

# ActinRod

Peter Gawthrop. *peter.gawthrop@unimelb.edu.au*

March 14, 2024

## Contents

<b>1</b>	<b>Introduction</b>	<b>2</b>
<b>2</b>	<b>Supporting software</b>	<b>2</b>
2.1	Import packages . . . . .	2
2.2	Numeric calculations . . . . .	2
<b>3</b>	<b>Computational functions</b>	<b>4</b>
<b>4</b>	<b>Case 1: Rigid filament normal to membrane</b>	<b>5</b>
4.1	Bond graph model . . . . .	5
4.2	Stoichiometry . . . . .	7
4.3	Plot velocity-force curve. . . . .	7
4.4	Plot mechanical power: $VF$ . . . . .	10
4.5	Plot chemical power : $v(\phi_A - \phi_B)$ and mechanical power . . . . .	11
4.6	Plot efficiency. . . . .	13
<b>5</b>	<b>Case 2a: Rigid filament at angle <math>\theta</math> from normal to membrane</b>	<b>15</b>
5.1	Bond graph model . . . . .	15
5.2	Stoichiometry . . . . .	17
5.3	Optimal angle (for max velocity) . . . . .	18
5.4	Plot velocity-theta curves. . . . .	18
5.5	Plot optimal angle $\theta_{opt}$ . . . . .	19
5.6	Plot effective stall force $F_s$ . . . . .	20
5.7	Plot velocity-force curve. . . . .	21
5.8	Plot velocity-force-angle surface. . . . .	22
<b>6</b>	<b>Case 2b: Flexible filament at angle <math>\theta</math> from normal to membrane</b>	<b>24</b>
6.1	Bond graph model . . . . .	24
6.2	Stoichiometry . . . . .	26
6.3	Parameters . . . . .	27
6.4	Compute deviation angle $\epsilon = \theta - \theta_0$ . . . . .	27
6.5	Plot velocity-angle curves. . . . .	27
6.6	Plot deviation angle-angle ( $\epsilon - \theta_0$ ) curves. . . . .	28
6.7	Plot $\epsilon$ error . . . . .	29
6.8	Plot optimal angle $\theta_{opt}$ . . . . .	30
6.9	Plot velocity-force curves - vary theta . . . . .	31
6.10	Plot velocity-force curves - vary chi . . . . .	33
6.11	Plot velocity-force-angle surface. . . . .	36
6.12	Singular value of $F/F_0$ . . . . .	37
6.13	Numerical values from MolOst96 . . . . .	38
6.14	Experimental results from LiBieWei22 . . . . .	40

# 1 Introduction

This notebook generates the figures for the paper: .

## 2 Supporting software

### 2.1 Import packages

```
[1]: ## Some useful imports
import BondGraphTools as bgt
import numpy as np
import sympy as sp
import matplotlib.pyplot as plt
import copy

## For reimporting: use imp.reload(module)
import importlib as imp

## Stoichiometric analysis
import stoich as st

## SVG
import svgBondGraph as sbg

## Stoichiometry to BG
import stoichBondGraph as stbg

## Display (eg disp.SVG(), disp.
import IPython.display as disp

## Physical constants
import scipy.constants as const
pi = np.pi

quiet = False

## Plotting

# Set Plotting = True to generate PDFs in Figs/
Plotting = False

lw = 5 # linewidth
fontsize = 16
plt.rcParams.update({'font.size': fontsize})
```

### 2.2 Numeric calculations

```
[2]: ## Numeric calculations
F = const.physical_constants['Faraday constant'][0]
k_B = const.physical_constants['Boltzmann constant'][0]
R = const.physical_constants['molar gas constant'][0]
```

```

N_A = const.physical_constants['Avogadro constant'][0]
T = 273 + 37
## Sanity check
print(f'R: {R:0.6f}, k_B*N_A: {k_B*N_A:0.6f}')

## Delta from Pes0de0st93
delta = 2.7e-9 # m

## alpha and beta values are unclear.
alpha = 113
beta = 1.6
print(f'alpha: {alpha:0.2f} 1/sec')
print(f'beta: {beta:0.2f} 1/sec')

m = delta*N_A
print(f'm (standard) {m:0.2e} m/mol')

m_F = delta*N_A/F
print(f'm (Faraday-equivalent) {m_F:0.2e} m/C')

V0 = delta*(alpha-beta)
print(f'V0: {V0*1e6:0.2F} micro m /sec')

F0 = (R*T/m)*np.log(alpha/beta)
print(f'F0: {F0*1e12:0.2F} pN')

P0 = F0*V0
print(f'P0: {P0*1e18:0.2F} aW')

gamma = np.log(alpha/beta)
print(f'gamma: {gamma:0.2F} ')

## Sanity check
print(F0 - gamma*(R*T/m))

```

```

R: 8.314463, k_B*N_A: 8.314463
alpha: 113.00 1/sec
beta: 1.60 1/sec
m (standard) 1.63e+15 m/mol
m (Faraday-equivalent) 1.69e+10 m/C
V0: 0.30 micro m /sec
F0: 6.75 pN
P0: 2.03 aW
gamma: 4.26
0.0

```

```

[3]: ## Numerical values from Mol0st96
lamb = 1e-6 #persistance length
print(f'lambda: {lamb/1e-6} micro m')

L = 30e-9 # length used in Fig 2

```

```

print(f'L: {L/1e-9:0.2f} nm')

chi = L*L*F0/(3*k_B*T*lamb)
print(f'chi: {chi:0.2f}')

```

```

lambda: 1.0 micro m
L: 30.00 nm
chi: 0.47

```

### 3 Computational functions

```

[4]: def FVnorm(F,gamma=5):
    V = (np.exp(gamma*(1-F)) - 1)/(np.exp(gamma)-1)
    return V

def normPar(alpha,beta,delta):
    V0 = delta*(alpha-beta)
    gamma = np.log(alpha/beta)
    F0 = gamma*(R*T)/m
    return F0,V0,gamma

def normParTheta(alpha,beta,delta,theta=0):
    F0,V0,gamma = normPar(alpha,beta,delta)
    Fth = F0/np.cos(theta)
    Vth = V0/np.cos(theta)
    return Fth,Vth,gamma

def epsilon(F,theta0,chi=0.3,useTan=False):
    ## chi and F Normalised by stall force F0
    sinth0 = np.sin(theta0)
    costh0 = np.cos(theta0)
    if useTan:
        eps = chi*F*np.tan(theta0)/(1-chi*F)
    else:
        eps = chi*F*sinth0/(1-chi*F*costh0)

    return eps

def FVnormTheta(F,gamma=5,theta=0):
    costh = np.cos(theta)
    V = FVnorm(F*costh,gamma=gamma)*costh
    return V

def FVnormFlex(F,gamma=5,theta0=0,chi=0.3,normaliseTheta=False,useTan=False):

    eps = epsilon(F,theta0,chi=chi,useTan=useTan)
    theta = theta0 + eps
    if normaliseTheta:
        costh = np.cos(theta0)
        V = FVnormTheta(F/costh,gamma=gamma,theta=theta)/costh

```

```

else:
    V = FVnormTheta(F,gamma=gamma,theta=theta)
return V,eps

```

```

[5]: ## Optional plotting
lw = 5 # linewidth
def Savefig(name):
    if Plotting:
        plt.rcParams.update({'font.size': fontsize})
        plt.tight_layout()
        plotname = 'Figs/'+name+'.pdf'
        print('Saving',plotname)
        plt.savefig(plotname)

```

```

[6]: ## Editing function (to change TF modulus)
def modulus(sys,moduli={}):
    q = ""
    compNames = moduli.keys()
    filename = sys+'.py'
    newfilename = sys+'_mod.py'
    text = open(filename, 'r')
    f = open(newfilename, 'w')
    for line in text.readlines():
        match = False
        for name in compNames:
            Name = q+name+q
            if Name in line:
                # print(name)
                # print(line)
                # print(line.parRename(Name,q+moduli[name]+q))
                f.write(line.parRename(Name,q+moduli[name]+q))
                match = True
        if not match:
            f.write(line)

modulus('ActinRodTheta_abg',moduli={'m_m':'m','m_cos':'cos(theta)'})

```

## 4 Case 1: Rigid filament normal to membrane

### 4.1 Bond graph model

At the moment: - this is not used in the computations. - experimental rewriting of parameters is used.

```

[7]: ## Set up simple model
imp.reload(sbg)
sbg.model('ActinRod_abg.svg',parRename={'m_m':'m'})
import ActinRod_abg
imp.reload(ActinRod_abg)
disp.SVG('ActinRod_abg.svg')

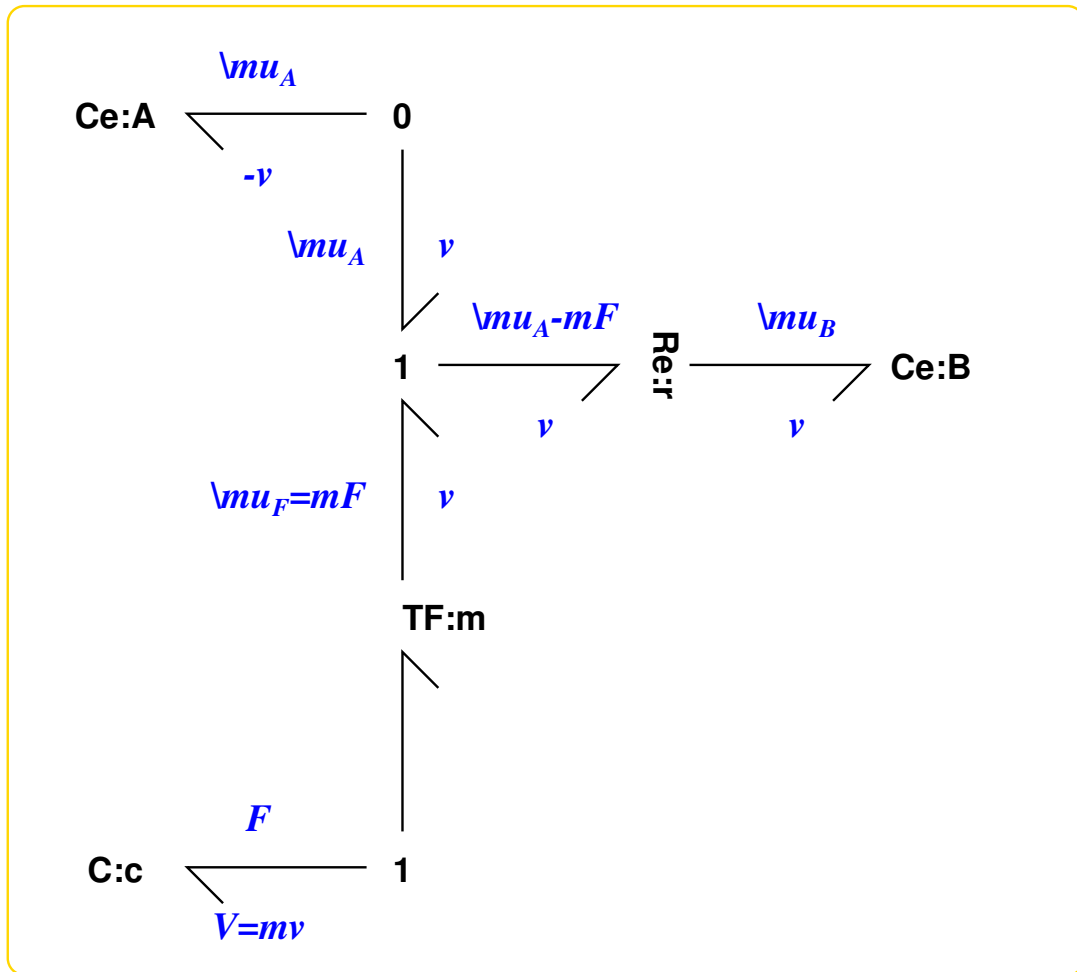
```

```

TF m
{'m_m': 'm'}
m_m
Replacing 'm_m' with 'm'

```

[7]:



```

[8]: # ## Reset TF moduli
      # modulus('ActinRod_abg',moduli={'m_m':'m'})
      # import ActinRod_abg_mod

```

```

[9]: imp.reload(ActinRod_abg)
      model=ActinRod_abg.model()
      model.constitutive_relations

```

```

[9]: [-K_A*kappa_r*m*x_1*exp(-m*x_0/(RT*c)) + K_B*kappa_r*m*x_2 + dx_0,
      K_A*kappa_r*x_1*exp(-m*x_0/(RT*c)) - K_B*kappa_r*x_2 + dx_1,
      -K_A*kappa_r*x_1*exp(-m*x_0/(RT*c)) + K_B*kappa_r*x_2 + dx_2]

```

## 4.2 Stoichiometry

```
[10]: ## Stoichiometry
s = st.stoich(ActinRod_abg.model(),linear=['c'],symbolic=True,quiet=quiet)
```

```
Computing N ...
Swapping Re:r for two Sf in ActinRod
Done.
Computing K ...
Done.
Computing G ...
Done.
```

```
[11]: st.sprint(s,'species')
st.sprint(s,'N')
st.sprint(s,'Nf')
st.sprint(s,'Nr')#
st.sprint(s,'Z')
st.sprint(s,'D')
```

```
species:
['c', 'A', 'B']
N:
Matrix([[m], [-1], [1]])
Nf:
Matrix([[-m], [1], [0]])
Nr:
Matrix([[0], [0], [1]])
Z:
[[-m 0]
 [1 0]
 [0 1]]
D:
[[-1]
 [ 1]]
```

```
[12]: disp.Latex(st.sprintvl(s))
```

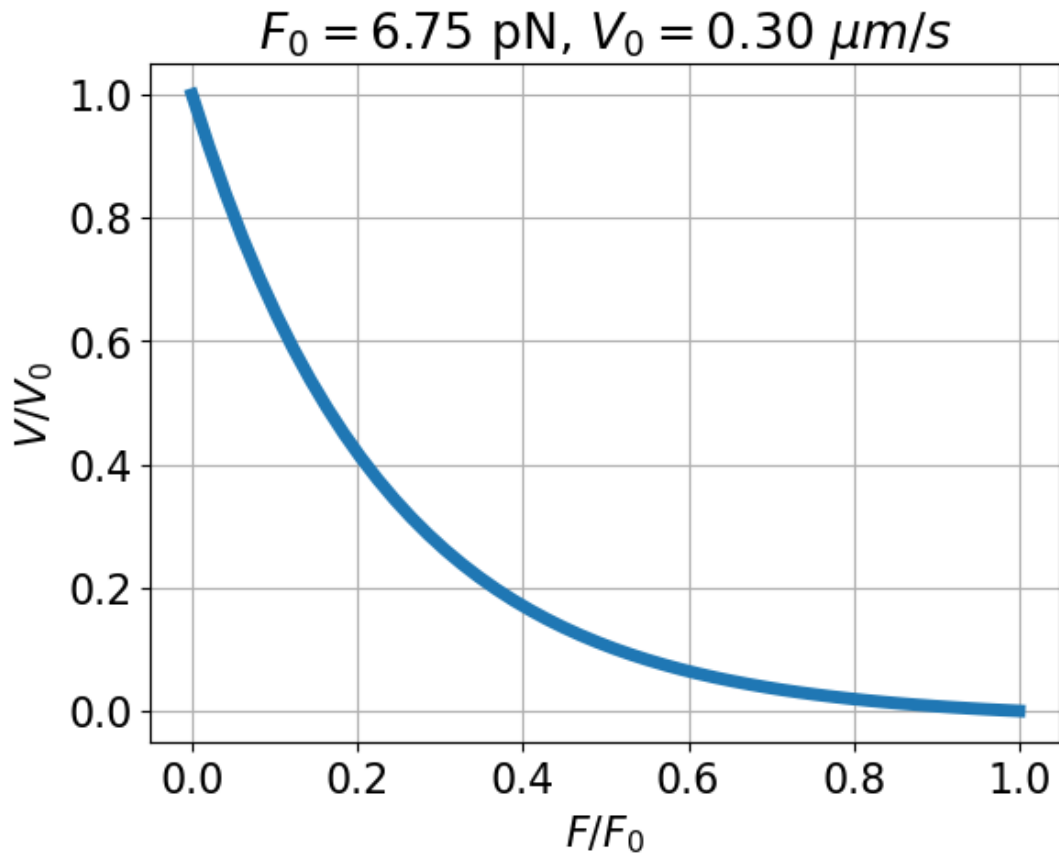
[12]:

$$v_r = \kappa_r \left( K_A x_A e^{-\frac{K_c m x_c}{V_N}} - K_B x_B \right) \quad (1)$$

