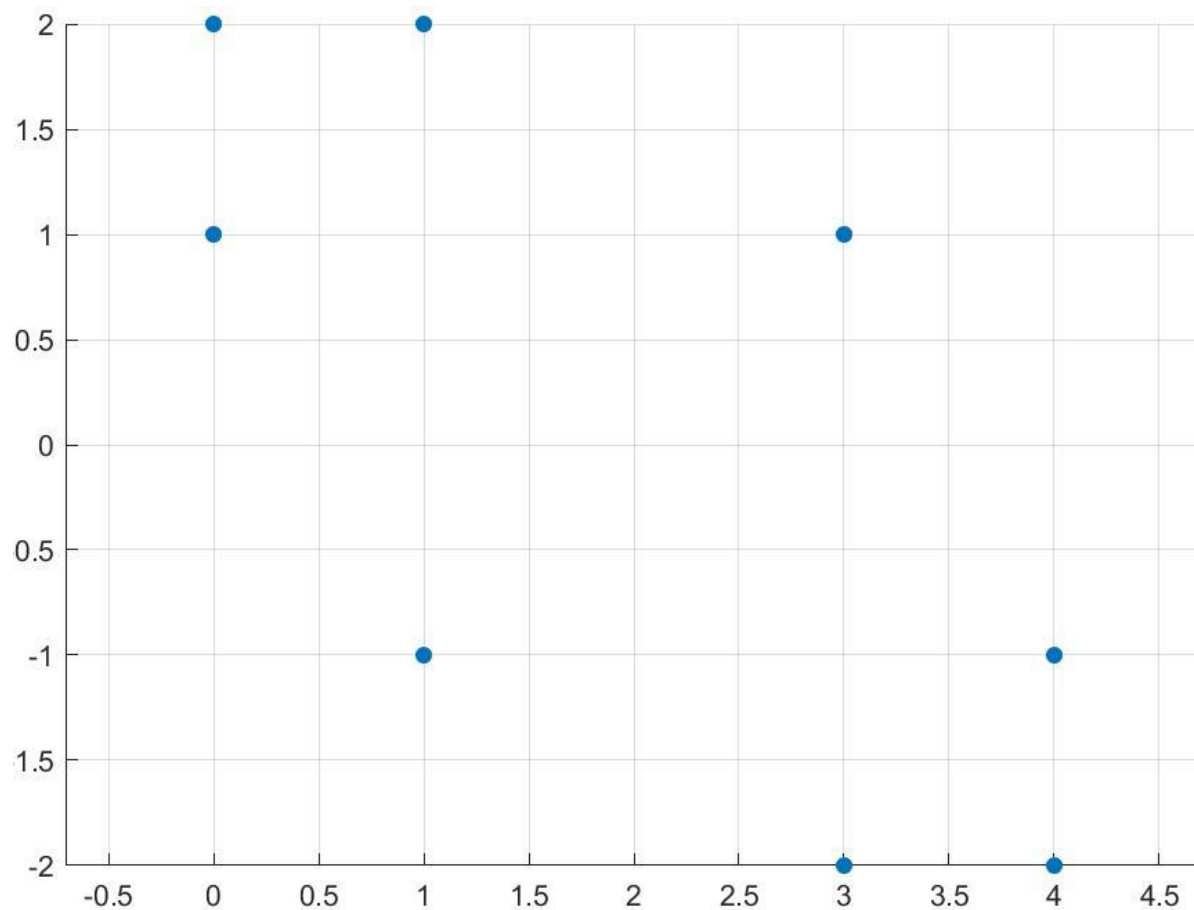


EXERCICE 2

Let the set of points

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

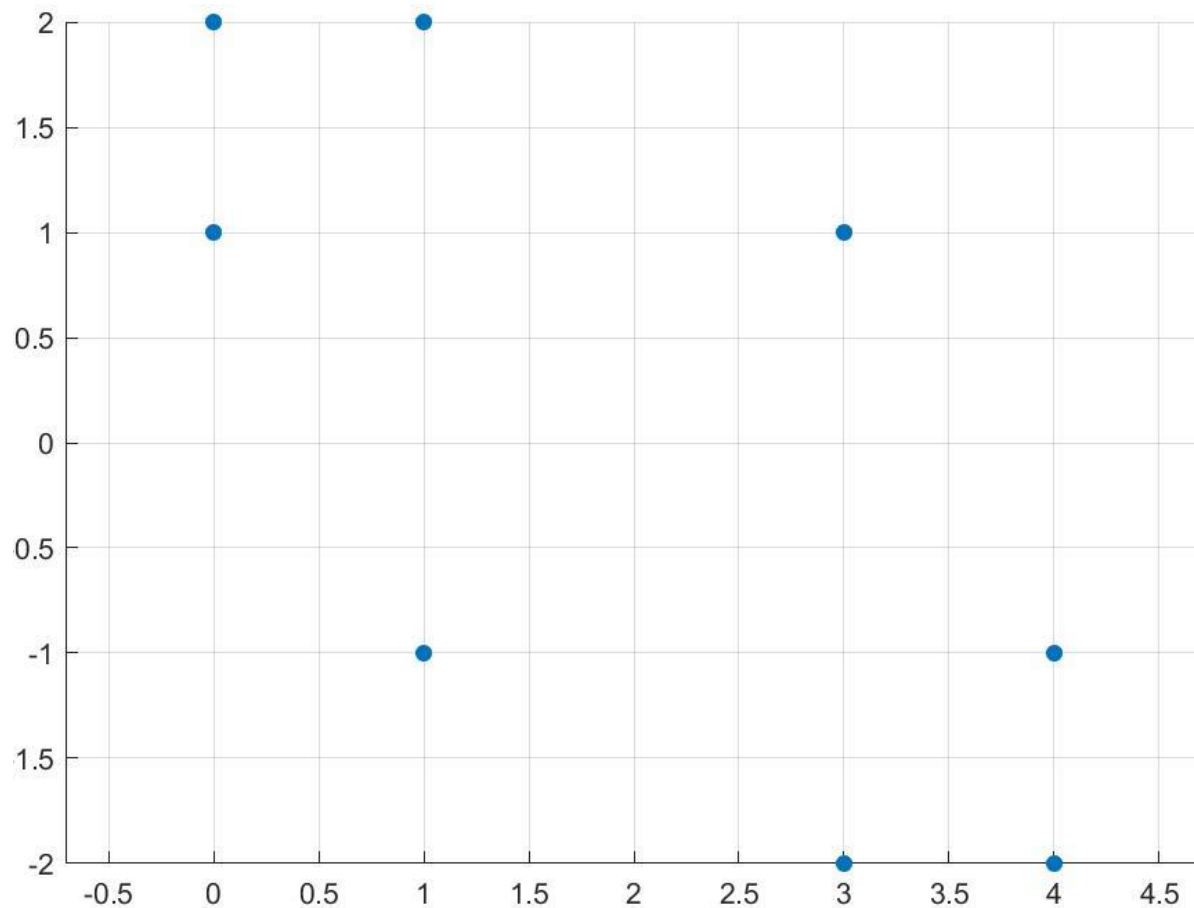
be driven from a Gaussian distribution. Estimate the parameters of such Gaussian distribution.



EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

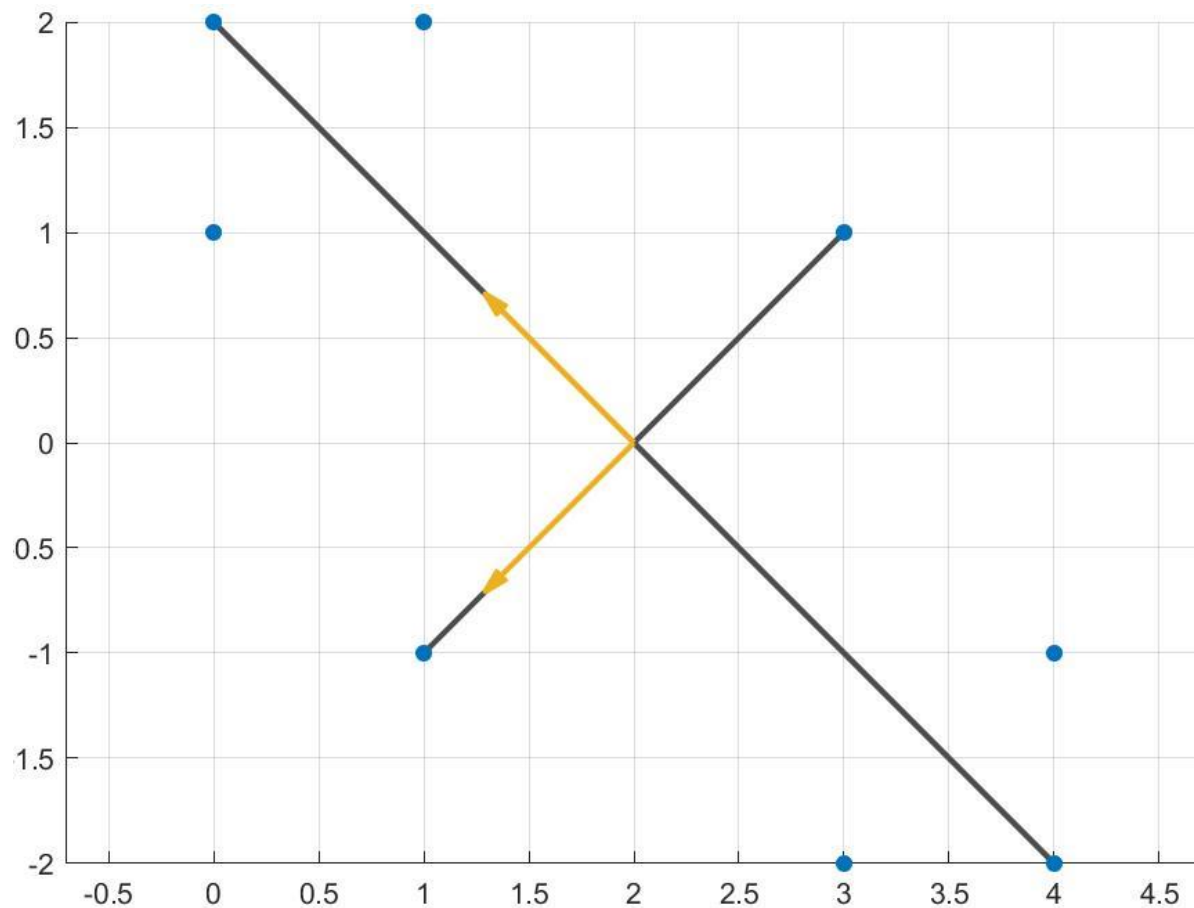
(a) Draw the set of points. Intuitively, draw the principal directions of the covariance matrix given by the Gaussian model.



EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(a) Draw the set of points. Intuitively, draw the principal directions of the covariance matrix given by the Gaussian model.



EXERCISE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(b) Compute the mean and the covariance matrix of the given set of points.

MEAN

$$\boldsymbol{\mu} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}^{(n)} = ?$$

COVARIANCE

$$\boldsymbol{\Sigma} = \frac{1}{N-1} (\mathbf{X} - \boldsymbol{\mu})(\mathbf{X} - \boldsymbol{\mu})^T = ?$$



This is the **unbiased** version of the sample covariance.
And it is what the Python function `np.cov` computes.

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(b) Compute the mean and the covariance matrix of the given set of points.

MEAN

$$\boldsymbol{\mu} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}^{(n)} = \frac{1}{8} \left[\begin{pmatrix} 0 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \end{pmatrix} + \begin{pmatrix} 3 \\ 1 \end{pmatrix} + \begin{pmatrix} 3 \\ -2 \end{pmatrix} + \begin{pmatrix} 4 \\ -1 \end{pmatrix} + \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right] = \frac{1}{8} \begin{pmatrix} 16 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

COVARIANCE

$$\boldsymbol{\Sigma} = \frac{1}{N-1} (\mathbf{X} - \boldsymbol{\mu})(\mathbf{X} - \boldsymbol{\mu})^T \text{ where}$$

$$\mathbf{X} - \boldsymbol{\mu} = \begin{pmatrix} 0 & 0 & 1 & 1 & 3 & 3 & 4 & 4 \\ 2 & 1 & 2 & -1 & 1 & -2 & -1 & -2 \end{pmatrix} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 & -2 & -1 & -1 & 1 & 1 & 2 & 2 \\ 2 & 1 & 2 & -1 & 1 & -2 & -1 & -2 \end{pmatrix}$$

$$\Rightarrow \boldsymbol{\Sigma} = \frac{1}{N-1} (\mathbf{X} - \boldsymbol{\mu})(\mathbf{X} - \boldsymbol{\mu})^T = \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(c) Compute the principal directions of the covariance matrix. Draw the resulting new coordinate system and check if they correspond to the directions you sketched in (1).

Principal directions of Σ = eigenvectors of $\Sigma \Rightarrow$ We have to diagonalize Σ

To diagonalize Σ :

1. Compute the characteristic polynomial $p_{\Sigma}(\lambda)$.
2. Compute the eigenvalues (which are the roots of $p_{\Sigma}(\lambda)$).
3. Compute the eigenvectors (which are the basis of the null space of $\Sigma - \lambda \text{Id}$ for each eigenvalue λ).

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(c) Compute the principal directions of the covariance matrix. Draw the resulting new coordinate system and check if they correspond to the directions you sketched in (1).

To diagonalize Σ :

1. Compute the characteristic polynomial $p_{\Sigma}(\lambda) = \det(\Sigma - \lambda \text{Id})$.

$$\Sigma = \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} \Rightarrow p_{\Sigma}(\lambda) = ?$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(c) Compute the principal directions of the covariance matrix. Draw the resulting new coordinate system and check if they correspond to the directions you sketched in (1).

To diagonalize Σ :

1. Compute the characteristic polynomial $p_{\Sigma}(\lambda) = \det(\Sigma - \lambda \text{Id})$.

$$\Sigma = \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} \Rightarrow p_{\Sigma}(\lambda) = \det \begin{pmatrix} \frac{20}{7} - \lambda & -2 \\ -2 & \frac{20}{7} - \lambda \end{pmatrix} = \left(\lambda^2 - \frac{40}{7} \lambda + \frac{204}{49} \right)$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(c) Compute the principal directions of the covariance matrix. Draw the resulting new coordinate system and check if they correspond to the directions you sketched in (1).

To diagonalize Σ :

2. Compute the eigenvalues (which are the roots of $p_{\Sigma}(\lambda)$).

$$p_{\Sigma}(\lambda) = \lambda^2 - \frac{40}{7}\lambda + \frac{204}{49} \Rightarrow \begin{cases} \lambda_1 = ? \\ \lambda_2 = ? \end{cases}$$

EXERCICE 2

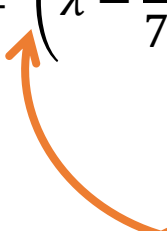
$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(c) Compute the principal directions of the covariance matrix. Draw the resulting new coordinate system and check if they correspond to the directions you sketched in (1).

To diagonalize Σ :

2. Compute the eigenvalues (which are the roots of $p_{\Sigma}(\lambda)$).

$$p_{\Sigma}(\lambda) = \lambda^2 - \frac{40}{7}\lambda + \frac{204}{49} = \left(\lambda - \frac{6}{7}\right)\left(\lambda - \frac{34}{7}\right) \Rightarrow \begin{cases} \lambda_1 = \frac{34}{7} \\ \lambda_2 = \frac{6}{7} \end{cases}$$


$$\lambda = \frac{40 \pm \sqrt{(-40)^2 - 4 \cdot 204}}{2}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(c) Compute the principal directions of the covariance matrix. Draw the resulting new coordinate system and check if they correspond to the directions you sketched in (1).

