

1. Symmetry of QM

2. Theory of Angular momentum.

3. Scattering theory.

Symmetry of transformation of space \mathbb{R}^3

Wave function $\psi(\vec{r}) \quad \vec{r} \in \mathbb{R}^3$

Consider linear transf. $Q: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$Q\vec{r} = \vec{r}' \quad \vec{r}: 3d \text{ column vector}$

$Q: 3 \times 3 \text{ matrix}$

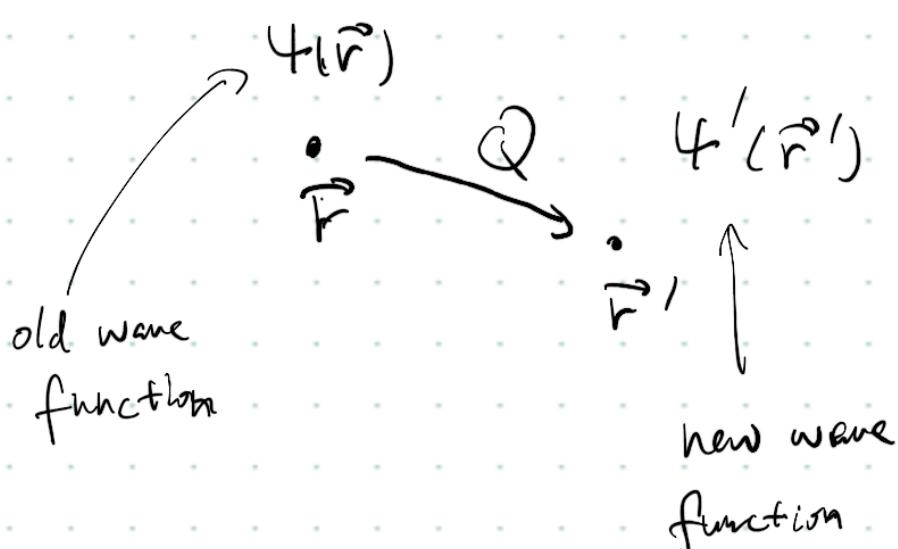
Q is a symmetry of the space, if it preserves the inner product

$$\vec{r}_1 \cdot \vec{r}_2 = (Q\vec{r}_1) \cdot (Q\vec{r}_2)$$

In particular, Q preserves the distance in \mathbb{R}^3

$$\vec{r} \cdot \vec{r} = (Q\vec{r}) \cdot (Q\vec{r}) \quad \checkmark$$

Q induces transformation of $\psi(\vec{r})$



$$\text{s.t. } \psi'(\vec{r}') = \psi(\vec{r})$$

$$\psi'(\vec{Q}\vec{r}) = \psi(\vec{r})$$

$$\vec{r}' \quad ||$$

$$Q^{-1}\vec{r}'$$

$$\psi'(\vec{r}) = \psi(Q^{-1}\vec{r})$$

$$\equiv \hat{D}(Q)\psi(\vec{r})$$

$$Q : \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

$$\hat{D}(Q) : \mathcal{H} \rightarrow \mathcal{H} \quad \mathcal{H} = L^2(\mathbb{R}^3, d^3x)$$

$$|\psi\rangle \rightarrow |\psi'\rangle \quad \psi'(\vec{r}) = D(Q)\psi(\vec{r})$$

$$= \psi(Q^{-1}\vec{r})$$

properties of $D(Q)$: linear operator on \mathcal{H} .

- Unitarity : $\langle \psi_1 | \psi_2 \rangle = \int d^3\vec{r} \overline{\psi_1(\vec{r})} \psi_2(\vec{r})$

change of

variable

$$\vec{r} \rightarrow Q^{-1}\vec{r}$$

$$= \int d^3(Q^{-1}\vec{r}) \overline{\psi_1(Q^{-1}\vec{r})} \psi_2(Q^{-1}\vec{r})$$

Lemma $\det Q = \pm 1$

Pf : $\vec{r} \cdot \vec{r}' = \underbrace{\delta_{ij} r^i r'^j}_{\text{||}} \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow \delta_{ij} Q^i_k Q^j_l = \delta_{kl}$

$Q \vec{r} \cdot Q \vec{r}' = \underbrace{\delta_{ij} Q^i_k r^k Q^j_l r'^l}_{\text{||}} \quad \left. \begin{array}{l} \\ \end{array} \right\} = \delta_{kl}$

$$Q^T Q = I_{3 \times 3}$$

$$\Rightarrow Q^T = Q^{-1}, \quad (\det Q)^2 = 1$$

$$\det Q = \pm 1$$

$$d^3(Q^{-1} \vec{r}) = d^3 \vec{r} \quad |\det Q^{-1}| = d^3 \vec{r}$$

$$\begin{aligned} \langle \psi_1 | \psi_2 \rangle &= \int d^3 \vec{r} \overrightarrow{\psi_1(Q^T \vec{r})} \psi_2(Q^T \vec{r}) \\ &= \langle D(Q) \psi_1 | D(Q) \psi_2 \rangle \end{aligned}$$

$\Rightarrow D(Q)$ is unitary operator.

