

# Generating uniform unit random vectors in $\mathbb{R}^n$

Andersen Ang

Mathématique et recherche opérationnelle  
UMONS, Belgium

[manshun.ang@umons.ac.be](mailto:manshun.ang@umons.ac.be)      Homepage: [angms.science](http://angms.science)

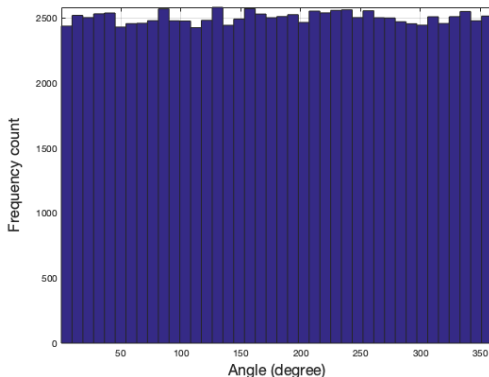
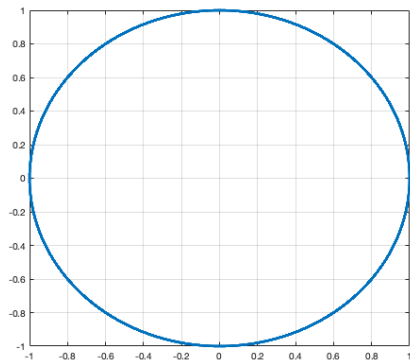
First draft : December 24, 2018

Last update : June 21, 2019

# Generating uniform distributed random unit vector in $\mathbb{R}^2$

Generating a random unit vector  $\mathbf{x}$  in  $\mathbb{R}^2$  is the same as randomly picking a point on the circumference of a circle centred at the origin.

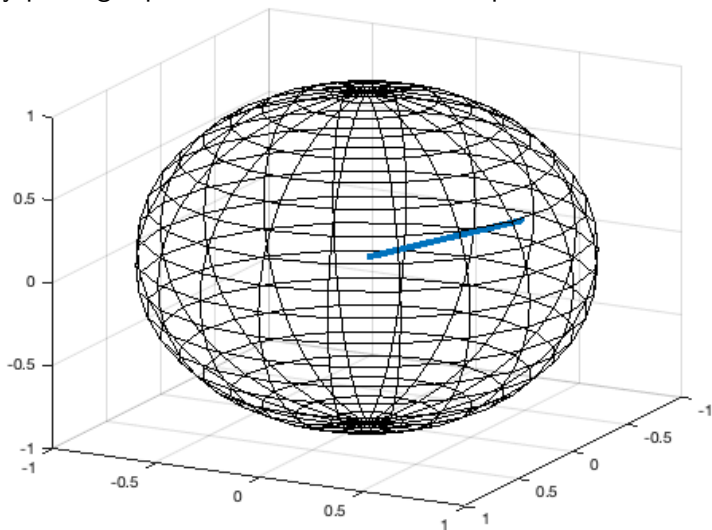
With the expression  $\mathbf{x} = [\cos \theta \ \sin \theta]$ , we can sample  $\theta \sim \mathcal{U}[0, 2\pi]$ , where  $\mathcal{U}$  stands for uniform distribution.



The points are uniformly distributed on the circumference.

## Random unit vector in $\mathbb{R}^3$

In  $\mathbb{R}^3$ , the same idea holds : generating a unit vector in  $\mathbb{R}^3$  is the same as randomly picking a point on the surface of a 2-sphere<sup>1</sup>.



<sup>1</sup>A  $n$ -sphere is defined as  $S^n = \{\mathbf{x} \in \mathbb{R}^{n+1} \mid \|\mathbf{x}\| = r\}$ .

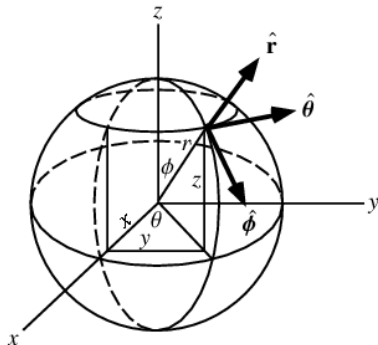
# Expression of points on the surface of 2-sphere

