



Procesamiento de series de tiempo en **GRASS GIS**

Aplicaciones en Ecología y Ambiente

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GRASS

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Mgter. en Aplicaciones Espaciales de Alerta y
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Aplicaciones de RS & GIS en Ecología

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Disease Ecology, Rodents, Hantavirus

GRASS GIS Dev Team

OSGeo Charter member

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Introduction to **GRASS GIS**



Brief intro to FOSS



Free and Open Source Software (FOSS) means that anyone is freely licensed to use, copy, study, and change the software. The source code is openly shared so that people are encouraged to voluntarily improve it.

Brief intro to OSGeo

The OSGeo Foundation was created in 2006, to support the collaborative development of open source geospatial software, and promote its widespread use.



Brief intro to OSGeo

- Projects should manage themselves, striving for consensus and encouraging participation from all contributors.
- Contributors are the scarce resource and successful projects court and encourage them.
- Projects are encouraged to adopt open standards and collaborate with other OSGeo projects.
- Projects are responsible for reviewing and controlling their code bases to assure integrity.



GRASS GIS

GRASS GIS: Brief history

- **GRASS GIS** (Geographic Resources Analysis Support System), is a FOSS GIS software suite used for geospatial data management and analysis, image processing, graphics and maps production, spatial modeling, and visualization.
- Used in academic and commercial settings around the world, as well as by many governmental agencies and consulting companies.
- Originally developed by the U.S. Army Construction Engineering Research Laboratories as a tool for land management and environmental planning by the military (USA-CERL, 1982-1995).



A bit of (geek) GRASS GIS history...



Advantages

- open source, you can use, modify, improve, share
- strong user community, commercial support
- large amount of tools for 2D/3D raster/vector, topology, imagery, spatio-temporal data
- both GUI and CLI (easy for scripting) interface
- Python API and libraries

Disadvantages

- complicated startup for newcomers
- native format (requires importing data, be aware of the possibility of linking external formats)
- vector topology (confusing for GIS beginners, sometimes tricky to import broken GIS data)

When to use GRASS GIS?

- doing (heavy) geospatial data analysis
- working with topological vector data
- analysing space-time datasets
- doing Python scripting
- deploying server-side applications (e.g. as WPS process)

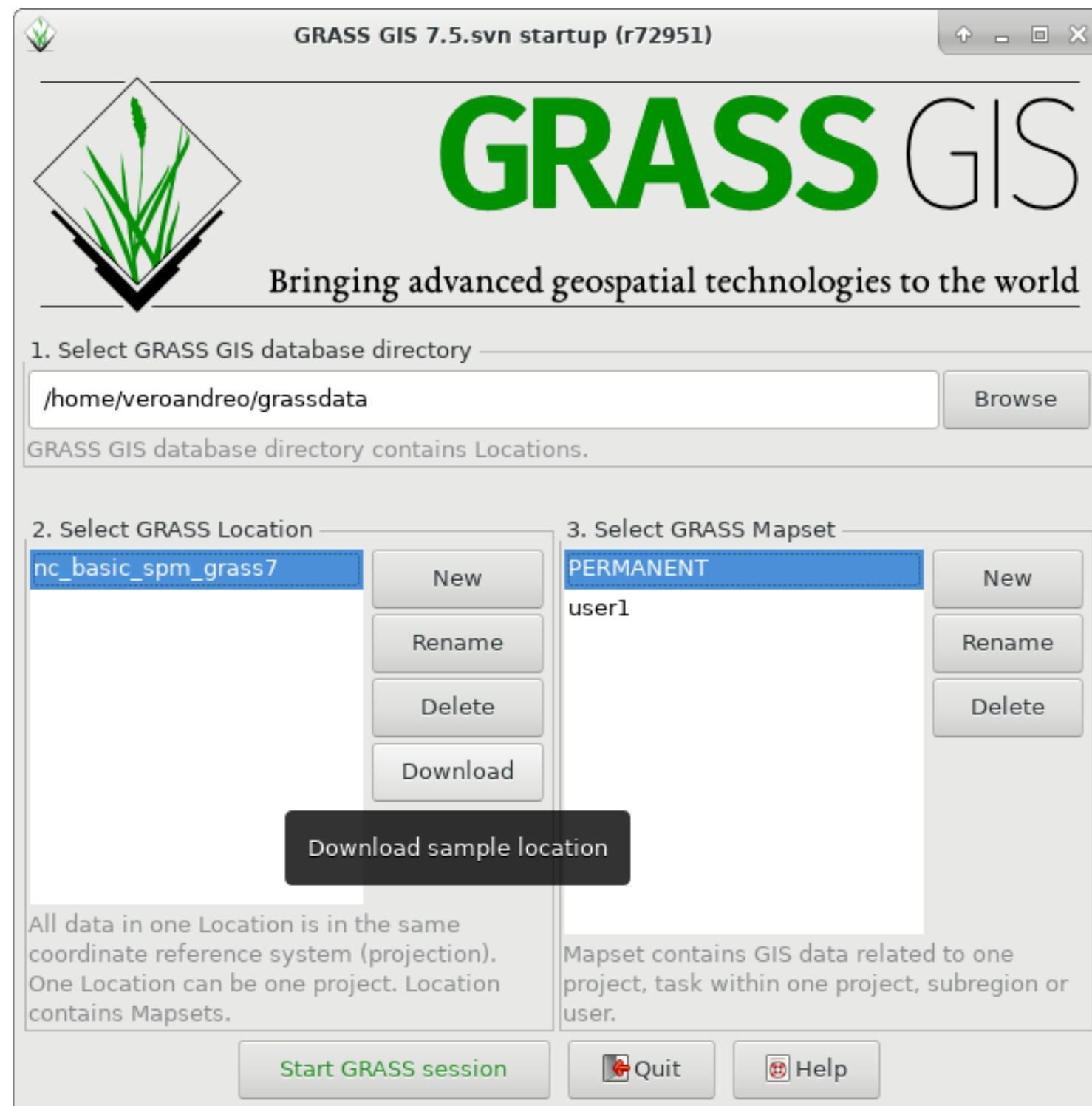
When to use rather something else?

- want to visualize geodata in easy and quick way (use QGIS instead)
- scared of location and mapsets :-)



Working with GRASS GIS is not much
different than any other GIS...

Well, except for this...



Basic notions



GRASS GIS

Basic notions

- The **GRASS DATABASE** (or "GISDBASE") is an existing directory containing all GRASS GIS LOCATIONS.

