

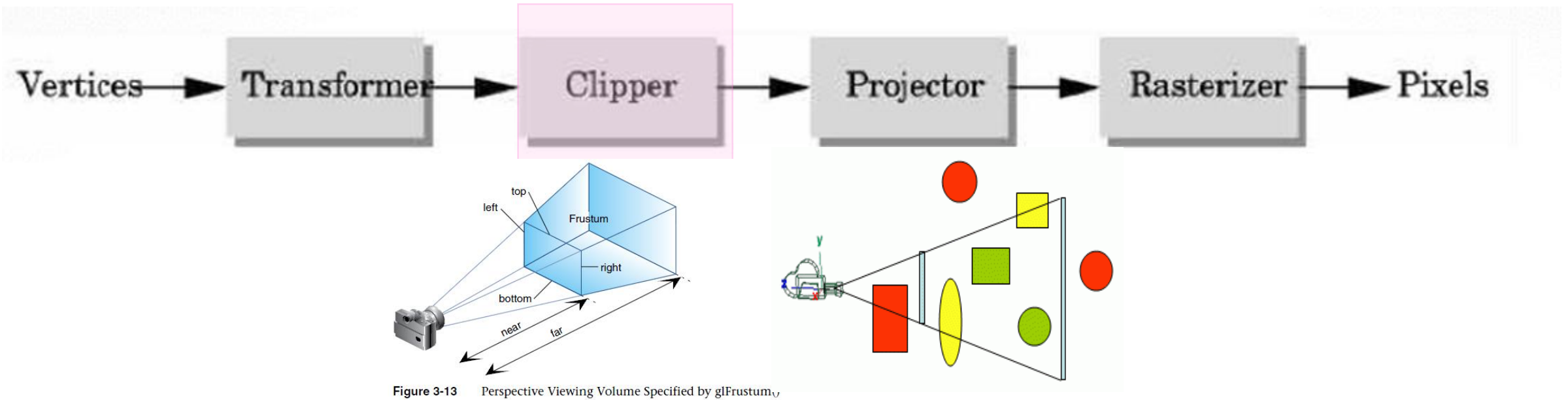
Computer Graphics - Line & Polygon Clipping

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<http://jjcao.github.io/ComputerGraphics/>

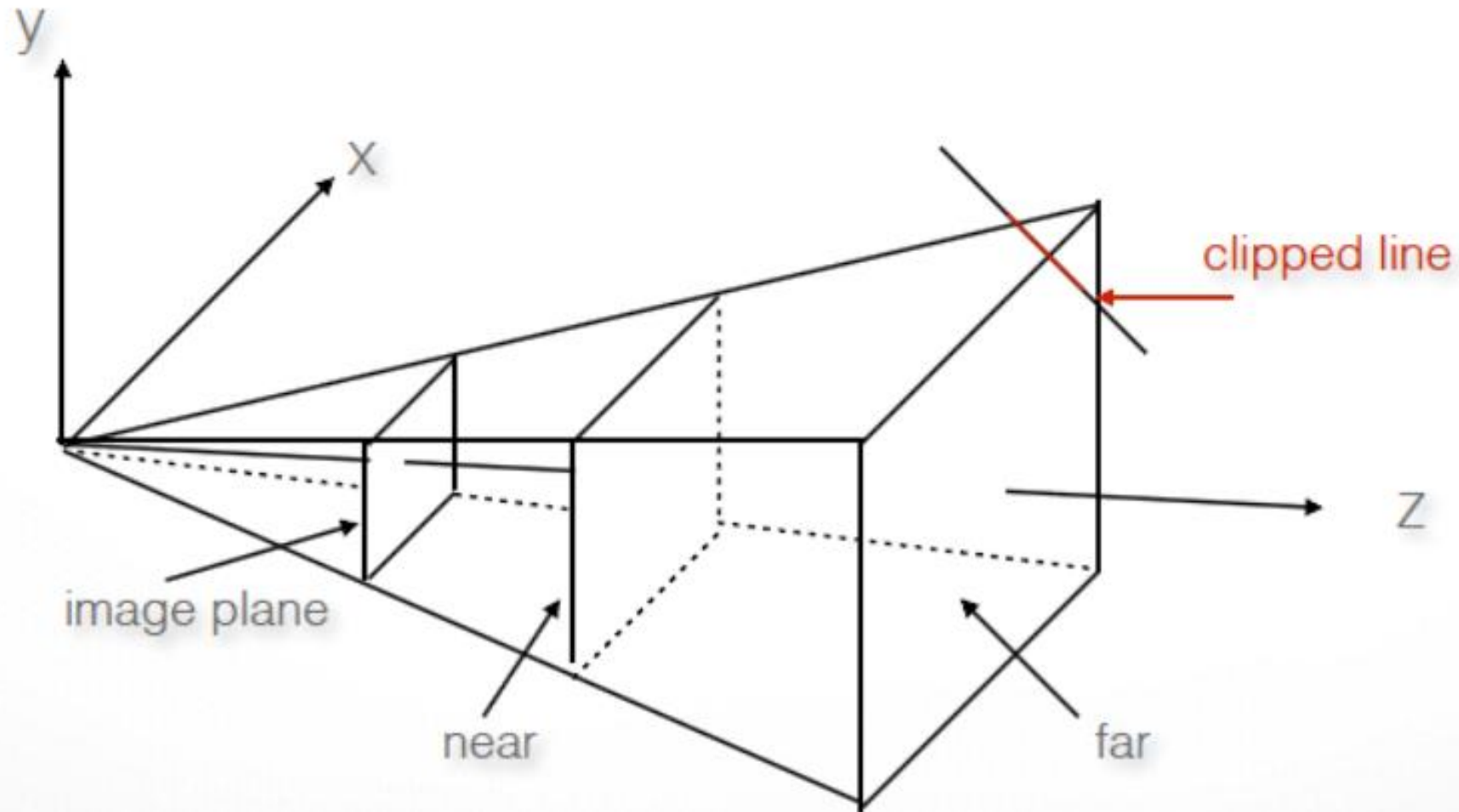
The Graphics Pipeline, Revisited



- Must eliminate objects that are outside of viewing frustum
- **Clipping**: object space (eye coordinates)
- **Scissoring**: image space (pixels in frame buffer)
 - most often less efficient than clipping
- We will first discuss **2D clipping** (for simplicity)
 - OpenGL uses 3D clipping

Clipping Against a Frustum

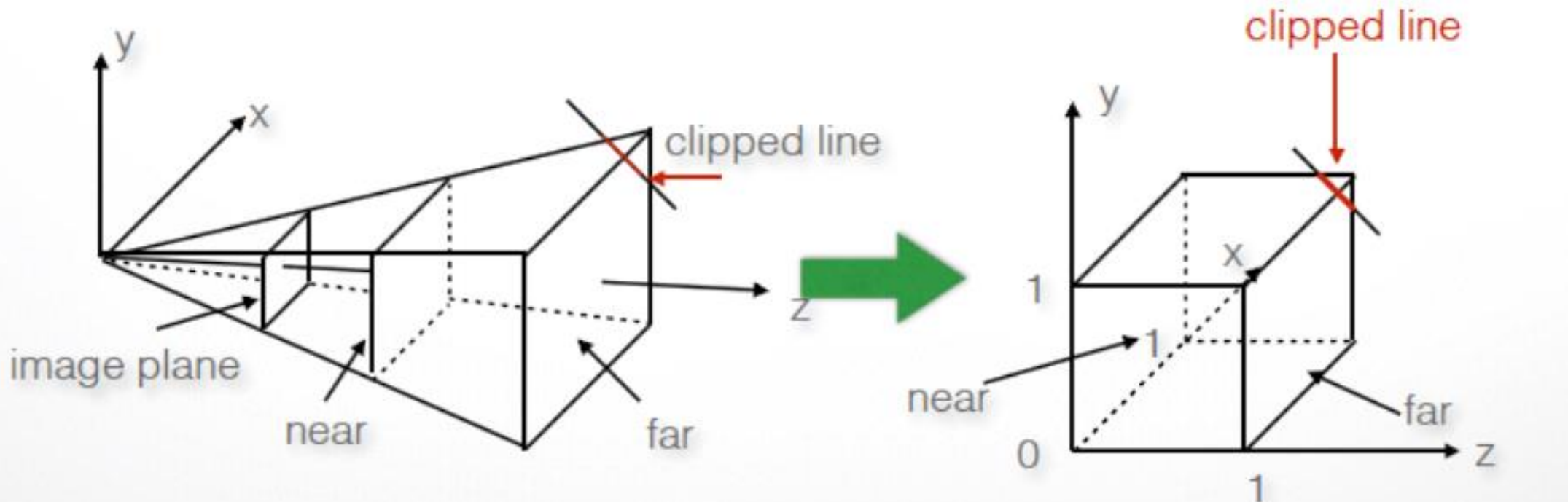
- General case of frustum (truncated pyramid)



- Clipping is tricky because of frustum shape

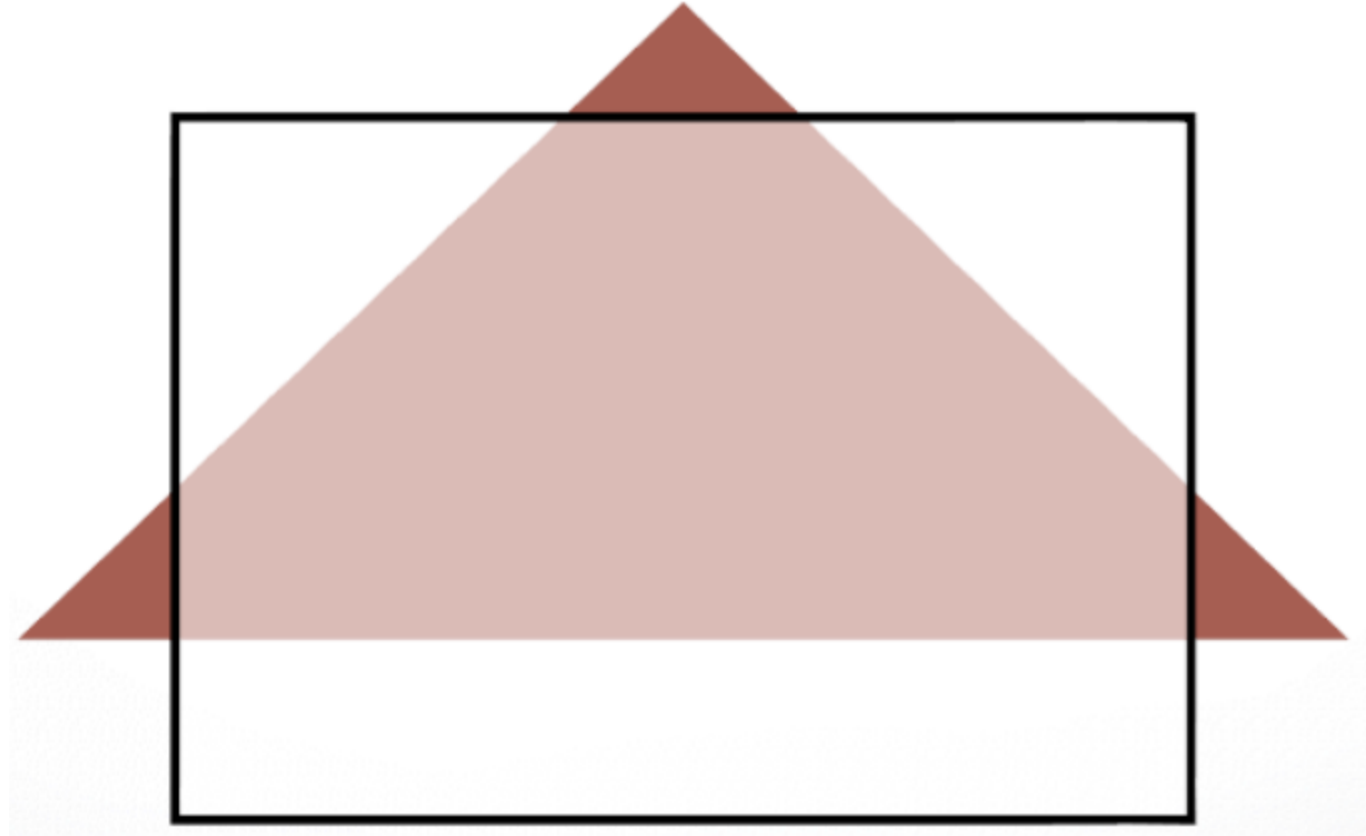
Perspective Normalization

- Solution: **Clip against resulting cube**
 - Implement perspective projection by **perspective normalization** and orthographic projection
 - Perspective normalization is a homogeneous transformation



