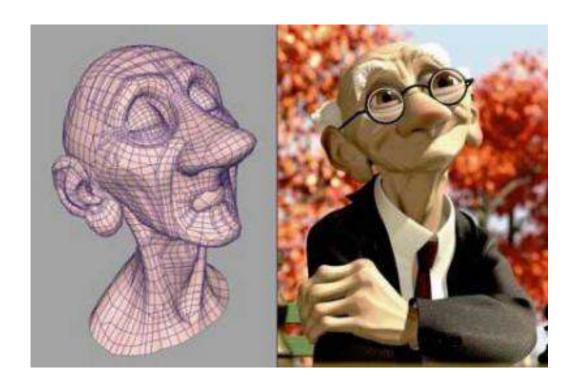
# Computer Graphics - Scene Graphs

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http://jjcao.github.io/ComputerGraphics/

#### The representations of Mesh && Scene

- Mesh: {triangles}, an object in a scene
- Scene: {objects} in desired positions => a great many transformations
- What => easier scene manipulation?
- Most scenes admit to a hierarchical organization =>
- Scene graph

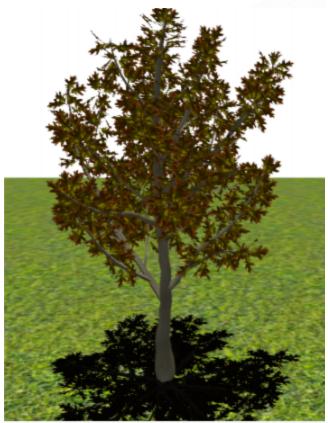




#### Hierarchical Models

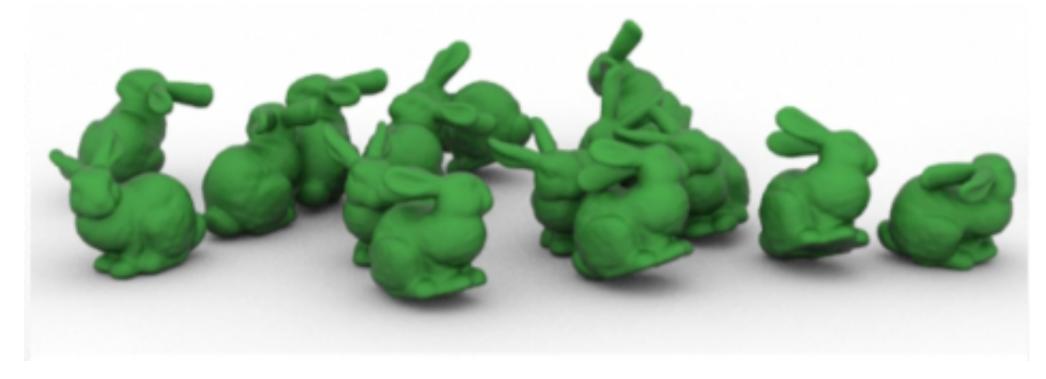
- Many graphical objects are structured
- Structure often naturally hierarchical
  - Wheels of a car
  - Arms or legs of a figure
  - Chess pieces
- Exploit structure for
  - Efficient rendering
    - Example: tree leaves
  - Concise specification of model parameters
    - Example: joint angles



