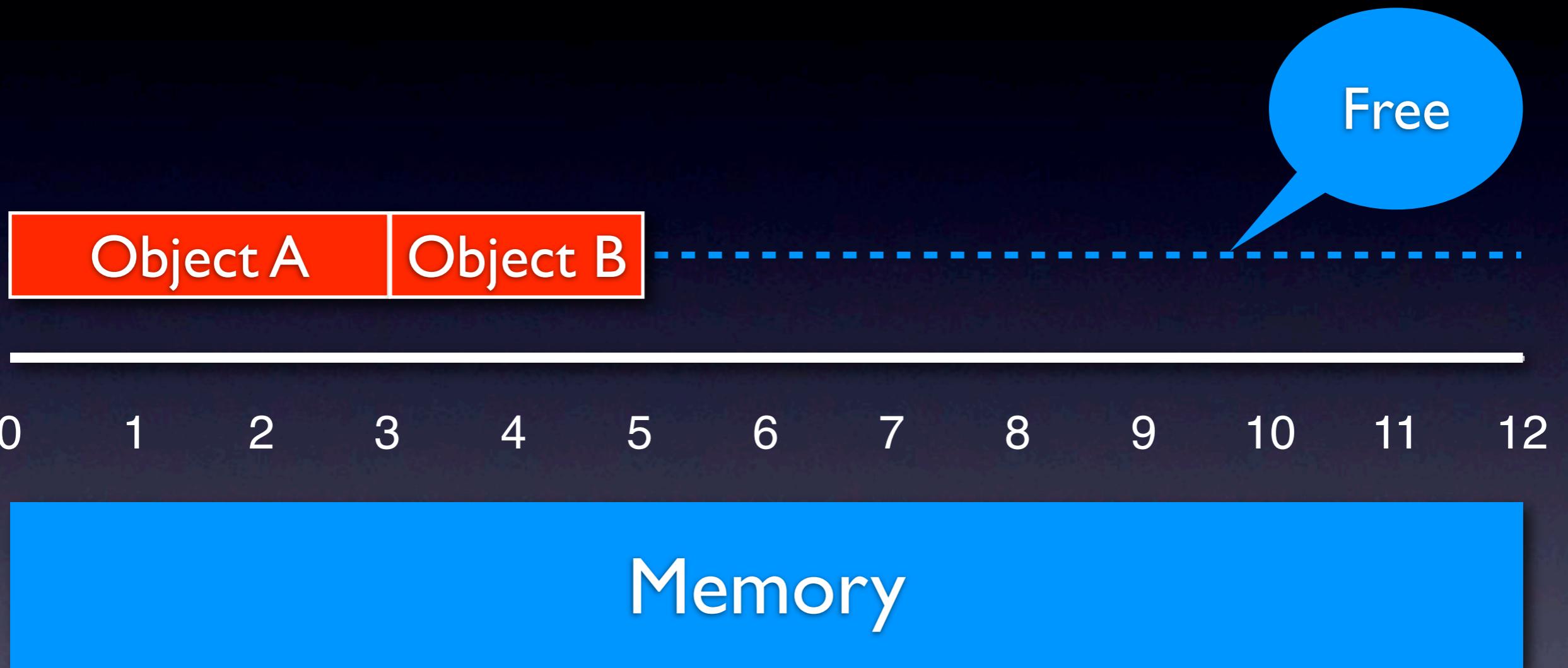
# I.Assumption:

Objects may have  
**different sizes**

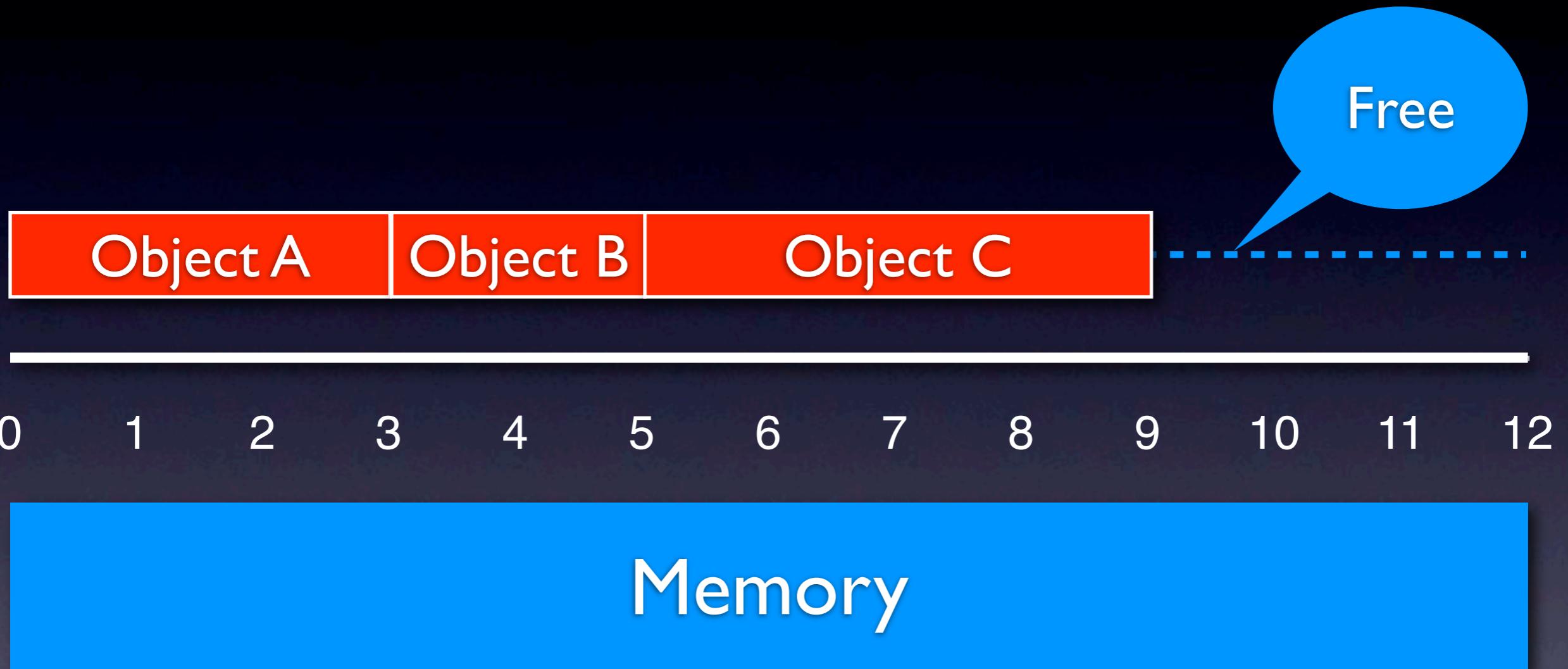
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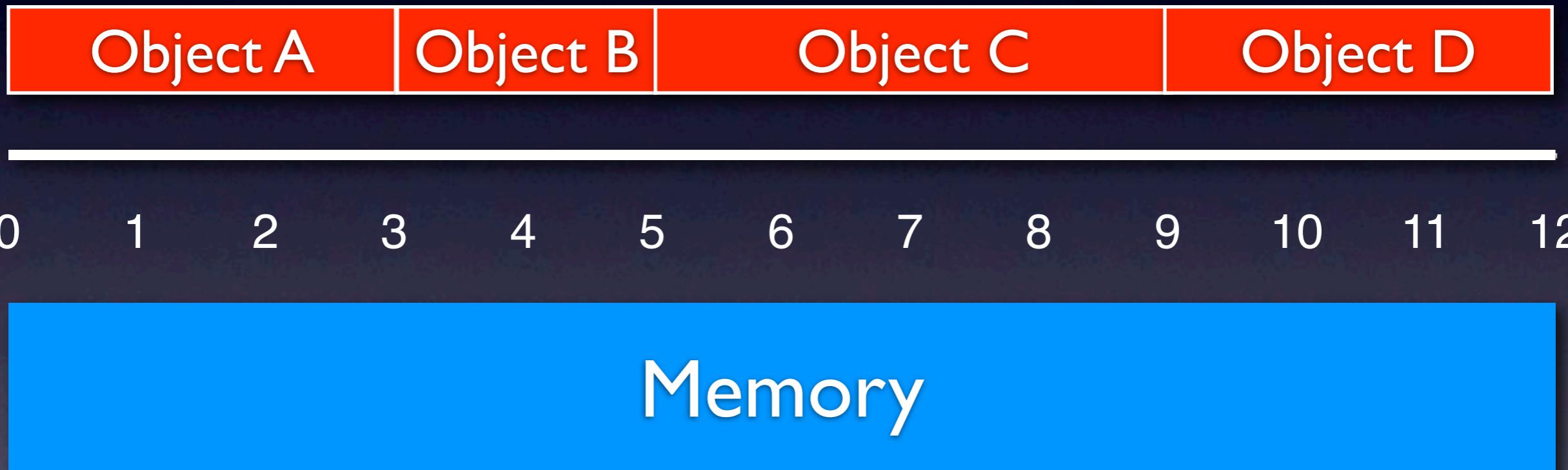
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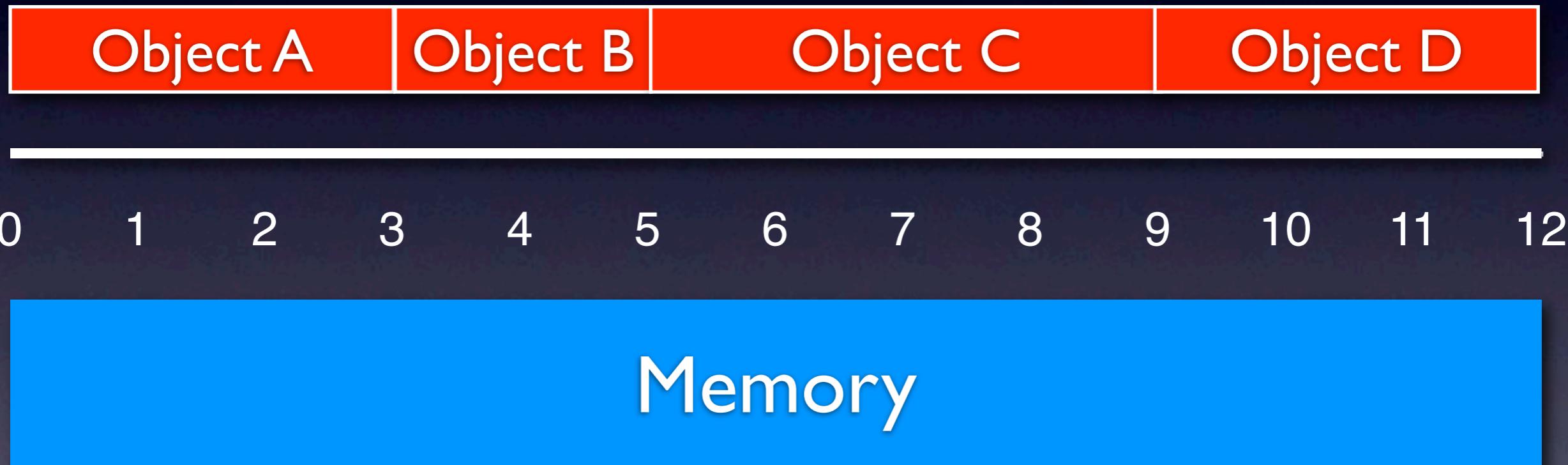
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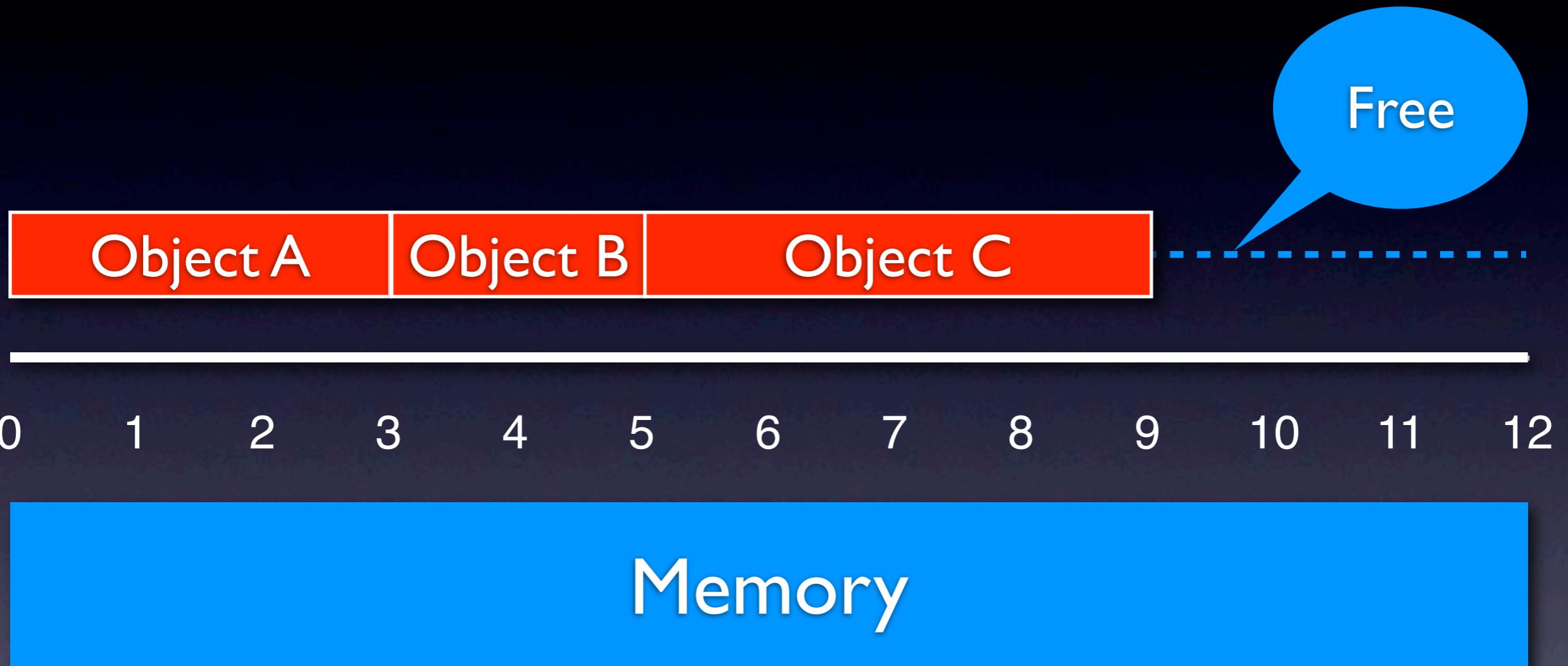
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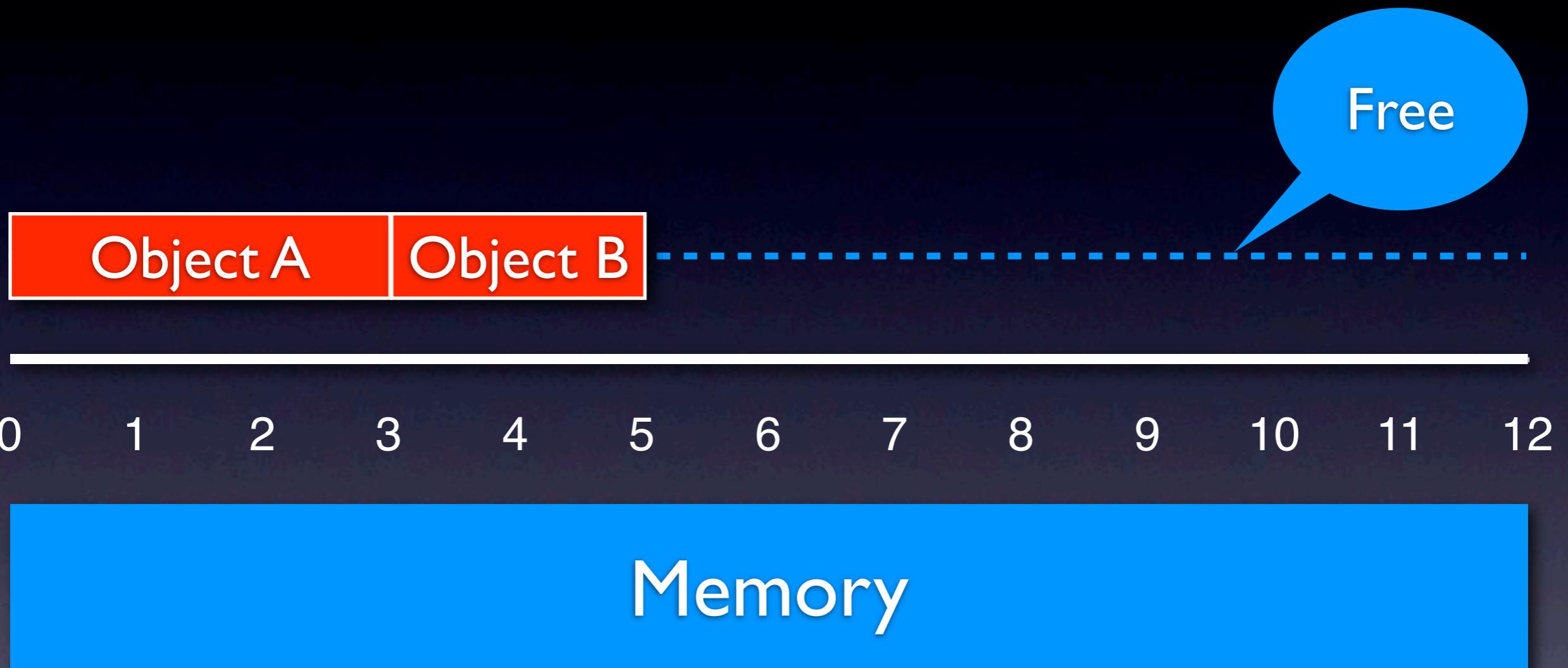
# Deallocation



