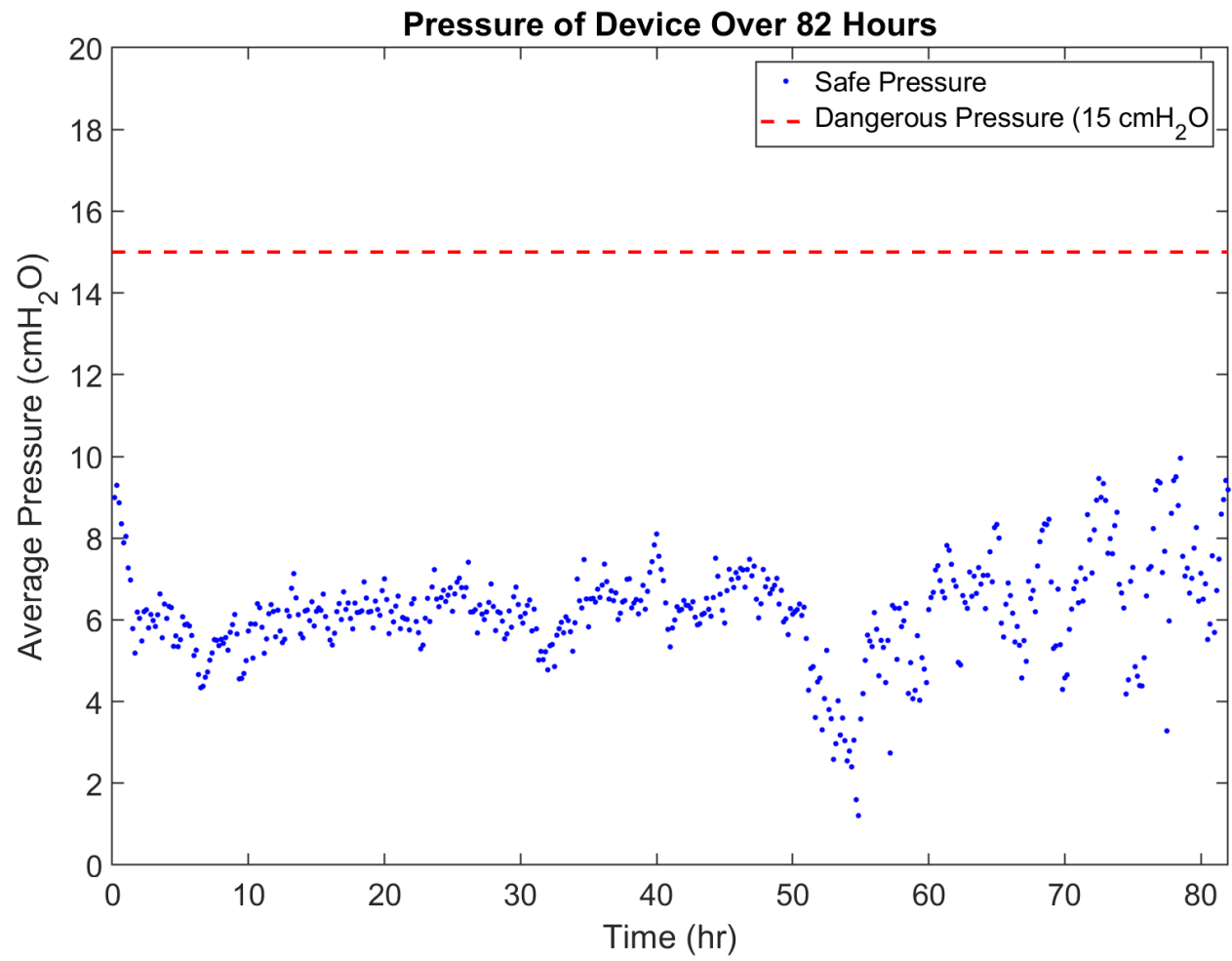


This is before accounting for sensor drift.



Data after sensor drift is removed