

# SMAI Assignment 1 Report

201401074

## Problem 1

A.

- MATLAB code

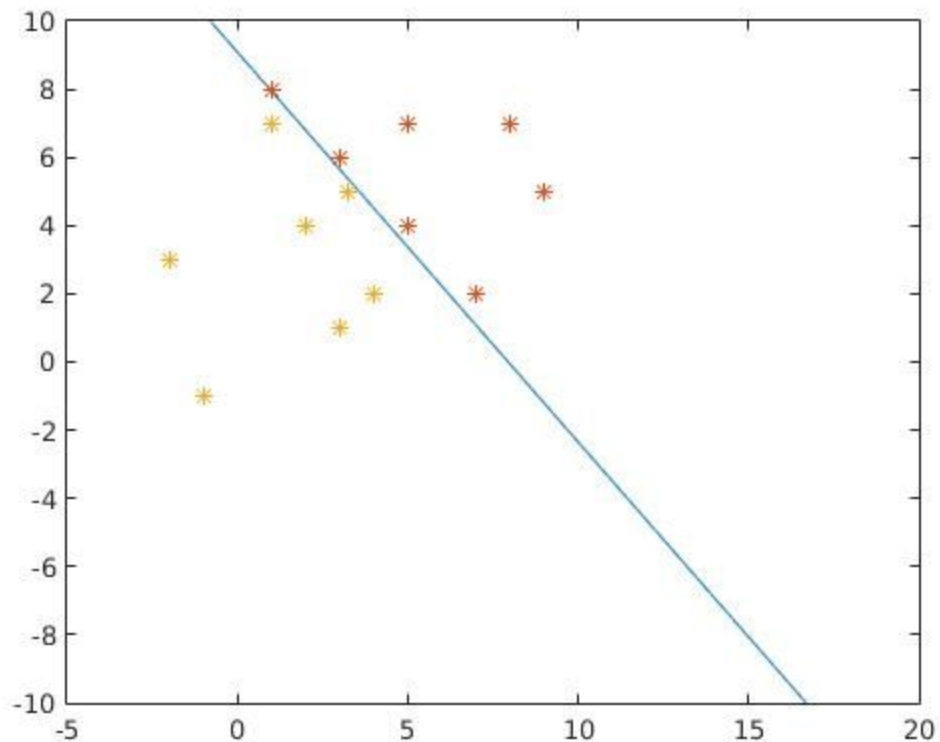
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```
%% Single-sample perceptron
a = rand(3,1);
w1 = [[2,7];[8,1];[7,5];[6,3];[7,8];[5,9];[4,5]];
w2 = [[4,2];[-1,-1];[1,3];[3,-2];[5,3.25];[2,4];[7,1]];
py = [ones(size(w1,1),1),w1];
ny = [-ones(size(w2,1),1),-w2];
y = [py;ny]';
k = 1;
n = size(y,2);
it = 0;
eta = 1;
while 1
    dist = a'*y;
    if size(find(dist<0),2) == 0
        break
    end
    if a'*y(:,k) < 0
        a = a + eta*y(:,k);
    end
    k = mod(k+1,n);
    if k == 0
        k = 1;
    end
    it = it + 1;
end
disp(it);
```

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- There is variation in convergence of algorithm on random initialisation of weight vector
- Eg :  $a = \text{transpose}(1,1,1)$ , converges in 853 iterations
- Eg :  $a = \text{transpose}(0.7209,0.0186,0.6748)$  converges in 970 iterations
- For random initialisation of  $a$  between 0-1 converges in average 1210 iterations
- For random initialisation of  $a$  between 0-10 converges in average 2671 iterations

