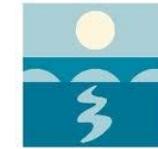




NUI Galway
OÉ Gaillimh



Ryan
Institute

Modelica Model Use During Operations: Learnings from the Annex 60

Raymond Sterling

27th October 2016

*Informatics Research Unit for Sustainable Engineering (IRUSE) Galway
Department of Civil Engineering and Ryan Institute
National University of Ireland, Galway*

GENSIM Scientific School. Corsica, France

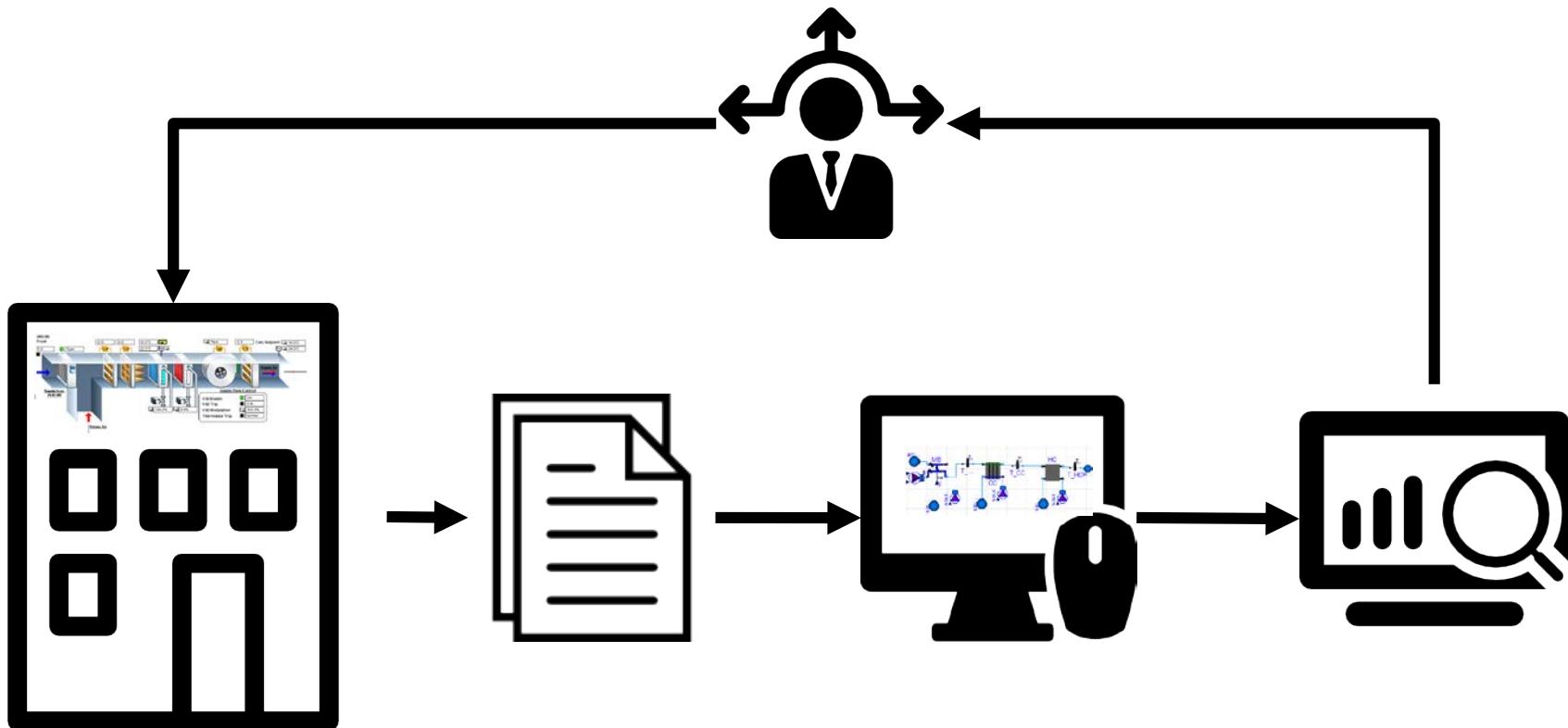
What is model use during operations?



- Use of models in conjunction with real data to understand and/or improve the performance of a system.
 - Model can be used offline, online or inline

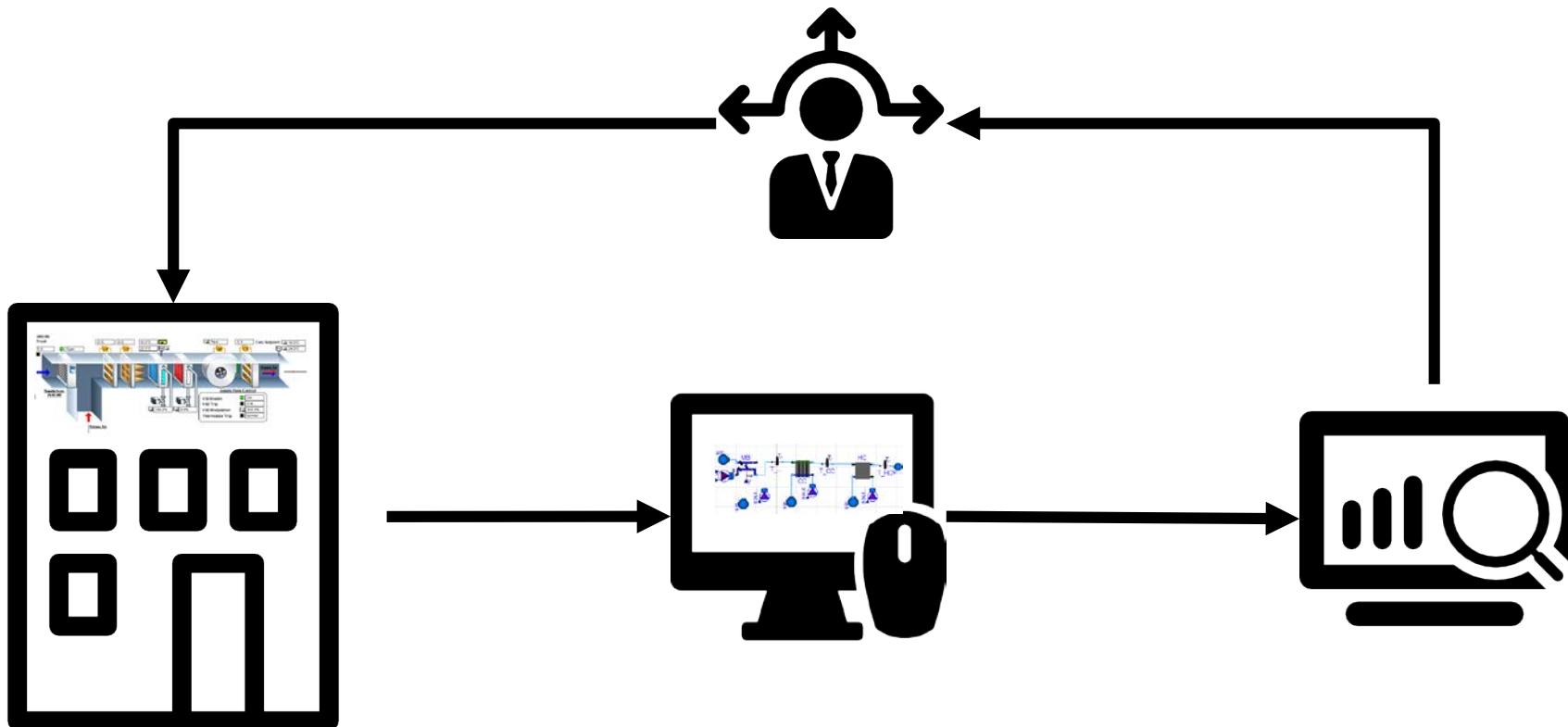
Model use during operations - offline

3

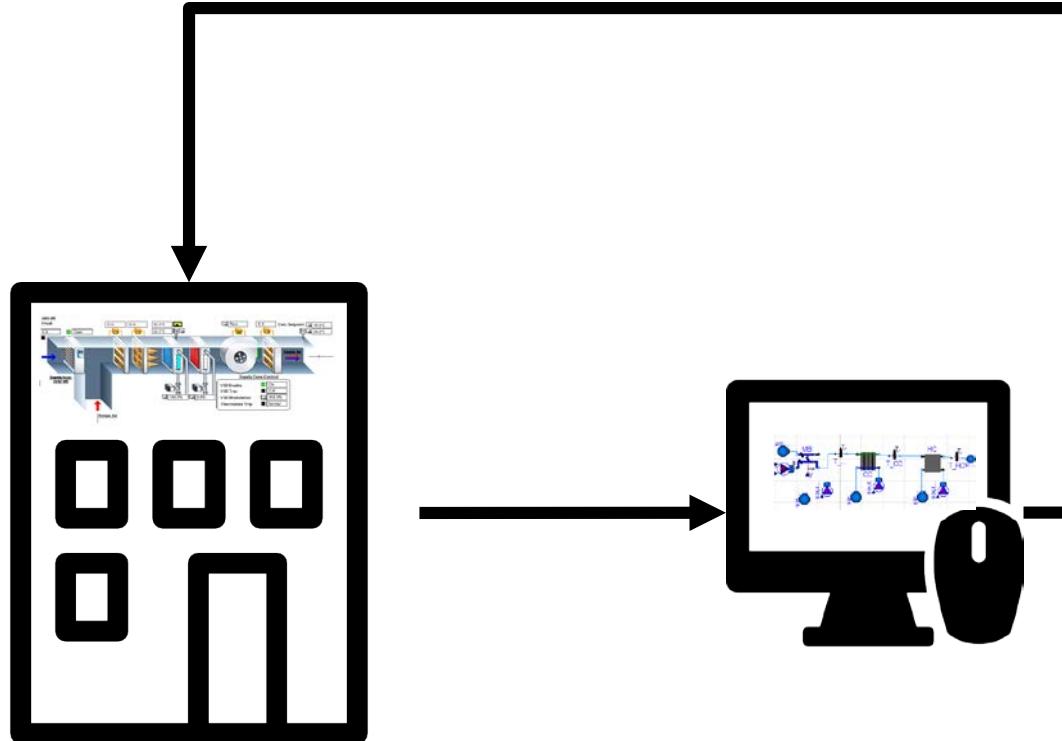


Model use during operations - online

4



Model use during operations - inline

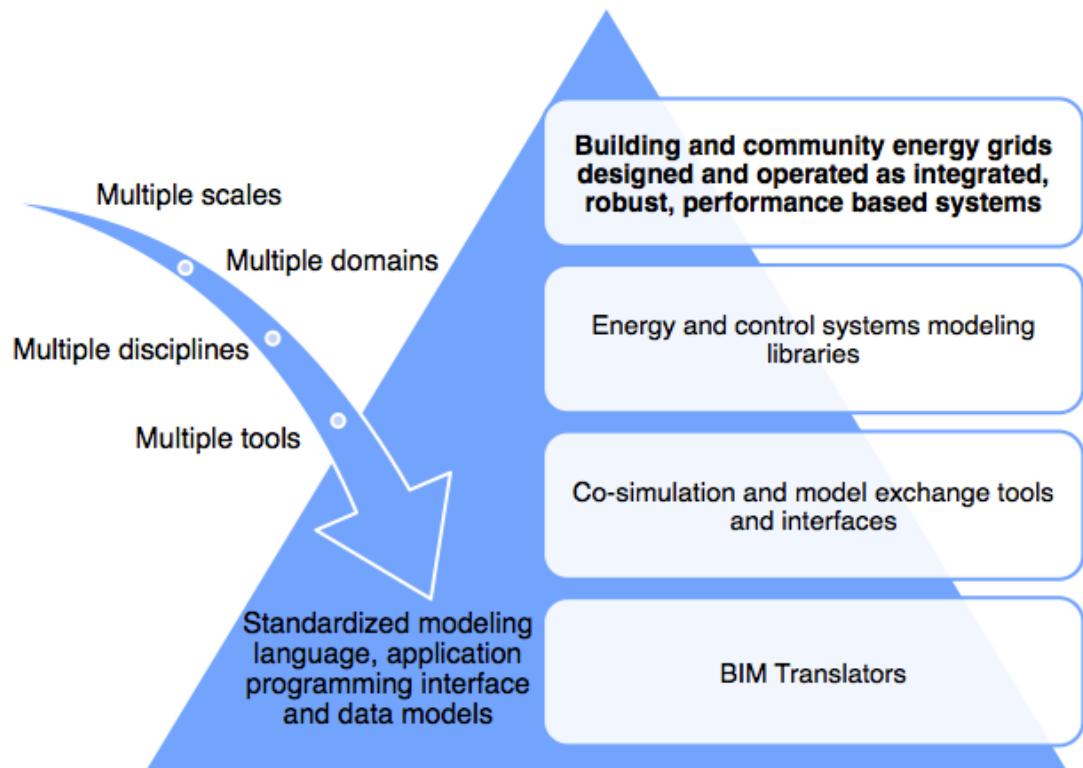


Typical issues

- Data quality
- Data quantity
- Access to data
- Access to documentation
- Availability for experimentation
- Cost of experimentation
- ...

The Annex 60

- The IEA EBC Annex 60 is developing and demonstrating new generation computational tools for building and community energy systems based on the non-proprietary Modelica modelling language and Functional Mock-up Interface standards.
- Activity 2.3 focuses on the use of models during building operations to augment monitoring, implement control algorithms and fault detection, and diagnostics methods



Activity 2.3 focus areas & projects

8

MPC

UNIVPM

KU Leuven

University of
Miami

HIL

University of
Alabama

FDD

Fraunhofer ISE

LBNL

NUI Galway

KU Leuven

Model Predictive Control

- Use the model of the system to predict the future evolution.
Some advantages:



Explicitly formulates constraints



Explicitly uses a Model



Well understood tuning parameters



Less development time for complex systems

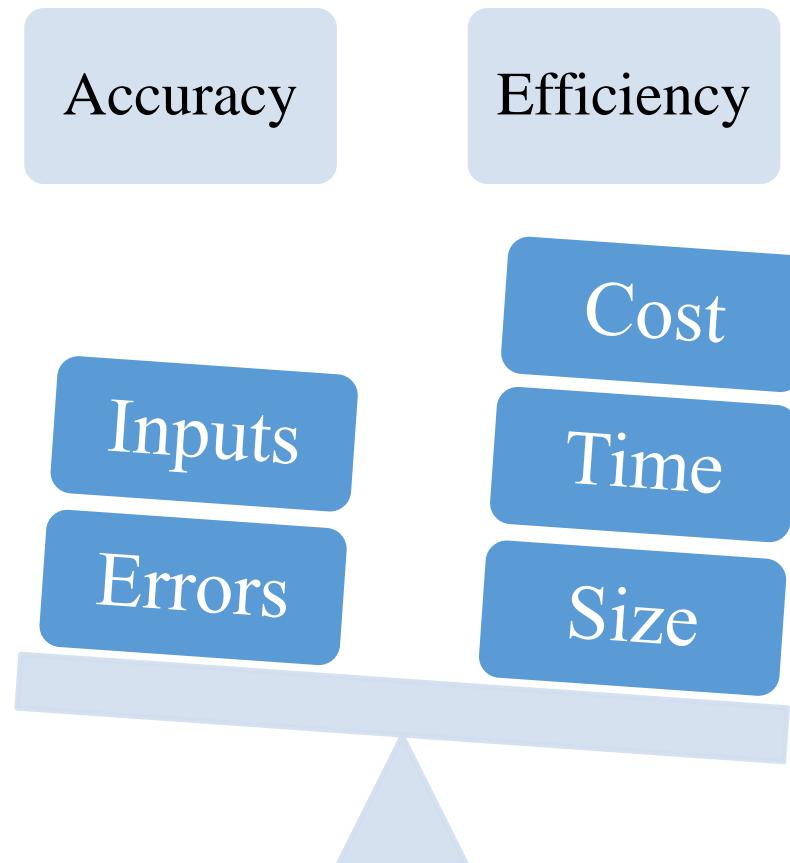


Improved prediction capability



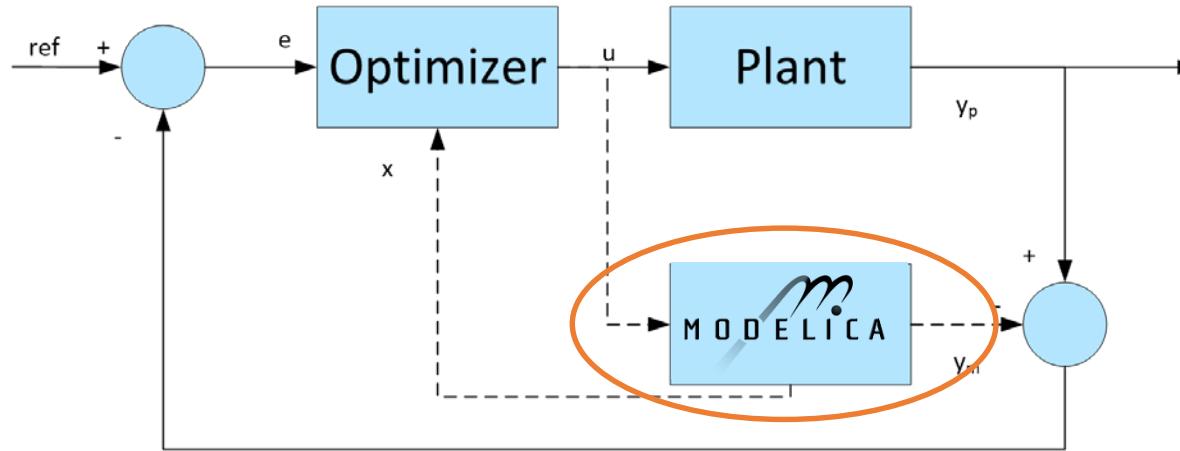
Adaptability to varying conditions

Modelling for MPC – A balance

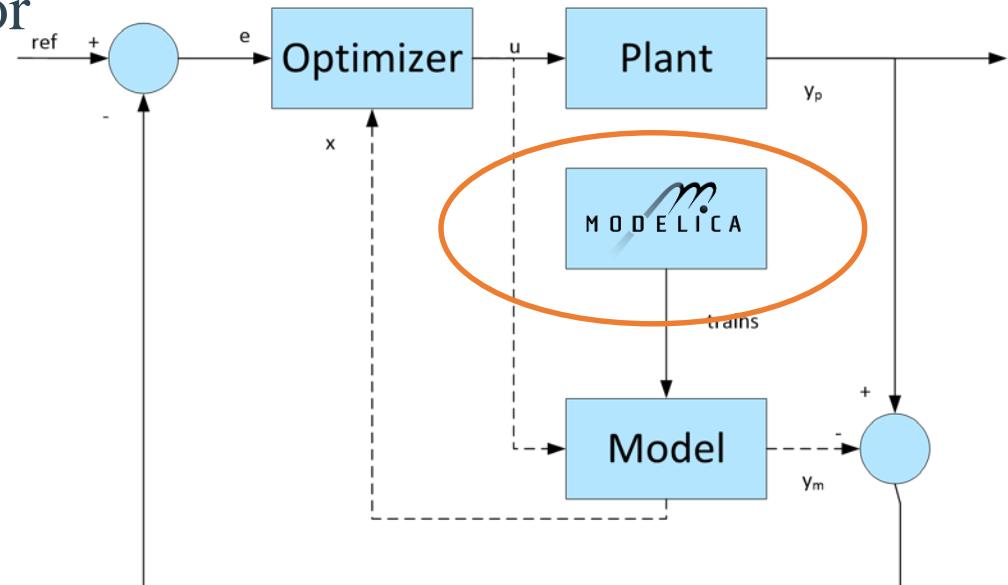


Modelica in the MPC Workflow Options

- Modelica model inline use

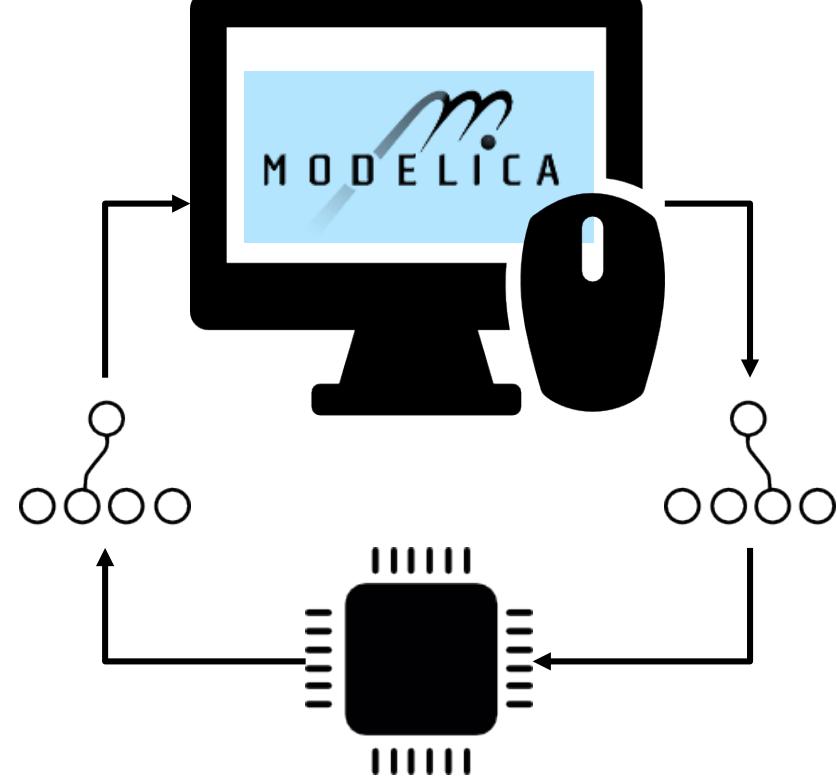


- Model as data generator for offline training



Hardware in the Loop (inline)