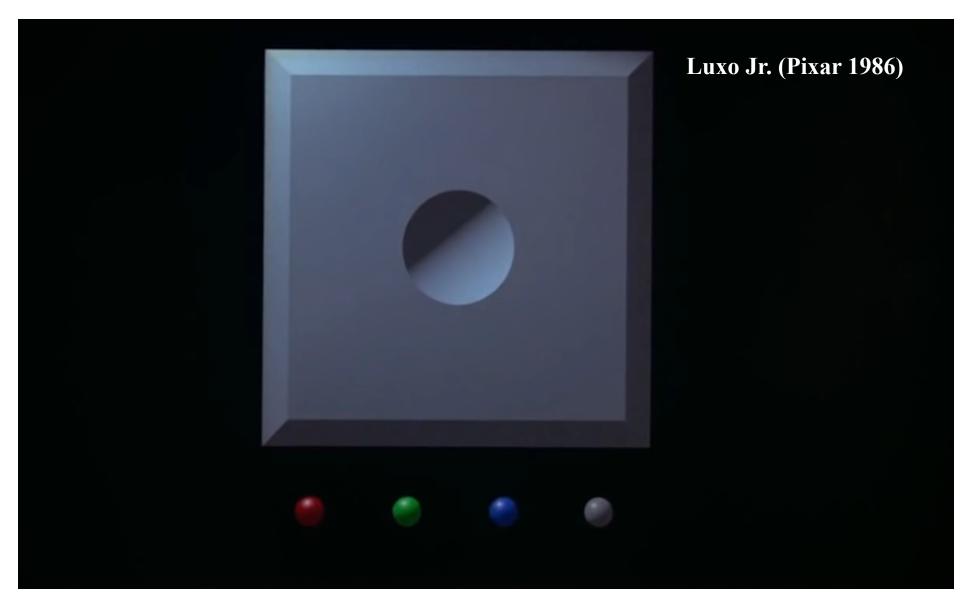


#### **Instance Transformation**

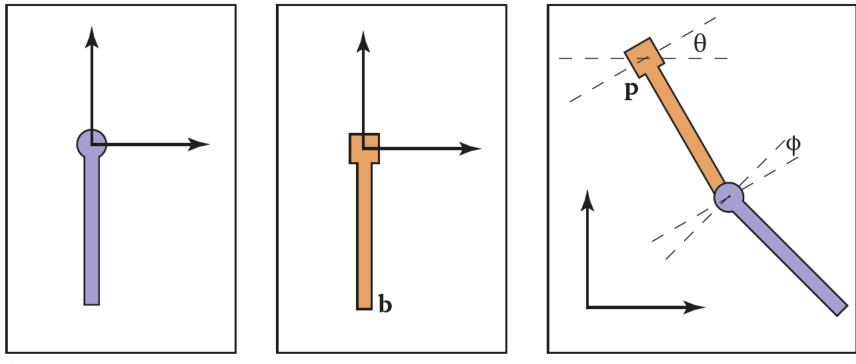
- Instances can be shared across space or time
- Write a function that renders the object in "standard" configuration
- Apply transformations to different instances
- Typical order: scaling, rotation, translation



## **Animation: modeling motion**



## 1<sup>st</sup> example



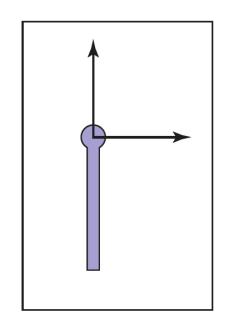
 $\mathbf{M}_1 = \mathrm{rotate}(\theta)$ 

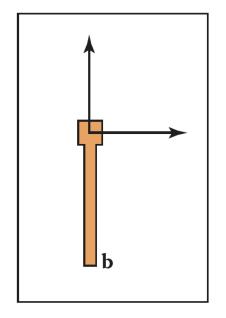
 $\mathbf{M}_2 = \operatorname{translate}(\mathbf{p})$ 

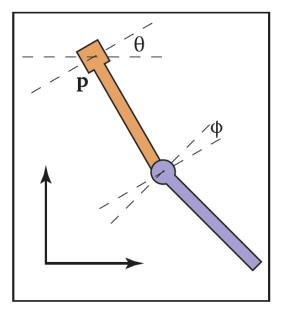
 $\mathbf{M}_3 = \mathbf{M}_2 \mathbf{M}_1$ 