- For random initialisation of a between 0-100 converges in average 6599 iterations
- Learning rate was kept fixed as 1 for above cases
- On decreasing learning rate to 0.01 reduces average convergence of algorithm to 876, 1516, 5842 iterations respectively. (for 0-1, 0-10, 0-100)
- Initialisation the weight vector in and around the dimensions of the data samples helps in convergence. Very high value makes convergence slow on the other hand, a very low value makes the descent unstable in the start.
- Plot : Red - Class 1, Yellow - Class 2



B.

- MATLAB code

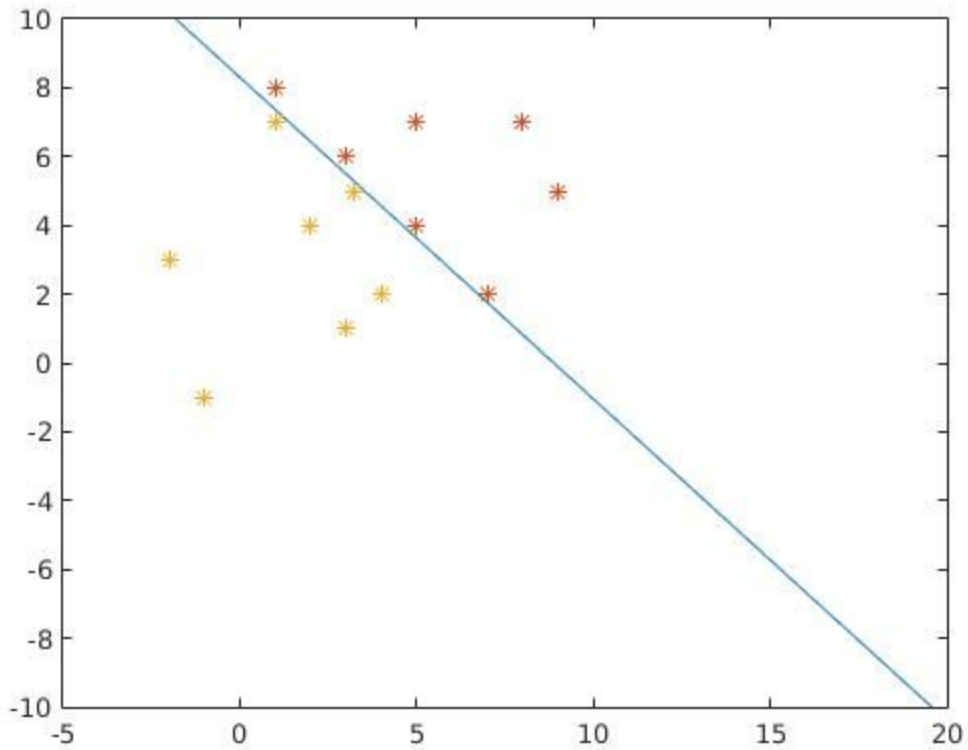
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```
%% Single-sample perceptron with margin
a = rand(3,1);
w1 = [[2,7];[8,1];[7,5];[6,3];[7,8];[5,9];[4,5]];
w2 = [[4,2];[-1,-1];[1,3];[3,-2];[5,3.25];[2,4];[7,1]];
py = [ones(size(w1,1),1),w1];
ny = [-ones(size(w2,1),1),-w2];
y = [py;ny]';
k = 1;
n = size(y,2);
b = 100;
eta = 1;
while 1
    dist = a'*y;
    if size(find(dist<b),2) == 0
        break
    end
    if a'*y(:,k) < b
        a = a + eta*y(:,k);
    end
    k = mod(k+1,n);
    if k == 0
        k = 1;
    end
end
end
```

