

Noise-Resilient Performance Modeling of HPC Applications



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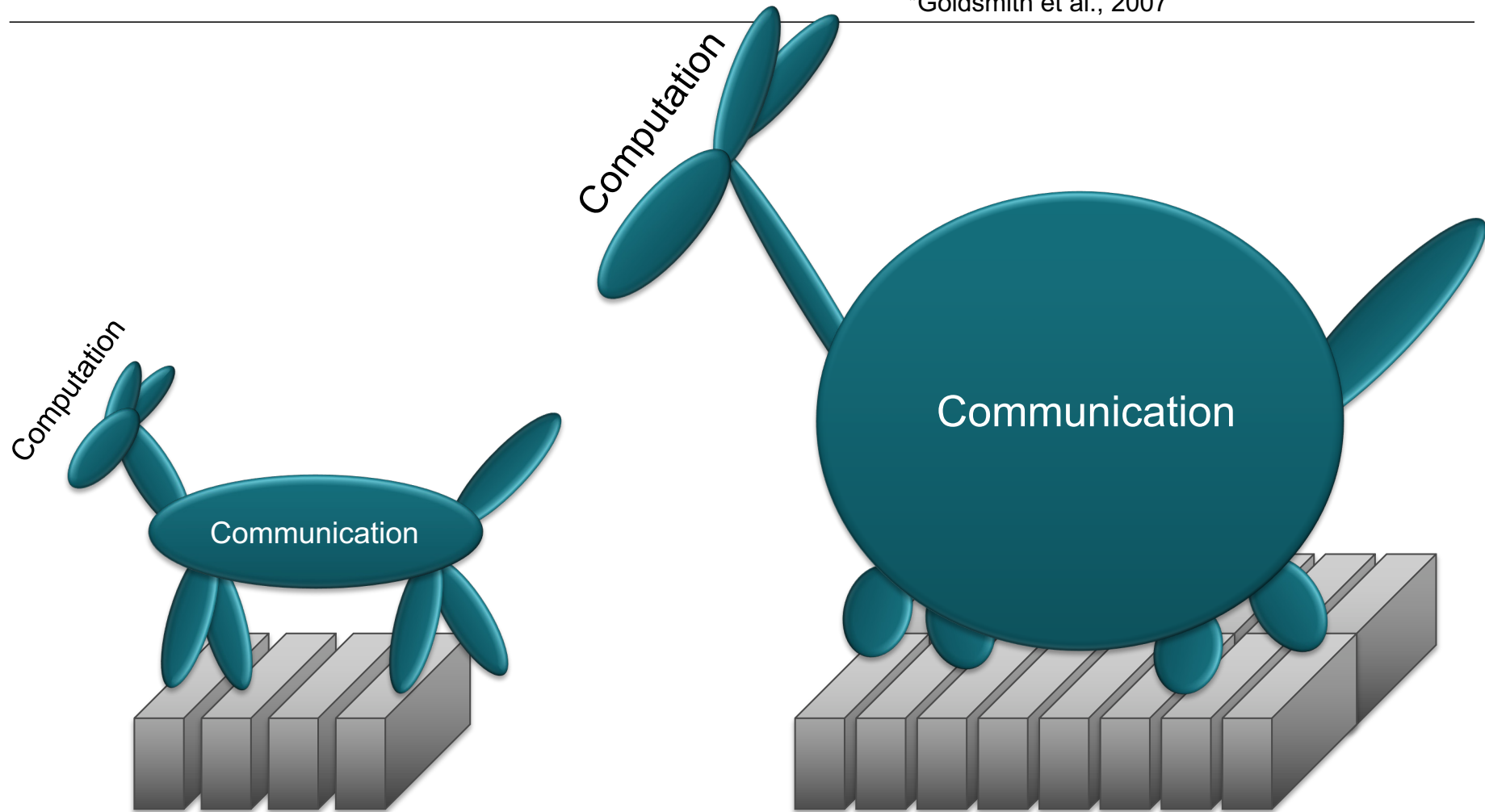


Scaling your code can harbor *performance surprises*...



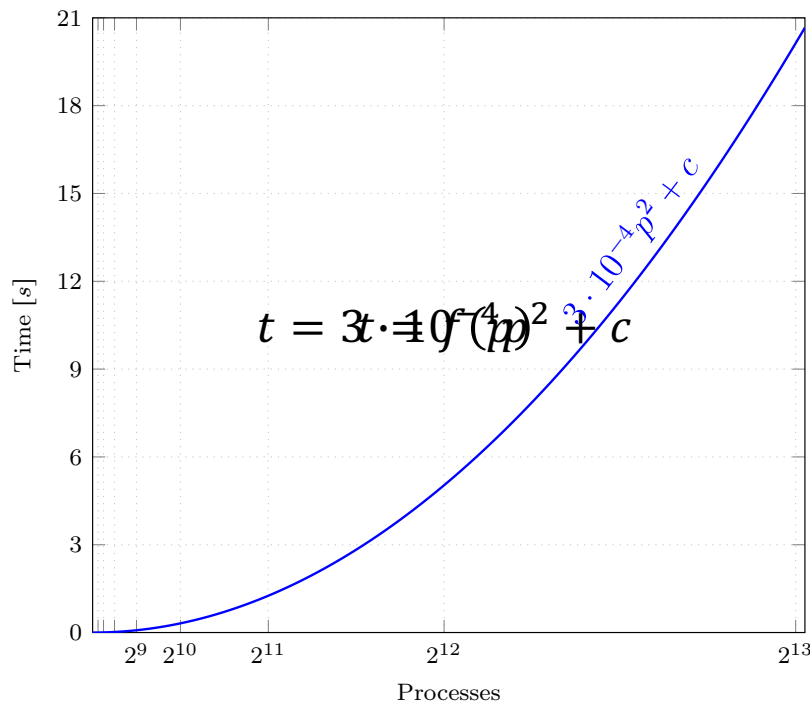
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*Goldsmith et al., 2007



