

# About the course

## Books

DIP by Gonzalez and Woods

Fundamentals of DIP by Jain

+ other sources

## Assessment

2 mid semester exams\* (30%) + 1 Final exam\* (25%) = 55% (theory)

Weekly assignments\* (25%) + 1 final project\* (20%) = 45% (practice)

\*If you fail to submit more than 1 assignment you will get 0/25 for the assignment component; If copying is detected, you get 0 marks for the assignment.

Portal for the course website <http://courses.iiit.ac.in>

Portal for Image processing virtual lab

<http://deploy.virtual-labs.ac.in/labs/cse19/index.php>

\* Weights may change depending on the final numbers in the class

**Visual information**  
**(in a digital image)**  
**processing: challenges**

# Why Image processing ?

- Proliferation of cameras
- Variety of uses for images
  - Personal, journalism/news, medical diagnostics, satellite, deep space probes, under water exploration...

Routine tasks of interest

Input



Processed output



Enhance the image



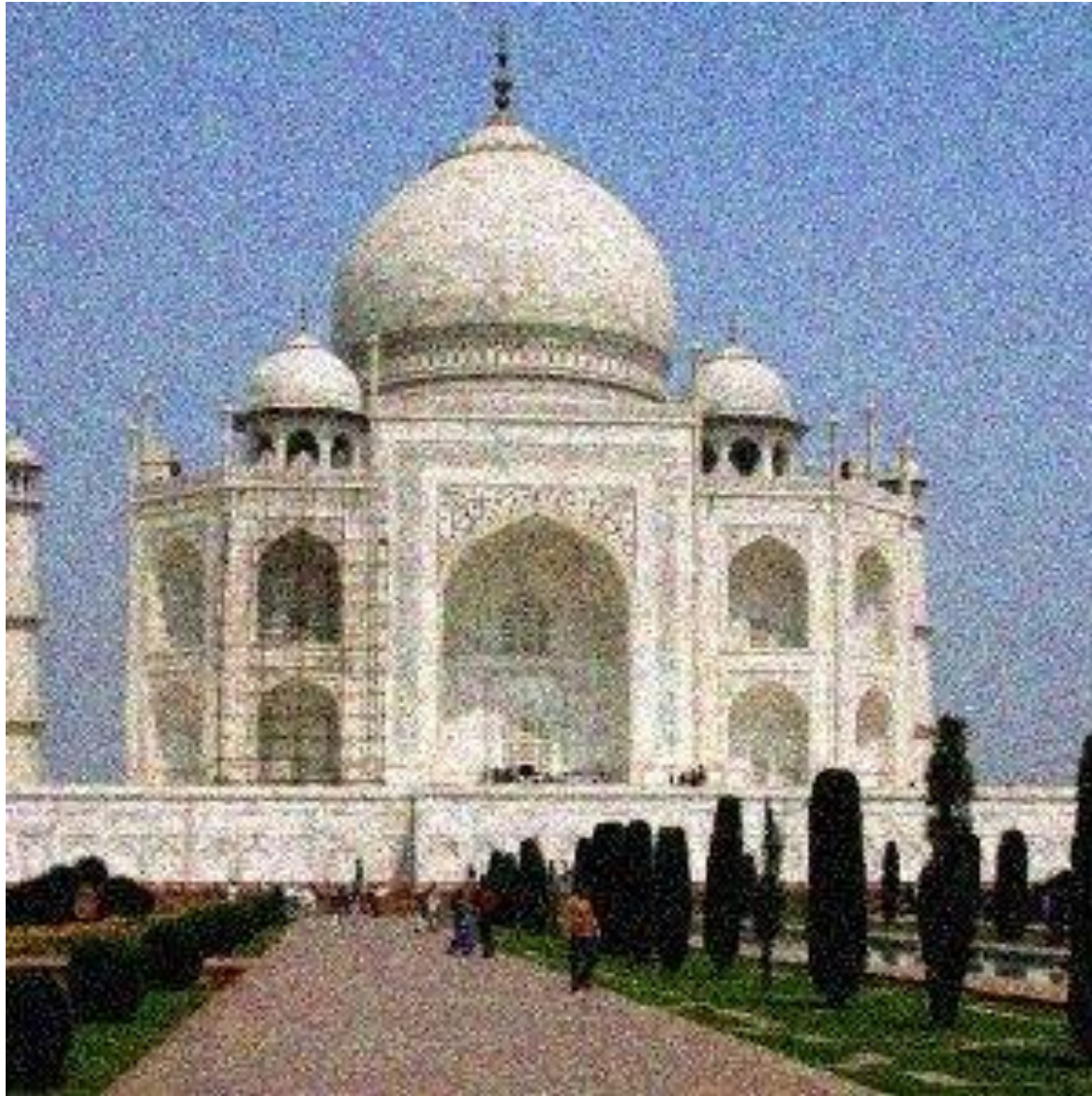
Input



output

Correct the view point





De-noise



De-blur



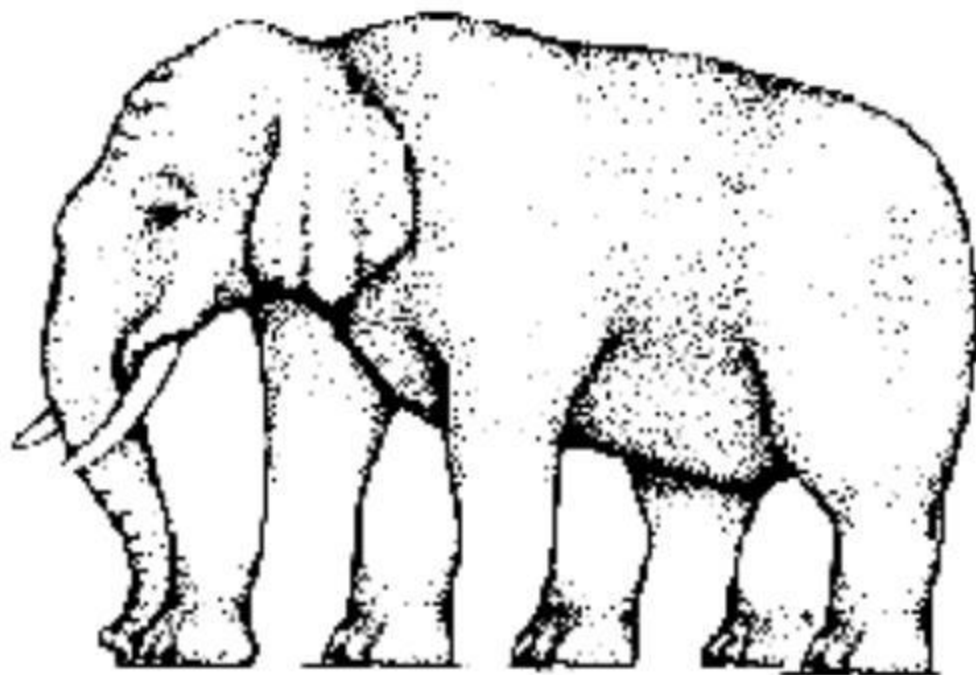


Higher order tasks of interest

# “Find and Replace” in images



Replace *Madras* with *Chennai*

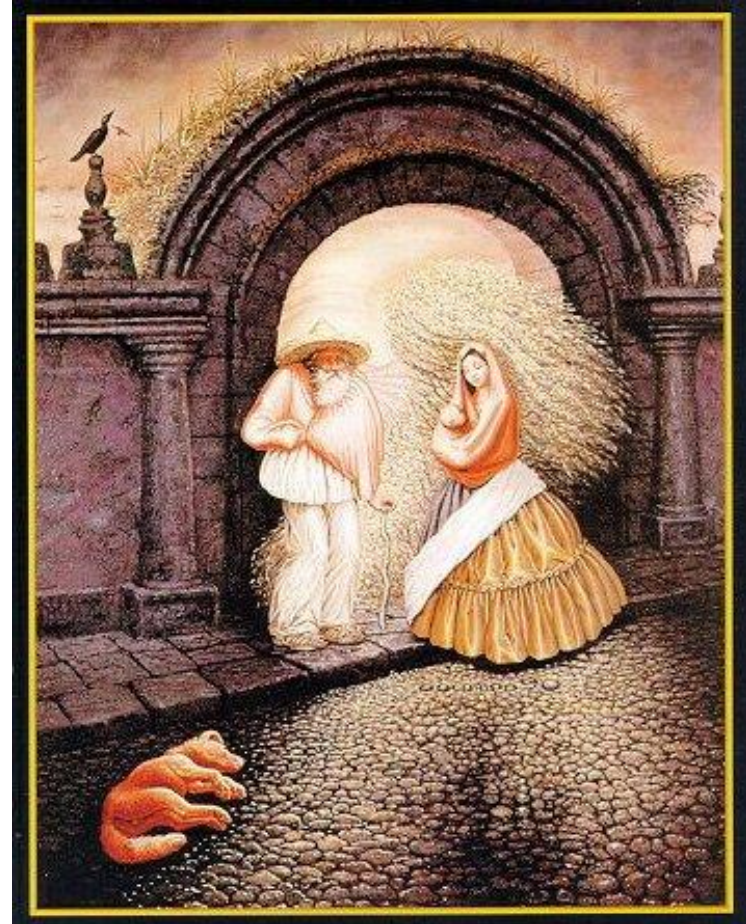


How many legs does this elephant have?