To diagonalize Σ :

3. Compute the eigenvectors (which are the basis of the null space of $\Sigma - \lambda \text{Id}$ for each eigenvalue λ).

$$\boxed{\lambda_1 = \frac{34}{7}} \quad \boldsymbol{v}^{(1)} = \text{Ker} \left(\Sigma - \frac{34}{7} \text{Id} \right) = ?$$

$$\boxed{\lambda_2 = \frac{6}{7}} \quad \boldsymbol{v}^{(2)} = \text{Ker} \left(\Sigma - \frac{6}{7} \text{Id} \right) = ?$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(c) Compute the principal directions of the covariance matrix. Draw the resulting new coordinate system and check if they correspond to the directions you sketched in (1).

To diagonalize Σ :

3. Compute the eigenvectors (which are the basis of the null space of $\Sigma - \lambda \text{Id}$ for each eigenvalue λ).

$$\boxed{\lambda_1 = \frac{34}{7}} \quad \mathbf{v}^{(1)} = \text{Ker} \begin{pmatrix} 20 - 34 & -14 \\ -14 & 20 - 34 \end{pmatrix} = \text{Ker} \begin{pmatrix} -14 & -14 \\ -14 & -14 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \Rightarrow \mathbf{v}^{(1)} := \frac{\mathbf{v}^{(1)}}{|\mathbf{v}^{(1)}|} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\text{Ker}(\mathbf{A}) = \text{Ker}(\alpha \mathbf{A}), \forall \alpha \in \mathbb{R}$$

$$\begin{pmatrix} \frac{20}{7} & \frac{-14}{7} \\ \frac{-14}{7} & \frac{20}{7} \end{pmatrix} - \begin{pmatrix} \frac{34}{7} & 0 \\ 0 & \frac{34}{7} \end{pmatrix} = \frac{1}{7} \left[\begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} - \begin{pmatrix} 34 & 0 \\ 0 & 34 \end{pmatrix} \right]$$

$$\begin{pmatrix} -14 & -14 \\ -14 & -14 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

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To diagonalize Σ :

3. Compute the eigenvectors (which are the basis of the null space of $\Sigma - \lambda \text{Id}$ for each eigenvalue λ).

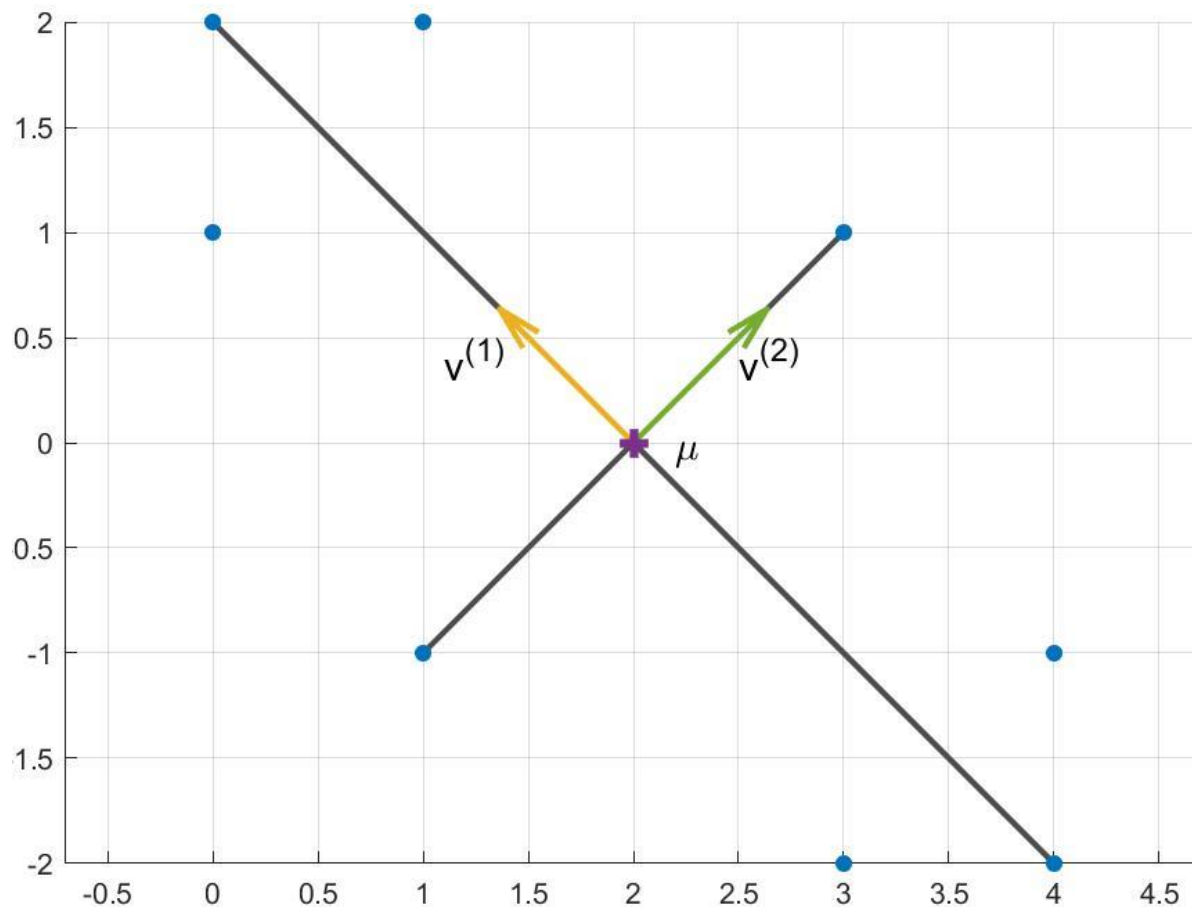
$$\boxed{\lambda_1 = \frac{34}{7}} \quad \mathbf{v}^{(1)} = \text{Ker} \begin{pmatrix} 20 - 34 & -14 \\ -14 & 20 - 34 \end{pmatrix} = \text{Ker} \begin{pmatrix} -14 & -14 \\ -14 & -14 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \Rightarrow \mathbf{v}^{(1)} := \frac{\mathbf{v}^{(1)}}{|\mathbf{v}^{(1)}|} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\boxed{\lambda_2 = \frac{6}{7}} \quad \mathbf{v}^{(2)} = \text{Ker} \begin{pmatrix} 20 - 6 & -14 \\ -14 & 20 - 6 \end{pmatrix} = \text{Ker} \begin{pmatrix} 14 & -14 \\ -14 & 14 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow \mathbf{v}^{(2)} := \frac{\mathbf{v}^{(2)}}{|\mathbf{v}^{(2)}|} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

EXERCISE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(c) Compute the principal directions of the covariance matrix. Draw the resulting new coordinate system and check if they correspond to the directions you sketched in (1).