Performance model

Formula that expresses a relevant performance metric as a function of one or more execution parameters



Analytical (i.e., manual) creation
challenging for entire programs

Identify
kernels

- Incomplete coverage

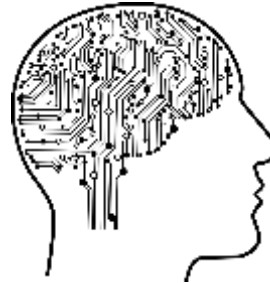
Create
models

- Laborious, difficult

Empirical performance modeling



Performance measurements
with different execution
parameters $\mathbf{x}_1, \dots, \mathbf{x}_n$



Machine
learning

$$t = f(x_1, \dots, x_n)$$

Alternative metrics:
FLOPs, data volume...

Challenges

Applications



Run-to-run variation / noise



System



Cost of the required experiments

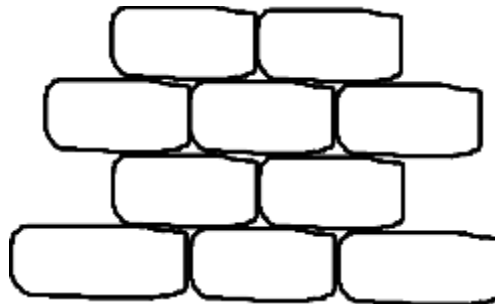
How to deal with noisy data

- Introduce **prior** into learning process
 - Assumption about the probability distribution generating the data




Time

~



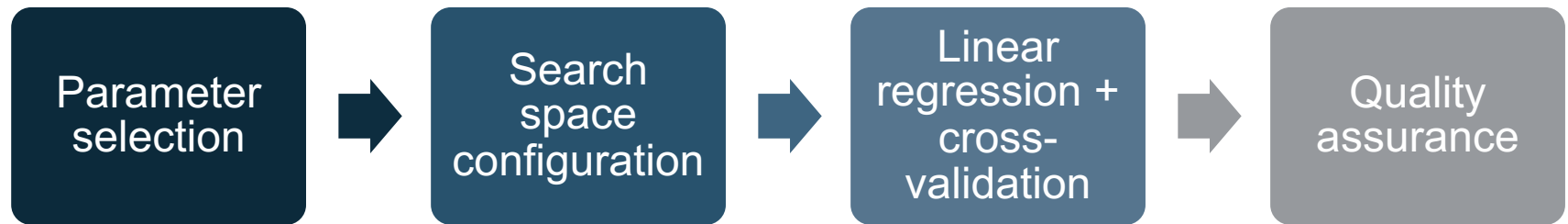
Effort

- 
- Computation
 - Memory access
 - Communication
 - I/O

Performance model normal form (PMNF)

$$f(x) = \sum_{k=1}^n c_k \cdot p^{i_k} \cdot \log_2^{j_k}(x)$$

Single parameter
[Calotoiu et al., SC13]