# Locate the faces and text in these images



Operation 'Hide and Seekh'  
reporting, Sir! We have  
found a lot of black bucks...



*Seeing* is effortless for us....

The challenge is to endow computers  
with the same ability !

*Image processing* is the first step in that  
direction



# Which of the tasks is DIP concerned with?

Mostly

- Routine tasks:  $I_{\text{in}} \rightarrow I_{\text{out}}$

Partly

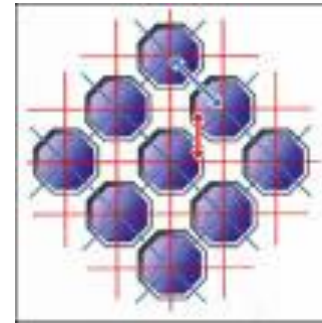
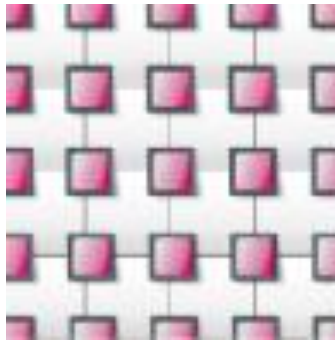
- Higher order tasks:  $I_{\text{in}} \rightarrow \text{detection/recognition}$

# Constraints

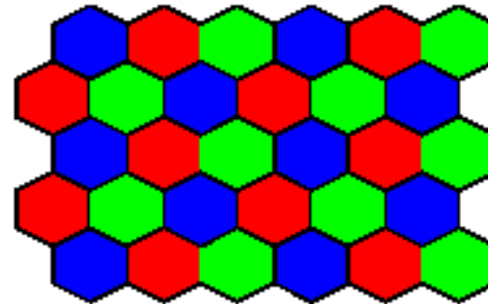
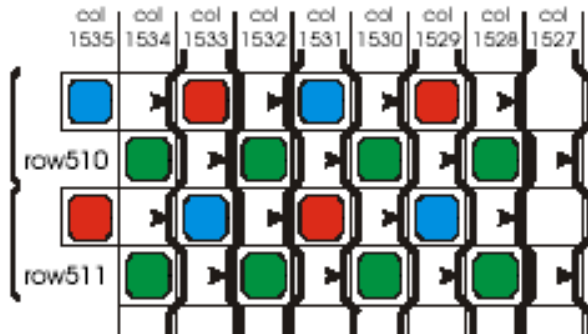
- An image is a set of integers
  - *intensity/colour* values, an objective quantity
- Each number depends on *several* factors
  - Surface property, illumination strength and wavelength
- The image is a 2D projection of a 3D scene
- What we perceive is *brightness*
  - A subjective sensation