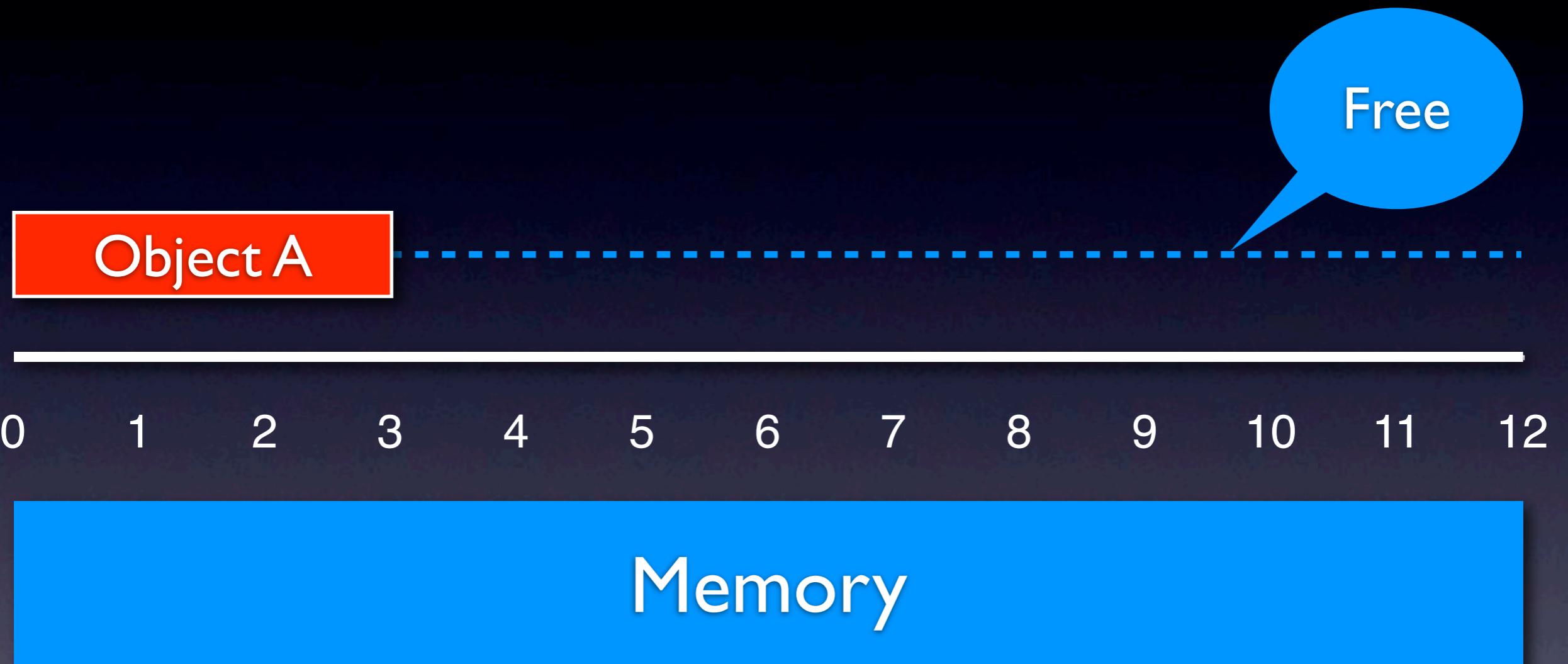
# Deallocation



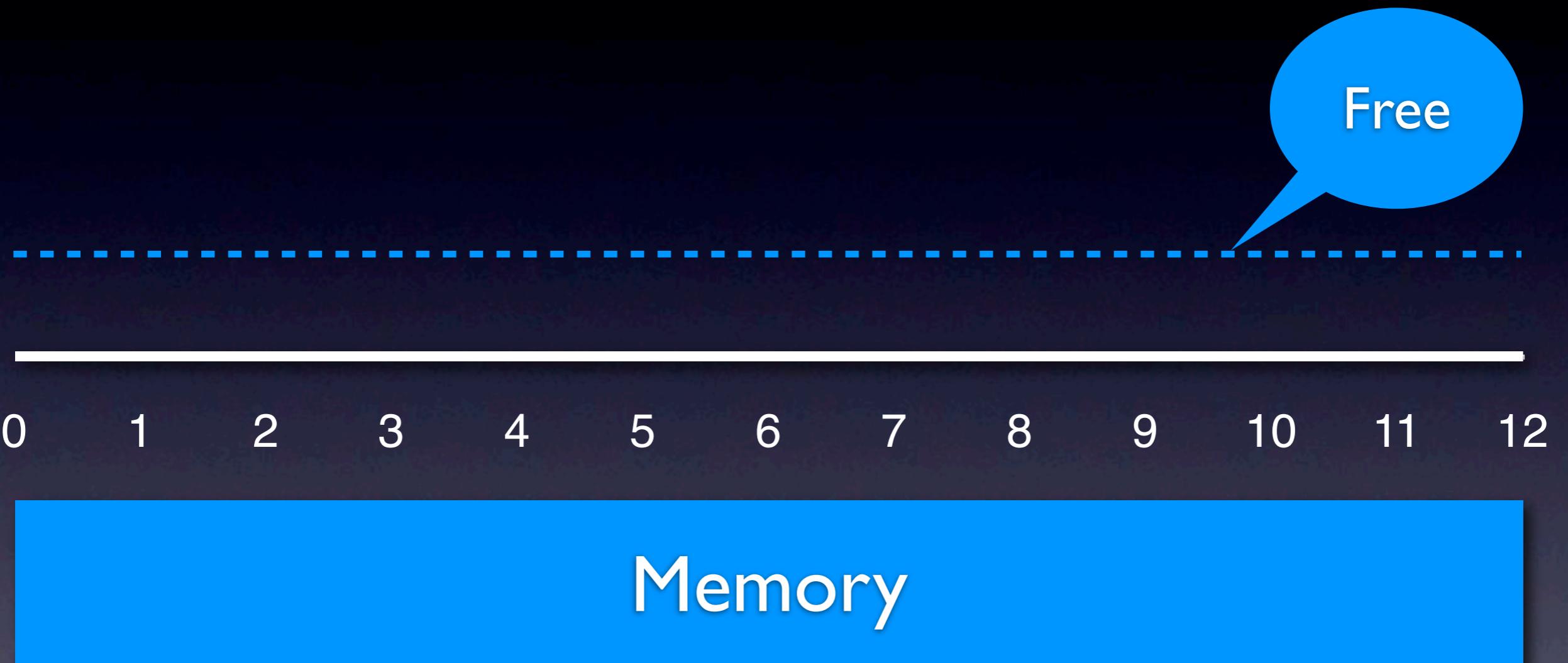
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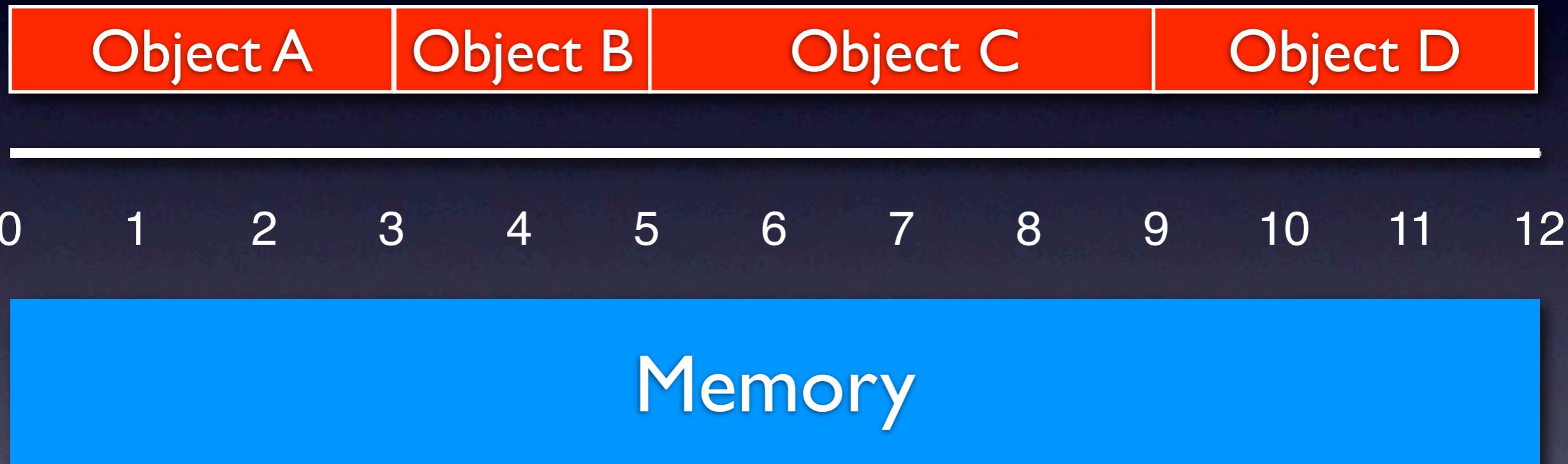
# Deallocation



