

Derivation of Space-Time DPG for the Euler Equations

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The 1D Euler equations are

$$\frac{\partial}{\partial t} \begin{bmatrix} \rho \\ \rho u \\ \rho e + \frac{1}{2} \rho u^2 \end{bmatrix} + \frac{\partial}{\partial x} \begin{bmatrix} \rho u \\ \rho u^2 + p \\ (\rho e + \frac{1}{2} \rho u^2 + p)u \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

If we define

$$\nabla := \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial t} \end{bmatrix}$$

then we can rewrite the 1D Euler equations as a system.

$$\begin{aligned} \nabla \cdot \begin{bmatrix} \rho u \\ \rho \end{bmatrix} &= 0 \\ \nabla \cdot \begin{bmatrix} \rho u^2 + p \\ \rho u \end{bmatrix} &= 0 \\ \nabla \cdot \begin{bmatrix} (\rho e + \frac{1}{2} \rho u^2 + p)u \\ \rho e + \frac{1}{2} \rho u^2 \end{bmatrix} &= 0 \end{aligned}$$

Multiplying each equation by v_m (for mass), v_x (for x-momentum), and v_e (for energy), and integrating by parts over spacetime Q :

$$\begin{aligned} \int_{\partial Q} v_m \begin{bmatrix} \rho u \\ \rho \end{bmatrix} \cdot \mathbf{n} - \int_Q \begin{bmatrix} \rho u \\ \rho \end{bmatrix} \cdot \nabla v_m &= 0 \\ \int_{\partial Q} v_x \begin{bmatrix} \rho u^2 + p \\ \rho u \end{bmatrix} \cdot \mathbf{n} - \int_Q \begin{bmatrix} \rho u^2 + p \\ \rho u \end{bmatrix} \cdot \nabla v_x &= 0 \\ \int_{\partial Q} v_e \begin{bmatrix} (\rho e + \frac{1}{2} \rho u^2 + p)u \\ \rho e + \frac{1}{2} \rho u^2 \end{bmatrix} \cdot \mathbf{n} - \int_Q \begin{bmatrix} (\rho e + \frac{1}{2} \rho u^2 + p)u \\ \rho e + \frac{1}{2} \rho u^2 \end{bmatrix} \cdot \nabla v_e &= 0 \end{aligned}$$

Now identify the fluxes

$$\begin{aligned}\hat{F}_m &:= \begin{bmatrix} \rho u \\ \rho \end{bmatrix} \cdot \mathbf{n} \\ \hat{F}_x &:= \begin{bmatrix} \rho u^2 + p \\ \rho u \end{bmatrix} \cdot \mathbf{n} \\ \hat{F}_e &:= \begin{bmatrix} (\rho e + \frac{1}{2}\rho u^2 + p)u \\ \rho e + \frac{1}{2}\rho u^2 \end{bmatrix} \cdot \mathbf{n}\end{aligned}$$

Assuming an ideal gas equation of state, linearize the volume terms.

$$F_m(\mathbf{U}) := \begin{bmatrix} \rho u \\ \rho \end{bmatrix} \approx \begin{bmatrix} u & \rho & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \Delta \rho \\ \Delta u \\ \Delta e \end{bmatrix}$$

$$F_x(\mathbf{U}) := \begin{bmatrix} \rho u^2 + \rho(\gamma - 1)e \\ \rho u \end{bmatrix} \approx \begin{bmatrix} u^2 + (\gamma - 1)e & 2\rho u & \rho(\gamma - 1) \\ u & \rho & 0 \end{bmatrix} \begin{bmatrix} \Delta \rho \\ \Delta u \\ \Delta e \end{bmatrix}$$

$$F_e(\mathbf{U}) := \begin{bmatrix} (\rho e + \frac{1}{2}\rho u^2 + \rho(\gamma - 1)e)u \\ \rho e + \frac{1}{2}\rho u^2 \end{bmatrix} \approx \begin{bmatrix} \gamma e u + \frac{1}{2}u^3 & \rho \gamma e + \frac{3}{2}\rho u^2 & \rho \gamma u \\ e + \frac{1}{2}u^2 & \rho u & \rho \end{bmatrix} \begin{bmatrix} \Delta \rho \\ \Delta u \\ \Delta e \end{bmatrix}$$

Finally, our space-time DPG formulation of the Euler equations is as follows.

Given background flow quantities $\rho, u, e \in L^2(Q)$, find $\Delta \rho, \Delta u, \Delta e \in L^2(Q)$, and $\hat{F}_m, \hat{F}_x, \hat{F}_e \in H^{-\frac{1}{2}}$ such that

$$\begin{aligned}\int_{\partial Q} \hat{F}_m v_m - \int_Q \begin{bmatrix} u & \rho & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \Delta \rho \\ \Delta u \\ \Delta e \end{bmatrix} \cdot \nabla v_m &= \int_Q \begin{bmatrix} \rho u \\ \rho \end{bmatrix} \cdot \nabla v_m \\ \int_{\partial Q} \hat{F}_x v_x - \int_Q \begin{bmatrix} u^2 + (\gamma - 1)e & 2\rho u & \rho(\gamma - 1) \\ u & \rho & 0 \end{bmatrix} \begin{bmatrix} \Delta \rho \\ \Delta u \\ \Delta e \end{bmatrix} \cdot \nabla v_x &= \int_Q \begin{bmatrix} \rho u^2 + \rho(\gamma - 1)e \\ \rho u \end{bmatrix} \cdot \nabla v_x \\ \int_{\partial Q} \hat{F}_e v_e - \int_Q \begin{bmatrix} \gamma e u + \frac{1}{2}u^3 & \rho \gamma e + \frac{3}{2}\rho u^2 & \rho \gamma u \\ e + \frac{1}{2}u^2 & \rho u & \rho \end{bmatrix} \begin{bmatrix} \Delta \rho \\ \Delta u \\ \Delta e \end{bmatrix} \cdot \nabla v_e &= \int_Q \begin{bmatrix} (\rho e + \frac{1}{2}\rho u^2 + \rho(\gamma - 1)e)u \\ \rho e + \frac{1}{2}\rho u^2 \end{bmatrix} \cdot \nabla v_e\end{aligned}$$

for all v_m, v_x , and v_e .

As a first cut, we will use the graph norm.