11. Dynamic Programming Introduction CPSC 535

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Dynamic Programming

- pattern for designing algorithms
- programming:
 - optimize subject to constraints
 - (same as Linear Programming)
 - not writing programs
- dynamic: curious buzzword
- specialized tool
 - dynamic programming only applies to problems with overlapping subproblems
 - rare
 - huge speedup over naive algorithms for such problems

Big Ideas

- important algorithm design approach in its own right
- problem solving to view a problem in a different way
- time-space trade-off
 - speedup costs space
- efficiency-complexity trade-off
 - ► top-down, bottom-up variants
 - top-down is simpler to design and implement
 - bottom-up has faster constant factors

Optimization, Value, Solution

- dynamic programming usually applies to optimization problems
 - correct output "minimizes" or "maximizes" something
- value: quality of the solution
 - quantity to minimize/maximize
- designing a dynamic programming algorithm to...
 - ...calculate optimal value is simpler
 - ...calculate optimal solution is more complicated
- .: some examples and exercises only involves values
- algo's for solutions are more practical but difficult

Example: Vertex Cover

vertex cover problem input: an undirected graph G = (V, E) output: a vertex cover C of minimum size

- solution = a set of vertices C
- ▶ value = size of C
- ightharpoonup optimal = minimize |C|

vertex cover value problem

input: an undirected graph G = (V, E)

output: the minimum size of a vertex cover of *G*

note: output data type is an integer, not a set

Example: Bipartite Matching

bipartite maximum matching problem

input: an undirected bipartite graph G = (V, E) with parts

 $V = L \cup R$

output: a matching $M \subseteq E$ where the number of matched vertices is maximum

- solution = a set of edges M
- ightharpoonup value = size of M

bipartite maximum matching value problem

input: an undirected bipartite graph G = (V, E) with parts

 $V = L \cup R$

output: the maximum number of edges in a matching of G

note: output data type is an integer, not a set

Ties

- we say an optimal solution
- not the optimal solution
- multiple solutions may have same value
- any of these are correct
- examples:
 - vertex cover: "a vertex cover C of minimum size"
 - ▶ bipartite matching: "a matching $M \subseteq E$ where the number of matched vertices is maximum"
- not worrying about ties simplifies dynamic programming algorithms

The Main Idea

- dynamic programming works on a problem where. . .
 - **a** solution has a **recursive structure**
 - so we could design a naive divide-and-conquer algorithm
 - but, subproblems overlap
 - so divide-and-conquer would do the same work repeatedly
 - would be slow (often exponential time)
- idea: store subproblem solutions in a table (array or hash dictionary)
- only solve subproblems not already in table
- :: each subproblem is solved only once
- ▶ fast polynomial time, often $\Theta(n)$ or $\Theta(n^2)$

Top-Down versus Bottom Up

two ways to write the pseudocode

top-down

- improvement to divide-and-conquer pseudocode
- add a base case that checks for a solution in the table
- simple to derive from divide-and-conquer algorithm
- usually depends on a hash dictionary data structure, so expected time

bottom-up

- clean-sheed redesign
- nested loops explicitly solve problems in sorted order
- base case, larger subproblems, ..., full problem
- store subproblems in array (not hash table)
- ▶ no recursion or hash table ⇒ faster constant factors

Design Process

- 1. Identify the problem's **solution** and **value**, and note which is our **goal**.
- 2. Derive a **recurrence** for an optimal value.
- 3. Design a divide-and-conquer algorithm that computes an **optimal value**.
- 4. Design a dynamic programming algorithm that computes an **optimal value**.
 - 4.1 top-down alternative: add table base case (memoization)
 - 4.2 **bottom-up** alternative: rewrite to use bottom-up loops instead of recursion
- 5. (if goal is a solution algo.) Design a dynamic programming algorithm that computes an **optimal solution**.

Rod Cutting Problem

story:

- have a rod of metal *n* inches long
- ightharpoonup can chop it into pieces of size $1, 2, \dots, n$
- total length of all pieces = n
- market price of a i-inch piece is p_i
- market price of a 0-inch piece is 0
- goal: maximize total price of the pieces

rod cutting value problem

input: an array of non-negative prices $P = \langle p_1, \dots, p_n \rangle$ **output:** the maximum total price that can be achieved by cutting an *n*-inch rod into pieces

Example with n = 4

i	1	2	3	4
pi	3	7	8	11

Ways of cutting $\Box\Box\Box\Box$:

1.
$$\square\square\square\square$$
: $p_4 = 11

2.
$$\Box \mid \Box \Box \Box : p_1 + p_3 = \$3 + \$8 = \$11$$

3.
$$\Box\Box | \Box\Box : p_2 + p_2 = \$7 + \$7 = \$14$$

4.
$$\Box\Box\Box | \Box : p_3 + p_1 = \$8 + \$3 = \$11$$

5.
$$\Box \mid \Box \mid \Box \Box : p_1 + p_1 + p_2 = \$3 + \$3 + \$7 = \$13$$

6.
$$\square \mid \square \square \mid \square : p_1 + p_2 + p_1 = \$3 + \$7 + \$3 = \$13$$

