

Worksheet 15

To accompany Section 5.4 Introduction to Filters

We will step through this worksheet in class.

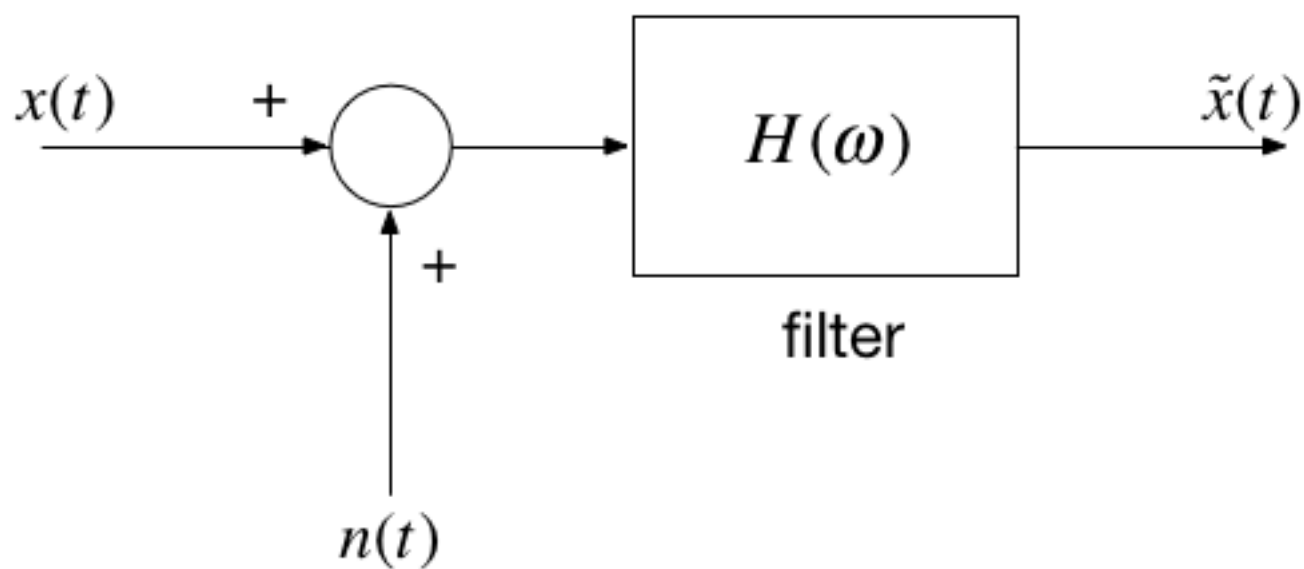
You are expected to have at least watched the video presentation of [Chapter 5.4](https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/ft4) (https://cpjobling.github.io/eg-247-textbook/fourier_transform/4/ft4) of the [notes](https://cpjobling.github.io/eg-247-textbook) (<https://cpjobling.github.io/eg-247-textbook>) before coming to class. If you haven't watch it afterwards!

Frequency Selective Filters

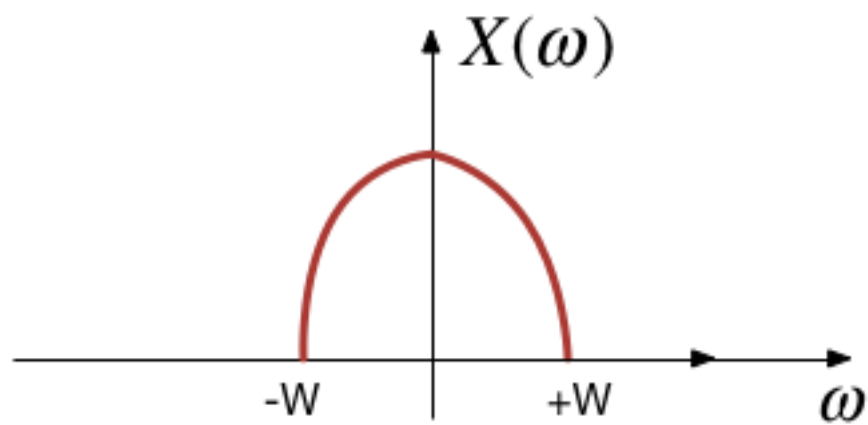
An ideal frequency-selective filter is a system that let's the frequency components of a signal through undistorted while frequency components at other components are completely cut off.