## 4.3 Plot velocity-force curve.

```
[13]: ## Plot curve: V-F
FF = np.linspace(0,1)
VV = delta*( alpha*np.exp(-gamma*FF) -beta )/V0
plt.title(f'$F_0 = \{F0*1e12:0.2f\}$ pN, $V_0 = \{V0*1e6:0.2f\}$ \mu m/s$')
plt.plot(FF,VV,lw=1w)
plt.xlabel('$F/F_0$')
plt.ylabel('$V/V_0$')
plt.grid()
```

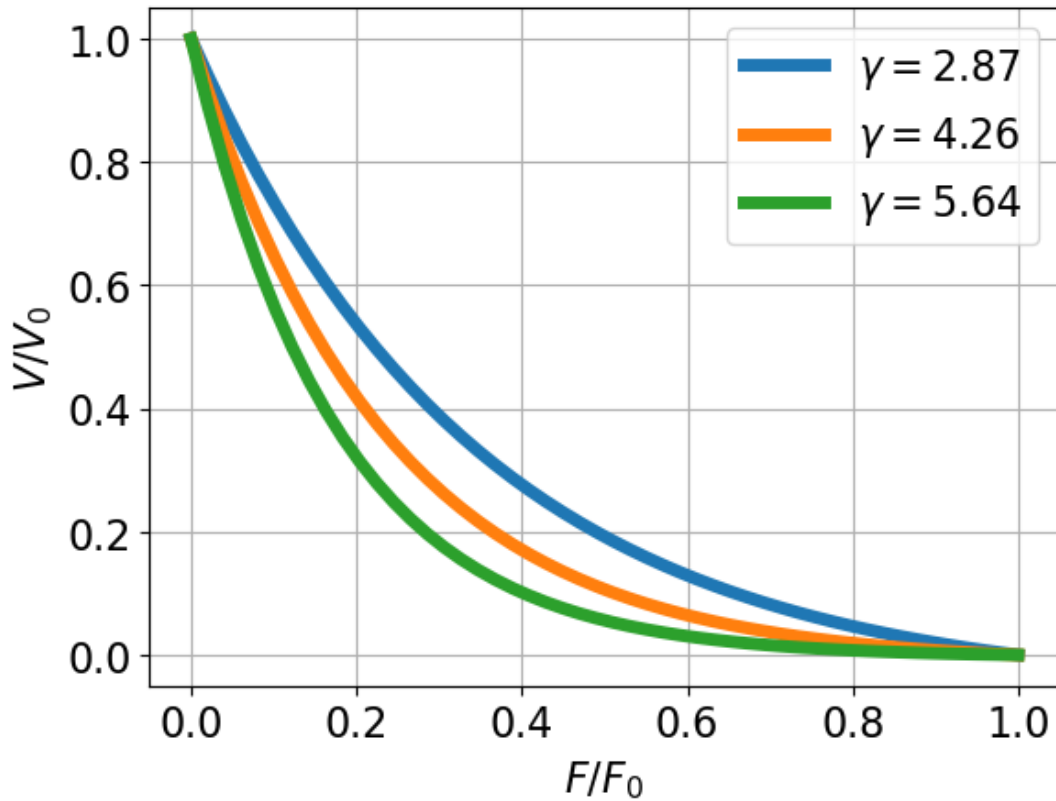
```
Savefig('FV0')
```



```
[14]: ## Plot normalised curve: V-F for various gamma
FF = np.linspace(0,1)
# Alpha = np.array([np.exp(3)*beta,alpha,np.exp(5)*beta])
Alpha = np.array([0.25,1,4])*alpha
# print(Alpha)
for alp in Alpha:
    F00,V00,gam = normPar(alp,beta,delta)
    label = f'$\\gamma = {gam:0.2f}$'
    VV = FVnorm(FF,gamma=gam)
    plt.plot(FF,VV,lw=1w,label=label)

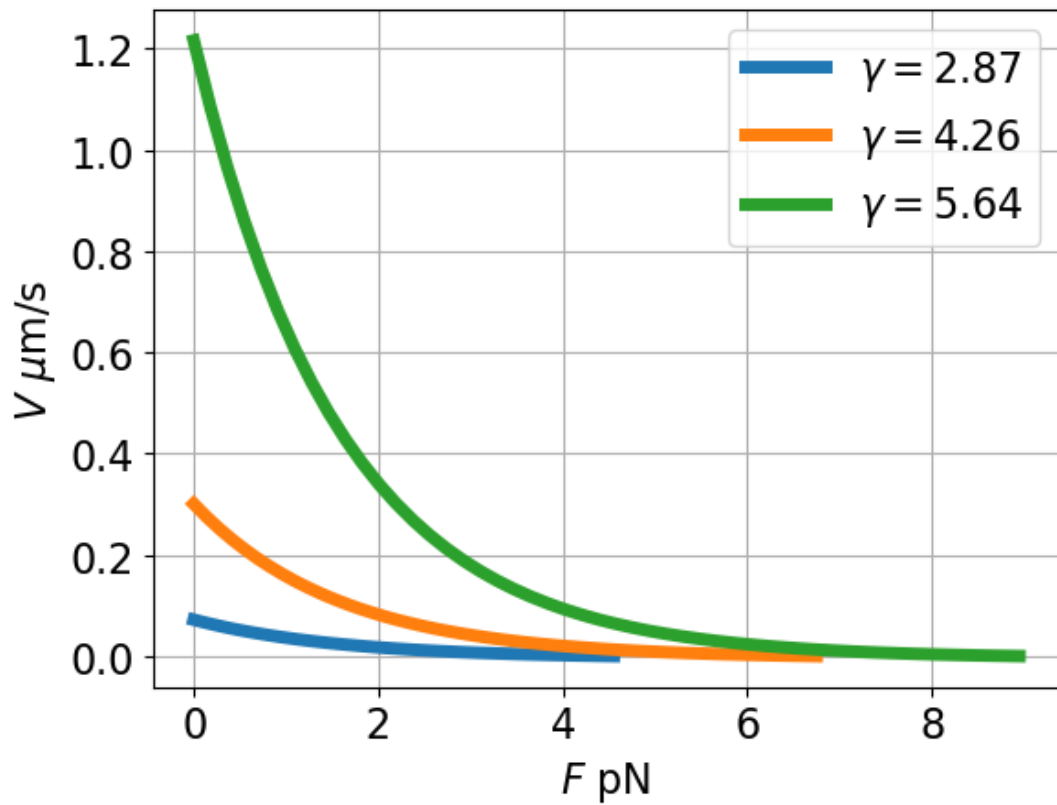
# plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$~\mu m/s$')
plt.xlabel('$F/F_0$')
plt.ylabel('$V/V_0$')
plt.grid()
plt.legend()
Savefig('FV0')
```





```
[15]: ## Plot unnormalised curve: V-F for various gamma
# print(Alpha)
# Alpha = [alpha]
for alp in Alpha:
    F0,V0,gam = normPar(alp,beta,delta)
    label = f'$\\gamma = {gam:0.2f}$' #', F_0 = {F0/1e-12:.2f}pN, V_0={V0/
    1e-6:.2f}\\mu m/s$'
    VV = FVnorm(FF,gamma=gam)
    plt.plot(FF*F0/1e-12,VV*V0/1e-6,lw=lw,label=label)

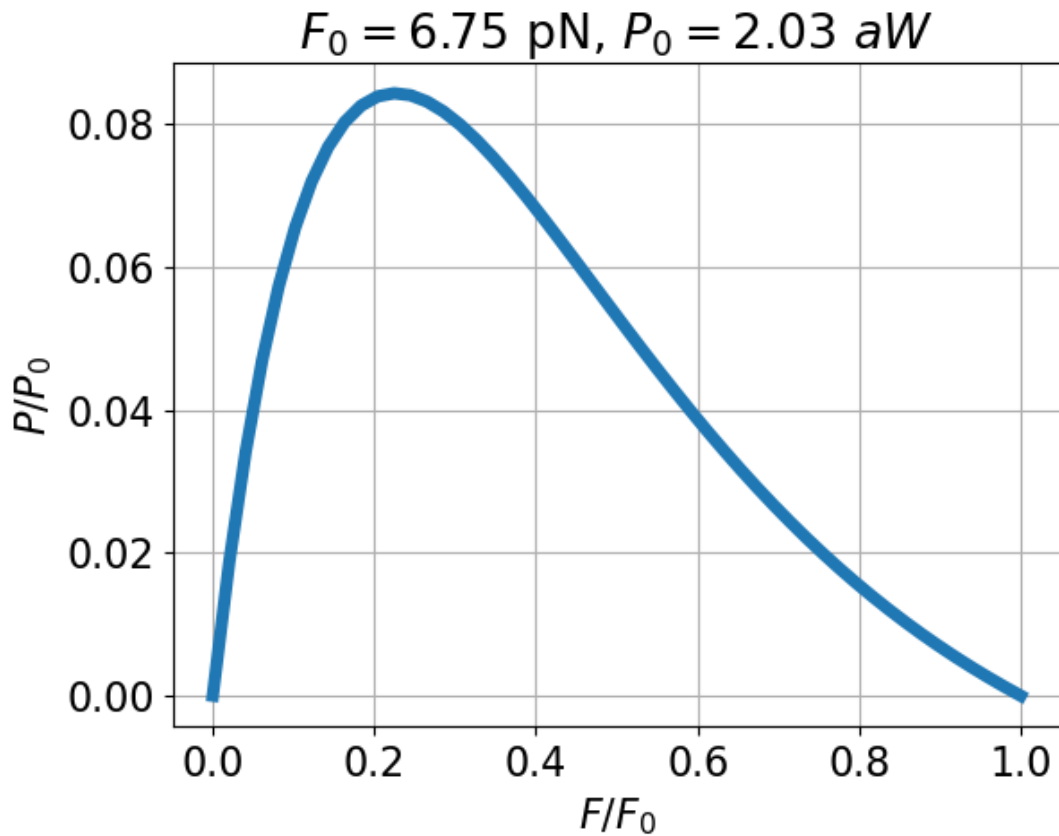
# plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = \u
    {V0*1e6:0.2f}\\mu m/s$')
plt.xlabel('$F$ pN')
plt.ylabel('$V\\mu m/s$')
plt.grid()
plt.legend()
Savefig('FV')
```



#### 4.4 Plot mechanical power: $VF$

```
[16]: ## Redo for standard values
F0,V0,gamma = normPar(alpha,beta,delta)
VV = FVnorm(FF,gamma=gamma)
```

```
[17]: ## Plot mechanical power
PP = FF*VV
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $P_0 = {P0*1e18:0.2f}$~aW$')
plt.plot(FF,PP,lw=1w)
plt.xlabel('$F/F_0$')
plt.ylabel('$P/P_0$')
plt.grid()
Savefig('FP_mech')
```



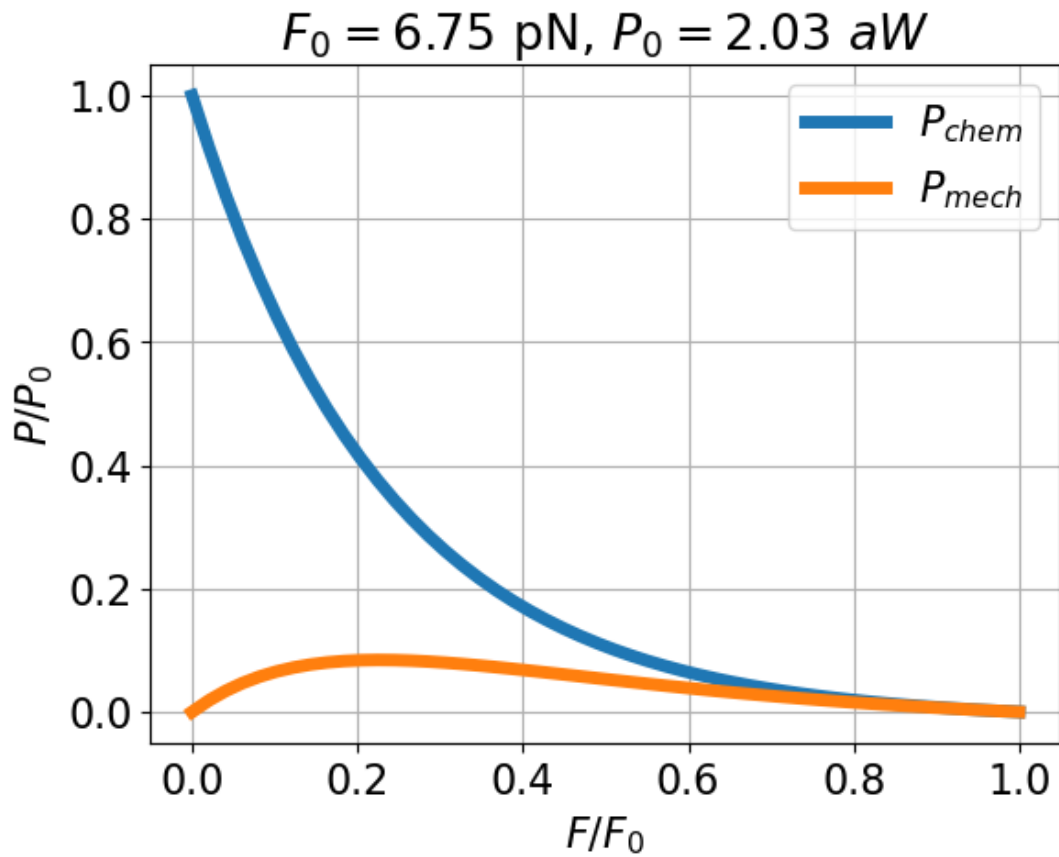
#### 4.5 Plot chemical power : $v(\phi_A - \phi_B)$ and mechanical power

```
[18]: ## Plot chemical power  $v(\phi_A - \phi_B)$ 
v = V0*VV/m #chemical flow
Phi = R*T*gamma
print(f'Phi: {Phi}')
PP_chem = Phi*v/P0 ## Normalised

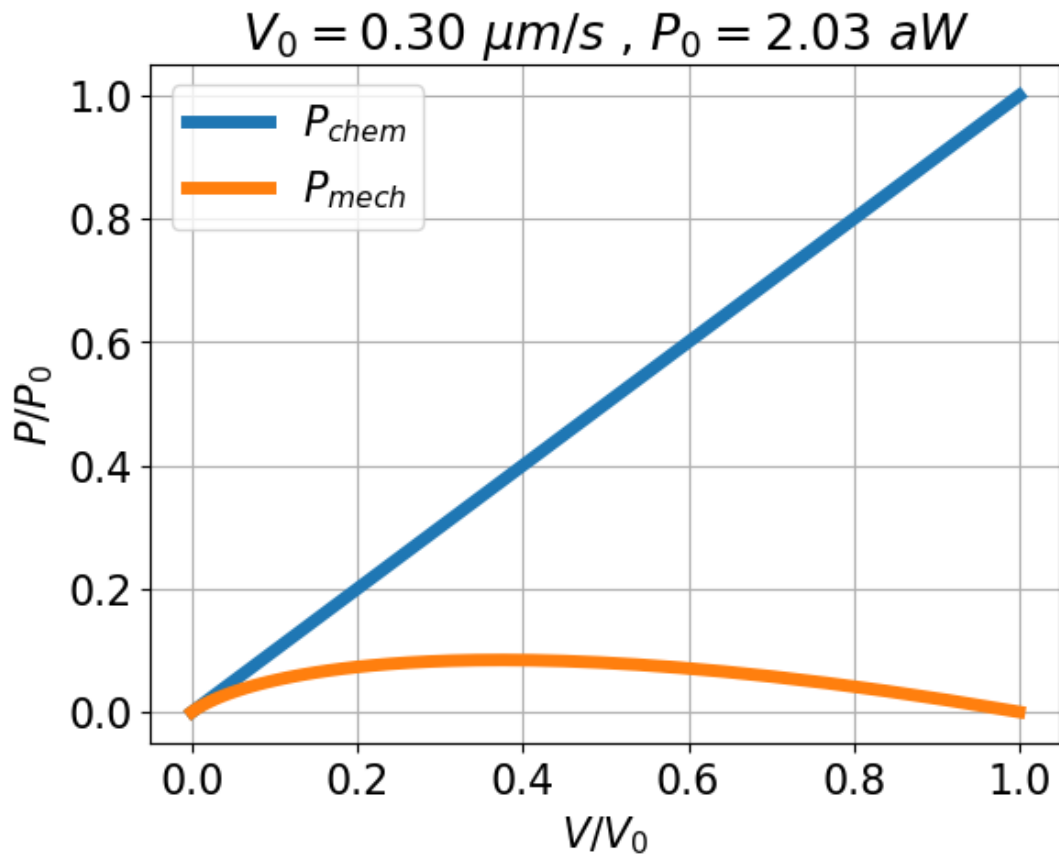
Phi_Re = Phi-m*FF*F0
PP_Re = Phi_Re*v/P0

plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $P_0 = {P0*1e18:0.2f}$~aW$')
plt.plot(FF,PP_chem,lw=lw,label='$P_{chem}$')
# plt.plot(FF,PP_Re,lw=lw,label='$P_{Re}$')
plt.plot(FF,PP,lw=lw,label='$P_{mech}$')
plt.legend()
plt.xlabel('$F/F_0$')
plt.ylabel('$P/P_0$')
plt.grid()
Savefig('FP')
```

