

# Derivation of Space-Time DPG for the Euler Equations in Conservation Form

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The 1D Euler equations in conservation form are

$$\frac{\partial}{\partial t} \begin{bmatrix} \rho \\ m \\ E \end{bmatrix} + \frac{\partial}{\partial x} \begin{bmatrix} m \\ m^2/\rho + p \\ (E+p)m/\rho \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

If we define

$$\nabla := \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial t} \end{bmatrix}$$

then we can rewrite the 1D Euler equations as a system.

$$\begin{aligned} \nabla \cdot \begin{bmatrix} m \\ \rho \end{bmatrix} &= 0 \\ \nabla \cdot \begin{bmatrix} m^2/\rho + p \\ m \end{bmatrix} &= 0 \\ \nabla \cdot \begin{bmatrix} (E+p)m/\rho \\ E \end{bmatrix} &= 0 \end{aligned}$$

Multiplying each equation by  $v_m$  (for mass),  $v_x$  (for x-momentum), and  $v_e$  (for energy), and integrating by parts over spacetime  $Q$ :

$$\begin{aligned} \int_{\partial Q} v_m \begin{bmatrix} m \\ \rho \end{bmatrix} \cdot \mathbf{n} - \int_Q \begin{bmatrix} m \\ \rho \end{bmatrix} \cdot \nabla v_m &= 0 \\ \int_{\partial Q} v_x \begin{bmatrix} m^2/\rho + p \\ m \end{bmatrix} \cdot \mathbf{n} - \int_Q \begin{bmatrix} m^2/\rho + p \\ m \end{bmatrix} \cdot \nabla v_x &= 0 \\ \int_{\partial Q} v_e \begin{bmatrix} (E+p)m/\rho \\ E \end{bmatrix} \cdot \mathbf{n} - \int_Q \begin{bmatrix} (E+p)m/\rho \\ E \end{bmatrix} \cdot \nabla v_e &= 0 \end{aligned}$$

Now identify the fluxes

$$\begin{aligned} \hat{F}_m &:= \begin{bmatrix} m \\ \rho \end{bmatrix} \cdot \mathbf{n} \\ \hat{F}_x &:= \begin{bmatrix} m^2/\rho + p \\ m \end{bmatrix} \cdot \mathbf{n} \\ \hat{F}_e &:= \begin{bmatrix} (E+p)m/\rho \\ E \end{bmatrix} \cdot \mathbf{n} \end{aligned}$$

Assuming an ideal gas equation of state, linearize the volume terms.

$$\begin{aligned}
F_m(\mathbf{U}) &:= \begin{bmatrix} m \\ \rho \end{bmatrix} \approx \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \Delta\rho \\ \Delta m \\ \Delta E \end{bmatrix} \\
F_x(\mathbf{U}) &:= \begin{bmatrix} \frac{3-\gamma}{2} \frac{m^2}{\rho} + (\gamma-1)E \\ m \end{bmatrix} \approx \begin{bmatrix} \frac{\gamma-3}{2} \frac{m^2}{\rho^2} & (3-\gamma)\frac{m}{\rho} & (\gamma-1) \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} \Delta\rho \\ \Delta m \\ \Delta E \end{bmatrix} \\
F_e(\mathbf{U}) &:= \begin{bmatrix} \frac{1-\gamma}{2} \frac{m^3}{\rho^2} + \gamma \frac{m}{\rho} E \\ E \end{bmatrix} \approx \begin{bmatrix} (\gamma-1)\frac{m^3}{\rho^3} - \gamma \frac{m}{\rho^2} E & \frac{3(1-\gamma)}{2} \frac{m^2}{\rho^2} + \gamma \frac{E}{\rho} & \gamma \frac{m}{\rho} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \Delta\rho \\ \Delta m \\ \Delta E \end{bmatrix}
\end{aligned}$$

Finally, our space-time DPG formulation of the Euler equations is as follows.

Given background flow quantities  $\rho, u, e \in L^2(Q)$ , find  $\Delta\rho, \Delta u, \Delta e \in L^2(Q)$ , and  $\hat{F}_m, \hat{F}_x, \hat{F}_e \in H^{-\frac{1}{2}}$  such that

$$\begin{aligned}
\int_{\partial Q} \hat{F}_m v_m - \int_Q \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \Delta\rho \\ \Delta m \\ \Delta E \end{bmatrix} \cdot \nabla v_m &= \int_Q \begin{bmatrix} m \\ \rho \end{bmatrix} \cdot \nabla v_m \\
\int_{\partial Q} \hat{F}_x v_x - \int_Q \begin{bmatrix} \frac{\gamma-3}{2} \frac{m^2}{\rho^2} & (3-\gamma)\frac{m}{\rho} & (\gamma-1) \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} \Delta\rho \\ \Delta m \\ \Delta E \end{bmatrix} \cdot \nabla v_x &= \int_Q \begin{bmatrix} \frac{3-\gamma}{2} \frac{m^2}{\rho} + (\gamma-1)E \\ m \end{bmatrix} \cdot \nabla v_x \\
\int_{\partial Q} \hat{F}_e v_e - \int_Q \begin{bmatrix} (\gamma-1)\frac{m^3}{\rho^3} - \gamma \frac{m}{\rho^2} E & \frac{3(1-\gamma)}{2} \frac{m^2}{\rho^2} + \gamma \frac{E}{\rho} & \gamma \frac{m}{\rho} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \Delta\rho \\ \Delta m \\ \Delta E \end{bmatrix} \cdot \nabla v_e &= \int_Q \begin{bmatrix} \frac{1-\gamma}{2} \frac{m^3}{\rho^2} + \gamma \frac{m}{\rho} E \\ E \end{bmatrix} \cdot \nabla v_e
\end{aligned}$$

for all  $v_m, v_x$ , and  $v_e$ .

As a first cut, we will use the graph norm.