GRASS
GIS

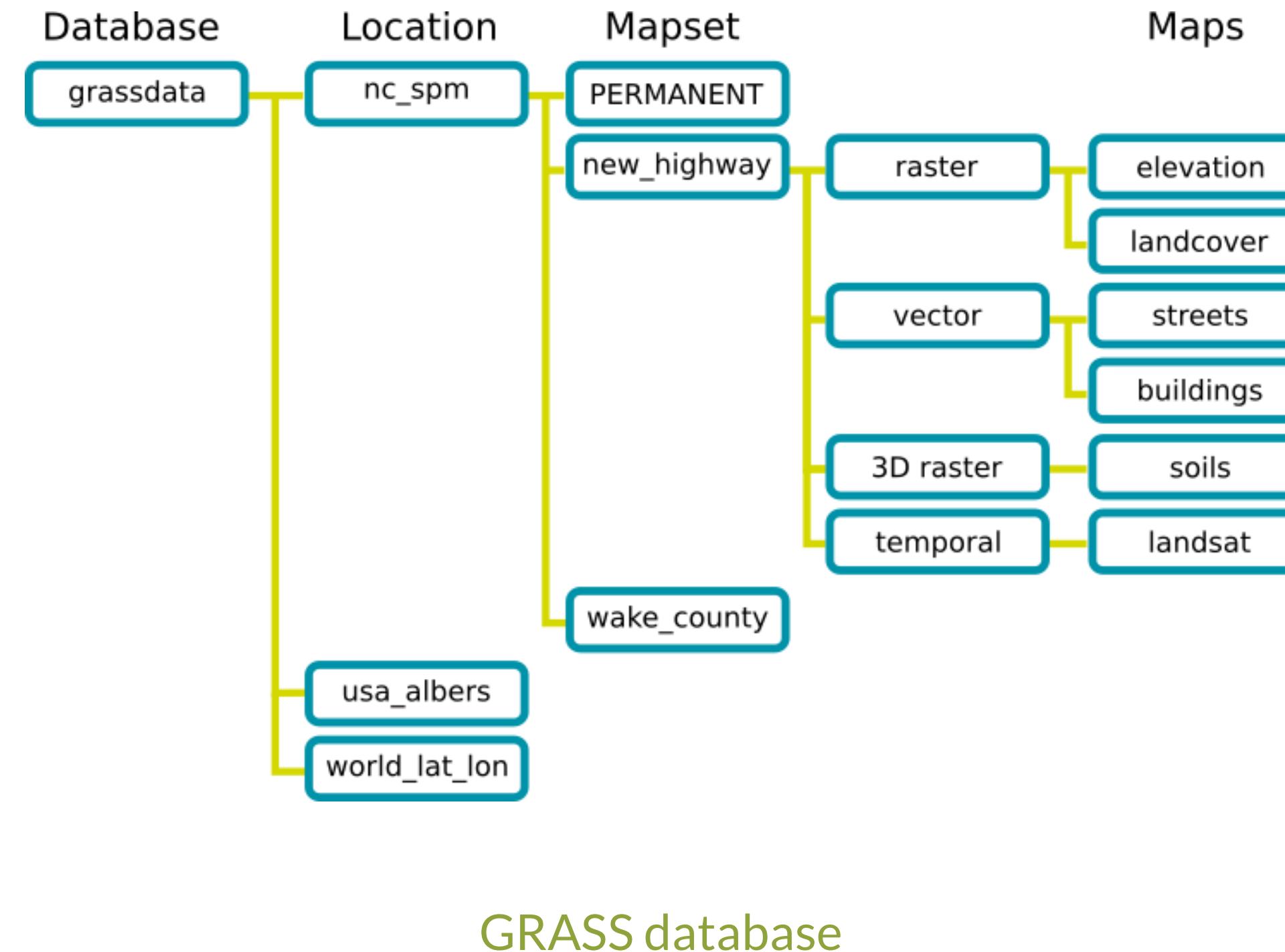
Basic notions

- The **GRASS DATABASE** (or "GISDBASE") is an existing directory containing all GRASS GIS LOCATIONS.
- A **LOCATION** is defined by its coordinate system, map projection and geographical boundaries.

Basic notions

- The **GRASS DATABASE** (or "GISDBASE") is an existing directory containing all GRASS GIS LOCATIONS.
- A **LOCATION** is defined by its coordinate system, map projection and geographical boundaries.
- **MAPSET** is a subdirectory within Locations. In a MAPSET you can organize GIS maps thematically, geographically, by project or however you prefer.

When GRASS GIS is started, it connects to the Database, Location and Mapset specified by the user



GRASS
GIS

- Why this structure?
 - GRASS GIS has a *native format* for raster and vector data, therefore they must be *imported* or *linked* into a GRASS Location/Mapset (see `r.external` for example).

- What are the advantages?
 - GRASS DATABASE, LOCATIONs and MAPSETs are folders that *can be easily shared with other users.*
 - The GRASS DATABASE can be *local or remote*, and *special permissions* can be set to specific mapsets in a LOCATION.
 - All data in a LOCATION have necessarily the *same CRS.*

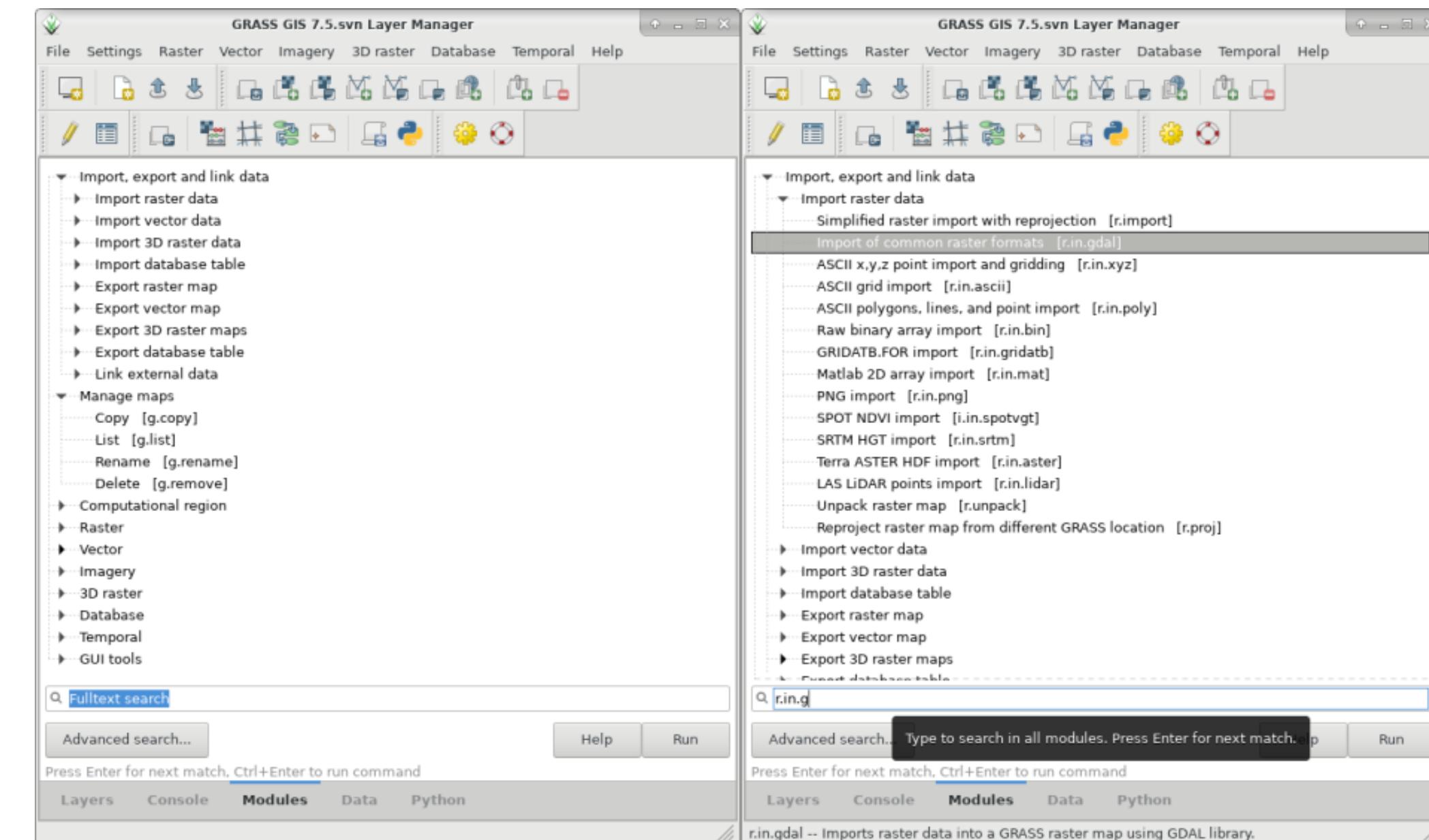
Data types in GRASS GIS

- Raster (including satellite imagery)
- 3D raster or voxel
- Vector: point, line, boundary, area, face
- Space-time datasets: collections of raster (**STRDS**), raster 3D (**STR3DS**) or vector (**STVDS**) maps

