Space-Time Navier-Stokes with Entropy Variables

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Nonlinear Forms

Primitive Variables

Consider the DPG Navier-Stokes derivation from previously with primitive variables:

$$\left(\frac{1}{\mu}\mathbb{D}, \mathbb{S}\right) + (2\boldsymbol{u}, \nabla \cdot \mathbb{S}) - \left(\frac{2}{3}\boldsymbol{u}, \nabla \operatorname{tr} \mathbb{S}\right) - \left\langle\frac{4}{3}\hat{\boldsymbol{u}}, \mathbb{S}\boldsymbol{n}_{x}\right\rangle = 0 \tag{1a}$$

$$\left(\frac{Pr}{C_{p}\mu}\boldsymbol{q},\boldsymbol{\tau}\right) - (T,\nabla\cdot\boldsymbol{\tau}) + \left\langle \hat{T},\tau_{n}\right\rangle = 0 \tag{1b}$$

$$-\left(\begin{pmatrix} \rho \mathbf{u} \\ \rho \end{pmatrix}, \nabla_{xt} v_c \right) + \langle \hat{t}_c, v_c \rangle = (f_c, v_c)$$
 (1c)

$$-\left(\left(\begin{array}{c} \rho \boldsymbol{u} \otimes \boldsymbol{u} + \rho R T \boldsymbol{I} - \mathbb{D} \\ \rho \boldsymbol{u} \end{array}\right), \nabla_{xt} \boldsymbol{v}_{m}\right) + \left\langle \hat{\boldsymbol{t}}_{m}, \boldsymbol{v}_{m} \right\rangle = (\boldsymbol{f}_{m}, \boldsymbol{v}_{m})$$
(1d)

$$-\left(\left(\begin{array}{c} \rho \boldsymbol{u} \left(C_{v}T + \frac{1}{2}\boldsymbol{u} \cdot \boldsymbol{u}\right) + \boldsymbol{u}\rho RT + \boldsymbol{q} - \boldsymbol{u} \cdot \mathbb{D} \\ \rho \left(C_{v}T + \frac{1}{2}\boldsymbol{u} \cdot \boldsymbol{u}\right) \end{array}\right), \nabla_{xt} v_{e} + \langle \hat{t}_{e}, v_{e} \rangle = (f_{e}, v_{e}), \quad (1e)$$

where

$$\hat{\boldsymbol{u}} = \operatorname{tr}(\boldsymbol{u})
\hat{T} = \operatorname{tr}(T)
\hat{t}_c = \operatorname{tr}(\rho \boldsymbol{u}) \cdot \boldsymbol{n}_x + \operatorname{tr}(\rho) n_t
\hat{\boldsymbol{t}}_m = \operatorname{tr}(\rho \boldsymbol{u} \otimes \boldsymbol{u} + \rho RT \boldsymbol{I} - \mathbb{D}) \cdot \boldsymbol{n}_x + \operatorname{tr}(\rho \boldsymbol{u}) n_t
\hat{t}_e = \operatorname{tr}\left(\rho \boldsymbol{u}\left(C_v T + \frac{1}{2}\boldsymbol{u} \cdot \boldsymbol{u}\right) + \boldsymbol{u}\rho RT + \boldsymbol{q} - \boldsymbol{u} \cdot \mathbb{D}\right) \cdot \boldsymbol{n}_x
+ \operatorname{tr}\left(\rho\left(C_v T + \frac{1}{2}\boldsymbol{u} \cdot \boldsymbol{u}\right)\right) n_t.$$

Now define primitive fluxes for continuity, momentum, and energy equations:

$$egin{aligned} oldsymbol{F}_c^p &:=
ho oldsymbol{u} \ oldsymbol{F}_m^p &:=
ho oldsymbol{u} \otimes oldsymbol{u} +
ho RT oldsymbol{I} \ oldsymbol{F}_e^p &:=
ho oldsymbol{u} \left(C_v T + rac{1}{2} oldsymbol{u} \cdot oldsymbol{u}
ight) + oldsymbol{u}
ho RT \end{aligned}$$

