

Digital Image Processing (CSE 478)

Lecture 24: Image Reconstruction from Projections

Vineet Gandhi

Center for Visual Information Technology (CVIT), IIIT Hyderabad

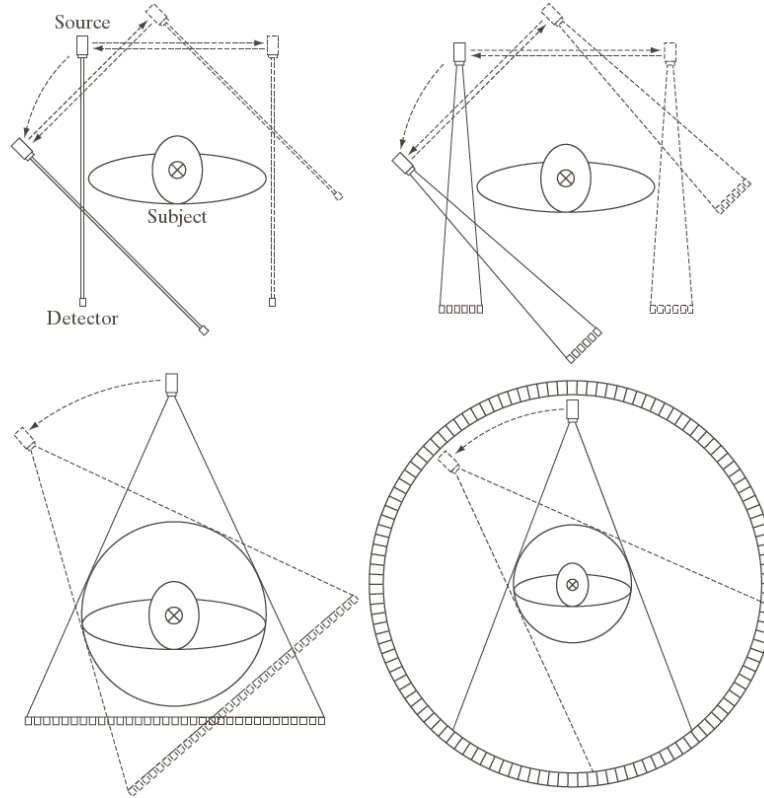
CT Scan



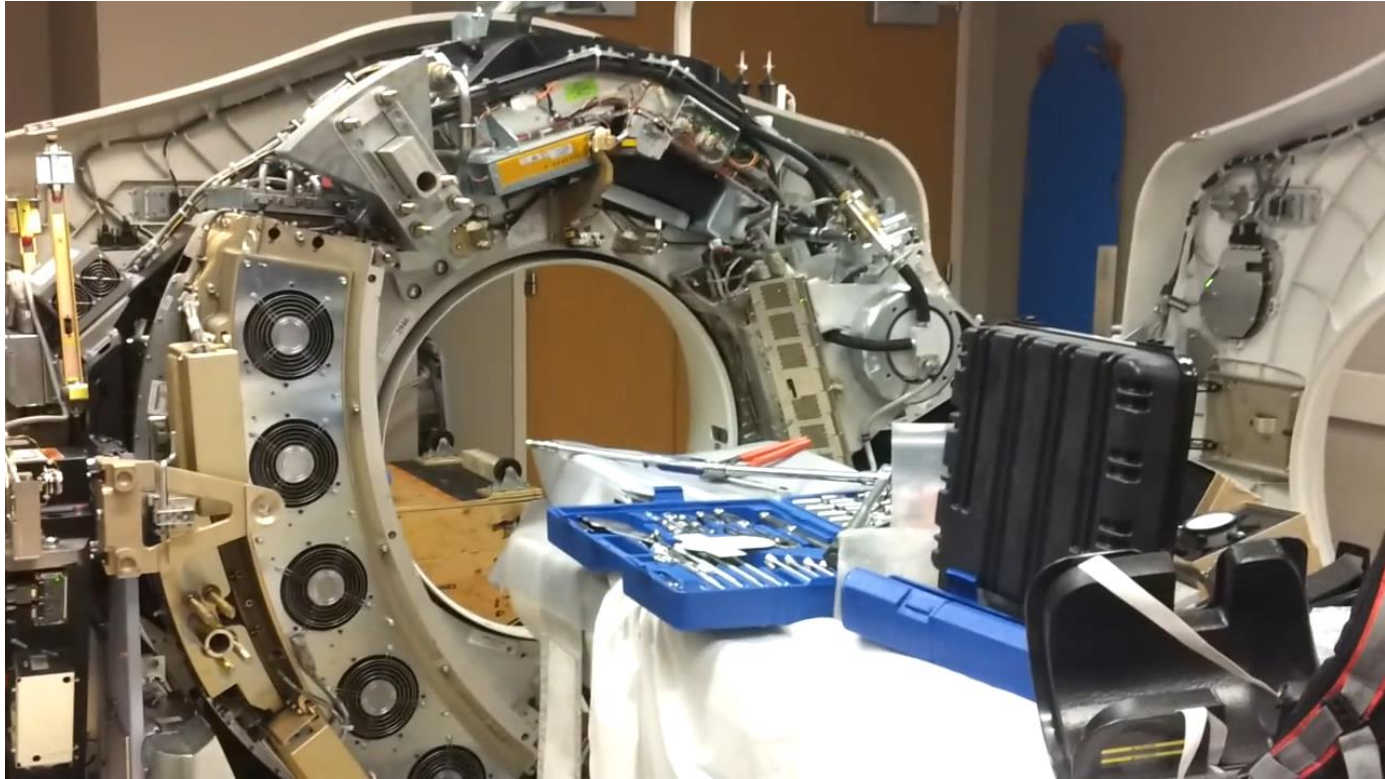
CT Scan

a b
c d

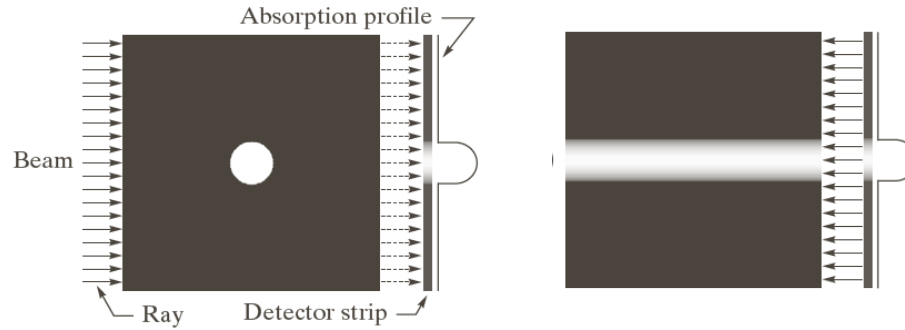
FIGURE 5.35 Four generations of CT scanners. The dotted arrow lines indicate incremental linear motion. The dotted arrow arcs indicate incremental rotation. The cross-mark on the subject's head indicates linear motion perpendicular to the plane of the paper. The double arrows in (a) and (b) indicate that the source/detector unit is translated and then brought back into its original position.