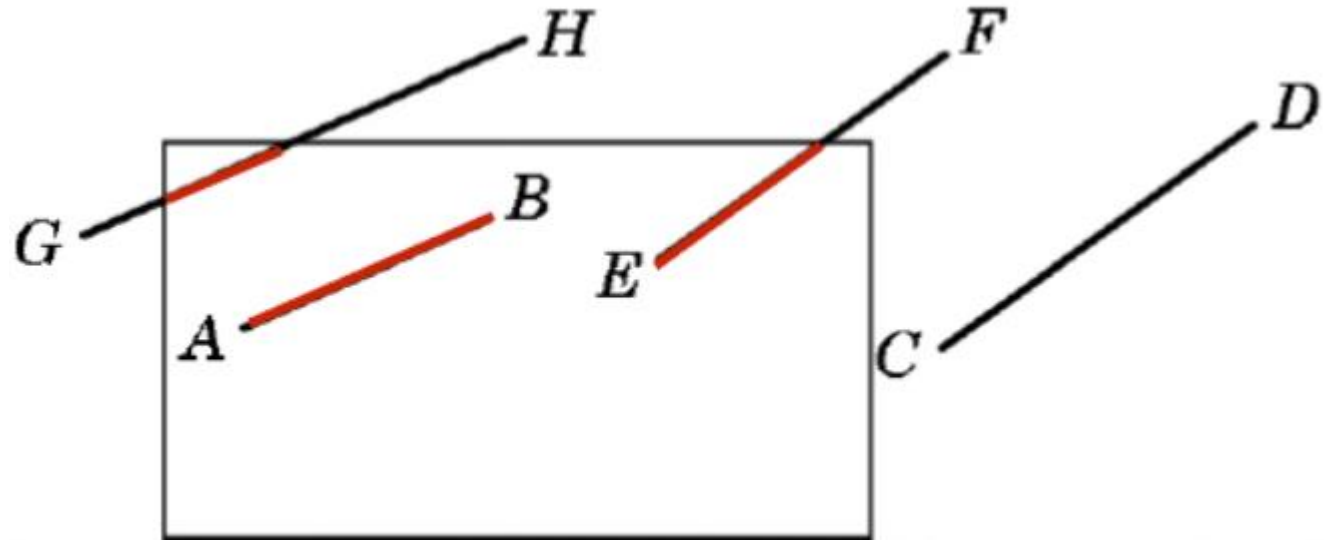
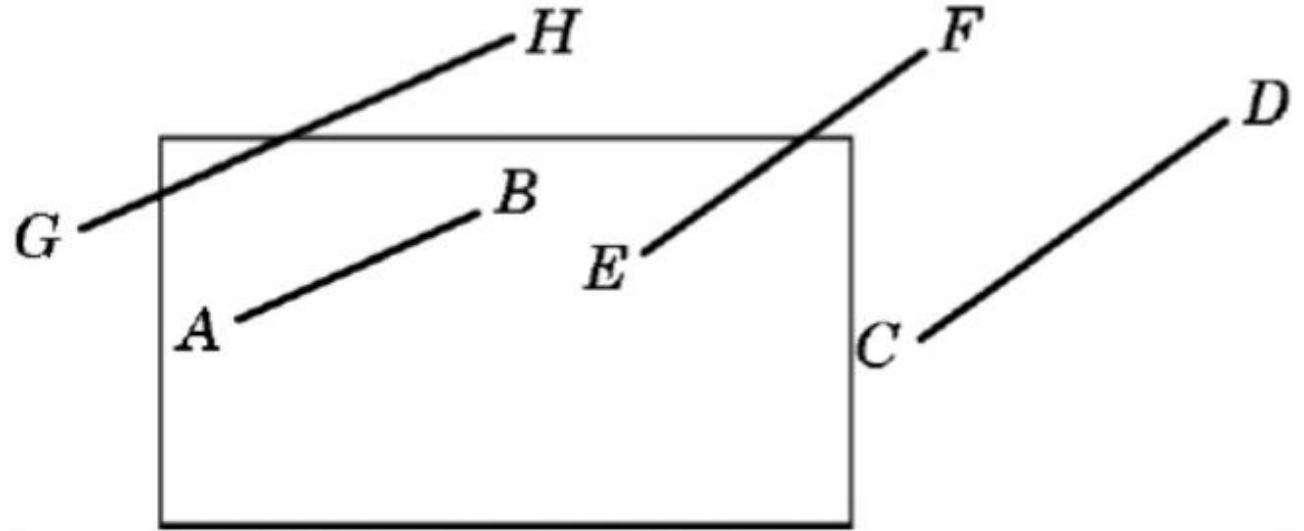
OpenGL uses $-1 \leq x, y, z \leq 1$ (others possible)

2D Clipping Problem



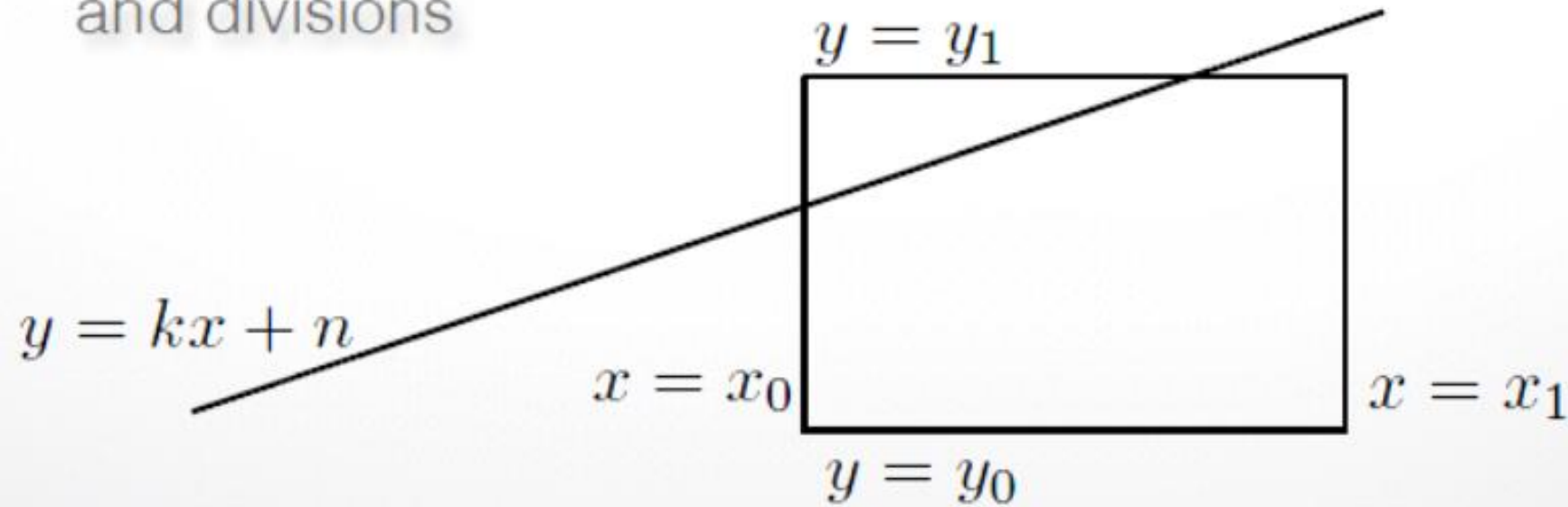
Clipping Against Rectangle in 2D

- Line-segment clipping: modify endpoints of lines to lie within clipping rectangle
- The result (in red)



Clipping Against Rectangle in 2D

- Could calculate intersections of line segments with clipping rectangle
 - expensive, due to floating point multiplications and divisions
- Want to minimize the number of multiplications and divisions

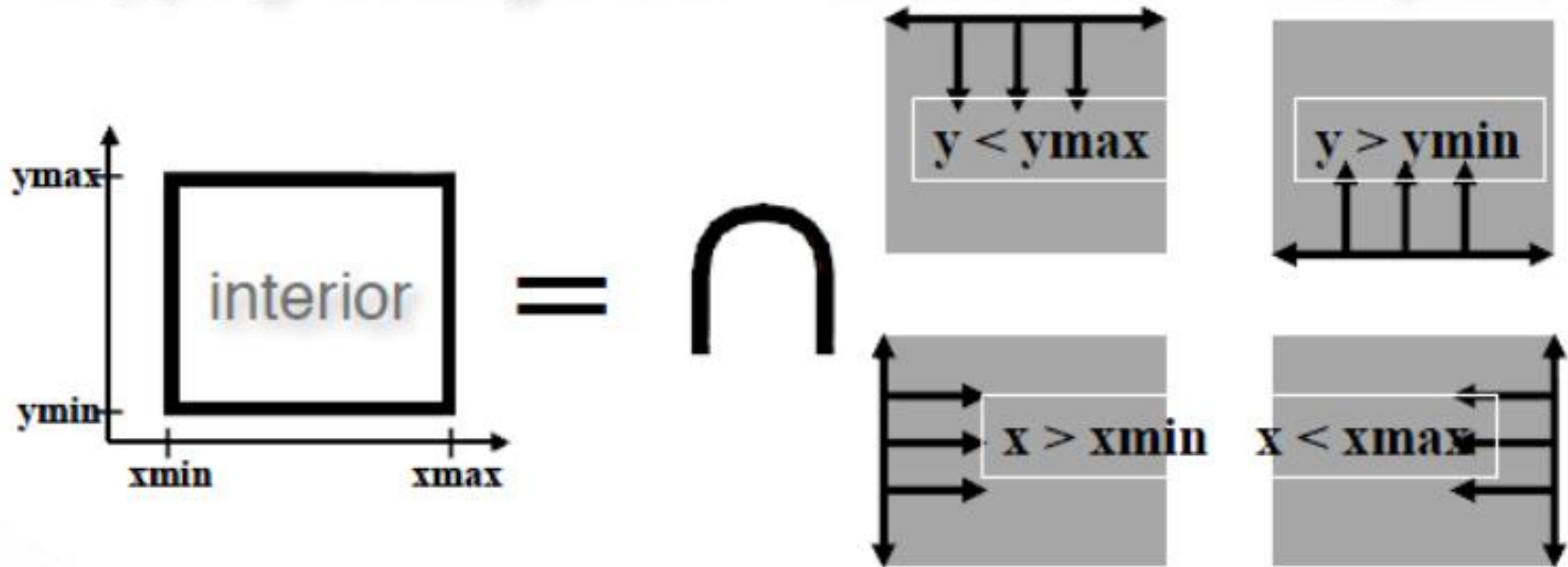


Several practical algorithms for clipping

- Main motivation:
 - **Avoid expensive** line-rectangle intersections (which require floating point divisions)
- Cohen-Sutherland Clipping (1967)
- Liang-Barsky Clipping
- There are many more (but many only work in 2D)