- Is a form of real time simulation that connects a model to hardware normally to test performance on emulated behaviour



HiL
testing

In plant
testing

+ Reliability &
quality & safety

+ efficient
development

- innovation
costs

- test costs

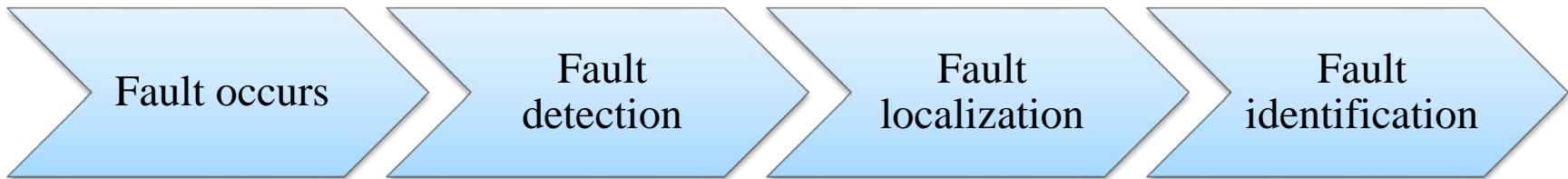
- Availability

- Variation &
Repeatability

+ failure & test
costs

Fault Detection and Diagnosis

- (Automated) Realisation of performance lost and determination of root causes.
- The FDD process



- Measured values are different from model predicted ones
- Each component is checked for intended operation
- The ‘localized’ component is checked against a set of possible fault (covering the whole set of possible misbehaviours is normally non-practical)

FDD Advantages and Disadvantages

14

Advantages

Improved reliability

Reduced maintenance needs

Improved performance

Challenges

Ease of use & Costs

Adaptability & robustness

Isolation & Identification

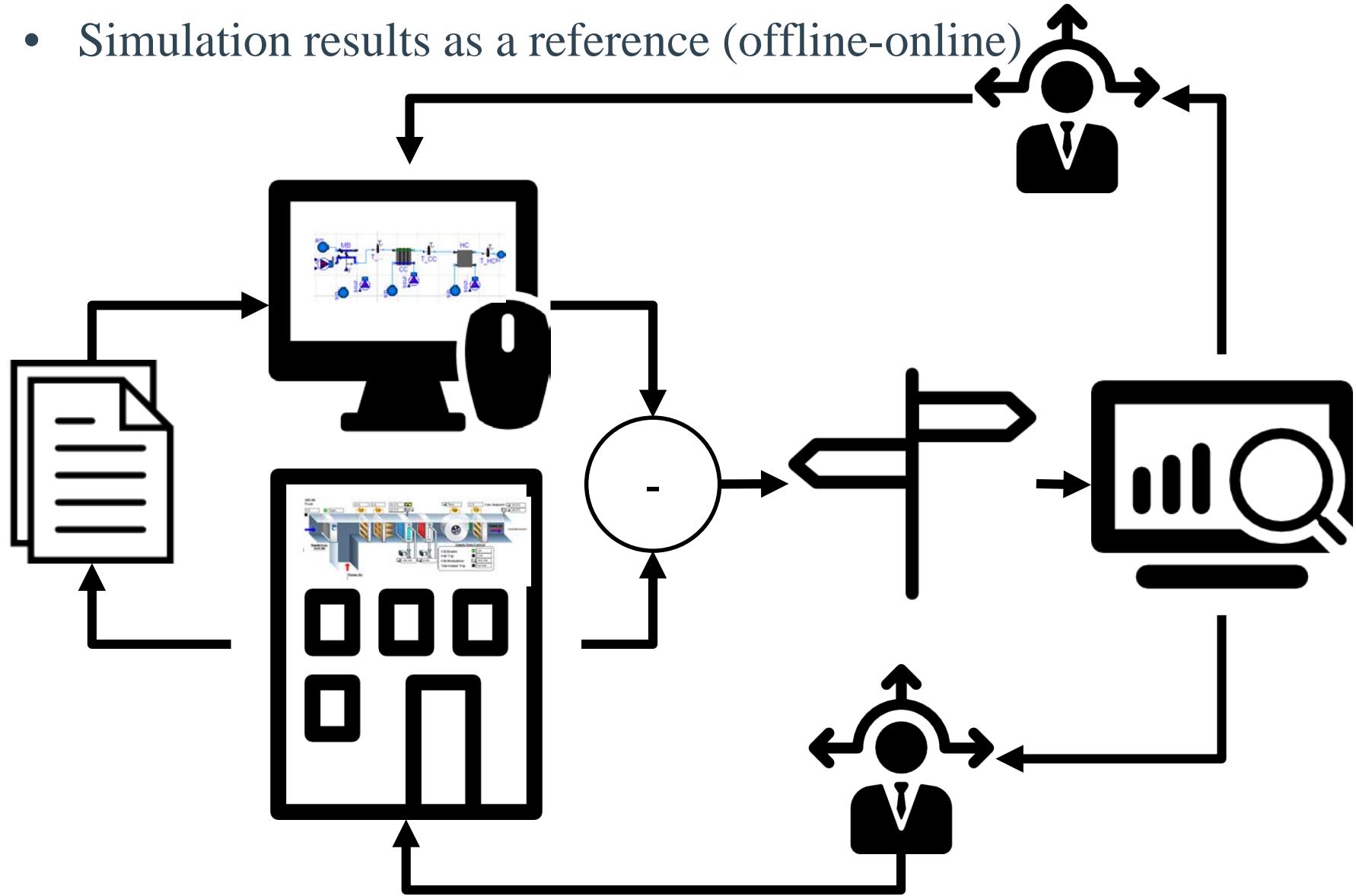
Computational requirement



Modelica in the FDD workflow

15

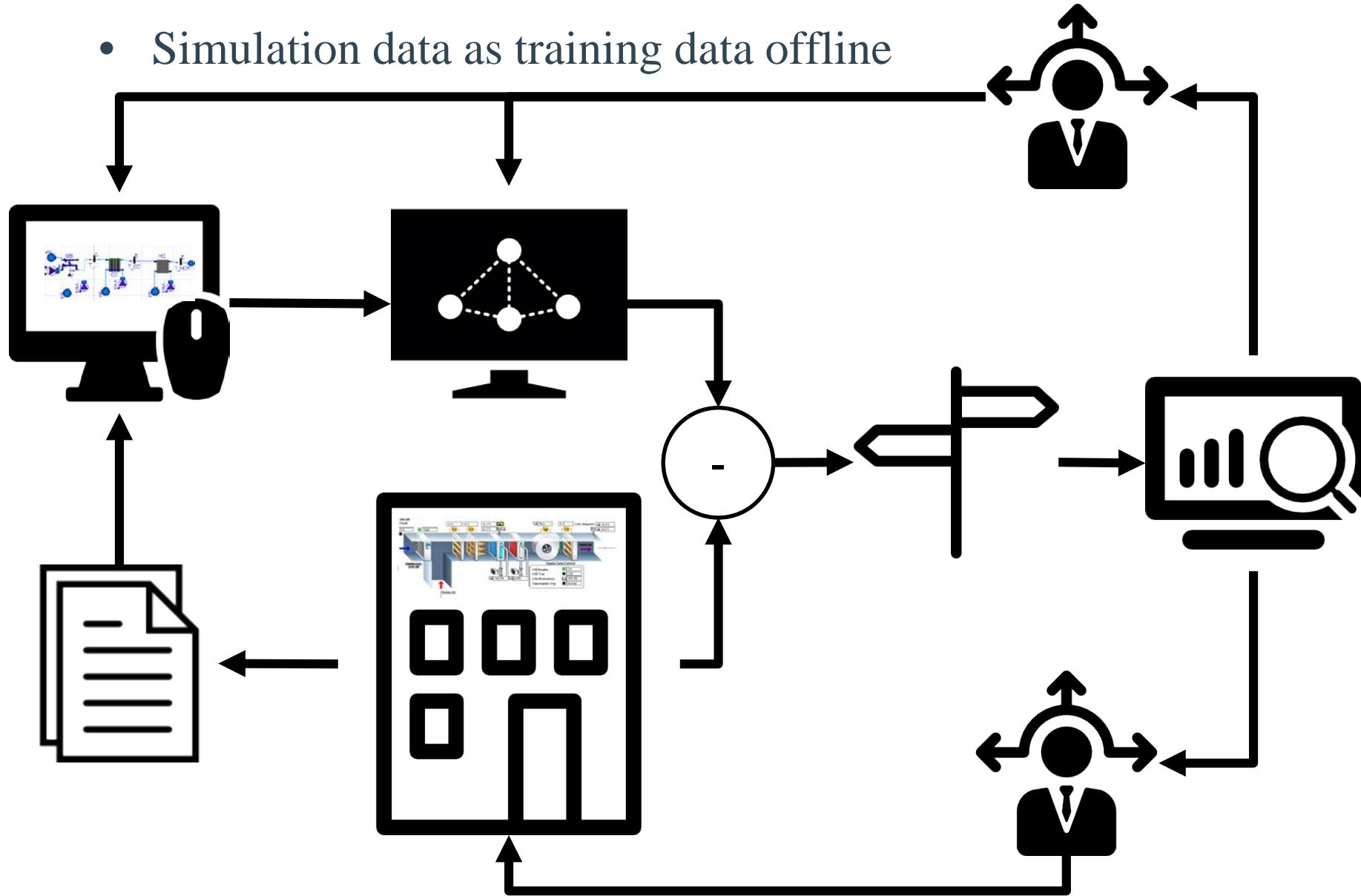
- Simulation results as a reference (offline-online)



Modelica in the FDD workflow

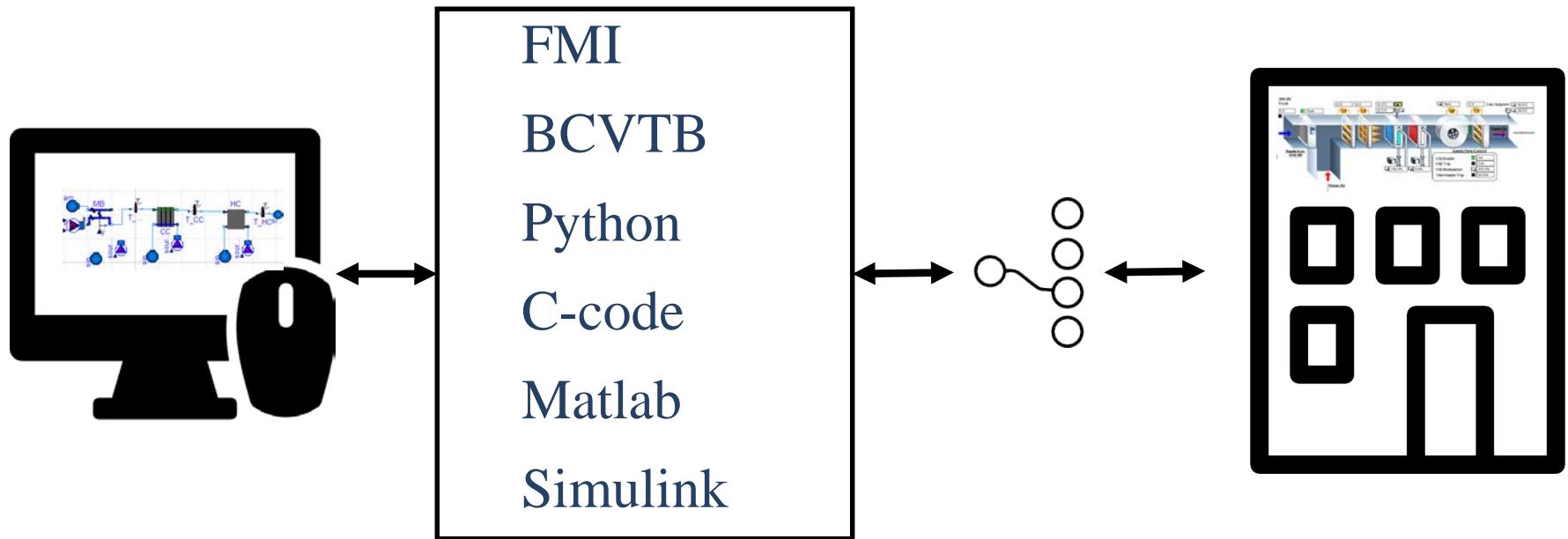
16

- Simulation data as training data offline



Some Modelica Interfacing Options

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Case Studies

18

MPC

Energy Control
Underground Public
Spaces

Chiller Plant

Heat Pumps

HIL

HVAC close-loop
control

FDD

AHU FD

Chillers in District
Cooling

AHU FDD
Automated Reasoning

AHU FDD Grey Box

MPC

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Underground Public
Spaces**

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Heat Pumps

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control

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AHU FD

Chillers in District
Cooling

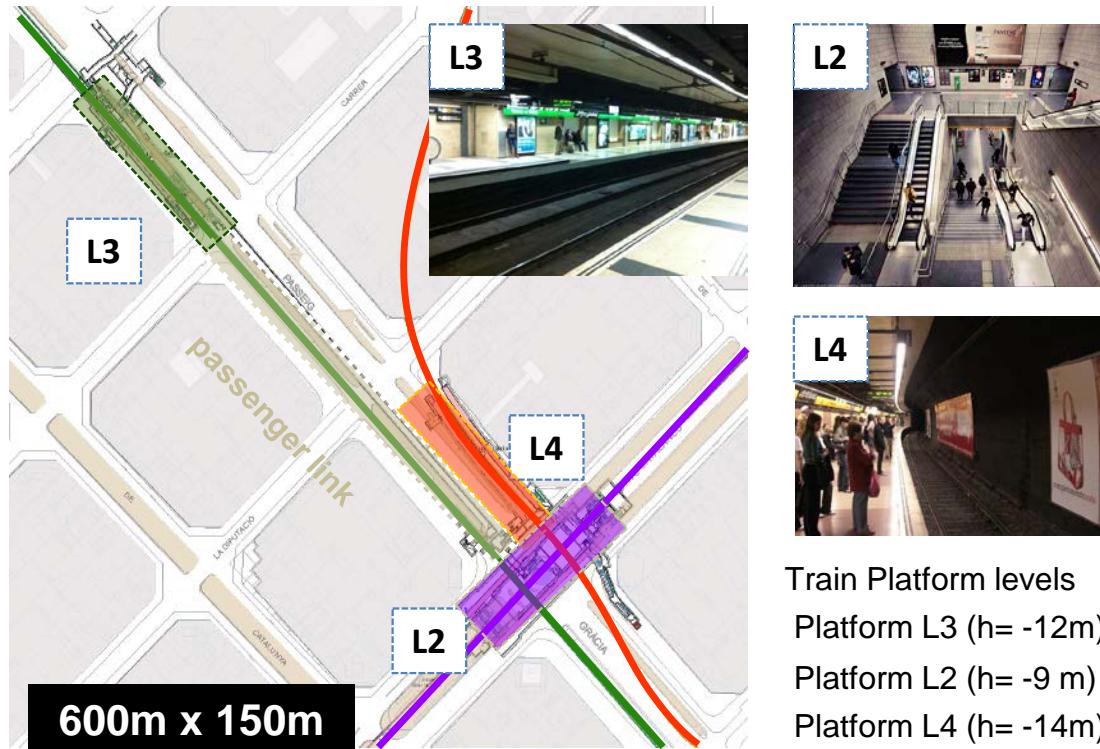
AHU FDD
Automated Reasoning

AHU FDD Grey Box

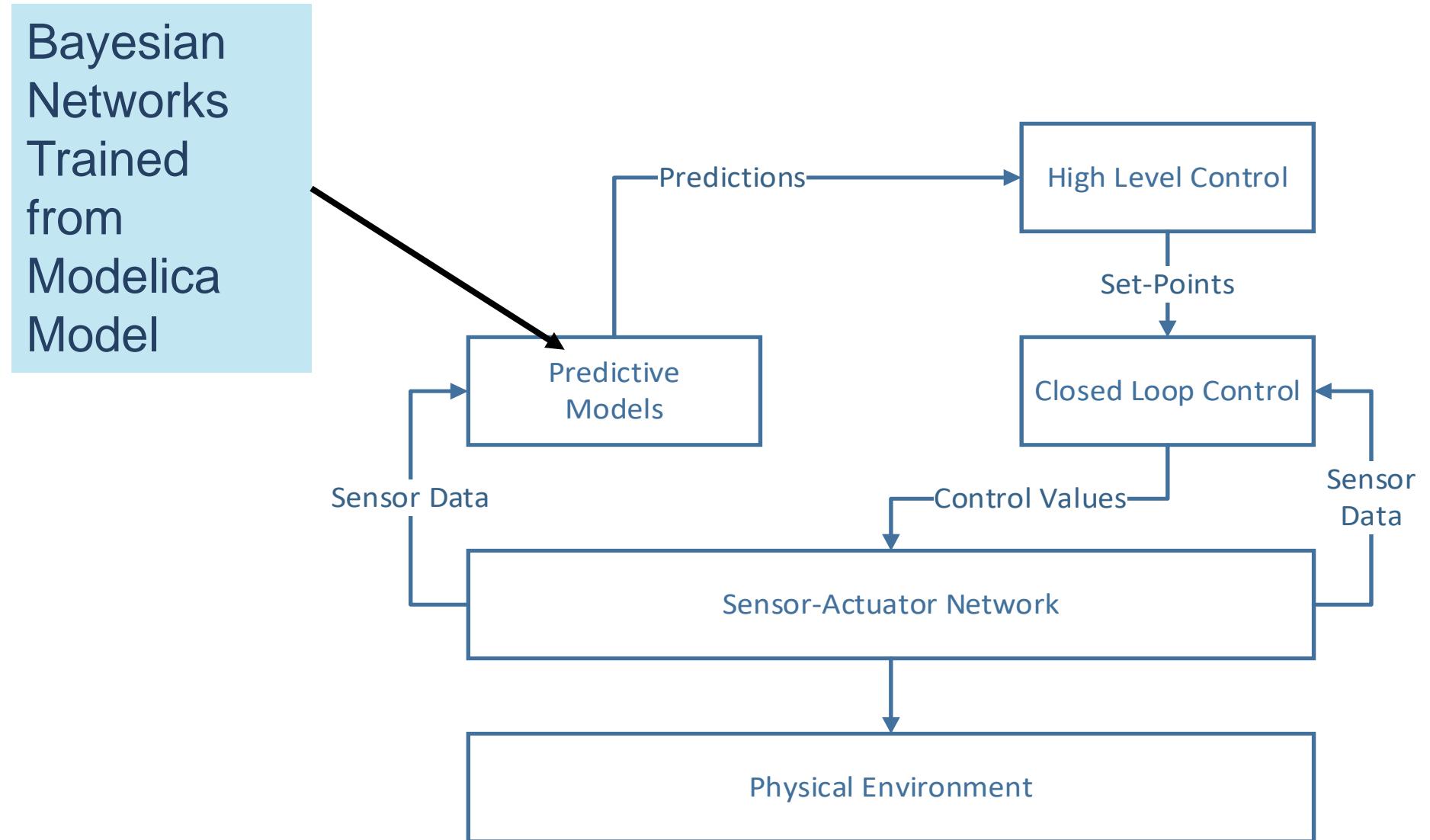
Energy control of underground public spaces

20

This case study concerns the SEAM4US EU FP7 project (SEAM4US, 2014) pilot that has been deployed, since August 2014, in the Passeig de Gracia (PdG) Line 3 metro Station in Barcelona, Spain.

