

2D transformations

Homogeneous coordinates

$$(x, y) \rightarrow (x_h, y_h, h)$$

$$P' = M_1 P + M_2$$

Harder to solve

⇓

$$P' = M_1 M_2 P$$

Multiplicative form is easier

$$x = \frac{x_h}{h}$$

$$y = \frac{y_h}{h}$$

should be non-zero

usually done

column major → right to left
row major → left to right

for translation

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} t_x \\ t_y \end{bmatrix} + \begin{bmatrix} x \\ y \end{bmatrix}$$

matrix is right to left and calculations are left to right!

$$P' = P + T \Rightarrow P' = T \cdot P$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

T

for rotation

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

For scaling

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

~~For composite transformation~~

Successive translations

Translations:

t_{x_1} and t_{x_2}

t_{y_1} and t_{y_2}

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_{x_2} \\ 0 & 1 & t_{y_2} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & t_{x_1} \\ 0 & 1 & t_{y_1} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} \quad \text{--- (I)}$$

Both
are same

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_{x_1} + t_{x_2} \\ 0 & 1 & t_{y_1} + t_{y_2} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} \quad \text{--- (II)}$$

(I) =

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_{x_1} \\ 0 & 1 & t_{y_1} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x + t_{x_1} \\ y + t_{y_1} \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} x + t_{x_1} + t_{x_2} \\ y + t_{y_1} + t_{y_2} \\ 1 \end{bmatrix}$$

So successive
translations are
additive

$$(II) = \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} x + t_{x_1} + t_{x_2} \\ y + t_{y_1} + t_{y_2} \\ 1 \end{bmatrix}$$

Successive rotations

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta_2 & -\sin \theta_2 & 0 \\ \sin \theta_2 & \cos \theta_2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos \theta_1 & -\sin \theta_1 & 0 \\ \sin \theta_1 & \cos \theta_1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta_2 & \sin \theta_2 & 0 \\ \sin \theta_2 & \cos \theta_2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \cos \theta_1 - y \sin \theta_1 \\ x \sin \theta_1 + y \cos \theta_1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta_2 (x \cos \theta_1 - y \sin \theta_1) - \sin \theta_2 (x \sin \theta_1 + y \cos \theta_1) \\ \sin \theta_2 (x \cos \theta_1 - y \sin \theta_1) + \cos \theta_2 (x \sin \theta_1 + y \cos \theta_1) \\ 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos(\theta_1 + \theta_2) & -\sin(\theta_1 + \theta_2) & 0 \\ \sin(\theta_1 + \theta_2) & \cos(\theta_1 + \theta_2) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\Rightarrow \boxed{P' = R(\theta_2) \cdot R(\theta_1) \cdot P}$$

$$\boxed{P' = R(\theta_1 + \theta_2) \cdot P}$$

Successive scaling

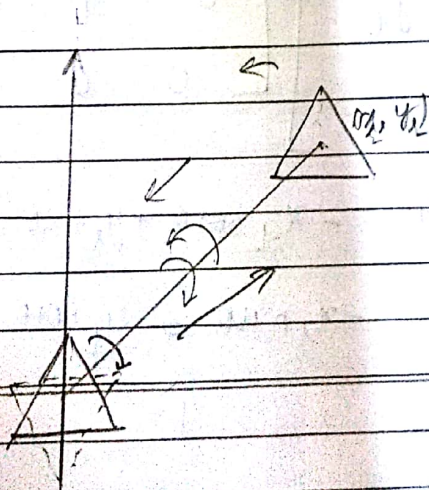
$$\begin{aligned}
 \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} &= \begin{bmatrix} s_{x_2} & 0 & 0 \\ 0 & s_{y_2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} s_{x_1} & 0 & 0 \\ 0 & s_{y_1} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} \\
 &= \begin{bmatrix} s_{x_2} & 0 & 0 \\ 0 & s_{y_2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x s_{x_1} + 0 + 0 \\ 0 + y s_{y_1} + 0 \\ 1 \end{bmatrix} \\
 &= \begin{bmatrix} x s_{x_1} s_{x_2} \\ y s_{y_1} s_{y_2} \\ 1 \end{bmatrix}
 \end{aligned}$$

$$\Rightarrow \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} s_{x_1} s_{x_2} & 0 & 0 \\ 0 & s_{y_1} s_{y_2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\boxed{P' = S_1 \cdot S_2 \cdot P}$$

Composite Scaling is multiplicative.
(successive)

Composite transformation



Step 1: Translate to the origin

Step 2: Rotate

Step 3: Reverse translate to original position

$$\text{Step 1: } T = \begin{bmatrix} 1 & 0 & -x_2 \\ 0 & 1 & -y_2 \\ 0 & 0 & 1 \end{bmatrix}$$

Step 2:

$$R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Step 3:

$$T^{-1} = \begin{bmatrix} 1 & 0 & x_2 \\ 0 & 1 & y_2 \\ 0 & 0 & 1 \end{bmatrix}$$

\therefore finally, $P' = T^{-1} \cdot R(\theta) \cdot T \cdot P$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & x_2 \\ 0 & 1 & y_2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -x_2 \\ 0 & 1 & -y_2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$T^{-1} \cdot R(\theta) \cdot T$$

$$= \begin{bmatrix} 1 & 0 & x_2 \\ 0 & 1 & y_2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -x_2 \\ 0 & 1 & -y_2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta & -\sin \theta & x_2 \\ \sin \theta & \cos \theta & y_2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -x_2 \\ 0 & 1 & -y_2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta & -\sin \theta & -x_2 \cos \theta + y_2 \sin \theta + x_2 \\ \sin \theta & \cos \theta & -x_2 \sin \theta - y_2 \cos \theta + y_2 \\ 0 & 0 & 1 \end{bmatrix}$$

Then,

$$T' = R(\theta) \cdot T \cdot P$$

$$= \begin{bmatrix} \cos \theta & \sin \theta & y_2 \sin \theta + x_2 (1 - \cos \theta) \\ -\sin \theta & \cos \theta & x_2 (1 - \cos \theta) + y_2 \sin \theta \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} x \cos \theta + y \sin \theta + y_2 \sin \theta + x_2 (1 - \cos \theta) \\ -x \sin \theta + y \cos \theta + x_2 (1 - \cos \theta) + y_2 \sin \theta \\ 1 \end{bmatrix}$$

$$x' = (\cos \theta)(x - x_2) + (\sin \theta)(y - y_2) + x_2$$

$$y' = (\sin \theta)(x - x_2) + (\cos \theta)(y - y_2) + y_2$$