Our bilinear form is then simplified:

$$\left(\frac{1}{\mu}\mathbb{D}, \mathbb{S}\right) + (2\boldsymbol{u}, \nabla \cdot \mathbb{S}) - \left(\frac{2}{3}\boldsymbol{u}, \nabla \operatorname{tr} \mathbb{S}\right) - \left\langle \frac{4}{3}\hat{\boldsymbol{u}}, \mathbb{S}\boldsymbol{n}_x \right\rangle = 0 \tag{2a}$$

$$\left(\frac{Pr}{C_p\mu}\mathbf{q},\boldsymbol{\tau}\right) - (T,\nabla\cdot\boldsymbol{\tau}) + \left\langle \hat{T},\tau_n\right\rangle = 0$$
(2b)

$$-\left(\begin{pmatrix} \mathbf{F}_{c}^{p} \\ \rho \end{pmatrix}, \nabla_{xt} v_{c}\right) + \langle \hat{t}_{c}, v_{c} \rangle = (f_{c}, v_{c})$$
 (2c)

$$-\left(\left(\begin{array}{c} \mathbb{F}_{m}^{p} - \mathbb{D} \\ \rho \boldsymbol{u} \end{array}\right), \nabla_{xt} \boldsymbol{v}_{m}\right) + \langle \hat{\boldsymbol{t}}_{m}, \boldsymbol{v}_{m} \rangle = (\boldsymbol{f}_{m}, \boldsymbol{v}_{m})$$
(2d)

$$-\left(\begin{pmatrix} \mathbf{F}_{e}^{p} + \mathbf{q} - \mathbf{u} \cdot \mathbb{D} \\ \rho \left(C_{v}T + \frac{1}{2}\mathbf{u} \cdot \mathbf{u}\right) \end{pmatrix}, \nabla_{xt}v_{e}\right) + \langle \hat{t}_{e}, v_{e} \rangle = (f_{e}, v_{e}) , \qquad (2e)$$

Conservation Variables

Now we wish to do a change of variables to conservation variables:

$$egin{aligned}
ho &=
ho \ m{m} &=
ho m{u} \end{aligned}$$
 $E =
ho \left(C_v T + rac{1}{2} m{u} \cdot m{u}
ight)$

We can define new fluxes in conservation variables:

$$\begin{split} & \boldsymbol{F}_{c}^{c} = \boldsymbol{m} \\ & \mathbb{F}_{m}^{c} = \frac{\boldsymbol{m} \otimes \boldsymbol{m}}{\rho} + (\gamma - 1) \left(E - \frac{\boldsymbol{m} \cdot \boldsymbol{m}}{2\rho} \right) \boldsymbol{I} \\ & \boldsymbol{F}_{e}^{c} = \frac{\boldsymbol{m}}{\rho} E + (\gamma - 1) \left(E - \frac{\boldsymbol{m} \cdot \boldsymbol{m}}{2\rho} \right) \frac{\boldsymbol{m}}{\rho} \end{split}$$

and our new bilinear form is

$$\left(\frac{1}{\mu}\mathbb{D}, \mathbb{S}\right) + \left(2\frac{\boldsymbol{m}}{\rho}, \nabla \cdot \mathbb{S}\right) - \left(\frac{2}{3}\frac{\boldsymbol{m}}{\rho}, \nabla \operatorname{tr} \mathbb{S}\right) - \left\langle\frac{4}{3}\hat{\boldsymbol{u}}, \mathbb{S}\boldsymbol{n}_x\right\rangle = 0 \tag{3a}$$

$$\left(\frac{Pr}{C_p\mu}\boldsymbol{q},\boldsymbol{\tau}\right) - \left(\frac{E - \frac{1}{2\rho}\boldsymbol{m} \cdot \boldsymbol{m}}{C_v\rho}, \nabla \cdot \boldsymbol{\tau}\right) + \left\langle \hat{T}, \tau_n \right\rangle = 0$$
(3b)

$$-\left(\begin{pmatrix} \mathbf{F}_{c}^{c} \\ \rho \end{pmatrix}, \nabla_{xt} v_{c}\right) + \langle \hat{t}_{c}, v_{c} \rangle = (f_{c}, v_{c})$$
 (3c)

$$-\left(\begin{pmatrix} \mathbb{F}_{m}^{c} - \mathbb{D} \\ \mathbf{m} \end{pmatrix}, \nabla_{xt} \mathbf{v}_{m}\right) + \langle \hat{\mathbf{t}}_{m}, \mathbf{v}_{m} \rangle = (\mathbf{f}_{m}, \mathbf{v}_{m})$$
(3d)

$$-\left(\begin{pmatrix} \mathbf{F}_{e}^{c} + \mathbf{q} - \frac{\mathbf{m}}{\rho} \cdot \mathbb{D} \\ E \end{pmatrix}, \nabla_{xt} v_{e}\right) + \langle \hat{t}_{e}, v_{e} \rangle = (f_{e}, v_{e}) , \qquad (3e)$$