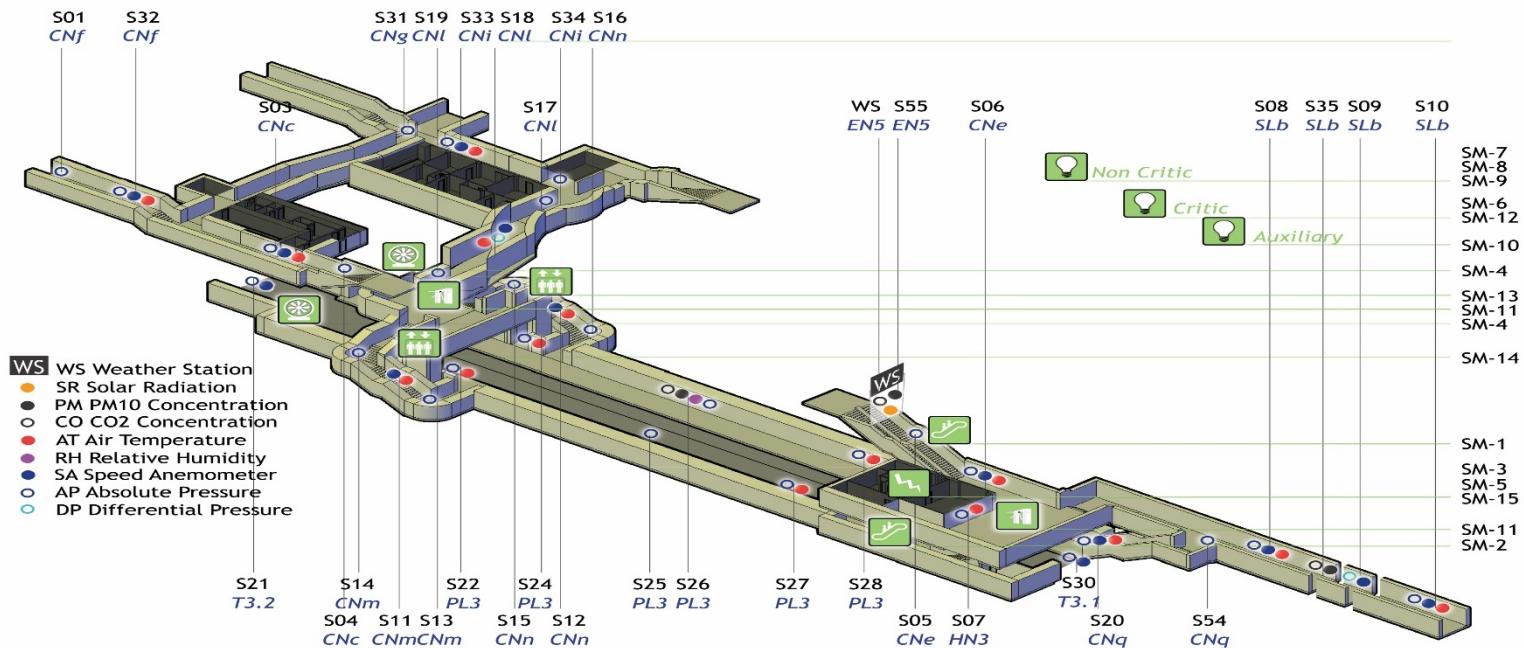


SEAM4US MPC Framework - offline



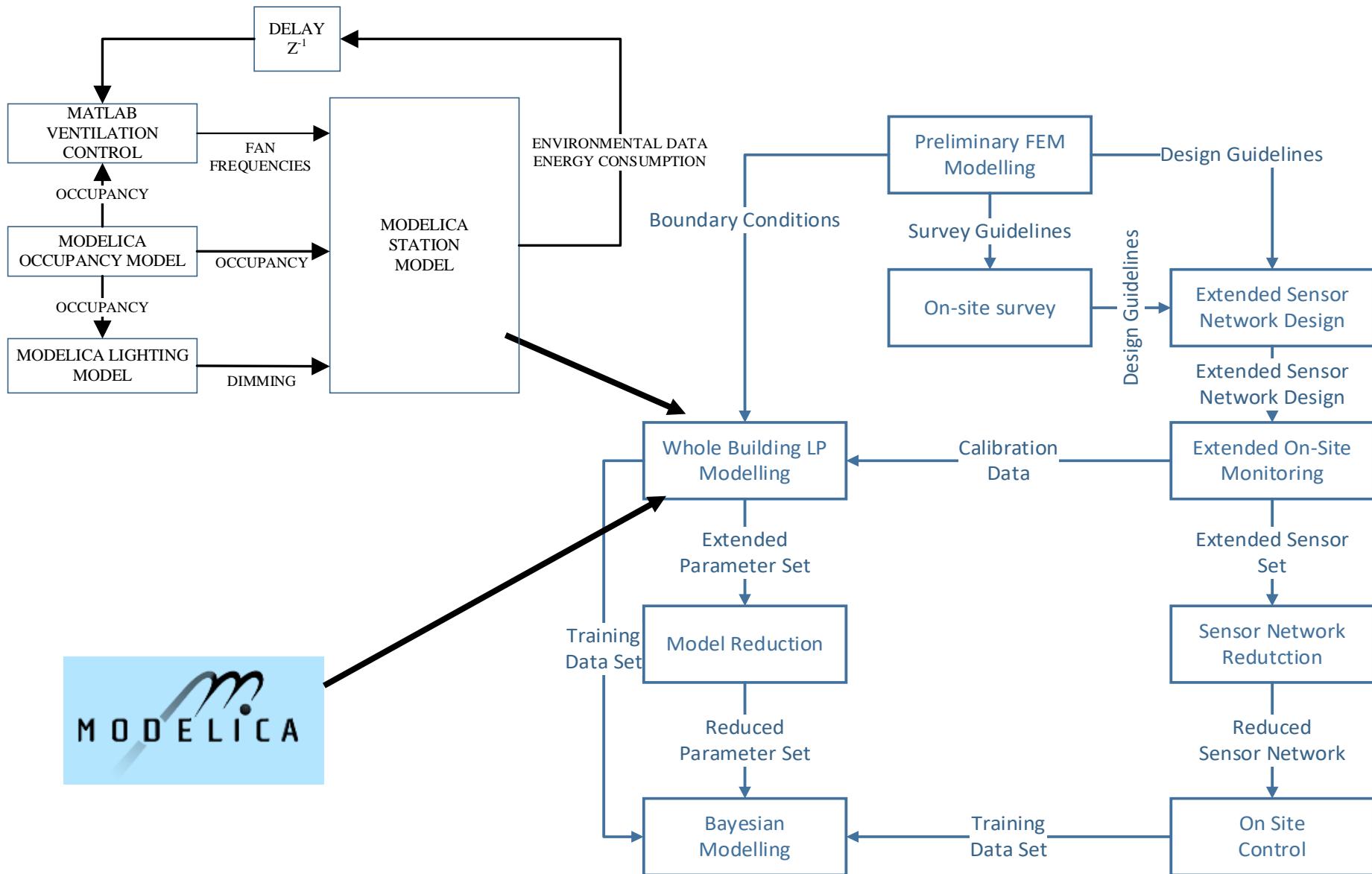
SEAM4US Monitoring Framework

- The deployed environmental sensor network amounts at 80 sensors, including air and surface temperatures, air speed, air pressure, humidity, CO₂ and PM10 concentration, and a weather station.
- 35 will be used for controlling the station equipment, the others provide redundancy and calibration support



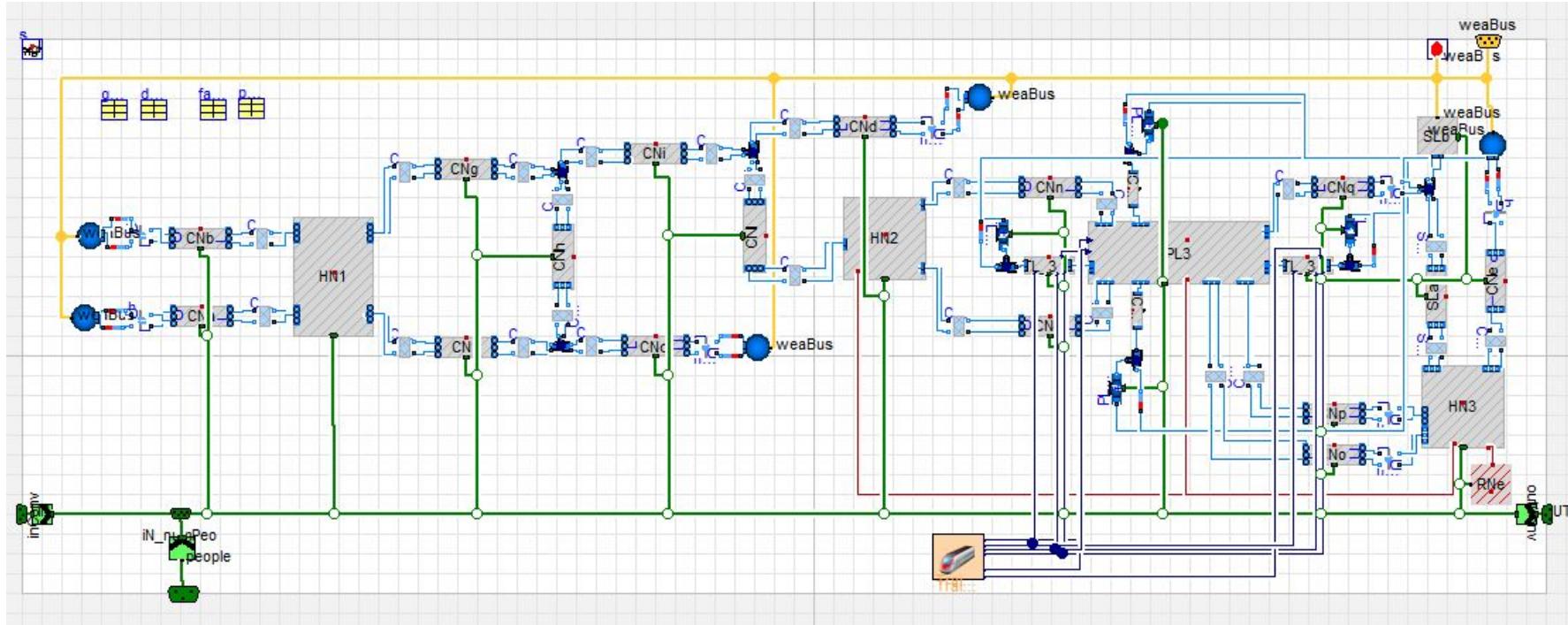
The SEAM4US model-engineering framework

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The SEAM4US Modelica Model

- The Modelica Station Model is a large model, the integration generates 38384 unknowns /equations based on Buildings Library
- The model is used to produce scenarios for training the reduced statistical model and for decision support.



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Cooling

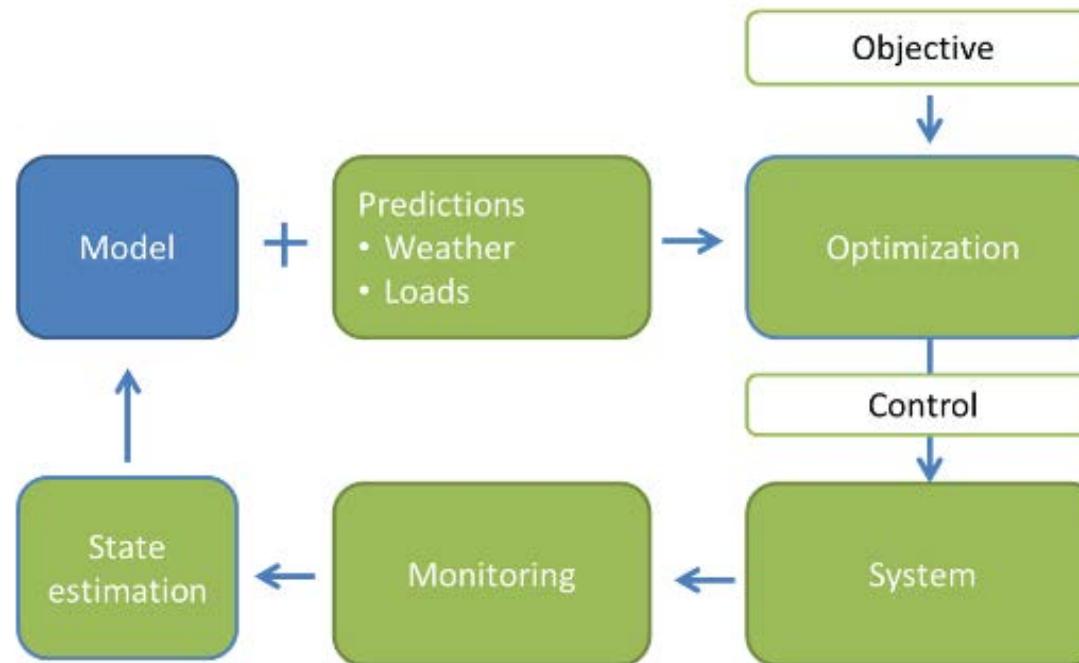
AHU FDD
Automated Reasoning

AHU FDD Grey Box

MPC for heat pumps - online

27

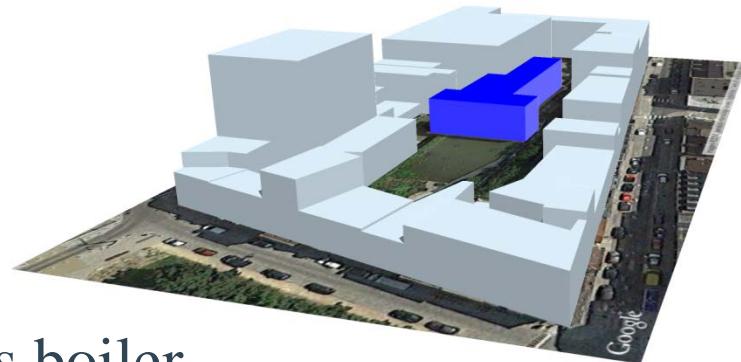
- In this case study, we developed an MPC approach to optimize the heat production of two identical heat pumps and a gas boiler. We have implemented and tested the MPC (using the Modelica environment) at the headquarters office building of 3E which is located in the center of Brussels, Belgium.



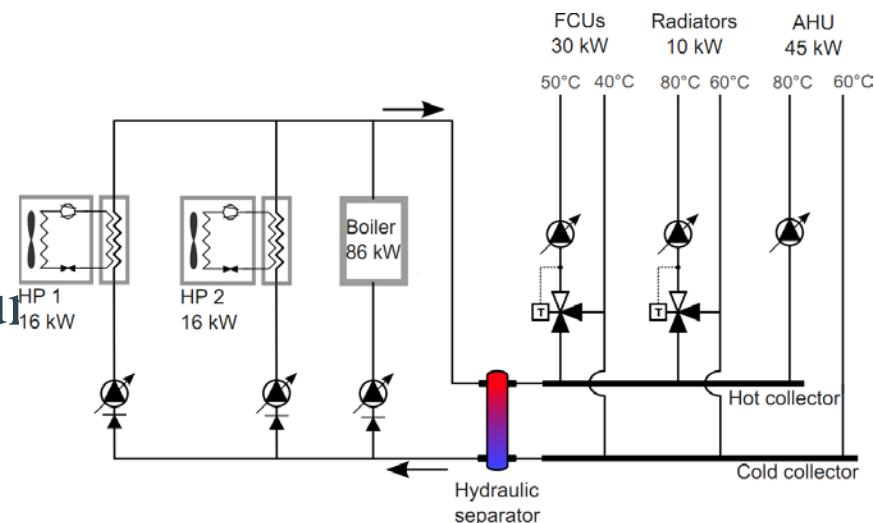
Cascade heat production to heat office building

28

- Office building, Brussels
- 50-70 occ
- ~1000m² conditioned surface

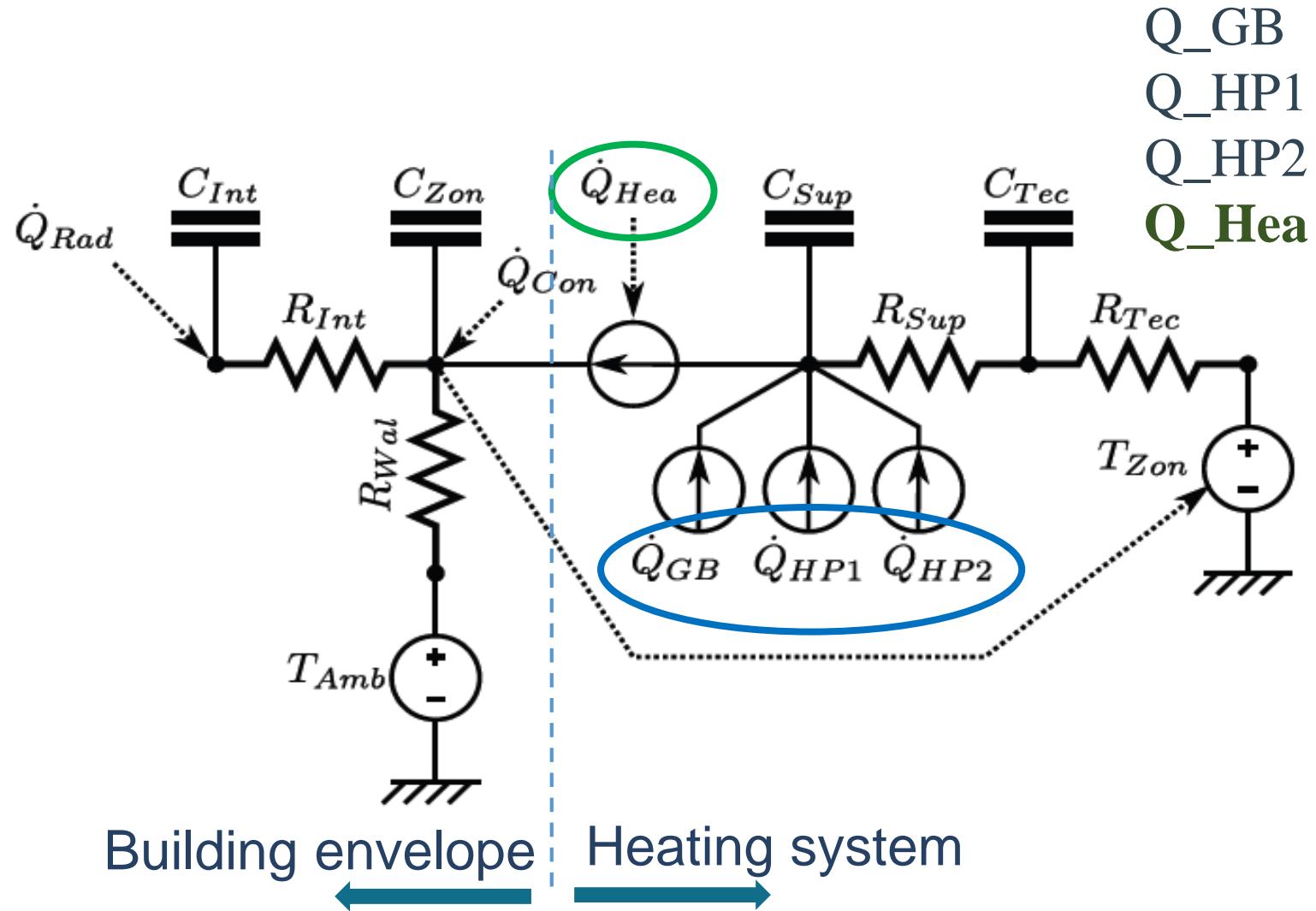


- PRODUCTION:
16 kWth heat pump (2x) 87kW gas boiler
- EMISSION:
FCU units in zones
AHU unit
- Zone temperatures: comfort bound