Modules

More than 500 modules but well structured:

Prefix	Function class	Type of command	Example
g.*	general	general data management	g.rename: renames map
d.*	display	graphical output	d.rast: display raster map
r.*	raster	raster processing	r.mapcalc: map algebra
v.*	vector	vector processing	v.clean: topological cleaning
i.*	imagery	imagery processing	i.pca: Principal Components Analysis on imagery group
r3.*	voxel	3D raster processing	r3.stats: voxel statistics
db.*	database	database management	db.select: select value(s) from table
ps.*	postscript	PostScript map creation	ps.map: PostScript map creation
t.*	temporal	space-time datasets	t.rast.aggregate: raster time series aggregation



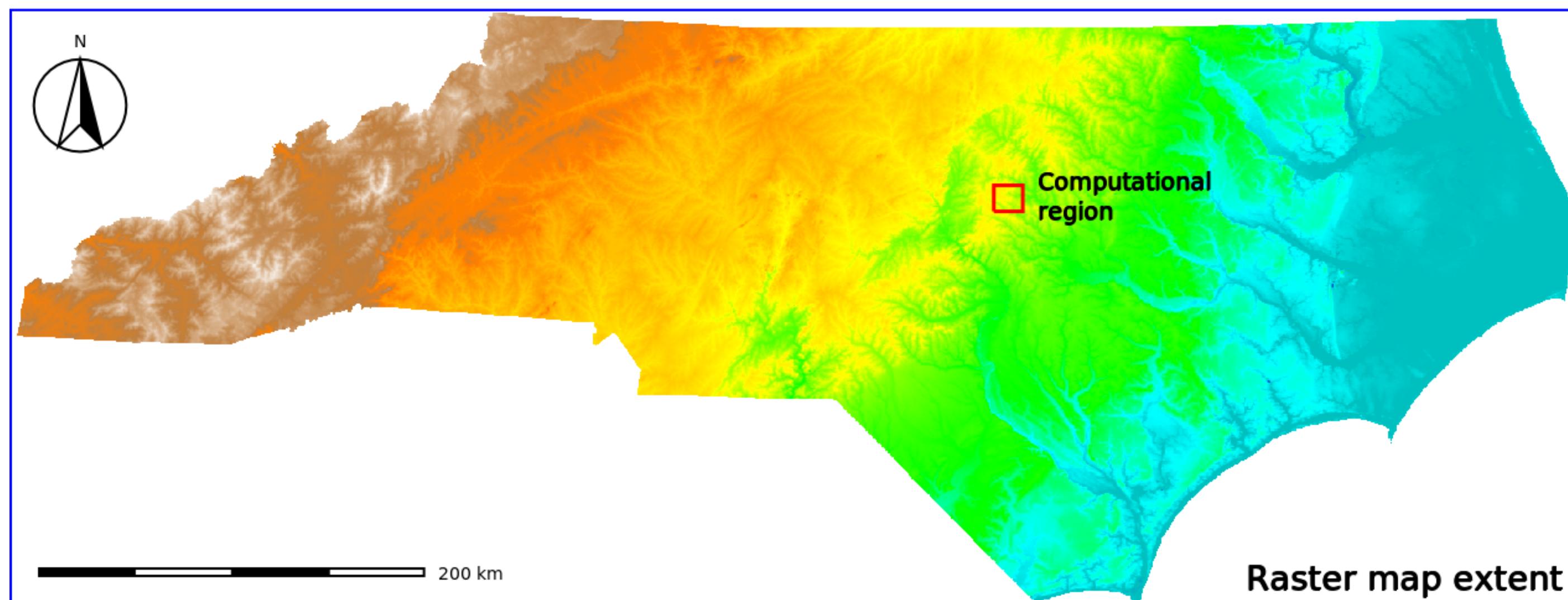
Module tree and module search engine

Add-ons

Plugins or **Add-ons** can be installed from a centralized **OSGeo repository** or from github (or similar repositories) using **g.extension** command.

```
# install extension from GRASS GIS Add-on repository  
g.extension extension=r.hants  
  
# install extension from github repository  
g.extension extension=r.in.sos \  
url=https://github.com/pesekon2/GRASS-GIS-SOS-tools/tree/master/sos/
```

Computational region





The **computational region** is the *actual setting of the region boundaries and the actual raster resolution*.

The **computational region** can be set and changed by means of `g.region` to the extent of a vector map, a raster map or manually to some area of interest.

Output raster maps will have their extent and resolution equal to those of the current computational region, while vector maps are always considered in their original extent.

Computational region

- Which are the advantages?
 - Keep your results consistent
 - Avoid clipping maps prior to subarea analysis
 - Test an algorithm or computationally demanding process in small areas
 - Fine-tune the settings of a certain module
 - Run different processes in different areas

More details at the [Computational region wiki](#)