- Consider 2 transformations $Q_1, Q_2 : \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$Q = Q_1 \circ Q_2 \quad Q \vec{r} = Q_1 \circ Q_2 \vec{r}$$

$$\begin{aligned}
 D(Q_1) D(Q_2) \psi(\vec{r}) &= D(Q_1) \psi(Q_2^{-1} \vec{r}) \\
 &= \psi(Q_2^{-1}(Q_1^{-1} \vec{r})) \\
 &= \psi(Q_2^{-1} Q_1^{-1} \vec{r}) = \psi((Q_1 Q_2)^{-1} \vec{r}) \\
 &\stackrel{?}{=} D(Q_1 Q_2) \psi(\vec{r})
 \end{aligned}$$

$$D(Q_1) D(Q_2) = D(Q_1 Q_2)$$

if we view D to be a map from symmetry transf. on \mathbb{R}^3
to linear operators on H .

D respects the product of transf.

- $D(Q) D(Q^{-1}) = D(Q Q^{-1}) = D(1_{3 \times 3})$

$$D(1) \psi(\vec{r}) = \psi(1 \vec{r}) = \psi(\vec{r})$$

$$D(1) = 1_{\text{op}}$$

$$D(Q)D(Q^{-1}) = I_H$$

$$\boxed{D(Q)^{-1} = D(Q^\top)}$$

D respects
the inverse.

Def A group is a set G together with a binary operation

$$a \cdot b \in G \quad \forall a, b \in G$$

called group multiplication

s.t. (1) $(a \cdot b) \cdot c = a \cdot (b \cdot c)$ $\forall a, b, c \in G$
 (associativity)

(2) $\exists ! e \in G$, s.t. $e \cdot a = a$ $\forall a \in G$
 (identity)

(3) $\forall a \in G$, $\exists a^{-1} \in G$ s.t. $a \cdot a^{-1} = a^{-1} \cdot a = e$
 (inverse)

Example (1) $\mathbb{R} \setminus \{0\}$ with multiplication

(2) set of symmetry transf. Q 's on \mathbb{R}^3

multiplication : composition of Q_1, Q_2

- Q : 3×3 matrix \rightarrow associativity

- identity $1_{3 \times 3}$

- inverse $Q^T Q = 1 \quad Q^{-1} = Q^T$

the set of all 3×3 matrices with $Q^{-1} = Q^T$

is called $O(3)$ group.

(Orthogonal group on \mathbb{R}^3)

(3) We have found a set of $D(Q)$ unitary operators on \mathcal{H}

$$\{D(Q) \mid Q \in O(3)\} = D(O(3))$$

multiplication, composition of operators
(product) $D(Q_1) D(Q_2)$

- $D(Q)$ ^{one} operators \rightarrow associativity

- identity operators $D(1_{3 \times 3}) = 1_{\mathcal{H}}$

$$\cdot \text{ inverse } D(Q^{-1}) = D(Q)^{-1}$$

$$D(Q_1)D(Q_2) = D(Q_1Q_2)$$

multiplication multiplication

$$\text{on } D(O(3)) \quad \text{on } O(3)$$

Def, given 2 groups G, H , a group homomorphism

is a map $h: G \rightarrow H$

$$\text{s.t. } h(g_1) h(g_2) = h(g_1g_2) \quad \forall g_1, g_2 \in G$$

$$\begin{matrix} & \uparrow \\ \text{multiplication} & & \downarrow \\ \text{in } H & & \text{multiplication} \\ & & \text{in } G \end{matrix}$$

$D: D(O(3)) \rightarrow D(O(3))$ is a homomorphism.

