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%%%%% Discretising the Boundary Integral Equation for the equation
%%%%% lap(u) + k^2u = 0      on the domain B(0,1)
%%%%% u = f      on the boundary of B(0,1)
clear;

%%%%%%%%%%%%% Trapezoidal Rule for sin(x^2log(|x|)) %%%%%%
%
f = @(x) (x.^2).*log(abs(x));
% f = @(x) x.*log(abs(x));
a = -1; b = 1;
nn = 1001;
ns = 1:2:nn;
I = zeros(length(ns),1);
for i = 1:length(ns)
    h = (b-a)/ns(i);
    l = [1/2; ones(ns(i)-1,1); 1/2];
    v = a:h:b;
    I(i) = h * f(v) * l;
end
p = 7001;
hh = (b-a)/p;
ll = [1/2; ones(p-1,1); 1/2];
vv = a : hh : b;
inte1 = hh * f(vv) * ll;
inte = integral(@(x) f(x), a, b);
loglog(ns, abs(I-inte), 'r.', 'MarkerSize', 15);
hold on; loglog(ns, 0.5*ns.^(-2), 'b.', 'MarkerSize', 10);

return
%%%%%%%%% Definition of function and the boundary %%%%%%
x0 = [5.1 3.14];
k = 1;
f = @(x) (1j/4)*besselh(0, k * sqrt( (x(:,1) - x0(:,1)).^2 + (x(:,2) - x0(:,2)).^2 ) );
a = 0.4; m = 3; b = 2;

% ge = @(t) [a*cos(t);b*sin(t)];
% der_ge = @(x) [-a*sin(x); b*cos(x)];
% der2_ge = @(x) [-a*cos(x); -b*sin(x)];
% nge = @(t) [b*cos(t);a*sin(t)]./( ((b*cos(t)).^2 + (a*sin(t)).^2).^0.5 );

ge = @(t) (1 + a*cos(m*t)).*[cos(t);sin(t)];
der_ge = @(t) -a*m*sin(m*t).*[cos(t);sin(t)] + (1 + a*cos(m*t)).*[-sin(t);cos(t)];
der2_ge = @(t) -(1 + a*cos(m*t)).*[cos(t);sin(t)] + 2*a*m*sin(m*t).*[sin(t);-cos(t)]...
    -a*m*m*cos(m*t).*[cos(t);sin(t)];
speed = @(t) -a*m*sin(m*t).*[sin(t);-cos(t)] + (1 + a*cos(m*t)).*[cos(t);sin(t)];

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nge = @t) speed(t)./vecnorm(speed(t));

%%%%% Defn of pts where diff between true sol and double_layer is evaluated %%%%
jj = 100;
pp = -pi : pi/jj : pi;
dir = [cos(pp);sin(pp)].';
rng(1); %%%%%% random number generator fixes seed
rr = 0.5 * min(a,b) * rand(length(pp),1);
x = rr.*dir;
xp = x(:,1); yp = x(:,2);

%%%%% Defn of true sol %%%%%%
sol = f(x);

% n = 500;
% t = -2*pi*n/(2*n+1) : 2*pi/(2*n+1) : pi;
%
% %%% Calculating bdry pts and bdry normal %%%%
% xx = ge(t).';
% nxx = nge(t).';
% w = (2*pi)/(2*n+1); % weight associated with the parameterisation
% l = length(xx(:,1));
% y = f(xx); % y for f = log|x-x0| or f = 5
% absder_g = (((der_ge(t).').^2)*[1;1]).^(0.5);
% ker = get_kerneldl(k, t, ge, nge, der_ge, der2_ge);
% A = -0.5*eye(2*n+1) + w*ker.*absder_g.';

% sigma = A\y;

% n = 100;
% t = -2*pi*n/(2*n+1) : 2*pi/(2*n+1) : pi;

%%%%% Calculating bdry pts and bdry normal for sigma evaluation %%%%
% xx = ge(t).';
% nxx = nge(t).';
%
% l = length(xx(:,1));
% y = f(xx); % y for f = log|x-x0| or f = 5
% w = (2*pi)/(2*n+1);
% absder_g = (((der_ge(t).').^2)*[1;1]).^(0.5);

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% ker = get_kerneldl(k, t, ge, nge, der_ge, der2_ge);
% A = -0.5*eye(2*n+1) + w*ker.*absder_g.');
% sigma = A\y;
% xg = xx(:,1).'; yg = xx(:,2).';
% xn = nxx(:,1).'; yn = nxx(:,2).';
% xgm = repmat(xg, length(xp), 1);
% ygm = repmat(yg, length(yp), 1);

%%%%% Calculation of Sigma %%%%%%
ns = 1:25:1000;
err = zeros(length(ns), 1);
for ii = 1:length(ns)
    n = ns(ii);
    % n = 100;
    t = -2*pi*n/(2*n+1) : 2*pi/(2*n+1) : pi;

