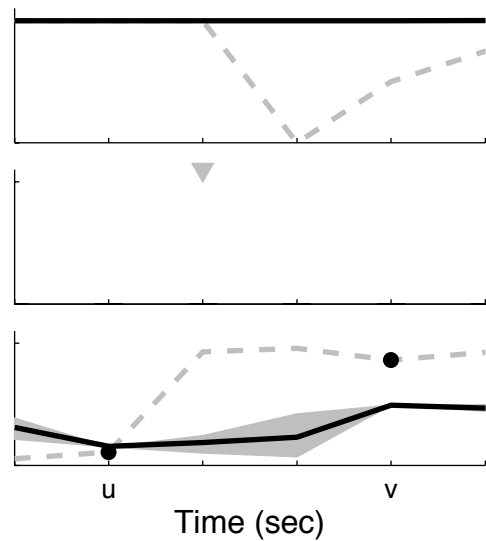
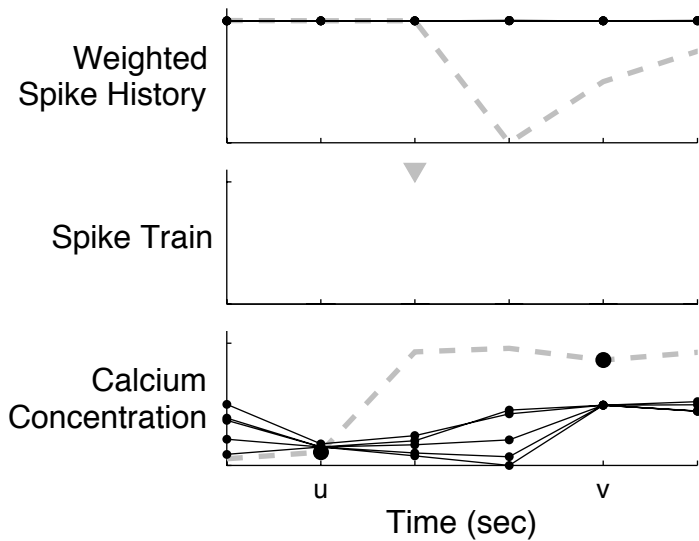


Prior sampler

Particles

Inferred Distributions



One observation ahead sampler

Particles

Inferred Distributions

