

Robust DPG Test Norms for Space-Time Convection-Diffusion

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Overview of DPG

A Framework for Computational Mechanics

Find $u \in U$ such that

$$b(u, v) = l(v) \quad \forall v \in V$$

with operator $B : U \rightarrow V'$ defined by $b(u, v) = \langle Bu, v \rangle_{V' \times V}$.

This gives the operator equation

$$Bu = l \in V'.$$

We wish to minimize the residual $Bu - l \in V'$:

$$u_h = \arg \min_{w_h \in U_h} \frac{1}{2} \|Bw_h - l\|_{V'}^2.$$

Dual norms are not computationally tractable. Inverse Riesz map moves the residual to a more accessible space:

$$u_h = \arg \min_{w_h \in U_h} \frac{1}{2} \|R_V^{-1}(Bw_h - l)\|_V^2.$$

Petrov-Galerkin with Optimal Test Functions

Taking the Gâteaux derivative to be zero in all directions $\delta u \in U_h$ gives,

$$(R_V^{-1}(Bu_h - l), R_V^{-1}B\delta u)_V = 0, \quad \forall \delta u \in U,$$

which by definition of the Riesz map is equivalent to

$$\langle Bu_h - l, R_V^{-1}B\delta u_h \rangle = 0 \quad \forall \delta u_h \in U_h,$$

with optimal test functions $v_{\delta u_h} := R_V^{-1}B\delta u_h$ for each trial function δu_h .

Resulting Petrov-Galerkin System

This gives a simple bilinear form

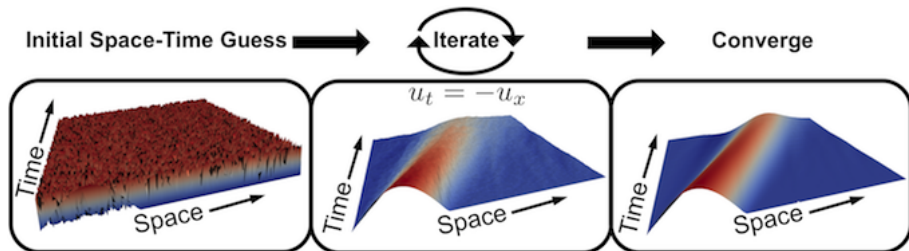
$$b(u_h, v_{\delta u_h}) = l(v_{\delta u_h}),$$

with $v_{\delta u_h} \in V$ that solves the auxiliary problem

$$(v_{\delta u_h}, \delta v)_V = \langle R_V v_{\delta u_h}, \delta v \rangle = \langle B\delta u_h, \delta v \rangle = b(\delta u_h, \delta v) \quad \forall \delta v \in V.$$

Extending DPG to Transient Problems

- Time stepping techniques are not ideally suited to highly adaptive grids
- Space-time FEM proposed as a solution
 - ✓ Unified treatment of space and time
 - ✓ Local space-time adaptivity (local time stepping)
 - ✓ Parallel-in-time integration (space-time multigrid)
 - ✗ Spatially stable FEM methods may not be stable in space-time
 - ✗ Need to support higher dimensional problems
- DPG provides necessary stability and adaptivity



Courtesy XBraid by LLNL

Space-Time Divergence Form

Equation is parabolic in space-time.

$$\frac{\partial u}{\partial t} + \beta \cdot \nabla u - \epsilon \Delta u = f$$

This is just a composition of a constitutive law and conservation of mass.

$$\sigma - \epsilon \nabla u = 0$$

$$\frac{\partial u}{\partial t} + \nabla \cdot (\beta u - \sigma) = f$$

We can rewrite this in terms of a space-time divergence.

$$\begin{aligned} \frac{1}{\epsilon} \sigma - \nabla u &= 0 \\ \nabla_{xt} \cdot \begin{pmatrix} \beta u - \sigma \\ u \end{pmatrix} &= f \end{aligned}$$

Multiply by test function and integrate by parts over space-time element K .

$$\begin{aligned} \left(\frac{1}{\epsilon} \boldsymbol{\sigma}, \boldsymbol{\tau} \right)_K + (u, \nabla \cdot \boldsymbol{\tau})_K - \langle \hat{u}, \boldsymbol{\tau} \cdot \mathbf{n}_x \rangle_{\partial K} &= 0 \\ - \left(\begin{pmatrix} \beta u - \boldsymbol{\sigma} \\ u \end{pmatrix}, \nabla_{xt} v \right)_K + \langle \hat{t}, v \rangle_{\partial K} &= f \end{aligned}$$