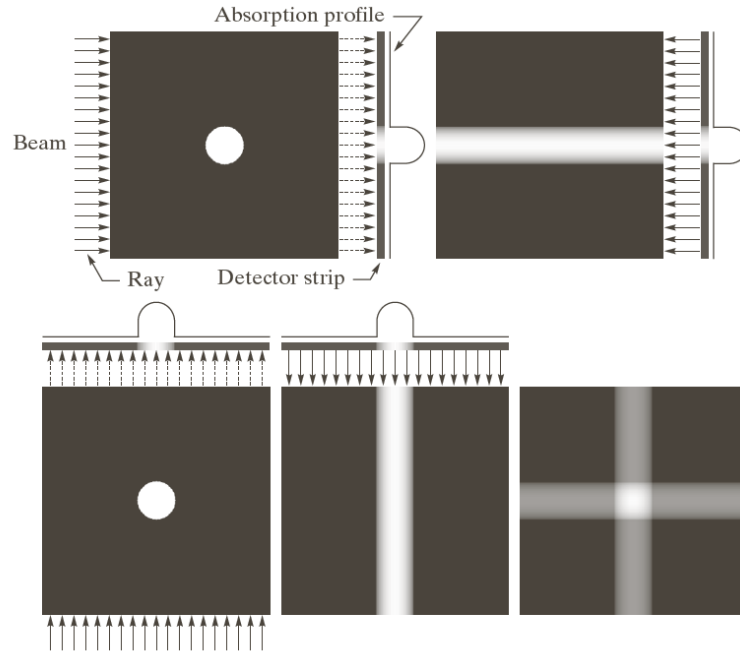
CT Scan



Projection with simple objects



Projection with simple objects



a b
c d e

FIGURE 5.32

(a) Flat region showing a simple object, an input parallel beam, and a detector strip. (b) Result of back-projecting the sensed strip data (i.e., the 1-D absorption profile). (c) The beam and detectors rotated by 90° . (d) Back-projection. (e) The sum of (b) and (d). The intensity where the back-projections intersect is twice the intensity of the individual back-projections.