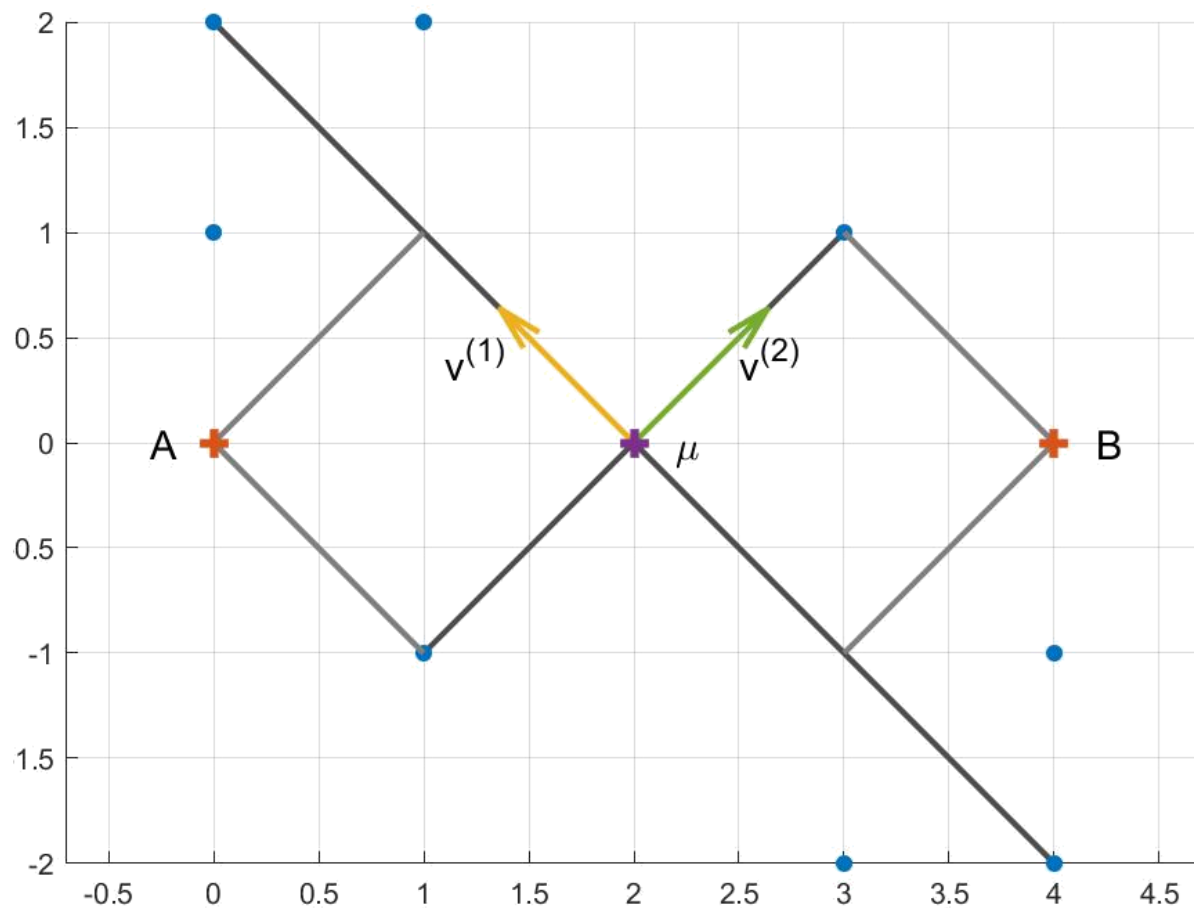
$$v^{(1)} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$v^{(2)} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

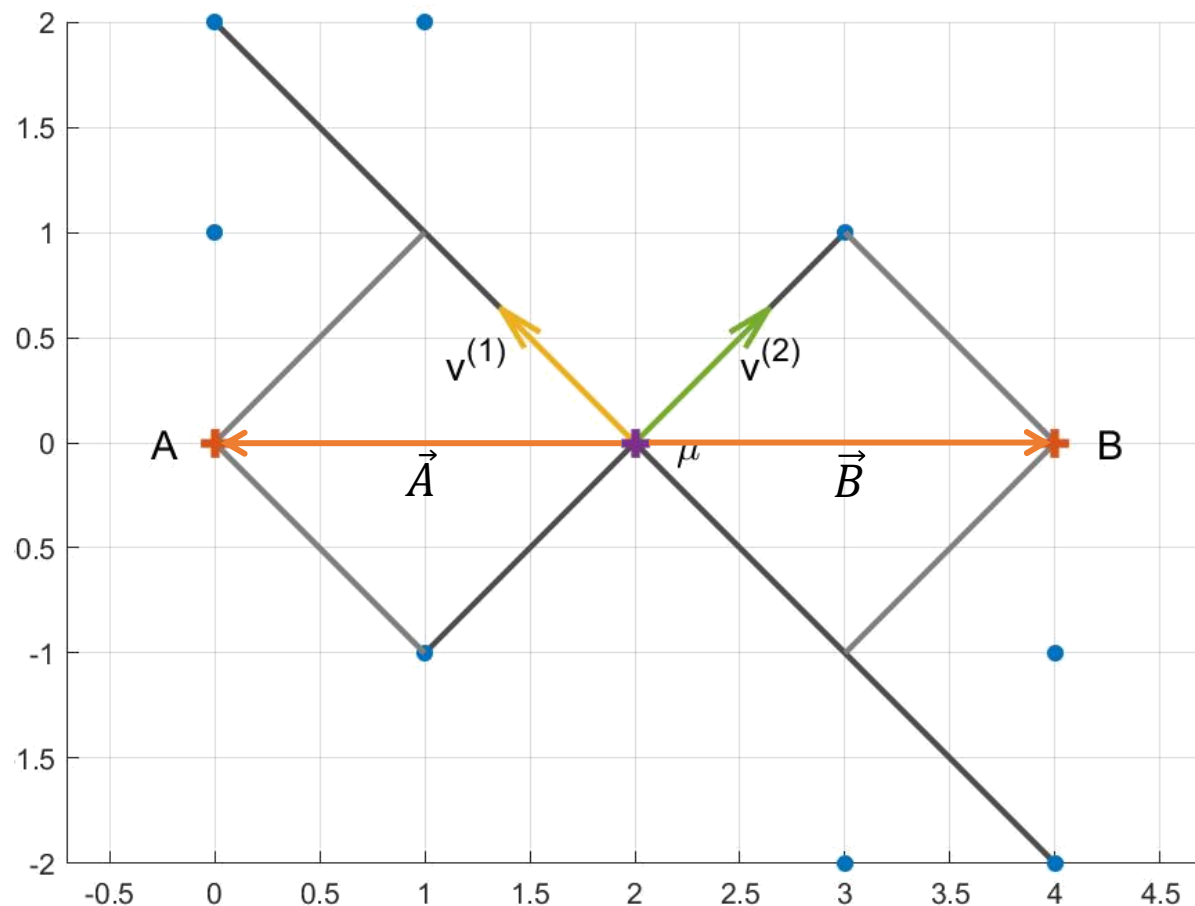
(d) Compute the coordinates of the points $A = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ and $B = \begin{pmatrix} 4 \\ 0 \end{pmatrix}$ in the system of coordinates adapted to the Gaussian.



EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

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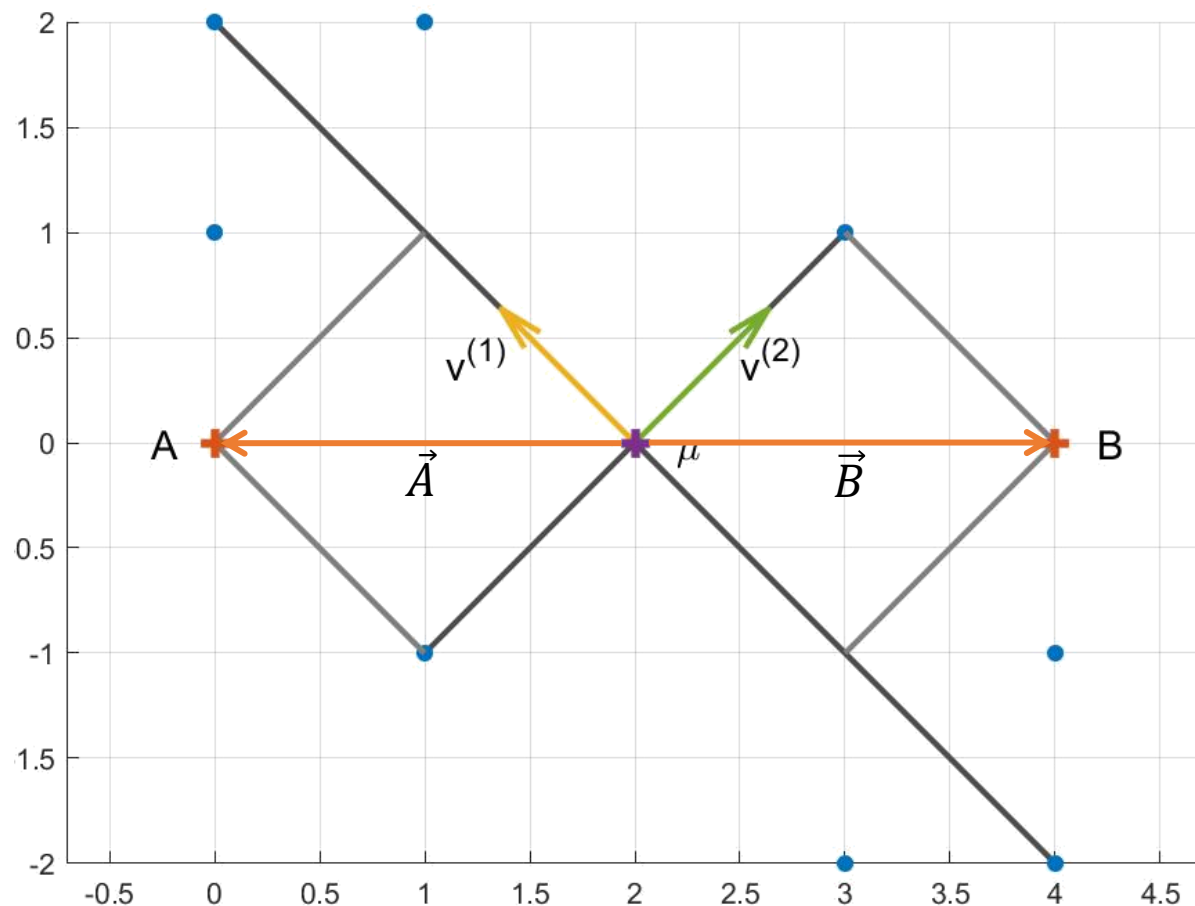
$$\vec{A} = A - \mu = \begin{pmatrix} 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 \\ 0 \end{pmatrix} \longrightarrow \vec{A}_{<v>?}$$