- The range of frequencies which are let through belong to the **pass Band**
- The range of frequencies which are cut-off by the filter are called the **stopband**
- A typical scenario where filtering is needed is when noise $n(t)$ is added to a signal $x(t)$ but that signal has most of its energy outside the bandwidth of a signal.

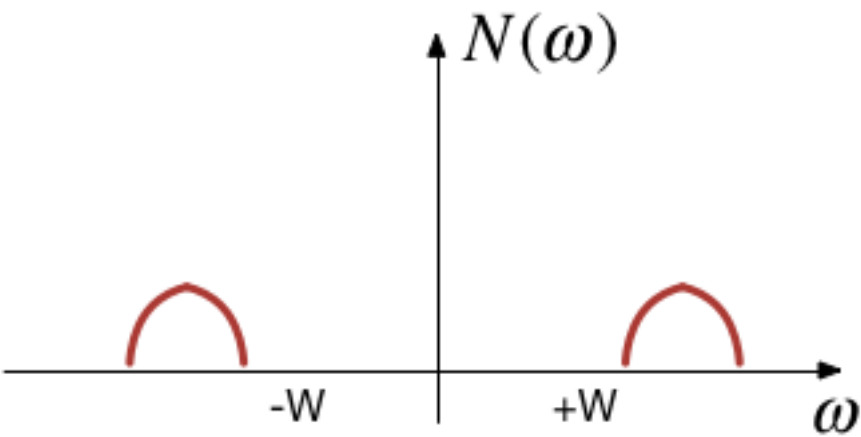
Typical filtering problem



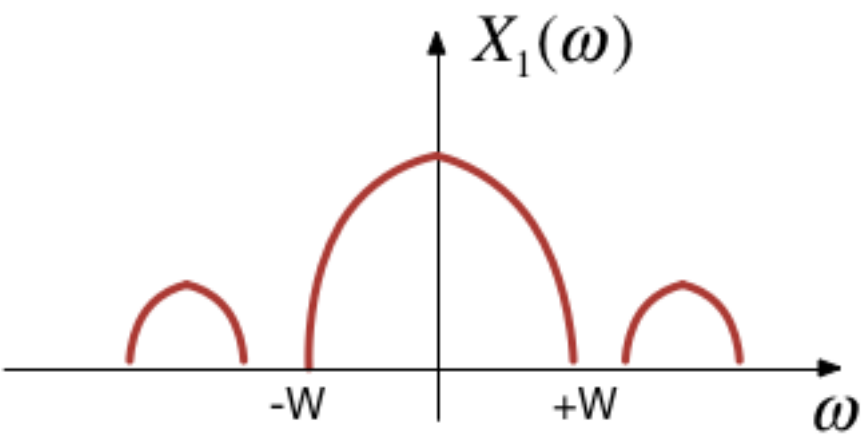
Signal



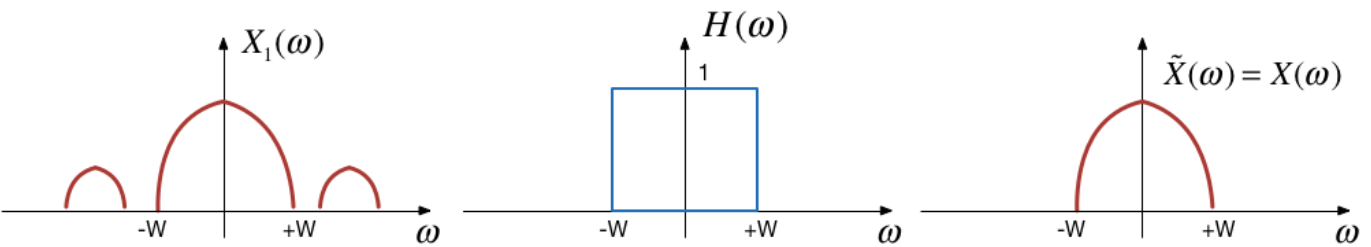
Out-of Bandwidth Noise



Signal plus Noise



Filtering



Motivating example

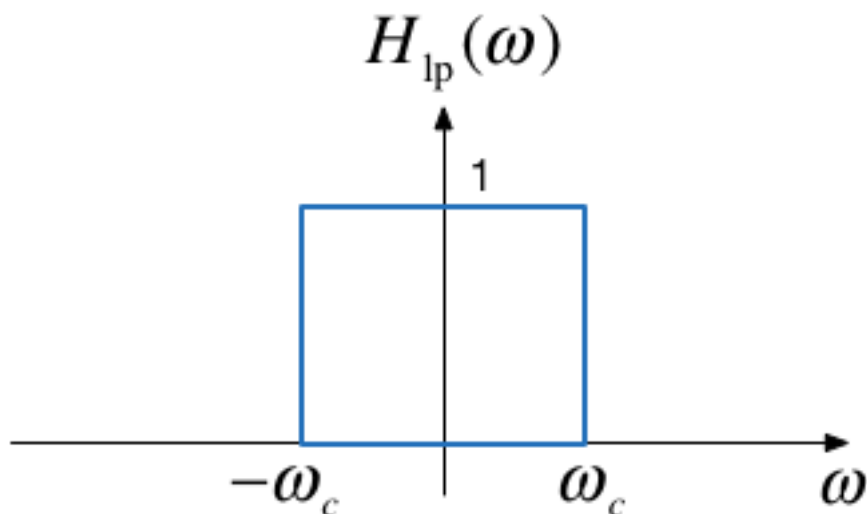
See the video and script on *Canvas Week 7*.

Ideal Low-Pass Filter

