

# A CODELESS INTRODUCTION TO GPU PARALLELISM

Will Landau, Prof. Jarad Niemi

# OUTLINE

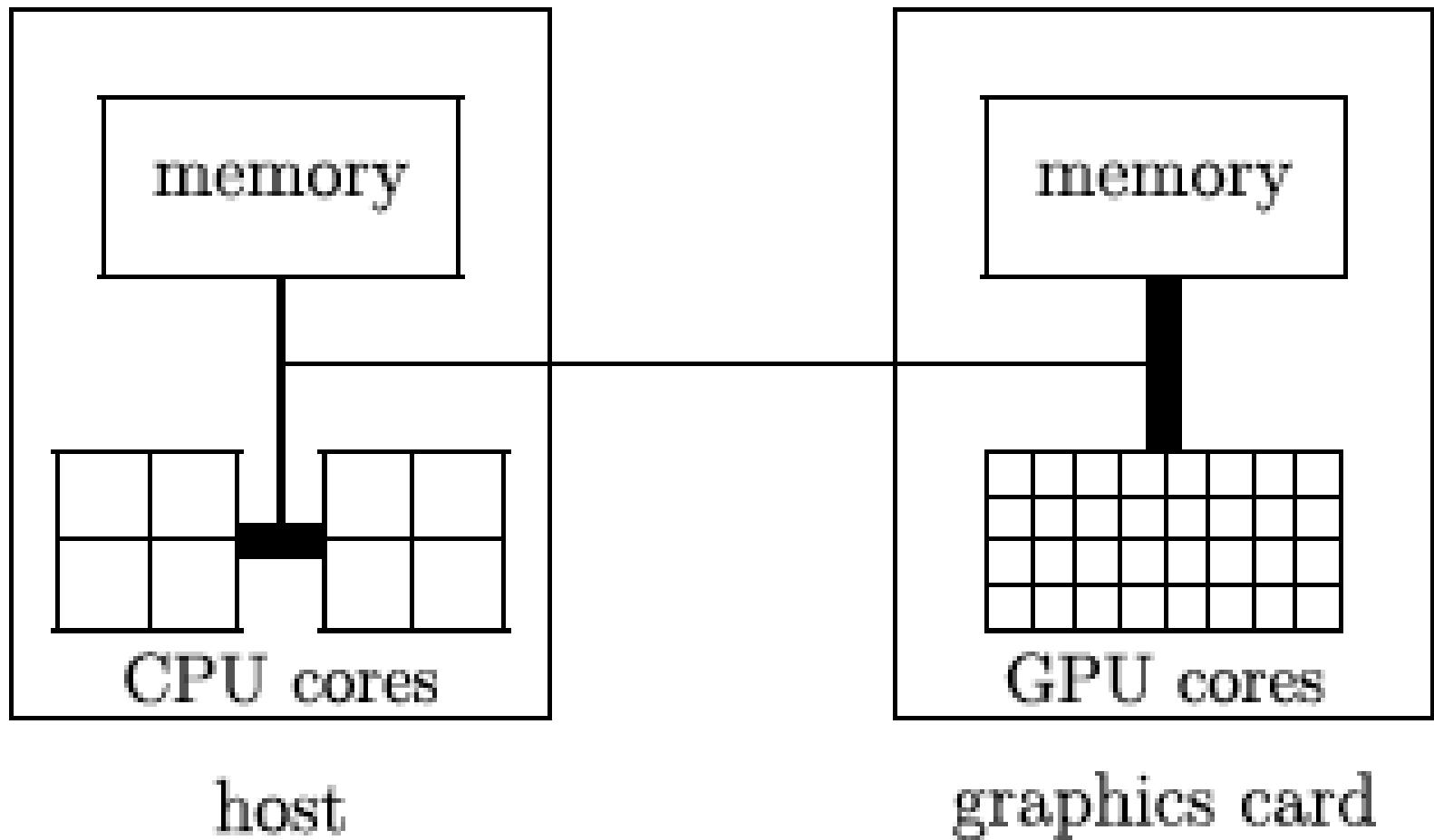
- A. A review of GPU parallelism
- B. How to GPU-parallelize the following:
  - 1. vector addition
  - 2. the pairwise (cascading) sum
  - 3. matrix multiplication

## HOW THE CPU AND GPU WORK TOGETHER

A GPU can't run a whole computer on its own because it doesn't have access to all the computer's hardware.