Phi: 10973.337125073138



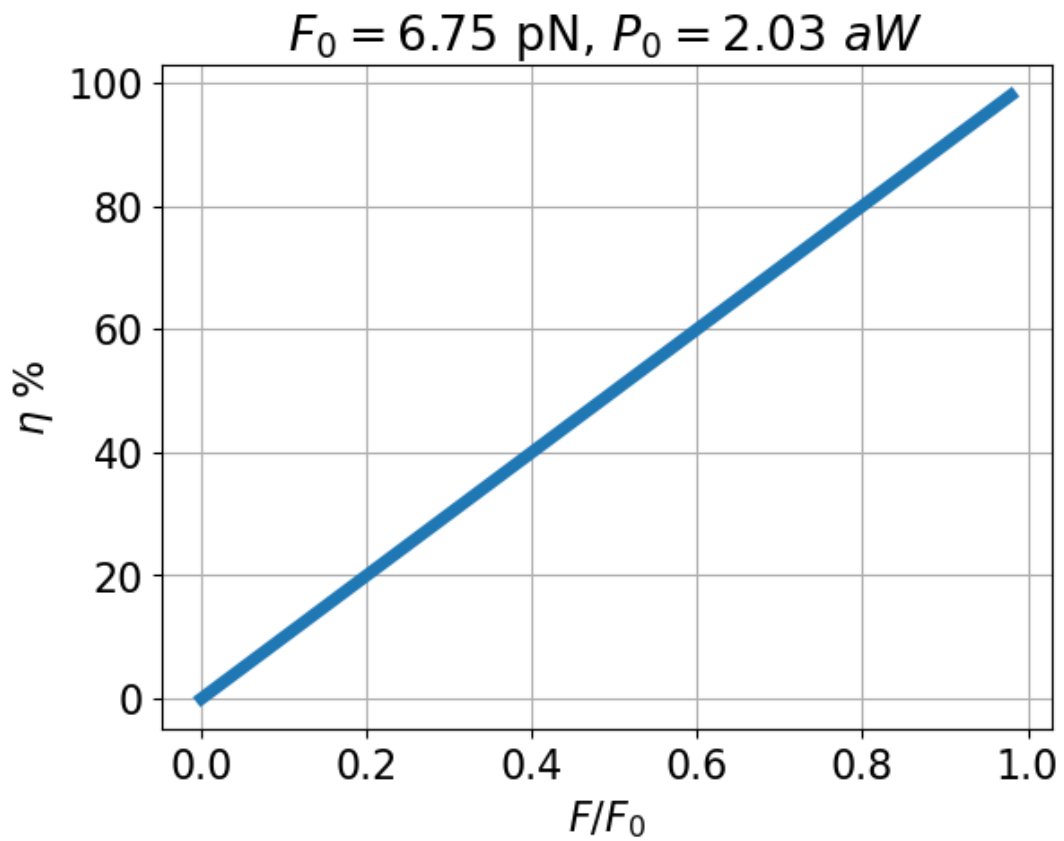
```
[19]: ## Redo plotted against V
plt.title(f'$V_0 = {V0*1e6:0.2f} \sim \mu \text{ m/s}$ , $P_0 = {P0*1e18:0.2f} \sim \text{aW}$')
plt.plot(VV, PP_chem, lw=lw, label='$P_{chem}$')
# plt.plot(VV, PP_Re, lw=lw, label='$P_{Re}$')
plt.plot(VV, PP, lw=lw, label='$P_{mech}$')
plt.legend()
plt.xlabel('$V/V_0$')
plt.ylabel('$P/P_0$')
plt.grid()
Savefig('VP')
```



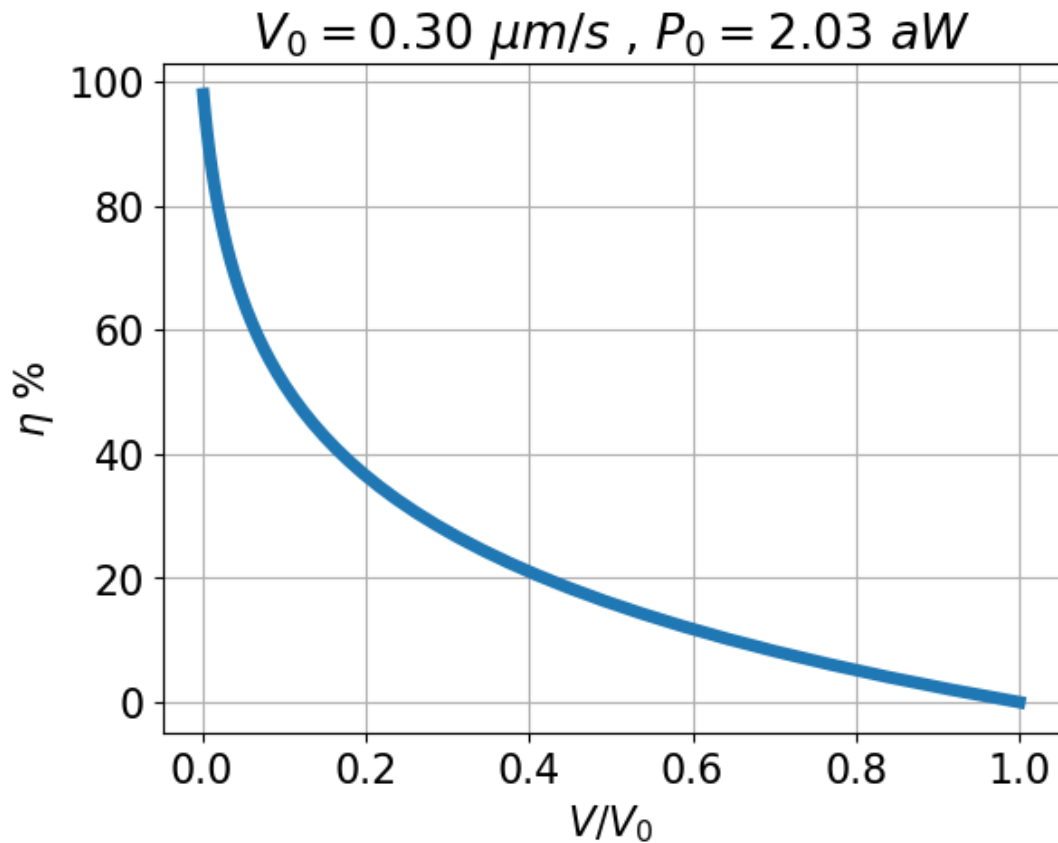
#### 4.6 Plot efficiency.

```
[20]: ## Efficiency (??)
eta = PP/PP_chem
plt.plot(FF,eta*100,lw=lw)
plt.xlabel('$F/F_0$')
plt.ylabel('$\eta$ %')
plt.grid()
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $P_0 = {P0*1e18:0.2f}$ aW$')
Savefig('Feta')
```

```
/tmp/ipykernel_87290/172306959.py:2: RuntimeWarning: invalid value encountered
in divide
eta = PP/PP_chem
```



```
[21]: ## Redo plotted against V
plt.plot(VV,eta*100,lw=lw)
plt.xlabel('$V/V_0$')
plt.ylabel('$\eta$ %')
plt.grid()
plt.title(f'$V_0 = \{V0*1e6:0.2f\} \sim \mu \text{ m/s}$ , $P_0 = \{P0*1e18:0.2f\} \sim \text{aW}$')
Savefig('Veta')
```



## 5 Case 2a: Rigid filament at angle $\theta$ from normal to membrane

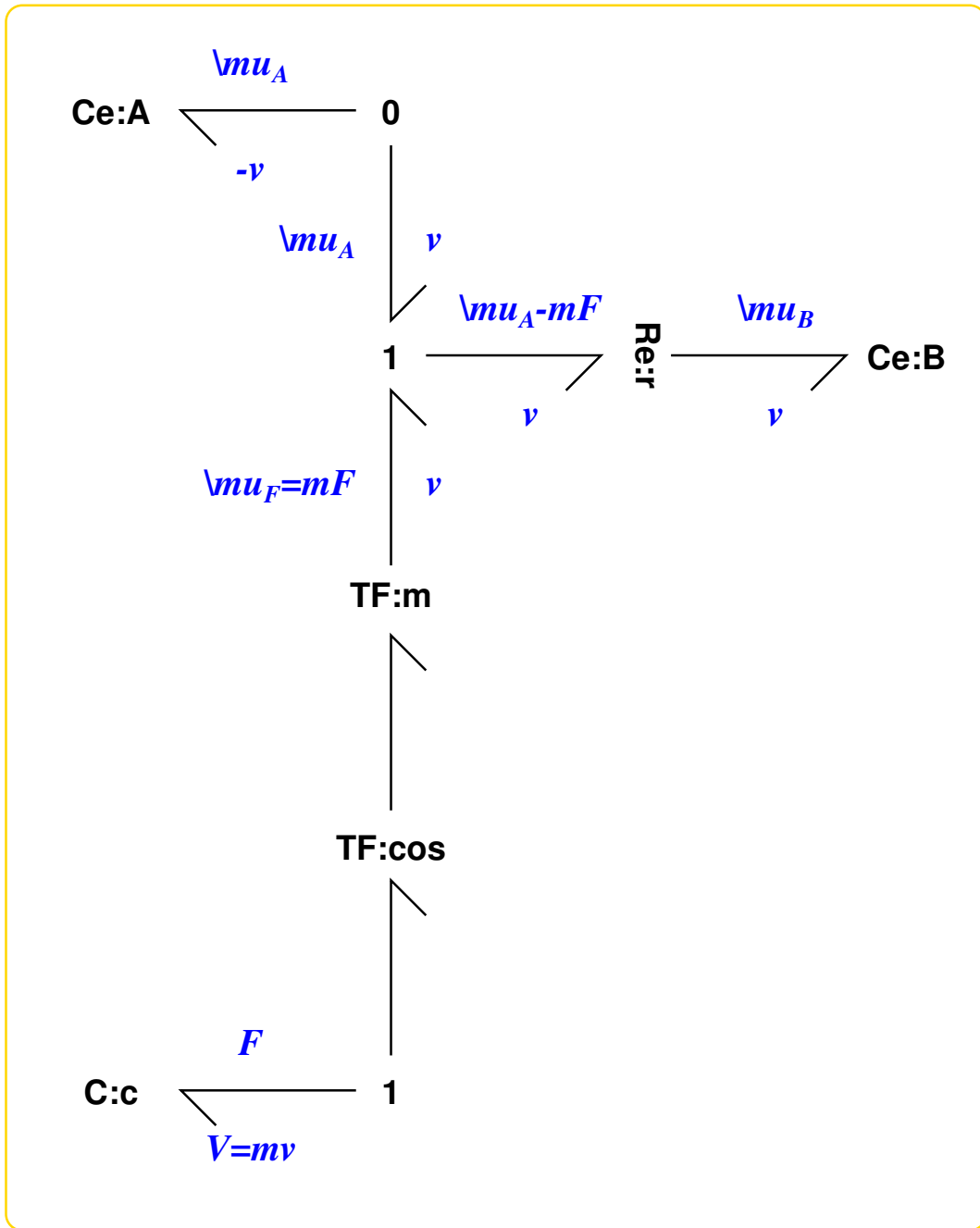
### 5.1 Bond graph model

At the moment: - this is not used in the computations. - experimental rewiring of parameters is used.

```
[22]: ## Set up simple model
imp.reload(sbg)
sbg.model('ActinRodTheta_abg.svg',parRename={'m_m':'m', 'm_cos':'cos(theta)'})
import ActinRodTheta_abg
imp.reload(ActinRodTheta_abg)
disp.SVG('ActinRodTheta_abg.svg')
```

```
TF cos
TF m
{'m_m': 'm', 'm_cos': 'cos(theta)'}
m_m
Replacing 'm_m' with 'm'
m_cos
Replacing 'm_cos' with 'cos(theta)'
```

[22]:



```
[23]: # ## Reset TF moduli
      # modulus('ActinRodTheta_abg',moduli={'m_m':'m', 'm_cos':'cos(theta)'})
      # import ActinRodTheta_abg_mod
```

```
[24]: imp.reload(ActinRodTheta_abg)
      model=ActinRodTheta_abg.model()
      model.constitutive_relations
```

```
[24]: [-K_A*cos(theta)*kappa_r*m*x_1*exp(-cos(theta)*m*x_0/(RT*c)) +
      K_B*cos(theta)*kappa_r*m*x_2 + dx_0,
      K_A*kappa_r*x_1*exp(-cos(theta)*m*x_0/(RT*c)) - K_B*kappa_r*x_2 + dx_1,
```



```
-K_A*kappa_r*x_1*exp(-cos(theta)*m*x_0/(RT*c)) + K_B*kappa_r*x_2 + dx_2]
```

## 5.2 Stoichiometry

```
[25]: ## Stoichiometry
s = st.stoich(ActinRodTheta_abg.
↳model(),linear=['c'],symbolic=True,quiet=quiet)
```

```
Computing N ...
Swapping Re:r for two Sf in ActinRodTheta
Done.
Computing K ...
Done.
Computing G ...
Done.
```

```
[26]: st.sprint(s,'species')
st.sprint(s,'N')
st.sprint(s,'Nf')
st.sprint(s,'Nr')#
st.sprint(s,'Z')
st.sprint(s,'D')
```

```
species:
['c', 'A', 'B']
N:
Matrix([[cos(theta)*m], [-1], [1]])
Nf:
Matrix([[ -cos(theta)*m], [1], [0]])
Nr:
Matrix([[0], [0], [1]])
Z:
[[-cos(theta)*m 0]
 [1 0]
 [0 1]]
D:
[[-1]
 [ 1]]
```

```
[27]: disp.Latex(st.sprintvl(s))
```

[27]:

$$v_r = \kappa_r \left( K_A x_A e^{-\frac{K_c \cos(\theta) m x_c}{V_N}} - K_B x_B \right) \quad (2)$$

```
[28]: disp.Latex(st.sprintl(s,'N'))
```

[28]:

$$N = \begin{pmatrix} \cos(\theta)m \\ -1 \\ 1 \end{pmatrix} \quad (3)$$

```
[29]: #disp.SVG('ActinRodTheta_abg.svg')
```

### 5.3 Optimal angle (for max velocity)

```
[30]: def optTheta(VV,Theta):

    V_max = np.max(VV)
    # print(V_max)
    for i,V in enumerate(VV):
        if V == V_max:
            # print(i,V)
            opt = Theta[i]

    return V_max,opt
```