# Imaging -Sensor layout in cameras

Traditional

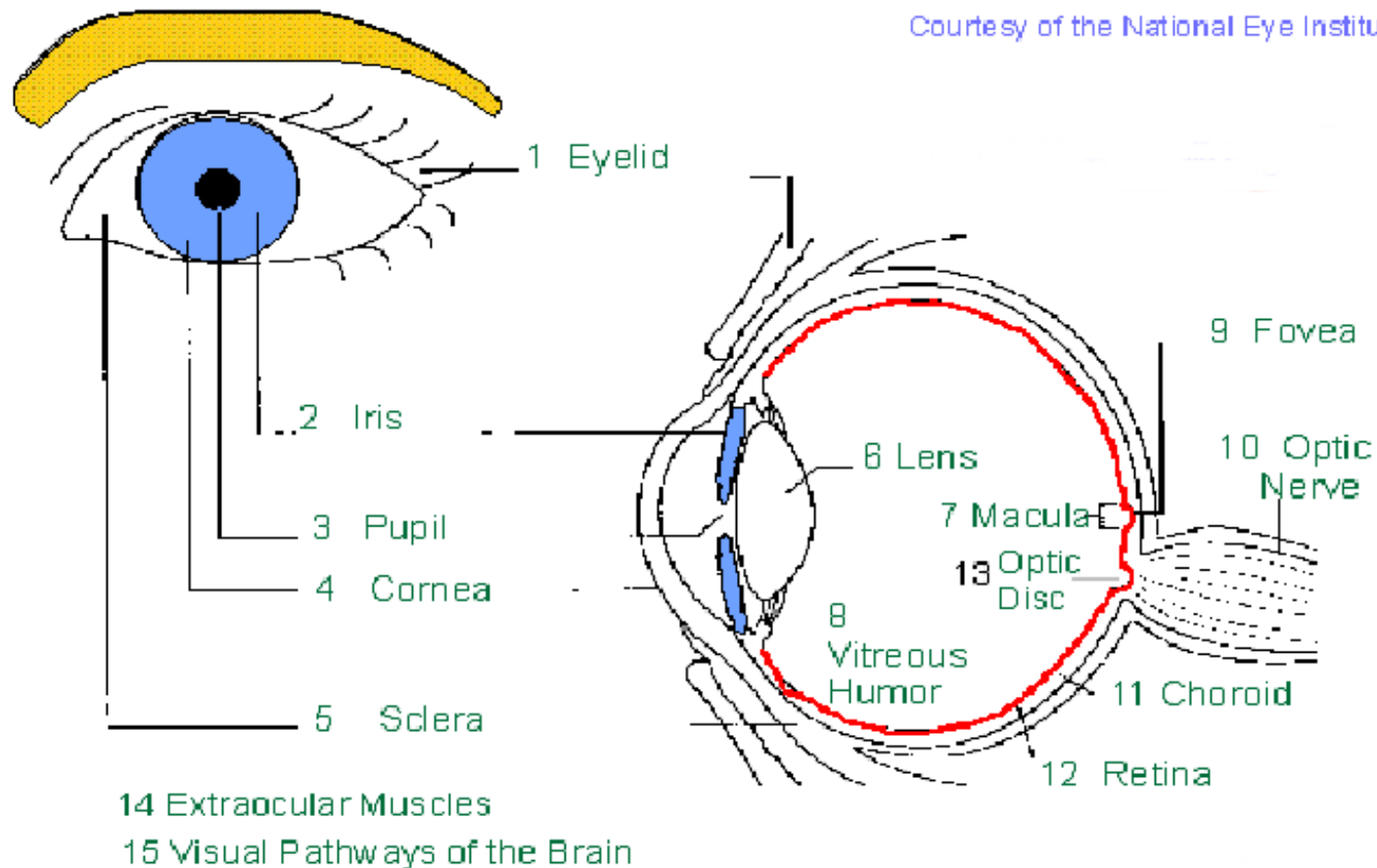


Novel

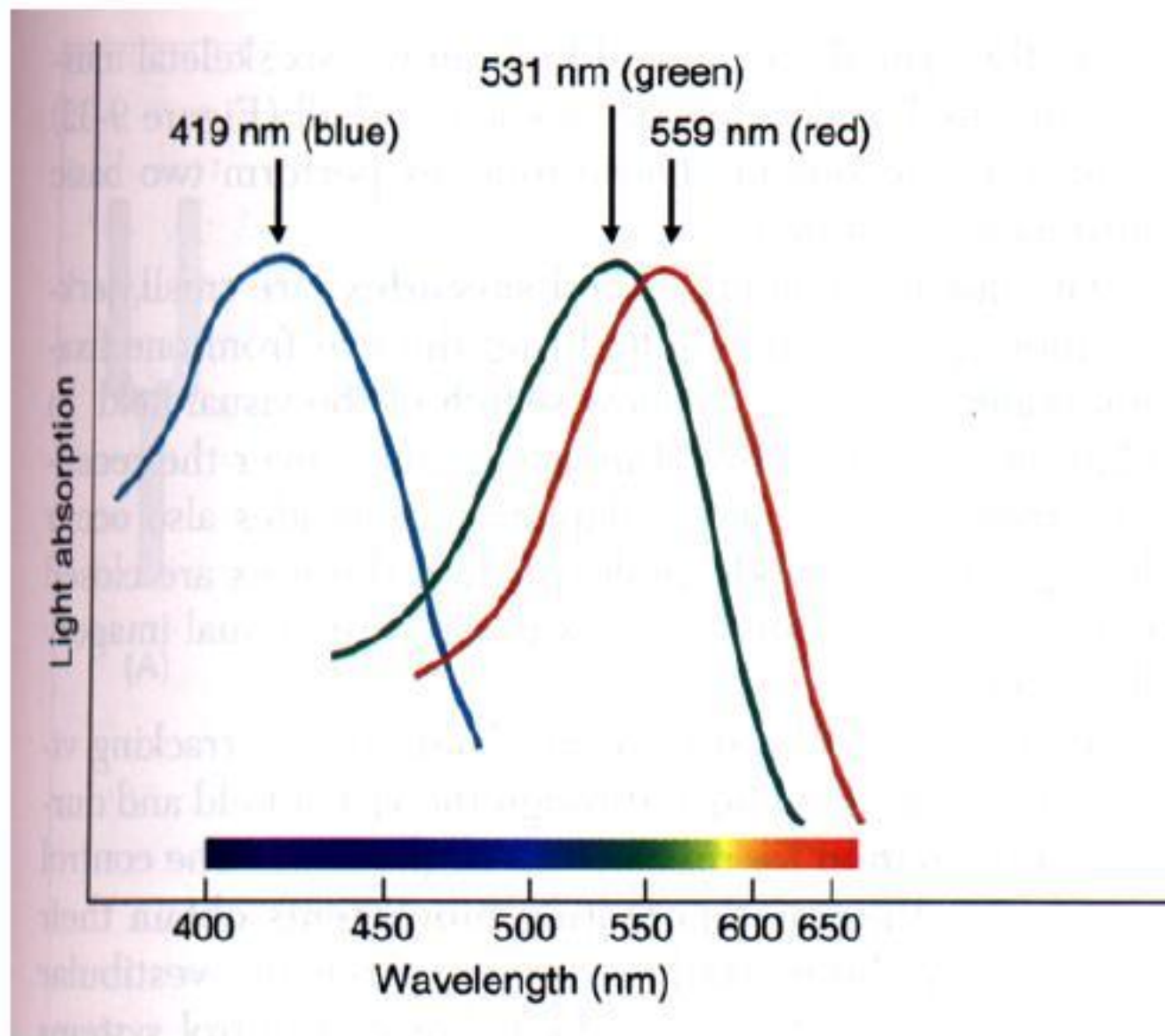