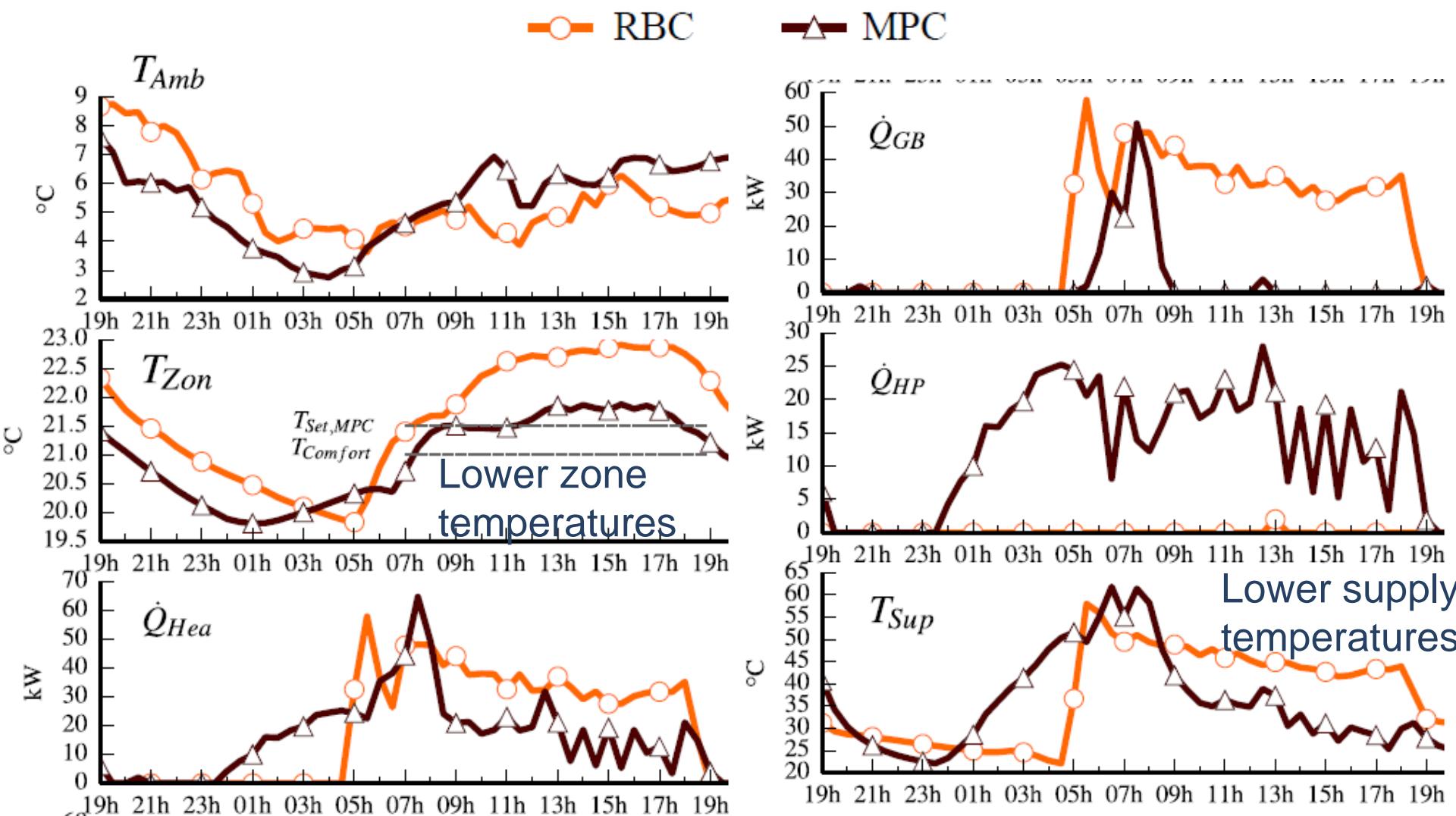
Control model building envelope

- 4 control variables in optimal control problem (OCP)



Zone temperature is controlled better and gas boiler is used less

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control

FDD

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Cooling

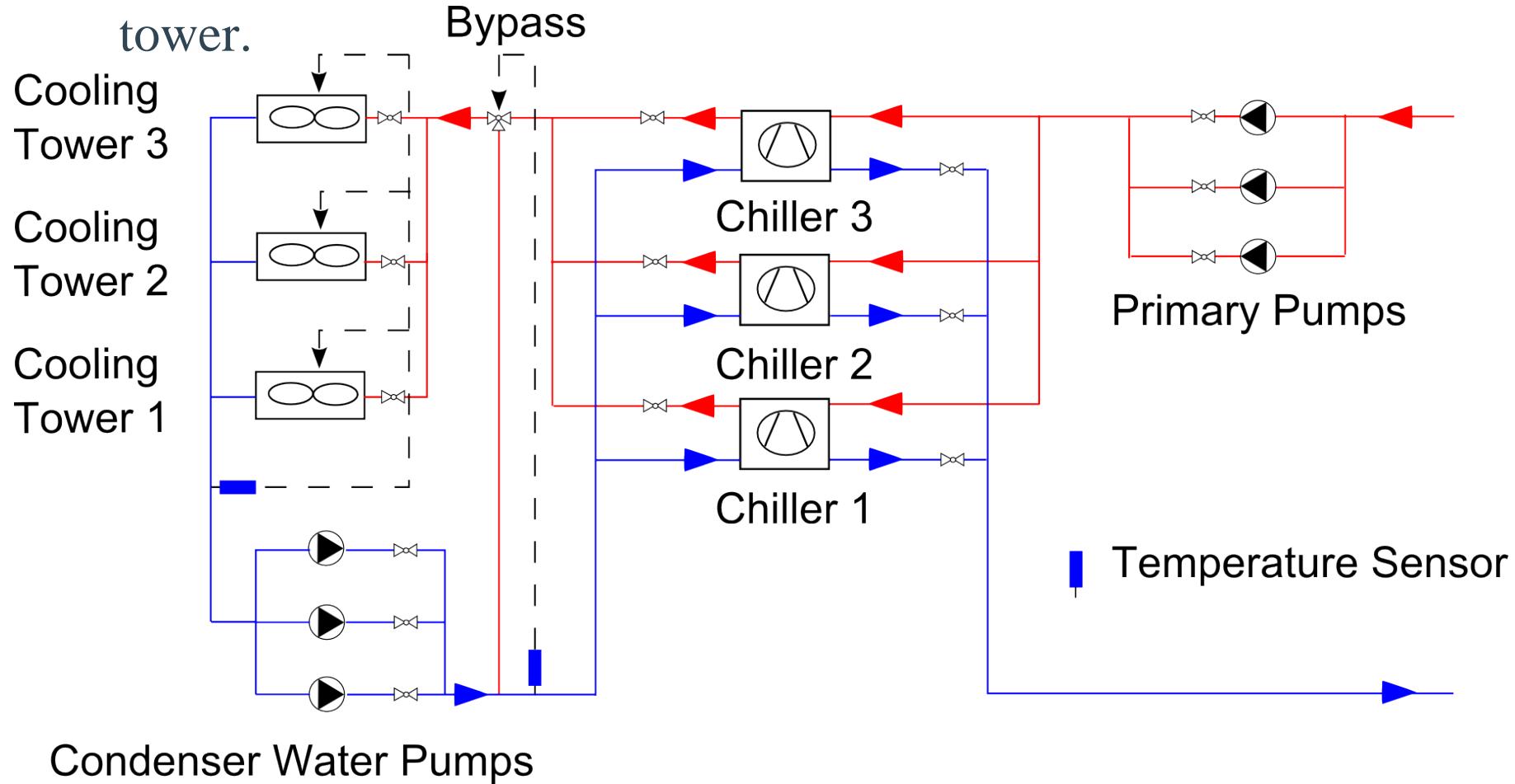
AHU FDD
Automated Reasoning

AHU FDD Grey Box

MPC approach for chiller plants - offline

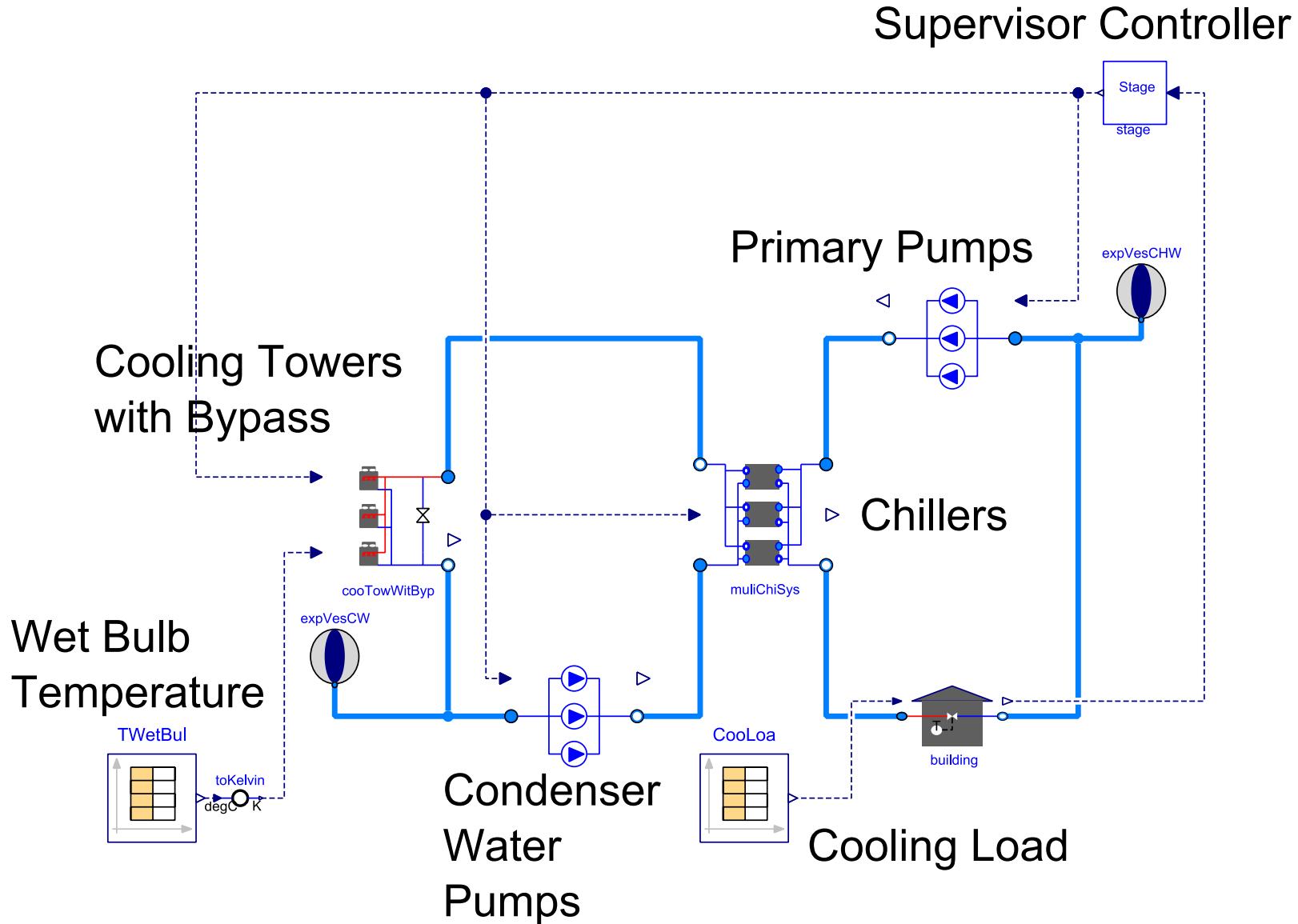
32

- The studied case is a chiller plant with 3 identical chillers, 3 identical chilled water pumps, 3 identical condenser water pumps, and three identical cooling towers. Each chiller has dedicated chilled water pump, condenser water pump, cooling tower.



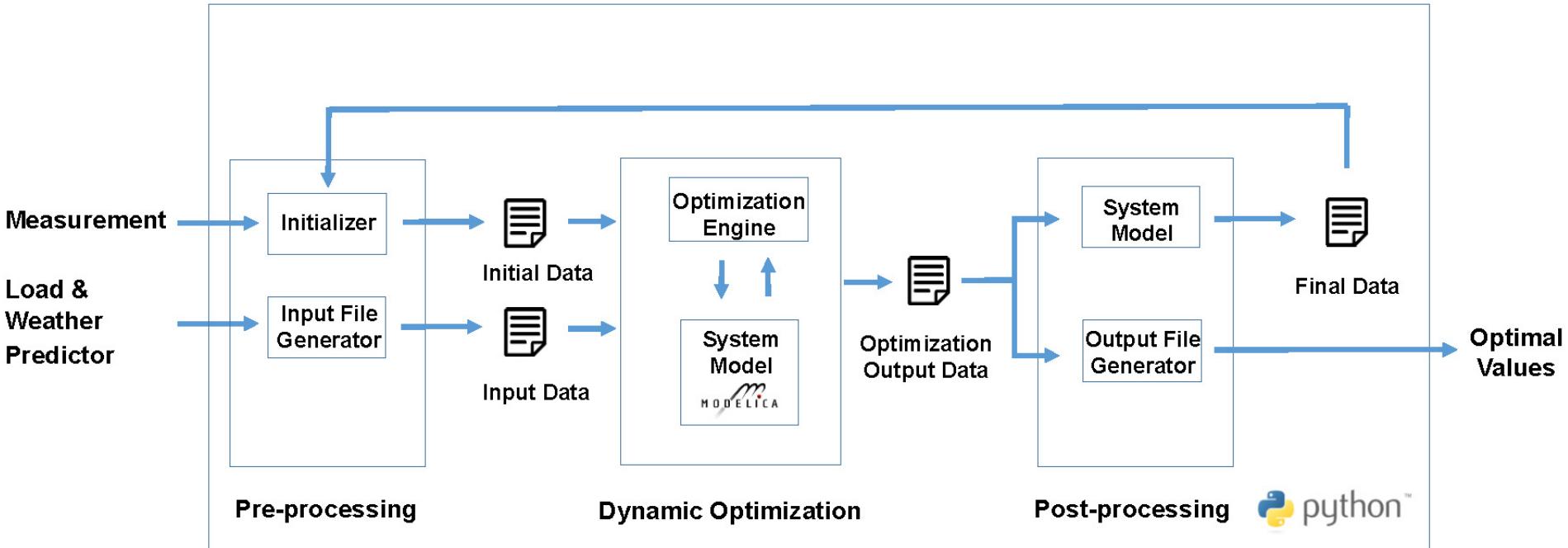
Modelica Model – Top Level

33



Modelica in the Process - offline

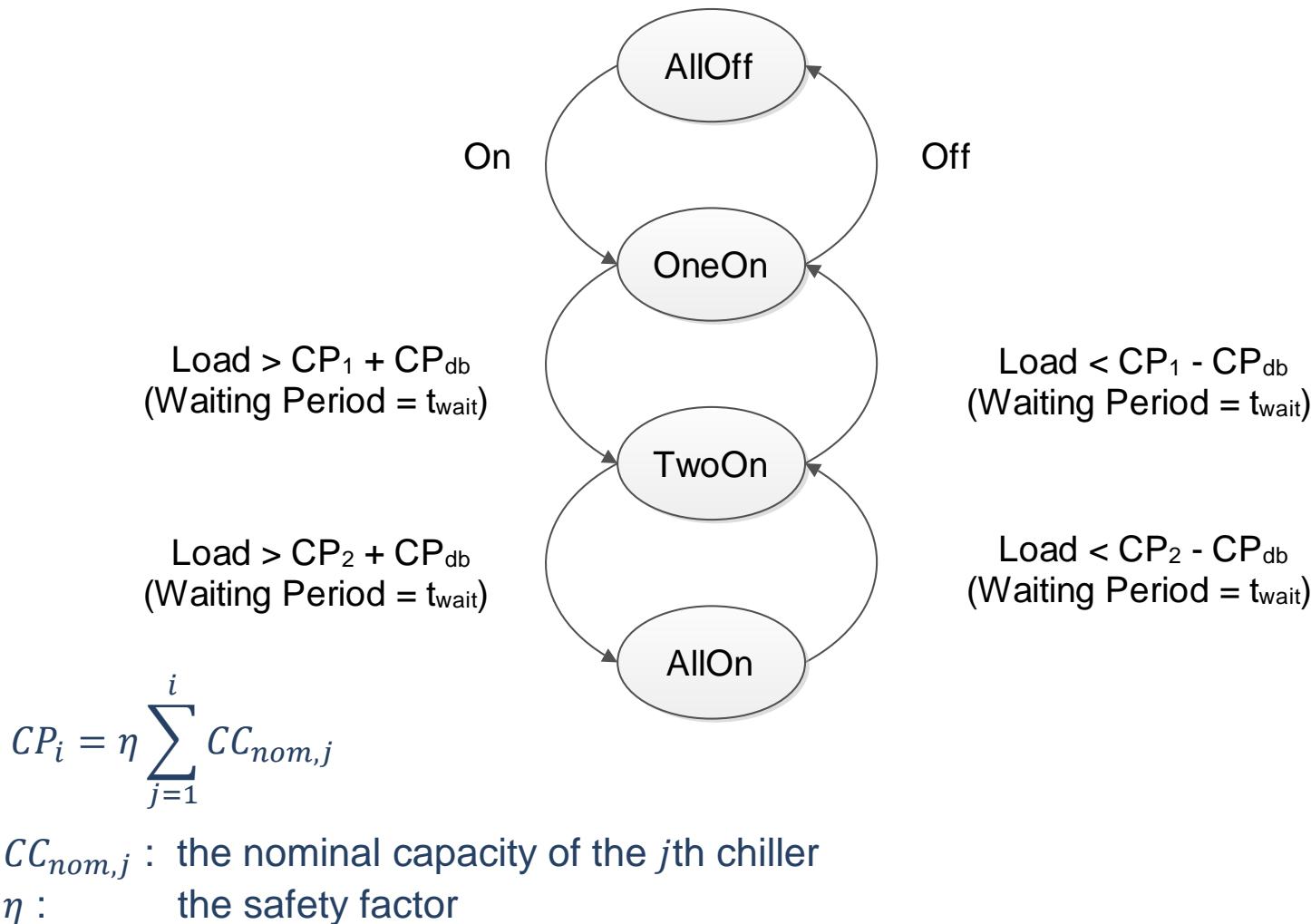
34



Sen Huang, Wangda Zuo, Michael D. Sohn. Amelioration of the Cooling Load based Chiller Sequencing Control. *Applied Energy*, 168, pp. 204-215, 2016