### 5.4 Plot velocity-theta curves.

```
[31]: ## Incidence angle theta - stiff filament
## Plot curve V - theta
#FF = F0*np.linspace(0,1)
FFF = np.array([0.2,0.3,0.5,1,2])
Theta = (np.pi/2)*np.linspace(0,1)
Opt = []
for FF in FFF:
    VV = FVnormTheta(FF,gamma=gamma,theta=Theta)

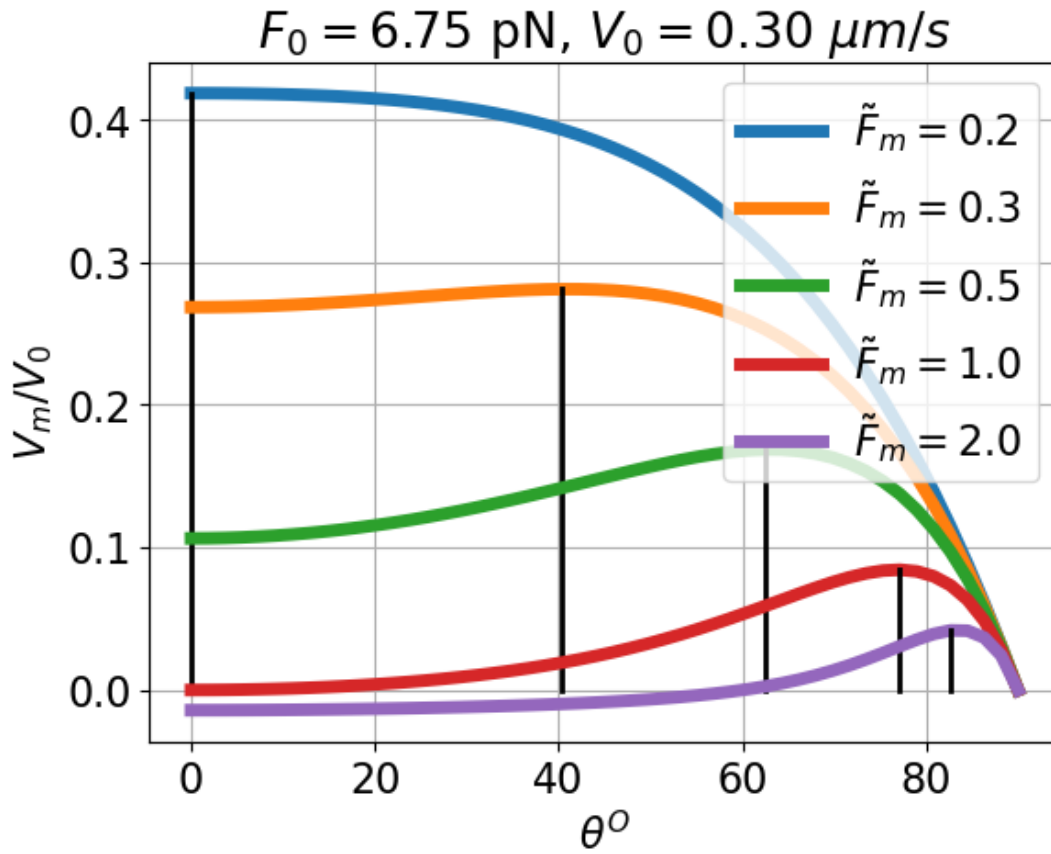
    label = f'$\\tilde F_m={FF:0.1f}$'
    plt.plot(Theta*(180/np.pi),VV,lw=lw,label=label)

    ## Optimum angle
    V_max,opt = optTheta(VV,Theta)
    Opt.append(opt)
    XX = np.array([opt,opt])*180/np.pi
    YY = np.array([0,V_max])
    # print(XX,YY)
    plt.plot(XX,YY,lw=2,color='black')
Opt = np.array(Opt)

## Save for later
Opt0 = Opt
FFF0 = FFF

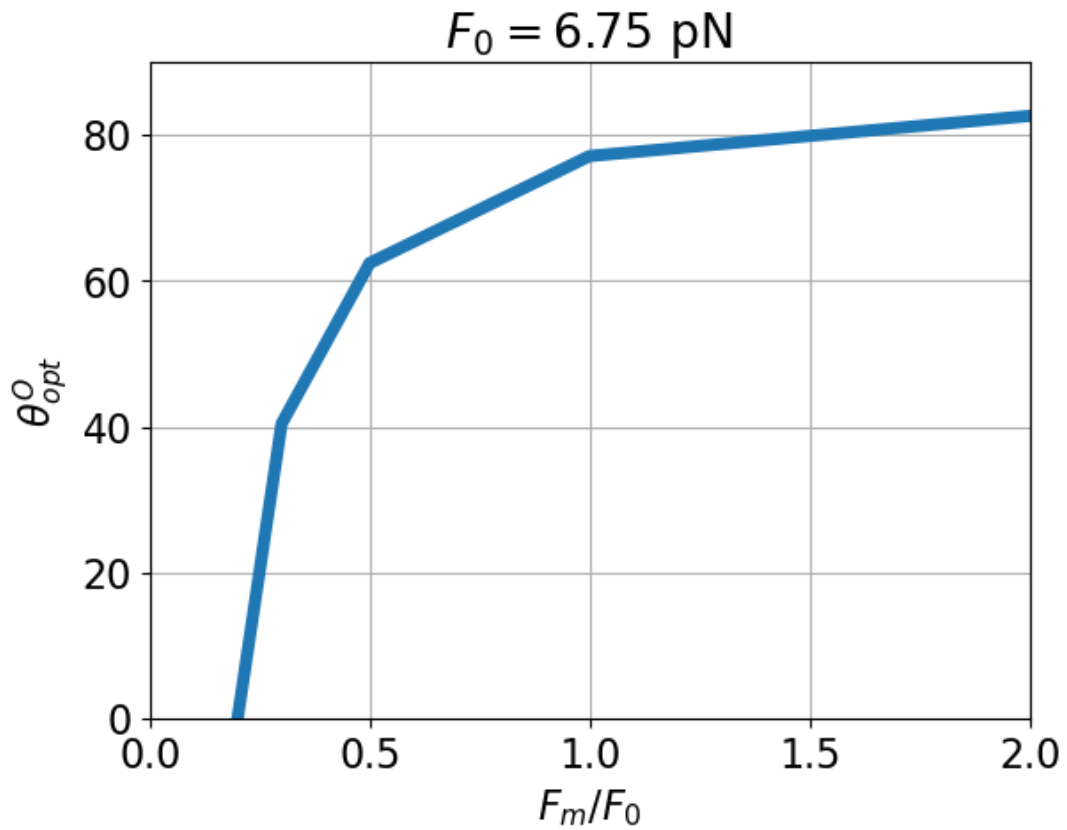
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$ ~\mu m/s$')
plt.xlabel('$\\theta^0$')
```

```
plt.ylabel('$V_m/V_0$')
plt.grid()
plt.legend()
Savefig('ThetaV_theta')
```



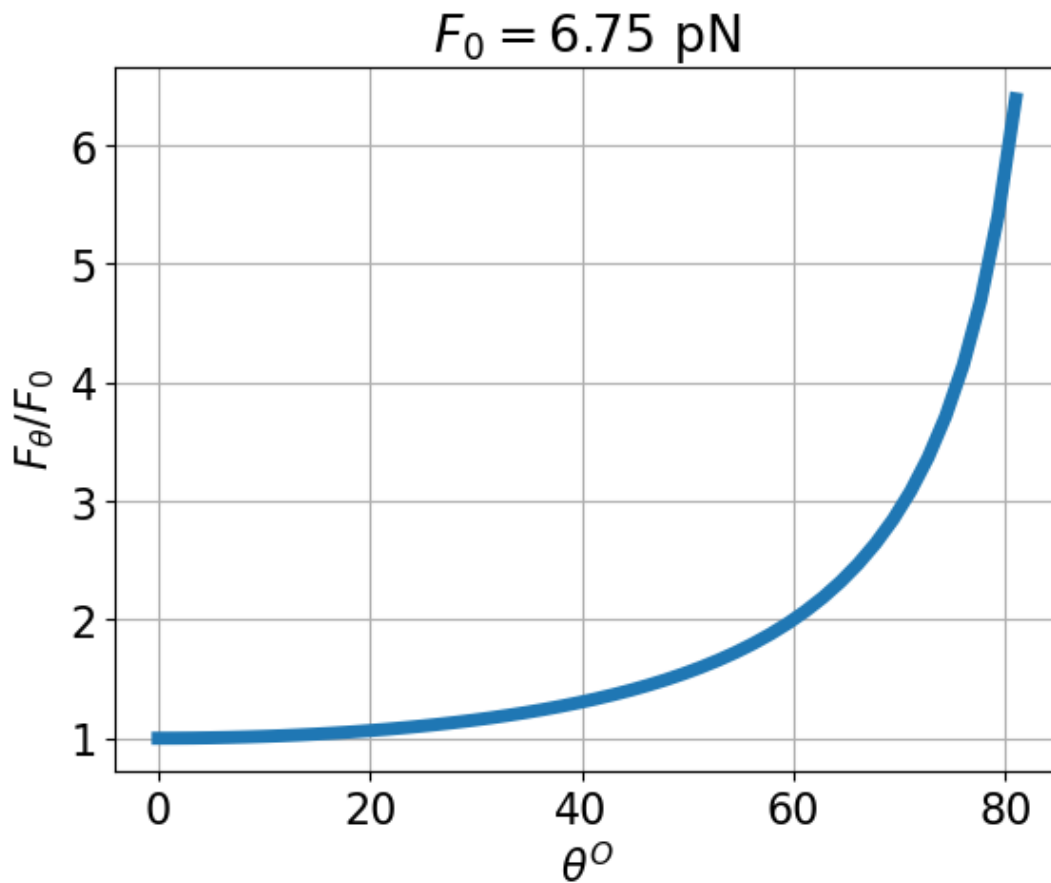
### 5.5 Plot optimal angle $\theta_{opt}$ .

```
[32]: ## Plot Theta_opt
plt.plot(FFF, Opt*180/pi, lw=lw)
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN')
plt.ylabel('$\\theta_{opt}^0$')
plt.xlabel('$F_m/F_0$')
plt.grid()
plt.ylim(0,90)
plt.xlim(0,max(FFF))
Savefig('ThetaOpt_theta')
```



## 5.6 Plot effective stall force $F_s$ .

```
[33]: ## Effective stall force
Theta = (np.pi/2)*np.linspace(0,0.9)
plt.plot(Theta*(180/np.pi), 1/np.cos(Theta),lw=lw)
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN')
plt.xlabel('$\\theta^0$')
plt.ylabel('$F_{\\theta}/F_0$')
plt.grid()
# plt.legend()
Savefig('ThetaFs_theta')
```



### 5.7 Plot velocity-force curve.

```
[34]: ## Incidence angle theta - stiff filament
      ## Plot curve V - F
      usingFs = False

      Theta = np.array([0,30,45,60,80])*pi/180
      for theta in Theta:
          label = f'$\\theta$={theta*180/pi:0.2f}'
          if usingFs:
              FF = np.linspace(0,1/costh)
          else:
              FF = np.linspace(0,1)

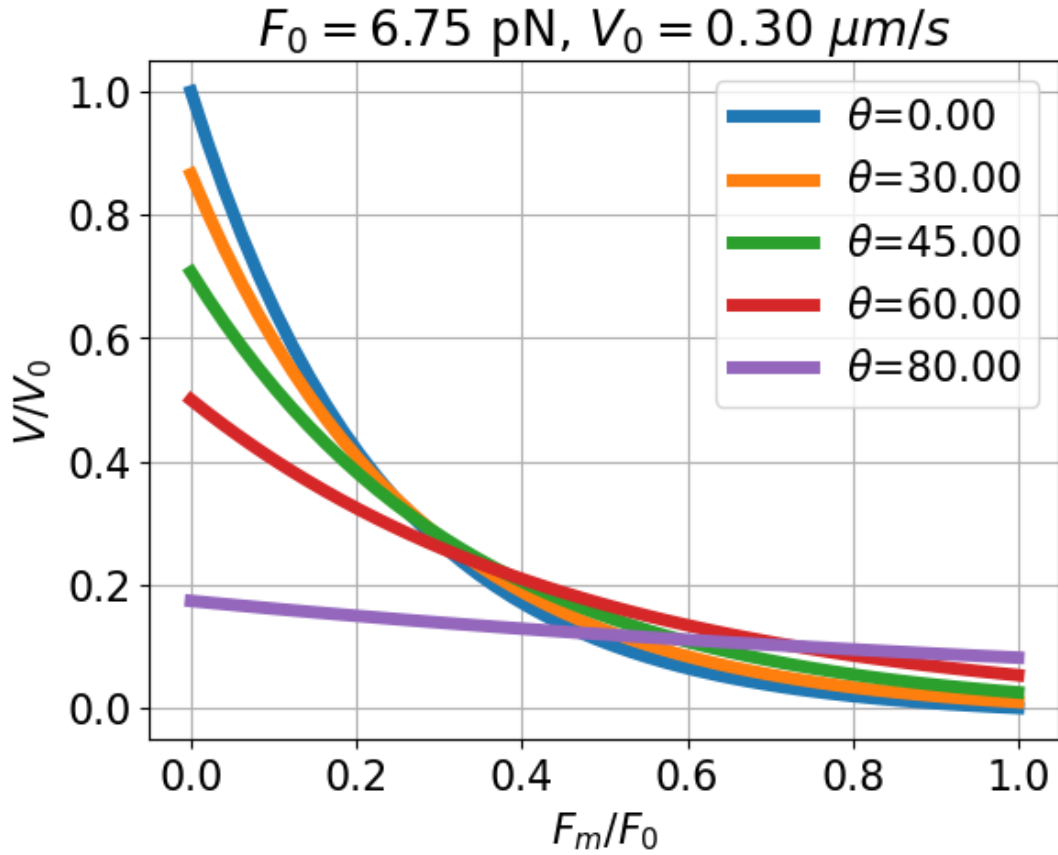
          VV = FVnormTheta(FF,gamma=gamma,theta=theta)
          if usingFs:
              plt.plot(FF*costh,VV,lw=lw,label=label)
          else:
              plt.plot(FF,VV,lw=lw,label=label)

      if usingFs:
```

```

        xlabel = '$F/F_s$'
    else:
        xlabel = '$F_m/F_0$'
    plt.xlabel(xlabel)
    plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$~\mu m/s$')
    plt.ylabel('$V/V_0$')
    plt.grid()
    plt.legend()
    Savefig('FV_theta')

```



## 5.8 Plot velocity-force-angle surface.

```

[35]: ## 3D plot.
from matplotlib import cm
FF = np.linspace(0,1,20)
Theta = (np.pi/2)*np.linspace(0,1,20)
FF,Theta = np.meshgrid(FF,Theta)
# costh = np.cos(Theta)
# VV = delta*costh*(alpha*np.exp(-gamma*FF*costh) -beta )/V0
# VV = FVnorm(FF*costh,gamma=gamma)*costh
VV = FVnormTheta(FF,gamma=gamma,theta=Theta)
# Plot the surface
fig, ax = plt.subplots(subplot_kw={"projection": "3d"})