# Imaging in Humans

Courtesy of the National Eye Institute



# Cone Sensitivities

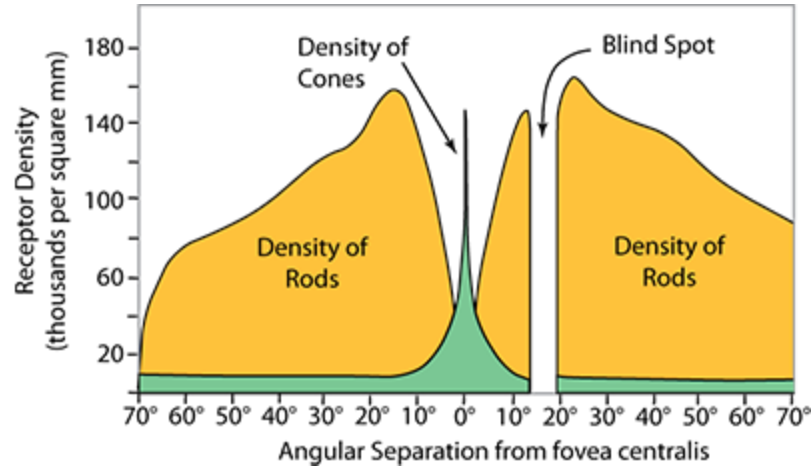
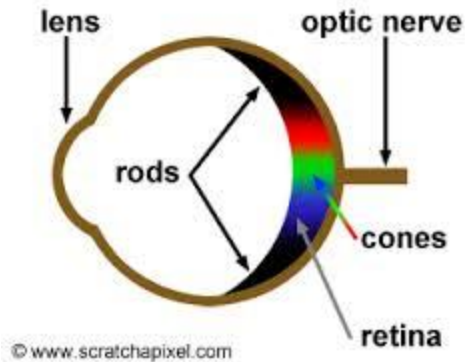