Apply  $M_3$  to all points in upper pendulum

#### 1<sup>st</sup> example







$$\mathbf{M}_a = \mathrm{rotate}(\phi)$$

$$\mathbf{M}_b = \operatorname{translate}(\mathbf{b})$$

$$\mathbf{M}_c = \mathbf{M}_b \mathbf{M}_a$$

$$\mathbf{M}_1 = \mathrm{rotate}(\theta)$$

$$\mathbf{M}_2 = \text{translate}(\mathbf{p})$$

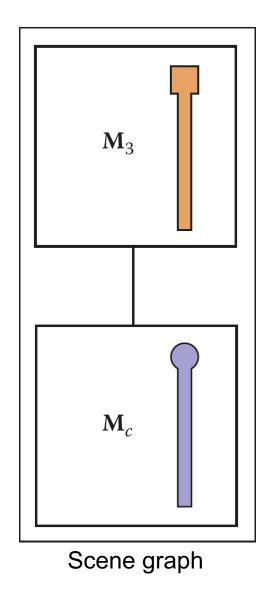
$$\mathbf{M}_d = \mathbf{M}_3 \mathbf{M}_c$$

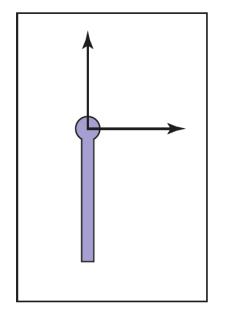
Apply  $M_d$  to all points in lower pendulum

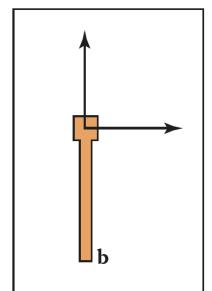
$$\mathbf{M}_3 = \mathbf{M}_2 \mathbf{M}_1$$

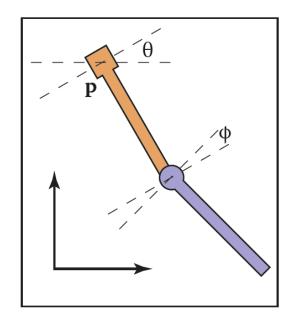
Apply  $M_3$  to all points in upper pendulum

## 1<sup>st</sup> example









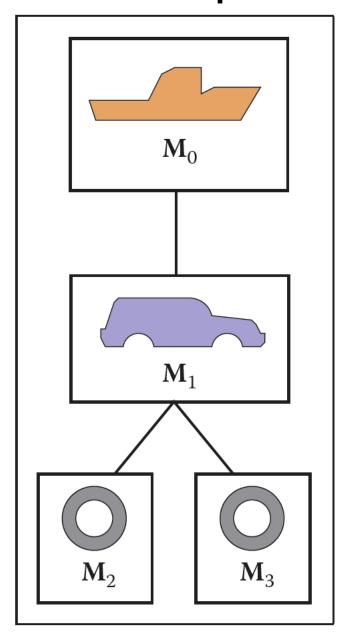
 $\mathbf{M}_3 = \mathbf{M}_2 \mathbf{M}_1$ 