GRASS

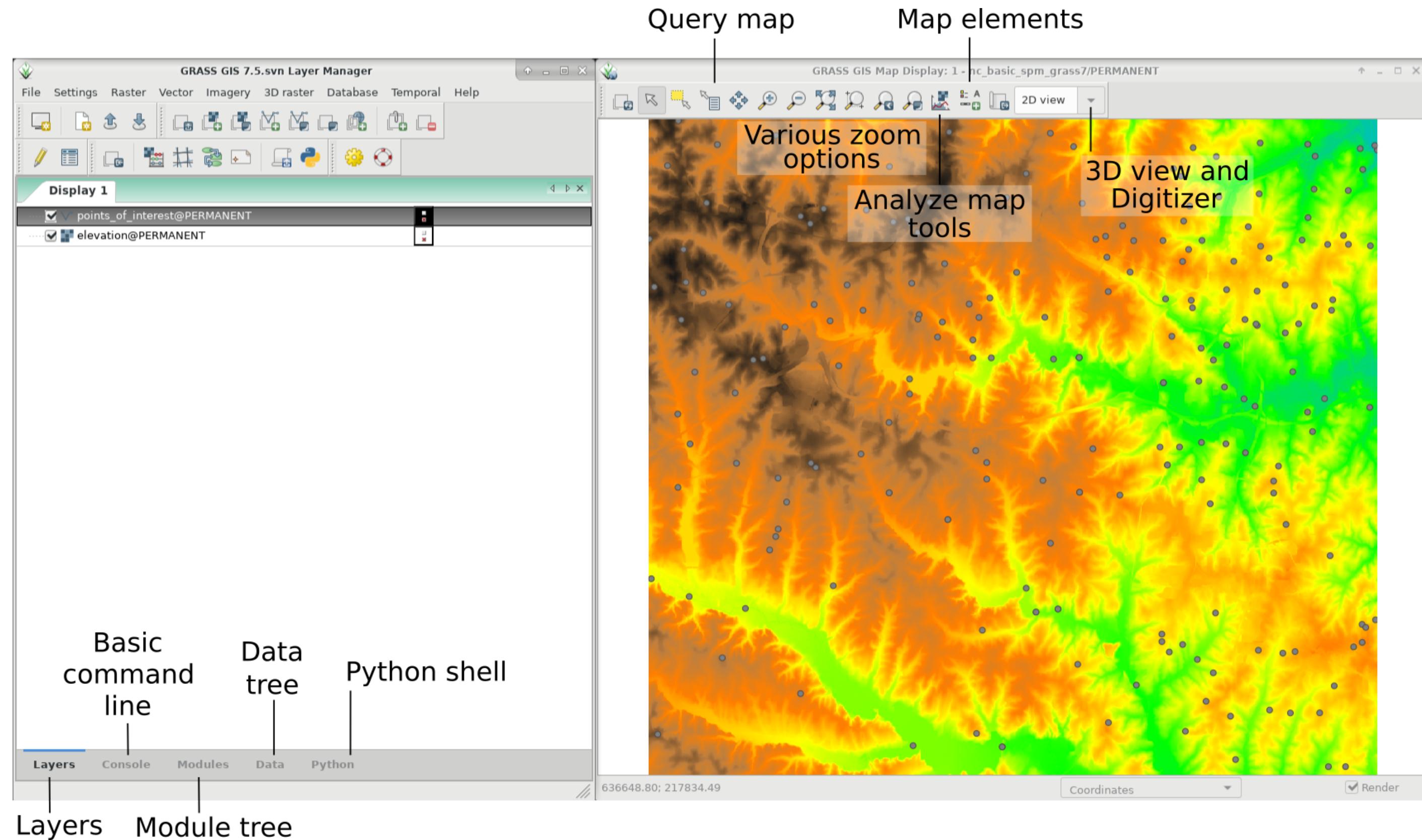
GIS

Interfaces

GRASS GIS offers different interfaces for the interaction between user and software.

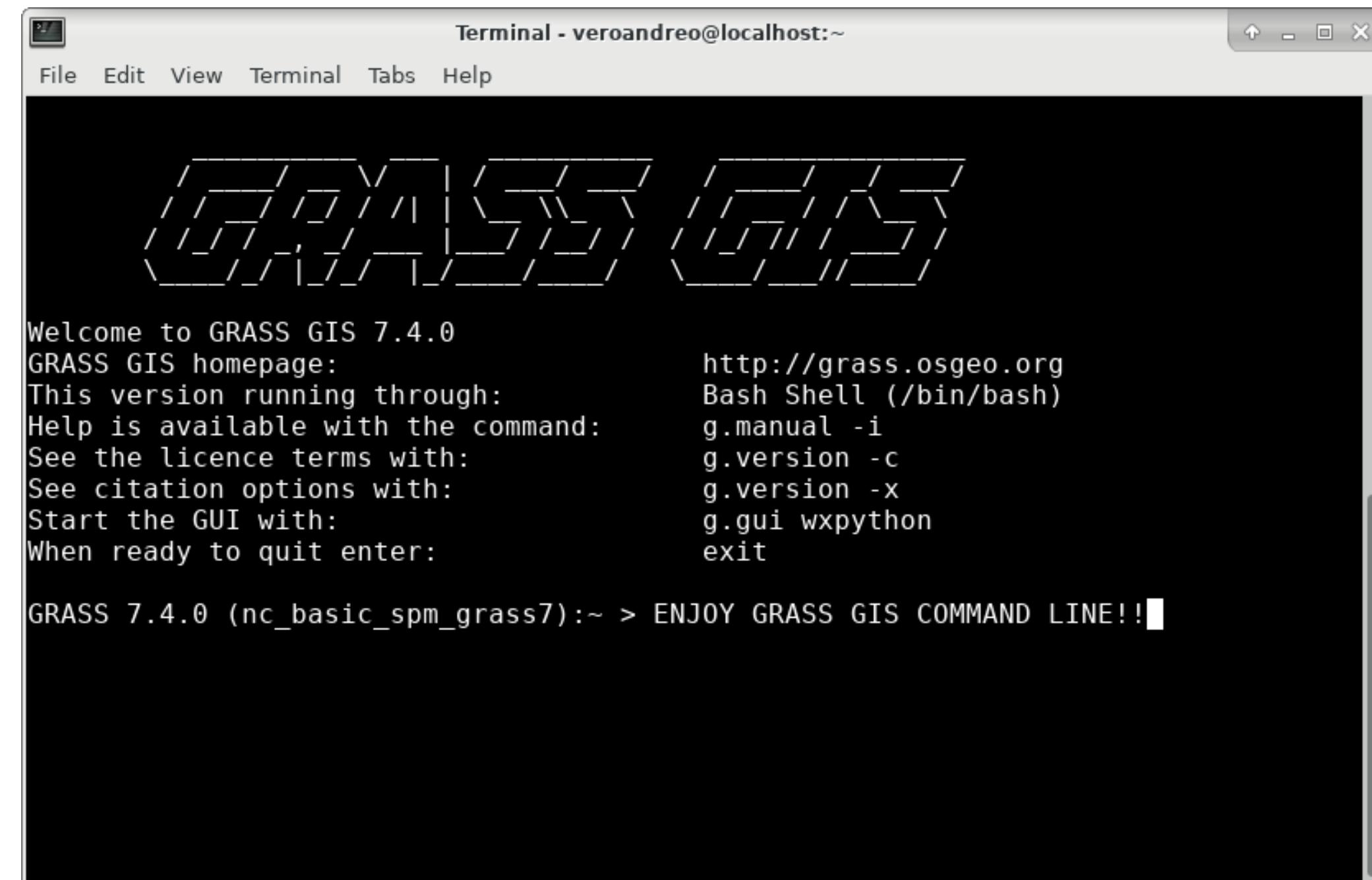
Let's see them!

Graphical User Interface (GUI)



Command line

The most powerful way to use GRASS GIS!!



Advantages of the command line

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- Run `history` to see all your previous commands

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- Search in history with `CTRL-R`