The point on the surface of unit 2-sphere in  $\mathbb{R}^3$  can be expressed as

$$\mathbf{x} = [\sin \phi \cos \theta \quad \sin \phi \sin \theta \quad \cos \phi],$$

where

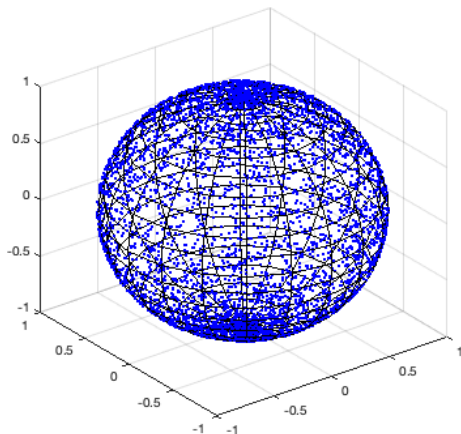
- $\theta$  is the azimuthal angle ranged in  $[0 \ 2\pi]$
- $\phi$  is the polar angle ranged in  $[0 \ \pi]$
- for unit 2-sphere the radius  $r = 1$



## Wrong way to generate uniform random unit vector in $\mathbb{R}^3$

As  $\mathbf{x} = [\sin \phi \cos \theta \quad \sin \phi \sin \theta \quad \cos \phi]$ ,  $\theta \in [0, 2\pi]$ ,  $\phi \in [0, \pi]$ . At first glance, to generate  $\mathbf{x}$ , one may pick  $\phi \sim \mathcal{U}[0, \pi]$  and  $\theta \sim \mathcal{U}[0, 2\pi]$ .

This method does not work : the resulting points will not be uniform on the surface of the sphere, there will be more points at the two poles.

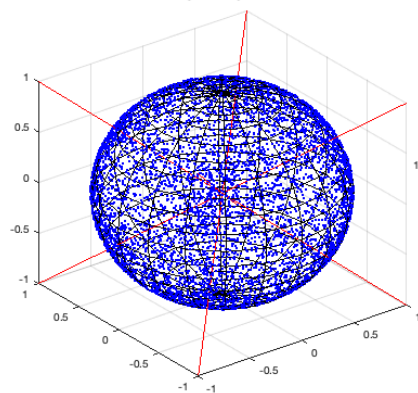


# Wrong way to generate uniform random unit vector in $\mathbb{R}^3$

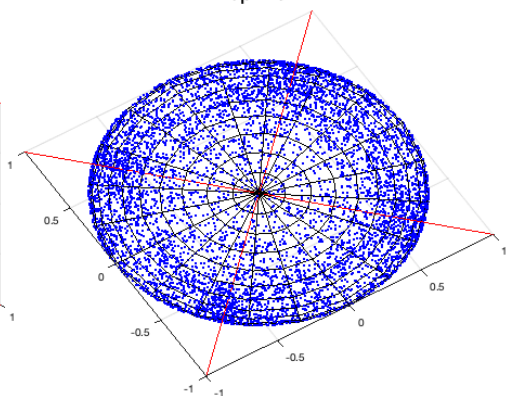
One may also generate  $\mathbf{x}$  by the *cube method* : randomly pick a point in  $[-1, 1]^3$ , then normalize it to have unit norm.

This method does not work : there will be more points on the diagonals.

3D view



Top view



Interesting fact : for  $\mathbf{x} = [x \ y \ z]$ , if  $\mathbf{x}$  is uniformly generated on the surface of the unit sphere, then  $(x, y, z)$  are all uniform in  $[-1, 1]$ , but the converse here is not true.

# The modified cube method in $\mathbb{R}^3$ using rejection sampling

We can modify the cube method to generate  $\mathbf{x}$  :

- 1 Generate 3 random number  $x, y, z \sim \mathcal{U}[-1, 1]$  (the cube method)
- 2 What's new : if  $x^2 + y^2 + z^2 \leq 1$ , let  $\mathbf{x} = \frac{[x \ y \ z]}{\sqrt{x^2 + y^2 + z^2}}$ .  
Otherwise, reject the point and re-sample again.

The distribution of  $\mathbf{x}$  would be uniform on surface of the unit 2-sphere.

Why it works : only the points inside of unit ball are normalized, the points outside the sphere are rejected. This technique is called *Rejection sampling*.

Drawback of this approach : inefficient/slow, which is the fundamental disadvantage of all methods that use rejection sampling.

# Why the modified cube method is inefficient

There are 2 step to generate  $\mathbf{x}$  :

- 1 Generate random number  $x, y, z \sim \mathcal{U}[-1, 1]$
- 2 Rejection : if  $x^2 + y^2 + z^2 > 1$ , re-sample again

Rejecting sampled point means some computer resources are wasted to generate a useless point. That is, this method requires some random number generations before  $x^2 + y^2 + z^2 \leq 1$  is true.