An ideal low pass filter cuts-off frequencies higher than its *cutoff frequency*, ω_c .

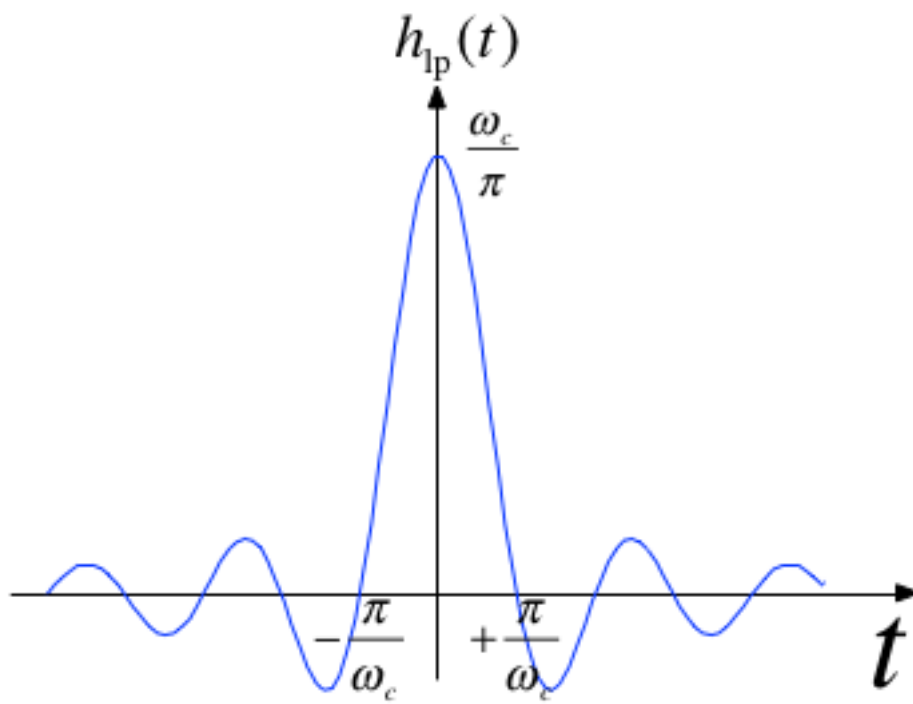
$$H_{\text{lp}}(\omega) = \begin{cases} 1, & |\omega| < \omega_c \\ 0, & |\omega| \geq \omega_c \end{cases}$$

Frequency response



Impulse response

$$h_{\text{lp}}(t) = \frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c}{\pi}t\right)$$



Filtering is Convolution

The output of an LTI system with impulse response

$$h(t) \Leftrightarrow H(\omega)$$

subject to an input signal

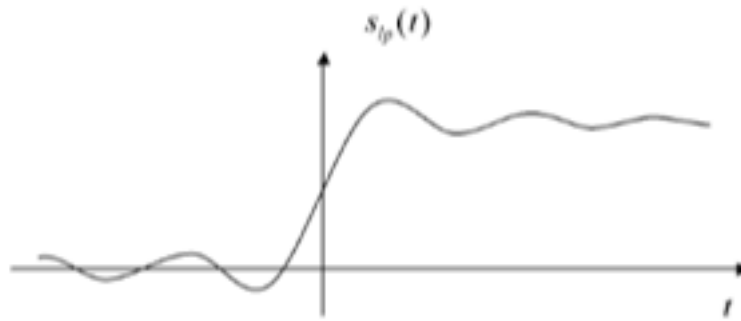
$$x(t) \Leftrightarrow X(\omega)$$

is given by

$$y(t) = h(t) * x(t) \Leftrightarrow Y(\omega) = H(\omega)X(\omega)$$

Issues with the "ideal" filter

This is the step response:



(reproduced from Boulet Fig. 5.23 p. 205)

Ripples in the impulse response would be undesirable, and because the impulse response is non-causal it cannot actually be implemented.

Butterworth low-pass filter

N-th Order Butterworth Filter

$$|H_B(\omega)| = \frac{1}{\left(1 + \left(\frac{\omega}{\omega_c}\right)^{2N}\right)^{\frac{1}{2}}}$$

Remarks

- DC gain is

$$|H_B(j0)| = 1$$

- Attenuation at the cut-off frequency is

$$|H_B(j\omega_c)| = 1/\sqrt{2}$$

for any N

More about the Butterworth filter: [Wikipedia Article](http://en.wikipedia.org/wiki/Butterworth_filter)
(http://en.wikipedia.org/wiki/Butterworth_filter)

Example 5: Second-order BW Filter

The second-order butterworth Filter is defined by its Characteristic Equation (CE):

$$p(s) = s^2 + \omega_c \sqrt{2}s + \omega_c^2 = 0^*$$

Calculate the roots of $p(s)$ (the poles of the filter transfer function) in both Cartesian and polar form.

Note: This has the same characteristic as a control system with damping ratio $\zeta = 1/\sqrt{2}$ and $\omega_n = \omega_c$!

Solution

Example 6

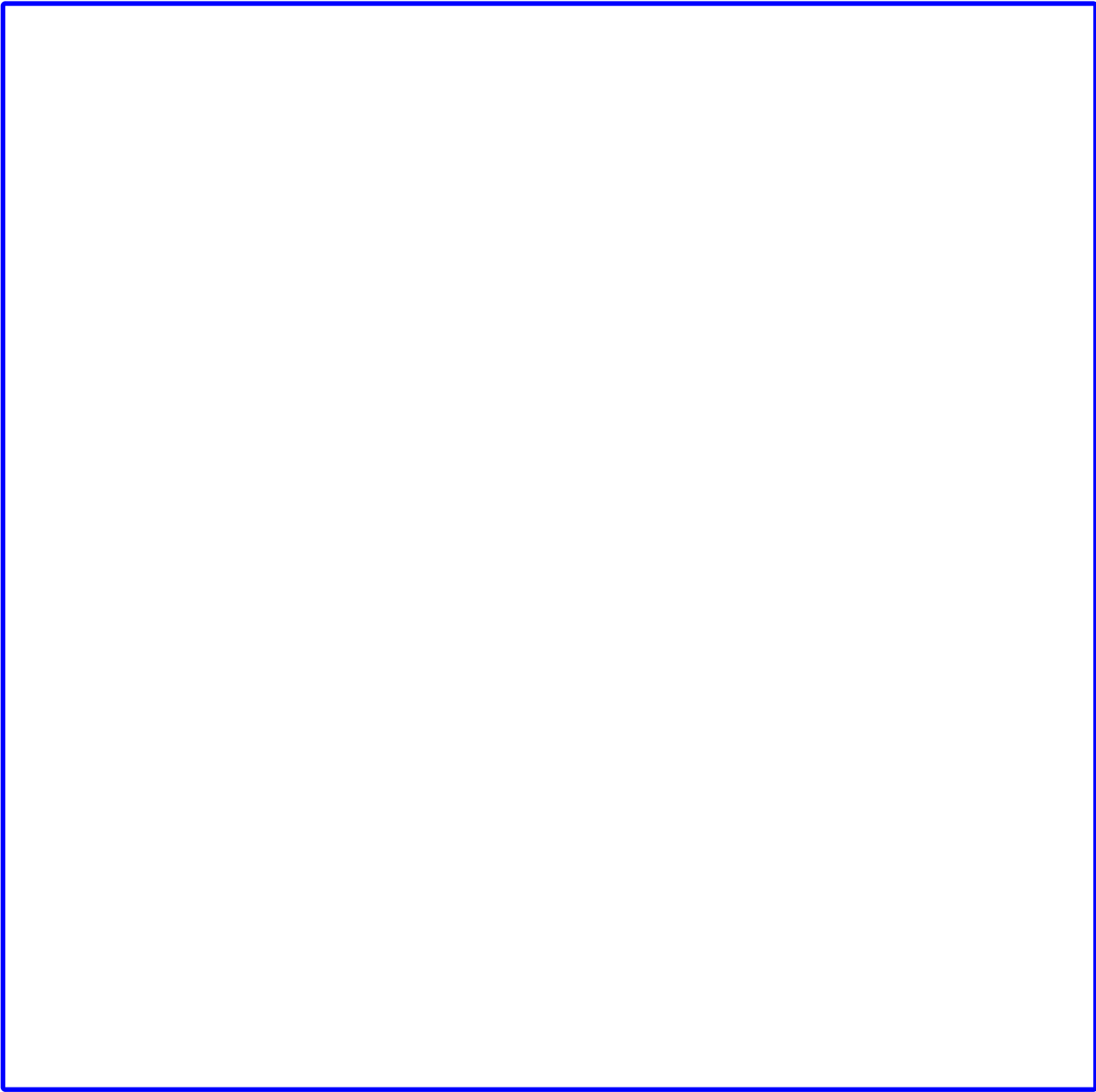
Derive the differential equation relating the input $x(t)$ to output $y(t)$ of the 2nd-Order Butterworth Low-Pass Filter with cutoff frequency ω_c .