```

```

surf = ax.plot_surface(FF, Theta*180/pi, VV, cmap=cm.coolwarm,
                      linewidth=0, antialiased=True)
ax.set_xlabel('$F_m/F_0$')
ax.set_ylabel(r'$\theta$')
ax.set_zlabel(r'$V_m/V_0$')
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$ ~\mu m/s, $\chi = \chi_0$')
plt.ylim(90,0)

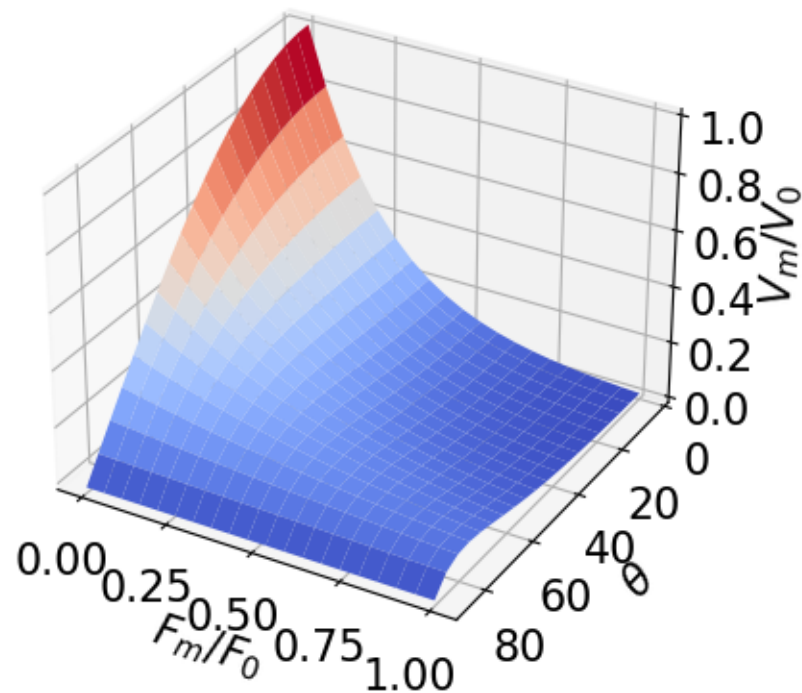
Savefig('surf')

# elev = 0
# azim = 0
# roll = 0
# ax.view_init(elev, azim, roll)
# Add a color bar which maps values to colors.
# fig.colorbar(surf, shrink=0.5, aspect=5)

# plt.zlabel('$V/V_0$')

```

$$F_0 = 6.75 \text{ pN}, V_0 = 0.30 \text{ } \mu\text{m/s}, \chi = 0$$



## 6 Case 2b: Flexible filament at angle $\theta$ from normal to membrane

### 6.1 Bond graph model

At the moment: - this is not used in the computations. - experimental rewiring of parameters is used.

```
[36]: ## Set up simple model
parRename = {'m_m': 'm', 'm_cos': 'cos(theta_0+eps)'}
parRename['m_Lsin'] = 'Lsin(theta_0)'
sbg.model('ActinRodThetaFlex_abg.svg', parRename=parRename)
import ActinRodThetaFlex_abg
imp.reload(ActinRodThetaFlex_abg)
disp.SVG('ActinRodThetaFlex_abg.svg')
```

TF Lsin

TF cos

TF m

{'m\_m': 'm', 'm\_cos': 'cos(theta\_0+eps)', 'm\_Lsin': 'Lsin(theta\_0)'}

m\_m

Replacing 'm\_m' with 'm'

m\_cos

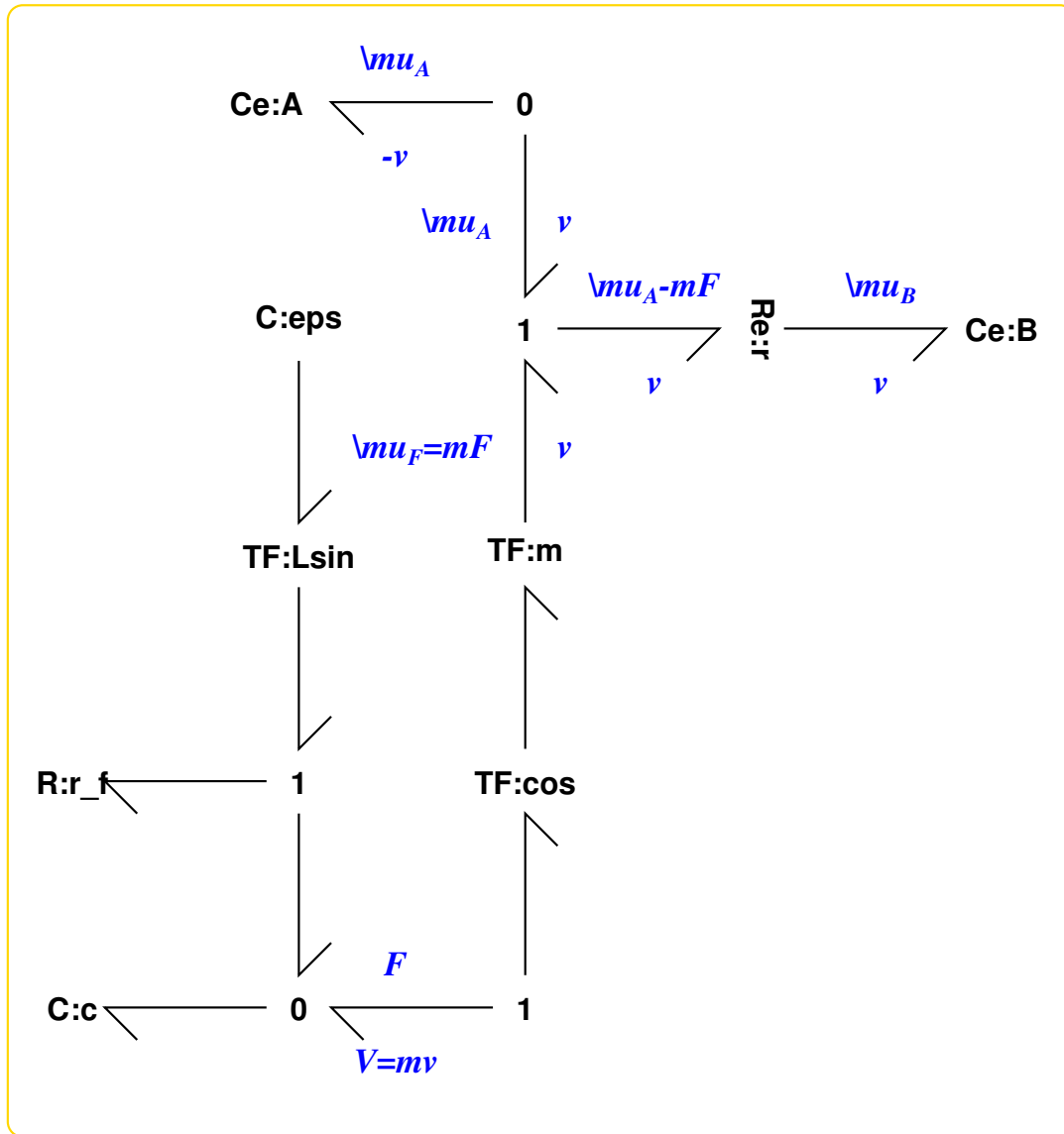
Replacing 'm\_cos' with 'cos(theta\_0+eps)'

m\_Lsin

Replacing 'm\_Lsin' with 'Lsin(theta\_0)'

[36]:





```
[37]: imp.reload(ActinRodThetaFlex_abg)
model=ActinRodThetaFlex_abg.model()
print(model.constitutive_relations)
print(len(model.constitutive_relations))

for i,cr in enumerate(model.constitutive_relations):
    print(i,cr)

print(model.state_vars)
```

```
[-K_A*cos(theta_0+eps)*kappa_r*m*x_2*exp(-cos(theta_0+eps)*m*x_0/(RT*c)) +
K_B*cos(theta_0+eps)*kappa_r*m*x_3 - Lsin(theta_0)*x_1/(eps*r_f) + dx_0 +
x_0/(c*r_f), Lsin(theta_0)**2*x_1/(eps*r_f) - Lsin(theta_0)*x_0/(c*r_f) + dx_1,
K_A*kappa_r*x_2*exp(-cos(theta_0+eps)*m*x_0/(RT*c)) - K_B*kappa_r*x_3 + dx_2,
-K_A*kappa_r*x_2*exp(-cos(theta_0+eps)*m*x_0/(RT*c)) + K_B*kappa_r*x_3 + dx_3]
```

4

```

0 -K_A*cos(theta_0+eps)*kappa_r*m*x_2*exp(-cos(theta_0+eps)*m*x_0/(RT*c)) +
K_B*cos(theta_0+eps)*kappa_r*m*x_3 - Lsin(theta_0)*x_1/(eps*r_f) + dx_0 +
x_0/(c*r_f)
1 Lsin(theta_0)**2*x_1/(eps*r_f) - Lsin(theta_0)*x_0/(c*r_f) + dx_1
2 K_A*kappa_r*x_2*exp(-cos(theta_0+eps)*m*x_0/(RT*c)) - K_B*kappa_r*x_3 + dx_2
3 -K_A*kappa_r*x_2*exp(-cos(theta_0+eps)*m*x_0/(RT*c)) + K_B*kappa_r*x_3 + dx_3
{'x_0': (C: c, 'q_0'), 'x_1': (C: eps, 'q_0'), 'x_2': (C: A, 'q_0'), 'x_3': (C:
B, 'q_0')}

```

## 6.2 Stoichiometry

```

[38]: ## Stoichiometry
imp.reload(st)
imp.reload(ActinRodThetaFlex_abg)
s = st.stoich(ActinRodThetaFlex_abg.
→model(),linear=['c','eps','r_f'],symbolic=True,quiet=quiet)

```

```

Computing N ...
Swapping Re:r_f for two Sf in ActinRodThetaFlex
No reverse component
Swapping Re:r for two Sf in ActinRodThetaFlex
Done.
Computing K ...
Done.
Computing G ...
Done.

```

```

[39]: st.sprint(s,'species')
st.sprint(s,'N')
st.sprint(s,'Nf')
st.sprint(s,'Nr')#
st.sprint(s,'Z')
st.sprint(s,'D')

```

```

species:
['c', 'eps', 'A', 'B']
N:
Matrix([[1, cos(theta_0+eps)*m], [-Lsin(theta_0), 0], [0, -1], [0, 1]])
Nf:
Matrix([[ -1, -cos(theta_0+eps)*m], [Lsin(theta_0), 0], [0, 1], [0, 0]])
Nr:
Matrix([[0, 0], [0, 0], [0, 0], [0, 1]])
Z:
[[-1 -cos(theta_0+eps)*m 0 0]
 [Lsin(theta_0) 0 0 0]
 [0 1 0 0]
 [0 0 0 1]]
D:
[[-1 0]
 [ 0 -1]
 [ 1 0]
 [ 0 1]]

```

```
[40]: disp.Latex(st.sprintvl(s))
```

```
[40]:
```

$$v_{rf} = \kappa_{rf} (-K_c x_c + K_{eps} L \sin(\theta_0) x_{eps}) \quad (4)$$

$$v_r = \kappa_r \left( K_A x_A e^{-\frac{K_c \cos(\theta_0 + \epsilon) m x_c}{V_N}} - K_B x_B \right) \quad (5)$$

### 6.3 Parameters

```
[41]: ## Flexible rod: spring at root
# chi = 0.3 # Compliance * length * F0
useTan = False
# print(f'cl = {chi} rad = {chi*180/pi:.1f} deg')
```

### 6.4 Compute deviation angle $\epsilon = \theta - \theta_0$

### 6.5 Plot velocity-angle curves.

```
[42]: ## Incidence angle theta - flexible filament
## Plot curve V - theta
#FF = F0*np.linspace(0,1)
FFF = np.array([0.2,0.3,0.5,1])
Theta0 = (np.pi/2)*np.linspace(0,0.9)
Opt = []
Eps = {}
Err = {}
for FF in FFF:
#     label = f'{F0*ff*1e12:0.2f} pN'
    label = f'$F_m=${FF:0.1f}'
#     costh0 = np.cos(Theta0)
#     sinth0 = np.sin(Theta0)
#     eps = chi*FF*sinth0/(1-chi*FF*costh0)
#     eps = epsilon(FF,Theta0,chi=chi,useTan=useTan)

    VV,eps = FVnormFlex(FF,gamma=gamma,theta0=Theta0,chi=chi,useTan=useTan)

    Eps[FF] = eps
#     Theta = Theta0 + eps
#     costh = np.cos(Theta)

    ## Sanity check
    err = eps - chi*FF*np.sin(Theta0+eps)
    Err[FF] = err

#     VV = delta*costh*( alpha*np.exp((-m/(R*T))*FF*costh) -beta )
#     VV = delta*costh*(alpha*np.exp(-gamma*FF*costh) -beta )/V0
#     VV = FVnorm(FF*costh,gamma=gamma)*costh

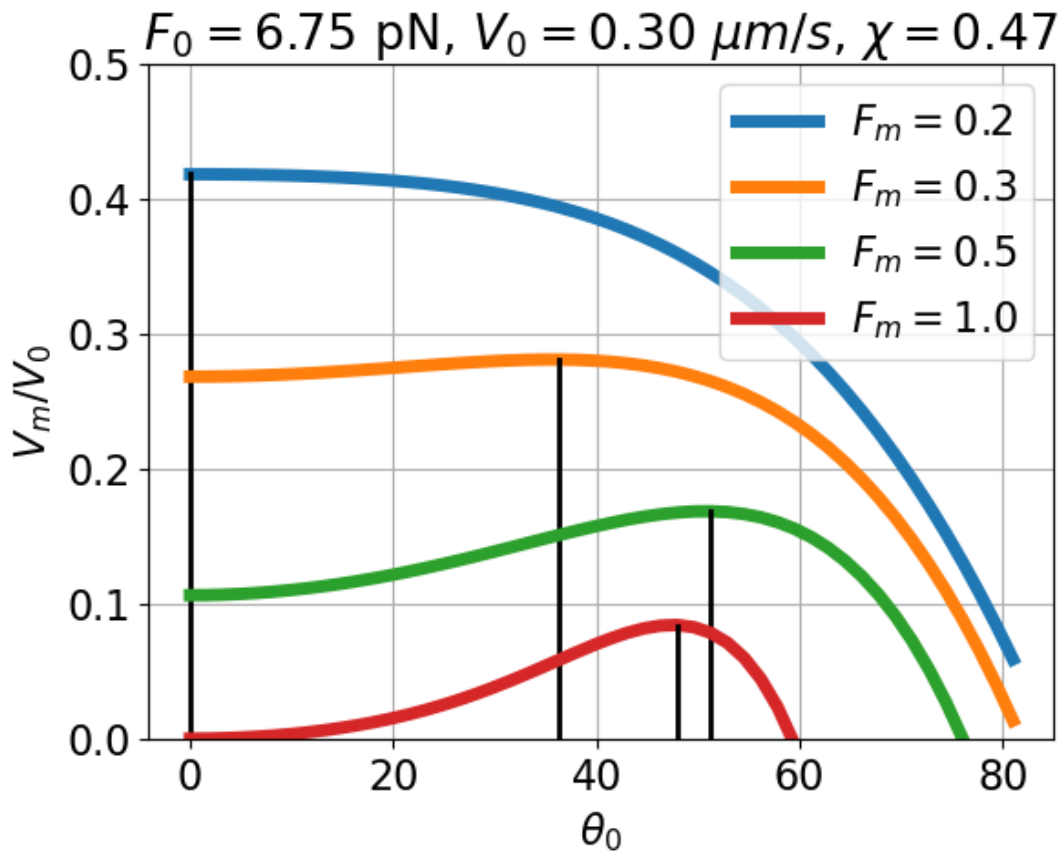
plt.plot(Theta0*(180/np.pi),VV,lw=lw,label=label)
```

```

## Optimum angle
V_max,opt = optTheta(VV,Theta0)
Opt.append(opt)
XX = np.array([opt,opt])*180/np.pi
YY = np.array([0,V_max])
# print(XX,YY)
plt.plot(XX,YY,lw=2,color='black')
Opt = np.array(Opt)
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$ ~\mu m/s$, $\chi = \chi_{\perp}$  

→ {chi:0.2f}$')
plt.xlabel('$\theta_0$')
plt.ylabel('$V_m/V_0$')
plt.grid()
plt.legend()
plt.ylim(bottom=0,top=0.5)
Savefig('ThetaV_flex')