---

- Effect of convergence of algorithm on the initialisation of weights is similar to that of Single Sample Perceptron case. High values of  $a$  leads to slower convergence. Values of  $a$  similar to the test data points leads to a faster convergence.
- Changing the value of the margin keeping the weight vector  $a$  the same also varies the iterations needed for algorithm to converge.
- For margin  $b = 0.01$ , 296 iterations to converge.
- For margin  $b = 0.1$ , 918 iterations to converge.
- For margin  $b = 1$ , 3562 iterations to converge.
- For margin  $b = 10$ , 20227 iterations to converge.
- For margin  $b = 100$ , 287650 iterations to converge.

- Decreasing value of learning rate speeds up the convergence of the algorithm till a point and then the convergence increases, same with increasing the eta value.
- For eta = 1, 515 iterations to converge.
- For eta = 0.1, 1009 iterations to converge.
- For eta = 2, 296 iterations to converge.
- For eta = 3, 749 iterations to converge.
- Plot : Red - Class 1, Yellow - Class 2



C.

- MATLAB code

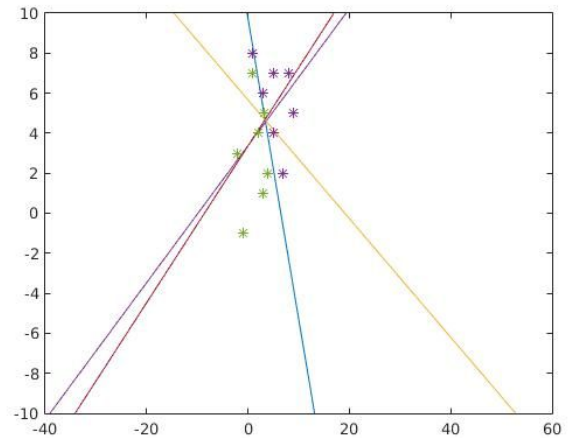
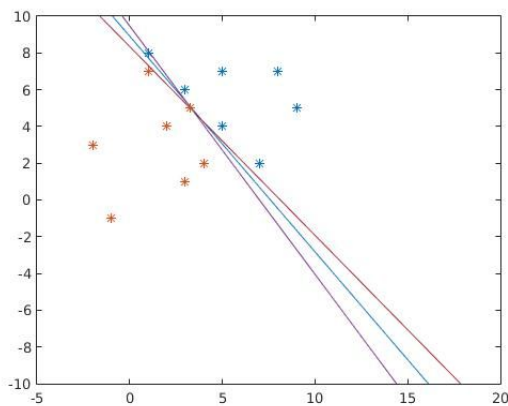
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```
%% Relaxation algorithm with margin
a = randi([-100 100],3,1);
w1 = [[2,7];[8,1];[7,5];[6,3];[7,8];[5,9];[4,5]];
w2 = [[4,2];[-1,-1];[1,3];[3,-2];[5,3.25];[2,4];[7,1]];
py = [ones(size(w1,1),1),w1];
ny = [-ones(size(w2,1),1),-w2];
y = [py;ny]';
k = 1;
n = size(y,2);
learningRate = 0.01;
b = 10;
theta = 0.00001;
it = 0;
while 1
    dist = a'*y - b;
    ind = find(dist<0);
    miscfd = y(:,ind);
    miscfd_dist = dist(ind);
    miscfd_norm = diag(miscfd'*miscfd)';
    miscfd_err = repmat(miscfd_dist ./ miscfd_norm,size(y,1),1);
    miscfd_err = miscfd_err .* miscfd;
    final_err = sum(miscfd_err')';
    if abs(sum(learningRate * final_err)) < theta
        break
    end
    a = a - learningRate * final_err;
    it = it + 1;
end
disp(it);
```

---

- In many cases, we do not get a good decision boundary. This is mostly due to the values of the learningRate and the threshold (theta). Sometimes the algorithm breaks out due to high theta value so a proper decision boundary is not found as the algorithm is not let to converge.
- Margin has the same effect on convergence time as discussed above, larger b values considerable slowing down the convergence.

- Smaller value of theta / threshold improve the convergence of the algorithm to find a decent decision boundary but also increase the convergence time considerably.
- Eg : if  $\theta = 0.1, 0.01, 0.001$  there are many outliers but the no. of iterations is  $< 500$  but for  $\theta = 0.0001, 0.00001, 0.000001$  we find a very good decision boundary but the no. of iterations is 10629, 80143, 712056 respectively.
- The initialization of the weight vector has similar results on convergence time and giving a good decision boundary as discussed earlier.
- Plot : Red - Class 1, Yellow - Class 2, Fig 1 - Different values of  $a$ , Fig 2 - Different values of  $b$



D.

- MATLAB code

---