Solution

Example 7

Determine the frequency response $H_B(\omega) = Y(\omega)/X(\omega)$

Solution



Magnitude of frequency response of a 2nd-order Butterworth Filter

In []:

```
wc = 100;
```

Transfer function

In []:

```
H = tf(wc^2,[1, wc*sqrt(2), wc^2])
```

Magnitude frequency response

In []:

```
w = -400:400;
mHlp = 1./((sqrt(1 + (w./wc).^4)));
plot(w,mHlp)
grid
ylabel('|H_B(j\omega)|')
title('Magnitude Frequency Response for 2nd-Order LP Butterworth Filter (\omega_c = 100 rad/s)')
xlabel('Radian Frequency \omega [rad/s]')
text(100,0.1,'\omega_c')
text(-100,0.1,'-\omega_c')
hold on
plot([-400,-100,-100,100,100,400],[0,0,1,1,0,0],'r:')
hold off
```

Bode plot

In []:

```
bode(H)
grid
title('Bode-plot of Butterworth 2nd-Order Butterworth Low Pass Filter')
```

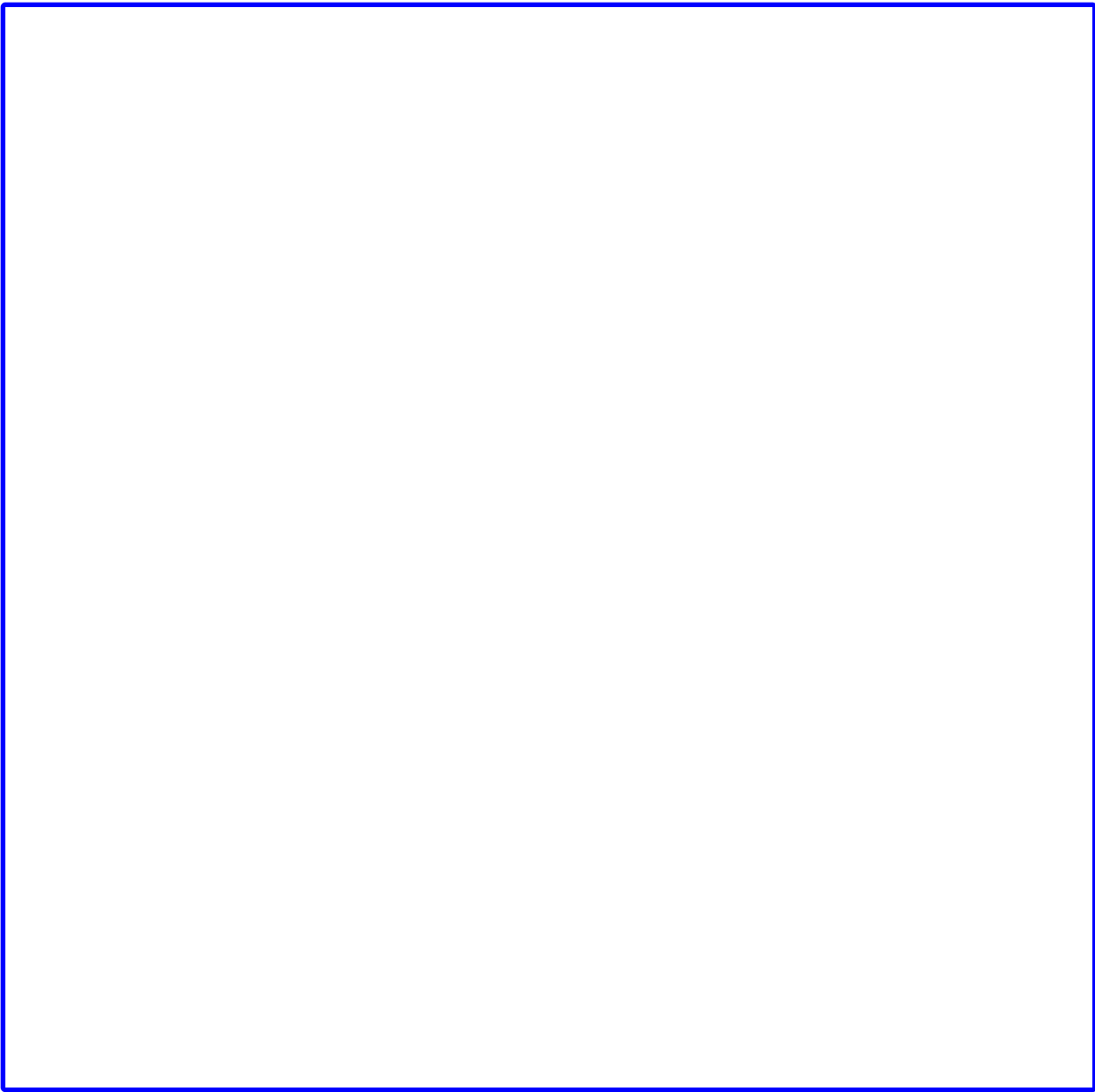
Example 8

Determine the impulse and step response of a butterworth low-pass filter.

You will find this Fourier transform pair useful:

$$e^{-at} \sin \omega_0 t u_0(t) \Leftrightarrow \frac{\omega_0}{(j\omega + a)^2 + \omega_0^2}$$

Solution



Impulse response

In []:

```
impulse(H,0.1)
grid
title('Impulse Response of 2nd-Order Butterworth Low Pass Filter')
```

Step response

In []:

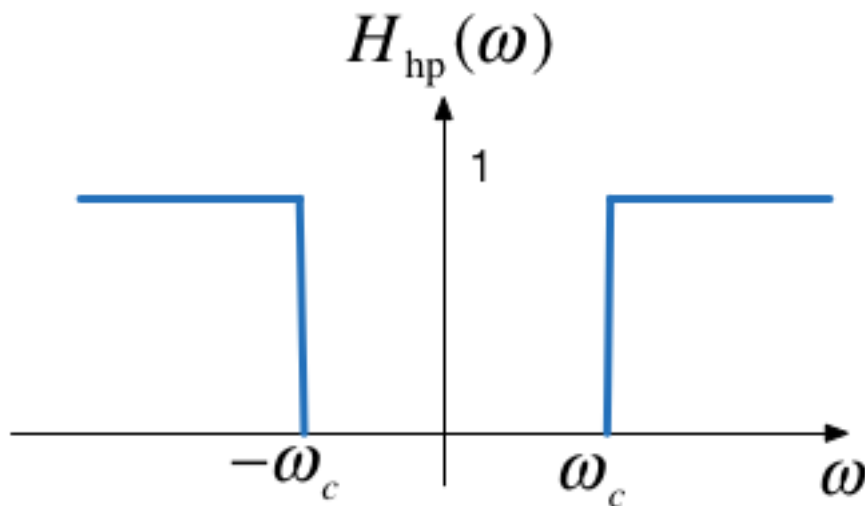
```
step(H,0.1)
title('Step Response of Butterworth 2nd-Order Butterworth Low
Pass Filter')
grid
text(0.008,1,'s_B(t) for \omega_c = 100 rad/s')
```

High-pass filter

An ideal highpass filter cuts-off frequencies lower than its *cutoff frequency*, ω_c .