Cohen-Sutherland Clipping – 1967 flight simulation

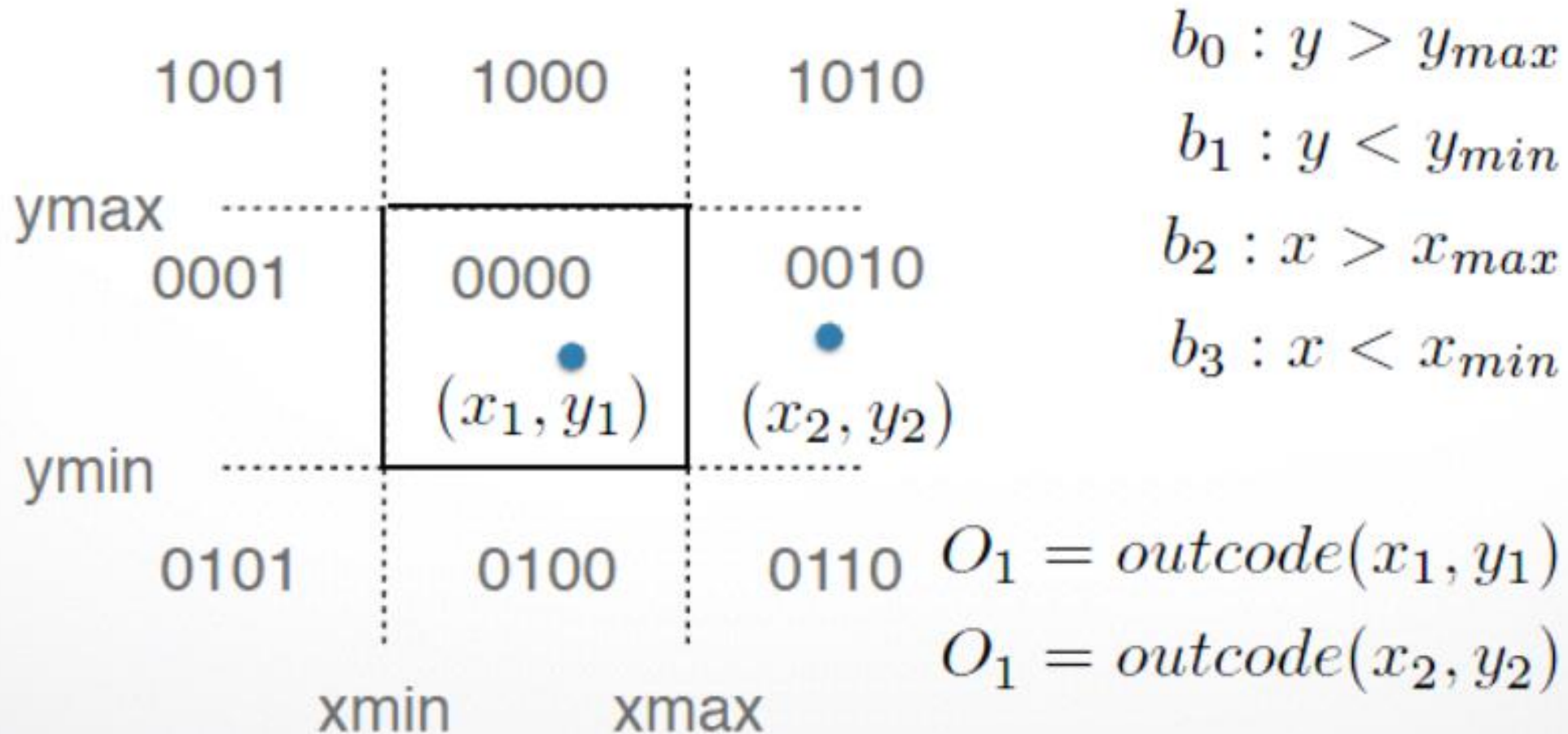
- Clipping rectangle is an intersection of 4 half-planes



- Encode results of four half-plane tests
- Generalizes to 3 dimensions (6 half-planes)

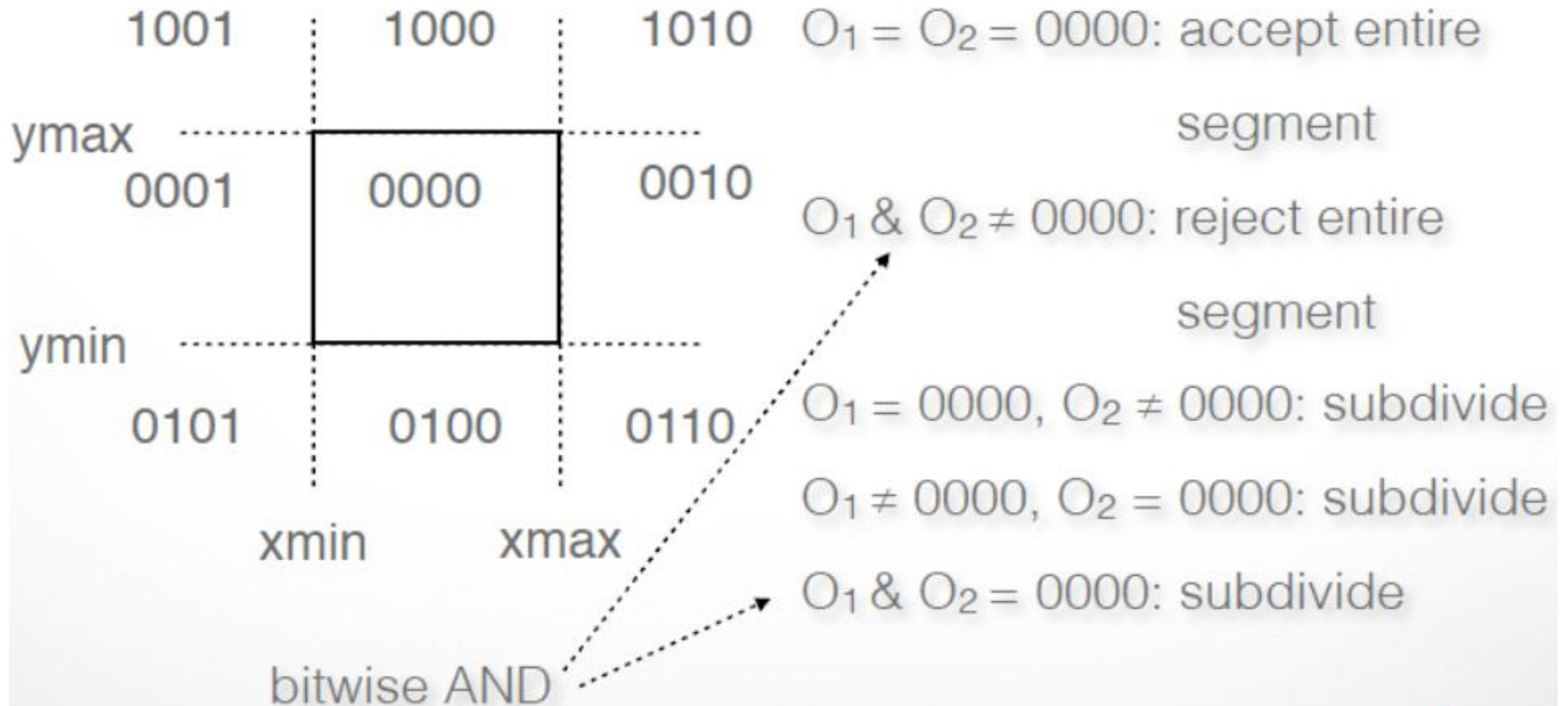
Outcodes (Cohen-Sutherland)

- Divide space into 9 regions
- 4-bit **outcode** determined by comparisons (TBRL)