Rule based Control For Chiller Staging

35



Model Predictive Control For Chiller Staging

$$J = \min \left(E_{tot} \Big|_{t_0}^{t_0 + \Delta t} \right)$$

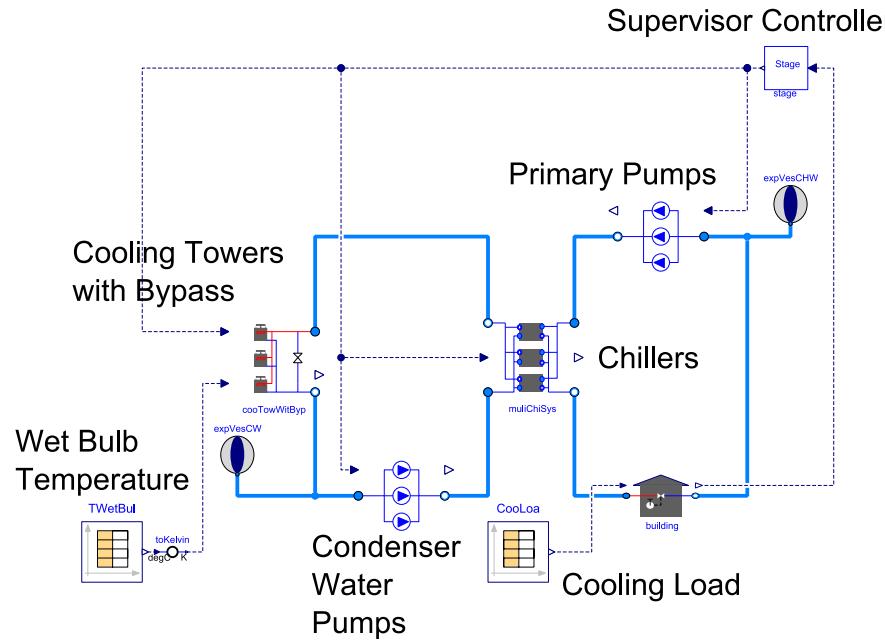
$$T_{cw,set,L} \leq T_{cw,set}(t_0) \leq T_{cw,set,H}$$

s.t.

$$CP_1^{\min} < CP_1(t_0) \leq CP_1^{\max}$$

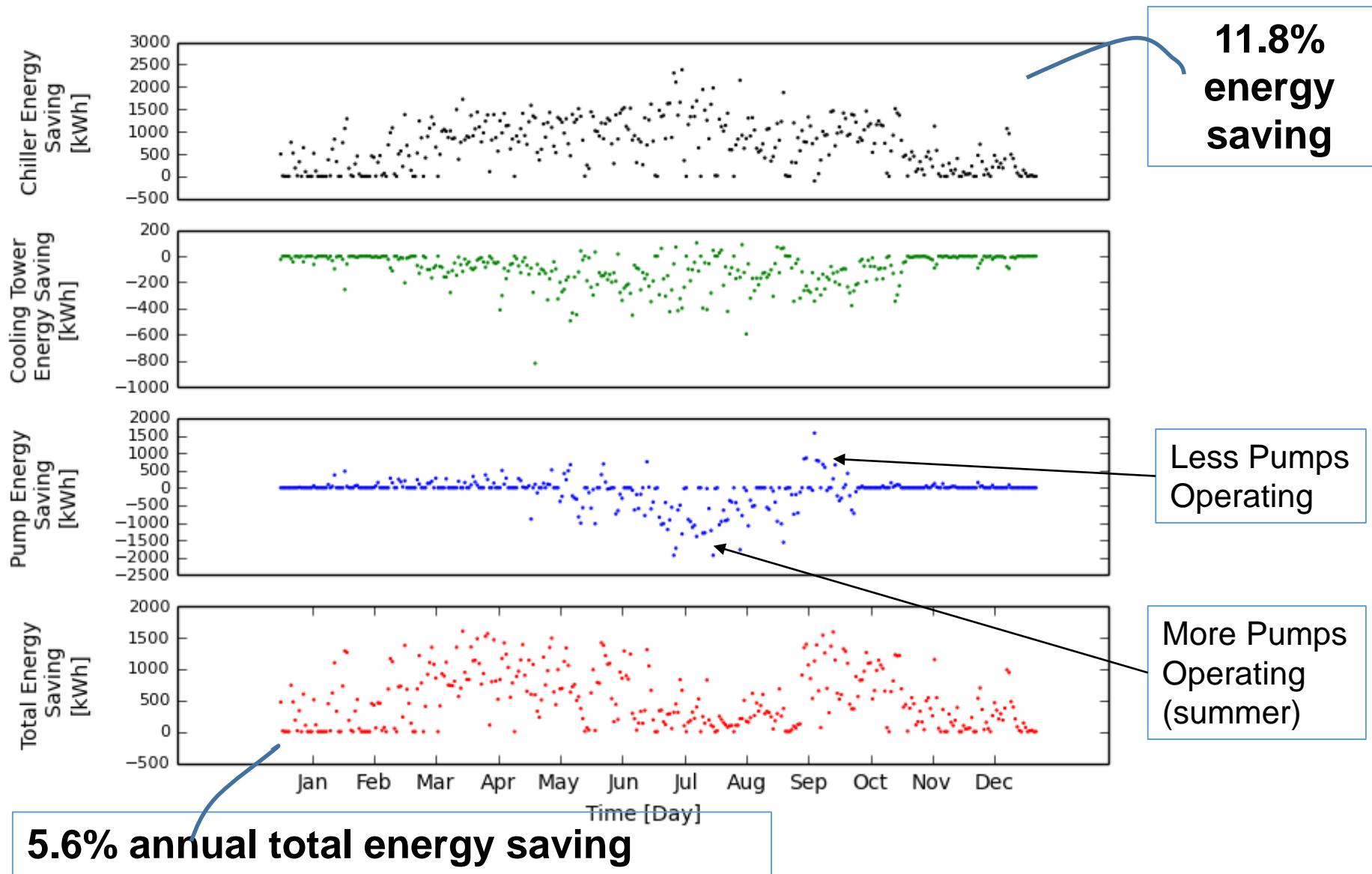
$$CP_{i-1}(t_0) < CP_i(t_0) \leq CP_i^{\max} \quad (i > 1)$$

$$\int_{t_0}^{t_0 + \Delta t} |T_{ch,lea}(t) - T_{ch,set}| dt \leq \int_{t_0}^{t_0 + \Delta t} |T_{ch,lea,base}(t) - T_{ch,set}| dt$$



Offline Simulation Results

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MPC

Energy Control
Underground Public
Spaces

Chiller Plant

Heat Pumps

HIL

**HVAC close-loop
control**

FDD

AHU FD

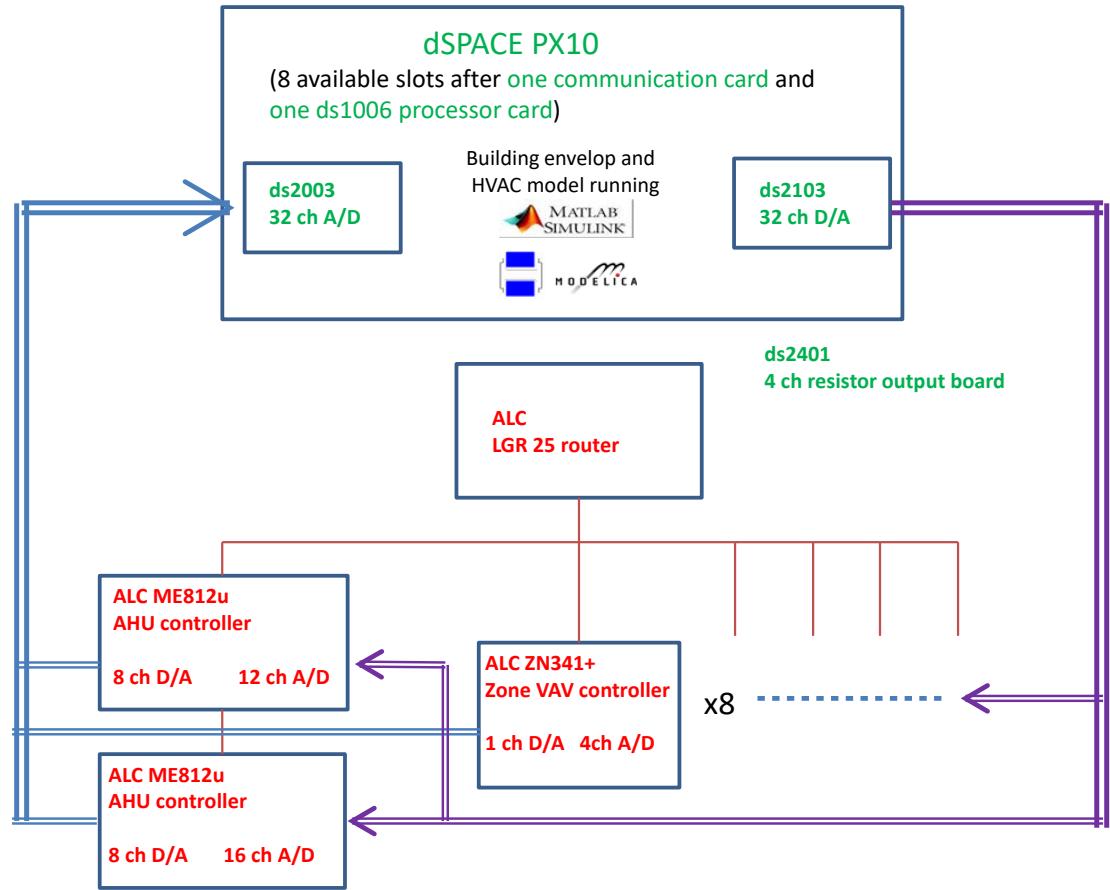
Chillers in District
Cooling

AHU FDD
Automated Reasoning

AHU FDD Grey Box

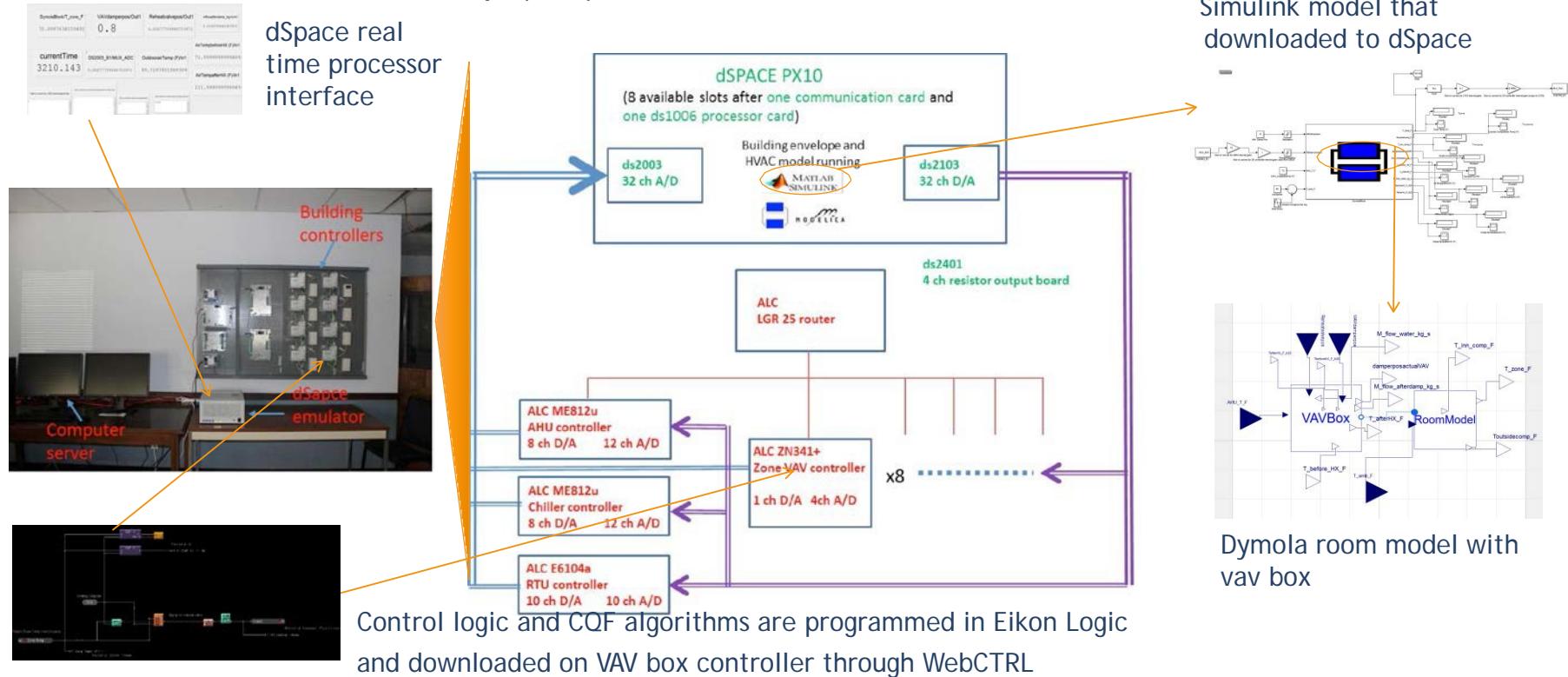
Hardware in the Loop - inline

- A room served by a VAV terminal
- Room and VAV modelled in Modelica
- Models downloaded to HiL machine connected to a real VAV box controller.
- The objective of this case study is to research different control algorithms including fault tolerant controls for VAV boxes.

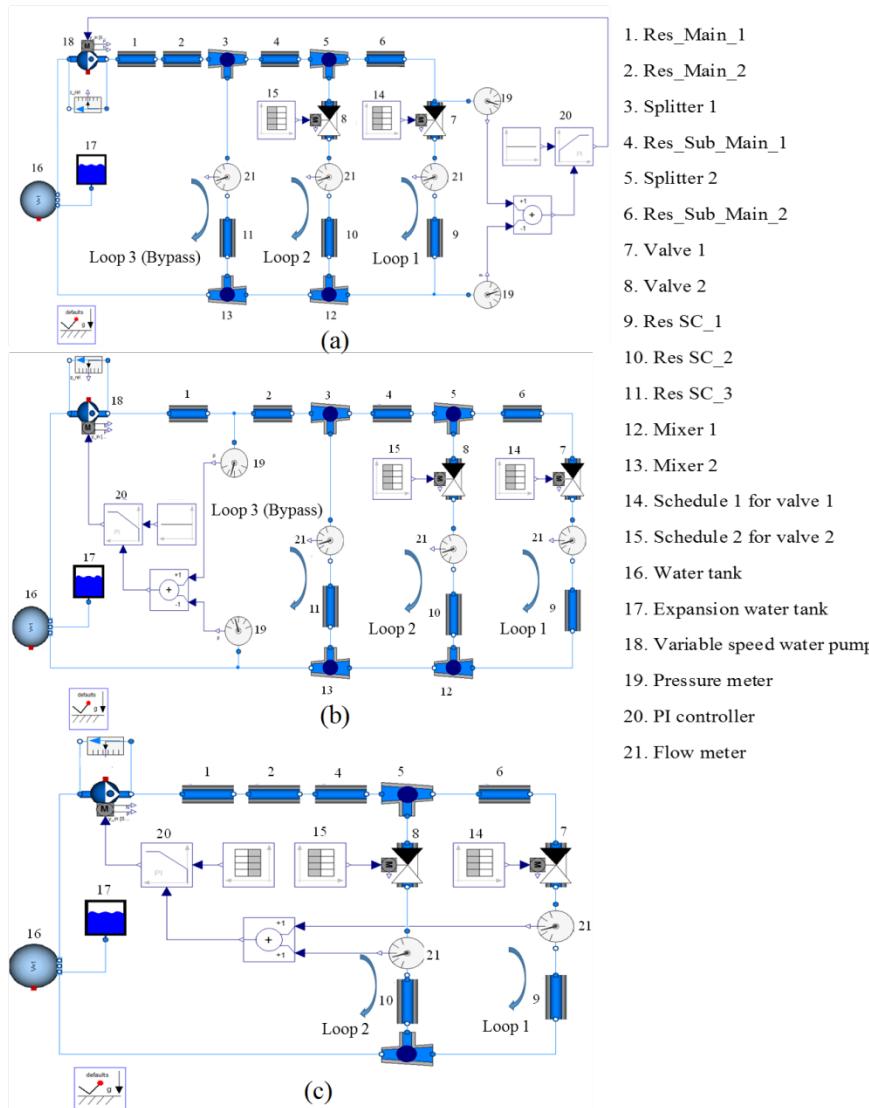


HiL Implementation

- **ASHRAE RP-1587 : Control Loop Performance Assessment** - develop, evaluate and field test an objective and quantitative metric and method to monitor and evaluate HVAC closed loop control performance
(Finished)
 - Using Modelica to generate simulation data (normal and faulty operations) to evaluate the proposed Control Quality Factor (CQF)



HiL Model

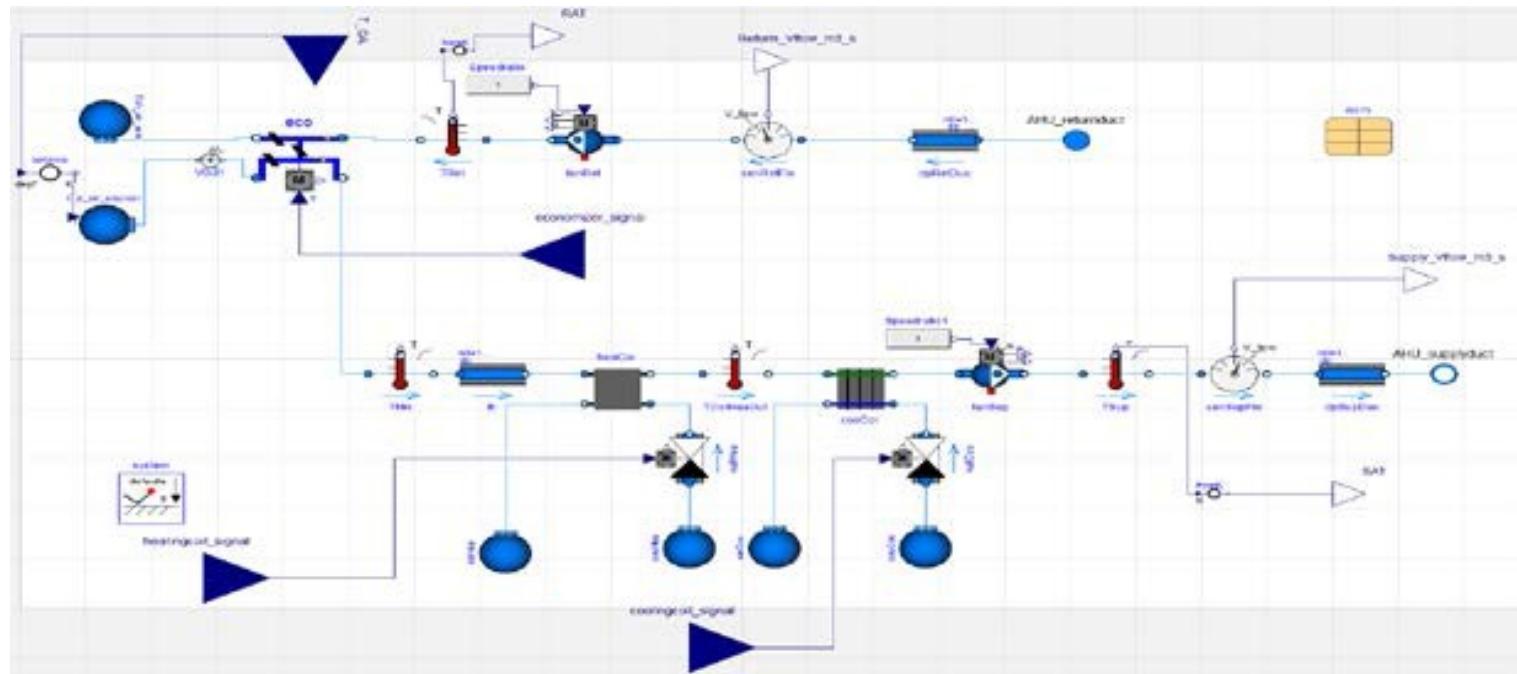


- A Modelica-Based Study on Different Control Strategies for Variable Speed Pump in Distributed Ground Source Heat Pump Systems**

- With Oak Ridge National Laboratory
- Simulation based study shows that the annual pumping energy consumption can be reduced by 62% using the flow-demand-based control
- The model validation is being conducted using experimental data from the tested at ORNL