$$H_{\text{hp}}(\omega) = \begin{cases} 0, & |\omega| \leq \omega_c \\ 1, & |\omega| > \omega_c \end{cases}$$

Frequency response



Responses

Frequency response

$$H_{\text{hp}}(\omega) = 1 - H_{\text{lp}}(\omega)$$

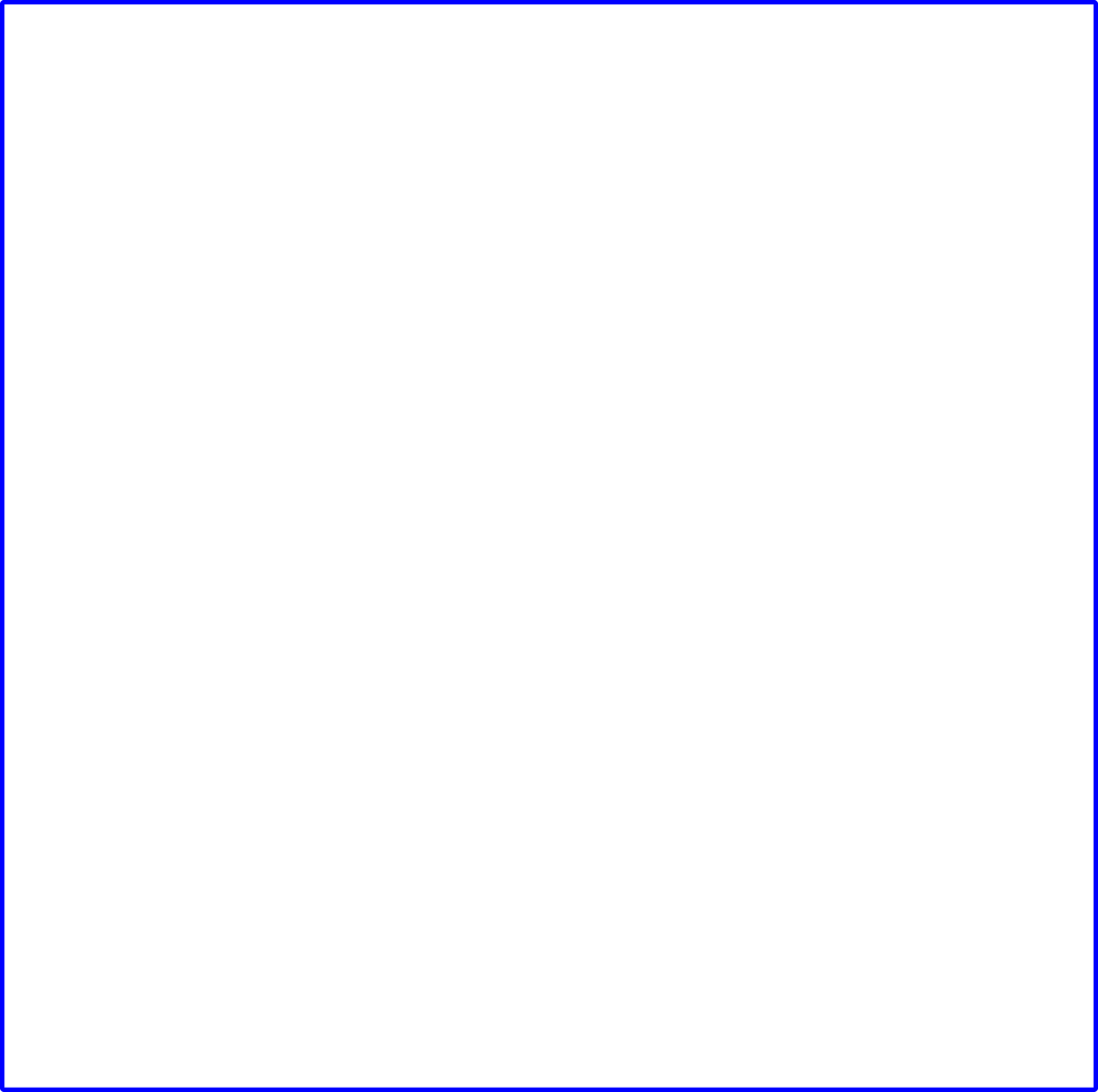
Impulse response

$$h_{\text{hp}}(t) = \delta(t) - h_{\text{lp}}(t)$$

Example 9

Determine the frequency response of a 2nd-order butterworth highpass filter

Solution



Magnitude frequency response

In []:

```
w = -400:400;
plot(w,1-mHlp)
grid
ylabel('|H_B(j\omega)|')
title('Magnitude Frequency Response for 2nd-Order HP Butterworth Filter (\omega_c = 100 rad/s)')
xlabel('Radian Frequency \omega [rad/s]')
text(100,0.9,'\omega_c')
text(-100,0.9,'-\omega_c')
hold on
plot([-400,-100,-100,100,100,400],[0,0,1,1,0,0],'r:')
hold off
```

