

Introduction to Filters

Colophon

An annotatable worksheet for this presentation is available as [Worksheet 15](https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/worksheet15.html) (https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/worksheet15.html).

- The source code for this page is [content/fourier_transform/4/ft4.ipynb](https://github.com/cpjobling/eg-247-textbook/blob/master/content/fourier_transform/4/ft4.ipynb) (https://github.com/cpjobling/eg-247-textbook/blob/master/content/fourier_transform/4/ft4.ipynb).
- You can view the notes for this presentation as a webpage (HTML (https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/ft4.html)).
- This page is downloadable as a [PDF](https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/ft4.pdf) (https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/ft4.pdf) file.

Scope and Background Reading

This section is Based on the section **Filtering** from Chapter 5 of [Benoit Boulet, Fundamentals of Signals and Systems](https://ebookcentral.proquest.com/lib/swansea-ebooks/reader.action?ppg=221&docID=3135971&tm=1518715953782) (<https://ebookcentral.proquest.com/lib/swansea-ebooks/reader.action?ppg=221&docID=3135971&tm=1518715953782>) from the **Recommended Reading List**.

This material is an introduction to analogue filters. You will find much more in-depth coverage on [Pages 11-1 – 11-48 of Karris](https://ebookcentral.proquest.com/lib/swansea-ebooks/reader.action?ppg=429&docID=3384197&tm=1518716026573) (<https://ebookcentral.proquest.com/lib/swansea-ebooks/reader.action?ppg=429&docID=3384197&tm=1518716026573>).

Agenda

- Frequency Selective Filters
- Ideal low-pass filter
- Butterworth low-pass filter

- High-pass filter
- Bandpass filter

Introduction

- Filter design is an important application of the Fourier transform
- Filtering is a rich topic often taught in graduate courses so we give only an introduction.
- Our introduction *will* illustrate the usefulness of the frequency domain viewpoint.
- We will explore how filters can shape the spectrum of a signal.

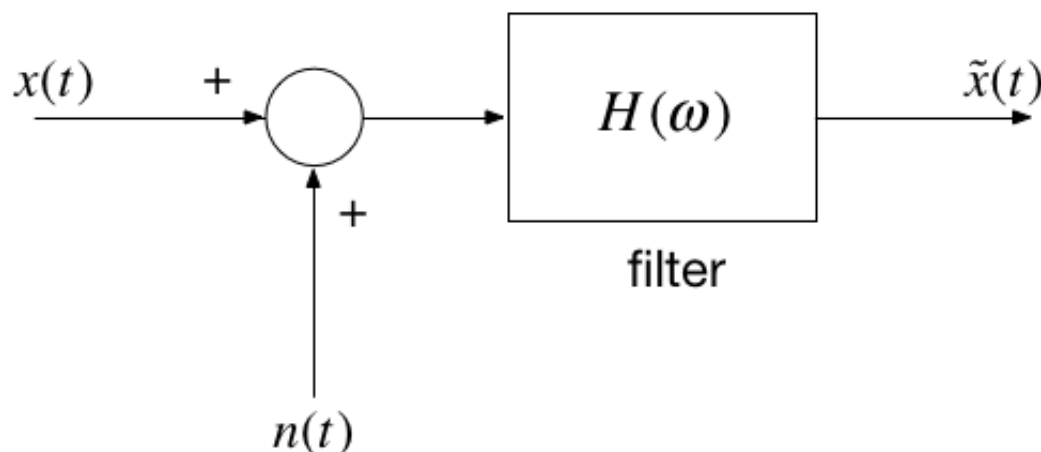
Other applications of the Fourier transform are sampling theory (introduced next week) and modulation.

Frequency Selective Filters

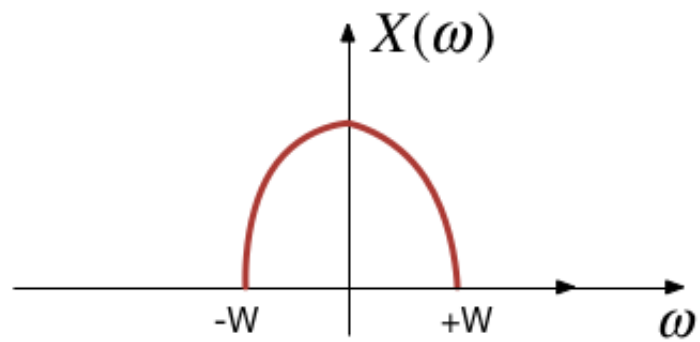
An ideal frequency-selective filter is a system that let's the frequency components of a signal through undistorted while frequency components at other components are completely cut off.