Apply  $M_3$  to all points in upper pendulum

 $\mathbf{M}_d = \mathbf{M}_3 \mathbf{M}_c$ 

Apply  $M_d$  to all points in lower pendulum

#### 2<sup>nd</sup> example – How to draw a scene?

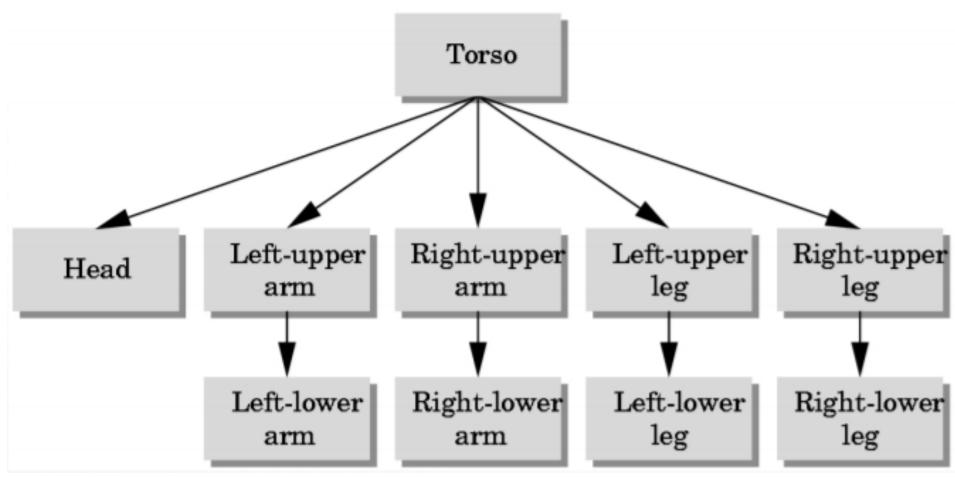


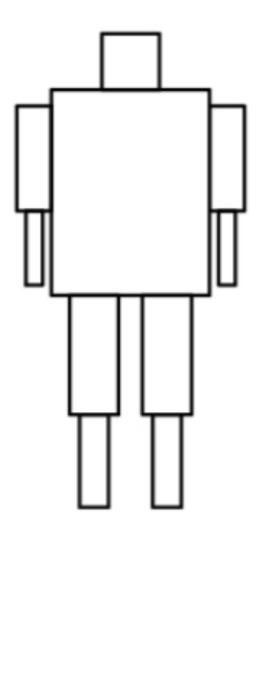
#### **Interleave Drawing**

- ferry transform using  $M_0$ ;
- car body transform using  $M_0M_1$ ;
- left wheel transform using  $M_0M_1M_2$ ;
- left wheel transform using  $M_0M_1M_3$ .

## More Complex Objects

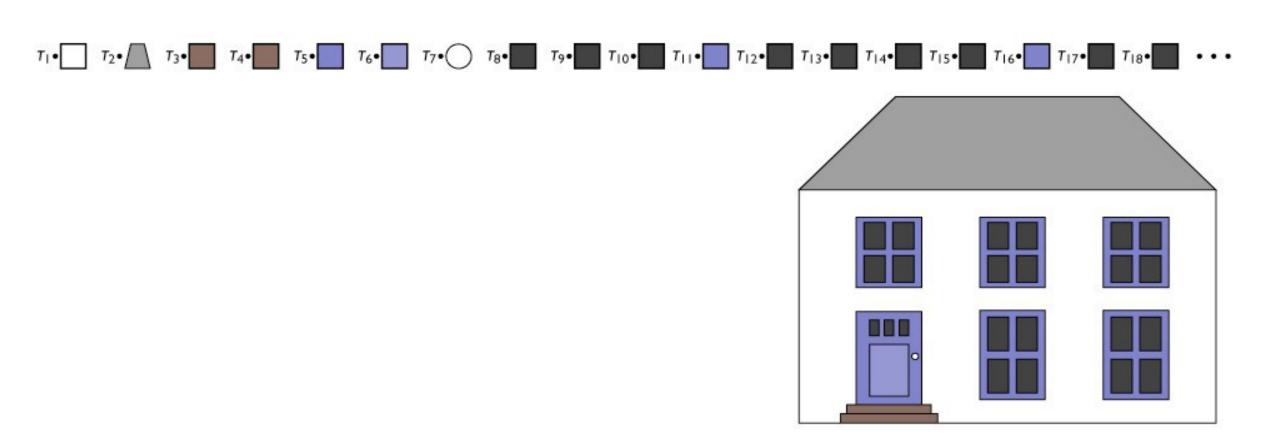
- Tree rather than linear structure
- Interleave along each branch
- Use push and pop to save state





## 3<sup>rd</sup> example

- Can represent drawing with flat list
  - but editing operations require updating many transforms