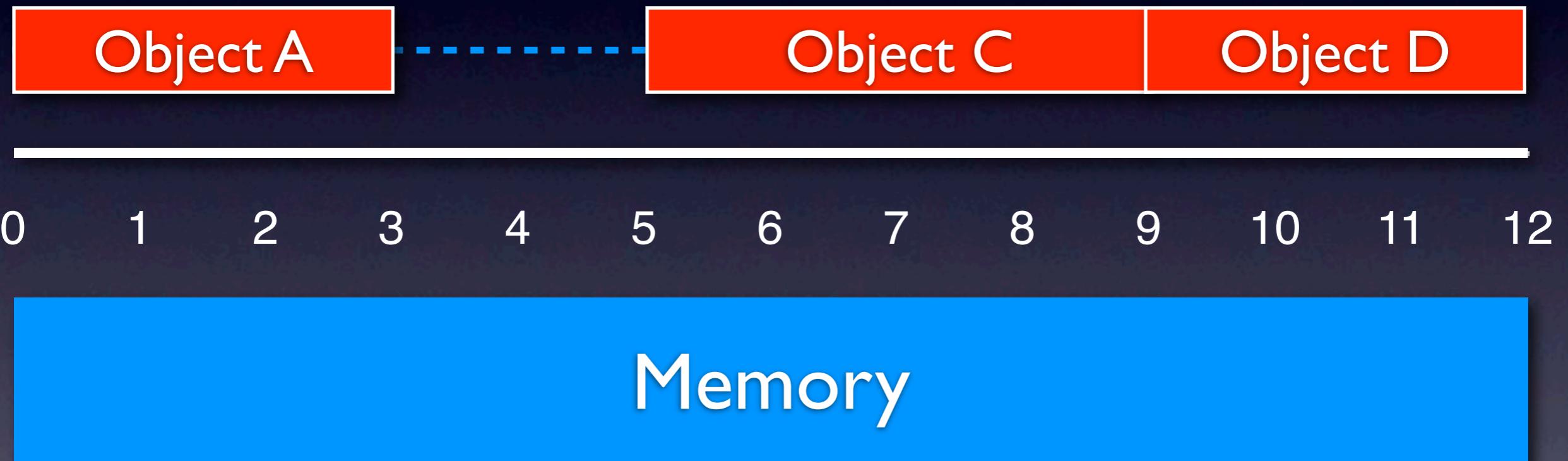
## 2. Assumption:

Objects may be  
allocated and deallocated  
in random order

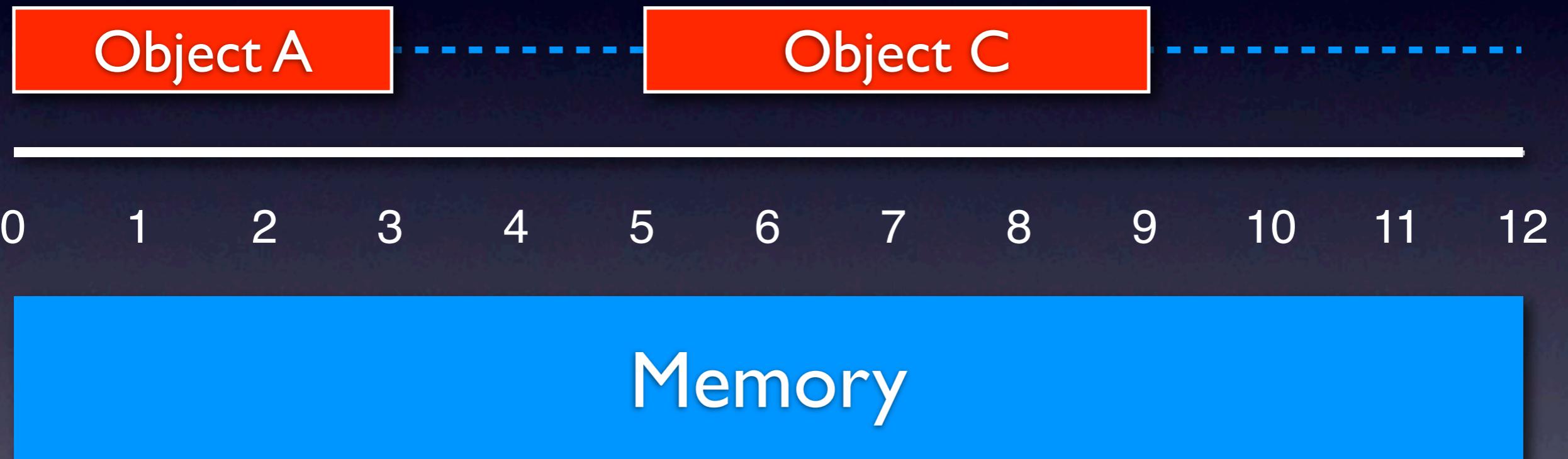
# Deallocation



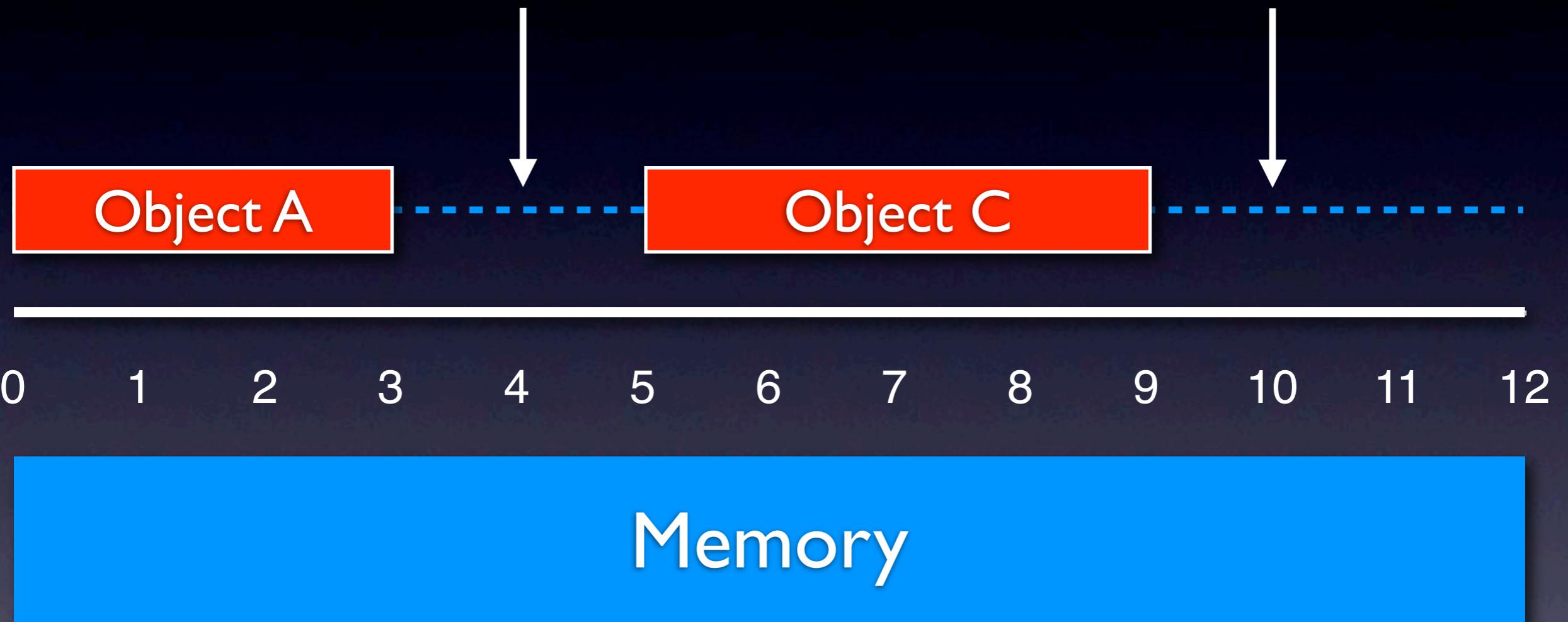
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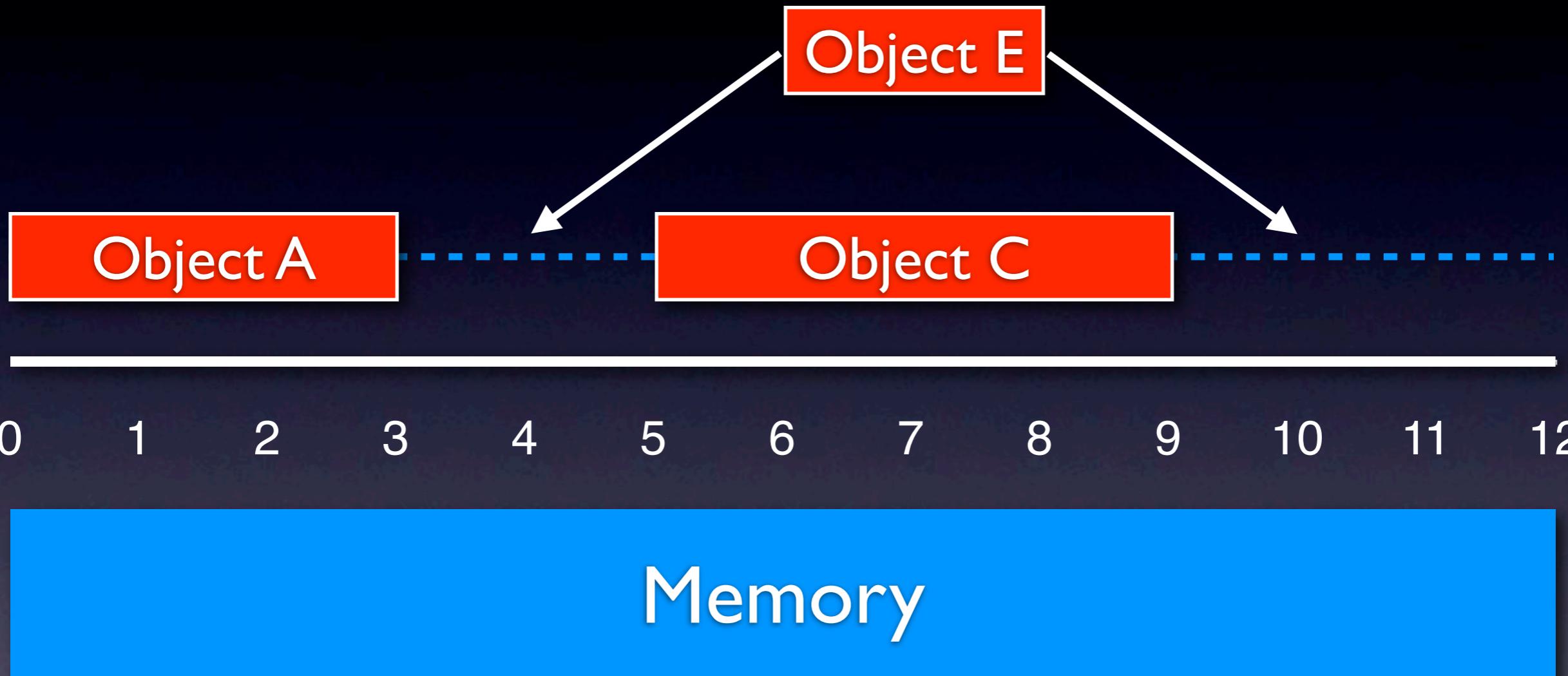
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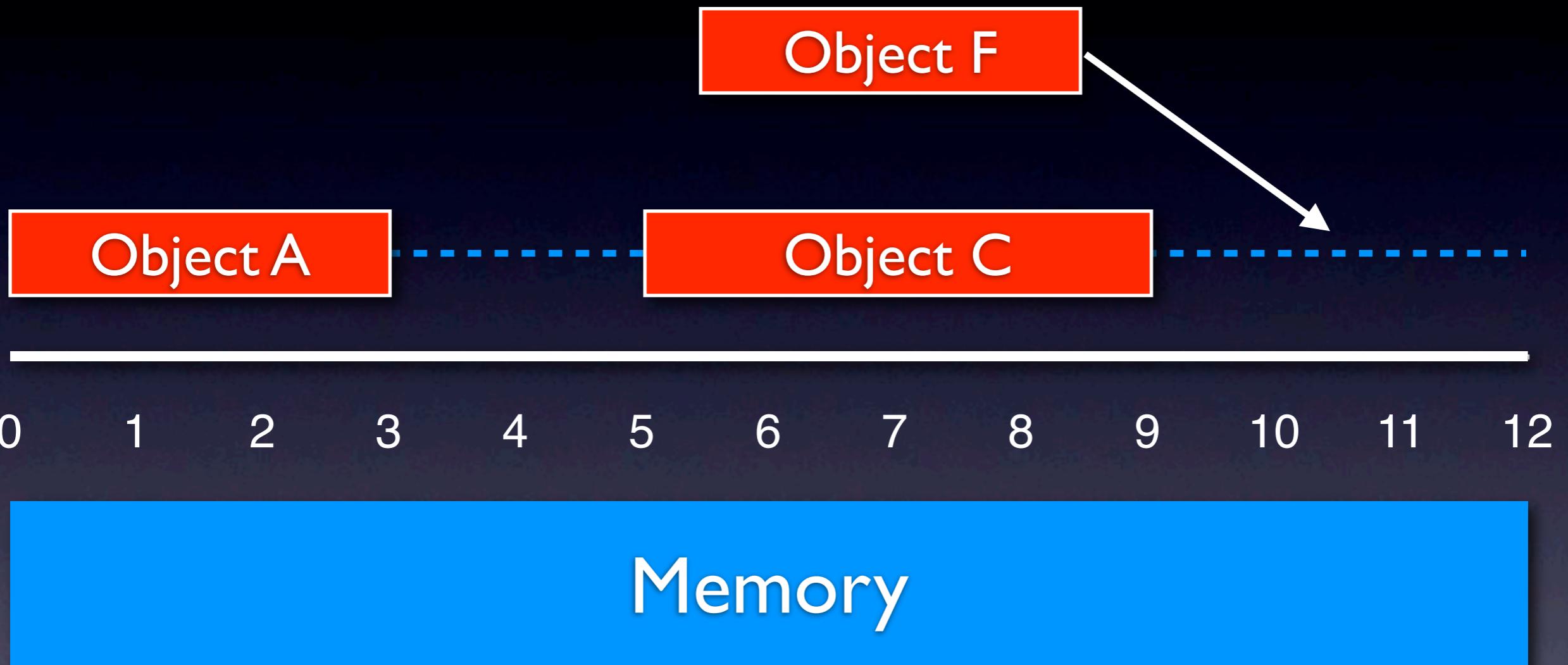
# External Fragmentation