in terms of Dirac bracket , $|4\rangle \in \mathcal{H}$

$$4(\vec{r}) := \langle \vec{r} | 4 \rangle \quad \hat{\vec{R}}(\vec{r}) = \vec{r} | \vec{r} \rangle$$

$$4'(\vec{r}) := \langle \vec{r} | 4' \rangle$$

$$|4'\rangle = D(Q)|4\rangle$$

$$\left\{ \begin{array}{l} 4'(\vec{r}) = \langle \vec{r} | D(Q) | 4 \rangle = \langle D(Q)^+ \vec{r} | 4 \rangle \\ \text{||} \end{array} \right.$$

$$4(Q^{-1}\vec{r}) = \langle Q^{-1}\vec{r} | 4 \rangle \quad \langle D(Q^{-1})\vec{r} | 4 \rangle$$

$$\langle + | \hat{O} | 4 \rangle = \langle \hat{O}^+ + | 4 \rangle$$

$$D(Q)^+ = D(Q)^{-1} = D(Q^{-1})$$

$$D(Q^{-1})|\vec{r}\rangle = |Q^{-1}\vec{r}\rangle$$

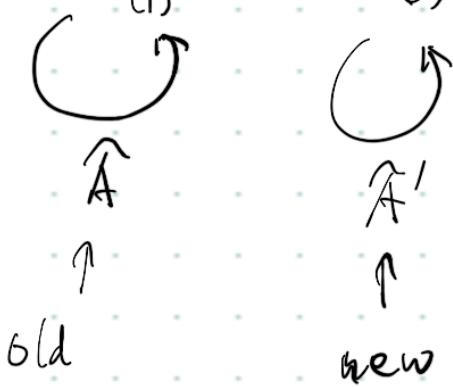
$$D(Q)|\vec{r}\rangle = |Q\vec{r}\rangle$$

$$D(Q) \vec{r} = \vec{r}'$$

$Q \rightarrow D(Q)$ transformations
 transf transf of operators on
 on \mathbb{R}^3 on \mathcal{H} \mathcal{H}

$$\hat{A} D(Q)^{-1} |4\rangle$$

$$D(Q) : \mathcal{H}_{(1)} \rightarrow \mathcal{H}_{(2)}$$



$$|4\rangle \in \mathcal{H}_{(2)}, \quad D(Q)^{-1} |4\rangle \in \mathcal{H}_{(1)}$$

$$\hat{A} D(Q)^{-1} |4\rangle \in \mathcal{H}_{(1)}$$

$$(D(Q) \hat{A} D(Q)^{-1}) |4\rangle \in \mathcal{H}_{(2)}$$

$$\hat{A}' := D(Q) \hat{A} D(Q)^{-1}$$

$\hat{A} \mapsto \hat{A}'$ transf. of operators induced
by Q .

$Q \rightarrow D(Q) \rightarrow$ transf. of operators

$$Q\vec{r} = \vec{r}'$$

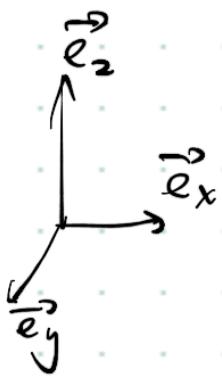
$$D(Q)|\psi\rangle = |\psi'\rangle$$

$$D(Q) \hat{A} D(Q)^{-1} = \hat{A}'$$

conjugate.

position operator: $\hat{\vec{R}}$ $\hat{\vec{R}} |\vec{r}\rangle = \vec{r} |\vec{r}\rangle$

$$\begin{aligned} \hat{\vec{R}} &= \hat{R}_1 \vec{e}_x + \hat{R}_2 \vec{e}_y + \hat{R}_3 \vec{e}_z \\ &= \sum_{i=1}^3 \hat{R}_i \vec{e}_i \end{aligned}$$



$$\hat{R}_i |\vec{r}\rangle = r_i |\vec{r}\rangle$$

$$i = 1, 2, 3$$

$$\hat{R} \rightarrow D(Q) \hat{R} D(Q)^{-1} = \hat{R}'$$

$$\hat{R}' |\vec{r}\rangle = \vec{r} |\vec{r}\rangle$$

$$D(Q)$$

\nearrow \uparrow
 $D(Q)^{-1} D(Q)$

$$\Rightarrow D(Q) \underbrace{\hat{R} D(Q)^{-1}}_{\sim} D(Q) |\vec{r}\rangle = D(Q) \vec{r} |\vec{r}\rangle$$

$$\hat{R}' \underbrace{D(Q)}_{\sim} |\vec{r}\rangle = \vec{r} \underbrace{D(Q)}_{\sim} |\vec{r}\rangle$$