Projection with simple objects

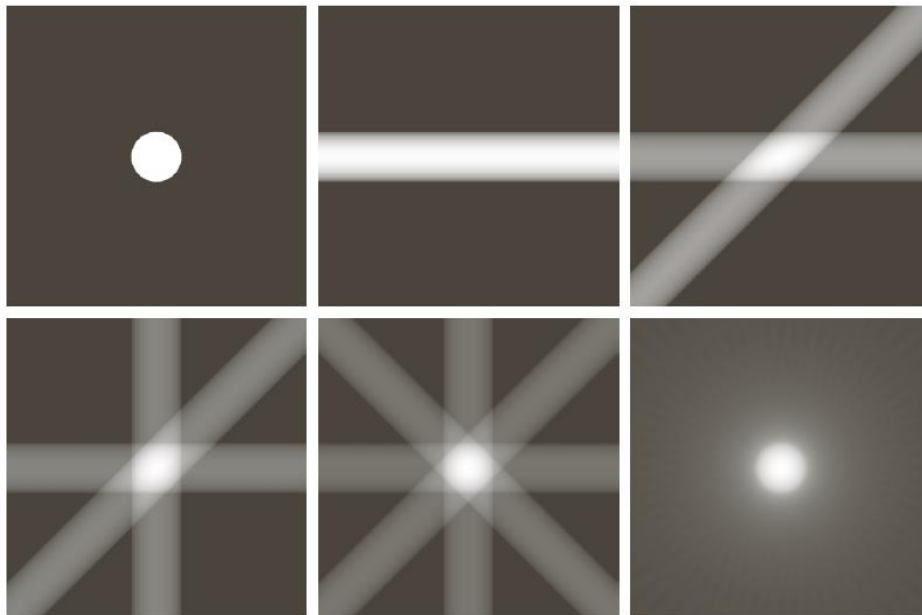
a	b	c
d	e	f

FIGURE 5.33

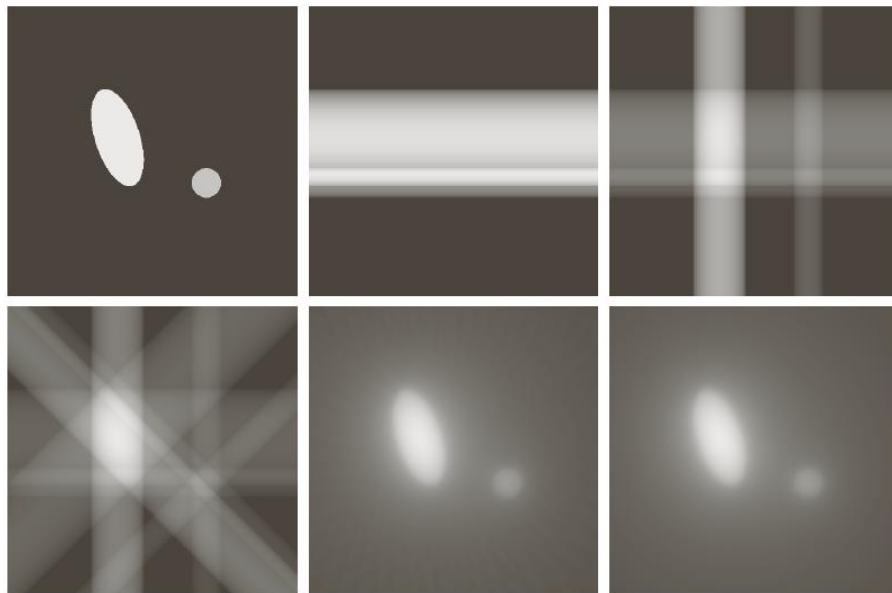
(a) Same as Fig. 5.32(a).

(b)–(e)
Reconstruction
using 1, 2, 3, and 4
backprojections 45°
apart.

(f) Reconstruction
with 32 backprojec-
tions 5.625° apart
(note the blurring).



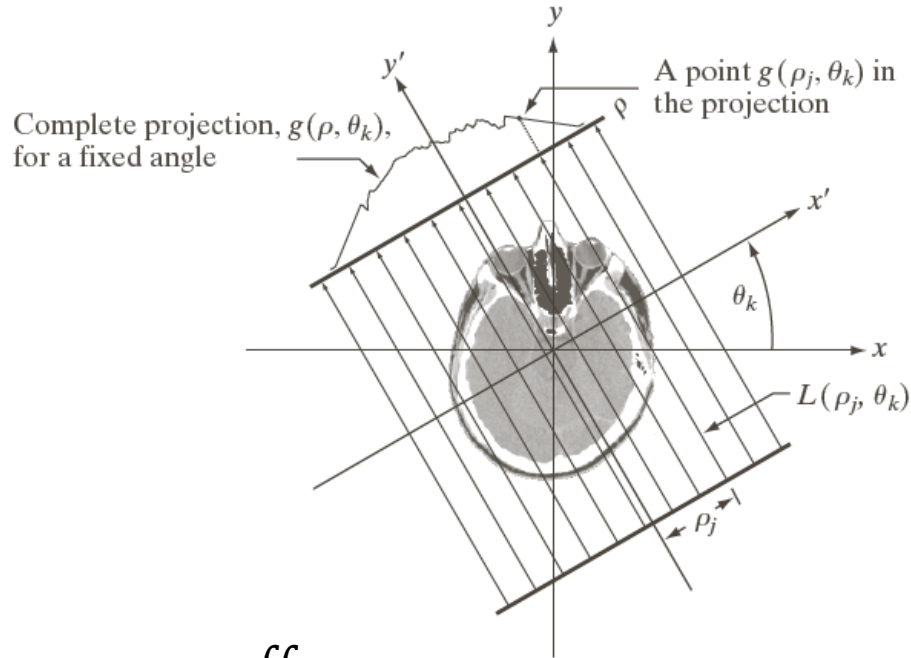
Projection with simple objects



a b c
d e f

FIGURE 5.34 (a) A region with two objects. (b)–(d) Reconstruction using 1, 2, and 4 backprojections 45° apart. (e) Reconstruction with 32 backprojections 5.625° apart. (f) Reconstruction with 64 backprojections 2.8125° apart.