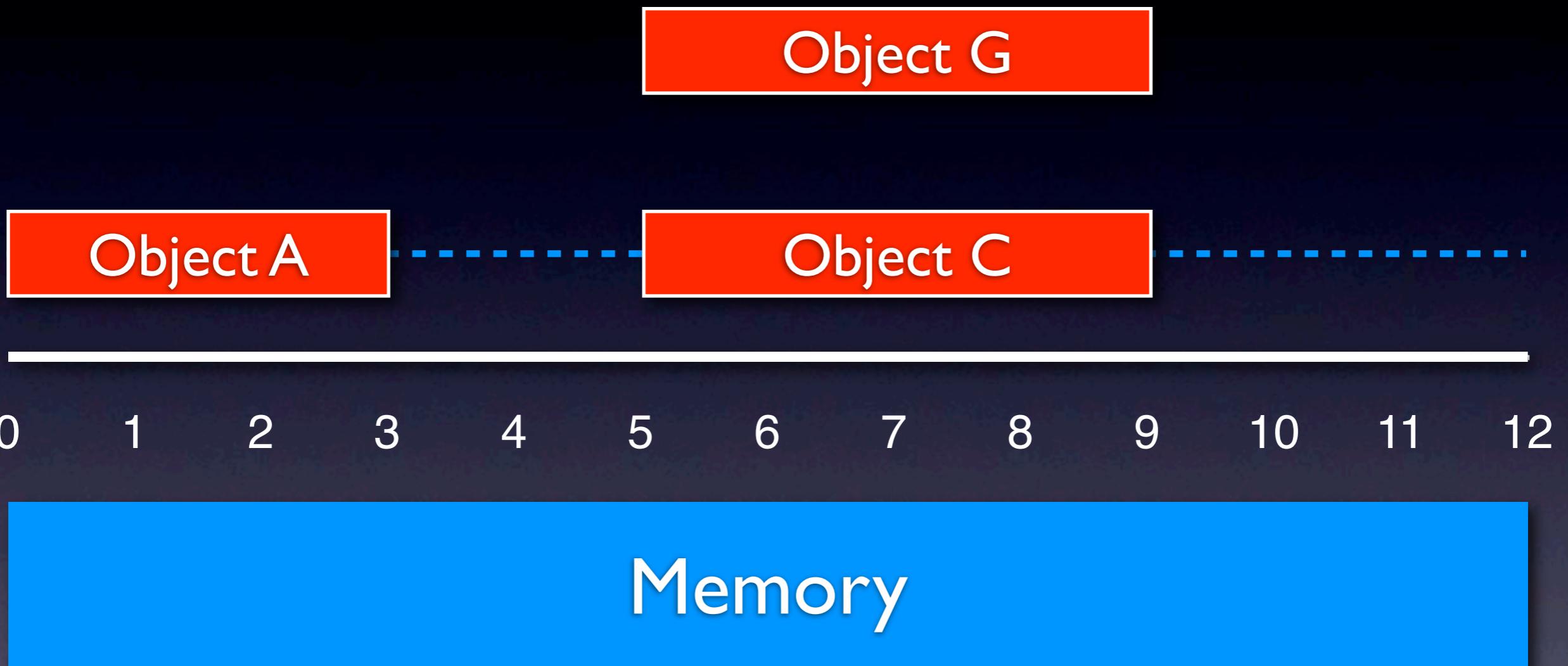
# Allocation



# Allocation



# Allocation



Memory is fragmented if  
the largest, contiguous  
piece of available space  
is  
smaller than  
the **total** available space

# Fragmentation

- Memory objects may have **different sizes**
  - Memory objects may be allocated and deallocated in **random** order
- ▶ creates the problem of memory **fragmentation!**

# Explicit, Dynamic Memory Management with Temporal and Spatial Guarantees

# Static versus Dynamic

- **Static memory management:**
  - ▶ Preallocate all memory at **compile time**

# Static versus Dynamic

- **Static memory management:**
  - ▶ Preallocate all memory at **compile time**
- **Dynamic memory management:**
  - ▶ Allocate and deallocate memory at **run time**

# Explicit, Dynamic Memory Management with Temporal and Spatial Guarantees

# Implicit versus Explicit

- **Implicit**, dynamic memory management:
  - ▶ Garbage collector (GC) deallocates objects, not programmer (**implicit free calls by GC**)

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- **Implicit**, dynamic memory management:
  - ▶ Garbage collector (GC) deallocates objects, not programmer (**implicit free calls by GC**)
- **Explicit**, dynamic memory management:
  - ▶ Objects are deallocated by programmer (**explicit free calls**)

# Programming Abstraction

# Runtime Overhead

Implicit, Dynamic Memory Management

Explicit, Dynamic Memory Management

Static Memory Management

# Programming Abstraction

# Runtime Overhead

Implicit

Web, Safety

Explicit

Server, Performance

Static

Embedded, Real Time

# Programming Abstraction

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# Programming Abstraction

# Runtime Overhead

Implicit

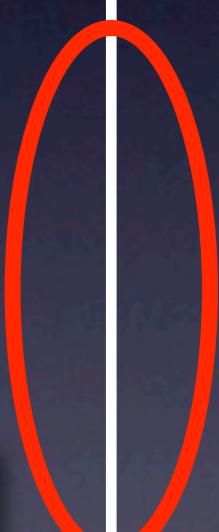
Web, Safety

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# Temporal Performance

- Throughput:
  - ▶ 10MB/s **allocation** rate
  - ▶ 10MB/s **deallocation** rate

# Temporal Performance

- Throughput:
  - ▶ 10MB/s **allocation** rate
  - ▶ 10MB/s **deallocation** rate
- Latency/Responsiveness:
  - ▶ 1ms **execution** time (malloc/free)
  - ▶ 0.1ms **preemption** time (malloc/free)

# Spatial Performance

- Degree of fragmentation:
  - ▶ The **number** of contiguous pieces of memory of a given size that can still be allocated

# Spatial Performance

- Degree of fragmentation:
  - ▶ The **number** of contiguous pieces of memory of a given size that can still be allocated
- Administrative space:
  - ▶ **meta** data structures (used, free lists)

There is a trade-off  
between  
**temporal** and **spatial**  
performance

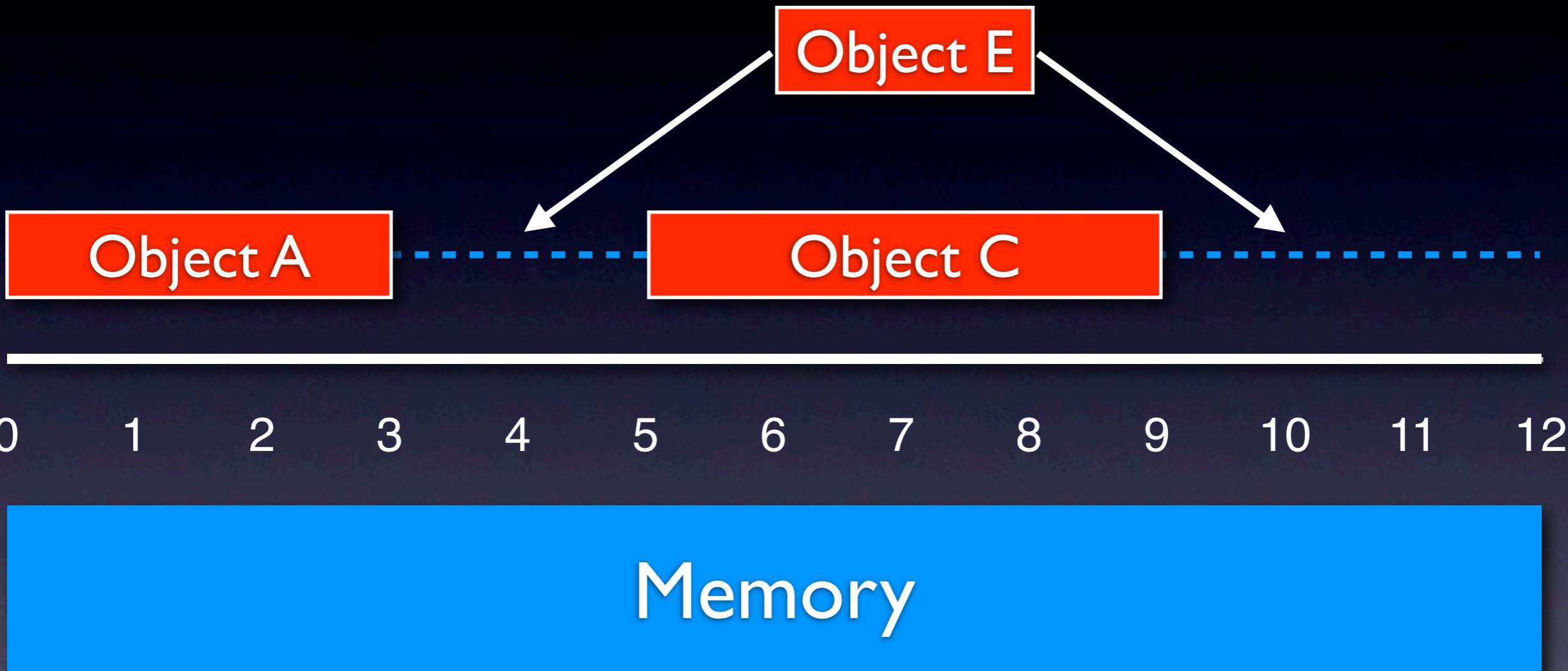
# Temporal Predictability

- Unpredictable complexity (in terms of input):
  - ▶ allocation/deallocation may take time proportional to the total size of memory

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- Unpredictable complexity (in terms of input):
  - ▶ allocation/deallocation may take time proportional to the total size of memory
- Predictable complexity (in terms of input):
  - ▶ allocation/deallocation takes time at most proportional to the size of involved object
  - ▶ access takes time at most proportional to the size of involved object

# Allocation Complexity



It may be difficult to  
improve  
average **performance**  
but it may still be possible to  
improve  
**predictability**  
without loosing too much  
**performance**

# Spatial Predictability

- Unpredictable fragmentation:
  - ▶ the degree of fragmentation may depend on the full allocation and deallocation **history**, i.e., the order of invocations

# Spatial Predictability

- Unpredictable fragmentation:
  - ▶ the degree of fragmentation may depend on the full allocation and deallocation **history**, i.e., the order of invocations
- Predictable fragmentation:
  - ▶ the degree of fragmentation only depends on the **number** of allocations and deallocations, independently of the order of invocations

Time

predictable  
unpredictable

unpredictable

predictable

Space

# Explicit, Dynamic Memory Management with **Temporal** and **Spatial Guarantees**

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# Programming Abstraction

# Runtime Overhead

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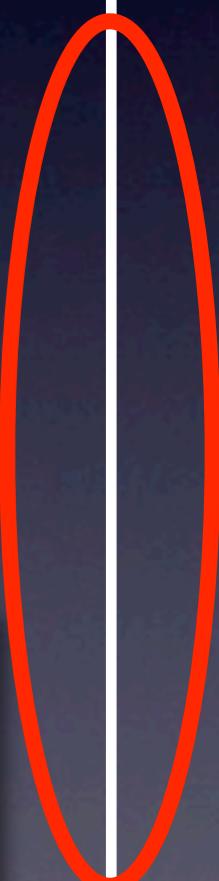
Web, Safety

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- Silviu Craciunas<sup>#</sup> (Programming Model)
- Andreas Haas (Memory Management)
- Hannes Payer<sup>#</sup> (Memory Management)
- Harald Röck (VM, Scheduling)
- Ana Sokolova<sup>\*</sup> (Theoretical Foundation)

<sup>#</sup>Supported by a 2007 IBM Faculty Award, the EU ArtistDesign Network of Excellence on Embedded Systems Design, and Austrian Science Fund Project P18913-N15.

<sup>\*</sup>Supported by Austrian Science Fund Project V00125.

