

# 01. Algorithm Fundamentals

CPSC 535 ~ Spring 2019

Kevin A. Wortman

California State University, Fullerton

January 27, 2019

# Problems

*Computational problem:* definition of output and desired output

Each is a mathematical object that could be stored in a computer data structure.

## Sorting problem

**input:** A sequence of  $n$  numbers  $\langle a_1, a_2, \dots, a_n \rangle$ .

**output:** A permutation (reordering)  $\langle a'_1, a'_2, \dots, a'_n \rangle$  of the input sequence such that  $a'_1 \leq a'_2 \leq \dots \leq a'_n$ .

# Algorithms

*Instance (of a problem):* Concrete input datum

## Example

$\langle 71, 14, 31, 2, 82 \rangle$

*Algorithm:* well-defined computational procedure that unerringly transforms input to output

# Motivation

Why do we care about algorithms, or algorithmic efficiency?

- ▶ Algorithms are automating major parts of the economy: operations research, high frequency trading, machine learning, etc.
- ▶ Efficiency can mean the difference between computations being viable, sustainable, for human use versus impractical.
- ▶ The principle of not wasting product.
- ▶ Intriguing mathematical questions are worth studying in their own right.

# Data Structures

*Data Structure*: method for storing, organizing data

- ▶ Data members e.g. head pointer, tail pointer
- ▶ *Invariant(s)* defining how the structure must be organized to remain valid, e.g. head points to first node, tail points to last node
- ▶ Defined *operations*, each operation is an algorithm that operates on the structure.

# Pseudocode

*Pseudocode*: code-like notation for conveying algorithms

- ▶ Goal is clear communication to a human audience
- ▶ Not compiled, so no need to be syntactically perfect
- ▶ Not software engineering; no need for error checking, modularity, encapsulation, etc.

*Algorithm implementer* is a specific role and skill set, bridging the gap between scholarly pseudocode and industrial coding practices.

## Insertion Sort

```
1: function INSERTION-SORT(A)
2:   for  $j = 2$  to  $A.length$  do
3:      $key = A[j]$ 
4:     // Insert  $A[j]$  into the sorted sequence  $A[1 \dots j-1]$ .
5:      $i = j - 1$ 
6:     while  $i > 0$  and  $A[i] > key$  do
7:        $A[i+1] = A[i]$ 
8:        $i = i-1$ 
9:     end while
10:     $A[i+1] = key$ 
11:  end for
12: end function
```

## Pseudocode Observations

- ▶ Algorithm is a function/procedure, input is argument(s)
- ▶ No global variables
- ▶ Code-like but not compile-able code
- ▶ Arrays start at 1
- ▶ No error checking or modularity
- ▶ Translatable into practically any programming language



# Analysis

*Analysis:* establish how efficient an algorithm is

- ▶ Usually a mathematical proof (alternatively empirical evidence)
- ▶ Usually analyze for time spent (or disk I/O, space, energy, randomness, etc.)
- ▶ Usually summarize resource use by *order of growth* in asymptotic notation;  $O(n)$ ,  $\Theta(n^2)$ , etc.

## RAM model

*Computational model:* defines how a computer executes an algorithm, specifically enough to measure time (or other resources)

*Random Access Machine (RAM):*

- ▶ "default" computational model, approximates a generic real-world CPU and memory
- ▶ CPU has instructions for integer arithmetic, floating point arithmetic, control (jump, call, return, if), logic (or, and, not), data copying.
- ▶ one step  $\equiv O(1)$  instructions; each pseudocode statement counts as 1 step (except function calls)
- ▶ CPU has some  $O(1)$  word size, e.g. 32 or 64 bit; one instruction is limited to writing that many bits
- ▶ cannot "cheat" by packing  $\Theta(n)$  information in one word

## Worst-Case Analysis

- ▶ In a time analysis, we need to prove how much time insertion sort takes when run
- ▶ depends on the type of input, e.g. pre-sorted, completely jumbled, in between
- ▶ convention: analyze the *worst case* for the algorithm at hand
- ▶ generous to skeptics, conservative for software engineers
- ▶ as an exception, sometimes analyze *average case* of deliberately randomized algorithms

*Claim:* The worst-case time complexity of insertion sort is  $\Theta(n^2)$ .

# Divide-and-conquer

1. **divide** input into several smaller instances of the same problem (often, divide input in half)
2. **"conquer"** by recursively solving all the sub-problems; may involve a simple base case
3. **combine** the many solutions into one coherent solution for the original problem

# Merge sort

*Merge sort*: classical sorting algorithm using divide-and-conquer

**divide:** chop list of  $n$  unsorted elements into two lists of  $n/2$  elements each

**conquer:** merge-sort each unsorted list; if  $n \leq 1$ , nothing to do

**combine:** *merge* two sorted lists of  $n/2$  elements, into one sorted list of  $n$  elements

# Merge pseudocode

**Ensure:**  $A[p \dots r]$  is sorted

```

1: function MERGE-SORT( $A, p, r$ )
2:   if  $p < r$  then
3:      $q = \lfloor (p + r) / 2 \rfloor$ 
4:     MERGE-SORT( $A, p, q$ )
5:     MERGE-SORT( $A, q + 1, r$ )
6:     MERGE( $A, p, q, r$ )
7:   end if

```

**Require:**  $p \leq q < r$ ,  $A[p \dots q]$  is sorted,  $A[q + 1 \dots r]$  is sorted

**Ensure:**  $A[p \dots r]$  is sorted

```

1: function MERGE( $A, p, q, r$ )
2:    $n_1 = (q - p + 1)$ ,  $n_2 = (r - q)$ 
3:   let  $L[1 \dots n_1 + 1]$  and  $R[1 \dots n_2 + 1]$  be new arrays
4:    $L[1 \dots n_1] = A[p \dots q]$ 
5:    $R[1 \dots n_2] = A[q + 1 \dots r]$ 
6:    $L[n_1 + 1] = R[n_2 + 1] = \infty$ 
7:    $i = j = 1$ 
8:   for  $k = p$  to  $r$  do
9:     if  $L[i] \leq R[j]$  then
10:       $A[k] = L[i]$ 
11:       $i = i + 1$ 
12:     else
13:       $A[k] = R[j]$ 
14:       $j = j + 1$ 
15:     end if
16:   end for

```

## Merge sort analysis

The worst-case time complexity of merge sort is given by the *recurrence relation*

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1, \\ 2T(n/2) + \Theta(n) & \text{if } n > 1. \end{cases}$$

*Claim:*  $T \in \Theta(n \log n)$

*Claim:* Merge sort uses  $\Theta(n)$  extra space for  $L$  and  $R$ . (Observe that at most one merge is happening at any moment, and the largest merge uses  $n + 2$  extra array elements.)

## Insertion sort versus merge sort

Insertion sort:  $\Theta(n^2)$  time,  $\Theta(1)$  space

Merge sort:  $\Theta(n \log n)$  time,  $\Theta(n)$  space

Merge sort is subjectively more convoluted

Space vs. time tradeoff (typical)

Efficiency vs. convolution tradeoff (typical)

Refactoring convolution into algorithm design is usually a win