Entropy Variables

Now we wish to do a change of variables to entropy variables:

$$V_c = \frac{-E + (E - \frac{1}{2\rho} \boldsymbol{m} \cdot \boldsymbol{m}) \left(\gamma + 1 - \ln \left[\frac{(\gamma - 1)(E - \frac{1}{2\rho} \boldsymbol{m} \cdot \boldsymbol{m})}{\rho^{\gamma}} \right] \right)}{E - \frac{1}{2\rho} \boldsymbol{m} \cdot \boldsymbol{m}}$$

$$\boldsymbol{V}_m = \frac{\boldsymbol{m}}{E - \frac{1}{2\rho} \boldsymbol{m} \cdot \boldsymbol{m}}$$

$$V_e = \frac{-\rho}{E - \frac{1}{2\rho} \boldsymbol{m} \cdot \boldsymbol{m}}$$

with reverse mapping:

$$\rho = -\alpha V_e$$

$$\boldsymbol{m} = \alpha \boldsymbol{V}_m$$

$$E = \alpha \left(1 - \frac{1}{2V_e} \boldsymbol{V}_m \cdot \boldsymbol{V}_m \right)$$

where

$$\alpha(V_c, \boldsymbol{V}_m, V_e) = \left[\frac{\gamma - 1}{-(V_e)^{\gamma}}\right]^{\frac{1}{\gamma - 1}} \exp\left[\frac{-\gamma + V_c - \frac{1}{2V_e}\boldsymbol{V}_m \cdot \boldsymbol{V}_m}{\gamma - 1}\right]$$

We can define new fluxes in entropy variables:

$$\begin{aligned} & \boldsymbol{F}_{c}^{e} = \alpha \boldsymbol{V}_{m} \\ & \boldsymbol{\mathbb{F}}_{m}^{e} = \alpha \left(-\frac{\boldsymbol{V}_{m} \otimes \boldsymbol{V}_{m}}{V_{e}} + (\gamma - 1)\boldsymbol{I} \right) \\ & \boldsymbol{F}_{e}^{e} = \alpha \frac{\boldsymbol{V}_{m}}{V_{e}} \left(\frac{1}{2V_{e}} \boldsymbol{V}_{m} \cdot \boldsymbol{V}_{m} - \gamma \right) \end{aligned}$$

and our new bilinear form is

$$\left(\frac{1}{\mu}\mathbb{D}, \mathbb{S}\right) - \left(2\frac{\boldsymbol{V}_m}{V_e}, \nabla \cdot \mathbb{S}\right) + \left(\frac{2}{3}\frac{\boldsymbol{V}_m}{V_e}, \nabla \operatorname{tr} \mathbb{S}\right) - \left\langle \frac{4}{3}\hat{\boldsymbol{u}}, \mathbb{S}\boldsymbol{n}_x \right\rangle = 0 \tag{4a}$$

$$\left(\frac{Pr}{C_{p}\mu}\boldsymbol{q},\boldsymbol{\tau}\right) + \left(\frac{1}{C_{v}V_{e}},\nabla\cdot\boldsymbol{\tau}\right) + \left\langle\hat{T},\tau_{n}\right\rangle = 0$$
(4b)

$$-\left(\begin{pmatrix} \mathbf{F}_{c}^{e} \\ -\alpha V_{e} \end{pmatrix}, \nabla_{xt} v_{c}\right) + \langle \hat{t}_{c}, v_{c} \rangle = (f_{c}, v_{c}) \tag{4c}$$

$$-\left(\left(\begin{array}{c} \mathbb{F}_{m}^{e} - \mathbb{D} \\ \alpha \mathbf{V}_{m} \end{array}\right), \nabla_{xt} \mathbf{v}_{m}\right) + \langle \hat{\mathbf{t}}_{m}, \mathbf{v}_{m} \rangle = (\mathbf{f}_{m}, \mathbf{v}_{m})$$
(4d)

$$-\left(\begin{pmatrix} \mathbf{F}_{e}^{e} + \mathbf{q} + \frac{\mathbf{V}_{m}}{V_{e}} \cdot \mathbb{D} \\ \alpha \left(1 - \frac{1}{2V_{e}} \mathbf{V}_{m} \cdot \mathbf{V}_{m}\right) \end{pmatrix}, \nabla_{xt} v_{e}\right) + \langle \hat{t}_{e}, v_{e} \rangle = (f_{e}, v_{e}) ,$$

$$(4e)$$

Linearization

For each change of variables, we maintain the same linear variables: $L := \{q, \hat{u}, \hat{e}, \hat{t}_c, \hat{t}_m, \hat{t}_e\}$. Let U be the set of variables involved in nonlinear interactions. We apply a linearization $U \approx \tilde{U} + \Delta U$ and solve