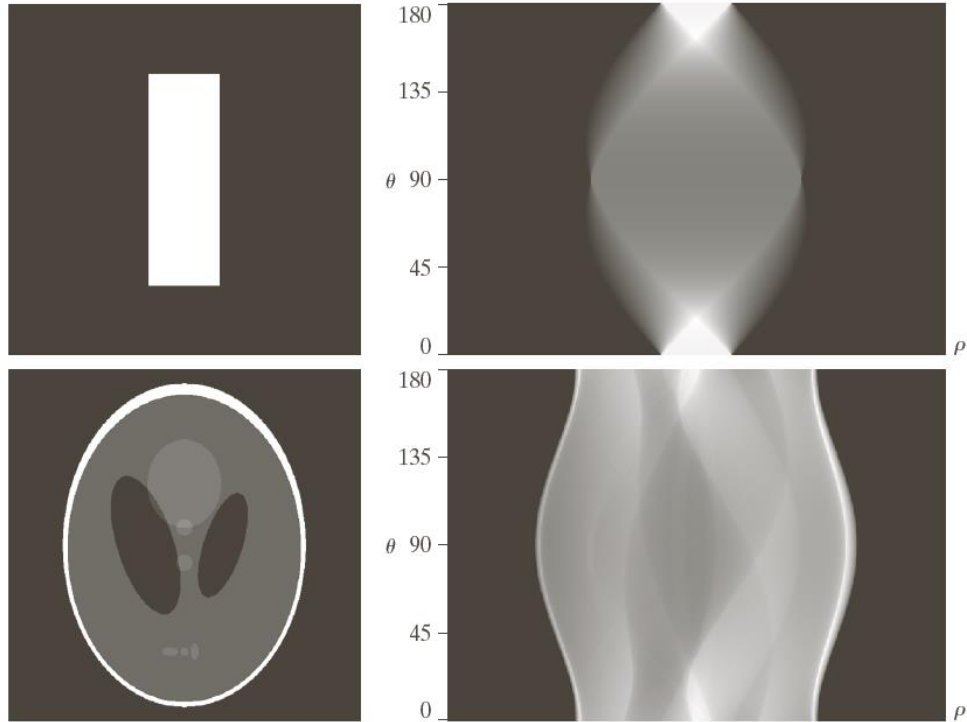
Radon Transform



$$g(\rho_j, \theta_k) = \iint f(x, y) \delta(x \cos \theta_k + y \sin \theta_k - \rho_j) dx dy$$

$$g(\rho, \theta) = \iint f(x, y) \delta(x \cos \theta + y \sin \theta - \rho) dx dy$$

