

# Package ‘multimolang’

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**Type** Package

**Title** Multimodal Language Analysis Tools

**Version** 0.1.0

**Description** Tools for analyzing multimodal language data. Includes dfMaker for processing OpenPose outputs.

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**Encoding** UTF-8

**Depends** R (>= 4.1.0)

**Imports** arrow,

**Suggests** roxygen2 (>= 7.0.0), testthat (>= 3.0.0), knitr, rmarkdown

**URL** <https://github.com/daedalusLAB/multimolang.git>

**BugReports** <https://github.com/daedalusLAB/multimolang/issues>

**Roxygen** list(markdown = TRUE)

**RoxygenNote** 7.3.2

**VignetteBuilder** knitr

**Keywords** multimodal, language, OpenPose, analysis

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dfMaker

*dfMaker Function***Description**

dfMaker processes and organizes keypoints data generated by OpenPose, compiling multiple JSON files into a structured data frame. While the function can be used to load data into R for analysis, its primary purpose is integration into data processing pipelines for large-scale applications.

The function supports datasets with pose\_keypoints alone or datasets containing pose\_keypoints along with face (--face) and hands (--hand) keypoints. It does not support partial datasets where only face or hand keypoints are provided, or where pose\_keypoints are combined with only face or only hands keypoints.

The JSON files may indicate an older data schema version (e.g., 1.3), which refers to the output format and not the actual OpenPose software version. This function has been tested with OpenPose version 1.7.0 and supports its output structure.

**Usage**

```
dfMaker(
  input.folder,
  config.path,
  output.file = NULL,
  output.path = NULL,
  no_save = FALSE,
  fast_scaling = TRUE,
  transformation_coords = c(1, 1, 5, 5)
)
```

**Arguments**

input.folder	Path to the folder containing OpenPose JSON files. The folder should contain only the JSON files to be processed; including other files may lead to unexpected behavior.
config.path	Path to the configuration file used for extracting metadata from filenames when processing data from the UCLA NewsScape archive. This configuration file specifies which metadata fields to extract based on the standard NewsScape file-name format. If not provided, default settings are used, which may not extract NewsScape-specific metadata.
output.file	Name of the output file. If NULL and there is only one unique id in the data, an auto-generated name with a .parquet extension is used. If there are multiple unique id values and output.file is NULL, the function will return an error; you must provide an explicit output file name. If the specified output.file ends with .csv, the output will be saved in CSV format. Otherwise, the default format is .parquet.
output.path	Path to save the output file. If NULL, the file is saved in a default directory called df_outputs in the current working directory.

<code>no_save</code>	Logical. If TRUE, the output is not saved to a file.
<code>fast_scaling</code>	Logical. If TRUE, uses fast scaling for transformation. <b>Warning:</b> When <code>fast_scaling</code> is TRUE, scaling is performed only using pose keypoints ( <code>t_typepoint = 1</code> ), and the secondary vector <code>v.j</code> is not utilized.
<code>transformation_coords</code>	<p>Numeric vector of length 4 that specifies the transformation coordinates. Each element of the vector has a specific role:</p> <ol style="list-style-type: none"> <li>1. <code>t_typepoint</code>: Type of keypoints to use. Possible values: <ol style="list-style-type: none"> <li>(a) 1: Body keypoints (pose).</li> <li>(b) 2: Face keypoints.</li> <li>(c) 3: Left hand keypoints.</li> <li>(d) 4: Right hand keypoints.</li> </ol> </li> <li>2. <code>o_point</code>: Index of the keypoint used as the <b>origin</b> in the new coordinate system.</li> <li>3. <code>i_point</code>: Index of the keypoint that defines the primary base vector <code>v.i</code>.</li> <li>4. <code>j_point</code>: Index of the keypoint that defines the secondary base vector <code>v.j</code>. <ul style="list-style-type: none"> <li>• If <code>i_point == j_point</code>, <code>v.j</code> is calculated as a <b>perpendicular</b> vector to <code>v.i</code> (orthonormalization).</li> <li>• If <code>fast_scaling = TRUE</code>, <code>v.j</code> is not utilized and should be set to NA.</li> </ul> </li> </ol>

## Details

This function depends on the **arrow** package for reading and writing JSON and Parquet files. Please ensure that the **arrow** package is installed.