$$R_{,U}(\tilde{U})\Delta U + R(L) = -R(\tilde{U}),$$

where

$$R(L) = \left(\frac{Pr}{C_p \mu} \boldsymbol{q}, \boldsymbol{\tau}\right) - \left(\boldsymbol{q}, \nabla v_e\right) - \left\langle\frac{4}{3}\hat{\boldsymbol{u}}, \mathbb{S}\boldsymbol{n}_x\right\rangle + \left\langle\hat{T}, \tau_n\right\rangle + \left\langle\hat{t}_c, v_c\right\rangle + \left\langle\hat{\boldsymbol{t}}_m, v_m\right\rangle + \left\langle\hat{t}_e, v_e\right\rangle - \left(f_c, v_c\right) - \left(f_m, \boldsymbol{v}_m\right) - \left(f_e, v_e\right)$$

Primitive Variables

The set of nonlinear variables is $U^p := \{\rho, \boldsymbol{u}, T, \mathbb{D}\}$. Then $R_{,U^p}(\tilde{U}^p)\Delta U^p$ is

$$\left(\frac{1}{\mu}\Delta\mathbb{D},\mathbb{S}\right) + (2\Delta\boldsymbol{u},\nabla\cdot\mathbb{S}) - \left(\frac{2}{3}\Delta\boldsymbol{u},\nabla\operatorname{tr}\mathbb{S}\right) \\
- (\Delta T,\nabla\cdot\boldsymbol{\tau}) \\
- \left(\left(\begin{array}{c} \boldsymbol{F}_{c,U^p}^p\Delta U^p \\ \Delta\rho \end{array}\right),\nabla_{xt}v_c \right) \\
- \left(\left(\begin{array}{c} \boldsymbol{F}_{m,U^p}^p\Delta U^p - \Delta\mathbb{D} \\ \Delta\rho\tilde{\boldsymbol{u}} + \tilde{\rho}\Delta\boldsymbol{u} \end{array}\right),\nabla_{xt}\boldsymbol{v}_m \right) \\
- \left(\left(\begin{array}{c} \boldsymbol{F}_{m,U^p}^p\Delta U^p - \Delta\boldsymbol{u} \cdot \tilde{\boldsymbol{D}} - \tilde{\boldsymbol{u}} \cdot \Delta\mathbb{D} \\ C_v\Delta\rho\tilde{\boldsymbol{T}} + C_v\tilde{\rho}\Delta T + \frac{1}{2}\left(\Delta\rho\tilde{\boldsymbol{u}} \cdot \tilde{\boldsymbol{u}} + \tilde{\rho}\Delta\boldsymbol{u} \cdot \tilde{\boldsymbol{u}} + \tilde{\rho}\tilde{\boldsymbol{u}} \cdot \Delta\boldsymbol{u}\right) \right),\nabla_{xt}v_e \right)$$

where

$$\begin{split} \boldsymbol{F}^p_{c,U^p} \Delta U^p &:= \Delta \rho \tilde{\boldsymbol{u}} + \tilde{\rho} \Delta \boldsymbol{u} \\ \mathbb{F}^p_{m,U^p} &:= \Delta \rho \tilde{\boldsymbol{u}} \otimes \tilde{\boldsymbol{u}} + \tilde{\rho} \Delta \boldsymbol{u} \otimes \tilde{\boldsymbol{u}} + \tilde{\rho} \tilde{\boldsymbol{u}} \otimes \Delta \boldsymbol{u} + R \left(\Delta \rho \tilde{T} + \tilde{\rho} \Delta T \right) \boldsymbol{I} \\ \boldsymbol{F}^p_{e,U^p} &:= C_v \Delta \rho \tilde{\boldsymbol{u}} \tilde{T} + C_v \tilde{\rho} \Delta \boldsymbol{u} \tilde{T} + C_v \tilde{\rho} \tilde{\boldsymbol{u}} \Delta T \\ &\quad + \frac{1}{2} \Delta \rho \tilde{\boldsymbol{u}} \tilde{\boldsymbol{u}} \cdot \tilde{\boldsymbol{u}} + \frac{1}{2} \tilde{\rho} \Delta \boldsymbol{u} \tilde{\boldsymbol{u}} \cdot \tilde{\boldsymbol{u}} + \frac{1}{2} \tilde{\rho} \tilde{\boldsymbol{u}} \Delta \boldsymbol{u} \cdot \tilde{\boldsymbol{u}} + \frac{1}{2} \tilde{\rho} \tilde{\boldsymbol{u}} \tilde{\boldsymbol{u}} \cdot \Delta \boldsymbol{u} \\ &\quad + R \Delta \boldsymbol{u} \tilde{\rho} \tilde{T} + R \tilde{\boldsymbol{u}} \Delta \rho \tilde{T} + R \tilde{\boldsymbol{u}} \tilde{\rho} \Delta T \end{split}$$