- The range of frequencies which are let through belong to the **pass Band**
- The range of frequencies which are cut-off by the filter are called the **stopband**
- A typical scenario where filtering is needed is when noise $n(t)$ is added to a signal $x(t)$ but that signal has most of its energy outside the bandwidth of a signal.

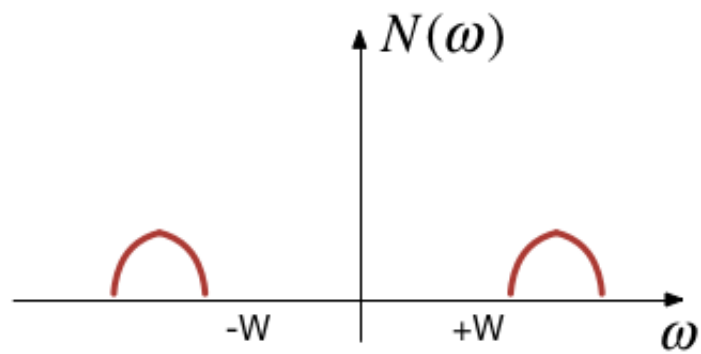
Typical filtering problem



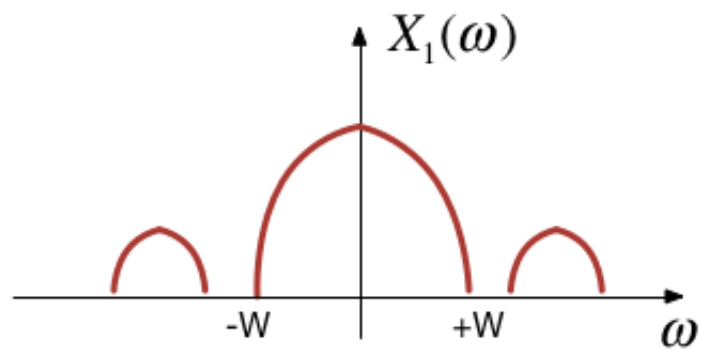
Signal



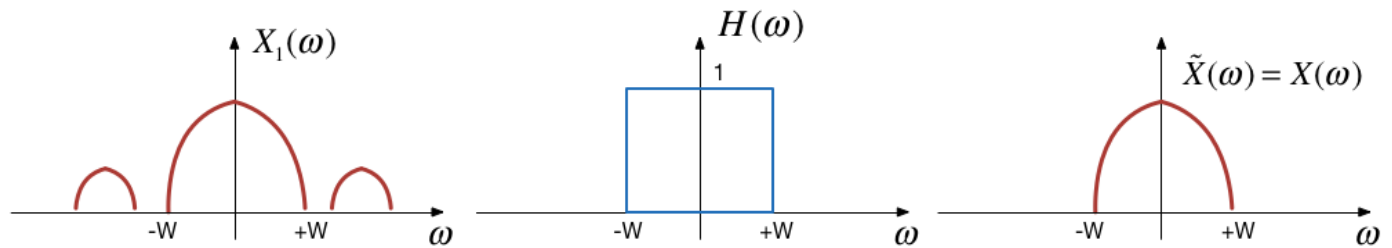
Out-of Bandwidth Noise



Signal plus Noise



Filtering



Motivating example

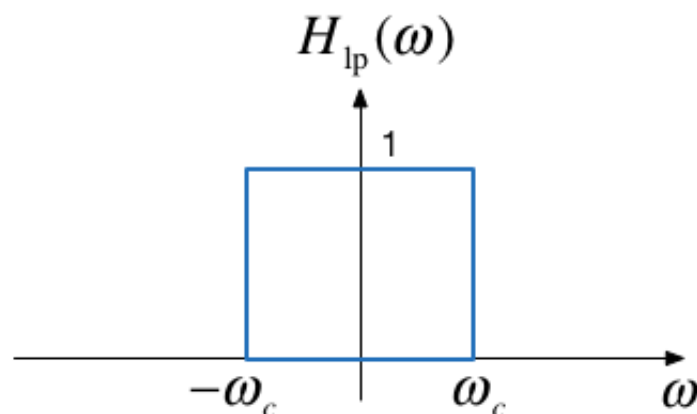
See the video and script on [Canvas Week 7 \(https://canvas.swansea.ac.uk/courses/646/pages/week-7-classroom-activities?module_item_id=398892\)](https://canvas.swansea.ac.uk/courses/646/pages/week-7-classroom-activities?module_item_id=398892).

Ideal Low-Pass Filter (LPF)

An ideal low pass filter cuts-off frequencies higher than its *cut-off frequency*, ω_c .