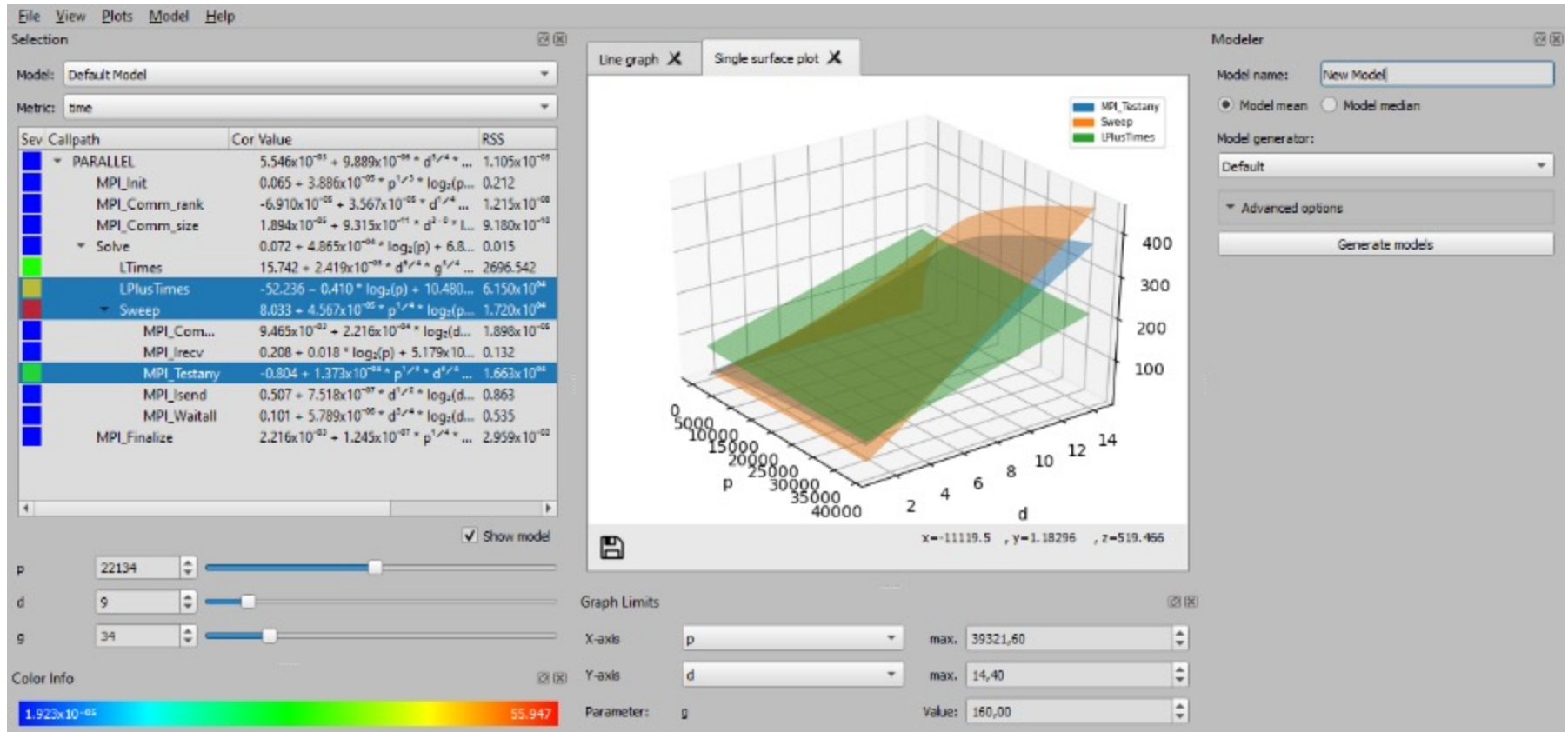


$$f(x_1, \dots, x_m) = \sum_{k=1}^n c_k \prod_{l=1}^m x_l^{i_{kl}} \cdot \log_2^{j_{kl}}(x_l)$$

Multiple parameters [Calotoiu et al., Cluster'16]

Heuristics to
reduce
search space

Extra-P 4.0

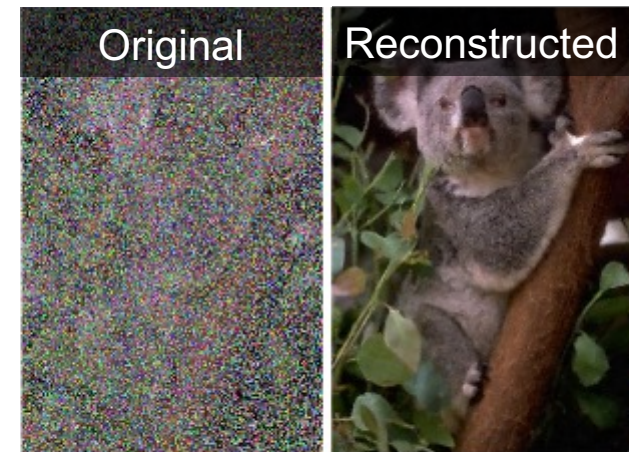
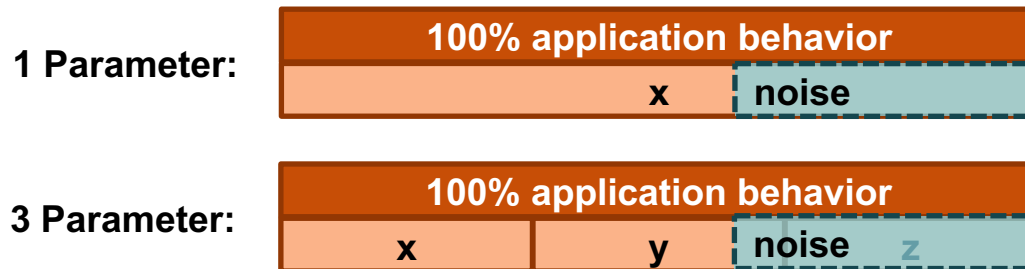


Available at: <https://github.com/extra-p/extrap>

Noise-resilient performance modeling

[Ritter et al., IPDPS'21]