#### Groups of objects



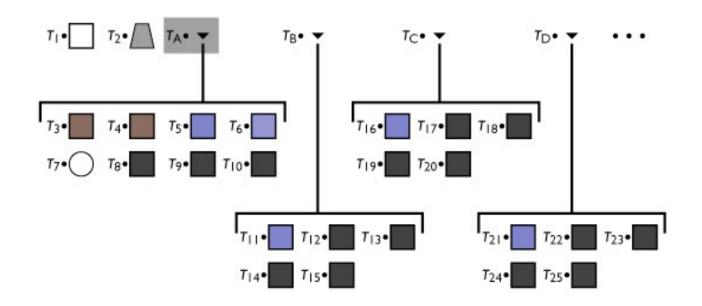
- Treat a set of objects as one
- Introduce new object type: group
  - contains list of references to member objects
- This makes the model into a tree
  - interior nodes = groups
  - leaf nodes = objects
  - edges = membership of object in group

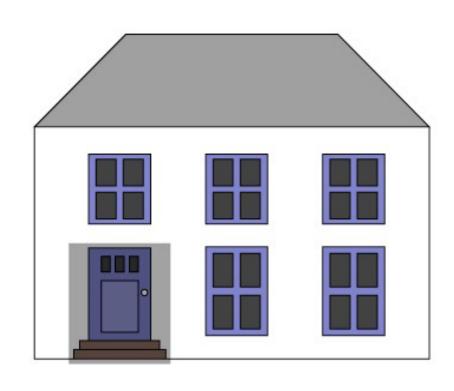


## 3<sup>rd</sup> example

#### Add group as a new object type

- lets the data structure reflect the drawing structure
- enables high-level editing by changing just one node





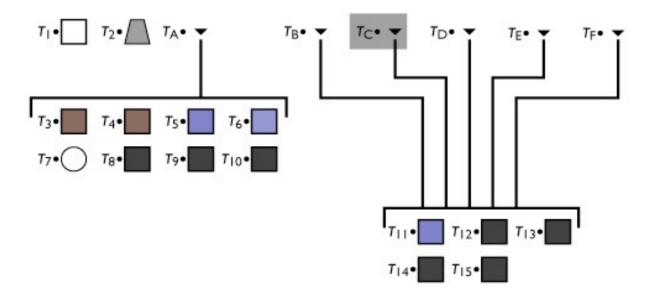
## Variants of the Scene Graph - Instancing

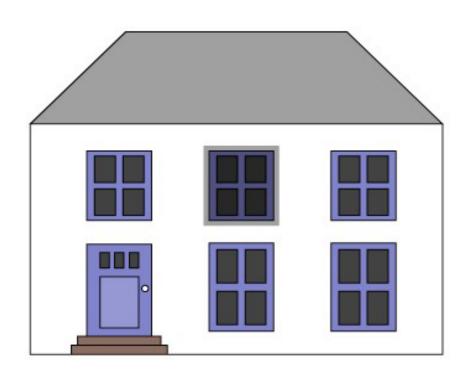
- Simple idea: allow an object to be a member of more than one group at once
  - transform different in each case
  - leads to linked copies
  - single editing operation changes all instances

## 3<sup>rd</sup> example

#### Allow multiple references to nodes

- reflects more of drawing structure
- allows editing of repeated parts in one operation

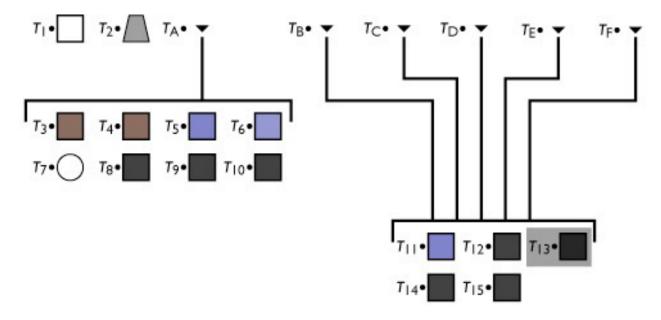




## 3<sup>rd</sup> example

#### Allow multiple references to nodes

- reflects more of drawing structure
- allows editing of repeated parts in one operation