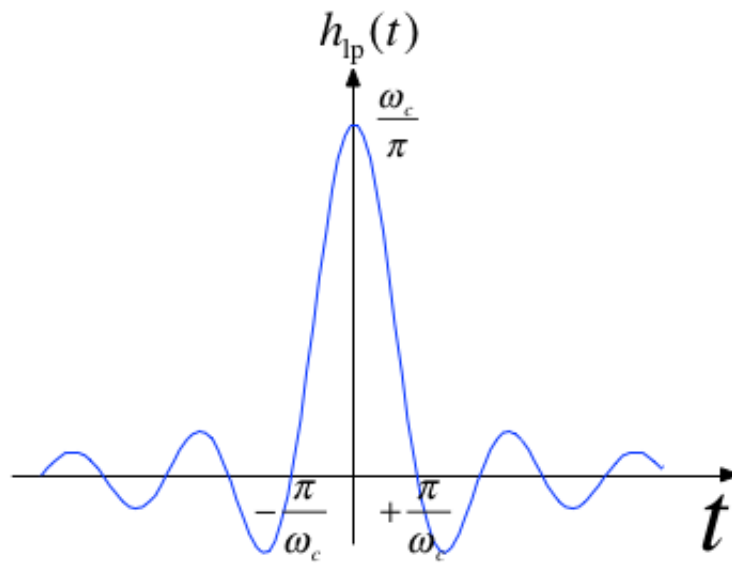
$$H_{lp}(\omega) = \begin{cases} 1, & |\omega| < \omega_c \\ 0, & |\omega| \geq \omega_c \end{cases}$$

Frequency response of LPF



Impulse response

$$h_{lp}(t) = \frac{\omega_c}{\pi} \operatorname{sinc}\left(\frac{\omega_c}{\pi} t\right)$$



Filtering is Convolution

The output of an LTI system with impulse response

$$h(t) \Leftrightarrow H(\omega)$$

subject to an input signal

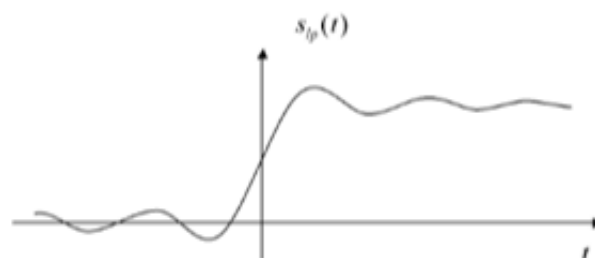
$$x(t) \Leftrightarrow X(\omega)$$

is given by

$$y(t) = h(t) * x(t) \Leftrightarrow Y(\omega) = H(\omega)X(\omega)$$

Issues with the "ideal" filter

This is the step response:



(reproduced from Boulet Fig. 5.23 p. 205)

Ripples in the impulse response would be undesirable, and because the impulse response is non-causal it cannot actually be implemented.

Butterworth low-pass filter

N-th Order Butterworth Filter

$$|H_B(\omega)| = \frac{1}{\left(1 + \left(\frac{\omega}{\omega_c}\right)^{2N}\right)^{\frac{1}{2}}}$$

Remarks

- DC gain is

$$|H_B(j0)| = 1$$

- Attenuation at the cut-off frequency is

$$|H_B(j\omega_c)| = 1/\sqrt{2}$$

for any N

More about the Butterworth filter: [Wikipedia Article \(http://en.wikipedia.org/wiki/Butterworth_filter\)](http://en.wikipedia.org/wiki/Butterworth_filter)

Example 5: Second-order BW Filter

The second-order butterworth Filter is defined by is Characteristic Equation (CE):

$$p(s) = s^2 + \omega_c \sqrt{2}s + \omega_c^2 = 0^*$$

Calculate the roots of $p(s)$ (the poles of the filter transfer function) in both Cartesian and polar form.

Note: This has the same characteristic as a control system with damping ratio $\zeta = 1/\sqrt{2}$ and $\omega_n = \omega_c$!

Solution to example 5



Example 6

Derive the differential equation relating the input $x(t)$ to output $y(t)$ of the 2nd-Order Butterworth Low-Pass Filter with cutoff frequency ω_c .

Solution to example 6**Example 7**

Determine the frequency response $H_B(\omega) = Y(\omega)/X(\omega)$

Solution to example 7



Magnitude of frequency response of a 2nd-order Butterworth Filter

```
In [2]: wc = 100;
```