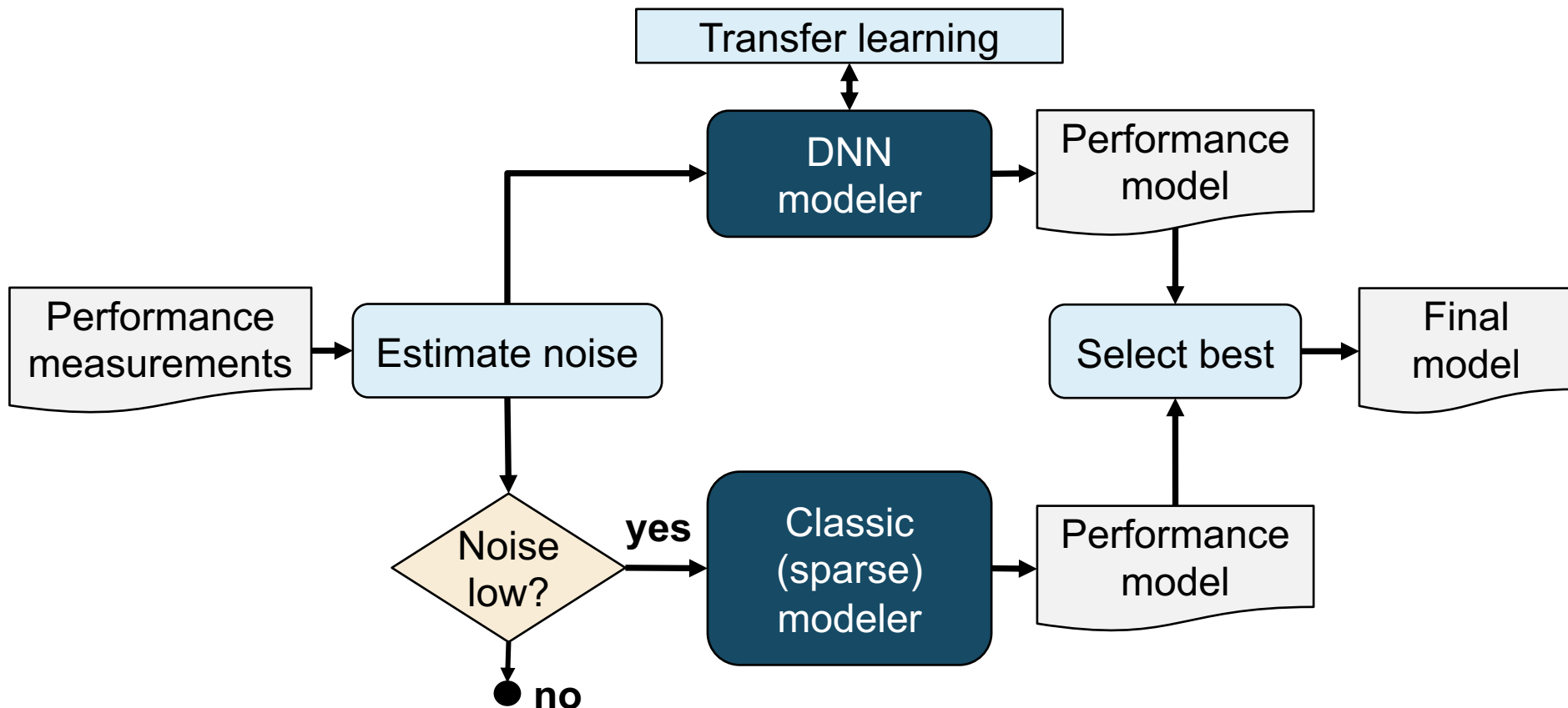
- Performance measurements frequently affected by noise
- Regression struggles with increased amounts of noise – especially w/ more parameters
- Neural networks are resilient to noise – **when noise is part of their training**



Adapted from: <https://developer.nvidia.com/blog/ai-can-now-fix-your-grainy-photos-by-only-looking-at-grainy-photos/>