7.
$$\square\square | \square | \square : p_2 + p_1 + p_1 = \$7 + \$3 + \$3 = \$13$$

8.
$$\Box |\Box |\Box |\Box |\Box : p_1 + p_1 + p_1 + p_1 = \$3 + \$3 + \$3 + \$3 = \$12$$

Greedy Fails

- greedy heuristics are not correct for this problem
- note that there is no requirement that prices p_i obey "common sense" market dynamics
- ightharpoonup e.g. it is allowed for $p_4 > p_5$
- ▶ example of an **incorrect** greedy heuristic: find length i with highest unit price p_i/i , then make $\lceil n/i \rceil$ pieces of length i
- ▶ fails when the leftover $n \lceil n/i \rceil$ inches could be used better
- Recall: the designer of a greedy algorithm has the burden of proving their heuristic is correct
- ➤ **Tip:** if you are tasked with designing a dynamic programming algorithm, don't waste time with greedy algorithms

1. Identify the problem's **solution** and **value**, and note which is our **goal**.

rod cutting problem

input: an array of non-negative prices $P = \langle p_1, \dots, p_n \rangle$ **output:** the maximum total price that can be achieved by cutting an *n*-inch rod into pieces

- **solution:** list of piece lengths e.g. $\langle 2, 2 \rangle$
- value: total price e.g. \$14
- goal: value

- 2. Derive a recurrence for an optimal value.
- ightharpoonup define r_i = the maximum total price starting from i inches
- ightharpoonup base case: $r_0 = 0$
- general case:
 - **think** divide-and-conquer; define r_i in terms of $r_{< i}$
 - make the problem one piece smaller
 - try to make one cut, then recursively use the remaining inches
 - try every option and keep the optimal one

$$r_i = \max_{1 \le i \le n} (p_i + r_{n-i})$$

3. Design a divide-and-conquer algorithm that computes an **optimal value**.

```
1: function CUT-ROD-DC(P[1..n])
      if n == 0 then
2:
3:
          return 0
   end if
4.
5: q = -\infty
    for i from 1 to n do
6.
          q = \max(q, P[i] + \text{CUT-ROD-DC}(p, n-i))
7:
      end for
8:
9:
       return q
10: end function
```

Sidebar: Analysis of CUT-ROD-DC

- CUT-ROD-DC corresponds directly to the r_i defition
- but it is very slow
- fundamental problem: CUT-ROD-DC calls itself many times
 - each iteration of the **for** loop is a recursive call
 - each of those has a **for** loop with recursive calls. . .
- ➤ recall: fast divide-and-conquer algorithms usually call themselves 1–2 times
- ▶ Claim: The time complexity of CUT-ROD-DC is $O(2^{n-1})$.
- dynamic programming will circumvent all this recursion

Rod Cutting Step 4.a

- 4. Design a dynamic programming algorithm that computes an **optimal value**.
 - 4.1 **top-down** alternative: add table base case (**memoization**)
- memoization: use a hash dictionary to make a "memo" of pre-calculated solutions
- use i as key in table T (same API as hash tables in deck 4)
- ▶ after we compute an r_i , set r_i .key = i and insert r_i into T
- \triangleright if T does not contain key i, then we haven't computed r_i yet
- need two functions
 - public non-recursive function to create T and start recursion
 - private recursive function that expects T to exist

Rod Cutting Step 4.a

```
1: function CUT-ROD-MEMOIZED(P[1..n])
      HASH-TABLE-CREATE(T)
      return CUT-ROD-MEMO-REC(T, P)
4: end function
5: function CUT-ROD-MEMO-REC(T, P[1..n])
6:
      q = \text{HASH-TABLE-SEARCH}(T, i)
7:
      if q \neq NIL then
8:
          return q
9.
    end if
10:
    if n == 0 then
11:
          q = 0
12:
       else
13:
          q = -\infty
14:
          for i from 1 to n do
15:
             q = \max(q, P[i] + \text{CUT-ROD-MEMO-REC}(T, P[1..n-i]))
16:
          end for
       end if
17:
18:
   q.key = n
19:
       HASH-TABLE-INSERT(q)
20:
       return a
21: end function
```

Rod Cutting Step 4.b

- 4. Design a dynamic programming algorithm that computes an **optimal value**.
 - 4.1 **top-down** alternative: add table base case (**memoization**)
 - 4.2 **bottom-up** alternative: rewrite to use bottom-up loops instead of recursion
- observe: in CUT-ROD-MEMOIZED, keys are inserted into T in order 0, 1, . . . , n
- **bottom-up:** write an explicit **for** loop that computes and stores every general case r_i in order r_1, \ldots, r_n
- base case is computed and stored before the loop
- convenient to use an array instead of hash table
- ▶ define $R[i] = r_i$
- no more recursion, just loops

Rod Cutting Step 4.b

```
1: function CUT-ROD-BU(P[1..n])
       Create array R[0..n]
    R[0] = 0
3:
    for j from 1 to n do
4:
5:
          q = -\infty
          for i from 1 to n do
6:
              q = \max(q, P[i] + R[j - i])
7:
          end for
8.
          R[i] = q
9:
10.
       end for
       return R[n]
11:
12: end function
```