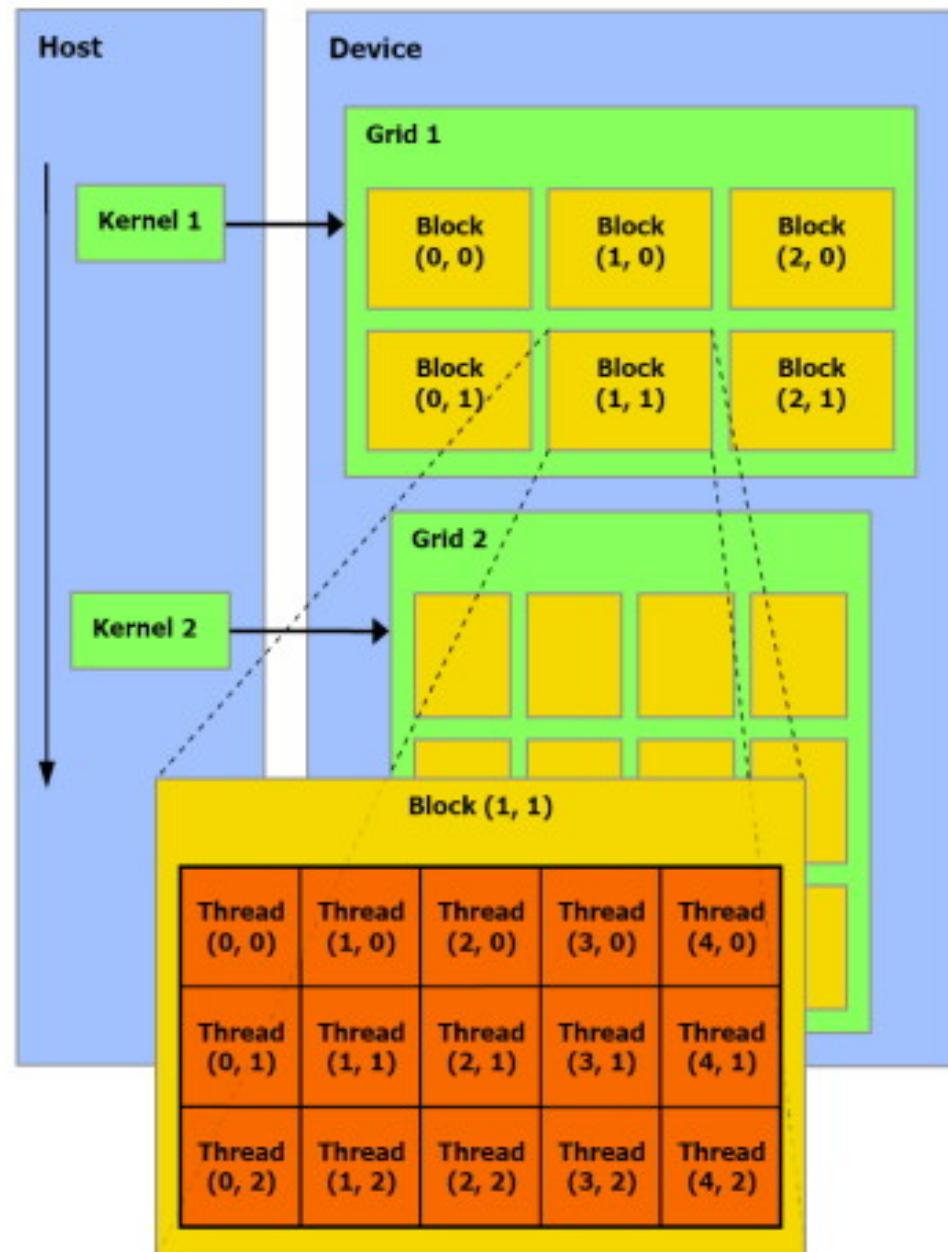
In a GPU-capable computer, the CPU is the main processor, and the GPU is an optional hardware add-on.

The CPU uses the GPU like a human would use a hand-held calculator: the CPU does all the main thinking and the GPU does the most cumbersome bits and pieces of number-crunching.



# GPU PARALLELISM

1. The CPU sends a CPU-to-GPU command called a **kernel** to a single GPU core.
2. The GPU core multitasks to execute the command:
  - a. The GPU makes  $B \cdot T$  **copies** of the kernel's code, and then runs all those copies simultaneously. Those parallel copies are called **threads**.
  - b. The  $B \cdot T$  threads are partitioned into  $B$  groups, called **blocks**, of  $T$  threads each.
  - c. The sum total of all the threads from a kernel call is a **grid**.



# WHEN TO PARALLELIZE

Calculations you want to parallelize:

- Highly repetitive floating point arithmetic procedures that can all be done simultaneously.

Calculations you don't want to parallelize:

- Inherently sequential calculations, such as recursions.
- Lengthy control flow: if-then statements, etc.
- CPU system routines, such as printing to the console.

# EXAMPLES OF EASILY PARALLELIZABLE ALGORITHMS

Linear algebraic algorithms are particularly amenable to GPU computing because they involve a high volume of simple arithmetic.

I will showcase:

1. vector addition
2. the pairwise (cascading) sum
3. matrix multiplication

# VECTOR ADDITION

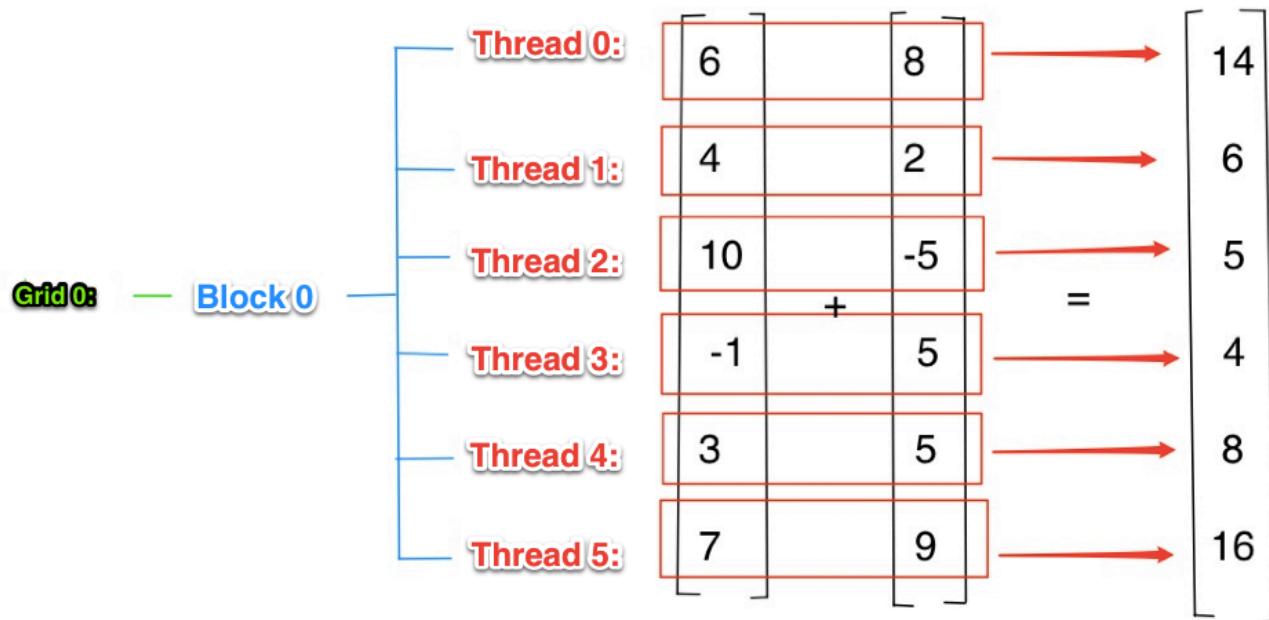
Say I have two vectors:

$$a = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

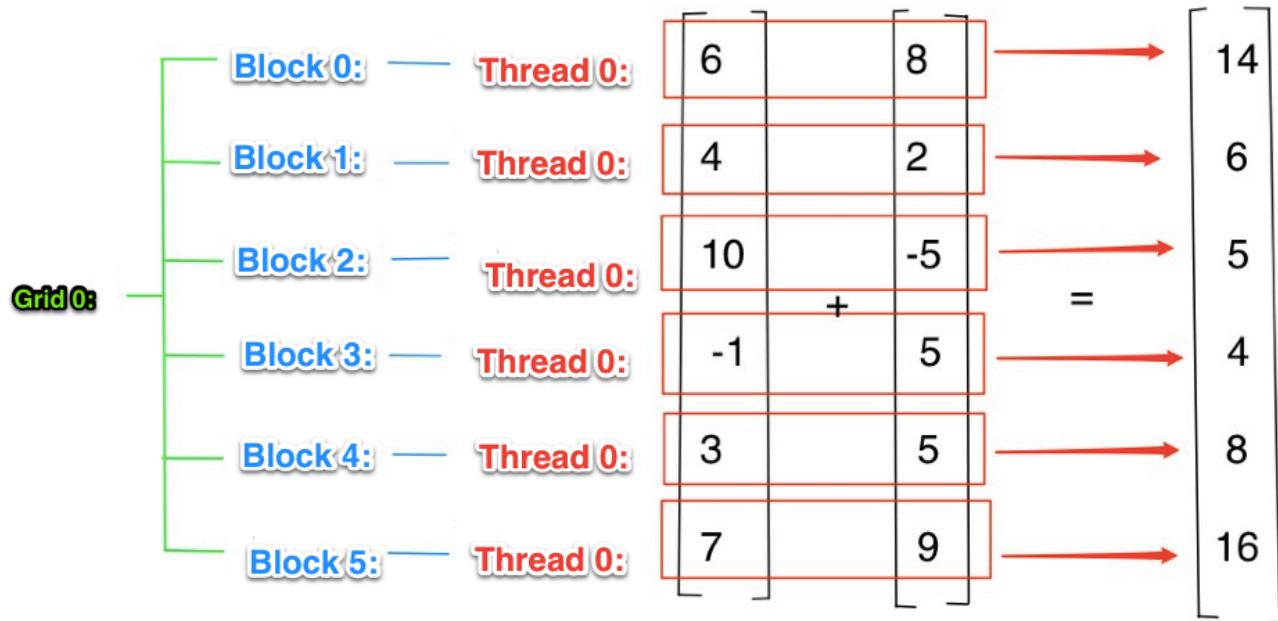
I compute their sum,  $c = a + b$ , by:

$$c = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} a_1 + b_1 \\ a_2 + b_2 \\ \vdots \\ a_n + b_n \end{bmatrix}$$

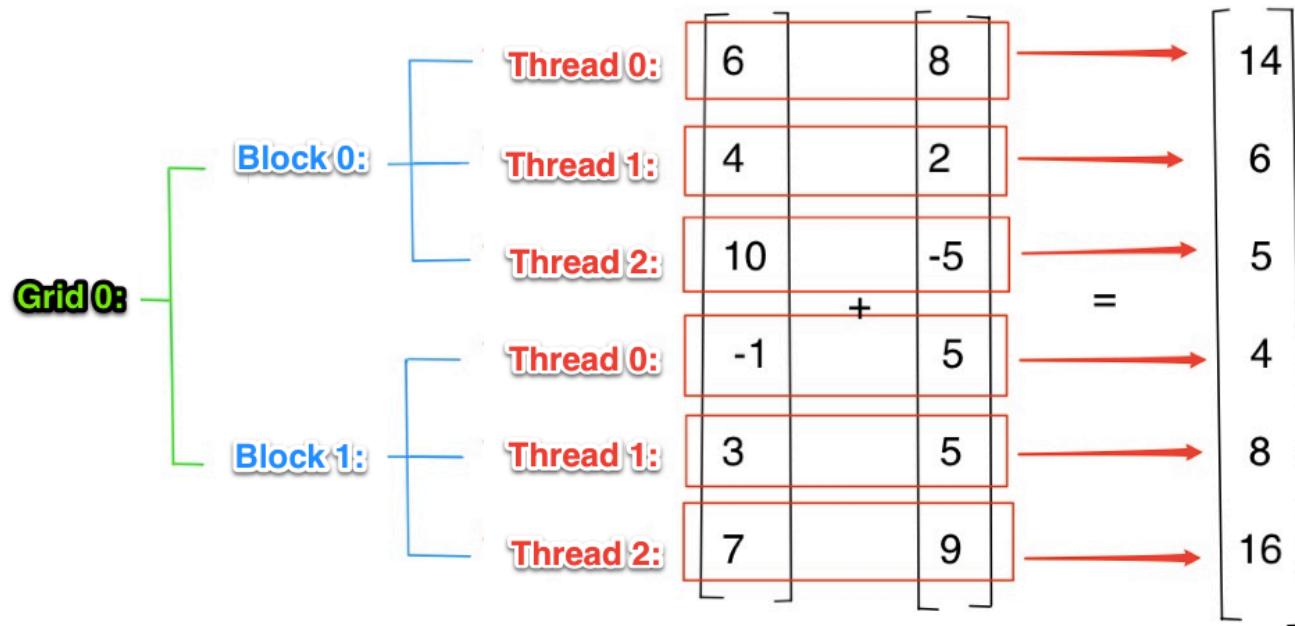
# PARALLELIZING VECTOR ADDITION: METHOD 1 OF 3