When processing data with multiple unique `id` values, ensure that you provide an explicit `output.file` name to avoid errors.

The function expects JSON files generated by OpenPose with a specific structure. Variations in the OpenPose configuration or version may affect the format of these files. Ensure that the JSON files conform to the expected structure for accurate processing.

Each row in the produced data frame represents a single keypoint detected in a specific frame and associated with a specific person. The columns **nx** and **ny** provide the transformed coordinates based on the selected origin and linear transformation parameters. The **id** column links the keypoints to the corresponding input file from which they were extracted.

The data frame may contain missing values (NA) for keypoints that could not be reliably detected.

## Value

A data frame containing the processed keypoints data with the following structure:

**id** Character. Identifier derived from the name of the file processed.

**frame** Numeric. Frame number from which the data is extracted.

**people\_id** Integer. Identifier for each detected person in the frame.

**type\_points** Character. Type of keypoints (e.g., "pose\_keypoints", "face\_keypoints", "hand\_left\_keypoints", "hand\_right\_keypoints").

**points** Integer. Index of the keypoints sequence.

- x** Numeric. X-coordinate of the keypoint.
- y** Numeric. Y-coordinate of the keypoint.
- c** Numeric. Confidence score for the detected keypoint, ranging from 0 to 1.
- nx** Numeric. Transformed X-coordinate in the new coordinate system.
- ny** Numeric. Transformed Y-coordinate in the new coordinate system.

Example of the returned data frame:

```
'data.frame': 8220 obs. of 10 variables:
 $ id      : chr  "2006-01-14_0600_US_KTTV-FOX_Ten_OClock_News_273-275_back_then" ...
 $ frame   : num  0 0 0 0 0 0 0 0 0 ...
 $ people_id : int  1 1 1 1 1 1 1 1 1 ...
 $ type_points: chr  "pose_keypoints" "pose_keypoints" "pose_keypoints" "pose_keypoints" ...
 $ points   : int  0 1 2 3 4 5 6 7 8 9 ...
 $ x       : num  223 209 131 113 NA ...
 $ y       : num  113 178 178 273 NA ...
 $ c       : num  0.892 0.7 0.522 0.273 0 ...
 $ nx      : num  0.165 0 -0.945 -1.165 NA ...
 $ ny      : num  0.791 0 -0.000446 -1.14343 NA ...
```

## R Version Requirements

This function uses the native pipe operator `|>` introduced in R version 4.1.0. Therefore, R version 4.1.0 or higher is required to use this function.

## Error Handling

If the JSON files do not have the expected format or are empty, the function will skip these files and print a message indicating the issue. If `output.file` is NULL and multiple unique `id` values are found, the function will stop and return an error, prompting you to provide an explicit `output.file` name.

#' @note The `dfMaker` function processes all keypoints provided by OpenPose, including pose, face, and hand keypoints. For the specific indices and descriptions of these keypoints, please refer to the OpenPose documentation.

## Note on NewsScape Data

The **UCLA NewsScape** archive is the largest TV news video archive globally, containing over 300,000 news programs from the United States and around the world, dating from 1979 to the present. The collection provides streaming of news content and includes time-stamped closed-caption texts of most broadcasts, along with various metadata generated by machine learning and computer vision classifiers. This offers advanced search functions and enables new possibilities for teaching, research, and scholarship.

When processing data from NewsScape, the `config.path` parameter allows you to specify a configuration file that defines how to extract metadata from the filenames of the videos. The filenames in this archive have specific structures containing metadata such as date, time, country code, network code, program name, and time range.