```



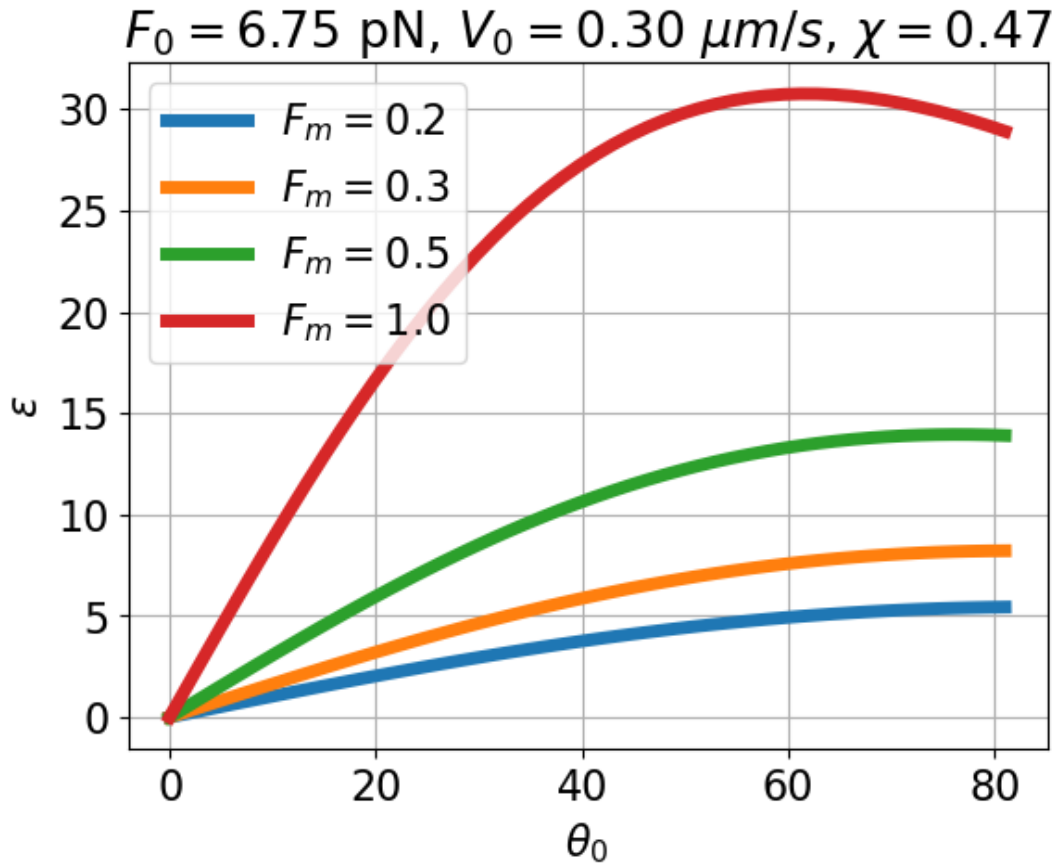
## 6.6 Plot deviation angle-angle ( $\epsilon - \theta_0$ ) curves.

```

[43]: ## PLOT Epsilon = Theta-Theta0
for FF in Eps.keys():
    label = f'$F_m=${FF:0.1f}$'
    plt.plot(Theta0*(180/np.pi),Eps[FF]*180/pi,lw=1w,label=label)

```

```
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$~\mu m/s$, $\chi = \chi_{\text{c}}$')
plt.xlabel('$\theta_0$')
plt.ylabel('$\epsilon$')
plt.grid()
plt.legend()
Savefig('eps_flex')
```

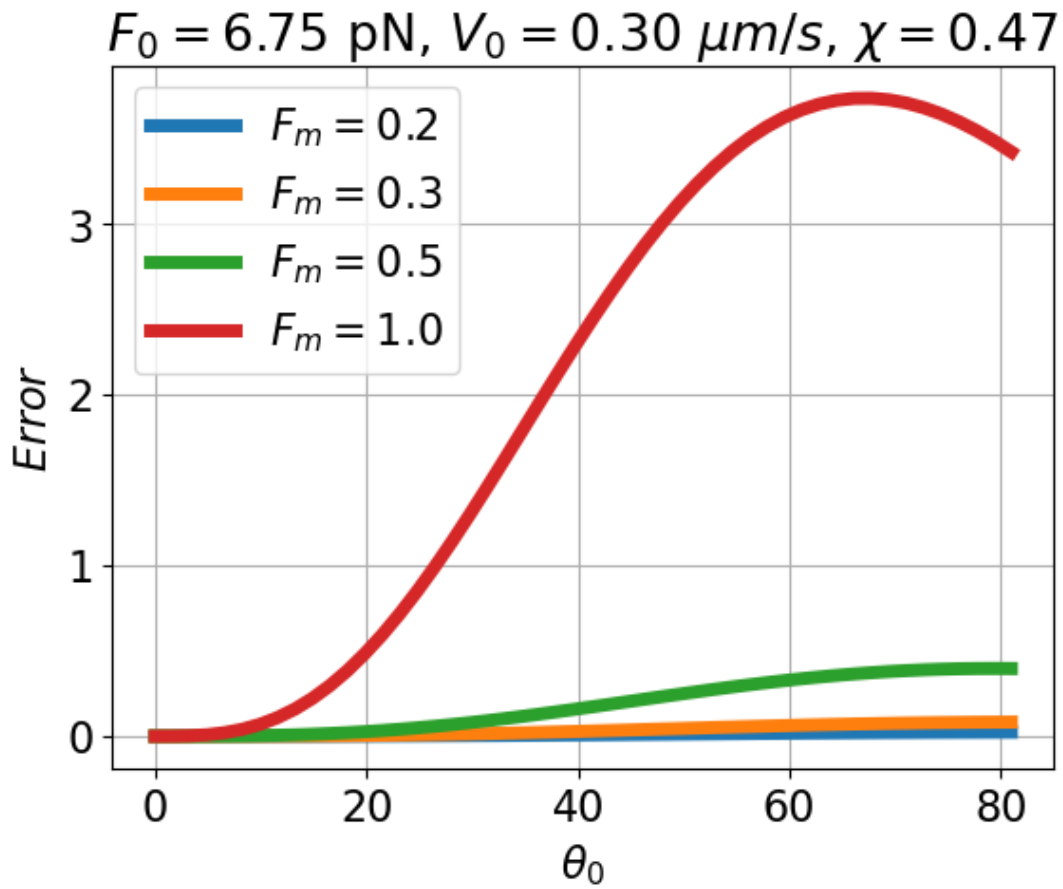


## 6.7 Plot $\epsilon$ error

```
[44]: ## Plot Epsilon error
for FF in Err.keys():
    label = f'$F_m = {FF:0.1f}$'
    plt.plot(Theta0*(180/np.pi), Err[FF]*180/pi, lw=lw, label=label)

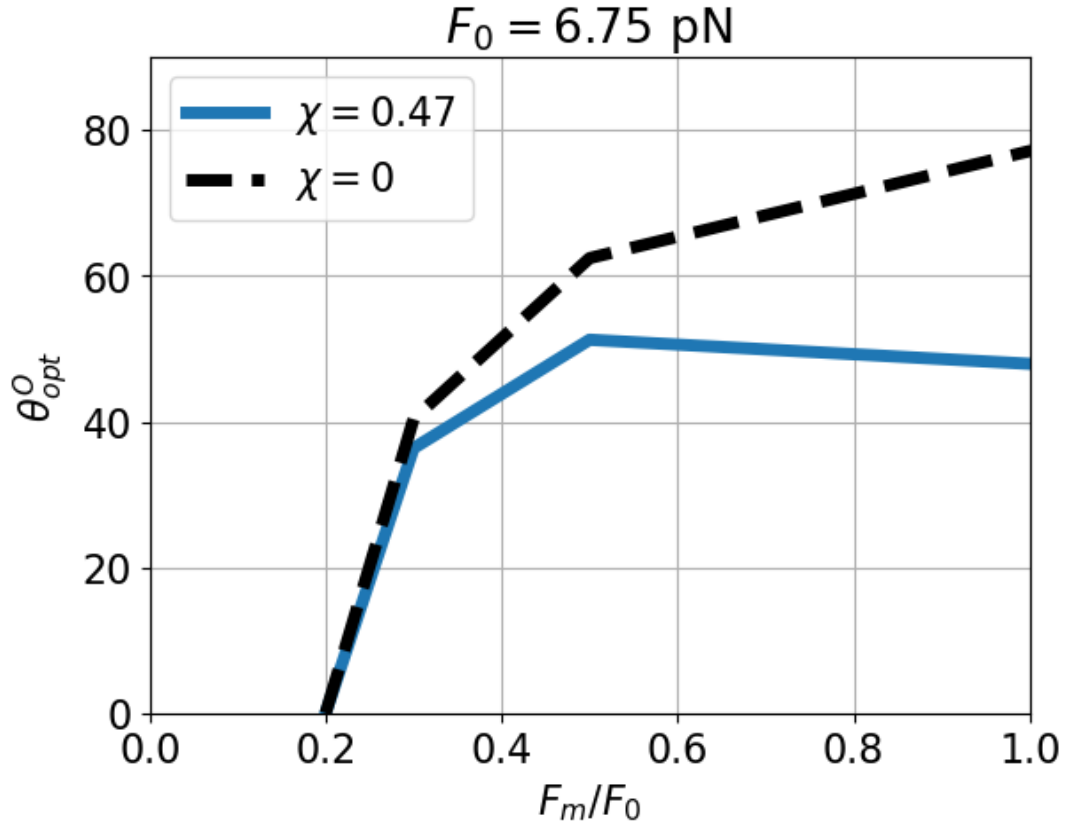
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$~\mu m/s$, $\chi = \chi_{\text{c}}$')
plt.xlabel('$\theta_0$')
plt.ylabel('$Error$')
plt.grid()
plt.legend()
```

```
Savefig('err_flex')
```



## 6.8 Plot optimal angle $\theta_{opt}$ .

```
[45]: ## Plot Theta_opt
plt.plot(FFF,Opt*180/pi,lw=lw,label=f'$\\chi = {chi:0.2f}$')
plt.plot(FFF0,Opt0*180/pi,lw=lw,ls='dashed',color='black',label='$\\chi=0$')
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN')
plt.ylabel('$\\theta_{opt}^0$')
plt.xlabel('$F_m/F_0$')
plt.grid()
plt.ylim(0,90)
plt.xlim(0,max(FFF))
plt.legend()
Savefig('ThetaOpt_flex')
```



## 6.9 Plot velocity-force curves - vary theta

```
[46]: ## Incidence angle theta - flexible filament
      ## Plot curve V - F

      usingFs=False

      THETA0 = np.array([0,45,60,70])*pi/180
      Opt = []
      Eps = {}
      Err = {}

      for Theta0 in THETA0:
          label = f'$\\theta_0=${Theta0*(180/pi):2.0f}$'
          costh0 = np.cos(Theta0)
          sinth0 = np.sin(Theta0)
          F_crit = 1/(chi*costh0)
          # print(F_crit)
          if usingFs:
              FF = np.linspace(0,1/costh0)
          else:
              FF = np.linspace(0,1.2)
```

```

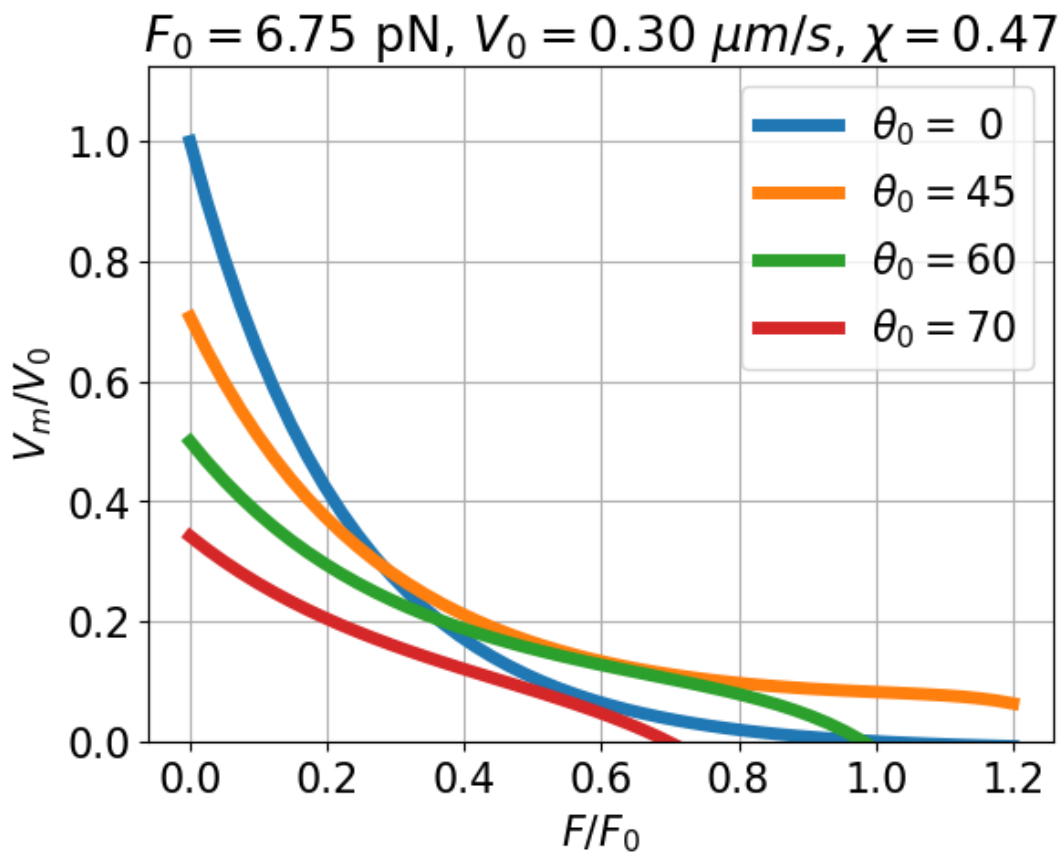
VV,eps = FVnormFlex(FF,gamma=gamma,theta0=Theta0,chi=chi,useTan=useTan)

## Sanity check
err = eps - chi*FF*np.sin(Theta0+eps)

if usingFs:
    plt.plot(FF*costh0,VV,lw=lw,label=label)
else:
    plt.plot(FF,VV,lw=lw,label=label)

if usingFs:
    xlabel = '$F/F_s$'
else:
    xlabel = '$F/F_0$'
plt.xlabel(xlabel)
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$ ~\mu m/s$, \chi = {chi:0.2f}$')
plt.ylabel('$V_m/V_0$')
plt.grid()
plt.legend()
plt.ylim(bottom=0)
Savefig('FV_flex')