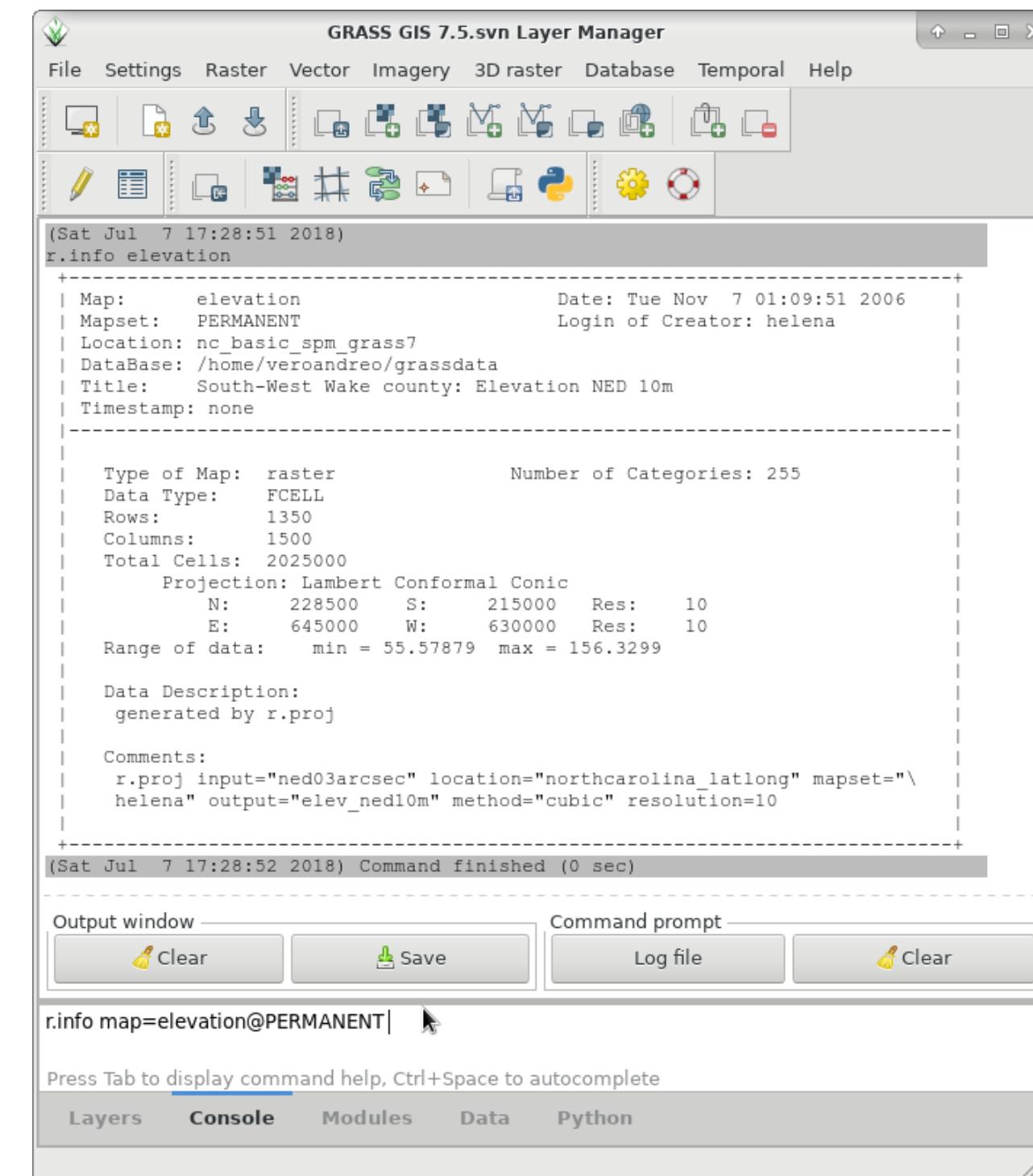
Advantages of the command line

- Run `history` to see all your previous commands
- History is stored individually per MAPSET
- Search in history with `CTRL-R`
- Save the commands to a file: `history > my_protocol.sh`, polish/annotate the protocol and re-run with: `sh my_protocol.sh`

Advantages of the command line

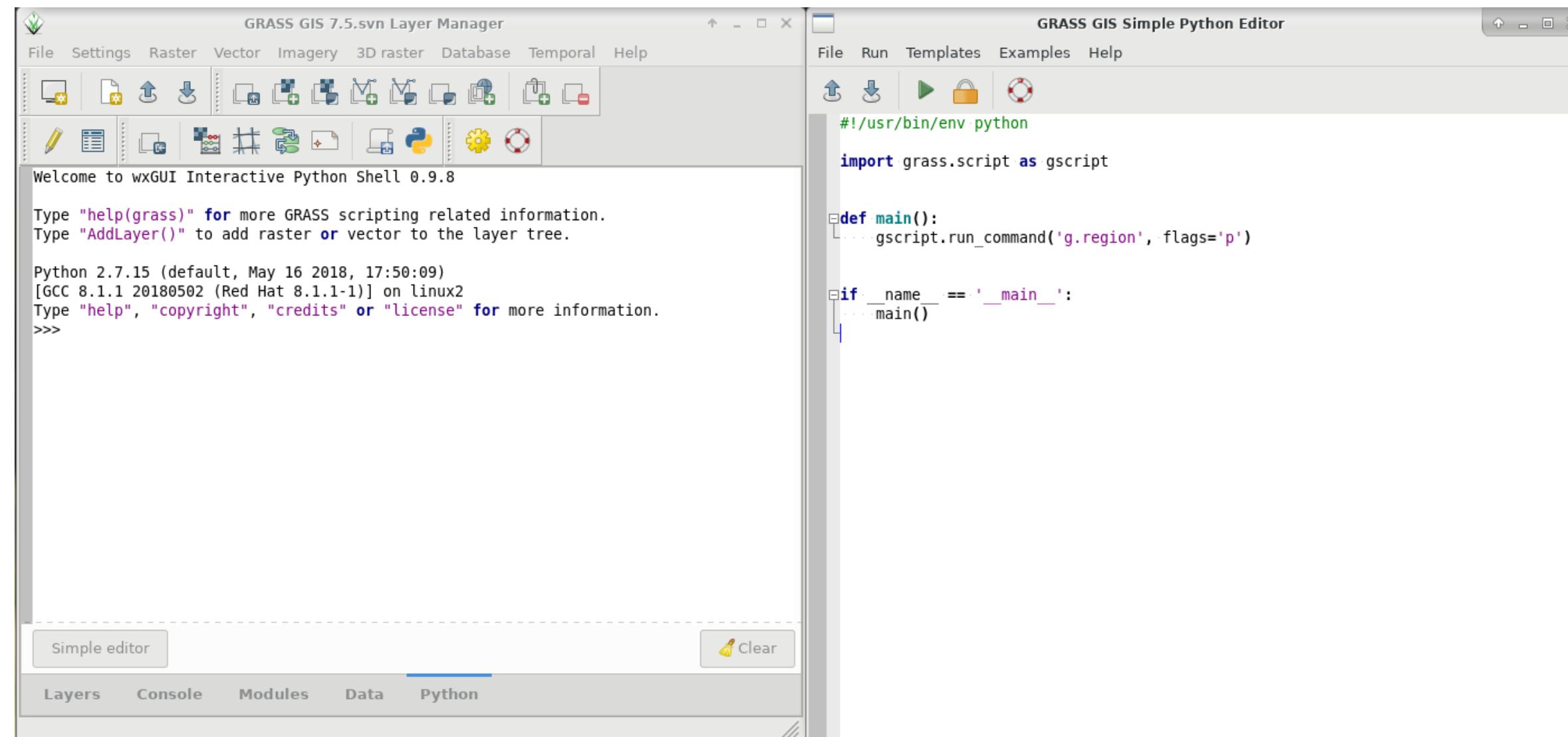
- Run `history` to see all your previous commands
- History is stored individually per MAPSET
- Search in history with `CTRL-R`
- Save the commands to a file: `history > my_protocol.sh`, polish/annotate the protocol and re-run with: `sh my_protocol.sh`
- Call module's GUI and "Copy" the command for further replication

The GUI's simplified command line offers a *Log file* button to save the history to a file



Python

The simplest way to execute a Python script is through
the *Simple Python editor*



... or write your Python script in your favorite editor
and run it:

```
#!/usr/bin/env python

# simple example for pyGRASS usage: raster processing via modules approach
from grass.pygrass.modules.shortcuts import general as g
from grass.pygrass.modules.shortcuts import raster as r
g.message("Filter elevation map by a threshold...")

# set computational region
input = 'elevation'
g.region(raster=input)
output = 'elev_100m'
thresh = 100.0

r.mapcalc("%s = if(%s > %d, %s, null())" % (output, input, thresh, input))
r.colors(map=output, color="elevation")
```

```
#!/usr/bin/env python

# Markus Neteler, 2018
#
# based on
# https://grasswiki.osgeo.org/wiki/Working_with_GRASS_without_starting_
#
# Requirements:
#           'sudo pip install grass-session'

# define where to process the data in the temporary grass-session
mygisdb = '/tmp/grassdata'
mylocation = 'world'
mymapset = 'user'

# the next line starts the GRASS GIS session
from grass_session import Session
```

Credits: Pietro Zambelli. See [grass-session GitHub](#) for further details.



```
mylocation = 'world'
mymapset = 'user'

# the next line starts the GRASS GIS session
from grass_session import Session

# import some convenient GRASS GIS Python API parts
from grass.script import core as gcore
import grass.script as gscript
import grass.script.setup as gsetup
# import grass python libraries
from grass.pygrass.modules.shortcuts import general as g

from grass.pygrass.modules.shortcuts import raster as r
from grass.pygrass.modules.shortcuts import vector as v
from grass.pygrass.modules.shortcuts import temporal as t

# set some common environmental variables, like for raster compression
import os
```