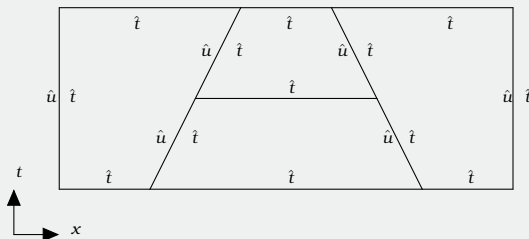
where

$$\hat{u} := \text{tr}(u)$$

$$\begin{aligned} \hat{t} &:= \text{tr}(\beta u - \boldsymbol{\sigma}) \cdot \mathbf{n}_x \\ &\quad + \text{tr}(u) \cdot n_t \end{aligned}$$

- Trace \hat{u} defined on spatial boundaries
- Flux \hat{t} defined on all boundaries

Support of Trace Variables



L^2 Equivalent Norms

Bilinear form with group variables:

$$b((u, \hat{u}), v) = (u, A_h^* v)_{L^2(\Omega_h)} + \langle \hat{u}, \llbracket v \rrbracket \rangle_{\Gamma_h}$$

For conforming v^* satisfying $A^* v^* = u$

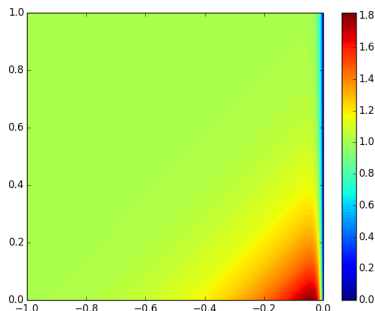
$$\begin{aligned} \|u\|_{L^2(\Omega_h)}^2 &= b(u, v^*) = \frac{b(u, v^*)}{\|v^*\|_V} \|v^*\|_V \\ &\leq \sup_{v^* \neq 0} \frac{|b(u, v^*)|}{\|v^*\|} \|v^*\| = \|u\|_E \|v^*\|_V \end{aligned}$$

Necessary robustness condition:

$$\begin{aligned} \|v^*\|_V &\lesssim \|u\|_{L^2(\Omega_h)} \\ \Rightarrow \|u\|_{L^2(\Omega_h)} &\lesssim \|u\|_E \end{aligned}$$

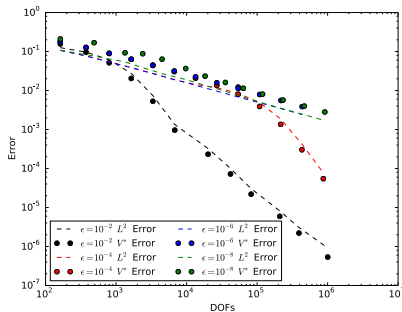
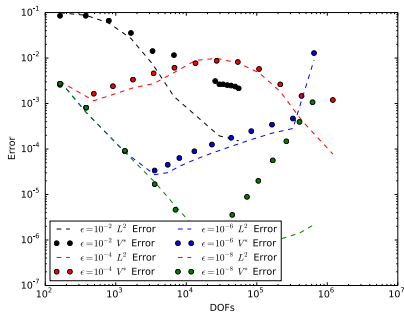
Analytical Solution

$$e^{-\lambda t} (e^{\lambda_1(x-1)} - e^{\lambda_2(x-1)}) + \left(1 - e^{\frac{1}{\epsilon} x}\right)$$



L^2 Equivalent Norms

A norm should be: bounded by $\|u\|_{L^2(\Omega_h)}$, have good conditioning, not produce boundary layers in the optimal test function.



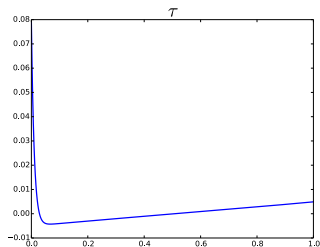
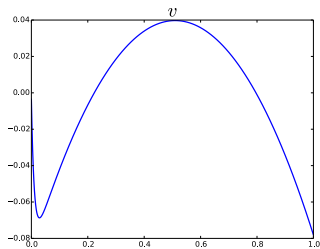
$$\begin{aligned} \|(v, \tau)\|^2 &= \left\| \nabla \cdot \tau - \tilde{\beta} \cdot \nabla_{xt} v \right\|^2 \\ &+ \left\| \frac{1}{\epsilon} \tau + \nabla v \right\|^2 + \|v\|^2 + \|\tau\|^2 \end{aligned}$$

$$\begin{aligned} \|(v, \tau)\|^2 &= \left\| \nabla \cdot \tau - \tilde{\beta} \cdot \nabla_{xt} v \right\|^2 \\ &+ \min \left(\frac{1}{h^2}, \frac{1}{\epsilon} \right) \|\tau\|^2 \\ &+ \epsilon \|\nabla v\|^2 + \|\beta \cdot \nabla v\|^2 + \|v\|^2 \end{aligned}$$