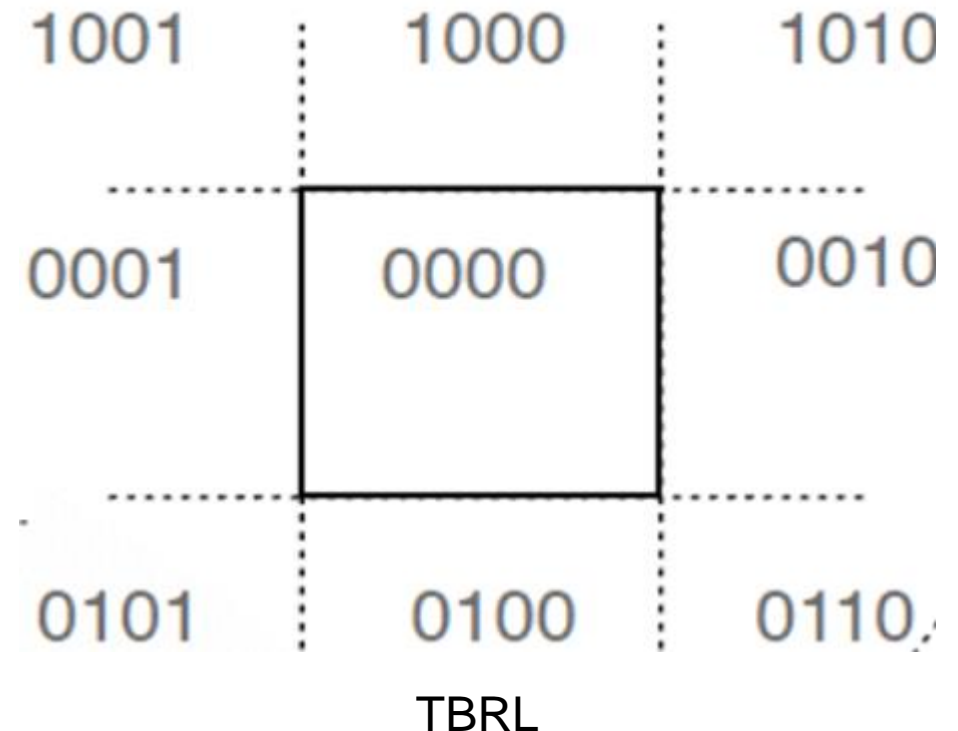
Cases for Outcodes

- Outcomes: accept, reject, subdivide

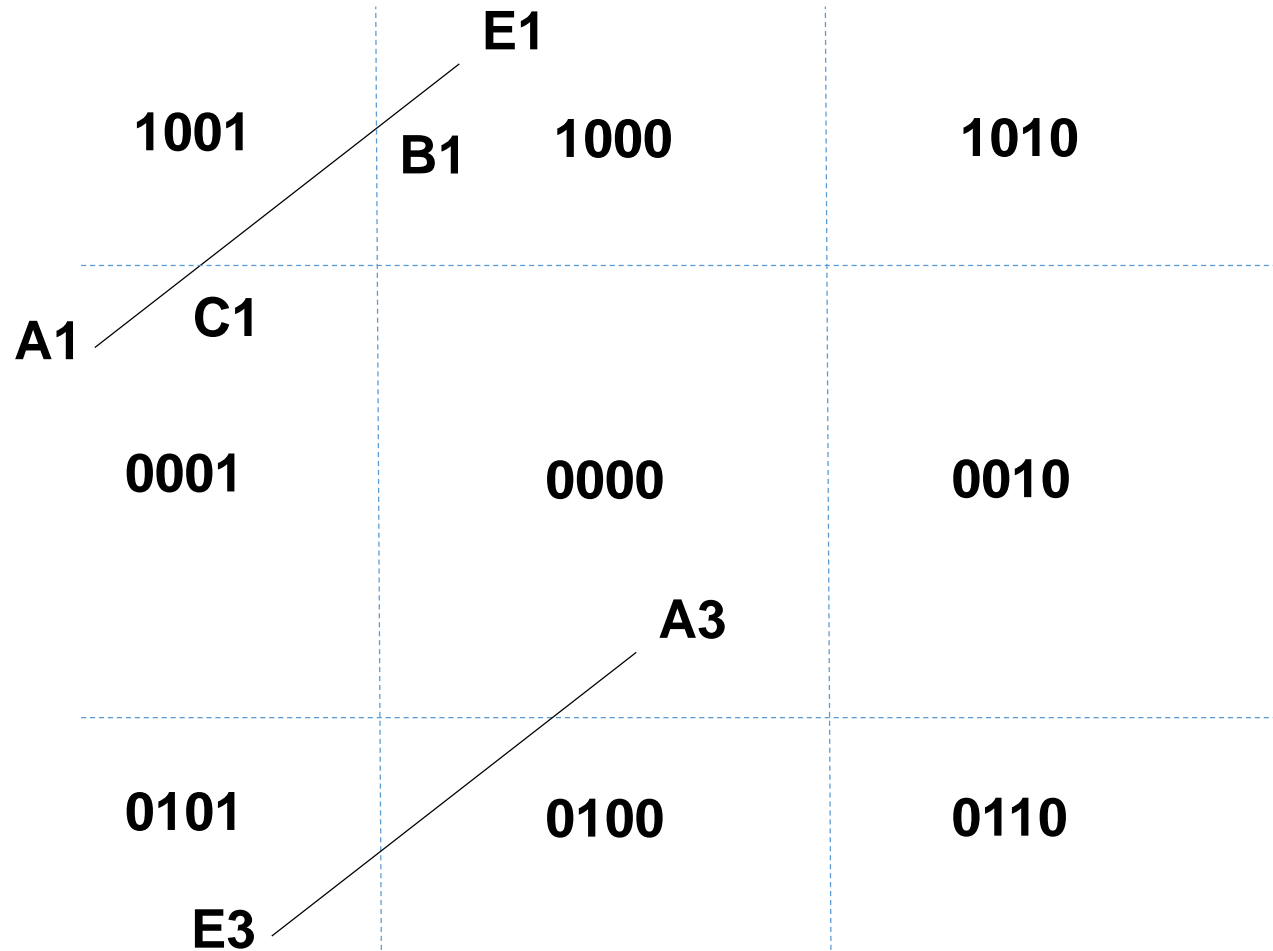


Cohen-Sutherland Subdivision

- Pick outside endpoint ($o \neq 0000$)
- Pick a crossed edge ($o = b_0b_1b_2b_3$ and $b_k \neq 0$)
- Compute intersection of this line and this edge
- Replace endpoint with intersection point
- Restart with new line segment
 - Outcodes of second point are unchanged
- This algorithm converges



Cohen-Sutherland Line-Clipping (example)



a) A1E1

b) B1E1

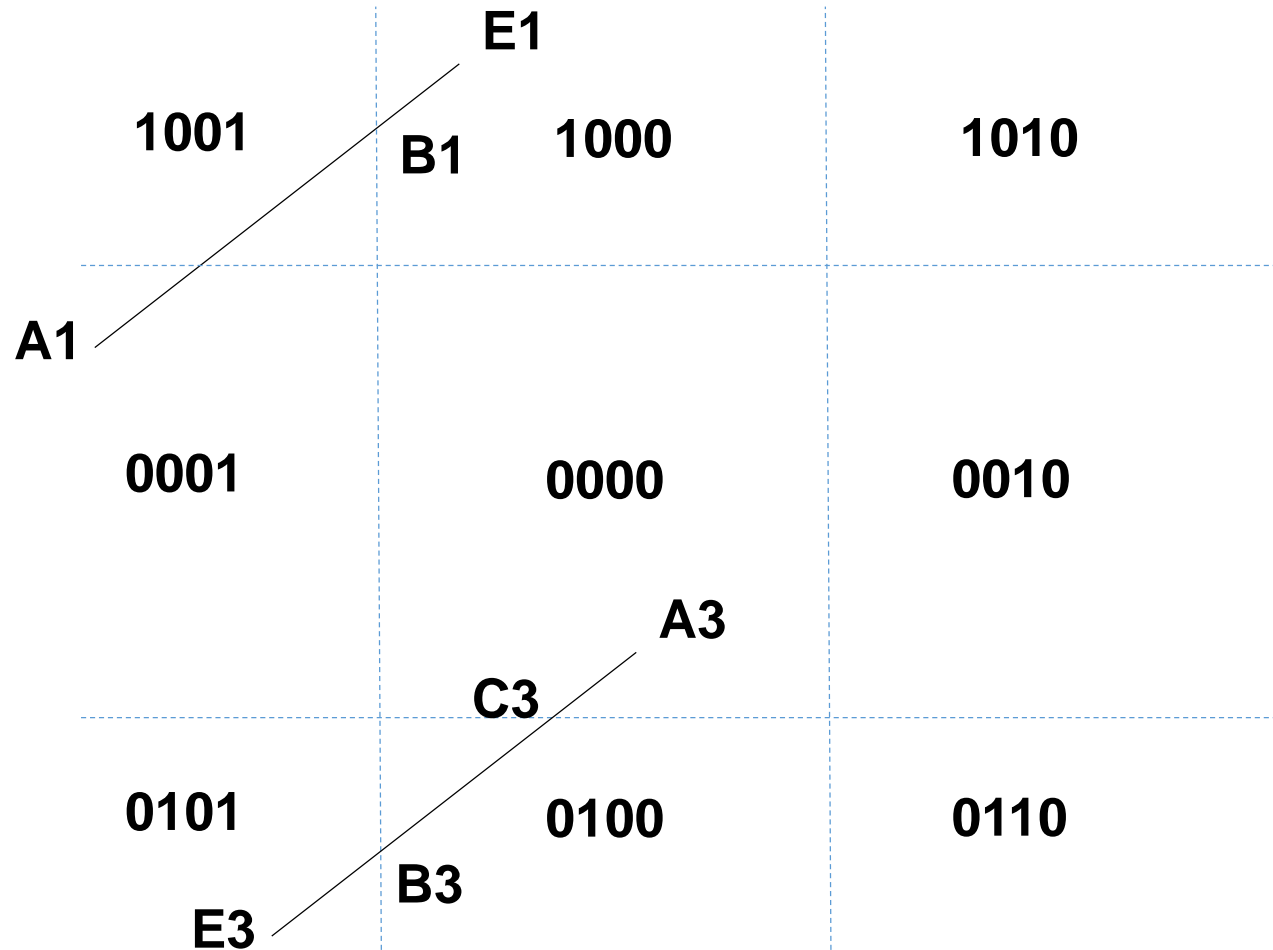
c) Reject

d) A1E1

e) E1C1

f) Reject

Cohen-Sutherland Line-Clipping (example)



a) A1E1

b) B1E1

c) Reject

d) A3E3

e) A3B3 (0,1,0,0)