In fact, step 1 has to be run on average 2 to 3 time to generate a feasible point :

$$\mathbb{P}(x^2 + y^2 + z^2 \leq 1) = \frac{\text{Volume of the sphere}}{\text{Volume of the cube}} = \frac{\frac{4\pi r^3}{3}}{(2r)^3} = \frac{\pi}{6} \in \left[\frac{1}{3}, \frac{1}{2}\right].$$



## The modified cube method is very inefficient in high dimension

The modified cube method works even worse when dimensions  $n$  is large. As the volume of unit ball shrinks fast in high dimension, it will require many random number generations before  $x_1^2 + x_2^2 + \cdots + x_n^2 \leq 1$  is true.

For example, when  $n = 8$ , we have volume of the unit 7-sphere as  $4.06r^8$ . Then

$$\mathbb{P}(x_1^2 + \cdots + x_n^2 \leq 1) = \frac{4.06r^8}{(2r)^8} \approx \frac{1}{2^6} = \frac{1}{64}.$$

It takes roughly 64 random generations to form a feasible point.

If  $n = 11$  :

$$\mathbb{P}(x_1^2 + \cdots + x_n^2 \leq 1) = \frac{1.884r^{11}}{(2r)^{11}} \approx \frac{1}{2^{10}} = \frac{1}{1024}.$$

It takes about 1000 generations to form a feasible point.

# Efficient and simple way to pick random unit vector in $\mathbb{R}^3$

The following is an efficient and simple way to generate  $\mathbf{x}$  by using Gaussian random variable<sup>2</sup> : generate 3 independent Gaussian random variables  $x, y, z \sim \mathcal{N}(0, 1)$ . Then the distribution of

$$\mathbf{x} = \frac{\begin{bmatrix} x & y & z \end{bmatrix}}{\sqrt{x^2 + y^2 + z^2}}$$

will be uniform over the surface of the sphere.

This works as multivariate normal distribution is *spherical*

- Further more, multivariate normal distribution is *symmetric* : it is invariant under rotation, so such approach is not the same as the cube method, points will not be concentrated on the diagonals
- Also, this method works for any dimension  $n$

---

<sup>2</sup>M. E. Muller "A Note on a Method for Generating Points Uniformly on N-Dimensional Spheres." 1959.

## Other ways to pick random unit vector in $\mathbb{R}^3$

There are other (more complicated) methods to generate  $\mathbf{x}$  in  $\mathbb{R}^3$  :

Using equal-area projection of sphere onto rectangle surface of the bounding cylinder, we have

$$\mathbf{x} = \begin{bmatrix} \sqrt{1-z^2} \cos \theta & \sqrt{1-z^2} \sin \theta & z \end{bmatrix},$$

where  $z \sim \mathcal{U}[-1, 1]$ ,  $\theta \sim \mathcal{U}[0, 2\pi]$  and here  $z = \cos \phi$  for the azimuthal angle  $\phi$ .

On spherical coordinate, we can set

$$\theta \sim \mathcal{U}[0, 2\pi], \quad \phi = \cos^{-1} a,$$

where  $a \sim \mathcal{U}[-1, 1]$ . Then we set  $\mathbf{x} = [\sin \phi \cos \theta \quad \sin \phi \sin \theta \quad \cos \phi]$ .

Note that  $\phi = \cos^{-1} a$ ,  $a \sim \mathcal{U}[-1, 1]$  is different from directly picking  $\phi \sim \mathcal{U}[0, \pi]$ .

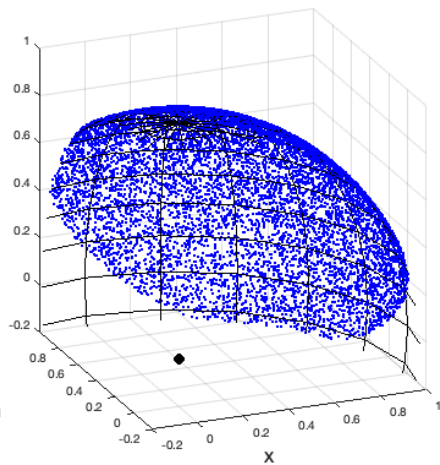
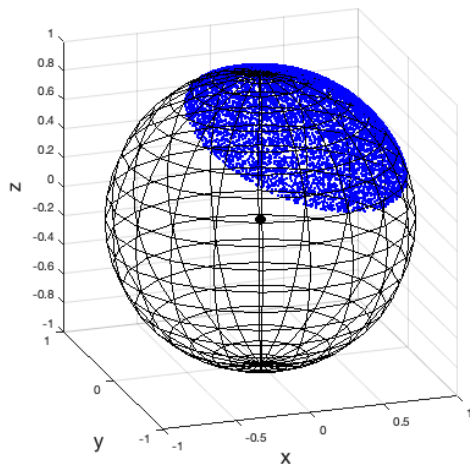
## Generating uniform random unit vector in $\mathbb{R}^n$