new eigenstate

$$\hat{R}' |\vec{q}_F\rangle = \vec{r} |\vec{q}_F\rangle$$

On the other hand, $\hat{R} |\vec{q}_F\rangle = Q_F |\vec{q}_F\rangle$

$$\Rightarrow \underbrace{Q^{-1} \hat{R}}_{\sim} |\vec{q}_F\rangle = \vec{r} |\vec{q}_F\rangle$$

$$Q^{-1} \hat{R} = \sum_{i=1}^3 \hat{R}_i \underbrace{(Q^{-1} \vec{e}_i)}_{\sim}$$

$$\hat{\vec{R}}' = Q^{-1} \hat{\vec{R}}$$

$$D(Q) \hat{\vec{R}} D(Q)^{-1} = Q^{-1} \hat{\vec{R}}$$

$$\hat{\vec{R}} = \sum_{i=1}^3 \hat{R}_i \hat{e}_i$$

$$Q^{-1} \hat{\vec{R}} = \sum_{i=1}^3 \hat{R}_i Q^{-1} \hat{e}_i$$

Parity transformation

$$P \in O(3) : P\vec{r} = -\vec{r}$$

$$D(P) |\vec{r}\rangle = |P\vec{r}\rangle = |-\vec{r}\rangle$$

$$D(P) \equiv \hat{P}$$

$\{P, 1_{3 \times 3}\}$ is a subgroup in $O(3)$

$$P^2 = 1, P \cdot 1 = P = 1 \cdot P.$$

$$\hat{P} |4\rangle = |4'\rangle$$

$$\boxed{\langle \vec{r} | \psi' \rangle = \langle \vec{r} | \hat{P} |\psi\rangle = \langle \vec{r} | \psi \rangle}$$

$$\langle \vec{r} | \hat{P} |\psi\rangle = \langle \hat{P}^+ | \vec{r} \rangle, \psi \rangle = \langle \hat{P}^+ | \vec{r} \rangle, \psi \rangle$$

$$\hat{P}^+ = \hat{P}^- \quad \boxed{\begin{aligned} \hat{P}^2 &= D(P)D(P) = D(P^2) \\ &= D(1) = \mathbb{1}_{\mathcal{H}} \end{aligned}}$$

$$\psi'(\vec{r}) = \psi(-\vec{r})$$

$$\boxed{\hat{P}: \psi(\vec{r}) \rightarrow \psi'(\vec{r}) = \psi(-\vec{r})}$$

$$\hat{P}^2 = \mathbb{1}_{\mathcal{H}} \Rightarrow \hat{P} \text{ has eigenvalue } \pm 1$$

eigenstates ψ_{\pm}

$$\hat{P} \psi_{\pm}(\vec{r}) = \underbrace{\psi_{\pm}(-\vec{r})}_{\pm \psi_{\pm}(\vec{r})}$$

ψ_+ : even parity

ψ_- : odd parity

$$\hat{P}^+ = \hat{P}^\dagger = \hat{P} \quad \hat{P} \text{ is Hermitian & unitary}$$

transf. of operators under parity

$$\hat{\vec{R}} \rightarrow \hat{P} \hat{\vec{R}} \hat{P}$$

$$\begin{aligned}\hat{P} \hat{\vec{R}} \hat{P} |\vec{r}\rangle &= \hat{P} \hat{\vec{R}} |-\vec{r}\rangle = (-\vec{r}) \hat{P} |-\vec{r}\rangle \\ &= (-\vec{r}) |\vec{r}\rangle \\ &\approx -\hat{\vec{R}} |\vec{r}\rangle\end{aligned}$$

$$\hat{P} \hat{\vec{R}} \hat{P} = -\hat{\vec{R}}$$

momentum operator $\hat{\vec{P}} |\vec{p}\rangle = \vec{p} |\vec{p}\rangle$

$$\begin{aligned}\langle \vec{r} | \vec{p} \rangle &= e^{\frac{i}{\hbar} \vec{r} \cdot \vec{p}} = e^{\frac{i}{\hbar} (-\vec{r}) \cdot (-\vec{p})} \\ &= \langle -\vec{r} | -\vec{p} \rangle\end{aligned}$$

$$\hat{\vec{P}} \rightarrow \hat{P} \hat{\vec{P}} \hat{P} \hat{\vec{P}}$$

$$\hat{P} |\vec{p}\rangle = \hat{P} \underbrace{\int d^3r |r\rangle \langle r |}_{\hat{P}} |\vec{p}\rangle$$