```
%% Widrow-Hoff or Least Mean Squared (LMS) Rule
a = randi([-100 100],3,1);
disp(a);
w1 = [[2,7];[8,1];[7,5];[6,3];[7,8];[5,9];[4,5]];
w2 = [[4,2];[-1,-1];[1,3];[3,-2];[5,3.25];[2,4];[7,1]];
b = 0.03*ones(1,size(w1,1)+size(w2,1));
py = [ones(size(w1,1),1),w1];
ny = [-ones(size(w2,1),1),-w2];
y = [py;ny]';
k = 1;
n = size(y,2);
it = 0;
learningRate = 0.01;
theta = 0.0000002;
while 1
    dist = (a'*y(:,k) - b(k));
    if abs( learningRate * y(:,k) * dist) < theta
        break
    end
    if a'*y(:,k) - b(k) < 0
        a = a - learningRate * y(:,k) * dist;
```



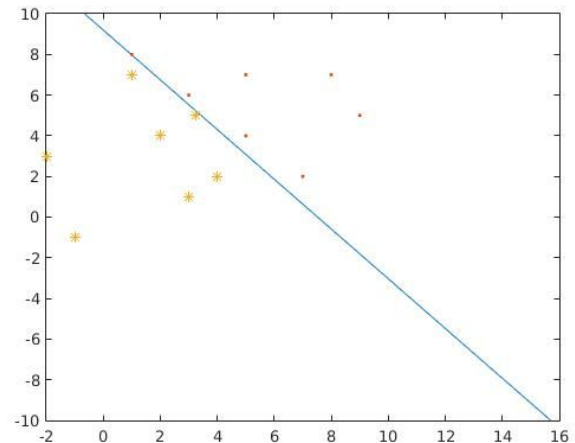
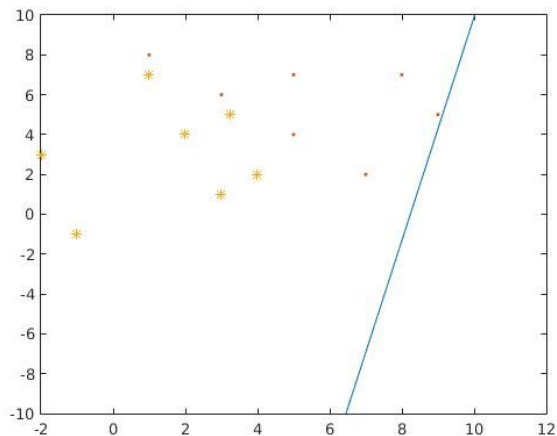
```

end
k = mod(k+1,n+1);
if k == 0
    k = 1;
end
it = it + 1;
end
disp(it);

```

---

- Full classification may not be achieved but good classification boundary is achieved, with mis-classified samples ranging from 2-3 at max.
- The effect of initialization and margin are the same as discussed earlier.
- Smaller value of theta / threshold improve the convergence of the algorithm to find a decent decision boundary but also increase the convergence time considerably. Experiments show similar results as in Relaxation with margin case.
- Plot : Red - Class 1, Yellow - Class 2, Fig 1 - Unclassified case, Fig 2 - Classified case



## Problem 2

- Layer class file :

---

```
import numpy as np

class layer:

    def __init__ (self, layerType, nUnits, nUnitsPrev):
        '''
            NN layer constructor
        '''
        self.layerType = layerType
        if self.layerType == 'input':
            self.weight = np.asmatrix(np.identity(nUnits))
            self.bias = np.asmatrix(np.zeros((nUnits,1), np.float))
        else:
            self.weight = np.asmatrix(np.random.normal(0,
np.sqrt(1.0/nUnitsPrev), (nUnits, nUnitsPrev)))
            self.bias = np.asmatrix(np.random.rand(nUnits, 1))
            self.netActiv = np.asmatrix(np.zeros((nUnits, 1), np.float))
            self.outputVal = np.asmatrix(np.zeros((nUnits, 1), np.float))
            self.inputVal = np.asmatrix(np.zeros((nUnits, 1), np.float))
            self.delta = np.asmatrix(np.zeros((nUnits, 1), np.float))

    def feedForward (self, inputVal): # inputVal is same as output of
previous layer
        '''
            calculates netActiv and outputVal of the layer
        '''
        self.inputVal = inputVal
        self.netActiv = np.add(np.dot(self.weight, inputVal), self.bias)
        if self.layerType == 'input':
            self.outputVal = self.netActiv
        else:
            self.outputVal = sigmoid(self.netActiv)

    def backProp (self, nextVal, learningRate, nextWeight = None):
```

```

    ...
    calculates delta, updates weight and bias of layer
    ...