$$\vec{B} = B - \mu = \begin{pmatrix} 4 \\ 0 \end{pmatrix} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \longrightarrow \vec{B}_{<v>?}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(d) Compute the coordinates of the points $A = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ and $B = \begin{pmatrix} 4 \\ 0 \end{pmatrix}$ in the system of coordinates adapted to the Gaussian.



$$A_{\langle v \rangle} = \langle \varepsilon \rangle M_{\langle v \rangle} \vec{A} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}^T \begin{pmatrix} -2 \\ 0 \end{pmatrix} = \begin{pmatrix} \sqrt{2} \\ -\sqrt{2} \end{pmatrix}$$

$$B_{\langle v \rangle} = \langle \varepsilon \rangle M_{\langle v \rangle} \vec{B} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}^T \begin{pmatrix} 2 \\ 0 \end{pmatrix} = \begin{pmatrix} -\sqrt{2} \\ \sqrt{2} \end{pmatrix}$$

$v^{(1)}$ and $v^{(2)}$ orthonormal

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(e) Write the PDF of the resulting Gaussian model in the new coordinate system and the standard coordinate system.

Gaussian PDF :

$$f(\mathbf{x}) = (2\pi)^{-\frac{k}{2}} \det(\mathbf{\Sigma})^{-\frac{1}{2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

- Standard coordinate system $\{ \boldsymbol{\sigma} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \mathbf{e}^{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \mathbf{e}^{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \}$:

$$\left. \begin{array}{l} \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \\ \mathbf{\Sigma} = \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} \end{array} \right\} f(\mathbf{x}) = ?$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(e) Write the PDF of the resulting Gaussian model in the new coordinate system and the standard coordinate system.

Gaussian PDF :

$$f(\mathbf{x}) = (2\pi)^{-\frac{k}{2}} \det(\Sigma)^{-\frac{1}{2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

- Standard coordinate system $\{\boldsymbol{o} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \mathbf{e}^{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \mathbf{e}^{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}\}$:

$$\begin{aligned} \boldsymbol{\mu} &= \begin{pmatrix} 2 \\ 0 \end{pmatrix} \\ \boldsymbol{\Sigma} &= \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} \end{aligned} \quad \left\{ \begin{aligned} f(\mathbf{x}) &= (2\pi)^{-1} \cdot \det \left(\frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} \right)^{-\frac{1}{2}} \cdot \exp \left[-\frac{1}{2} \left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} \right)^T \begin{pmatrix} \frac{20}{7} & \frac{-14}{7} \\ \frac{-14}{7} & \frac{20}{7} \end{pmatrix}^{-1} \left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} \right) \right] \end{aligned} \right.$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

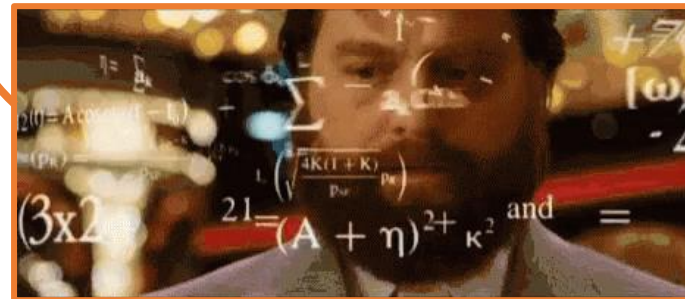
(e) Write the PDF of the resulting Gaussian model in the new coordinate system and the standard coordinate system.

Gaussian PDF :

$$f(\mathbf{x}) = (2\pi)^{-\frac{k}{2}} \det(\mathbf{\Sigma})^{-\frac{1}{2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

- Standard coordinate system $\{\boldsymbol{o} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \mathbf{e}^{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \mathbf{e}^{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}\}$:

$$\left. \begin{array}{l} \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \\ \mathbf{\Sigma} = \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} \end{array} \right\} f(\mathbf{x}) = (2\pi)^{-1} \cdot \det \left(\frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} \right)^{-\frac{1}{2}} \cdot \exp \left[-\frac{1}{2} \left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} \right)^T \begin{pmatrix} \frac{20}{7} & \frac{-14}{7} \\ \frac{-14}{7} & \frac{20}{7} \end{pmatrix}^{-1} \left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} \right) \right]$$



EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(e) Write the PDF of the resulting Gaussian model in the new coordinate system and the standard coordinate system.

Gaussian PDF :

$$f(\mathbf{x}) = (2\pi)^{-\frac{k}{2}} \det(\mathbf{\Sigma})^{-\frac{1}{2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

- New coordinate system $\left\{ \boldsymbol{\sigma} = \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}; \mathbf{v}^{(1)} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \mathbf{v}^{(2)} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$:

$$\left. \begin{aligned} \boldsymbol{\mu}_{<\mathbf{v}>} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ \mathbf{\Sigma}_{<\mathbf{v}>} &= \frac{1}{7} \begin{pmatrix} 34 & 0 \\ 0 & 6 \end{pmatrix} \end{aligned} \right\} f(\mathbf{x}) = ?$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(e) Write the PDF of the resulting Gaussian model in the new coordinate system and the standard coordinate system.

Gaussian PDF :

$$f(\mathbf{x}) = (2\pi)^{-\frac{k}{2}} \det(\Sigma)^{-\frac{1}{2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

- New coordinate system $\left\{ \boldsymbol{\sigma} = \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}; \mathbf{v}^{(1)} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \mathbf{v}^{(2)} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$:

$$\boldsymbol{\mu}_{<\mathbf{v}>} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Sigma_{<\mathbf{v}>} = \frac{1}{7} \begin{pmatrix} 34 & 0 \\ 0 & 6 \end{pmatrix}$$

$$f(\mathbf{x}) = (2\pi)^{-1} \cdot \det \left(\frac{1}{7} \begin{pmatrix} 34 & 0 \\ 0 & 6 \end{pmatrix} \right)^{-\frac{1}{2}} \cdot \exp \left[-\frac{1}{2} \left(\mathbf{x} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right)^T \left(\begin{pmatrix} \frac{34}{7} & 0 \\ 0 & \frac{6}{7} \end{pmatrix} \right)^{-1} \left(\mathbf{x} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right) \right]$$

$$\det \begin{pmatrix} \frac{34}{7} & 0 \\ 0 & \frac{6}{7} \end{pmatrix} = \lambda_1 \cdot \lambda_2 = \frac{34 \cdot 6}{7 \cdot 7}$$

$$\begin{pmatrix} \frac{34}{7} & 0 \\ 0 & \frac{6}{7} \end{pmatrix}^{-1} = \begin{pmatrix} \frac{34}{7}^{-1} & 0 \\ 0 & \frac{6}{7}^{-1} \end{pmatrix} = \begin{pmatrix} \frac{7}{34} & 0 \\ 0 & \frac{7}{6} \end{pmatrix}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(e) Write the PDF of the resulting Gaussian model in the new coordinate system and the standard coordinate system.