# PARALLELIZING VECTOR ADDITION: METHOD 2 OF 3



# PARALLELIZING VECTOR ADDITION: METHOD 3 OF 3

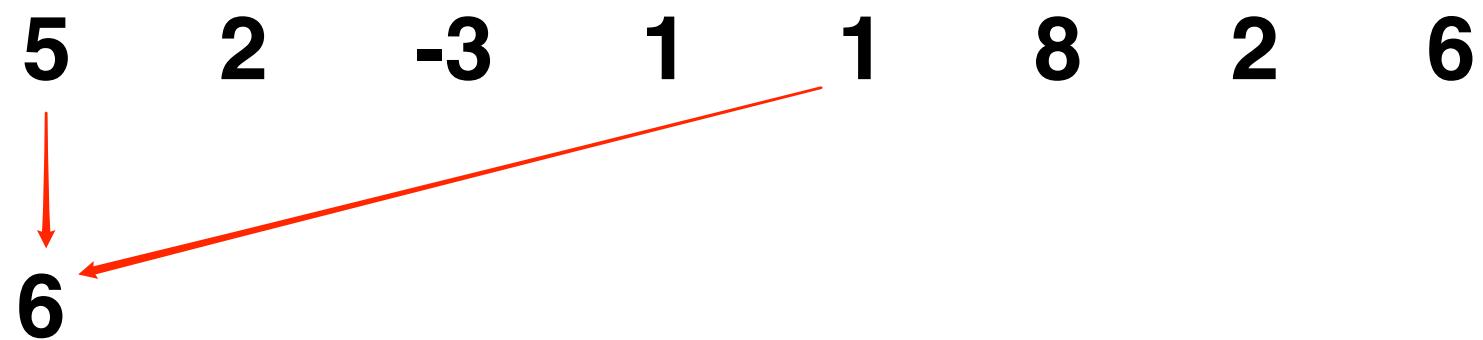


## THE PAIRWISE SUM

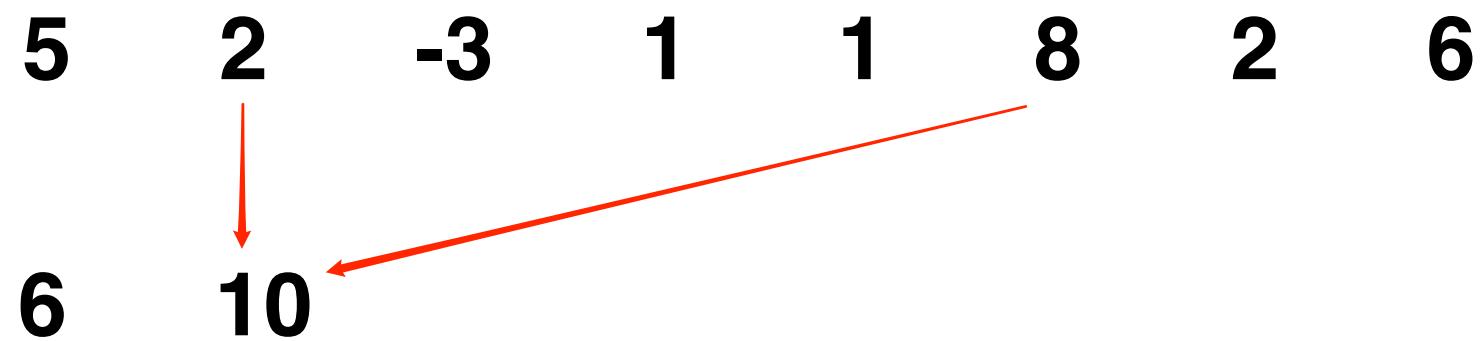
Let's take the pairwise sum of the vector:

$$(5, 2, -3, 1, 1, 8, 2, 6)$$

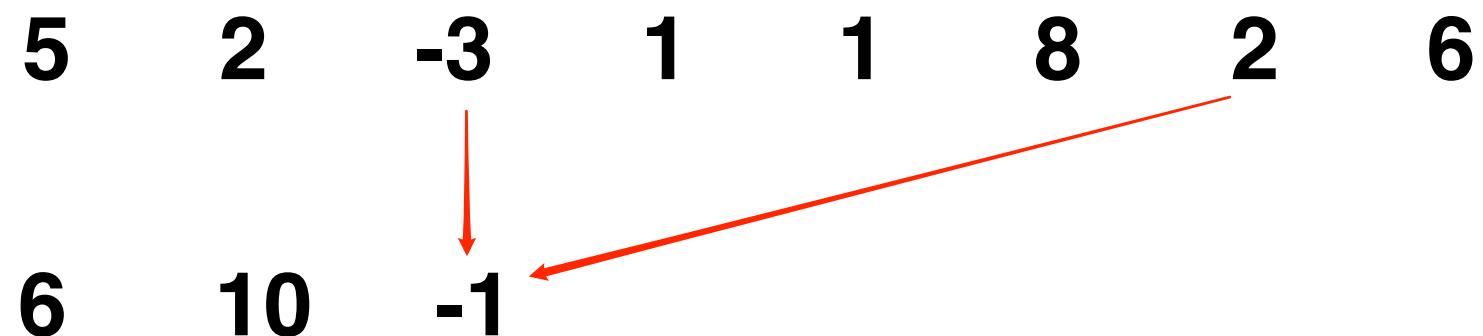
Using one block of 4 threads.