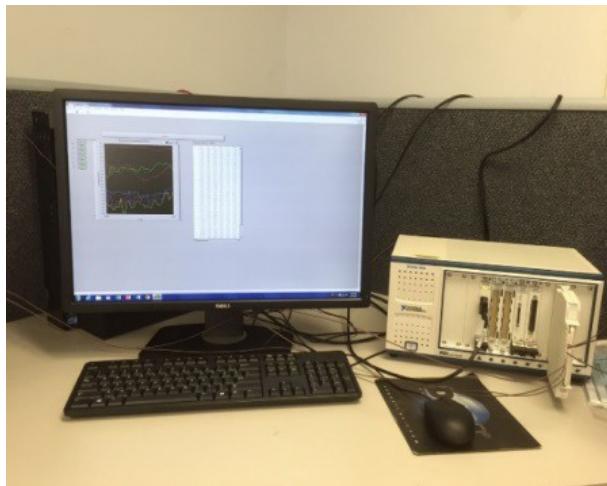
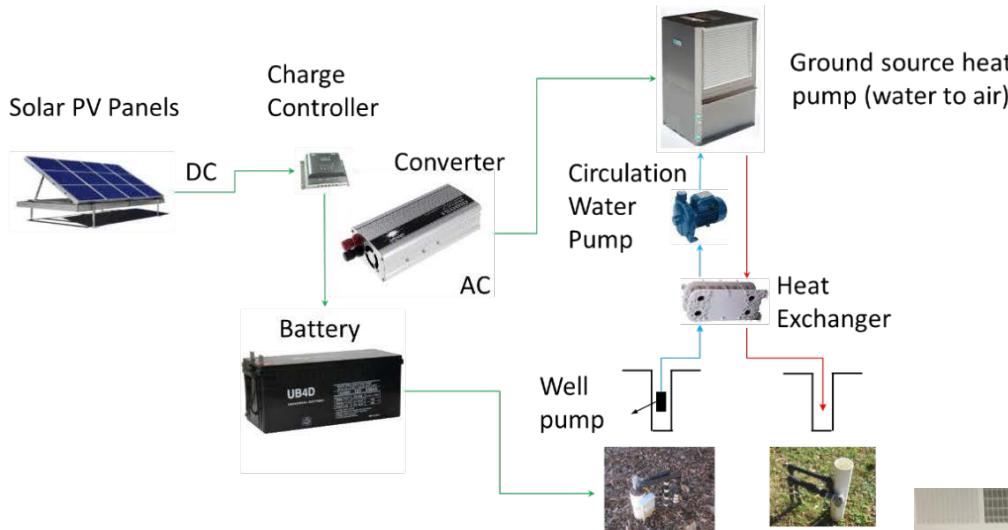
Project overview and current status

- Implementing Fault Tolerant Control using Hardware-in-the-loop with Modelica
- Focus on a single duct VAV system



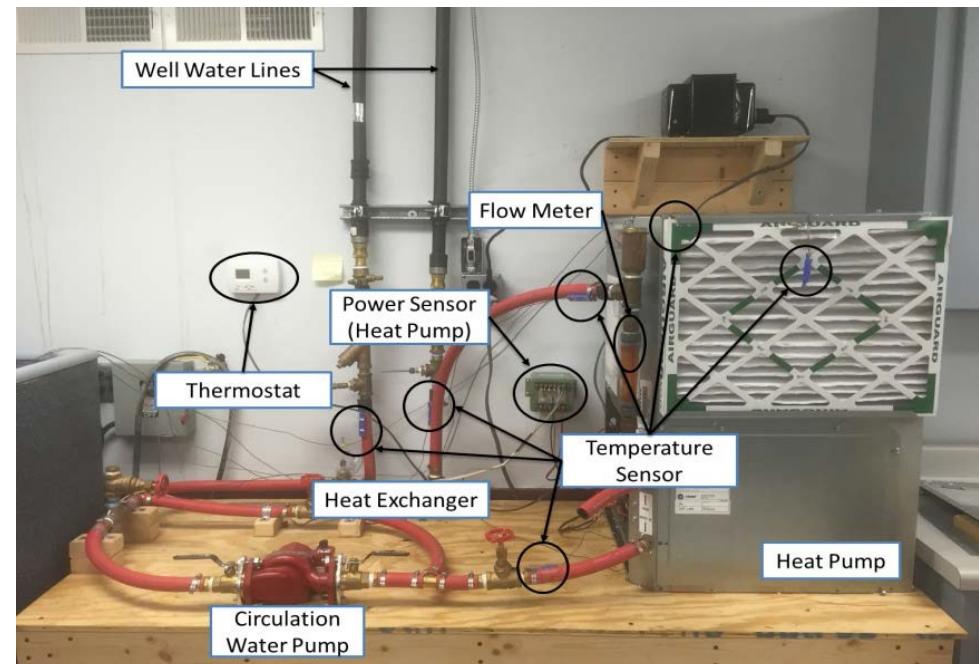
Project overview and current status

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- **Modeling of a Solar Powered Ground Source Heat Pump System using Modelica**

- Data is being collected from an experimental testbed in the lab
- Working on the Modelica model



MPC

Energy Control
Underground Public
Spaces

Chiller Plant

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control

FDD

AHU FD

**Chillers in District
Cooling**

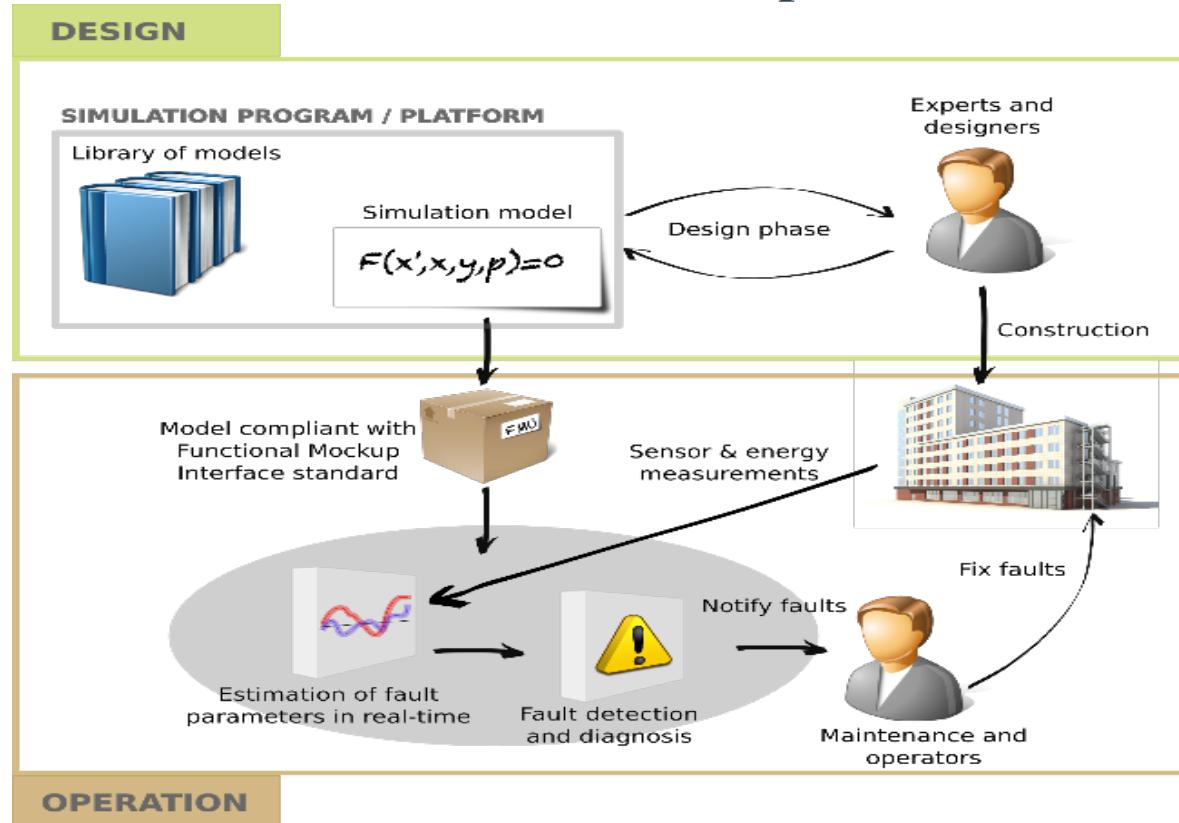
AHU FDD
Automated Reasoning

AHU FDD Grey Box

Model-based FDD for District Cooling Systems

45

- 20 buildings utilize the chilled water (CHW) for air conditioning.
- CHW provided to the central loop by two separate plants located in different zones of the campus.



FDD case study - online

Six chillers

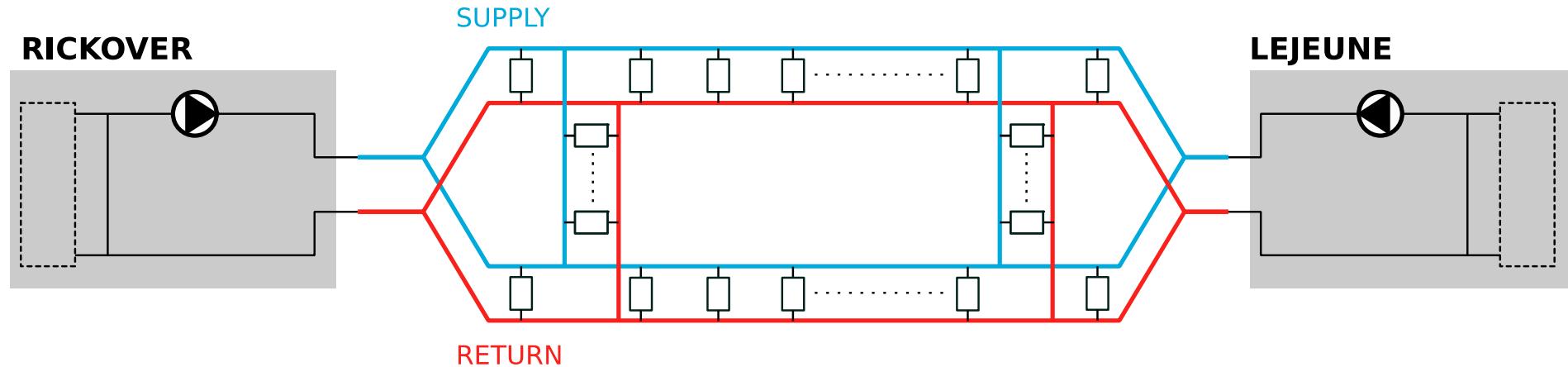
2 x 1250 Ton 734 kW (single compressor, fixed speed)
4 x 2500 Ton 1512 kW (two stage compressor, fixed speed)

Eight cooling towers

2 x 37.3 kW (two fan per tower)



Building representing a cooling load and also hydraulic resistance. The number of buildings plugged in the network is not known. We don't know how the cooling load and the hydraulic resistance vary with respect to time and outdoor condition.



FDD results

Details of fault identification algorithm, comparison between expected and estimated COP. The red rectangles have been identified as faulty periods where the performance of the chiller were lower than expected.



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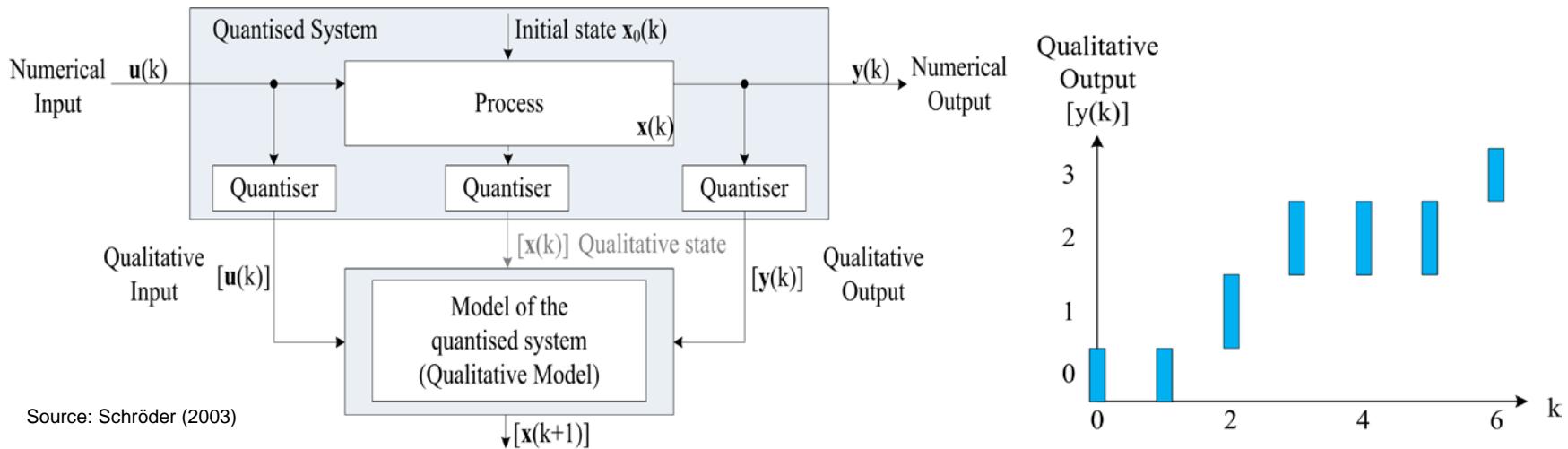
AHU FDD
Automated Reasoning

AHU FDD Grey Box

MB-Qualitative FD of AHU components

49

- The basis for using a qualitative model for fault detection is a quantised system



- The quantised system shows the qualitative behaviour of the process

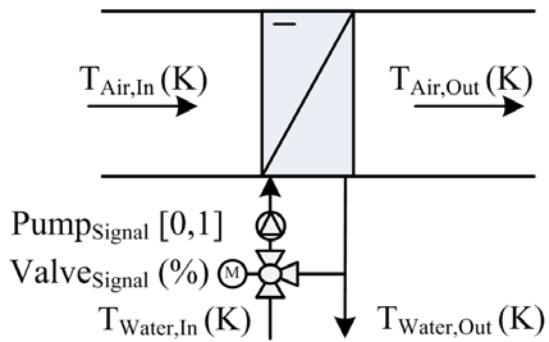
Fault Detection - offline

51

- Different faults have been simulated with the Modelica fault triggering library, developed by the German Aerospace Center (DLR)
- The basis for Fault Detection is a qualitative observation algorithm
- The algorithm yields for each time step the probability vector p_z which describes the possible behaviour of the system states depending on the measured qualitative input-output combination
- If the probability vector contains only zeros, the measured input-output combination is inconsistent with the qualitative model and a fault can be structurally detected

Application example

- Cooler of an HVAC&R System:
 - 8 physical signals,
 - Measured nominal and faulty condition

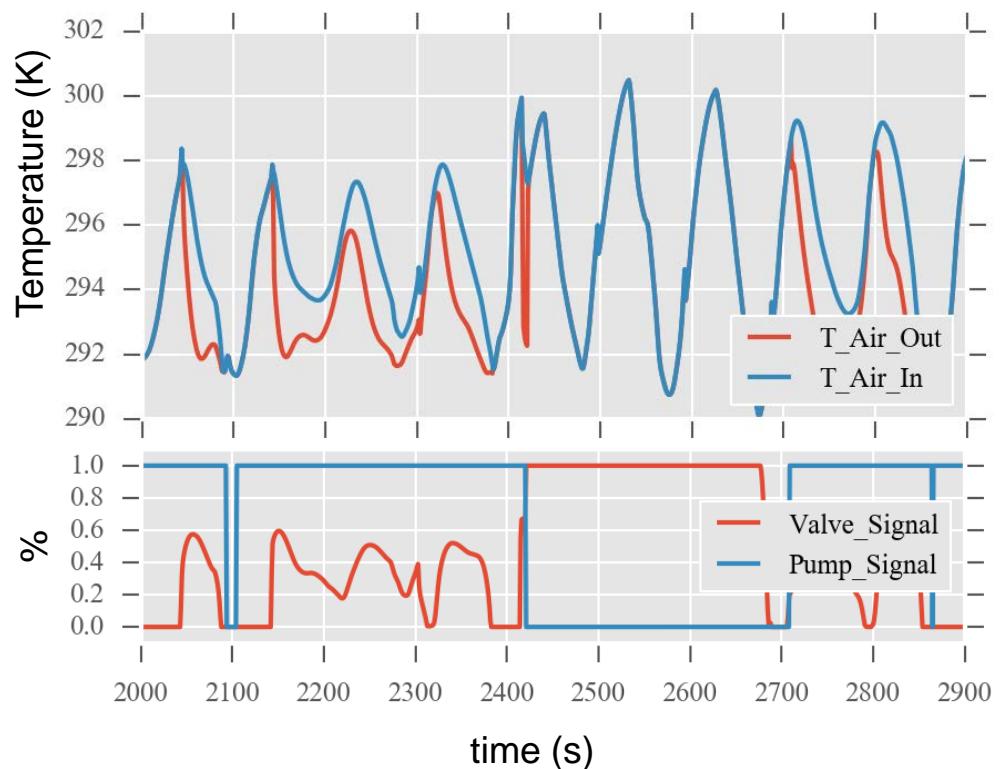


- Signals and partitioning of the spaces
 - 5 qualitative intervals for the temp inputs
 - 2 qualitative intervals for valve inputs
 - 5 qualitative intervals the outputs
- Sampling Time $T_s = 900\text{s}$
- **The behaviour relation of the automaton is a 10-dimensional tensor**
- **The behaviour relation includes more than $3.9 \cdot 10^6$ values**

- Higher number of inputs, outputs and states → combinatorial explosion of the behavior relation of the stochastic automaton
- Behavior relation can be reduced by a non-negative CP-tensor decomposition

Application example

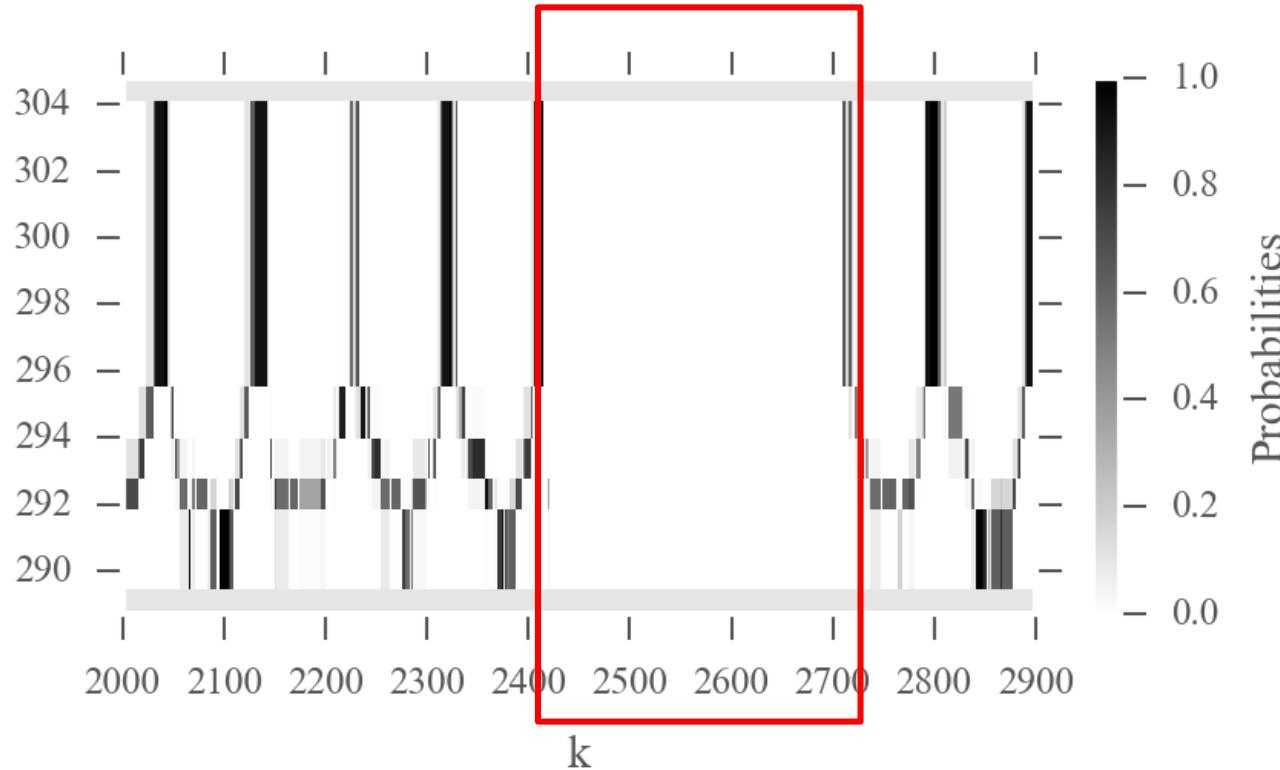
- Fault simulation with Modelica Fault Triggering Library
- The simulated fault describes a malfunction of the pump leading to a fully opened valve, because the controller tries to reach the regarded set point of the air outlet temperature