```





## 6.10 Plot velocity-force curves - vary chi

```
[47]: ## Incidence angle theta - flexible filament
      ## Plot curve V - F

      usingFs=True

      Chi = np.array([0,chi,1])

      Eps = {}
      Err = {}
      FFF = {}

      Theta0= pi/3
      # Theta0 = pi/6

      for ch in Chi:

          costh0 = np.cos(Theta0)
          sinth0 = np.sin(Theta0)
          F_crit = 1/(ch*costh0)
          # print(chi,costh0,F_crit)
          # if usingFs:
          #     FF = np.linspace(0,1/costh0)
          # else:
          #     FF = np.linspace(0,2)

          maxFF = min(2.5,0.5*F_crit)
          # print(maxFF)
          FF = np.linspace(0,maxFF)
          VV,eps = FVnormFlex(FF,gamma=gamma,theta0=Theta0,chi=ch,useTan=useTan)

          ## Sanity check
          err = eps - ch*FF*np.sin(Theta0+eps)

          Eps[ch] = eps
          Err[ch] = err
          FFF[ch] = FF

          label = f'$\\chi={ch:.2f}$'
          # label += f' ({F_crit:0.1f})'
          #

          if usingFs:
              plt.plot(FF*costh0,VV,lw=lw,label=label)
          else:
              plt.plot(FF,VV,lw=lw,label=label)

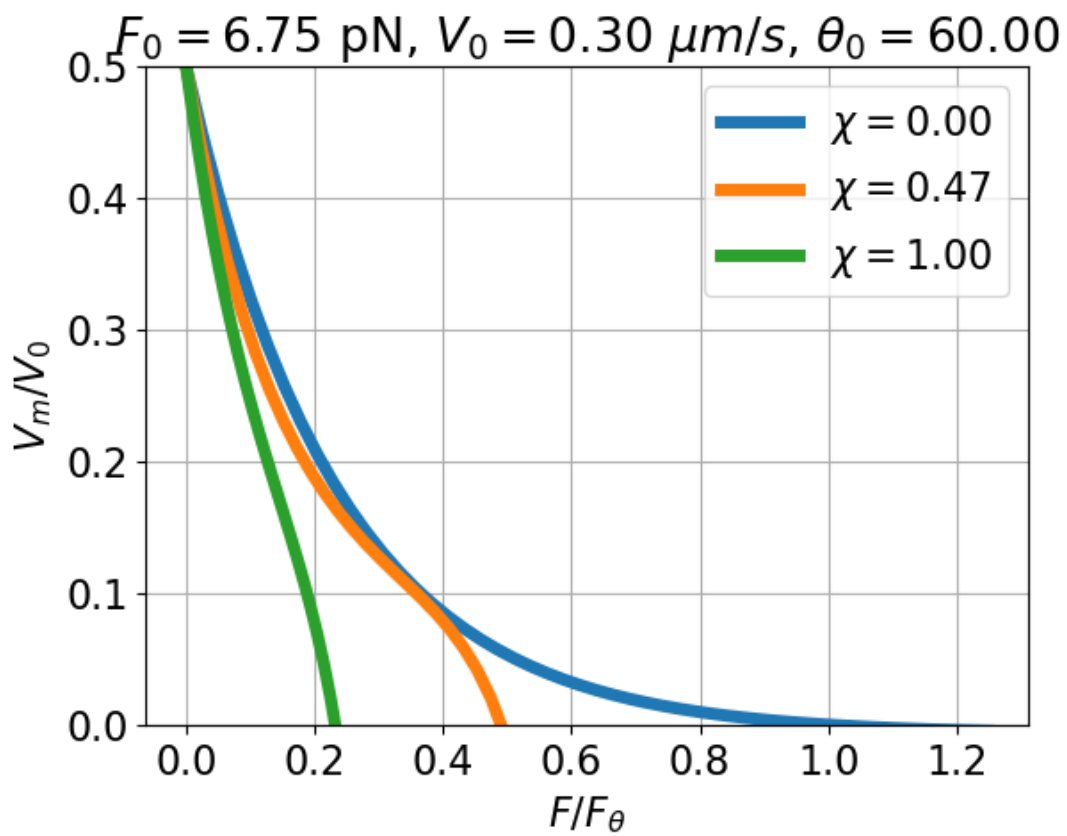
          # plt.plot(FF,eps*180/pi,lw=lw,label=label)
      if usingFs:
          xlabel = '$F/F_\\theta$'
```

```

else:
    xlabel = '$F/F_0$'
    plt.xlabel(xlabel)
    plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$ ~\mu m/s$, \theta_0 = {Theta0*180/pi:0.2f}$')
    plt.ylabel('$V_m/V_0$')
    plt.grid()
    plt.legend()
    plt.ylim(bottom=0,top=max(VV))
    Savefig('FVchi_flex')

```

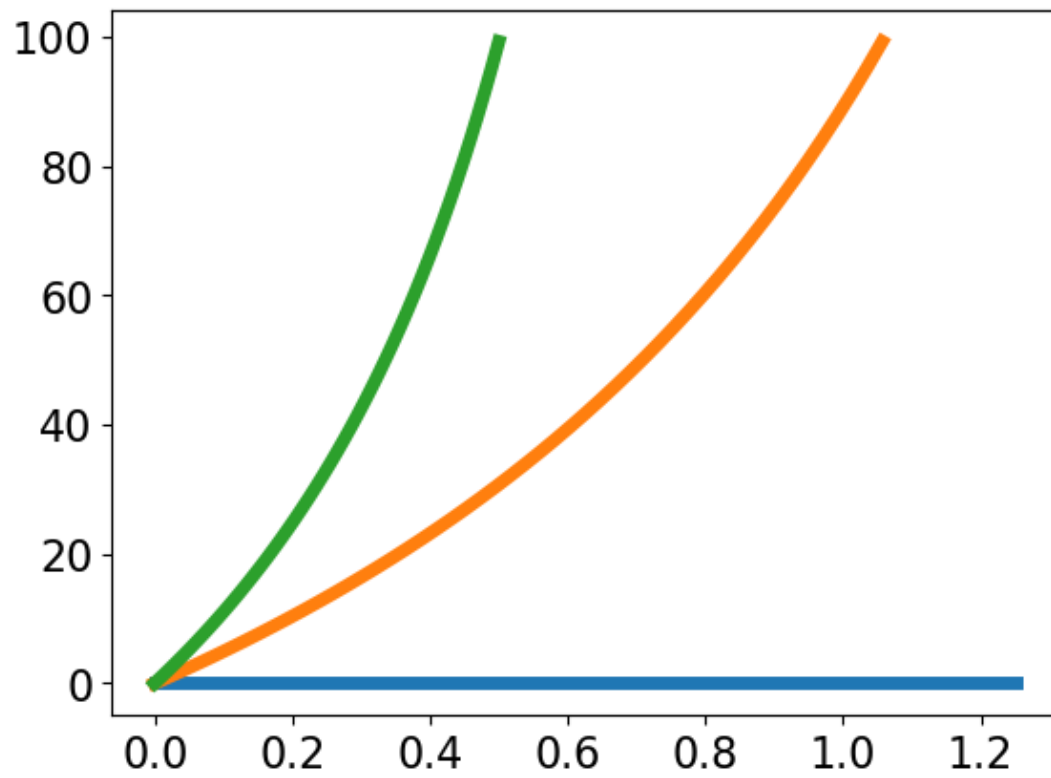
/tmp/ipykernel\_87290/3783813117.py:19: RuntimeWarning: divide by zero encountered in scalar divide  
 F\_crit = 1/(ch\*costh0)



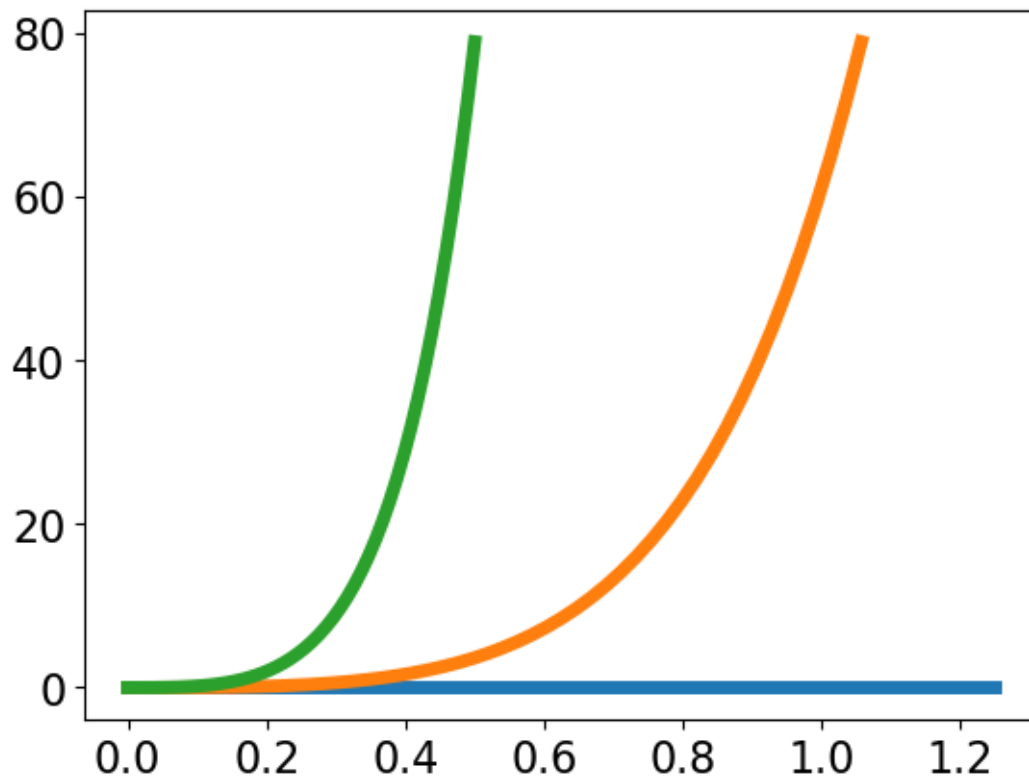
```

[48]: ## Plot eps.
      for ch in Eps.keys():
          plt.plot(FFF[ch]*costh0,Eps[ch]*180/pi,lw=1w)

```



```
[49]: ## Plot error
      for ch in Eps.keys():
          plt.plot(FFF[ch]*costh0,Err[ch]*180/pi,lw=1w)
```



```
[50]: print(chi)
```

```
0.4730426877097931
```

### 6.11 Plot velocity-force-angle surface.

```
[51]: ## 3D plot.

from matplotlib import cm
FF = np.linspace(0,1,20)
Theta0 = ((80/90)*np.pi/2)*np.linspace(0,1,20)
FF,Theta0 = np.meshgrid(FF,Theta0)

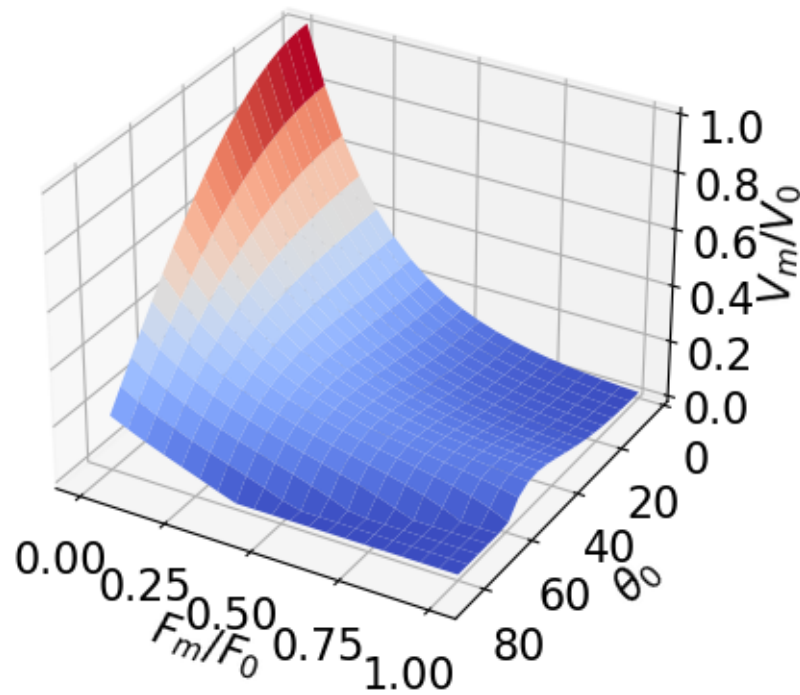
VV,eps = FVnormFlex(FF,gamma=gamma,theta0=Theta0,chi=chi,useTan=useTan)

## Clip at zero
VV_clip = np.clip(VV,0,None)

# Plot the clipped surface
fig, ax = plt.subplots(subplot_kw={"projection": "3d"})
surf = ax.plot_surface(FF, Theta0*180/pi, VV_clip, cmap=cm.coolwarm,
                      linewidth=0, antialiased=True)
ax.set_xlabel('$F_m/F_0$')
ax.set_ylabel(r'$\theta_0$')
ax.set_zlabel(r'$V_m/V_0$')
```

```
plt.ylim(90,0)
plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN, $V_0 = {V0*1e6:0.2f}$~\mu m/s$, $\chi =_{\square}$
    ↳{chi:0.2f}$')
Savefig('surf_flex')
```

$$F_0 = 6.75 \text{ pN}, V_0 = 0.30 \text{ } \mu\text{m/s}, \chi = 0.47$$

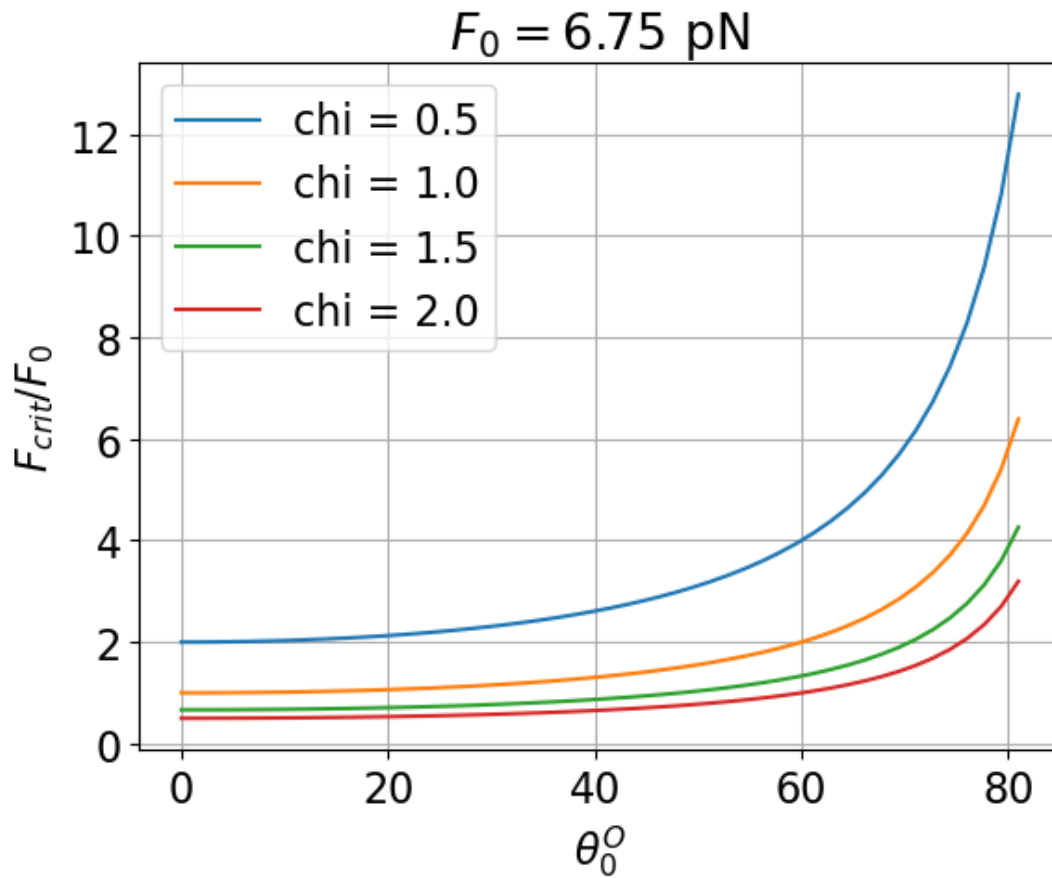


## 6.12 Singular value of $F/F_0$

```
[52]: ## Singular value of F/F0
CL = np.linspace(0.5,2,4) # Compliance
# CL = [2]
for ch in CL:
    Theta0 = (np.pi/2)*np.linspace(0,0.9)
    F_crit = 1/(ch*np.cos(Theta0))
    # print(F_crit)
    label = f'chi = {ch}'
    plt.plot((180/pi)*Theta0,F_crit,label=label)

plt.title(f'$F_0 = {F0*1e12:0.2f}$ pN')
plt.xlabel('$\\theta_0$')
plt.ylabel('$F_{crit}/F_0$')
plt.grid()
# plt.ylim(0,90)
# plt.xlim(0,max(FFF))
```

```
plt.legend()
Savefig('F_crit_flex')
```