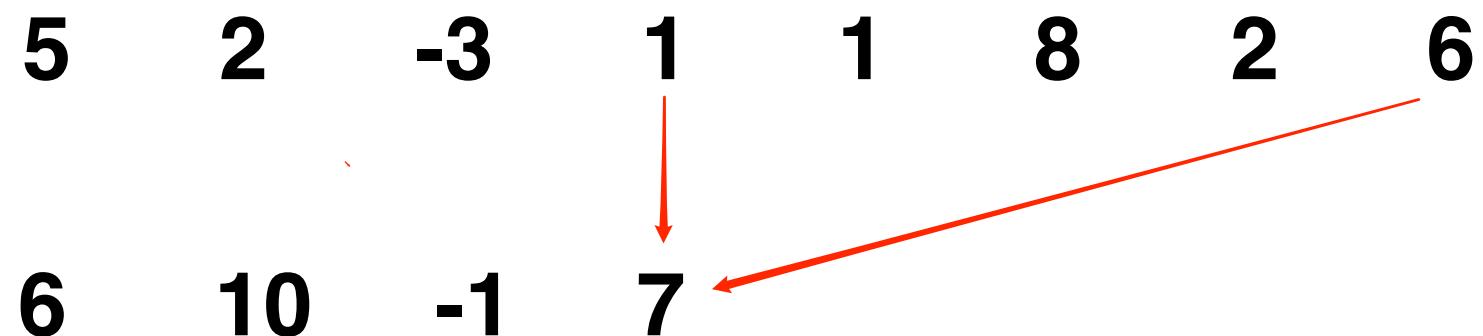
Thread 0



Thread 1



**Thread 2**



Thread 3

5    2    -3    1    1    8    2    6

6    10    -1    7



**Synchronize threads**

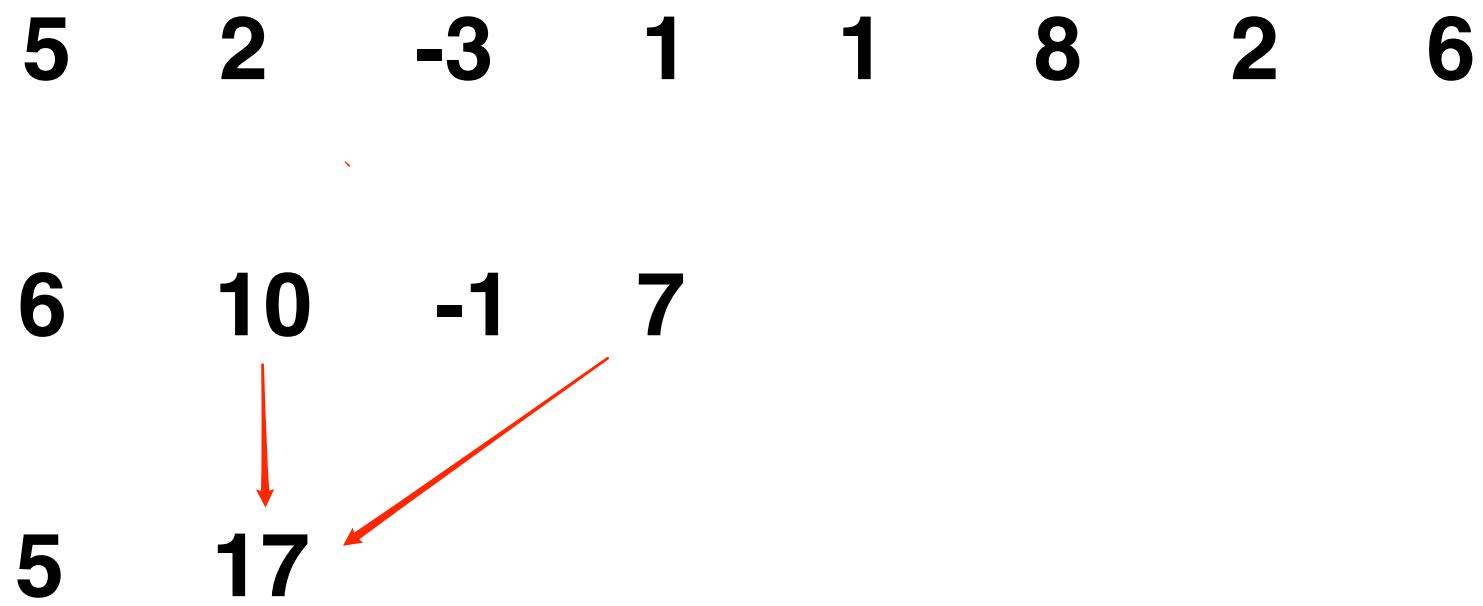
5    2    -3    1    1    8    2    6

6    10    -1    7

5

A red arrow points from the number 6 in the top row to the number 5 in the bottom row.

Thread 0



5    2    -3    1    1    8    2    6

6    10    -1    7

5    17

---

Synchronize Threads

5    2    -3    1    1    8    2    6

6    10    -1    7

5    17



22

Thread 0

## AN ASIDE: SYNCHRONIZING THREADS

**Synchronization:** Waiting for all parallel tasks to reach a checkpoint before allowing any of them to proceed.

- Threads from the same block can be synchronized easily.
- In general, do not try to synchronize threads from different blocks. It's possible, but extremely inefficient.

# A RIGOROUS DESCRIPTION OF THE PAIRWISE SUM

Suppose you have a vector  $X_0 = (x_{(0,0)}, x_{(0,2)}, \dots, x_{(0,n-1)})$ , where  $n = 2^m$  for some  $m > 0$ .

Compute  $\sum_{i=1}^n x_{(0,i)}$  in the following way:

1. Create a new vector:

$$X_1 = \left( \underbrace{x_{(0,0)} + x_{(0,n/2)}}_{x_{(1,0)}}, \underbrace{x_{(0,1)} + x_{(0,n/2+1)}}_{x_{(1,1)}}, \dots, \underbrace{x_{(0,n/2-1)} + x_{(0,n-1)}}_{x_{(1,n/2-1)}} \right)$$

2. Create another new vector:

$$X_2 = \left( \underbrace{x_{(1,0)} + x_{(1,n/4)}}_{x_{(2,0)}}, \underbrace{x_{(1,1)} + x_{(1,n/4+1)}}_{x_{(2,1)}}, \dots, \underbrace{x_{(1,n/4-1)} + x_{(1,n/2-1)}}_{x_{(2,n/4-1)}} \right)$$

3. Continue this process until you get a singleton vector:

$$X_m = \left( \underbrace{x_{(m-1,0)} + x_{(m-1,1)}}_{x_{(m,0)}} \right)$$

Notice:  $\sum_{i=1}^n x_{(0,i)} = x_{(m,0)}$

# PARALLELIZING THE PAIRWISE SUM

Spawn one grid with a single block and  $n/2$  threads ( $n = 2^m$ ). Starting with  $i = 1$ , do the following:

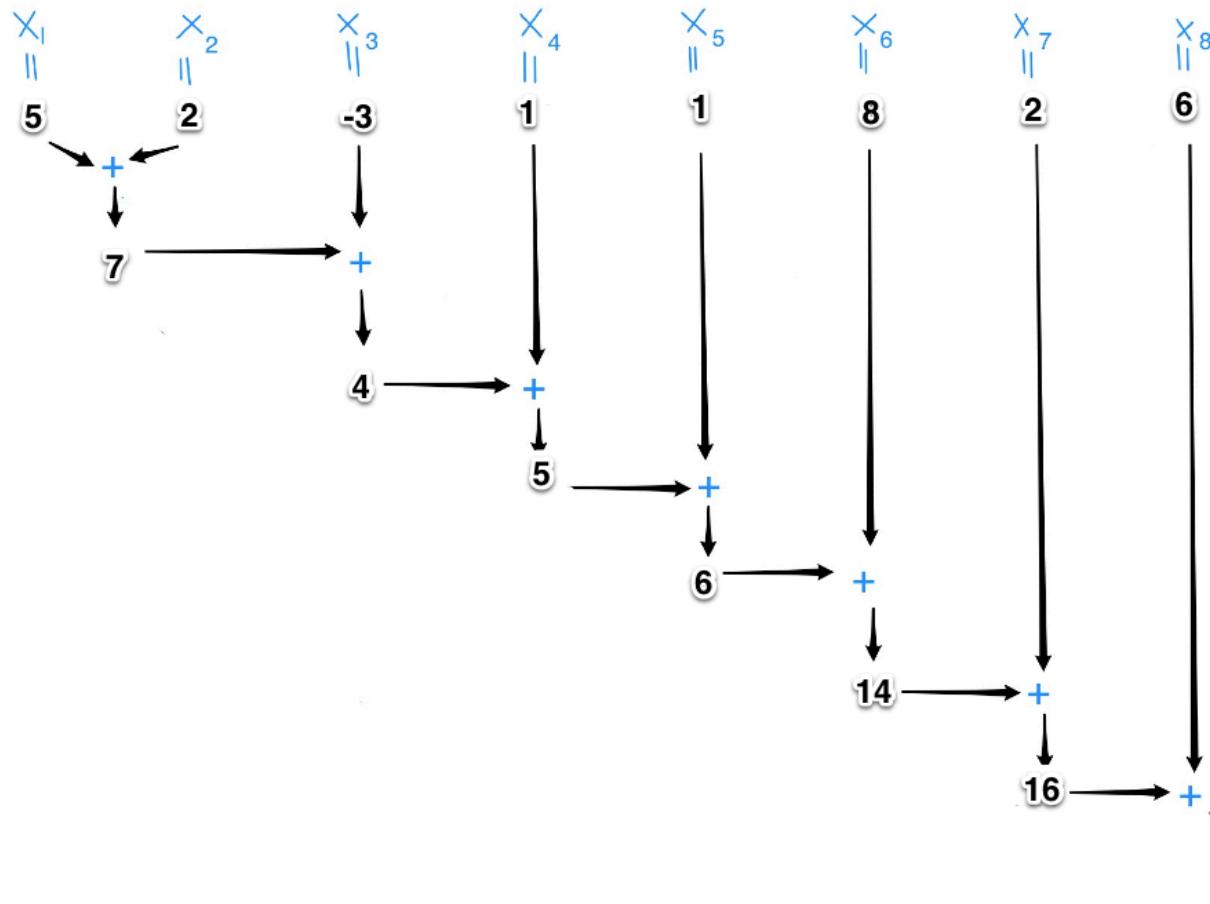
1. Set offset =  $n/2^i$ .
2. Assign thread  $j$  to compute:

$$x_{(i,j)} = x_{(i-1, j)} + x_{(i-1, j+\text{offset})}$$

for  $j = 0, 2, \dots, \text{offset} - 1$ .

3. Wait until all the above  $\frac{n}{2^i}$  threads have completed step 2.
4. Integer divide offset by 2. Repeat if offset > 0.

## ASIDE: COMPARE TO THE SEQUENTIAL VERSION



The pairwise sum requires only  $\log_2(n)$  sequential steps, whereas the sequential sum requires  $n - 1$  steps.

### 3. MATRIX MULTIPLICATION

Consider an  $m \times n$  matrix,  $A = (a_{ij})$ , and an  $n \times p$  matrix,  $B = (b_{ij})$ . Compute  $A \cdot B$ :

1. Break apart  $A$  into its rows:  $A = \begin{bmatrix} a_{1\cdot} \\ a_{2\cdot} \\ \vdots \\ a_{m\cdot} \end{bmatrix}$ , where each  $a_{i\cdot} = [a_{i1} \ a_{i2} \ \cdots \ a_{in}]$
2. Break apart  $B$  into its columns:  $B = [b_{\cdot 1} \ b_{\cdot 2} \ \cdots \ b_{\cdot p}]$ , where each  $b_{\cdot j} = \begin{bmatrix} b_{1j} \\ b_{2j} \\ \vdots \\ b_{nj} \end{bmatrix}$
3. Compute  $C = A \cdot B$  elementwise, using the usual matrix multiplication rules to find each  $a_i \cdot b_j$ :

$$C = A \cdot B = \begin{bmatrix} (a_{1\cdot} \cdot b_{\cdot 1}) & (a_{1\cdot} \cdot b_{\cdot 2}) & \cdots & (a_{1\cdot} \cdot b_{\cdot p}) \\ (a_{2\cdot} \cdot b_{\cdot 1}) & (a_{2\cdot} \cdot b_{\cdot 2}) & & (a_{2\cdot} \cdot b_{\cdot p}) \\ \vdots & & \ddots & \vdots \\ (a_{m\cdot} \cdot b_{\cdot 1}) & (a_{m\cdot} \cdot b_{\cdot 2}) & \cdots & (a_{m\cdot} \cdot b_{\cdot p}) \end{bmatrix}$$

i.e.:

$$C_{(i,j)} = a_{i\cdot} \cdot b_{\cdot j}$$

# PARALLELIZING MATRIX MULTIPLICATION

Spawn one grid with  $m \cdot p$  blocks. Assign block  $(i, j)$  to compute  $C_{(i,j)} = a_{i\cdot} \cdot b_{\cdot j}$ . Within each block:

1. Spawn  $n$  threads.
2. Tell the  $k$ 'th thread to compute  $c_{ijk} = a_{ik}b_{kj}$ .
3. Synchronize the  $n$  threads to make sure we have finished calculating all of  $c_{ij1}, c_{ij2}, \dots, c_{ijn}$  before proceeding.
4. Compute  $C_{(i,j)} = \sum_{k=1}^n c_{ijk}$  as a pairwise sum.