and $R(\tilde{U}^p)$ is

$$\begin{split} \left(\frac{1}{\mu}\tilde{\mathbb{D}}, \mathbb{S}\right) + \left(2\tilde{\boldsymbol{u}}, \nabla \cdot \mathbb{S}\right) - \left(\frac{2}{3}\tilde{\boldsymbol{u}}, \nabla \operatorname{tr} \mathbb{S}\right) \\ - \left(\tilde{T}, \nabla \cdot \boldsymbol{\tau}\right) \\ - \left(\left(\begin{array}{c} \boldsymbol{F}_c^p(\tilde{U}^p) \\ \tilde{\rho} \end{array}\right), \nabla_{xt} v_c \right) \\ - \left(\left(\begin{array}{c} \mathbb{F}_m^p(\tilde{U}^p) - \tilde{\mathbb{D}} \\ \tilde{\rho}\tilde{\boldsymbol{u}} \end{array}\right), \nabla_{xt} \boldsymbol{v}_m \right) \\ - \left(\left(\begin{array}{c} \boldsymbol{F}_e^p(\tilde{U}^p) - \tilde{\boldsymbol{u}} \cdot \tilde{\mathbb{D}} \\ \tilde{\rho}\left(C_v \tilde{T} + \frac{1}{2}\tilde{\boldsymbol{u}} \cdot \tilde{\boldsymbol{u}}\right) \end{array}\right), \nabla_{xt} v_e \right) \end{split}$$

Conservation Variables

The set of nonlinear variables is $U^c := \{\rho, \boldsymbol{m}, E, \mathbb{D}\}$. Then $R_{U^c}(\tilde{U}^c)\Delta U^c$ is

$$\frac{\left(\frac{1}{\mu}\Delta\mathbb{D},\mathbb{S}\right) + \left(2\left(\frac{\Delta\boldsymbol{m}}{\tilde{\rho}} - \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}^{2}}\Delta\rho\right),\nabla\cdot\mathbb{S}\right) - \left(\frac{2}{3}\left(\frac{\Delta\boldsymbol{m}}{\tilde{\rho}} - \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}^{2}}\Delta\rho\right),\nabla\operatorname{tr}\mathbb{S}\right)}{C_{v}\tilde{\rho}} - \left(\frac{\Delta E - \frac{1}{2\tilde{\rho}}\Delta\boldsymbol{m}\cdot\tilde{\boldsymbol{m}} - \frac{1}{2\tilde{\rho}}\tilde{\boldsymbol{m}}\cdot\Delta\boldsymbol{m} + \frac{1}{2\tilde{\rho}^{2}}\tilde{\boldsymbol{m}}\cdot\tilde{\boldsymbol{m}}\Delta\rho}{C_{v}\tilde{\rho}^{2}} - \frac{\tilde{E} - \frac{1}{2\tilde{\rho}}\tilde{\boldsymbol{m}}\cdot\tilde{\boldsymbol{m}}}{C_{v}\tilde{\rho}^{2}}\Delta\rho,\nabla\cdot\boldsymbol{\tau}\right) - \left(\left(\begin{array}{c} \boldsymbol{F}_{c,U^{c}}^{c}\Delta\boldsymbol{U}^{c} \\ \Delta\rho \end{array}\right),\nabla_{xt}\boldsymbol{v}_{c}\right) - \left(\left(\begin{array}{c} \boldsymbol{F}_{c,U^{c}}^{c}\Delta\boldsymbol{U}^{c} - \Delta\mathbb{D} \\ \Delta\boldsymbol{m} \end{array}\right),\nabla_{xt}\boldsymbol{v}_{m}\right) - \left(\left(\begin{array}{c} \boldsymbol{F}_{e,U^{c}}^{c}\Delta\boldsymbol{U}^{c} - \Delta\mathbb{D} \\ \Delta\boldsymbol{m} \end{array}\right),\nabla_{xt}\boldsymbol{v}_{e}\right) - \left(\left(\begin{array}{c} \boldsymbol{F}_{e,U^{c}}^{c}\Delta\boldsymbol{U}^{c} - \frac{\Delta\boldsymbol{m}}{\tilde{\rho}}\cdot\tilde{\boldsymbol{p}} + \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}^{2}}\Delta\rho\cdot\tilde{\mathbb{D}} - \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}}\cdot\Delta\mathbb{D} \\ \Delta E \end{array}\right),\nabla_{xt}\boldsymbol{v}_{e}\right)$$