Noise-resilient adaptive modeling

DNNs often better at guessing models in the presence of noise



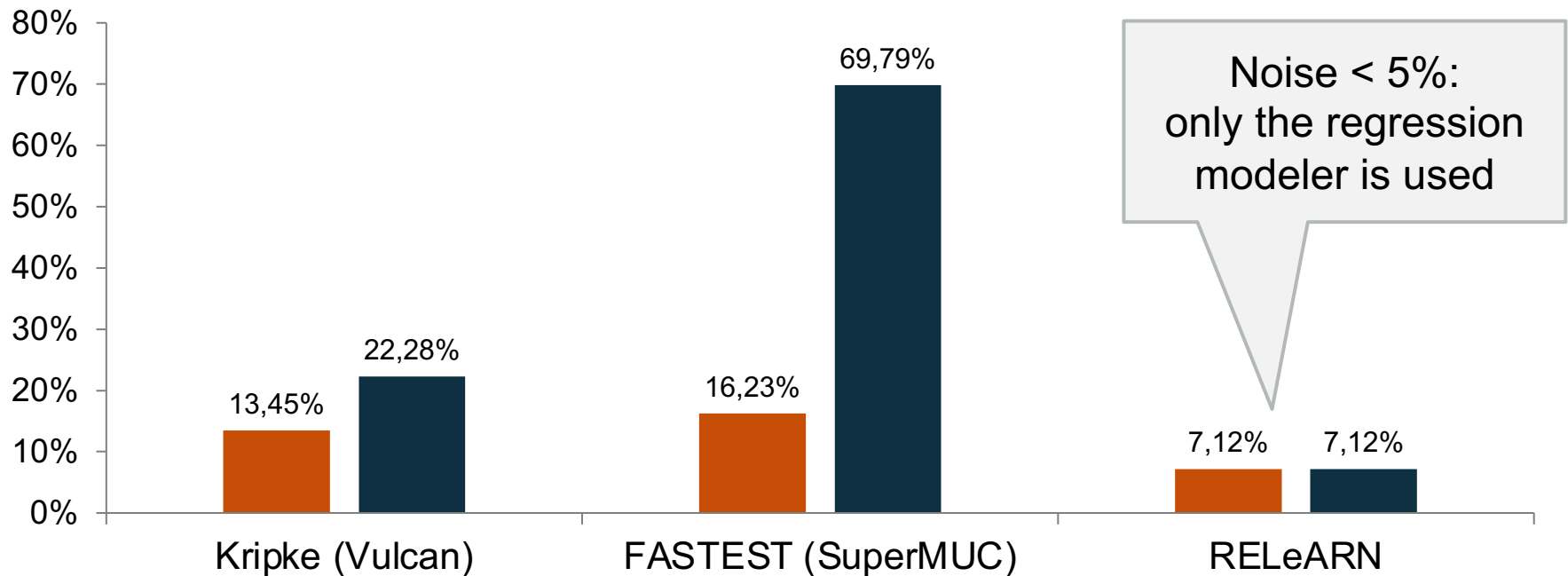
Noise-resilient performance modeling

Case studies – Results

Median relative error

(at unseen point, one tick in each dimension)

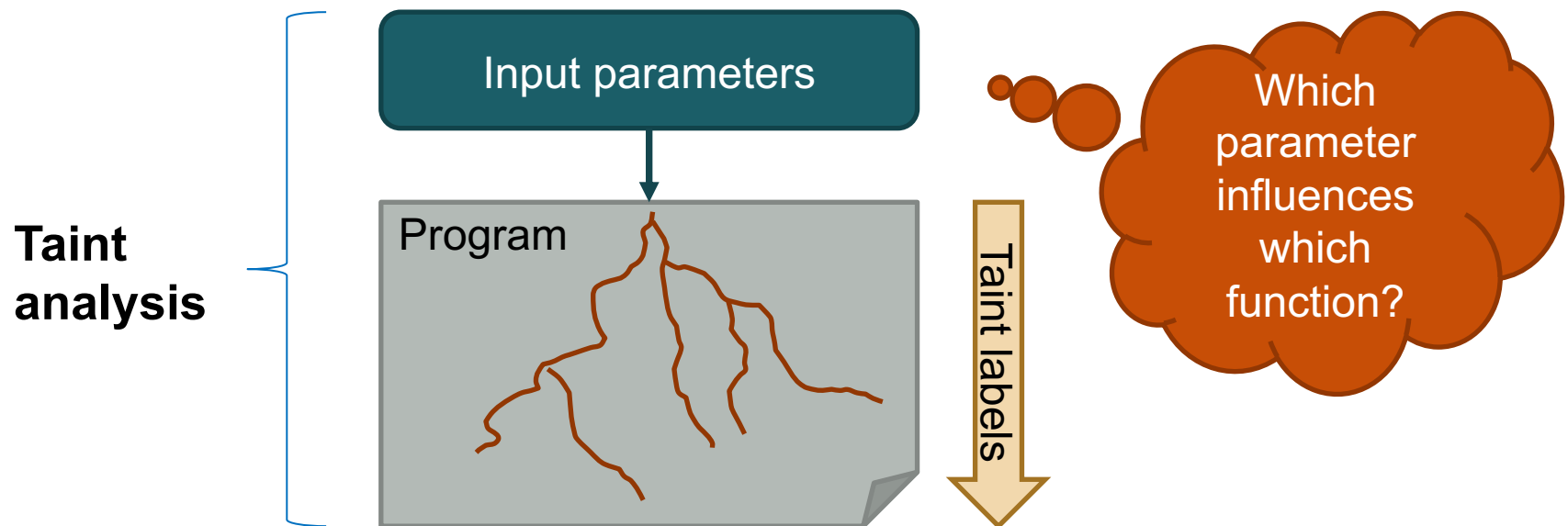
■ Adaptive ■ Regression



Parameter selection

[Copik et al, PPoPP'21]

- The more parameters the more experiments
- Modeling parameters without performance impact is harmful

