



# ISMRM 27<sup>TH</sup> ANNUAL MEETING & EXHIBITION

Palais des congrès de Montréal  Montréal, QC, Canada  11–16 May 2019

## Secret Session: Master coding in your research environment

# Code Structure and Syntax

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## What constitutes good scientific code?

- Best practices for scientific computing (Wilson et al., 2014, PLOS Biology)
- Good enough practices in scientific computing (Wilson et al., 2017, PLOS CB)



<https://www.software.ac.uk/blog/2016-10-07-what-makes-good-code-good-digital-social-research-view>



## Readability

- You and future-you, your PI, the reviewer of your paper and the grad student taking over your project can understand what's happening
- Note: follows the same rules as scientific writing (clear, simple and short)
- sections: definitions, data read-in, preprocessing, ...
- meaningful function and variable names: `fieldStrength_T`,  
`compute_gradient_moment`
- linear and explicit



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## Habits for good scientific code

- Refactor (rewrite) your code
    - remove the copy and paste bits
    - split your code in small functional units (functions)
    - less code, increased readability, increased functionality
  - Use toolboxes & the latest core functions
    - the 20 minutes invested in the tutorial will give you hours in functionality
    - write good (and tested) open source code :P
  - Contribute
    - adapt to the coding principles/style
    - good learning experience
- + choose a scientific programming language
- + keep it simple



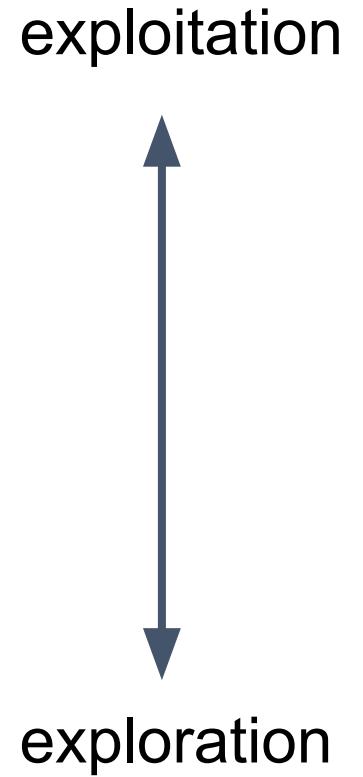
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## Why is it so hard? OR The purpose of scientific code

- analyse my data / do stuff
- find the solution for a problem (or, more often, find the problem)
  - spaghetti code
  - unnecessary parameters/functions
  - cryptic comments
  - loops/if/else
- educate
  - great tool to understand a method
- it's science, dude!
  - reproducibility challenge, re-inventing the wheel, non-linearity





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## Procedural vs. OOP

- Scenario: need to solve an optimization problem (a nasty one)
- Found an algorithm. Goes like:

$$\arg \min_{\mathbf{x}, \mathbf{y}} f(\mathbf{x}) + g(\mathbf{y}) \quad \text{s. t.} \quad A\mathbf{x} + B\mathbf{y} = \mathbf{c}$$

$$\mathbf{x}^{j+1} = \arg \min_{\mathbf{x}} f(\mathbf{x}) + \frac{\rho}{2} \|A\mathbf{x} - (\mathbf{c} - B\mathbf{y}^j - \mathbf{u}^j)\|_2^2$$

$$\mathbf{y}^{j+1} = \arg \min_{\mathbf{y}} g(\mathbf{y}) + \frac{\rho}{2} \|B\mathbf{y} - (\mathbf{c} - A\mathbf{x}^j - \mathbf{u}^j)\|_2^2$$

$$\mathbf{u}^{j+1} = \mathbf{u}^j + A\mathbf{x}^{j+1} + B\mathbf{y}^{j+1} - \mathbf{c}$$



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## Procedural vs. OOP

- General algorithm
  - + pen & paper
  - + your problem
  - = tailored solution
- + Concise
- + Doesn't get faster
- Hard to generalize

```
for iter_num in range(iter_num_max):  
    # update x, the minimizer  
    GHdyu = np.conj(Gf) * fftn(dy - du, axes=(0,1))  
    DHyu = np.conj(Df) * fftn( y - u, axes=(0,1))  
  
    x_prev = x  
    x = ifftn( (DHys + rho*GHdyu.sum(axis=-1)) / \  
               (np.finfo(float).eps + DHDf + rho*GHGf) ).real  
  
    x_update = 100 * np.linalg.norm(x-x_prev) / np.linalg.norm(x)  
    print(f'Iter: {iter_num}. Update: {x_update:.3g}%')  
  
    if x_update < tol_update:  
        break  
  
    # update y, the gradient variable  
    xf = fftn(x)  
    dx = ifftn(Gf * xf[...,:None], axes=(0,1)).real  
  
    dy = np.maximum(abs(dx + du) - regweight * (alpha/rho), 0) \  
        * np.sign(dx + du)  
    y = Wy + (ifftn(Df*xf)+u).real / (weight + rho)  
  
    # update u, the dual variable  
    du += dx - dy  
    u += ifftn(Df*xf).real - y
```



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## Procedural vs. OOP

- General algorithm  
= base class
- Inheritance
  - + pen & paper
  - + your problem
  - = tailored solution
- + Easy to generalize
- + Easier to extend
- ~~This will never work~~   
Takes extra thought

```
class OptimizerBase:  
  
class TVDenoise(OptimizerBase):  
    def __init__(self, data):  
        xshape = data.shape  
        # specifics of the problem  
        super().__init__(xshape, yshape, ushape)  
  
    def solve(self):  
        # left alone  
  
    def xstep(self):  
        # specific implementation...  
  
    def ustep(self):  
        return self.const_A(self.x) + self.const_B(self.y) - self.const_c()  
    def const_A(self, x):  
        return X  
    def const_B(self, y):  
        return -y  
    def const_c(self):  
        return 0.0
```



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## Procedural vs. OOP

- Should you? Depends
- Code to do one job / publish one paper -> procedural
- See it extendable, possibly by others -> OOP