where

$$\begin{split} \boldsymbol{F}^{c}_{c,U^{c}} \Delta U^{c} &= \Delta \boldsymbol{m} \\ \mathbb{E}^{c}_{m,U^{c}} \Delta U^{c} &= \frac{\Delta \boldsymbol{m} \otimes \tilde{\boldsymbol{m}}}{\tilde{\rho}} + \frac{\tilde{\boldsymbol{m}} \otimes \Delta \boldsymbol{m}}{\tilde{\rho}} - \frac{\tilde{\boldsymbol{m}} \otimes \tilde{\boldsymbol{m}}}{\tilde{\rho}^{2}} \Delta \rho \\ &+ (\gamma - 1) \left(\Delta E - \frac{\Delta \boldsymbol{m} \cdot \tilde{\boldsymbol{m}}}{2\tilde{\rho}} - \frac{\tilde{\boldsymbol{m}} \cdot \Delta \boldsymbol{m}}{2\tilde{\rho}} + \frac{\tilde{\boldsymbol{m}} \cdot \tilde{\boldsymbol{m}}}{2\tilde{\rho}^{2}} \Delta \rho \right) \boldsymbol{I} \\ \boldsymbol{F}^{c}_{e,U^{c}} \Delta U^{c} &= \frac{\Delta \boldsymbol{m}}{\tilde{\rho}} \tilde{E} + \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}} \Delta E - \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}^{2}} \tilde{E} \Delta \rho \\ &+ (\gamma - 1) \left(\Delta E \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}} + \tilde{E} \frac{\Delta \boldsymbol{m}}{\tilde{\rho}} - \tilde{E} \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}^{2}} \Delta \rho \right) \\ &+ (\gamma - 1) \left(-\frac{\Delta \boldsymbol{m} \tilde{\boldsymbol{m}} \cdot \tilde{\boldsymbol{m}}}{2\tilde{\rho}^{2}} - \frac{\tilde{\boldsymbol{m}} \Delta \boldsymbol{m} \cdot \tilde{\boldsymbol{m}}}{2\tilde{\rho}^{2}} - \frac{\tilde{\boldsymbol{m}} \tilde{\boldsymbol{m}} \cdot \Delta \boldsymbol{m}}{2\tilde{\rho}^{2}} + \frac{\tilde{\boldsymbol{m}} \tilde{\boldsymbol{m}} \cdot \tilde{\boldsymbol{m}}}{\tilde{\rho}^{3}} \Delta \rho \right) \end{split}$$

and $R(\tilde{U}^p)$ is

$$\begin{split} \left(\frac{1}{\mu}\tilde{\mathbb{D}}, \mathbb{S}\right) + \left(2\frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}}, \nabla \cdot \mathbb{S}\right) - \left(\frac{2}{3}\frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}}, \nabla \operatorname{tr} \mathbb{S}\right) \\ - \left(\frac{\tilde{E} - \frac{1}{2\tilde{\rho}}\tilde{\boldsymbol{m}} \cdot \tilde{\boldsymbol{m}}}{C_v \tilde{\rho}}, \nabla \cdot \boldsymbol{\tau}\right) \\ - \left(\begin{pmatrix} \boldsymbol{F}_c^c \\ \tilde{\rho} \end{pmatrix}, \nabla_{xt} v_c\right) \\ - \left(\begin{pmatrix} \boldsymbol{F}_m^c - \tilde{\mathbb{D}} \\ \tilde{\boldsymbol{m}} \end{pmatrix}, \nabla_{xt} \boldsymbol{v}_m\right) \\ - \left(\begin{pmatrix} \boldsymbol{F}_e^c - \frac{\tilde{\boldsymbol{m}}}{\tilde{\rho}} \cdot \tilde{\mathbb{D}} \\ \tilde{E} \end{pmatrix}, \nabla_{xt} v_e\right) \end{split}$$