Gaussian PDF :

$$f(\mathbf{x}) = (2\pi)^{-\frac{k}{2}} \det(\Sigma)^{-\frac{1}{2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

- New coordinate system $\left\{ \boldsymbol{\sigma} = \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}; \mathbf{v}^{(1)} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \mathbf{v}^{(2)} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$:

$$\boldsymbol{\mu}_{<\mathbf{v}>} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Sigma_{<\mathbf{v}>} = \frac{1}{7} \begin{pmatrix} 34 & 0 \\ 0 & 6 \end{pmatrix}$$

$$f(\mathbf{x}) = (2\pi)^{-1} \cdot \frac{7}{2\sqrt{51}} \cdot \exp \left[-\frac{1}{2} \mathbf{x}^T \begin{pmatrix} \frac{7}{34} & 0 \\ 0 & \frac{7}{6} \end{pmatrix} \mathbf{x} \right]$$

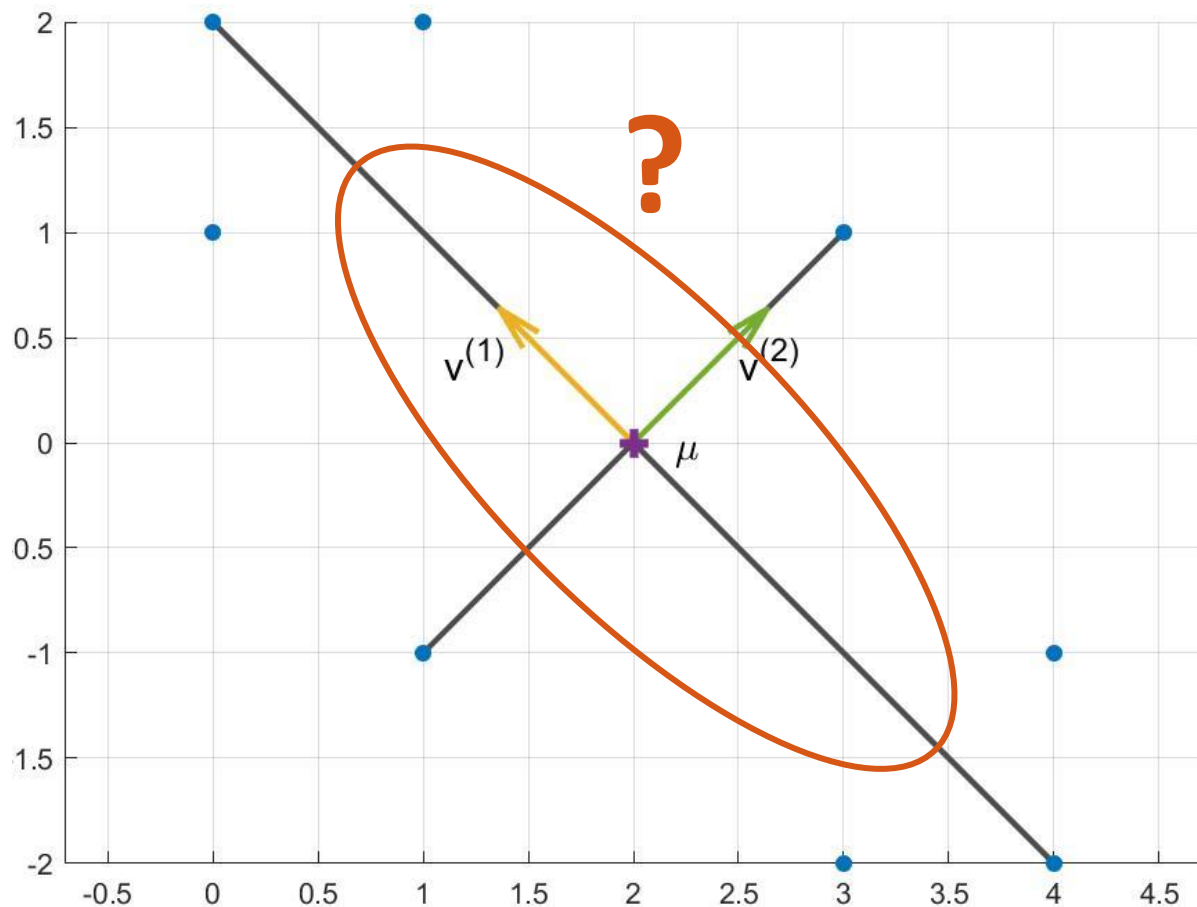


Should be written in the new coordinate system.

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(f) Draw the ellipses defined by the points with Mahalanobis distances equal to 1 and 2 (without computing it).



REMINDER

Equation of an ellipse

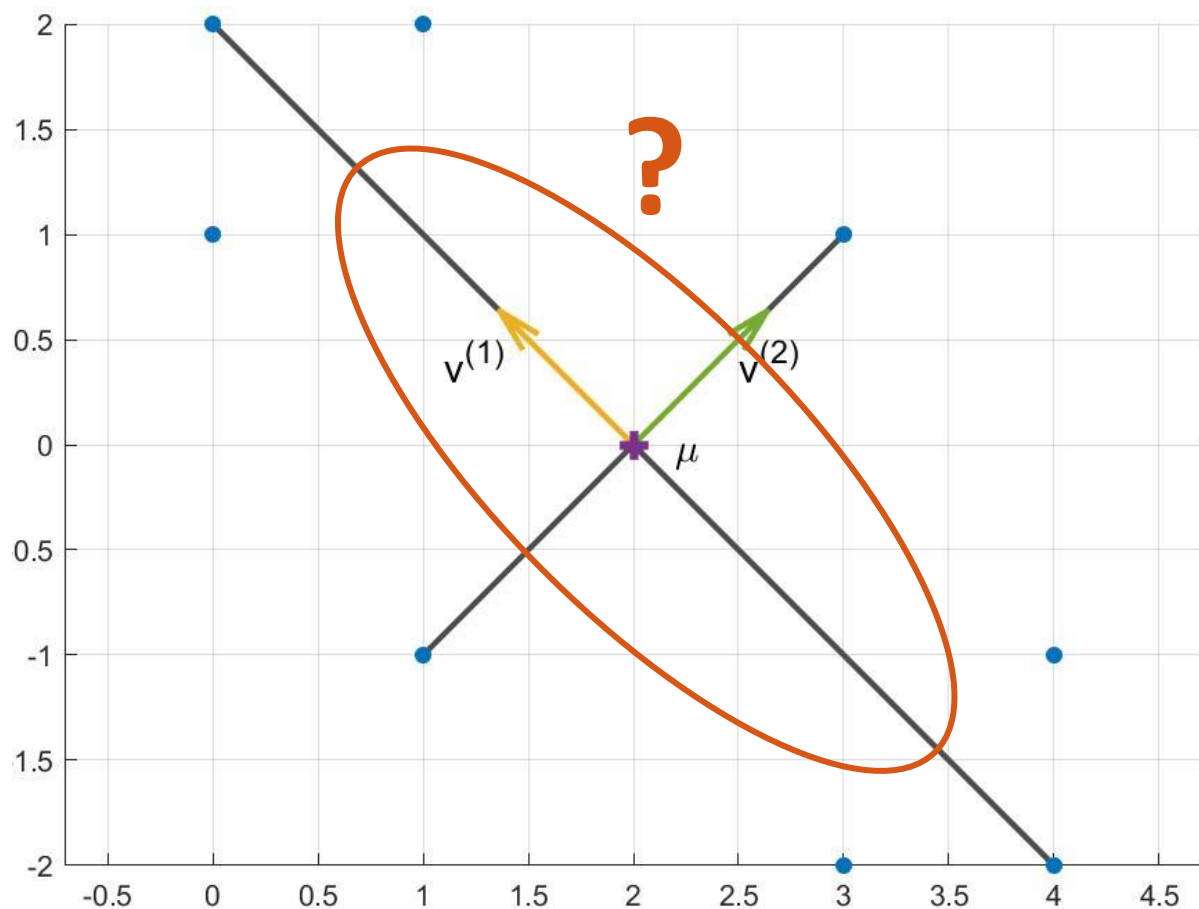
$$k^2 = \frac{x^2}{a^2} + \frac{y^2}{b^2} = d_{\text{Mah}}^2$$