f) A3C3

g) accept

a) A3E3

b) A3C3

c) accept

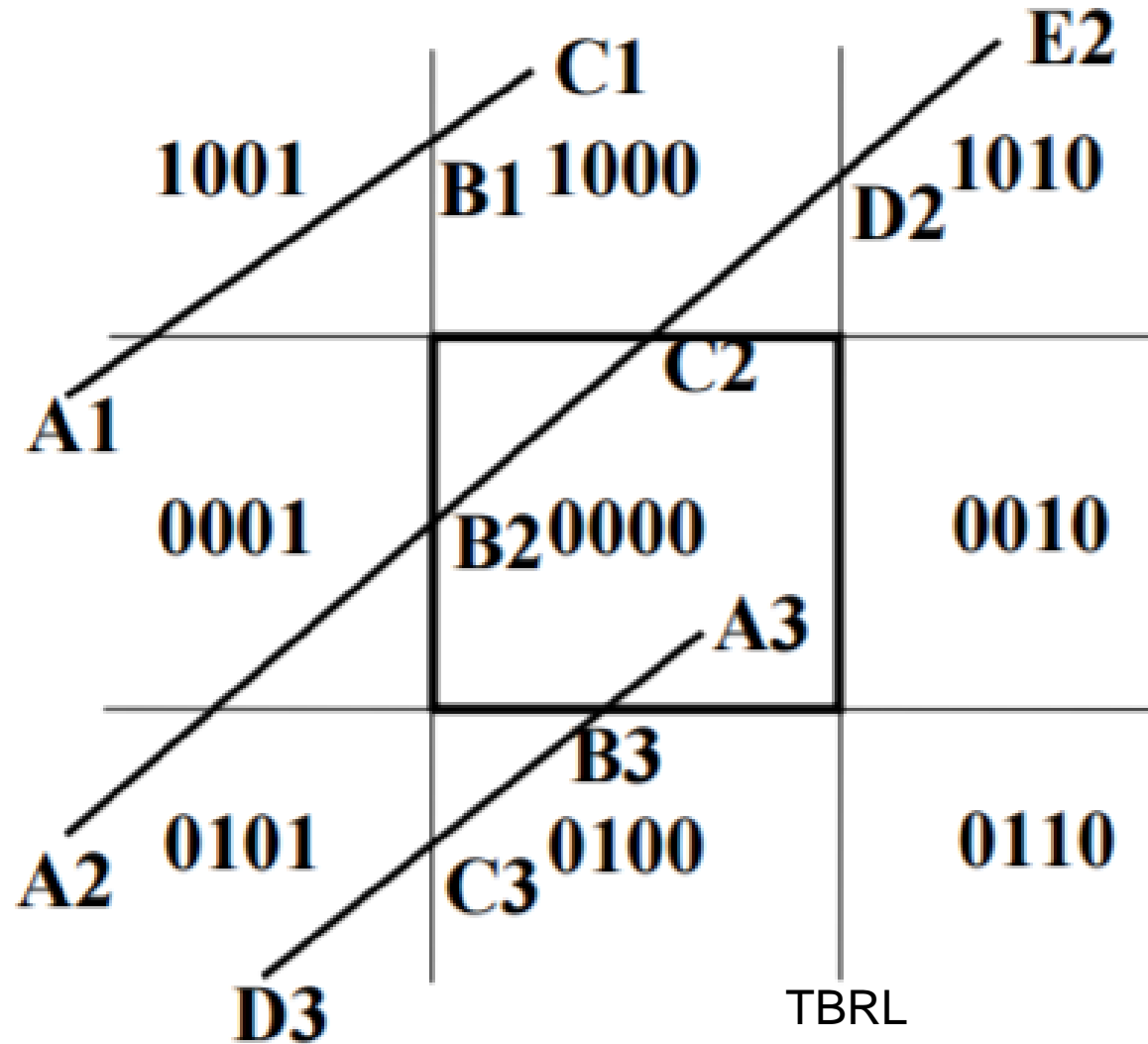
Cohen-Sutherland Line-Clipping

Clip order: Left, Right, Bottom, Top

- 1) A1C1
- 2) B1C1
- 3) reject

- 1) A3D3
- 2) A3C3
- 3) A3B3
- 4) accept

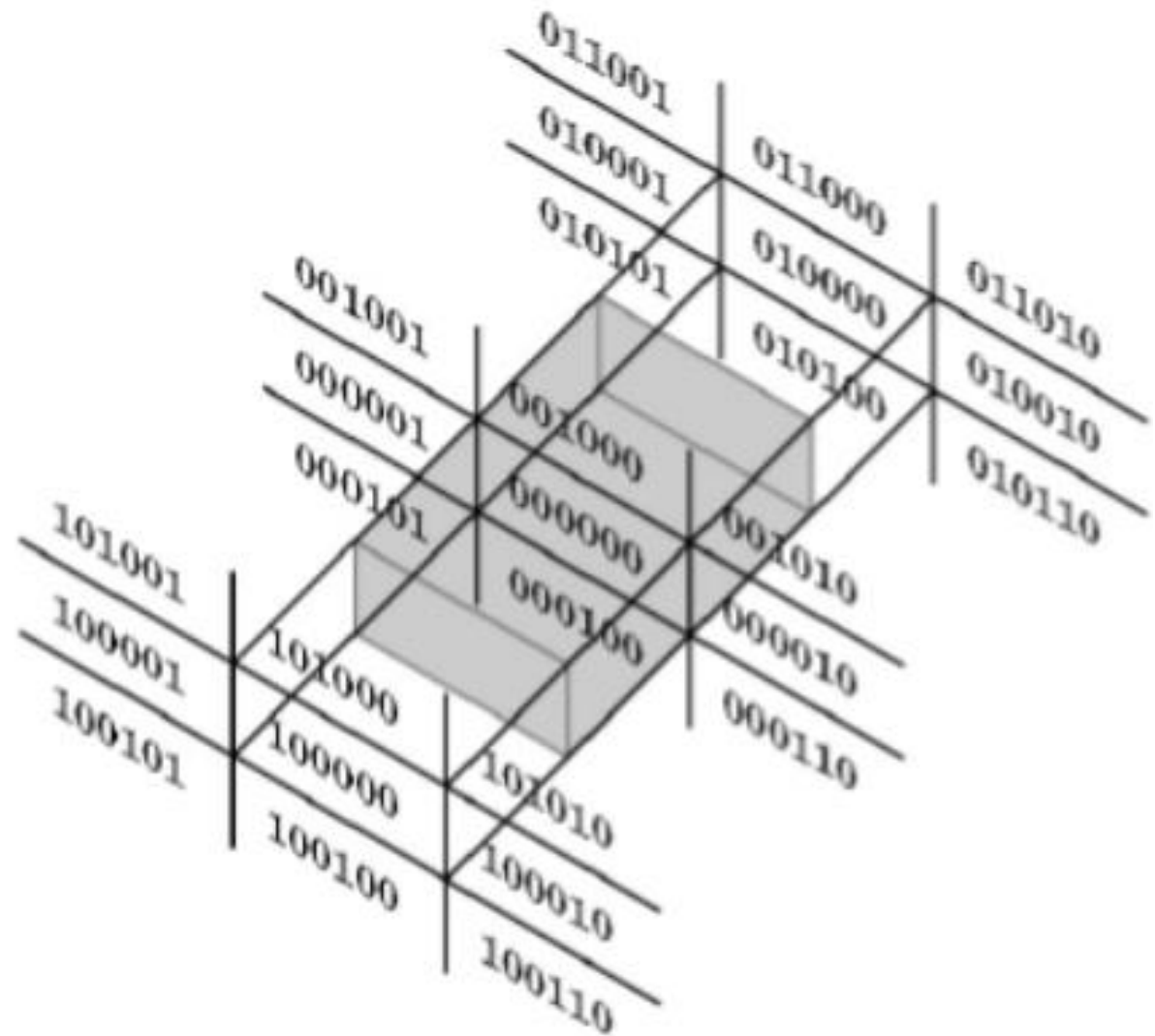
- 1) A2E2
- 2) B2E2
- 3) B2D2
- 4) B2C2
- 5) accept



TBRL

Cohen-Sutherland in 3D

- Use 6 bits in outcode
 - $b_4: Z > Z_{\max}$
 - $b_5: Z < Z_{\min}$
- Other calculations as before



Cohen-Sutherland Line-Clipping

- Advantages:
 - Simple to program
 - Extends to 3-D cubic volumes
 - Efficient when most of the lines to be clipped are either rejected or accepted (not so many subdivisions).
- Disadvantages:
 - Fixed-order decision can do needless work
 - Can improve using more regions (Nicholl-Lee-Nicholl Alg)
- **Parametric clipping are more efficient.**

Liang-Barsky Clipping

- **You-Dong Liang** (梁友栋) is a [mathematician](#) and [educator](#), best known for his contributions in [geometric modeling](#) and the [Liang-Barsky algorithm](#).
- Born on July 19, 1935
- Design Liang-Barsky clipping when he is 49
- Liang, Y.D., and Barsky, B., "A New Concept and Method for Line Clipping", **ACM Transactions on Graphics**, 3(1):1-22, January **1984**.
- Liang, Y.D., B.A., Barsky, and M. Slater, Some Improvements to a Parametric Line Clipping Algorithm, CSD-92-688, Computer Science Division, University of California, Berkeley, 1992.
- Fu-Chung Huang, Gordon Wetzstein, Brian A. Barsky, and Ramesh Raskar. "**Eyeglasses-free Display: Towards Correcting Visual Aberrations with Computational Light Field Displays**", *Proceedings of ACM SIGGRAPH 2014*, Vancouver, 10-14 August 2014, *ACM Transactions on Graphics (TOG)*, Volume 33, Issue 4, July 2014, Article No. 59.

Parametric form - Liang-Barsky Clipping

- A line segment with endpoints

$$(x_0, y_0) \text{ and } (x_{\text{end}}, y_{\text{end}})$$

we can describe in the parametric form

$$\begin{aligned} x &= x_0 + u\Delta x \\ y &= y_0 + u\Delta y \end{aligned} \quad 0 \leq u \leq 1$$

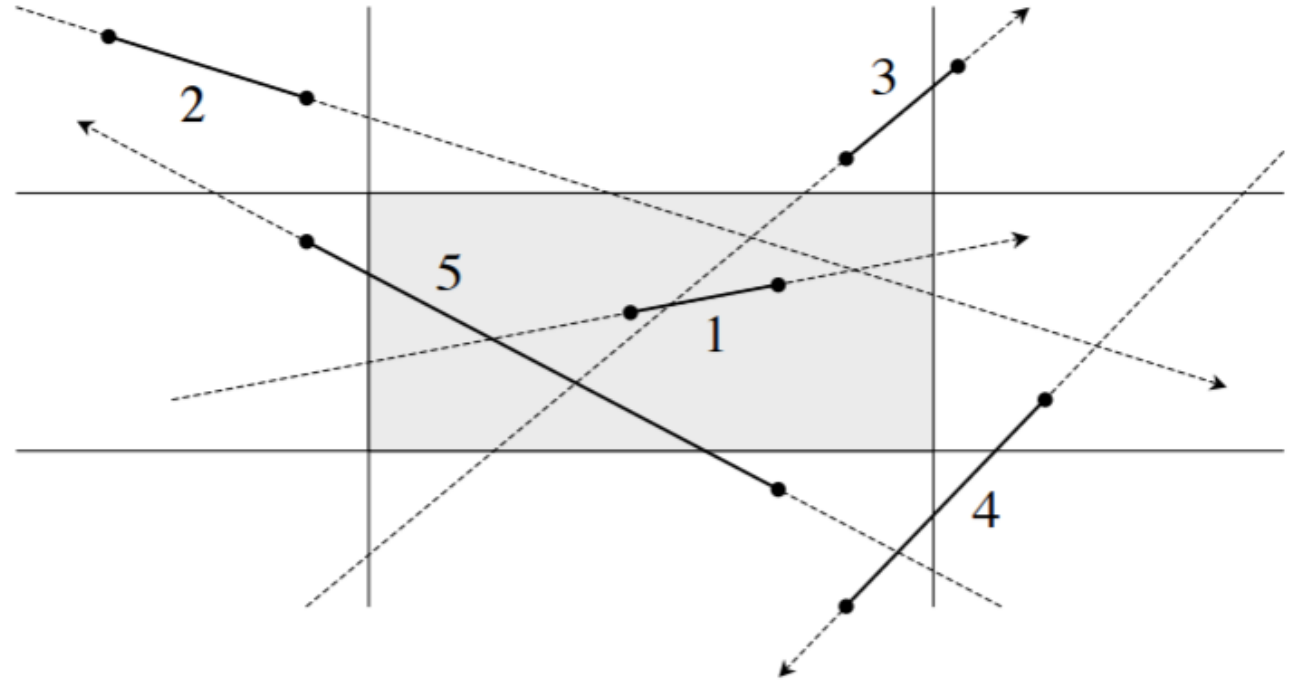
where

$$\begin{aligned} \Delta x &= x_{\text{end}} - x_0 \\ \Delta y &= y_{\text{end}} - y_0 \end{aligned}$$

Liang-Barsky Clipping

- Liang-Barsky asks: for **what values of u** does a line segment enter or exit the **bounds**?
- There can be, at most, two of each; we care about the **maximum entry** value and the **minimum exit** value

$$x = x_0 + u\Delta x$$
$$y = y_0 + u\Delta y$$



- Line 1: max entry < 0 , min exit > 1 — *accept*
Line 2: max entry > 1 , min exit > 1 — *reject*
Line 3: max entry < 0 , min exit < 0 — *reject*
Line 4: max entry $>$ min exit — *reject*
Line 5: max entry > 0 , min exit < 1 , max entry $<$ min exit — *clip*

Liang-Barsky Clipping

- A line is inside clipping region for values of u such that:

$$\begin{array}{ll} xw_{\min} \leq x_0 + u\Delta x \leq xw_{\max} & \Delta x = x_{\text{end}} - x_0 \\ yw_{\min} \leq y_0 + u\Delta y \leq yw_{\max} & \Delta y = y_{\text{end}} - y_0 \end{array}$$

- Can be described as

$$u p_k \leq q_k, \quad k = 1, 2, 3, 4$$

- The infinitely line intersect the clip region edges when

$u_k = \frac{q_k}{p_k}$ where	$p_1 = -\Delta x$	$q_1 = x_0 - xw_{\min}$	Left boundary
	$p_2 = \Delta x$	$q_2 = xw_{\max} - x_0$	Right boundary
	$p_3 = -\Delta y$	$q_3 = y_0 - yw_{\min}$	Bottom boundary
	$p_4 = \Delta y$	$q_4 = yw_{\max} - y_0$	Top boundary

Liang-Barsky Clipping

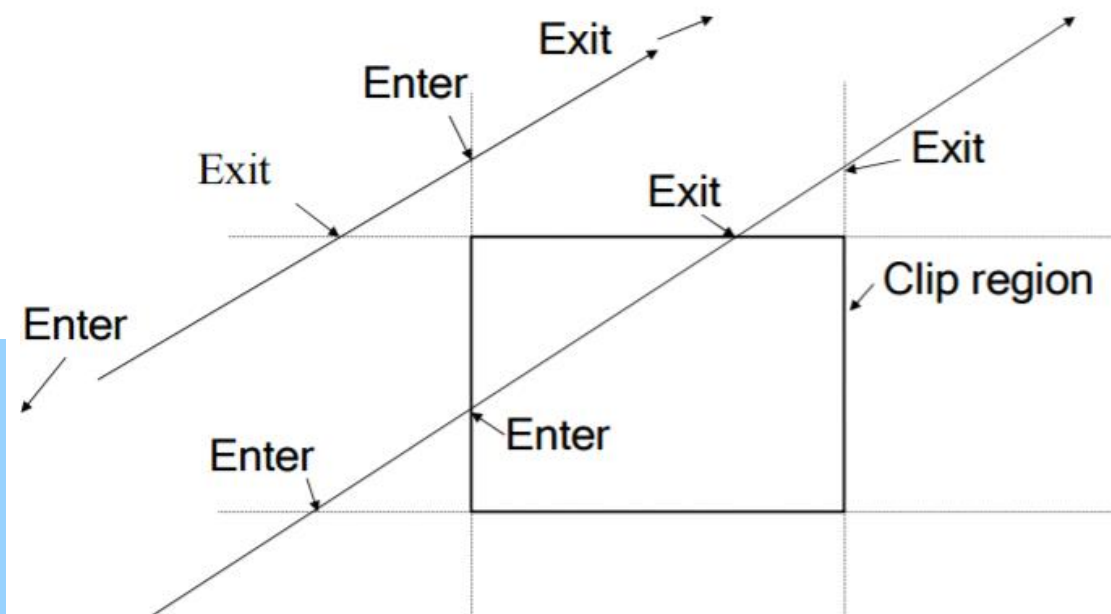
- Liang-Barsky asks: for what values of u does a line segment enter or exit the bounds?