Transfer function

```
In [3]: H = tf(wc^2,[1, wc*sqrt(2), wc^2])
```

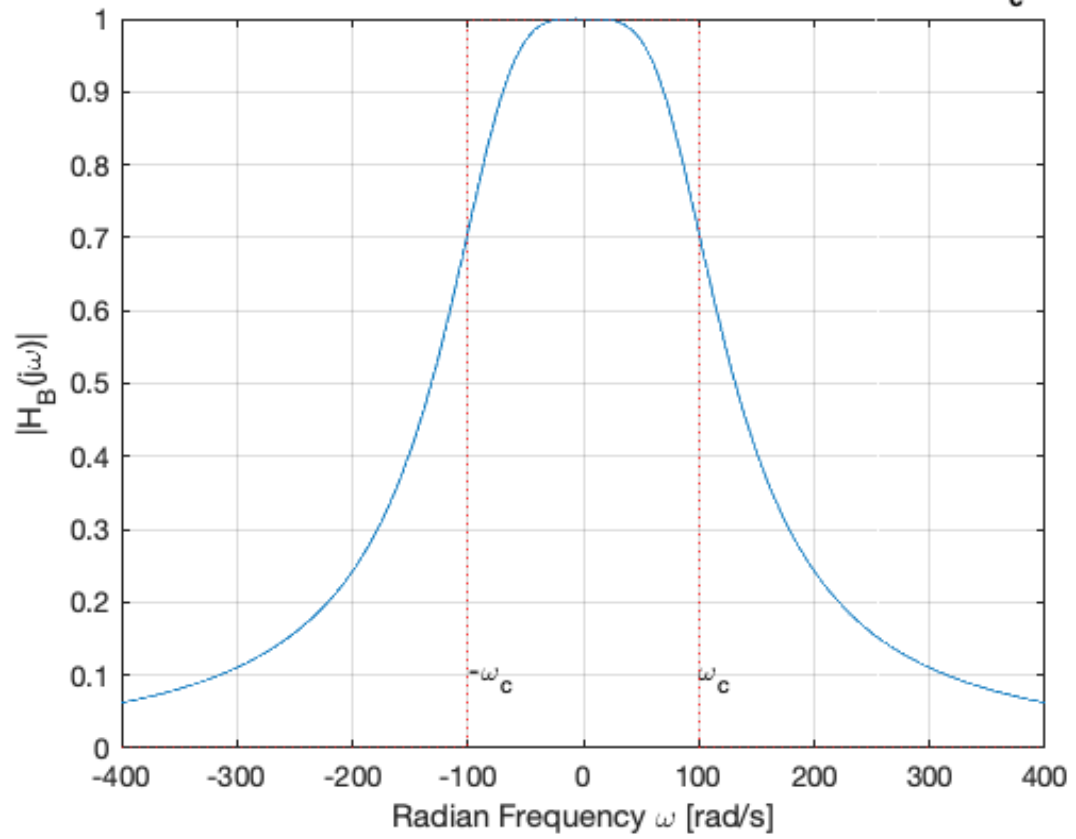
H =

$$\frac{10000}{s^2 + 141.4 s + 10000}$$

Continuous-time transfer function.

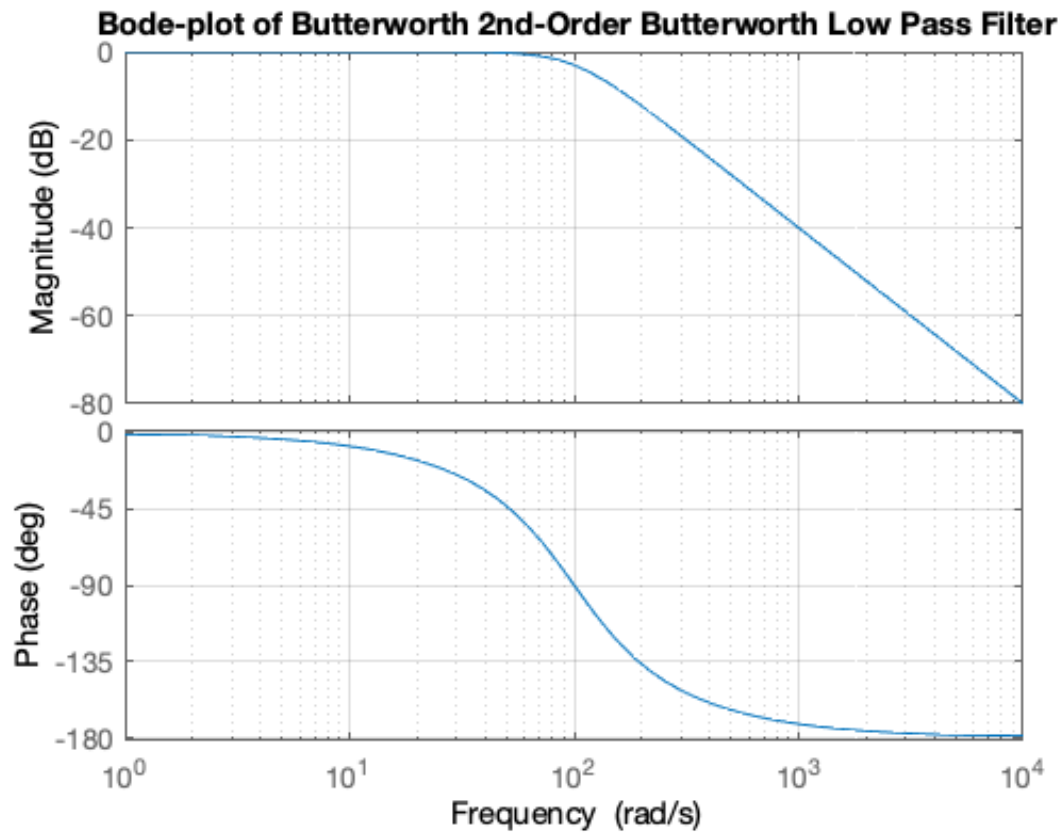
Magnitude frequency response

```
In [4]: w = -400:400;
mHlp = 1./((sqrt(1 + (w./wc).^4));
plot(w,mHlp)
grid
ylabel('|H_B(j\omega)|')
title('Magnitude Frequency Response for 2nd-Order LP Butterworth Fi
lter (\omega_c = 100 rad/s)')
xlabel('Radian Frequency \omega [rad/s]')
text(100,0.1,'\omega_c')
text(-100,0.1,'-\omega_c')
hold on
plot([-400,-100,-100,100,100,400],[0,0,1,1,0,0],'r:')
hold off
```

