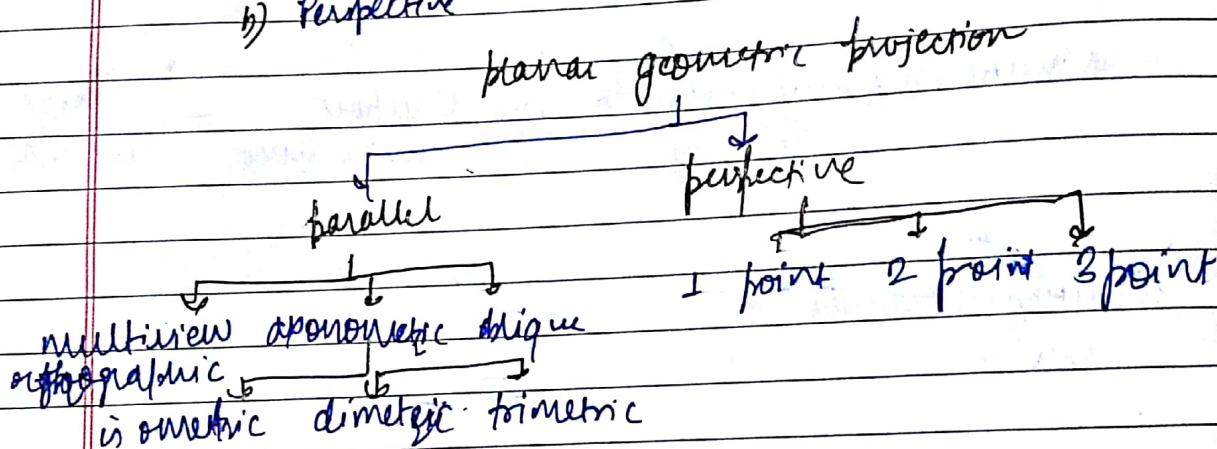


Projection -

The world coordinate description of an object in a scene is converted to viewing coordinate.
The 3D view is projected on a 2D view plane.

Types of projection -

- a) Parallel projection
- b) Perspective



Parallel projection

Coordinate posⁿ are transformed to the view plane along parallel lines.

Relative positions are maintained

Perspective projection

Object positions are transformed to the view plane along lines that converge to a point called projection reference point.

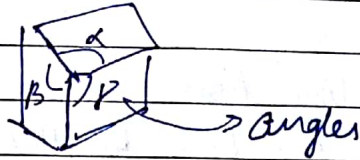
Orthographic projection

- Elevation - Front side, rear side orthographic image
- Plan view : top orthographic projection of an object.

#

Axonometric orthographic projection

- Can display more than one face at a time.
- Isometric projection: by aligning projection plane such that it intersects each co-ordinate axis in which -



- Isometric - All angles are equal
- Dimetric - Two angles are equal
- Trimetric - None of the angles are equal.

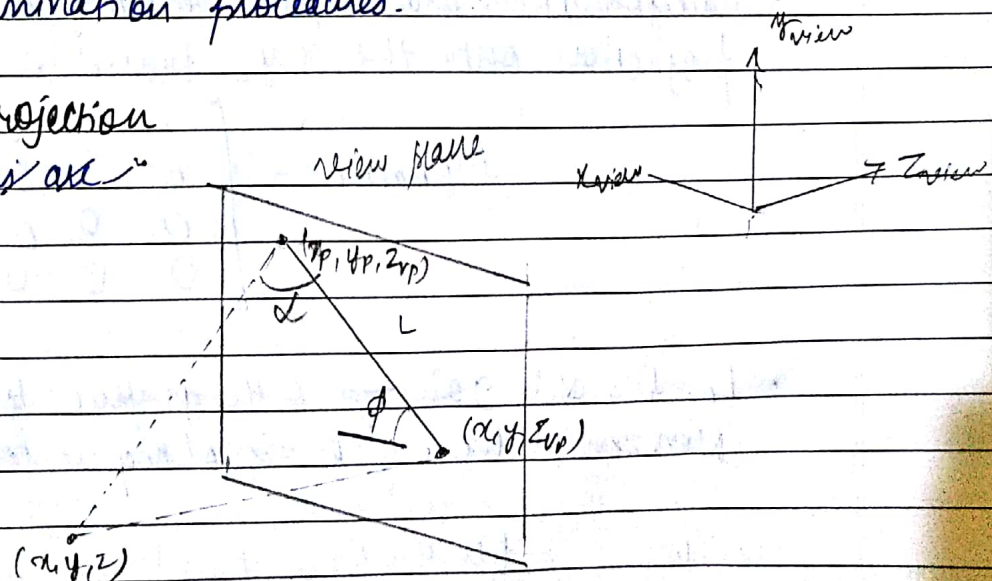
#

Transformation equation of orthographic parallel projection.

- View plane is placed at position Z_{vp} along the the Z axis.
- Any point (x, y, z) in viewing coordinate is transformed to projection co-ordinate as $x_p = x$; $y_p = y$.
- Original z coordinate value is preserved for depth information needed in depth culling and visible surface determination procedures.

Oblique projection

Projections are -



Transformation equation of oblique parallel projection

• Oblique projection vector is specified by two angles: α and θ .

• Point (x, y, z) is projected at a position (x_p, y_p) on view plane.

• Orthographic projection coordinates on the plane are (x, y) .

• The oblique projection line from (x, y, z) to (x_p, y_p) make an angle with the line on the projection plane that joins (x_p, y_p) and (x, y) .

• The line of length L , is at angle ϕ with the horizontal direction on the projection plane.

• Projection ~~and~~ coordinates are defined in terms of x, y, L, ϕ as

$$-x_p = x + L \cos \phi \quad \text{and} \quad y_p = y + L \sin \phi$$

$$-\tan \alpha = z/L \quad ; \quad L = z / \tan \alpha \quad ; \quad \cancel{L = z \tan \alpha} \quad L = z \tan \alpha$$

$$L = \frac{1}{\tan \alpha} \quad \text{if } z=1, \quad L=L$$

$$-x_p = x + z(L \cos \phi) \quad \text{and} \quad y_p = y + z(L \sin \phi)$$

• Transformation matrix for producing any parallel projection onto the x, y plane is

$$M_{\text{parallel}} = \begin{bmatrix} 1 & 0 & L \cos \phi & 0 \\ 0 & 1 & L \sin \phi & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

• $L=1, \alpha=90^\circ \rightarrow$ orthographic projection
Non zero value of $L \Rightarrow$ oblique projection

Cavalier $\tan \alpha = 1 \quad L = 1$
Cabinet $\tan \alpha = 2 \quad L = 1/2$