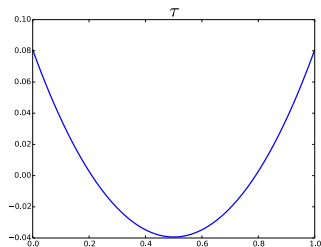
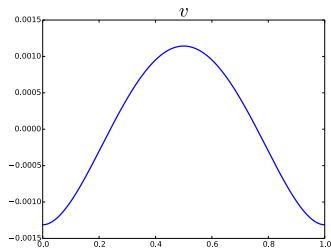
Steady Convection-Diffusion

Ideal Optimal Shape Functions

Graph Norm



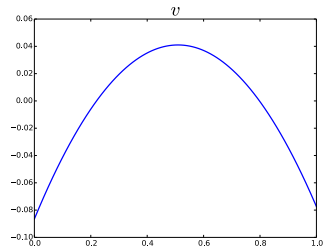
Coupled Robust Norm



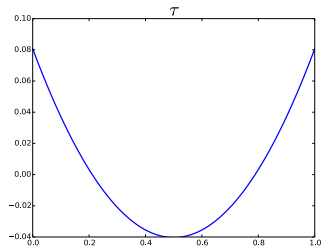
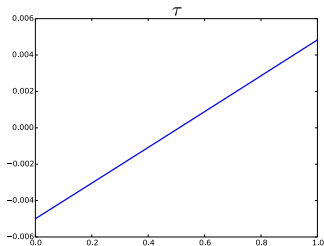
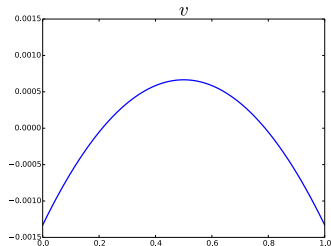
Steady Convection-Diffusion

Approximated ($p = 3$) Optimal Shape Functions

Graph Norm



Coupled Robust Norm



Two Robust Norms for Steady Convection-Diffusion

The following norms are robust for steady convection-diffusion.

The robust norm was derived in¹:

$$\begin{aligned} \|(v, \tau)\|^2 = & \|\beta \cdot \nabla v\|^2 + \epsilon \|\nabla v\|^2 + \min\left(\frac{\epsilon}{h^2}, 1\right) \|v\|^2 \\ & + \|\nabla \cdot \tau\|^2 + \min\left(\frac{1}{h^2}, \frac{1}{\epsilon}\right) \|\tau\|^2. \end{aligned}$$

The case for the coupled robust norm was made in²:

$$\begin{aligned} \|(v, \tau)\|^2 = & \|\beta \cdot \nabla v\|^2 + \epsilon \|\nabla v\|^2 + \min\left(\frac{\epsilon}{h^2}, 1\right) \|v\|^2 \\ & + \|\nabla \cdot \tau - \beta \cdot \nabla v\|^2 + \min\left(\frac{1}{h^2}, \frac{1}{\epsilon}\right) \|\tau\|^2. \end{aligned}$$

¹J. Chan et al. "A robust DPG method for convection-dominated diffusion problems II: Adjoint boundary conditions and mesh-dependent test norms". In: *Comp. Math. Appl.* 67.4 (2014). High-order Finite Element Approximation for Partial Differential Equations, pp. 771–795.

²J.L. Chan. "A DPG Method for Convection-Diffusion Problems". PhD thesis. University of Texas at Austin, 2013.

Space-Time Convection-Diffusion

Two Robust Norms for Transient Convection-Diffusion

Let $\tilde{\beta} := \begin{pmatrix} \beta \\ 1 \end{pmatrix}$ and $\nabla_{xt} v := \begin{pmatrix} \nabla v \\ \frac{\partial v}{\partial t} \end{pmatrix}$.

The following norms are robust for space-time convection-diffusion.