Magnitude Frequency Response for 2nd-Order LP Butterworth Filter ($\omega_c = 100$ rad/s)

Bode plot

```
In [5]: bode(H)
grid
title('Bode-plot of Butterworth 2nd-Order Butterworth Low Pass Filter')
```



Example 8

Determine the impulse and step response of a butterworth low-pass filter.

You will find this Fourier transform pair useful:

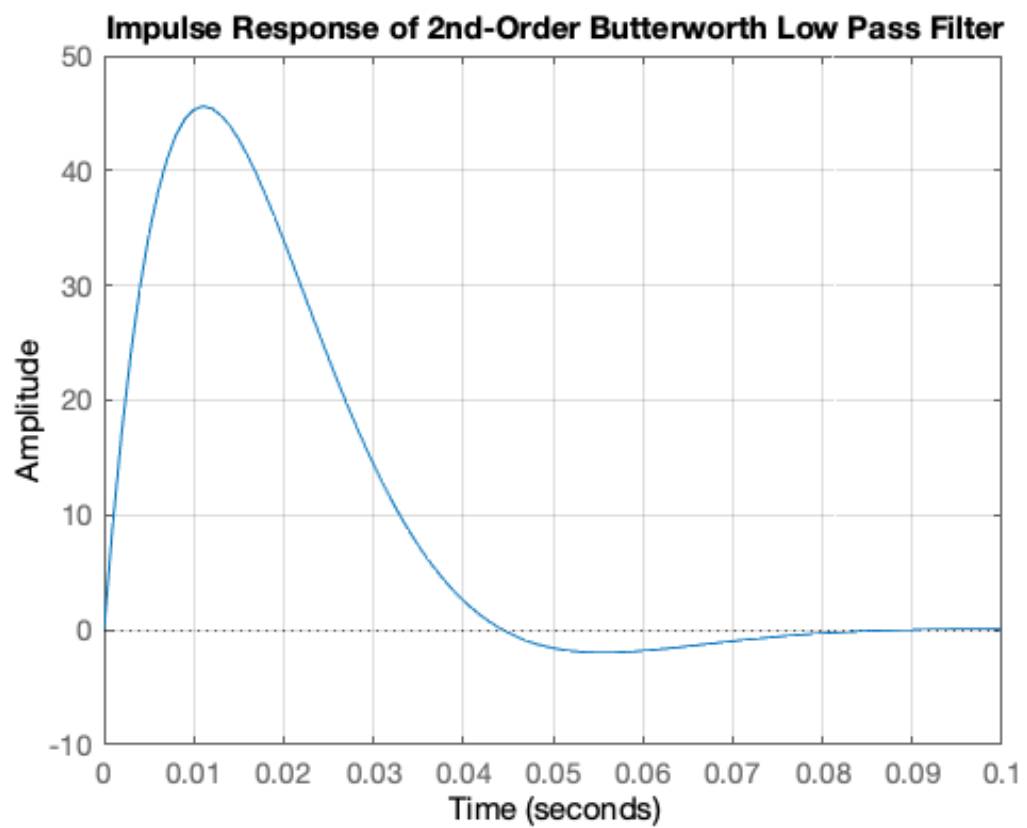
$$e^{-at} \sin \omega_0 t u_0(t) \Leftrightarrow \frac{\omega_0}{(j\omega + a)^2 + \omega_0^2}$$