- **How to measure enter or exit via p_k , q_k instead of u ?**

$$\Delta x = x_{end} - x_0$$

$p_1 = -\Delta x$	$q_1 = x_0 - xw_{min}$	Left boundary
$p_2 = \Delta x$	$q_2 = xw_{max} - x_0$	Right boundary
$p_3 = -\Delta y$	$q_3 = y_0 - yw_{min}$	Bottom boundary
$p_4 = \Delta y$	$q_4 = yw_{max} - y_0$	Top boundary

- When $p_k < 0$, as u increases
 - line goes from outside to inside - entering
- When $p_k > 0$,
 - line goes from inside to outside - exiting
- When $p_k = 0$,
 - line is parallel to an edge



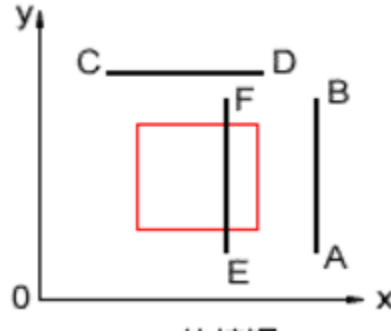
If there is a segment of the line inside the clip region, a sequence of infinite line intersections must go:

Entering, entering, exiting, exiting.

Conditions

- If ($p_k = 0$) – parallel line to one of the clipping edge

- ($q_k < 0$) – outside, **reject**
- ($q_k \geq 0$) – inside

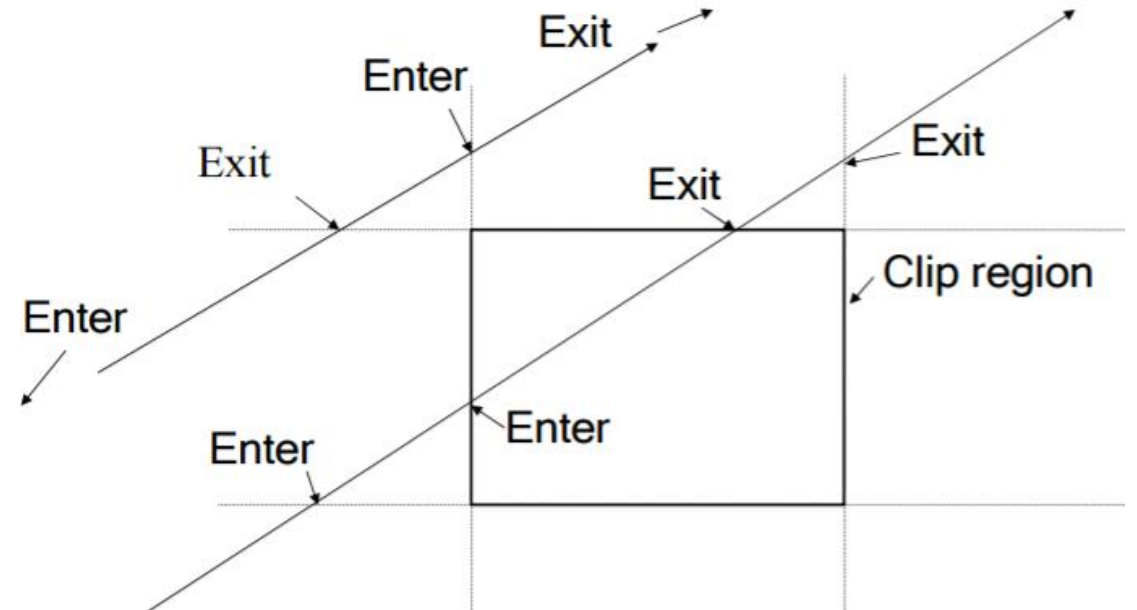


- If ($p_k < 0$) – from outside to inside

- Intersection at: $t_1 = q_k/p_k$ (OIP)

- If ($p_k > 0$) – from inside to outside

- Intersection at: $t_2 = q_k/p_k$ (IOP)

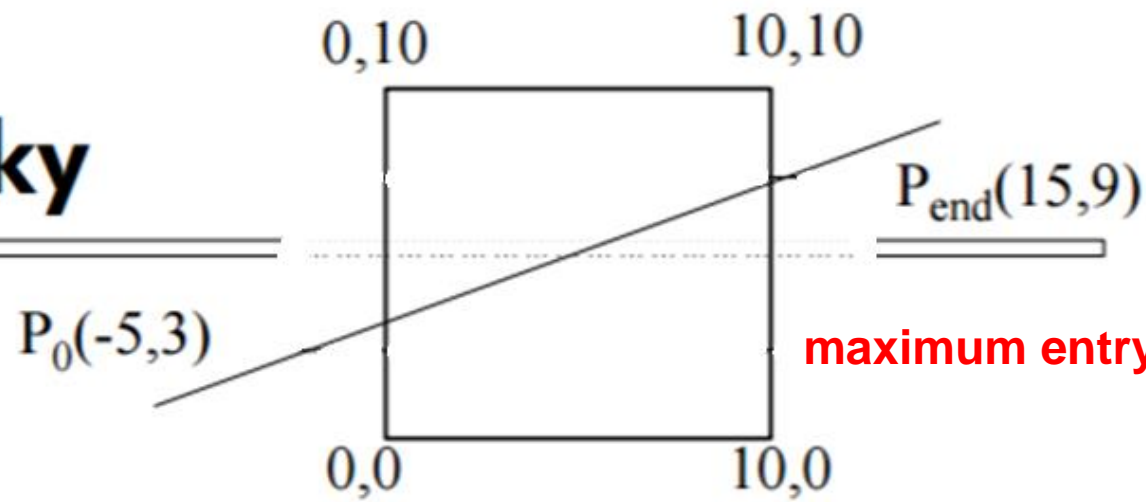


- Key Insight: we need to find two intersection points, one OIP, one IOP.

Intersection Point Computation

- For $(p_k < 0)$ (Outside to inside point)
 - $r_k = q_k / p_k$
 - OIP $t_1 = \max(r_k, 0)$
- For $(p_k > 0)$ (Inside to outside point)
 - $r_k = q_k / p_k$
 - IOP $t_2 = \min(r_k, 1)$
- If $(t_1 > t_2)$, complete outside, **REJECT**
- Else clipped line is between (t_1, t_2)

Example Liang-Barsky



maximum entry value and the minimum exit value

$$u_{left} = \frac{q_1}{p_1} = \frac{x_0 - xw_{min}}{-\Delta x} = \frac{-5 - 0}{-(15 - (-5))} = \frac{1}{4}$$

Entering $\Rightarrow u_{min} = 1/4$

$$u_{right} = \frac{q_2}{p_2} = \frac{xw_{max} - x_0}{\Delta x} = \frac{10 - (-5)}{15 - (-5)} = \frac{3}{4}$$

Exiting $\Rightarrow u_{max} = 3/4$

$$u_{bottom} = \frac{q_3}{p_3} = \frac{y_0 - yw_{min}}{-\Delta y} = \frac{3 - 0}{-(9 - 3)} = -\frac{1}{2}$$

$u < 0$ then ignore

$$u_{top} = \frac{q_4}{p_4} = \frac{yw_{max} - y_0}{\Delta y} = \frac{10 - 3}{9 - 3} = \frac{7}{6}$$

$u > 1$ then ignore

Liang-Barsky Clipping

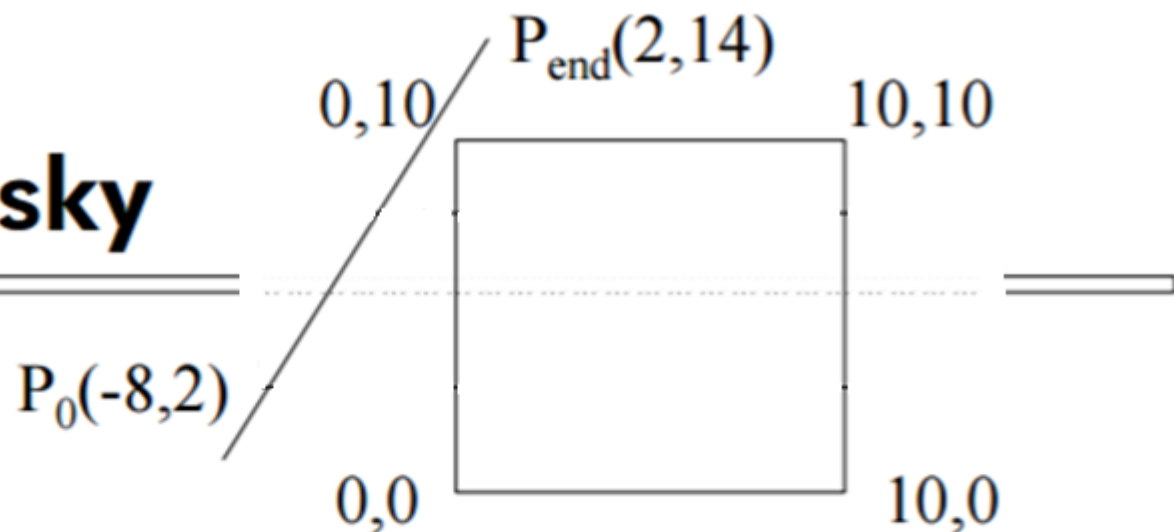
- We have $u_{\min} = 1/4$ and $u_{\max} = 3/4$

$$P_{\text{end}} - P_0 = (15+5, 9-3) = (20, 6)$$

$\downarrow \quad \downarrow$
 $\Delta x \quad \Delta y$

- If $u_{\min} < u_{\max}$, there is a line segment
 - compute endpoints by substituting u values
- Draw a line from
 $(-5+(20) \cdot (1/4), 3+(6) \cdot (1/4))$
to
 $(-5+(20) \cdot (3/4), 3+(6) \cdot (3/4))$

Example Liang-Barsky



$$u_{left} = \frac{q_1}{p_1} = \frac{x_0 - xw_{min}}{-\Delta x} = \frac{-8 - 0}{-(2 - (-8))} = \frac{4}{5}$$

Entering $\Rightarrow u_{min} = 4/5$

$$u_{right} = \frac{q_2}{p_2} = \frac{xw_{max} - x_0}{\Delta x} = \frac{10 - (-8)}{2 - (-8)} = \frac{9}{5}$$

$u > 1$ then ignore

$$u_{bottom} = \frac{q_3}{p_3} = \frac{y_0 - yw_{min}}{-\Delta y} = \frac{2 - 0}{-(14 - 2)} = -\frac{1}{6}$$

$u < 0$ then ignore

$$u_{top} = \frac{q_4}{p_4} = \frac{yw_{max} - y_0}{\Delta y} = \frac{10 - 2}{14 - 2} = \frac{2}{3}$$

Exiting $\Rightarrow u_{max} = 2/3$

Liang-Barsky Clipping

- We have $u_{\min} = 4/5$ and $u_{\max} = 2/3$

$$P_{\text{end}} - P_0 = (2+8, 14-2) = (10, 12)$$

- $u_{\min} > u_{\max}$,
there is no line segment to draw

Summary: Liang-Barsky

- (x,y) coordinates are only computed for the two final intersection points
- At most 4 parameter values (division) are computed
- This is a non-iterative algorithm
- Can be extended to 3-D