Jan-Walter Schliep, Burak Kahraman, Timm Dapper | Laubwerk via PBRT gallery

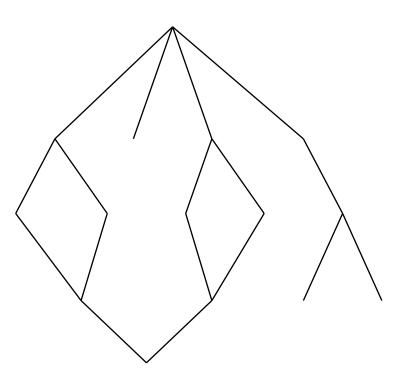
## The Scene Graph (with instances)

#### With instances, there is no more tree

 an object that is instanced multiple times has more than one parent

#### Transform tree becomes DAG

- directed acyclic graph
- group is not allowed to contain itself, even indirectly
- Transforms still accumulate along path from root
  - now paths from root to leaves are identified with scene objects



## Scene Graph & matrix stack

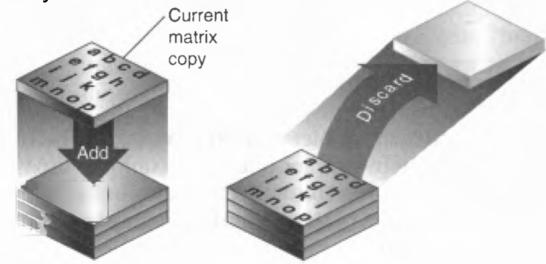
Active matrix M = I

 $egin{aligned} & \operatorname{push}(\mathbf{M}_0) \ & \operatorname{push}(\mathbf{M}_1) \ & \operatorname{push}(\mathbf{M}_2) \end{aligned}$  Active matrix  $\mathbf{M} = \mathbf{M}_0 \mathbf{M}_1 \mathbf{M}_2$ 

pop()  $\begin{aligned} &\text{Active matrix} \\ &\mathbf{M} = \mathbf{M}_0 \mathbf{M}_1 \end{aligned}$ 

 $\mathbf{M}_{0}$  $\mathbf{M}_1$ 

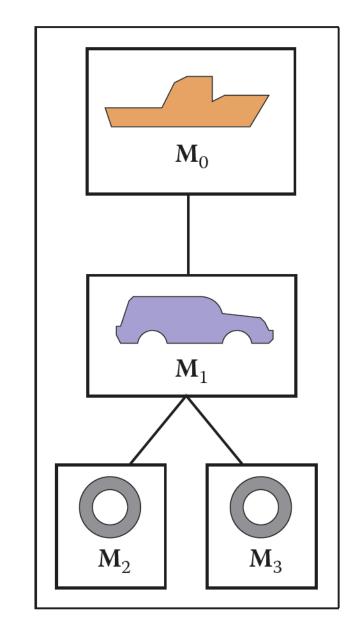
The current matrix is postmultiplied by the matrix



#### A recursive traversal of a scene graph

```
\begin{aligned} & \textbf{function} \text{ traverse}(node) \\ & push(\mathbf{M}_{local}) \\ & draw \text{ object using composite matrix from stack} \\ & traverse(left child) \\ & traverse(right child) \\ & pop() \end{aligned}
```

- ferry transform using  $M_0$ ;
- car body transform using  $M_0M_1$ ;
- left wheel transform using  $M_0M_1M_2$ ;
- left wheel transform using  $M_0M_1M_3$ .