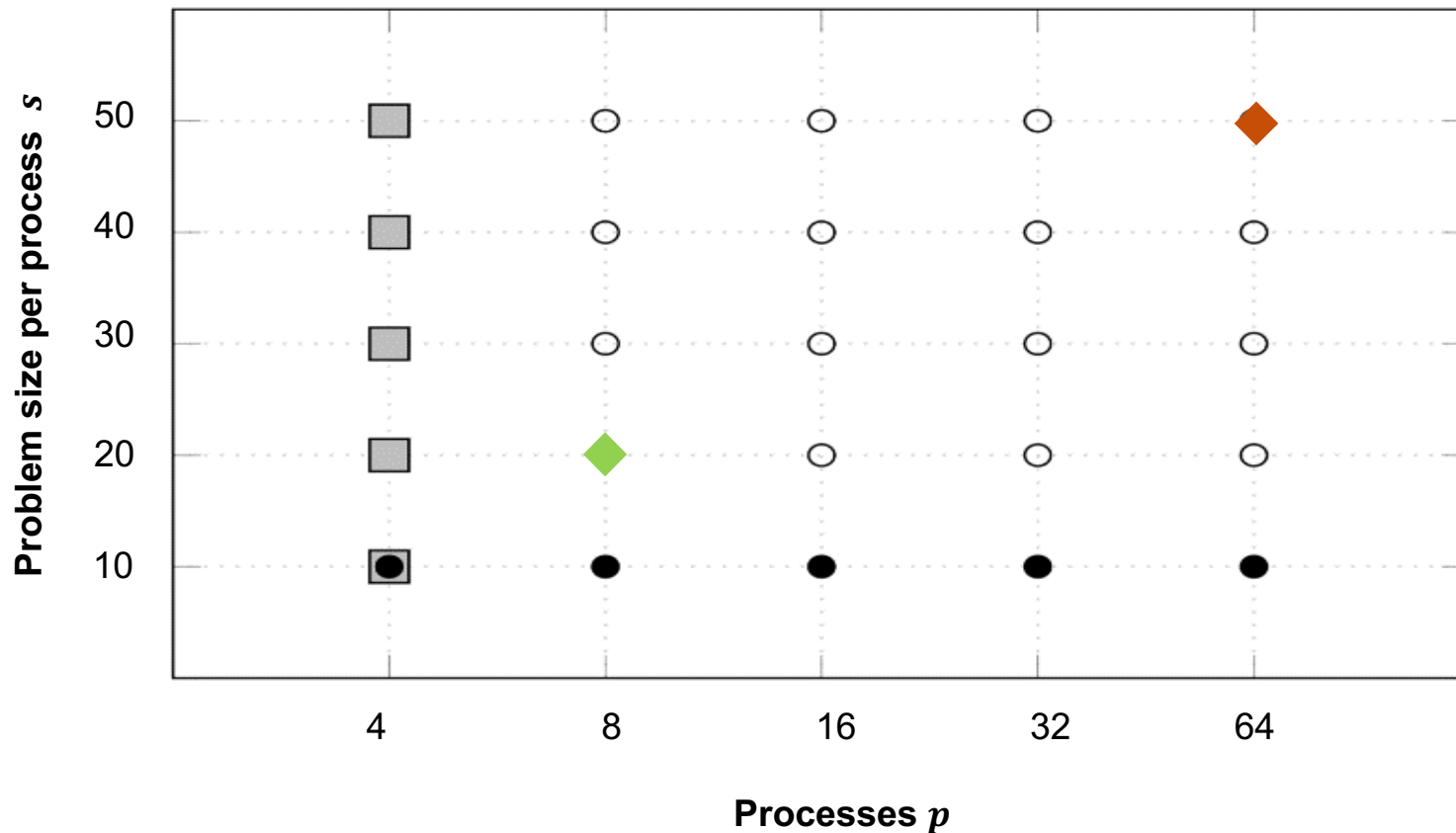


Case study – LULESH & MILC

Influence of program parameters

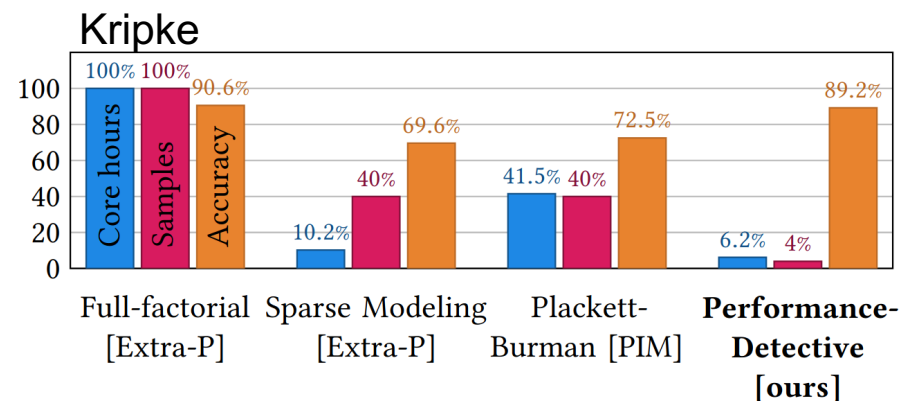
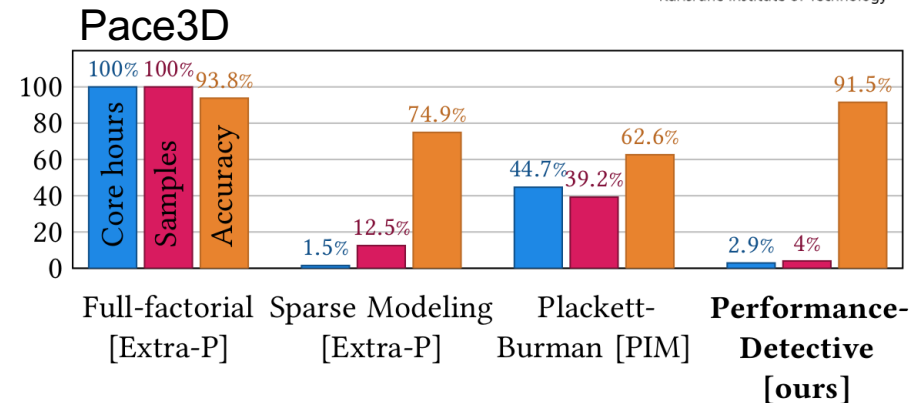
LULESH	Total	p	size	regions	iters	balance	cost		p, size
Functions	349	2	40	15	1	1	2		40
Loops	275	2	78	29	1	1	2		78
MILC	Total	p	size	trajecs	warms steps	nrest. niter	mass, beta nfl.	u0	p, size
Functions	621	54	53	12	9	6	1	4	56
Loops	874	187	161	39	31	15	1	7	196

How many data points do we really need?