Solution to example 8



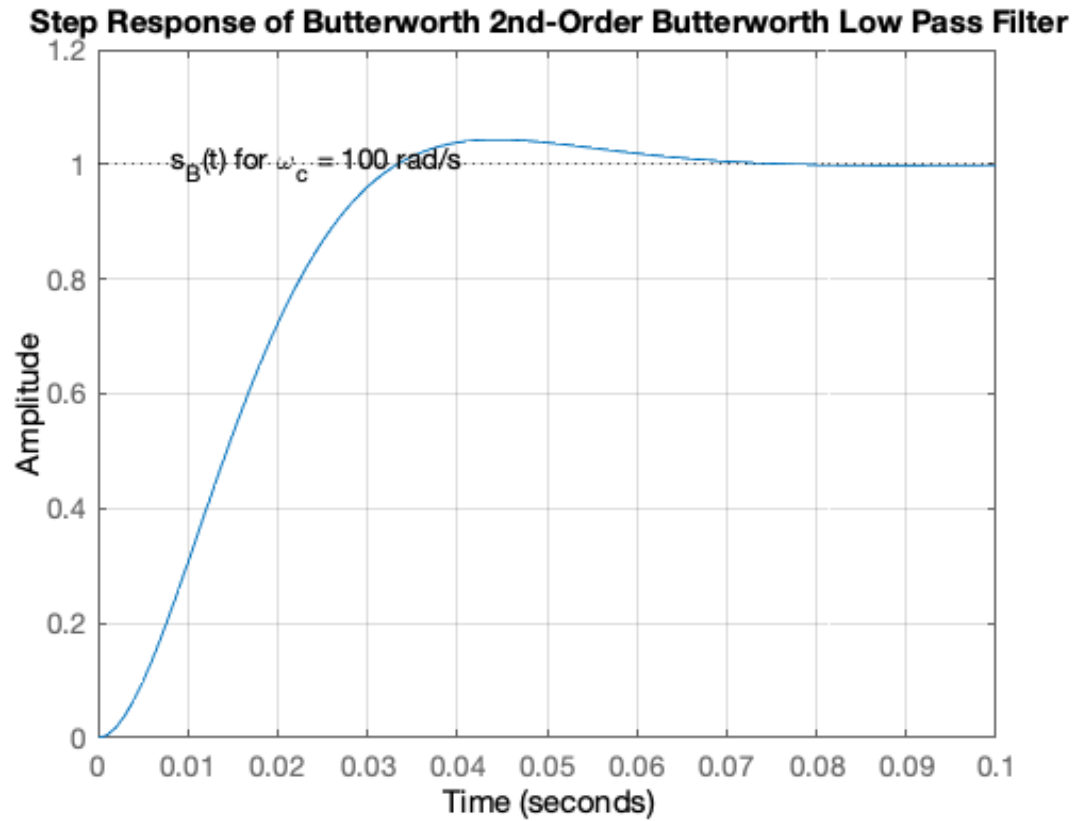
Impulse response

```
In [6]: impulse(H,0.1)
grid
title('Impulse Response of 2nd-Order Butterworth Low Pass Filter')
```



Step response

```
In [7]: step(H,0.1)
title('Step Response of Butterworth 2nd-Order Butterworth Low Pass
Filter')
grid
text(0.008,1,'sB(t) for \omegac = 100 rad/s')
```

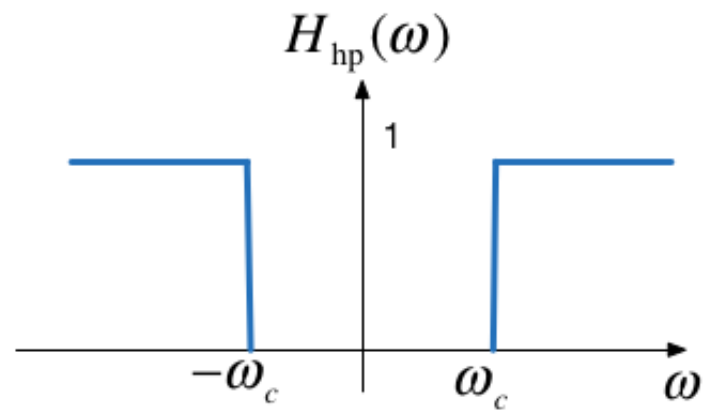


High-pass filter (HPF)

An ideal highpass filter cuts-off frequencies lower than its *cutoff frequency*, ω_c .

$$H_{\text{hp}}(\omega) = \begin{cases} 0, & |\omega| \leq \omega_c \\ 1, & |\omega| > \omega_c \end{cases}$$