### 6.13 Numerical values from MolOst96

```
[53]: ## Numerical values from MolOst96
# lamb = 1e-6
LL = np.linspace(30,150)*1e-9 # 30-150 nm
c = LL/(3*k_B*T*lamb)
c1 = 1/(3*k_B*T*lamb)
c = c1*LL

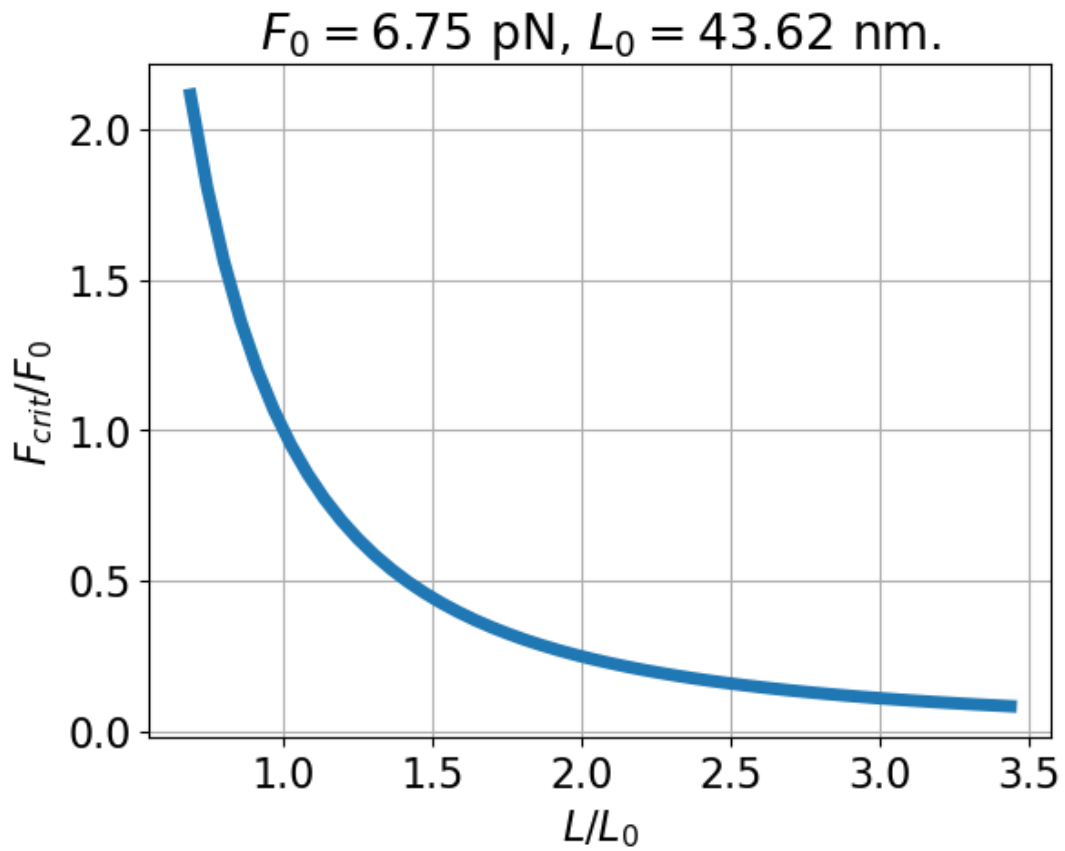
L0 = np.sqrt(1/(c1*F0))

## Corresponding values of chi
Chi = LL*LL*F0/(3*k_B*T*lamb)
F_crit = 1/Chi

title = f'$F_0 = {F0*1e12:0.2f}$ pN, $L_0 = {L0*1e9:0.2f}$ nm.'
plt.title(title)
print(title)
plt.plot(LL/L0,F_crit,lw=lw)
```

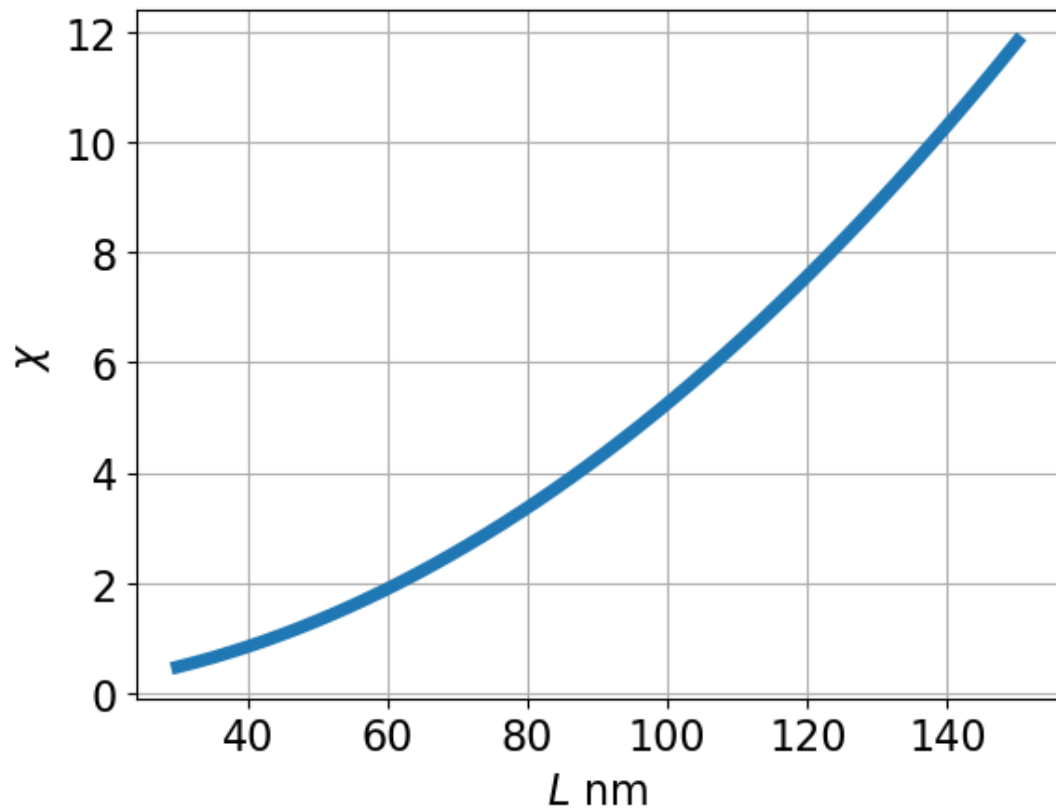
```
plt.ylabel('$F_{crit}/F_0$ ')
plt.xlabel('$L/L_0$')
plt.grid()
Savefig('F_crit')
```

$F_0 = 6.75$  pN,  $L_0 = 43.62$  nm.



```
[54]: # Plot chi as well
chi_min = min(Chi)
print(f'min chi: {chi_min:0.2f}')
plt.plot(LL/1e-9,Chi,lw=lw)
plt.ylabel('$\\chi$ ')
plt.xlabel('$L$ nm')
plt.grid()
Savefig('chi')
```

min chi: 0.47



## 6.14 Experimental results from LiBieWei22

```
[55]: dat = np.array(
    [
        [10,6.31,1.03],
        [26,5.69,0.85],
        [51,4.73,0.80],
        [102,3.40,0.74],
        [153,2.51,0.55],
        [255,1.75,0.42],
        [383,1.39,0.36],
        [510,0.97,0.32],
        [638,0.83,0.40],
        [765,0.64,0.33],
        [1020,0.42,0.14],
        [1276,0.29,0.10]
    ])

datT = dat.T
F_dat = datT[0]
V_dat = datT[1]
sd_dat = datT[2]

# F_dat = F_dat - min(F_dat)
```



```
# V_dat = V_dat - min(V_dat)
```

```
[56]: F_dat_0 = max(F_dat)
V_dat_0 = max(V_dat)

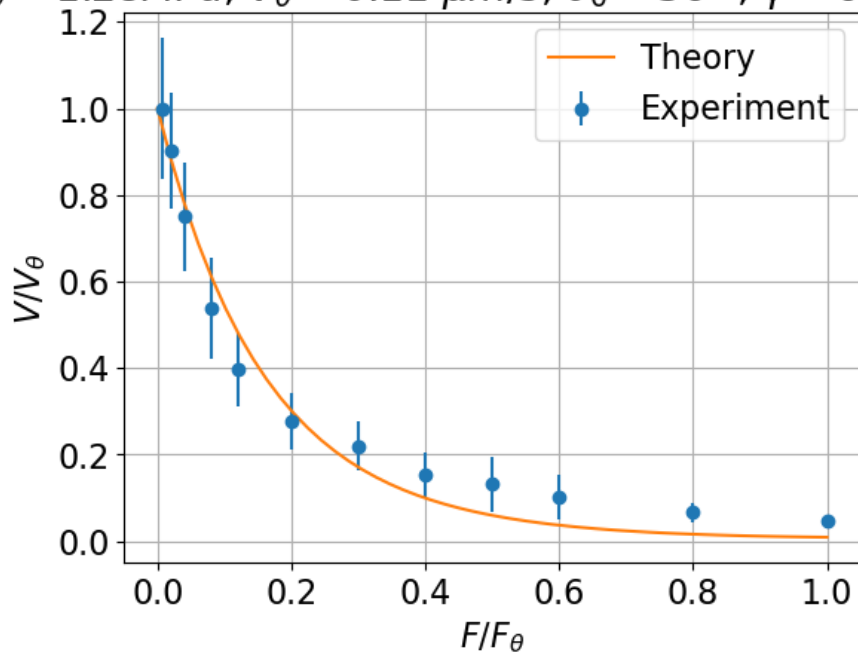
F_th_est = F_dat_0
V_th_est = V_dat_0

gamma_est = 6
contactAngle = 54 # degrees - see LiBieWei p12. NB normal = 90deg
theta0 = (90-contactAngle)*pi/180
# theta0 = pi/3
costh0 = np.cos(theta0)
chi_est = 0.4

plt.errorbar(F_dat/F_th_est,V_dat/V_th_est,sd_dat/
    ↪V_th_est,fmt='o',label='Experiment')
FF = np.linspace(0,1)

#VV = FVnorm(FF,gamma=gamma_est)
VV,eps = □
    ↪FVnormFlex(FF,gamma=gamma_est,theta0=theta0,chi=chi_est,normaliseTheta=True)
plt.plot(FF,VV,label=f'Theory')
plt.grid()
plt.xlabel('$F/F_\\theta$')
plt.ylabel('$V/V_\\theta$')
plt.legend()
title = ''
title += f'$F_\\theta = {(F_th_est/1e3):0.2f}$ MPa$'
title += f', $V_\\theta={ (V_th_est/60):0.2f}~\\mu m /s$'
title += f', $\\theta_0={ (theta0*180/pi):0.0f}^\\circ$'
title += f', $\\gamma={gamma_est}$'
title += f', $\\chi = {chi_est}$'
plt.title(title)
# plt.title(f'$F_\\theta={F_th_est/1e3:0.2f}$ MPa, $V_\\theta={ (V_th_est/60):0.2f}~\\mu m /s$, $\\gamma={gamma_est:0.1f}$' )
Savefig('Experiment0')
```

$F_\theta = 1.28 \text{ MPa}$ ,  $V_\theta = 0.11 \text{ } \mu\text{m/s}$ ,  $\theta_0 = 36^\circ$ ,  $\gamma = 6$ ,  $\chi = 0.4$



```
[57]: ## Optimisation
from scipy.optimize import minimize

def fun(par):

    ## extract parameters
    gamma = par[0]
    chi = par[1]
    # theta0 = par[2]
    # F0 = par[2]
    # V0 = par[3]
    F0 = F_th_est
    V0 = V_th_est

    FF = F_dat/F0
    VV,eps = FVnormFlex(FF,gamma=gamma,theta0=theta0,chi=chi,normaliseTheta=True)
    err = VV-V_dat/V0

    return np.linalg.norm(err)

## Initialise parameter vector
par0 = np.zeros(4)
par0[0] = gamma_est
par0[1] = chi_est
# par0[2] = theta0
# par0[2] = F_th_est
# par0[3] = V_th_est
```

```

## Minimise
tol = 1e-6
par = minimize(fun, par0,tol=tol)

print(par)
## extract parameters.
gamma_est = par.x[0]
chi_est = par.x[1]
# theta0 = par.x[2]
# F_th_est = par.x[2]
# V_th_est = par.x[3]

print(f'gamma_est = {gamma_est}')

```

```

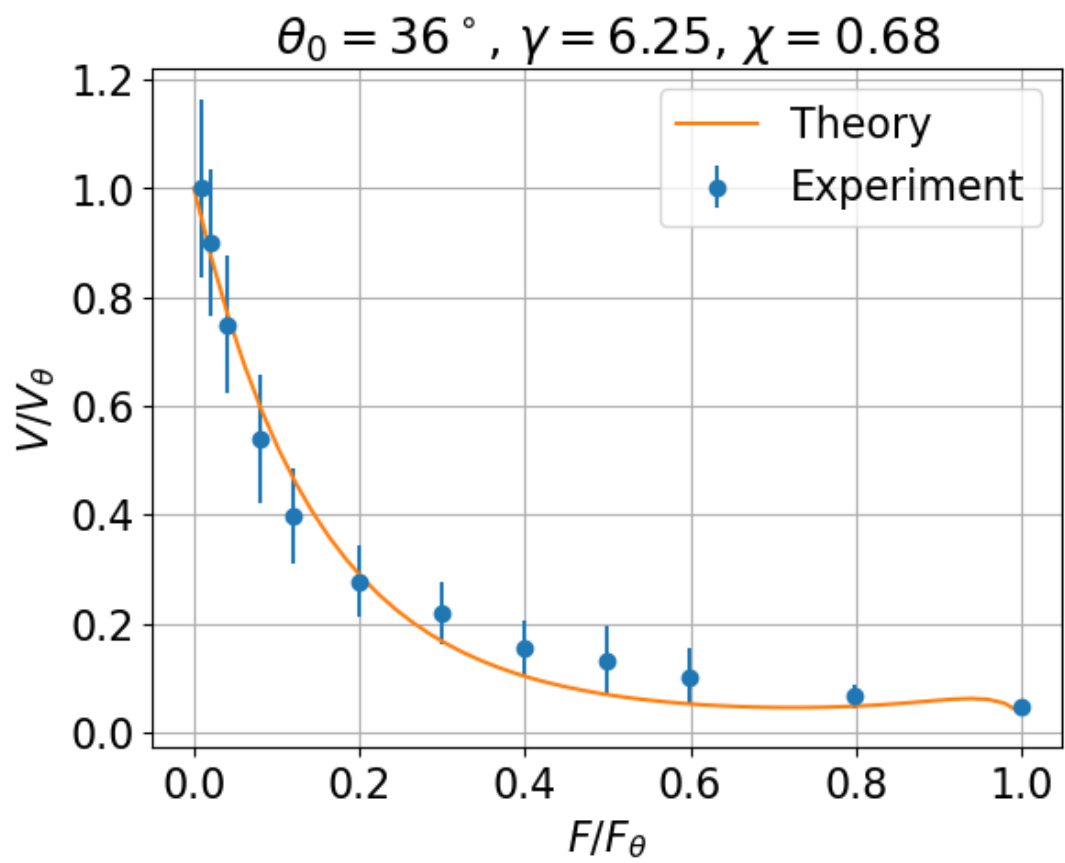
fun: 0.1558736037818
hess_inv: array([[1.31138473e+01, 1.06209908e-02],
                 [1.06209908e-02, 3.43936034e-02]])
jac: array([-2.60770321e-08, -1.21071935e-07])
message: 'Optimization terminated successfully.'
nfev: 60
nit: 7
njev: 20
status: 0
success: True
x: array([6.24633392, 0.68499184])
gamma_est = 6.246333917391744

```

```

[58]: plt.errorbar(F_dat/F_th_est,V_dat/V_th_est,sd_dat/
    ↪V_th_est,fmt='o',label='Experiment')
VV,eps = □
    ↪FVnormFlex(FF,gamma=gamma_est,theta0=theta0,chi=chi_est,normaliseTheta=True)
plt.plot(FF,VV,label=f'Theory')
plt.grid()
plt.xlabel('$F/F_\\theta$')
plt.ylabel('$V/V_\\theta$')
plt.legend()
title = ''
# title += f'$F_\\theta = {(F_th_est/1e3):0.2f}$ MPa$'
# title += f', $V_\\theta={ (V_th_est/60):0.2f}~\\mu m /s$'
title += f'$\\theta_0={ (theta0*180/pi):0.0f}^\\circ$'
title += f', $\\gamma={gamma_est:0.2f}$'
title += f', $\\chi = {chi_est:0.2f}$'
plt.title(title)
# plt.title(f'$F_\\theta={F_th_est/1e3:0.2f}$ MPa, $V_\\theta={ (V_th_est/60):
    ↪0.2f}~\\mu m /s$, $\\gamma={gamma_est:0.1f}$' )
Savefig('Experiment')

```



```
[59]: print(chi)
```

```
0.4730426877097931
```

```
[ ]:
```

## References