$a, b, k?$

EXERCISE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(f) Draw the ellipses defined by the points with Mahalanobis distances equal to 1 and 2 (without computing it).



REMINDER

Equation of an ellipse

$$k^2 = \frac{x^2}{a^2} + \frac{y^2}{b^2} = d_{\text{Mah}}^2$$

→ $a, b, k?$

$$d_{\text{Mah}}^2 = (\mathbf{x} - \mathbf{m})^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \mathbf{m})$$

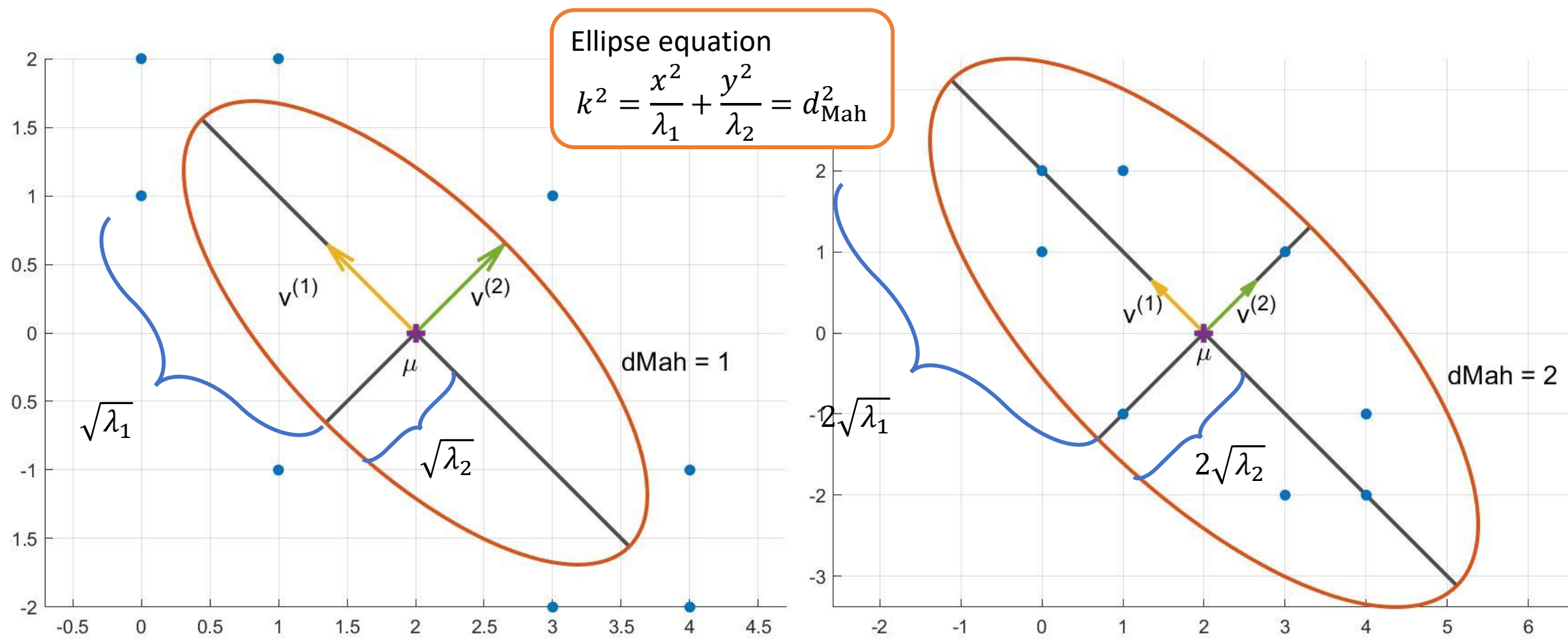
!
$$= \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}^{-1} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} \frac{1}{\lambda_1} & 0 \\ 0 & \frac{1}{\lambda_2} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \frac{x_1^2}{\lambda_1} + \frac{x_2^2}{\lambda_2}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(f) Draw the ellipses defined by the points with Mahalanobis distances equal to 1 and 2 (without computing it).



EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(g) Write the equation of the ellipse defined by the points at Mahalanobis distance 3 in the new coordinate system and the cartesian coordinate system.

Mahalanobis distance:
$$d(\mathbf{x}) = \sqrt{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})}$$

- Standard coordinate system $\left\{ \boldsymbol{o} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \mathbf{e}^{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \mathbf{e}^{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$:

$$\boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$\boldsymbol{\Sigma} = \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(g) Write the equation of the ellipse defined by the points at Mahalanobis distance 3 in the new coordinate system and the cartesian coordinate system.

Mahalanobis distance:

$$d(\mathbf{x}) = \sqrt{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})}$$

- Standard coordinate system $\{\boldsymbol{\sigma} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \mathbf{e}^{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \mathbf{e}^{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}\}$:

$$\boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$\boldsymbol{\Sigma} = \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix}$$

$$d(\mathbf{x}) = \sqrt{\left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix}\right)^T \begin{pmatrix} \frac{20}{7} & \frac{-14}{7} \\ \frac{-14}{7} & \frac{20}{7} \end{pmatrix}^{-1} \left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix}\right)}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(g) Write the equation of the ellipse defined by the points at Mahalanobis distance 3 in the new coordinate system and the cartesian coordinate system.

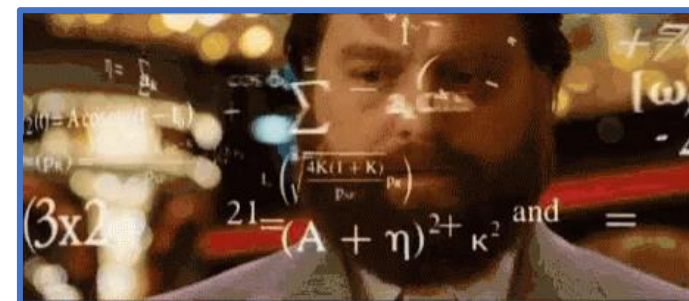
Mahalanobis distance:

$$d(\mathbf{x}) = \sqrt{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})}$$

- Standard coordinate system $\{\boldsymbol{\sigma} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \mathbf{e}^{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \mathbf{e}^{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}\}$:

$$\left. \begin{array}{l} \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \\ \boldsymbol{\Sigma} = \frac{1}{7} \begin{pmatrix} 20 & -14 \\ -14 & 20 \end{pmatrix} \end{array} \right\} d(\mathbf{x}) = \sqrt{\left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix}\right)^T \begin{pmatrix} \frac{20}{7} & \frac{-14}{7} \\ \frac{-14}{7} & \frac{20}{7} \end{pmatrix}^{-1} \left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix}\right)}$$

$$\Rightarrow 3^2 = d(\mathbf{x})^2 = \left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix}\right)^T \begin{pmatrix} \frac{20}{7} & \frac{-14}{7} \\ \frac{-14}{7} & \frac{20}{7} \end{pmatrix}^{-1} \left(\mathbf{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix}\right) = \dots\dots\dots$$



EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(g) Write the equation of the ellipse defined by the points at Mahalanobis distance 3 in the new coordinate system and the cartesian coordinate system.