Frequency response of HPF



Responses

Frequency response

$$H_{hp}(\omega) = 1 - H_{lp}(\omega)$$

Impulse response

$$h_{hp}(t) = \delta(t) - h_{lp}(t)$$

Example 9

Determine the frequency response of a 2nd-order butterworth highpass filter

Solution to example 9

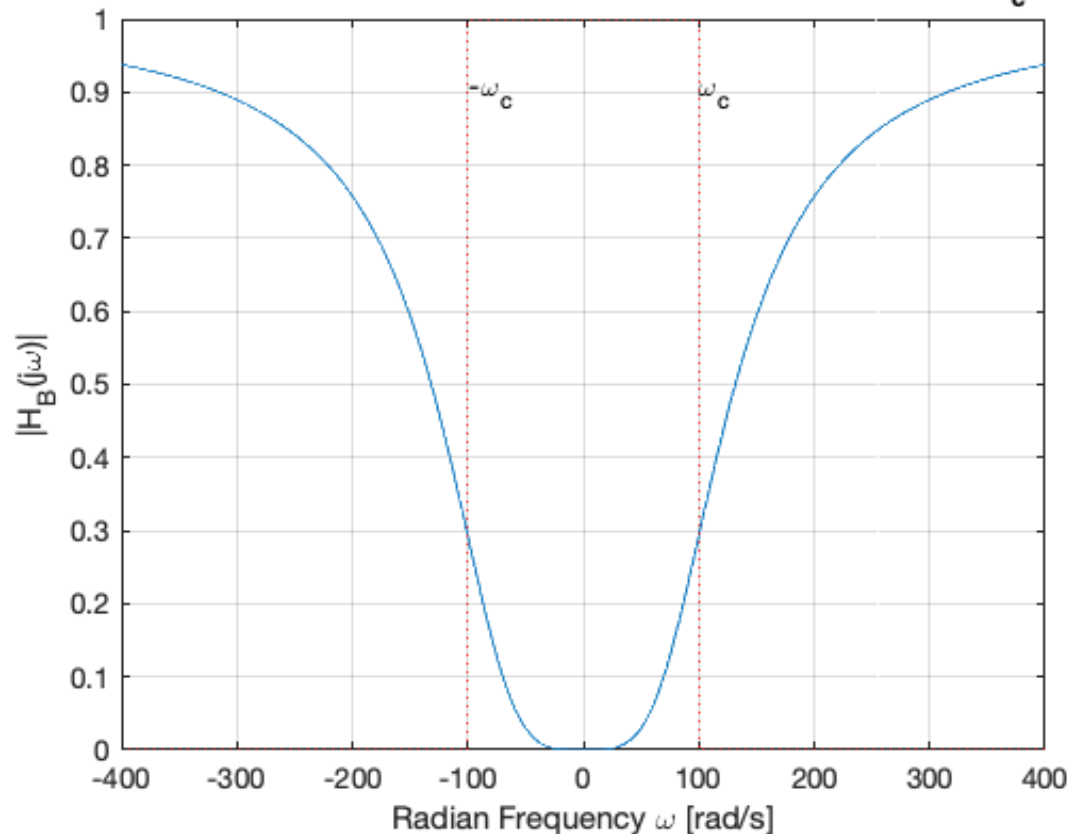
Magnitude frequency response

```

In [8]: w = -400:400;
plot(w,1-mHlp)
grid
ylabel('|H_B(j\omega)|')
title('Magnitude Frequency Response for 2nd-Order HP Butterworth Fi
lter (\omega_c = 100 rad/s)')
xlabel('Radian Frequency \omega [rad/s]')
text(100,0.9,'\omega_c')
text(-100,0.9,'-\omega_c')
hold on
plot([-400,-100,-100,100,100,400],[0,0,1,1,0,0],'r:')
hold off

```

Magnitude Frequency Response for 2nd-Order HP Butterworth Filter ($\omega_c = 100$ rad/s)