%%%%% Calculating bdry pts and bdry normal %%%%
xx = ge(t).';
nxx = nge(t).';
w = (2*pi)/(2*n+1); % weight associated with the parameterisation
l = length(xx(:,1));
y = f(xx); % y for f = log|x-x0| or f = 5
absder_g = (((der_ge(t).').^2)*[1;1]).^(0.5);
ker = get_kerneldl(k, t, ge, nge, der_ge, der2_ge);
A = -0.5*eye(2*n+1) + w*ker.*absder_g.');
sigma = A\y;

% jj = 100;
% pp = -pi:pi/jj:pi;
% dir = [cos(pp);sin(pp)].';
% rng(1); %%%%%% random number generator fixes seed
% rr = (ii/length(ns)) * min(a,b) * rand(length(pp),1);
% x = rr.*dir;
% xp = x(:,1); yp = x(:,2);
%
% %%%% Defn of true sol %%%%%%
% 
% sol = f(x);

%%%%% Calculating Double Layer %%%%%%
xg = xx(:,1).'; yg = xx(:,2).';
xn = nxx(:,1).'; yn = nxx(:,2).';
xgm = repmat(xg, length(xp), 1);

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ygm = repmat(yg, length(yp), 1);
xpt = repmat(xp, 1, length(xg));
ypt = repmat(yp, 1, length(yg));
double_layer = (1i*k*w/4)*( besselh(1, k*sqrt( (xpt - xgm).^2 + ...
(ypt - ygm).^2)).*( (xpt - xgm).*xn + (ypt - ygm).*yn )./ ...
(sqrt( (xpt - xgm).^2 + (ypt - ygm).^2 ) )*(sigma.*absder_g);

%%%%%%%%%%%%% Calculating error between true sol and Double Layer %%%%%%
err(ii) = max(abs(sol - double_layer));
end
figure; loglog(ns, err, 'r.', 'MarkerSize', 10);
% hold on; semilogy(ns, exp(-0.3*ns), 'b.')

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function [ker] = get_kerneldl(k, t, gamma, normal, der1, der2)
x = gamma(t).';
n = normal(t).';
d1 = der1(t).';
d2 = der2(t).';
xx = x(:,1); xy = x(:,2);
nx = n(:,1).'; ny = n(:,2).';
xpt = repmat(xx, 1, length(xx)); xgm = repmat(xx.', length(xx), 1);
ypt = repmat(xy, 1, length(xy)); ygm = repmat(xy.', length(xy), 1);

ker = (1i*k/4)*besselh(1,k*sqrt( (xpt-xgm).^2 + (ypt-ygm).^2)) .*((xpt-xgm).*nx ...
+ (ypt-ygm).*ny)./(sqrt( (xpt-xgm).^2 + (ypt-ygm).^2));

for i = 1:length(ker(:,1))
    ker(i,i) = (1/(4*pi))*( n(i,1)*d2(i,1) + n(i,2)*d2(i,2) )/(
    d1(i,1)^2 + d1(i,2)^2 );
end
end

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%%%%%%%%%%%%% Learning points
% if your discretising points on "boundary" are all distant 'h' away from each other,
% then you can get the error around points in the "domain" which are at atmost

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% distance 5h from the boundary.

%%%%%%% Homeworks %%%%%%
% 1. Plot the error as a function of the number 'n' and try to get the error
% and try to justify it.
% ANSWER:- For a fixed x(according to our notations which is the pts inside domain
% where we evaluate the error), the error behaves as the
% c.n^(-3) where c = 0.009
% depends upon distance between the boundary and x, as the kernel
% is of the order 1/(x-y) when x is in domain and y is in boundary.

% 2. Now try to solve the Helmholtz equation and see the asymptotics of
% Single Layer and Double Layer in this case, where Green's function is
% given by G(x,y) = i/4*Hankel(0,1)(k|x-y|), i.e., calculate the limit as x
% goes to y of G_s(x,y) and limit as x goes to y of G_d(x,y)
% ANSWER:- Look at the notes titled NODES exercise section

% 3. Plot the error in Helmholtz case and get the rates and explain the reason
% for the deacys.
% ANSWER:- Error is of the order

%%%%%%% Observations %%%%%%
% 1. In this case, error is given by err(n) = c.n^(-3), which we have observed
% by fixing the pts(x in our notations), where error is to be evaluated,
% and varying the nodes.
% 2. In this case, also error depends on the distance of interior points and
% boundary points, which is the "5h rule" which we have observed by fixing
% the node as 100, and varying the distance of pts(x in our notations),
% where error is to be evaluated, from the boundary
% 3. The nearer the points(x in our notations), where we are evaluating the
% difference (u(x) - double_layer(x)), the more the error, which is
% basically the point number 2

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