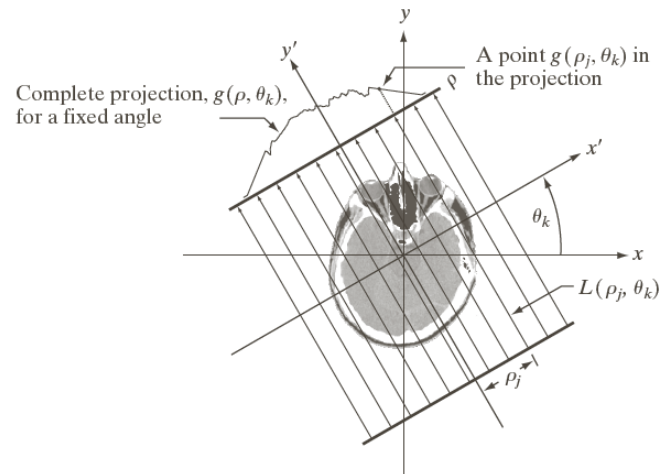
Sinograms



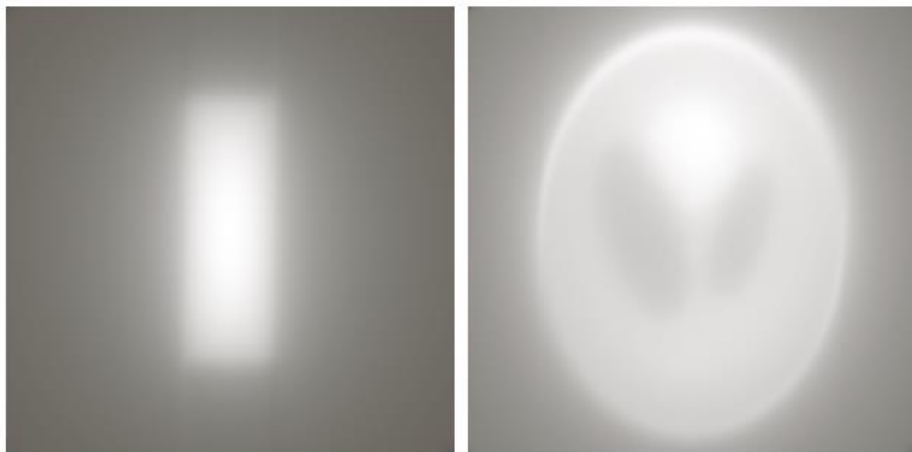
Reconstruction

$$f_{\theta}(x, y) = g(\rho, \theta_k) = g(x \cos \theta_k + y \sin \theta_k, \theta_k)$$

$$f(x, y) = \int_{\theta=0}^{\pi} f_{\theta}(x, y)$$



Reconstruction



a b

FIGURE 5.40
Backprojections
of the sinograms
in Fig. 5.39.

Fourier Slice theorem

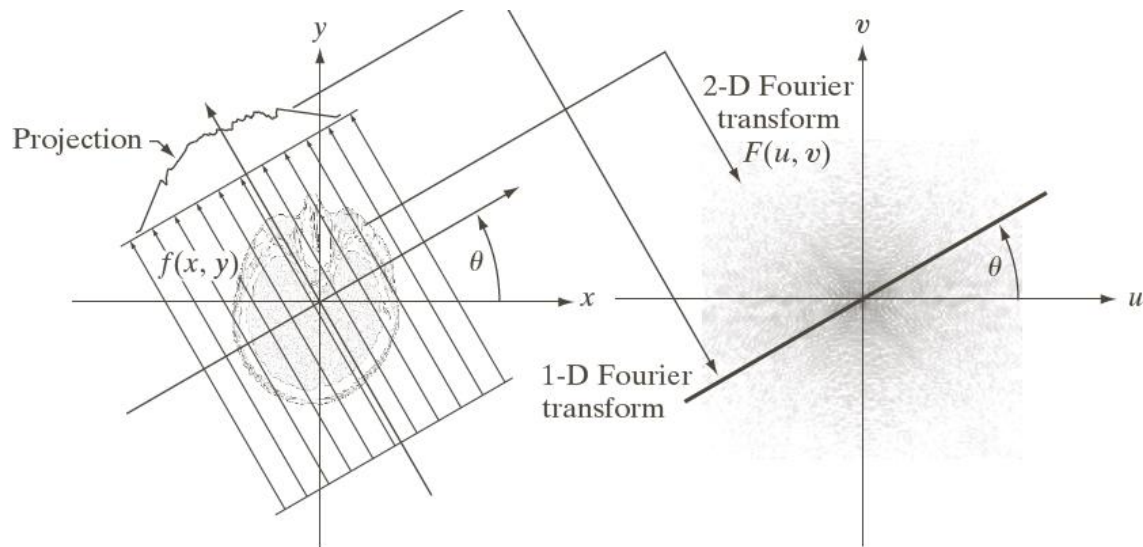


FIGURE 5.41

Illustration of the Fourier-slice theorem. The 1-D Fourier transform of a projection is a slice of the 2-D Fourier transform of the region from which the projection was obtained. Note the correspondence of the angle θ .

Filtered projection example



a b

FIGURE 5.44

Filtered backprojections of the head phantom using (a) a ramp filter, and (b) a Hamming-windowed ramp filter. Compare with Fig. 5.40(b).

CT Scan

a b
c d

FIGURE 5.35 Four generations of CT scanners. The dotted arrow lines indicate incremental linear motion. The dotted arrow arcs indicate incremental rotation. The cross-mark on the subject's head indicates linear motion perpendicular to the plane of the paper. The double arrows in (a) and (b) indicate that the source/detector unit is translated and then brought back into its original position.