resolution
 of identity

$$\begin{aligned}
 d^3\vec{r} &= d^3(-\vec{r}) & = \int d^3\vec{r} |-\vec{r}\rangle \langle -\vec{r}| - \vec{p} \rangle \\
 && = \underbrace{\int d^3(-\vec{r}) |-\vec{r}\rangle \langle -\vec{r}| - \vec{p} \rangle}_{= 1 - \vec{p} \rangle}
 \end{aligned}$$

$$\begin{aligned}
 \hat{p} \hat{p} \hat{p} | \vec{p} \rangle &= \hat{p} \hat{p} \hat{p} | -\vec{p} \rangle = (-\vec{p}) \hat{p} | -\vec{p} \rangle \\
 &= (-\vec{p}) | \vec{p} \rangle = -\hat{p} | \vec{p} \rangle \\
 \Rightarrow \hat{p} \hat{p} \hat{p} &= -\hat{p}
 \end{aligned}$$

angular momentum operator:

$$\hat{L} = \hat{R} \times \hat{p}$$

$$\begin{aligned}
 \hat{p} \hat{L} \hat{p} &= \hat{p} (\hat{R} \times \hat{p}) \hat{p} = \hat{p} \hat{R} \hat{p} \times \hat{p} \hat{p} \hat{p} \\
 &= (-\hat{R}) \times (-\hat{p}) \\
 &= \hat{L}
 \end{aligned}$$

$$\hat{\vec{V}} = \sum_{i=1}^3 \hat{V}_i \hat{e}_i$$

$\hat{\vec{V}}$ is vector operator if $\hat{p} \hat{\vec{V}} \hat{p} = -\hat{\vec{V}}$, like, $\hat{\vec{R}}$

" pseudo-vector operator if $\hat{p} \hat{\vec{V}} \hat{p} = \hat{\vec{V}}$

like $\hat{\vec{L}}$, $\hat{\vec{s}}$ —————
 ↑
 spin

$\hat{\vec{O}}$ scalar operator if $\hat{p} \hat{\vec{O}} \hat{p} = \hat{\vec{O}}$ e.g.

Hamiltonian of central potential

pseudo-scalar operator if $\hat{p} \hat{\vec{O}} \hat{p} = -\hat{\vec{O}}$ e.g.

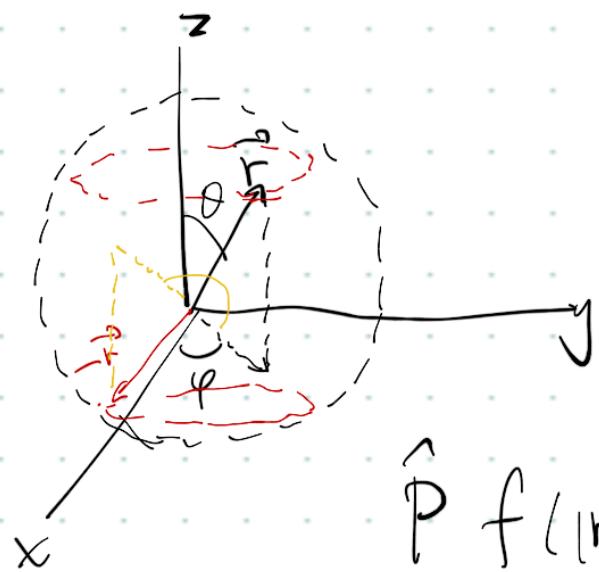
helicity operator

$$\hat{\vec{s}} \cdot \frac{\hat{\vec{p}}}{|\hat{\vec{p}}|} = \hat{h}$$

because $\hat{P} \hat{L} \hat{P} = \hat{L}$ i.e. $[\hat{P}, \hat{L}] = 0$

they share the same eigenbasis.

indeed in spherical coordinate.



$$P: \vec{r} \rightarrow -\vec{r}$$

$$\theta \rightarrow \pi - \theta$$

$$\varphi \rightarrow \varphi + \pi$$

$$\hat{P} f(r, \theta, \varphi) = f(r, \pi - \theta, \varphi + \pi)$$

$$\left\{ \begin{array}{l} \hat{P} Y_{lm}(\theta, \varphi) = (-1)^l Y_{lm}(\theta, \varphi) \\ \hat{L}^2 Y_{lm}(\theta, \varphi) = \hbar^2 l(l+1) Y_{lm}(\theta, \varphi) \\ \hat{L}_z Y_{lm}(\theta, \varphi) = \hbar m Y_{lm}(\theta, \varphi) \end{array} \right.$$