High-pass filter

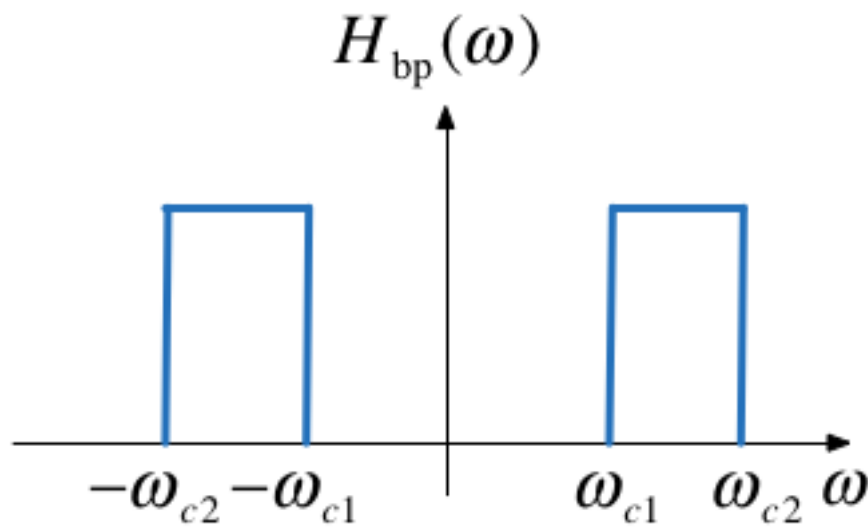
In []:

```
Hhp = 1 - H
bode(Hhp)
grid
title('Bode-plot of Butterworth 2nd-Order Butterworth High Pass Filter')
```

Band-pass filter

An ideal bandpass filter cuts-off frequencies lower than its first *cutoff frequency* ω_{c1} , and higher than its second *cutoff frequency* ω_{c2} .

$$H_{bp}(\omega) = \begin{cases} 1, & \omega_{c1} < |\omega| < \omega_{c2} \\ 0, & \text{otherwise} \end{cases}$$



Bandpass filter design

A bandpass filter can be obtained by multiplying the frequency responses of a lowpass filter by a highpass filter.

$$H_{bp}(\omega) = H_{hp}(\omega)H_{lp}(\omega)$$

- The highpass filter should have cut-off frequency of ω_{c1}
- The lowpass filter should have cut-off frequency of ω_{c2}

Solutions

Solutions to Examples 5-9 are captured as a PenCast which you will find attached to the Worked Solutions section of the [Week 7 Section \(https://swanseauniversity-my.sharepoint.com/personal/c_p_jobling_swansea_ac_uk/_layouts/OneNote.aspx?id=%2Fpersonal%2Fc_p_jobling_swansea_ac_uk%2FDocuments%2FClass%20Not%20247-EG-3068%20Signals%20and%20Systems%20%282019-2020%29&wd=target%28_Content%20Library%2FWorksheets.one%7C6DB507FF-A52A-442F-8ED4-3BCF0DC3D570%2FWorked%20Solutions%20to%20Examples%7C0827F501-1A74-104B-8FAA-7C96C30F1282%2F%29\)](https://swanseauniversity-my.sharepoint.com/personal/c_p_jobling_swansea_ac_uk/_layouts/OneNote.aspx?id=%2Fpersonal%2Fc_p_jobling_swansea_ac_uk%2FDocuments%2FClass%20Not%20247-EG-3068%20Signals%20and%20Systems%20%282019-2020%29&wd=target%28_Content%20Library%2FWorksheets.one%7C6DB507FF-A52A-442F-8ED4-3BCF0DC3D570%2FWorked%20Solutions%20to%20Examples%7C0827F501-1A74-104B-8FAA-7C96C30F1282%2F%29) of the OneNote Class Notebook