To generate unit vector  $\mathbf{x} = [x_1, x_2, \dots, x_n] \in \mathbb{R}^n$  such that  $\mathbf{x}$  is uniformly distributed on the surface of the unit  $(n - 1)$ -sphere :

- 1 Generate  $n$  i.i.d. Gaussian random variable :  $x_i \sim \mathcal{N}(0, 1)$ .
- 2 Form  $\mathbf{x} = [x_1, x_2, \dots, x_n]$ .
- 3 Normalize  $\mathbf{x}$  to have unit  $l_2$  norm.

# Generating random unit vector in $\mathbb{R}^3$ within a cone

"Generating random unit vector in  $\mathbb{R}^n$  inside a cone" is the same as "picking a point on the partial surface of a  $(n - 1)$ -sphere defined by the solid angle of the cone".



# Points on the surface of 2-sphere inside a cone

The points on the surface of 2-sphere are

$$\mathbf{x} = [\sin \phi \cos \theta \quad \sin \phi \sin \theta \quad \cos \phi],$$

where

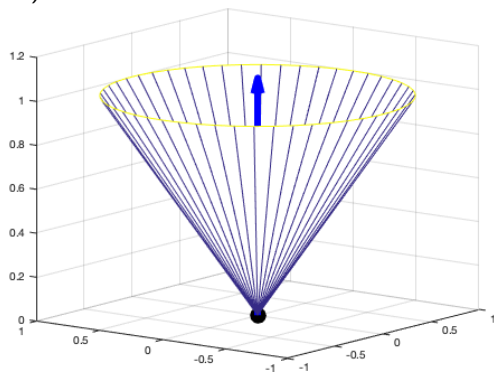
- $\theta$  is the azimuthal angle ranged in  $[\theta_1, \theta_2] \subseteq [0, 2\pi]$
- $\phi$  is the polar angle ranged in  $[\phi_1, \phi_2] \subseteq [0, \pi]$
- $\theta_1, \theta_2, \phi_1, \phi_2$  are all unknown value yet to be determined based on the information on the circular cone  $C$

# The characterization of circular cone $C(\mathbf{p}, \mathbf{d}, \psi)$

A circular cone  $C$  is completely determined by three parameters :

- the origin of the cone  $\mathbf{p} \in \mathbb{R}^n$
- the direction of the cone  $\mathbf{d} \in \mathbb{R}^n$
- the side angle of the cone  $\psi \in [0, \pi]$

An example in  $\mathbb{R}^3$ :  $\mathbf{p} = [0, 0, 0]$  (the black dot),  $\mathbf{d} = [0, 0, 1]$  (the blue arrow),  $\psi = \frac{\pi}{4}$  (the angles between all the line on the yellow circle and  $\mathbf{d}$  are all equal to  $45^\circ$ )



## Unit vector inside a cone

Now consider  $n = 3$  and  $\mathbf{p} = [0, 0, 0]$ . (If the cone is not centred at origin, we can just translate it by adding  $\mathbf{p}$ ). We are given a cone  $C(\mathbf{d}, \psi)$ , we want to generate unit vector such that these vectors are uniformly distributed inside the cone  $C$ .

How to generate these vectors:

$$\mathbf{x} = \begin{bmatrix} \sqrt{1 - z^2} \cos \theta & \sqrt{1 - z^2} \sin \theta & z \end{bmatrix},$$

where  $\theta \sim \mathcal{U}[0, 2\pi]$  and  $z \sim \mathcal{U}[\cos \phi, 1]$ , the polar angle  $\phi$  is obtained by the z-component of the direction vector  $\mathbf{d}$  of the cone  $C$ , that is :

$$\phi = \cos^{-1} \langle [0, 0, 1], \hat{\mathbf{d}} \rangle = \cos^{-1} \left( \frac{\mathbf{d}_z}{\|\mathbf{d}\|_2} \right).$$



- Generating random unit vector in  $\mathbb{R}^n$  is the same as picking a point randomly on the surface of a unit  $(n - 1)$ -sphere
- Wrong ways to generating random unit vector in  $\mathbb{R}^n$
- Inefficient rejection sampling based method to generating random unit vector in  $\mathbb{R}^n$
- Efficient way to generating random unit vector in  $\mathbb{R}^n$
- A way to generating random unit vector within a cone in  $\mathbb{R}^3$

Not discussed : how to generate random unit vector within a cone in  $\mathbb{R}^n$

End of document