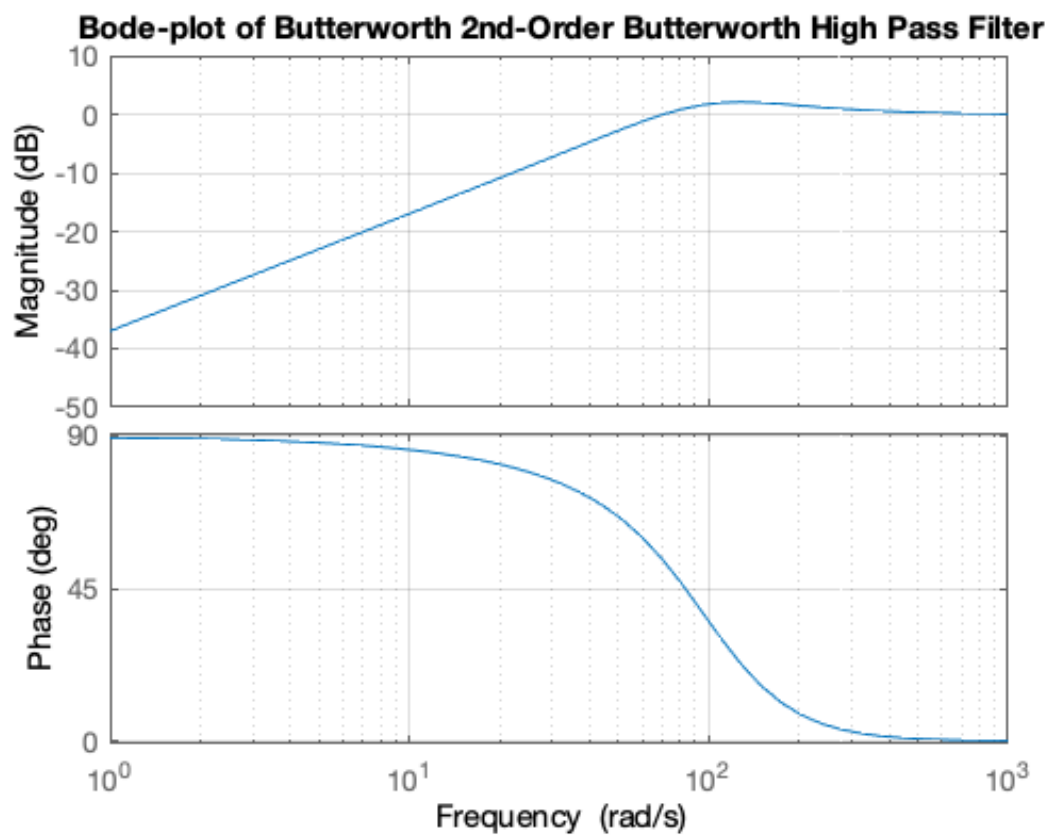
High-pass filter

```
In [9]: Hhp = 1 - H
bode(Hhp)
grid
title('Bode-plot of Butterworth 2nd-Order Butterworth High Pass Filter')
```

Hhp =

$$\frac{s^2 + 141.4 s}{s^2 + 141.4 s + 10000}$$

Continuous-time transfer function.

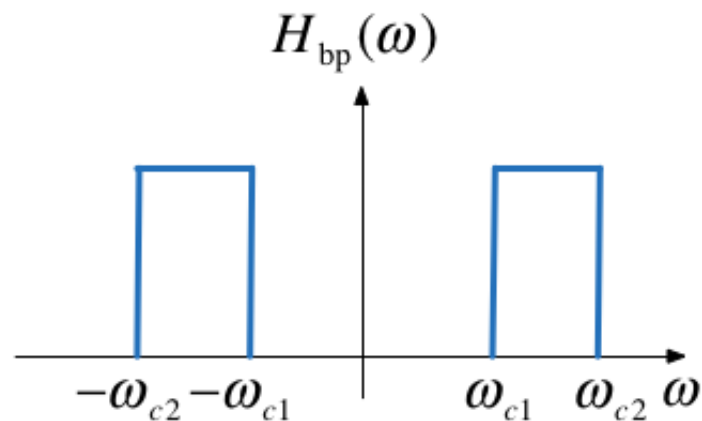


Band-pass filter (BPF)

An ideal bandpass filter cuts-off frequencies lower than its first *cutoff frequency* ω_{c1} , and higher than its second *cutoff frequency* ω_{c2} .

$$H_{bp}(\omega) = \begin{cases} 1, & \omega_{c1} < |\omega| < \omega_{c2} \\ 0, & \text{otherwise} \end{cases}$$

Frequency response of BPF



Bandpass filter design

A bandpass filter can be obtained by multiplying the frequency responses of a lowpass filter by a highpass filter.

$$H_{bp}(\omega) = H_{hp}(\omega)H_{lp}(\omega)$$

- The highpass filter should have cut-off frequency of ω_{c1}
- The lowpass filter should have cut-off frequency of ω_{c2}

To generate all the plots shown in this presentation, you can use [butter2_ex.mlx](https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/butter2_ex.mlx) (https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/butter2_ex.mlx).

Summary

- Frequency-Selective Filters
- Ideal low-pass filter
- Butterworth low-pass filter
- High-pass filter
- Bandpass filter

Solutions

Solutions to Examples 5-9 are captured as a PenCast in [filters.pdf \(https://cpjobling.github.io/eg-247-textbook/fourier_transform/solutions/filters2.pdf\)](https://cpjobling.github.io/eg-247-textbook/fourier_transform/solutions/filters2.pdf).