**Example of Configuration File** (`config.json`):

```
{
  "extract_datetime": true,
  "extract_time": true,
  "extract_exp_search": true,
  "extract_country_code": true,
  "extract_network_code": true,
  "extract_program_name": true,
  "extract_time_range": true,
  "timezone": "America/Los_Angeles"
}
```

This configuration allows you to control which metadata fields are extracted from the filenames. The `search_exp` variable is used in linguistic studies to analyze specific expressions within the content.

**Important:** Ensure that your data filenames follow the standard NewsScape naming convention for accurate metadata extraction. If your data does not conform to this naming convention, you may need to adjust your filenames or modify the configuration accordingly.

#### Example of a NewsScape Filename and Its Components:

2006-01-14\_0600\_US\_KTTV-FOX\_Ten\_OClock\_News\_273-275\_back\_then\_000000000000\_keypoints.json

#### Breakdown of Filename Components:

2006-01-14 Extracted by `extract_datetime`: The date of the broadcast (YYYY-MM-DD).

0600 Extracted by `extract_time`: The time of the broadcast in 24-hour format (HHMM).

US Extracted by `extract_country_code`: The country code where the broadcast originated.

KTTV-FOX\_Ten\_OClock\_News\_273-275\_back\_then Extracted by `extract_network_code`, `extract_program_name`, and `extract_exp_search`:

KTTV-FOX The network code and station identifier.

Ten\_OClock\_News The program name.

273-275 The time range or segment identifier within the program.

back\_then Extracted by `extract_exp_search`: A specific expression or keyword used in linguistic studies.

**Note on Timezone:** The `timezone` parameter in the configuration file is used to standardize the broadcast times and is not treated as a variable within the data extraction process.

Example of how `timezone` is applied in R:

```
datetime <- as.POSIXct(datetime_str, format = "%Y-%m-%d %H%M", tz = timezone)
```

## References

For more information about the UCLA NewsScape archive, visit the official website: <https://bigdatasocialscience.ucla.edu/newsscape/>

The **arrow** R package is used for efficient reading and writing of JSON and Parquet files. For more information, visit: <https://cran.r-project.org/package=arrow>

OpenPose GitHub Repository: <https://github.com/CMU-Perceptual-Computing-Lab/openpose>

OpenPose Academic Article: Cao, Z., Hidalgo, G., Simon, T., Wei, S.-E., & Sheikh, Y. (2019). OpenPose: Realtime Multi-Person 2D Pose Estimation Using Part Affinity Fields. *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 43(1), 172–186. <https://doi.org/10.1109/TPAMI.2019.2929257>

Alternatively, explore the OpenPose GitHub repository for implementation details: <https://github.com/CMU-Perceptual-Computing-Lab/openpose>

## Examples

```
# Example 1: Define paths to example data included with the package
input.folder <- system.file("extdata/ex_videos/o1",
                             package = "multimolang")
output.file <- file.path(tempdir(), "processed_data.csv")
output.path <- tempdir() # Use a temporary directory for writing output

# Run dfMaker with example data
df <- dfMaker(
  input.folder = input.folder,
  output.file = output.file,
  output.path = output.path,
  no_save = FALSE,
  fast_scaling = TRUE,
  transformation_coords = c(1, 1, 5, 5)
)

# View the first few rows of the resulting data frame
head(df)

# Example 2: Using NewsScape data with a custom configuration file

# Define paths to example data
input.folder <- system.file("extdata/ex_videos/o1",
                             package = "multimolang")

# Define the configuration file path
config.path <- system.file("extdata/config_all_true.json",
                             package = "multimolang")

# Define output paths
output.file <- file.path(tempdir(), "processed_data.csv")
output.path <- tempdir()

# Run dfMaker with custom configuration
df <- dfMaker(
  input.folder = input.folder,
  config.path = config.path,
  output.file = output.file,
  output.path = output.path,
  no_save = FALSE,
  fast_scaling = TRUE,
  transformation_coords = c(1, 1, 5, 5)
```

```
)  
  
# View the first few rows  
head(df)
```

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