    # calculate delta
    if self.layerType == 'output':
        desiredOutputVal = nextVal
        costDerivative = np.subtract(self.outputVal,
desiredOutputVal)
        self.delta = np.multiply(costDerivative,
sigmoidDerivative(self.netActiv))
    elif self.layerType == 'hidden':
        nextDelta = nextVal
        self.delta = np.multiply(np.dot(np.transpose(nextWeight),
nextDelta), sigmoidDerivative(self.netActiv))
    # update wight
    weightPartialDerivative = np.dot(self.delta,
np.transpose(self.inputVal))
    self.weight = np.subtract(self.weight, np.multiply(learningRate,
weightPartialDerivative))
    # update bias
    biasPartialDerivative = self.delta
    self.bias = np.subtract(self.bias, np.multiply(learningRate,
biasPartialDerivative))

def sigmoid (x):
    ...
    sigmoid function  $y = 1 / (1 + \exp(-x))$ 
    ...
    y = np.divide(1.0, np.add(1.0, np.exp(np.multiply(-1, x))))
    return y

def sigmoidDerivative (x):
    ...
     $y' = \text{sigmoid}(x) * (1 - \text{sigmoid}(x))$ 
    ...
    y = sigmoid(x)
    yDash = np.multiply(y, np.subtract(1.0, y))
    return yDash

```

---

- Main file for NN :
- 

```
from layer import *
import numpy as np
import math

layerType = {0:'input', 1:'hidden', 2:'output'}
nUnits = {0:64, 1:20, 2:10}
nUnitsPrev = {0:64, 1:64, 2:20}

def process():
    '''
        processing stuff
    '''
    TEST_FILE = 'optdigits.tes'
    TRAIN_FILE = 'optdigits.tra'
    # read training data
    with open(TRAIN_FILE) as f:
        tra_raw = f.readlines()
    # process training data
    tra_list = [map(int, item.strip().split(',')) for item in tra_raw]
    tra_data = np.transpose(np.asmatrix([item[:-1] for item in
tra_list]))
    tra_gt = [item[-1] for item in tra_list]
    # normalise training data
    mean_sample = np.divide(tra_data.sum(axis = 1), tra_data.shape[1])
    tra_data = np.subtract(tra_data, mean_sample)
    # read testing data
    with open(TEST_FILE) as f:
        tes_raw = f.readlines()
    # process training data
    tes_list = [map(int, item.strip().split(',')) for item in tes_raw]
    tes_data = np.transpose(np.asmatrix([item[:-1] for item in
tes_list]))
    tes_gt = [item[-1] for item in tes_list]
    # normalise training data
    mean_sample = np.divide(tes_data.sum(axis = 1), tes_data.shape[1])
    tes_data = np.subtract(tes_data, mean_sample)
```

```

    return tra_data,tra_gt,tes_data,tes_gt

def main():
    '''
        runs and trains NN
    '''
    ***** TRAINING PART *****
    tra_data, tra_gt, tes_data, tes_gt = process()

    learningRate = 0.001
    nLayers = 3
    nEpochs = 100
    nSamples = tra_data.shape[1]
    layers = []

    for i in range(nLayers):
        tmpLayer = layer(layerType[i], nUnits[i], nUnitsPrev[i])
        layers.append(tmpLayer)

    for epoch in range(nEpochs):

        nCorrect = 0

        for i in range(nSamples):
            # feed forward
            layers[0].feedForward(tra_data[:,i])
            layers[1].feedForward(layers[0].outputVal)
            layers[2].feedForward(layers[1].outputVal)

            # check correctly classified
            OutputVec = layers[2].outputVal
            if np.argmax(OutputVec) == tra_gt[i]:
                nCorrect += 1