Robust Norm:

$$\begin{aligned} \|(v, \tau)\|^2 &= \left\| \tilde{\beta} \cdot \nabla_{xt} v \right\|^2 + \epsilon \|\nabla v\|^2 + \min\left(\frac{\epsilon}{h^2}, 1\right) \|v\|^2 \\ &\quad + \|\nabla \cdot \tau\|^2 + \min\left(\frac{1}{h^2}, \frac{1}{\epsilon}\right) \|\tau\|^2. \end{aligned}$$

Coupled Robust Norm

$$\begin{aligned} \|(v, \tau)\|^2 &= \left\| \tilde{\beta} \cdot \nabla_{xt} v \right\|^2 + \epsilon \|\nabla v\|^2 + \min\left(\frac{\epsilon}{h^2}, 1\right) \|v\|^2 \\ &\quad + \left\| \nabla \cdot \tau - \tilde{\beta} \cdot \nabla_{xt} v \right\|^2 + \min\left(\frac{1}{h^2}, \frac{1}{\epsilon}\right) \|\tau\|^2. \end{aligned}$$

Adjoint Operator

Consider the problem with homogeneous boundary conditions

$$\begin{aligned}\frac{1}{\epsilon} \boldsymbol{\sigma} - \nabla u &= 0 \\ \tilde{\boldsymbol{\beta}} \cdot \nabla_{xt} u - \nabla \cdot \boldsymbol{\sigma} &= f \\ \beta_n u - \epsilon \frac{\partial u}{\partial n} &= 0 \text{ on } \Gamma_- \\ u &= 0 \text{ on } \Gamma_+ \\ u &= u_0 \text{ on } \Gamma_0.\end{aligned}$$

The adjoint operator A^* is given by

$$A^*(v, \boldsymbol{\tau}) = \left(\frac{1}{\epsilon} \boldsymbol{\tau} + \nabla v, -\tilde{\boldsymbol{\beta}} \cdot \nabla_{xt} v + \nabla \cdot \boldsymbol{\tau} \right).$$

Controlling Different Field Variables

We decompose the continuous adjoint problem $A^*(\tau, v) = (\sigma, u)$ into

Continuous part with forcing u

$$\begin{aligned} \frac{1}{\epsilon} \tau_1 + \nabla v_1 &= 0 & \tau_1 \cdot \mathbf{n}_x &= 0 \text{ on } \Gamma_- \\ -\tilde{\beta} \cdot \nabla_{xt} v_1 + \nabla \cdot \tau_1 &= u & v_1 &= 0 \text{ on } \Gamma_+ \\ & & v_1 &= 0 \text{ on } \Gamma_T \end{aligned}$$

Continuous part with forcing σ

$$\begin{aligned} \frac{1}{\epsilon} \tau_2 + \nabla v_2 &= \sigma & \tau_2 \cdot \mathbf{n}_x &= 0 \text{ on } \Gamma_- \\ -\tilde{\beta} \cdot \nabla_{xt} v_2 + \nabla \cdot \tau_2 &= 0 & v_2 &= 0 \text{ on } \Gamma_+ \\ & & v_2 &= 0 \text{ on } \Gamma_T \end{aligned}$$

Proved Bounds at Our Disposal

Proofs of these lemmas can be found in³.

Lemma (1)

If $\nabla \cdot \beta = 0$, we can bound

$$\|v\|^2 + \epsilon \|\nabla v\|^2 \leq \|u\|^2 + \epsilon \|\sigma\|^2$$

where $v = v_1 + v_2$.

Lemma (2)

If $\|\nabla \beta - \frac{1}{2} \nabla \cdot \beta \mathbf{I}\|_{L^\infty} \leq C_\beta$, we can bound

$$\|\tilde{\beta} \cdot \nabla_{xt} v_1\| \lesssim \|u\|.$$

³T.E. Ellis, J.L. Chan, and L.F. Demkowicz. *Robust DPG Methods for Transient Convection-Diffusion*. Tech. rep. 15-21, ICES, Oct. 2015.

Bound on $\|(v_1, \tau_1)\|$

$$\text{Lemma (2)} \Rightarrow \left\| \tilde{\beta} \cdot \nabla_{xt} v_1 \right\| \lesssim \|u\|$$

$$\text{Lemma (2)} \Rightarrow \left\| \nabla \cdot \tau_1 \right\| \leq \|u\| + \left\| \tilde{\beta} \cdot \nabla_{xt} v_1 \right\| \lesssim 2 \|u\|$$

$$\text{Lemma (2)} \Rightarrow \left\| \nabla \cdot \tau_1 - \tilde{\beta} \cdot \nabla_{xt} v_1 \right\| = \|u\|$$

$$\text{Lemma (1)} \Rightarrow \|v_1\|^2 + \epsilon \|\nabla v_1\|^2 \leq \|u\|^2$$

$$\text{Lemma (1)} \Rightarrow \frac{1}{\epsilon} \|\tau_1\| = \epsilon \|\nabla v_1\| \leq \|u\|$$