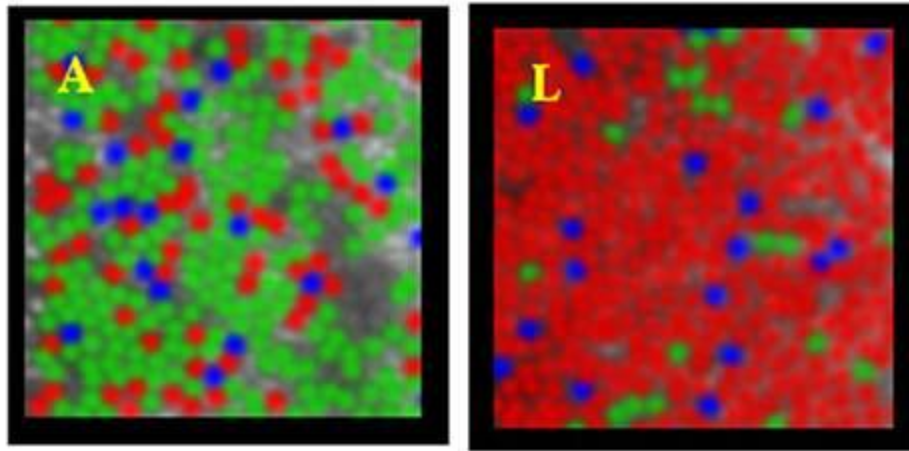
# Retinal sensors

- Sensors: rods and cones
- Rods are achromatic
  - contribute mostly to low resolution peripheral vision
- Cones are chromatic
  - contribute to high resolution central colour vision

# Retinal sensor layout



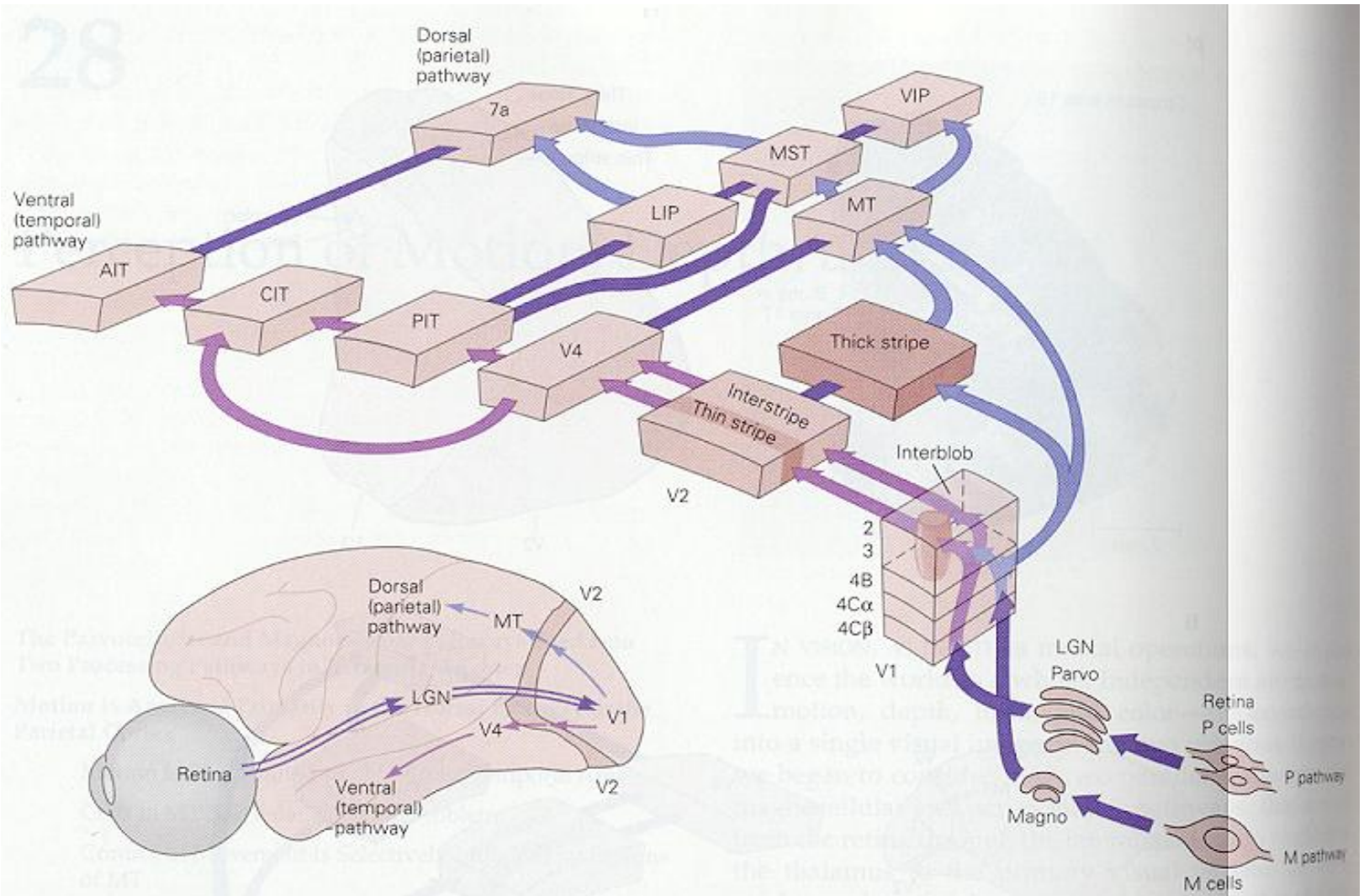
Unequal rod-cone distribution within retina