# Tiptoe

- Tiptoe is a microkernel-based virtual machine and process monitor for embedded systems

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- Tiptoe virtualizes the host platform (system VM) and provides infrastructure to run process VMs and processes in real time

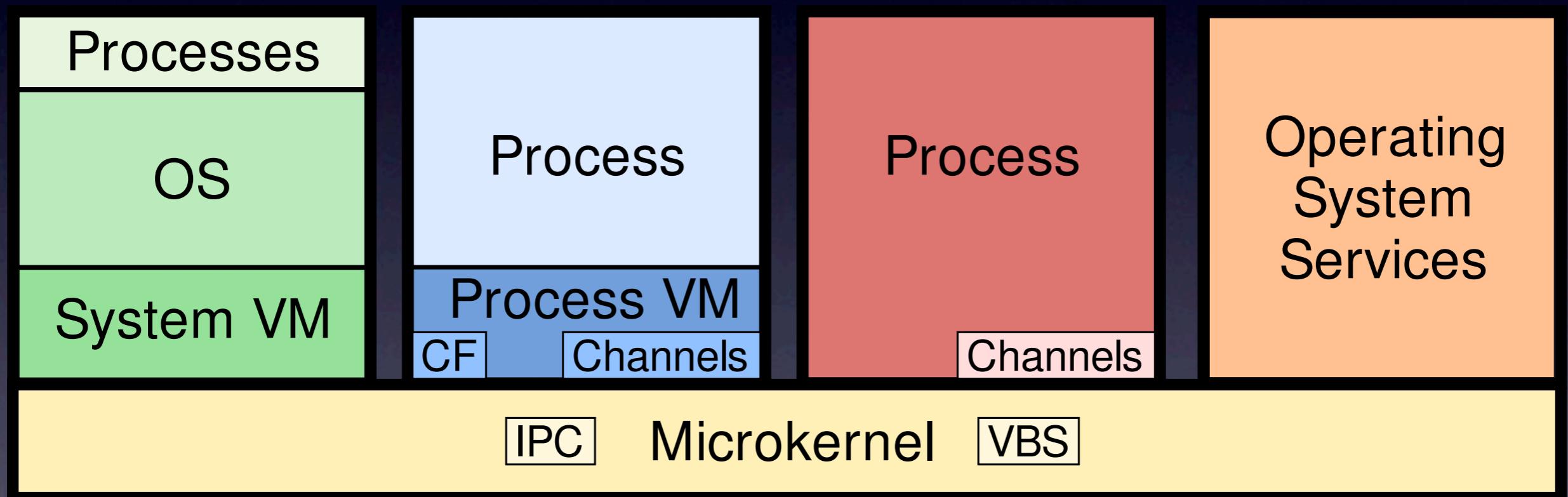
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- Tiptoe is a microkernel-based virtual machine and process monitor for embedded systems
- Tiptoe virtualizes the host platform (system VM) and provides infrastructure to run process VMs and processes in real time
- Tiptoe controls throughput and latency of CPU, memory, and I/O
- I/O is multiplexed through IPC to a system VM running Linux

# Tiptoe



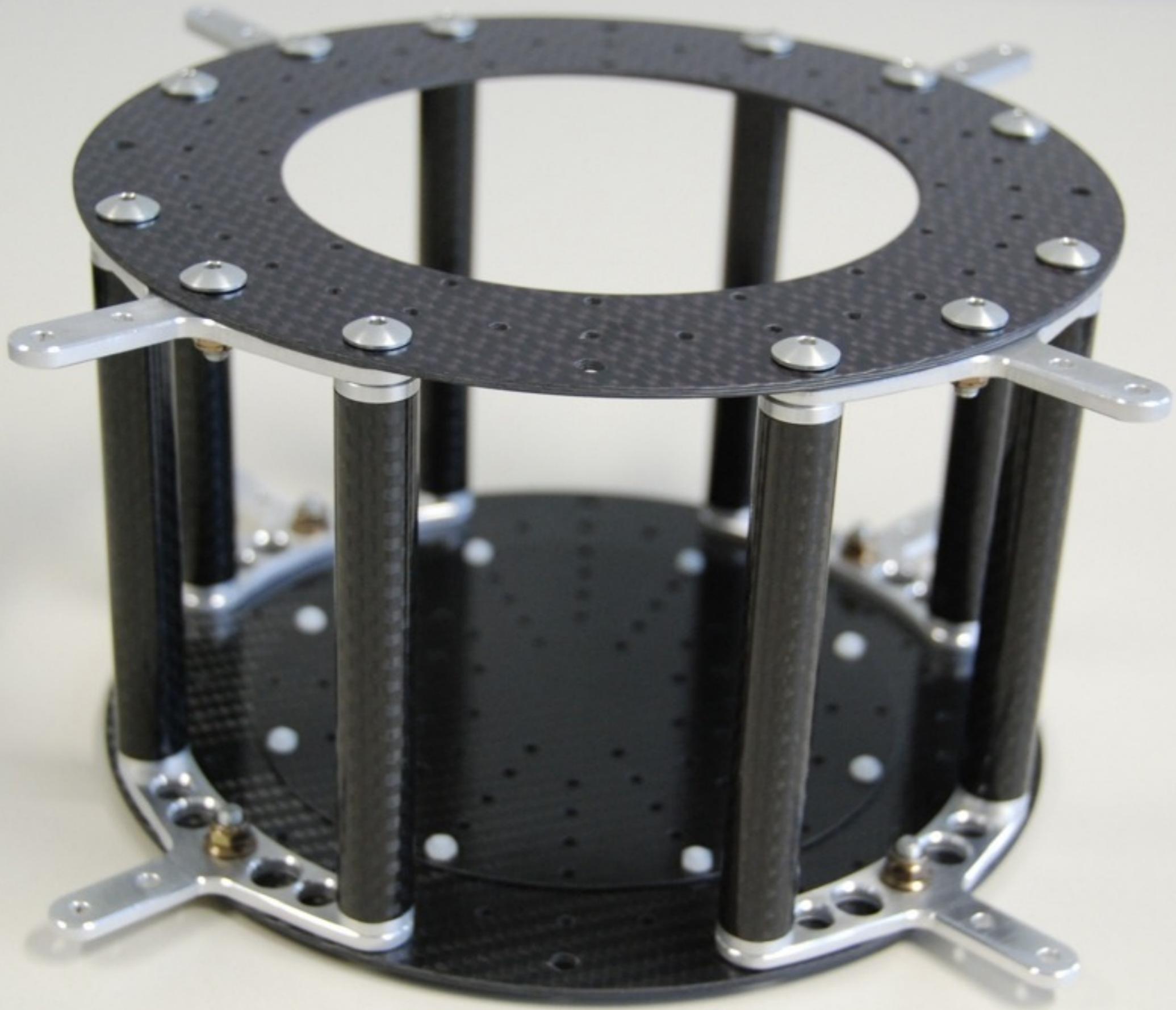


The JAviator  
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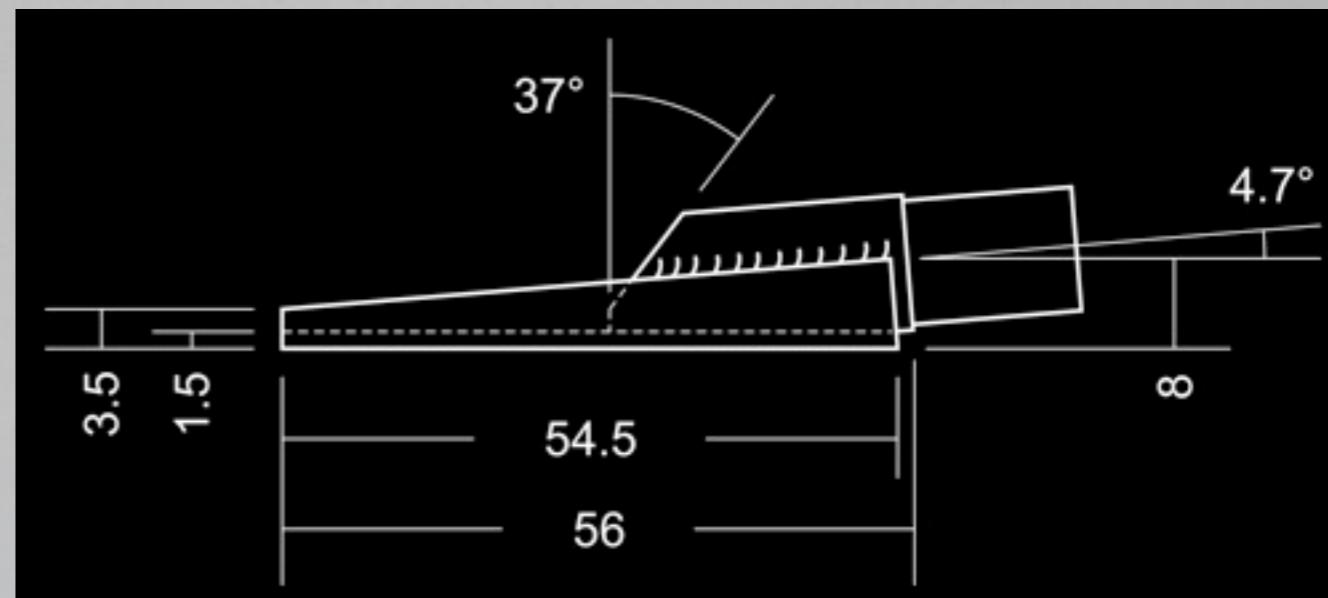
# Quad-Rotor Helicopter