Entropy Variables

The set of nonlinear variables is $U^e := \{V_c, \mathbf{V}_m, V_e, \mathbb{D}\}$. Then $R_{U^e}(\tilde{U}^e)\Delta U^e$ is

$$\left(\frac{1}{\mu}\Delta\mathbb{D},\mathbb{S}\right) - \left(2\left(\frac{\Delta\boldsymbol{V}_{m}}{\tilde{V}_{e}} - \frac{\tilde{\boldsymbol{V}}_{m}}{\tilde{V}_{e}^{2}}\Delta V_{e}\right),\nabla\cdot\mathbb{S}\right) + \left(\frac{2}{3}\left(\frac{\Delta\boldsymbol{V}_{m}}{\tilde{V}_{e}} - \frac{\tilde{\boldsymbol{V}}_{m}}{\tilde{V}_{e}^{2}}\Delta V_{e}\right),\nabla\operatorname{tr}\mathbb{S}\right)$$

$$+ \left(\frac{1}{C_{v}V_{e}},\nabla\cdot\boldsymbol{\tau}\right)$$

$$- \left(\left(\begin{array}{c} \boldsymbol{F}_{c,U^{e}}^{e}\Delta U^{e} \\ -\alpha_{,U^{e}}\Delta U^{e}\tilde{\boldsymbol{V}}_{e} - \alpha\Delta V_{e} \end{array}\right),\nabla_{xt}v_{c}\right)$$

$$- \left(\left(\begin{array}{c} \mathbb{F}_{m,U^{e}}^{e}\Delta U^{e} - \Delta\mathbb{D} \\ \alpha_{,U^{e}}\Delta U^{e}\tilde{\boldsymbol{V}}_{m} + \alpha\Delta \boldsymbol{V}_{m} \end{array}\right),\nabla_{xt}\boldsymbol{v}_{m}\right)$$

$$- \left(\left(\begin{array}{c} \boldsymbol{F}_{m,U^{e}}^{e}\Delta U^{e} - \Delta\mathbb{D} \\ \alpha_{,U^{e}}\Delta U^{e}\tilde{\boldsymbol{V}}_{m} + \alpha\Delta \boldsymbol{V}_{m} \end{array}\right),\nabla_{xt}\boldsymbol{v}_{m}\right)$$

$$- \left(\left(\begin{array}{c} \boldsymbol{F}_{e,U^{e}}^{e}\Delta U^{e} + \frac{\Delta\boldsymbol{V}_{m}}{\tilde{\boldsymbol{V}}_{e}} \cdot \tilde{\mathbb{D}} + \frac{\tilde{\boldsymbol{V}}_{m}}{\tilde{\boldsymbol{V}}_{e}} \cdot \Delta\mathbb{D} - \frac{\tilde{\boldsymbol{V}}_{m}}{\tilde{\boldsymbol{V}}_{e}^{2}} \cdot \tilde{\mathbb{D}}\Delta V_{e} \\ \alpha_{,U^{e}}\Delta U^{e}\left(1 - \frac{1}{2\tilde{\boldsymbol{V}}_{e}}\tilde{\boldsymbol{V}}_{m} \cdot \tilde{\boldsymbol{V}}_{m}\right) - \alpha\frac{1}{2\tilde{\boldsymbol{V}}_{e}}\Delta \boldsymbol{V}_{m} \cdot \tilde{\boldsymbol{V}}_{m} - \alpha\frac{1}{2\tilde{\boldsymbol{V}}_{e}}\tilde{\boldsymbol{V}}_{m} \cdot \Delta\boldsymbol{V}_{m} + \alpha\frac{1}{2\tilde{\boldsymbol{V}}_{e}^{2}}\tilde{\boldsymbol{V}}_{m} \cdot \tilde{\boldsymbol{V}}_{m}\Delta V_{e} \end{array}\right), \nabla_{xt}v_{e}$$