Application example

54

- Qualitative state trajectory for a faulty condition



MPC

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Spaces

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HVAC close-loop
control

FDD

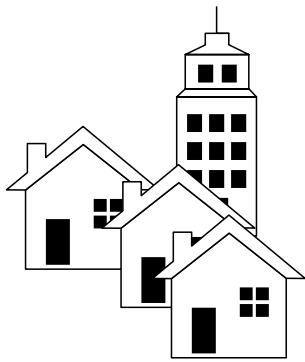
AHU FD

Chillers in District
Cooling

AHU FDD
Automated Reasoning

AHU FDD Grey Box

Quantitative MB-FDD of AHUs - offline



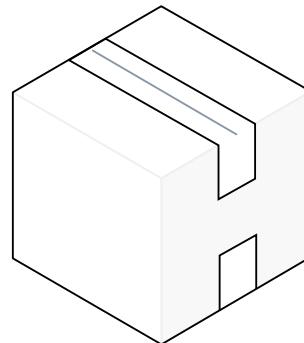
Suboptimal
HVAC

- Lack of standardization
- Lack of awareness
- Expensive system

Increase of energy use
during operational
phase

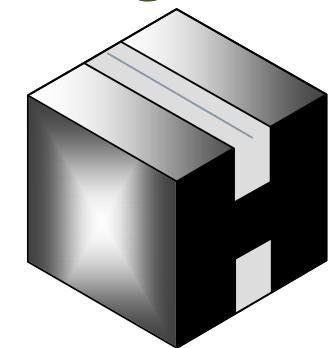
Easy to implement
Open concepts, tools and languages

Fault
detection



White box model
(detailed Modelica
Model)

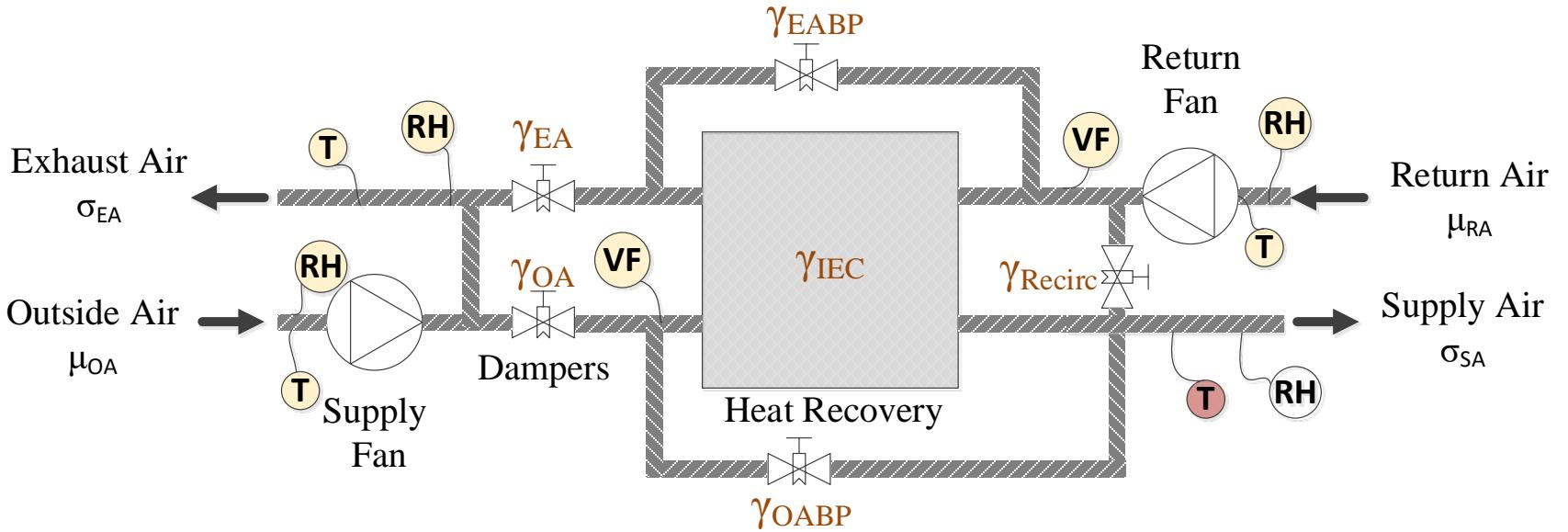
Fault
diagnosis



Black box model
(Classifiers)

HVAC system: Mixing box

Control system: γ_{EA} , γ_{EABP} , γ_{OA} , γ_{IEC} , γ_{Recirc} , γ_{OABP}



OA: Outside Air

EA: Exhaust Air

EABP: Exhaust Air By Pass

OABP: Outside Air By-Pass

IEC: Indirect Evaporative Cooling

T Temperature Sensor

RH Relative Humidity Sensor

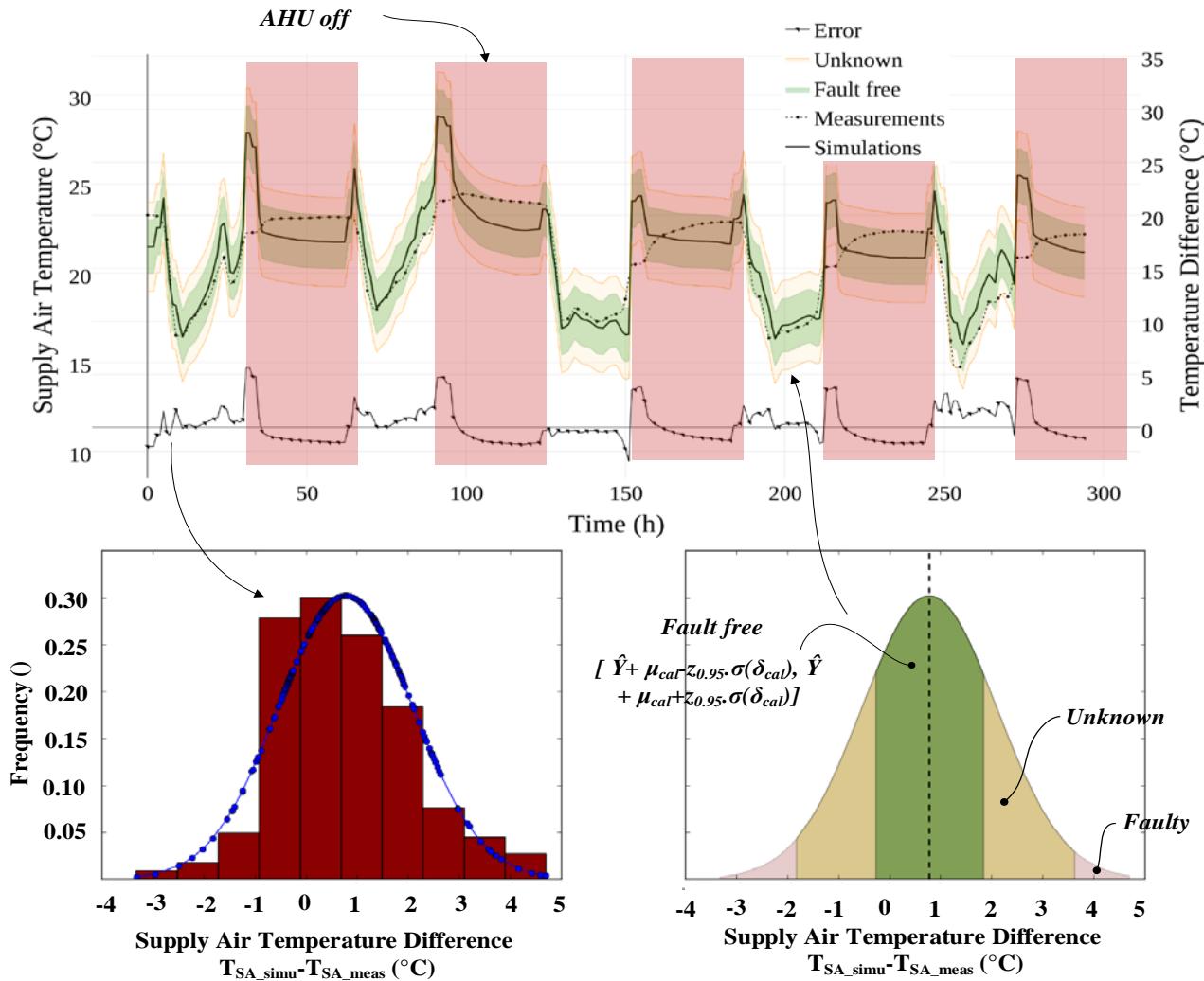
VF Volume Flow Sensor

γ_i : Control signals

σ_i : Outputs

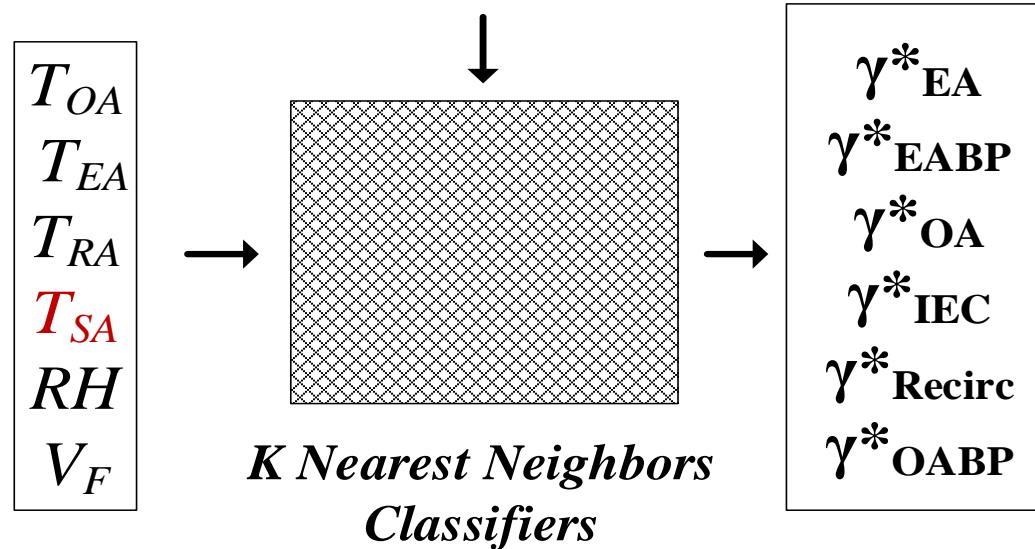
μ_i : Inputs

Fault Detection



Fault Diagnosis and Categorization

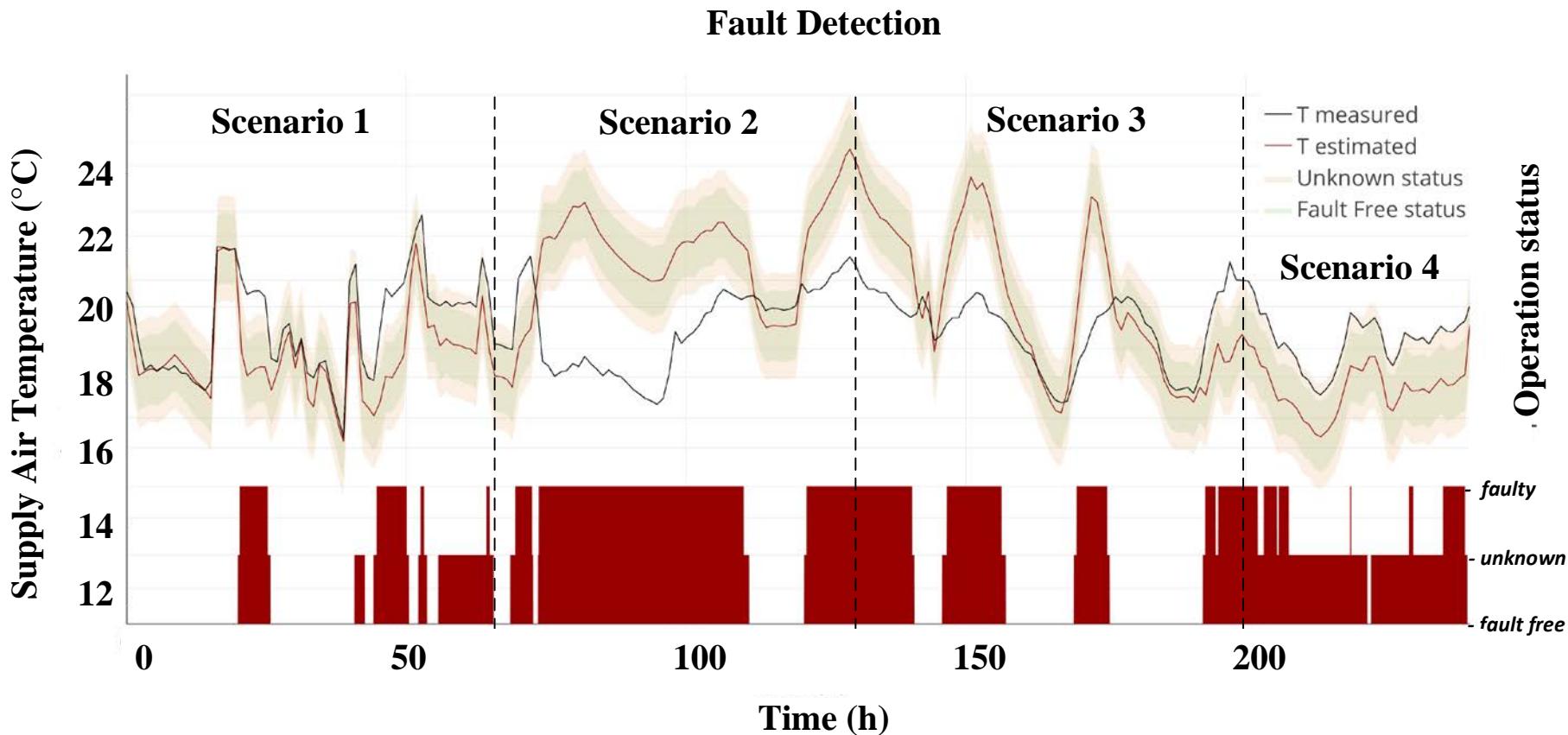
Initial commissioning training set:
 $T_{OA}, T_{EA}, T_{RA}, T_{SA}, RH, V_F, \gamma_{EA}, \gamma_{EABP},$
 $\gamma_{OA}, \gamma_{IEC}, \gamma_{Recirc}, \gamma_{OABP}$



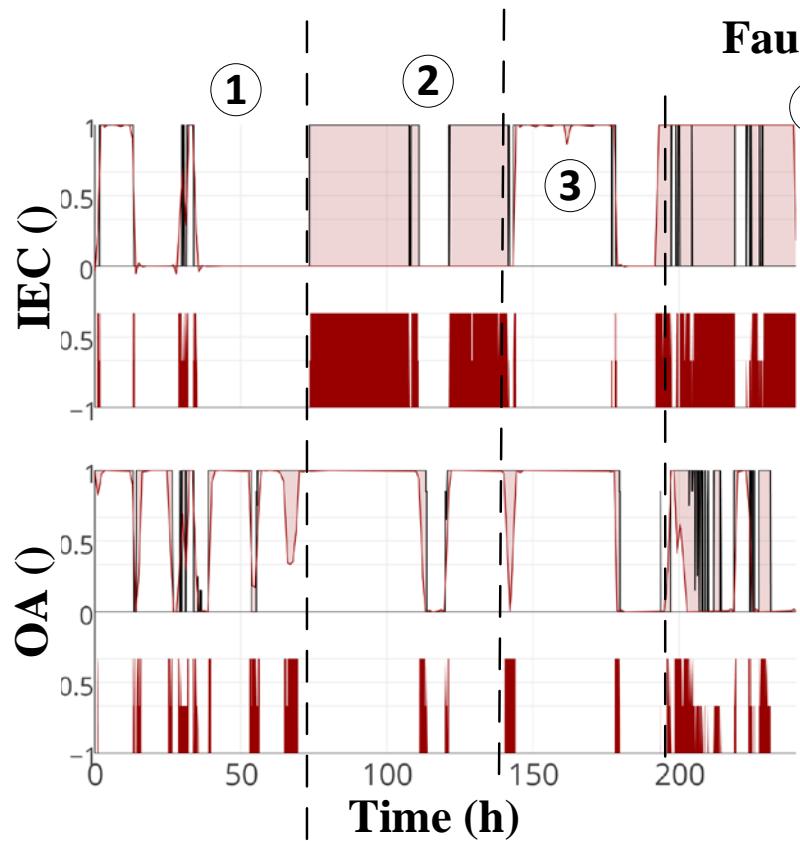
- If γ^* AND $\gamma \in \text{Same Class}$ $p(\gamma^*) > 0.75 \rightarrow$ fault free
If γ^* AND $\gamma \in \text{Same Class}$ $p(\gamma^*) < 0.75 \rightarrow$ unknown
If γ^* AND $\gamma \in \text{Different Class}$ $p(\gamma^*) > 0.75 \rightarrow$ faulty

Application: virtual scenario

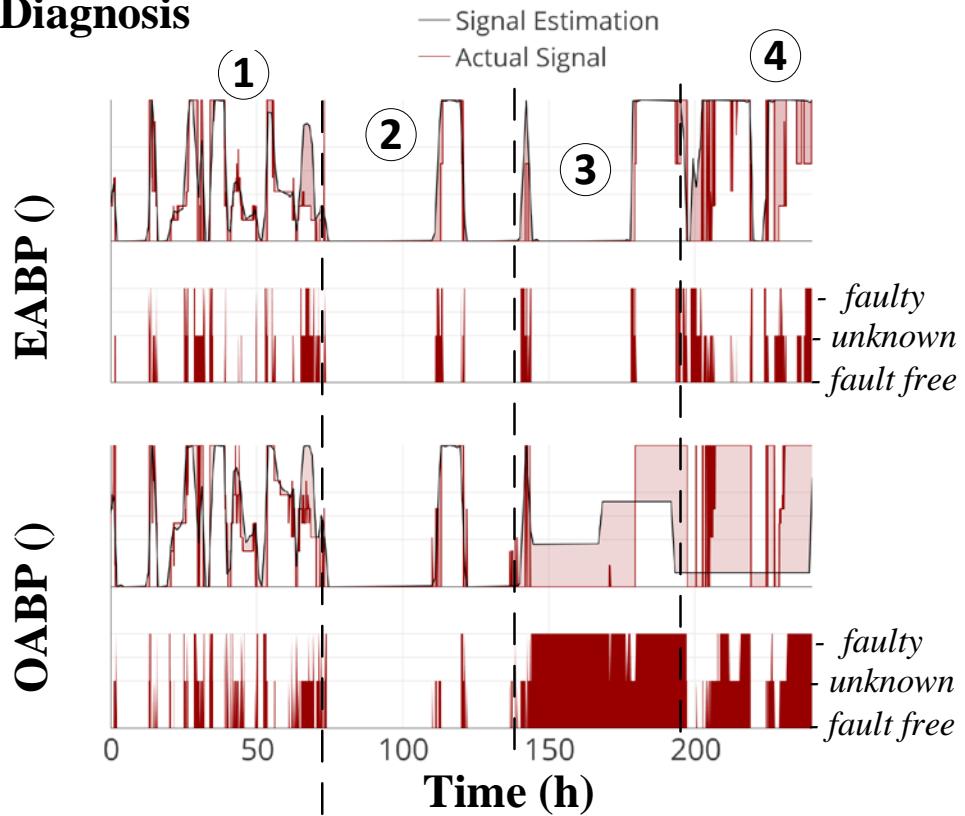
- 1) No error introduced.
- 2) The Indirect Evaporative Cooling (IEC) keeps running despite a stop signal.
- 3) The Outside Air damper bypass (OA BP) is stuck on closed status.
- 4) Multiple errors introduced (faulty OA BP and IEC).