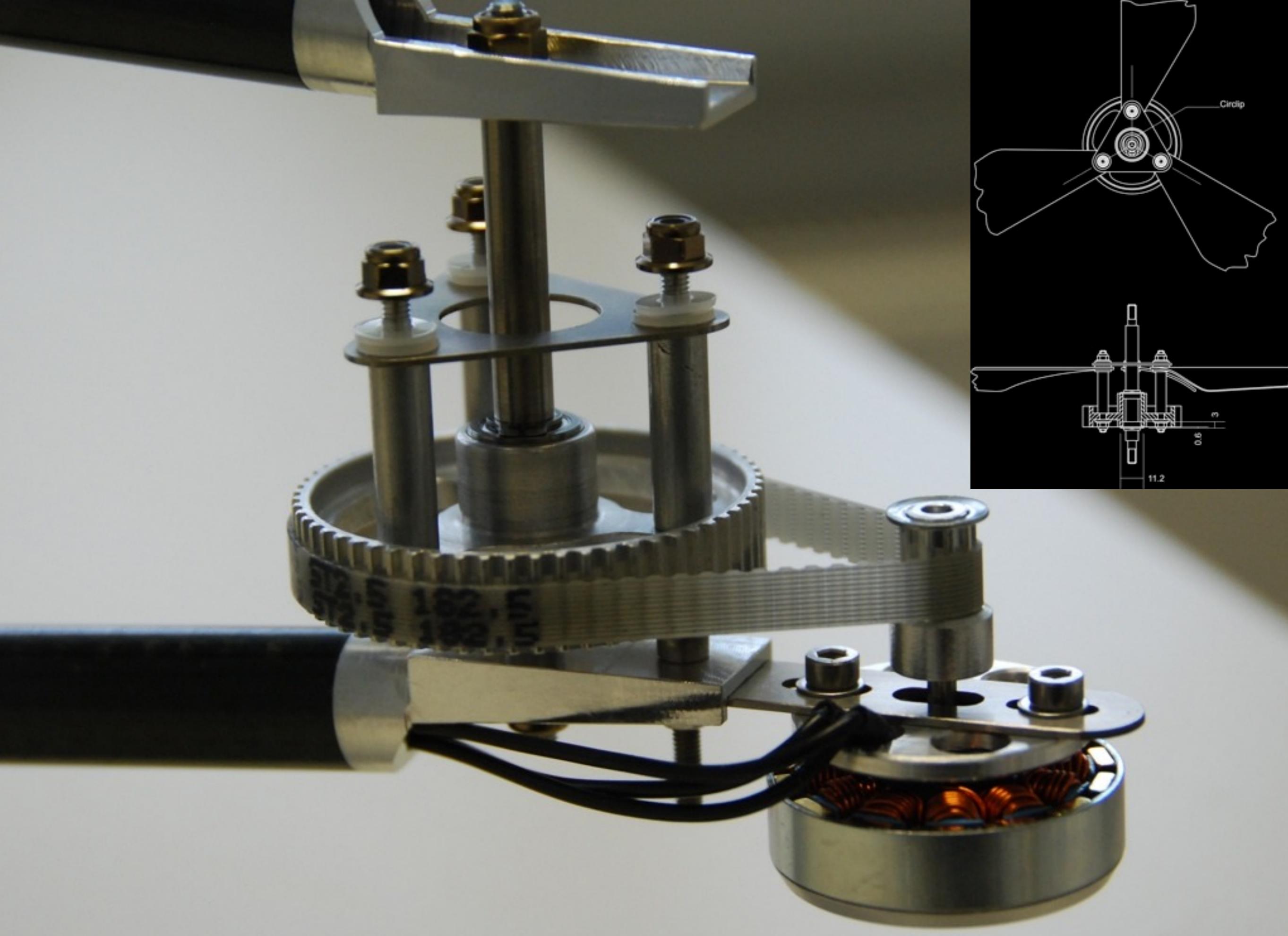








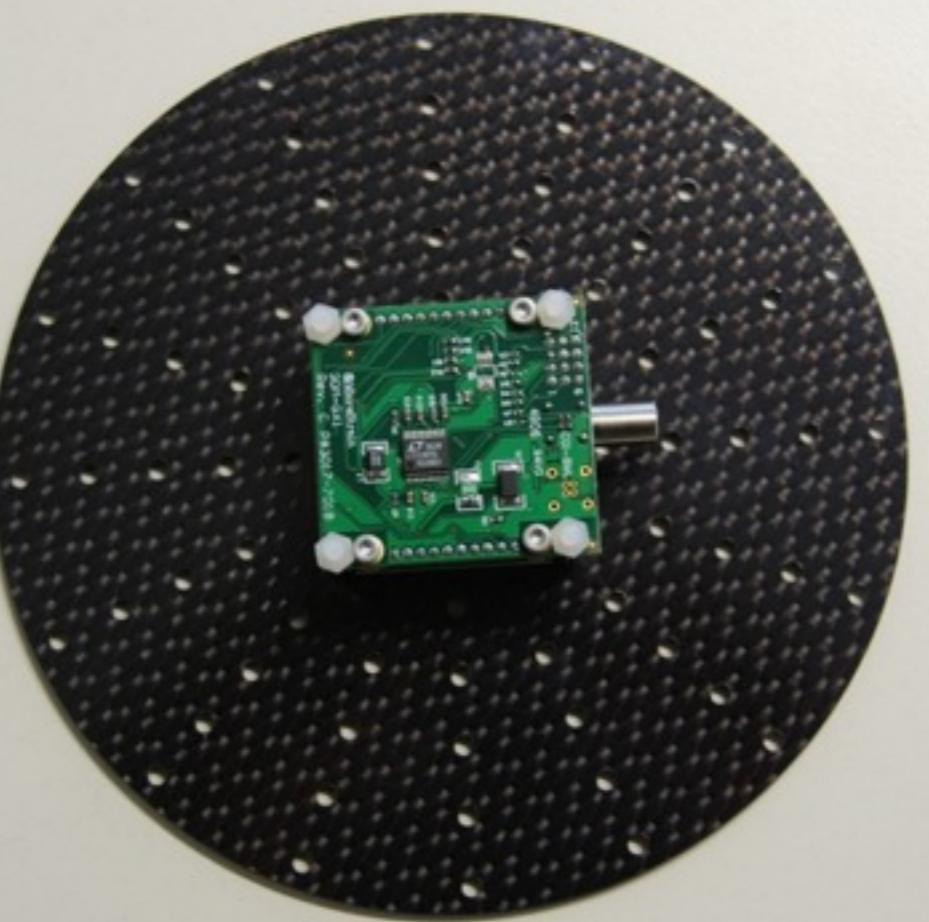




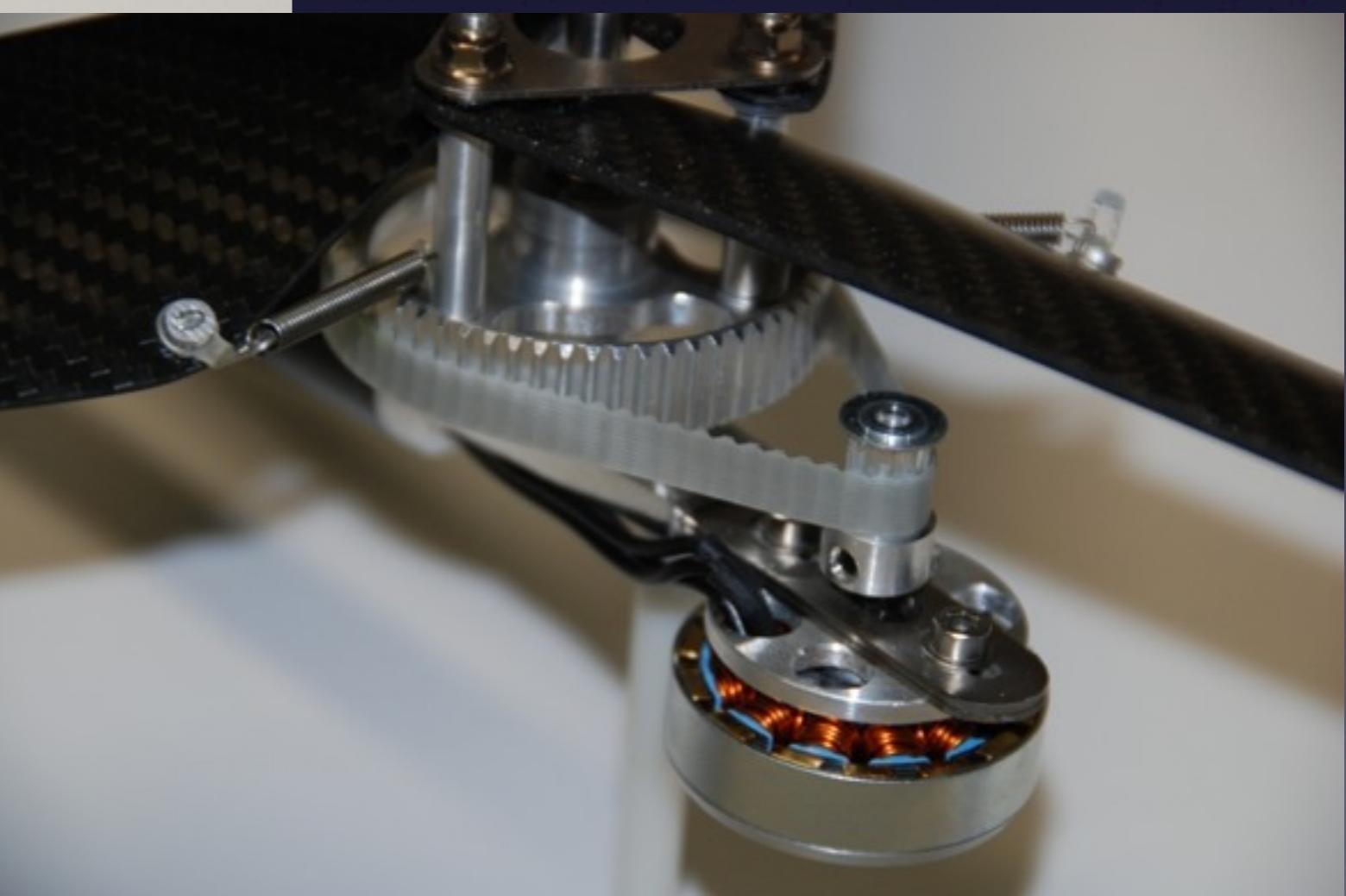


25/12/2005



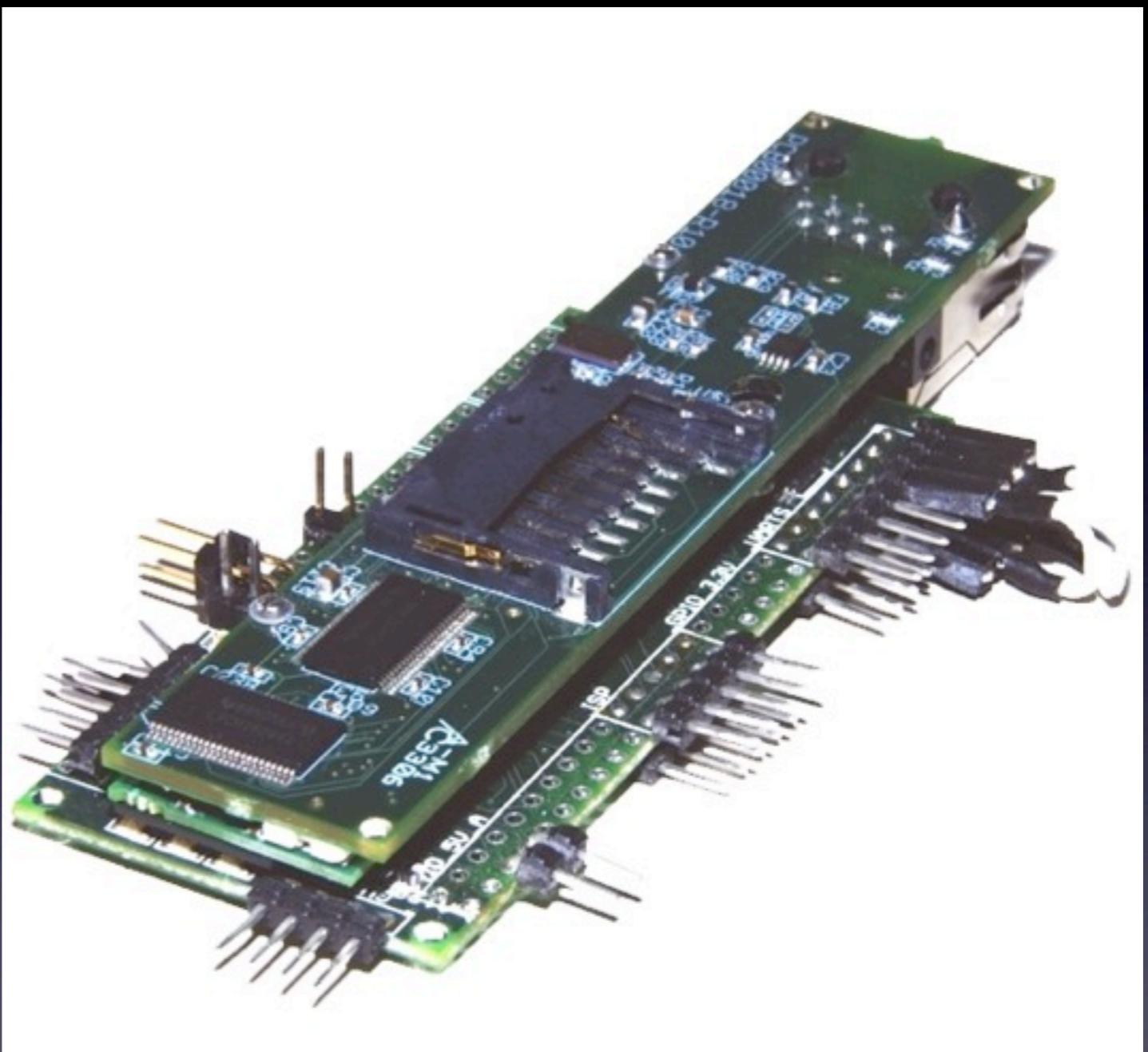


Propulsion

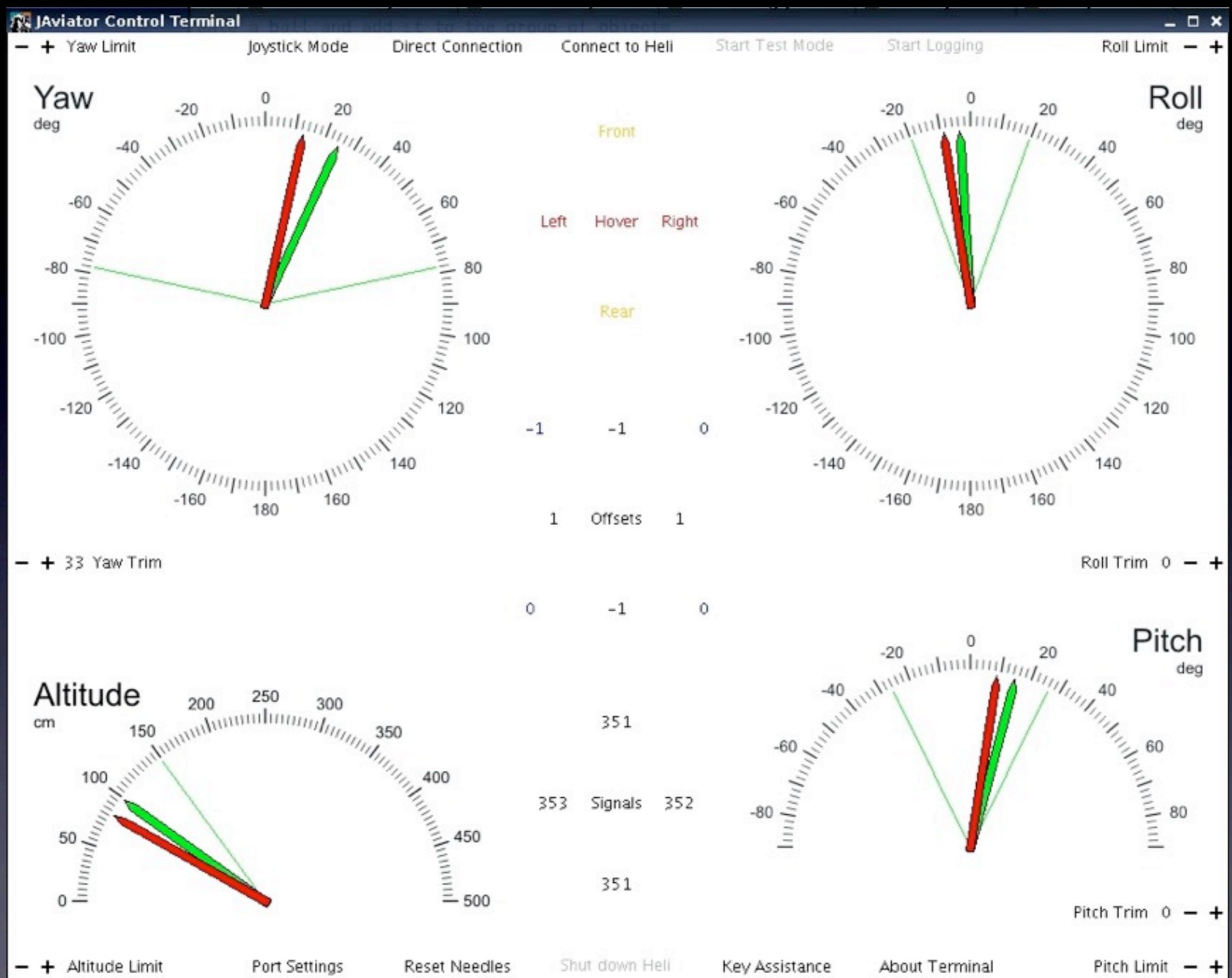


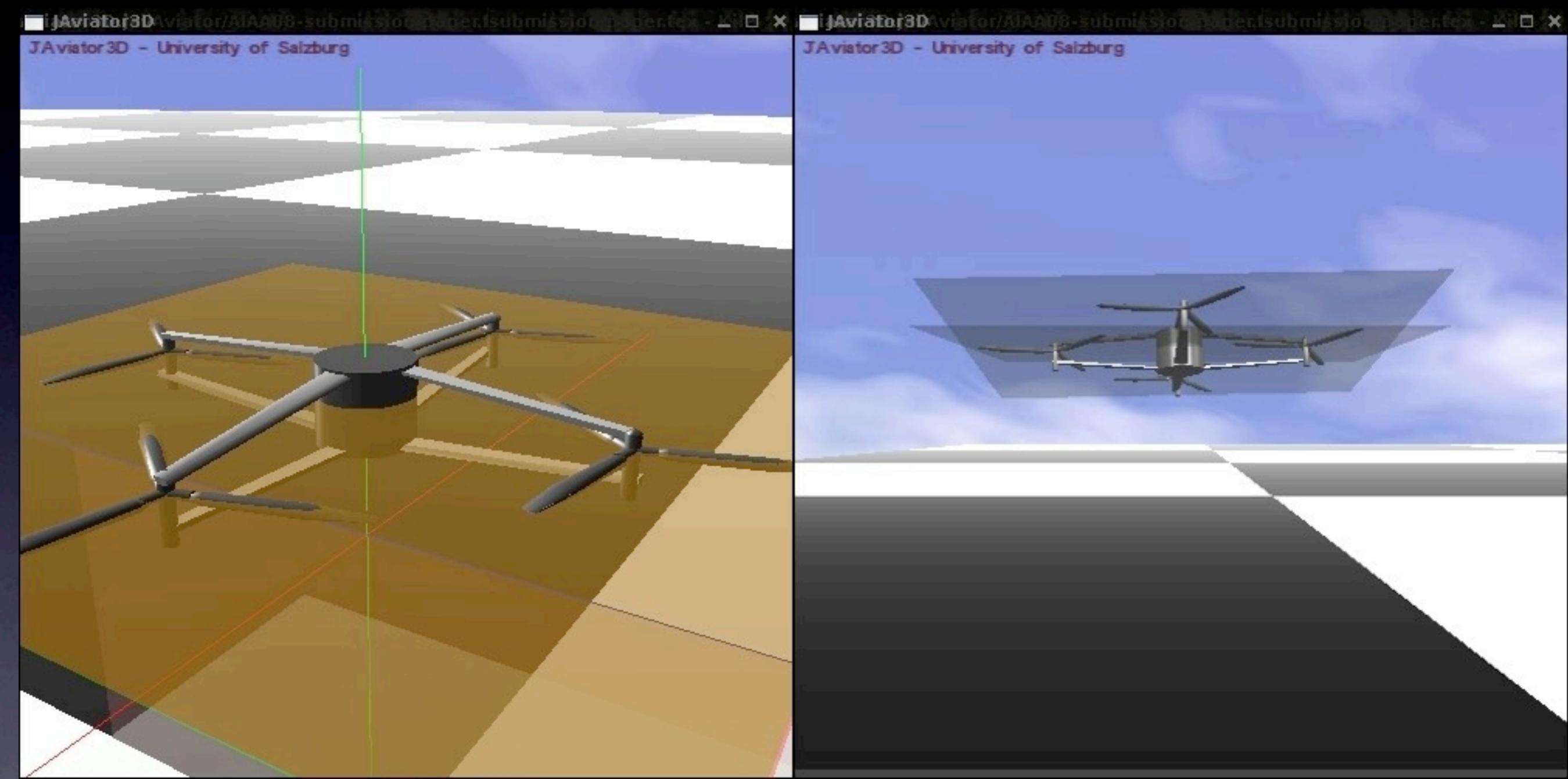
Gyro

# Gumstix

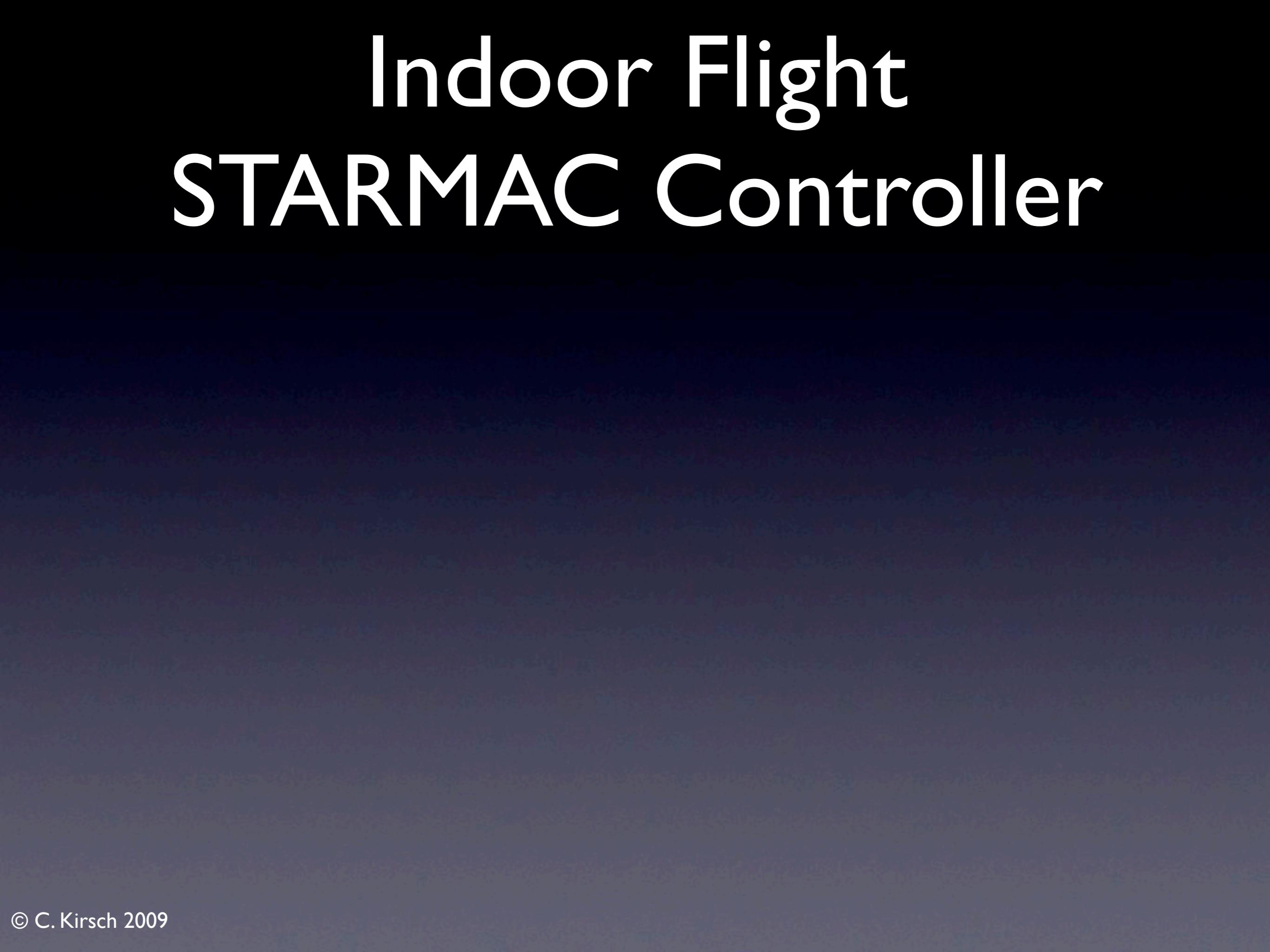