## EXAMPLE

Say I want to compute  $A \cdot B$ , where:

$$A = \begin{bmatrix} 1 & 2 \\ -1 & 5 \\ 7 & -9 \end{bmatrix} \quad B = \begin{bmatrix} 8 & 8 & 7 \\ 3 & 5 & 2 \end{bmatrix}$$

which I'm setting up as:

$$C = A \cdot B = \begin{bmatrix} \left( [1 \ 2] \cdot \begin{bmatrix} 8 \\ 3 \end{bmatrix} \right) & \left( [1 \ 2] \cdot \begin{bmatrix} 8 \\ 5 \end{bmatrix} \right) & \left( [1 \ 2] \cdot \begin{bmatrix} 7 \\ 2 \end{bmatrix} \right) \\ \left( [-1 \ 5] \cdot \begin{bmatrix} 8 \\ 3 \end{bmatrix} \right) & \left( [-1 \ 5] \cdot \begin{bmatrix} 8 \\ 5 \end{bmatrix} \right) & \left( [-1 \ 5] \cdot \begin{bmatrix} 7 \\ 2 \end{bmatrix} \right) \\ \left( [7 \ -9] \cdot \begin{bmatrix} 8 \\ 3 \end{bmatrix} \right) & \left( [7 \ -9] \cdot \begin{bmatrix} 8 \\ 5 \end{bmatrix} \right) & \left( [7 \ -9] \cdot \begin{bmatrix} 7 \\ 2 \end{bmatrix} \right) \end{bmatrix}$$

$$\begin{bmatrix} \text{Block (0, 0)} \\ \left( [1 \ 2] \cdot \begin{bmatrix} 8 \\ 3 \end{bmatrix} \right) \end{bmatrix} \quad \begin{bmatrix} \text{Block (1, 0)} \\ \left( [1 \ 2] \cdot \begin{bmatrix} 8 \\ 5 \end{bmatrix} \right) \end{bmatrix} \quad \begin{bmatrix} \text{Block (2, 0)} \\ \left( [1 \ 2] \cdot \begin{bmatrix} 7 \\ 2 \end{bmatrix} \right) \end{bmatrix}$$
  

$$\begin{bmatrix} \text{Block (0, 1)} \\ \left( [-1 \ 5] \cdot \begin{bmatrix} 8 \\ 3 \end{bmatrix} \right) \end{bmatrix} \quad \begin{bmatrix} \text{Block (1, 1)} \\ \left( [-1 \ 5] \cdot \begin{bmatrix} 8 \\ 5 \end{bmatrix} \right) \end{bmatrix} \quad \begin{bmatrix} \text{Block (2, 1)} \\ \left( [-1 \ 5] \cdot \begin{bmatrix} 7 \\ 2 \end{bmatrix} \right) \end{bmatrix}$$
  

$$\begin{bmatrix} \text{Block (0, 2)} \\ \left( [7 \ -9] \cdot \begin{bmatrix} 8 \\ 3 \end{bmatrix} \right) \end{bmatrix} \quad \begin{bmatrix} \text{Block (1, 2)} \\ \left( [7 \ -9] \cdot \begin{bmatrix} 8 \\ 5 \end{bmatrix} \right) \end{bmatrix} \quad \begin{bmatrix} \text{Block (2, 2)} \\ \left( [7 \ -9] \cdot \begin{bmatrix} 7 \\ 2 \end{bmatrix} \right) \end{bmatrix}$$

We don't need to synchronize the blocks because they can do their jobs independently.

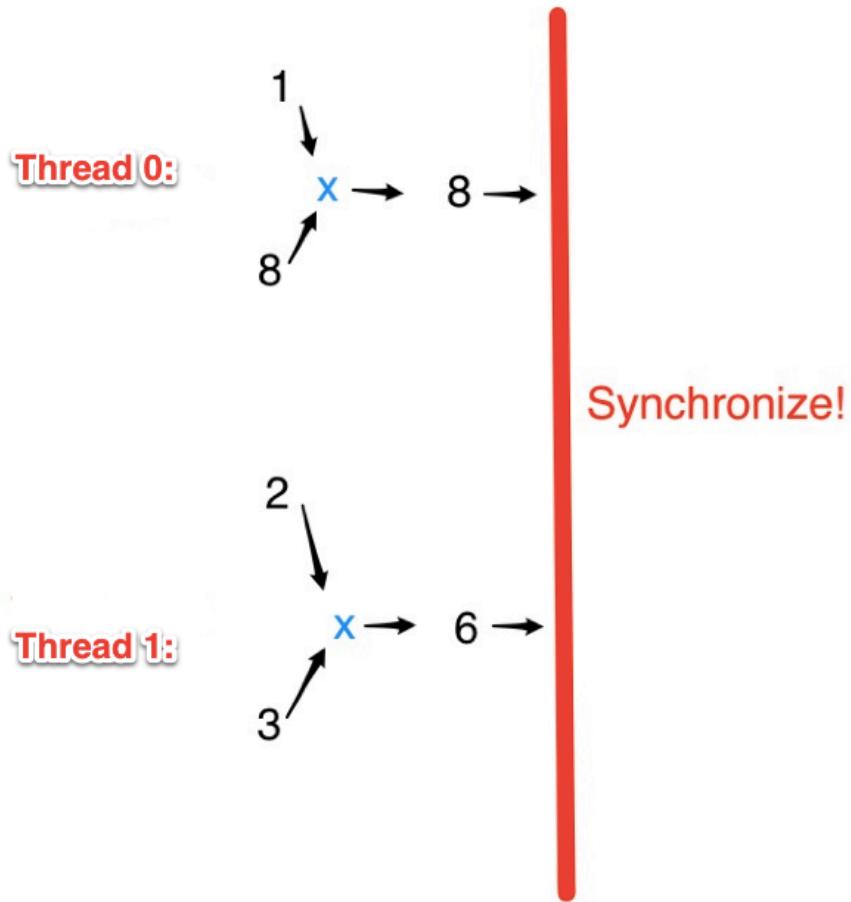
Consider Block (0,0), which computes  $\begin{bmatrix} 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} 8 \\ 3 \end{bmatrix}$ :