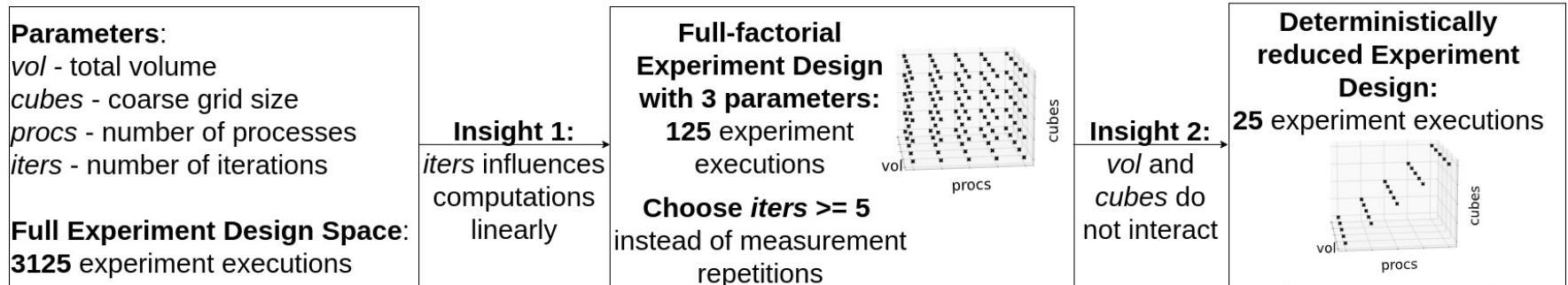
Performance Detective – Automatic deduction of cheap and accurate performance models [Schmidt et al, ICS 2022]

- **Problem** – Current heuristic sampling strategy too expensive
- **Contribution** – Use PerfTaint to deduce minimum set of experiments
- Case studies show same model accuracy at reduced cost



Performance Detective (2)

- Parameters that influence computation linearly
 - Instead of repeating measurements, set parameter influencing the computation linearly to ≥ 5
- Strike out configurations aimed at finding interactions between parameters that do not interact



Refine prior based on noise-resilient metrics

[de Moraes et al., work in progress]



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Single parameter

$$f_{\text{bb}}(x) = \sum_{k=1}^{n_1} c_k \cdot p^{i_k} \cdot \log_2^{j_k}(x)$$

(basic block based model)



Search space to (i, j)



$$f(x) = \sum_{k=1}^{n_2} c_k \cdot p^{i_k} \cdot \log_2^{j_k}(x)$$

(time based model)

Multiple parameters

$$f_{\text{bb}}(x_1, \dots, x_m) = \sum_{k=1}^{n_3} c_k \prod_{l=1}^{m_3} x_l^{i_{kl}} \cdot \log_2^{j_{kl}}(x_l)$$

(basic block based model)



Search space to (i, j)

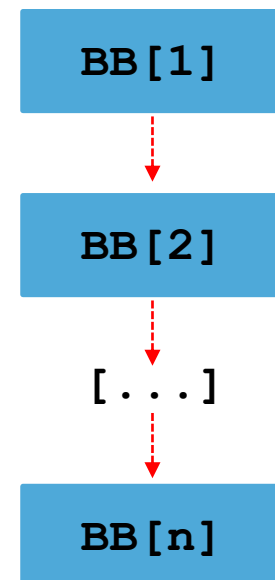


$$f(x_1, \dots, x_m) = \sum_{k=1}^{n_4} c_k \prod_{l=1}^{m_4} x_l^{i_{kl}} \cdot \log_2^{j_{kl}}(x_l)$$

(time based model)