Import libraries

Credits: Pietro Zambelli. See [grass-session GitHub](#) for further details.

```
# needs G75:          GRASS_COMPRESSOR='ZSTD'))\n\n# create a PERMANENT mapset; create a Session instance\nPERMANENT = Session()\n# hint: EPSG code lookup: https://epsg.io\nPERMANENT.open(gisdb=mygisdb, location=mylocation,\n                create_opts='EPSG:4326')\n\n# exit from PERMANENT right away in order to perform analysis in our own mapset\nPERMANENT.close()\n\n# create a new mapset in the same location\nuser = Session()\nuser.open(gisdb=mygisdb, location=mylocation, mapset=mymapset,\n          create_opts='')
```

Create Location and Mapset

Credits: Pietro Zambelli. See [grass-session GitHub](#) for further details.

```
# execute some command inside user mapset

# import admin0 vector data - it downloads and imports including topology
# Data source: https://www.naturalearthdata.com/downloads/10m-cultural-vectors/10m-admin-0-countries
# VSI driver for remote access: http://www.gdal.org/gdal_virtual_file.html
inputfile = "/vsizip/vsicurl/https://www.naturalearthdata.com/http//www.naturalearthdata.com/gis/data/cultural/ne_10m_admin_0_countries.zip"

# note the pythonic underscore
v.in_ogr(input=inputfile, output="countries", overwrite = True)

# show the attribute column names
v.info(map="countries", flags="c")

# list vector maps available in the current mapset
g.list(type="vector", flags="m")

# now do analysis with the map...
```

Run modules

Credits: Pietro Zambelli. See [grass-session GitHub](#) for further details.

```
# import admin0 vector data - it downloads and imports including topology
#   Data source: https://www.naturalearthdata.com/downloads/10m-cultural-vectors/10m-administrative-vector-data.json
#   VSI driver for remote access: http://www.gdal.org/gdal_virtual_file.html
inputfile = "/vsizip/vsicurl/https://www.naturalearthdata.com/http//www.naturalearthdata.com/json/admin0.zip"

# note the pythonic underscore
v.in_ogr(input=inputfile, output="countries", overwrite = True)

# show the attribute column names
v.info(map="countries", flags="c")

# list vector maps available in the current mapset
g.list(type="vector", flags="m")

# now do analysis with the map...

# exit from user mapset (the data will remain)
user_close()
```

Clean and close

Credits: Pietro Zambelli. See [grass-session GitHub](#) for further details.