600MHz XScale, 128MB RAM, WLAN, Atmega uController

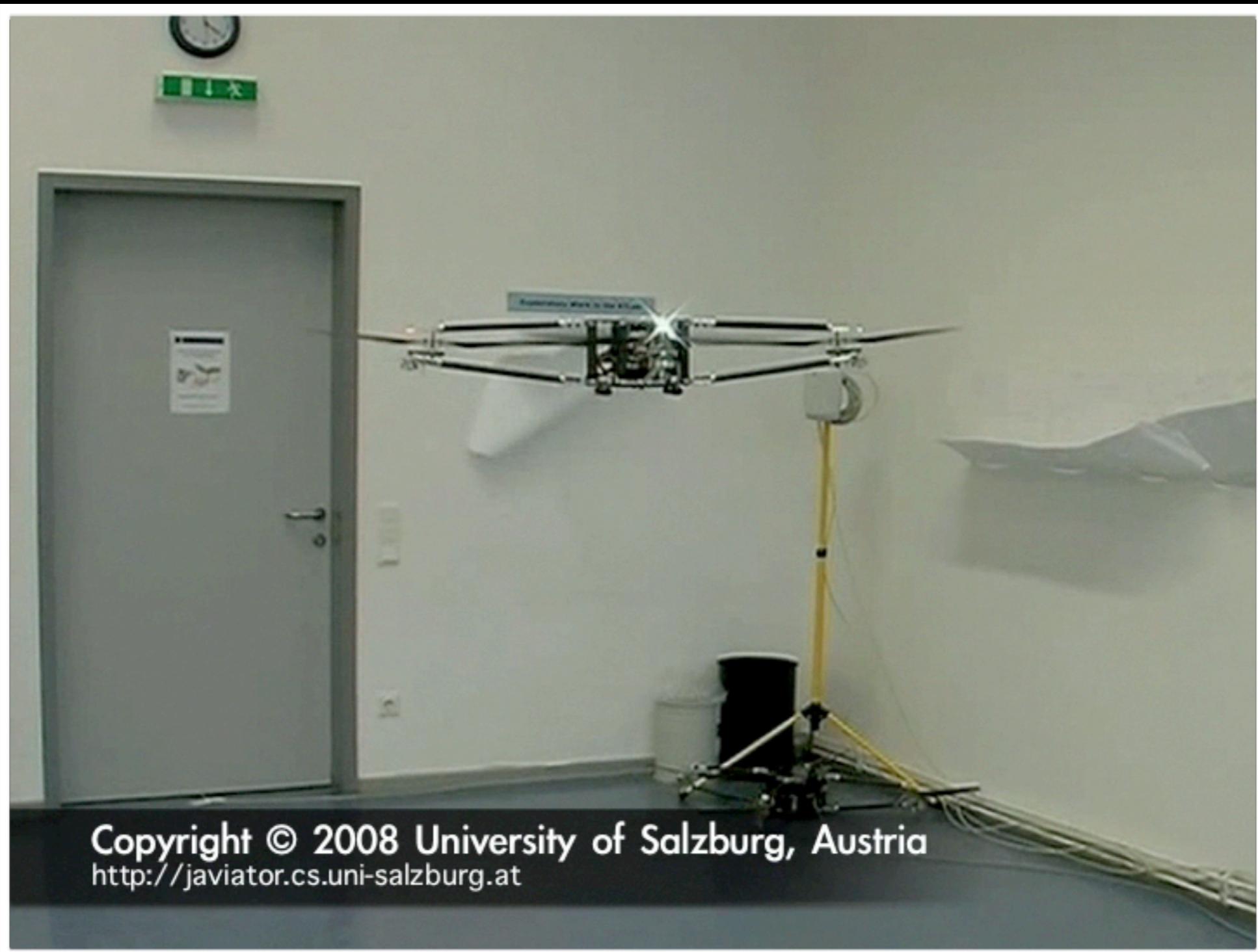




# Indoor Flight STARMAC Controller

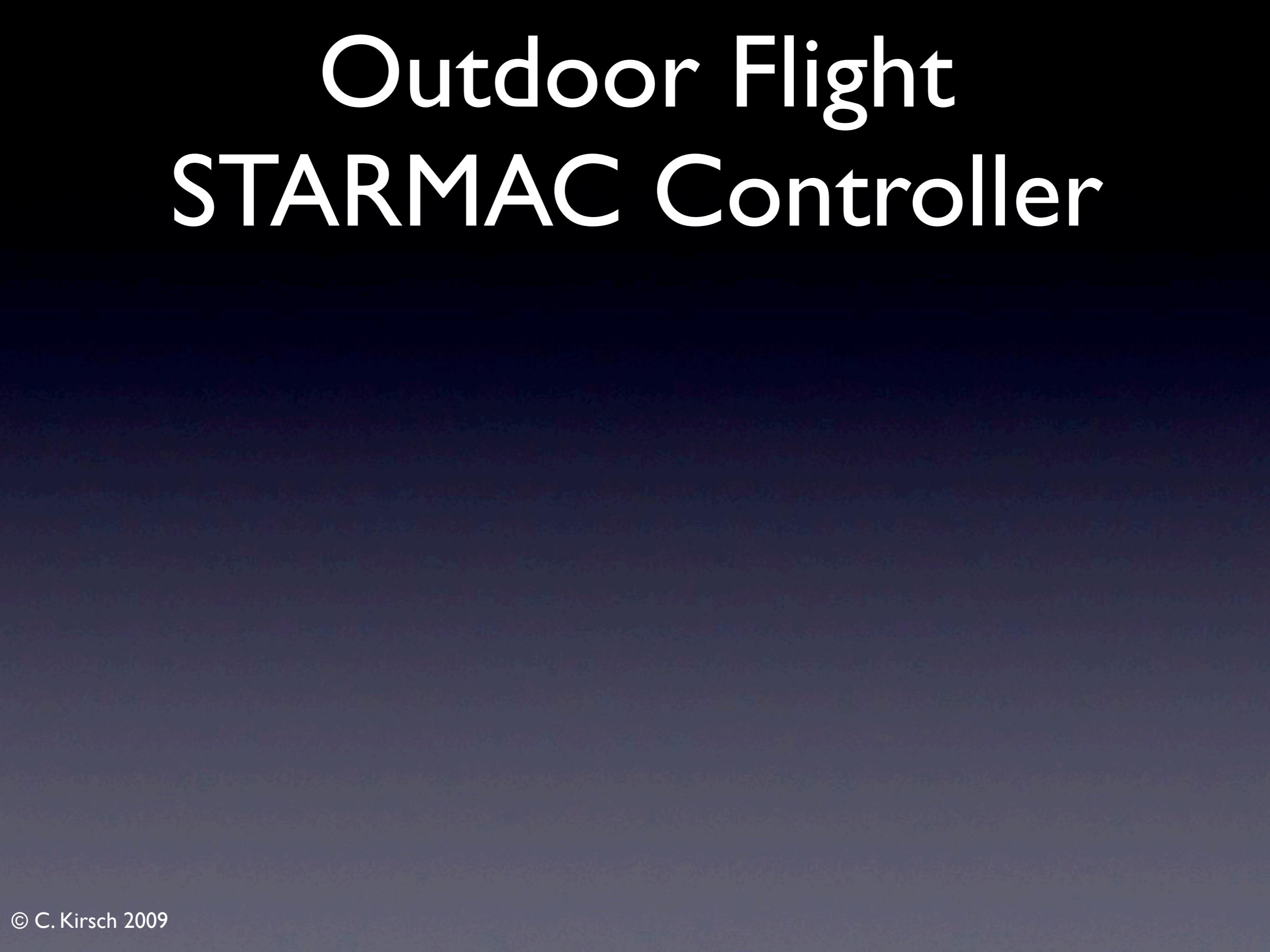


# Indoor Flight STARMAC Controller



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# Outdoor Flight STARMAC Controller