#### Hierarchical Tree Traversal

- Order not necessarily fixed
- Example:

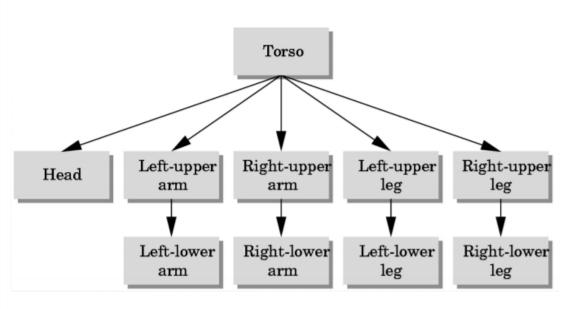
```
Torso
            Left-upper
                                        Left-upper
                         Right-upper
                                                      Right-upper
Head
                                           leg
                                                         leg
               arm
                             arm
            Left-lower
                          Right-lower
                                        Left-lower
                                                      Right-lower
                                           leg
                                                         leg
               arm
                             arm
```

```
void drawFigure()
                                          glPushMatrix();
                                          glTranslatef(...);
 glPushMatrix(); /* save */
                                          glRotatef(...);
 drawTorso();
                                          drawLeftUpperArm();
 glTranslatef(...); /* move head */
                                          glTranslatef(...)
 glRotatef(...); /* rotate head */
                                          glRotatef(...)
 drawHead();
                                          drawLeftLowerArm();
 glPopMatrix(); /* restore */
                                          glPopMatrix();
                                                                  34
```

## Using Tree Data Structures

Can make tree form explicit in data structure

```
typedef struct treenode
 GLfloat m[16];
 void (*f) ();
 struct treenode *sibling;
 struct treenode *child;
} treenode;
```



## Initializing Tree Data Structure

 Initializing transformation matrix for node treenode torso, head, ...;
 /\* in init function \*/ glLoadIdentity(); glRotatef(...); glGetFloatv(GL MODELVIEW MATRIX, torso.m);

Initializing pointers
 torso.f = drawTorso;
 torso.sibling = NULL;
 torso.child = &head;

#### **Generic Traversal**

Recursive definition

```
Head
void traverse (treenode *root)
 if (root == NULL) return;
 glPushMatrix();
 glMultMatrixf(root->m);
 root \rightarrow f();
 if (root->child != NULL) traverse(root->child);
 glPopMatrix();
 if (root->sibling != NULL) traverse(root->sibling);
```

```
Torso
                                          Right-upper
             Right-upper
                            Left-upper
Left-upper
                                             leg
                               leg
  arm
                 arm
Left-lower
             Right-lower
                            Left-lower
                                          Right-lower
                               leg
                                             leg
  arm
                 arm
```

## Implementing a hierarchy

- Object-oriented language is convenient
  - define shapes and groups as derived from single class

```
abstract class Shape { void draw();}
class Square extends Shape {
 void draw() {
// draw unit square
class Circle extends Shape {
 void draw() {
  , // draw unit circle
```

#### Implementing traversal

Pass a transform down the hierarchy

```
    before drawing, concatenate

abstract class Shape { void draw(Transform t_c);}
                                          class Group extends Shape {
class Square extends Shape {
void draw(Transform t_c) {
    // draw t_c * unit square
                                          Transform t;
                                           ShapeList members;
                                           void draw(Transform t c) {
class Circle extends Shape {
                                            for (m in members) {
void draw(Transform t_c) {
   // draw t_c * unit circle
                                              m.draw(t_c * t);
```

#### Basic Scene Graph operations

#### Editing a transformation

- good to present usable UI

#### Getting transform of object in canonical (world) frame

- traverse path from root to leaf

#### Grouping and ungrouping

- can do these operations without moving anything
- group: insert identity node
- ungroup: remove node, push transform to children

#### Reparenting

- move node from one parent to another
- can do without altering position

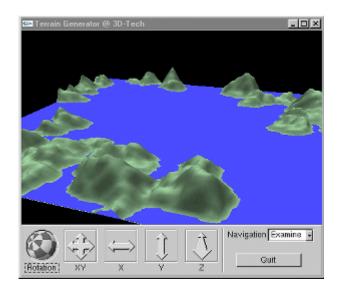
#### Scene Graph variations

- Where transforms go
  - in every node
  - on edges
  - in group nodes only
  - in special Transform nodes
- Tree vs. DAG
- Nodes for cameras and lights
- Nodes that set attributes
  - e.g. "make everything in my subtree green"