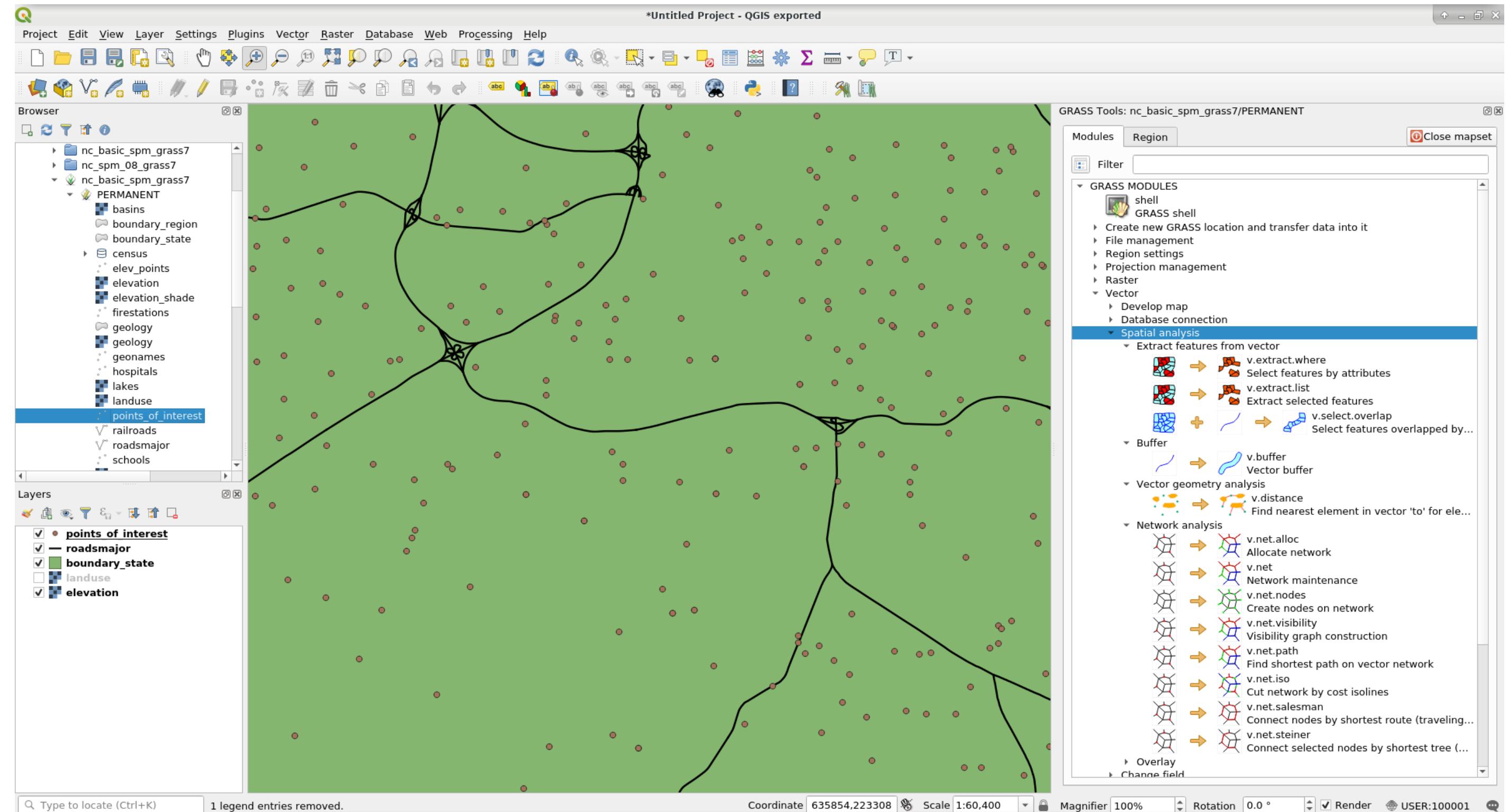


GRASS GIS

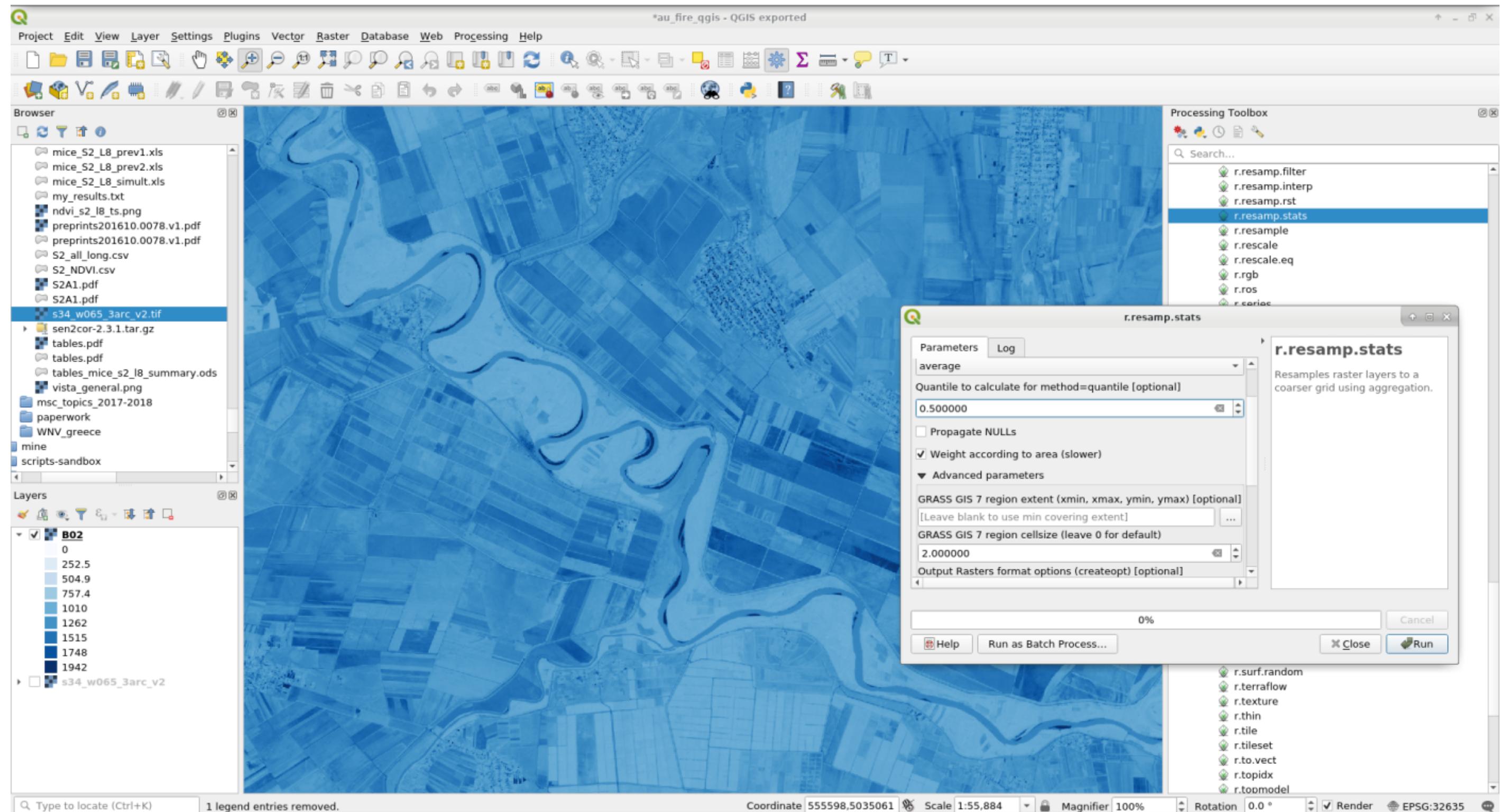
QGIS

There are two ways to use GRASS GIS functionalities within QGIS:

- GRASS GIS plugin
- Processing toolbox



Using GRASS GIS modules through the GRASS Plugin in QGIS



Using GRASS GIS modules through the Processing Toolbox



R + rgrass7

GRASS GIS and R can be used together in two ways:

- Using R within a GRASS GIS session,
- Using GRASS GIS within an R session,

Details and examples at the [GRASS and R wiki](#)



Welcome to GRASS GIS 7.4.0
 GRASS GIS homepage: <http://grass.osgeo.org>
 This version running through: Bash Shell (/bin/bash)
 Help is available with the command: g.manual -i
 See the licence terms with: g.version -c
 See citation options with: g.version -x
 Start the GUI with: g.gui wxpython
 When ready to quit enter: exit

```
GRASS 7.4.0 (nc_basic_spm_grass7):~ > R
R version 3.5.0 (2018-04-23) -- "Joy in Playing"
Copyright (C) 2018 The R Foundation for Statistical Computing
Platform: x86_64-redhat-linux-gnu (64-bit)

R is free software and comes with ABSOLUTELY NO WARRANTY.
You are welcome to redistribute it under certain conditions.
Type 'license()' or 'licence()' for distribution details.

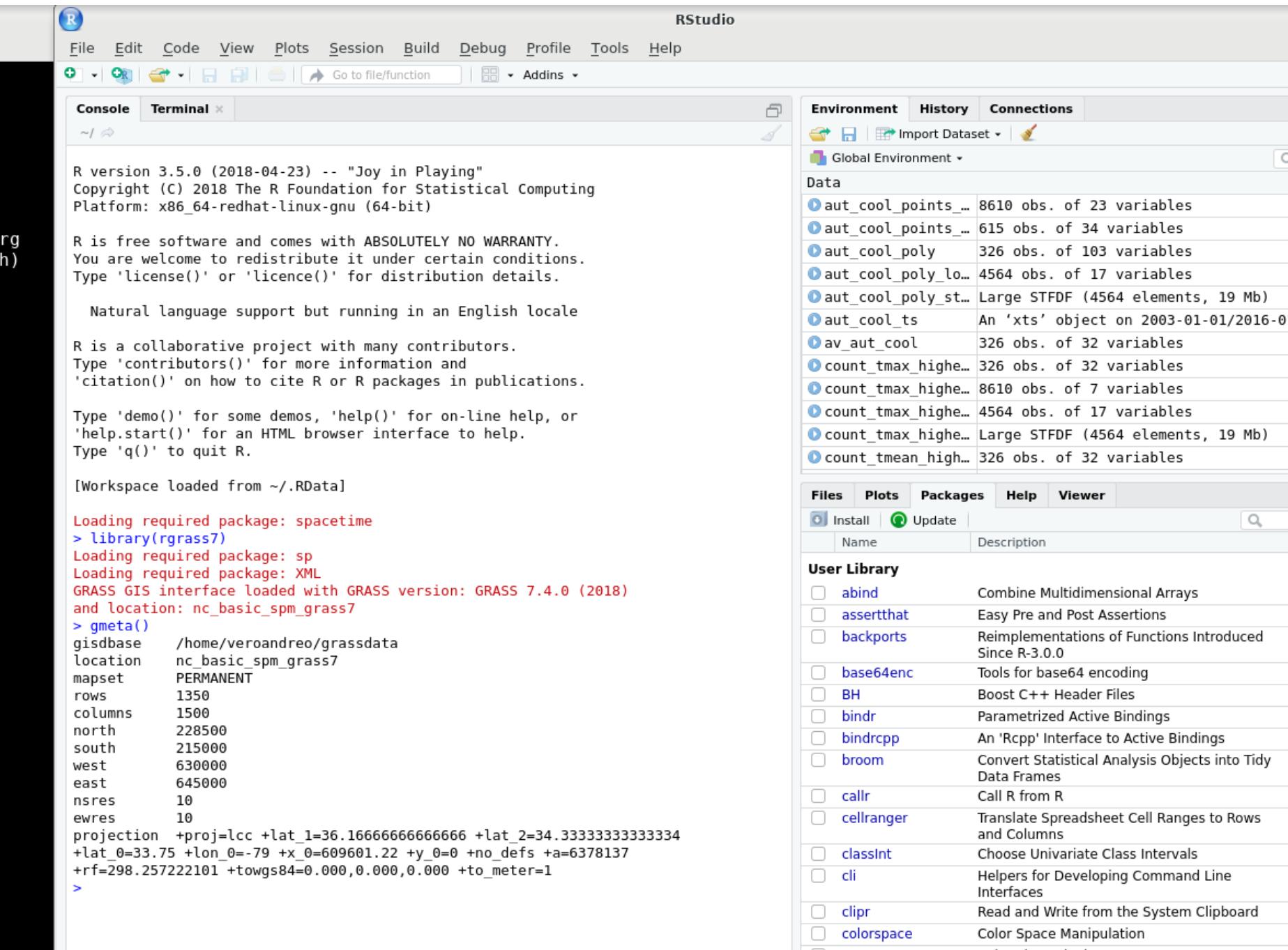
  Natural language support but running in an English locale

R is a collaborative project with many contributors.
Type 'contributors()' for more information and
'citation()' on how to cite R or R packages in publications.

Type 'demo()' for some demos, 'help()' for on-line help, or
'help.start()' for an HTML browser interface to help.
Type 'q()' to quit R.

[Workspace loaded from ~/.RData]

Loading required package: spacetime
> library(rgrass7)
Loading required package: sp
Loading required package: XML
GRASS GIS interface loaded with GRASS version: GRASS 7.4.0 (2018)
and location: nc_basic_spm_grass7
> gmeta()
gisdbase    /home/veroandreo/grassdata
location    nc_basic_spm_grass7
mapset      PERMANENT
rows        1350
columns     1500
north       228500
south       215000
west        630000
east        645000
nsres       10
ewres       10
projection +proj=lcc +lat_1=36.16666666666666 +lat_2=34.33333333333334
+lat_0=33.75 +lon_0=-79 +x_0=609601.22 +y_0=0 +no_defs +a=6378137
+rff=298.257222101 +towgs84=0.000,0.000,0.000 +to_meter=1
>
```