Mahalanobis distance:

$$d(\mathbf{x}) = \sqrt{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})}$$

- New coordinate system $\left\{ \boldsymbol{\sigma} = \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}; \mathbf{v}^{(1)} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \mathbf{v}^{(2)} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$:

$$\boldsymbol{\mu}_{<\mathbf{v}>} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\boldsymbol{\Sigma}_{<\mathbf{v}>} = \frac{1}{7} \begin{pmatrix} 34 & 0 \\ 0 & 6 \end{pmatrix}$$

$$d(\mathbf{x}) = \sqrt{\left(\mathbf{x} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right)^T \begin{pmatrix} \frac{34}{7} & 0 \\ 0 & \frac{6}{7} \end{pmatrix}^{-1} \left(\mathbf{x} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right)}$$

$$\begin{pmatrix} \frac{34}{7} & 0 \\ 0 & \frac{6}{7} \end{pmatrix}^{-1} = \begin{pmatrix} \frac{34}{7}^{-1} & 0 \\ 0 & \frac{6}{7}^{-1} \end{pmatrix} = \begin{pmatrix} \frac{7}{34} & 0 \\ 0 & \frac{7}{6} \end{pmatrix}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(g) Write the equation of the ellipse defined by the points at Mahalanobis distance 3 in the new coordinate system and the cartesian coordinate system.

Mahalanobis distance:

$$d(\mathbf{x}) = \sqrt{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})}$$

- New coordinate system $\left\{ \boldsymbol{\sigma} = \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}; \mathbf{v}^{(1)} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \mathbf{v}^{(2)} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$:

$$\left. \begin{aligned} \boldsymbol{\mu}_{<\mathbf{v}>} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ \boldsymbol{\Sigma}_{<\mathbf{v}>} &= \frac{1}{7} \begin{pmatrix} 34 & 0 \\ 0 & 6 \end{pmatrix} \end{aligned} \right\} d(\mathbf{x}) = \sqrt{\left(\mathbf{x} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right)^T \begin{pmatrix} \frac{7}{34} & 0 \\ 0 & \frac{7}{6} \end{pmatrix} \left(\mathbf{x} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right)}$$

$$\Rightarrow 3^2 = d(\mathbf{x})^2 = \mathbf{x}^T \begin{pmatrix} \frac{7}{34} & 0 \\ 0 & \frac{7}{6} \end{pmatrix} \mathbf{x} = \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} \frac{7}{34} & 0 \\ 0 & \frac{7}{6} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \frac{7 \cdot x_1^2}{34} + \frac{7 \cdot x_2^2}{6} \Rightarrow 9 = \frac{x_1^2}{34/7} + \frac{x_2^2}{6/7}$$

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(g) Write the equation of the ellipse defined by the points at Mahalanobis distance 3 in the new coordinate system and the cartesian coordinate system.

Mahalanobis distance:

$$d(\mathbf{x}) = \sqrt{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})}$$

- New coordinate system $\left\{ \boldsymbol{\sigma} = \boldsymbol{\mu} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}; \mathbf{v}^{(1)} = \frac{\sqrt{2}}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \mathbf{v}^{(2)} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$:

$$\boldsymbol{\mu}_{<\mathbf{v}>} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\boldsymbol{\Sigma}_{<\mathbf{v}>} = \frac{1}{7} \begin{pmatrix} 34 & 0 \\ 0 & 6 \end{pmatrix}$$

$$d(\mathbf{x}) = \sqrt{\left(\mathbf{x} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right)^T \begin{pmatrix} \frac{7}{34} & 0 \\ 0 & \frac{7}{6} \end{pmatrix} \left(\mathbf{x} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right)}$$

$$9 = \frac{x_1^2}{34/7} + \frac{x_2^2}{6/7}$$

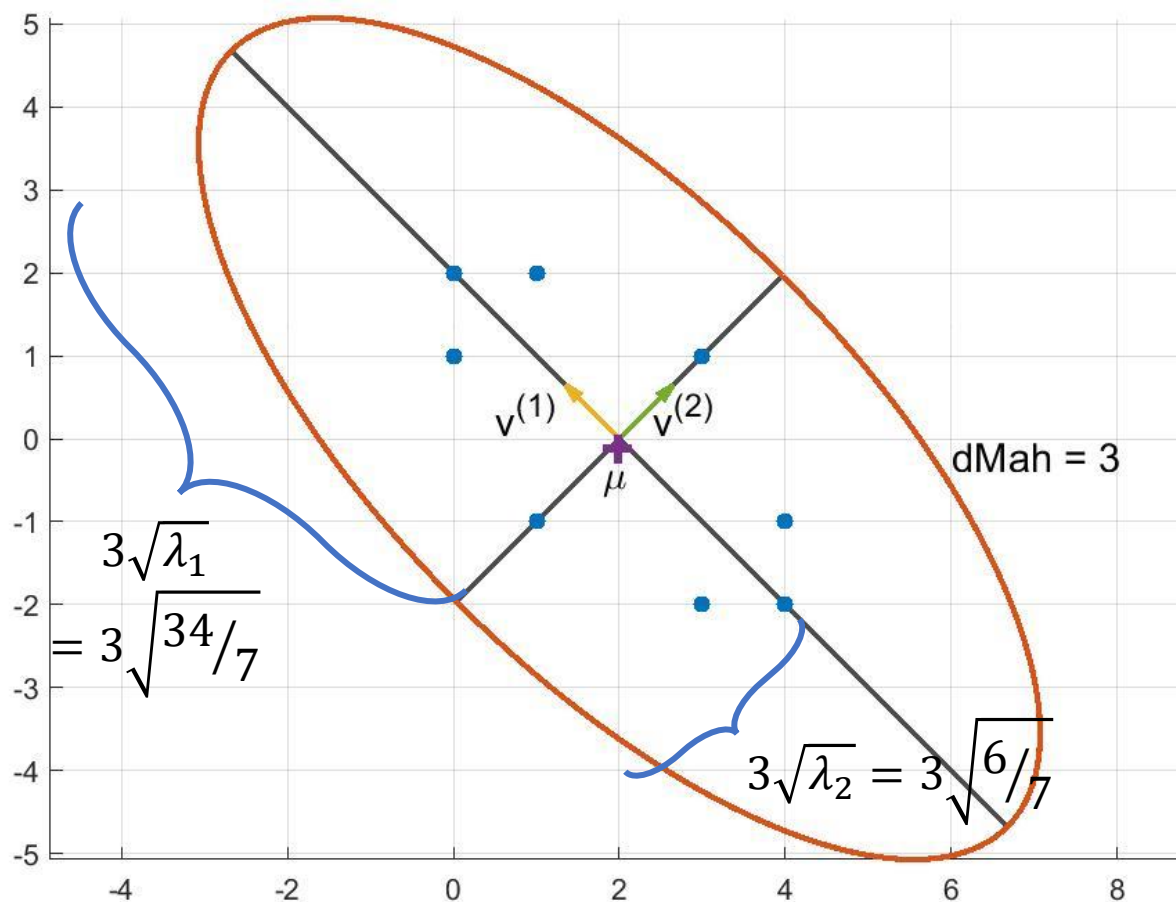
$$k^2 = \frac{x_1^2}{\lambda_1} + \frac{x_2^2}{\lambda_2}$$

Ellipse of Mahalanobis distance equal to k

EXERCICE 2

$$\left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 4 \\ -1 \end{pmatrix}, \begin{pmatrix} 4 \\ -2 \end{pmatrix} \right\} \subset \mathbb{R}^2$$

(g) Write the equation of the ellipse defined by the points at Mahalanobis distance 3 in the new coordinate system and the cartesian coordinate system.



Ellipse equation

$$9 = \frac{x_1^2}{34/7} + \frac{x_2^2}{6/7}$$