We can guarantee robust control

$$\|(u, 0)\|_{L^2(\Omega_h)} \lesssim \|(u, \sigma)\|_E .$$

Bound on $\|(v_2, \tau_2)\|$

$$\text{Definition} \Rightarrow \left\| \nabla \cdot \tau_2 - \tilde{\beta} \cdot \nabla_{xt} v_2 \right\| = 0 \leq \|\sigma\|$$

$$\text{Lemma (1)} \Rightarrow \|v_2\|^2 + \epsilon \|\nabla v_2\|^2 \leq \epsilon \|\sigma\|^2$$

$$\text{Lemma (1)} \Rightarrow \frac{1}{\epsilon} \|\tau_2\| = \|\sigma\| + \epsilon \|\nabla v_2\| = (1 + \epsilon) \|\sigma\|$$

We have not been able to prove bounds on $\|\tilde{\beta} \cdot \nabla_{xt} v_2\|$ or $\|\nabla \cdot \tau_2\|$.

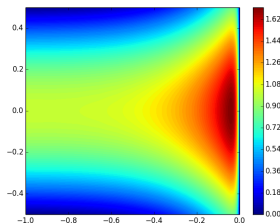
We can **not** guarantee robust control

$$\|(0, \sigma)\|_{L^2(\Omega_h)} \not\lesssim \|(u, \sigma)\|_E .$$

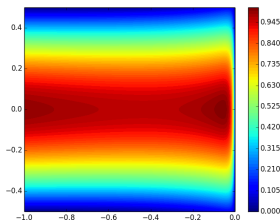
Transient Analytical Solution

Transient impulse decays to Eriksson-Johnson steady state solution.

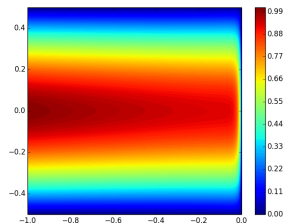
$$u = \exp(-lt) [\exp(\lambda_1 x) - \exp(\lambda_2 x)] + \cos(\pi y) \frac{\exp(s_1 x) - \exp(r_1 x)}{\exp(-s_1) - \exp(-r_1)}$$



$t = 0.0$



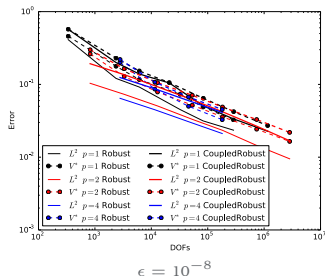
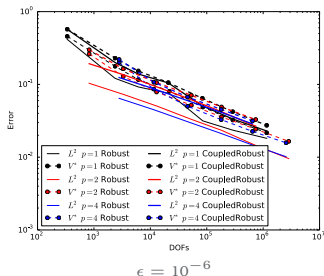
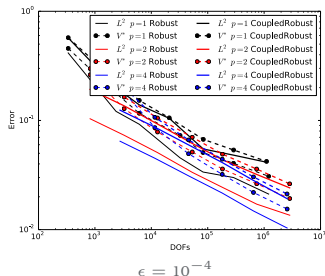
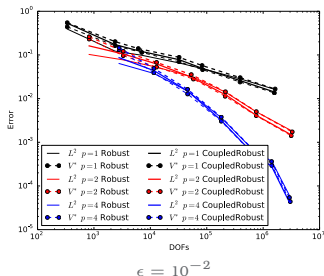
$t = 0.5$



$t = 1.0$

Robust Norms for Transient Convection-Diffusion

Robust Convergence to Analytical Solution



Thank You!

Recommended References

- ▶ J. Chan et al. "A robust DPG method for convection-dominated diffusion problems II: Adjoint boundary conditions and mesh-dependent test norms". In: *Comp. Math. Appl.* 67.4 (2014). High-order Finite Element Approximation for Partial Differential Equations, pp. 771–795.
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- ▶ L.F. Demkowicz and J. Gopalakrishnan. *Discontinuous Petrov-Galerkin (DPG) Method*. Tech. rep. 15-20. ICES, Dec. 2015.
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- ▶ N.V. Roberts, L.F. Demkowicz, and R.D. Moser. "A discontinuous Petrov-Galerkin methodology for adaptive solutions to the incompressible Navier-Stokes equations". In: *J. Comput. Phys.* 301 (2015), pp. 456–483. issn: 0021-9991.