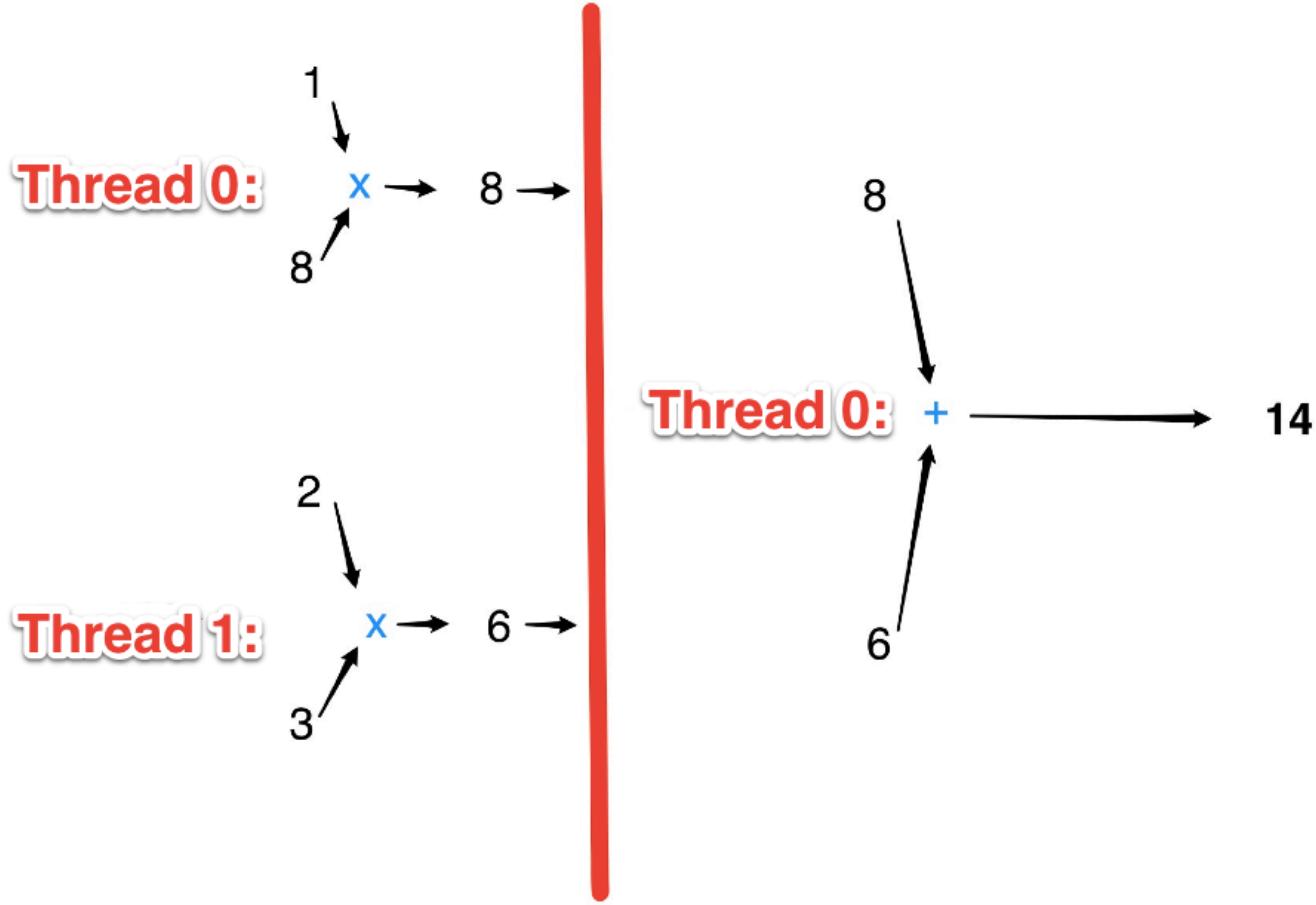
**Thread 0:**

$$\begin{array}{ccc} 1 & \downarrow & \\ & x \rightarrow & 8 \\ 8 & \nearrow & \end{array}$$

**Thread 1:**

$$\begin{array}{ccc} 2 & \downarrow & \\ & x \rightarrow & 6 \\ 3 & \nearrow & \end{array}$$





# OUTLINE

- A. A review of GPU parallelism
- B. How to GPU-parallelize the following:
  - 1. vector addition
  - 2. the pairwise (cascading) sum
  - 3. matrix multiplication

## PREVIEW: skeleton.cu, A BARE BONES CUDA C WORKFLOW

```
#include <stdio.h>
#include <stdlib.h>
#include <cuda.h>
#include <cuda_runtime.h>

__global__ void some_kernel(...){...}

int main (void){
    // Declare all variables.
    ...
    // Dynamically allocate host memory.
    ...
    // Dynamically allocate device memory.
    ...
    // Write to host memory.
    ...
    // Copy host memory to device memory.
    ...
    // Execute kernel on the device.
    some_kernel<<< num_blocks, num_threads_per_block >>>(...);

    // Write device memory back to host memory.
    ...
    // Free dynamically-allocated host memory
    ...
    // Free dynamically-allocated device memory
    ...
}
```

# MATERIALS

These slides, a tentative syllabus for the whole lecture series, and code are available at:

<https://github.com/wlandau/gpu>.

After logging into you home directory on impact1, type:

```
git clone https://github.com/wlandau/gpu
```

into the command line to download all the materials.

## REFERENCES

Lay, David C. *Linear Algebra and Its Applications*. 3rd Ed. Addison Wesley, 2006.

J. Sanders and E. Kandrot. *CUDA by Example*. Addison-Wesley, 2010.