R version 3.5.0 (2018-04-23) -- "Joy in Playing"
 Copyright (C) 2018 The R Foundation for Statistical Computing
 Platform: x86_64-redhat-linux-gnu (64-bit)

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 Loading required package: XML
 GRASS GIS interface loaded with GRASS version: GRASS 7.4.0 (2018)
 and location: nc_basic_spm_grass7
 > gmeta()
 gisdbase /home/veroandreo/grassdata
 location nc_basic_spm_grass7
 mapset PERMANENT
 rows 1350
 columns 1500
 north 228500
 south 215000
 west 630000
 east 645000
 nsres 10
 ewres 10
 projection +proj=lcc +lat_1=36.16666666666666 +lat_2=34.33333333333334
 +lat_0=33.75 +lon_0=-79 +x_0=609601.22 +y_0=0 +no_defs +a=6378137
 +rff=298.257222101 +towgs84=0.000,0.000,0.000 +to_meter=1
 >

Environment History Connections

Data

- aut_cool_points... 8610 obs. of 23 variables
- aut_cool_points... 615 obs. of 34 variables
- aut_cool_poly... 326 obs. of 103 variables
- aut_cool_poly_lo... 4564 obs. of 17 variables
- aut_cool_poly_st... Large STFDF (4564 elements, 19 Mb)
- aut_cool_ts... An 'xts' object on 2003-01-01/2016-0...
- av_aut_cool... 326 obs. of 32 variables
- count_tmax_highe... 326 obs. of 32 variables
- count_tmax_highe... 8610 obs. of 7 variables
- count_tmax_highe... 4564 obs. of 17 variables
- count_tmax_highe... Large STFDF (4564 elements, 19 Mb)
- count_tmean_high... 326 obs. of 32 variables

Files Plots Packages Help Viewer

User Library

- abind Combine Multidimensional Arrays
- assertthat Easy Pre and Post Assertions
- backports Reimplementations of Functions Introduced Since R-3.0.0
- base64enc Tools for base64 encoding
- BH Boost C++ Header Files
- bindr Parametrized Active Bindings
- bindrcpp An 'Rcpp' Interface to Active Bindings
- broom Convert Statistical Analysis Objects into Tidy Data Frames
- callr Call R from R
- cellranger Translate Spreadsheet Cell Ranges to Rows and Columns
- classInt Choose Univariate Class Intervals
- cli Helpers for Developing Command Line Interfaces
- clipr Read and Write from the System Clipboard
- colorspace Color Space Manipulation
- crayon Colored Terminal Output

We'll study this on Friday morning. Stay tuned! 

WPS - OGC Web Processing Service

- Web Processing Service is an OGC standard.
- ZOO-Project and PyWPS allow the user to run GRASS GIS commands in a simple way through the web.

Some useful commands and cool stuff

- **r.import** and **v.import**: import of raster and vector maps with reprojection, subsetting and resampling on the fly.

```
## IMPORT RASTER DATA: SRTM V3 data for NC

# set computational region to e.g. 10m elevation model:
g.region raster=elevation -p

# Import with reprojection on the fly
r.import input=n35_w079_1arc_v3.tif output=srtmv3_resamp10m \
resample=bilinear extent=region resolution=region \
title="SRTM V3 resampled to 10m resolution"

## IMPORT VECTOR DATA

# import SHAPE file, clip to region extent and reproject to
# current location projection
v.import input=research_area.shp output=research_area extent=region
```

- **g.list**: Lists available GRASS data base files of the user-specified data type (i.e., raster, vector, 3D raster, region, label) optionally using the search pattern.

```
g.list type=vector pattern="r*"  
g.list type=vector pattern="[ra]*"  
g.list type=raster pattern="{soil,landuse}*"
```

- **g.remove, g.rename and g.copy:**

These modules remove maps from the GRASSDBASE, rename maps and copy maps either in the same mapset or from other mapset.

Always perform these tasks from within GRASS

- **g.region**: Manages the boundary definitions and resolution for the computational region.

```
## Subset a raster map
# 1. Check region settings
g.region -p
# 2. Change region (here: relative to current N and W values, expanding)
g.region n=n-3000 w=w+4000
# 3. Subset map
r.mapcalc "new_elev = elevation"
r.colors new_elev color=viridis
# 4. Display maps
d.mon wx0
d.rast elevation
d.rast new_elev
```

- **g.mapset** and **g.mapssets**: These modules allow to change mapset and add/remove mapsets from the accessible mapsets list.

```
# print current mapset
g.mapset -p
# change to a different mapset
g.mapset mapset=modis_lst
# print mapsets in the search path
g.mapssets -p
# list available mapsets in the location
g.mapssets -l
# add mapset to the search path
g.mapssets mapset=modis_lst operation=add
```

- **r.info** and **v.info**: useful to get basic info about maps as well as their history.

```
# info for raster map  
r.info elevation  
# info for vector map  
v.info nc_state  
# history of vector map  
v.info nc_state -h
```

- **--exec in the grass74 startup command:** This flag allows to run modules or complete workflows written in Bash shell or Python without starting GRASS GIS.

```
# running a module  
grass74 /path/to/grassdata/nc_spm_08_grass7/PERMANENT/ --exec r.univar  
  
# running a script  
grass74 /path/to/grassdata/nc_spm_08_grass7/PERMANENT/ --exec sh test.  
  
## test.sh might be as simple as:  
  
#!/bin/bash  
  
g.region -p  
g.list type=raster  
r.info elevation
```

HELP!!!

KEEP CALM and GRASS GIS

- **g.manual**: in the main GUI under Help or just pressing *F1*
- **--help** or **--h** flag after the module name
- **GRASS wiki**: examples, explanations and help on particular modules or tasks, **tutorials**, applications, news, etc.
- **Jupyter/IPython notebooks** with example workflows for different applications
- **GRASS user mailing list**: Just **subscribe** and post or check the **archives**.

Other (very) useful links

- GRASS intro workshop held at NCSU
- Unleash the power of GRASS GIS at US-IALE 2017
- GRASS GIS workshop in Jena 2018
- Raster data processing in GRASS GIS
- Vector data processing in GRASS GIS

References

- Neteler, M., Mitasova, H. (2008): *Open Source GIS: A GRASS GIS Approach*. Third edition. ed. Springer, New York. [Book site](#)
- Neteler, M., Bowman, M.H., Landa, M. and Metz, M. (2012): *GRASS GIS: a multi-purpose Open Source GIS*. Environmental Modelling & Software, 31: 124-130 [DOI](#)

QUESTIONS?



GRASS
GIS

Thanks for your attention!!





Join and enjoy GRASS GIS!!

<!--



GRASS GIS

Move on to: GRASS GIS Installation party

Presentation powered by