Line-Segment Clipping Assessment

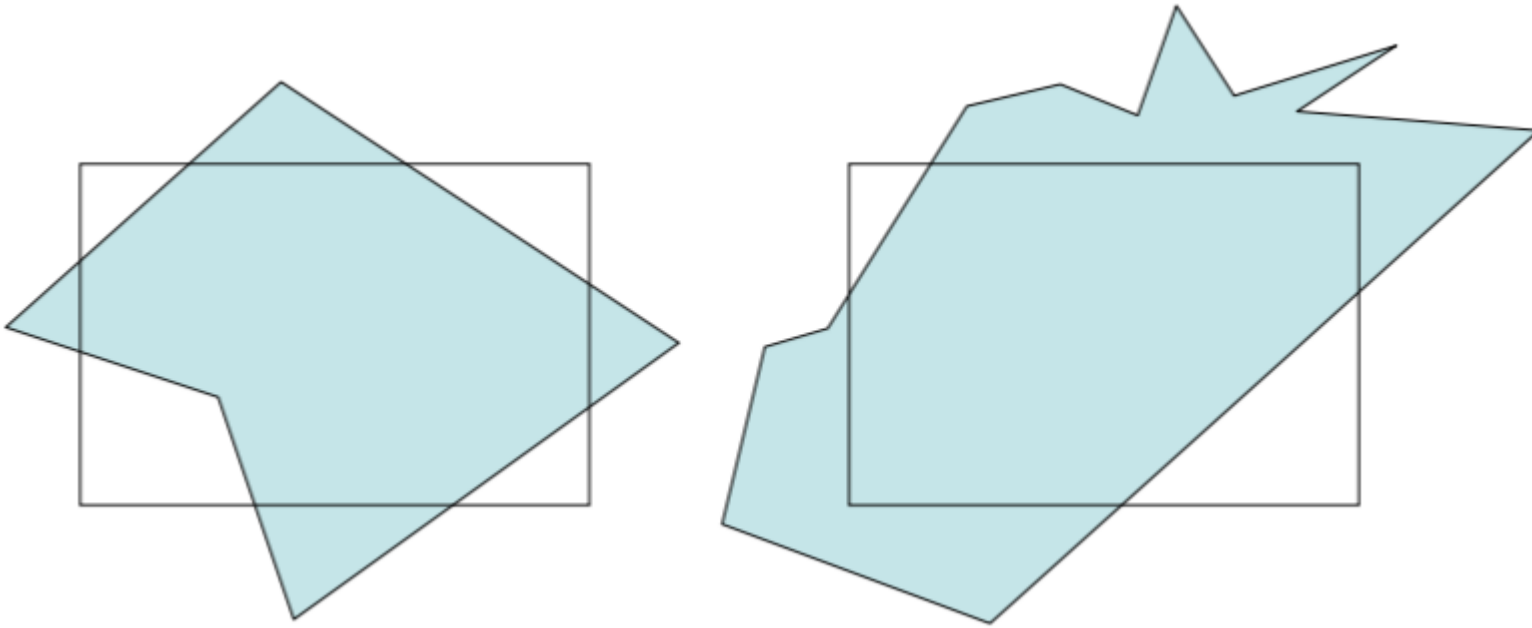
- Cohen-Sutherland
 - Works well if many lines can be rejected early
 - Recursive structure (multiple subdivisions) is a drawback
- Liang-Barsky
 - Avoids recursive calls
 - Many cases to consider (tedious, but not expensive)
 - In general **much faster** than Cohen-Sutherland

Outline

- Line-Segment Clipping
 - Cohen-Sutherland
 - Liang-Barsky
- Polygon Clipping
 - Sutherland-Hodgeman
 - Weiler-Atherton

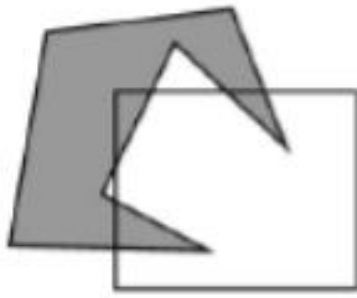
Polygon Clipping

- Clipping polygons complicates the problem because we have to take account the enclosed area
- Also, where line segment clipping always maps two points to two (possibly other) points, polygon clipping may actually change the number of points after clipping



Concave Polygons

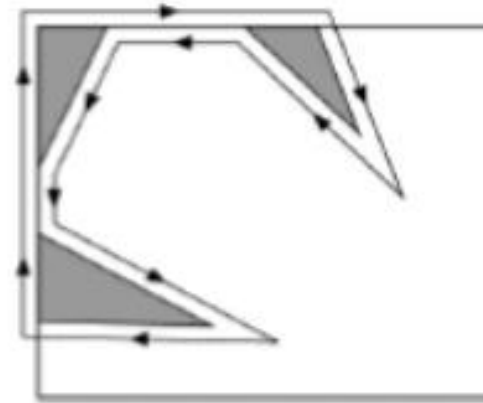
- Approach 1: clip, and then join pieces to a single polygon
 - often difficult to manage



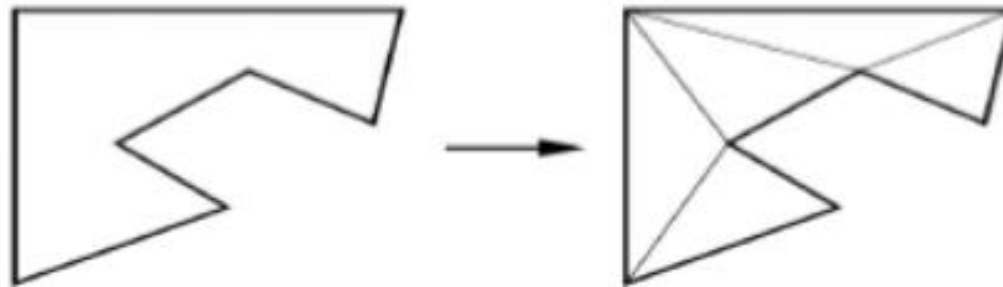
(a)



(b)

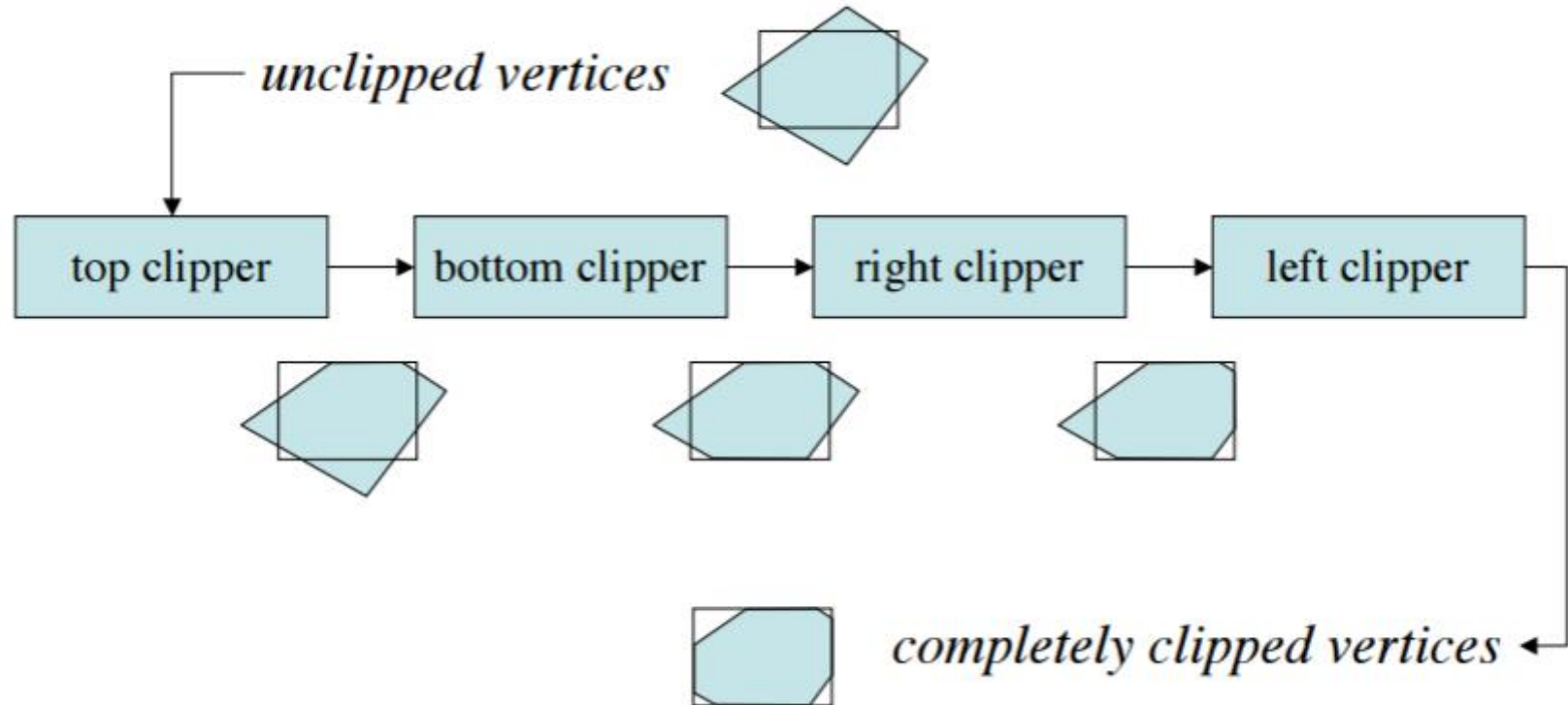


- Approach 2: tessellate and clip triangles
 - this is the common solution



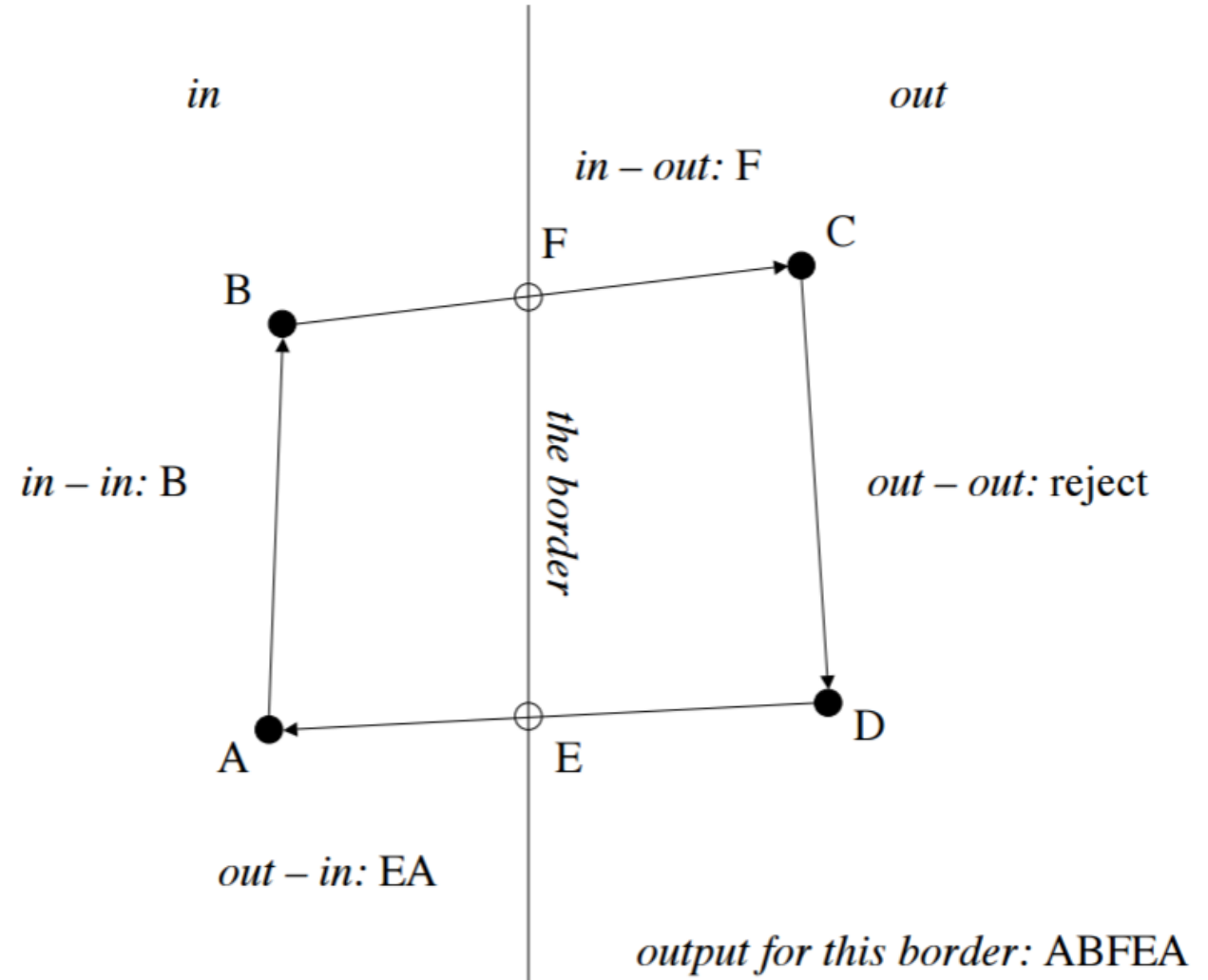
Sutherland-Hodgeman (part 1)