- Unequal distribution of colour sensor (cones) within the fovea

- The ratio of R,G cones varies across individuals (~1:1 to 16:1)
- Hofer *et al.* Jour. Neuroscience 2005

# Processing in HVS



# Image basics

# An image.....

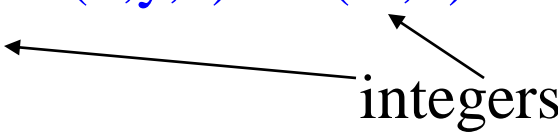
- Is a 2D signal, I.e. a function of **intensity** values  
 $\mathbf{f}(\mathbf{x},\mathbf{y}): \mathfrak{R}^2 \rightarrow \mathfrak{R}$  or  $\mathfrak{R}^3 \rightarrow \mathfrak{R}$ 
  - (x,y) or (x,y,z) spatial coordinates
  - domain and range of **f** is real

Intensity depends on many factors:

- Sensor
  - spectral characteristics
  - optics (lens)
- Environment and object
  - illumination
  - surface characteristics of the object



# Digital image

- The intensity function is a digital signal
  - $f(x,y)$  or  $f(x,y,z)$  is sampled and quantised
  - $(x,y)$  or  $(x,y,z) \rightarrow (m,n)$  or  $(m,n,k)$
  - $f \rightarrow I$    
integers
- the dimensionality of the spatial coordinates results in a 2-D pixel or 3-D voxel as the basic element

**In this course, we deal with 2-D planar images**

**$\therefore$  digital image  $I(m,n): \mathbb{Z}^2 \rightarrow \mathbb{Z}$**

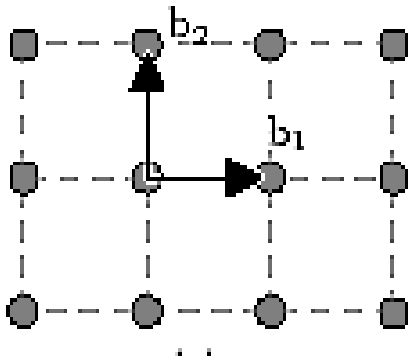
How do we sample a 2-D space?