Bottom-Up Analysis

- ▶ CUT-ROD-BU is clearly $\Theta(n^2)$ time
- ► (Note: easy analysis)

Top-Down Analysis

- trickier analysis
- observe: hash if statement guarantees that each subproblem is solved exactly once
- ▶ solving subproblem i, not counting recursion: $\Theta(i)$ time due to **for** loop
- ▶ total of all subproblems is $\sum_{i=1}^{n} i \in \Theta(n^2)$
- hash operations add "expected" qualifier
- ▶ ∴ CUT-ROD-MEMOIZED takes $\Theta(n^2)$ expected time
- with effort we could replace the hash table with an array for $\Theta(n^2)$ worst-case time
- CUT-ROD-MEMOIZED has worse constant factors due to the overhead of recursive function calls

Trade-Offs

Factor	Naive	TDDP	BUDP
Ease of design	easiest	difficult	very difficult
Ease of analysis	medium	difficult	easy
Time efficiency	$O(2^{n-1})$	$\Theta(n^2)$	$\Theta(n^2)$ w/ fast const.
Space overhead	n/a	O(n) hashtable	O(n) array

- according to principles, bottom up dynamic programming is superior
- but top-down dynamic programming is a close second

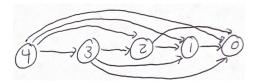
Subproblem Graphs

solutions have a recursive structure

$$r_i = \max_{1 \le i \le n} (p_i + r_{n-i})$$

- a general-case solution depends on other solution(s)
- algorithm must compute solutions in an order that satisfies dependencies
- memoization automates this, with overhead
- bottom-up loops must be designed carefully to iterate in satisfactory order
- visualize dependencies in a subproblem graph

Subproblem Graphs



- vertex i = subproblem i
- ▶ directed edge (i,j) = computing i requires solution to j
- subproblem i must wait until all outgoing neighbors have been computed
- top-down manages with hashtable
- bottom up manages with loop iteration order

5. (if goal is a solution algo.) Design a dynamic programming algorithm that computes an **optimal solution**.

rod cutting value problem input: an array of non-negative prices $P = \langle p_1, \dots, p_n \rangle$ output: the maximum total price that can be achieved by cutting an n-inch rod into pieces

rod cutting problem input: an array of non-negative prices $P = \langle p_1, \dots, p_n \rangle$ output: the list of cut-lengths of maximum total price for an n-inch rod

Storing All Subproblem Solutions Is Expensive

- ▶ solution to rod cutting problem: a list of cut-lengths; O(n) space each
- \triangleright our algorithms compute n+1 solutions
- ▶ storing all subproblem solutions would takes $O((n+1) \times n) = O(n^2)$ space, **expensive**
- instead, store only O(n) information

Backtracking

- algorithm computes optimal value, and logs (records) how it made each decision
- after all optimal values have been computed, follow a "trail" to create solution object
- trail ends at the optimal solution
- each log entry says how to go one step backwards
- follow them until we get to the start (a base case)
- traverses solution in backwards order; reverse it if order matters
- **b** backtracking is usually only O(n) time, and O(n) space overhead

- 5. (if goal is a solution algo.) Design a dynamic programming algorithm that computes an **optimal solution**.
- bottom-up algo. makes optimal choices with

$$q = \max(q, P[i] + R[j - i])$$

step

- i.e. it chooses how many inches to cut right now
- log these choices in another array
- recall R[j] = maximum total price starting from j inches
- define S[j] = size of the first optimal cut starting from j inches
- need to update pseudocode to
 - create S
 - update S inside the loops
 - \triangleright at the end, backtrack S to compute a list of lengths

Rod Cutting Step 5 - Pseudocode

```
1: function CUT-ROD-SOLUTION(P[1..n])
2:
3:
4:
5:
67:
8:
9:
       Create arrays R[0..n] and S[0..n]
       R[0] = 0
       for j from 1 to n do
           q = -\infty
           for i from 1 to n do
               if q < (P[i] + R[j-1]) then
                   q = P[i] + R[j - i]
                  S[j] = i
10:
11:
12:
                 end if
             end for
             R[j] = q
13:
14:
         end for
         soln = empty list
15:
         i = n
16:
         while i > 0 do
17:
            soln.add(S[i])
18:
            j = j - S[j]
19:
20:
21:
22:
         end while
         reverse soln
         return soln
     end function
```

Analysis

- CUT-ROD-SOLUTION solves the rod cutting problem
 - it returns a list of cut-lengths, not a price
- analysis is actually straightforward
- time efficiency:
 - ▶ nested **for** loops: $\Theta(n^2)$
 - ▶ backtracking: **while** loop iterates at most n times $\Rightarrow \Theta(n)$ time
 - reverse soln: $\Theta(n)$
 - ▶ total $\Theta(n^2 + n + n) = \Theta(n^2)$ time
- ▶ space efficiency: R and S take $\Theta(n+n) = \Theta(n)$ space
- (same as the step-4 algorithms)