# 01. Algorithm Fundamentals CPSC 535 ∼ Spring 2019

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### **Problems**

Computational problem: definition of input and desired output

Each is a mathematical object that could be stored in a computer data structure.

#### Sorting problem

**input:** A sequence of *n* numbers  $\langle a_1, a_2, \dots, a_n \rangle$ .

**output:** A permutation (reordering)  $\langle a_1', a_2', \dots, a_n' \rangle$  of the input sequence such that  $a_1' \leq a_2' \leq \dots \leq a_n'$ .

# Algorithms

Instance (of a problem): Concrete input datum

#### Example

 $\langle 71, 14, 31, 2, 82 \rangle$ 

Algorithm: well-defined computational procedure that unerringly transforms input to output

#### Motivation

Why do we care about algorithms, or algorithmic efficiency?

- Algorithms are automating major parts of the economy: operations research, high frequency trading, machine learning, etc.
- Efficiency can mean the difference between computations being viable, sustainable, for human use versus impractical.
- ▶ The principle of not wasting product.
- Intriguing mathematical questions are worth studying in their own right.

#### Data Structures

Data Structure: method for storing, organizing data

- Data members e.g. head pointer, tail pointer
- Invariant(s) defining how the structure must be organized to remain valid, e.g. head points to first node, tail points to last node
- ▶ Defined *operations*, each operation is an algorithm that operates on the structure.

#### Pseudocode

Pseudocode: code-like notation for conveying algorithms

- Goal is clear communication to a human audience
- Not compiled, so no need to be syntactically perfect
- Not software engineering; no need for error checking, modularity, encapsulation, etc.

Algorithm implementer is a specific role and skill set, bridging the gap between scholarly pseudocode and industrial coding practices.

### Insertion Sort

```
1: function INSERTION-SORT(A)
       for j = 2 to A.length do
          key = A[i]
3:
          // Insert A[i] into the sorted sequence A[1 ... i-1].
4:
5:
          i = i - 1
          while i > 0 and A[i] > key do
6:
              A[i+1] = A[i]
7:
              i = i-1
8:
          end while
9:
          A[i+1] = key
10:
       end for
11:
12: end function
```

#### Pseudocode Observations

- Algorithm is a function/procedure, input is argument(s)
- No global variables
- Code-like but not compile-able code
- Arrays start at 1
- ▶ No error checking or modularity
- Translatable into practically any programming language

# **Analysis**

Analysis: establish how efficient an algorithm is

- Usually a mathematical proof (alternatively empirical evidence)
- Usually analyze for time spent (or disk I/O, space, energy, randomness, etc.)
- ▶ Usually summarize resource use by *order of growth* in asymptotic notation; O(n),  $\Theta(n^2)$ , etc.

### RAM model

Computational model: defines how a computer executes an algorithm, specifically enough to measure time (or other resources) Random Access Machine (RAM):

- "default" computational model, approximates a generic real-world CPU and memory
- CPU has instructions for integer arithmetic, floating point arithmetic, control (jump, call, return, if), logic (or, and, not), data copying.
- one step  $\equiv O(1)$  instructions; each pseudocode statement counts as 1 step (except function calls)
- ► CPU has some *O*(1) word size, e.g. 32 or 64 bit; one instruction is limited to writing that many bits
- $\triangleright$  cannot "cheat" by packing  $\Theta(n)$  information in one word

# Worst-Case Analysis

- ▶ In a time analysis, we need to prove how much time insertion sort takes when run
- depends on the type of input, e.g. pre-sorted, completely jumbled, in between
- convention: analyze the worst case for the algorithm at hand
- generous to skeptics, conservative for software engineers
- as an exception, sometimes analyze average case of deliberately randomized algorithms

Claim: The worst-case time complexity of insertion sort is  $\Theta(n^2)$ .

# Divide-and-conquer

- divide input into several smaller instances of the same problem (often, divide input in half)
- 2. "conquer" by recursively solving all the sub-problems; may involve a simple base case
- combine the many solutions into one coherent solution for the original problem