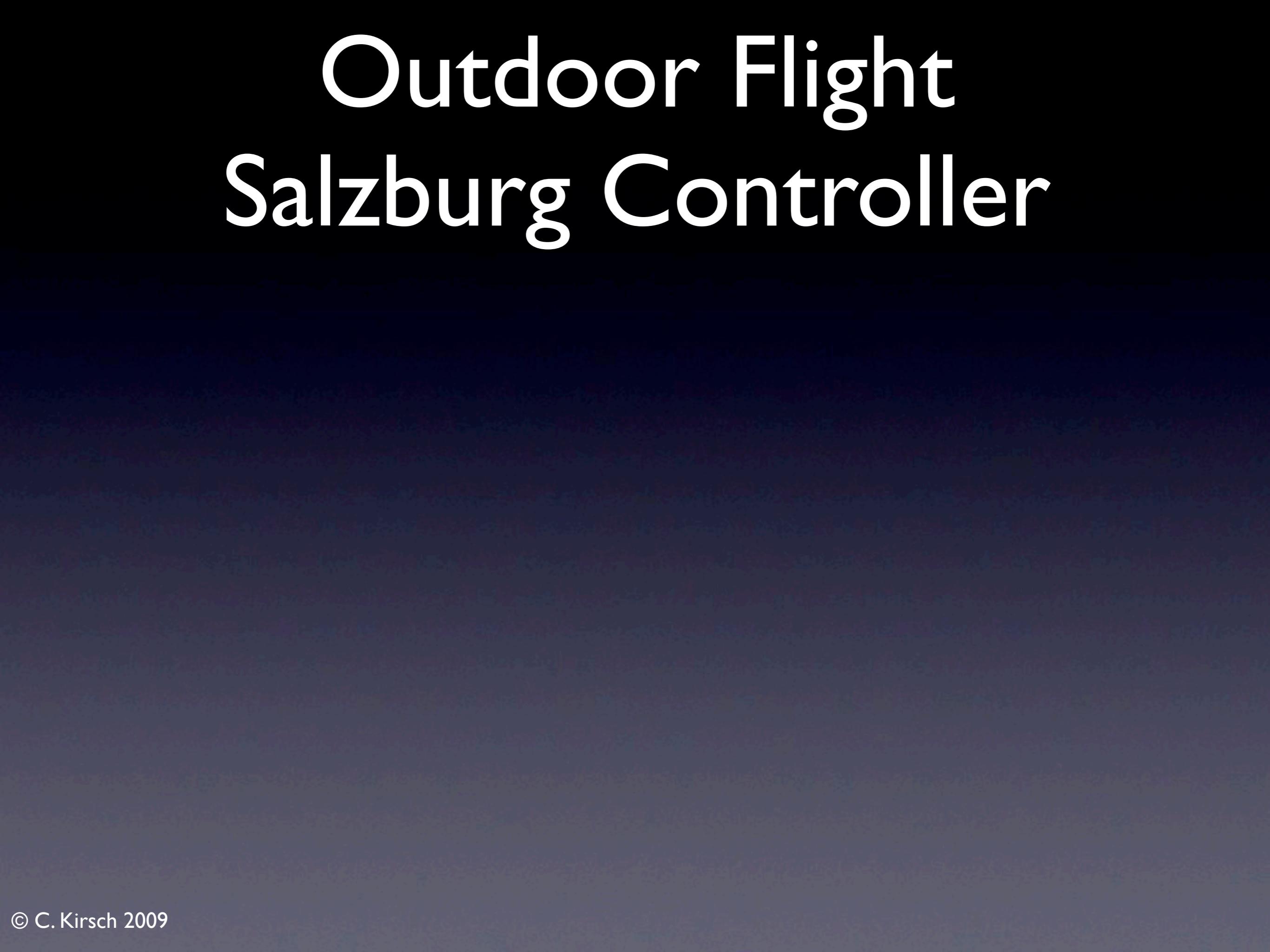


# Outdoor Flight STARMAC Controller



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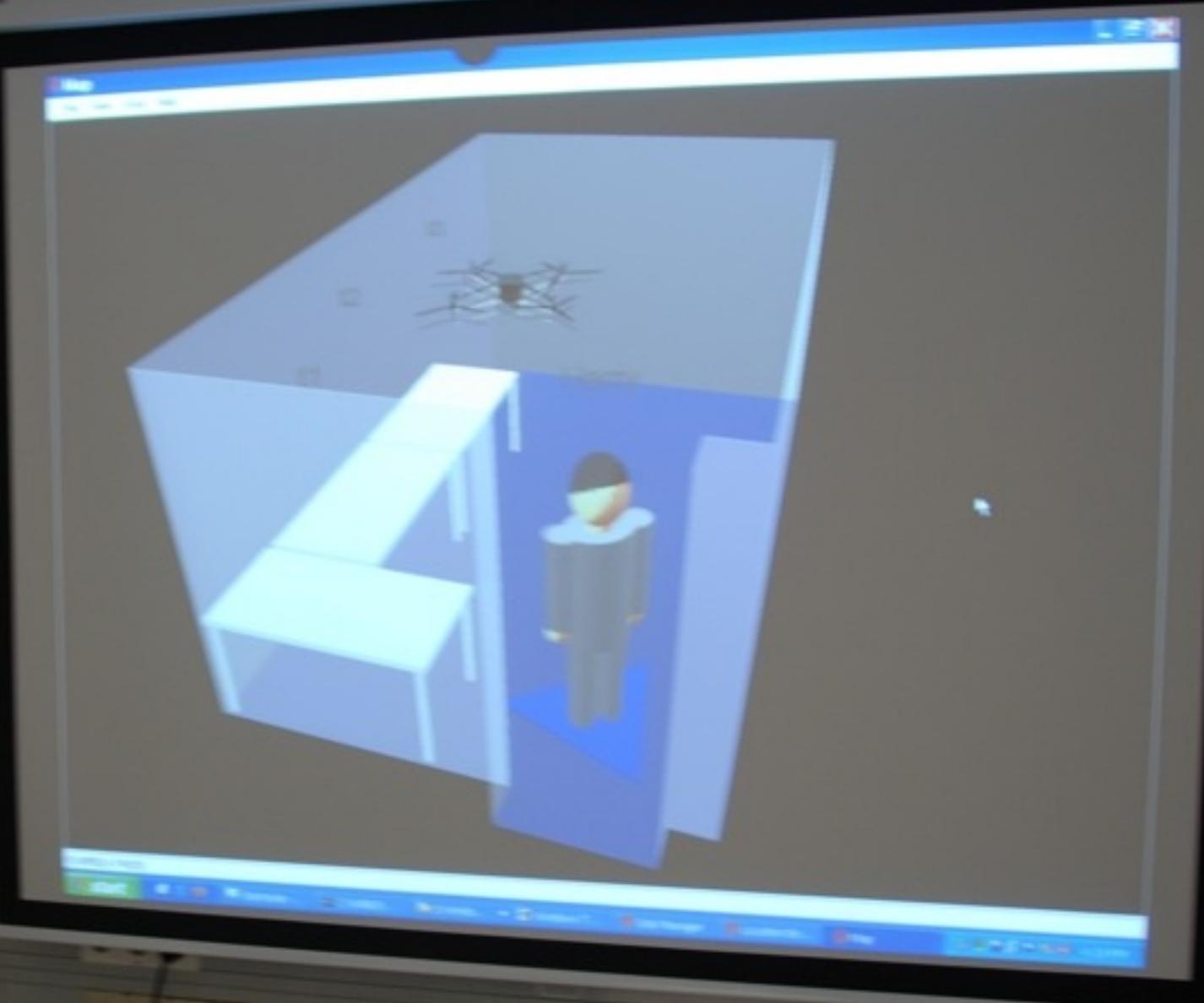
# What's next?

- Autonomous single-vehicle flights
  - position controller
  - waypoint controller

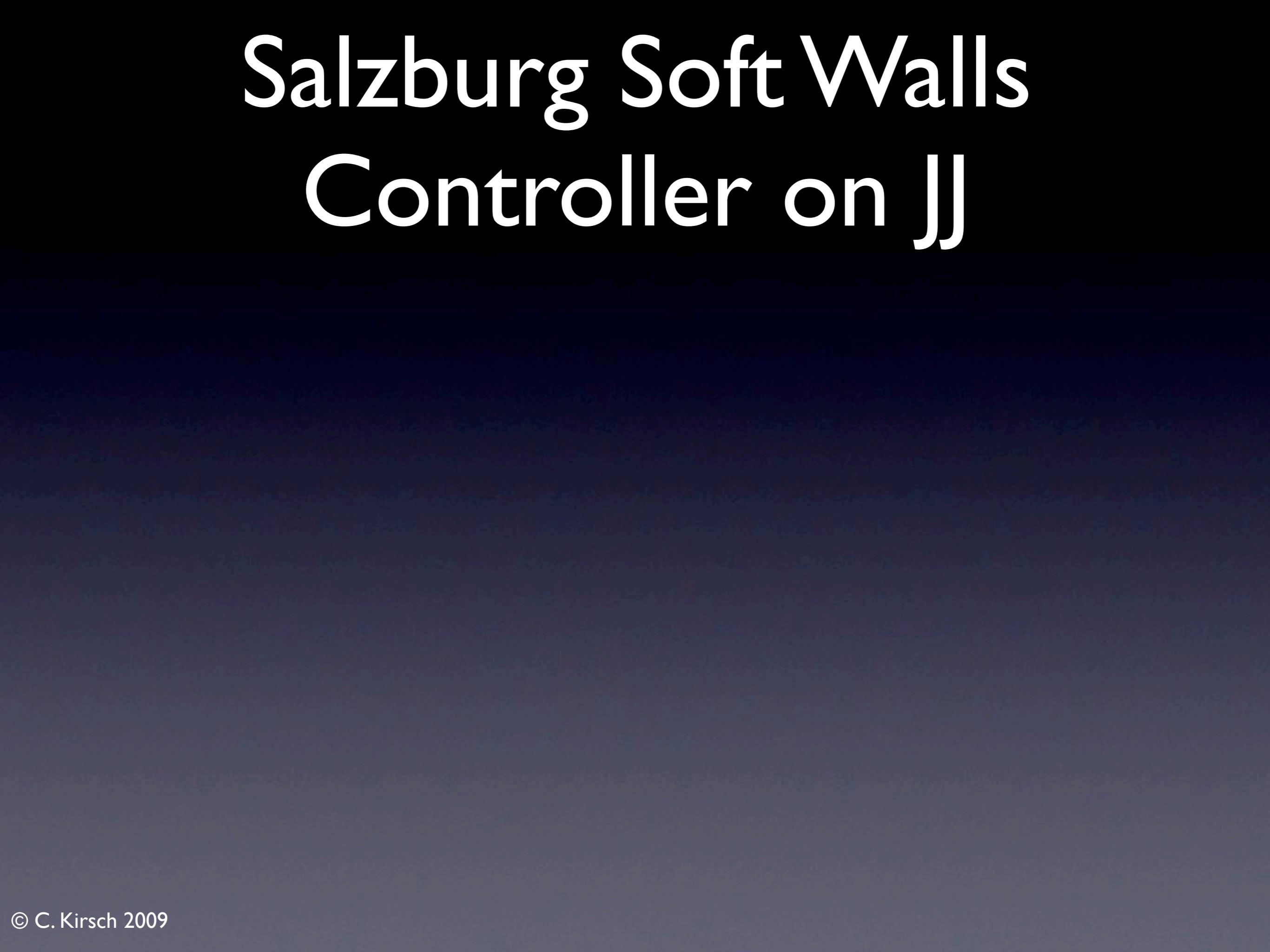
# What's next?

- Autonomous single-vehicle flights
  - position controller
  - waypoint controller
- Autonomous multi-vehicle flights
  - mission controller

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# Salzburg Soft Walls Controller on JJ



# Salzburg Soft Walls Controller on JJ