- Subproblem:
 - Input: polygon (vertex list) and single clip plane
 - Output: new (clipped) polygon (vertex list)
- Apply once for each clip plane
 - 4 in two dimensions
 - 6 in three dimensions
 - Can arrange in pipeline



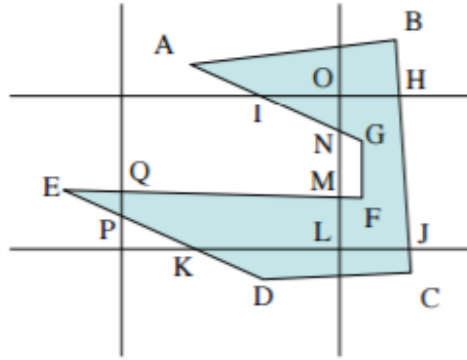
Sutherland-Hodgeman (part 2)

- To clip vertex list (polygon) against a **half-plane**:
 - Test first vertex. Output if inside, otherwise skip.
 - Then loop through list, testing transitions
 - In-to-in: output vertex
 - In-to-out: output intersection
 - out-to-in: output intersection & vertex
 - out-to-out: no output
 - Will output clipped polygon as vertex list

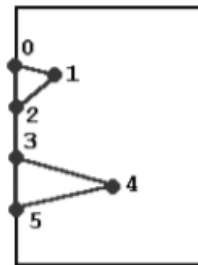


- Can combine with Liang-Barsky idea

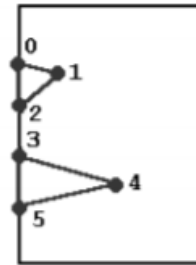
Example & problem



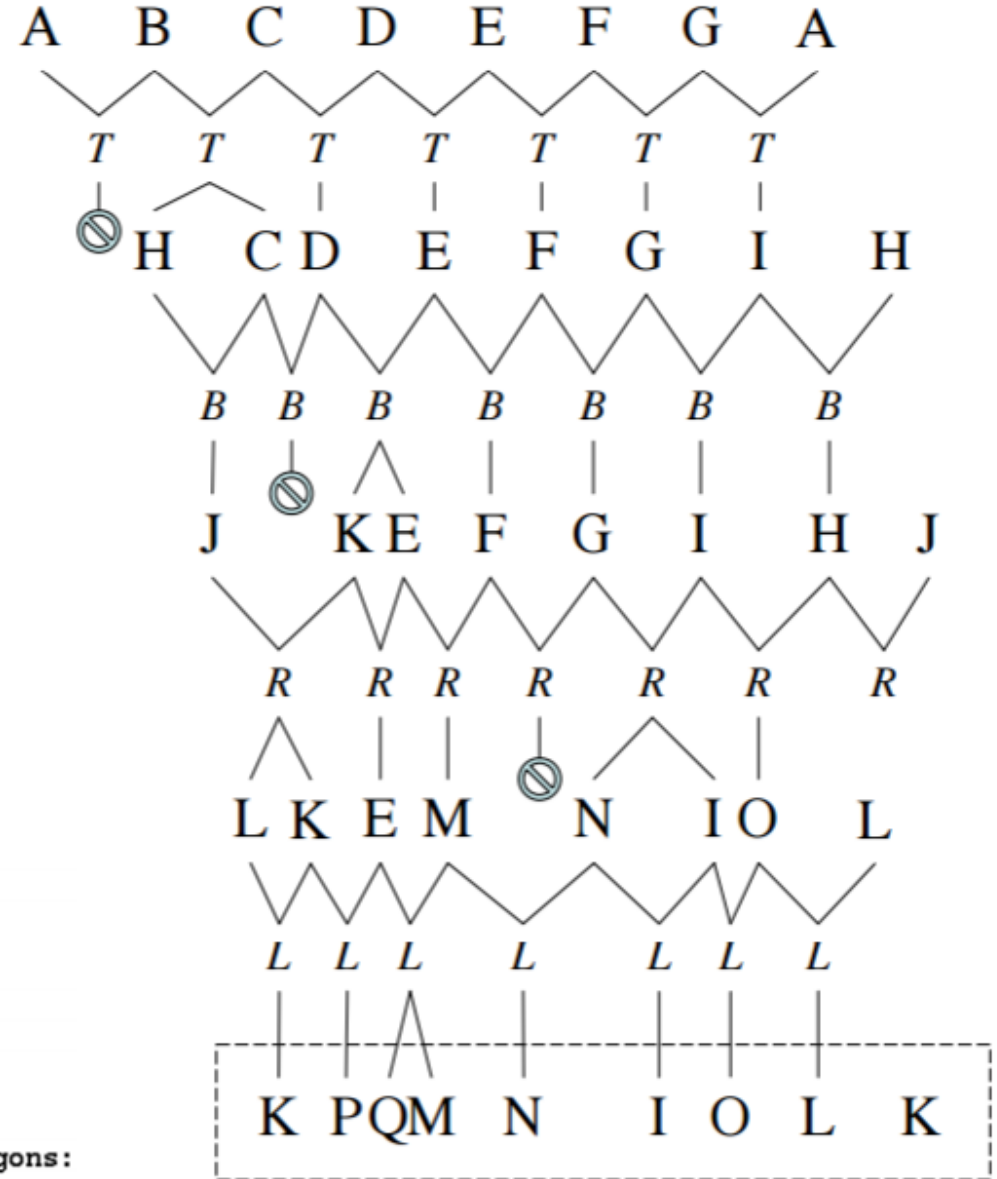
- Works fine with convex polygons
- Concave polygons problematic
 - **Coincident edges** along a clip boundary may be generated as part of the output polygon
 - Such as MN, OL
 - Could cause problems with **polygon filling**, shadows, etc



Polygon: 0,1,2,3,4,5
0,2,3,5 are vertices
along the left boundary



So break into two polygons:
0,1,2 and 3,4,5

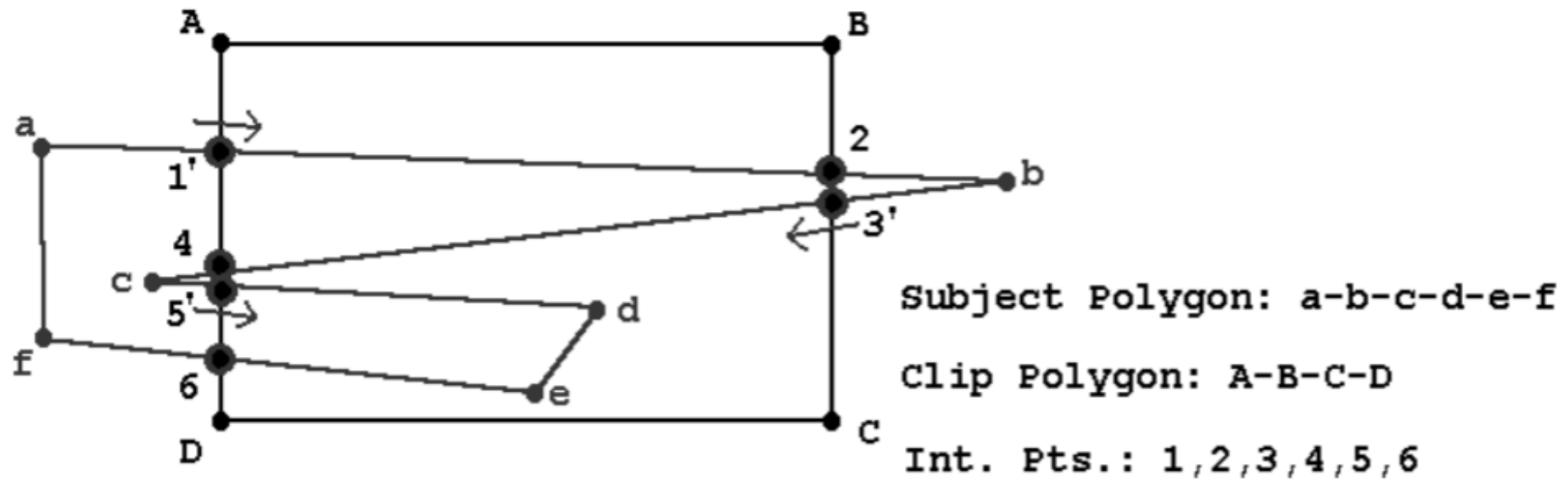


Weiler-Atherton Polygon Clipping

- Clips concave polygons correctly
 - produces **separate polygons** for each visible fragment
- Instead of always going around the polygon edges, we **also**, want to **follow window boundaries**.
 - For an outside-to-inside pair of vertices, follow the polygon boundary.
 - For an inside-to-outside pair of vertices, follow the window boundary in a clockwise direction.

Example

- outside-to-inside, follow the polygon boundary.
- inside-to-outside, follow the window boundary in a clockwise direction.



1st Iteration:

Subject: a → 1' → 2 b 3' → 4 c 5' d e 6 f

Clip: A B 2 → 3' C D 6 5' → 4 → 1'

Output: 1 2 3 4

1 revisited so stop out poly

2nd Iteration:

Subject: a (1') (2) b (3') (4) c → 5' → d → e → 6 f

Clip: A B 2 → 3' C D 6 → 5' 4 1'

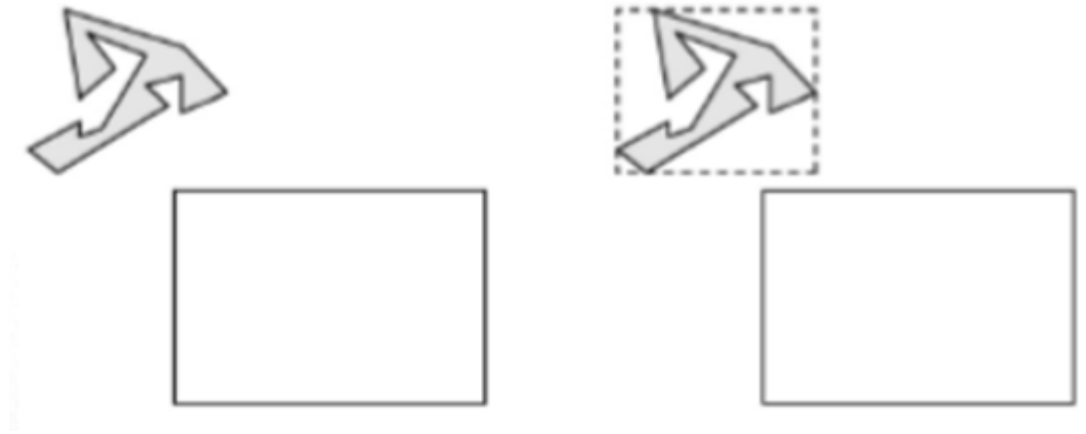
Output: 5 d e 6

5 revisited so stop out poly

All intersection points visited ⇒ Done!

Other Cases and Optimizations

- Curves and surfaces
 - Do it analytically if possible
 - Otherwise, approximate curves / surfaces by lines and polygons
- Bounding boxes
 - Easy to calculate and maintain
 - Sometimes big savings



Summary: Clipping

- Clipping line segments to rectangle or cube
 - **Lessen** expensive multiplications and divisions
 - Cohen-Sutherland or Liang-Barsky
- Polygon clipping
 - Sutherland-Hodgeman pipeline
 - Weiler-Atherton Polygon Clipping
- Clipping in 3D
 - essentially extensions of 2D algorithms