## Merge sort

Merge sort: classical sorting algorithm using divide-and-conquer

**divide:** chop list of n unsorted elements into two lists of n/2 elements each

**conquer:** merge-sort each unsorted list; if  $n \le 1$ , nothing to do **combine:** merge two sorted lists of n/2 elements, into one sorted

list of *n* elements

## Merge pseudocode

```
Ensure: A[p...r] is sorted

1: function MERGE-SORT(A, p, r)

2: if p < r then

3: q = \lfloor (p+r)/2 \rfloor

4: MERGE-SORT(A, p, q)

5: MERGE-SORT(A, q + 1, r)

6: MERGE(A, p, q, r)

7: end if

8: end function
```

```
Require: p \leq q < r, A[p \dots q] is sorted, A[q+1 \dots r] is sorted
Ensure: A[p \dots r] is sorted
1: function MERGE(A, p, q, r)
       n_1 = (q - p + 1), n_2 = (r - q)
       let L[1 \dots n_1 + 1] and R[1 \dots n_2 + 1] be new arrays
    L[1 \dots n_1] = A[p \dots q]
    R[1 ... n_2] = A[p + 1 ... q]
    L[n_1 + 1] = R[n_2 + 2] = \infty
      i = i = 1
       for k = p to r do
           if L[i] \leq R[j] then
10:
                 A[k] = L[i]
11:
12:
13:
                i = i + 1
            else
                A[k] = R[j]
14:
15:
                i = i + 1
             end if
         end for
      end function
```

## Merge sort analysis

The worst-case time complexity of merge sort is given by the recurrence relation

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1, \\ 2T(n/2) + \Theta(n) & \text{if } n > 1. \end{cases}$$

Claim:  $T \in \Theta(n \log n)$ 

Claim: Merge sort uses  $\Theta(n)$  extra space for L and R. (Observe that at most one merge is happening at any moment, and the largest merge uses n+2 extra array elements.)

## Insertion sort versus merge sort

Insertion sort:  $\Theta(n^2)$  time,  $\Theta(1)$  space

Merge sort:  $\Theta(n \log n)$  time,  $\Theta(n)$  space

Merge sort is subjectively more convoluted

Space vs. time tradeoff (typical)

Efficiency vs. convolution tradeoff (typical)

Refactoring convolution into algorithm design is usually a win

# Asymptotic notation

Asymptotic notation:  $\Theta(n^2)$ ,  $O(n^2)$ ,  $\Omega(n^2)$ , etc.

Solves some problems with algorithm analysis

- ▶ Whole point is how algorithms perform on very large *n*
- ightharpoonup ignore small n
- We count abstract "steps" so constant factors are not meaningful
- ▶ i.e.  $4n^2$  and  $5n^2$  should count as essentially the same
- ► Want to prioritize speeding up the part of the algorithm that actually accounts for the most time
- Running time functions usually include multiple terms; the asymptotically fastest-growing term dominates the running time

### Example: insertion sort

Suppose insertion sort's run time is

$$T(n) = (\text{inner loop steps}) + (\text{outer loop steps}) + (\text{outside loop})$$
  
=  $3n^2 + 4n + 1$ 

Let n=2,

$$T(n) = 3(2)^2 + 4(2) + 1 = 12 + 8 + 1 = 21.$$

Let n = 1,000,

$$T(n) = 3(1,000)^2 + 4(1,000) + 1 = 3,000,000 + 4,000 + 1.$$

⇒ inner loop dominates time, focus on speeding that up

### Θ notation

"big-theta": intuitively,

$$\Theta(g(n)) = \{f(n) : f(n) \text{ grows asymptotically the same as } g(n)\}$$

Formally,

$$\Theta(g(n)) = \{f(n) : \exists \text{ positive constants } c_1, c_2, n_0 \\ \text{such that } 0 \le c_1 g(n) \le f(n) \le c_2 g(n) \quad \forall n \ge n_0 \}.$$

This is set notation, so e.g.

$$3n^2+4n+1\in\Theta(n^2).$$

 $\Theta$ -notation indicates a *tight bound*: set of functions upper- and lower-bounded by g(n)

## $O, \Omega, o, \text{ and } \omega$

Intuitively,

▶ "big-oh":

$$O(g(n)) = \{f(n) : f(n) \text{ grows asymptotically } \leq g(n)\}$$

▶ "big-omega":

$$\Omega(g(n)) = \{f(n) : f(n) \text{ grows asymptotically } \geq g(n)\}$$

▶ "little-oh":

$$o(g(n)) = \{f(n) : f(n) \text{ grows asymptotically } \langle g(n) \rangle$$

▶ "little-omega":

$$\omega(g(n)) = \{f(n) : f(n) \text{ grows asymptotically } > g(n)\}$$

## Knuth-style notation abuse

An asymptotic notation expression such a  $O(n^2)$  is, technically, a **set** of function objects

⇒ a run-time function may be an **element** of one of these sets

Mathematically precise:

$$3n^2 + 4n + 1 \in O(n^2).$$

Some others (notably Knuth) abuse notation to use =, which is technically incorrect since the operands are different types, but is arguably more readable:

$$3n^2 + 4n + 1 = O(n^2).$$