# Options for sampling lattice

Sampling in

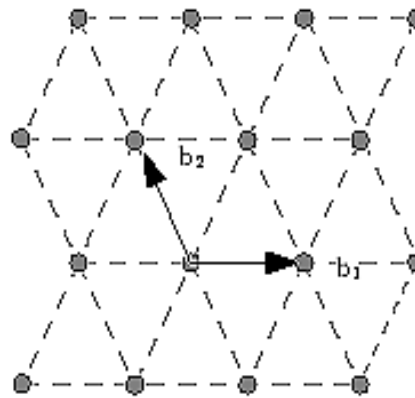
Orthogonal directions

Non-orthogonal directions



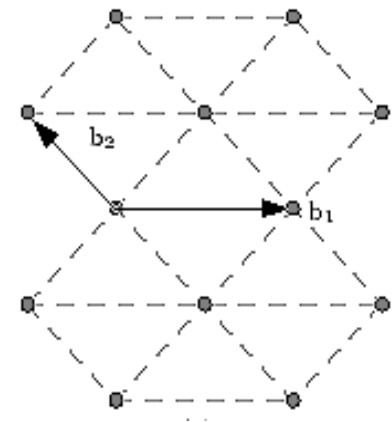
**Square**

$$L_s = \begin{bmatrix} (1,0) & (0,1) \\ b_1 & b_2 \end{bmatrix}$$



**Hexagonal**

$$L_h = [(1,0) \quad (-1/2, \sqrt{3}/2)]$$



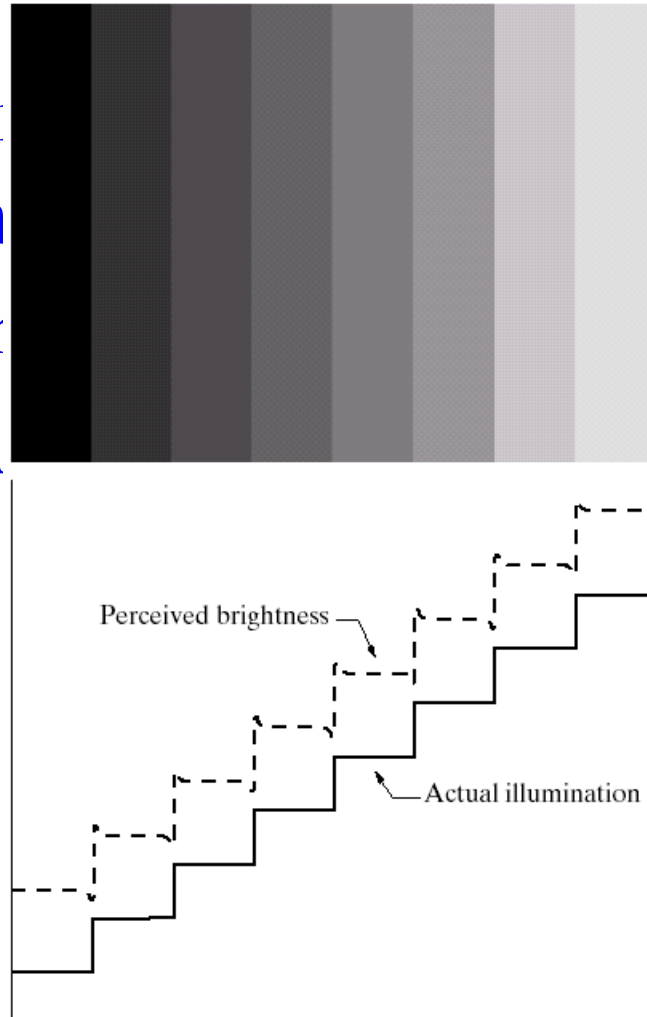
**Quincunx**

$$L_q = [(2,0) \quad (-1,1)]$$

A point in the image is now expressed as  $[m \ n] L$   
 $m, n$  are integer coordinates,  $L$  is the lattice

# Luminosity and Brightness

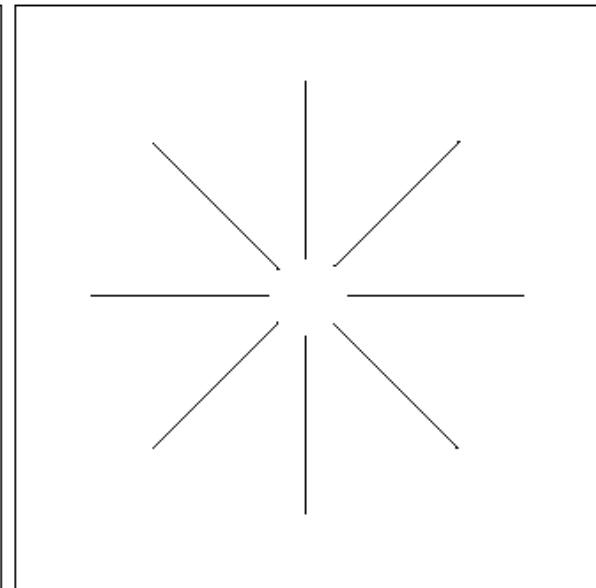
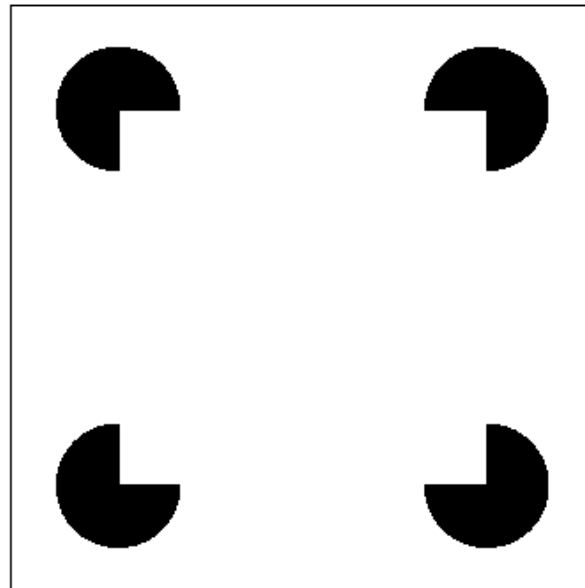
- *Luminosity* is the amount of light that comes from a certain source – reflected from a surface
- *Brightness* is the amount of light that is perceived or received



Brightness is not a simple function of intensity



Al



vely

Human perception is not fully understood !!

Per

- c
- e

, etc.

# Pixel depth

- Current standard is 8 bits/colour plane
- Dolby is proposing 12-16 bits/colour plane
- Display brightness in candellas/m<sup>2</sup> (nits)
- Current std: 48 (legacy from film projectors) Dolby proposes 4000