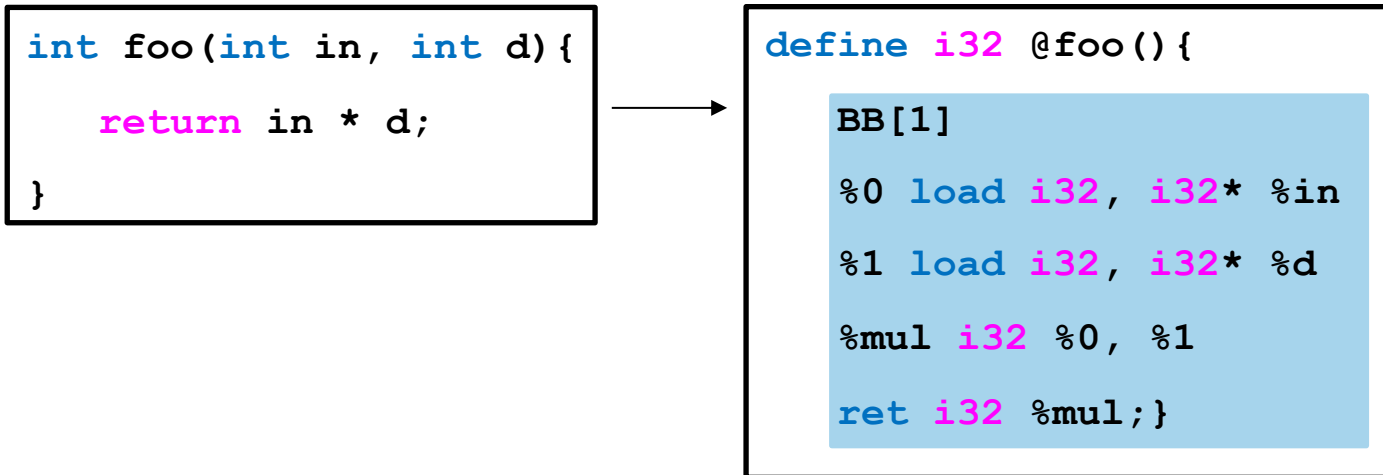
Basic block

- Code sequence with no branches (except input and output) where all the instructions are executed sequentially
- Roughly constant execution time modulo noise
 - Good unit of effort
 - Number of basic blocks executed is reproducible



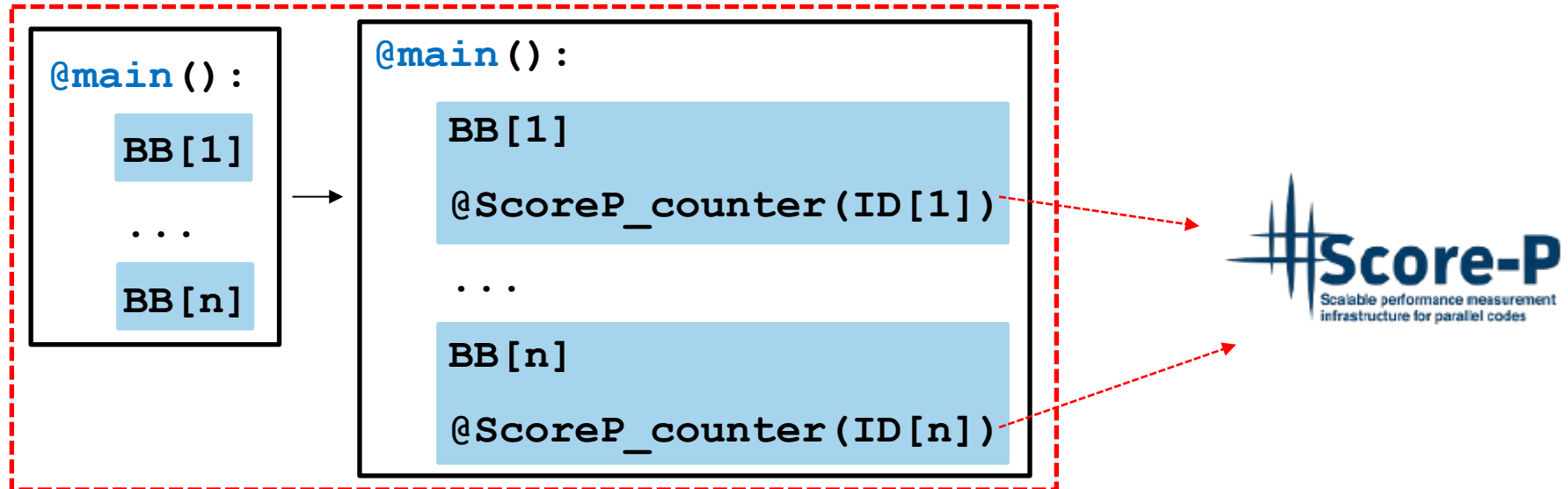
- Converts C/C++ source code to Intermediate Representation (IR)
- Allows automatic instrumentation, analyses, and optimizations of source codes on the IR level

C/C++ code to IR representation:



Basic block instrumentation w/ Score-P

IR instrumentation



- Static analysis: shows the number of functions, basic blocks and instructions present in the code
- Dynamic analysis: runs the code and counts the basic blocks as they are executed

Selected papers

Topic	Bibliography
Foundation (single model paramter)	Alexandru Calotoiu, Torsten Hoefer, Marius Poke, Felix Wolf: Using Automated Performance Modeling to Find Scalability Bugs in Complex Codes. SC13 .
Foundation (multipler model paramters)	Alexandru Calotoiu, David Beckingsale, Christopher W. Earl, Torsten Hoefer, Ian Karlin, Martin Schulz, Felix Wolf: Fast Multi-Parameter Performance Modeling. IEEE Cluster 2016 .
Noise resilience	Marcus Ritter, Alexander Geiß, Johannes Wehrstein, Alexandru Calotoiu, Thorsten Reimann, Torsten Hoefer, Felix Wolf: Noise-Resilient Empirical Performance Modeling with Deep Neural Networks. IPDPS 2021 .
Taint-based performance modeling	Marcin Copik, Alexandru Calotoiu, Tobias Grosser, Nicolas Wicki, Felix Wolf, Torsten Hoefer: Extracting Clean Performance Models from Tainted Programs. PPoPP 2021 .
Performance detective	Larissa Schmid, Marcin Copik, Alexandru Calotoiu, Dominik Werle, Andreas Reiter, Michael Selzer, Anne Koziolk, Torsten Hoefer: Performance-Detective: Automatic Deduction of Cheap and Accurate Performance Models. ICS 2022 .

Thank you!



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Q&A