Application: virtual scenario



Fault Diagnosis



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FDD

AHU FD

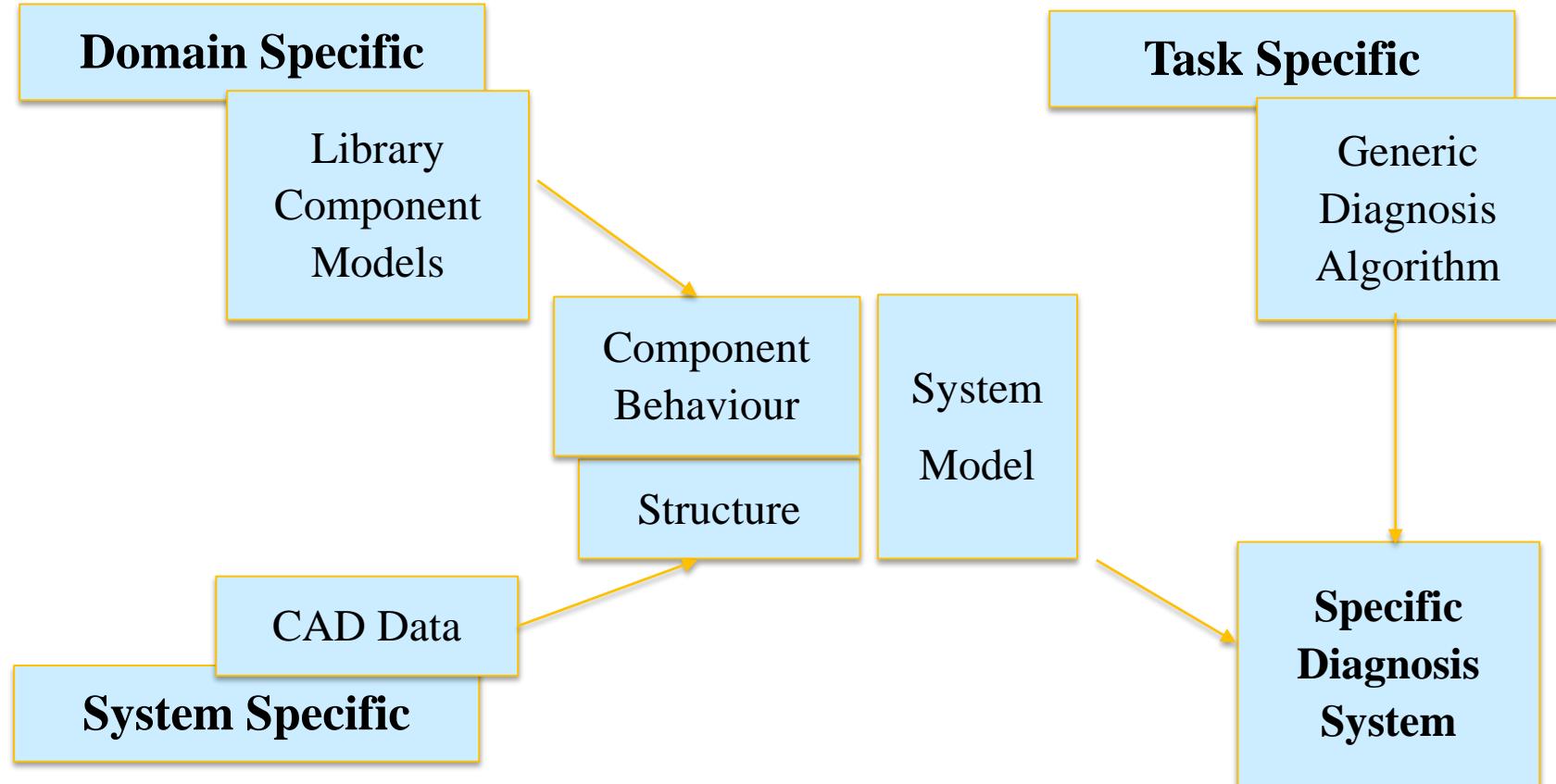
Chillers in District
Cooling

**AHU FDD
Automated Reasoning**

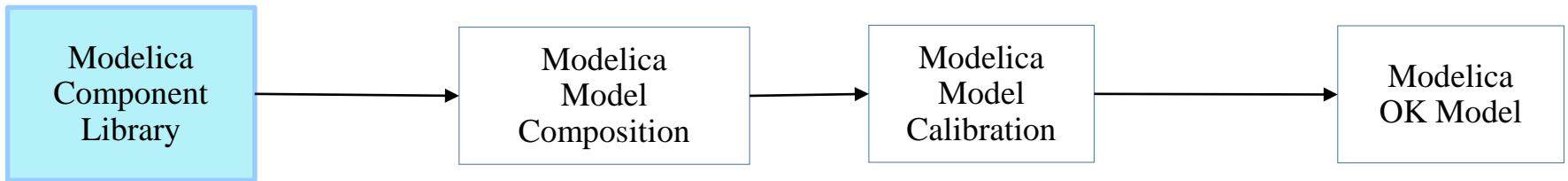
AHU FDD Grey Box

An intuitive introduction

- Generate diagnostics systems instead of programming them



QMBD: Domain Specific



Modelica
Component
Library

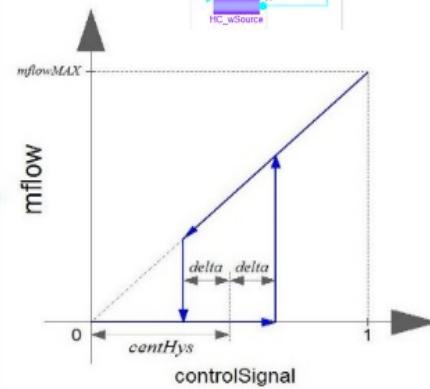
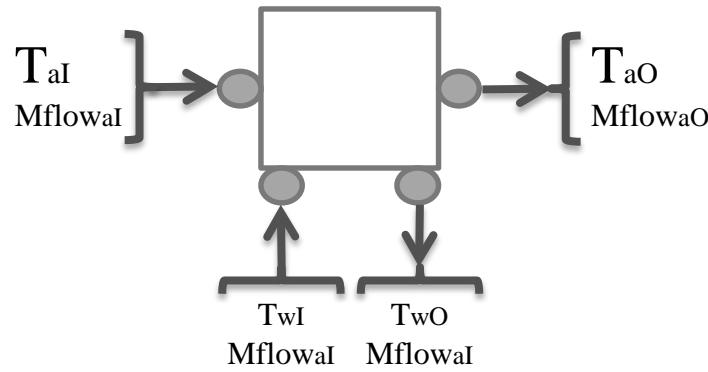
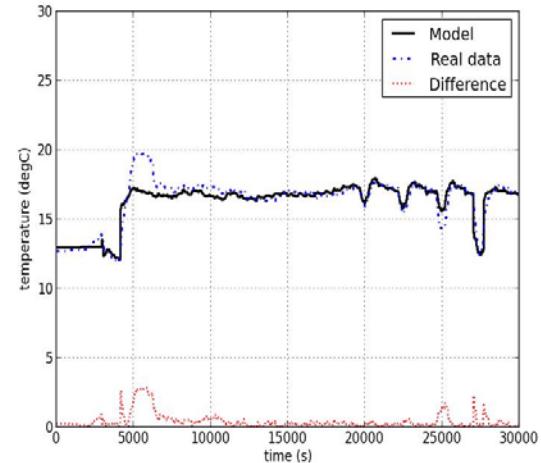
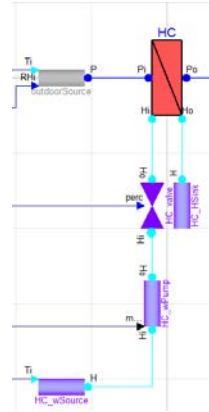
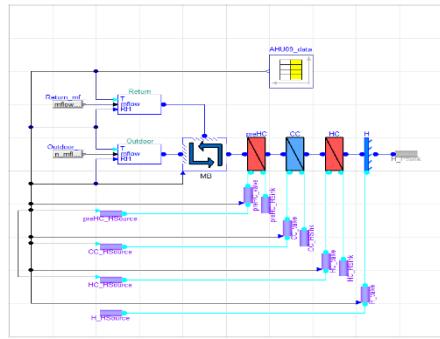
Modelica
Model
Composition

Modelica
Model
Calibration

Modelica
OK Model

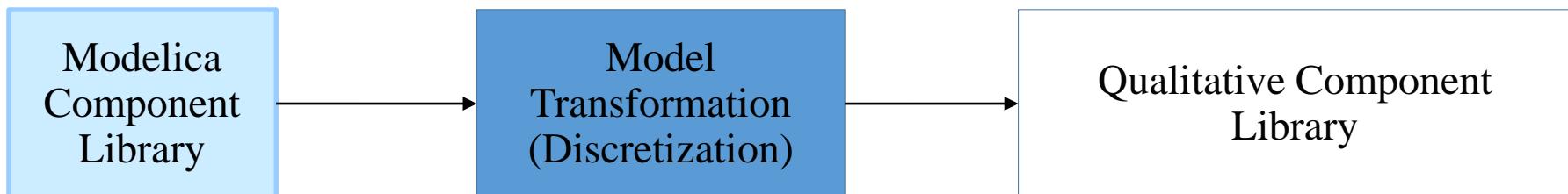
$$Q = c_a * M\text{flow}_{aI} * (T_{aO} - T_{al})$$

$$Q = c_w * M\text{flow}_{wI} * (T_{wI} - T_{wO})$$



QMBD: Task Specific

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$$Q = c_a * Mflow_{al} * (T_{aO} - T_{al})$$

$$Q = c_w * Mflow_{wl} * (T_{wl} - T_{wO})$$

Deviations

$$\Delta x := x_{act} - x_{ref}$$

$$0 = c_a * Mflow_{al} * (T_{aO} - T_{al}) - c_w * Mflow_{wl} * (T_{wl} - T_{wO})$$

$$0 = \Delta(c_a * Mflow_{al} * (T_{al} - T_{aO})) \oplus \Delta(c_w * Mflow_{wl} * (T_{wl} - T_{wO}))$$

$$0 = \Delta T_{al} \ominus \Delta T_{aO} \oplus \Delta mflow_w$$

Table 1. Relation on temperature deviations and water flow deviation

$\Delta mflow_w$	ΔT_{al}	ΔT_{aO}
0	-	-
0	0	0
0	+	+
-	-	-
-	0	-
-	+	*
+	-	*
+	0	+
+	+	+

Table 2 Qualitative representation of the OK mode

Cmd	$\Delta mflow_w$
0	0
+	0

Table 3 Qualitative representation of the stuck closed valve mode

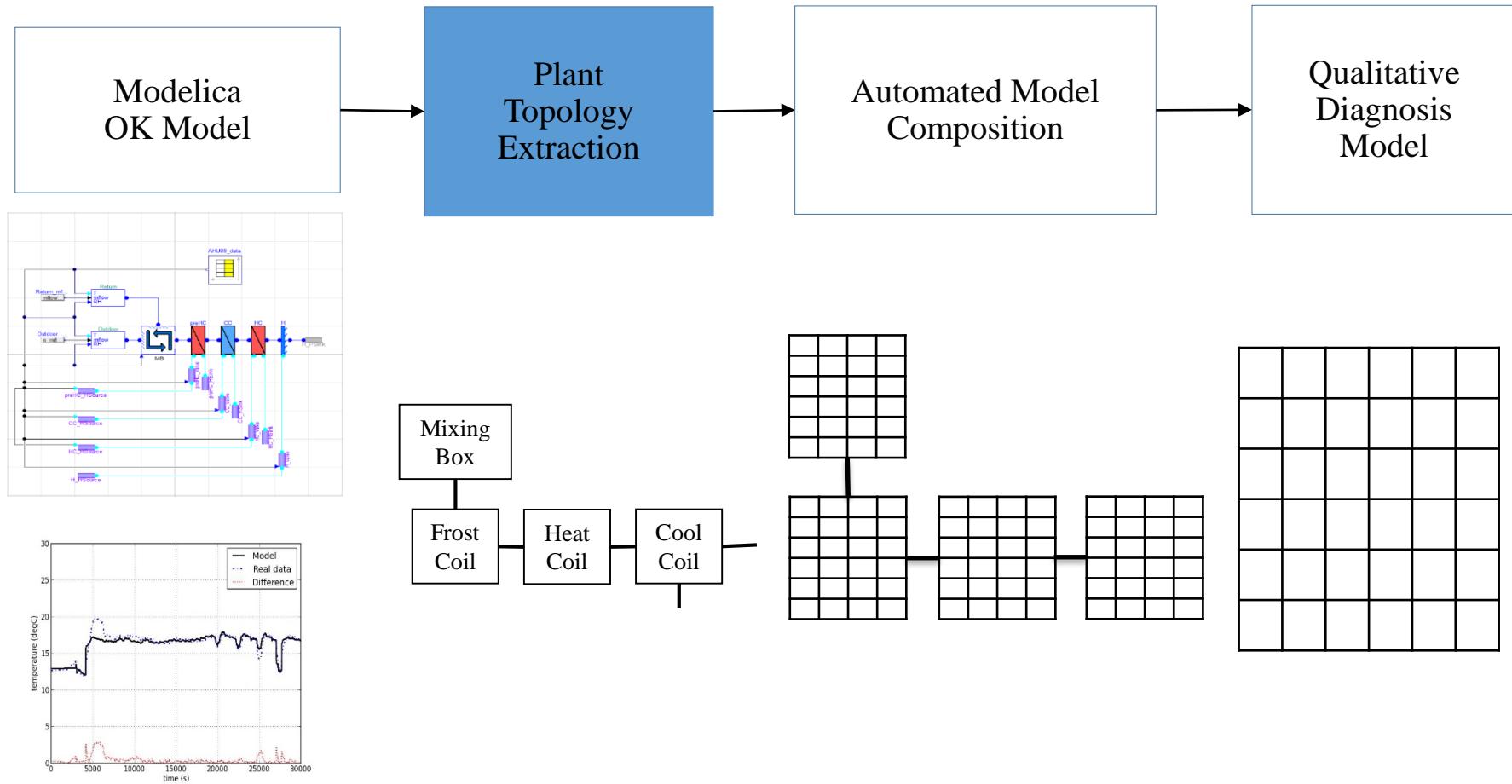
Cmd	$\Delta mflow_w$
0	0
+	-

Table 4 Qualitative representation of the passing valve mode

Cmd	$\Delta mflow_w$
0	+
+	0
+	+

QMBD: System Specific

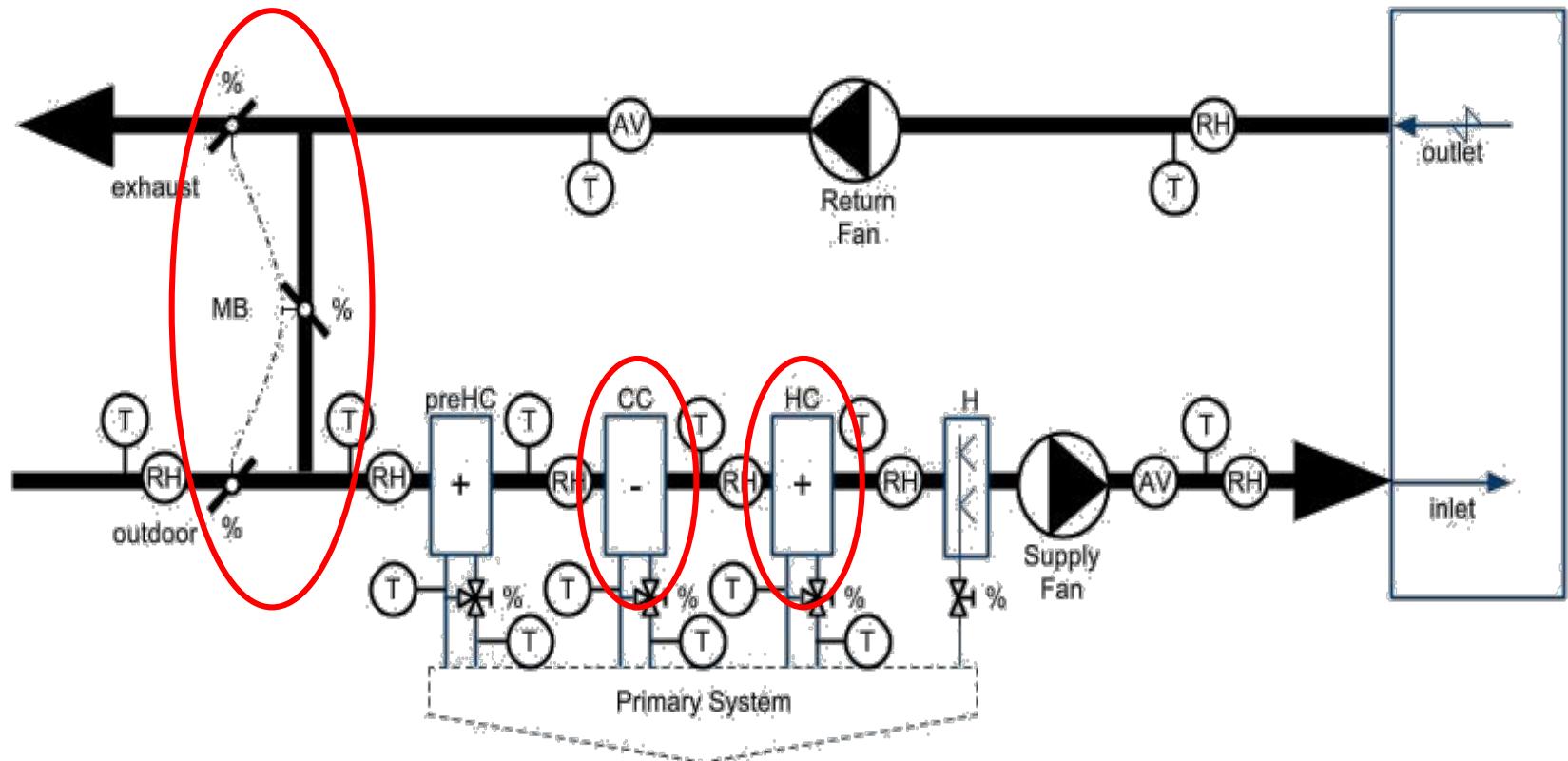
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Results - offline

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- Air handling unit



Results comparison against APAR

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Component	MB		CC		HC	
Scenario	APAR	QMBD	APAR	QMBD	APAR	QMBD
Nominal	-	-	-	-	-	-
Passing Cooling Coil Valve	-	-	-	X	-	-
Passing Heating Coil Valve	-	X	-	-	X	X
Stuck Mixing Damper	X	X	-	-	-	-

Concluding remarks

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- The Modelica component oriented language integrates in hybrid modelling processes
- The Modelica object-oriented approach allows for the development and the management of large and complex models. In such large-scale applications, the translators, the modelling language and environment are significantly stressed, and their robustness proved an enabling factor of the overall modelling process

Concluding remarks

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- Modelica allows for a seamless use of the models developed in the design phase during the operational phase, for example, by exporting models as FMUs.
- It is important to note that the advantages of Modelica can turn against the unexperienced developer. For example, because of the object-orientation employed in many libraries, it can be difficult to predict the depth to which a change in one component can have an effect in other components in the library. Annex60 library is working on regression tests to avoid these side effects

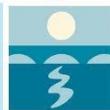
**Thank you for your attention
(any more) Questions?**



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