#### OpenGL Terrain Generator

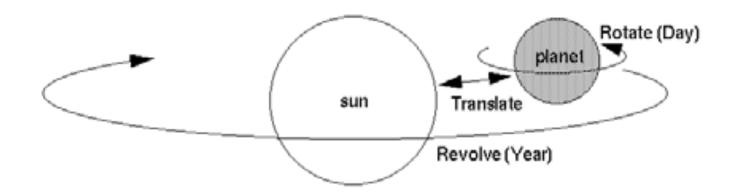
 An example of OpenGL terrain generator developed by António Ramires Fernandes can be found in:

http://www.lighthouse3d.com/opengl/appstools/tg/



 Terrain generation from an image, computing normals and simulating both directional and positional lights

## Assignment 1: Building the solar system



 You will need to write from scratch a complete OpenGL programme that renders a Sun with an orbiting planet and a moon orbiting the planet

#### **Assignment Basic Implementation**

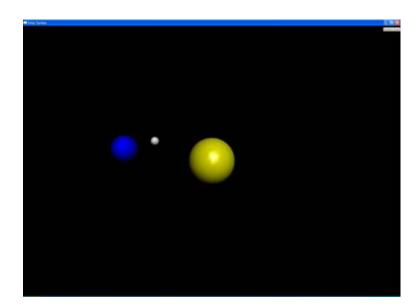
The basic implementation includes the following:

- Add a sphere representing the sun planet
- Make the sun planet to rotate around itself
- Add another sphere representing the earth
- Make the earth planet to rotate around itself
- Make the earth planet to rotate around sun
- Add another sphere representing the moon
- Make the moon planet to rotate around itself
- Make the moon planet to rotate around the earth
- Control the camera position using the keyboard
- Control the camera position using widget menus
- Add a light source
- Add shading to the planets
- Add material properties to the planets (you have to check this out
- yourselves)

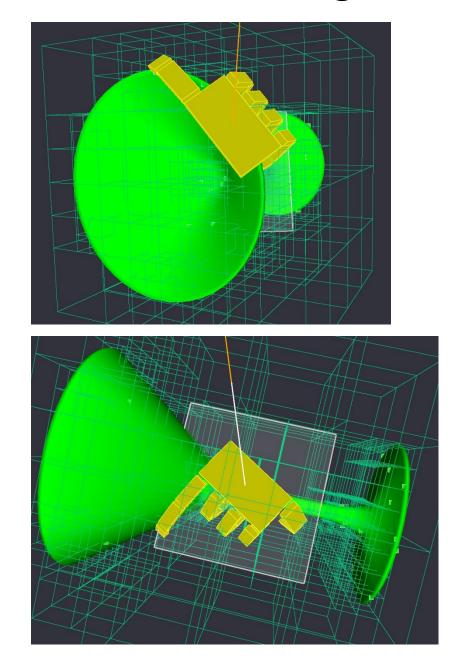
#### Assignment Advanced Implementation

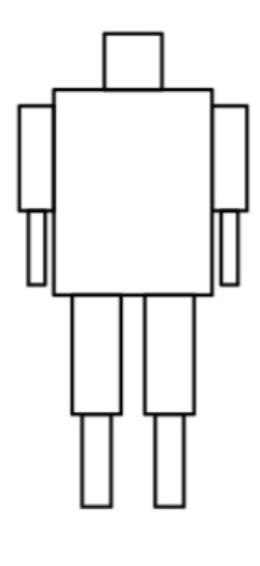
#### Recommended Implementation

- Add more planets, e.g. if you are quick enough you could create the complete solar system
- Add more light sources (OpenGL supports up to 8 lights)
- Have planets counter rotating
- Add more moons to planets
- Add stars to the planetary system
- Add spaceships



## Assignment 2: Building a robot arm or a robot





## Thanks