            # desired output
            desiredOutputVec = np.asmatrix(np.zeros((nUnits[2], 1),
np.float))
            desiredOutputVec[tra_gt[i]] = 1.0

```

```

        # back prop
        layers[2].backProp(desiredOutputVec, learningRate)
        layers[1].backProp(layers[2].delta, learningRate,
layers[2].weight)

    if epoch % 9 == 0:
        print "Training error after epoch", epoch, "is",
(float(nSamples - nCorrect)/nSamples)*100, '%'

    ***** TESTING PART
    *****

    nTestingSamples = tes_data.shape[1]
    nCorrect = 0

    for i in range(nTestingSamples):
        # feed forward
        layers[0].feedForward(tes_data[:,i])
        layers[1].feedForward(layers[0].outputVal)
        layers[2].feedForward(layers[1].outputVal)

        # check correctly classified
        OutputVec = layers[2].outputVal
        if np.argmax(OutputVec) == tes_gt[i]:
            nCorrect += 1

    print "Testing error is", (float(nTestingSamples -
nCorrect)/nTestingSamples)*100, '%'

if __name__ == "__main__":
    main()

```

---

- Normalise the data by mean centering the data.
- Making sure that the output of every layer is distributed normally by zero mean and unit variance using the fan in for every neuron.
- Took a constant learningRate = 0.001

```

joycode@nelovo:~/sem5/smai/Assign1$ python main.p
Training error after epoch 0 is 84.0701020141 %
Training error after epoch 9 is 11.3261836254 %
Training error after epoch 18 is 6.80094166885 %
Training error after epoch 27 is 5.36228093121 %
Training error after epoch 36 is 4.70834423228 %
Training error after epoch 45 is 4.13287993722 %
Training error after epoch 54 is 3.55741564217 %
Training error after epoch 63 is 3.34815589851 %
Training error after epoch 72 is 3.1127386869 %
Training error after epoch 81 is 2.87732147528 %
Training error after epoch 90 is 2.61574679571 %
Training error after epoch 99 is 2.53727439184 %
Testing error is 2.44852531998 %

```

- Took a constant learningRate = 0.0001

```

joycode@nelovo:~/sem5/smai/Assign1$ python main.py
Training error after epoch 0 is 92.5451216322 %
Training error after epoch 9 is 73.6332722992 %
Training error after epoch 18 is 52.445723254 %
Training error after epoch 27 is 38.2422181533 %
Training error after epoch 36 is 30.2641904264 %
Training error after epoch 45 is 26.1051530212 %
Training error after epoch 54 is 22.8616269945 %
Training error after epoch 63 is 20.2981951347 %
Training error after epoch 72 is 18.2579126341 %
Training error after epoch 81 is 16.453047345 %
Training error after epoch 90 is 14.3081349725 %
Training error after epoch 99 is 13.0787339786 %
Testing error is 12.8547579299 %

```

- Took a decaying learningRate =  $A * \text{iteration}^{-p}$ , a and p being constants

```

Training error after epoch 0 is 25.006539367 %
/home/joycode/sem5/smai/Assign1/layer.py:55: RuntimeWarning: overflow encountered in exp
  y = np.divide(1.0, np.add(1.0, np.exp(np.multiply(-1, x))))
Training error after epoch 9 is 12.3463248758 %
Training error after epoch 18 is 8.68427936176 %
Training error after epoch 27 is 8.37038974627 %
Training error after epoch 36 is 8.39654721423 %
Training error after epoch 45 is 7.97802772692 %
Training error after epoch 54 is 8.16113000262 %
Training error after epoch 63 is 7.97802772692 %
Training error after epoch 72 is 6.90557154067 %
Training error after epoch 81 is 7.95187025896 %
Training error after epoch 90 is 7.82108291917 %
Training error after epoch 99 is 7.66413811143 %
Testing error is 6.84474123539 %

```

- Hidden Layer Output and Weights are given in the following link.

<https://drive.google.com/open?id=0B6aMBqXsxQfgT3h4cUV2QVE3eWc>