where

$$\begin{split} \boldsymbol{F}^{e}_{c,U^{e}} \Delta U^{e} &= \alpha_{,U^{e}} \Delta U^{e} \tilde{\boldsymbol{V}}_{m} + \alpha \Delta \boldsymbol{V}_{m} \\ \mathbb{F}^{e}_{m,U^{e}} \Delta U^{e} &= \alpha_{,U^{e}} \Delta U^{e} \left(-\frac{\tilde{\boldsymbol{V}}_{m} \otimes \tilde{\boldsymbol{V}}_{m}}{\tilde{V}_{e}} + (\gamma - 1) \boldsymbol{I} \right) \\ &+ \alpha \left(-\frac{\Delta \boldsymbol{V}_{m} \otimes \tilde{\boldsymbol{V}}_{m}}{\tilde{V}_{e}} - \frac{\tilde{\boldsymbol{V}}_{m} \otimes \Delta \boldsymbol{V}_{m}}{\tilde{V}_{e}} + \frac{\tilde{\boldsymbol{V}}_{m} \otimes \tilde{\boldsymbol{V}}_{m}}{\tilde{V}_{e}^{2}} \Delta V_{e} \right) \\ \boldsymbol{F}^{e}_{e,U^{e}} \Delta U^{e} &= \alpha_{,U^{e}} \Delta U^{e} \frac{\tilde{\boldsymbol{V}}_{m}}{\tilde{V}_{e}} \left(\frac{1}{2\tilde{V}_{e}} \tilde{\boldsymbol{V}}_{m} \cdot \tilde{\boldsymbol{V}}_{m} - \gamma \right) \\ &+ \alpha \left(\frac{\Delta \boldsymbol{V}_{m}}{\tilde{V}_{e}} \left(\frac{1}{2\tilde{V}_{e}} \tilde{\boldsymbol{V}}_{m} \cdot \tilde{\boldsymbol{V}}_{m} - \gamma \right) - \frac{\tilde{\boldsymbol{V}}_{m}}{V_{e}^{2}} \left(\frac{1}{2\tilde{V}_{e}} \tilde{\boldsymbol{V}}_{m} \cdot \tilde{\boldsymbol{V}}_{m} - \gamma \right) \Delta V_{e} \\ &+ \frac{\tilde{\boldsymbol{V}}_{m}}{\tilde{V}_{e}} \left(\frac{1}{2\tilde{V}_{e}} \Delta \boldsymbol{V}_{m} \cdot \tilde{\boldsymbol{V}}_{m} + \frac{1}{2\tilde{V}_{e}} \tilde{\boldsymbol{V}}_{m} \cdot \Delta \boldsymbol{V}_{m} - \frac{1}{2\tilde{V}_{e}^{2}} \tilde{\boldsymbol{V}}_{m} \cdot \tilde{\boldsymbol{V}}_{m} \Delta V_{e} \right) \right) \end{split}$$

$$\alpha_{,U^{e}} \Delta U^{e} = \frac{1}{\gamma - 1} \left[\frac{\gamma - 1}{-(\tilde{V}_{e})^{\gamma}} \right]^{\frac{2 - \gamma}{\gamma - 1}} (\gamma - 1) \gamma (-\tilde{V}_{e})^{-(\gamma + 1)} \exp \left[\frac{-\gamma + \tilde{V}_{c} - \frac{1}{2\tilde{V}_{e}} \tilde{V}_{m} \cdot \tilde{V}_{m}}{\gamma - 1} \right] \Delta V_{e}$$

$$+ \left[\frac{\gamma - 1}{-(\tilde{V}_{e})^{\gamma}} \right]^{\frac{1}{\gamma - 1}} \exp \left[\frac{-\gamma + \tilde{V}_{c} - \frac{1}{2\tilde{V}_{e}} \tilde{V}_{m} \cdot \tilde{V}_{m}}{\gamma - 1} \right] \frac{1}{\gamma - 1}$$

$$\left(\Delta V_{c} - \frac{1}{2\tilde{V}_{e}} \Delta V_{m} \cdot \tilde{V}_{m} - \frac{1}{2\tilde{V}_{e}} \tilde{V}_{m} \cdot \Delta V_{m} + \frac{1}{2\tilde{V}_{e}^{2}} \tilde{V}_{m} \cdot \tilde{V}_{m} \Delta V_{e} \right)$$

and $R(\tilde{U}^p)$ is

$$\left(\frac{1}{\mu}\tilde{\mathbb{D}}, \mathbb{S}\right) - \left(2\frac{\tilde{\boldsymbol{V}}_{m}}{\tilde{V}_{e}}, \nabla \cdot \mathbb{S}\right) + \left(\frac{2}{3}\frac{\tilde{\boldsymbol{V}}_{m}}{V_{e}}, \nabla \operatorname{tr} \mathbb{S}\right) \\
+ \left(\frac{1}{C_{v}\tilde{V}_{e}}, \nabla \cdot \boldsymbol{\tau}\right) \\
- \left(\left(\begin{array}{c} \boldsymbol{F}_{c}^{e} \\ -\alpha\tilde{V}_{e} \end{array}\right), \nabla_{xt}v_{c}\right) \\
- \left(\left(\begin{array}{c} \mathbb{F}_{m}^{e} - \tilde{\mathbb{D}} \\ \alpha\tilde{\boldsymbol{V}}_{m} \end{array}\right), \nabla_{xt}\boldsymbol{v}_{m}\right) \\
- \left(\left(\begin{array}{c} \boldsymbol{F}_{e}^{e} + \frac{\tilde{\boldsymbol{V}}_{m}}{V_{e}} \cdot \tilde{\mathbb{D}} \\ \alpha\left(1 - \frac{1}{2\tilde{V}_{e}}\tilde{\boldsymbol{V}}_{m} \cdot \tilde{\boldsymbol{V}}_{m}\right) \end{array}\right), \nabla_{xt}v_{e}\right)$$